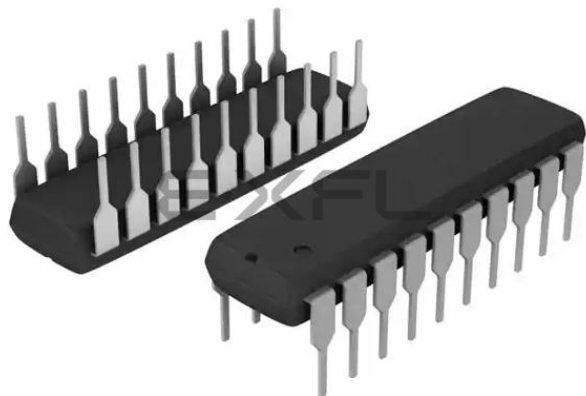




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Details

Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	16
Program Memory Size	32KB (32K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323hsp2032c



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Table 11. GP323HA DC Characteristics

$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$								
Symbol	Parameter	V_{CC}	Min	Typ(7)	Max	Units	Conditions	Notes
V_{CC}	Supply Voltage		2.0		5.5	V	See Note 5	5
V_{CH}	Clock Input High Voltage	2.0-5.5	$0.8 V_{CC}$		$V_{CC}+0.3$	V	Driven by External Clock Generator	
V_{CL}	Clock Input Low Voltage	2.0-5.5	$V_{SS}-0.3$		0.4	V	Driven by External Clock Generator	
V_{IH}	Input High Voltage	2.0-5.5	$0.7 V_{CC}$		$V_{CC}+0.3$	V		
V_{IL}	Input Low Voltage	2.0-5.5	$V_{SS}-0.3$		$0.2 V_{CC}$	V		
V_{OH1}	Output High Voltage	2.0-5.5	$V_{CC}-0.4$			V	$I_{OH} = -0.5\text{mA}$	
V_{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	$V_{CC}-0.8$			V	$I_{OH} = -7\text{mA}$	
V_{OL1}	Output Low Voltage	2.0-5.5			0.4	V	$I_{OL} = 4.0\text{mA}$	
V_{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	$I_{OL} = 10\text{mA}$	
V_{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V_{REF}	Comparator Reference Voltage	2.0-5.5	0		$V_{DD} -1.75$	V		
I_{IL}	Input Leakage	2.0-5.5	-1		1	μA	$V_{IN} = 0\text{V}$, V_{CC} Pull-ups disabled	
R_{PU}	Pull-up Resistance	2.0V	200		700	$\text{K}\Omega$	$V_{IN} = 0\text{V}$; Pullups selected by mask option	
		3.6V	50		300	$\text{K}\Omega$		
		5.0V	25		175	$\text{K}\Omega$		
I_{OL}	Output Leakage	2.0-5.5	-1		1	μA	$V_{IN} = 0\text{V}$, V_{CC}	
I_{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I_{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	$V_{IN} = 0\text{V}$, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	$V_{IN} = 0\text{V}$, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	$V_{IN} = 0\text{V}$, Clock at 8.0MHz	1, 2, 6
I_{CC2}	Standby Current (Stop Mode)	2.0V		1.6	15	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT not Running	3
		3.6V		1.8	20	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT not Running	3
		5.5V		1.9	25	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT not Running	3
		2.0V		5	30	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT is Running	3
		3.6V		8	40	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT is Running	3
		5.5V		15	60	μA	$V_{IN} = 0\text{V}$, V_{CC} WDT is Running	3
I_{LV}	Standby Current (Low Voltage)			1.2	6	μA	Measured at 1.3V	4
V_{BO}	V_{CC} Low Voltage Protection			1.9	2.15	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V_{CC} Low Voltage Detection			2.4		V		



Table 13. AC Characteristics

				T _A =0°C to +70°C (S) –40°C to +105°C (E) –40°C to +125°C (A) 8.0MHz				Watch-Dog Timer Mode Register (D1, D0)
No	Symbol	Parameter	V _{CC}	Minimum	Maximum	Units	Notes	
1	TpC	Input Clock Period	2.0–5.5	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–5.5		25	ns	1	
3	TwC	Input Clock Width	2.0–5.5	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 5.5	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–5.5	3TpC			1	
6	TpTin	Timer Input Period	2.0–5.5	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–5.5		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 5.5	100 70		ns	1, 2	
9	TwIH	Interrupt Request Input High Time	2.0–5.5	5TpC			1, 2	
10	Twsm	Stop-Mode Recovery Width Spec	2.0–5.5	12 5TpC		ns	3 4	
11	Tost	Oscillator Start-Up Time	2.0–5.5		5TpC		4	
12	Twdt	Watch-Dog Timer Delay Time	2.0–5.5 2.0–5.5 2.0–5.5 2.0–5.5	5 10 20 80		ms ms ms ms	0, 0 0, 1 1, 0 1, 1	
13	T _{POR}	Power-On Reset	2.0–5.5	2.5	10	ms		

Notes:

1. Timing Reference uses 0.9 V_{CC} for a logic 1 and 0.1 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).
3. SMR – D5 = 1.
4. SMR – D5 = 0.

