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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LVD, POR, PWM, WDT
Number of I/O	21
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 10x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128ga202-e-so">https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128ga202-e-so</a>

# PIC24FJ128GA204 FAMILY

## 3.3 Arithmetic Logic Unit (ALU)

The PIC24F ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are 2's complement in nature. Depending on the operation, the ALU may affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array, or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

The PIC24F CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

### 3.3.1 MULTIPLIER

The ALU contains a high-speed, 17-bit x 17-bit multiplier. It supports unsigned, signed or mixed sign operation in several multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

### 3.3.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. The 16-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor (Wn), and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

### 3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided in [Table 3-2](#).

**TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE BIT AND MULTI-BIT SHIFT OPERATION**

Instruction	Description
ASR	Arithmetic Shift Right Source register by one or more bits.
SL	Shift Left Source register by one or more bits.
LSR	Logical Shift Right Source register by one or more bits.

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## 4.0 MEMORY ORGANIZATION

As Harvard architecture devices, PIC24F microcontrollers feature separate program and data memory spaces and buses. This architecture also allows direct access of program memory from the Data Space (DS) during code execution.

### 4.1 Program Memory Space

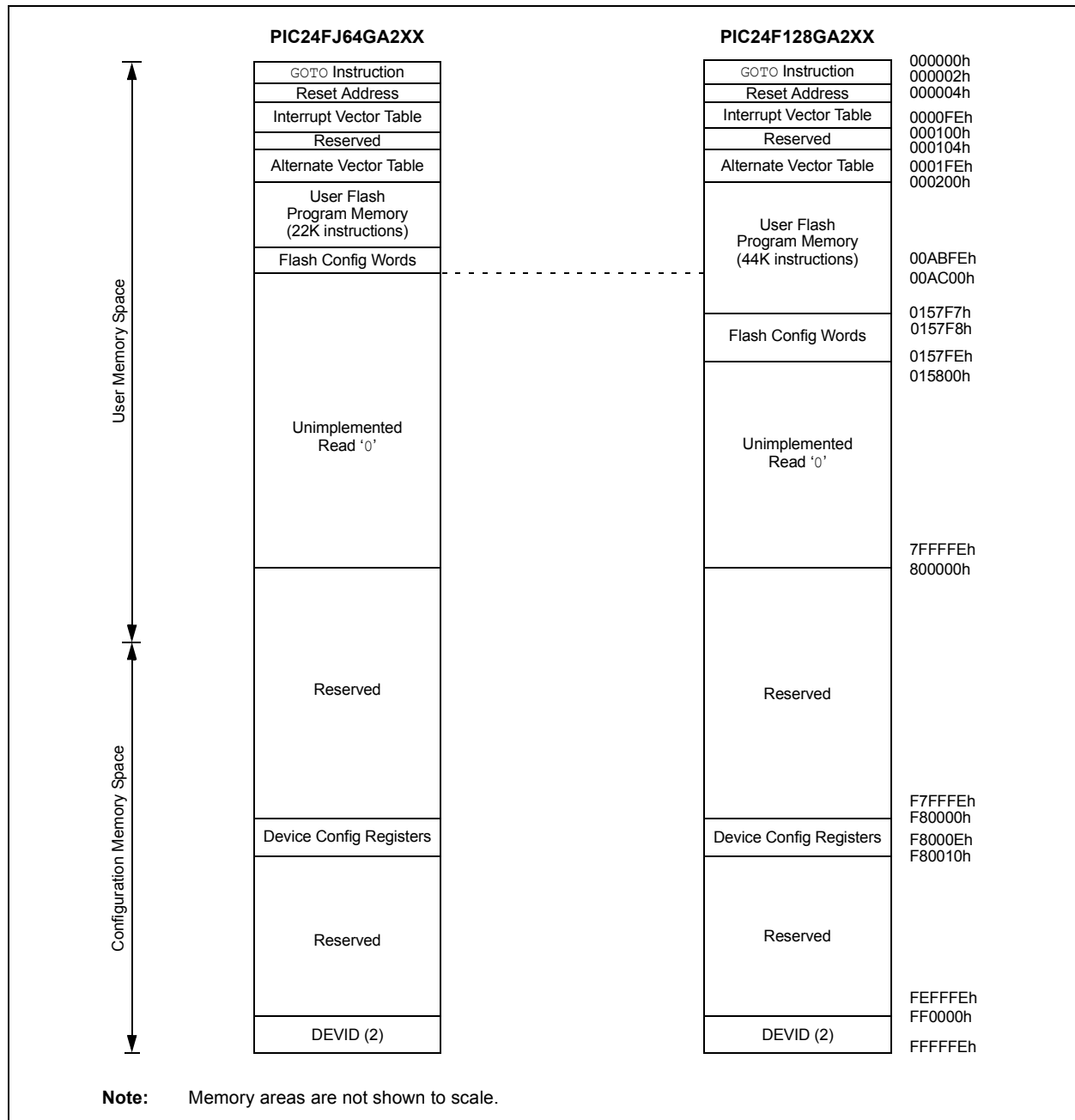
The program address memory space of the PIC24FJ128GA204 family devices is 4M instructions. The space is addressable by a 24-bit value derived

from either the 23-bit Program Counter (PC) during program execution, or from table operation or Data Space remapping, as described in [Section 4.3 “Interfacing Program and Data Memory Spaces”](#).

