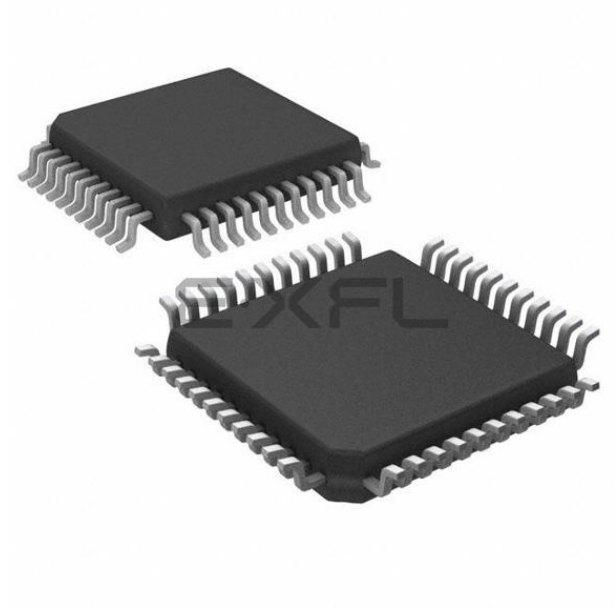
Infineon Technologies - C505CA4EMCAFXQMA1 Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	C500
Core Size	8-Bit
Speed	20MHz
Connectivity	CANbus, EBI/EMI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (32K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	1.25K x 8
Voltage - Supply (Vcc/Vdd)	4.25V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-QFP
Supplier Device Package	PG-MQFP-44-2
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/c505ca4emcafxqma1

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Features (continued) :

- 32 + 2 digital I/O lines
  - Four 8-bit digital I/O ports
  - One 2-bit digital I/O port (port 4)
  - Port 1 with mixed analog/digital I/O capability
- Three 16-bit timers/counters
  - Timer 0 / 1 (C501 compatible)
  - Timer 2 with 4 channels for 16-bit capture/compare operation
- Full duplex serial interface with programmable baudrate generator (USART)
- Full CAN Module, version 2.0 B compliant (C505C and C505CA only)
  - 256 register/data bytes located in external data memory area
  - 1 MBaud CAN baudrate when operating frequency is equal to or above 8 MHz
  - internal CAN clock prescaler when input frequency is over 10 MHz
- On-chip A/D Converter
  - up to 8 analog inputs
  - C505/C505C : 8-bit resolution
  - C505A/C505CA: 10-bit resolution
- Twelve interrupt sources with four priority levels
- On-chip emulation support logic (Enhanced Hooks Technology ™)
- Programmable 15-bit watchdog timer
- Oscillator watchdog
- Fast power on reset
- Power Saving Modes
  - Slow-down mode
  - Idle mode (can be combined with slow-down mode)
  - Software power-down mode with wake up capability through P3.2/$\overline{\text{INT0}}$ or P4.1/RXDC pin
- P-MQFP-44 package
- Pin configuration is compatible to C501, C504, C511/C513-family
- Temperature ranges:

SAB-C505 versions	T_A = 0 to 70 °C
SAF-C505 versions	T_A = -40 to 85°C
SAH-C505 versions	T_A = -40 to 110°C
SAK-C505 versions	T_A = -40 to 125°C

Table 2
Pin Definitions and Functions (cont'd)

Symbol	Pin Number	I/O *)	Function
P4.0 P4.1	6 28	I/O I/O	**Port 4** is a 2-bit quasi-bidirectional port with internal pull-up arrangement. Port 4 pins that have 1's written to them are pulled high by the internal pull-up transistors and in that state can be used as inputs. As inputs, port 4 pins being externally pulled low will source current (I_{IL}, in the DC characteristics) because of the internal pullup transistors. The output latch corresponding to the secondary function RXDC must be programmed to a one (1) for that function to operate. The secondary functions are assigned to the two pins of port 4 as follows (C505C and C505CA only) : P4.0 / TXDC Transmitter output of CAN controller P4.1 / RXDC Receiver input of CAN controller
XTAL2	14	O	**XTAL2** Output of the inverting oscillator amplifier.
XTAL1	15	I	**XTAL1** Input to the inverting oscillator amplifier and input to the internal clock generator circuits. To drive the device from an external clock source, XTAL1 should be driven, while XTAL2 is left unconnected. To operate above a frequency of 16 MHz, a duty cycle of the etxernal clock signal of 50 % should be maintained. Minimum and maximum high and low times as well as rise/ fall times specified in the AC characteristics must be observed.

*) I = Input
O = Output

Special Function Registers

The registers, except the program counter and the four general purpose register banks, reside in the special function register area. The special function register area consists of two portions : the standard special function register area and the mapped special function register area. Five special function register of the C505 (PCON1,P1ANA, VR0, VR1, VR2) are located in the mapped special function register area. For accessing the mapped special function register area, bit RMAP in special function register SYSCON must be set. All other special function registers are located in the standard special function register area which is accessed when RMAP is cleared (“0“).

The registers and data locations of the CAN controller (CAN-SFRs) are located in the external data memory area at addresses $F700_H$ to $F7FF_H$..

Special Function Register SYSCON (Address $B1_H$) **Reset Value : $XX100X01_B$**
(C505CA only) **Reset Value : $XX100001_B$**

Bit No.	MSB 7	6	5	4	3	2	1	LSB 0	
$B1_H$	–	–	EALE	RMAP	CMOD	CSWO 1)	XMAP1	XMAP0	SYSCON

The functions of the shaded bits are not described here.
1) This bit is only available in the C505CA.

Bit	Function
RMAP	Special function register map bit RMAP = 0 : The access to the non-mapped (standard) special function register area is enabled. RMAP = 1 : The access to the mapped special function register area is enabled.
CSWO	CAN Controller switch-off bit CSWO = 0 : CAN Controller is enabled (default after reset). CSWO = 1 : CAN Controller is switched off.

As long as bit RMAP is set, mapped special function register area can be accessed. This bit is not cleared by hardware automatically. Thus, when non-mapped/mapped registers are to be accessed, the bit RMAP must be cleared/set respectively by software.

All SFRs with addresses where address bits 0-2 are 0 (e.g. 80_H, 88_H, 90_H, 98_H, ..., $F8_H$, FF_H) are bitaddressable.

The 52 special function registers (SFRs) in the standard and mapped SFR area include pointers and registers that provide an interface between the CPU and the other on-chip peripherals. The SFRs of the C505 are listed in **Table 3** and **Table 4**. In **Table 3** they are organized in groups which refer to the functional blocks of the C505. The CAN-SFRs (applicable for the C505C and C505CA only) are also included in **Table 3**. **Table 4** illustrates the contents of the SFRs in numeric order of their addresses. **Table 5** list the CAN-SFRs in numeric order of their addresses.

