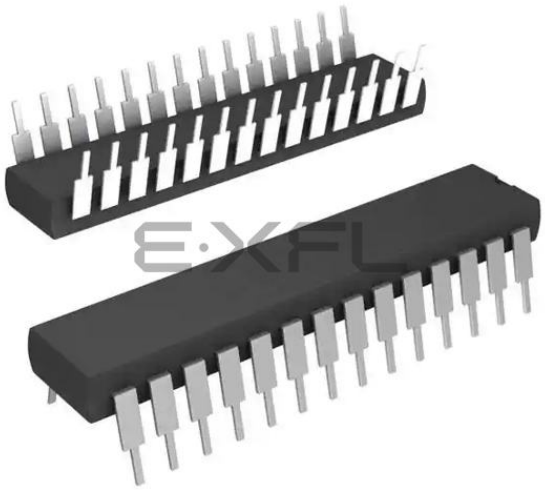


Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	24
Program Memory Size	4KB (4K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.600", 15.24mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323hsp2804g

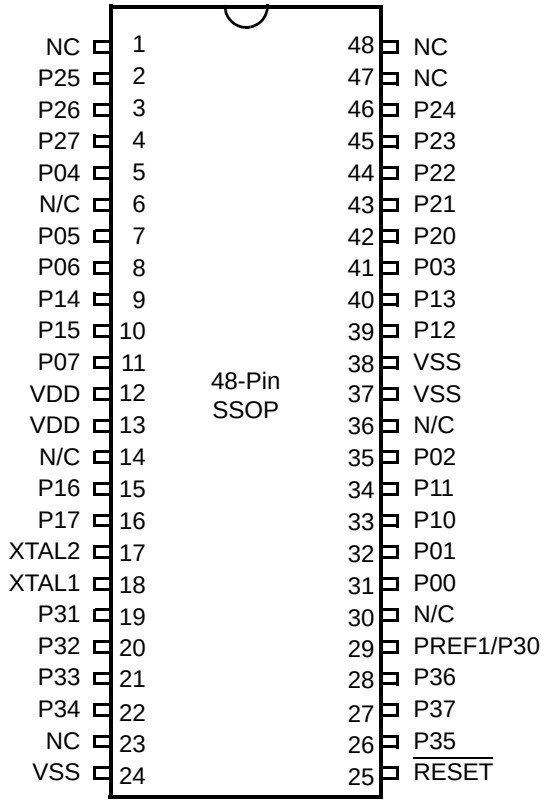


Figure 6. 48-Pin SSOP Pin Configuration

Table 6. 40- and 48-Pin Configuration

40-Pin PDIP #	48-Pin SSOP #	Symbol
26	31	P00
27	32	P01
30	35	P02
34	41	P03
5	5	P04
6	7	P05
7	8	P06
10	11	P07
28	33	P10
29	34	P11
32	39	P12

Table 6. 40- and 48-Pin Configuration (Continued)

40-Pin PDIP #	48-Pin SSOP #	Symbol
33	40	P13
8	9	P14
9	10	P15
12	15	P16
13	16	P17
35	42	P20
36	43	P21
37	44	P22
38	45	P23
39	46	P24
2	2	P25
3	3	P26
4	4	P27
16	19	P31
17	20	P32
18	21	P33
19	22	P34
22	26	P35
24	28	P36
23	27	P37
20	23	NC
40	47	NC
1	1	NC
21	25	$\overline{\text{RESET}}$
15	18	XTAL1
14	17	XTAL2
11	12, 13	V_{DD}
31	24, 37, 38	V_{SS}
25	29	Pref1/P30
	48	NC
	6	NC
	14	NC
	30	NC
	36	NC

Table 9. GP323HS DC Characteristics (Continued)

			T_A=0°C to +70°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
I_{OL}	Output Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC}	
I_{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I_{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I_{CC2}	Standby Current (Stop Mode)	2.0V		1.6	8	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		3.6V		1.8	10	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		5.5V		1.9	12	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		2.0V		5	20	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		3.6V		8	30	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		5.5V		15	45	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
I_{LV}	Standby Current (Low Voltage)			1.2	6	µA	Measured at 1.3V	4
V_{BO}	V_{CC} Low Voltage Protection			1.9	2.0	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V_{CC} Low Voltage Detection			2.4		V		
V_{HVD}	Vcc High Voltage Detection			2.7		V		

Notes:
1. All outputs unloaded, inputs at rail.
2. CL1 = CL2 = 100 pF.
3. Oscillator stopped.
4. Oscillator stops when V_{CC} falls below V_{BO} limit.
5. It is strongly recommended to add a filter capacitor (minimum 0.1 µF), physically close to VCC and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.
6. Comparator and Timers are on. Interrupt disabled.
7. Typical values shown are at 25 degrees C.

Table 10. GP323HE DC Characteristics

			T_A= -40°C to +105°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
V_{CC}	Supply Voltage		2.0		5.5	V	See Note 5	5
V_{CH}	Clock Input High Voltage	2.0-5.5	0.8 V_{CC}		V_{CC}+0.3	V	Driven by External Clock Generator	
V_{CL}	Clock Input Low Voltage	2.0-5.5	V_{SS}–0.3		0.4	V	Driven by External Clock Generator	
V_{IH}	Input High Voltage	2.0-5.5	0.7 V_{CC}		V_{CC}+0.3	V		
V_{IL}	Input Low Voltage	2.0-5.5	V_{SS}–0.3		0.2 V_{CC}	V		
V_{OH1}	Output High Voltage	2.0-5.5	V_{CC}–0.4			V	I_{OH} = –0.5mA	

