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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	38
Program Memory Size	16KB (5.5K x 24)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 22x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-UQFN Exposed Pad
Supplier Device Package	48-UQFN (6x6)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24f16km104-i-mv">https://www.e-xfl.com/product-detail/microchip-technology/pic24f16km104-i-mv</a>

TABLE 4-24: PAD CONFIGURATION REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PADCFG1	2FCh	—	—	—	—	SDO2DIS <sup>(1)</sup>	SCK2DIS <sup>(1)</sup>	SDO1DIS	SCK1DIS	—	—	—	—	—	—	—	—	0000

**Legend:** x = unknown, u = unchanged, — = unimplemented, q = value depends on condition, r = reserved.

**Note 1:** These bits are not available on the PIC24F(V)08KM101 device, read as '0'.

# PIC24FV16KM204 FAMILY

## 7.1 Clock Source Selection at Reset

If clock switching is enabled, the system clock source at device Reset is chosen, as shown in Table 7-2. If clock switching is disabled, the system clock source is always selected according to the Oscillator Configuration bits. For more information, see **Section 9.0 “Oscillator Configuration”**.

**TABLE 7-2: OSCILLATOR SELECTION vs. TYPE OF RESET (CLOCK SWITCHING ENABLED)**

Reset Type	Clock Source Determinant
POR	FNOSC<2:0> Configuration bits (FOSCSEL<2:0>)
BOR	
MCLR	COSC<2:0> Control bits (OSCCON<14:12>)
WDTO	
SWR	

## 7.2 Device Reset Times

The Reset times for various types of device Reset are summarized in Table 7-3. Note that the system Reset signal,  $\overline{\text{SYSRST}}$ , is released after the POR and PWRT delay times expire.

The time at which the device actually begins to execute code will also depend on the system oscillator delays, which include the Oscillator Start-up Timer (OST) and the PLL lock time. The OST and PLL lock times occur in parallel with the applicable  $\overline{\text{SYSRST}}$  delay times.

The FSCM delay determines the time at which the FSCM begins to monitor the system clock source after the  $\overline{\text{SYSRST}}$  signal is released.

**TABLE 7-3: RESET DELAY TIMES FOR VARIOUS DEVICE RESETS**

Reset Type	Clock Source	$\overline{\text{SYSRST}}$ Delay	System Clock Delay	Notes
POR <sup>(6)</sup>	EC	TPOR + TPWRT	—	1, 2
	FRC, FRCDIV	TPOR + TPWRT	TFRC	1, 2, 3
	LPRC	TPOR + TPWRT	TLPRC	1, 2, 3
	ECPLL	TPOR + TPWRT	TLOCK	1, 2, 4
	FRCPLL	TPOR + TPWRT	TFRC + TLOCK	1, 2, 3, 4
	XT, HS, SOSC	TPOR + TPWRT	TOST	1, 2, 5
	XTPLL, HSPLL	TPOR + TPWRT	TOST + TLOCK	1, 2, 4, 5
BOR	EC	TPWRT	—	2
	FRC, FRCDIV	TPWRT	TFRC	2, 3
	LPRC	TPWRT	TLPRC	2, 3
	ECPLL	TPWRT	TLOCK	2, 4
	FRCPLL	TPWRT	TFRC + TLOCK	2, 3, 4
	XT, HS, SOSC	TPWRT	TOST	2, 5
	XTPLL, HSPLL	TPWRT	TFRC + TLOCK	2, 3, 4
All Others	Any Clock	—	—	None

