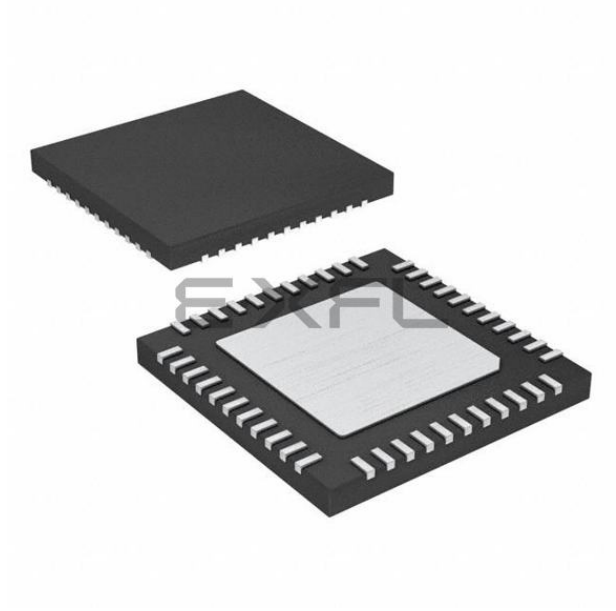


Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	32
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VFQFN Exposed Pad
Supplier Device Package	44-VQFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega644pa-mur

- Programmable Watchdog Timer with Separate On-chip Oscillator
- On-chip Analog Comparator
- Interrupt and Wake-up on Pin Change

- Special Microcontroller Features
  - Power-on Reset and Programmable Brown-out Detection
  - Internal Calibrated RC Oscillator
  - External and Internal Interrupt Sources
  - Six Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, Standby and Extended Standby
- I/O and Packages
  - 32 Programmable I/O Lines
  - 40-pin PDIP, 44-lead TQFP, 44-pad VQFN/QFN/MLF
  - 44-pad DRQFN

– 49-ball VFBGA

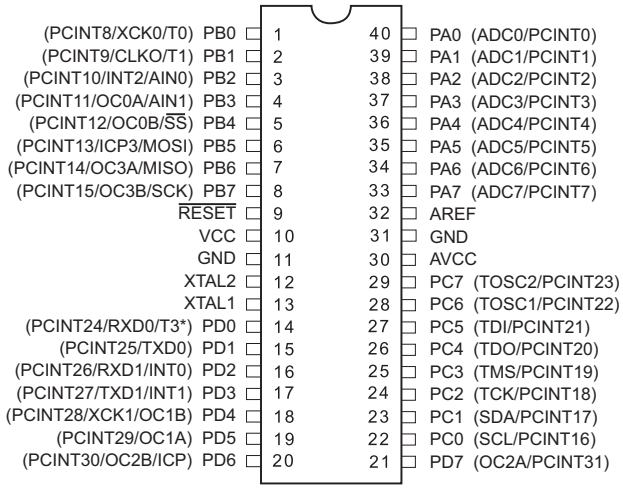
- Operating Voltages
  - 1.8 - 5.5V
- Speed Grades
  - 0 - 4MHz @ 1.8 - 5.5V
  - 0 - 10MHz @ 2.7 - 5.5V
  - 0 - 20MHz @ 4.5 - 5.5V
- Power Consumption at 1MHz, 1.8V, 25°C
  - Active: 0.4mA
  - Power-down Mode: 0.1µA
  - Power-save Mode: 0.6µA (Including 32kHz RTC)

Note: 1. See ”Data retention” on page 9 for details.

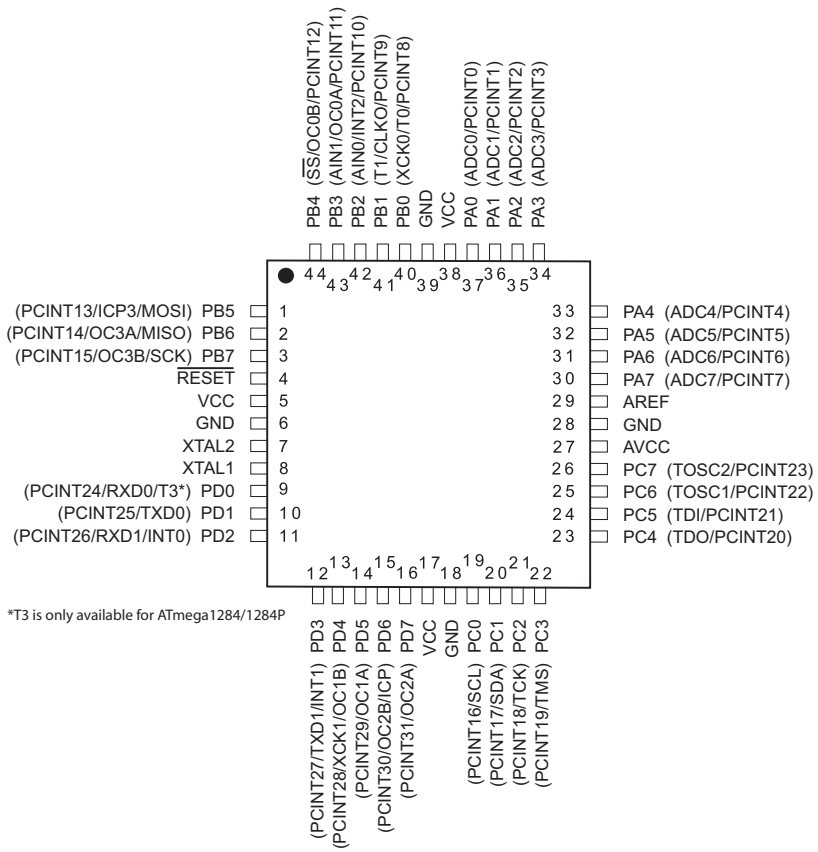
1. Pin configurations

1.1 Pinout - PDIP/TQFP/VQFN/QFN/MLF for ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P

Figure 1-1. Pinout.