Table 10. GP323HE DC Characteristics (Continued)

			T_A= -40°C to +105°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
V_{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	V_{CC}–0.8			V	I_{OH} = –7mA	
V_{OL1}	Output Low Voltage	2.0-5.5			0.4	V	I_{OL} = 4.0mA	
V_{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	I_{OL} = 10mA	
V_{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V_{REF}	Comparator Reference Voltage	2.0-5.5	0		V_{DD} -1.75	V		
I_{IL}	Input Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC} Pull-ups disabled	
R_{PU}	Pull-up Resistance	2.0V	200.0		700.0	KΩ	V_{IN} = 0V; Pullups selected by mask option	
		3.6V	50.0		300.0	KΩ		
		5.0V	25.0		175.0	KΩ		
I_{OL}	Output Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC}	
I_{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I_{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I_{CC2}	Standby Current (Stop Mode)	2.0V		1.6	12	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		3.6V		1.8	15	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		5.5V		1.9	18	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		2.0V		5	30	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		3.6V		8	40	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		5.5V		15	60	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
I_{LV}	Standby Current (Low Voltage)			1.2	6	µA	Measured at 1.3V	4
V_{BO}	V_{CC} Low Voltage Protection			1.9	2.15	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V_{CC} Low Voltage Detection			2.4		V		
V_{HVD}	Vcc High Voltage Detection			2.7		V		

Notes:

1. All outputs unloaded, inputs at rail.
2. CL1 = CL2 = 100 pF.
3. Oscillator stopped.
4. Oscillator stops when V_{CC} falls below V_{BO} limit.
5. It is strongly recommended to add a filter capacitor (minimum 0.1 µF), physically close to VCC and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.
6. Comparator and Timers are on. Interrupt disabled.
7. Typical values shown are at 25 degrees C.

Table 13. AC Characteristics

				T_A=0°C to +70°C (S) –40°C to +105°C (E) –40°C to +125°C (A) 8.0MHz				Watch-Dog Timer Mode Register (D1, D0)
No	**Symbol**	**Parameter**	**V_{CC}**	**Minimum**	**Maximum**	**Units**	**Notes**	
1	TpC	Input Clock Period	2.0–5.5	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–5.5		25	ns	1	
3	TwC	Input Clock Width	2.0–5.5	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 5.5	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–5.5	3TpC			1	
6	TpTin	Timer Input Period	2.0–5.5	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–5.5		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 5.5	100 70		ns	1, 2	
9	TwIH	Interrupt Request Input High Time	2.0–5.5	5TpC			1, 2	
10	Twsm	Stop-Mode Recovery Width Spec	2.0–5.5	12 5TpC		ns	3 4	
11	Tost	Oscillator Start-Up Time	2.0–5.5		5TpC		4	
12	Twdt	Watch-Dog Timer Delay Time	2.0–5.5 2.0–5.5 2.0–5.5 2.0–5.5	5 10 20 80		ms ms ms ms		0, 0 0, 1 1, 0 1, 1
13	T_{POR}	Power-On Reset	2.0–5.5	2.5	10	ms		

Notes:
1. Timing Reference uses 0.9 V_{CC} for a logic 1 and 0.1 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).
3. SMR – D5 = 1.
4. SMR – D5 = 0.

