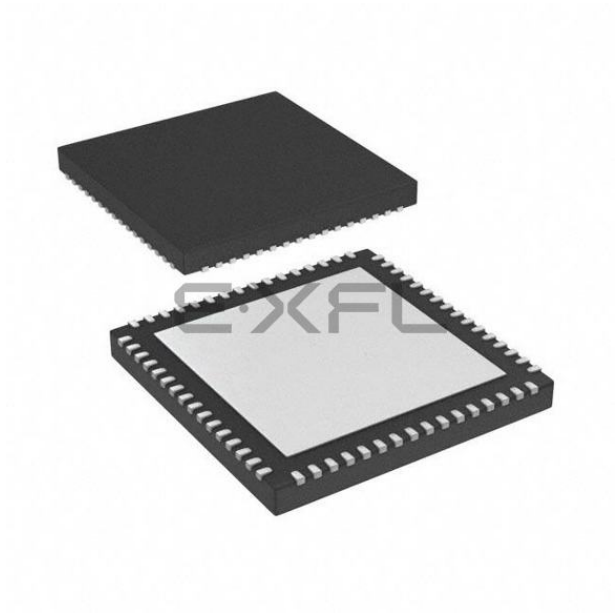

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, IrDA, LINbus, PMP, QEI, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, Motor Control PWM, WDT
Number of I/O	49
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 27x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mk0512mcf064t-i-mr

TABLE 8-3: INTERRUPT IRQ, VECTOR AND BIT LOCATION

Interrupt Source(1)	XC32 Vector Name	IRQ #	Vector #	Interrupt Bit Location				Persistent Interrupt
				Flag	Enable	Priority	Sub-priority	
Highest Natural Order Priority								
Core Timer Interrupt	_CORE_TIMER_VECTOR	0	OFF000<17:1>	IFS0<0>	IEC0<0>	IPC0<4:2>	IPC0<1:0>	No
Core Software Interrupt 0	_CORE_SOFTWARE_0_VECTOR	1	OFF001<17:1>	IFS0<1>	IEC0<1>	IPC0<12:10>	IPC0<9:8>	No
Core Software Interrupt 1	_CORE_SOFTWARE_1_VECTOR	2	OFF002<17:1>	IFS0<2>	IEC0<2>	IPC0<20:18>	IPC0<17:16>	No
External Interrupt 0	_EXTERNAL_0_VECTOR	3	OFF003<17:1>	IFS0<3>	IEC0<3>	IPC0<28:26>	IPC0<25:24>	No
Timer1	_TIMER_1_VECTOR	4	OFF004<17:1>	IFS0<4>	IEC0<4>	IPC1<4:2>	IPC1<1:0>	No
Input Capture 1 Error	_INPUT_CAPTURE_1_ERROR_VECTOR	5	OFF005<17:1>	IFS0<5>	IEC0<5>	IPC1<12:10>	IPC1<9:8>	Yes
Input Capture 1	_INPUT_CAPTURE_1_VECTOR	6	OFF006<17:1>	IFS0<6>	IEC0<6>	IPC1<20:18>	IPC1<17:16>	Yes
Output Compare 1	_OUTPUT_COMPARE_1_VECTOR	7	OFF007<17:1>	IFS0<7>	IEC0<7>	IPC1<28:26>	IPC1<25:24>	No
External Interrupt 1	_EXTERNAL_1_VECTOR	8	OFF008<17:1>	IFS0<8>	IEC0<8>	IPC2<4:2>	IPC2<1:0>	No
Timer2	_TIMER_2_VECTOR	9	OFF009<17:1>	IFS0<9>	IEC0<9>	IPC2<12:10>	IPC2<9:8>	No
Input Capture 2 Error	_INPUT_CAPTURE_2_ERROR_VECTOR	10	OFF010<17:1>	IFS0<10>	IEC0<10>	IPC2<20:18>	IPC2<17:16>	Yes
Input Capture 2	_INPUT_CAPTURE_2_VECTOR	11	OFF011<17:1>	IFS0<11>	IEC0<11>	IPC2<28:26>	IPC2<25:24>	Yes
Output Compare 2	_OUTPUT_COMPARE_2_VECTOR	12	OFF012<17:1>	IFS0<12>	IEC0<12>	IPC3<4:2>	IPC3<1:0>	No
External Interrupt 2	_EXTERNAL_2_VECTOR	13	OFF013<17:1>	IFS0<13>	IEC0<13>	IPC3<12:10>	IPC3<9:8>	No
Timer3	_TIMER_3_VECTOR	14	OFF014<17:1>	IFS0<14>	IEC0<14>	IPC3<20:18>	IPC3<17:16>	No
Input Capture 3 Error	_INPUT_CAPTURE_3_ERROR_VECTOR	15	OFF015<17:1>	IFS0<15>	IEC0<15>	IPC3<28:26>	IPC3<25:24>	Yes
Input Capture 3	_INPUT_CAPTURE_3_VECTOR	16	OFF016<17:1>	IFS0<16>	IEC0<16>	IPC4<4:2>	IPC4<1:0>	Yes
Output Compare 3	_OUTPUT_COMPARE_3_VECTOR	17	OFF017<17:1>	IFS0<17>	IEC0<17>	IPC4<12:10>	IPC4<9:8>	No
External Interrupt 3	_EXTERNAL_3_VECTOR	18	OFF018<17:1>	IFS0<18>	IEC0<18>	IPC4<20:18>	IPC4<17:16>	No
Timer4	_TIMER_4_VECTOR	19	OFF019<17:1>	IFS0<19>	IEC0<19>	IPC4<28:26>	IPC4<25:24>	No
Input Capture 4 Error	_INPUT_CAPTURE_4_ERROR_VECTOR	20	OFF020<17:1>	IFS0<20>	IEC0<20>	IPC5<4:2>	IPC5<1:0>	Yes
Input Capture 4	_INPUT_CAPTURE_4_VECTOR	21	OFF021<17:1>	IFS0<21>	IEC0<21>	IPC5<12:10>	IPC5<9:8>	Yes
Output Compare 4	_OUTPUT_COMPARE_4_VECTOR	22	OFF022<17:1>	IFS0<22>	IEC0<22>	IPC5<20:18>	IPC5<17:16>	No
External Interrupt 4	_EXTERNAL_4_VECTOR	23	OFF023<17:1>	IFS0<23>	IEC0<23>	IPC5<28:26>	IPC5<25:24>	No
Timer5	_TIMER_5_VECTOR	24	OFF024<17:1>	IFS0<24>	IEC0<24>	IPC6<4:2>	IPC6<1:0>	No
Input Capture 5 Error	_INPUT_CAPTURE_5_ERROR_VECTOR	25	OFF025<17:1>	IFS0<25>	IEC0<25>	IPC6<12:10>	IPC6<9:8>	Yes
Input Capture 5	_INPUT_CAPTURE_5_VECTOR	26	OFF026<17:1>	IFS0<26>	IEC0<26>	IPC6<20:18>	IPC6<17:16>	Yes
Output Compare 5	_OUTPUT_COMPARE_5_VECTOR	27	OFF027<17:1>	IFS0<27>	IEC0<27>	IPC6<28:26>	IPC6<25:24>	No
Reserved	—	28	—	—	—	—	—	—

