Renesas Electronics America Inc - R5F10Y14ASP#V0 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Not For New Designs
Core Processor	RL78
Core Size	16-Bit
Speed	20MHz
Connectivity	CSI, I²C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	6
Program Memory Size	1KB (1K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	A/D 4x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	10-LSSOP (0.173", 4.40mm Width)
Supplier Device Package	10-LSSOP
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f10y14asp-v0

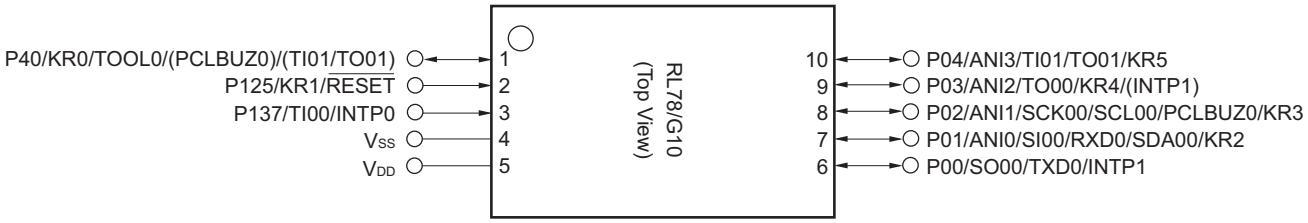
Note For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G10**.

Caution The part number represents the number at the time of publication.
Be sure to review the latest part number through the target product page in the Renesas Electronics Corp.website.

<R> 1.3 Pin Configuration (Top View)

1.3.1 10-pin products

- 10-pin plastic LSSOP (4.4 × 3.6 mm, 0.65 mm pitch)

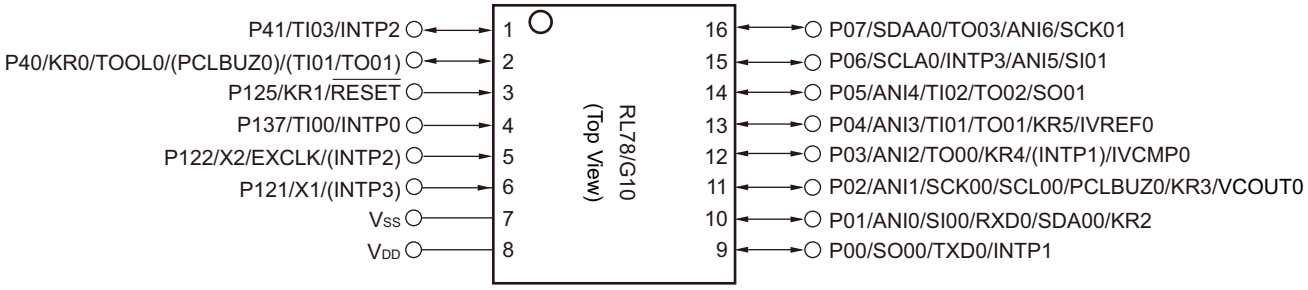


Remarks 1. For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). See **Figure 4-6 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G10 User's Manual.