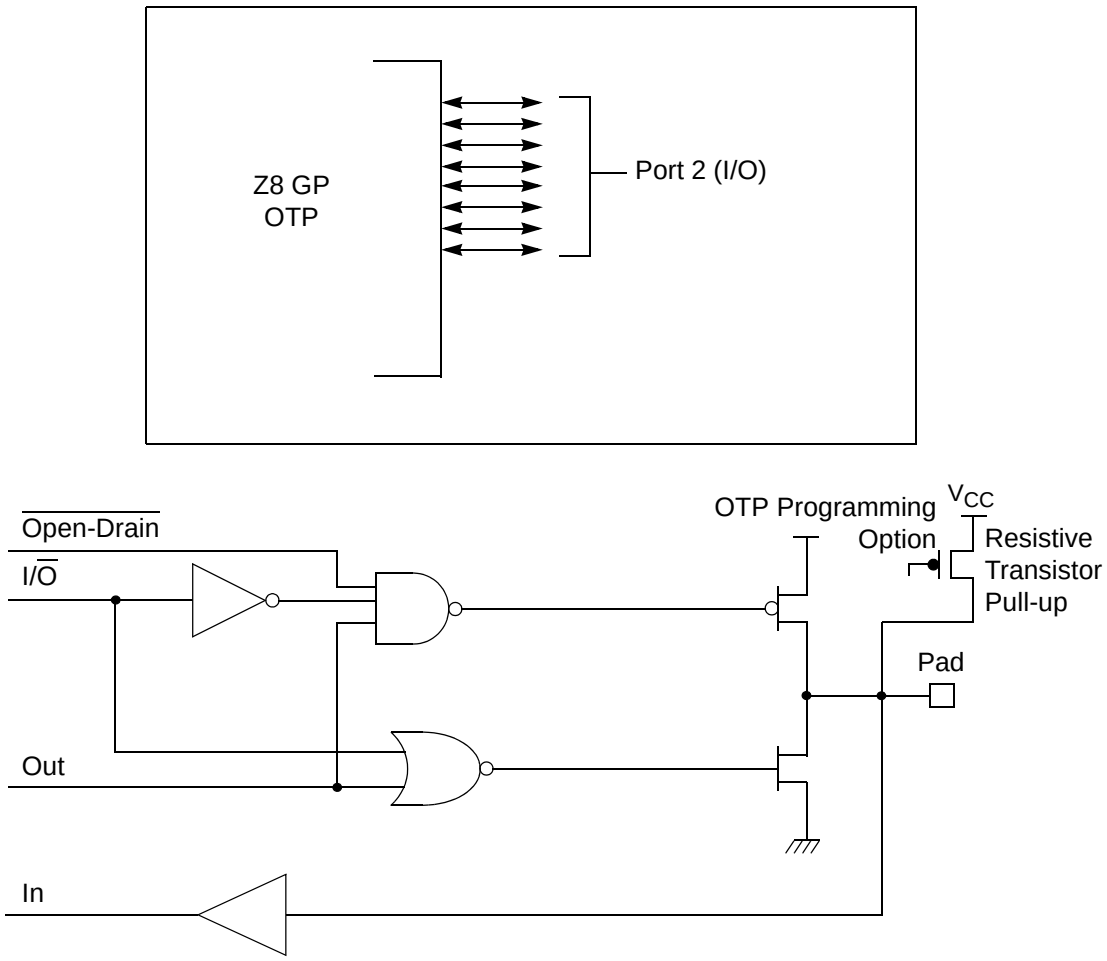


Figure 11. Port 2 Configuration

Port 3 (P37–P30)

Port 3 is a 8-bit, CMOS-compatible fixed I/O port (see Figure 12). Port 3 consists of four fixed input (P33–P30) and four fixed output (P37–P34), which can be configured under software control for interrupt and as output from the counter/timers. P30, P31, P32, and P33 are standard CMOS inputs; P34, P35, P36, and P37 are push-pull outputs.

CTR1(0D)01H" on page 35). Other edge detect and IRQ modes are described in Table 14.

Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery (SMR) source, these inputs must be placed into digital mode.

Table 14. Port 3 Pin Function Summary

Pin	I/O	Counter/Timers	Comparator	Interrupt
Pref1/P30	IN		RF1	
P31	IN	IN	AN1	IRQ2
P32	IN		AN2	IRQ0
P33	IN		RF2	IRQ1
P34	OUT	T8	AO1	
P35	OUT	T16		
P36	OUT	T8/16		
P37	OUT		AO2	
P20	I/O	IN		

Port 3 also provides output for each of the counter/timers and the AND/OR Logic (see Figure 13). Control is performed by programming bits D5–D4 of CTR1, bit 0 of CTR0, and bit 0 of CTR2.

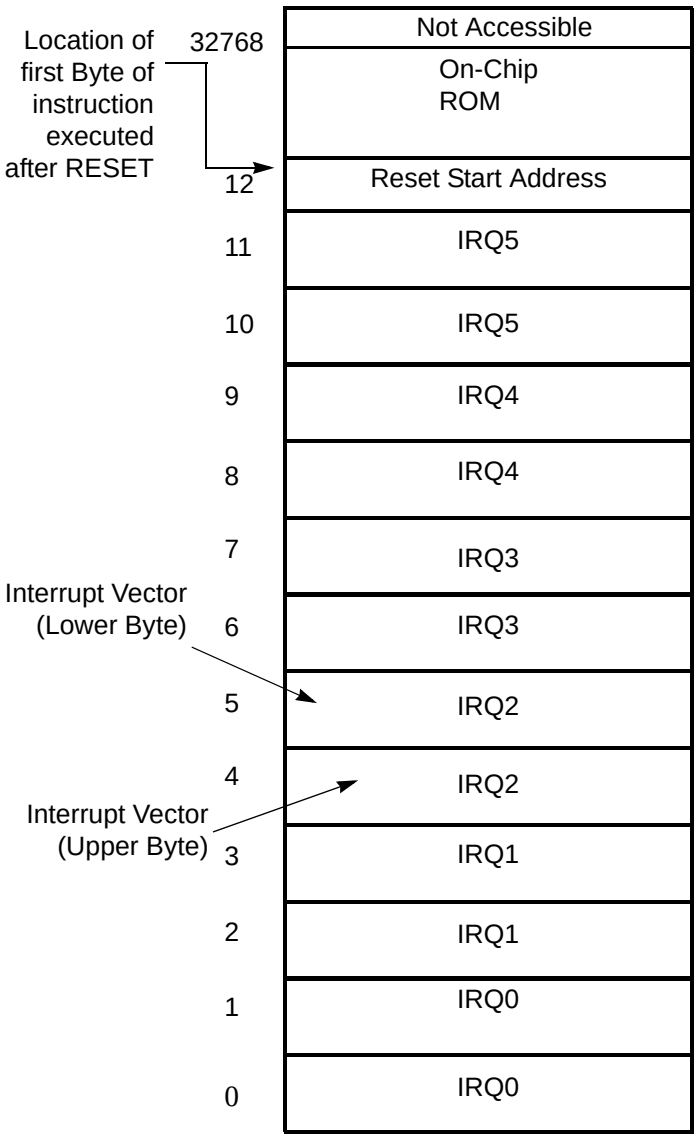


Figure 14. Program Memory Map (32K OTP)

Expanded Register File

The register file has been expanded to allow for additional system control registers and for mapping of additional peripheral devices into the register address area. The Z8® register address space (R0 through R15) has been implemented as 16 banks, with 16 registers per bank. These register groups are known as the

Table 16. CTR1(0D)01H T8 and T16 Common Functions (Continued)

Field	Bit Position		Value	Description
Transmit_Submode/ Glitch_Filter	----32--	R/W		Transmit Mode
			00*	Normal Operation
			01	Ping-Pong Mode
			10	T16_Out = 0
			11	T16_Out = 1
				Demodulation Mode
			00*	No Filter
			01	4 SCLK Cycle
			10	8 SCLK Cycle
			11	Reserved
Initial_T8_Out/ Rising Edge	------1-			Transmit Mode
		R/W	0*	T8_OUT is 0 Initially
			1	T8_OUT is 1 Initially
				Demodulation Mode
		R	0*	No Rising Edge
			1	Rising Edge Detected
		W	0	No Effect
			1	Reset Flag to 0
Initial_T16_Out/ Falling_Edge	-------0			Transmit Mode
		R/W	0*	T16_OUT is 0 Initially
			1	T16_OUT is 1 Initially
				Demodulation Mode
		R	0*	No Falling Edge
			1	Falling Edge Detected
		W	0	No Effect
			1	Reset Flag to 0

Note:
*Default at Power-On Reset
*Default at Power-On Reset. Not reset with Stop Mode recovery.

