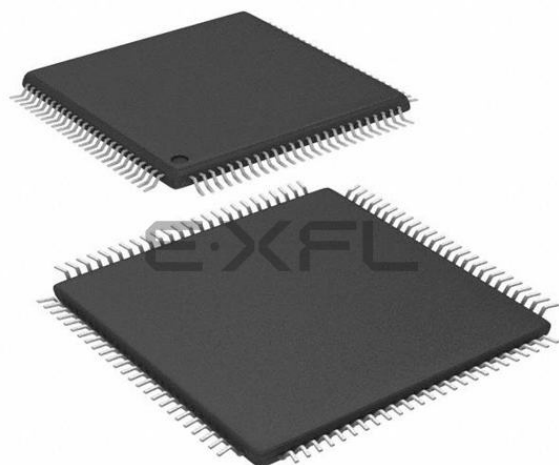




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, IrDA, LINbus, PMP, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, WDT
Number of I/O	77
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 42x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mk1024gpe100-i-pt

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TABLE 1-2: OSCILLATOR PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	100-pin TQFP	64-pin QFN/TQFP			
CLKI	63	39	I	ST	External clock source input. Always associated with OSC1 pin function.
CLKO	64	40	O	CMOS	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes. Always associated with OSC2 pin function.
OSC1	63	39	I	ST/CMOS	Oscillator crystal input. ST buffer when configured in RC mode; CMOS otherwise.
OSC2	64	40	O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes.
SOSCI	73	47	I	ST/CMOS	32.768 kHz low-power oscillator crystal input; CMOS otherwise.
SOSCO	74	48	O	CMOS	32.768 low-power oscillator crystal output.
REFCLKI	PPS	PPS	I	—	Reference Clock Generator Outputs 1-4
REFCLKO1	PPS	PPS	O	—	
REFCLKO2	PPS	PPS	O	—	
REFCLKO3	PPS	PPS	O	—	
REFCLKO4	PPS	PPS	O	—	

Legend: CMOS = CMOS-compatible input or output
ST = Schmitt Trigger input with CMOS levels
TTL = Transistor-transistor Logic input buffer

Analog = Analog input
O = Output
PPS = Peripheral Pin Select

P = Power
I = Input

TABLE 1-3: IC1 THROUGH IC16 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	100-pin TQFP	64-pin QFN/ TQFP			
Input Capture					
IC1	PPS	PPS	I	ST	Input Capture Inputs 1-6
IC2	PPS	PPS	I	ST	
IC3	PPS	PPS	I	ST	
IC4	PPS	PPS	I	ST	
IC5	PPS	PPS	I	ST	
IC6	PPS	PPS	I	ST	
IC7	PPS	PPS	I	ST	
IC8	PPS	PPS	I	ST	
IC9	PPS	PPS	I	ST	
IC10	PPS	PPS	I	ST	
IC11	PPS	PPS	I	ST	
IC12	PPS	PPS	I	ST	
IC13	PPS	PPS	I	ST	
IC14	PPS	PPS	I	ST	
IC15	PPS	PPS	I	ST	
IC16	PPS	PPS	I	ST	

Legend: CMOS = CMOS-compatible input or output
ST = Schmitt Trigger input with CMOS levels
TTL = Transistor-transistor Logic input buffer

Analog = Analog input
O = Output
PPS = Peripheral Pin Select

P = Power
I = Input

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TABLE 1-8: SPI1 THROUGH SPI 6 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	100-pin TQFP	64-pin QFN/ TQFP			
Serial Peripheral Interface 1					
SCK1	72	46	I/O	ST/CMOS	SPI1 Synchronous Serial Clock Input/Output
SDI1	PPS	PPS	I	ST	SPI1 Data In
SDO1	PPS	PPS	O	CMOS	SPI1 Data Out
SS1	PPS	PPS	I/O	ST/CMOS	SPI1 Slave Synchronization Or Frame Pulse I/O
Serial Peripheral Interface 2					
SCK2	70	44	I/O	ST/CMOS	SPI2 Synchronous Serial Clock Input/output
SDI2	PPS	PPS	I	ST	SPI2 Data In
SDO2	PPS	PPS	O	CMOS	SPI2 Data Out
SS2	PPS	PPS	I/O	ST/CMOS	SPI2 Slave Synchronization Or Frame Pulse I/O
Serial Peripheral Interface 3					
SCK3	PPS	PPS	I/O	ST/CMOS	SPI3 Synchronous Serial Clock Input/Output
SDI3	PPS	PPS	I	ST	SPI3 Data In
SDO3	PPS	PPS	O	CMOS	SPI3 Data Out
SS3	PPS	PPS	I/O	ST/CMOS	SPI3 Slave Synchronization Or Frame Pulse I/O
Serial Peripheral Interface 4					
SCK4	PPS	PPS	I/O	ST/CMOS	SPI4 Synchronous Serial Clock Input/Output
SDI4	PPS	PPS	I	ST	SPI4 Data In
SDO4	PPS	PPS	O	CMOS	SPI4 Data Out
SS4	PPS	PPS	I/O	ST/CMOS	SPI4 Slave Synchronization Or Frame Pulse I/O
Serial Peripheral Interface 5					
SCK5	PPS	PPS	I/O	ST/CMOS	SPI5 Synchronous Serial Clock Input/Output
SDI5	PPS	PPS	I	ST	SPI5 Data In
SDO5	PPS	PPS	O	CMOS	SPI5 Data Out
SS5	PPS	PPS	I/O	ST/CMOS	SPI5 Slave Synchronization Or Frame Pulse I/O
Serial Peripheral Interface 6					
SCK6	PPS	PPS	I/O	ST/CMOS	SPI6 Synchronous Serial Clock Input/Output
SDI6	PPS	PPS	I	ST	SPI6 Data In
SDO6	PPS	PPS	O	CMOS	SPI6 Data Out
SS6	PPS	PPS	I/O	ST/CMOS	SPI6 Slave Synchronization Or Frame Pulse I/O

