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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

| Product Status | Not For New Designs |
|----------------------------|--|
| Core Processor | R8C |
| Core Size | 16-Bit |
| Speed | 20MHz |
| Connectivity | UART/USART |
| Peripherals | POR, PWM, Voltage Detect, WDT |
| Number of I/O | 17 |
| Program Memory Size | 2KB (2K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 256 x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 5.5V |
| Data Converters | A/D 6x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 20-LSSOP (0.173", 4.40mm Width) |
| Supplier Device Package | 20-LSSOP |
| Purchase URL | https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f2m120adsp-u0 |

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1.1.2 Differences between Groups

Table 1.1 lists the Specification Comparison between R8C/M11A Group and R8C/M12A Group. The explanations in 1.1.3 and subsequent sections apply to the R8C/M12A Group specifications only, unless otherwise specified.

| Item | Function | R8C/M11A Group | R8C/M12A Group |
|---------------|------------------------------------|--|--|
| Interrupts | External interrupt inputs | 6 (INT × 3, key input × 3) | 8 ($\overline{INT} \times 4$, key input $\times 4$) |
| I/O ports | Number of pins | 14 Non-provided pins: P1_0/AN0/TRCIOD/KI0 P3_3/IVCMP3/TRCCLK/INT3 P3_4/IVREF3/TRCIOC/INT2 P3_5/TRCIOD/KI2/VCOUT3 P4_2/TRB0/TXD0/KI3 P4_5/INT0/ADTRG | 20 |
| | Number of CMOS I/O ports | 11 Non-provided ports: P1_0, P3_3, P3_4, P3_5, P4_2, P4_5 | 17 |
| | Number of high-current drive ports | 5 Non-provided ports: P3_3, P3_4, P3_5 | 8 |
| A/D converter | Number of A/D channels | 5 channels Non-provided port: AN0 | 6 channels |
| Comparator B | Number of channels | Comparator B1 | Comparator B1, comparator B3 |

 Table 1.1
 Specification Comparison between R8C/M11A Group and R8C/M12A Group



Table 1.2 lists the R8C/M11A Group Register Settings. These settings correspond to the specification differences between the R8C/M11A Group and R8C/M12A Group.

| Related Function | Register Name | Address | Bit | Setting Method for Access |
|---------------------|---------------|---------|---------------------------------------|--|
| INT3 | INTEN | 00038h | INT3EN | Reserved bit. Set to 0. |
| | INTF0 | 0003Ah | INT3F0, INT3F1 | Reserved bits. Set to 0. |
| | ISCR0 | 0003Ch | INT3SA, INT3SB | Reserved bits. Set to 0. |
| | ILVLD | 0004Dh | ILVLD0, ILVLD1 | Reserved bits. Set to 0. |
| | IRR3 | 00053h | IRI3 | Reserved bit. Set to 0. |
| KI0 | KIEN | 0003Eh | KI0EN, KI0PL | Reserved bits. Set to 0. |
| Comparator B3 | ILVL2 | 00042h | ILVL24, ILVL25 | Reserved bits. Set to 0. |
| interrupt | IRR2 | 00052h | IRCMP3 | Reserved bit. Set to 0. |
| P1_0 | PD1 | 000A9h | PD1_0 | Reserved bit. Set to 0. |
| | P1 | 000AFh | P1_0 | Reserved bit. Set to 0. |
| | PUR1 | 000B5h | PU1_0 | Reserved bit. Set to 0. |
| | POD1 | 000C1h | POD1_0 | Reserved bit. Set to 0. |
| | PML1 | 000C8h | P10SEL0, P10SEL1 | Reserved bits. Set to 0. |
| P3_3, P3_4, | PD3 | 000ABh | PD3_3, PD3_4, PD3_5 | Reserved bits. Set to 0. |
| P3_5 | P3 | 000B1h | P3_3, P3_4, P3_5 | Reserved bits. Set to 0. |
| | PUR3 | 000B7h | PU3_3, PU3_4, PU3_5 | Reserved bits. Set to 0. |
| | DRR3 | 000BDh | DRR3_3, DRR3_4, DRR3_5 | Reserved bits. Set to 0. |
| | POD3 | 000C3h | POD3_3, POD3_4, POD3_5 | Reserved bits. Set to 0. |
| | PML3 | 000CCh | P33SEL0, P33SEL1 | Reserved bits. Set to 0. |
| | PMH3 | 000CDh | P34SEL0, P34SEL1, P35SEL0, P35SEL1 | Reserved bits. Set to 0. |
| P4_2, P4_5 | PD4 | 000ACh | PD4_2, PD4_5 | Reserved bits. Set to 0. |
| | P4 | 000B2h | P4_2, P4_5 | Reserved bits. Set to 0. |
| | PUR4 | 000B8h | PU4_2, PU4_5 | Reserved bits. Set to 0. |
| | POD4 | 000C4h | POD4_2, POD4_5 | Reserved bits. Set to 0. |
| | PML4 | 000CEh | P42SEL0, P42SEL1 | Reserved bits. Set to 0. |
| | PMH4 | 000CFh | P45SEL0, P45SEL1 | Reserved bits. Set to 0. |
| AN0 | ADINSEL | 0009Dh | CH0, ADGSEL0, ADGSEL1 | Do not set to 000. |
| Comparator B3 | WCMPR | 00180h | WCB3M0, WCB3OUT | Reserved bits. Set to 0. |
| | WCB3INTR | 00182h | All bits | Reserved register. No access is allowed. |