User access to the program memory space is restricted to the lower half of the address range (000000h to 7FFFFFFh). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

Memory maps for the PIC24FJ128GA204 family of devices are shown in [Figure 4-1](#).

**FIGURE 4-1: PROGRAM SPACE MEMORY MAP FOR PIC24FJ128GA204 FAMILY DEVICES**



**TABLE 4-23: REAL-TIME CLOCK AND CALENDAR (RTCC) REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ALRMVAL	011E	Alarm Value Register Window Based on ALRMPTR<1:0>																xxxx
ALCFGRPT	0120	ALRMEN	CHIME	AMASK3	AMASK2	AMASK1	AMASK0	ALRMPTR1	ALRMPTR0	ARPT7	ARPT6	ARPT5	ARPT4	ARPT3	ARPT2	ARPT1	ARPT0	0000
RTCVAL	0122	RTCC Value Register Window Based on RTCPTR<1:0>																xxxx
RCFGCAL	0124	RTCEN	—	RTCWREN	RTCSYNC	HALFSEC	RTCOE	RTCPTR1	RTCPTR0	CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	Note 1
RTCPWC	0126	PWCEN	PWCPOL	PWCPRE	PWSPRE	RTCLK1	RTCLK0	RTCOUT1	RTCOUT0	—	—	—	—	—	—	—	—	Note 1

**Legend:** — = unimplemented, read as '0'; x = unknown value on Reset. Reset values are shown in hexadecimal.

**Note 1:** The status of the RCFGCAL and RTCPWC registers on POR is '0000' and on other Resets, it is unchanged.

**TABLE 4-24: DATA SIGNAL MODULATOR (DSM) REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
MDCON	02FA	MDEN	—	MDSIDL	—	—	—	—	—	—	MDOE	MDSLRL	MDOPOL	—	—	—	MDBIT	0020
MDSRC	02FC	—	—	—	—	—	—	—	—	SODIS	—	—	—	MS3	MS2	MS1	MS0	0000
MDCAR	02FE	CHODIS	CHPOL	CHSYNC	—	CH3	CH2	CH1	CH0	CLODIS	CLPOL	CLSYNC	—	CL3	CL2	CL1	CL0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-25: COMPARATOR REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CMSTAT	0242	CMIDL	—	—	—	—	C3EVT	C2EVT	C1EVT	—	—	—	—	—	C3OUT	C2OUT	C1OUT	0000
CVRCON	0244	—	—	—	—	—	CVREFP	CVREFM1	CVREFM0	CVREN	CVROE	CVRSS	CVR4	CVR3	CVR2	CVR1	CVR0	0000
CM1CON	0246	CON	COE	CPOL	—	—	—	CEVT	COUT	EVPOL1	EVPOL0	—	CREF	—	—	CCH1	CCH0	0000
CM2CON	0248	CON	COE	CPOL	—	—	—	CEVT	COUT	EVPOL1	EVPOL0	—	CREF	—	—	CCH1	CCH0	0000
CM3CON	024A	CON	COE	CPOL	—	—	—	CEVT	COUT	EVPOL1	EVPOL0	—	CREF	—	—	CCH1	CCH0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-29: DEEP SLEEP REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DSCON	010E	DSSEN	—	—	—	—	—	—	—	—	—	—	—	—	r	DSBOR	RELEASE	0000 <sup>(1)</sup>
DSWAKE	0110	—	—	—	—	—	—	—	DSINT0	DSFLT	—	—	DSWD	DSRTCC	DSMCLR	—	—	0000 <sup>(1)</sup>
DSGPR0	0112	Deep Sleep Semaphore Data 0 Register																0000 <sup>(1)</sup>
DSGPR1	0114	Deep Sleep Semaphore Data 1 Register																0000 <sup>(1)</sup>

**Legend:** — = unimplemented, read as '0'; r = reserved. Reset values are shown in hexadecimal.

**Note 1:** These registers are only reset on a VDD POR event.

**TABLE 4-30: CRYPTOGRAPHIC ENGINE REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CRYCONL	01A4	CRYON	—	CRYSIDL	ROLLIE	DONEIE	FREEIE	—	CRYGO	OPMOD3	OPMOD2	OPMOD1	OPMOD0	CPHRSEL	CPHRMOD2	CPHRMOD1	CPHRMOD0	0000
CRYCONH	01A6	—	CTRSIZE6	CTRSIZE5	CTRSIZE4	CTRSIZE3	CTRSIZE2	CTRSIZE1	CTRSIZE0	SKEYSEL	KEYMOD1	KEYMOD0	—	KEYSRC3	KEYSRC2	KEYSRC1	KEYSRC0	0000
CRYSTAT	01A8	—	—	—	—	—	—	—	—	CRYBSY	TXTABSY	CRYABRT	ROLLOVR	—	MODFAIL	KEYFAIL	PGMFAIL	0000
CRYOTP	01AC	—	—	—	—	—	—	—	—	PGMTST	OTPIE	CRYREAD	KEYPG3	KEYPG2	KEYPG1	KEYPG0	CRYWR	0020
CRYTXTA	01B0	Cryptographic Text Register A (128 bits wide)																xxxx
CRYKEY	01C0	Cryptographic Key Register (256 bits wide, write-only)																xxxx
CRYTXTB	01E0	Cryptographic Text Register B (128 bits wide)																xxxx
CRYTXTC	01F0	Cryptographic Text Register C (128 bits wide)																xxxx

**Legend:** — = unimplemented, read as '0'; x = unknown value on Reset. Reset values are shown in hexadecimal.

**TABLE 4-31: NVM REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	—	—	—	—	—	—	ERASE	—	—	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000 <sup>(1)</sup>
NVMKEY	0766	—	—	—	—	—	—	—	—	—	NVMKEY Register<7:0>							0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** The Reset value shown is for POR only. The value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.









