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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, IrDA, LINbus, PMP, QEI, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, Motor Control PWM, WDT
Number of I/O	49
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 27x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic32mk0512mcf064-e-mr">https://www.e-xfl.com/product-detail/microchip-technology/pic32mk0512mcf064-e-mr</a>



## REGISTER 9-5: REFOxCON: REFERENCE OSCILLATOR CONTROL REGISTER ('x' = 1-4)

bit 3-0 ROSEL<3:0>: Reference Clock Source Select bits<sup>(3)</sup>

1111 = Reserved

•

•

•

1001 = Reserved

1000 = REFCLKI

0111 = SPLL

0110 = UPLL

0101 = Sosc

0100 = LPRC

0011 = FRC

0010 = Posc

0001 = PBCLK1

0000 = SYSCLK

**Note 1:** Do not write to this register when the ON bit is not equal to the ACTIVE bit.

**2:** This bit is ignored when the ROSEL<3:0> bits = 0000 or 0001.

**3:** The ROSEL<3:0> bits should not be written while the ACTIVE bit is '1', as undefined behavior may result.



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## REGISTER 12-8: UxEIR: USB ERROR INTERRUPT STATUS REGISTER ('x' = 1 AND 2)

- bit 1    **CRC5EF:** CRC5 Host Error Flag bit<sup>(4)</sup>  
    1 = Token packet rejected due to CRC5 error  
    0 = Token packet accepted  
**EOFEF:** EOF Error Flag bit<sup>(3,5)</sup>  
    1 = EOF error condition detected  
    0 = No EOF error condition
- bit 0    **PIDEF:** PID Check Failure Flag bit  
    1 = PID check failed  
    0 = PID check passed

- Note 1:** This type of error occurs when the module's request for the DMA bus is not granted in time to service the module's demand for memory, resulting in an overflow or underflow condition, and/or the allocated buffer size is not sufficient to store the received data packet causing it to be truncated.
- 2:** This type of error occurs when more than 16-bit-times of Idle from the previous End-of-Packet (EOP) has elapsed.
- 3:** This type of error occurs when the module is transmitting or receiving data and the SOF counter has reached zero.
- 4:** Device mode.
- 5:** Host mode.

**TABLE 13-2: OUTPUT PIN SELECTION (CONTINUED)**

RPn Port Pin	RPnR SFR	RPnR bits	RPnR Value to Peripheral Selection
RPA1	RPA1R	RPA1R<4:0>	00000 = Off 00001 = U3RTS
RPB5	RPB5R	RPB5R<4:0>	00010 = U4TX 00011 = SDO1
RPB1	RPB1R	RPB1R<4:0>	00100 = SDO2 00101 = OC2 00110 = OC8
RPB11	RPB11R	RPB11R<4:0>	00111 = C3OUT 01000 = OC9 01001 = OC12
RPA8	RPA8R	RPA8R<4:0>	01010 = OC16 01011 = U6RTS
RPC8	RPC8R	RPC8R<4:0>	01100 = C4TX 01101 = Reserved
RPB12	RPB12R	RPB12R<4:0>	01110 = SDO3 01111 = SDO4
RPA12	RPA12R	RPA12R<4:0>	10000 = SDO5 10001 = SCK6
RPD6	RPD6R	RPD6R<4:0>	10010 = REFCLKO3 10011 = Reserved
RPG7	RPG7R	RPG7R<4:0>	10100 = QEICMP2 10101 = QEICMP6
RPG0 <sup>(1)</sup>	RPG0R <sup>(1)</sup>	RPG0R<4:0> <sup>(1)</sup>	10110 = Reserved · · ·
RPE1 <sup>(1)</sup>	RPE1R <sup>(1)</sup>	RPE1R<4:0> <sup>(1)</sup>	11111 = Reserved
RPA14 <sup>(1)</sup>	RPA14R <sup>(1)</sup>	RPA14R<4:0> <sup>(1)</sup>	

**Note 1:** This selection is not available on 64-pin devices.



# **PIC32MK GP/MC Family**

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**NOTES:**

## 16.0 DEADMAN TIMER (DMT)

**Note:** This data sheet summarizes the features of the PIC32MK GP/MC family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 9. "Watchdog, Deadman, and Power-up Timers"** (DS60001114), which is available from the *Documentation > Reference Manual* section of the Microchip PIC32 web site ([www.microchip.com/pic32](http://www.microchip.com/pic32)).

