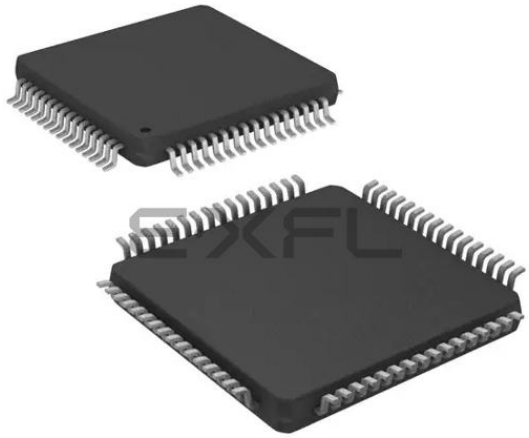
Microchip Technology - PIC32MK0512GPD064T-I/PT Datasheet



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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	IrDA, LINbus, PMP, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, WDT
Number of I/O	48
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 26x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mk0512gpd064t-i-pt

TABLE 1-20: POWER, GROUND, AND VOLTAGE REFERENCE PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	100-pin TQFP	64-pin QFN/ TQFP			
Power and Ground					
AVDD	30	19	P	P	Positive supply for analog modules. This pin must be connected at all times.
AVSS	31	20	P	P	Ground reference for analog modules. This pin must be connected at all times.
VDD	2, 16, 37, 46, 62, 86	10, 26, 38, 57	P	—	Positive supply for peripheral logic and I/O pins. This pin must be connected at all times.
VSS	15, 36, 45, 65, 75, 85	9, 25, 41, 56	P	—	Ground reference for logic, I/O pins, and USB. This pin must be connected at all times.
VBAT(1)	68	42	P	P	Battery backup for selected peripherals; otherwise connect to VDD.
Voltage Reference					
VREF+	29	16	I	Analog	Analog Voltage Reference (High) Input
VREF-	28	15	I	Analog	Analog Voltage Reference (Low) Input

Legend: CMOS = CMOS-compatible input or output; Analog = Analog input; P = Power
ST = Schmitt Trigger input with CMOS levels; O = Output; I = Input
TTL = Transistor-transistor Logic input buffer; PPS = Peripheral Pin Select

Note 1: VBAT functionality is compromised, see errata for additional information. This pin should be connected to VDD.

3.1.4 FLOATING POINT UNIT (FPU)

The Floating Point Unit (FPU), Coprocessor (CP1), implements the MIPS Instruction Set Architecture for floating point computation. The implementation supports the ANSI/IEEE Standard 754 (IEEE for Binary Floating Point Arithmetic) for single- and double-precision data formats. The FPU can be programmed to have thirty-two 32-bit or 64-bit floating point registers used for floating point operations.

The performance is optimized for single precision formats. Most instructions have one FPU cycle throughput and four FPU cycle latency. The FPU implements the multiply-add (MADD) and multiply-sub (MSUB) instructions with intermediate rounding after the multiply function. The result is guaranteed to be the same as executing a MUL and an ADD instruction separately, but the instruction latency, instruction fetch, dispatch bandwidth, and the total number of register accesses are improved.

IEEE denormalized input operands and results are supported by hardware for some instructions. IEEE denormalized results are not supported by hardware in general, but a fast flush-to-zero mode is provided to optimize performance. The fast flush-to-zero mode is enabled through the FCCR register, and use of this mode is recommended for best performance when denormalized results are generated.

The FPU has a separate pipeline for floating point instruction execution. This pipeline operates in parallel with the integer core pipeline and does not stall when the integer pipeline stalls. This allows long-running FPU operations, such as divide or square root, to be partially masked by system stalls and/or other integer unit instructions. Arithmetic instructions are always dispatched and completed in order, but loads and stores can complete out of order. The exception model is “precise” at all times.

Table 3-4 contains the floating point instruction latencies and repeat rates for the processor core. In this table, 'Latency' refers to the number of FPU cycles necessary for the first instruction to produce the result needed by the second instruction. The “Repeat Rate” refers to the maximum rate at which an instruction can be executed per FPU cycle.