TQFP/QFN/MLF



Note: The large center pad underneath the VQFN/QFN/MLF package should be soldered to ground on the board to ensure good mechanical stability.

1.2 Pinout - DRQFN for Atmel ATmega164A/164PA/324A/324PA

Figure 1-2. DRQFN - pinout.

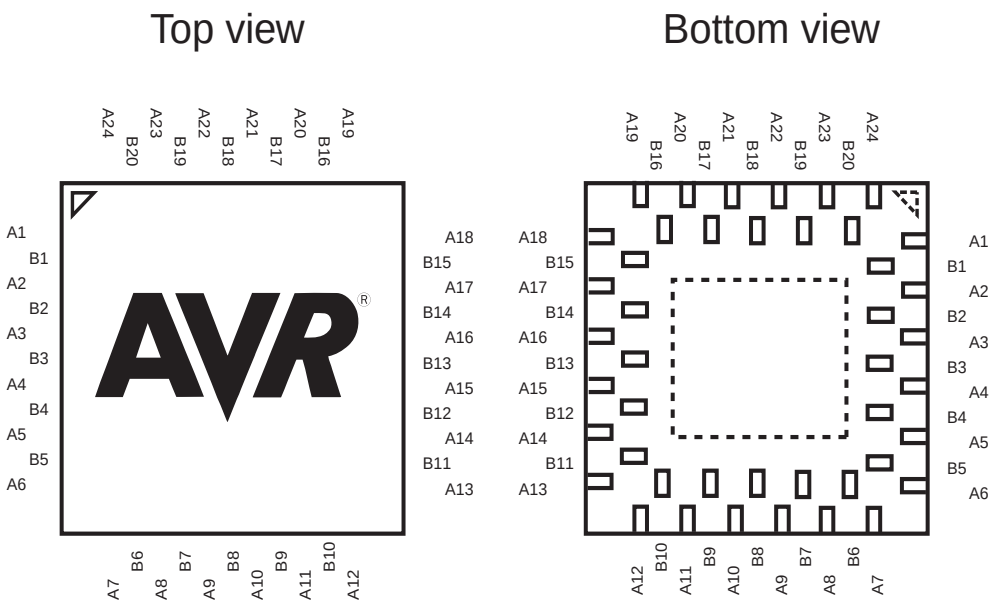
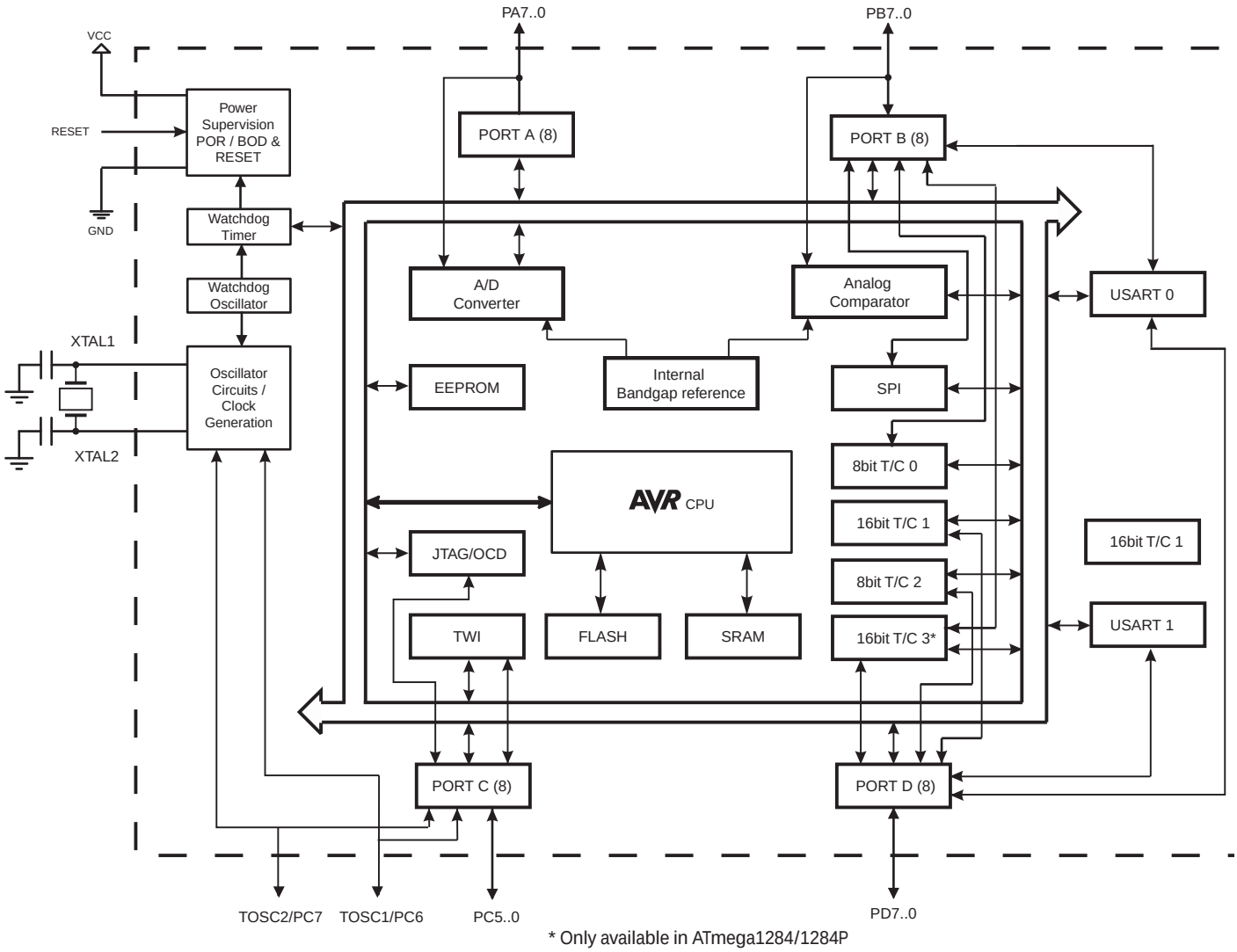