 Table 1.2
 R8C/M11A Group Register Settings



| Table 1.4 | Specifications | (2) |
|-----------|----------------|-----|
|-----------|----------------|-----|

| Item | Function | Description | |
|--|----------|--|--|
| Flash memory | | Program/erase voltage for program ROM: VCC = 1.8 V to 5.5 V Program/erase voltage for data flash: VCC = 1.8 V to 5.5 V Program/erase endurance: 10,000 times (data flash) 10,000 times (program ROM) Program security: ID code check, protection enabled by lock bit Debug functions: On-chip debug, on-board flash rewrite function | |
| Operating frequency/ Power supply voltage | | f(XIN) = 20 MHz (VCC = 2.7 V to 5.5 V) f(XIN) = 5 MHz (VCC = 1.8 V to 5.5 V) | |
| Temperature range | | -20 °C to 85 °C (N version) -40 °C to 85 °C (D version) ⁽¹⁾ | |
| Package | | 14-pin TSSOP: [Package code] PTSP0014JA-B 14-pin DIP: [Package code] PRDP0014AC-A 20-pin LSSOP: [Package code] PLSP0020JB-A 20-pin DIP: [Package code] PRDP0020AD-A | |

1. Specify the D version if it is to be used.



| Pin N | umber | | | | I/O Pins for | Peripheral Fu | nctions |
|-------------------|-------------------|-------------|------|--------------|---------------|---------------------|--------------------------------|
| R8C/M11A Group | R8C/M12A Group | Control Pin | Port | Interrupt | Timer | Serial Interface | A/D Converter, Comparator B |
| | 1 | | P4_2 | KI3 | TRBO | TXD0 | |
| 1 | 2 | | P3_7 | | TRJO/TRCIOD | | ADTRG |
| 2 | 3 | RESET | PA_0 | | | | |
| 3 | 4 | XOUT | P4_7 | INT2 | | | |
| 4 | 5 | VSS/AVSS | | | | | |
| 5 | 6 | XIN | P4_6 | INT1 | TRJIO | RXD0/TXD0 | VCOUT1 |
| 6 | 7 | VCC/AVCC | | | | | |
| 7 | 8 | MODE | | | | | |
| | 9 | | P3_5 | KI2 | TRCIOD | | VCOUT3 |
| | 10 | | P3_4 | INT2 | TRCIOC | | IVREF3 |
| | 11 | | P3_3 | INT3 | TRCCLK | | IVCMP3 |
| | 12 | | P4_5 | INT 0 | | | ADTRG |
| 8 | 13 | | P1_7 | INT1 | TRJIO/TRCCLK | | AN7/IVCMP1 |
| 9 | 14 | | P1_6 | | TRJO/TRCIOB | CLK0 | IVREF1 |
| 10 | 15 | | P1_5 | INT1 | TRJIO | RXD0 | VCOUT1 |
| 11 | 16 | | P1_4 | INT0 | TRCIOB | RXD0/TXD0 | AN4 |
| 12 | 17 | | P1_3 | KI3 | TRBO/TRCIOC | | AN3 |
| 13 | 18 | | P1_2 | KI2 | TRCIOB | | AN2 |
| 14 | 19 | | P1_1 | KI1 | TRCIOA/TRCTRG | | AN1 |
| | 20 | | P1_0 | KI0 | TRCIOD | | ANO |

 Table 1.6
 Pin Name Information by Pin Number



3.2 Special Function Registers (SFRs)

An SFR (special function register) is a control register for a peripheral function. Tables 3.1 to 3.8 list the SFR Information. Table 3.9 lists the ID Code Area and Option Function Select Area.

| Address | Register Name | Symbol | After Reset |
|---------|--|--------|--|
| 00000h | | , | |
| 00001h | | | |
| 00002h | | | |
| 00003h | | | |
| 00004h | | | |
| 00005h | | | |
| 00006h | | | |
| 00007h | | | |
| 00008h | | | |
| 00009h | | | |
| 0000Ah | | | |
| 0000Bh | | | |
| 000000h | | | |
| 0000Eh | | | |
| 0000Eh | | | |
| 00010h | Processor Mode Register 0 | PM0 | 00h |
| 00011h | | | |
| 00012h | Module Standby Control Register | MSTCR | 00h ⁽²⁾ 01110111h ⁽³⁾ |
| 00013h | Protect Register | PRCR | 00h |
| 00014h | | | |
| 00015h | | | |
| 00016h | Hardware Reset Protect Register | HRPR | 00h |
| 00017h | | | |
| 00018h | | | |
| 00019h | | | |
| 0001Ah | | | |
| 0001Bh | | | |
| 0001Ch | | | |
| 0001Dh | | | |
| 0001Eh | | | |
| 0001FI | External Clock Control Register | EXCKCB | 00b |
| 00020h | High-Speed/Low-Speed On-Chip Oscillator Control Register | OCOCR | 00h |
| 00022h | System Clock f Control Register | SCKCR | 00h |
| 00023h | System Clock f Select Register | PHISEL | 00h |
| 00024h | Clock Stop Control Register | CKSTPR | 00h |
| 00025h | Clock Control Register When Returning from Modes | CKRSCR | 00h |
| 00026h | Oscillation Stop Detection Register | BAKCR | 00h |
| 00027h | | | |
| 00028h | | | |
| 00029h | | | |
| 0002Ah | | | |
| 0002BN | | | |
| 000201 | | | |
| 0002Dn | | | |
| 0002Fh | | | |
| 00030h | Watchdog Timer Function Register | RISR | 10000000b ⁽⁴⁾ |
| 00031h | Watchdog Timer Reset Register | WDTR | XXh |
| 00032h | Watchdog Timer Start Register | WDTS | XXh |
| 00033h | Watchdog Timer Control Register | WDTC | 01XXXXXXb |
| 00034h | Count Source Protection Mode Register | CSPR | 10000000b ⁽⁴⁾ 00h ⁽⁵⁾ |
| 00035h | Periodic Timer Interrupt Control Register | WDTIR | 00h |
| 00036h | | | |
| 00037h | | | |
| 00038h | External Input Enable Register | INTEN | 00h |
| 00039h | | | |

