



Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	15
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f1847-e-ml

3.0 MEMORY ORGANIZATION

There are three types of memory in PIC16(L)F1847: Data Memory, Program Memory and Data EEPROM Memory⁽¹⁾.

- Program Memory
- Data Memory
 - Core Registers
 - Special Function Registers
 - General Purpose RAM
 - Common RAM
 - Device Memory Maps
 - Special Function Registers Summary
- Data EEPROM memory⁽¹⁾

Note 1: The Data EEPROM Memory and the method to access Flash memory through the EECON registers is described in [Section 11.0 “Data EEPROM and Flash Program Memory Control”](#).

The following features are associated with access and control of program memory and data memory:

- PCL and PCLATH
- Stack
- Indirect Addressing

3.1 Program Memory Organization

The enhanced mid-range core has a 15-bit program counter capable of addressing a 32K x 14 program memory space. [Table 3-1](#) shows the memory sizes implemented for the PIC16(L)F1847 family. Accessing a location above these boundaries will cause a wrap-around within the implemented memory space. The Reset vector is at 0000h and the interrupt vector is at 0004h (see [Figure 3-1](#)).

TABLE 3-1: DEVICE SIZES AND ADDRESSES

Device	Program Memory Space (Words)	Last Program Memory Address
PIC16(L)F1847	8,192	1FFFh

PIC16(L)F1847

TABLE 3-8: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets		
Bank 2													
100h ⁽¹⁾	INDF0	Addressing this location uses contents of FSR0H/FSR0L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx		
101h ⁽¹⁾	INDF1	Addressing this location uses contents of FSR1H/FSR1L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx		
102h ⁽¹⁾	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000		
103h ⁽¹⁾	STATUS	—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	---1 1000	---q quuu		
104h ⁽¹⁾	FSR0L	Indirect Data Memory Address 0 Low Pointer								0000 0000	uuuu uuuu		
105h ⁽¹⁾	FSR0H	Indirect Data Memory Address 0 High Pointer								0000 0000	0000 0000		
106h ⁽¹⁾	FSR1L	Indirect Data Memory Address 1 Low Pointer								0000 0000	uuuu uuuu		
107h ⁽¹⁾	FSR1H	Indirect Data Memory Address 1 High Pointer								0000 0000	0000 0000		
108h ⁽¹⁾	BSR	—	—	—	BSR<4:0>					---0 0000	---0 0000		
109h ⁽¹⁾	WREG	Working Register								0000 0000	uuuu uuuu		
10Ah ⁽¹⁾	PCLATH	—	Write Buffer for the upper 7 bits of the Program Counter									-000 0000	-000 0000
10Bh ⁽¹⁾	INTCON	GIE	PEIE	TMR0IE	INTE	IOCE	TMR0IF	INTF	IOCF	0000 000x	0000 000u		
10Ch	LATA	LATA7	LATA6	—	LATA4	LATA3	LATA2	LATA1	LATA0	xx-x xxxx	uu-u uuuu		
10Dh	LATB	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx xxxx	uuuu uuuu		
10Eh	—	Unimplemented								—	—		
10Fh	—	Unimplemented								—	—		
110h	—	Unimplemented								—	—		
111h	CM1CON0	C1ON	C1OUT	C1OE	C1POL	—	C1SP	C1HYS	C1SYNC	0000 -100	0000 -100		
112h	CM1CON1	C1INTP	C1INTN	C1PCH<1:0>		—	—	C1NCH<1:0>		0000 --00	0000 --00		
113h	CM2CON0	C2ON	C2OUT	C2OE	C2POL	—	C2SP	C2HYS	C2SYNC	0000 -100	0000 -100		
114h	CM2CON1	C2INTP	C2INTN	C2PCH<1:0>		—	—	C2NCH<1:0>		0000 --00	0000 --00		
115h	CMOUT	—	—	—	—	—	—	MC2OUT	MC1OUT	---- --00	---- --00		
116h	BORCON	SBOREN	—	—	—	—	—	—	BORRDY	1--- ---q	u--- ---u		
117h	FVRCON	FVREN	FVRDY	TSEN	TSRNG	CDAFVR<1:0>		ADFVR<1:0>		0qrr 0000	0qrr 0000		
118h	DACCON0	DACEN	DACLPS	DACOE	—	DACPSS<1:0>		—	DACNSS	000- 00-0	000- 00-0		
119h	DACCON1	—	—	—	DACR<4:0>					---0 0000	---0 0000		
11Ah	SRCON0	SRLN	SRCLK<2:0>			SRQEN	SRNQEN	SRPS	SRPR	0000 0000	0000 0000		
11Bh	SRCON1	SRSPE	SRSCKE	SRSC2E	SRSC1E	SRRPE	SRRCKE	SRRC2E	SRRC1E	0000 0000	0000 0000		
11Ch	—	Unimplemented								—	—		
11Dh	APFCON0	RXDTSEL	SDO1SEL	SS1SEL	P2BSEL	CCP2SEL	P1DSEL	P1CSEL	CCP1SEL	0000 0000	0000 0000		
11Eh	APFCON1	—	—	—	—	—	—	—	TXCKSEL	---- --0	---- --0		
11Fh	—	Unimplemented								—	—		

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved.
Shaded locations are unimplemented, read as '0'.

Note 1: These registers can be addressed from any bank.
2: Unimplemented, read as '1'.