Note 1: Not all interrupt sources are available on all devices. See **TABLE 1: "PIC32MK General Purpose (GP) Family Features"** for the list of available peripherals.

2: This interrupt source is not available on 64-pin devices.

3: This interrupt source is not available on 100-pin devices.

REGISTER 8-7: IPCx: INTERRUPT PRIORITY CONTROL REGISTER 'x' ('x' = 0-63) (CONTINUED)

bit 12-10 **IP1<2:0>:** Interrupt Priority bits
- 111 = Interrupt priority is 7
- •
- •
- •
- 010 = Interrupt priority is 2
- 001 = Interrupt priority is 1
- 000 = Interrupt is disabled

bit 9-8 **IS1<1:0>:** Interrupt Subpriority bits
- 11 = Interrupt subpriority is 3
- 10 = Interrupt subpriority is 2
- 01 = Interrupt subpriority is 1
- 00 = Interrupt subpriority is 0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-2 **IP0<2:0>:** Interrupt Priority bits
- 111 = Interrupt priority is 7
- •
- •
- •
- 010 = Interrupt priority is 2
- 001 = Interrupt priority is 1
- 000 = Interrupt is disabled

bit 1-0 **IS0<1:0>:** Interrupt Subpriority bits
- 11 = Interrupt subpriority is 3
- 10 = Interrupt subpriority is 2
- 01 = Interrupt subpriority is 1
- 00 = Interrupt subpriority is 0

Note: This register represents a generic definition of the IPCx register. Refer to Table 8-3 for the exact bit definitions.

REGISTER 9-3: SPLLCON: SYSTEM PLL CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	R/W-y	R/W-y	R/W-y
	—	—	—	—	—	PLLODIV<2:0>		
23:16	U-0	R/W-y	R/W-y	R/W-y	R/W-y	R/W-y	R/W-y	R/W-y
	—	PLLMULT<6:0>						
15:8	U-0	U-0	U-0	U-0	U-0	R/W-y	R/W-y	R/W-y
	—					PLLIDIV<2:0>		
7:0	R/W-y	U-0	U-0	U-0	U-0	R/W-y	R/W-y	R/W-y
	PLLICLK	—	—	—	—	PLLRANGE<2:0>		

Legend:	y = Value set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-27 **Unimplemented:** Read as '0'

bit 26-24 **PLLODIV<2:0>:** System PLL Output Clock Divider bits

111 = Reserved
110 = Reserved
101 = PLL Divide by 32
100 = PLL Divide by 16
011 = PLL Divide by 8
010 = PLL Divide by 4
001 = PLL Divide by 2
000 = Reserved

The default setting is specified by the FPLLODIV<2:0> Configuration bits in the DEVCFG2 register. Refer to Register 33-5 in **33.0 "Special Features"** for information.

bit 23 **Unimplemented:** Read as '0'

bit 22-16 **PLLMULT<6:0>:** System PLL Multiplier bits

1111111 = Multiply by 128
1111110 = Multiply by 127
1111101 = Multiply by 126
1111100 = Multiply by 125
•
•
•
0000000 = Multiply by 1

The default setting is specified by the FPLLMULT<6:0> Configuration bits in the DEVCFG2 register. Refer to Register 33-5 in **33.0 "Special Features"** for information.

bit 15-11 **Unimplemented:** Read as '0'

Note 1: Writes to this register require an unlock sequence. Refer to **Section 42. "Oscillators with Enhanced PLL"** (DS60001250) in the *"PIC32 Family Reference Manual"* for details.

2: Writes to this register are not allowed if the SPLL is selected as a clock source (COSC<2:0> = 001).