Table 3.1SFR Information (1) (1)

Notes:

1. The blank areas are reserved. No access is allowed.

2. The MSTINI bit in the OFS2 register is 0.

3. The MSTINI bit in the OFS2 register is 1.

4. The CSPROINI bit in the OFS register is 0.

5. The CSPROINI bit in the OFS register is 1.



| Address | Register Name | Symbol | After Reset |
|---------|---------------|--------|-------------|
| 00140h | | | |
| 00141h | | | |
| 00142h | | | |
| 0014211 | | | |
| 001430 | | | |
| 00144h | | | |
| 00145h | | | |
| 00146h | | | |
| 00147h | | | |
| 00148h | | | |
| 00149h | | | |
| 00140b | | | |
| 0014An | | | |
| 0014BN | | | |
| 0014Ch | | | |
| 0014Dh | | | |
| 0014Eh | | | |
| 0014Fh | | | |
| 00150h | | | |
| 00151h | | | |
| 00152h | | | |
| 00152h | | | |
| 0015311 | | | |
| 00154h | | | |
| 00155h | | | |
| 00156h | | | |
| 00157h | | | |
| 00158h | | | |
| 00159h | | | |
| 0015Ah | | | |
| 0015Bh | | | |
| 0015Ch | | | |
| 0015Dh | | | |
| 0015Dh | | | |
| 0015Eh | | | |
| 0015Fh | | | |
| 00160h | | | |
| 00161h | | | |
| 00162h | | | |
| 00163h | | | |
| 00164h | | | |
| 00165h | | | |
| 00166h | | | |
| 00167h | | | |
| 0010711 | | | |
| 00168h | | | |
| 00169h | | | |
| 0016Ah | | | |
| 0016Bh | | | |
| 0016Ch | | | |
| 0016Dh | | | |
| 0016Eh | | | |
| 0016Fh | | | |
| 001706 | | | |
| 0017011 | | | |
| 001710 | | | |
| 00172h | | | |
| 00173h | | | |
| 00174h | | | |
| 00175h | | | |
| 00176h | | | |
| 00177h | | | |
| 00178h | | | |
| 00170h | | | |
| 001750 | | | |
| 0017An | | | |
| 0017Bh | | | |
| 0017Ch | | | |
| 0017Dh | | | |
| 0017Eh | | | |
| 0017Fh | | | |
| | | | |

Table 3.6SFR Information (6) (1)

1. The blank areas are reserved. No access is allowed.



| Address | Area Name | Symbol | After Reset |
|---------|-----------------------------------|--------|-------------|
| : | | | |
| 0FFDBh | Option Function Select Register 2 | OFS2 | (Note 1) |
| : | | | |
| 0FFDFh | ID1 | | (Note 2) |
| : | | | |
| 0FFE3h | ID2 | | (Note 2) |
| : | | | |
| 0FFEBh | ID3 | | (Note 2) |
| : | | | |
| 0FFEFh | ID4 | | (Note 2) |
| : | | | |
| 0FFF3h | ID5 | | (Note 2) |
| : | | | |
| 0FFF7h | ID6 | | (Note 2) |
| : | | | |
| 0FFFBh | ID7 | | (Note 2) |
| : | | | |
| 0FFFFh | Option Function Select Register | OFS | (Note 1) |

Table 3.9 ID Code Area and Option Function Select Area

 The option function select area is allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program. Do not perform an additional write to the option function select area. Erasure of the block including the option function select area causes the option function select area to be set to FFh.

When blank products are shipped, the option function select area is set to FFh. It is set to the written value after written by the user. When factory-programming products are shipped, the value of the option function select area is the value programmed by the user.

2. The ID code area is allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program. Do not perform an additional write to the ID code area. Erasure of the block including the ID code area causes the ID code area to be set to FFh. When blank products are shipped, the ID code areas are set to FFh. They are set to the written value after written by the user. When factory-programming products are shipped, the value of the ID code areas is the value programmed by the user.