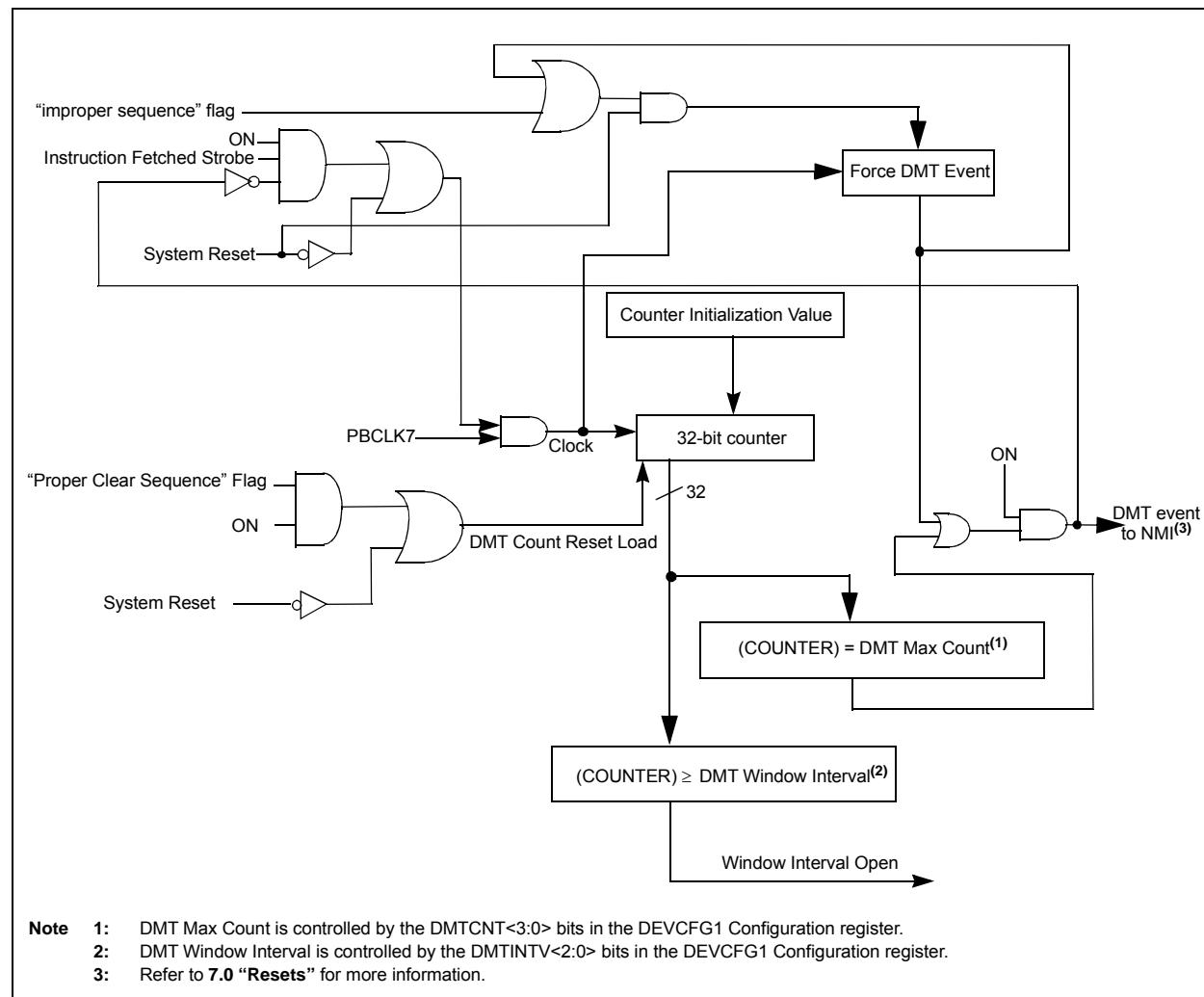
The primary function of the Deadman Timer (DMT) is to reset the processor in the event of a software malfunction. The DMT is a free-running instruction fetch timer, which is clocked whenever an instruction fetch occurs until a count match occurs. Instructions are not fetched when the processor is in Sleep mode.

The DMT consists of a 32-bit counter with a time-out count match value as specified by the DMTCNT<3:0> bits in the DEVCFG1 Configuration register.

A Deadman Timer is typically used in mission critical and safety critical applications, where any single failure of the software functionality and sequencing must be detected.