TABLE 3-4: FPU INSTRUCTION LATENCIES AND REPEAT RATES

Op code	Latency (FPU Cycles)	Repeat Rate (FPU Cycles)
ABS.[S,D], NEG.[S,D], ADD.[S,D], SUB.[S,D], C.cond.[S,D], MUL.S	4	1
MADD.S, MSUB.S, NMADD.S, NMSUB.S, CABS.cond.[S,D]	4	1
CVT.D.S, CVT.PS.PW, CVT.[S,D].[W,L]	4	1
CVT.S.D, CVT.[W,L].[S,D], CEIL.[W,L].[S,D], FLOOR.[W,L].[S,D], ROUND.[W,L].[S,D], TRUNC.[W,L].[S,D]	4	1
MOV.[S,D], MOVF.[S,D], MOVN.[S,D], MOVT.[S,D], MOVZ.[S,D]	4	1
MUL.D	5	2
MADD.D, MSUB.D, NMADD.D, NMSUB.D	5	2
RECIP.S	13	10
RECIP.D	26	21
RSQRT.S	17	14
RSQRT.D	36	31
DIV.S, SQRT.S	17	14
DIV.D, SQRT.D	32	29
MTC1, DMTC1, LWC1, LDC1, LDXC1, LUXC1, LWXC1	4	1
MFC1, DMFC1, SWC1, SDC1, SDXC1, SUXC1, SWXC1	1	1

Legend: S = Single D = Double
W = Word L = Long word

REGISTER 3-8: FCCR: FLOATING POINT CONDITION CODES REGISTER; CP1 REGISTER 25

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	FCC<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7-0 **FCC<7:0>:** Floating Point Condition Code bits

These bits record the results of floating point compares and are tested for floating point conditional branches and conditional moves.

4.1.1 BOOT FLASH SEQUENCE AND CONFIGURATION SPACES

Sequence space is used to identify which boot Flash is aliased by aliased regions. If the value programmed into the TSEQ<15:0> bits of the BF1SEQ word is equal to or greater than the value programmed into the TSEQ<15:0> bits of the BF2SEQ word, Boot Flash 1 is aliased by the lower boot alias region, and Boot Flash 2 is aliased by the upper boot alias region. If the TSEQ<15:0> bits of the BF2SEQ word is greater than the TSEQ<15:0> bits of the BF1SEQ word, the opposite is true (see Table 4-2 and Table 4-3 for BFxSEQ word memory locations).

Once boot Flash memories are aliased, configuration space located in the lower boot alias region is used as the basis for the Configuration words, DEVSIGN0, DEVCP0, and DEVCFGx. This means that the boot Flash region to be aliased by lower boot alias region memory must contain configuration values in the appropriate memory locations.

Note:	Use only Quad Word program operation (NVMOP<3:0> = `0010`) when programming data into the sequence and configuration spaces.

The System Bus arbitration scheme implements a non-programmable, Least Recently Serviced (LRS) priority, which provides Quality Of Service (QOS) for most initiators. However, some initiators can use Fixed High Priority (HIGH) arbitration to guarantee their access to data.

The arbitration scheme for the available initiators is shown in Table 4-5.

TABLE 4-5: INITIATOR ID AND QOS

Name	ID	QOS
CPU-IS	1	LRS
CPU-DS	2	LRS
DMA Read	3	LRS
DMA Write	4	LRS
Flash Controller	5	HIGH
ICD-JTAG	6	LRS
ADC	7	LRS
USB1	8	LRS
USB2	9	LRS
CAN1	10	LRS
CAN2	11	LRS
CAN3	12	LRS
CAN4	13	LRS

4.3 Permission Access and System Bus Registers

The System Bus on PIC32MK GP/MC family of microcontrollers provides access control capabilities for the transaction initiators on the System Bus.

The System Bus divides the entire memory space into fourteen target regions and permits access to each target by initiators through permission groups. Four Permission Groups (0 through 3) can be assigned to each initiator. Each permission group is independent of the others and can have exclusive or shared access to a region.

Using the CFGPG register (see Register 33-8 in **33.0 “Special Features”**), Boot firmware can assign a permission group to each initiator, which can make requests on the System Bus.

The available targets and their regions, as well as the associated control registers to assign protection, are described and listed in Table 4-6.

Register 4-2 through Register 4-10 are used for setting and controlling access permission groups and regions.

To change these registers, they must be unlocked in hardware. The register lock is controlled by the PGLOCK Configuration bit (CFGCON<11>). Setting the PGLOCK bit prevents writes to the control registers and clearing the PGLOCK bit allows writes.

To set or clear the PGLOCK bit, an unlock sequence must be executed. Refer to **Section 42. “Oscillators with Enhanced PLL”** (DS60001250) in the *“PIC32 Family Reference Manual”* for details.