Table 4
Contents of the SFRs, SFRs in numeric order of their addresses (cont'd)

Addr	Register	Content after Reset[1)]	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
$B0_H$[2)]	P3	FF_H	$\overline{RD}$	$\overline{WR}$	T1	T0	$\overline{INT1}$	$\overline{INT0}$	TxD	RxD
$B1_H$	SYSCON[3)]	$XX10\text{-}0X01_B$	–	–	EALE	RMAP	CMOD	–	XMAP1	XMAP0
$B1_H$	SYSCON[4)]	$XX10\text{-}0001_B$	–	–	EALE	RMAP	CMOD	CSWO	XMAP1	XMAP0
$B8_H$[2)]	IEN1	00_H	EXEN2	SWDT	EX6	EX5	EX4	EX3	ECAN	EADC
$B9_H$	IP1	$XX00\text{-}0000_B$	–	–	.5	.4	.3	.2	.1	.0
BA_H	SRELH	$XXXX\text{-}XX11_B$	–	–	–	–	–	–	.1	.0
$C0_H$[2)]	IRCON	00_H	EXF2	TF2	IEX6	IEX5	IEX4	IEX3	SWI	IADC
$C1_H$	CCEN	00_H	COCAH3	COCAL3	COCAH2	COCAL2	COCAH1	COCAL1	COCAH0	COCAL0
$C2_H$	CCL1	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C3_H$	CCH1	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C4_H$	CCL2	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C5_H$	CCH2	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C6_H$	CCL3	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C7_H$	CCH3	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$C8_H$[2)]	T2CON	$00X0\text{-}0000_B$	T2PS	I3FR	–	T2R1	T2R0	T2CM	T2I1	T2I0
CA_H	CRCL	00_H	.7	.6	.5	.4	.3	.2	.1	.0
CB_H	CRCH	00_H	.7	.6	.5	.4	.3	.2	.1	.0
CC_H	TL2	00_H	.7	.6	.5	.4	.3	.2	.1	.0
CD_H	TH2	00_H	.7	.6	.5	.4	.3	.2	.1	.0
$D0_H$[2)]	PSW	00_H	CY	AC	F0	RS1	RS0	OV	F1	P
$D8_H$[2)]	ADCON0	$00X0\text{-}0000_B$	BD	CLK	–	BSY	ADM	MX2	MX1	MX0

1) X means that the value is undefined and the location is reserved
2) Bit-addressable special function registers
3) C505 /C505C/C505A only
4) C505CA only

Timer/Counter 2 with Compare/Capture/Reload

The timer 2 of the C505 provides additional compare/capture/reload features. which allow the selection of the following operating modes:

- Compare : up to 4 PWM signals with 16-bit/300 ns resolution (@ 20 MHz clock)
- Capture : up to 4 high speed capture inputs with 300 ns resolution
- Reload : modulation of timer 2 cycle time

The block diagram in **Figure 11** shows the general configuration of timer 2 with the additional compare/capture/reload registers. The I/O pins which can used for timer 2 control are located as multifunctional port functions at port 1.

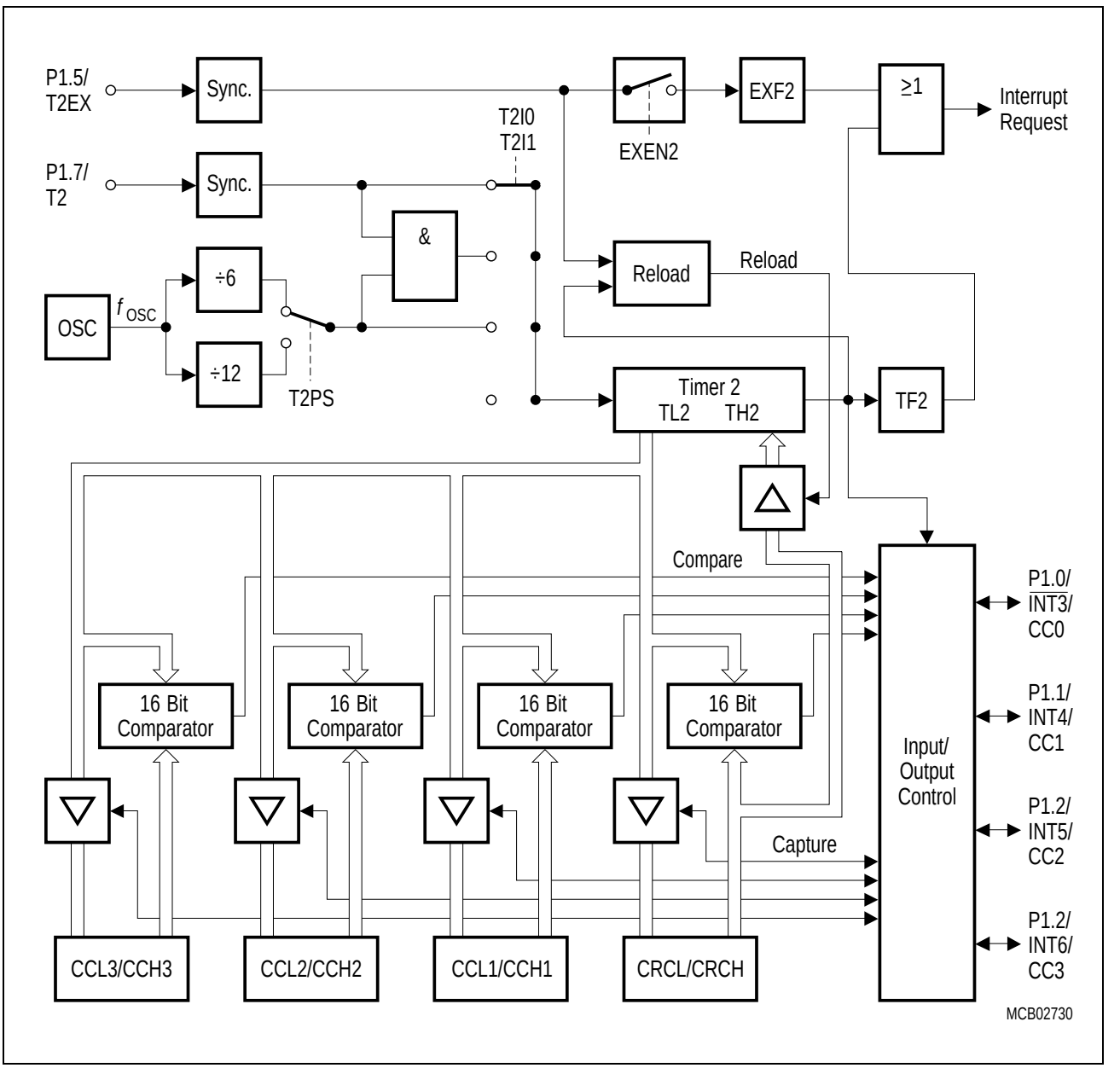


Figure 11
Timer 2 Block Diagram

Compare Mode 1

If compare mode 1 is enabled and the software writes to the appropriate output latch at the port, the new value will not appear at the output pin until the next compare match occurs. Thus, it can be choosen whether the output signal has to make a new transition (1-to-0 or 0-to-1, depending on the actual pin-level) or should keep its old value at the time when the timer value matches the stored compare value.

In compare mode 1 (see **Figure 13**) the port circuit consists of two separate latches. One latch (which acts as a "shadow latch") can be written under software control, but its value will only be transferred to the port latch (and thus to the port pin) when a compare match occurs.