Mode

If the result is 0, the counter/timers are in TRANSMIT mode; otherwise, they are in DEMODULATION mode.

P36_Out/Demodulator_Input

In TRANSMIT Mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In DEMODULATION Mode, this bit defines whether the input signal to the Counter/Timers is from P20 or P31.

If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

Table 17. CTR2(D)02H: Counter/Timer16 Control Register

Field	Bit Position		Value	Description
T16_Enable	7-------	R	0*	Counter Disabled
			1	Counter Enabled
		W	0	Stop Counter
			1	Enable Counter
Single/Modulo-N	-6------	R/W		Transmit Mode
			0*	Modulo-N
			1	Single Pass Demodulation Mode
			0	T16 Recognizes Edge
			1	T16 Does Not Recognize Edge
Time_Out	--5-----	R	0*	No Counter Timeout
			1	Counter Timeout Occurred
		W	0	No Effect
			1	Reset Flag to 0
T16 _Clock	---43---	R/W	00**	SCLK
			01	SCLK/2
			10	SCLK/4
			11	SCLK/8
Capture_INT_Mask	-----2--	R/W	0**	Disable Data Capture Int.
			1	Enable Data Capture Int.
Counter_INT_Mask	------1-	R/W	0*	Disable Timeout Int. Enable Timeout Int.
P35_Out	-------0	R/W	0*	P35 as Port Output
			1	T16 Output on P35

Note:
*Indicates the value upon Power-On Reset.
**Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

T16_Enable

This field enables T16 when set to 1.

Single/Modulo-N

In TRANSMIT Mode, when set to 0, the counter reloads the initial value when it reaches the terminal count. When set to 1, the counter stops when the terminal count is reached.