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If a  $\overline{\text{MCLR}}$  Reset event occurs during Deep Sleep, the DSGPRx, DSCON and DSWAKE registers will remain valid, and the RELEASE bit will remain set. The state of the SOSC will also be retained. The I/O pins, however, will be reset to their MCLR Reset state. Since RELEASE is still set, changes to the SOSCEN bit (OSCCON<1>) cannot take effect until the RELEASE bit is cleared.

In all other Deep Sleep wake-up cases, application firmware must clear the RELEASE bit in order to reconfigure the I/O pins.

## 10.4.5 DEEP SLEEP WDT

To enable the DSWDT in Deep Sleep mode, program the Configuration bit, DSWDTEN (CW4<7>). The device WDT need not be enabled for the DSWDT to function. Entry into Deep Sleep modes automatically resets the DSWDT.

The DSWDT clock source is selected by the DSWDTOSC Configuration bit (CW4<5>). The postscaler options are programmed by the DSWDTPS<4:0> Configuration bits (CW4<4:0>). The minimum time-out period that can be achieved is 1 ms and the maximum is 25.7 days. For more information on the CW4 Configuration register and DSWDT configuration options, refer to [Section 29.0 “Special Features”](#).

### 10.4.5.1 Switching Clocks in Deep Sleep Mode

Both the RTCC and the DSWDT may run from either SOSC or the LPRC clock source. This allows both the RTCC and DSWDT to run without requiring both the LPRC and SOSC to be enabled together, reducing power consumption.

Running the RTCC from LPRC will result in a loss of accuracy in the RTCC of approximately 5 to 10%. If a more accurate RTCC is required, it must be run from the SOSC clock source. The RTCC clock source is selected with the RTCLK<1:0> bits (RTCPWC<11:10>).

Under certain circumstances, it is possible for the DSWDT clock source to be off when entering Deep Sleep mode. In this case, the clock source is turned on automatically (if DSWDT is enabled), without the need for software intervention. However, this can cause a delay in the start of the DSWDT counters. In order to avoid this delay when using SOSC as a clock source, the application can activate SOSC prior to entering Deep Sleep mode.

## 10.4.6 CHECKING AND CLEARING THE STATUS OF DEEP SLEEP

Upon entry into Deep Sleep mode, the status bit, DPSLP (RCON<10>), becomes set and must be cleared by the software.

On power-up, the software should read this status bit to determine if the Reset was due to an exit from Deep Sleep mode and clear the bit if it is set. Of the four possible combinations of DPSLP and POR bit states, the following three cases can be considered:

- Both the DPSLP and POR bits are cleared. In this case, the Reset was due to some event other than a Deep Sleep mode exit.
- The DPSLP bit is clear, but the POR bit is set; this is a normal Power-on Reset.
- Both the DPSLP and POR bits are set. This means that Deep Sleep mode was entered, the device was powered down and Deep Sleep mode was exited.

## 10.4.7 POWER-ON RESETS (PORs)

VDD voltage is monitored to produce PORs. Since exiting from Deep Sleep mode functionally looks like a POR, the technique described in [Section 10.4.6 “Checking and Clearing the Status of Deep Sleep”](#) should be used to distinguish between Deep Sleep and a true POR event. When a true POR occurs, the entire device, including all Deep Sleep logic (Deep Sleep registers, RTCC, DSWDT, etc.) is reset.

## 10.5 VBAT Mode

This mode represents the lowest power state that the microcontroller can achieve and still resume operation. VBAT mode is automatically triggered when the microcontroller's main power supply on VDD fails. When this happens, the microcontroller's on-chip power switch connects to a backup power source, such as a battery, supplied to the VBAT pin. This maintains a few key systems at an extremely low-power draw until VDD is restored.

The power supplied on VBAT only runs two systems: the RTCC and the Deep Sleep Semaphore registers (DSGPR0 and DSGPR1). To maintain these systems during a sudden loss of VDD, it is essential to connect a power source, other than VDD or AVDD, to the VBAT pin.

When the RTCC is enabled, it continues to operate with the same clock source (SOSC or LPRC) that was selected prior to entering VBAT mode. There is no provision to switch to a lower power clock source after the mode switch.

Since the loss of VDD is usually an unforeseen event, it is recommended that the contents of the Deep Sleep Semaphore registers be loaded with the data to be retained at an early point in code execution.

### 10.5.1 VBAT MODE WITH NO RTCC

By disabling RTCC operation during VBAT mode, power consumption is reduced to the lowest of all power-saving modes. In this mode, only the Deep Sleep Semaphore registers are maintained.