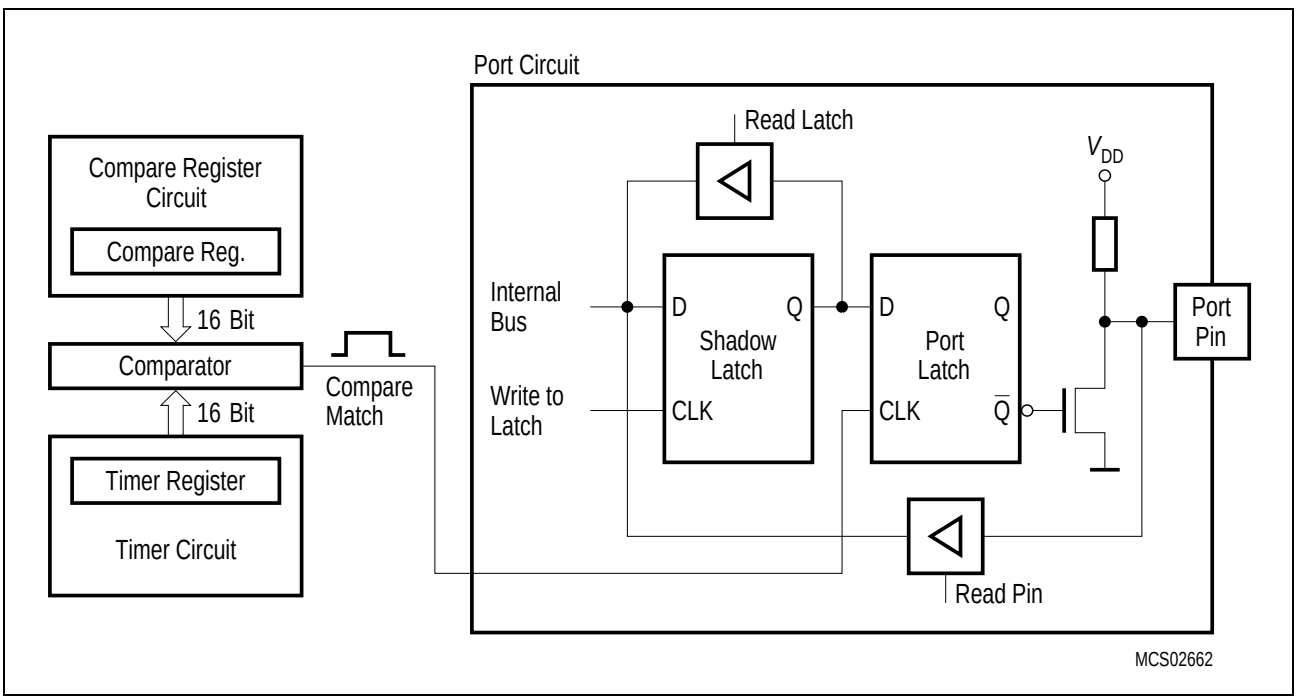


Figure 13
Compare Function in Compare Mode 1

Timer 2 Capture Modes

Each of the compare/capture registers CC1 to CC3 and the CRC register can be used to latch the current 16-bit value of the timer 2 registers TL2 and TH2. Two different modes are provided for this function.

In mode 0, the external event causing a capture is :

- for CC registers 1 to 3: a positive transition at pins CC1 to CC3 of port 1
- for the CRC register: a positive or negative transition at the corresponding pin, depending on the status of the bit I3FR in SFR T2CON.

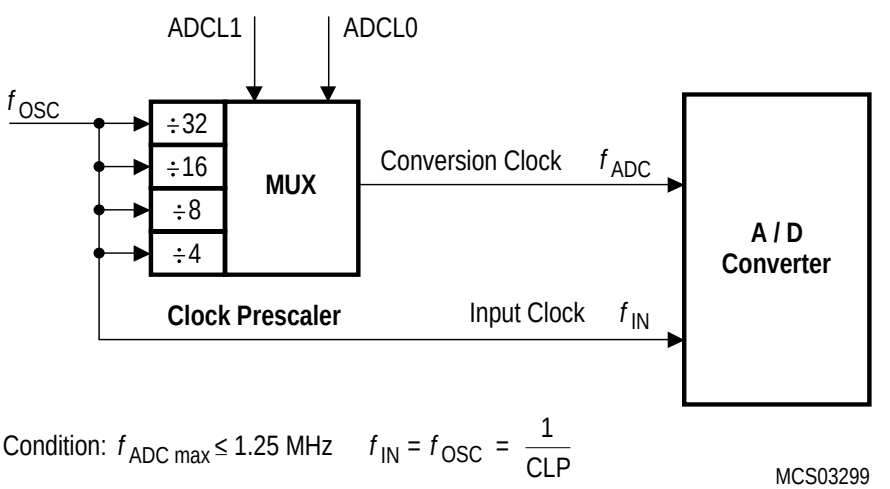
In mode 1 a capture occurs in response to a write instruction to the low order byte of a capture register. The write-to-register signal (e.g. write-to-CRCL) is used to initiate a capture. The timer 2 contents will be latched into the appropriate capture register in the cycle following the write instruction. In this mode no interrupt request will be generated.

8-Bit A/D Converter (C505 and C505C only)

The C505/C505C includes a high performance / high speed 8-bit A/D converter (ADC) with 8 analog input channels. It operates with a successive approximation technique and provides the following features:

- 8 multiplexed input channels (port 1), which can also be used as digital outputs/inputs
- 8-bit resolution
- Internal start-of-conversion trigger
- Interrupt request generation after each conversion
- Single or continuous conversion mode

The 8-bit ADC uses two clock signals for operation : the conversion clock f_{ADC} (=1/t_{ADC}) and the input clock f_{IN} (1/t_{IN}). f_{ADC} is derived from the C505 system clock f_{OSC} which is applied at the XTAL pins via the ADC clock prescaler as shown in **Figure 17**. The input clock is equal to f_{OSC}. The conversion clock f_{ADC} is limited to a maximum frequency of 1.25 MHz. Therefore, the ADC clock prescaler must be programmed to a value which assures that the conversion clock does not exceed 1.25 MHz. The prescaler ratio is selected by the bits ADCL1 and ADCL0 of SFR ADCON1.



MCU System Clock Rate (f_{OSC})	f_{IN} [MHz]	Prescaler Ratio	f_{ADC} [MHz]	ADCL1	ADCL0
2 MHz	2	÷ 4	0.5	0	0
5 MHz	5	÷ 4	1.25	0	0
6 MHz	6	÷ 8	0.75	0	1
10 MHz	10	÷ 8	1.25	0	1
12 MHz	12	÷ 16	0.75	1	0
16 MHz	16	÷ 16	1	1	0
20 MHz	20	÷ 16	1.25	1	0

Figure 17
8-Bit A/D Converter Clock Selection

Fail Save Mechanisms

The C505 offers enhanced fail safe mechanisms, which allow an automatic recovery from software upset or hardware failure :

- a programmable watchdog timer (WDT), with variable time-out period from 192 µs up to approx. 393.2 ms at 16 MHz (314.5 ms at 20 MHz).
- an oscillator watchdog (OWD) which monitors the on-chip oscillator and forces the microcontroller into reset state in case the on-chip oscillator fails; it also provides the clock for a fast internal reset after power-on.