Table 1-1. DRQFN - pinout.

A1	PB5	**A7**	PD3	**A13**	PC4	**A19**	PA3
B1	PB6	**B6**	PD4	**B11**	PC5	**B16**	PA2
A2	PB7	**A8**	PD5	**A14**	PC6	**A20**	PA1
B2	$\overline{\text{RESET}}$	**B7**	PD6	**B12**	PC7	**B17**	PA0
A3	VCC	**A9**	PD7	**A15**	AVCC	**A21**	VCC
B3	GND	**B8**	VCC	**B13**	GND	**B18**	GND
A4	XTAL2	**A10**	GND	**A16**	AREF	**A22**	PB0
B4	XTAL1	**B9**	PC0	**B14**	PA7	**B19**	PB1
A5	PD0	**A11**	PC1	**A17**	PA6	**A23**	PB2
B5	PD1	**B10**	PC2	**B15**	PA5	**B20**	PB3
A6	PD2	**A12**	PC3	**A18**	PA4	**A24**	PB4

2.1 Block diagram

Figure 2-1. Block diagram.



The AVR core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The Atmel ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P provide the following features:

16/32/64/128Kbytes of In-System Programmable Flash with Read-While-Write capabilities, 512/1K/2K/4Kbytes EEPROM, 1/2/4/16Kbytes SRAM, 32 general purpose I/O lines, 32 general purpose working registers, Real Time Counter (RTC), three (four for ATmega1284/1284P) flexible Timer/Counters with compare modes and PWM, 2 USARTs, a byte oriented two-wire Serial Interface, a 8-channel, 10-bit ADC with optional differential input stage with programmable gain, programmable Watchdog Timer with Internal Oscillator, an SPI serial port, IEEE std. 1149.1 compliant JTAG test interface, also used for accessing the On-chip Debug system and programming and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a

timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except Asynchronous Timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the Crystal/Resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low power consumption. In Extended Standby mode, both the main Oscillator and the Asynchronous Timer continue to run.

Atmel offers the QTouch® library for embedding capacitive touch buttons, sliders and wheels functionality into AVR microcontrollers. The patented charge-transfer signal acquisition offers robust sensing and includes fully debounced reporting of touch keys and includes Adjacent Key Suppression® (AKS™) technology for unambiguous detection of key events. The easy-to-use QTouch Suite toolchain allows you to explore, develop and debug your own touch applications.

The device is manufactured using Atmel's high-density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed in-system through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, in-circuit emulators, and evaluation kits.

2.2 Comparison between ATmega164A, ATmega164PA, ATmega324A, ATmega324PA, ATmega644A, ATmega644PA, ATmega1284 and ATmega1284P

Table 2-1. Differences between ATmega164A, ATmega164PA, ATmega324A, ATmega324PA, ATmega644A, ATmega644PA, ATmega1284 and ATmega1284P.

Device	Flash	EEPROM	RAM	Units
ATmega164A	16K	512	1K	bytes
ATmega164PA	16K	512	1K	
ATmega324A	32K	1K	2K	
ATmega324PA	32K	1K	2K	
ATmega644A	64K	2K	4K	
ATmega644PA	64K	2K	4K	
ATmega1284	128K	4K	16K	
ATmega1284P	128K	4K	16K	

2.3 Pin Descriptions11

2.3.1 VC

Digital supply voltage.

2.3.2 GND

Ground.

2.3.3 Port A (PA7:PA0)

Port A serves as analog inputs to the Analog-to-digital Converter.
Port A also serves as an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.
Port A also serves the functions of various special features of the Atmel ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P as listed on page 79.

2.3.4 Port B (PB7:PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.
Port B also serves the functions of various special features of the ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P as listed on page 80.

2.3.5 Port C (PC7:PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.
Port C also serves the functions of the JTAG interface, along with special features of the Atmel ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P as listed on page 83.

2.3.6 Port D (PD7:PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.
Port D also serves the functions of various special features of the ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P as listed on page 86.

2.3.7 $\overline{\text{RESET}}$

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in "" on page 325. Shorter pulses are not guaranteed to generate a reset.

2.3.8 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

2.3.9 XTAL2

Output from the inverting Oscillator amplifier.

2.3.10 AVCC

AVCC is the supply voltage pin for Port A and the Analog-to-digital Converter. It should be externally connected to V_{CC}, even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter.

2.3.11 AREF

This is the analog reference pin for the Analog-to-digital Converter.

3. Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

4. About code examples

This documentation contains simple code examples that briefly show how to use various parts of the device. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

The code examples assume that the part specific header file is included before compilation. For I/O registers located in extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR".

5. Data retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

6. Capacitive touch sensing

The Atmel QTouch Library provides a simple to use solution to realize touch sensitive interfaces on most Atmel AVR microcontrollers. The QTouch Library includes support for the QTouch and QMatrix acquisition methods.

Touch sensing can be added to any application by linking the appropriate Atmel QTouch Library for the AVR Microcontroller. This is done by using a simple set of APIs to define the touch channels and sensors, and then calling the touch sensing API's to retrieve the channel information and determine the touch sensor states.

The QTouch Library is FREE and downloadable from the Atmel website at the following location: www.atmel.com/qtouchlibrary. For implementation details and other information, refer to the Atmel QTouch Library User Guide - also available for download from the Atmel website.

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
(0x7C)	ADMUX	REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	249
(0x7B)	ADCSRB	-	ACME	-	-	-	ADTS2	ADTS1	ADTS0	233
(0x7A)	ADCSRA	ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0	250
(0x79)	ADCH	ADC Data Register High byte								251
(0x78)	ADCL	ADC Data Register Low byte								251
(0x77)	Reserved	-	-	-	-	-	-	-	-	
(0x76)	Reserved	-	-	-	-	-	-	-	-	
(0x75)	Reserved	-	-	-	-	-	-	-	-	
(0x74)	Reserved	-	-	-	-	-	-	-	-	
(0x73)	PCMSK3	PCINT31	PCINT30	PCINT29	PCINT28	PCINT27	PCINT26	PCINT25	PCINT24	70
(0x72)	Reserved	-	-	-	-	-	-	-	-	
(0x71)	TIMSK3	-	-	ICIE3	-	-	OCIE3B	OCIE3A	TOIE3	134
(0x70)	TIMSK2	-	-	-	-	-	OCIE2B	OCIE2A	TOIE2	156
(0x6F)	TIMSK1	-	-	ICIE1	-	-	OCIE1B	OCIE1A	TOIE1	134
(0x6E)	TIMSK0	-	-	-	-	-	OCIE0B	OCIE0A	TOIE0	105
(0x6D)	PCMSK2	PCINT23	PCINT22	PCINT21	PCINT20	PCINT19	PCINT18	PCINT17	PCINT16	70
(0x6C)	PCMSK1	PCINT15	PCINT14	PCINT13	PCINT12	PCINT11	PCINT10	PCINT9	PCINT8	70
(0x6B)	PCMSK0	PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	71
(0x6A)	Reserved	-	-	-	-	-	-	-	-	
(0x69)	EICRA	-	-	ISC21	ISC20	ISC11	ISC10	ISC01	ISC00	67
(0x68)	PCICR	-	-	-	-	PCIE3	PCIE2	PCIE1	PCIE0	69
(0x67)	Reserved	-	-	-	-	-	-	-	-	
(0x66)	OSCCAL	Oscillator Calibration Register								40
(0x65)	PRR1	-	-	-	-	-	-	-	--PRTIM3	49
(0x64)	PRR0	PRTWI	PRTIM2	PRTIM0	PRUSART1	PRTIM1	PRSPI	PRUSART0	PRADC	48
(0x63)	Reserved	-	-	-	-	-	-	-	-	
(0x62)	Reserved	-	-	-	-	-	-	-	-	
(0x61)	CLKPR	CLKPCE	-	-	-	CLKPS3	CLKPS2	CLKPS1	CLKPS0	40
(0x60)	WDTCSR	WDIF	WDIE	WDP3	WDCE	WDE	WDP2	WDP1	WDP0	59
0x3F (0x5F)	SREG	I	T	H	S	V	N	Z	C	11
0x3E (0x5E)	SPH	SP15	SP14	SP13	SP12	SP11	SP10	SP9	SP8	12
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	12
0x3C (0x5C)	Reserved	-	-	-	-	-	-	-	-	
0x3B (0x5B)	Reserved	-	-	-	-	-	-	-	-	
0x3A (0x5A)	Reserved	-	-	-	-	-	-	-	-	
0x39 (0x59)	Reserved	-	-	-	-	-	-	-	-	
0x38 (0x58)	Reserved	-	-	-	-	-	-	-	-	
0x37 (0x57)	SPMCSR	SPMIE	RWWSB	SIGRD	RWWSRE	BLBSET	PGWRT	PGERS	SPMEN	285
0x36 (0x56)	Reserved	-	-	-	-	-	-	-	-	
0x35 (0x55)	MCUCR	JTD	BODS[6]	BODSE[6]	PUD	-	-	IVSEL	IVCE	89/268
0x34 (0x54)	MCUSR	-	-	-	JTRF	WDRF	BORF	EXTRF	PORF	58/268
0x33 (0x53)	SMCR	-	-	-	-	SM2	SM1	SM0	SE	47
0x32 (0x52)	Reserved	-	-	-	-	-	-	-	-	
0x31 (0x51)	OCDR	On-Chip Debug Register								259
0x30 (0x50)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	250
0x2F (0x4F)	Reserved	-	-	-	-	-	-	-	-	
0x2E (0x4E)	SPDR	SPI 0 Data Register								166
0x2D (0x4D)	SPSR	SPIF0	WCOL0	-	-	-	-	-	SPI2X0	165
0x2C (0x4C)	SPCR	SPIE0	SPE0	DORD0	MSTR0	CPOL0	CPHA0	SPR01	SPR00	164
0x2B (0x4B)	GPIOR2	General Purpose I/O Register 2								29
0x2A (0x4A)	GPIOR1	General Purpose I/O Register 1								29
0x29 (0x49)	Reserved	-	-	-	-	-	-	-	-	
0x28 (0x48)	OCR0B	Timer/Counter0 Output Compare Register B								105
0x27 (0x47)	OCR0A	Timer/Counter0 Output Compare Register A								105
0x26 (0x46)	TCNT0	Timer/Counter0 (8 Bit)								105
0x25 (0x45)	TCCR0B	FOC0A	FOC0B	-	-	WGM02	CS02	CS01	CS00	104
0x24 (0x44)	TCCR0A	COM0A1	COM0A0	COM0B1	COM0B0	-	-	WGM01	WGM00	105
0x23 (0x43)	GTCCR	TSM	-	-	-	-	-	PSRASY	PSRSYNC	157
0x22 (0x42)	EEARH	-	-	-	-	EEPROM Address Register High Byte				24
0x21 (0x41)	EEARL	EEPROM Address Register Low Byte								24
0x20 (0x40)	EEDR	EEPROM Data Register								24
0x1F (0x3F)	EECR	-	-	EEPM1	EEPM0	EERIE	EEMPE	EEPE	EERE	24
0x1E (0x3E)	GPIOR0	General Purpose I/O Register 0								29
0x1D (0x3D)	EIMSK	-	-	-	-	-	INT2	INT1	INT0	68
0x1C (0x3C)	EIFR	-	-	-	-	-	INTF2	INTF1	INTF0	68
0x1B (0x3B)	PCIFR	-	-	-	-	PCIF3	PCIF2	PCIF1	PCIF0	69
0x1A (0x3A)	Reserved	-	-	-	-	-	-	-	-	
0x19 (0x39)	Reserved	-	-	-	-	-	-	-	-	