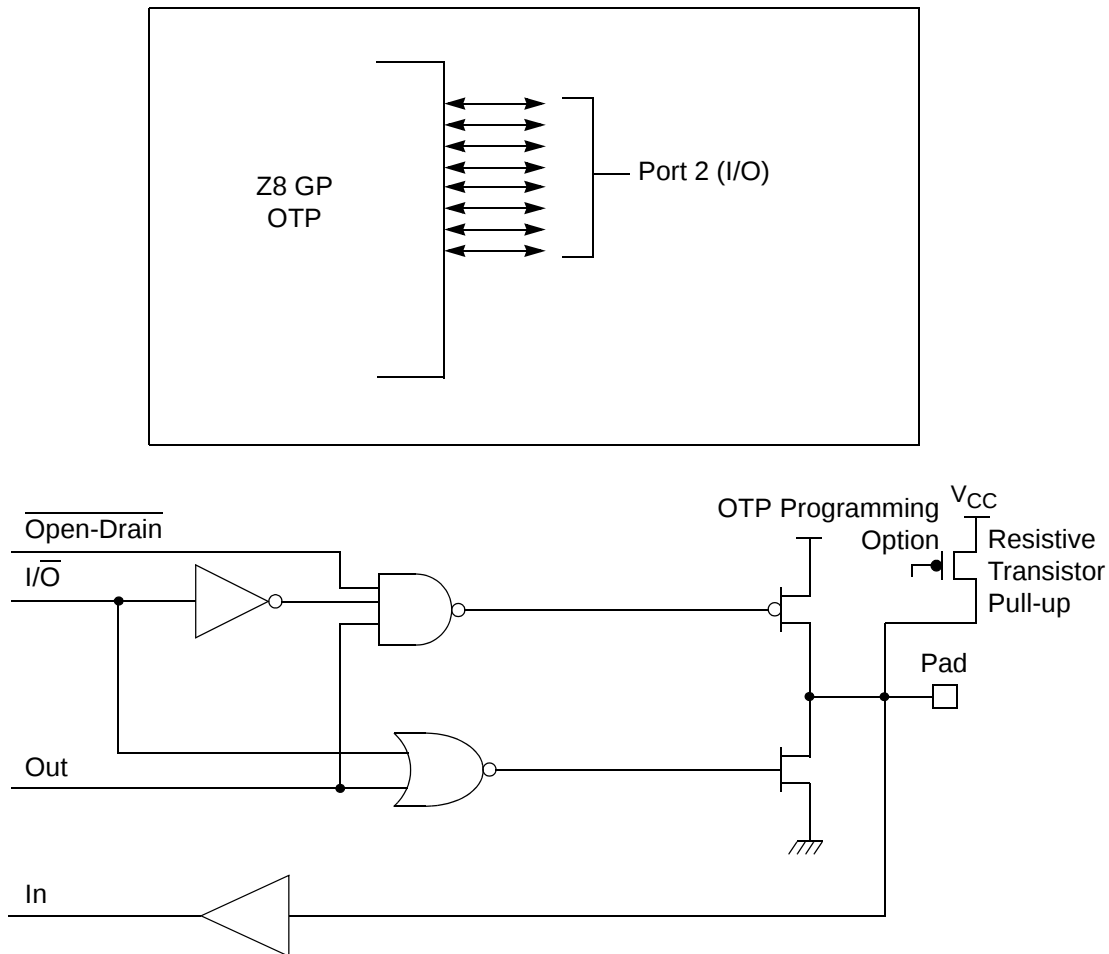


Figure 11. Port 2 Configuration

Port 3 (P37–P30)

Port 3 is a 8-bit, CMOS-compatible fixed I/O port (see Figure 12). Port 3 consists of four fixed input (P33–P30) and four fixed output (P37–P34), which can be configured under software control for interrupt and as output from the counter/timers. P30, P31, P32, and P33 are standard CMOS inputs; P34, P35, P36, and P37 are push-pull outputs.

Table 17. CTR2(D)02H: Counter/Timer16 Control Register

Field	Bit Position		Value	Description
T16_Enable	7-----	R	0*	Counter Disabled
			1	Counter Enabled
		W	0	Stop Counter
			1	Enable Counter
Single/Modulo-N	-6-----	R/W	0*	Transmit Mode
			1	Modulo-N
			0	Single Pass
			1	Demodulation Mode
Time_Out	--5-----	R	0*	T16 Recognizes Edge
			1	T16 Does Not Recognize Edge
		W	0	No Counter Timeout
			1	Counter Timeout Occurred
T16_Clock	---43---	R/W	00**	No Effect
			01	Reset Flag to 0
			10	SCLK
			11	SCLK/2
Capture_INT_Mask	-----2--	R/W	0**	SCLK/4
			1	SCLK/8
Counter_INT_Mask	-----1-	R/W	0*	Disable Data Capture Int.
			1	Enable Data Capture Int.
P35_Out	-----0	R/W	0*	Disable Timeout Int.
			1	Enable Timeout Int.

Note:

*Indicates the value upon Power-On Reset.

**Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

T16_Enable

This field enables T16 when set to 1.

Single/Modulo-N

In TRANSMIT Mode, when set to 0, the counter reloads the initial value when it reaches the terminal count. When set to 1, the counter stops when the terminal count is reached.

► **Note:** The letter *h* denotes hexadecimal values.

Transition from 0 to FF_h is not a timeout condition.



Caution: Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur. See Figure 21 and Figure 22.