Legend: CMOS = CMOS-compatible input or output Analog = Analog input P = Power
ST = Schmitt Trigger input with CMOS levels O = Output I = Input
TTL = Transistor-transistor Logic input buffer PPS = Peripheral Pin Select

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REGISTER 3-8: FCCR: FLOATING POINT CONDITION CODES REGISTER; CP1 REGISTER 25

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	FCC<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7-0 **FCC<7:0>:** Floating Point Condition Code bits

These bits record the results of floating point compares and are tested for floating point conditional branches and conditional moves.

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REGISTER 3-9: FEXR: FLOATING POINT EXCEPTIONS STATUS REGISTER; CP1 REGISTER 26

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x
	—	—	—	—	—	—	CAUSE<5:4>	
							E	V
15:8	R/W-x	R/W-x	R/W-x	U-0	U-0	U-0	U-0	U-0
	CAUSE<3:0>				—	—	—	—
	Z	O	U	I				
7:0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	U-0	U-0
	—	FLAGS<4:0>					—	—
		V	Z	O	U	I		

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-18 **Unimplemented:** Read as '0'

bit 17-12 **CAUSE<5:0>:** FPU Exception Cause bits

These bits indicated the exception conditions that arise during execution of an FPU arithmetic instruction.

bit 17 **E:** Unimplemented Operation bit

bit 16 **V:** Invalid Operation bit

bit 15 **Z:** Divide-by-Zero bit

bit 14 **O:** Overflow bit

bit 13 **U:** Underflow bit

bit 12 **I:** Inexact bit

bit 11-7 **Unimplemented:** Read as '0'

bit 6-2 **FLAGS<4:0>:** FPU Flags bits

These bits show any exception conditions that have occurred for completed instructions since the flag was last reset by software.

bit 6 **V:** Invalid Operation bit

bit 4 **Z:** Divide-by-Zero bit

bit 4 **O:** Overflow bit

bit 3 **U:** Underflow bit

bit 2 **I:** Inexact bit

bit 1-0 **Unimplemented:** Read as '0'

PIC32MK GP/MC Family

4.2 System Bus Arbitration

Note: The System Bus interconnect implements one or more instantiations of the SonicsSX® interconnect from Sonics, Inc. This document contains materials that are (c) 2003-2015 Sonics, Inc., and that constitute proprietary information of Sonics, Inc. SonicsSX is a registered trademark of Sonics, Inc. All such materials and trademarks are used under license from Sonics, Inc.

As shown in the PIC32MK GP/MC Family Block Diagram (see [Figure 1-1](#)), there are multiple initiator modules (I1 through I13) in the system that can access various target modules (T1 through T14). [Table 4-4](#) illustrates which initiator can access which target. The System Bus supports simultaneous access to targets by initiators, so long as the initiators are accessing different targets. The System Bus will perform arbitration, if multiple initiators attempt to access the same target.