The watchdog timer in the C505 is a 15-bit timer, which is incremented by a count rate of $f_{OSC}/12$ upto $f_{OSC}/192$. The system clock of the C505 is divided by two prescalers, a divide-by-two and a divide-by-16 prescaler. For programming of the watchdog timer overflow rate, the upper 7 bits of the watchdog timer can be written. **Figure 24** shows the block diagram of the watchdog timer unit.

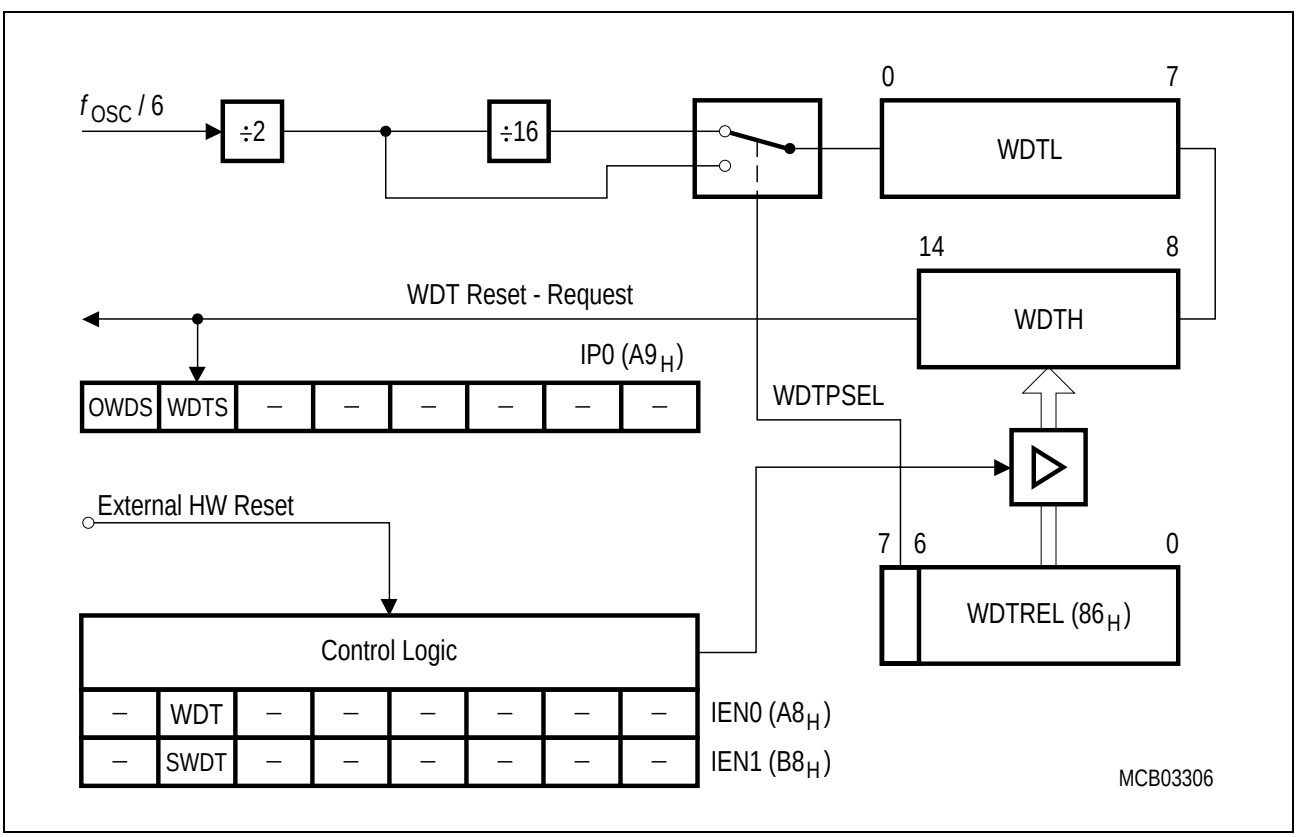


Figure 24
Block Diagram of the Programmable Watchdog Timer

The watchdog timer can be started by software (bit SWDT in SFR IEN1) but it cannot be stopped during active mode of the device. If the software fails to refresh the running watchdog timer an internal reset will be initiated on watchdog timer overflow. For refreshing of the watchdog timer the content of the SFR WDTREL is transfered to the upper 7-bit of the watchdog timer. The refresh sequence consists of two consequtive instructions which set the bits WDT and SWDT each. The reset cause (external reset or reset caused by the watchdog) can be examined by software (flag WDTS). It must be noted, however, that the watchdog timer is halted during the idle mode and power down mode of the processor.

Oscillator Watchdog

The oscillator watchdog unit serves for three functions:

- **Monitoring of the on-chip oscillator's function**
  The watchdog supervises the on-chip oscillator's frequency; if it is lower than the frequency of the auxiliary RC oscillator in the watchdog unit, the internal clock is supplied by the RC oscillator and the device is brought into reset; if the failure condition disappears (i.e. the on-chip oscillator has a higher frequency than the RC oscillator), the part, in order to allow the oscillator to stabilize, executes a final reset phase of typ. 1 ms; then the oscillator watchdog reset is released and the part starts program execution from address 0000_H again.
- **Fast internal reset after power-on**
  The oscillator watchdog unit provides a clock supply for the reset before the on-chip oscillator has started. The oscillator watchdog unit also works identically to the monitoring function.
- **Control of external wake-up from software power-down mode**
  When the power-down mode is left by a low level at the P3.2/$\overline{\text{INT0}}$ pin or the P4.1/RXDC pin, the oscillator watchdog unit assures that the microcontroller resumes operation (execution of the power-down wake-up interrupt) with the nominal clock rate. In the power-down mode the RC oscillator and the on-chip oscillator are stopped. Both oscillators are started again when power-down mode is released. When the on-chip oscillator has a higher frequency than the RC oscillator, the microcontroller starts program execution by processing a power down interrupt after a final delay of typ. 1 ms in order to allow the on-chip oscillator to stabilize.