Figure 16-1 shows a block diagram of the Deadman Timer module.

**FIGURE 16-1: DEADMAN TIMER BLOCK DIAGRAM**





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## REGISTER 22-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 11	<b>RTSMD:</b> Mode Selection for UxRTS Pin bit 1 = UxRTS pin is in Simplex mode 0 = UxRTS pin is in Flow Control mode
bit 10	<b>Unimplemented:</b> Read as '0'
bit 9-8	<b>UEN&lt;1:0&gt;:</b> UARTx Enable bits <sup>(2)</sup> 11 = UxTX, UxRX and UxBCLK pins are enabled and used; UxCTS pin is controlled by corresponding bits in the PORTx register 10 = UxTX, UxRX, UxCTS and UxRTS pins are enabled and used 01 = UxTX, UxRX and UxRTS pins are enabled and used; UxCTS pin is controlled by corresponding bits in the PORTx register 00 = UxTX and UxRX pins are enabled and used; UxCTS and UxRTS/UxBCLK pins are controlled by corresponding bits in the PORTx register
bit 7	<b>WAKE:</b> Enable Wake-up on Start bit Detect During Sleep Mode bit 1 = Wake-up is enabled 0 = Wake-up is disabled
bit 6	<b>LPBACK:</b> UARTx Loopback Mode Select bit 1 = Loopback mode is enabled 0 = Loopback mode is disabled
bit 5	<b>ABAUD:</b> Auto-Baud Enable bit 1 = Enable baud rate measurement on the next reception of Sync character (0x55); cleared by hardware upon completion 0 = Baud rate measurement disabled or completed
bit 4	<b>RXINV:</b> Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	<b>BRGH:</b> High Baud Rate Enable bit 1 = High-Speed mode – 4x baud clock enabled 0 = Standard Speed mode – 16x baud clock enabled
bit 2-1	<b>PDSEL&lt;1:0&gt;:</b> Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	<b>STSEL:</b> Stop Selection bit 1 = 2 Stop bits 0 = 1 Stop bit

- Note 1:** These bits can be changed only when the ON bit (UxMODE<15>) is set to '0'.
- 2:** These bits are present for legacy compatibility, and are superseded by PPS functionality on these devices (see 13.3 “Peripheral Pin Select (PPS)” for more information).



## REGISTER 25-24: ADCTRG7: ADC TRIGGER SOURCE 7 REGISTER

- bit 23-21 **Unimplemented:** Read as '0'
- bit 20-16 **TRGSRC26<4:0>:** Trigger Source for Conversion of Analog Input AN26 Select bits  
See bits 28-24 for bit value definitions.
- bit 15-13 **Unimplemented:** Read as '0'
- bit 12-8 **TRGSRC25<4:0>:** Trigger Source for Conversion of Analog Input AN25 Select bits  
See bits 28-24 for bit value definitions.
- bit 7-5 **Unimplemented:** Read as '0'
- bit 4-0 **TRGSRC24<4:0>:** Trigger Source for Conversion of Analog Input AN24 Select bits  
See bits 28-24 for bit value definitions.

**Note:** This register is not available on 64-pin devices.



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## REGISTER 25-31: ADCDATAx: ADC OUTPUT DATA REGISTER 'x' ('x' = 0-27, 33-41, AND 45-53)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	DATA<31:24>							
23:16	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	DATA<23:16>							
15:8	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	DATA<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	DATA<7:0>							

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 31-0      **DATA<31:0>**: ADC Converted Data Output bits.

- Note 1:** The registers, ADCDATA23-20, ADCDATA41-33, and ADCDATA45-47, are not available on 64-pin devices.
- 2:** The registers, ADCDATA32-28 and ADCDATA44-42, are not available on 64-pin and 100-pin devices.
- 3:** When an alternate input is used as the input source for a dedicated ADC module, the data output is still read from the Primary input Data Output Register.
- 4:** Reading the ADCDATAx register value after changing the FRACT bit converts the data into the format specified by FRACT bit.

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## REGISTER 30-4: POSxCNT: POSITION COUNTER REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	POSCNT<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	POSCNT<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	POSCNT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	POSCNT<7:0>							

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

### bit 31-0 POSCNT<31:0>: 32-bit Position Counter Register bits

The Operating mode of the position counter is controlled by the CCM bit in the QEIxCON register.