TABLE 4-4: INITIATORS TO TARGETS ACCESS ASSOCIATION

Target #	Initiator ID:	1	2	3	4	5	6	7	8	9	10	11	12	13
	Name:	CPU IS	CPU ID	DMA Read	DMA Write	Flash	ICD JTAG	ADC Mem.	USB1	USB2	CAN1	CAN2	CAN3	CAN4
1	Program Flash	X		X										
2	Data		X											
3	Peripheral Module			X			X		X	X	X	X	X	X
4	RAM Bank 1	X	X	X	X	X	X	X	X	X	X	X	X	X
5	RAM Bank 2	X	X	X	X	X	X	X	X	X	X	X	X	X
7	Peripheral Bus 1: DMT, CVR, PPS Input, PPS Output, WDT						X							
8	Peripheral Bus 2: Timer1-Timer9, I2C1-I2C2, SPI1-SPI2, UART1-UART2, CDAC1, OC1-OC9, IC1-IC9, PMP, Comparator 1- Comparator 5, Op amp 1-Op amp 4 PWM1-PWM12 QE11-QE16		X	X	X		X							
9	Peripheral Bus 3: IC10-IC16, OC10-OC16, SPI3-SPI6, I2C3-I2C4, UART3-UART6, CDAC2-CDAC3		X	X	X		X							
10	Peripheral Bus 4: PORTA-PORTG		X	X	X		X							
11	Peripheral Bus 5: USB1-USB2, CAN1-CAN4 ADC		X				X							
14	Peripheral Bus 6: DSCON, RTCC		X				X							

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REGISTER 11-16: DCHxCSIZ: DMA CHANNEL x CELL-SIZE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CHCSIZ<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CHCSIZ<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **CHCSIZ<15:0>:** Channel Cell-Size bits

1111111111111111 = 65,535 bytes transferred on an event

.

.

.

0000000000000010 = 2 bytes transferred on an event

0000000000000001 = 1 byte transferred on an event

0000000000000000 = 65,536 bytes transferred on an event

PIC32MK GP/MC Family

13.1 Parallel I/O (PIO) Ports

All port pins have ten registers directly associated with their operation as digital I/O. The data direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx) read the latch. Writes to the latch write the latch. Reads from the port (PORTx) read the port pins, while writes to the port pins write the latch.

13.1.1 OPEN-DRAIN CONFIGURATION

In addition to the PORTx, LATx, and TRISx registers for data control, some port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any desired 5V-tolerant pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

Refer to the pin name tables ([Table 3](#) and [Table 5](#)) for the available pins and their functionality.

13.1.2 CONFIGURING ANALOG AND DIGITAL PORT PINS

The ANSELx register controls the operation of the analog port pins. The port pins that are to function as analog inputs must have their corresponding ANSEL and TRIS bits set. In order to use port pins for I/O functionality with digital modules, such as Timers, UARTs, etc., the corresponding ANSELx bit must be cleared.

The ANSELx register has a default value of 0xFFFF; therefore, all pins that share analog functions are analog (not digital) by default.

If the TRIS bit is cleared (output) while the ANSELx bit is set, the digital output level (VOH or VOL) is converted by an analog peripheral, such as the ADC module or Comparator module.

When the PORT register is read, all pins configured as analog input channels are read as cleared (a low level).

Pins configured as digital inputs do not convert an analog input. Analog levels on any pin defined as a digital input (including the ANx pins) can cause the input buffer to consume current that exceeds the device specifications.

13.1.3 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically this instruction would be an NOP.

13.1.4 INPUT CHANGE NOTIFICATION

The input change notification function of the I/O ports allows the PIC32MK GP/MC devices to generate interrupt requests to the processor in response to a change-of-state on selected input pins. This feature can detect input change-of-states even in Sleep mode, when the clocks are disabled. Every I/O port pin can be selected (enabled) for generating an interrupt request on a change-of-state.

Five control registers are associated with the CN functionality of each I/O port. The CNENx and CNNEEx registers contain the CN interrupt enable control bits for each of the input pins. Setting these bits enables a CN interrupt for the corresponding pins. The CNENx register enables a mismatch CN interrupt condition when the EDGEDETECT bit (CNCONx<11>) is not set. When the EDGEDETECT bit is set, the CNNEEx register controls the negative edge while the CNENx register controls the positive edge.

The CNSTATx and CNFx registers indicate the status of change notice based on the setting of the EDGEDETECT bit. If the EDGEDETECT bit is set to '0', the CNSTATx register indicates whether a change occurred on the corresponding pin since the last read of the PORTx bit. If the EDGEDETECT bit is set to '1', the CNFx register indicates whether a change has occurred and through the CNNEEx and CNENx registers the edge type of the change that occurred is also indicated.

Each I/O pin also has a weak pull-up and a weak pull-down connected to it. The pull-ups act as a current source or sink source connected to the pin, and eliminate the need for external resistors when push-button or keypad devices are connected. The pull-ups and pull-downs are enabled separately using the CNPUx and the CNPDx registers, which contain the control bits for each of the pins. Setting any of the control bits enables the weak pull-ups and/or pull-downs for the corresponding pins.

Note: Pull-ups and pull-downs on change notification pins should always be disabled when the port pin is configured as a digital output.

An additional control register (CNCONx) is shown in [Register 13-3](#).