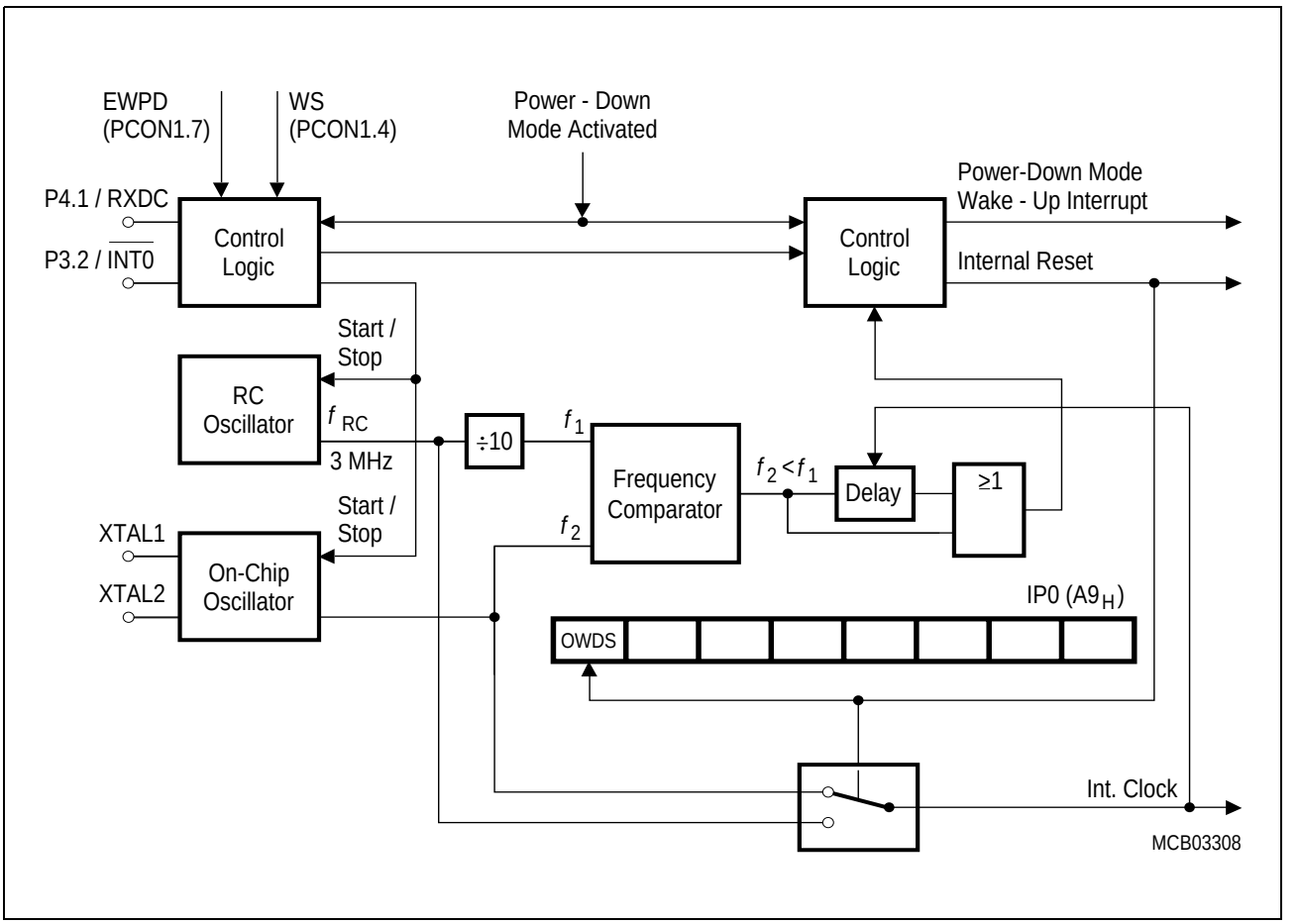


Figure 25
Functional Block Diagram of the Oscillator Watchdog

Pin Configuration in Programming Mode

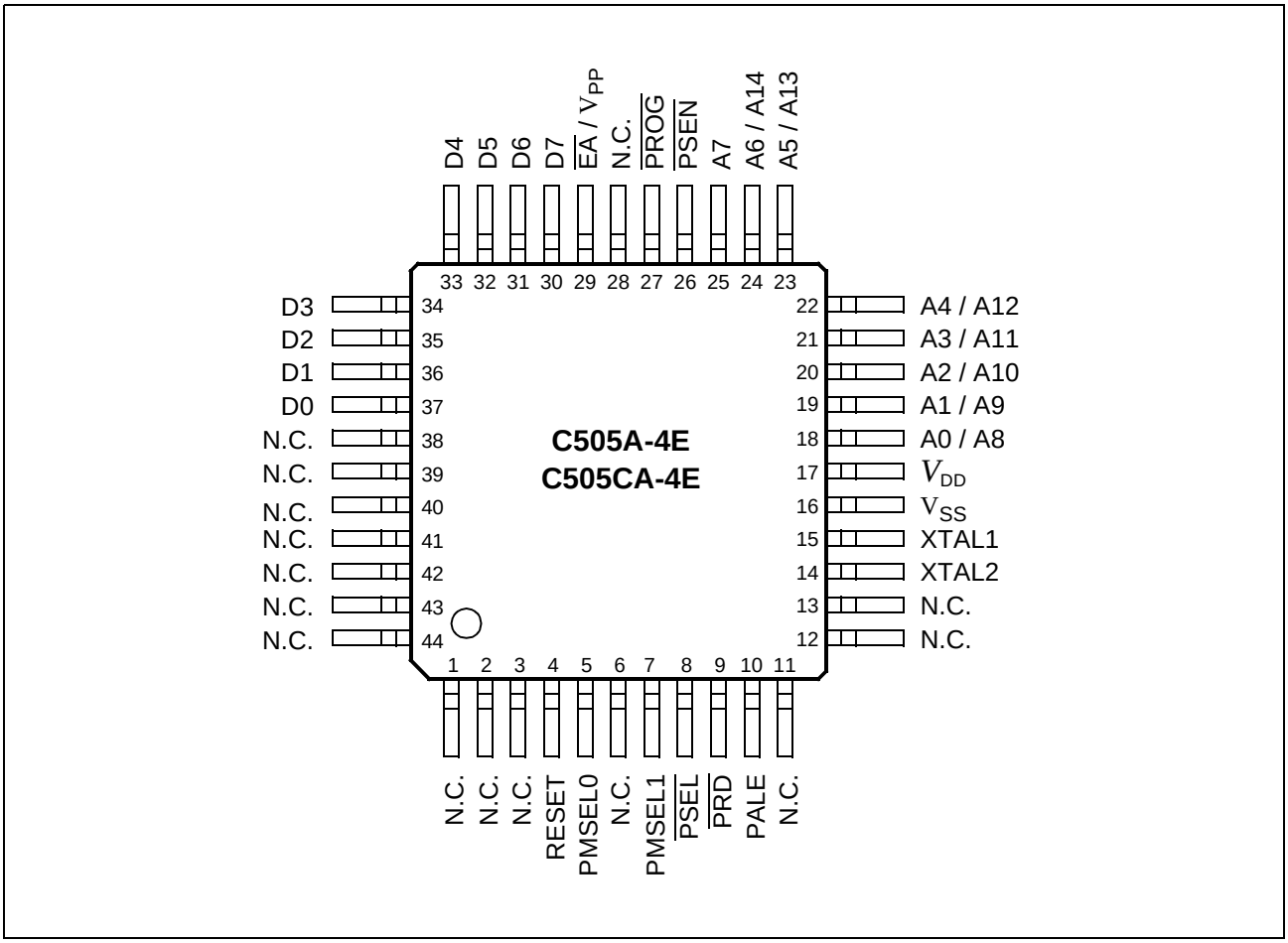


Figure 27
P-MQFP-44 Pin Configuration of the C505A-4E/C505CA-4E in Programming Mode (Top View)

Table 11
Pin Definitions and Functions in Programming Mode (cont'd)

