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Details

Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	24
Program Memory Size	8KB (2.75K x 24)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 19x10b/12b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24f08km202-e-so

TABLE 1-5: PIC24FV16KM204 FAMILY PINOUT DESCRIPTION (CONTINUED)

Function	F					FV					I/O	Buffer	Description
	Pin Number					Pin Number							
	20-Pin PDIP/ SSOP/ SOIC	28-Pin PDIP/ SSOP/ SOIC	28-Pin QFN	44-Pin QFN/ TQFP	48-Pin UQFN	20-Pin PDIP/ SSOP/ SOIC	28-Pin PDIP/ SSOP/ SOIC	28-Pin QFN	44-Pin QFN/ TQFP	48-Pin UQFN			
CN13	16	24	21	11	12	16	24	21	11	12	I	ST	Interrupt-on-Change Inputs
CN14	15	23	20	10	11	15	23	20	10	11	I	ST	Interrupt-on-Change Inputs
CN15	—	22	19	9	10	—	22	19	9	10	I	ST	Interrupt-on-Change Inputs
CN16	—	21	18	8	9	—	21	18	8	9	I	ST	Interrupt-on-Change Inputs
CN17	—	—	—	3	3	—	—	—	3	3	I	ST	Interrupt-on-Change Inputs
CN18	—	—	—	2	2	—	—	—	2	2	I	ST	Interrupt-on-Change Inputs
CN19	—	—	—	5	5	—	—	—	5	5	I	ST	Interrupt-on-Change Inputs
CN20	—	—	—	4	4	—	—	—	4	4	I	ST	Interrupt-on-Change Inputs
CN21	13	18	15	1	1	13	18	15	1	1	I	ST	Interrupt-on-Change Inputs
CN22	12	17	14	44	48	12	17	14	44	48	I	ST	Interrupt-on-Change Inputs
CN23	11	16	13	43	47	11	16	13	43	47	I	ST	Interrupt-on-Change Inputs
CN24	—	15	12	42	46	—	15	12	42	46	I	ST	Interrupt-on-Change Inputs
CN25	—	—	—	37	40	—	—	—	37	40	I	ST	Interrupt-on-Change Inputs
CN26	—	—	—	38	41	—	—	—	38	41	I	ST	Interrupt-on-Change Inputs
CN27	—	14	11	41	45	—	14	11	41	45	I	ST	Interrupt-on-Change Inputs
CN28	—	—	—	36	39	—	—	—	36	39	I	ST	Interrupt-on-Change Inputs
CN29	8	10	7	31	34	8	10	7	31	34	I	ST	Interrupt-on-Change Inputs
CN30	7	9	6	30	33	7	9	6	30	33	I	ST	Interrupt-on-Change Inputs
CN31	—	—	—	26	28	—	—	—	26	28	I	ST	Interrupt-on-Change Inputs
CN32	—	—	—	25	27	—	—	—	25	27	I	ST	Interrupt-on-Change Inputs
CN33	—	—	—	32	35	—	—	—	32	35	I	ST	Interrupt-on-Change Inputs
CN34	—	—	—	35	38	—	—	—	35	38	I	ST	Interrupt-on-Change Inputs
CN35	—	—	—	12	13	—	—	—	12	13	I	ST	Interrupt-on-Change Inputs
CN36	—	—	—	13	14	—	—	—	13	14	I	ST	Interrupt-on-Change Inputs
CTCMP	4	4	1	21	23	4	4	1	21	23	I	ANA	CTMU Comparator Input

Legend: ANA = Analog level input/output, ST = Schmitt Trigger input buffer, I²C™ = I²C/SMBus input buffer

PIC24FV16KM204 FAMILY

4.0 MEMORY ORGANIZATION

As with Harvard architecture devices, the PIC24F microcontrollers feature separate program and data memory space and busing. This architecture also allows the direct access of program memory from the Data Space (DS) during code execution.

4.1 Program Address Space

The program address memory space of the PIC24F devices is 4M instructions. The space is addressable by a 24-bit value derived from either the 23-bit Program Counter (PC) during program execution, or from a table operation or Data Space remapping, as described in **Section 4.3 “Interfacing Program and Data Memory Spaces”**.

The user access to the program memory space is restricted to the lower half of the address range (000000h to 7FFFFFFh). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

Memory maps for the PIC24FV16KM204 family of devices are displayed in Figure 4-1.