1.3.2 16-pin products

- **16-pin plastic SSOP (4.4 × 5.0 mm, 0.65 mm pitch)**

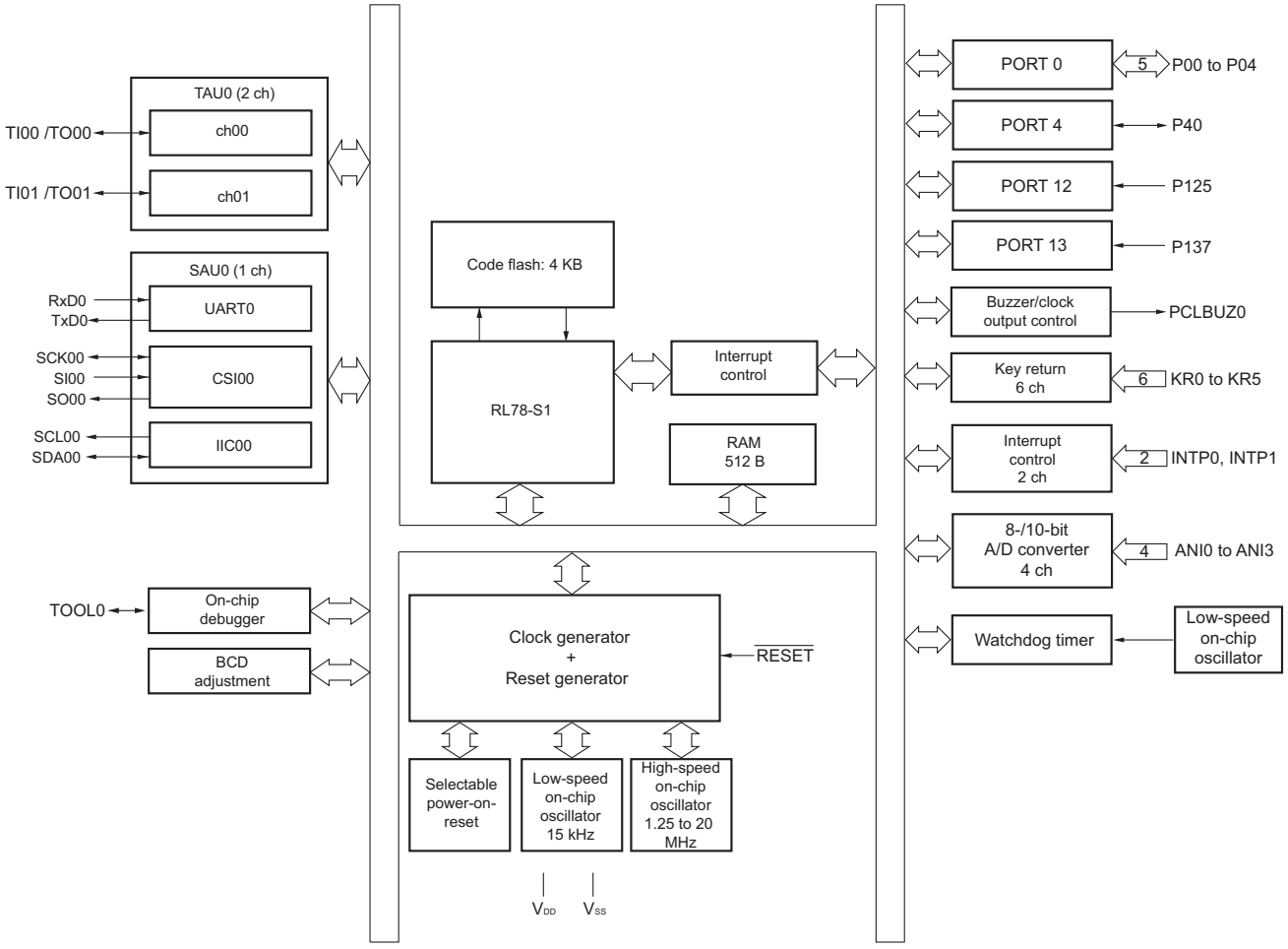


Remarks 1. For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). See **Figure 4-6 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G10 User's Manual.

1.5 Block Diagram

1.5.1 10-pin products



1.6 Outline of Functions

This outline describes the function at the time when Peripheral I/O redirection register (PIOR) is set to 00H.

Item		10-pin			16-pin		
		R5F10Y14	R5F10Y16	R5F10Y17	R5F10Y44	R5F10Y46	R5F10Y47
Code flash memory		1 KB	2 KB	4 KB	1 KB	2 KB	4 KB
RAM		128 B	256 B	512 B	128 B	256 B	512 B
Main system clock	High-speed system clock	—			X1, X2 (crystal/ceramic) oscillation, external main system clock input (EXCLK): 1 to 20 MHz: V_{DD} = 2.7 to 5.5 V 1 to 5 MHz: V_{DD} = 2.0 to 5.5 V Note 3		
	High-speed on-chip oscillator clock	• 1.25 to 20 MHz (V_{DD} = 2.7 to 5.5 V) • 1.25 to 5 MHz (V_{DD} = 2.0 to 5.5 V Note 3)					
Low-speed on-chip oscillator clock		15 kHz (TYP)					
General-purpose register		8-bit register × 8					
Minimum instruction execution time		0.05 μs (20 MHz operation)					
Instruction set		• Data transfer (8 bits) • Adder and subtractor/logical operation (8 bits) • Multiplication (8 bits × 8 bits) • Rotate, barrel shift, and bit manipulation (set, reset, test, and Boolean operation), etc.					
I/O port	Total	8			14		
	CMOS I/O	6 (N-ch open-drain output (V_{DD} tolerance): 2)			10 (N-ch open-drain output (V_{DD} tolerance): 4)		
	CMOS input	2			4		
Timer	16-bit timer	2 channels			4 channels		
	Watchdog timer	1 channel					
	12-bit interval timer	—			1 channel		
	Timer output	2 channels (PWM output: 1)			4 channels (PWM outputs: 3 Note 1)		
Clock output/buzzer output		1 2.44 kHz to 10 MHz: (Peripheral hardware clock: f_{MAIN} = 20 MHz operation)					
Comparator		—			1		
8-/10-bit resolution A/D converter		4 channels			7 channels		
Serial interface		[10-pin products] CSI: 1 channel/simplified I^2C: 1 channel/UART: 1 channel [16-pin products] CSI: 2 channels/simplified I^2C: 1 channel/UART: 1 channel					
	I^2C bus	—			1 channel		
Vectored interrupt sources	Internal	8			14		
	External	3			5		
Key interrupt		6					
Reset		• Reset by $\overline{\text{RESET}}$ pin • Internal reset by watchdog timer • Internal reset by selectable power-on-reset • Internal reset by illegal instruction execution Note 2 • Internal reset by data retention lower limit voltage					
Selectable power-on-reset circuit		• Detection voltage Rising edge (V_{SPOR}): 2.25 V/2.68 V/3.02 V/4.45 V (max.) Falling edge (V_{SPDR}): 2.20 V/2.62 V/2.96 V/4.37 V (max.)					

2. ELECTRICAL SPECIFICATIONS

Cautions 1. The RL78 microcontrollers have an on-chip debug function, which is provided for development and evaluation. Do not use the on-chip debug function in products designated for mass production, because the guaranteed number of rewritable times of the flash memory may be exceeded when this function is used, and product reliability therefore cannot be guaranteed. Renesas Electronics is not liable for problems occurring when the on-chip debug function is used.

2. The pins mounted depend on the product. Refer to 2.1 Port Functions and 2.2.1 Functions for each product in the RL78/G10 User's Manual.

3. Use this product within the voltage range from 2.25 to 5.5 V because the detection voltage (V_{SPOR}) of the selectable power-on-reset (SPOR) circuit should also be considered.

2.2 Oscillator Characteristics

2.2.1 X1 oscillator characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Resonator	Conditions	MIN.	TYP.	MAX.	Unit
X1 clock oscillation frequency (f_X)Note	Ceramic resonator/ crystal resonator	2.7 V ≤ V_{DD} ≤ 5.5 V	1		20	MHz
		2.0 V ≤ V_{DD} < 2.7 V	1		5	MHz

Note Indicates only permissible oscillator frequency ranges. Refer to AC Characteristics for instruction execution time. Request evaluation by the manufacturer of the oscillator circuit mounted on a board to check the oscillator characteristics.

Caution Since the CPU is started by the high-speed on-chip oscillator clock after a reset release, check the X1 clock oscillation stabilization time using the oscillation stabilization time counter status register (OSTC) by the user. Determine the oscillation stabilization time of the OSTC register and the oscillation stabilization time select register (OSTS) after sufficiently evaluating the oscillation stabilization time with the resonator to be used.

Remark When using the X1 oscillator, refer to **5.4 System Clock Oscillator** in the RL78/G10 User's Manual.