3: While the PLL is active, and if updating the PLL bits in the OSCCON register at run-time, the user application must remain within the following limits at all times for all nodes in the PLL clock tree. Therefore, the order in which the PLL values may be modified, (i.e., PLLODIV, PLLMULT, PLLODIV) becomes important. Failure to maintain PLL nodes within min/max ranges may result in unstable PLL and system behavior.

- Output and input to PLLIDIV block (i.e., FPLLI) 5 MHz to 64 MHz (min/max at all times)
- VCO output, (i.e., FVCO) 350 MHz to 700 MHz (min/max at all times)
- Output of PLLODIV, (i.e., FPLL) 10 MHz to 120 MHz (min/max at all times)

REGISTER 11-4: DCRCCON: DMA CRC CONTROL REGISTER (CONTINUED)

bit 6 **CRCAPP:** CRC Append Mode bit(1)
- 1 = The DMA transfers data from the source into the CRC but NOT to the destination. When a block transfer completes the DMA writes the calculated CRC value to the location given by CHxDSA
- 0 = The DMA transfers data from the source through the CRC obeying WBO as it writes the data to the destination

bit 5 **CRCTYP:** CRC Type Selection bit
- 1 = The CRC module will calculate an IP header checksum
- 0 = The CRC module will calculate a LFSR CRC

bit 4-3 **Unimplemented:** Read as '0'

bit 2-0 **CRCCH<2:0>:** CRC Channel Select bits
- 111 = CRC is assigned to Channel 7
- 110 = CRC is assigned to Channel 6
- 101 = CRC is assigned to Channel 5
- 100 = CRC is assigned to Channel 4
- 011 = CRC is assigned to Channel 3
- 010 = CRC is assigned to Channel 2
- 001 = CRC is assigned to Channel 1
- 000 = CRC is assigned to Channel 0

Note 1: When WBO = 1, unaligned transfers are not supported and the CRCAPP bit cannot be set.
2: The maximum CRC length supported by the DMA module is 32.
3: This bit is unused when CRCTYP is equal to '1'.

REGISTER 11-16: DCHxCSIZ: DMA CHANNEL x CELL-SIZE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CHCSIZ<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CHCSIZ<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **CHCSIZ<15:0>:** Channel Cell-Size bits

1111111111111111 = 65,535 bytes transferred on an event
•
•
•
0000000000000010 = 2 bytes transferred on an event
0000000000000001= 1 byte transferred on an event
0000000000000000 = 65,536 bytes transferred on an event

TABLE 13-2: OUTPUT PIN SELECTION (CONTINUED)

RPn Port Pin	RPnR SFR	RPnR bits	RPnR Value to Peripheral Selection
RPB6	RPB6R	RPB6R<4:0>	00000 = Off 00001 = U3TX 00010 = U4RTS 00011 = SS1 00100 = Reserved 00101 = OC4 00110 = OC5 00111 = REFCLKO1 01000 = C5OUT 01001 = OC10 01010 = OC14 01011 = U6TX 01100 = C3TX 01101 = Reserved 01110 = SS3 01111 = SS4 10000 = SS5 10001 = SDO6 10010 = REFCLKO2 10011 = Reserved 10100 = QEICMP3 10101 = Reserved . . . 11111 = Reserved
RPC15	RPC15R	RPC15R<4:0>	
RPA4	RPA4R	RPA4R<4:0>	
RPB13	RPB13R	RPB13R<4:0>	
RPB2	RPB2R	RPB2R<4:0>	
RPC6	RPC6R	RPC6R<4:0>	
RPC1	RPC1R	RPC1R<4:0>	
RPA7	RPA7R	RPA7R<4:0>	
RPE14	RPE14R	RPE14R<4:0>	
RPG8	RPG8R	RPG8R<4:0>	
RPF0	RPF0R	RPF0R<4:0>	
RPD4(1)	RPD4R(1)	RPD4R<4:0> (1)	

Note 1: This selection is not available on 64-pin devices.

REGISTER 22-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
1 = $\overline{\text{UxRTS}}$ pin is in Simplex mode
0 = $\overline{\text{UxRTS}}$ pin is in Flow Control mode

bit 10 **Unimplemented:** Read as '0'

bit 9-8 **UEN<1:0>:** UARTx Enable bits(2)
11 = UxTX, UxRX and UxBCLK pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by corresponding bits in the PORTx register
10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by corresponding bits in the PORTx register
00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$/UxBCLK pins are controlled by corresponding bits in the PORTx register

bit 7 **WAKE:** Enable Wake-up on Start bit Detect During Sleep Mode bit
1 = Wake-up is enabled
0 = Wake-up is disabled

bit 6 **LPBACK:** UARTx Loopback Mode Select bit
1 = Loopback mode is enabled
0 = Loopback mode is disabled

bit 5 **ABAUD:** Auto-Baud Enable bit
1 = Enable baud rate measurement on the next reception of Sync character (0x55); cleared by hardware upon completion
0 = Baud rate measurement disabled or completed

bit 4 **RXINV:** Receive Polarity Inversion bit
1 = UxRX Idle state is '0'
0 = UxRX Idle state is '1'