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REGISTER 17-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<15:8>							
23:16	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<7:0>							
15:8	R/W-0	U-0	U-0	R-y	R-y	R-y	R-y	R-y
	ON ⁽¹⁾	—	—	RUNDIV<4:0>				
7:0	U-0	U-0	R-y	R-y	R-y	R-y	R-y	R/W-0
	—	—	SLPDIV<4:0>					WDTWINEN

Legend:	y = Values set from Configuration bits on POR
R = Readable bit	W = Writable bit
-n = Value at POR	U = Unimplemented bit, read as '0'
	'1' = Bit is set
	'0' = Bit is cleared
	x = Bit is unknown

bit 31-16 **WDTCLRKEY<15:0>**: Watchdog Timer Clear Key bits

To clear the Watchdog Timer to prevent a time-out, software must write the value 0x5743 to these bits using a single 16-bit write.

bit 15 **ON**: Watchdog Timer Enable bit⁽¹⁾

1 = The Watchdog Timer module is enabled
0 = The Watchdog Timer module is disabled

bit 14-13 **Unimplemented**: Read as '0'

bit 12-8 **RUNDIV<4:0>**: Watchdog Timer Postscaler Value in Run Mode bits

In Run mode, these bits are set to the values of the WDTPS<4:0> Configuration bits in the DEVCFG1 register.

bit 7-6 **Unimplemented**: Read as '0'

bit 5-1 **SLPDIV<4:0>**: Watchdog Timer Postscaler Value in Sleep Mode bits

In Sleep mode, these bits are set to the values of the WDTPS <4:0> Configuration bits in the DEVCFG1 register.

bit 0 **WDTWINEN**: Watchdog Timer Window Enable bit

1 = Enable windowed Watchdog Timer
0 = Disable windowed Watchdog Timer

Note 1: This bit only has control when FWDTEN (DEVCFG1<23>) = 0.

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REGISTER 24-2: RTCALRM: REAL-TIME CLOCK ALARM CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
	ALRMEN ^(1,2)	CHIME ⁽²⁾	PIV ⁽²⁾	ALRMSYNC	AMASK<3:0> ⁽²⁾			
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ARPT<7:0> ⁽²⁾							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ALRMEN:** Alarm Enable bit^(1,2)

1 = Alarm is enabled

0 = Alarm is disabled

bit 14 **CHIME:** Chime Enable bit⁽²⁾

1 = Chime is enabled – ARPT<7:0> is allowed to rollover from 0x00 to 0xFF

0 = Chime is disabled – ARPT<7:0> stops once it reaches 0x00

bit 13 **PIV:** Alarm Pulse Initial Value bit⁽²⁾

When ALRMEN = 0, PIV is writable and determines the initial value of the Alarm Pulse.

When ALRMEN = 1, PIV is read-only and returns the state of the Alarm Pulse.

bit 12 **ALRMSYNC:** Alarm Sync bit

1 = ARPT<7:0> and ALRMEN may change as a result of a half second rollover during a read.

The ARPT must be read repeatedly until the same value is read twice. This must be done since multiple bits may be changing.

0 = ARPT<7:0> and ALRMEN can be read without concerns of rollover because the prescaler is more than 32 real-time clocks away from a half-second rollover

bit 11-8 **AMASK<3:0>:** Alarm Mask Configuration bits⁽²⁾

0000 = Every half-second

0001 = Every second

0010 = Every 10 seconds

0011 = Every minute

0100 = Every 10 minutes

0101 = Every hour

0110 = Once a day

0111 = Once a week

1000 = Once a month

1001 = Once a year (except when configured for February 29, once every four years)

1010 = Reserved

1011 = Reserved

11xx = Reserved

Note 1: Hardware clears the ALRMEN bit anytime the alarm event occurs, when ARPT<7:0> = 00 and CHIME = 0.

2: This field should not be written when the RTCC ON bit = '1' (RTCCON<15>) and ALRMSYNC = 1.

Note: The RTCALRM register is reset on a MCLR, Power-on Reset (POR), or any time on an exit from Deep Sleep or VBAT mode.

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REGISTER 26-10: CxFLTCN0: CAN FILTER CONTROL REGISTER 0 ('x' = 1-4)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0 FLTEN3	R/W-0 MSEL3<1:0>	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
23:16	R/W-0 FLTEN2	R/W-0 MSEL2<1:0>	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
15:8	R/W-0 FLTEN1	R/W-0 MSEL1<1:0>	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
7:0	R/W-0 FLTEN0	R/W-0 MSEL0<1:0>	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31 **FLTEN3:** Filter 3 Enable bit

1 = Filter is enabled

0 = Filter is disabled

bit 30-29 **MSEL3<1:0>:** Filter 3 Mask Select bits

11 = Reserved

10 = Acceptance Mask 2 is selected

01 = Acceptance Mask 1 is selected

00 = Acceptance Mask 0 is selected

bit 28-24 **FSEL3<4:0>:** FIFO Selection bits

11111 = Message matching filter is stored in FIFO buffer 31

11110 = Message matching filter is stored in FIFO buffer 30

.

.

.