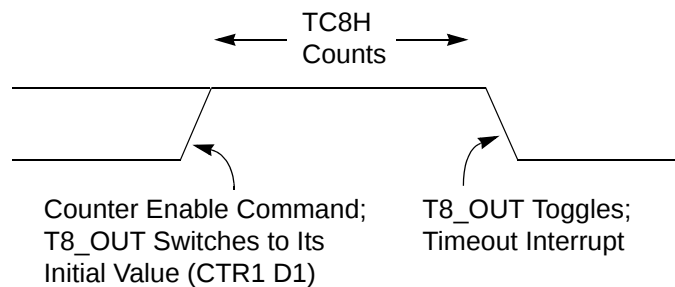


Figure 21. T8_OUT in Single-Pass Mode

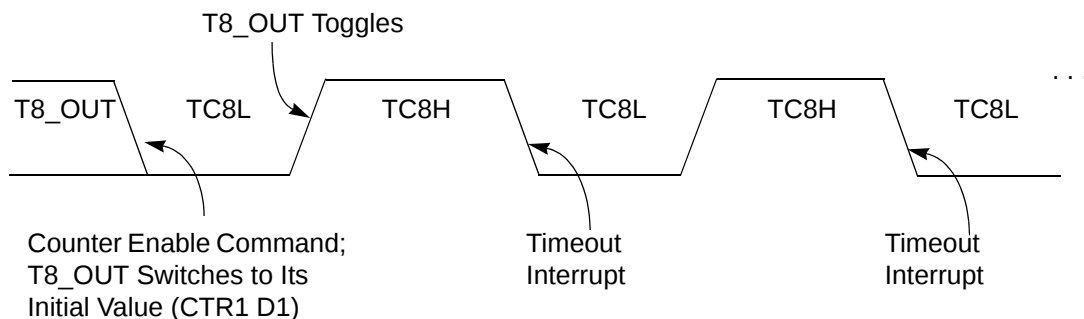


Figure 22. T8_OUT in Modulo-N Mode

T8 Demodulation Mode

The user must program TC8L and TC8H to FF_h. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put

If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from `FFFFh`. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

Ping-Pong Mode

This operation mode is only valid in TRANSMIT Mode. T8 and T16 must be programmed in Single-Pass mode (CTR0, D6; CTR2, D6), and Ping-Pong mode must be programmed in CTR1, D3; D2. The user can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8_OUT is set to this initial value (CTR1, D1). According to T8_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the ping-pong operation, write 00 to bits D3 and D2 of CTR1. See Figure 28.

- **Note:** Enabling ping-pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status flags before instituting this operation.