8.2 Interrupts

The PIC32MK GP/MC family uses variable offsets for vector spacing. This allows the interrupt vector spacing to be configured according to application needs. A unique interrupt vector offset can be set for each vector using its associated OFFx register.

For details on the Variable Offset feature, refer to **8.5.2 "Variable Offset"** in **Section 8. "Interrupt Controller"** (DS60001108) of the *"PIC32 Family Reference Manual"*.

Table 8-3 provides the Interrupt IRQ, vector and bit location information.

REGISTER 11-1: DMACON: DMA CONTROLLER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	U-0	R/W-0	R/W-0	U-0	U-0	U-0
	ON	—	—	SUSPEND(1)	DMABUSY	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** DMA On bit
- 1 = DMA module is enabled
- 0 = DMA module is disabled

bit 14-13 **Unimplemented:** Read as '0'

bit 12 **SUSPEND:** DMA Suspend bit(1)
- 1 = DMA transfers are suspended to allow CPU uninterrupted access to data bus
- 0 = DMA operates normally

bit 11 **DMABUSY:** DMA Module Busy bit
- 1 = DMA module is active and is transferring data
- 0 = DMA module is disabled and not actively transferring data

bit 10-0 **Unimplemented:** Read as '0'

Note 1: If the user application clears this bit, it may take a number of cycles before the DMA module completes the current transaction and responds to this request. The user application should poll the BUSY bit to verify that the request has been honored.

REGISTER 12-9: UxEIE: USB ERROR INTERRUPT ENABLE REGISTER ('x' = 1 AND 2)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	BTSEE	BMXEE	DMAEE	BTOEE	DFN8EE	CRC16EE	CRC5EE(1) / EOFEE(2)	PIDEE

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7 **BTSEE:** Bit Stuff Error Interrupt Enable bit
- 1 = BTSEF interrupt is enabled
- 0 = BTSEF interrupt is disabled

bit 6 **BMXEE:** Bus Matrix Error Interrupt Enable bit
- 1 = BMXEF interrupt is enabled
- 0 = BMXEF interrupt is disabled

bit 5 **DMAEE:** DMA Error Interrupt Enable bit
- 1 = DMAEF interrupt is enabled
- 0 = DMAEF interrupt is disabled

bit 4 **BTOEE:** Bus Turnaround Time-out Error Interrupt Enable bit
- 1 = BTOEF interrupt is enabled
- 0 = BTOEF interrupt is disabled

bit 3 **DFN8EE:** Data Field Size Error Interrupt Enable bit
- 1 = DFN8EF interrupt is enabled
- 0 = DFN8EF interrupt is disabled

bit 2 **CRC16EE:** CRC16 Failure Interrupt Enable bit
- 1 = CRC16EF interrupt is enabled
- 0 = CRC16EF interrupt is disabled

bit 1 **CRC5EE:** CRC5 Host Error Interrupt Enable bit(1)
- 1 = CRC5EF interrupt is enabled
- 0 = CRC5EF interrupt is disabled

EOFEE: EOF Error Interrupt Enable bit(2)
- 1 = EOF interrupt is enabled
- 0 = EOF interrupt is disabled

bit 0 **PIDEE:** PID Check Failure Interrupt Enable bit
- 1 = PIDEF interrupt is enabled
- 0 = PIDEF interrupt is disabled

Note 1: Device mode.
2: Host mode.

Note: For an interrupt to propagate USBIF, the UERRIE bit (UxIE<1>) must be set.

REGISTER 12-16: UxSOF: USB SOF THRESHOLD REGISTER ('x' = 1 AND 2)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CNT<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7-0 **CNT<7:0>:** SOF Threshold Value bits

Typical values of the threshold are:
01001010 = 64-byte packet
00101010 = 32-byte packet
00011010 = 16-byte packet
00010010 = 8-byte packet

REGISTER 12-17: UxBDTP1: USB BDT PAGE 1 REGISTER ('x' = 1 AND 2)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
	BDTPTRL<15:9>							—

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7-1 **BDTPTRL<15:9>:** BDT Base Address bits

This 7-bit value provides address bits 15 through 9 of the BDT base address, which defines the starting location of the BDT in system memory.