00001 = Message matching filter is stored in FIFO buffer 1

00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN2:** Filter 2 Enable bit

1 = Filter is enabled

0 = Filter is disabled

bit 22-21 **MSEL2<1:0>:** Filter 2 Mask Select bits

11 = Reserved

10 = Acceptance Mask 2 is selected

01 = Acceptance Mask 1 is selected

00 = Acceptance Mask 0 is selected

bit 20-16 **FSEL2<4:0>:** FIFO Selection bits

11111 = Message matching filter is stored in FIFO buffer 31

11110 = Message matching filter is stored in FIFO buffer 30

.

.

.

00001 = Message matching filter is stored in FIFO buffer 1

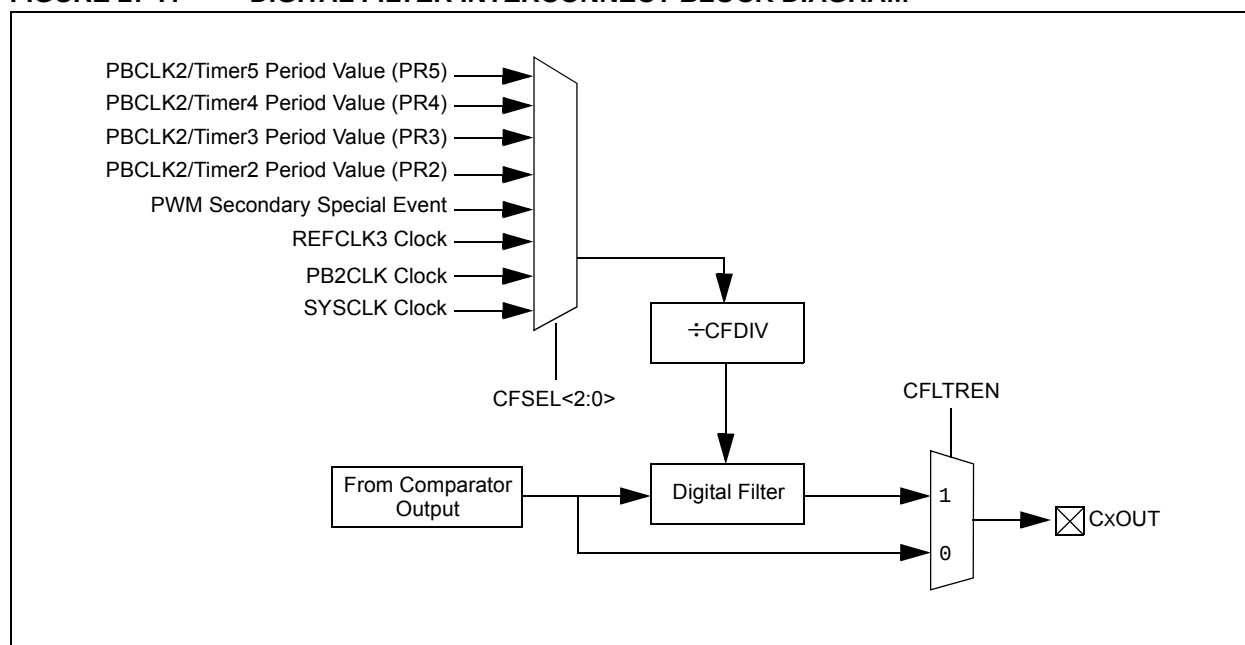
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

27.4 Comparator Output Filtering

The outputs can also be digitally filtered for glitches or noise. The digital filter has the capability to sample at different frequencies using different clock sources specified by the CFSEL<2:0> bits in the CxCON register. The digital filter looks for three consecutive samples of the same logic state before updating the comparator output. Since the digital filter affects the response times of the output, care should be taken while choosing the filter clock divisor to best suit the application at hand.