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## REGISTER 11-18: RPINR27: PERIPHERAL PIN SELECT INPUT REGISTER 27

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U4CTSR5	U4CTSR4	U4CTSR3	U4CTSR2	U4CTSR1	U4CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U4RXR5	U4RXR4	U4RXR3	U4RXR2	U4RXR1	U4RXR0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'  
 bit 13-8      **U4CTSR<5:0>:** Assign UART4 Clear-to-Send Input ( $\overline{\text{U4CTS}}$ ) to Corresponding RPn or RPIn Pin bits  
 bit 7-6      **Unimplemented:** Read as '0'  
 bit 5-0      **U4RXR<5:0>:** Assign UART4 Receive Input (U4RX) to Corresponding RPn or RPIn Pin bits

## REGISTER 11-19: RPINR28: PERIPHERAL PIN SELECT INPUT REGISTER 28

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK3R5	SCK3R4	SCK3R3	SCK3R2	SCK3R1	SCK3R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI3R5	SDI3R4	SDI3R3	SDI3R2	SDI3R1	SDI3R0
bit 7							bit 0

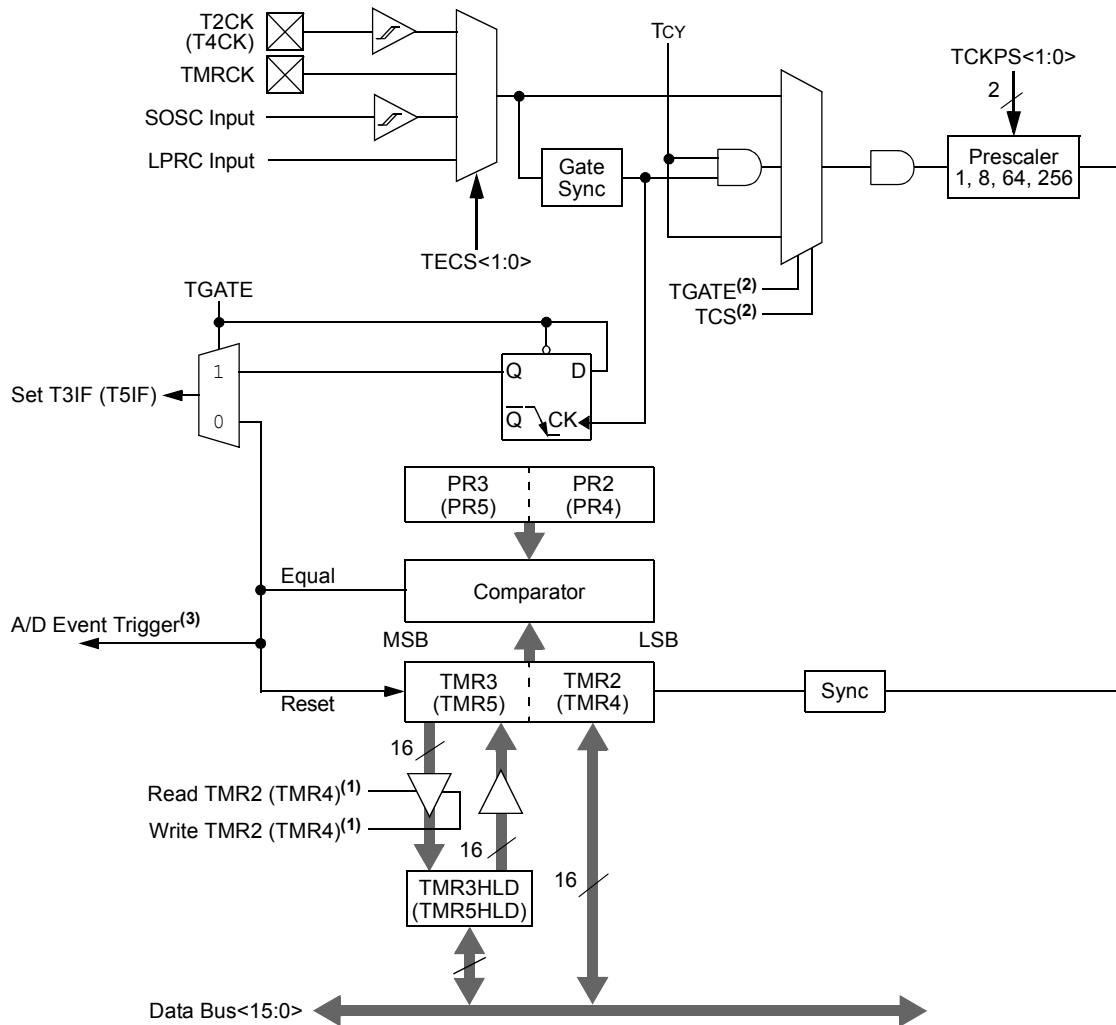
### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'  
 bit 13-8      **SCK3R<5:0>:** Assign SPI3 Clock Input (SCK3IN) to Corresponding RPn or RPIn Pin bits  
 bit 7-6      **Unimplemented:** Read as '0'  
 bit 5-0      **SDI3R<5:0>:** Assign SPI3 Data Input (SDI3) to Corresponding RPn or RPIn Pin bits

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- Note**
- 1: The 32-Bit Timer Configuration bit, T32, must be set for 32-bit timer/counter operation. All control bits are respective to the T2CON and T4CON registers.
  - 2: The timer clock input must be assigned to an available RPN/RPIn pin before use. See [Section 11.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
  - 3: The A/D Event Trigger is available only on Timer2/3 in 32-bit mode and Timer3 in 16-bit mode.