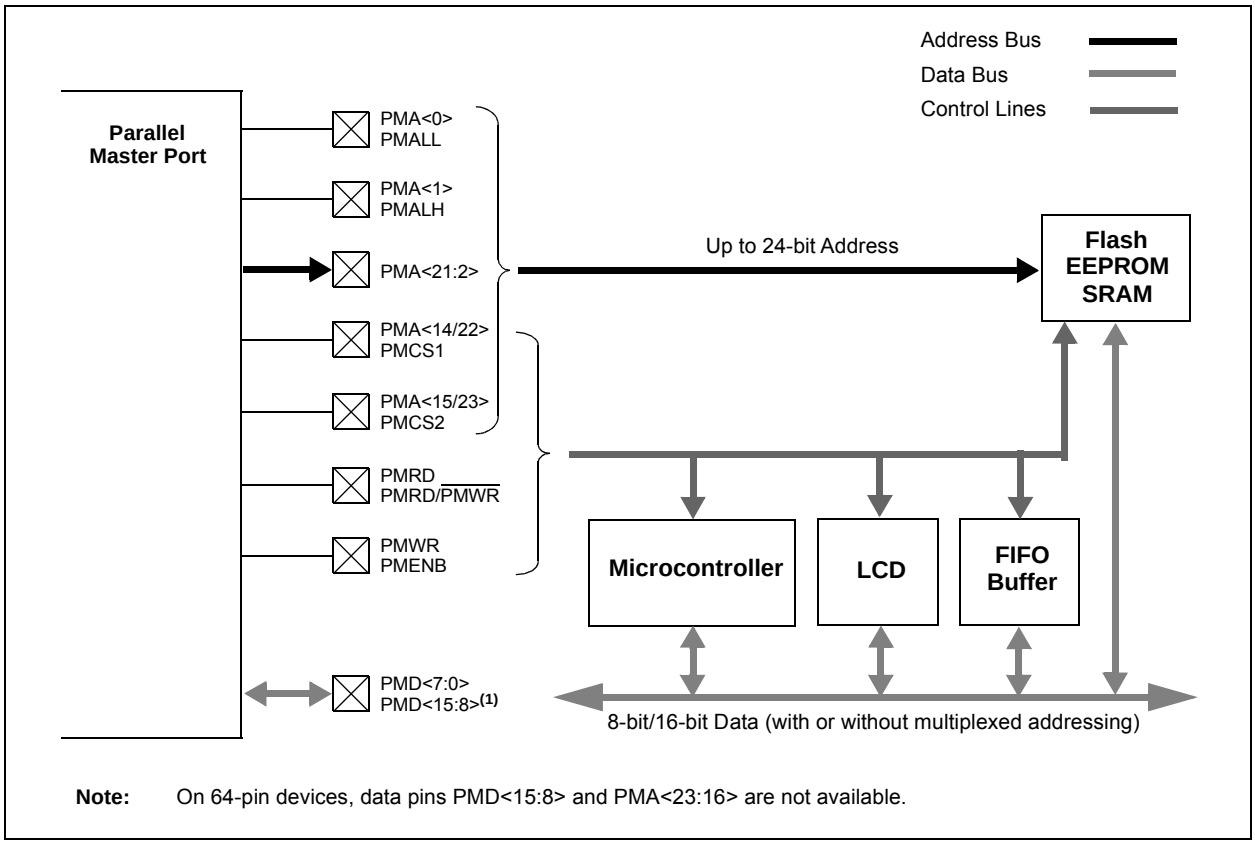
bit 3 **BRGH:** High Baud Rate Enable bit
1 = High-Speed mode – 4x baud clock enabled
0 = Standard Speed mode – 16x baud clock enabled

bit 2-1 **PDSEL<1:0>:** Parity and Data Selection bits
11 = 9-bit data, no parity
10 = 8-bit data, odd parity
01 = 8-bit data, even parity
00 = 8-bit data, no parity