The 32-bit BDT base address is 512-byte aligned.

bit 0 **Unimplemented:** Read as '0'

TABLE 13-16: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP (CONTINUED)

Virtual Address (BF80_#)	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
16D0	RPD4R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD4R<4:0>					0000
16D4	RPD5R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD5R<4:0>					0000
16D8	RPD6R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPD6R<4:0>					0000
1700	RPE0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPE0R<4:0>					0000
1704	RPE1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPE1R<4:0>					0000
1738	RPE14R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPF14R<4:0>					0000
173C	RPE15R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPE15R<4:0>					0000
1740	RPF0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPF0R<4:0>					0000
1744	RPF1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPF1R<4:0>					0000
1780	RPG0R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG0R<4:0>					0000
1784	RPG1R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG1R<4:0>					0000
1798	RPG6R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG6R<4:0>					0000
179C	RPG7R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG7R<4:0>					0000
17A0	RPG8R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG8R<4:0>					0000
17A4	RPG9R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG9R<4:0>					0000
17B0	RPG12R	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RPG12R<4:0>					0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

REGISTER 18-1: ICxCON: INPUT CAPTURE 'x' CONTROL REGISTER ('x' = 1-16) (CONTINUED)

bit 2-0 **ICM<2:0>:** Input Capture Mode Select bits

111 = Interrupt-Only mode (only supported while in Sleep mode or Idle mode)
110 = Simple Capture Event mode – every edge, specified edge first and every edge thereafter
101 = Prescaled Capture Event mode – every sixteenth rising edge
100 = Prescaled Capture Event mode – every fourth rising edge
011 = Simple Capture Event mode – every rising edge
010 = Simple Capture Event mode – every falling edge
001 = Edge Detect mode – every edge (rising and falling)
000 = Input Capture module is disabled

Note 1: Refer to Table 18-1 for Timerx and Timery selections.

REGISTER 26-3: CxINT: CAN INTERRUPT REGISTER ('x' = 1-4)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
	IVRIE	WAKIE	CERRIE	SERRIE	RBOVIE	—	—	—
23:16	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	MODIE	CTMRIE	RBIE	TBIE
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
	IVRIF	WAKIF	CERRIF	SERRIF(1)	RBOVIF	—	—	—
7:0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	MODIF	CTMRIF	RBIF	TBIF

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **IVRIE:** Invalid Message Received Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 30 **WAKIE:** CAN Bus Activity Wake-up Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 29 **CERRIE:** CAN Bus Error Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 28 **SERRIE:** System Error Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 27 **RBOVIE:** Receive Buffer Overflow Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 26-20 **Unimplemented:** Read as '0'

bit 19 **MODIE:** Mode Change Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 18 **CTMRIE:** CAN Timestamp Timer Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

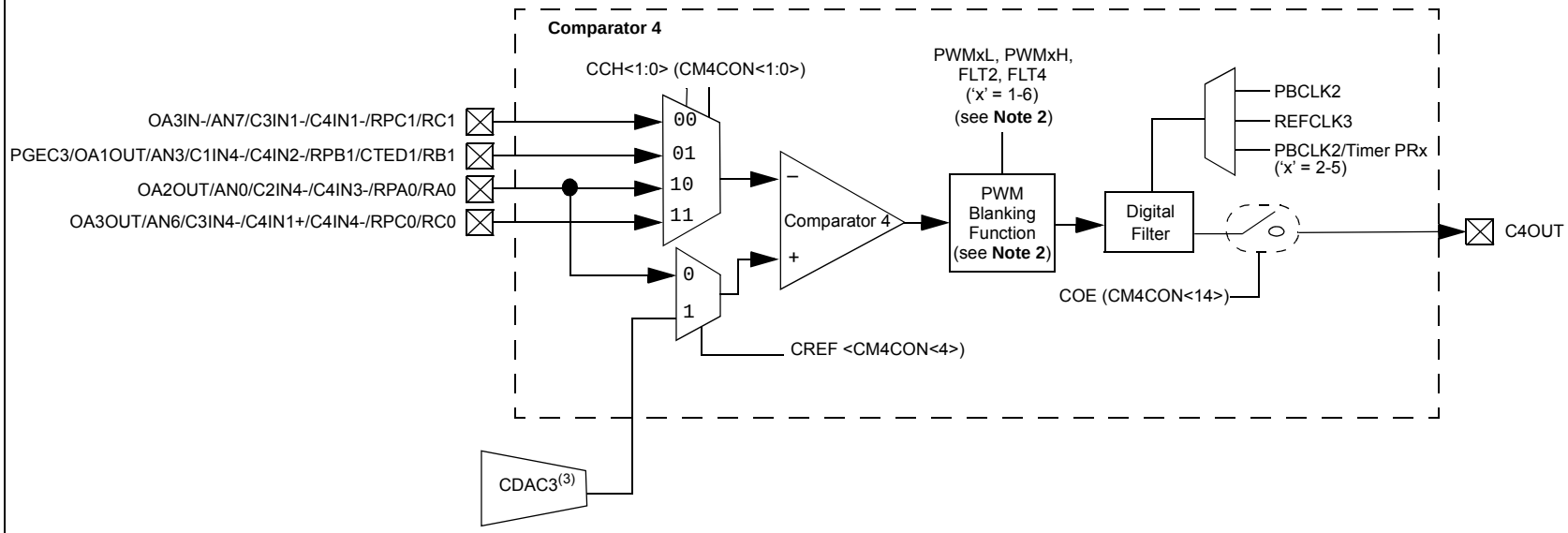
bit 17 **RBIE:** Receive Buffer Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 16 **TBIE:** Transmit Buffer Interrupt Enable bit
1 = Interrupt request is enabled
0 = Interrupt request is not enabled