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## REGISTER 14-1: ICxCON1: INPUT CAPTURE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—
bit 15						bit 8	

U-0	R/W-0	R/W-0	R-0, HSC	R-0, HSC	R/W-0	R/W-0	R/W-0
—	ICI1	ICI0	ICOV	ICBNE	ICM2 <sup>(1)</sup>	ICM1 <sup>(1)</sup>	ICM0 <sup>(1)</sup>
bit 7						bit 0	

<b>Legend:</b>	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **ICSIDL:** Input Capture x Module Stop in Idle Control bit  
 1 = Input capture module halts in CPU Idle mode  
 0 = Input capture module continues to operate in CPU Idle mode

bit 12-10 **ICTSEL<2:0>:** Input Capture x Timer Select bits  
 111 = System clock (FOSC/2)  
 110 = Reserved  
 101 = Reserved  
 100 = Timer1  
 011 = Timer5  
 010 = Timer4  
 001 = Timer2  
 000 = Timer3

bit 9-7 **Unimplemented:** Read as '0'

bit 6-5 **ICI<1:0>:** Select Number of Captures per Interrupt bits  
 11 = Interrupt on every fourth capture event  
 10 = Interrupt on every third capture event  
 01 = Interrupt on every second capture event  
 00 = Interrupt on every capture event

bit 4 **ICOV:** Input Capture x Overflow Status Flag bit (read-only)  
 1 = Input capture overflow has occurred  
 0 = No input capture overflow has occurred

bit 3 **ICBNE:** Input Capture x Buffer Empty Status bit (read-only)  
 1 = Input capture buffer is not empty, at least one more capture value can be read  
 0 = Input capture buffer is empty

bit 2-0 **ICM<2:0>:** Input Capture x Mode Select bits<sup>(1)</sup>  
 111 = Interrupt mode: Input capture functions as an interrupt pin only when the device is in Sleep or Idle mode (rising edge detect only, all other control bits are not applicable)  
 110 = Unused (module is disabled)  
 101 = Prescaler Capture mode: Capture on every 16<sup>th</sup> rising edge  
 100 = Prescaler Capture mode: Capture on every 4<sup>th</sup> rising edge  
 011 = Simple Capture mode: Capture on every rising edge  
 010 = Simple Capture mode: Capture on every falling edge  
 001 = Edge Detect Capture mode: Capture on every edge (rising and falling); ICI<1:0> bits do not control interrupt generation for this mode  
 000 = Input capture module is turned off

**Note 1:** The ICx input must also be configured to an available RPN/RPIn pin. For more information, see [Section 11.4 "Peripheral Pin Select \(PPS\)"](#).

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## REGISTER 15-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
FLTMD	FLTOUT	FLTTRIEN	OCINV	—	DCB1 <sup>(3)</sup>	DCB0 <sup>(3)</sup>	OC32
bit 15						bit 8	

R/W-0	R/W-0, HS	R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0
OCTRIG	TRIGSTAT	OCTRIIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0
bit 7						bit 0	

<b>Legend:</b>	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **FLTMD:** Fault Mode Select bit  
1 = Fault mode is maintained until the Fault source is removed and the corresponding OCFLT0 bit is cleared in software  
0 = Fault mode is maintained until the Fault source is removed and a new PWM period starts
- bit 14      **FLTOUT:** Fault Out bit  
1 = PWM output is driven high on a Fault  
0 = PWM output is driven low on a Fault
- bit 13      **FLTTRIEN:** Fault Output State Select bit  
1 = Pin is forced to an output on a Fault condition  
0 = Pin I/O condition is unaffected by a Fault
- bit 12      **OCINV:** Output Compare x Invert bit  
1 = OCx output is inverted  
0 = OCx output is not inverted
- bit 11      **Unimplemented:** Read as '0'
- bit 10-9    **DCB<1:0>:** PWM Duty Cycle Least Significant bits<sup>(3)</sup>  
11 = Delays OCx falling edge by ¾ of the instruction cycle  
10 = Delays OCx falling edge by ½ of the instruction cycle  
01 = Delays OCx falling edge by ¼ of the instruction cycle  
00 = OCx falling edge occurs at the start of the instruction cycle
- bit 8      **OC32:** Cascade Two Output Compare Modules Enable bit (32-bit operation)  
1 = Cascade module operation is enabled  
0 = Cascade module operation is disabled
- bit 7      **OCTRIG:** Output Compare x Trigger/Sync Select bit  
1 = Triggers OCx from the source designated by the SYNCSELx bits  
0 = Synchronizes OCx with the source designated by the SYNCSELx bits
- bit 6      **TRIGSTAT:** Timer Trigger Status bit  
1 = Timer source has been triggered and is running  
0 = Timer source has not been triggered and is being held clear
- bit 5      **OCTRIIS:** Output Compare x Output Pin Direction Select bit  
1 = OCx pin is tri-stated  
0 = Output Compare Peripheral x is connected to an OCx pin

- Note 1:** Never use an OCx module as its own trigger source, either by selecting this mode or another equivalent SYNCSELx setting.
- 2:** Use these inputs as trigger sources only and never as sync sources.
- 3:** The DCB<1:0> bits are double-buffered in PWM modes only (OCM<2:0> (OCxCON1<2:0>) = 111, 110).