2.2.2 On-chip oscillator characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Oscillators	Parameters	Conditions	MIN.	TYP.	MAX.	Unit
High-speed on-chip oscillator oscillation clock frequency Notes 1, 2	f_{IH}		1.25		20	MHz
High-speed on-chip oscillator oscillation clock frequency accuracy		T_A = -20 to +85°C	-2.0		+2.0	%
		T_A = -40 to -20°C	-3.0		+3.0	%
Low-speed on-chip oscillator oscillation clock frequency	f_{IL}			15		kHz
Low-speed on-chip oscillator oscillation clock frequency accuracy			-15		+15	%

Notes 1. High-speed on-chip oscillator frequency is selected by bits 0 to 2 of option byte (000C2H).

2. This only indicates the oscillator characteristics. Refer to AC Characteristics for instruction execution time.

2.3 DC Characteristics

2.3.1 Pin characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V) **(1/2)**

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Output current, high Note 1	I_{OH1}	Per pin for 10-pin products: P00 to P04, P40 16-pin products: P00 to P07, P40, P41				-10.0 Note 2	mA
		Total of 10-pin products: P40 16-pin products: P40, P41 (When duty ≤ 70% Note 3)	4.0 V ≤ V_{DD} ≤ 5.5 V			-20.0	mA
			2.7 V ≤ V_{DD} < 4.0 V			-4.0	mA
			2.0 V ≤ V_{DD} < 2.7 V			-3.0	mA
		Total of 10-pin products: P00 to P04 16-pin products: P00 to P07 (When duty ≤ 70% Note 3)	4.0 V ≤ V_{DD} ≤ 5.5 V			-60.0	mA
			2.7 V ≤ V_{DD} < 4.0 V			-12.0	mA
			2.0 V ≤ V_{DD} < 2.7 V			-9.0	mA
		Total of all pins (When duty ≤ 70% Note 3)				-80.0	mA
Output current, low Note 4	I_{OL1}	Per pin for 10-pin products: P00 to P04, P40 16-pin products: P00 to P07, P40, P41				20.0 Note 2	mA
		Total of 10-pin products: P40 16-pin products: P40, P41 (When duty ≤ 70% Note 3)	4.0 V ≤ V_{DD} ≤ 5.5 V			40.0	mA
			2.7 V ≤ V_{DD} < 4.0 V			6.0	mA
			2.0 V ≤ V_{DD} < 2.7 V			1.2	mA
		Total of 10-pin products: P00 to P04 16-pin products: P00 to P07 (When duty ≤ 70% Note 3)	4.0 V ≤ V_{DD} ≤ 5.5 V			80.0	mA
			2.7 V ≤ V_{DD} < 4.0 V			12.0	mA
			2.0 V ≤ V_{DD} < 2.7 V			2.4	mA
		Total of all pins (When duty ≤ 70% Note 3)				120.0	mA

Notes 1. Value of current at which the device operation is guaranteed even if the current flows from the V_{DD} pin to an output pin.

2. Do not exceed the total current value.

3. This is the output current value under conditions where the duty factor ≤ 70%.
The output current value when the duty factor > 70% can be calculated with the following expression (when changing the duty factor to n%).

- Total output current of pins = (I_{OH} × 0.7)/(n × 0.01)
  <Example> Where n = 80 % and I_{OH} = - 10.0 mA
  Total output current of pins = (- 10.0 × 0.7)/(80 × 0.01) ≅ - 8.7 mA
- Total output current of pins = (I_{OL} × 0.7)/(n × 0.01)
  <Example> Where n = 80 % and I_{OL} = 10.0 mA
  Total output current of pins = (10.0 × 0.7)/(80 × 0.01) ≅ 8.7 mA

However, the current that is allowed to flow into one pin does not vary depending on the duty factor. A current higher than the absolute maximum rating must not flow into one pin.

4. Value of current at which the device operation is guaranteed even if the current flows from an output pin to the V_{SS} pin.

Caution P00, P01, P06, and P07 do not output high level in N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port.

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V) (2/2)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input voltage, high	V_{IH1}			0.8 V_{DD}		V_{DD}	V
Input voltage, low	V_{IL1}			0		0.2 V_{DD}	V
Output voltage, high Note 1	V_{OH1}	4.0 V ≤ V_{DD} ≤ 5.5 V	I_{OH} = -10 mA	V_{DD} - 1.5			V
			I_{OH} = -3.0 mA	V_{DD} - 0.7			V
		2.7 V ≤ V_{DD} ≤ 5.5 V	I_{OH} = -2.0 mA	V_{DD} - 0.6			V
		2.0 V ≤ V_{DD} ≤ 5.5 V	I_{OH} = -1.5 mA	V_{DD} - 0.5			V
Output voltage, low Note 2	V_{OL1}	4.0 V ≤ V_{DD} ≤ 5.5 V	I_{OL} = 20 mA			1.3	V
			I_{OL} = 8.5 mA			0.7	V
		2.7 V ≤ V_{DD} ≤ 5.5 V	I_{OL} = 3.0 mA			0.6	V
			I_{OL} = 1.5 mA			0.4	V
		2.0 V ≤ V_{DD} ≤ 5.5 V	I_{OL} = 0.6 mA			0.4	V
Input leakage current, high	I_{LIH1}	P00 to P07, P40, P41, P125, P137 V_I = V_{DD}				1	μA
	I_{LIH2}	P121, P122 (X1, X2, EXCLK) V_I = V_{DD}	In input port or external clock input			1	
			In resonator connection			10	
Input leakage current, low	I_{LIL1}	P00 to P07, P40, P41, P125, P137 V_I = V_{SS}				-1	μA
	I_{LIL2}	P121, P122 (X1, X2, EXCLK) V_I = V_{SS}	In input port or external clock input			-1	
			In resonator connection			-10	
On-chip pull-up resistance	R_U	V_I = V_{SS}		10	20	100	kΩ

Notes 1. The value under the condition which satisfies the high-level output current (I_{OH1}).