PIC16(L)F1847

TABLE 3-8: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets	
Bank 8												
400h ⁽¹⁾	INDF0	Addressing this location uses contents of FSR0H/FSR0L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx	
401h ⁽¹⁾	INDF1	Addressing this location uses contents of FSR1H/FSR1L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx	
402h ⁽¹⁾	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000	
403h ⁽¹⁾	STATUS	—	—	—	\overline{TO}	\overline{PD}	Z	DC	C	---1 1000	---q quuu	
404h ⁽¹⁾	FSR0L	Indirect Data Memory Address 0 Low Pointer								0000 0000	uuuu uuuu	
405h ⁽¹⁾	FSR0H	Indirect Data Memory Address 0 High Pointer								0000 0000	0000 0000	
406h ⁽¹⁾	FSR1L	Indirect Data Memory Address 1 Low Pointer								0000 0000	uuuu uuuu	
407h ⁽¹⁾	FSR1H	Indirect Data Memory Address 1 High Pointer								0000 0000	0000 0000	
408h ⁽¹⁾	BSR	—	—	—	BSR<4:0>					---0 0000	---0 0000	
409h ⁽¹⁾	WREG	Working Register								0000 0000	uuuu uuuu	
40Ah ⁽¹⁾	PCLATH	—	Write Buffer for the upper 7 bits of the Program Counter								-000 0000	-000 0000
40Bh ⁽¹⁾	INTCON	GIE	PEIE	TMR0IE	INTE	IOCE	TMR0IF	INTF	IOCF	0000 000x	0000 000u	
40Ch	—	Unimplemented								—	—	
40Dh	—	Unimplemented								—	—	
40Eh	—	Unimplemented								—	—	
40Fh	—	Unimplemented								—	—	
410h	—	Unimplemented								—	—	
411h	—	Unimplemented								—	—	
412h	—	Unimplemented								—	—	
413h	—	Unimplemented								—	—	
414h	—	Unimplemented								—	—	
415h	TMR4	Timer4 Module Register								0000 0000	0000 0000	
416h	PR4	Timer4 Period Register								1111 1111	1111 1111	
417h	T4CON	—	T4OUTPS<3:0>				TMR4ON	T4CKPS<1:0>		-000 0000	-000 0000	
418h	—	Unimplemented								—	—	
419h	—	Unimplemented								—	—	
41Ah	—	Unimplemented								—	—	
41Bh	—	Unimplemented								—	—	
41Ch	TMR6	Timer6 Module Register								0000 0000	0000 0000	
41Dh	PR6	Timer6 Period Register								1111 1111	1111 1111	
41Eh	T6CON	—	T6OUTPS<3:0>				TMR6ON	T6CKPS<1:0>		-000 0000	-000 0000	
41Fh	—	Unimplemented								—	—	

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, r = reserved.
Shaded locations are unimplemented, read as '0'.

Note 1: These registers can be addressed from any bank.
2: Unimplemented, read as '1'.

3.5 Stack

All devices have a 16-level x 15-bit wide hardware stack (refer to Figures 3-4 through 3-7). The stack space is not part of either program or data space. The PC is PUSHed onto the stack when `CALL` or `CALLW` instructions are executed or an interrupt causes a branch. The stack is POPed in the event of a `RETURN`, `RETLW` or a `RETFIE` instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer if the `STVREN` bit = 0 (Configuration Words). This means that after the stack has been PUSHed 16 times, the 17th PUSH overwrites the value that was stored from the first PUSH. The 18th PUSH overwrites the second PUSH (and so on). The `STKOVF` and `STKUNF` flag bits will be set on an Overflow/Underflow, regardless of whether the Reset is enabled.

Note 1: There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the `CALL`, `CALLW`, `RETURN`, `RETLW` and `RETFIE` instructions or the vectoring to an interrupt address.

3.5.1 ACCESSING THE STACK

The stack is available through the TOSH, TOSL and STKPTR registers. STKPTR is the current value of the Stack Pointer. TOSH:TOSL register pair points to the TOP of the stack. Both registers are read/writable. TOS is split into TOSH and TOSL due to the 15-bit size of the PC. To access the stack, adjust the value of STKPTR, which will position TOSH:TOSL, then read/write to TOSH:TOSL. STKPTR is five bits to allow detection of overflow and underflow.

Note: Care should be taken when modifying the STKPTR while interrupts are enabled.

During normal program operation, `CALL`, `CALLW` and Interrupts will increment STKPTR while `RETLW`, `RETURN`, and `RETFIE` will decrement STKPTR. At any time STKPTR can be inspected to see how much stack is left. The STKPTR always points at the currently used place on the stack. Therefore, a `CALL` or `CALLW` will increment the STKPTR and then write the PC, and a return will unload the PC and then decrement STKPTR.

Reference Figure 3-4 through Figure 3-7 for examples of accessing the stack.