# PIC24FJ128GA204 FAMILY

## REGISTER 17-1: I2CxCONL: I2Cx CONTROL REGISTER LOW

R/W-0	U-0	R/W-0, HC	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL <sup>(1)</sup>	STRICT	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **I2CEN:** I2Cx Enable bit (writable from SW only)  
 1 = Enables the I2Cx module, and configures the SDAx and SCLx pins as serial port pins  
 0 = Disables the I2Cx module; all I<sup>2</sup>C™ pins are controlled by port functions
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **I2CSIDL:** I2Cx Stop in Idle Mode bit  
 1 = Discontinues module operation when device enters Idle mode  
 0 = Continues module operation in Idle mode
- bit 12 **SCLREL:** SCLx Release Control bit (I<sup>2</sup>C Slave mode only)<sup>(1)</sup>  
 Module resets and (I2CEN = 0) sets SCLREL = 1.  
If STREN = 0:<sup>(2)</sup>  
 1 = Releases clock  
 0 = Forces clock low (clock stretch)  
If STREN = 1:  
 1 = Releases clock  
 0 = Holds clock low (clock stretch); user may program this bit to '0'; clock stretch is at the next SCLx low
- bit 11 **STRICT:** I2Cx Strict Reserved Address Rule Enable bit  
 1 = Strict reserved addressing is enforced; for reserved addresses, refer to [Table 17-1](#).  
 (In Slave Mode) – The device doesn't respond to reserved address space and addresses falling in that category are NACKed.  
 (In Master Mode) – The device is allowed to generate addresses with reserved address space.  
 0 = Reserved addressing would be Acknowledged.  
 (In Slave Mode) – The device will respond to an address falling in the reserved address space. When there is a match with any of the reserved addresses, the device will generate an ACK.  
 (In Master Mode) – Reserved.
- bit 10 **A10M:** 10-Bit Slave Address Flag bit  
 1 = I2CxADD is a 10-bit slave address  
 0 = I2CADD is a 7-bit slave address
- bit 9 **DISSLW:** Slew Rate Control Disable bit  
 1 = Slew rate control is disabled for Standard Speed mode (100 kHz, also disabled for 1 MHz mode)  
 0 = Slew rate control is enabled for High-Speed mode (400 kHz)
- bit 8 **SMEN:** SMBus Input Levels Enable bit  
 1 = Enables input logic so thresholds are compliant with the SMBus specification  
 0 = Disables SMBus-specific inputs

**Note 1:** Automatically cleared to '0' at the beginning of slave transmission; automatically cleared to '0' at the end of slave reception.

**2:** Automatically cleared to '0' at the beginning of slave transmission.

# PIC24FJ128GA204 FAMILY

## REGISTER 17-1: I2CxCONL: I2Cx CONTROL REGISTER LOW (CONTINUED)

- bit 7      **GCEN:** General Call Enable bit (I<sup>2</sup>C Slave mode only)  
1 = Enables interrupt when a general call address is received in I2CxRSR; module is enabled for reception  
0 = General call address is disabled
- bit 6      **STREN:** SCLx Clock Stretch Enable bit  
In I<sup>2</sup>C Slave mode only; used in conjunction with the SCLREL bit.  
1 = Enables clock stretching  
0 = Disables clock stretching
- bit 5      **ACKDT:** Acknowledge Data bit  
In I<sup>2</sup>C Master mode during Master Receive mode. The value that will be transmitted when the user initiates an Acknowledge sequence at the end of a receive.  
In I<sup>2</sup>C Slave mode when AHEN = 1 or DHEN = 1. The value that the slave will transmit when it initiates an Acknowledge sequence at the end of an address or data reception.  
1 = A NACK is sent  
0 = ACK is sent
- bit 4      **ACKEN:** Acknowledge Sequence Enable bit  
In I<sup>2</sup>C Master mode only; applicable during Master Receive mode.  
1 = Initiates Acknowledge sequence on SDAx and SCLx pins, and transmits ACKDT data bit  
0 = Acknowledge sequence is Idle
- bit 3      **RCEN:** Receive Enable bit (I<sup>2</sup>C Master mode only)  
1 = Enables Receive mode for I<sup>2</sup>C; automatically cleared by hardware at the end of an 8-bit receive data byte  
0 = Receive sequence is not in progress
- bit 2      **PEN:** Stop Condition Enable bit (I<sup>2</sup>C Master mode only)  
1 = Initiates Stop condition on SDAx and SCLx pins  
0 = Stop condition is Idle
- bit 1      **RSEN:** Restart Condition Enable bit (I<sup>2</sup>C Master mode only)  
1 = Initiates Restart condition on the SDAx and SCLx pins  
0 = Restart condition is Idle
- bit 0      **SEN:** Start Condition Enable bit (I<sup>2</sup>C Master mode only)  
1 = Initiates Start condition on the SDAx and SCLx pins  
0 = Start condition is Idle

- Note 1:** Automatically cleared to '0' at the beginning of slave transmission; automatically cleared to '0' at the end of slave reception.
- 2:** Automatically cleared to '0' at the beginning of slave transmission.