**Quadrature Count mode:** The QEA and QEB inputs are decoded to generate count pulses and direction information for controlling the position counter operation.

**External Count with External Up/Down mode:** The QEA/EXTCNT input is treated as an external count signal, and the QEB/DIR/GATE input provides the count direction information.

**External Count with External Gate mode:** The QEA/EXTCNT input is treated as an external count signal. If the GATEN bit in the QEIxCON register is equal to '1', the QEB/DIR/GATE input will gate the counter signal.

**Internal Timer mode:** The position counter uses PBCLK2 divided by the clock divider INTDIV as the count source.



## 35.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/  
MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for  
Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICkit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,  
Evaluation Kits and Starter Kits
- Third-party development tools

## 35.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

### Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

### User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

### Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

### File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

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**TABLE 36-34: SPI<sub>x</sub> MODULE SLAVE MODE (CKE = 0, SMP = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	Symbol	Characteristics <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP9a	TSCK	SCK <sub>x</sub> Period	20	—	—	ns	(V <sub>DD</sub> ≥ 3.0V and the SMP bit (SPI <sub>x</sub> CON<9> = 1), I/O Pin Slew Rate Control (x = A-F, y = port pin), SRCON0x.y = 0, SRCON1x.y = 0 Dedicated SCK1 and SCK2 on RB7 and RB6, respectively or PPS remappable SPI onto pins RB5, RA1, and RB15.)
			27	—	—	ns	(V <sub>DD</sub> ≥ 3.0V and the SMP bit (SPI <sub>x</sub> CON<9> = 1), I/O Pin Slew Rate Control (x = A-F, y = port pin), SRCON0x.y = 1, SRCON1x.y = 0 Dedicated SCK1 and SCK2 on RB7 and RB6, respectively or PPS remappable SPI onto pins RB5, RA1, and RB15.)
			33	—	—	ns	(V <sub>DD</sub> ≥ 3.0V and the SMP bit (SPI <sub>x</sub> CON<9> = 1), I/O Pin Slew Rate Control (x = A-F, y = port pin), SRCON0x.y = 0, SRCON1x.y = 1 Dedicated SCK1 and SCK2 on RB7 and RB6, respectively or PPS remappable SPI onto pins RB5, RA1, and RB15.)
			39	—	—	ns	(V <sub>DD</sub> ≥ 3.0V and the SMP bit (SPI <sub>x</sub> CON<9> = 1), I/O Pin Slew Rate Control (x = A-F, y = port pin), SRCON0x.y = 1, SRCON1x.y = 1 Dedicated SCK1 and SCK2 on RB7 and RB6, respectively or PPS remappable SPI onto pins RB5, RA1, and RB15.)

**Note 1:** These parameters are characterized, but not tested in manufacturing.

**2:** Data in the “Typical” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

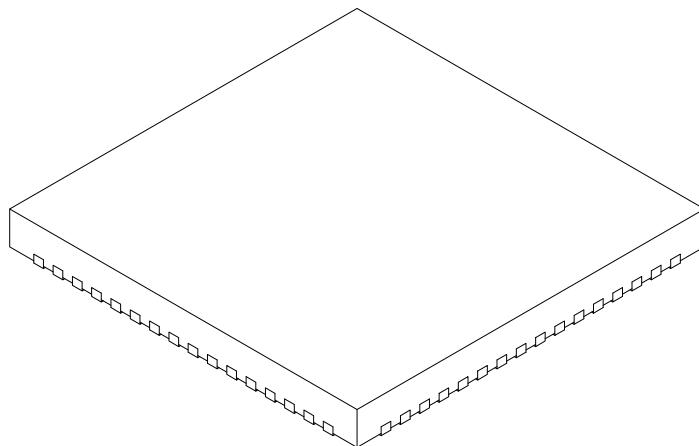
**3:** Assumes 10 pF load on all SPI<sub>x</sub> pins.



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## 64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body with 5.40 x 5.40 Exposed Pad [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension	Limits	UNITS MILLIMETERS		
		MIN	NOM	MAX
Number of Pins	N		64	
Pitch	e		0.50 BSC	
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3		0.20 REF	
Overall Width	E		9.00 BSC	
Exposed Pad Width	E2	5.30	5.40	5.50
Overall Length	D		9.00 BSC	
Exposed Pad Length	D2	5.30	5.40	5.50
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.30	0.40	0.50
Contact-to-Exposed Pad	K	0.20	-	-

### Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.