FIGURE 3-4: ACCESSING THE STACK EXAMPLE 1

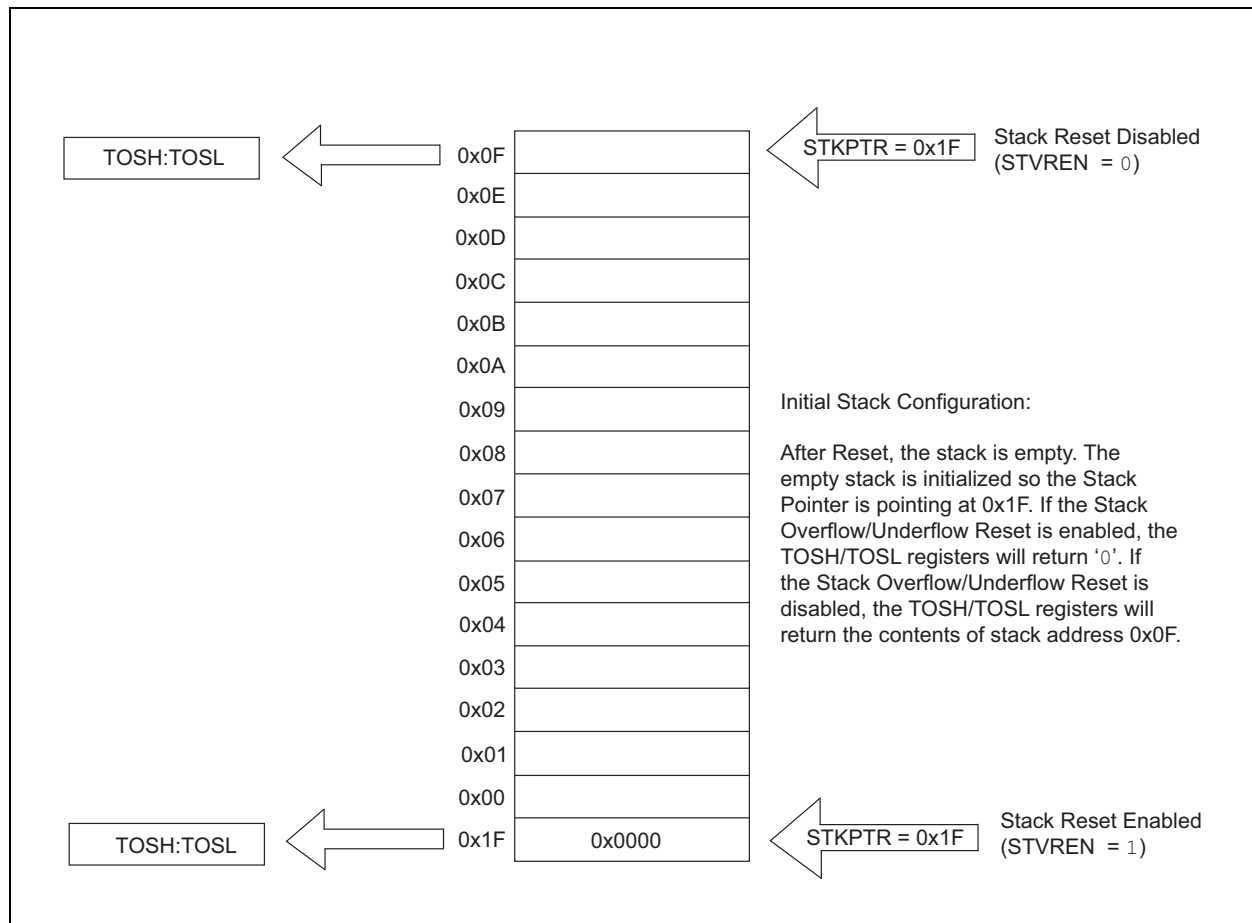
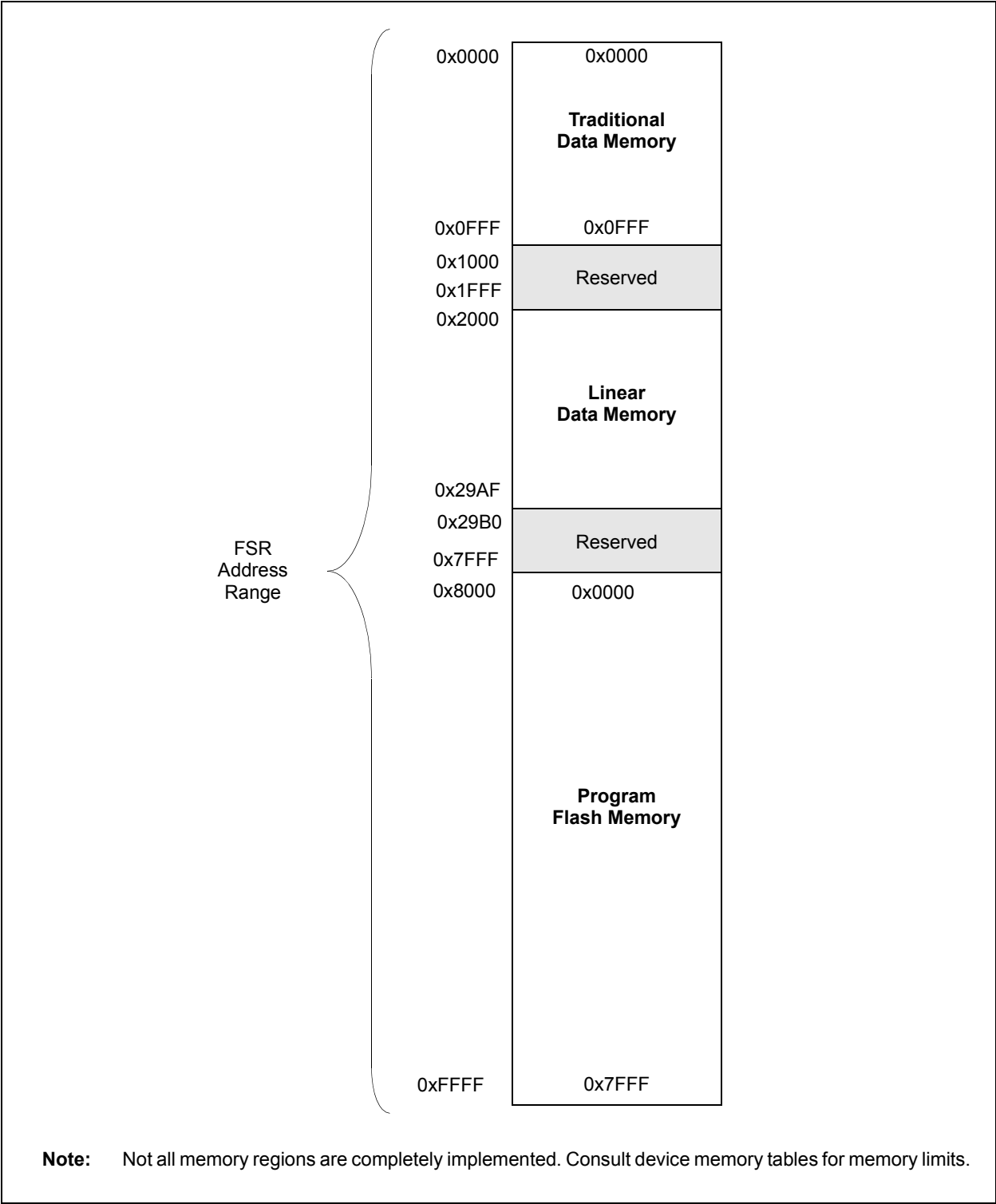