FIGURE 4-1: PROGRAM SPACE MEMORY MAP FOR PIC24FXXXXX FAMILY DEVICES

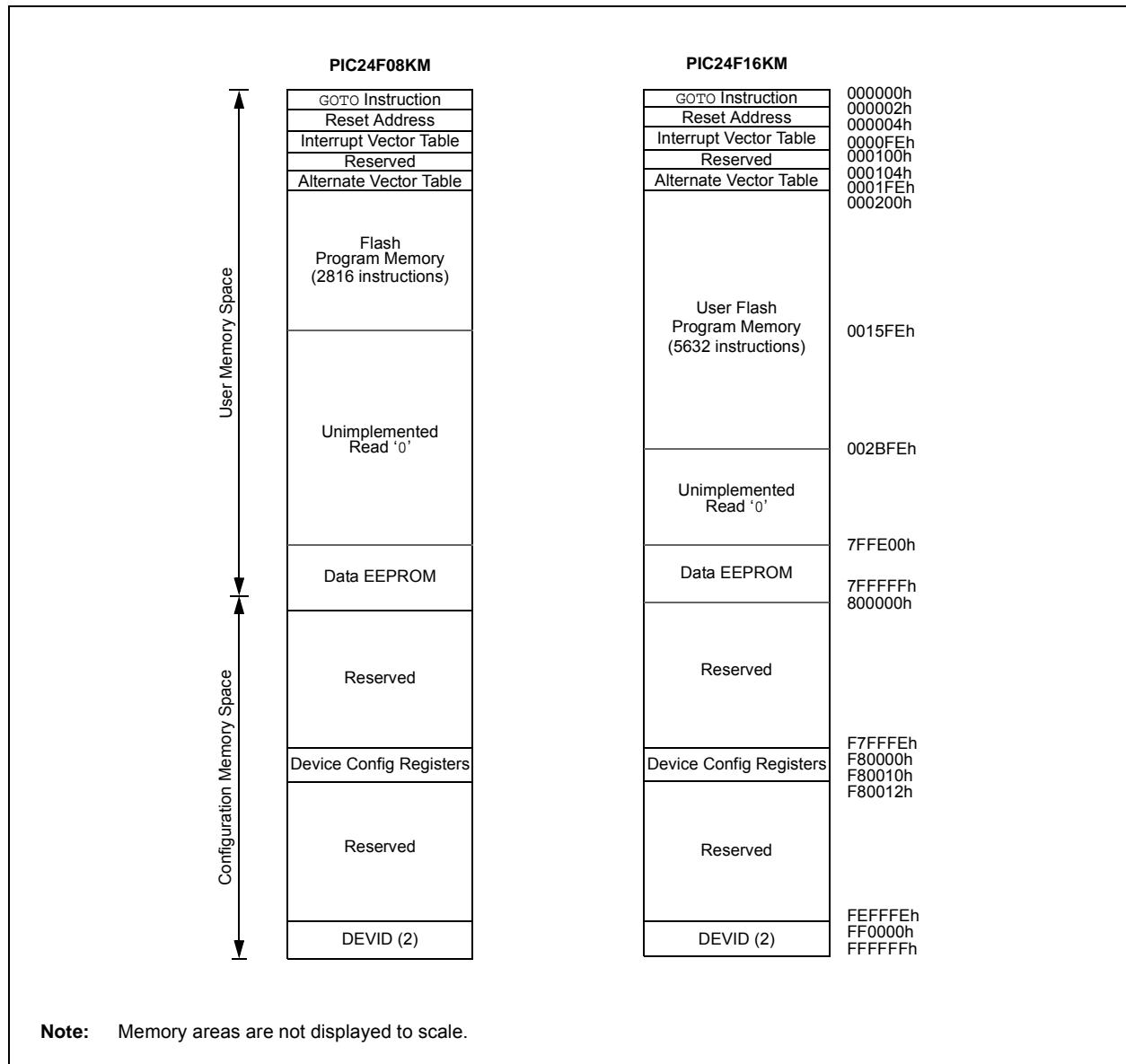


TABLE 4-9: MCCP2 REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CCP2CON1L	164h	CCPON	—	CCPSIDL	r	TMRSYNC	CLKSEL2	CLKSEL1	CLKSEL0	TMRPS1	TMRPS0	T32	CCSEL	MOD3	MOD2	MOD1	MOD0	0000
CCP2CON1H	166h	OPSSRC	RTRGEN	—	—	IOPS3	IOPS2	IOPS1	IOPS0	TRIGEN	ONESHOT	ALTSYNC	SYNC4	SYNC3	SYNC2	SYNC1	SYNC0	0000
CCP2CON2L	168h	PWMRSEN	ASDGM	—	SSDG	—	—	—	—	ASDG7	ASDG6	ASDG5	ASDG4	ASDG3	ASDG2	ASDG1	ASDG0	0000
CCP2CON2H	16Ah	OENSYNC	—	OCFEN ⁽¹⁾	OCEEN ⁽¹⁾	OCDEN ⁽¹⁾	OCCEN ⁽¹⁾	OCBEN ⁽¹⁾	OCAEN	ICGSM1	ICGSM0	—	AUXOUT1	AUXOUT0	ICSEL2	ICSEL1	ICSEL0	0100
CCP2CON3L	16Ch	—	—	—	—	—	—	—	—	—	—	DT5	DT4	DT3	DT2	DT1	DT0	0000
CCP2CON3H	16Eh	OETRIG	OSCNT2	OSCNT1	OSCNT0	—	OUTM2 ⁽¹⁾	OUTM1 ⁽¹⁾	OUTM0 ⁽¹⁾	—	—	POLACE	POLBDF ⁽¹⁾	PSSACE1	PSSACE0	PSSBDF1 ⁽¹⁾	PSSBDF0 ⁽¹⁾	0000
CCP2STATL	170h	—	—	—	—	—	—	—	—	CCPTRIG	TRSET	TRCLR	ASEVT	SCEVT	ICDIS	ICOV	ICBNE	0000
CCP2TMRL	174h	MCCP2 Time Base Register Low Word																0000
CCP2TMRH	176h	MCCP2 Time Base Register High Word																0000
CCP2PRL	178h	MCCP2 Time Base Period Register Low Word																FFFF
CCP2PRH	17Ah	MCCP2 Time Base Period Register High Word																FFFF
CCP2RAL	17Ch	Output Compare 2 Data Word A																0000
CCP2RBL	180h	Output Compare 2 Data Word B																0000
CCP2BUFL	184h	Input Capture 2 Data Buffer Low Word																0000
CCP2BUFH	186h	Input Capture 2 Data Buffer High Word																0000

Legend: x = unknown, u = unchanged, — = unimplemented, q = value depends on condition, r = reserved.