2. The value under the condition which satisfies the low-level output current (I_{OL1}).

Caution The maximum value of V_{IH} of P00, P01, P06, and P07 is V_{DD} even in N-ch open-drain mode. P00, P01, P06, and P07 do not output high level in N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port.

2.3.2 Supply current characteristics

(1) Flash ROM: 1 and 2 KB of 10-pin products

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit
Supply current Note 1	I_{DD1}	Operating mode	Basic operation	f_{IH} = 20 MHz	V_{DD} = 3.0 V, 5.0 V		0.91		mA
			Normal operation	f_{IH} = 20 MHz	V_{DD} = 3.0 V, 5.0 V		1.57	2.04	
				f_{IH} = 5 MHz	V_{DD} = 3.0 V, 5.0 V		0.85	1.15	
	I_{DD2} Note 2	HALT mode		f_{IH} = 20 MHz	V_{DD} = 3.0 V, 5.0 V		350	820	µA
				f_{IH} = 5 MHz	V_{DD} = 3.0 V, 5.0 V		290	600	
	I_{DD3} Note 3	STOP mode		V_{DD} = 3.0 V			0.56	2.00	µA

Notes 1. Total current flowing into V_{DD}, including the input leakage current flowing when the level of the input pin is fixed to V_{DD} or V_{SS}. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, I/O port, and on-chip pull-up/pull-down resistors.

2. During HALT instruction execution by flash memory.

3. Not including the current flowing into the watchdog timer.

Remarks 1. f_{IH}: High-speed on-chip oscillator clock frequency

2. Temperature condition of the typical value is T_A = 25°C

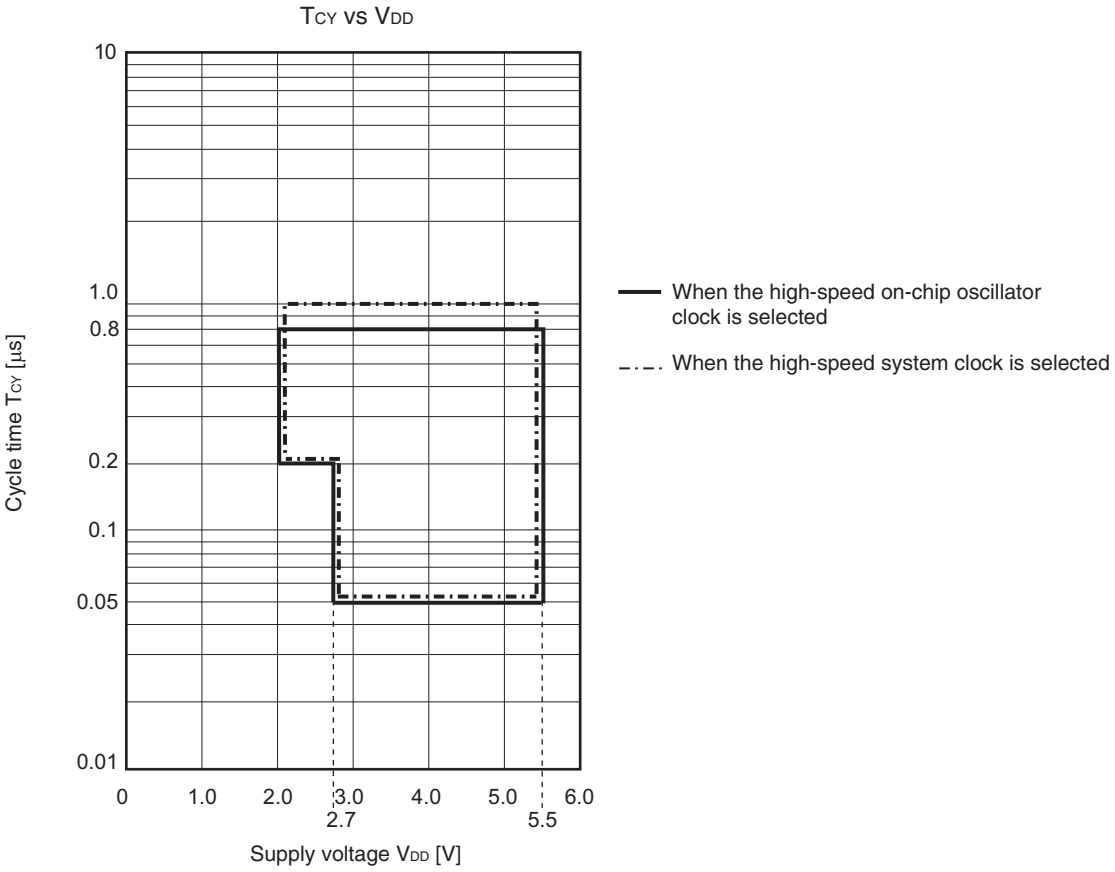
2.4 AC Characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

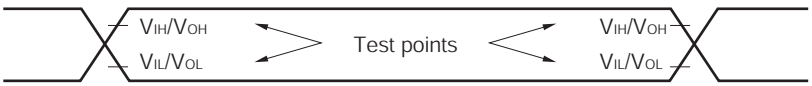
Items	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Instruction cycle (minimum instruction execution time)	T_{CY}	When high-speed on-chip oscillator clock (f_{IH}) is selected	2.7 V ≤ V_{DD} ≤ 5.5 V	0.05		0.8	μs
			2.0 V ≤ V_{DD} < 2.7 V	0.2		0.8	μs
		When high-speed system clock (f_{MX}) is selected	2.7 V ≤ V_{DD} ≤ 5.5 V	0.05		1.0	μs
			2.0 V ≤ V_{DD} < 2.7 V	0.2		1.0	μs
External system clock frequency	T_{EX}		2.7 V ≤ V_{DD} ≤ 5.5 V	1.0		20	MHz
			2.0 V ≤ V_{DD} < 2.7 V	1.0		5	MHz
External system clock input high-level width, low-level width	T_{EXH}, T_{EXL}		2.7 V ≤ V_{DD} ≤ 5.5 V	24			ns
			2.0 V ≤ V_{DD} < 2.7 V	95			ns
TI00 to TI03 input high-level width, low-level width	t_{TIH}, t_{TIL}	Noise filter is not used		1/f_{MCK} + 10			ns
TO00 to TO03 output frequency	f_{TO}	4.0 V ≤ V_{DD} ≤ 5.5 V				10	MHz
		2.7 V ≤ V_{DD} < 4.0 V				5	MHz
		2.0 V ≤ V_{DD} < 2.7 V				2.5	MHz
PCLBUZ0 output frequency	f_{PCL}	4.0 V ≤ V_{DD} ≤ 5.5 V				10	MHz
		2.7 V ≤ V_{DD} < 4.0 V				5	MHz
		2.0 V ≤ V_{DD} < 2.7 V				2.5	MHz
$\overline{\text{RESET}}$ low-level width	t_{RSL}			10			μs