bit 0 **STSEL:** Stop Selection bit
1 = 2 Stop bits
0 = 1 Stop bit

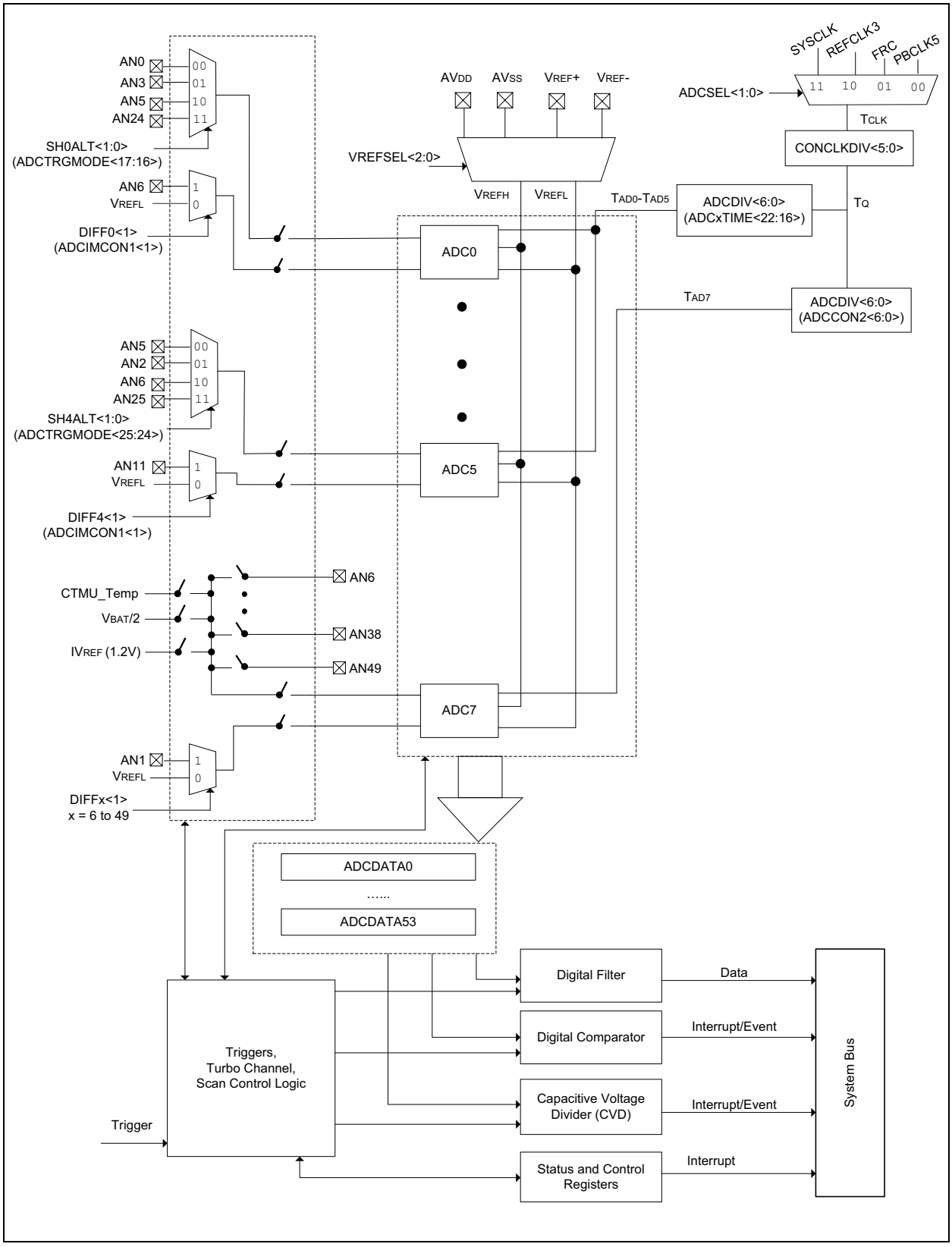
Note 1: These bits can be changed only when the ON bit (UxMODE<15>) is set to '0'.
2: These bits are present for legacy compatibility, and are superseded by PPS functionality on these devices (see **13.3 "Peripheral Pin Select (PPS)"** for more information).

FIGURE 23-1: PMP MODULE PINOUT AND CONNECTIONS TO EXTERNAL DEVICES



Note: On 64-pin devices, data pins PMD<15:8> and PMA<23:16> are not available.

FIGURE 25-1: ADC BLOCK DIAGRAM



REGISTER 25-18: ADCTRG1: ADC TRIGGER SOURCE 1 REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	TRGSRC3<4:0>				
23:16	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	TRGSRC2<4:0>				
15:8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	TRGSRC1<4:0>				
7:0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	TRGSRC0<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-29 **Unimplemented:** Read as '0'

bit 28-24 **TRGSRC3<4:0>:** Trigger Source for Conversion of ADC3 Module Select bits
- 11111 = Reserved
- 11110 = Reserved
- 11101 = PWM Generator 6 Current-Limit (Motor Control Variants Only)
- 11100 = PWM Generator 5 Current-Limit (Motor Control Variants Only)
- 11011 = PWM Generator 4 Current-Limit (Motor Control Variants Only)
- 11010 = PWM Generator 3 Current-Limit (Motor Control Variants Only)
- 11001 = PWM Generator 2 Current-Limit (Motor Control Variants Only)
- 11000 = PWM Generator 1 Current-Limit (Motor Control Variants Only)
- 10111 = Reserved
- 10110 = Reserved
- 10101 = Reserved
- 10100 = CTMU trip
- 10011 = Output Compare 4 (Rising Edge Only)
- 10010 = Output Compare 3 (Rising Edge Only)
- 10001 = Output Compare 2 (Rising Edge Only)
- 10000 = Output Compare 1 (Rising Edge Only)
- 01111 = PWM Generator 6 trigger (Motor Control Variants Only)
- 01110 = PWM Generator 5 trigger (Motor Control Variants Only)
- 01101 = PWM Generator 4 trigger (Motor Control Variants Only)
- 01100 = PWM Generator 3 trigger (Motor Control Variants Only)
- 01011 = PWM Generator 2 trigger (Motor Control Variants Only)
- 01010 = PWM Generator 1 trigger (Motor Control Variants Only)
- 01001 = Secondary Special Event trigger (Motor Control Variants Only)
- 01000 = Primary Special Event trigger (Motor Control Variants Only)
- 00111 = General Purpose Timer5
- 00110 = General Purpose Timer3
- 00101 = General Purpose Timer1
- 00100 = INT0
- 00011 = Scan trigger (see **Note**)
- 00010 = Software level trigger
- 00001 = Software edge trigger
- 00000 = No Trigger

Note: For Scan Trigger, in addition to setting the trigger, it also requires programming of the STRGSRC<4:0> bits (ADCCON1<20:16>) to select the trigger source, and requires the appropriate CSS bits to be set in the ADCCSSx registers.

bit 23-21 **Unimplemented:** Read as '0'