FIGURE 3-8: INDIRECT ADDRESSING



4.0 DEVICE CONFIGURATION

Device Configuration consists of Configuration Word 1 and Configuration Word 2, Code Protection and Device ID.

4.1 Configuration Words

There are several Configuration Word bits that allow different oscillator and memory protection options. These are implemented as Configuration Word 1 at 8007h and Configuration Word 2 at 8008h.

<p>Note: The <code>DEBUG</code> bit in Configuration Word is managed automatically by device development tools including debuggers and programmers. For normal device operation, this bit should be maintained as a '1'.</p>

TABLE 6-1: SUMMARY OF REGISTERS ASSOCIATED WITH REFERENCE CLOCK SOURCES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CLKRCON	CLKREN	CLKROE	CLKRSLR	CLKRDC<1:0>		CLKRDIV<2:0>			70

Legend: — = unimplemented locations read as '0'. Shaded cells are not used by reference clock sources.

TABLE 6-2: SUMMARY OF CONFIGURATION WORD WITH REFERENCE CLOCK SOURCES

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIG1	13:8	—	—	FCMEN	IESO	CLKOUTEN	BOREN<1:0>		CPD	46
	7:0	CP	MCLRE	PWRTÉ	WDTE<1:0>		FOSC<2:0>			

Legend: — = unimplemented locations read as '0'. Shaded cells are not used by reference clock sources.

REGISTER 8-4: **PIE3: PERIPHERAL INTERRUPT ENABLE REGISTER 3**

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	U-0
—	—	CCP4IE	CCP3IE	TMR6IE	—	TMR4IE	—
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7-6 **Unimplemented:** Read as '0'
- bit 5 **CCP4IE:** CCP4 Interrupt Enable bit
 - 1 = Enables the CCP4 interrupt
 - 0 = Disables the CCP4 interrupt
- bit 4 **CCP3IE:** CCP3 Interrupt Enable bit
 - 1 = Enables the CCP3 interrupt
 - 0 = Disables the CCP3 interrupt
- bit 3 **TMR6IE:** TMR6 to PR6 Match Interrupt Enable bit
 - 1 = Enables the TMR6 to PR6 Match interrupt
 - 0 = Disables the TMR6 to PR6 Match interrupt
- bit 2 **Unimplemented:** Read as '0'
- bit 1 **TMR4IE:** TMR4 to PR4 Match Interrupt Enable bit
 - 1 = Enables the TMR4 to PR4 Match interrupt
 - 0 = Disables the TMR4 to PR4 Match interrupt
- bit 0 **Unimplemented:** Read as '0'

Note 1: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

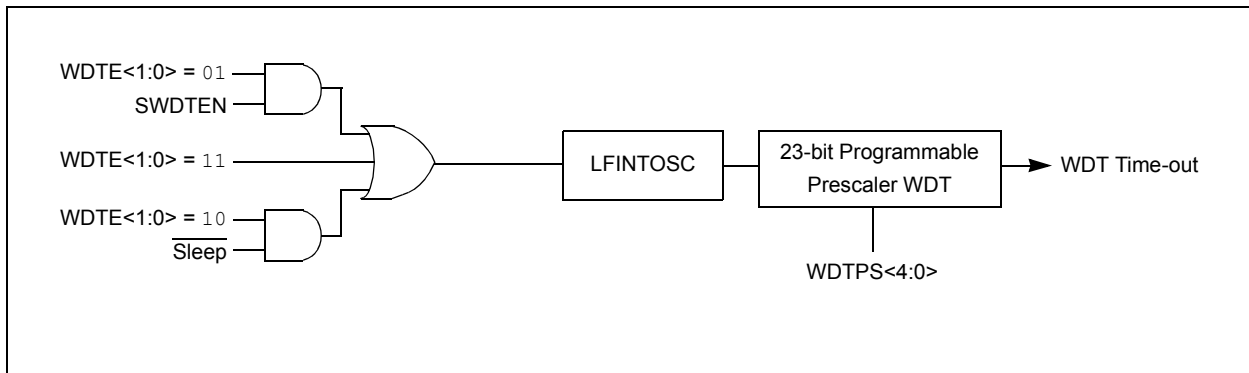
10.0 WATCHDOG TIMER

The Watchdog Timer is a system timer that generates a Reset if the firmware does not issue a `CLRWDT` instruction within the time-out period. The Watchdog Timer is typically used to recover the system from unexpected events.