FIGURE 27-7: DIGITAL FILTER INTERCONNECT BLOCK DIAGRAM



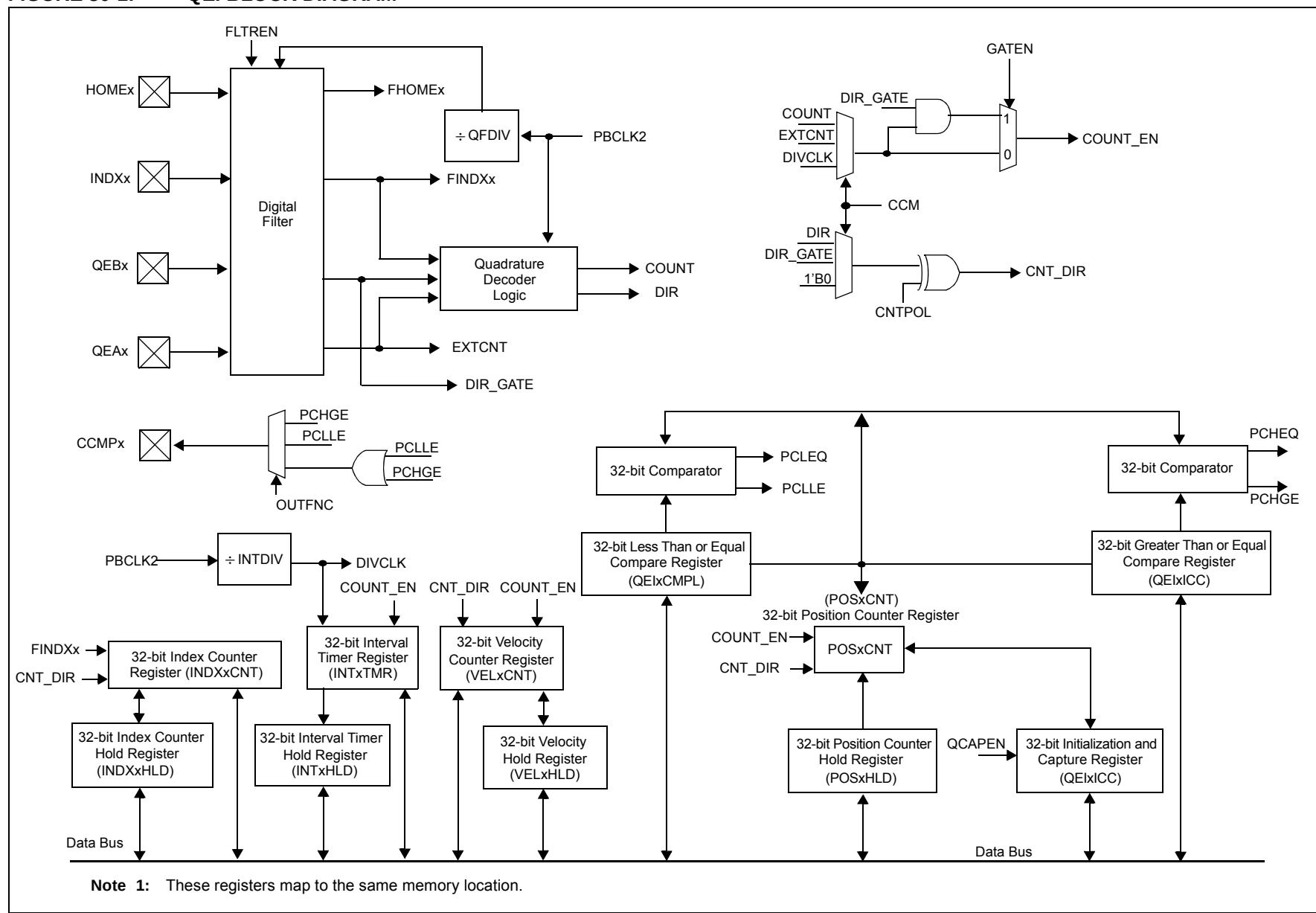
29.1 Control Registers

TABLE 29-1: CDAC REGISTER MAP

Virtual Address	Register Name ⁽¹⁾	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	
BF82_C200	DAC1CON	31:16	—	—	—	—	DACDAT<11:0>											0000
		15:0	ON	—	—	—	—	—	—	DACOE	—	—	—	—	—	—	REFSEL<1:0>	0000
BF84_C400	DAC2CON	31:16	—	—	—	—	DACDAT<11:0>											0000
		15:0	ON	—	—	—	—	—	—	DACOE	—	—	—	—	—	—	REFSEL<1:0>	0000
BF84_C600	DAC3CON	31:16	—	—	—	—	DACDAT<11:0>											0000
		15:0	ON	—	—	—	—	—	—	DACOE	—	—	—	—	—	—	REFSEL<1:0>	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET, and INV registers at its virtual address, plus an offset of 0x4, 0x8, and 0xC, respectively. See [Section 13.2 “CLR, SET, and INV Registers”](#) for more information.

FIGURE 30-1: QEI BLOCK DIAGRAM

PIC32MK GP/MC Family

REGISTER 30-10: QE1xICC: QE1x INITIALIZE/CAPTURE/COMPARE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ICCH<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ICCH<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ICCH<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ICCH<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-0 **ICCH<31:0>**: 32-bit Initialize/Capture/Compare High bits

REGISTER 30-11: QE1xCMPL: CAPTURE LOW REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CMPL<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CMPL<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CMPL<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CMPL<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-0 **CMPL<31:0>**: 32-bit Compare Low Value bits

TABLE 31-1: MCPWM REGISTER MAP (CONTINUED)