REGISTER 26-9: CxRXMn: CAN ACCEPTANCE FILTER MASK 'n' REGISTER ('x' = 1-4; 'n' = 0, 1, 2 OR 3)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	SID<10:3>							
23:16	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0
	SID<2:0>			—	MIDE	—	EID<17:16>	
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	EID<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	EID<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-21 **SID<10:0>:** Standard Identifier bits
1 = Include the SIDx bit in filter comparison
0 = The SIDx bit is a 'don't care' in filter operation

bit 20 **Unimplemented:** Read as '0'

bit 19 **MIDE:** Identifier Receive Mode bit
1 = Match only message types (standard/extended address) that correspond to the EXID bit in filter
0 = Match either standard or extended address message if filters match (that is, if (Filter SID) = (Message SID) or if (FILTER SID/EID) = (Message SID/EID))

bit 18 **Unimplemented:** Read as '0'

bit 17-0 **EID<17:0>:** Extended Identifier bits
1 = Include the EIDx bit in filter comparison
0 = The EIDx bit is a 'don't care' in filter operation

Note: This register can only be modified when the CAN module is in Configuration mode (OPMOD<2:0> (CxCON<23:21>) = 100).

REGISTER 26-16: CxFIFOCONn: CAN FIFO CONTROL REGISTER 'n' ('x' = 1-4;'n' = 0 THROUGH 15)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	FSIZE<4:0>(1)				
15:8	U-0	S/HC-0	S/HC-0	R/W-0	U-0	U-0	U-0	U-0
	—	FRESET	UINC	DONLY(1)	—	—	—	—
7:0	R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
	TXEN	TXABAT(2)	TXLARB(3)	TXERR(3)	TXREQ	RTREN	TXPR<1:0>	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-21 **Unimplemented:** Read as '0'

bit 20-16 **FSIZE<4:0>:** FIFO Size bits(1)

11111 = FIFO is 32 messages deep

•

•

•

00010 = FIFO is 3 messages deep

00001 = FIFO is 2 messages deep

00000 = FIFO is 1 message deep

bit 15 **Unimplemented:** Read as '0'

bit 14 **FRESET:** FIFO Reset bits

1 = FIFO will be reset when bit is set, cleared by hardware when FIFO is reset. After setting, the user should poll whether this bit is clear before taking any action.

0 = No effect

bit 13 **UINC:** Increment Head/Tail bit

TXEN = 1: (FIFO configured as a Transmit FIFO)
When this bit is set the FIFO head will increment by a single message

TXEN = 0: (FIFO configured as a Receive FIFO)
When this bit is set the FIFO tail will increment by a single message

bit 12 **DONLY:** Store Message Data Only bit(1)

TXEN = 1: (FIFO configured as a Transmit FIFO)
This bit is not used and has no effect.

TXEN = 0: (FIFO configured as a Receive FIFO)
1 = Only data bytes will be stored in the FIFO
0 = Full message is stored, including identifier

bit 11-8 **Unimplemented:** Read as '0'

Note 1: These bits can only be modified when the CAN module is in Configuration mode (OPMOD<2:0> bits (CxCON<23:21>) = 100).

2: This bit is updated when a message completes (or aborts) or when the FIFO is reset.

3: This bit is reset on any read of this register or when the FIFO is reset.

REGISTER 30-1: QEIxCON: QEIx CONTROL REGISTER (CONTINUED)

bit 6-4 **INTDIV<2:0>:** Timer Input Clock Prescale Select bits (Interval timer, Main timer (position counter), velocity counter and index counter internal clock divider select)(3)

111 = 1:128 prescale value
110 = 1:64 prescale value
101 = 1:32 prescale value
100 = 1:16 prescale value
011 = 1:8 prescale value
010 = 1:4 prescale value
001 = 1:2 prescale value
000 = 1:1 prescale value

bit **CNTPOL:** Position and Index Counter/Timer Direction Select bit

1 = Counter direction is negative unless modified by external Up/Down signal
0 = Counter direction is positive unless modified by external Up/Down signal

bit **GATEN:** External Count Gate Enable bit

1 = External gate signal controls position counter operation
0 = External gate signal does not affect position counter/timer operation

bit **CCM<1:0>:** Counter Control Mode Selection bits

11 = Internal Timer mode with optional QEB external clock gating input control based on GATEN.
QEB High = Timer Run, QEB Low = Timer Stop.
10 = QEA is the external clock input, QEB is optional clock gating input control based on GATEN.
QEB High = Clock Run, QEB Low = Clock Stop.
01 = QEA is the external clock input, QEB is external UP/DN direction input.
QEB High = Count Up, QEB Low = Count Down
00 = Quadrature Encoder Interface Count mode (x4 mode)

Note 1: When CCM equals modes '01', '10', and '11', all of the QEI counters operate as timers and the PIMOD<2:0> bits are ignored.

2: When CCM = 00 and QEA and QEB values match Index Match Value (IMV), the POSxCNTH and POSxCNTL registers are reset.

3: The selected clock rate should be at least twice the expected maximum quadrature count rate.

REGISTER 30-6: VELxHLD: VELOCITY HOLD REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	VELHLD<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	VELHLD<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	VELHLD<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	VELHLD<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **VELHLD<31:0>:** 32-bit Velocity Hold bits
When VELxCNT is read, the contents are captured at the same time into the VELxHLD register.

REGISTER 30-7: INTxHLD: INTERVAL TIMER HOLD REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	INTHLD<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	INTHLD<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	INTHLD<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	INTHLD<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **INTHLD<31:0>:** 32-bit Index Counter Hold bits
When the next count pulse is detected, the current contents of the interval timer (INTxTMR) are transferred to the Interval Hold register (INTxHLD) and the interval timer is cleared and the process repeats.