The WDT has the following features:

- Independent clock source
- Multiple operating modes
 - WDT is always on
 - WDT is off when in Sleep
 - WDT is controlled by software
 - WDT is always off
- Configurable time-out period is from 1 ms to 256 seconds (typical)
- Multiple Reset conditions
- Operation during Sleep

FIGURE 10-1: WATCHDOG TIMER BLOCK DIAGRAM



16.2.7 ADC REGISTER DEFINITIONS

The following registers are used to control the operation of the ADC.

REGISTER 16-1: ADCON0: ADC CONTROL REGISTER 0

U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	CHS<4:0>					GO/DONE	ADON
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7 **Unimplemented:** Read as '0'

bit 6-2 **CHS<4:0>:** Analog Channel Select bits

00000 = AN0

00001 = AN1

00010 = AN2

00011 = AN3

00100 = AN4

00101 = AN5

00110 = AN6

00111 = AN7

01000 = AN8

01001 = AN9

01010 = AN10

01011 = AN11

01100 = Reserved. No channel connected.

•

•

•

11100 = Reserved. No channel connected.

11101 = Temperature Indicator

11110 = DAC output⁽¹⁾

11111 = FVR (Fixed Voltage Reference) Buffer 1 Output⁽²⁾

bit 1 **GO/DONE:** ADC Conversion Status bit

1 = ADC conversion cycle in progress. Setting this bit starts an ADC conversion cycle.

This bit is automatically cleared by hardware when the ADC conversion has completed.

0 = ADC conversion completed/not in progress

bit 0 **ADON:** ADC Enable bit

1 = ADC is enabled

0 = ADC is disabled and consumes no operating current

Note 1: See [Section 17.0 “Digital-to-Analog Converter \(DAC\) Module”](#) for more information.

2: See [Section TABLE 14-1: “Summary of Registers Associated with the Fixed Voltage Reference”](#) for more information.

REGISTER 19-2: CMxCON1: COMPARATOR Cx CONTROL REGISTER 1

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0
CxINTP	CxINTN	CxPCH<1:0>	—	—	—	CxNCH<1:0>	—
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7 **CxINTP:** Comparator Interrupt on Positive Going Edge Enable bits
 1 = The CxIF interrupt flag will be set upon a positive going edge of the CxOUT bit
 0 = No interrupt flag will be set on a positive going edge of the CxOUT bit
- bit 6 **CxINTN:** Comparator Interrupt on Negative Going Edge Enable bits
 1 = The CxIF interrupt flag will be set upon a negative going edge of the CxOUT bit
 0 = No interrupt flag will be set on a negative going edge of the CxOUT bit
- bit 5-4 **CxPCH<1:0>:** Comparator Positive Input Channel Select bits
 00 = CxVP connects to CxIN+ pin⁽¹⁾
 01 = CxVP connects to DAC Voltage Reference
 10 = CxVP connects to FVR Voltage Reference
For C1:
 11 = CxVP connects to C12IN+ pin
For C2:
 11 = CxVP connects to Vss
- bit 3-2 **Unimplemented:** Read as '0'
- bit 1-0 **CxNCH<1:0>:** Comparator Negative Input Channel Select bits
 00 = CxVN connects to C12IN0- pin
 01 = CxVN connects to C12IN1- pin
 10 = CxVN connects to C12IN2- pin
 11 = CxVN connects to C12IN3- pin

Note 1: CxVP connects to C12IN+ pin when using Comparator 2.

REGISTER 19-3: CMOUT: COMPARATOR OUTPUT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R-0/0	R-0/0
—	—	—	—	—	—	MC2OUT	MC1OUT
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7-2 **Unimplemented:** Read as '0'
- bit 1 **MC2OUT:** Mirror Copy of C2OUT bit
- bit 0 **MC1OUT:** Mirror Copy of C1OUT bit

PIC16(L)F1847

TABLE 22-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER2/4/6

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
INTCON	GIE	PEIE	TMR0IE	INTE	IOCE	TMR0IF	INTF	IOCF	88
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	CCP1IE	TMR2IE	TMR1IE	89
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	CCP1IF	TMR2IF	TMR1IF	93
PIE3	—	—	CCP4IE	CCP3IE	TMR6IE	—	TMR4IE	—	91
PIR3	—	—	CCP4IF	CCP3IF	TMR6IF	—	TMR4IF	—	95
PR2	Timer2 Module Period Register								189*
PR4	Timer4 Module Period Register								189*
PR6	Timer6 Module Period Register								189*
T2CON	—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>		191
T4CON	—	T4OUTPS<3:0>				TMR4ON	T4CKPS<1:0>		191
T6CON	—	T6OUTPS<3:0>				TMR6ON	T6CKPS<1:0>		191
TMR2	Holding Register for the 8-bit TMR2 Time Base								189*
TMR4	Holding Register for the 8-bit TMR4 Time Base								189*
TMR6	Holding Register for the 8-bit TMR6 Time Base								189*

Legend: — = unimplemented read as '0'. Shaded cells are not used for Timer2 module.

* Page provides register information.