**Note 1:** TPOR = Power-on Reset delay.

**2:** TPWRT = 64 ms nominal if the Power-up Timer is enabled; otherwise, it is zero.

**3:** TFRC and TLPRC = RC Oscillator start-up times.

**4:** TLOCK = PLL Lock time.

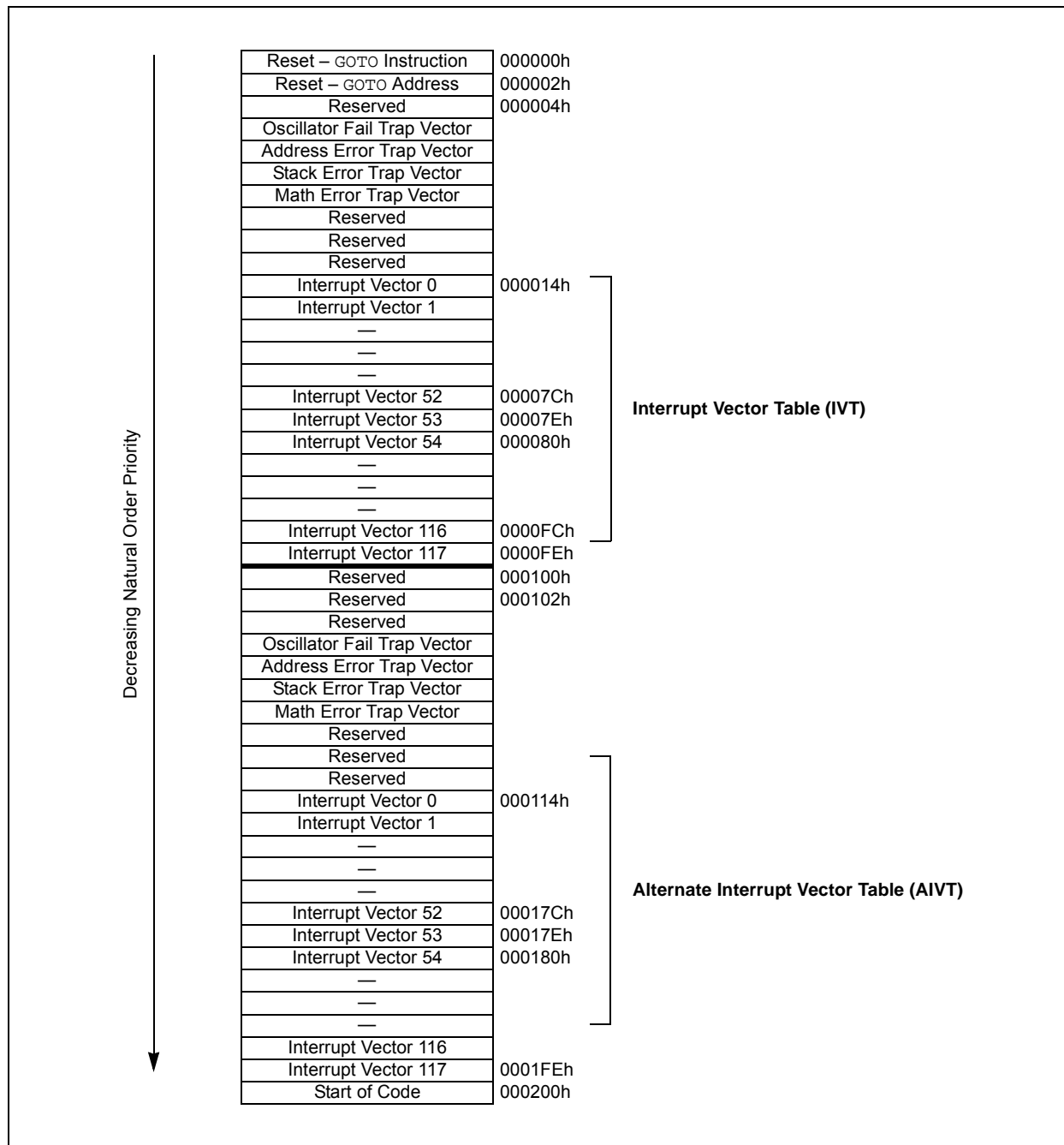
**5:** TOST = Oscillator Start-up Timer (OST). A 10-bit counter waits 1024 oscillator periods before releasing the oscillator clock to the system.

**6:** If Two-Speed Start-up is enabled, regardless of the Primary Oscillator selected, the device starts with FRC, and in such cases, FRC start-up time is valid.

**Note:** For detailed operating frequency and timing specifications, see **Section 27.0 “Electrical Characteristics”**.

# PIC24FV16KM204 FAMILY

**FIGURE 8-1: PIC24F INTERRUPT VECTOR TABLE**



# PIC24FV16KM204 FAMILY

## REGISTER 8-32: IPC19: INTERRUPT PRIORITY CONTROL REGISTER 19

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	DAC2IP2	DAC2IP1	DAC2IP0	—	DAC1IP2	DAC1IP1	DAC1IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	CTMUIP2	CTMUIP1	CTMUIP0	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **DAC2IP<2:0>:** Digital-to-Analog Converter 2 Event Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **DAC1IP<2:0>:** Digital-to-Analog Converter 1 Event Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **CTMUIP<2:0>:** CTMU Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