Note 1: These bits are available only on PIC24F(V)16KM2XX devices.

PIC24FV16KM204 FAMILY

4.3.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of Data Space may optionally be mapped into a 16K word page of the program space. This provides transparent access of stored constant data from the Data Space without the need to use special instructions (i.e., `TBLRDH/H`).

Program space access through the Data Space occurs if the MSb of the Data Space, EA, is '1' and PSV is enabled by setting the PSV bit in the CPU Control (`CORCON<2>`) register. The location of the program memory space to be mapped into the Data Space is determined by the Program Space Visibility Page Address register (`PSVPAG`). This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, `PSVPAG` functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits.

By incrementing the PC by 2 for each program memory word, the lower 15 bits of Data Space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads from this area add an additional cycle to the instruction being executed, since two program memory fetches are required.

Although each Data Space address, 8000h and higher, maps directly into a corresponding program memory address (see Figure 4-7), only the lower 16 bits of the

24-bit program word are used to contain the data. The upper 8 bits of any program space locations used as data should be programmed with '1111 1111' or '0000 0000' to force a `NOP`. This prevents possible issues should the area of code ever be accidentally executed.

Note: PSV access is temporarily disabled during Table Reads/Writes.

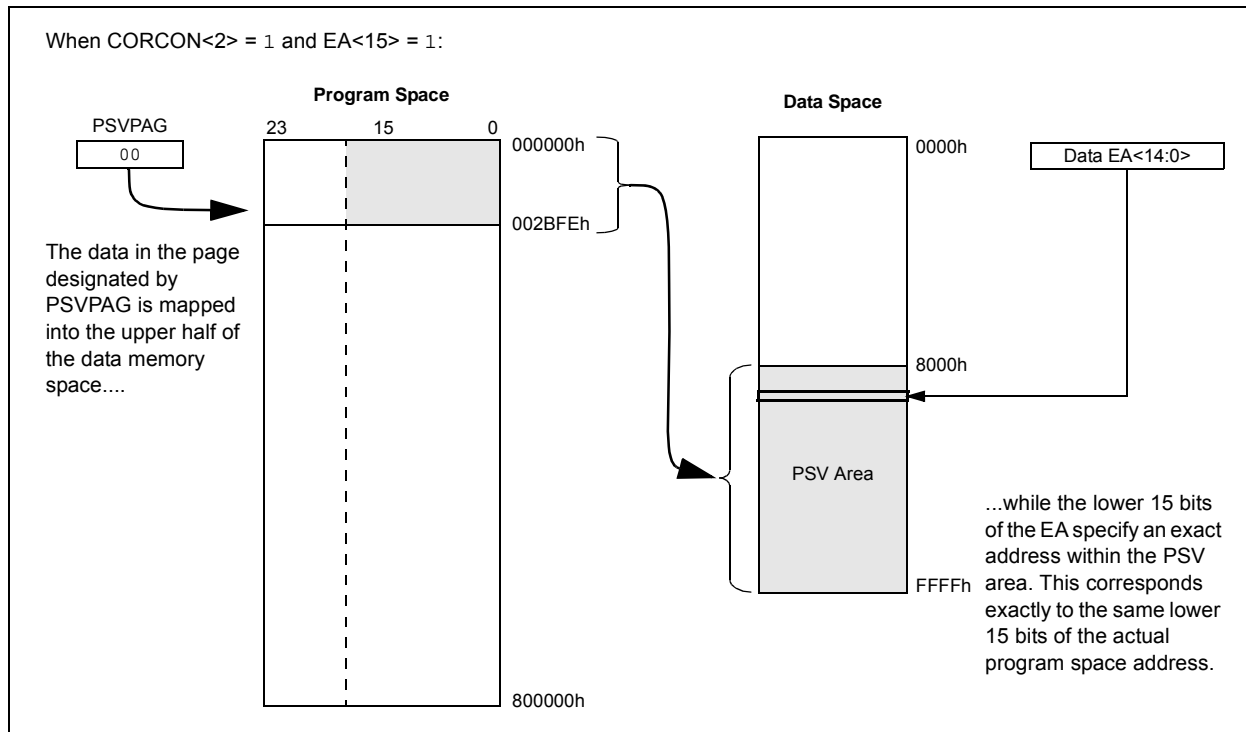
For operations that use PSV and are executed outside a `REPEAT` loop, the `MOV` and `MOV.D` instructions will require one instruction cycle in addition to the specified execution time. All other instructions will require two instruction cycles in addition to the specified execution time.

For operations that use PSV, which are executed inside a `REPEAT` loop, there will be some instances that require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the `REPEAT` loop will allow the instruction accessing data, using PSV, to execute in a single cycle.