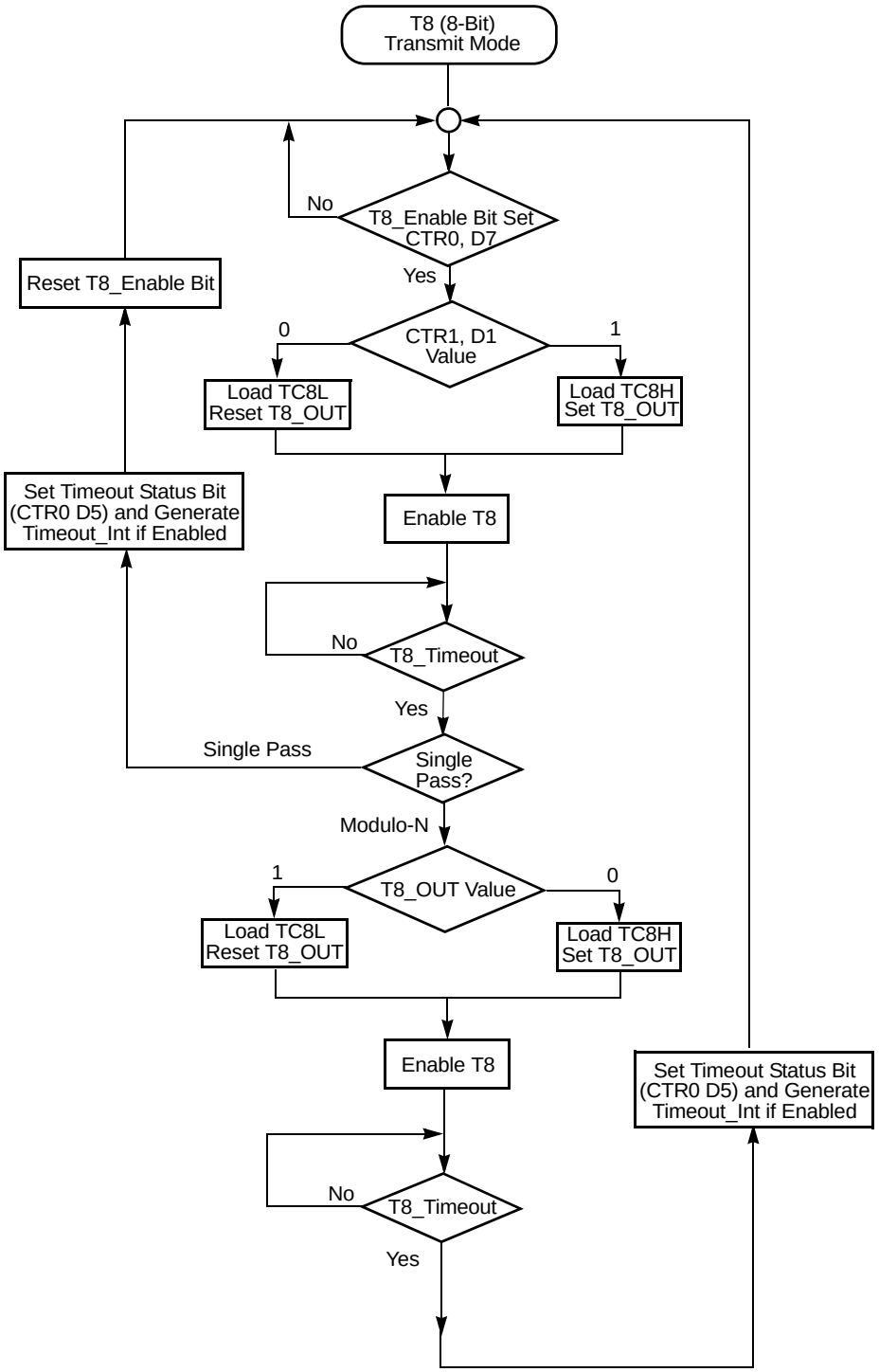


Figure 19. Transmit Mode Flowchart

When T8 is enabled, the output T8_OUT switches to the initial value (CTR1, D1). If the initial value (CTR1, D1) is 0, TC8L is loaded; otherwise, TC8H is loaded into the counter. In SINGLE-PASS Mode (CTR0, D6), T8 counts down to 0 and stops, T8_OUT toggles, the timeout status bit (CTR0, D5) is set, and a timeout interrupt can be generated if it is enabled (CTR0, D1). In Modulo-N Mode, upon reaching terminal count, T8_OUT is toggled, but no interrupt is generated. From that point, T8 loads a new count (if the T8_OUT level now is 0), TC8L is loaded; if it is 1, TC8H is loaded. T8 counts down to 0, toggles T8_OUT, and sets the timeout status bit (CTR0, D5), thereby generating an interrupt if enabled (CTR0, D1). One cycle is thus completed. T8 then loads from TC8H or TC8L according to the T8_OUT level and repeats the cycle. See Figure 20.

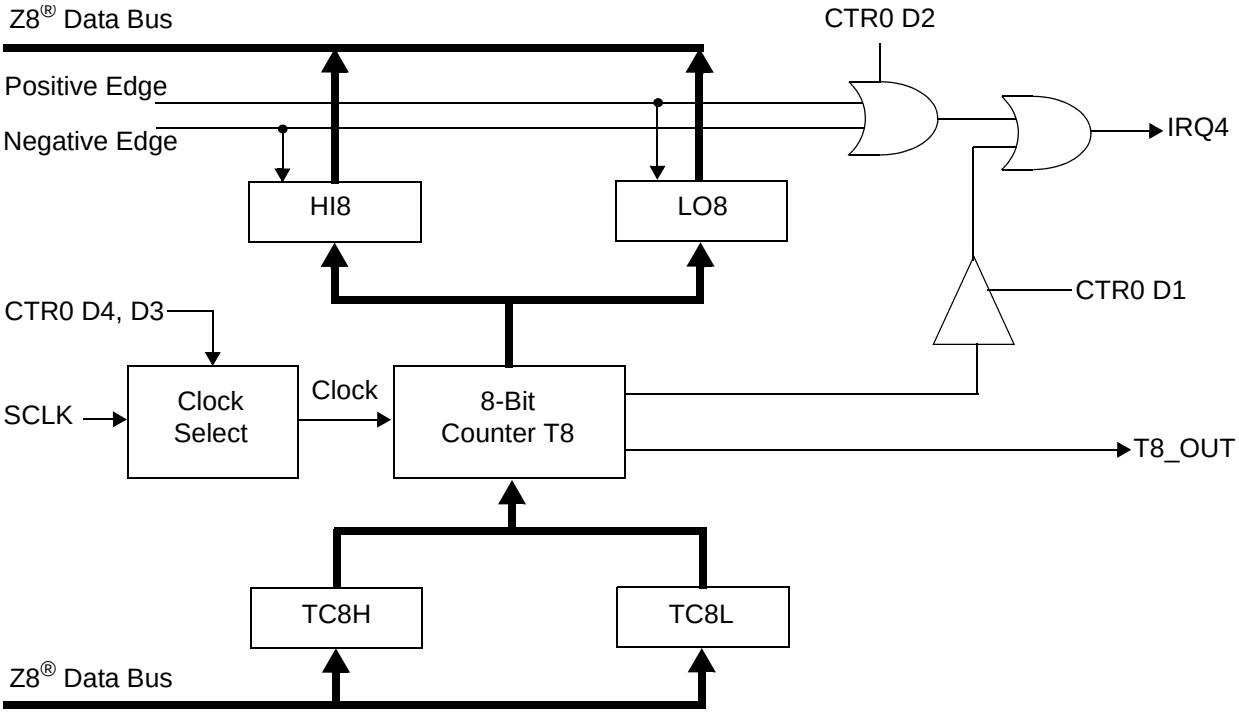


Figure 20. 8-Bit Counter/Timer Circuits

You can modify the values in TC8H or TC8L at any time. The new values take effect when they are loaded.

Caution: To ensure known operation do not write these registers at the time the values are to be loaded into the counter/timer. *An initial count of 1 is not allowed (a non-function occurs).* An initial count of 0 causes TC8 to count from 0 to FFH to FEH.

Note: The letter h denotes hexadecimal values.

Transition from 0 to FFh is not a timeout condition.

Caution: Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur. See Figure 21 and Figure 22.