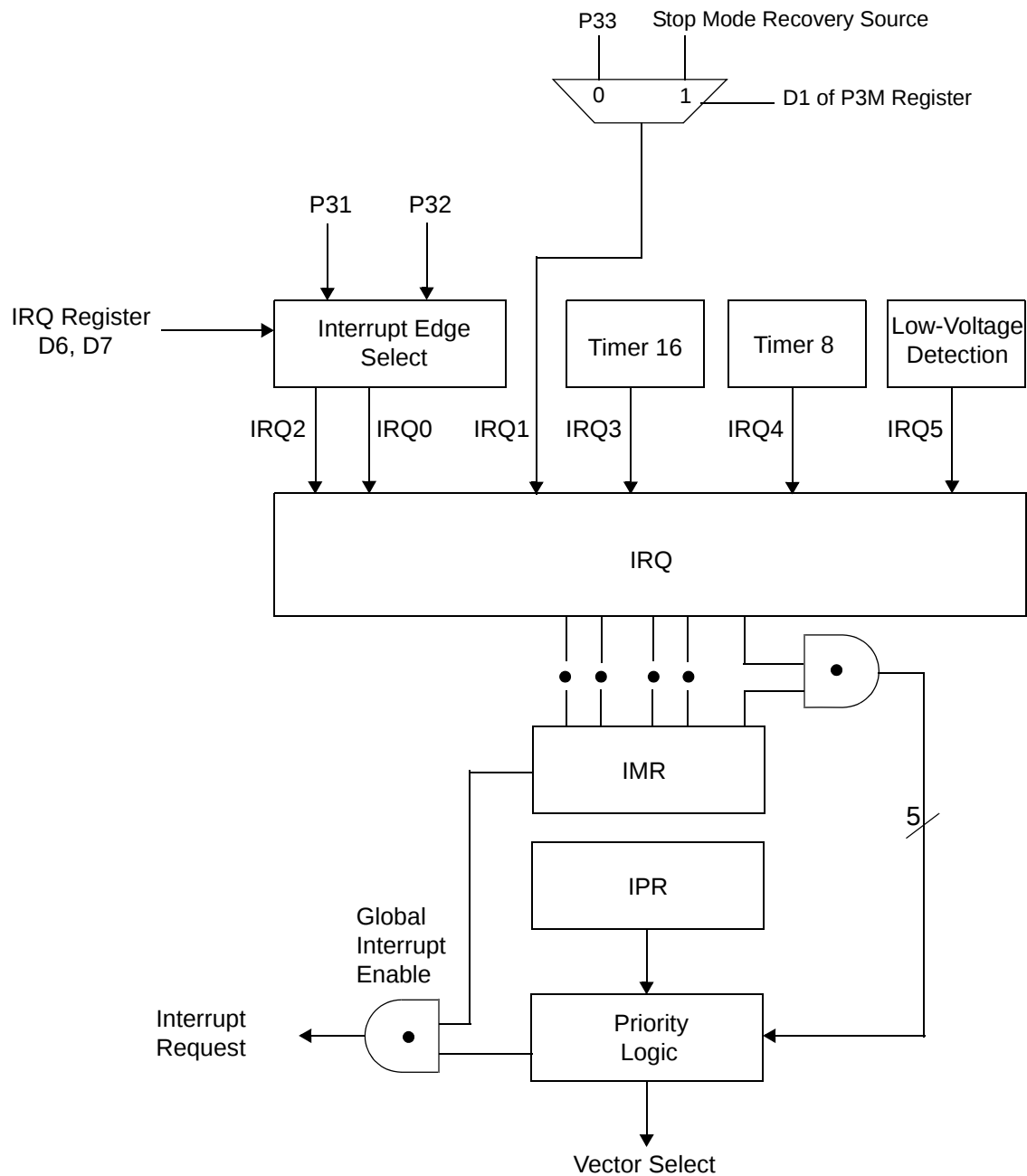


Figure 30. Interrupt Block Diagram



Power-On Reset

A timer circuit clocked by a dedicated on-board RC-oscillator is used for the Power-On Reset (POR) timer function. The POR time allows V_{DD} and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- Power Fail to Power OK status, including Waking up from V_{BO} Standby
- Stop-Mode Recovery (if D5 of SMR = 1)
- WDT Timeout

The POR timer is 2.5 ms minimum. Bit 5 of the Stop-Mode Register determines whether the POR timer is bypassed after Stop-Mode Recovery (typical for external clock).

HALT Mode

This instruction turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2, IRQ3, IRQ4, and IRQ5 remain active. The devices are recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after HALT Mode.

STOP Mode

This instruction turns off the internal clock and external crystal oscillation, reducing the standby current to 10 μ A or less. STOP Mode is terminated only by a reset, such as WDT timeout, POR, SMR or external reset. This condition causes the processor to restart the application program at address 000CH. To enter STOP (or HALT) mode, first flush the instruction pipeline to avoid suspending execution in mid-instruction. Execute a NOP (Opcode = FFH) immediately before the appropriate sleep instruction, as follows:



Port 0 Output Mode (D2)

Bit 2 controls the output mode of port 0. A 1 in this location sets the output to push-pull, and a 0 sets the output to open-drain.

Stop-Mode Recovery Register (SMR)

This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 33). All bits are write only except bit 7, which is read only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level at the XOR-gate input (Figure 35 on page 59) is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits D2, D3, and D4 of the SMR register specify the source of the Stop Mode Recovery signal. Bits D0 determines if SCLK/TCLK are divided by 16 or not. The SMR is located in Bank F of the Expanded Register Group at address 0BH.