FIGURE 4-7: PROGRAM SPACE VISIBILITY OPERATION



PIC24FV16KM204 FAMILY

EXAMPLE 5-3: LOADING THE WRITE BUFFERS – ASSEMBLY LANGUAGE CODE

```
; Set up NVMCON for row programming operations
MOV    #0x4004, W0                ;
MOV    W0, NVMCON                 ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
MOV    #0x0000, W0                ;
MOV    W0, TBLPAG                 ; Initialize PM Page Boundary SFR
MOV    #0x1500, W0                ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
MOV    #LOW_WORD_0, W2            ;
MOV    #HIGH_BYTE_0, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
; 1st_program_word
MOV    #LOW_WORD_1, W2            ;
MOV    #HIGH_BYTE_1, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
; 2nd_program_word
MOV    #LOW_WORD_2, W2            ;
MOV    #HIGH_BYTE_2, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
.
.
.
; 32nd_program_word
MOV    #LOW_WORD_31, W2           ;
MOV    #HIGH_BYTE_31, W3         ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0]                  ; Write PM high byte into program latch
```

EXAMPLE 5-4: LOADING THE WRITE BUFFERS – ‘C’ LANGUAGE CODE

```
// C example using MPLAB C30

#define NUM_INSTRUCTION_PER_ROW 64
int __attribute__((space(auto_psv))) progAddr = 0x1234    // Variable located in Pgm Memory
unsigned int offset;
unsigned int i;
unsigned int progData[2*NUM_INSTRUCTION_PER_ROW];        // Buffer of data to write

//Set up NVMCON for row programming
NVMCON = 0x4004;                                         // Initialize NVMCON

//Set up pointer to the first memory location to be written
TBLPAG = __builtin_tblpage(&progAddr);                  // Initialize PM Page Boundary SFR
offset = __builtin_tbloffset(&progAddr);                 // Initialize lower word of address

//Perform TBLWT instructions to write necessary number of latches
for(i=0; i < 2*NUM_INSTRUCTION_PER_ROW; i++)
{
    __builtin_tblwtl(offset, progData[i++]);             // Write to address low word
    __builtin_tblwth(offset, progData[i]);               // Write to upper byte
    offset = offset + 2;                                  // Increment address
}
```

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6.4.3 READING THE DATA EEPROM

To read a word from data EEPROM, the Table Read instruction is used. Since the EEPROM array is only 16 bits wide, only the `TBLRD1` instruction is needed. The read operation is performed by loading `TBLPAG` and `WREG` with the address of the EEPROM location, followed by a `TBLRD1` instruction.

A typical read sequence, using the Table Pointer management (`builtin_tblpage` and `builtin_tbloffset`) and Table Read (`builtin_tblr1`) procedures from the C30 compiler library, is provided in Example 6-5.

Program Space Visibility (PSV) can also be used to read locations in the data EEPROM.

EXAMPLE 6-5: READING THE DATA EEPROM USING THE `TBLRD` COMMAND

```
int __attribute__((space(eedata))) eeData = 0x1234;
int data;                                     // Data read from EEPROM
/*-----
The variable eeData must be a Global variable declared outside of any method

the code following this comment can be written inside the method that will execute the read
-----
*/
    unsigned int offset;

    // Set up a pointer to the EEPROM location to be erased
    TBLPAG = __builtin_tblpage(&eeData);           // Initialize EE Data page pointer
    offset = __builtin_tbloffset(&eeData);          // Initizlize lower word of address
    data = __builtin_tblr1(offset);                 // Write EEPROM data to write latch
```

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REGISTER 8-23: IPC4: INTERRUPT PRIORITY CONTROL REGISTER 4

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CNIP2	CNIP1	CNIP0	—	CMIP2	CMIP1	CMIP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	BCL1IP2	BCL1IP1	BCL1IP0	—	SSP1IP2	SSP1IP1	SSP1IP0
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **CNIP<2:0>:** Input Change Notification Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **CMIP<2:0>:** Comparator Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **BCL1IP<2:0>:** MSSP1 I²C™ Bus Collision Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SSP1IP<2:0>:** MSSP1 SPI/I²C Event Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

PIC24FV16KM204 FAMILY

REGISTER 8-26: IPC7: INTERRUPT PRIORITY CONTROL REGISTER 7

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U2TXIP2	U2TXIP1	U2TXIP0	—	U2RXIP2	U2RXIP1	U2RXIP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	INT2IP2	INT2IP1	INT2IP0	—	CCT4IP2	CCT4IP1	CCT4IP0
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **U2TXIP<2:0>:** UART2 Transmitter Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **U2RXIP<2:0>:** UART2 Receiver Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **INT2IP<2:0>:** External Interrupt 2 Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **CCT4IP<2:0>:** Capture/Compare 4 Timer Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

PIC24FV16KM204 FAMILY

REGISTER 13-6: CCPxCON3H: CCPx CONTROL 3 HIGH REGISTERS

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
OETRIG	OSCNT2	OSCNT1	OSCNT0	—	OUTM2 ⁽¹⁾	OUTM1 ⁽¹⁾	OUTM0 ⁽¹⁾
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	POLACE	POLBDF ⁽¹⁾	PSSACE1	PSSACE0	PSSBDF1 ⁽¹⁾	PSSBDF0 ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **OETRIG:** CCPx Dead-Time Select bit

1 = For Triggered mode (TRIGEN = 1): Module does not drive enabled output pins until triggered

0 = Normal output pin operation

bit 14-12 **OSCNT<2:0>:** One-Shot Event Count bits

111 = Extend one-shot event by 7 time base periods (8 time base periods total)

110 = Extend one-shot event by 6 time base periods (7 time base periods total)

101 = Extend one-shot event by 5 time base periods (6 time base periods total)

100 = Extend one-shot event by 4 time base periods (5 time base periods total)

011 = Extend one-shot event by 3 time base periods (4 time base periods total)