Virtual Address (BF82_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
A450	TRGCON4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	TRGDIV<3:0>				TRGSEL<1:0>		STRGSEL<1:0>		DTM	STRGIS	—	—	—	—	—	—	0000
A460	STRIG4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	STRGCMP<15:0>																0000
A470	CAP4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CAP<15:0>																0000
A480	LEBCON4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	—	—	—	—	—	—	0000
A490	LEBDLY4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	LEB<11:0>												0000
A4A0	AUXCON4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000	
A4B0	PTMR4	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	TMR<15:0>																0000
A4C0	PWMCON5	31:16	FLTIF	CLIF	TRGIF	PWMLIF	PWMHIF	—	—	—	FLTIE	CLIE	TRGIE	PWMLIE	PWMHIE	—	—	—	0000
		15:0	FLTSTAT	CLTSTAT	—	—	ECAM<1:0>		ITB	—	DTC<1:0>		DTCP	PTDIR	MTBS	—	XPRES	—	0000
A4D0	IOCON5	31:16	—	—	CLSRC<3:0>				CLPOL	CLMOD	—	FLTSRC<3:0>				FLTPOL	FLTMOD<1:0>		0078
		15:0	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000
A4E0	PDC5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	PDC<15:0>																0000
A4F0	SDC5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	SDC<15:0>																0000
A500	PHASE5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	PHASE<15:0>																0000
A510	DTR5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	DTR<15:0>																0000
A520	ALTDTR5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ALTDTR<15:0>																0000
A530	DTCOMP5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	COMP<13:0>													0000	
A540	TRIG5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	TRGCMP<15:0>																0000
A550	TRGCON5	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	TRGDIV<3:0>				TRGSEL<1:0>		STRGSEL<1:0>		DTM	STRGIS	—	—	—	—	—	—	0000

Legend: '—' = unimplemented; read as '0'.

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TABLE 36-22: I/O TIMING REQUIREMENTS (CONTINUED)

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	Symbol	Characteristics ⁽²⁾	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions
DO32	TIOF	Port Output Fall Time I/O Pins: 4x Source Driver Pins - RA0, RA4, RA11, RA12, RA14, RA15, RB0-RB3, RB8, RB9 RC0, RC1, RC2, RC10, RC12, RC13 RD8, RD12-RD15 RE0, RE1, RE8, RE9 RF5-RF7, RF9, RF10, RF12, RF13 RG0, RG1, RG6-RG15	—	—	9.5	ns	CLOAD = 50 pF
			—	—	6	ns	CLOAD = 20 pF
		Port Output Fall Time I/O Pins: 8x Source Driver Pins - RA1, RA7, RA8, RA10 RB4-RB7, RB10-RB15 RC6-RC9, RC11, RC15 RD1-RD6 RE12-RE15 RF0, RF1	—	—	8	ns	CLOAD = 50 pF
			—	—	6	ns	CLOAD = 20 pF
DI35	TINP	INTx Pin High or Low Time	5	—	—	ns	—
DI40	TRBP	CNx High or Low Time (input)	5	—	—	ns	—

Note 1: Data in the “Typical” column is at 3.3V, +25°C unless otherwise stated.

2: This parameter is characterized, but not tested in manufacturing.