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x18 (0x38)	TIFR3	-	-	ICF3	-	-	OCF3B	OCF3A	TOV3	136
0x17 (0x37)	TIFR2	-	-	-	-	-	OCF2B	OCF2A	TOV2	156
0x16 (0x36)	TIFR1	-	-	ICF1	-	-	OCF1B	OCF1A	TOV1	135
0x15 (0x35)	TIFR0	-	-	-	-	-	OCF0B	OCF0A	TOV0	106
0x14 (0x34)	Reserved	-	-	-	-	-	-	-	-	
0x13 (0x33)	Reserved	-	-	-	-	-	-	-	-	
0x12 (0x32)	Reserved	-	-	-	-	-	-	-	-	
0x11 (0x31)	Reserved	-	-	-	-	-	-	-	-	
0x10 (0x30)	Reserved	-	-	-	-	-	-	-	-	
0x0F (0x2F)	Reserved	-	-	-	-	-	-	-	-	
0x0E (0x2E)	Reserved	-	-	-	-	-	-	-	-	
0x0D (0x2D)	Reserved	-	-	-	-	-	-	-	-	
0x0C (0x2C)	Reserved	-	-	-	-	-	-	-	-	
0x0B (0x2B)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	90
0x0A (0x2A)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	90
0x09 (0x29)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	90
0x08 (0x28)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	90
0x07 (0x27)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	90
0x06 (0x26)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	90
0x05 (0x25)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	89
0x04 (0x24)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	89
0x03 (0x23)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	90
0x02 (0x22)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	89
0x01 (0x21)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	89
0x00 (0x20)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	89

Notes:
1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
2. I/O registers within the address range $00 - $1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
3. Some of the status flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers 0x00 to 0x1F only.
4. When using the I/O specific commands IN and OUT, the I/O addresses $00 - $3F must be used. When addressing I/O registers as data space using LD and ST instructions, $20 must be added to these addresses. The ATmega164A/164PA/324A/324PA/644A/644PA/1284/1284P is a complex microcontroller with more peripheral units than can be supported within the 64 location reserved in Opcode for the IN and OUT instructions. For the Extended I/O space from $60 - $FF, only the ST/STS/STD and LD/LDS/LDD instructions can be used.
5. USART in SPI Master Mode.
6. Only available in the ATmega164PA/324PA/644PA/1284P.
7. Only available in the ATmega1284/1284P

8. Instruction set summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND LOGIC INSTRUCTIONS					
ADD	Rd, Rr	Add two Registers	Rd ← Rd + Rr	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	Rd ← Rd + Rr + C	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	Rd ← Rd - Rr - C	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	Rd ← Rd - K - C	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	Rd ← Rd • Rr	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	Rd ← Rd • K	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	Rd ← Rd v K	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	Rd ← Rd ⊕ Rr	Z,N,V	1
COM	Rd	One's Complement	Rd ← 0xFF – Rd	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← 0x00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	Rd ← Rd v K	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	Rd ← Rd • (0xFF - K)	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd – 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	Rd ← Rd • Rd	Z,N,V	1
CLR	Rd	Clear Register	Rd ← Rd ⊕ Rd	Z,N,V	1
SER	Rd	Set Register	Rd ← 0xFF	None	1
MUL	Rd, Rr	Multiply Unsigned	R1:R0 ← Rd x Rr	Z,C	2
MULS	Rd, Rr	Multiply Signed	R1:R0 ← Rd x Rr	Z,C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	R1:R0 ← Rd x Rr	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
BRANCH INSTRUCTIONS					
RJMP	k	Relative Jump	PC ← PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC ← Z	None	2
JMP	k	Direct Jump	PC ← k	None	3
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)	PC ← Z	None	3
CALL	k	Direct Subroutine Call	PC ← k	None	4
RET		Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK	I	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1/2/3
CP	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if (Rr(b)=1) PC ← PC + 2 or 3	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if (P(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC ← PC + 2 or 3	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC←PC+k + 1	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC←PC+k + 1	None	1/2
BREQ	k	Branch if Equal	if (Z = 1) then PC ← PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC ← PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC ← PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC ← PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if (N ⊕ V= 0) then PC ← PC + k + 1	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if (N ⊕ V= 1) then PC ← PC + k + 1	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1/2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC ← PC + k + 1	None	1/2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC ← PC + k + 1	None	1/2
BRTC	k	Branch if T Flag Cleared	if (T = 0) then PC ← PC + k + 1	None	1/2
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC ← PC + k + 1	None	1/2