010 = Extend one-shot event by 2 time base periods (3 time base periods total)

001 = Extend one-shot event by 1 time base period (2 time base periods total)

000 = Do not extend one-shot Trigger event

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OUTM<2:0>:** PWMx Output Mode Control bits⁽¹⁾

111 = Reserved

110 = Output Scan mode

101 = Brush DC Output mode, forward

100 = Brush DC Output mode, reverse

011 = Reserved

010 = Half-Bridge Output mode

001 = Push-Pull Output mode

000 = Steerable Single Output mode

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **POLACE:** CCPx Output Pins, OCxA, OCxC and OCxE, Polarity Control bit

1 = Output pin polarity is active-low

0 = Output pin polarity is active-high

bit 4 **POLBDF:** CCPx Output Pins, OCxB, OCxD and OCxF, Polarity Control bit⁽¹⁾

1 = Output pin polarity is active-low

0 = Output pin polarity is active-high

bit 3-2 **PSSACE<1:0>:** PWMx Output Pins, OCxA, OCxC and OCxE, Shutdown State Control bits

11 = Pins are driven active when a shutdown event occurs

10 = Pins are driven inactive when a shutdown event occurs

0x = Pins are tri-stated when a shutdown event occurs

bit 1-0 **PSSBDF<1:0>:** PWMx Output Pins, OCxB, OCxD, and OCxF, Shutdown State Control bits⁽¹⁾

11 = Pins are driven active when a shutdown event occurs

10 = Pins are driven inactive when a shutdown event occurs

0x = Pins are in a high-impedance state when a shutdown event occurs

Note 1: These bits are implemented in MCCPx modules only.

PIC24FV16KM204 FAMILY

REGISTER 14-7: SSPxCON3: MSSPx CONTROL REGISTER 3 (I²C™ MODE)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ACKTIM ⁽¹⁾	PCIE	SCIE	BOEN	SDAHT	SBCDE	AHEN	DHEN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **ACKTIM:** Acknowledge Time Status bit⁽¹⁾

- 1 = Indicates the I²C bus is in an Acknowledge sequence, set on the 8th falling edge of the SCLx clock
- 0 = Not an Acknowledge sequence, cleared on the 9th rising edge of the SCLx clock

bit 6 **PCIE:** Stop Condition Interrupt Enable bit

- 1 = Enables interrupt on detection of a Stop condition
- 0 = Stop detection interrupts are disabled⁽²⁾

bit 5 **SCIE:** Start Condition Interrupt Enable bit

- 1 = Enables interrupt on detection of a Start or Restart condition
- 0 = Start detection interrupts are disabled⁽²⁾

bit 4 **BOEN:** Buffer Overwrite Enable bit

I²C Master mode:

This bit is ignored.

I²C Slave mode:

- 1 = SSPxBUF is updated and an ACK is generated for a received address/data byte, ignoring the state of the SSPOV bit only if the BF bit = 0
- 0 = SSPxBUF is only updated when SSPOV is clear

bit 3 **SDAHT:** SDAx Hold Time Selection bit

- 1 = Minimum of 300 ns hold time on SDAx after the falling edge of SCLx
- 0 = Minimum of 100 ns hold time on SDAx after the falling edge of SCLx

bit 2 **SBCDE:** Slave Mode Bus Collision Detect Enable bit (Slave mode only)

- 1 = Enables slave bus collision interrupts
- 0 = Slave bus collision interrupts are disabled

bit 1 **AHEN:** Address Hold Enable bit (Slave mode only)

- 1 = Following the 8th falling edge of SCLx for a matching received address byte; CKP bit of the SSPxCON1 register will be cleared and SCLx will be held low
- 0 = Address holding is disabled

bit 0 **DHEN:** Data Hold Enable bit (Slave mode only)

- 1 = Following the 8th falling edge of SCLx for a received data byte; slave hardware clears the CKP bit of the SSPxCON1 register and SCLx is held low
- 0 = Data holding is disabled

Note 1: This bit has no effect in Slave modes for which Start and Stop condition detection is explicitly listed as enabled.

2: The ACKTIM status bit is active only when the AHEN bit or DHEN bit is set.

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REGISTER 14-8: SSPxADD: MSSPx SLAVE ADDRESS/BAUD RATE GENERATOR REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADD7	ADD6	ADD5	ADD4	ADD3	ADD2	ADD1	ADD0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **ADD<7:0>:** Slave Address/Baud Rate Generator Value bits

SPI Master and I²C™ Master modes:

Reload value for the Baud Rate Generator. Clock period is $(([SPxADD] + 1) * 2) / F_{osc}$.

I²C Slave modes:

Represents 7 or 8 bits of the slave address, depending on the addressing mode used:

7-Bit mode: Address is ADD<7:1>; ADD<0> is ignored.

10-Bit LSb mode: ADD<7:0> are the Least Significant bits of the address.

10-Bit MSb mode: ADD<2:1> are the two Most Significant bits of the address; ADD<7:3> are always '11110' as a specification requirement; ADD<0> is ignored.

REGISTER 14-9: SSPxMSK: I²C™ SLAVE ADDRESS MASK REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
MSK7	MSK6	MSK5	MSK4	MSK3	MSK2	MSK1	MSK0 ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **MSK<7:0>:** Slave Address Mask Select bits⁽¹⁾

1 = Masking of corresponding bit of SSPxADD is enabled

0 = Masking of corresponding bit of SSPxADD is disabled

Note 1: MSK0 is not used as a mask bit in 7-bit addressing.