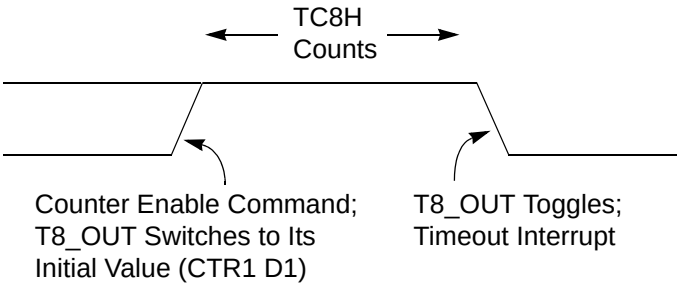


Figure 21. T8_OUT in Single-Pass Mode

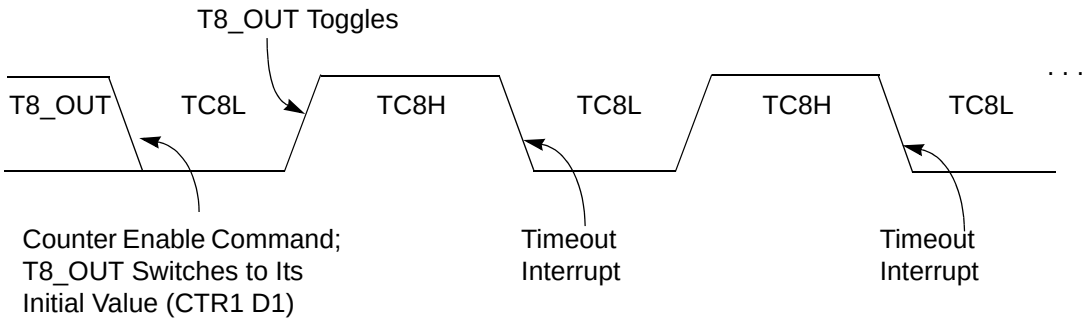


Figure 22. T8_OUT in Modulo-N Mode

T8 Demodulation Mode

The user must program TC8L and TC8H to FFH. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put

T16 Transmit Mode

In NORMAL or PING-PONG mode, the output of T16 when not enabled, is dependent on CTR1, D0. If it is a 0, T16_OUT is a 1; if it is a 1, T16_OUT is 0. You can force the output of T16 to either a 0 or 1 whether it is enabled or not by programming CTR1 D3; D2 to a 10 or 11.

When T16 is enabled, TC16H * 256 + TC16L is loaded, and T16_OUT is switched to its initial value (CTR1, D0). When T16 counts down to 0, T16_OUT is toggled (in NORMAL or PING-PONG mode), an interrupt (CTR2, D1) is generated (if enabled), and a status bit (CTR2, D5) is set. See Figure 25.

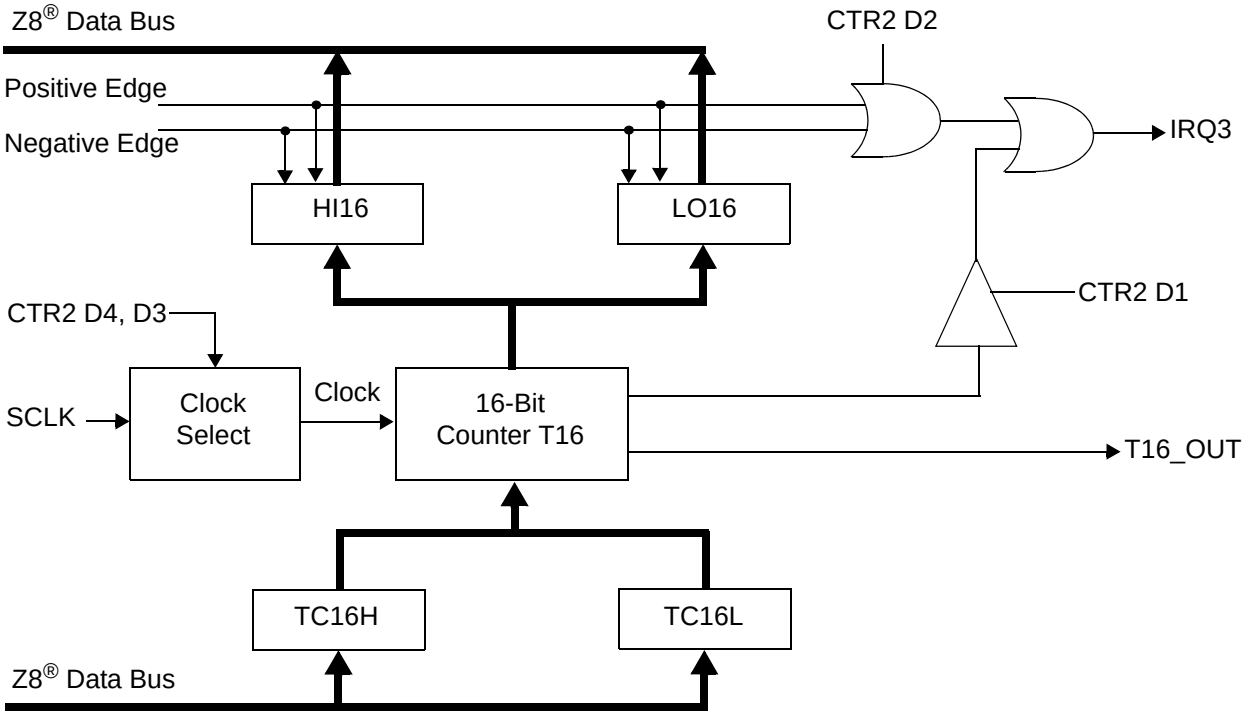


Figure 25. 16-Bit Counter/Timer Circuits

Note: Global interrupts override this function as described in "Interrupts" on page 50.