# PIC24FV16KM204 FAMILY

## REGISTER 14-1: SSPxSTAT: MSSPx STATUS REGISTER (SPI MODE)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

R/W-0	R/W-0	R-0	R-0	R-0	R-0	R-0	R-0
SMP	CKE <sup>(1)</sup>	D/ $\overline{A}$	P	S	R/ $\overline{W}$	UA	BF
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **SMP:** Sample bit

SPI Master mode:

1 = Input data is sampled at the end of data output time

0 = Input data is sampled at the middle of data output time

SPI Slave mode:

SMP must be cleared when SPI is used in Slave mode.

bit 6 **CKE:** SPI Clock Select bit<sup>(1)</sup>

1 = Transmit occurs on transition from active to Idle clock state

0 = Transmit occurs on transition from Idle to active clock state

bit 5 **D/ $\overline{A}$ :** Data/Address bit

Used in I<sup>2</sup>C™ mode only.

bit 4 **P:** Stop bit

Used in I<sup>2</sup>C mode only. This bit is cleared when the MSSPx module is disabled; SSPEN bit is cleared.

bit 3 **S:** Start bit

Used in I<sup>2</sup>C mode only.

bit 2 **R/ $\overline{W}$ :** Read/Write Information bit

Used in I<sup>2</sup>C mode only.

bit 1 **UA:** Update Address bit

Used in I<sup>2</sup>C mode only.

bit 0 **BF:** Buffer Full Status bit

1 = Receive is complete, SSPxBUF is full

0 = Receive is not complete, SSPxBUF is empty

**Note 1:** Polarity of clock state is set by the CKP bit (SSPxCON1<4>).

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## REGISTER 15-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0 <sup>(2)</sup>	R/W-0 <sup>(2)</sup>
UARTEN	—	USIDL	IREN <sup>(1)</sup>	RTSMD	—	UEN1	UEN0
bit 15						bit 8	

R/C-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7						bit 0	

<b>Legend:</b>	C = Clearable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15      **UARTEN:** UARTx Enable bit  
1 = UARTx is enabled; all UARTx pins are controlled by UARTx, as defined by UEN<1:0>  
0 = UARTx is disabled; all UARTx pins are controlled by port latches, UARTx power consumption is minimal
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **USIDL:** UARTx Stop in Idle Mode bit  
1 = Discontinues module operation when the device enters Idle mode  
0 = Continues module operation in Idle mode
- bit 12      **IREN:** IrDA<sup>®</sup> Encoder and Decoder Enable bit<sup>(1)</sup>  
1 = IrDA encoder and decoder are enabled  
0 = IrDA encoder and decoder are disabled
- bit 11      **RTSMD:** Mode Selection for UxRTS Pin bit  
1 = UxRTS pin is in Simplex mode  
0 = UxRTS pin is in Flow Control mode
- bit 10      **Unimplemented:** Read as '0'
- bit 9-8      **UEN<1:0>:** UARTx Enable bits<sup>(2)</sup>  
11 = UxTX, UxRX and UxBCLK pins are enabled and used; UxCTS pin is controlled by port latches  
10 = UxTX, UxRX, UxCTS and UxRTS pins are enabled and used  
01 = UxTX, UxRX and UxRTS pins are enabled and used; UxCTS pin is controlled by port latches  
00 = UxTX and UxRX pins are enabled and used; UxCTS and UxRTS/UxBCLK pins are controlled by port latches
- bit 7      **WAKE:** Wake-up on Start Bit Detect During Sleep Mode Enable bit  
1 = UARTx will continue to sample the UxRX pin; interrupt is generated on the falling edge, bit is cleared in hardware on the following rising edge  
0 = No wake-up is enabled
- bit 6      **LPBACK:** UARTx Loopback Mode Select bit  
1 = Enables Loopback mode  
0 = Loopback mode is disabled
- bit 5      **ABAUD:** Auto-Baud Enable bit  
1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion  
0 = Baud rate measurement is disabled or completed
- bit 4      **URXINV:** UARTx Receive Polarity Inversion bit  
1 = UxRX Idle state is '0'  
0 = UxRX Idle state is '1'

**Note 1:** This feature is only available for the 16x BRG mode (BRGH = 0).

**2:** The bit availability depends on the pin availability.

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## REGISTER 15-3: UxTXREG: UARTx TRANSMIT REGISTER

U-x	U-x	U-x	U-x	U-x	U-x	U-x	W-x
—	—	—	—	—	—	—	UTX8
bit 15							bit 8

W-x	W-x	W-x	W-x	W-x	W-x	W-x	W-x
UTX7	UTX6	UTX5	UTX4	UTX3	UTX2	UTX1	UTX0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8 **UTX8:** Data of the Transmitted Character bit (in 9-bit mode)

bit 7-0 **UTX<7:0>:** Data of the Transmitted Character bits

## REGISTER 15-4: UxRXREG: UARTx RECEIVE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R-0, HSC
—	—	—	—	—	—	—	URX8
bit 15							bit 8