Mnemonics	Operands	Description	Operation	Flags	#Clocks
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC ← PC + k + 1	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1/2
BIT AND BIT-TEST INSTRUCTIONS					
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	Rd(n+1) ← Rd(n), Rd(0) ← 0	Z,C,N,V	1
LSR	Rd	Logical Shift Right	Rd(n) ← Rd(n+1), Rd(7) ← 0	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	Rd(0)←C,Rd(n+1)← Rd(n),C←Rd(7)	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	Rd(7)←C,Rd(n)← Rd(n+1),C←Rd(0)	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	Rd(n) ← Rd(n+1), n=0..6	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(3..0)←Rd(7..4),Rd(7..4)←Rd(3..0)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	s	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	T ← Rr(b)	T	1
BLD	Rd, b	Bit load from T to Register	Rd(b) ← T	None	1
SEC		Set Carry	C ← 1	C	1
CLC		Clear Carry	C ← 0	C	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	I	1
CLI		Global Interrupt Disable	I ← 0	I	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	T	1
SEH		Set Half Carry Flag in SREG	H ← 1	H	1
CLH		Clear Half Carry Flag in SREG	H ← 0	H	1
DATA TRANSFER INSTRUCTIONS					
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	Rd ← (X)	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	Rd ← (X), X ← X + 1	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	X ← X - 1, Rd ← (X)	None	2
LD	Rd, Y	Load Indirect	Rd ← (Y)	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	Rd ← (Y), Y ← Y + 1	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	Y ← Y - 1, Rd ← (Y)	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	Rd ← (Y + q)	None	2
LD	Rd, Z	Load Indirect	Rd ← (Z)	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	Rd ← (Z), Z ← Z+1	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	Z ← Z - 1, Rd ← (Z)	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	Rd ← (Z + q)	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	(X) ← Rr, X ← X + 1	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	X ← X - 1, (X) ← Rr	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	(Y) ← Rr, Y ← Y + 1	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	Y ← Y - 1, (Y) ← Rr	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	(Z) ← Rr	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	(Z) ← Rr, Z ← Z + 1	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	Z ← Z - 1, (Z) ← Rr	None	2
STD	Z+q,Rr	Store Indirect with Displacement	(Z + q) ← Rr	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	Rd ← (Z)	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	Rd ← (Z), Z ← Z+1	None	3
SPM		Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2

9.2 Atmel ATmega164PA

Speed [MHz] (3)	Power supply	Ordering code (2)	Package (1)	Operational range
20	1.8 - 5.5V	ATmega164PA-AU ATmega164PA-AUR(5) ATmega164PA-PU ATmega164PA-MU ATmega164PA-MUR(5) ATmega164PA-MCH(4) ATmega164PA-MCHR(4)(5) ATmega164PA-CU ATmega164PA-CUR(5)	44A 44A 40P6 44M1 44M1 44MC 44MC 49C2 49C2	Industrial (-40°C to 85°C)
20	1.8 - 5.5V	ATmega164PA-AN ATmega164PA-ANR(5) ATmega164PA-PN ATmega164PA-MN ATmega164PA-MNR(5)	44A 44A 40P6 44M1 44M1	Industrial (-40°C to 105°C)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see ”Speed grades” on page 324.
4. NiPdAu Lead Finish.
5. Tape & Reel.

Package Type	
44A	44-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)
40P6	40-pin, 0.600” Wide, Plastic Dual Inline Package (PDIP)
44M1	44-pad, 7 × 7 × 1.0mm body, lead pitch 0.50mm, Thermally Enhanced Plastic Very Thin Quad Flat No-Lead (VQFN)
44MC	44-lead (2-row Staggered), 5 × 5 × 1.0mm body, 2.60 × 2.60mm Exposed Pad, Quad Flat No-Lead Package (QFN)
49C2	49-ball, (7 × 7 Array) 0.65mm Pitch, 5 × 5 × 1mm, Very Thin, Fine-Pitch Ball Grid Array Package (VFBGA)

9.3 Atmel ATmega324A

Speed [MHz] (3)	Power supply	Ordering code (2)	Package (1)	Operational range
20	1.8 - 5.5V	ATmega324A-AU ATmega324A-AUR(5) ATmega324A-PU ATmega324A-MU ATmega324A-MUR(5) ATmega324A-MCH(4) ATmega324A-MCHR(4)(5) ATmega324A-CU ATmega324A-CUR(5)	44A 44A 40P6 44M1 44M1 44MC 44MC 49C2 49C2	Industrial (-40°C to 85°C)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see ”Speed grades” on page 324.
4. NiPdAu Lead Finish.
5. Tape & Reel.