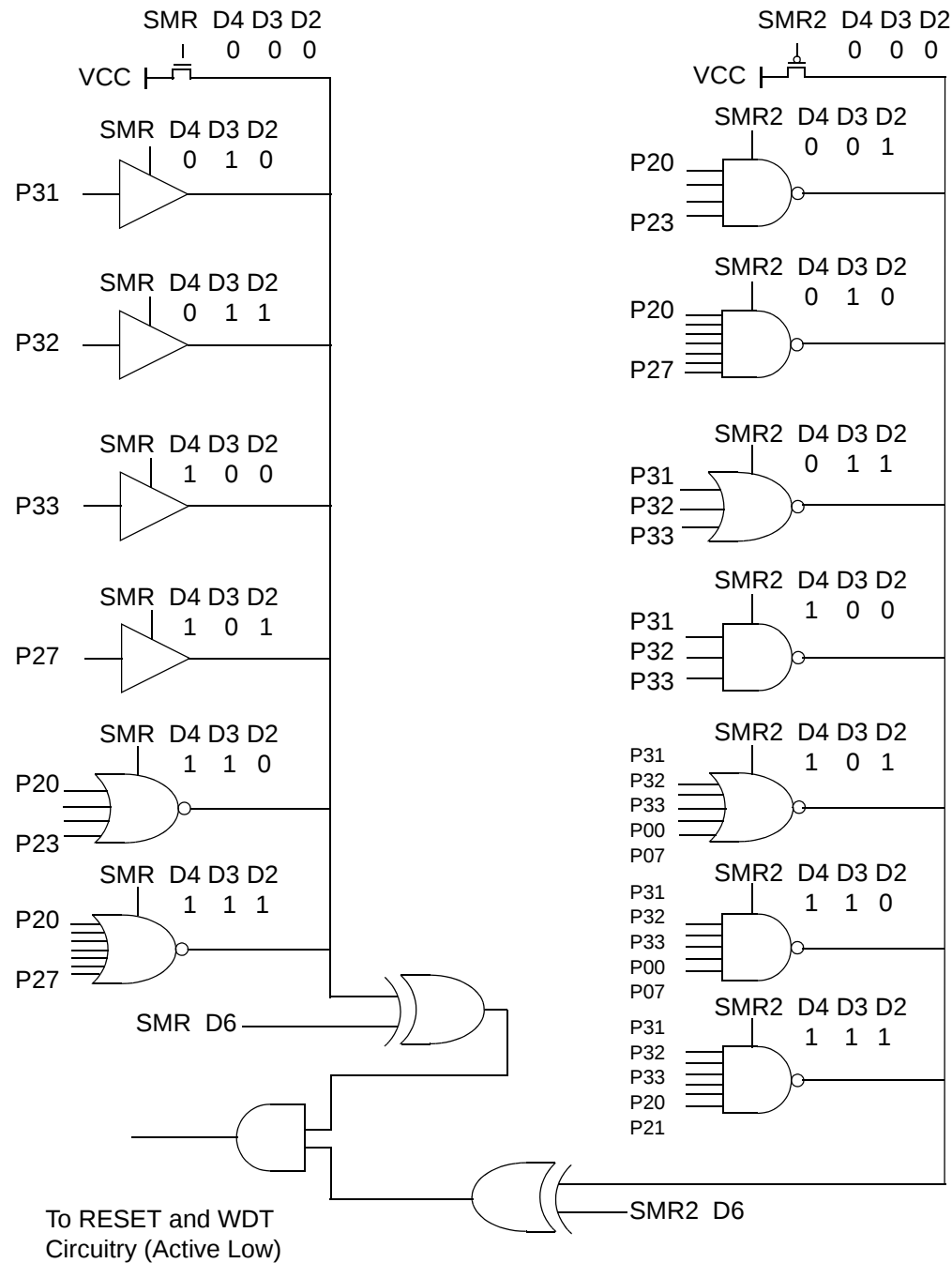
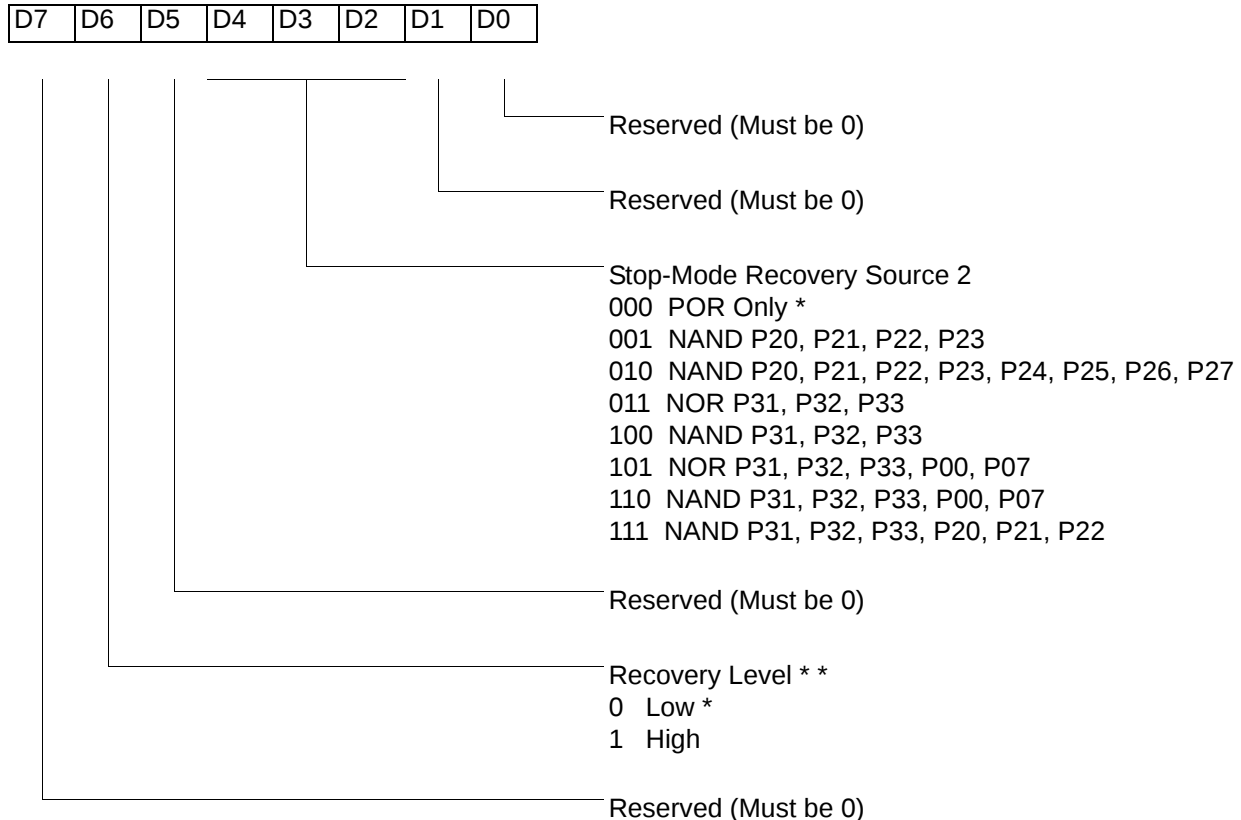


Figure 35. Stop Mode Recovery Source

Stop Mode Recovery Register 2 (SMR2)

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 36).

SMR2(0F)DH



Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

* Default setting after reset

* * At the XOR gate input

Figure 36. Stop Mode Recovery Register 2 ((0F)DH:D2–D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.

► **Note:** Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.