Remark f_{MCK}: Timer array unit operation clock frequency
(Operation clock to be set by the timer clock select register 0 (TPS0) and the CKS0n1 bit of timer mode register 0nH (TMR0nH). n: Channel number (n = 0 to 3))

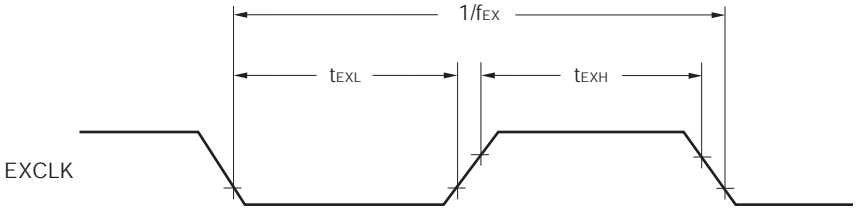
Minimum Instruction Execution Time during Main System Clock Operation



AC Timing Test Points



External System Clock Timing



(2) CSI mode (master mode, SCKp... internal clock output)

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
SCKp cycle time	t_{KCY1}	$t_{KCY1} \geq 4/f_{CLK}$	2.7 V ≤ V_{DD} ≤ 5.5 V	200			ns
			2.0 V ≤ V_{DD} ≤ 5.5 V	800			ns
SCKp high-/low-level width	t_{KH1}, t_{KL1}	2.7 V ≤ V_{DD} ≤ 5.5 V		t_{KCY1}/2 - 18			ns
		2.0 V ≤ V_{DD} ≤ 5.5 V		t_{KCY1}/2 - 50			ns
SIp setup time (to SCKp↑) Note 1	t_{SIK1}	2.7 V ≤ V_{DD} ≤ 5.5 V		47			ns
		2.0 V ≤ V_{DD} ≤ 5.5 V		110			ns
SIp hold time (from SCKp↑) Note 1	t_{KSI1}			19			ns
Delay time from SCKp↓ to SOp output Note 2	t_{KSO1}	C = 30 pF Note 3				25	ns

Notes 1. When DAP0n = 0 and CKP0n = 0, or DAP0n = 1 and CKP0n = 1. The SIp setup time becomes "to SCKp↓" and SIp hold time becomes "from SCKp↓" when DAP0n = 0 and CKP0n = 1, or DAP0n = 1 and CKP0n = 0.

2. When DAP0n = 0 and CKP0n = 0, or DAP0n = 1 and CKP0n = 1. The delay time to SOp output becomes "from SCKp↑" when DAP0n = 0 and CKP0n = 1, or DAP0n = 1 and CKP0n = 0.

3. C is the load capacitance of the SCKp and SOp output lines.

(3) CSI mode (slave mode, SCKp... external clock input)

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
SCKp cycle time	t_{KCY2}	2.7 V ≤ V_{DD} ≤ 5.5 V	f_{MCK} > 16 MHz	8/f_{MCK}			ns
			f_{MCK} ≤ 16 MHz	6/f_{MCK}			ns
		2.0 V ≤ V_{DD} ≤ 5.5 V		6/f_{MCK}			ns
SCKp high-/low-level width	t_{KH2}, t_{KL2}	2.0 V ≤ V_{DD} ≤ 5.5 V		t_{KCY2}/2 - 18			ns
SIp setup time (to SCKp↑) Note 1	t_{SIK2}	2.7 V ≤ V_{DD} ≤ 5.5 V		1/f_{MCK} + 20			ns
		2.0 V ≤ V_{DD} ≤ 5.5 V		1/f_{MCK} + 30			ns
SIp hold time (from SCKp↑) Note 1	t_{KSI2}	2.0 V ≤ V_{DD} ≤ 5.5 V		1/f_{MCK} + 31			ns
Delay time from SCKp↓ to SOp output Note 2	t_{KSO2}	C = 30 pF Note 3	2.7 V ≤ V_{DD} ≤ 5.5 V			2/f_{MCK} + 50	ns
			2.0 V ≤ V_{DD} ≤ 5.5 V			2/f_{MCK} + 110	ns

Notes 1. When DAP0n = 0 and CKP0n = 0, or DAP0n = 1 and CKP0n = 1. The SIp setup time becomes "to SCKp↓" and the SIp hold time becomes "from SCKp↓" when DAP0n = 0 and CKP0n = 1, or DAP0n = 1 and CKP0n = 0.

2. When DAP0n = 0 and CKP0n = 0, or DAP0n = 1 and CKP0n = 1. The delay time to SOp output becomes "from SCKp↑" when DAP0n = 0 and CKP0n = 1, or DAP0n = 1 and CKP0n = 0.