PIC16(L)F1847

REGISTER 23-1: MDCON: MODULATION CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-1/1	R/W-0/0	R-0/0	U-0	U-0	R/W-0/0
MDEN	MDOE	MDSLRL	MDOPOL	MDOUT	—	—	MDBIT
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	MDEN: Modulator Module Enable bit 1 = Modulator module is enabled and mixing input signals 0 = Modulator module is disabled and has no output
bit 6	MDOE: Modulator Module Pin Output Enable bit 1 = Modulator pin output enabled 0 = Modulator pin output disabled
bit 5	MDSLRL: MDOUT Pin Slew Rate Limiting bit 1 = MDOUT pin slew rate limiting enabled 0 = MDOUT pin slew rate limiting disabled
bit 4	MDOPOL: Modulator Output Polarity Select bit 1 = Modulator output signal is inverted 0 = Modulator output signal is not inverted
bit 3	MDOUT: Modulator Output bit Displays the current output value of the Modulator module. ⁽¹⁾
bit 2-1	Unimplemented: Read as '0'
bit 0	MDBIT: Allows software to manually set modulation source input to module ⁽²⁾

Note 1: The modulated output frequency can be greater and asynchronous from the clock that updates this register bit, the bit value may not be valid for higher speed modulator or carrier signals.

2: MDBIT must be selected as the modulation source in the MDSRC register for this operation.

When one device is transmitting a logical one, or letting the line float, and a second device is transmitting a logical zero, or holding the line low, the first device can detect that the line is not a logical one. This detection, when used on the SCLx line, is called clock stretching. Clock stretching gives slave devices a mechanism to control the flow of data. When this detection is used on the SDAx line, it is called arbitration. Arbitration ensures that there is only one master device communicating at any single time.

25.3.1 CLOCK STRETCHING

When a slave device has not completed processing data, it can delay the transfer of more data through the process of Clock Stretching. An addressed slave device may hold the SCLx clock line low after receiving or sending a bit, indicating that it is not yet ready to continue. The master that is communicating with the slave will attempt to raise the SCLx line in order to transfer the next bit, but will detect that the clock line has not yet been released. Because the SCLx connection is open-drain, the slave has the ability to hold that line low until it is ready to continue communicating.

Clock stretching allows receivers that cannot keep up with a transmitter to control the flow of incoming data.

25.3.2 ARBITRATION

Each master device must monitor the bus for Start and Stop bits. If the device detects that the bus is busy, it cannot begin a new message until the bus returns to an Idle state.

However, two master devices may try to initiate a transmission on or about the same time. When this occurs, the process of arbitration begins. Each transmitter checks the level of the SDAx data line and compares it to the level that it expects to find. The first transmitter to observe that the two levels do not match, loses arbitration, and must stop transmitting on the SDAx line.

For example, if one transmitter holds the SDAx line to a logical one (lets it float) and a second transmitter holds it to a logical zero (pulls it low), the result is that the SDAx line will be low. The first transmitter then observes that the level of the line is different than expected and concludes that another transmitter is communicating.

The first transmitter to notice this difference is the one that loses arbitration and must stop driving the SDAx line. If this transmitter is also a master device, it also must stop driving the SCLx line. It then can monitor the lines for a Stop condition before trying to reissue its transmission. In the meantime, the other device that has not noticed any difference between the expected and actual levels on the SDAx line continues with its original transmission. It can do so without any complications, because so far, the transmission appears exactly as expected with no other transmitter disturbing the message.

Slave Transmit mode can also be arbitrated, when a master addresses multiple slaves, but this is less common.

If two master devices are sending a message to two different slave devices at the address stage, the master sending the lower slave address always wins arbitration. When two master devices send messages to the same slave address, and addresses can sometimes refer to multiple slaves, the arbitration process must continue into the data stage.

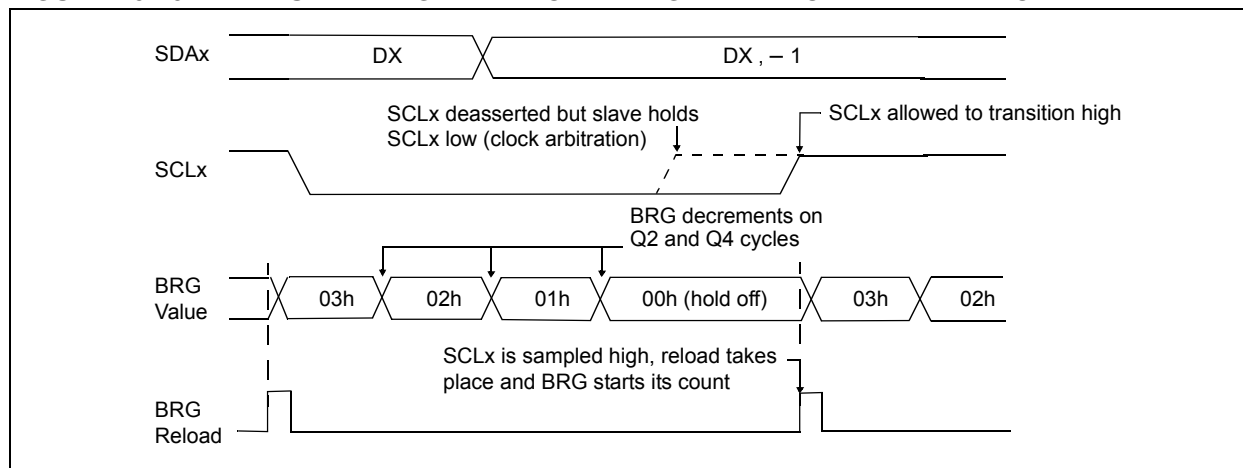
Arbitration usually occurs very rarely, but it is a necessary process for proper multi-master support.