Symbol	Pin Number	I/O *)	Function
P2.0-7	18-25	I	**Address lines** P2.0-7 are used as multiplexed address input lines A0-A7 and A8-A14. A8-A14 must be latched with PALE.
$\overline{\text{PSEN}}$	26	I	**Program store enable** This input must be at static "0" level during the whole programming mode.
$\overline{\text{PROG}}$	27	I	**Programming mode write strobe** This input is used in programming mode as a write strobe for OTP memory program, and lock bit write operations During basic programming mode selection a low level must be applied to $\overline{\text{PROG}}$.
$\overline{\text{EA}}/V_{PP}$	29	–	**$\overline{\text{External Access}}$ / Programming voltage** This pin must be at 11.5V (V_{PP}) voltage level during programming of an OTP memory byte or lock bit. During an OTP memory read operation this pin must be at V_{IH} high level. This pin is also used for basic programming mode selection. At basic programming mode selection a low level must be applied to $\overline{\text{EA}}/V_{PP}$.
D7-0	30-37	I/O	**Data lines 0-7** During programming mode, data bytes are transferred via the bidirectional port 0 data lines.
N.C.	1-3, 6, 11-13, 28, 38-44	–	**Not Connected** These pins should not be connected in programming mode.

*) I = Input
O = Output

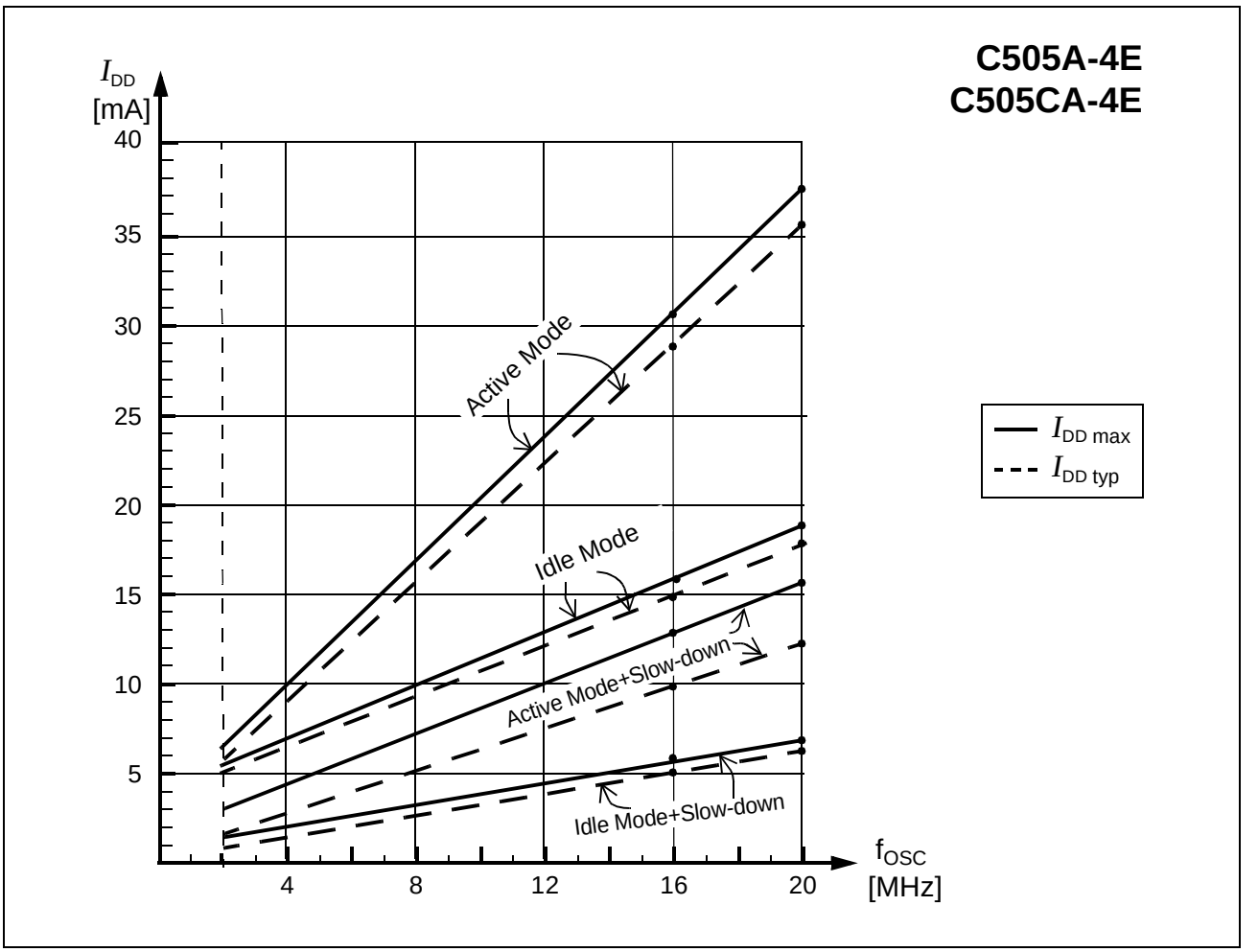


Figure 30
I_{DD} Diagram of C505A-4E and C505CA-4E

C505A-4E/C505CA-4E : Power Supply Current Calculation Formulas

Parameter	Symbol	Formula
Active mode	$I_{DD\ typ}$ $I_{DD\ max}$	$1.63 * f_{OSC} + 2.6$ $1.74 * f_{OSC} + 2.8$
Idle mode	$I_{DD\ typ}$ $I_{DD\ max}$	$0.69 * f_{OSC} + 3.9$ $0.74 * f_{OSC} + 4.1$
Active mode with slow-down enabled	$I_{DD\ typ}$ $I_{DD\ max}$	$0.6 * f_{OSC} + 0.3$ $0.7 * f_{OSC} + 1.6$
Idle mode with slow-down enabled	$I_{DD\ typ}$ $I_{DD\ max}$	$0.3 * f_{OSC} + 0.3$ $0.3 * f_{OSC} + 0.8$

Note: f_{osc} is the oscillator frequency in MHz. I_{DD} values are given in mA.

Note:

1) V_{AIN} may exeed V_{AGND} or V_{AREF} up to the absolute maximum ratings. However, the conversion result in these cases will be 00_H or FF_H, respectively.

2) During the sample time the input capacitance C_{AIN} must be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach their final voltage level within t_S. After the end of the sample time t_S, changes of the analog input voltage have no effect on the conversion result.

3) This parameter includes the sample time t_S, the time for determining the digital result. Values for the conversion clock t_{ADC} depend on programming and can be taken from the table on the previous page.

4) T_{UE} (max.) is tested at $-40 \le T_A \le 125$ °C ; $V_{DD} \le 5.5$ V; $V_{AREF} \le V_{DD} + 0.1$ V and $V_{SS} \le V_{AGND}$. It is guaranteed by design characterization for all other voltages within the defined voltage range.
If an overload condition occurs on maximum 2 unused analog input pins and the absolute sum of input overload currents on all analog input pins does not exceed 10 mA, an additional conversion error of 1/2 LSB is permissible.