| Symbol | Parameter | | Condition | Standard | | | Llnit |
|-----------|------------------------------------|------------------------------|--|----------|------|---------|-------|
| Symbol | | | Condition | Min. | Тур. | Max. | Unit |
| Vcc/AVcc | Power supply voltage | | | 1.8 | — | 5.5 | V |
| Vss/AVss | Power supply voltage | | | | 0 | _ | V |
| Viн | Input high voltage | Other than CMOS input | | 0.8 Vcc | — | Vcc | V |
| | | CMOS input | $4.0~V \leq Vcc \leq 5.5~V$ | 0.65 Vcc | — | Vcc | V |
| | | | $2.7~V \leq Vcc < 4.0~V$ | 0.7 Vcc | — | Vcc | V |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | 0.8 Vcc | — | Vcc | V |
| VIL | Input low voltage | Other than CMOS input | | 0 | — | 0.2 Vcc | V |
| | | CMOS input | $4.0~V \leq Vcc \leq 5.5~V$ | 0 | — | 0.4 Vcc | V |
| | | | $2.7~V \leq Vcc < 4.0~V$ | 0 | — | 0.3 Vcc | V |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | 0 | — | 0.2 Vcc | V |
| IOH(sum) | Peak sum output high current | Sum of all pins IOH(peak) | | _ | | -160 | mA |
| IOH(sum) | Average sum output high current | Sum of all pins IOH(avg) | | _ | | -80 | mA |
| IOH(peak) | Peak output high current | | When drive capacity is low | _ | — | -10 | mA |
| | | | When drive capacity is high (5) | _ | — | -40 | mA |
| IOH(avg) | Average output high current | | When drive capacity is low | _ | | -5 | mA |
| | | | When drive capacity is high (5) | — | _ | -20 | mA |
| IOL(sum) | Peak sum output low current | Sum of all pins IOL(peak) | | _ | | 160 | mA |
| IOL(sum) | Average sum output low current | Sum of all pins IOL(avg) | | _ | — | 80 | mA |
| IOL(peak) | Peak output low current | | When drive capacity is low | _ | — | 10 | mA |
| | | | When drive capacity is high (5) | _ | — | 40 | mA |
| IOL(avg) | Average output low current | | When drive capacity is low | _ | _ | 5 | mA |
| | | | When drive capacity is high (5) | _ | | 20 | mA |
| f(XIN) | XIN oscillation frequency | | $2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | 2 | — | 20 | MHz |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | 2 | — | 5 | MHz |
| | XIN clock input oscillation fr | requency | $2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | 0 | — | 20 | MHz |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | 0 | — | 5 | MHz |
| fHOCO | High-speed on-chip oscillat | or oscillation frequency (3) | $1.8 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | _ | 20 | _ | MHz |
| fLOCO | Low-speed on-chip oscillato | or oscillation frequency (4) | $1.8 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | _ | 125 | | kHz |
| — | System clock frequency | 1 7 | $2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | _ | | 20 | MHz |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | _ | — | 5 | MHz |
| fs | CPU clock frequency | | $2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$ | 0 | — | 20 | MHz |
| | | | $1.8 \text{ V} \leq \text{Vcc} < 2.7 \text{ V}$ | 0 | — | 5 | MHz |

Table 4.2 Recommended Operating Conditions

1. Vcc = 1.8 V to 5.5 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified.

2. The average output current indicates the average value of current measured during 100 ms.

3. For details, see Table 4.10 High-Speed On-Chip Oscillator Circuit Electrical Characteristics.

4. For details, see Table 4.11 Low-Speed On-Chip Oscillator Circuit Electrical Characteristics.

5. The pins with high drive capacity are P1_2, P1_3, P1_4, P1_5, P3_3, P3_4, P3_5, and P3_7.



Figure 4.1 Ports P1, P3, and P4 Timing Measurement Circuit



| Cumhal | Doromotor | Condition | | | Linit | | |
|---------------|-------------------------------------|---|--|------|-------|------|-----|
| Symbol | Parameter | | Min. | Тур. | Max. | Unit | |
| | Resolution | | | | — | 10 | Bit |
| | Absolute accuracy | AVcc = 5.0 V | AN0 to AN4, AN7 input | _ | — | ±3 | LSB |
| | | AVcc = 3.0 V | AN0 to AN4, AN7 input | _ | — | ±5 | LSB |
| | | AVcc = 1.8 V | AN0 to AN4, AN7 input | _ | — | ±5 | LSB |
| — | A/D conversion clock | | | 2 | — | 20 | MHz |
| | | | | 2 | — | 16 | MHz |
| | | $2.7 \text{ V} \leq \text{AVcc} \leq 3$ | $2.7 \text{ V} \le \text{AVcc} \le 5.5 \text{ V}^{(2)}$ 1.8 \text{ V} \le \text{AVcc} \le 5.5 \text{ V}^{(2)} | | — | 10 | MHz |
| | | 1.8 V \leq AVcc \leq | | | — | 5 | MHz |
| | Permissible signal source impedance | | | | 3 | | kΩ |
| tCONV | Conversion time | AVcc = 5.0 V, A/D conversion clock = 20 MHz | | 2.20 | _ | _ | μs |
| t SAMP | Sampling time | A/D conversion clock = 20 MHz | | 0.80 | — | — | μs |
| Via | Analog input voltage | | | 0 | — | AVcc | V |

 Table 4.3
 A/D Converter Characteristics

1. Vcc/AVcc = 1.8 V to 5.5 V and Vss = 0 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified.

2. The A/D conversion result will be undefined in stop mode, or when the flash memory is in low-current-consumption read mode or stopped. Do not perform A/D conversion in these states. Do not enter these states during A/D conversion.

Table 4.4 Comparator B Electrical Characteristics

| Symbol | Parameter | Condition | | Lloit | | |
|--------|--|--------------------|------|-------|-----------|------|
| Symbol | Falanetei | Condition | Min. | Тур. | Max. | Onit |
| Vref | IVREF1, IVREF3 input reference voltage | | 0 | _ | Vcc - 1.4 | V |
| VI | IVCMP1, IVCMP3 input voltage | | -0.3 | _ | Vcc + 0.3 | V |
| — | Offset | | _ | 5 | 100 | mV |
| td | Comparator output delay time (2) | VI = Vref ± 100 mV | - | 0.1 | — | μS |
| ICMP | Comparator operating current | Vcc = 5.0 V | _ | 17.5 | — | μA |

Notes:

1. Vcc = 2.7 V to 5.5 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified.

2. When the digital filter is disabled.



| Symbol | Beremeter | Condition | | | Unit | |
|---------|---|---|------|------|------|------|
| Symbol | Falameter | Condition | Min. | Тур. | Max. | Unit |
| Vdet0 | Voltage detection level Vdet0_0 ⁽²⁾ | | 1.80 | 1.90 | 2.05 | V |
| | Voltage detection level Vdet0_1 ⁽²⁾ | | 2.15 | 2.35 | 2.50 | V |
| | Voltage detection level Vdet0_2 (2) | | 2.70 | 2.85 | 3.05 | V |
| | Voltage detection level Vdet0_3 (2) | | 3.55 | 3.80 | 4.05 | V |
| — | Voltage detection 0 circuit response time ⁽³⁾ | When Vcc decreases from 5 V to (Vdet0_0 - 0.1) V | _ | 30 | _ | μS |
| — | Self power consumption in voltage detection circuit | VC0E = 1, Vcc = 5.0 V | _ | 1.5 | _ | μΑ |
| td(E-A) | Wait time until voltage detection circuit operation starts ⁽⁴⁾ | | _ | — | 100 | μS |