PIC16(L)F1847

25.6.2 CLOCK ARBITRATION

Clock arbitration occurs when the master, during any receive, transmit or Repeated Start/Stop condition, releases the SCLx pin (SCLx allowed to float high). When the SCLx pin is allowed to float high, the Baud Rate Generator (BRG) is suspended from counting until the SCLx pin is actually sampled high. When the SCLx pin is sampled high, the Baud Rate Generator is reloaded with the contents of SSPxADD<7:0> and begins counting. This ensures that the SCLx high time will always be at least one BRG rollover count in the event that the clock is held low by an external device (Figure 25-25).

FIGURE 25-25: BAUD RATE GENERATOR TIMING WITH CLOCK ARBITRATION



25.6.3 WCOL STATUS FLAG

If the user writes the SSPxBUF when a Start, Restart, Stop, Receive or Transmit sequence is in progress, the WCOL bit is set and the contents of the buffer are unchanged (the write does not occur). Any time the WCOL bit is set it indicates that an action on SSPxBUF was attempted while the module was not Idle.

Note: Because queueing of events is not allowed, writing to the lower five bits of SSPxCON2 is disabled until the Start condition is complete.

26.3 EUSART Baud Rate Generator (BRG)

The Baud Rate Generator (BRG) is an 8-bit or 16-bit timer that is dedicated to the support of both the asynchronous and synchronous EUSART operation. By default, the BRG operates in 8-bit mode. Setting the BRG16 bit of the BAUDCON register selects 16-bit mode.

The SPBRGH, SPBRGL register pair determines the period of the free running baud rate timer. In Asynchronous mode the multiplier of the baud rate period is determined by both the BRGH bit of the TXSTA register and the BRG16 bit of the BAUDCON register. In Synchronous mode, the BRGH bit is ignored.

Table 26-3 contains the formulas for determining the baud rate. Example 26-1 provides a sample calculation for determining the baud rate and baud rate error.

Typical baud rates and error values for various asynchronous modes have been computed for your convenience and are shown in Table 26-3. It may be advantageous to use the high baud rate (BRGH = 1), or the 16-bit BRG (BRG16 = 1) to reduce the baud rate error. The 16-bit BRG mode is used to achieve slow baud rates for fast oscillator frequencies.

Writing a new value to the SPBRGH, SPBRGL register pair causes the BRG timer to be reset (or cleared). This ensures that the BRG does not wait for a timer overflow before outputting the new baud rate.

If the system clock is changed during an active receive operation, a receive error or data loss may result. To avoid this problem, check the status of the RCIDL bit to make sure that the receive operation is Idle before changing the system clock.

EXAMPLE 26-1: CALCULATING BAUD RATE ERROR

For a device with FOSC of 16 MHz, desired baud rate of 9600, Asynchronous mode, 8-bit BRG:

$$\text{Desired Baud Rate} = \frac{F_{OSC}}{64(SPBRGH:SPBRGL + 1)}$$

Solving for SPBRGH:SPBRGL:

$$X = \frac{\frac{F_{OSC}}{\text{Desired Baud Rate}}}{64} - 1$$

$$= \frac{\frac{16000000}{9600}}{64} - 1$$

$$= [25.042] = 25$$

$$\text{Calculated Baud Rate} = \frac{16000000}{64(25 + 1)}$$

$$= 9615$$

$$\text{Error} = \frac{\text{Calc. Baud Rate} - \text{Desired Baud Rate}}{\text{Desired Baud Rate}}$$

$$= \frac{(9615 - 9600)}{9600} = 0.16\%$$

26.4.2 SYNCHRONOUS SLAVE MODE

The following bits are used to configure the EUSART for Synchronous slave operation:

- SYNC = 1
- CSRC = 0
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TXSTA register configures the device for synchronous operation. Clearing the CSRC bit of the TXSTA register configures the device as a slave. Clearing the SREN and CREN bits of the RCSTA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RCSTA register enables the EUSART.

26.4.2.1 EUSART Synchronous Slave Transmit

The operation of the Synchronous Master and Slave modes are identical (see [Section 26.4.1.3 “Synchronous Master Transmission”](#)), except in the case of the Sleep mode.

If two words are written to the TXREG and then the SLEEP instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in TXREG register.
3. The TXIF bit will not be set.
4. After the first character has been shifted out of TSR, the TXREG register will transfer the second character to the TSR and the TXIF bit will now be set.
5. If the PEIE and TXIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

26.4.2.2 Synchronous Slave Transmission Setup:

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the ANSEL bit for the CK pin (if applicable).
3. Clear the CREN and SREN bits.
4. If interrupts are desired, set the TXIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit transmission is desired, set the TX9 bit.
6. Enable transmission by setting the TXEN bit.
7. If 9-bit transmission is selected, insert the Most Significant bit into the TX9D bit.
8. Start transmission by writing the Least Significant eight bits to the TXREG register.

TABLE 26-9: SUMMARY OF REGISTERS ASSOCIATED WITH SYNCHRONOUS SLAVE TRANSMISSION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
APFCON0	RXDTESEL	SDO1SEL	SS1SEL	P2BSEL	CCP2SEL	P1DSEL	P1CSEL	CCP1SEL	118
APFCON1	—	—	—	—	—	—	—	TXCKSEL	118
BAUDCON	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	298
INTCON	GIE	PEIE	TMR0IE	INTE	IOCE	TMR0IF	INTF	IOCF	88
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	CCP1IE	TMR2IE	TMR1IE	89
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	CCP1IF	TMR2IF	TMR1IF	93
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	297
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	126
TXREG	EUSART Transmit Data Register								289*
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	296

Legend: — = unimplemented location, read as '0'. Shaded cells are not used for Synchronous Slave Transmission.

* Page provides register information.