FIGURE 36-5: EXTERNAL RESET TIMING CHARACTERISTICS

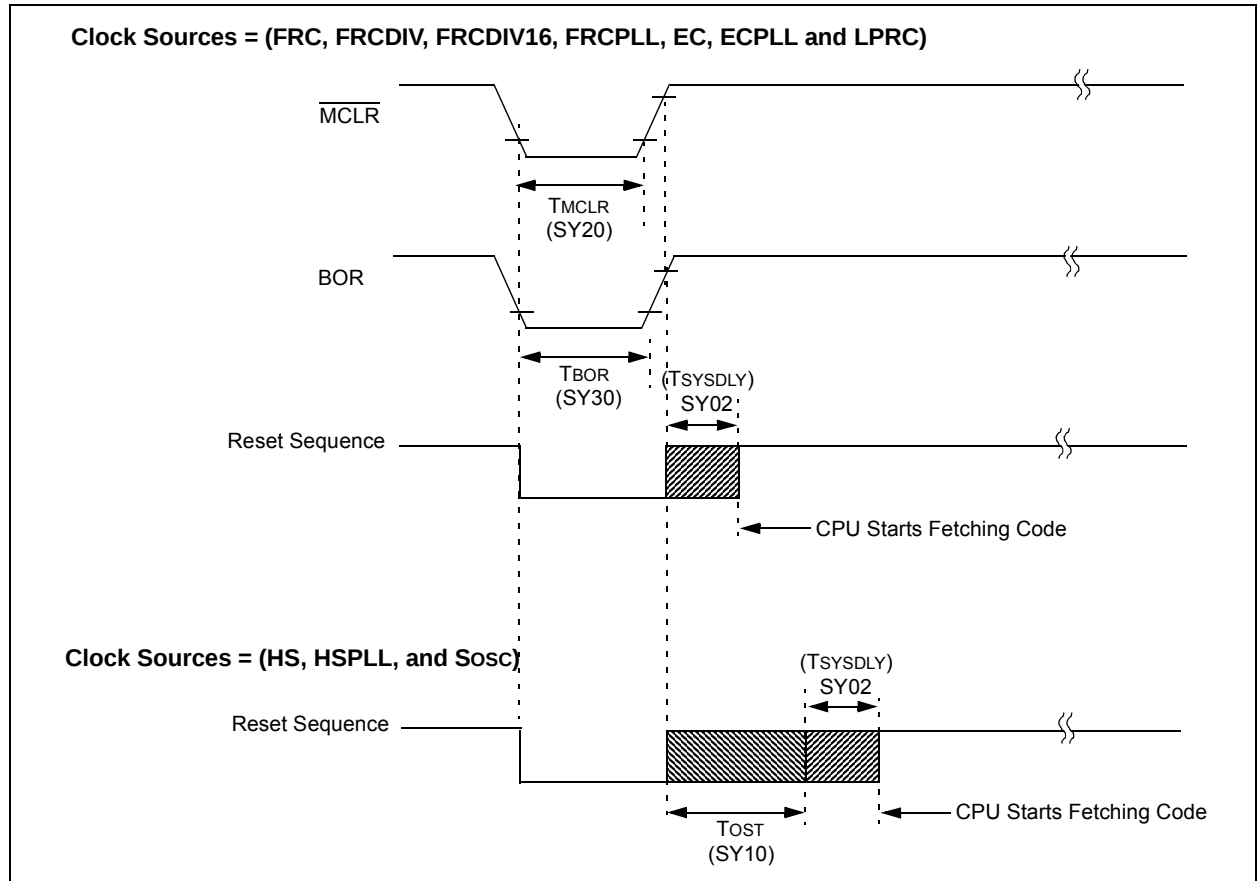


TABLE 36-23: RESETS TIMING

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param. No.	Symbol	Characteristics ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SY00	TPU	Power-up Period Internal Voltage Regulator Enabled	—	400	600	μs	—
SY02	TSYSDLY	System Delay Period: Time Required to Reload Device Configuration Fuses plus SYSCLK Delay before First instruction is Fetched.	—	$1\ \mu\text{s} + 8\ \text{SYSCLK cycles}$	—	—	—
SY20	TMCLR	MCLR Pulse Width (low)	2	—	—	μs	—
SY30	TBOR	BOR Pulse Width (low)	—	1	—	μs	—

Note 1: These parameters are characterized, but not tested in manufacturing.

2: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Characterized by design but not tested.

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TABLE 36-39: ADC MODULE SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param. No.	Symbol	Characteristics	Min.	Typ.	Max.	Units	Conditions
Device Supply							
AD01	AVDD	Module VDD Supply	Greater of VDD – 0.3 or 2.3	—	Lesser of VDD + 0.3 or 3.6	V	—
AD02	AVSS	Module Vss Supply	VSS	—	VSS + 0.3	V	—
Reference Inputs							
AD05	VREFH	Reference Voltage High	VREFL + 1.8	—	AVDD	V	(Note 1)
AD06	VREFL	Reference Voltage Low	AVSS	—	VREFH – 1.8	V	(Note 1)
AD07	VREF	Absolute Reference Voltage (VREFH – VREFL)	1.8	—	AVDD	V	(Note 2)
AD08	IREF	Current Drain	—	102	—	μA	ADC is operating or is in Stand-by.
Analog Input							
AD12	VINH-VINL	Full-Scale Input Span	VREFL	—	VREFH	V	—
AD13	VINL	Absolute VINL Input Voltage	AVSS	—	VREFL	V	—
AD14	VINH	Absolute VINH Input Voltage	AVSS	—	VREFH	V	—
ADC Accuracy – Measurements with External VREF+/VREF-							
AD20c	Nr	Resolution	6	—	12	bits	Selectable 6, 8, 10, 12 Resolution Ranges
AD21c	INL	Integral Nonlinearity	—	±3	—	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.3V
AD22c	DNL	Differential Nonlinearity	—	±1	—	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.3V
AD23c	GERR	Gain Error	—	±8	—	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.3V
AD24c	EOFF	Offset Error	—	±2	—	LSb	VINL = AVSS = 0V, AVDD = 3.3V
AD25c	—	Monotonicity	—	—	—	—	Guaranteed (Note 2)
Dynamic Performance							
AD31b	SINAD	Signal to Noise and Distortion	—	67	—	dB	Single-ended (Notes 2,3)
AD34b	ENOB	Effective Number of bits	—	10.8	—	bits	(Notes 2,3)

Note 1: These parameters are not characterized or tested in manufacturing.

2: These parameters are characterized, but not tested in manufacturing.

3: Characterized with a 1 kHz sine wave.

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