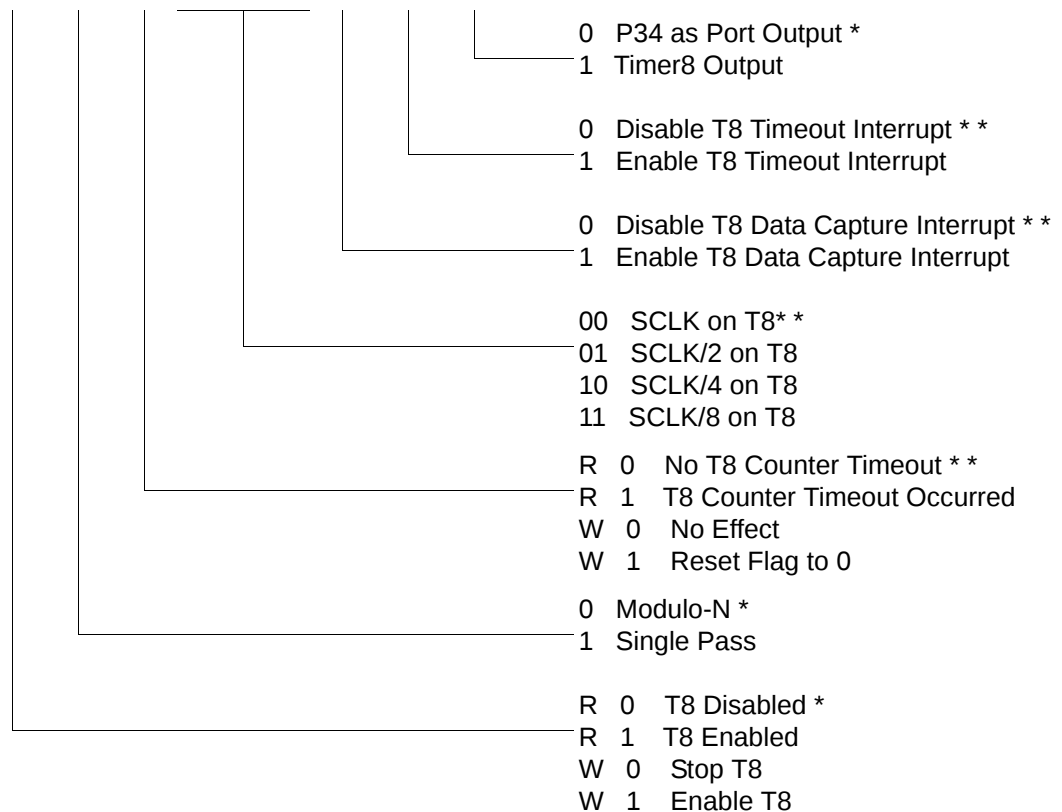


Expanded Register File Control Registers (0D)

The expanded register file control registers (0D) are depicted in Figure 39 through Figure 43.

CTR0(0D)00H

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----



* Default setting after reset.

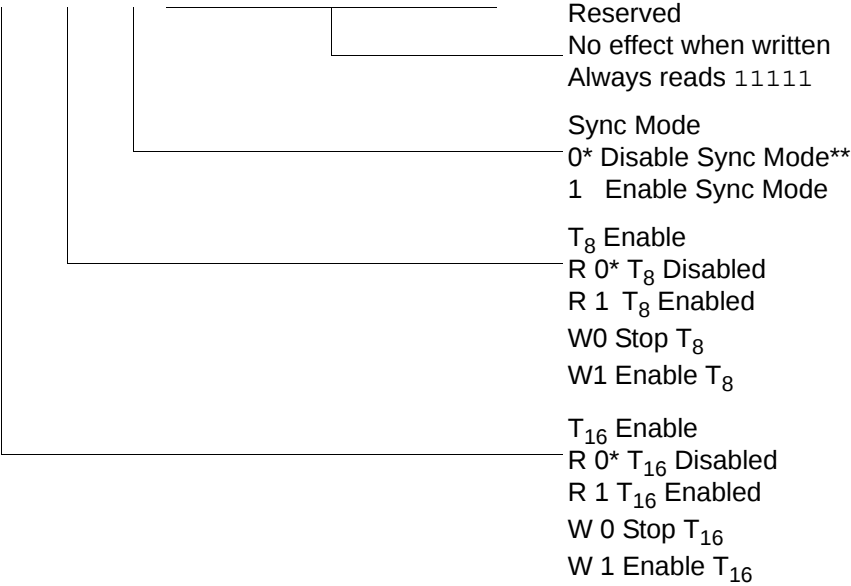
* * Default setting after Reset.. Not reset with a Stop-Mode recovery.

Figure 39. TC8 Control Register ((0D)00H: Read/Write Except Where Noted)



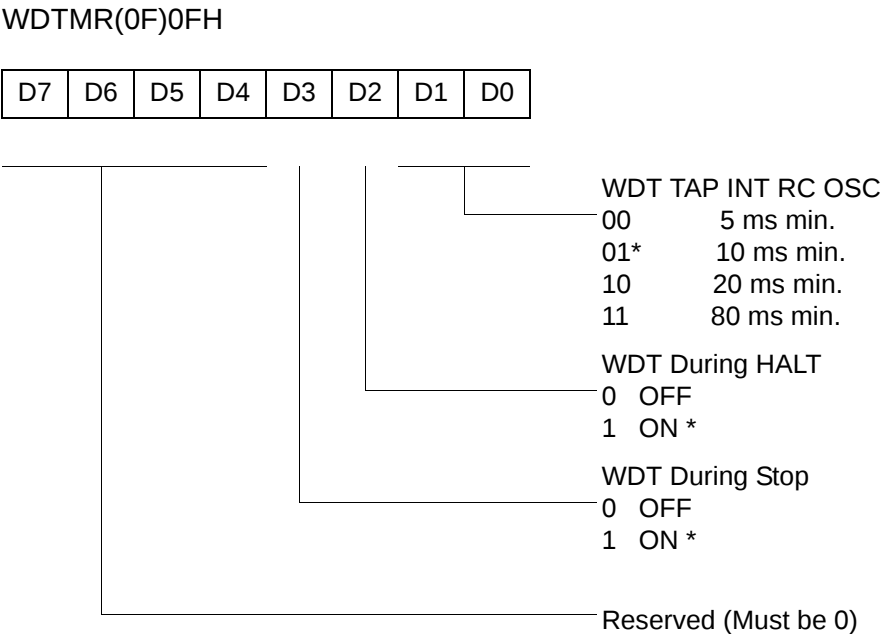
CTR3(0D)03H

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----



* Default setting after reset.
** Default setting after reset. Not reset with a Stop Mode recovery.