5) During the conversion the ADC's capacitance must be repeatedly charged or discharged. The internal resistance of the reference source must allow the capacitance to reach their final voltage level within the indicated time. The maximum internal resistance results from the programmed conversion timing.

6) Not 100% tested, but guaranteed by design characterization.

A/D Converter Characteristics of C505A and C505CA

(Operating Conditions apply)

Parameter	Symbol	Limit Values		Unit	Test Condition
		min.	max.		
Analog input voltage	V_{AIN}	V_{AGND}	V_{AREF}	V	1)
Sample time	t_S	–	64 x t_{IN} 32 x t_{IN} 16 x t_{IN} 8 x t_{IN}	ns	Prescaler ÷ 32 Prescaler ÷ 16 Prescaler ÷ 8 Prescaler ÷ 4 2)
Conversion cycle time	t_{ADCC}	–	384 x t_{IN} 192 x t_{IN} 96 x t_{IN} 48 x t_{IN}	ns	Prescaler ÷ 32 Prescaler ÷ 16 Prescaler ÷ 8 Prescaler ÷ 4 3)
Total unadjusted error	T_{UE}	–	± 2	LSB	V_{SS}+0.5V ≤ V_{AIN} ≤ V_{DD}-0.5V 4)
		–	± 4	LSB	V_{SS} < V_{AIN} < V_{DD}+0.5V V_{DD} - 0.5 V < V_{AIN} < V_{DD} 4)
Internal resistance of reference voltage source	R_{AREF}	–	t_{ADC} / 250 - 0.25	kΩ	t_{ADC} in [ns] 5) 6)
Internal resistance of analog source	R_{ASRC}	–	t_S / 500 - 0.25	kΩ	t_S in [ns] 2) 6)
ADC input capacitance	C_{AIN}	–	50	pF	6)

Notes see next page.

Clock calculation table :

Clock Prescaler Ratio	ADCL1, 0		t_{ADC}	t_S	t_{ADCC}
÷ 32	1	1	32 x t_{IN}	64 x t_{IN}	384 x t_{IN}
÷ 16	1	0	16 x t_{IN}	32 x t_{IN}	192 x t_{IN}
÷ 8	0	1	8 x t_{IN}	16 x t_{IN}	96 x t_{IN}
÷ 4	0	0	4 x t_{IN}	8 x t_{IN}	48 x t_{IN}

Further timing conditions : t_{ADC} min = 500 ns
$t_{IN} = 1 / f_{OSC} = t_{CLP}$

AC Characteristics (20 MHz, 0.5 Duty Cycle, cont'd)

External Data Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		20 MHz clock 0.5 Duty Cycle		Variable Clock 1/CLP = 2 MHz to 20 MHz		
		min.	max.	min.	max.	
$\overline{RD}$ pulse width	t_{RLRH}	120	–	3 CLP - 30	–	ns
$\overline{WR}$ pulse width	t_{WLWH}	120	–	3 CLP - 30	–	ns
Address hold after ALE	t_{LLAX2}	35	–	CLP - 15	–	ns
$\overline{RD}$ to valid data in	t_{RLDV}	–	75	–	5/2 CLP- 50	ns
Data hold after $\overline{RD}$	t_{RHDX}	0	–	0	–	ns
Data float after $\overline{RD}$	t_{RHDZ}	–	38	–	CLP - 12	ns
ALE to valid data in	t_{LLDV}	–	150	–	4 CLP - 50	ns
Address to valid data in	t_{AVDV}	–	150	–	9/2 CLP - 75	ns
ALE to $\overline{WR}$ or $\overline{RD}$	t_{LLWL}	60	90	3/2 CLP - 15	3/2 CLP + 15	ns
Address valid to $\overline{WR}$	t_{AVWL}	70	–	2 CLP - 30	–	ns
$\overline{WR}$ or $\overline{RD}$ high to ALE high	t_{WHLH}	10	40	CLP/2 - 15	CLP/2 + 15	ns
Data valid to $\overline{WR}$ transition	t_{QVWX}	5	–	CLP/2 - 20	–	ns
Data setup before $\overline{WR}$	t_{QVWH}	125	–	7/2 CLP - 50	–	ns
Data hold after $\overline{WR}$	t_{WHQX}	5	–	CLP/2 - 20	–	ns
Address float after $\overline{RD}$	t_{RLAZ}	–	0	–	0	ns

External Clock Drive Characteristics

Parameter	Symbol	Limit Values		Unit
		Variable Clock Freq. = 2 MHz to 20 MHz		
		min.	max.	
Oscillator period	CLP	50	500	ns
High time	TCL_H	15	$CLP-TCL_L$	ns
Low time	TCL_L	15	$CLP-TCL_H$	ns
Rise time	t_R	–	10	ns
Fall time	t_F	–	10	ns
Oscillator duty cycle	DC	0.5	0.5	–