R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
URX7	URX6	URX5	URX4	URX3	URX2	URX1	URX0
bit 7							bit 0

### Legend:

HSC = Hardware Settable/Clearable bit

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8 **URX8:** Data of the Received Character bit (in 9-bit mode)

bit 7-0 **URX<7:0>:** Data of the Received Character bits



# PIC24FV16KM204 FAMILY

## 16.2.6 ALRMVAL REGISTER MAPPINGS

### REGISTER 16-8: ALMTHDY: ALARM MONTH AND DAY VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	MTHTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	DAYTEN1	DAYTEN0	DAYONE3	DAYONE2	DAYONE1	DAYONE0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **MTHTEN0:** Binary Coded Decimal Value of Month's Tens Digit bit  
Contains a value of '0' or '1'.

bit 11-8 **MTHONE<3:0>:** Binary Coded Decimal Value of Month's Ones Digit bits  
Contains a value from 0 to 9.

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **DAYTEN<1:0>:** Binary Coded Decimal Value of Day's Tens Digit bits  
Contains a value from 0 to 3.

bit 3-0 **DAYONE<3:0>:** Binary Coded Decimal Value of Day's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

### REGISTER 16-9: ALWDHR: ALARM WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit bits  
Contains a value from 0 to 6.

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit bits  
Contains a value from 0 to 2.

bit 3-0 **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

# PIC24FV16KM204 FAMILY

## 17.1 Control Registers

The CLCx module is controlled by the following registers:

- CLCxCONL
- CLCxCONH
- CLCxSEL
- CLCxGLSL
- CLCxGLSH

The CLCx Control registers (CLCxCONL and CLCxCONH) are used to enable the module and interrupts, control the output enable bit, select output polarity and select the logic function. The CLCx Control registers also allow the user to control the logic polarity of not only the cell output, but also some intermediate variables.

The CLCx Source Select register (CLCxSEL) allows the user to select up to 4 data input sources using the 4 data input selection multiplexers. Each multiplexer has a list of 8 data sources available.

The CLCx Gate Logic Select registers (CLCxGLSL and CLCxGLSH) allow the user to select which outputs from each of the selection MUXes are used as inputs to the input gates of the logic cell. Each data source MUX outputs both a true and a negated version of its output. All of these 8 signals are enabled, ORed together by the logic cell input gates.

### REGISTER 17-1: CLCxCONL: CLCx CONTROL REGISTER (LOW)

R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	U-0	U-0
LCEN	—	—	—	INTP	INTN	—	—
bit 15				bit 8			

R-0	R-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
LCOE	LCOUT	LCPOL	—	—	MODE2	MODE1	MODE0
bit 7				bit 0			

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **LCEN:** CLCx Enable bit  
1 = CLCx is enabled and mixing input signals  
0 = CLCx is disabled and has logic zero outputs
- bit 14-12    **Unimplemented:** Read as '0'
- bit 11      **INTP:** CLCx Positive Edge Interrupt Enable bit  
1 = Interrupt will be generated when a rising edge occurs on LCOUT  
0 = Interrupt will not be generated
- bit 10      **INTN:** CLCx Negative Edge Interrupt Enable bit  
1 = Interrupt will be generated when a falling edge occurs on LCOUT  
0 = Interrupt will not be generated
- bit 9-8      **Unimplemented:** Read as '0'
- bit 7      **LCOE:** CLCx Port Enable bit  
1 = CLCx port pin output is enabled  
0 = CLCx port pin output is disabled
- bit 6      **LCOUT:** CLCx Data Output Status bit  
1 = CLCx output high  
0 = CLCx output low
- bit 5      **LCPOL:** CLCx Output Polarity Control bit  
1 = The output of the module is inverted  
0 = The output of the module is not inverted
- bit 4-3      **Unimplemented:** Read as '0'

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## REGISTER 17-3: CLCxSEL: CLCx INPUT MUX SELECT REGISTER (CONTINUED)

bit 6-4      **DS2<2:0>**: Data Selection MUX 2 Signal Selection bits

111 = MCCP2 Compare Event Flag (CCP2IF)

110 = MCCP1 Compare Event Flag (CCP1IF)