3. C is the load capacitance of the SOp output lines.

Remarks 1. p: CSI number (p = 00, 01), n: Channel number (n = 0, 1)

2. f_{MCK}: Serial array unit operation clock frequency
(Operation clock to be set by the serial clock select register 0 (SPS0) and the CKS0n bit of the serial mode register 0nH (SMR0nH). n: Channel number (n = 0, 1))

(4) Simplified I²C mode

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

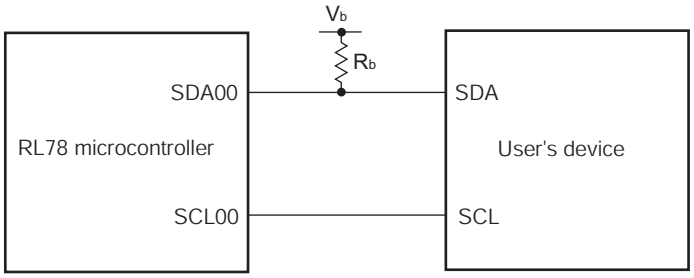
Parameter	Symbol	Conditions	MIN.	MAX.	Unit
SCLr clock frequency	f_{SCL}	C_b = 100 pF, R_b = 3 kΩ		400 Note 1	kHz
Hold time when SCLr = "L"	t_{LOW}	C_b = 100 pF, R_b = 3 kΩ	1150		ns
Hold time when SCLr = "H"	t_{HIGH}	C_b = 100 pF, R_b = 3 kΩ	1150		ns
Data setup time (reception)	$t_{SU:DAT}$	C_b = 100 pF, R_b = 3 kΩ	1/f_{MCK} + 145 Note 2		ns
Data hold time (transmission)	$t_{HD:DAT}$	C_b = 100 pF, R_b = 3 kΩ	0	355	ns

Notes 1. The value must also be equal to or less than f_{MCK}/4.

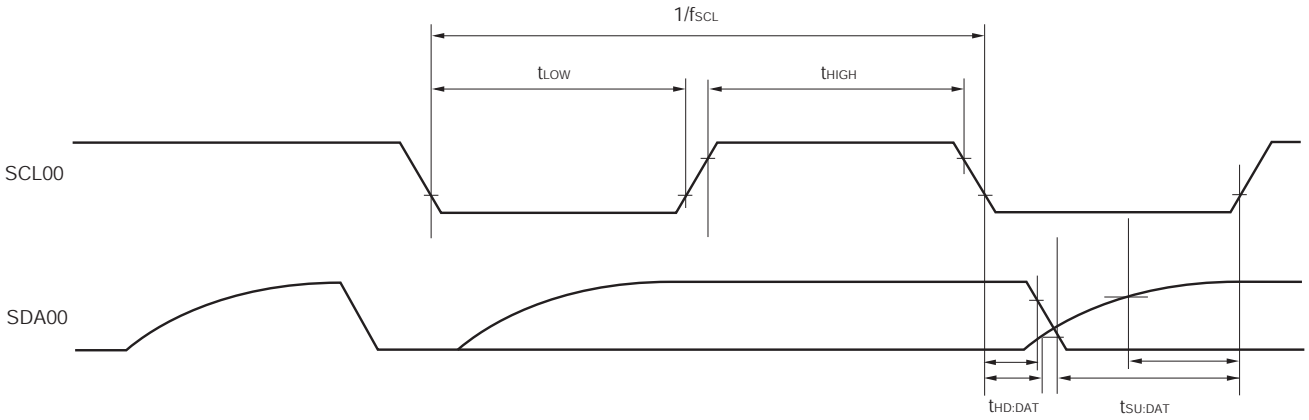
2. Set the f_{MCK} value to keep the hold time of SCLr = "L" and SCLr = "H".

Caution Select the N-ch open drain output (V_{DD} tolerance) mode for the SDAr pin by using the port output mode register 0 (POM0).

Simplified I²C mode connection diagram



Simplified I²C mode serial transfer timing



Remarks 1. R_b [Ω]: Communication line (SDAr) pull-up resistance,
C_b [F]: Communication line (SCLr, SDAr) load capacitance

2. r: IIC number (r = 00)

3. f_{MCK}: Serial array unit operation clock frequency
(Operation clock to be set by the serial clock select register 0 (SPS0) and the CKS0n bit of the serial mode register 0nH (SMR0nH). n: Channel number (n = 0))

2.6 Analog Characteristics

2.6.1 A/D converter characteristics

(Target pin: ANI0 to ANI6, internal reference voltage)

(T_A = –40 to +85°C, 2.4 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		10	bit
Overall error Notes 1, 2, 3	AINL	10-bit resolution	V_{DD} = 5 V		±1.7	±3.1	LSB
			V_{DD} = 3 V		±2.3	±4.5	LSB
Conversion time	t_{CONV}	10-bit resolution Target pin: ANI0 to ANI6	2.7 V ≤ V_{DD} ≤ 5.5 V	3.4		18.4	μs
			2.4 V ≤ V_{DD} ≤ 5.5 V Note 5	4.6		18.4	μs
		10-bit resolution Target pin: internal reference voltage Note 6	2.4 V ≤ V_{DD} ≤ 5.5 V	4.6		18.4	μs
Zero-scale error Notes 1, 2, 3, 4	E_{ZS}	10-bit resolution	V_{DD} = 5 V			±0.19	%FSR
			V_{DD} = 3 V			±0.39	%FSR
Full-scale error Notes 1, 2, 3, 4	E_{FS}	10-bit resolution	V_{DD} = 5 V			±0.29	%FSR
			V_{DD} = 3 V			±0.42	%FSR
Integral linearity error Notes 1, 2, 3	ILE	10-bit resolution	V_{DD} = 5 V			±1.8	LSB
			V_{DD} = 3 V			±1.7	LSB
Differential linearity error Notes 1, 2, 3	DLE	10-bit resolution	V_{DD} = 5 V			±1.4	LSB
			V_{DD} = 3 V			±1.5	LSB
Analog input voltage	V_{AIN}	Target pin: ANI0 to ANI6		0		V_{DD}	V
		Target pin: internal reference voltage Note 6		V_{REG} Note 7			V

Notes 1. TYP. Value is the average value at T_A = 25°C. MAX. value is the average value ±3σ at normal distribution.

2. These values are the results of characteristic evaluation and are not checked for shipment.

3. Excludes quantization error (±1/2 LSB).

4. This value is indicated as a ratio (%FSR) to the full-scale value.

5. Set the LV0 bit in the A/D converter mode register 0 (ADM0) to 0 when conversion is done in the operating voltage range of 2.4 V ≤ V_{DD} < 2.7 V.