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REGISTER 17-5: CLCxGLSH: CLCx GATE LOGIC INPUT SELECT HIGH REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G4D4T	G4D4N	G4D3T	G4D3N	G4D2T	G4D2N	G4D1T	G4D1N
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G3D4T	G3D4N	G3D3T	G3D3N	G3D2T	G3D2N	G3D1T	G3D1N
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **G4D4T:** Gate 4 Data Source 4 True Enable bit
 1 = The Data Source 4 inverted signal is enabled for Gate 4
 0 = The Data Source 4 inverted signal is disabled for Gate 4

bit 14 **G4D4N:** Gate 4 Data Source 4 Negated Enable bit
 1 = The Data Source 4 inverted signal is enabled for Gate 4
 0 = The Data Source 4 inverted signal is disabled for Gate 4

bit 13 **G4D3T:** Gate 4 Data Source 3 True Enable bit
 1 = The Data Source 3 inverted signal is enabled for Gate 4
 0 = The Data Source 3 inverted signal is disabled for Gate 4

bit 12 **G4D3N:** Gate 4 Data Source 3 Negated Enable bit
 1 = The Data Source 3 inverted signal is enabled for Gate 4
 0 = The Data Source 3 inverted signal is disabled for Gate 4

bit 11 **G4D2T:** Gate 4 Data Source 2 True Enable bit
 1 = The Data Source 2 inverted signal is enabled for Gate 4
 0 = The Data Source 2 inverted signal is disabled for Gate 4

bit 10 **G4D2N:** Gate 4 Data Source 2 Negated Enable bit
 1 = The Data Source 2 inverted signal is enabled for Gate 4
 0 = The Data Source 2 inverted signal is disabled for Gate 4

bit 9 **G4D1T:** Gate 4 Data Source 1 True Enable bit
 1 = The Data Source 1 inverted signal is enabled for Gate 4
 0 = The Data Source 1 inverted signal is disabled for Gate 4

bit 8 **G4D1N:** Gate 4 Data Source 1 Negated Enable bit
 1 = The Data Source 1 inverted signal is enabled for Gate 4
 0 = The Data Source 1 inverted signal is disabled for Gate 4

bit 7 **G3D4T:** Gate 3 Data Source 4 True Enable bit
 1 = The Data Source 4 inverted signal is enabled for Gate 3
 0 = The Data Source 4 inverted signal is disabled for Gate 3

bit 6 **G3D4N:** Gate 3 Data Source 4 Negated Enable bit
 1 = The Data Source 4 inverted signal is enabled for Gate 3
 0 = The Data Source 4 inverted signal is disabled for Gate 3

bit 5 **G3D3T:** Gate 3 Data Source 3 True Enable bit
 1 = The Data Source 3 inverted signal is enabled for Gate 3
 0 = The Data Source 3 inverted signal is disabled for Gate 3

bit 4 **G3D3N:** Gate 3 Data Source 3 Negated Enable bit
 1 = The Data Source 3 inverted signal is enabled for Gate 3
 0 = The Data Source 3 inverted signal is disabled for Gate 3

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REGISTER 17-5: CLCxGLSH: CLCx GATE LOGIC INPUT SELECT HIGH REGISTER (CONTINUED)

- bit 3 **G3D2T:** Gate 3 Data Source 2 True Enable bit
1 = The Data Source 2 inverted signal is enabled for Gate 3
0 = The Data Source 2 inverted signal is disabled for Gate 3
- bit 2 **G3D2N:** Gate 3 Data Source 2 Negated Enable bit
1 = The Data Source 2 inverted signal is enabled for Gate 3
0 = The Data Source 2 inverted signal is disabled for Gate 3
- bit 1 **G3D1T:** Gate 3 Data Source 1 True Enable bit
1 = The Data Source 1 inverted signal is enabled for Gate 3
0 = The Data Source 1 inverted signal is disabled for Gate 3
- bit 0 **G3D1N:** Gate 3 Data Source 1 Negated Enable bit
1 = The Data Source 1 inverted signal is enabled for Gate 3
0 = The Data Source 1 inverted signal is disabled for Gate 3

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REGISTER 19-1: AD1CON1: A/D A/D CONTROL REGISTER 1 (CONTINUED)

- bit 3 **Unimplemented:** Read as '0'
- bit 2 **ASAM:** A/D Sample Auto-Start bit
1 = Sampling begins immediately after the last conversion; SAMP bit is auto-set
0 = Sampling begins when the SAMP bit is manually set
- bit 1 **SAMP:** A/D Sample Enable bit
1 = A/D Sample-and-Hold amplifiers are sampling
0 = A/D Sample-and-Hold amplifiers are holding
- bit 0 **DONE:** A/D Conversion Status bit
1 = A/D conversion cycle has completed
0 = A/D conversion cycle has not started or is in progress

Note 1: This version of the TMR1 Trigger allows A/D conversions to be triggered from TMR1 while the device is operating in Sleep mode. The SSRC<3:0> = 0101 option allows conversions to be triggered in Run or Idle modes only.