101 = Digital logic low

100 = A/D end of conversion event

For CLC1:

011 = UART1 TX

010 = Comparator 1 output

001 = CLC2 output

000 = CLCINB I/O pin

For CLC2:

011 = UART2 TX

010 = Comparator 1 output

001 = CLC1 output

000 = CLCINB I/O pin

bit 3      **Unimplemented:** Read as '0'

bit 2-0      **DS1<2:0>**: Data Selection MUX 1 Signal Selection bits

111 = SCCP5 Compare Event Flag (CCP5IF)

110 = SCCP4 Compare Event Flag (CCP4IF)

101 = Digital logic low

100 = 8 MHz FRC clock source

011 = LPRC clock source

010 = SOSC clock source

001 = System clock (Tcy)

000 = CLCINA I/O pin

## 18.0 HIGH/LOW-VOLTAGE DETECT (HLVD)

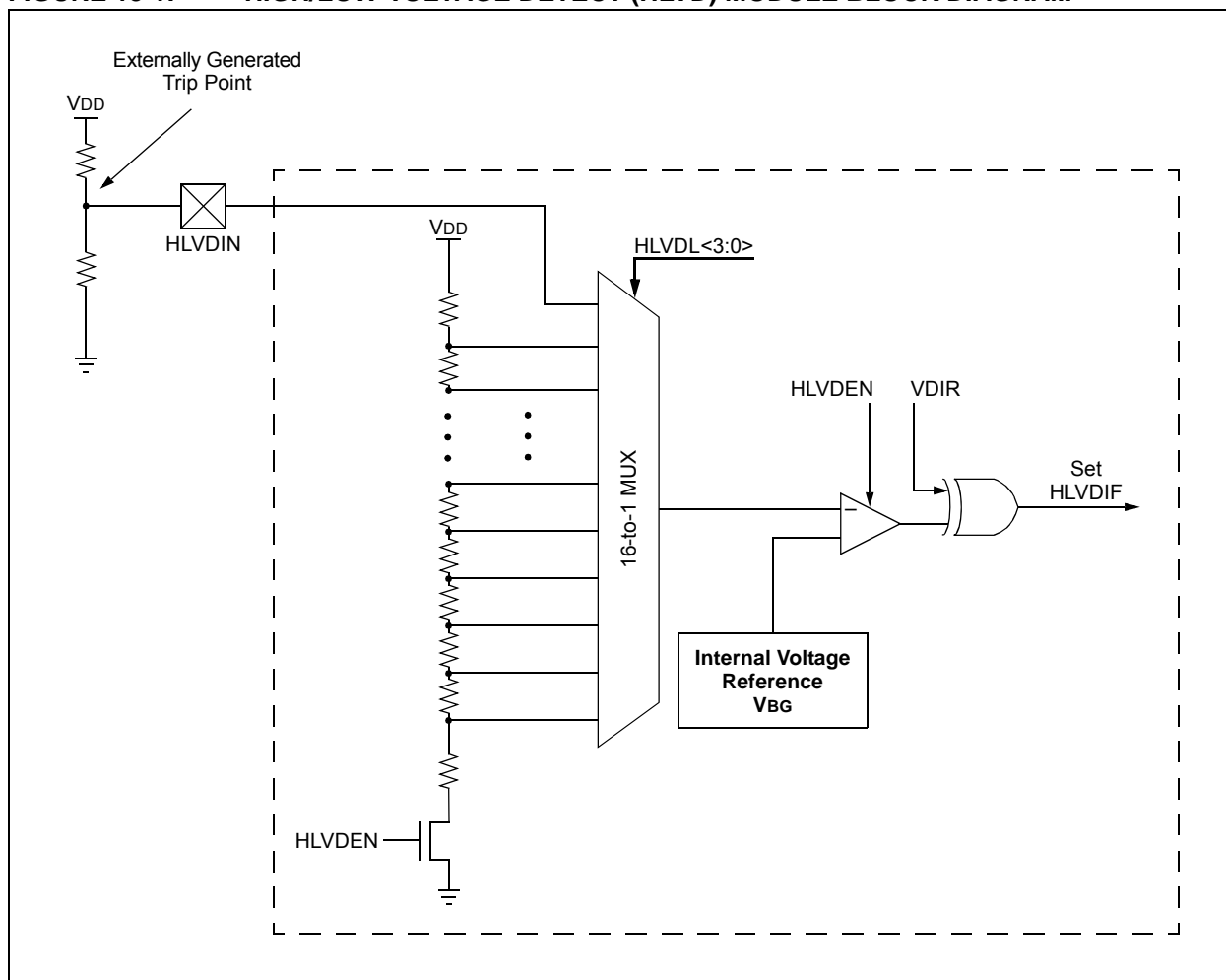
**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the High/Low-Voltage Detect, refer to the “PIC24F Family Reference Manual”, “High-Level Integration with Programmable High/Low-Voltage Detect (HLVD)” (DS39725).