 Table 4.7
 Voltage Detection 0 Circuit Electrical Characteristics

1. The measurement condition is Vcc = 1.8 V to 5.5 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version).

2. Select the voltage detection level with bits VDSEL0 and VDSEL1 in the OFS register.

3. The response time is from when the voltage passes Vdet0 until the voltage monitor 0 reset is generated.

4. The wait time is necessary for the voltage detection circuit to operate when the VC0E bit in the VCA2 register is set to 0 and then 1.

| Table 4.8 | Voltage Detection | 1 Circuit | Electrical | Characteristics |
|-----------|-------------------|-----------|------------|-----------------|
| | | | | • |

| Symbol | Parameter | Condition | | Llnit | | |
|---------|---|--|------|-------|------|------|
| Symbol | Faranielei | Condition | Min. | Тур. | Max. | Unit |
| Vdet1 | Voltage detection level Vdet1_1 ⁽²⁾ | When Vcc decreases | 2.15 | 2.35 | 2.55 | V |
| | Voltage detection level Vdet1_3 ⁽²⁾ | When Vcc decreases | 2.45 | 2.65 | 2.85 | V |
| | Voltage detection level Vdet1_5 ⁽²⁾ | When Vcc decreases | 2.75 | 2.95 | 3.15 | V |
| | Voltage detection level Vdet1_7 ⁽²⁾ | When Vcc decreases | 3.00 | 3.25 | 3.55 | V |
| | Voltage detection level Vdet1_9 ⁽²⁾ | When Vcc decreases | 3.30 | 3.55 | 3.85 | V |
| V | Voltage detection level Vdet1_B (2) | When Vcc decreases | 3.60 | 3.85 | 4.15 | V |
| | Voltage detection level Vdet1_D (2) | When Vcc decreases | 3.90 | 4.15 | 4.45 | V |
| | Voltage detection level Vdet1_F (2) | When Vcc decreases | 4.20 | 4.45 | 4.75 | V |
| — | Hysteresis width at the rising of Vcc in | Vdet1_1 to Vdet1_5 selected | _ | 0.07 | — | V |
| | voltage detection 1 circuit | Vdet1_7 to Vdet1_F selected | _ | 0.10 | _ | V |
| — | Voltage detection 1 circuit response time ⁽³⁾ | When Vcc decreases from 5 V to (Vdet1_0 - 0.1) V | _ | 60 | 150 | μS |
| | Self power consumption in voltage detection circuit | VC1E = 1, Vcc = 5.0 V | _ | 1.7 | — | μΑ |
| td(E-A) | Wait time until voltage detection circuit operation starts ⁽⁴⁾ | | _ | _ | 100 | μS |

Notes:

1. The measurement condition is Vcc = 1.8 V to 5.5 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version).

2. Select the voltage detection level with bits VD1S1 to VD1S3 in the VD1LS register.

3. The response time is from when the voltage passes Vdet1 until the voltage monitor 1 interrupt request is generated.

4. The wait time is necessary for the voltage detection circuit to operate when the VC1E bit in the VCA2 register is set to 0 and then 1.



| Symbol | Parameter | Package | Condition | | LInit | | |
|--------|--|--------------|---------------------------------|--------|--------|--------|------|
| Symbol | Farameter | гаскауе | Condition | Min. | Тур. | Max. | Unit |
| — | High-speed on-chip oscillator | 14-pin TSSOP | Vcc = 1.8 V to 5.5 V, | 19.2 | 20.0 | 20.8 | MHz |
| | frequency after reset is | 20-pin LSSOP | -20 °C ≤ Topr ≤ 85 °C | | | | |
| | cleared | 14-pin DIP | | 19.0 | 20.0 | 21.0 | MHz |
| | | 20-pin DIP | | | | | |
| | | 14-pin TSSOP | Vcc = 1.8 V to 5.5 V, | 19.0 | 20.0 | 21.0 | MHz |
| | | 20-pin LSSOP | -40 °C \leq Topr \leq 85 °C | | | | |
| | High-speed on-chip oscillator | 14-pin TSSOP | Vcc = 1.8 V to 5.5 V, | 17.694 | 18.432 | 19.169 | MHz |
| | frequency when the FR18S0 | 20-pin LSSOP | -20 °C \leq Topr \leq 85 °C | | | | |
| | register adjustment value is | 14-pin DIP | | 17.510 | 18.432 | 19.353 | MHz |
| | written into the FRV1 register | 20-pin DIP | | | | | |
| | and the FR18S1 register | 14-pin TSSOP | Vcc = 1.8 V to 5.5 V, | 17.510 | 18.432 | 19.353 | MHz |
| | adjustment value into the | 20-pin LSSOP | -40 °C \leq Topr \leq 85 °C | | | | |
| | FRV2 register (2) | | | | | | |
| - | Oscillation stabilization time | — | | _ | _ | 30 | μS |
| — | Self power consumption at oscillation | _ | Vcc = 5.0 V, Topr = 25 °C | _ | 530 | | μĀ |

| Table 4.10 | High-Speed On-Chi | o Oscillator Circu | it Electrical Characteris | stics |
|------------|-------------------|--------------------|---------------------------|-------|
| | | | | |

1. Vcc = 1.8 V to 5.5 V, Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified.

2. This enables the setting errors of bit rates such as 9600 bps and 38400 bps to be 0 % when the serial interface is used in UART mode.