Package Type	
44A	44-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)
40P6	40-pin, 0.600” Wide, Plastic Dual Inline Package (PDIP)
44M1	44-pad, 7 × 7 × 1.0mm body, lead pitch 0.50mm, Thermally Enhanced Plastic Very Thin Quad Flat No-Lead (VQFN)
44MC	44-lead (2-row Staggered), 5 × 5 × 1.0mm body, 2.60 × 2.60mm Exposed Pad, Quad Flat No-Lead Package (QFN)
49C2	49-ball, (7 × 7 Array) 0.65mm Pitch, 5 × 5 × 1mm, Very Thin, Fine-Pitch Ball Grid Array Package (VFBGA)

9.4 Atmel ATmega324PA

Speed [MHz] (3)	Power supply	Ordering code (2)	Package (1)	Operational range
20	1.8 - 5.5V	ATmega324PA-AU ATmega324PA-AUR(5) ATmega324PA-PU ATmega324PA-MU ATmega324PA-MUR(5) ATmega324PA-MCH(4) ATmega324PA-MCHR(4)(5) ATmega324PA-CU ATmega324PA-CUR(5)	44A 44A 40P6 44M1 44M1 44MC 44MC 49C2 49C2	Industrial (-40°C to 85°C)
20	1.8 - 5.5V	ATmega324PA-AN ATmega324PA-ANR(5) ATmega324PA-PN ATmega324PA-MN ATmega324PA-MNR(5)	44A 44A 40P6 44M1 44M1	Industrial (-40°C to 105°C)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see ”Speed grades” on page 324.
4. NiPdAu Lead Finish.
5. Tape & Reel.

Package Type	
44A	44-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)
40P6	40-pin, 0.600” Wide, Plastic Dual Inline Package (PDIP)
44M1	44-pad, 7 × 7 × 1.0mm body, lead pitch 0.50mm, Thermally Enhanced Plastic Very Thin Quad Flat No-Lead (VQFN)
44MC	44-lead (2-row Staggered), 5 × 5 × 1.0mm body, 2.60 × 2.60mm Exposed Pad, Quad Flat No-Lead Package (QFN)
49C2	49-ball, (7 × 7 Array) 0.65mm Pitch, 5 × 5 × 1mm, Very Thin, Fine-Pitch Ball Grid Array Package (VFBGA)

9.8 Atmel ATmega1284P

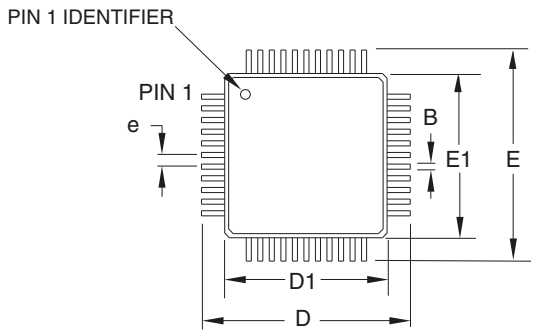
Speed [MHz] (3)	Power supply	Ordering code (2)	Package (1)	Operational range
20	1.8 - 5.5V	ATmega1284P-AU ATmega1284P-AUR(4) ATmega1284P-PU ATmega1284P-MU ATmega1284P-MUR(4)	44A 44A 40P6 44M1 44M1	Industrial (-40°C to 85°C)
20	1.8 - 5.5V	ATmega1284P-AN ATmega1284P-ANR(4) ATmega1284P-PN ATmega1284P-MN ATmega1284P-MNR(4)	44A 44A 40P6 44M1 44M1	Industrial (-40°C to 105°C)

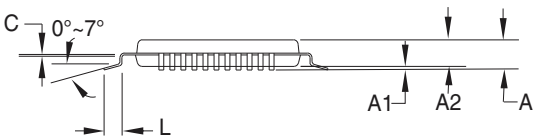
Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see ”Speed grades” on page 324.
4. Tape & Reel.

Package Type	
44A	44-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)
40P6	40-pin, 0.600” Wide, Plastic Dual Inline Package (PDIP)
44M1	44-pad, 7 × 7 × 1.0mm body, lead pitch 0.50mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)

10. Packaging information

10.1 44A





COMMON DIMENSIONS
(Unit of Measure = mm)

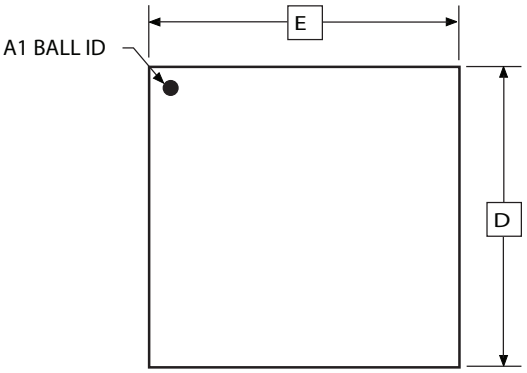
SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	1.20	
A1	0.05	–	0.15	
A2	0.95	1.00	1.05	
D	11.75	12.00	12.25	
D1	9.90	10.00	10.10	Note 2
E	11.75	12.00	12.25	
E1	9.90	10.00	10.10	Note 2
B	0.30	0.37	0.45	
C	0.09	(0.17)	0.20	
L	0.45	0.60	0.75	
e	0.80 TYP			

Notes:
1. This package conforms to JEDEC reference MS-026, Variation ACB.
2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.
3. Lead coplanarity is 0.10mm maximum.