# PIC24FJ128GA204 FAMILY

## REGISTER 17-2: I2CxCONH: I2Cx CONTROL REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	PCIE	SCIE	BOEN	SDAHT	SBCDE	AHEN	DHEN
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6 **PCIE:** Stop Condition Interrupt Enable bit (I<sup>2</sup>C™ Slave mode only).

1 = Enables interrupt on detection of Stop condition

0 = Stop detection interrupts are disabled

bit 5 **SCIE:** Start Condition Interrupt Enable bit (I<sup>2</sup>C Slave mode only)

1 = Enables interrupt on detection of Start or Restart conditions

0 = Start detection interrupts are disabled

bit 4 **BOEN:** Buffer Overwrite Enable bit (I<sup>2</sup>C Slave mode only)

1 = I2CxRCV is updated and an ACK is generated for a received address/data byte, ignoring the state of the I2COV bit only if the RBF bit = 0

0 = I2CxRCV is only updated when I2COV is clear

bit 3 **SDAHT:** SDAx Hold Time Selection bit

1 = Minimum of 300 ns hold time on SDAx after the falling edge of SCLx

0 = Minimum of 100 ns hold time on SDAx after the falling edge of SCLx

bit 2 **SBCDE:** Slave Mode Bus Collision Detect Enable bit (I<sup>2</sup>C Slave mode only)

If, on the rising edge of SCLx, SDAx is sampled low when the module is outputting a high state, the BCL bit is set and the bus goes Idle. This Detection mode is only valid during data and ACK transmit sequences.

1 = Enables slave bus collision interrupts

0 = Slave bus collision interrupts are disabled

bit 1 **AHEN:** Address Hold Enable bit (I<sup>2</sup>C Slave mode only)

1 = Following the 8th falling edge of SCLx for a matching received address byte; SCLREL bit (I2CxCONL<12>) will be cleared and the SCLx will be held low

0 = Address holding is disabled

bit 0 **DHEN:** Data Hold Enable bit (I<sup>2</sup>C Slave mode only)

1 = Following the 8th falling edge of SCLx for a received data byte; slave hardware clears the SCLREL bit (I2CxCONL<12>) and SCLx is held low

0 = Data holding is disabled



# PIC24FJ128GA204 FAMILY

## REGISTER 20-1: PMCON1: EPMP CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
PMPEN	—	PSIDL	ADRMUX1	ADRMUX0	—	MODE1	MODE0
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP	ALMODE	—	BUSKEEP	IRQM1	IRQM0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **PMPEN:** EPMP Enable bit  
1 = EPMP is enabled  
0 = EPMP is disabled
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **PSIDL:** EPMP Stop in Idle Mode bit  
1 = Discontinues module operation when device enters Idle mode  
0 = Continues module operation in Idle mode
- bit 12-11 **ADRMUX<1:0>:** Address/Data Multiplexing Selection bits  
11 = Lower address bits are multiplexed with data bits using 3 address phases  
10 = Lower address bits are multiplexed with data bits using 2 address phases  
01 = Lower address bits are multiplexed with data bits using 1 address phase  
00 = Address and data appear on separate pins
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **MODE<1:0>:** Parallel Port Mode Select bits  
11 = Master mode  
10 = Enhanced PSP: Pins used are PMRD, PMWR, PMCS, PMD<7:0> and PMA<1:0>  
01 = Buffered PSP: Pins used are PMRD, PMWR, PMCS and PMD<7:0>  
00 = Legacy Parallel Slave Port: Pins used are PMRD, PMWR, PMCS and PMD<7:0>
- bit 7-6 **CSF<1:0>:** Chip Select Function bits  
11 = Reserved  
10 = PMA<14> is used for Chip Select 1  
01 = Reserved  
00 = PMCS1 is used for Chip Select 1
- bit 5 **ALP:** Address Latch Polarity bit  
1 = Active-high (PMALL, PMALH and PMALU)  
0 = Active-low (PMALL, PMALH and PMALU)
- bit 4 **ALMODE:** Address Latch Strobe Mode bit  
1 = Enables "smart" address strobes (each address phase is only present if the current access would cause a different address in the latch than the previous address)  
0 = Disables "smart" address strobes
- bit 3 **Unimplemented:** Read as '0'
- bit 2 **BUSKEEP:** Bus Keeper bit  
1 = Data bus keeps its last value when not actively being driven  
0 = Data bus is in a high-impedance state when not actively being driven
- bit 1-0 **IRQM<1:0>:** Interrupt Request Mode bits  
11 = Interrupt is generated when Read Buffer 3 is read or Write Buffer 3 is written (Buffered PSP mode), or on a read or write operation when PMA<1:0> = 11 (Addressable PSP mode only)  
10 = Reserved  
01 = Interrupt is generated at the end of a read/write cycle  
00 = No interrupt is generated

# PIC24FJ128GA204 FAMILY

## 22.13 Programming CFGPAGE (Page 0) Configuration Bits

1. If not already set, set the CRYON bit. Set KEYPG<3:0> to '0000'.
2. Read the PGMFAIL status bit. If this bit is '1', an illegal configuration has been selected and the programming operation will not be performed.
3. Write the data to be programmed into the Configuration Page into CRYTXXC<31:0>. Any bits that are set ('1') will be permanently programmed, while any bits that are cleared ('0') will not be programmed and may be programmed at a later time.
4. Set the CRYWR bit. Poll the bit until it is cleared; alternatively, set the OTPIE bit (CRYOTP<6>) to enable the optional OTP done interrupt.
5. Once all programming has completed, set the CRYREAD bit to reload the values from the on-chip storage. A read operation must be performed to complete programming.