The High/Low-Voltage Detect module (HLVD) is a programmable circuit that allows the user to specify both the device voltage trip point and the direction of change.

An interrupt flag is set if the device experiences an excursion past the trip point in the direction of change. If the interrupt is enabled, the program execution will branch to the interrupt vector address and the software can then respond to the interrupt.

The HLVD Control register (see Register 18-1) completely controls the operation of the HLVD module. This allows the circuitry to be “turned off” by the user under software control, which minimizes the current consumption for the device.

**FIGURE 18-1: HIGH/LOW-VOLTAGE DETECT (HLVD) MODULE BLOCK DIAGRAM**



## 19.0 12-BIT A/D CONVERTER WITH THRESHOLD DETECT

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the 12-Bit A/D Converter with Threshold Detect, refer to the “PIC24F Family Reference Manual”, “12-Bit A/D Converter with Threshold Detect” (DS39739).

The PIC24F 12-bit A/D Converter has the following key features:

- Successive Approximation Register (SAR) Conversion
- Conversion Speeds of up to 100 ksps
- Up to 32 Analog Input Channels (internal and external)
- Multiple Internal Reference Input Channels
- External Voltage Reference Input Pins
- Unipolar Differential Sample-and-Hold (S/H) Amplifier
- Automated Threshold Scan and Compare Operation to Pre-Evaluate Conversion Results
- Selectable Conversion Trigger Source
- Fixed-Length (one word per channel), Configurable Conversion Result Buffer
- Four Options for Results Alignment
- Configurable Interrupt Generation
- Operation During CPU Sleep and Idle modes

The 12-bit A/D Converter module is an enhanced version of the 10-bit module offered in some PIC24 devices. Both modules are Successive Approximation Register (SAR) converters at their cores, surrounded by a range of hardware features for flexible configuration. This version of the module extends functionality by providing 12-bit resolution, a wider range of automatic sampling options and tighter integration with other analog modules, such as the CTMU, and a configurable results buffer. There is a legacy 10-bit mode on this A/D to allow the option to run with lower resolution in order to obtain higher throughput. This module also includes a unique Threshold Detect feature that allows the module itself to make simple decisions based on the conversion results.

A simplified block diagram for the module is illustrated in Figure 19-1.

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To perform an A/D conversion:

1. Configure the A/D module:
  - a) Configure the port pins as analog inputs and/or select band gap reference inputs (ANSx registers).
  - b) Select the voltage reference source to match the expected range on the analog inputs (AD1CON2<15:13>).
  - c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
  - d) Select the appropriate sample/conversion sequence (AD1CON1<7:4> and AD1CON3<12:8>).
  - e) Configure the MODE12 bit to select A/D resolution (AD1CON1<10>).
  - f) Select how conversion results are presented in the buffer (AD1CON1<9:8>).
  - g) Select the interrupt rate (AD1CON2<6:2>).
  - h) Turn on the A/D module (AD1CON1<15>).
2. Configure the A/D interrupt (if required):
  - a) Clear the AD1IF bit.
  - b) Select the A/D interrupt priority.

To perform an A/D sample and conversion using Threshold Detect scanning:

1. Configure the A/D module:
  - a) Configure the port pins as analog inputs (ANSx registers).
  - b) Select the voltage reference source to match the expected range on the analog inputs (AD1CON2<15:13>).
  - c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
  - d) Select the appropriate sample/conversion sequence (AD1CON1<7:4> and AD1CON3<12:8>).
  - e) Configure the MODE12 bit to select A/D resolution (AD1CON1<10>).
  - f) Select how the conversion results are presented in the buffer (AD1CON1<9:8>).
  - g) Select the interrupt rate (AD1CON2<6:2>).

2. Configure the threshold compare channels:
  - a) Enable auto-scan; set the ASEN bit (AD1CON5<15>).
  - b) Select the Compare mode, "Greater Than, Less Than or Windowed"; set the CMx bits (AD1CON5<1:0>).
  - c) Select the threshold compare channels to be scanned (AD1CSSH, AD1CSSL).
  - d) If the CTMU is required as a current source for a threshold compare channel, enable the corresponding CTMU channel (AD1CTMENH, AD1CTMENL).
  - e) Write the threshold values into the corresponding ADC1BUFx registers.
  - f) Turn on the A/D module (AD1CON1<15>).