REGISTER 33-4: DEVCFG1: DEVICE CONFIGURATION WORD 1 (CONTINUED)

bit 2-0 **FNOSC<2:0>:** Oscillator Selection bits

111 = Reserved
110 = Reserved
101 = Low-Power RC Oscillator (LPRC)
100 = Secondary Oscillator (SOSC)
011 = USB PLL (UPLL Module) (input clock and divider set by UPLLCON)
010 = Primary Oscillator (POSC) (HS, EC)
001 = System PLL (SPLL Module) (input clock and divider set by SPLLCON)
000 = Fast RC Oscillator (FRC) divided by the FRCDIV<2:0> bits (OSCCON<26:24>)
(supports FRC / n, where n = 1, 2, 4, 8, 16, 32, 64, 256

35.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

35.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

35.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

35.9 PICkit 3 In-Circuit Debugger/ Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

35.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at V_{DDMIN} and V_{DDMAX} for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

36.2 AC Characteristics and Timing Parameters

The information contained in this section defines PIC32MK GP/MC device AC characteristics and timing parameters.

FIGURE 36-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

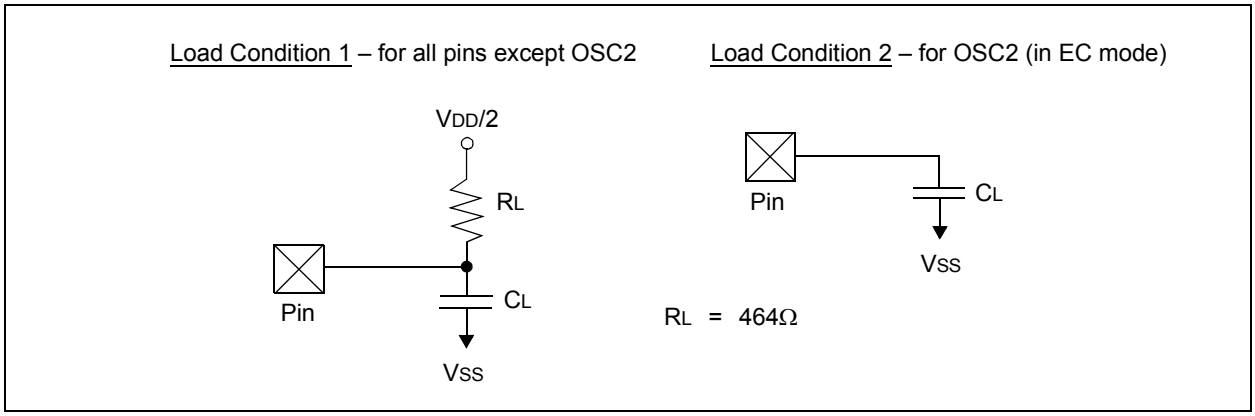


TABLE 36-14: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Symbol**	**Characteristics**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
DO56	CL	All I/O pins	—	—	50	pF	—

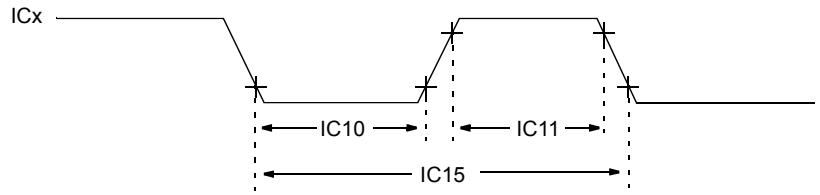
Note 1: Data in the "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 36-25: TIMER2-TIMER9 EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS				Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Symbol**	**Characteristics(1)**		**Min.**	**Max.**	**Units**	**Conditions**	
TB10	TTXH	TxCK High Time	Synchronous, with prescaler	[(12.5 ns or 1 TPBCLK3) /N] + 25 ns	—	ns	Must also meet parameter TB15	N = prescale value (1, 2, 4, 8, 16, 32, 64, 256)
TB11	TTXL	TxCK Low Time	Synchronous, with prescaler	[(12.5 ns or 1 TPBCLK3) /N] + 25 ns	—	ns	Must also meet parameter TB15	
TB15	TTXP	TxCK Input Period	Synchronous, with prescaler	[(Greater of [(25 ns or 2 TPBCLK3)/N] + 30 ns	—	ns	VDD > 2.7V	
				[(Greater of [(25 ns or 2 TPBCLK3)/N] + 50 ns	—	ns	VDD < 2.7V	
TB20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		—	1	TPBCLK3	—	

Note 1: These parameters are characterized, but not tested in manufacturing.

FIGURE 36-7: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS



Note: Refer to Figure 36-1 for load conditions.

TABLE 36-26: INPUT CAPTURE MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Symbol**	**Characteristics(1)**	**Min.**	**Max.**	**Units**	**Conditions**	
IC10	TCCL	ICx Input Low Time	((TPBCLKx/N) + 25 ns)	—	ns	Must also meet parameter IC15.	x = 2 for IC1-IC9 x = 3 for IC10-IC16 N = prescale value (1, 4, 16)
IC11	TCCH	ICx Input High Time	((TPBCLKx/N) + 25 ns)	—	ns	Must also meet parameter IC15.	
IC15	TCCP	ICx Input Period	((TPBCLKx/N) + 50 ns)	—	ns	—	

Note 1: These parameters are characterized, but not tested in manufacturing.