Table 4.11 Low-Speed On-Chip Oscillator Circuit Electrical Characteristics

| Symbol | Parameter | Condition | | Lloit | | |
|--------|--|-------------------------------------|------|-------|------|------|
| Symbol | | Condition | Min. | Тур. | Max. | Onit |
| fLOCO | Low-speed on-chip oscillator frequency | 60 | 125 | 250 | kHz | |
| — | Oscillation stabilization time | | — | — | 35 | μS |
| — | Self power consumption at oscillation | Vcc = 5.0 V, Topr = 25 $^{\circ}$ C | — | 2 | | μΑ |
| | | | | | | |

Note:

1. Vcc = 1.8 V to 5.5 V, Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified.

Table 4.12 Power Supply Circuit Timing Characteristics

| Symbol | Parameter | Condition | | Linit | | |
|---------|---|-----------|------|-------|-------|------|
| | | Condition | Min. | Тур. | Max. | Unit |
| td(P-R) | Time for internal power supply stabilization during power-on ⁽²⁾ | | | | 2,000 | μS |

Notes:

1. The measurement condition is Vcc = 1.8 V to 5.5 V and Topr = 25 °C.

2. Wait time until the internal power supply generation circuit stabilizes during power-on.



| Symbol | Parameter | | Condi | tion | S | Unit | | |
|---------|---------------------|---|--------------------------------|--------------|-----------|------|------|------|
| Symbol | | | Cond | | Min. | Тур. | Max. | Onit |
| Vон | Output high voltage | P1_2, P1_3, P1_4, P1_5, P3_3, P3_4, P3_5, P3_7 ⁽²⁾ | When drive capacity is high | Iон = -20 mA | Vcc - 2.0 | — | Vcc | V |
| | | | When drive capacity is low | Іон = -5 mA | Vcc - 2.0 | — | Vcc | V |
| | | P1_0, P1_1, P1_6, P1_7, P4_2, P4_5, P4_6, P4_7, PA_0 | | юн = -5 mA | Vcc - 2.0 | _ | Vcc | V |
| Vol | Output low voltage | P1_2, P1_3, P1_4, P1_5, P3_3, P3_4, P3_5, P3_7 ⁽²⁾ | When drive capacity is high | IoL = 20 mA | _ | _ | 2.0 | V |
| | | | When drive capacity is low | IOL = 5 mA | | — | 2.0 | V |
| | | P1_0, P1_1, P1_6, P1_7, P4_2, P4_5, P4_6, P4_7, PA_0 | | Iol = 5 mA | | _ | 2.0 | V |
| VT+-VT- | Hysteresis | INT0, INT1, INT2, INT3, KI0, KI1, KI2, KI3, TRJIO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, RXD0, CLK0 | Vcc = 5 V | | 0.1 | 1.2 | _ | V |
| | | RESET | Vcc = 5 V | | 0.1 | 1.2 | | V |
| Ін | Input high current | | VI = 5 V, Vcc = 5 | 5.0 V | — | _ | 5.0 | μA |
| lı∟ | Input low current | | VI = 0 V, $Vcc = 5$ | 5.0 V | — | — | -5.0 | μA |
| RPULLUP | Pull-up resistance | | VI = 0 V, $Vcc = 5$ | 5.0 V | 25 | 50 | 100 | kΩ |
| RfXIN | Feedback resistance | XIN | | | — | 2.2 | — | MΩ |
| VRAM | RAM hold voltage | | In stop mode | | 1.8 | — | — | V |

Table 4.13 DC Characteristics (1) [4.0 V \leq Vcc \leq 5.5 V]

1. 4.0 V ≤ Vcc ≤ 5.5 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), f(XIN) = 20 MHz, unless otherwise specified.

2. High drive capacity can also be used while the peripheral output function is used.



| | | | | | | Cond | dition | | | | Condition | | | | | | | | | | |
|--------|--------------------|--|------------------------|----------------------|---------------|-------------------|---|---|------|----------|-----------|------|--|--|--|--|--|--|--|--|--|
| Symbol | Parameter | | Oscillation Circuit | On-Chip C | Oscillator | CPU | Low-Power- | Othor | | Standard | | Unit | | | | | | | | | |
| | | | XIN (2) | High- Speed | Low- Speed | Clock | Setting | Other | Min. | Тур. (3) | Max. | | | | | | | | | | |
| lcc | Power supply | High-speed clock mode | 20 MHz | Off | 125 kHz | No division | — | | | 3 | 7.0 | mA | | | | | | | | | |
| | current (1) | | 16 MHz | Off | 125 kHz | No division | — | | | 2.5 | 6.0 | mA | | | | | | | | | |
| | | | 10 MHz | Off | 125 kHz | No division | — | | - | 1.7 | _ | mA | | | | | | | | | |
| | | | 20 MHz | Off | 125 kHz | Division by 8 | — | | | 1.5 | _ | mA | | | | | | | | | |
| | | | 16 MHz | Off | 125 kHz | Division by 8 | — | | I | 1.2 | _ | mA | | | | | | | | | |
| | | | 10 MHz | Off | 125 kHz | Division by 8 | _ | | I | 1.0 | _ | mA | | | | | | | | | |
| | | High-speed on-chip | Off | 20 MHz | 125 kHz | No division | | | | 3.5 | 7.5 | mA | | | | | | | | | |
| | oscillator mode | oscillator mode | Off | 20 MHz | 125 kHz | Division by 8 | | | | 2.0 | | mA | | | | | | | | | |
| | | | Off | 4 MHz ⁽⁴⁾ | 125 kHz | Division by 16 | MSTTRC = 1 | | | 1.0 | _ | mA | | | | | | | | | |
| | | Low-speed on-chip oscillator mode | Off | Off | 125 kHz | Division by 8 | FMR27 = 1 LPE = 0 | | _ | 60 | 270 | μΑ | | | | | | | | | |
| | | Wait mode | Off | Off | 125 kHz | _ | VC1E = 0 VC0E = 0 LPE = 1 | Peripheral clock supplied during WAIT instruction execution | | 15 | 100 | μΑ | | | | | | | | | |
| | | | Off | Off | 125 kHz | _ | VC1E = 0 VC0E = 0 LPE = 1 WCKSTP = 1 | Peripheral clock stopped during WAIT instruction execution | _ | 4.0 | 90 | μA | | | | | | | | | |
| | | Stop mode | Off | Off | Off | _ | VC1E = 0 VC0E = 0 STPM = 1 | Topr = 25 °C Peripheral clock stopped | — | 1.0 | 4.0 | μΑ | | | | | | | | | |
| | | | Off | Off | Off | — | VC1E = 0 VC0E = 0 STPM = 1 | Topr = 85 °C Peripheral clock stopped | _ | 1.5 | - | μΑ | | | | | | | | | |