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REGISTER 22-1: CMxCON: COMPARATOR x CONTROL REGISTERS (CONTINUED)

- bit 2 **Unimplemented:** Read as '0'
- bit 1-0 **CCH<1:0>:** Comparator x Channel Select bits
 11 = Inverting input of the comparator connects to BGBUF1⁽¹⁾
 10 = Inverting input of the comparator connects to the CxIND pin
 01 = Inverting input of the comparator connects to the CxINC pin
 00 = Inverting input of the comparator connects to the CxINB pin

- Note 1:** BGBUF1 voltage is configured by BUFREF1<1:0> (BUFCON0<1:0>).
- 2:** If the EVPOL<1:0> bits are set to a value other than '00', the first interrupt generated will occur on any transition of COUT. Subsequent interrupts will occur based on the EVPOLx bits setting.

REGISTER 22-2: CMSTAT: COMPARATOR MODULE STATUS REGISTER

R/W-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
CMIDL	—	—	—	—	C3EVT ⁽¹⁾	C2EVT ⁽¹⁾	C1EVT
bit 15				bit 8			

U-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
—	—	—	—	—	C3OUT ⁽¹⁾	C2OUT ⁽¹⁾	C1OUT
bit 7				bit 0			

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **CMIDL:** Comparator x Stop in Idle Mode bit
 1 = Comparator interrupts are disabled in Idle mode; enabled comparators remain operational
 0 = Continues operation of all enabled comparators in Idle mode
- bit 14-11 **Unimplemented:** Read as '0'
- bit 10 **C3EVT:** Comparator 3 Event Status bit (read-only)⁽¹⁾
 Shows the current event status of Comparator 3 (CM3CON<9>).
- bit 9 **C2EVT:** Comparator 2 Event Status bit (read-only)⁽¹⁾
 Shows the current event status of Comparator 2 (CM2CON<9>).
- bit 8 **C1EVT:** Comparator 1 Event Status bit (read-only)
 Shows the current event status of Comparator 1 (CM1CON<9>).
- bit 7-3 **Unimplemented:** Read as '0'
- bit 2 **C3OUT:** Comparator 3 Output Status bit (read-only)⁽¹⁾
 Shows the current output of Comparator 3 (CM3CON<8>).
- bit 1 **C2OUT:** Comparator 2 Output Status bit (read-only)⁽¹⁾
 Shows the current output of Comparator 2 (CM2CON<8>).
- bit 0 **C1OUT:** Comparator 1 Output Status bit (read-only)
 Shows the current output of Comparator 1 (CM1CON<8>).

- Note 1:** Comparator 2 and Comparator 3 are only available on PIC24F(V)16KM2XX devices.

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REGISTER 25-9: DEVREV: DEVICE REVISION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 23				bit 16			

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

U-0	U-0	U-0	U-0	R	R	R	R
—	—	—	—	REV3	REV2	REV1	REV0
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 23-4

Unimplemented: Read as '0'

bit 3-0

REV<3:0>: Minor Revision Identifier bits

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TABLE 27-17: OPERATIONAL AMPLIFIER SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Comments
	GBWP	Gain Bandwidth Product	—	5	—	MHz	SPDSEL = 1
			—	0.5	—	MHz	SPDSEL = 0
	SR	Slew Rate	—	1.2	—	V/μs	SPDSEL = 1
			—	0.3	—	V/μs	SPDSEL = 0
	AOL	DC Open-Loop Gain	—	90	—	dB	
	V _{IOFF}	Input Offset Voltage	—	±2	±10	mV	
	V _{IBC}	Input Bias Current	—	—	—	nA	(Note 1)
	V _{ICM}	Common-Mode Input Voltage Range	AVSS	—	AVDD	V	
	CMRR	Common-Mode Rejection Ratio	—	60	—	db	
	PSRR	Power Supply Rejection Ratio	—	60	—	dB	
	VOR	Output Voltage Range	AVSS + 200	AVSS + 5 to AVDD – 5	AVDD – 200	mV	0.5V input overdrive, no output loading

Note 1: The op amps use CMOS input circuitry with negligible input bias current. The maximum “effective bias current” is the I/O pin leakage specified by electrical Parameter DI50.

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TABLE 27-26: COMPARATOR TIMING REQUIREMENTS

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Comments
300	TRESP	Response Time ^{*(1)}	—	150	400	ns	
301	TMC2OV	Comparator Mode Change to Output Valid*	—	—	10	μs	

* Parameters are characterized but not tested.

Note 1: Response time is measured with one comparator input at $(V_{DD} - 1.5)/2$, while the other input transitions from VSS to VDD.

TABLE 27-27: COMPARATOR VOLTAGE REFERENCE SETTLING TIME SPECIFICATIONS

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Comments
VR310	TSET	Settling Time ⁽¹⁾	—	—	10	μs	

Note 1: Settling time is measured while CVRSS = 1 and the CVR<3:0> bits transition from '0000' to '1111'.