PIC16(L)F1847

SWAPF **Swap Nibbles in f**

Syntax: [*label*] SWAPF f,d

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(f<3:0>) \rightarrow (\text{destination}<7:4>)$,
 $(f<7:4>) \rightarrow (\text{destination}<3:0>)$

Status Affected: None

Description: The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed in register 'f'.

XORLW **Exclusive OR literal with W**

Syntax: [*label*] XORLW k

Operands: $0 \leq k \leq 255$

Operation: $(W) .XOR. k \rightarrow (W)$

Status Affected: Z

Description: The contents of the W register are XOR'ed with the 8-bit literal 'k'. The result is placed in the W register.

TRIS **Load TRIS Register with W**

Syntax: [*label*] TRIS f

Operands: $5 \leq f \leq 7$

Operation: $(W) \rightarrow \text{TRIS register 'f'}$

Status Affected: None

Description: Move data from W register to TRIS register.
 When 'f' = 5, TRISA is loaded.
 When 'f' = 6, TRISB is loaded.
 When 'f' = 7, TRISC is loaded.

XORWF **Exclusive OR W with f**

Syntax: [*label*] XORWF f,d

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(W) .XOR. (f) \rightarrow (\text{destination})$

Status Affected: Z

Description: Exclusive OR the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

PIC16(L)F1847

FIGURE 30-7: CLKOUT AND I/O TIMING

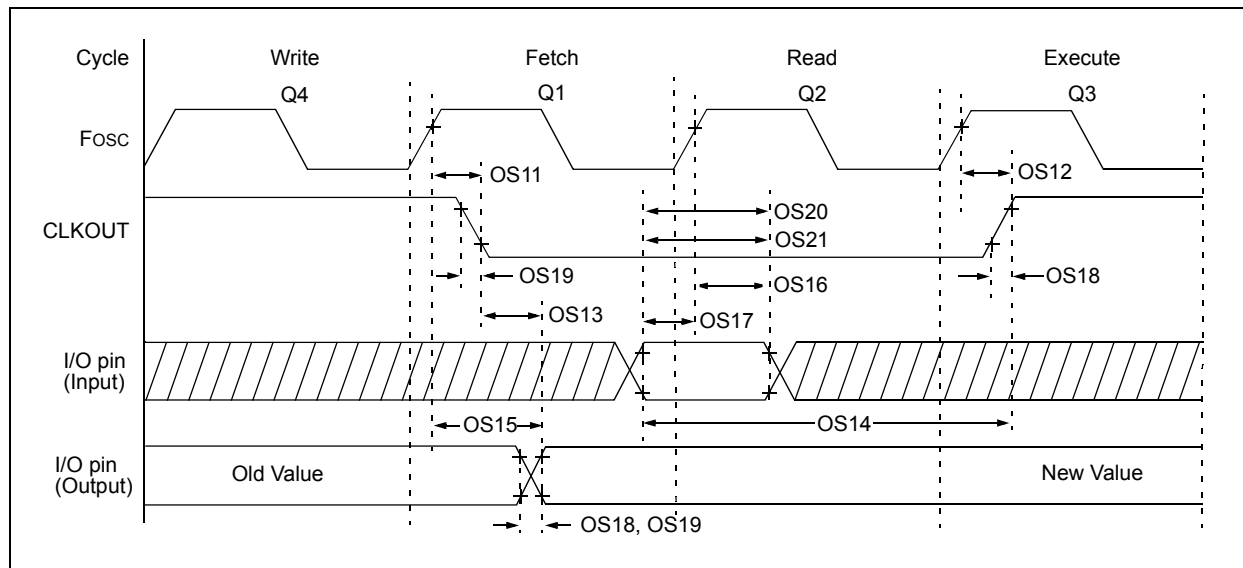


TABLE 30-10: CLKOUT AND I/O TIMING PARAMETERS

Standard Operating Conditions (unless otherwise stated)							
Param. No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
OS11	TosH2ckL	Fosc↑ to CLKOUT↓ ⁽¹⁾	—	—	70	ns	3.3V ≤ VDD ≤ 5.0V
OS12	TosH2ckH	Fosc↑ to CLKOUT↑ ⁽¹⁾	—	—	72	ns	3.3V ≤ VDD ≤ 5.0V
OS13	TckL2ioV	CLKOUT↓ to Port out valid ⁽¹⁾	—	—	20	ns	
OS14	TioV2ckH	Port input valid before CLKOUT↑ ⁽¹⁾	Tosc + 200 ns	—	—	ns	
OS15	TosH2ioV	Fosc↑ (Q1 cycle) to Port out valid	—	50	70*	ns	3.3V ≤ VDD ≤ 5.0V
OS16	TosH2ioI	Fosc↑ (Q2 cycle) to Port input invalid (I/O in setup time)	50	—	—	ns	3.3V ≤ VDD ≤ 5.0V
OS17	TioV2osH	Port input valid to Fosc↑ (Q2 cycle) (I/O in setup time)	20	—	—	ns	
OS18*	TioR	Port output rise time	—	40 15	72 32	ns	VDD = 1.8V 3.3V ≤ VDD ≤ 5.0V
OS19*	TioF	Port output fall time	—	28 15	55 30	ns	VDD = 1.8V 3.3V ≤ VDD ≤ 5.0V
OS20*	Tinp	INT pin input high or low time	25	—	—	ns	
OS21*	Tioc	Interrupt-on-change new input level time	25	—	—	ns	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated.

Note 1: Measurements are taken in EXTRC mode where CLKOUT output is 4 x Tosc.

FIGURE 30-21: I²C™ BUS DATA TIMING