Table 4.14DC Characteristics (2) [4.0 V \leq Vcc \leq 5.5 V]
(Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified)

Notes:

1. Vcc = 4.0 V to 5.5 V, single-chip mode, output pins are open, and other pins are connected to Vss.

2. When the XIN input is a square wave.

3. Vcc = 5.0 V

4. Set the system clock to 4 MHz with the PHISEL register.

Table 4.23Serial Interface

| Symbol | Deromotor | Stan | dard | Lloit |
|----------|------------------------|------|------|-------|
| Symbol | Falameter | Min. | Max. | Unit |
| tc(CK) | CLK0 input cycle time | 300 | _ | ns |
| tw(CKH) | CLK0 input high width | 150 | | ns |
| tw(CKL) | CLK0 input low width | 150 | — | ns |
| td(C-Q) | TXD0 output delay time | _ | 80 | ns |
| th(C-Q) | TXD0 hold time | 0 | | ns |
| tsu(D-C) | RXD0 input setup time | 70 | | ns |
| th(C-D) | RXD0 input hold time | 90 | _ | ns |



Figure 4.10 Serial Interface Timing When Vcc = 3 V

Table 4.24 External Interrupt INTi Input, Key Input Interrupt Kli (i = 0 to 3)

| Symbol | Parameter | Stan | Unit | |
|---------|---|---------|------|------|
| | Farameter | | | Max. |
| tw(INH) | INTi input high width, Kli input high width | 380 (1) | _ | ns |
| tw(INL) | INTi input low width, Kli input low width | 380 (2) | | ns |

Notes:

1. When the digital filter is enabled by the INTi input filter select bit, the INTi input high width is (1/digital filter clock frequency × 3) or the minimum value of the standard, whichever is greater.

2. When the digital filter is enabled by the INTi input filter select bit, the INTi input low width is (1/digital filter clock frequency × 3) or the minimum value of the standard, whichever is greater.



Figure 4.11 Timing for External Interrupt INTi Input and Key Input Interrupt Kli When Vcc = 3 V



| Symbol | Parameter | | Condi | ition | S | Lloit | | |
|---------|---------------------|---|--------------------------------|-------------|-----------|-------|------|------|
| Symbol | | arameter | Cond | luon | Min. | Тур. | Max. | Unit |
| Vон | Output high voltage | P1_2, P1_3, P1_4, P1_5, P3_3, P3_4, P3_5, P3_7 ⁽²⁾ | When drive capacity is high | Іон = -2 mA | Vcc - 0.5 | _ | Vcc | V |
| | | | When drive capacity is low | Iон = -1 mA | Vcc - 0.5 | _ | Vcc | V |
| | | P1_0, P1_1, P1_6, P1_7, P4_2, P4_5, P4_6, P4_7, PA_0 | | Іон = -1 mA | Vcc - 0.5 | _ | Vcc | V |
| Vol | Output low voltage | P1_2, P1_3, P1_4, P1_5, P3_3, P3_4, P3_5, P3_7 ⁽²⁾ | When drive capacity is high | IoL = 2 mA | — | | 0.5 | V |
| | | | When drive capacity is low | IOL = 1 mA | _ | — | 0.5 | V |
| | | P1_0, P1_1, P1_6, P1_7, P4_2, P4_5, P4_6, P4_7, PA_0 | | IoL = 1 mA | _ | | 0.5 | V |
| VT+-VT- | Hysteresis | INT0, INT1, INT2, INT3, KI0, KI1, KI2, KI3, TRJIO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, RXD0, CLK0 | Vcc = 2.2 V | | 0.05 | 0.20 | _ | V |
| | | RESET | Vcc = 2.2 V | | 0.05 | 0.20 | | V |
| Ін | Input high current | | VI = 2.2 V, Vcc = | = 2.2 V | — | _ | 4.0 | μA |
| lı∟ | Input low current | | VI = 0 V, $Vcc = 2$ | 2.2 V | — | _ | -4.0 | μA |
| RPULLUP | Pull-up resistance | | VI = 0 V, $Vcc = 2$ | 2.2 V | 70 | 140 | 300 | kΩ |
| RfXIN | Feedback resistance | XIN | | | — | 2.2 | | MΩ |
| Vram | RAM hold voltage | | In stop mode | | 1.8 | — | | V |

Table 4.25 DC Characteristics (5) [1.8 V \leq Vcc < 2.7 V]

1. 1.8 V \leq Vcc < 2.7 V and Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), f(XIN) = 5 MHz, unless otherwise specified.