<p><b>Note:</b> If performing an A/D sample and conversion, using Threshold Detect in Sleep Mode, the RC A/D clock source must be selected before entering into Sleep mode.</p>
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3. Configure the A/D interrupt (OPTIONAL):
  - a) Clear the AD1IF bit.
  - b) Select the A/D interrupt priority.

# PIC24FV16KM204 FAMILY

## REGISTER 19-10: AD1CTMENH: CTMU ENABLE REGISTER (HIGH WORD)<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CTMEN23	CTMEN22	CTMEN21	CTMEN20 <sup>(2)</sup>	CTMEN19 <sup>(2)</sup>	CTMEN18	CTMEN17	CTMEN16
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-8                      **Unimplemented:** Read as '0'.

bit 7-0                      **CTMEN<23:16>:** CTMU Enabled During Conversion bits<sup>(2)</sup>

1 = CTMU is enabled and connected to the selected channel during conversion

0 = CTMU is not connected to this channel

**Note 1:** Unimplemented channels are read as '0'.

**2:** The CTMEN<20:19> bits are not implemented in 20-pin devices.

## REGISTER 19-11: AD1CTMENL: CTMU ENABLE REGISTER (LOW WORD)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CTMEN15	CTMEN14	CTMEN13	CTMEN12	CTMEN11	CTMEN10	CTMEN9	CTMEN8 <sup>(2,3)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CTMEN7 <sup>(2,3)</sup>	CTMEN6 <sup>(2,3)</sup>	CTMEN5 <sup>(2)</sup>	CTMEN4	CTMEN3	CTMEN2	CTMEN1	CTMEN0
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **CTMEN<15:0>:** CTMU Enabled During Conversion bits<sup>(2,3)</sup>

1 = CTMU is enabled and connected to the selected channel during conversion

0 = CTMU is not connected to this channel

**Note 1:** Unimplemented channels are read as '0'.

**2:** The CTMEN<8:5> bits are not implemented in 20-pin devices.

**3:** The CTMEN<8:6> bits are not implemented in 28-pin devices.

# PIC24FV16KM204 FAMILY

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## REGISTER 24-2: CTMUCON1H: CTMU CONTROL 1 HIGH REGISTER (CONTINUED)

- bit 6        **EDG2POL:** Edge 2 Polarity Select bit  
            1 = Edge 2 is programmed for a positive edge  
            0 = Edge 2 is programmed for a negative edge
- bit 5-2      **EDG2SEL<3:0>:** Edge 2 Source Select bits  
            1111 = Edge 2 source is the Comparator 3 output  
            1110 = Edge 2 source is the Comparator 2 output  
            1101 = Edge 2 source is the Comparator 1 output  
            1100 = Unimplemented; do not use  
            1011 = Edge 2 source is CLC1  
            1010 = Edge 2 source is the MCCP2 Compare Event (CCP2IF)  
            1001 = Unimplemented; do not use  
            1000 = Edge 2 source is CTED13  
            0111 = Edge 2 source is CTED12  
            0110 = Edge 2 source is CTED11<sup>(2)</sup>  
            0101 = Edge 2 source is CTED10  
            0100 = Edge 2 source is CTED9<sup>(2)</sup>  
            0011 = Edge 2 source is CTED1  
            0010 = Edge 2 source is CTED2  
            0001 = Edge 2 source is the MCCP1 Compare Event (CCP1IF)  
            0000 = Edge 2 source is Timer1
- bit 1-0      **Unimplemented:** Read as '0'

**Note 1:** Edge sources, CTED7 and CTED8, are not available on 28-pin and 20-pin devices.

**2:** Edge sources, CTED3, CTED9 and CTED11, are not available on 20-pin devices.



# PIC24FV16KM204 FAMILY

## REGISTER 25-2: FGS: GENERAL SEGMENT CONFIGURATION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/C-1	R/C-1
—	—	—	—	—	—	GCP	GWRP
bit 7							bit 0

### Legend:

R = Readable bit      C = Clearable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 7-2      **Unimplemented:** Read as '0'
- bit 1      **GCP:** General Segment Code Flash Code Protection bit  
             1 = No protection  
             0 = Standard security is enabled
- bit 0      **GWRP:** General Segment Code Flash Write Protection bit  
             1 = General Segment may be written  
             0 = General Segment is write-protected