bit 15 **IVRIF:** Invalid Message Received Interrupt Flag bit
1 = An invalid messages interrupt has occurred
0 = An invalid message interrupt has not occurred

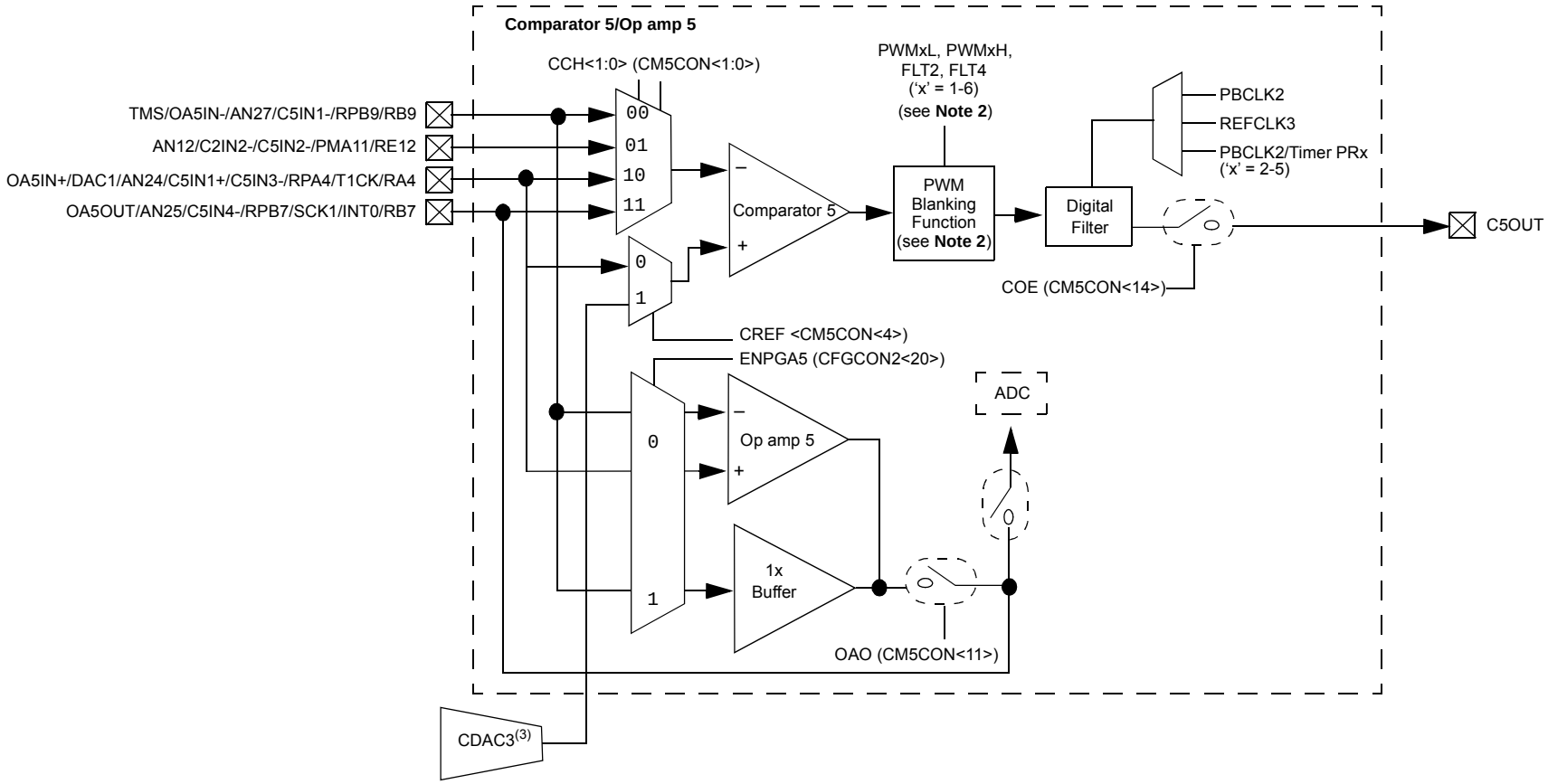
Note 1: This bit can only be cleared by turning the CAN module Off and On by clearing or setting the ON bit (CxCON<15>).