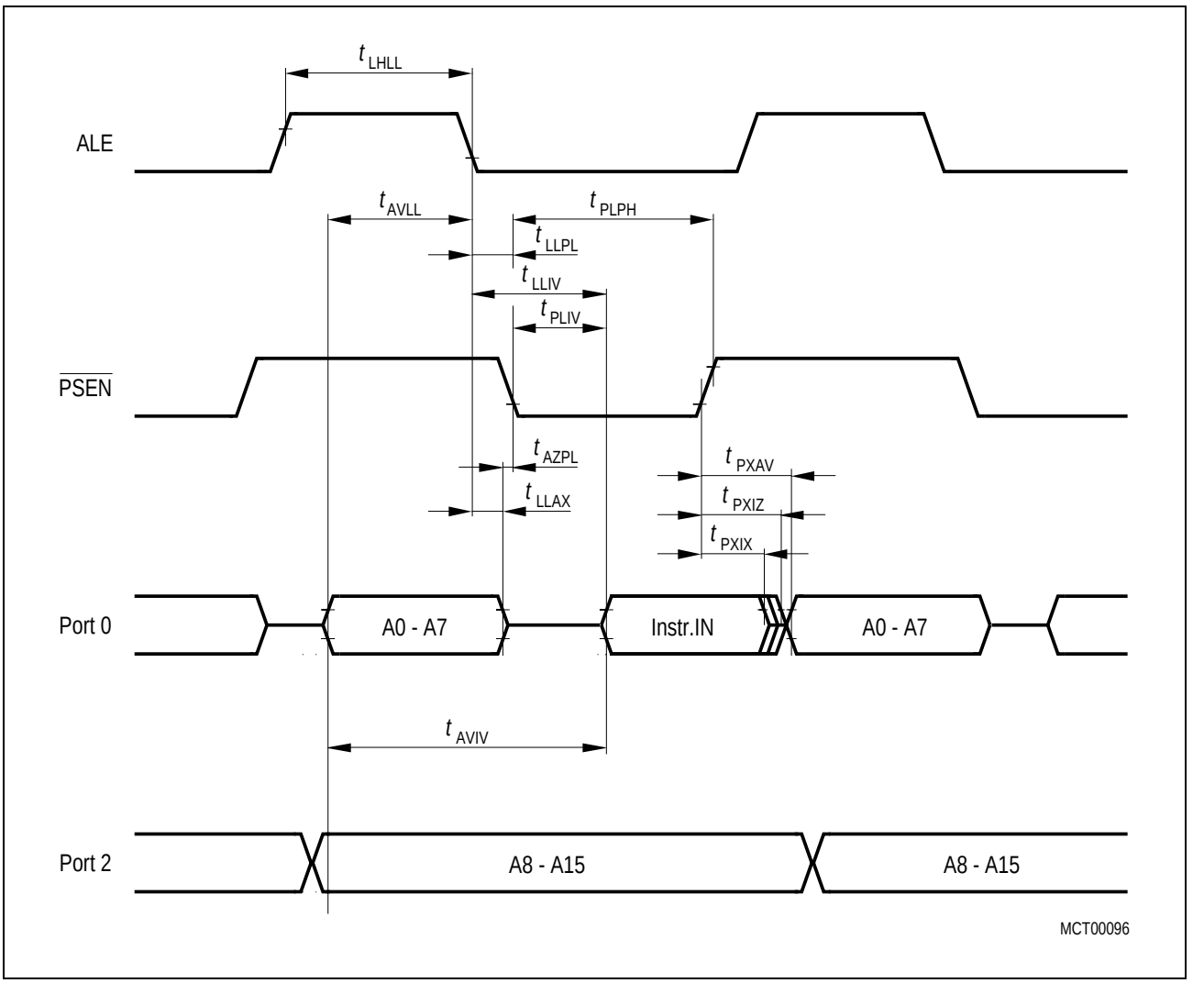
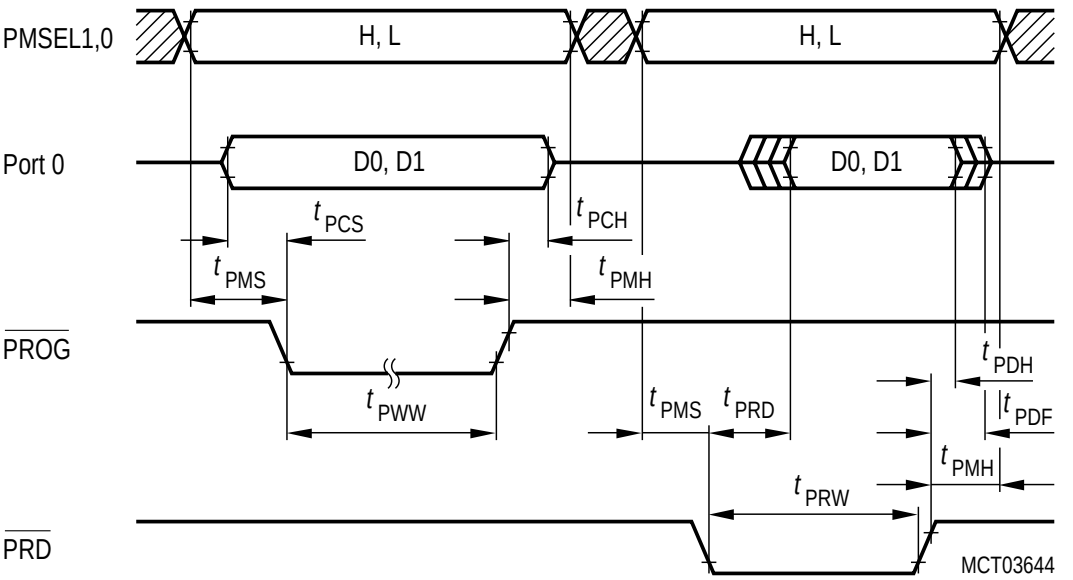
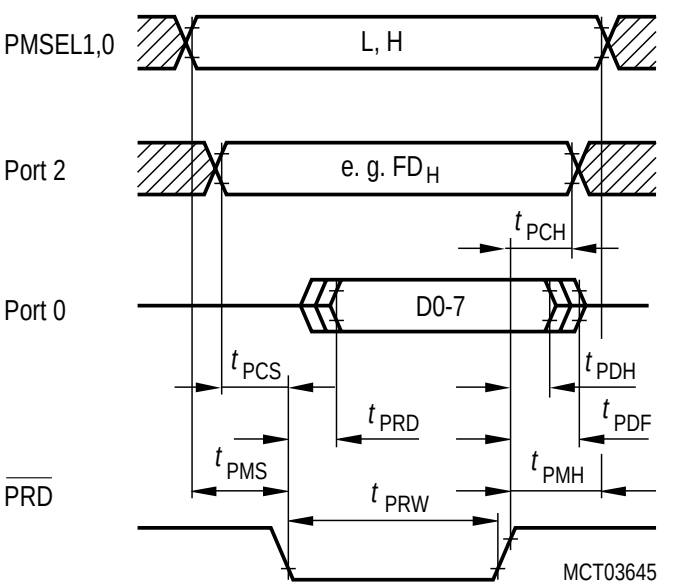


Figure 32
Program Memory Read Cycle



Note: PALE should be low during a lock bit read / write cycle.

Figure 38
Lock Bit Access Timing



Note: $\overline{\text{PROG}}$ must be high during a programming read cycle.

Figure 39
Version Byte Read Timing

ROM/OTP Verification Characteristics for C505 (cont'd)

ROM/OTP Verification Mode 2

Parameter	Symbol	Limit Values			Unit
		min.	typ	max.	
ALE pulse width	t_{AWD}	–	CLP	–	ns
ALE period	t_{ACY}	–	6 CLP	–	ns
Data valid after ALE	t_{DVA}	–	–	2 CLP	ns
Data stable after ALE	t_{DSA}	4 CLP	–	–	ns
P3.5 setup to ALE low	t_{AS}	–	t_{CL}	–	ns
Oscillator frequency	1/ CLP	4	–	6	MHz

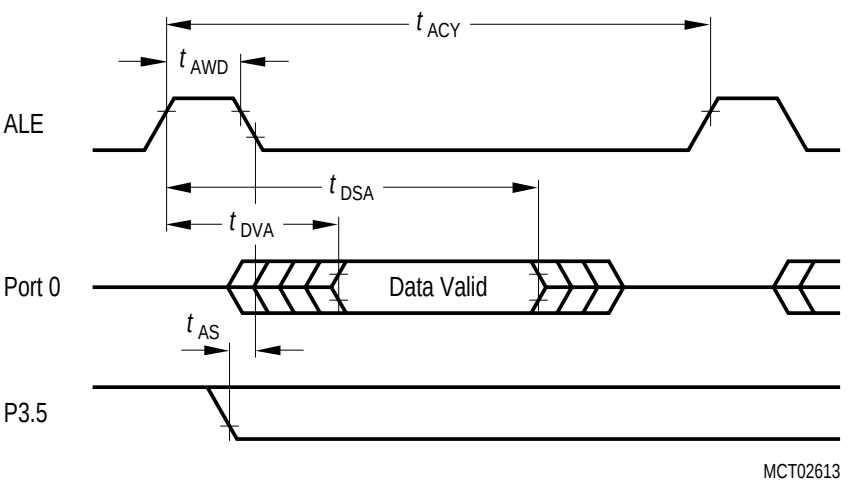


Figure 41
ROM/OTP Verification Mode 2