6. Set the LV0 bit in the A/D converter mode register 0 (ADM0) to 0 when the internal reference voltage is selected as the target for conversion.

7. Refer to **2.6.3 Internal reference voltage characteristics**.

Cautions 1. Arrange wiring and insert the capacitor so that no noise appears on the power supply/ground line.

2. Do not allow any pulses that rapidly change such as digital signals to be input/output to/from the pins adjacent to the conversion pin during A/D conversion.

3. Note that the internal reference voltage cannot be used as the reference voltage of the comparator when the internal reference voltage is selected as the target for A/D conversion.

2.6.2 Comparator characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input voltage range	I_{VREF}	IVREF0 pin input (when C0VFR bit = 0)		0		V_{DD} - 1.4	V
		Internal reference voltage (when C0VRF bit = 1) Note 1		V_{REG} Note 2			V
	I_{VCMP}	IVCMP0 pin input		-0.3		V_{DD} + 0.3	V
Output delay	t_d	V_{DD} = 3.0 V, input slew rate > 50 mV/µs	High-speed mode			0.5	µs
			Low-speed mode		2.0		µs
Operation stabilization wait time	t_{CMP}			100			µs

Notes 1. When the internal reference voltage is selected as the reference voltage of the comparator, the internal reference voltage cannot be used as the target for A/D conversion.

2. Refer to **2.6.3 Internal reference voltage characteristics**.

2.6.3 Internal reference voltage characteristics

(T_A = –40 to +85°C, 2.0 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Internal reference voltage	V_{REG}		0.74	0.815	0.89	V
Operation stabilization wait time	t_{AMP}	When A/D converter is used (ADS register = 07H)	5			µs

Note The internal reference voltage cannot be simultaneously used by the A/D converter and the comparator; only one of them must be selected.

2.8 Flash Memory Programming Characteristics

(T_A = 0 to + 40°C, 4.5 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Code flash memory rewritable times Notes 1, 2, 3	C_{erwr}	Retained for 20 years.	T_A = +85°C	1000			Times

Notes 1. 1 erase + 1 write after the erase is regarded as 1 rewrite. The retaining years are until next rewrite after the rewrite.

2. When using flash memory programmer.

3. These are the characteristics of the flash memory and the results obtained from reliability testing by Renesas Electronics Corporation.

2.9 Dedicated Flash Memory Programmer Communication (UART)

(T_A = 0 to + 40°C, 4.5 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Transfer rate				115,200		bps

Remark The transfer rate during flash memory programming is fixed to 115,200 bps.

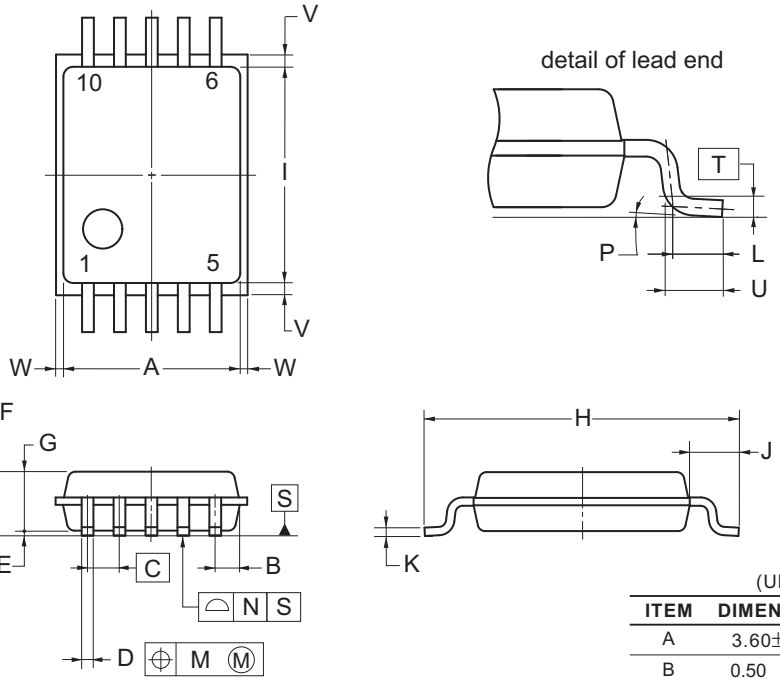
3. PACKAGE DRAWINGS

3.1 10-pin products

R5F10Y17ASP, R5F10Y16ASP, R5F10Y14ASP

<R> R5F10Y17DSP, R5F10Y16DSP, R5F10Y14DSP

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LSSOP10-4.4x3.6-0.65	PLSP0010JA-A	P10MA-65-CAC-2	0.05



(UNIT:mm)

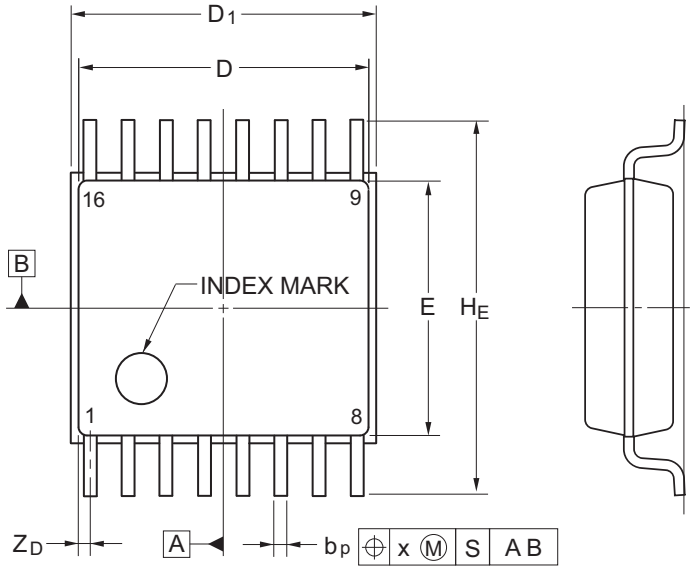
ITEM	DIMENSIONS
A	3.60±0.10
B	0.50
C	0.65 (T.P.)
D	0.24±0.08
E	0.10±0.05
F	1.45 MAX.
G	1.20±0.10
H	6.40±0.20
I	4.40±0.10
J	1.00±0.20
K	$0.17^{+0.08}_{-0.07}$
L	0.50
M	0.13
N	0.10
P	$3^{\circ}{}^{+5^{\circ}}_{-3^{\circ}}$
T	0.25 (T.P.)
U	0.60±0.15
V	0.25 MAX.
W	0.15 MAX.