If T16 is in SINGLE-PASS mode, it is stopped at this point (see Figure 26). If it is in Modulo-N Mode, it is loaded with TC16H * 256 + TC16L, and the counting continues (see Figure 27).

You can modify the values in TC16H and TC16L at any time. The new values take effect when they are loaded.

Power-On Reset

A timer circuit clocked by a dedicated on-board RC-oscillator is used for the Power-On Reset (POR) timer function. The POR time allows V_{DD} and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- Power Fail to Power OK status, including Waking up from V_{BO} Standby
- Stop-Mode Recovery (if D5 of SMR = 1)
- WDT Timeout

The POR timer is 2.5 ms minimum. Bit 5 of the Stop-Mode Register determines whether the POR timer is bypassed after Stop-Mode Recovery (typical for external clock).

HALT Mode

This instruction turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2, IRQ3, IRQ4, and IRQ5 remain active. The devices are recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after HALT Mode.

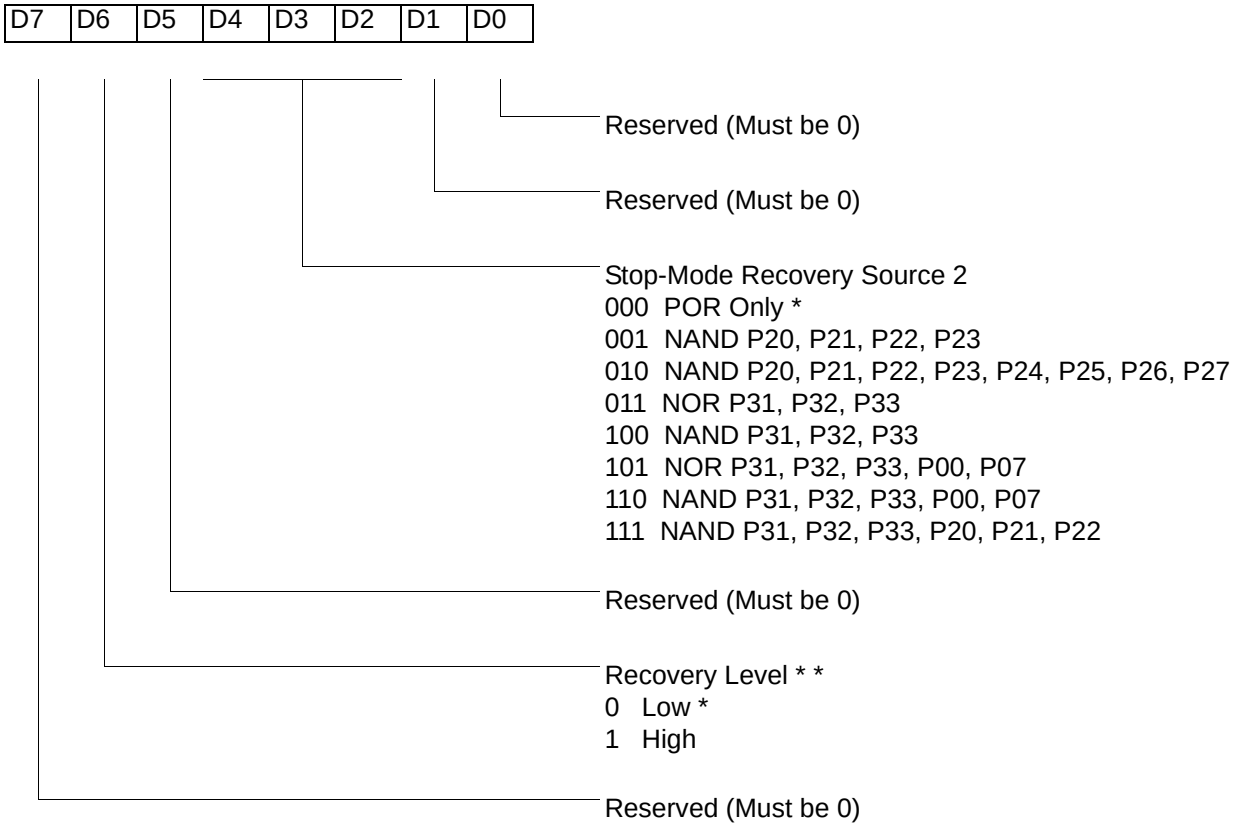
STOP Mode

This instruction turns off the internal clock and external crystal oscillation, reducing the standby current to 10 μA or less. STOP Mode is terminated only by a reset, such as WDT timeout, POR, SMR or external reset. This condition causes the processor to restart the application program at address 000CH. To enter STOP (or HALT) mode, first flush the instruction pipeline to avoid suspending execution in mid-instruction. Execute a NOP (Opcode = FFH) immediately before the appropriate sleep instruction, as follows:

Stop Mode Recovery Register 2 (SMR2)

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 36).

SMR2(0F)DH



Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.
* Default setting after reset
* * At the XOR gate input

Figure 36. Stop Mode Recovery Register 2 ((0F)DH:D2–D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.

Note: Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.

Low-Voltage Detection Register—LVD(D)0Ch

Note: Voltage detection does not work at Stop mode. It must be disabled during Stop mode in order to reduce current.