2. High drive capacity can also be used while the peripheral output function is used.



Table 4.26 DC Characteristics (6) [1.8 V \leq Vcc < 2.7 V] (Topr = -20 °C to 85 °C (N version)/-40 °C to 85 °C (D version), unless otherwise specified)

| | | | Condition | | | | | | | | | |
|--------|------------------------|---|------------------------|----------------------|---------------|-------------------|---|---|------|---------------------|------|----|
| Symbol | Parameter | ameter | Oscillation Circuit | On-Chip C | Scillator | CPU Low-Power- | Low-Power- Consumption Other Setting | Standard | | | Unit | |
| | | | XIN (2) | High- Speed | Low- Speed | Clock | | Other | Min. | Тур. ⁽³⁾ | Max. | |
| lcc | Power supply | High-speed clock mode | 5 MHz | Off | 125 kHz | No division | — | | - | 1.0 | _ | mA |
| | current ⁽¹⁾ | | 5 MHz | Off | 125 kHz | Division by 8 | — | | — | 0.6 | _ | mA |
| | | High-speed on-chip oscillator mode | Off | 5 MHz ⁽⁴⁾ | 125 kHz | No division | | | — | 1.6 | 6.5 | mA |
| | | | Off | 5 MHz ⁽⁴⁾ | 125 kHz | Division by 8 | | | — | 1.1 | _ | mA |
| | | | Off | 4 MHz ⁽⁴⁾ | 125 kHz | Division by 16 | MSTTRC = 1 | | — | 1.0 | _ | mA |
| | | Low-speed on-chip oscillator mode | Off | Off | 125 kHz | Division by 8 | FMR27 = 1 LPE = 0 | | _ | 60 | 200 | μΑ |
| | | Wait mode | Off | Off | 125 kHz | _ | VC1E = 0 VC0E = 0 LPE = 1 | Peripheral clock supplied during WAIT instruction execution | — | 15 | 90 | μΑ |
| | | | Off | Off | 125 kHz | _ | VC1E = 0 VC0E = 0 LPE = 1 WCKSTP = 1 | Peripheral clock stopped during WAIT instruction execution | — | 4.0 | 80 | μΑ |
| | | Stop mode | Off | Off | Off | — | VC1E = 0 VC0E = 0 STPM = 1 | Topr = 25 °C Peripheral clock stopped | — | 1.0 | 4.0 | μΑ |
| | | | Off | Off | Off | _ | VC1E = 0 VC0E = 0 STPM = 1 | Topr = 85 °C Peripheral clock stopped | — | 1.5 | — | μΑ |

Notes:

1. Vcc = 1.8 V to 2.7 V, single-chip mode, output pins are open, and other pins are connected to Vss.

2. When the XIN input is a square wave.

3. Vcc = 2.2 V

4. Set the system clock to 5 MHz or 4 MHz with the PHISEL register.



Timing Requirements (Vcc = 2.2 V, Vss = 0 V at Topr = 25 °C, unless otherwise specified)

Table 4.27 External Clock Input (XIN)

| Symbol | Parameter | Stan | Lloit | |
|----------|----------------------|------|-------|------|
| | | Min. | Max. | Unit |
| tc(XIN) | XIN input cycle time | 200 | | ns |
| twh(xin) | XIN input high width | 90 | _ | ns |
| twl(XIN) | XIN input low width | 90 | _ | ns |



Figure 4.12 External Clock Input Timing When Vcc = 2.2 V

Table 4.28 TRJIO Input

| Symbol | Parameter | Stan | Linit | |
|------------|------------------------|------|-------|------|
| | | Min. | Max. | Unit |
| tc(TRJIO) | TRJIO input cycle time | 500 | _ | ns |
| twh(trjio) | TRJIO input high width | 200 | _ | ns |
| twl(trjio) | TRJIO input low width | 200 | _ | ns |



Figure 4.13 TRJIO Input Timing When Vcc = 2.2 V



Table 4.29Serial Interface

| Symbol | Parameter | | Standard | | |
|----------|------------------------|-----|----------|------|--|
| | | | Max. | Onit | |
| tc(CK) | CLK0 input cycle time | 800 | _ | ns | |
| tw(CKH) | CLK0 input high width | 400 | - | ns | |
| tw(CKL) | CLK0 input low width | 400 | - | ns | |
| td(C-Q) | TXD0 output delay time | _ | 200 | ns | |
| th(C-Q) | TXD0 hold time | 0 | _ | ns | |
| tsu(D-C) | RXD0 input setup time | 150 | _ | ns | |
| th(C-D) | RXD0 input hold time | 90 | | ns | |



Figure 4.14 Serial Interface Timing When Vcc = 2.2 V

Table 4.30 External Interrupt INTi Input, Key Input Interrupt Kli (i = 0 to 3)

| Symbol | Derometer | | Standard | | |
|---------|---|-----------|----------|------|--|
| | r al all'elei | Min. | Max. | Unit | |
| tw(INH) | INTi input high width, Kli input high width | 1,000 (1) | _ | ns | |
| tw(INL) | INTi input low width, Kli input low width | 1,000 (2) | _ | ns | |

Notes:

1. When the digital filter is enabled by the INTi input filter select bit, the INTi input high width is (1/digital filter clock frequency × 3) or the minimum value of the standard, whichever is greater.

2. When the digital filter is enabled by the INTi input filter select bit, the INTi input low width is (1/digital filter clock frequency × 3) or the minimum value of the standard, whichever is greater.



Figure 4.15 Timing for External Interrupt INTi Input and Key Input Interrupt Kli When Vcc = 2.2 V

Package Dimensions

Diagrams showing the latest package dimensions and mounting information are available in the "Packages" section of the Renesas Electronics website.







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