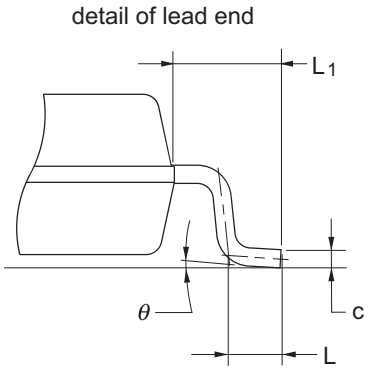
NOTE
Each lead centerline is located within 0.13 mm of its true position (T.P.) at maximum material condition.

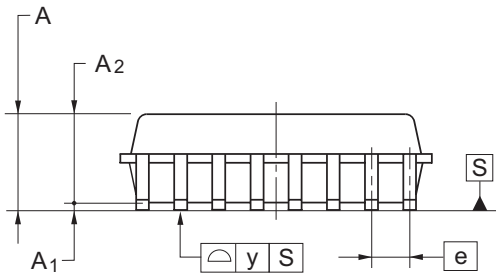
3.2 16-pin products

R5F10Y47ASP, R5F10Y46ASP, R5F10Y44ASP
<R> R5F10Y47DSP, R5F10Y46DSP, R5F10Y44DSP

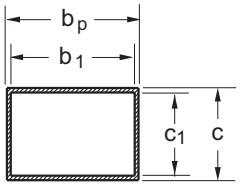
JEITA Package code	RENESAS code	Previous code	MASS(TYP.)[g]
P-SSOP16-4.4x5-0.65	PRSP0016JC-B	P16MA-65-FAB-1	0.08







Terminal cross section



Referance Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	4.85	5.00	5.15
D_1	5.05	5.20	5.35
E	4.20	4.40	4.60
A_2	—	1.50	—
A_1	0.075	0.125	0.175
A	—	—	1.725
b_p	0.17	0.24	0.32
b_1	—	0.22	—
c	0.14	0.17	0.20
c_1	—	0.15	—
θ	0°	—	8°
H_E	6.20	6.40	6.60
e	—	0.65	—
x	—	—	0.13
y	—	—	0.10
Z_D	—	0.225	—
L	0.35	0.50	0.65
L_1	—	1.00	—

Revision History	RL78/G10 Datasheet

Rev.	Date	Description	
		Page	Summary
1.00	Apr 15, 2013	-	First Edition issued
2.00	Jan 10, 2014	1, 2	Modification of descriptions in 1.1 Features
		3	Modification of description in 1.2 List of Part Numbers
		4	Modification of remark 2 in 1.3.1 10-pin products and 1.3.2 16-pin products
		8, 9	Addition of description of R5F10Y17ASP in 1.6 Outline of Functions
		11	Modification of description in 2.1 Absolute Maximum Ratings
		12	Modification of description in 2.2 Oscillator Characteristics
		13, 14	Modification of description, notes 1 to 4, and caution in 2.3.1 Pin characteristics
		16	Addition of description, notes 1 to 6, and remarks 1 and 2 in (2) Flash ROM: 4 KB of 10-pin products, and 16-pin products
		17	Addition of description, notes 1 to 6, and remarks 1 to 3 in (3) Peripheral Functions (Common to all products)
		18	Modification of description in 2.4 AC Characteristics
		19	Addition of figure of Minimum Instruction Execution Time during Main System Clock Operation
		19	Addition of figure of External System Clock Timing
		20	Modification of TI/TO Timing
		25	Addition of description in 2.5.2 Serial interface IICA
		26	Modification of description and notes 1 to 6 in 2.6.1 A/D converter characteristics
		27	Addition of description, notes 1 and 2 in 2.6.2 Comparator characteristics
		27	Addition of description and note in 2.6.3 Internal reference voltage characteristics
		28	Addition of caution in 2.6.4 SPOR Circuit characteristics
		28	Addition of figure in 2.6.6 Data retention power supply voltage characteristics
		31	Addition of R5F10Y17ASP in 3.1 10-pin products
		32	Modification of package drawing in 3.2 16-pin products
3.00	Nov 19, 2014	3	Addition of industrial applications in Figure 1-1 Part Number, Memory Size, and Package of RL78/G10
		3	Addition of industrial applications in Table 1-1 List of Ordering Part Numbers
		4	Addition of description to pin configuration in 1.3.1 10-pin products and 1.3.2 16-pin products
		22	Correction of error in 2.5.1 Serial array unit, (3) CSI mode (slave mode, SCKp... external clock input)
		28	Renamed to 2.7 RAM Data Retention Characteristics and modification of figure
		31	Addition of industrial application in 3.1 10-pin products
		32	Addition of industrial application in 3.2 16-pin products and modification of package drawing
3.10	Aug 12, 2016	1	Addition of description to Rich Analog in 1.1 Features
		3	Corrected Table 1-1. List of Ordering Part Numbers
		4	Modification of 1.3 Pin Configuration (Top View)
		31, 32	Deletion of under development

NOTES FOR CMOS DEVICES

(1) VOLTAGE APPLICATION WAVEFORM AT INPUT PIN: Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between VIL (MAX) and VIH (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between VIL (MAX) and VIH (MIN).

(2) HANDLING OF UNUSED INPUT PINS: Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

(3) PRECAUTION AGAINST ESD: A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

(4) STATUS BEFORE INITIALIZATION: Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

(5) POWER ON/OFF SEQUENCE: In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.

(6) INPUT OF SIGNAL DURING POWER OFF STATE : Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.

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