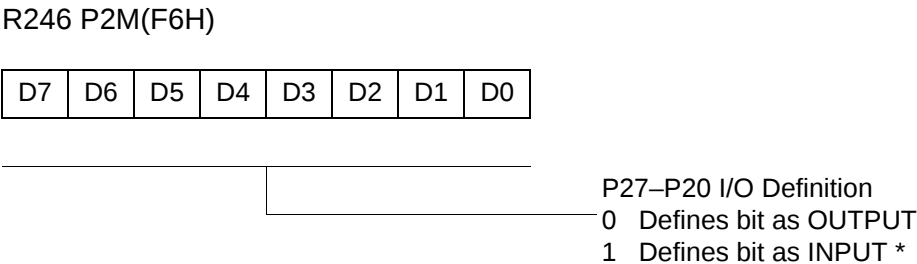
Figure 42. T8/T16 Control Register (0D)03H: Read/Write (Except Where Noted)



* Default setting after reset. Not reset with a Stop Mode recovery.

Figure 47. Watch-Dog Timer Register ((0F) 0FH: Write Only)

Standard Control Registers



* Default setting after reset. Not reset with a Stop Mode recovery.

Figure 48. Port 2 Mode Register (F6H: Write Only)



R249 IPR(F9H)

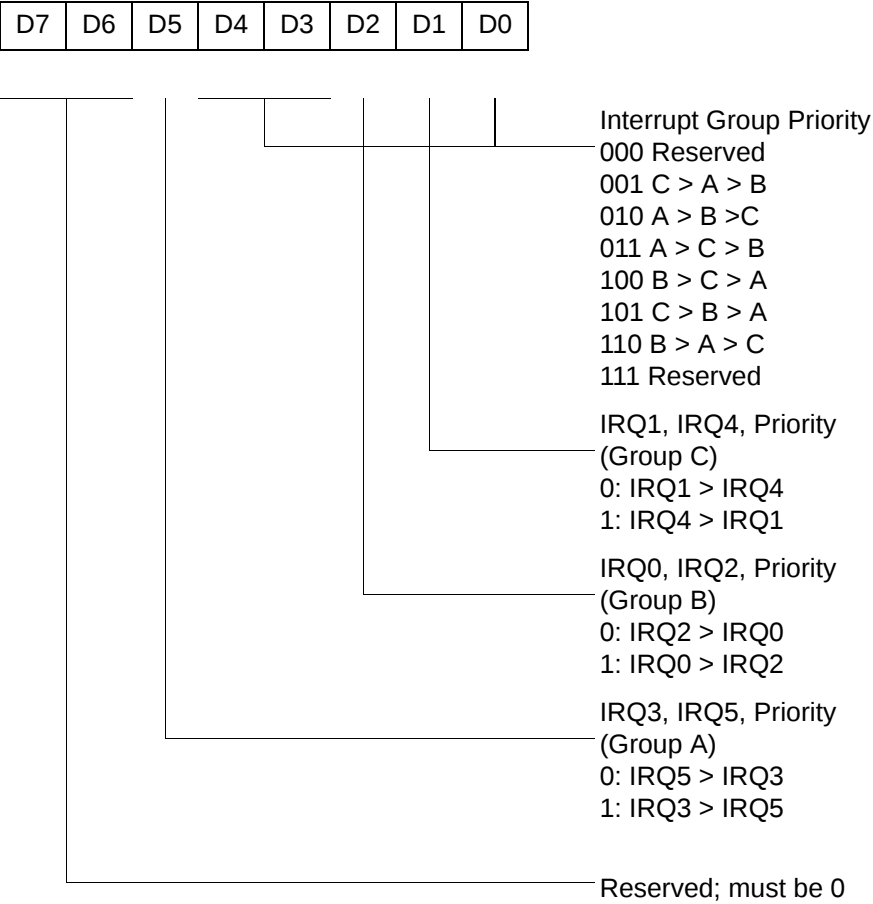


Figure 51. Interrupt Priority Register (F9H: Write Only)

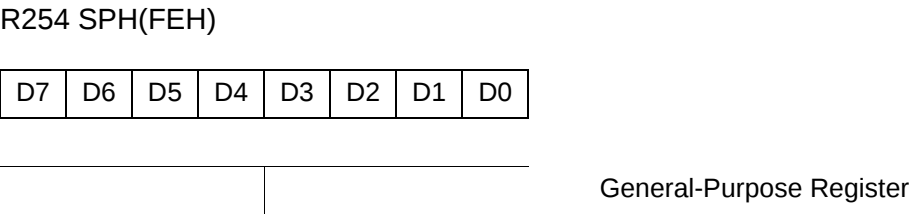


Figure 56. Stack Pointer High (FEH: Read/Write)