FIGURE 27-4: COMPARATOR 4 MODULE BLOCK DIAGRAM



Note 1: Refer to the device pin tables (Table 3 and Table 5) for other analog inputs that may be also be connected to the Op amp and Comparator inputs.
2: The PWM Blank Function is only available on PIC32MKXXMCXXX devices.
3: Caution: To avoid false comparator output faults or glitches when using the internal DAC as a comparator reference, always initialize the DAC before initializing and enabling the comparator.

FIGURE 27-5: OP AMP 5/COMPARATOR 5 MODULE BLOCK DIAGRAM



Note 1: Refer to the device pin tables (Table 3 and Table 5) for other analog inputs that may be also be connected to the Op amp and Comparator inputs.
2: The PWM Blank Function is only available on PIC32MKXXMCXXX devices.
3: Caution: To avoid false comparator output faults or glitches when using the internal DAC as a comparator reference, always initialize the DAC before initializing and enabling the comparator.

REGISTER 28-1: CTMUCON: CTMU CONTROL REGISTER (CONTINUED)

bit 25 **EDG2STAT:** Edge 2 Status bit
Indicates the status of Edge 2 and can be written to control edge source
1 = Edge 2 has occurred
0 = Edge 2 has not occurred

bit 24 **EDG1STAT:** Edge 1 Status bit
Indicates the status of Edge 1 and can be written to control edge source
1 = Edge 1 has occurred
0 = Edge 1 has not occurred

bit 23 **EDG2MOD:** Edge 2 Edge Sampling Select bit
1 = Input is edge-sensitive
0 = Input is level-sensitive

bit 22 **EDG2POL:** Edge 2 Polarity Select bit
1 = Edge 2 programmed for a positive edge response
0 = Edge 2 programmed for a negative edge response

bit 21-18 **EDG2SEL<3:0>:** Edge 2 Source Select bits
1111 = C5OUT Capture Event is selected
1110 = C4OUT pin is selected
1101 = C1OUT pin is selected
1100 = IC6 Capture Event is selected
1011 = IC5 Capture Event is selected
1010 = IC4 Capture Event is selected
1001 = IC3 pin is selected
1000 = IC2 pin is selected
0111 = IC1 pin is selected
0110 = OC4 pin is selected
0101 = OC3 pin is selected
0100 = OC2 pin is selected
0011 = CTED1 pin is selected
0010 = CTED2 pin is selected
0001 = OC1 Compare Event is selected
0000 = Timer1 Event is selected

bit 17-16 **Unimplemented:** Read as '0'

bit 15 **ON:** ON Enable bit
1 = Module is enabled
0 = Module is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **CTMUSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

Note 1: When this bit is set for Pulse Delay Generation, the EDG2SEL<3:0> bits must be set to '1101' to select C1OUT.

2: The ADC module Sample and Hold capacitor is not automatically discharged between sample/conversion cycles. Software using the ADC as part of a capacitive measurement, must discharge the ADC capacitor before conducting the measurement. The IDISSEN bit, when set to '1', performs this function. The ADC module must be sampling while the IDISSEN bit is active to connect the discharge sink to the capacitor array.

3: Refer to the CTMU Current Source Specifications (Table 36-43) in **Section 36.0 "Electrical Characteristics"** for current values.

4: This bit setting is not available for the CTMU temperature diode.