Field	Bit Position			Description
LVD	76543---			Reserved No Effect
	-----2--	R	1 0*	HVD flag set HVD flag reset
	------1-	R	1 0*	LVD flag set LVD flag reset
	-------0	R/W	1 0*	Enable VD Disable VD

***Default after POR

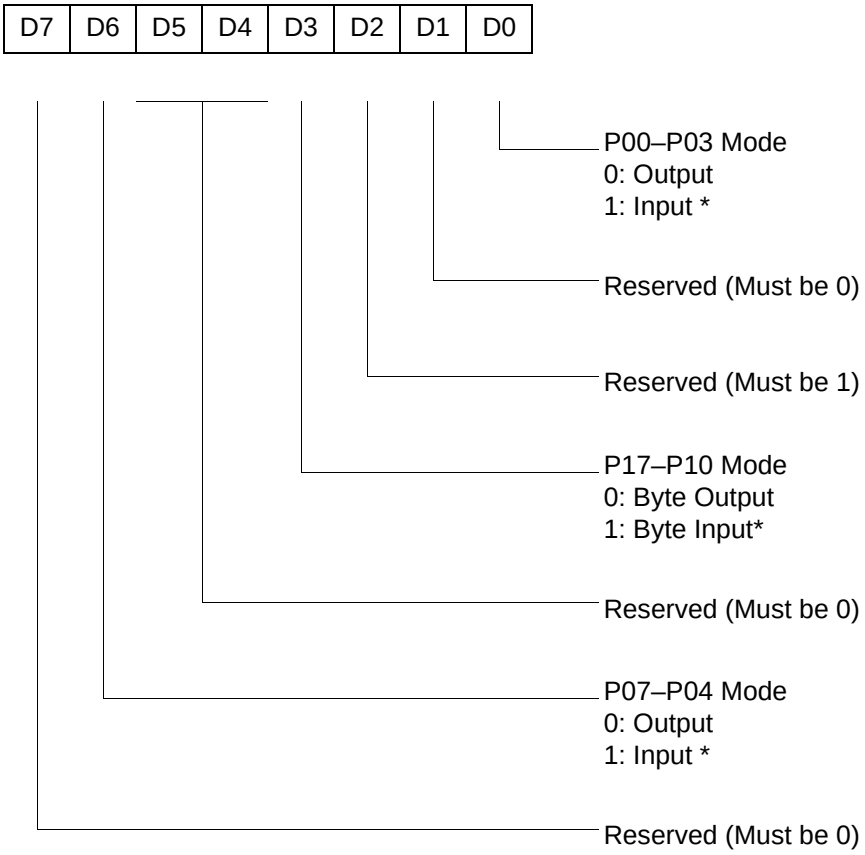
Note: Do not modify register P01M while checking a low-voltage condition. Switching noise of both ports 0 and 1 together might trigger the LVD flag.

Voltage Detection and Flags

The Voltage Detection register (LVD, register 0CH at the expanded register bank 0Dh) offers an option of monitoring the V_{CC} voltage. The Voltage Detection is enabled when bit 0 of LVD register is set. Once Voltage Detection is enabled, the the V_{CC} level is monitored in real time. The flags in the LVD register valid 20uS after Voltage Detection is enabled. The HVD flag (bit 2 of the LVD register) is set only if V_{CC} is higher than $V_{HVD.}$ The LVD flag (bit 1 of the LVD register) is set only if V_{CC} is lower than the V_{LVD}. When Voltage Detection is enabled, the LVD flag also triggers IRQ5. The IRQ bit 5 latches the low voltage condition until it is cleared by instructions or reset. The IRQ5 interrupt is served if it is enabled in the IMR register. Otherwise, bit 5 of IRQ register is latched as a flag only.

Notes: If it is necessary to receive an LVD interrupt upon power-up at an operating voltage lower than the low battery detect threshold, enable interrupts using the Enable Interrupt instruction (EI) prior to enabling the voltage detection.

R248 P01M(F8H)



* Default setting after reset; only P00, P01 and P07 are available on 20-pin configurations.

Figure 50. Port 0 and 1 Mode Register (F8H: Write Only)

8KB Standard Temperature: 0° to +70°C			
Part Number	**Description**	**Part Number**	**Description**
ZGP323HSH4808C	48-pin SSOP 8K OTP	ZGP323HSS2808C	28-pin SOIC 8K OTP
ZGP323HSP4008C	40-pin PDIP 8K OTP	ZGP323HSH2008C	20-pin SSOP 8K OTP
ZGP323HSH2808C	28-pin SSOP 8K OTP	ZGP323HSP2008C	20-pin PDIP 8K OTP
ZGP323HSP2808C	28-pin PDIP 8K OTP	ZGP323HSS2008C	20-pin SOIC 8K OTP

8KB Extended Temperature: -40° to +105°C			
Part Number	**Description**	**Part Number**	**Description**
ZGP323HEH4808C	48-pin SSOP 8K OTP	ZGP323HES2808C	28-pin SOIC 8K OTP
ZGP323HEP4008C	40-pin PDIP 8K OTP	ZGP323HEH2008C	20-pin SSOP 8K OTP
ZGP323HEH2808C	28-pin SSOP 8K OTP	ZGP323HEP2008C	20-pin PDIP 8K OTP
ZGP323HEP2808C	28-pin PDIP 8K OTP	ZGP323HES2008C	20-pin SOIC 8K OTP

8KB Automotive Temperature: -40° to +125°C			
Part Number	**Description**	**Part Number**	**Description**
ZGP323HAH4808C	48-pin SSOP 8K OTP	ZGP323HAS2808C	28-pin SOIC 8K OTP
ZGP323HAP4008C	40-pin PDIP 8K OTP	ZGP323HAH2008C	20-pin SSOP 8K OTP
ZGP323HAH2808C	28-pin SSOP 8K OTP	ZGP323HAP2008C	20-pin PDIP 8K OTP
ZGP323HAP2808C	28-pin PDIP 8K OTP	ZGP323HAS2008C	20-pin SOIC 8K OTP
Replace C with G for Lead-Free Packaging			