TABLE 36-40: ANALOG-TO-DIGITAL CONVERSION TIMING REQUIREMENTS

AC CHARACTERISTICS(2)			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	**Symbol**	**Characteristics**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
Clock Parameters							
AD50	TAD	ADC Clock Period	16.667	—	6250	ns	—
Throughput Rate							
AD51	FTP	Sample Rate for ADC0-ADC5 (Class 1 Inputs)	— — — —	— — — —	3.75 4.284 4.992 6	Msps Msps Msps Msps	12-bit resolution Source Impedance ≤ 200Ω 10-bit resolution Source Impedance ≤ 200Ω 8-bit resolution Source Impedance ≤ 200Ω 6-bit resolution Source Impedance ≤ 200Ω
		Sample Rate for ADC7 (Class 2 and Class 3 Inputs)	— — — —	— — — —	3.53 4.00 4.615 5.45	Msps Msps Msps Msps	12-bit resolution Source Impedance ≤ 200Ω 10-bit resolution Source Impedance ≤ 200Ω 8-bit resolution Source Impedance ≤ 200Ω 6-bit resolution Source Impedance ≤ 200Ω
Timing Parameters							
AD60	TSAMP	Sample Time for ADC0-ADC5 (Class 1 Inputs)	3 4 5 13	—	—	TAD	Source Impedance ≤ 200Ω, Max ADC clock Source Impedance ≤ 500Ω, Max ADC clock Source Impedance ≤ 1 KΩ, Max ADC clock Source Impedance ≤ 5 KΩ, Max ADC clock
		Sample Time for ADC7 (Class 2 and Class 3 Inputs)	4 5 6 14	—	—	TAD	Source Impedance ≤ 200Ω, Max ADC clock Source Impedance ≤ 500Ω, Max ADC clock Source Impedance ≤ 1 KΩ, Max ADC clock Source Impedance ≤ 5 KΩ, Max ADC clock
		Sample Time for ADC7 (Class 2 and Class 3 Inputs)	See Table 36-41	—	—	TAD	CVDEN (ADCCON1<11>) = 1
AD62	TCONV	Conversion Time (after sample time is complete)	— — — —	— — — —	13 11 9 7	TAD	12-bit resolution 10-bit resolution 8-bit resolution 6-bit resolution
AD65	TWAKE	Wake-up time from Low-Power Mode	— —	500 20	— —	TAD µs	Lesser of 500 TAD or 20 µs

Note 1: These parameters are characterized, but not tested in manufacturing.

2: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is guaranteed, but not characterized.

Revision E (April 2018)

This revision includes the following major changes, which are referenced by their respective chapter in Table A-3.

In addition, minor updates to text and formatting were incorporated throughout the document.

TABLE A-3: MAJOR SECTION UPDATES

Section Name	Update Description
"32-bit General Purpose and Motor Control Application MCUs with FPU and up to 1 MB Live-Update Flash, 256 KB SRAM, 4 KB EEPROM, and Op amps"	The 120 MHz Operating Conditions were updated. Secure boot was removed from the Security Features. The FRC internal oscillator Clock Management operating conditions were updated. The number of ADC channels for 64-pin TQFP and QFN Motor Control devices was updated (see Table 2).
1.0 "Device Overview"	The I2Cx and PLVD references were removed from the PIC32MK GP/MC Family Block Diagram (see Figure 1-1).
5.0 "Flash Program Memory"	The Wait state bits, LPRDWS<4:0> (NVMCON2), were updated to include a table with low-power Wait state information (see Register 5-8).
10.0 "Prefetch Module"	The Wait states table in the PFMWS<2:0> bits (CHECON<2:0>) was updated (see Register 10-1).
11.0 "Direct Memory Access (DMA) Controller"	A note was added to the CHSIRQ<7:0> bits (DCHxECON<15:8>) (see Register 11-8).
14.0 "Timer1"	The Timer1 Block Diagram was updated (see Figure 14-1).
15.0 "Timer2 Through Timer9"	The Timer2-Timer9 Block Diagram was updated (see Figure 15-1).
25.0 "12-bit High-Speed Successive Approximation Register (SAR) Analog-to-Digital Converter (ADC)"	The Step 7 was updated (see **25.1 "Activation Sequence"**). **Table 25-1: "PIC32MKXXX Based on a 60 MHz TAD clock (16.667 ns)"** was updated. IVTEMP references were removed from the: • ADC Block Diagram (see Figure 25-1) • S&H Block Diagram (see Figure 25-2) • ADC Register Map (see Table 25-2) The ADCDATA51 register was removed (see Table 25-2). The ADCCON2 register was updated (see Register 25-12). The following bits were removed: • CSS51 (see Table 25-2 and Register 25-12) • ARDY51 (see Table 25-2 and Register 25-14) • EIRDY51 (see Table 25-2 and Register 25-37) • AN51 (see Table 25-2 and Register 25-41) The definition for bit value '110011' in the ADINSEL<5:0> bits in the ADC Control Register 3 was updated to Reserved (see Register 25-3). A Note was added to the TRGSRC3<4:0> bits in the ADC Trigger Source x Registers (see Register 25-18 through Register 25-24). The definition for bit value '110101' in the AINID<5:0> bits in the ADC Digital Comparator 1 Control Register 3 was updated to Reserved (see Register 25-25). The definition for the LVL27:LVL0 bits in the ADC Trigger Level/Edge Sensitivity Register was updated (see Register 25-32).