5: For CTMU temperature measurements on this range, ADC sampling time ≥ 1.6 µs.

6: For CTMU temperature measurements on this range, ADC sampling time ≥ 300 ns.

33.3 On-Chip Voltage Regulator

The core and digital logic for all PIC32MK GP/MC devices is designed to operate at a nominal 1.2V. To simplify system designs, devices in the PIC32MK GP/MC family incorporate an on-chip regulator providing the required core logic voltage from VDD.

33.3.1 ON-CHIP REGULATOR AND POR

It takes a fixed delay for the on-chip regulator to generate an output. During this time, designated as TPU, code execution is disabled. TPU is applied every time the device resumes operation after any power-down, including Sleep mode.

33.3.2 ON-CHIP REGULATOR AND BOR

PIC32MK GP/MC devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain a regulated level, the regulator Reset circuitry will generate a Brown-out Reset. This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage levels are specific in **36.1 "DC Characteristics"**.

33.4 On-chip Temperature Sensor

PIC32MK GP/MC devices include a temperature sensor that provides accurate measurement of a device's junction temperature (see **36.2 "AC Characteristics and Timing Parameters"** for more information).

The temperature sensor is connected to the ADC module and can be measured using the shared S&H circuit (see **25.0 "12-bit High-Speed Successive Approximation Register (SAR) Analog-to-Digital Converter (ADC)"** for more information).

33.5 Programming and Diagnostics

PIC32MK GP/MC devices provide a complete range of programming and diagnostic features that can increase the flexibility of any application using them. These features allow system designers to include:

- Simplified field programmability using two-wire In-Circuit Serial Programming™ (ICSP™) interfaces
- Debugging using ICSP
- Programming and debugging capabilities using the EJTAG extension of JTAG
- JTAG boundary scan testing for device and board diagnostics

PIC32MK devices incorporate two programming and diagnostic modules, and a trace controller, that provide a range of functions to the application developer.

FIGURE 33-1: BLOCK DIAGRAM OF PROGRAMMING, DEBUGGING AND TRACE PORTS

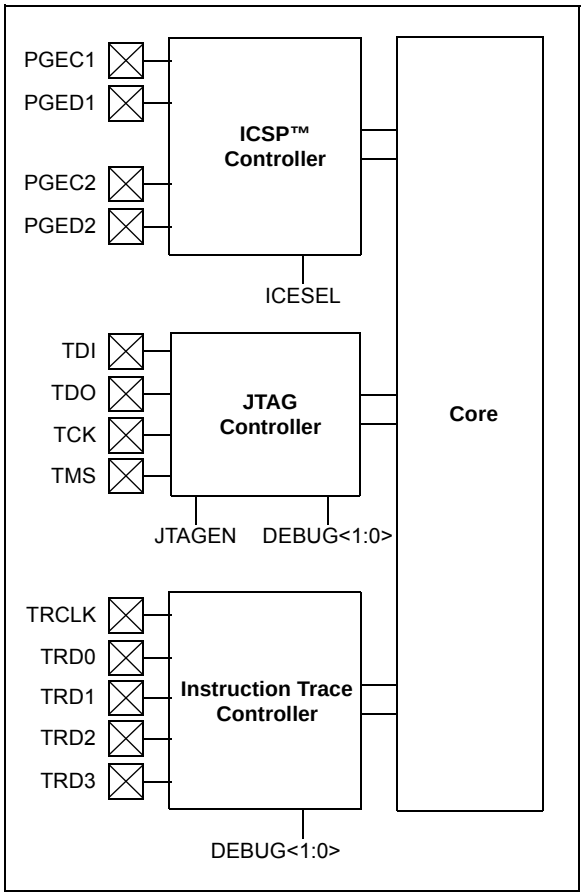


TABLE 36-11: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	**Sym.**	**Characteristic**	**Min.**	**Typ.**	**Max.**	**Units**	**Conditions(1)**
DO20a	VOH1	**Output High Voltage** I/O Pins: 4x Source Driver Pins - RA0, RA4, RA11, RA12, RA14, RA15 RB0-RB3, RB8, RB9 RC0, RC1, RC2, RC10, RC12, RC13 RD8, RD12-RD15 RE0, RE1, RE8, RE9 RF5, RF6, RF7, RF9, RF10, RF12, RF13 RG0, RG1, RG6-RG15	1.5	—	—	V	IOH ≥ -14 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -12 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -7 mA, VDD = 3.3V
		Output High Voltage I/O Pins: 8x Source Driver Pins - 8x Source Driver Pins - RA1, RA7, RA8, RA10 RB4-RB7, RB10-RB15 RC6, RC7, RC8, RC9, RC11, RC15 RD1-RD6 RE12-RE15 RF0, RF1	1.5	—	—	V	IOH ≥ -22 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -18 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -10 mA, VDD = 3.3V

Note 1: Parameters are characterized, but not tested.