**Note:** Do not clear the CRYON bit while the CRYREAD bit is set; this will result in an incomplete read operation and unavailable key data. To recover, set CRYON and CRYREAD, and allow the read operation to fully complete.

6. Poll the CRYREAD bit until it is cleared; alternatively, set the OTPIE bit (CRYOTP<6>) to enable the optional OTP done interrupt.
7. For production programming, the TSTPGM bit can be set to indicate a successful programming operation. When TSTPGM is set, the PGMTST bit (CRYOTP<7>) will also be set, allowing users to see the OTP array status with performing a read operation on the array.

**Note:** If the device enters Sleep mode during OTP programming, the contents of the OTP array may become corrupted. This is not a recoverable error. Users must ensure that entry into power-saving modes is disabled before OTP programming is performed.

## 22.14 Programming Keys

1. If not already set, set the CRYON bit.
2. Configure KEYPG<3:0> to the page you want to program.
3. Read the PGMFAIL status bit. If this bit is '1', an illegal configuration has been selected and the programming operation will not be performed.
4. Write the data to be programmed into the Configuration Page into CRYTXXC<63:0>. Any bits that are set ('1') will be permanently programmed, while any bits that are cleared ('0') will not be programmed and may be programmed at a later time.
5. Set the CRYWR bit. Poll the bit until it is cleared; alternatively, set the OTPIE bit (CRYOTP<6>) to enable the optional OTP done interrupt.
6. Repeat Steps 2 through 5 for each OTP array page to be programmed.
7. Once all programming has completed, set the CRYREAD bit to reload the values from the on-chip storage. A read operation must be performed to complete programming.

**Note:** Do not clear the CRYON bit while the CRYREAD bit is set; this will result in an incomplete read operation and unavailable key data. To recover, set CRYON and CRYREAD, and allow the read operation to fully complete.

8. Poll the CRYREAD bit until it is cleared; alternatively, set the OTPIE bit (CRYOTP<6>) to enable the optional OTP done interrupt.
9. For production programming, the TSTPGM bit can be set to indicate a successful programming operation. When TSTPGM is set, the PGMTST bit (CRYOTP<7>) will also be set, allowing users to see the OTP array status with performing a read operation on the array.

**Note:** If the device enters Sleep mode during OTP programming, the contents of the OTP array may become corrupted. This is not a recoverable error. Users must ensure that entry into power-saving modes is disabled before OTP programming is performed.

## 22.15 Verifying Programmed Keys

To maintain key security, the secure OTP array has no provision to read back its data to any user-accessible memory space in any operating mode. Therefore, there is no way to directly verify programmed data. The only method for verifying that they have been programmed correctly is to perform an encryption operation with a known plaintext/ciphertext pair for each programmed key.

FIGURE 32-7: I<sup>2</sup>C™ BUS DATA TIMING CHARACTERISTICS (SLAVE MODE)

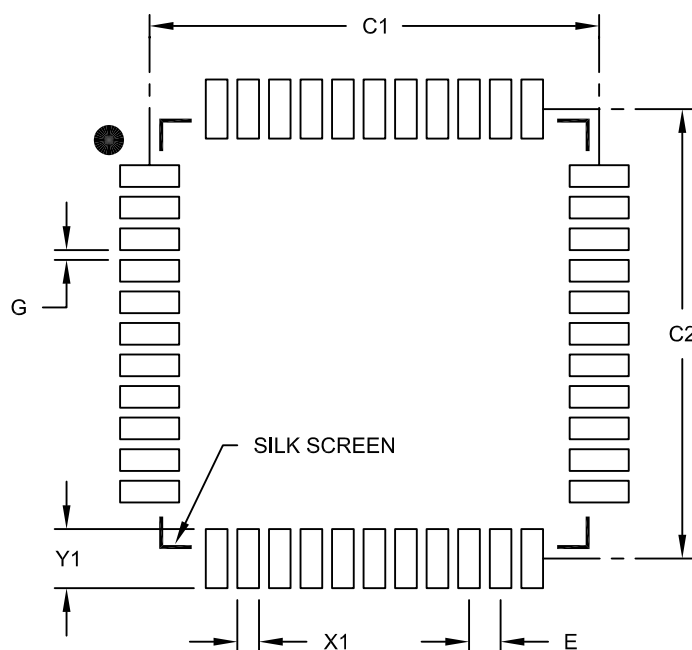
TABLE 32-25: I<sup>2</sup>C™ BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

AC CHARACTERISTICS		Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)	
Operating temperature		-40°C ≤ TA ≤ +85°C for Industrial	
		-40°C ≤ TA ≤ +125°C for Extended	
Param No.			

# PIC24FJ128GA204 FAMILY

44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

		Units	MILLIMETERS		
Dimension Limits			MIN	NOM	MAX
Contact Pitch	E		0.80 BSC		
Contact Pad Spacing	C1			11.40	
Contact Pad Spacing	C2			11.40	
Contact Pad Width (X44)	X1				0.55
Contact Pad Length (X44)	Y1				1.50
Distance Between Pads	G		0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B

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