FIGURE 27-10: CAPTURE/COMPARE/PWM TIMINGS (MCCPx, SCCPx MODULES)

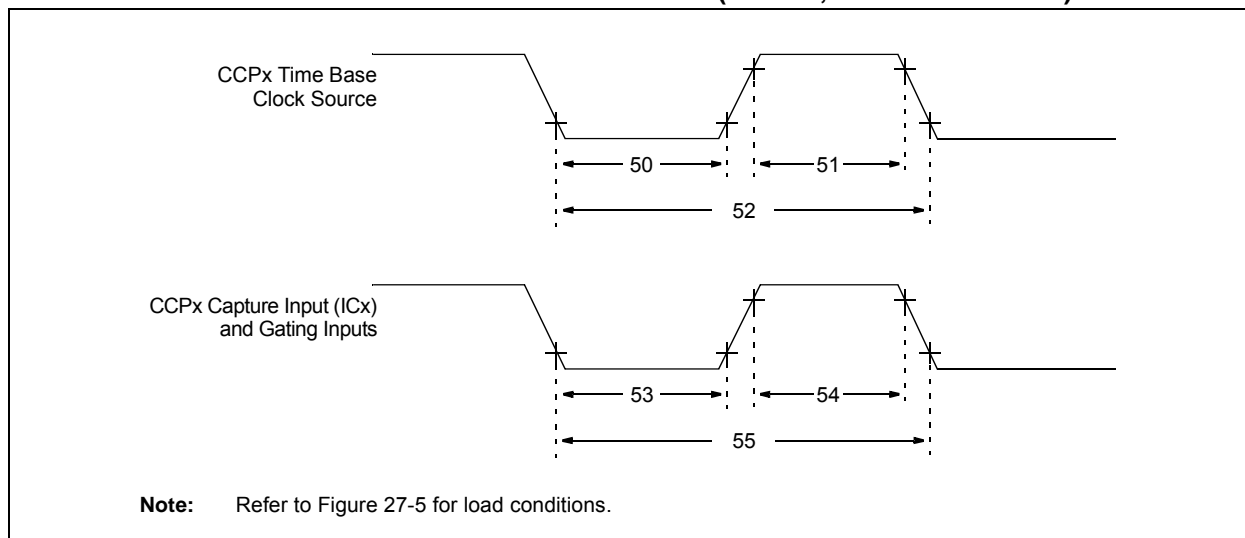


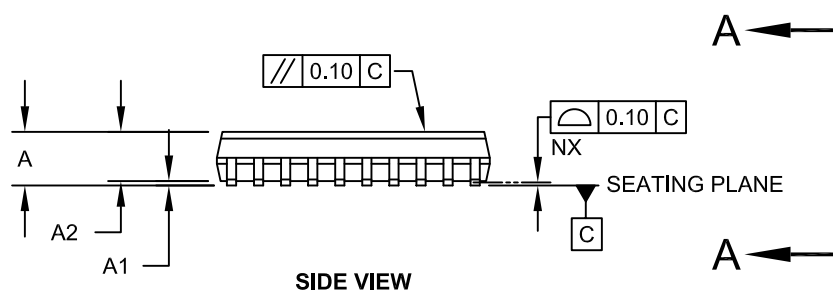
TABLE 27-28: CAPTURE/COMPARE/PWM REQUIREMENTS (MCCPx, SCCPx MODULES)

Param No.	Symbol	Characteristic	Min	Max	Units	Conditions
50	TCLKL	CCPx Time Base Clock Source Low Time	$T_{CY}/2$	—	ns	
51	TCLKH	CCPx Time Base Clock Source High Time	$T_{CY}/2$	—	ns	
52	TCLK	CCPx Time Base Clock Source Period	T_{CY}	—	ns	
53	TccL	CCPx Capture or Gating Input Low Time	TCLK	—	ns	
54	TccH	CCPx Capture or Gating Input High Time	TCLK	—	ns	
55	TccP	CCPx Capture or Gating Input Period	$2 * TCLK/N$	—	ns	N = Prescale Value (1, 4 or 16)

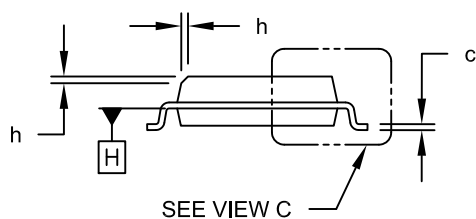
20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

[illegible]

TOP VIEW



SIDE VIEW



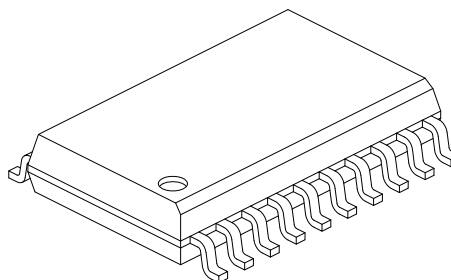
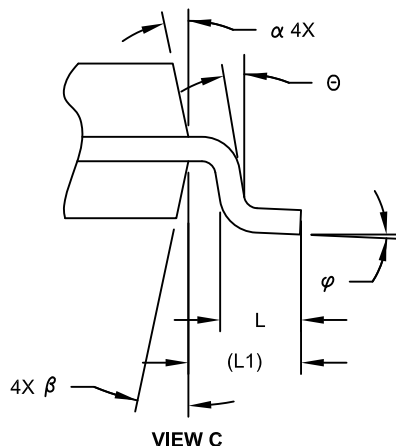
VIEW A-A

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20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	20		
Pitch	e	1.27 BSC		
Overall Height	A	-	-	2.65
Molded Package Thickness	A2	2.05	-	-
Standoff §	A1	0.10	-	0.30
Overall Width	E	10.30 BSC		
Molded Package Width	E1	7.50 BSC		
Overall Length	D	12.80 BSC		
Chamfer (Optional)	h	0.25	-	0.75
Foot Length	L	0.40	-	1.27
Footprint	L1	1.40 REF		
Lead Angle	Θ	0°	-	-
Foot Angle	φ	0°	-	8°
Lead Thickness	c	0.20	-	0.33
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.
- Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-094C Sheet 2 of 2