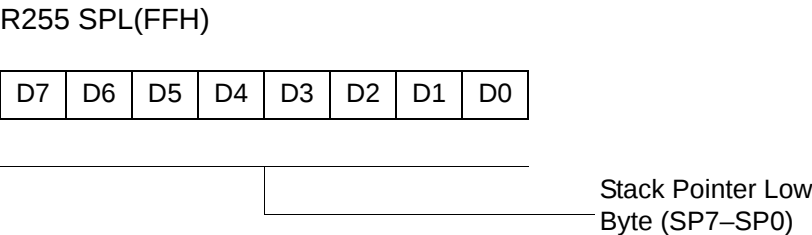
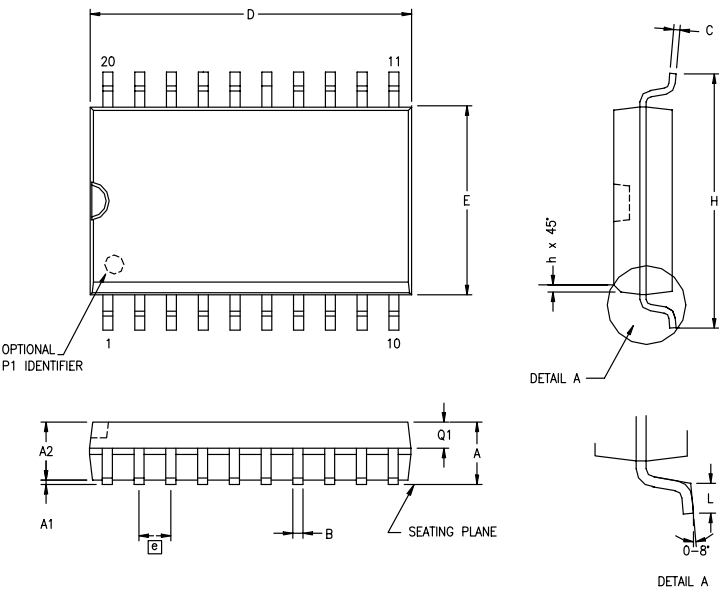


Figure 57. Stack Pointer Low (FFH: Read/Write)

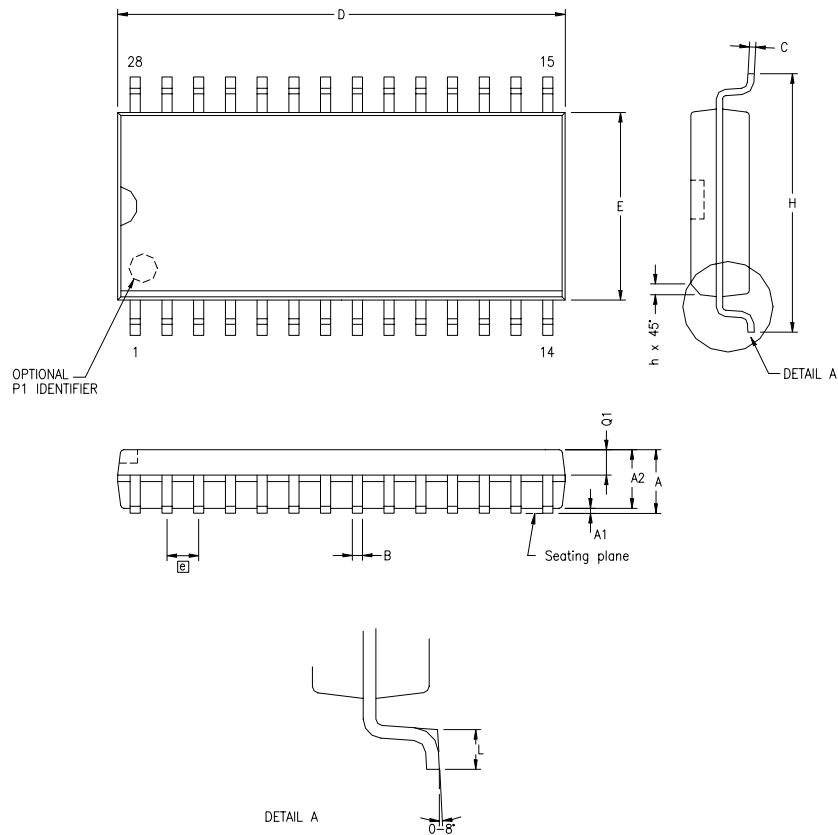
Package Information

Package information for all versions of ZGP323H is depicted in Figures 59 through Figure 68.



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.65	.094	.104
A1	0.10	0.30	.004	.012
A2	2.24	2.44	.088	.096
B	0.36	0.46	.014	.018
C	0.23	0.30	.009	.012
D	12.60	12.95	.496	.510
E	7.40	7.60	.291	.299
⌀	1.27 BSC		.050 BSC	
H	10.00	10.65	.394	.419
h	0.30	0.40	.012	.016
L	0.60	1.00	.024	.039
Q1	0.97	1.07	.038	.042

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.64	.094	.104
A1	0.10	0.30	.004	.012
A2	2.24	2.44	.088	.096
B	0.36	0.46	.014	.018
C	0.23	0.30	.009	.012
D	17.78	18.00	.700	.710
E	7.40	7.60	.291	.299
@	1.27 BSC		.050 BSC	
H	10.00	10.65	.394	.419
h	0.30	0.71	.012	.028
L	0.61	1.00	.024	.039
Q1	0.97	1.09	.038	.043

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 62. 28-Pin SOIC Package Diagram