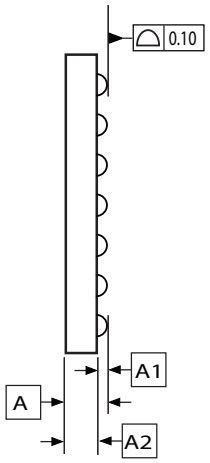
06/02/2014

Atmel Package Drawing Contact: packagedrawings@atmel.com	TITLE	DRAWING NO.	REV.
	44A, 44-lead, 10 x 10mm body size, 1.0mm body thickness, 0.8 mm lead pitch, thin profile plastic quad flat package (TQFP)	44A	C

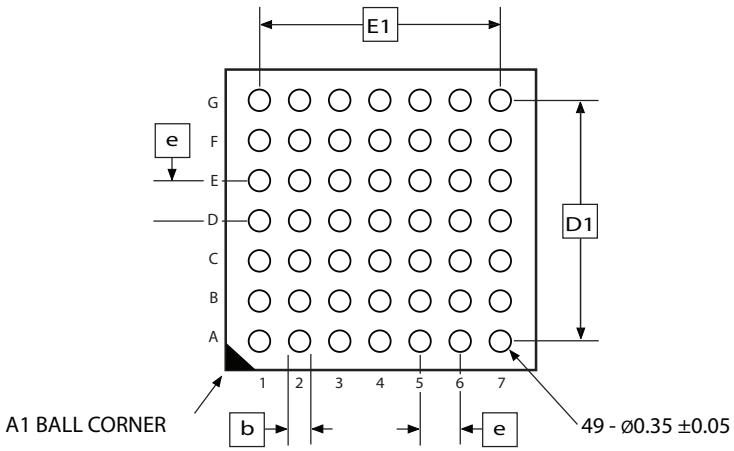
10.5 49C2



TOP VIEW



SIDE VIEW



BOTTOM VIEW

COMMON DIMENSIONS
(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	1.00	
A1	0.20	–	–	
A2	0.65	–	–	
D	4.90	5.00	5.10	
D1		3.90 BSC		
E4.90	5.00	5.10		
E1		3.90 BSC		
b	0.30	0.35	0.40	
e		0.65 BSC		

3/14/08

Atmel Package Drawing Contact: packagedrawings@atmel.com	TITLE 49C2, 49-ball (7 x 7 array), 0.65mm pitch, 5.0 x 5.0 x 1.0mm, very thin, fine-pitch ball grid array package (VFBGA)	GPC CBD	DRAWING NO. 49C2	REV. A

11. Errata

11.1 Errata for ATmega164A

11.1.1 Rev. E

No known Errata.

11.2 Errata for ATmega164PA

11.2.1 Rev. E

No known Errata.

11.3 Errata for ATmega324A

11.3.1 Rev. F

No known Errata.

11.4 Errata for ATmega324PA

11.4.1 Rev. F

No known Errata.

11.5 Errata for ATmega644A

11.5.1 Rev. F

No known Errata.

11.6 Errata for ATmega644PA

11.6.1 Rev. F

No known Errata.

11.7 Errata for ATmega1284

11.7.1 Rev. B

No known Errata.

11.8 Errata for ATmega1284P

11.8.1 Rev. B

No known Errata.

12. Datasheet revision history

Please note that the referring page numbers in this section are referred to this document. The referring revision in this section are referring to the document revision.

12.1 Rev. 8272G - 01/2015

1.	Updated Table 1-2 on page 5, Table 8-1 on page 25, Table 10-1 on page 42, Table 14-3 on page 79, Table 19-4 on page 187, Table 19-11 on page 192 and Table 28-16 on page 328 for formatting consistency errors
2.	Updated ”Ordering information” on page 17: – Added ordering information for ATmega164PA @105°C; ATmega324PA @ 105°C; ATmega324PA @105°C; ATmega644PA @ 105°C and ATmega1284P @ 105°C
3.	Updated the ”Packaging information” on page 25: – Replaced the drawing ”44M1” on page 27 by a correct package

12.2 Rev. 8272F - 08/2014

1.	Updated text in Section 13.2.8 ”PCMSK1 – Pin Change Mask Register 1” on page 70 to: “If PCINT15:8 is set and the PCIE1 bit in PCICR is set, pin change interrupt is enabled on the corresponding I/O pin.”
2.	Corrected description of PAGEMSB in Table 26-9 on page 281. The device has 64 words in a page and not 128.
3.	Corrected description of PAGEMSB in Table 26-12 on page 282. PAGESMB is 5 and the device has 64 words in a page and not 128. The page require six bits and not seven.
4.	Corrected values in Table 26-16 on page 284. PAGEMSB is 6. ZPAGEMSB is Z7 and PCPAGE is Z15:Z8
5.	Corrected value for PCPAGE in Table 27-7 on page 290. The correct value is PC[14:7]
6.	Updated description in Table 17-2 on page 151 to “Normal port operation, OC2A disconnected.”
7.	Updated Assembly code examples on for ”Watchdog Timer” on page 55. and onwards “out WDTCSR, r16” changed to “sts WDTCSR, r16” “in r16, WDTCSR” changed to “lds r16, WDTCSR” “idi r16, WDTCSR” changed to “lds r16, WDTCSR”
8.	Updated addresses 0x65 and 0x64 in Section 7. ”Register summary” on page 10.
9.	Removed notes 5 and 6 from Table 28-16 on page 328.
10.	Corrected values in Section 8. ”Instruction set summary” on page 14.Changed clock values for RCALL and ICALL to 2, for Call, Ret and RETI to 4. Also changed values in Section 7.7.1 ”Interrupt response time” on page 18.
11.	Updated layout, footer and back page according to template 0205/2014