FIGURE 36-16: CANx MODULE I/O TIMING CHARACTERISTICS

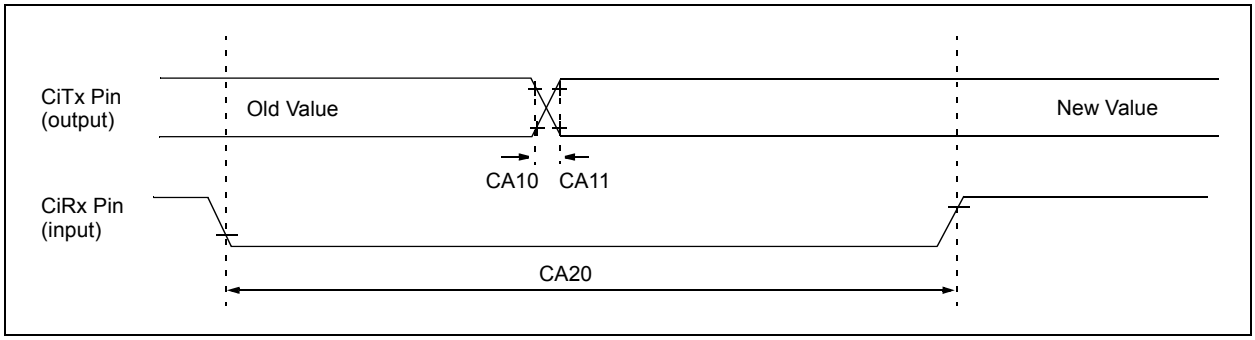


TABLE 36-38: CANx MODULE I/O TIMING REQUIREMENTS

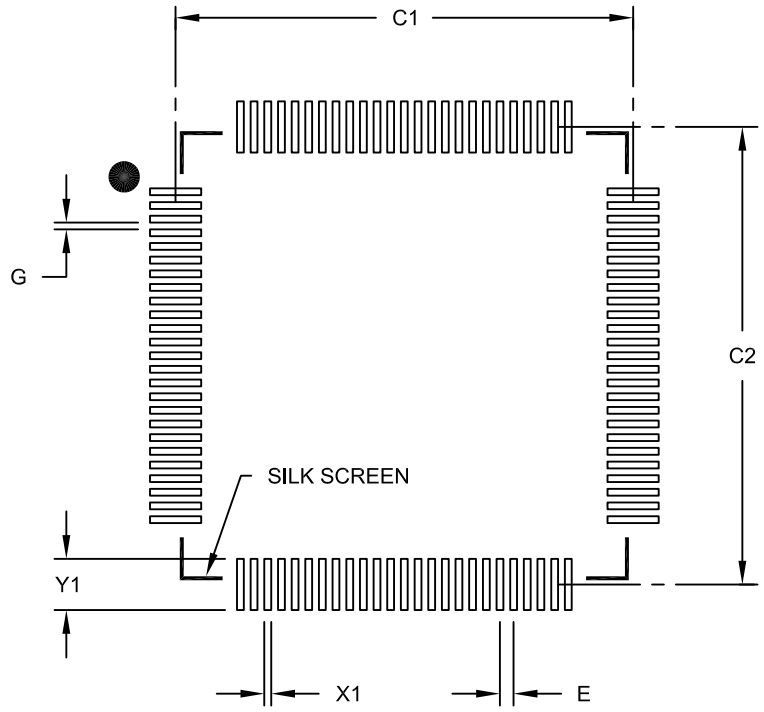
AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic(1)**	**Min.**	**Typ.(2)**	**Max.**	**Units**	**Conditions**
CA10	TioF	Port Output Fall Time	—	—	—	ns	See parameter DO32
CA11	TioR	Port Output Rise Time	—	—	—	ns	See parameter DO31
CA20	Tcwf	Pulse Width to Trigger CAN Wake-up Filter	700	—	—	ns	—

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

100-Lead Plastic Thin Quad Flatpack (PT)- 12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

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