## REGISTER 25-3: FOSCSEL: OSCILLATOR SELECTION CONFIGURATION REGISTER

R/P-1	R/P-1	R/P-1	U-0	U-0	R/P-1	R/P-1	R/P-1
IESO	LPRCSEL	SOSCSRC	—	—	FNOSC2	FNOSC1	FNOSC0
bit 7							bit 0

### Legend:

R = Readable bit      P = Programmable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 7      **IESO:** Internal External Switchover bit  
             1 = Internal External Switchover mode is enabled (Two-Speed Start-up is enabled)  
             0 = Internal External Switchover mode is disabled (Two-Speed Start-up is disabled)
- bit 6      **LPRCSEL:** Internal LPRC Oscillator Power Select bit  
             1 = High-Power/High-Accuracy mode  
             0 = Low-Power/Low-Accuracy mode
- bit 5      **SOSCSRC:** Secondary Oscillator Clock Source Configuration bit  
             1 = SOSC analog crystal function is available on the SOSCI/SOSCO pins  
             0 = SOSC crystal is disabled; digital SCLKI function is selected on the SOSCO pin
- bit 4-3      **Unimplemented:** Read as '0'
- bit 2-0      **FNOSC<2:0>:** Oscillator Selection bits  
             000 = Fast RC Oscillator (FRC)  
             001 = Fast RC Oscillator with Divide-by-N with PLL module (FRCDIV+PLL)  
             010 = Primary Oscillator (XT, HS, EC)  
             011 = Primary Oscillator with PLL module (HS+PLL, EC+PLL)  
             100 = Secondary Oscillator (SOSC)  
             101 = Low-Power RC Oscillator (LPRC)  
             110 = 500 kHz Low-Power FRC Oscillator with Divide-by-N (LPFRCDIV)  
             111 = 8 MHz FRC Oscillator with Divide-by-N (FRCDIV)

# PIC24FV16KM204 FAMILY

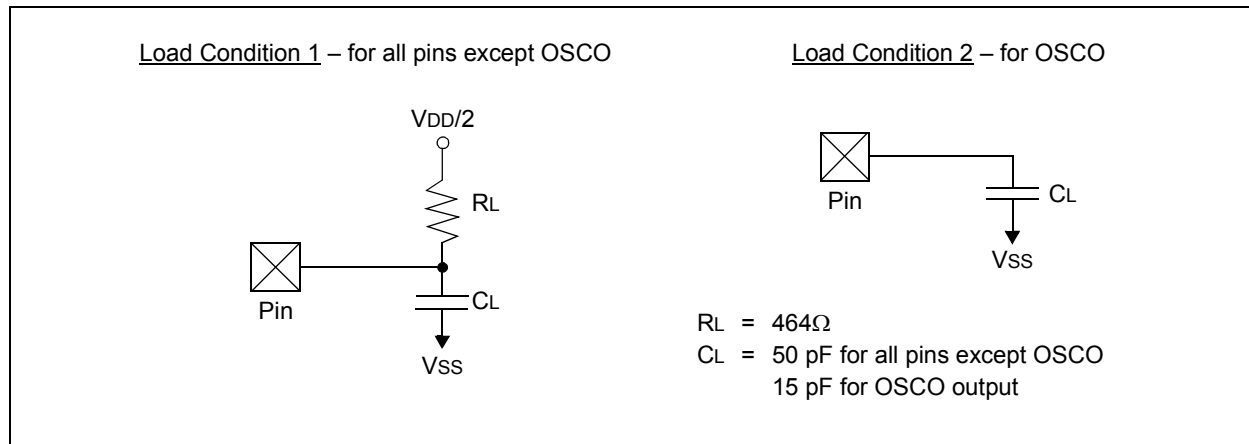
## 27.2 AC Characteristics and Timing Parameters

The information contained in this section defines the PIC24FV16KM204 family AC characteristics and timing parameters.

**TABLE 27-18: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

<b>AC CHARACTERISTICS</b>	<b>Standard Operating Conditions: 1.8V to 3.6V</b>	
	Operating temperature	-40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended
	Operating voltage VDD range as described in Section 27.1 “DC Characteristics”.	

**FIGURE 27-5: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



**TABLE 27-19: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO50	Cosc2	OSCO/CLKO Pin	—	—	15	pF	In XT and HS modes when External Clock is used to drive OSCI
DO56	CIO	All I/O Pins and OSCO	—	—	50	pF	EC mode
DO58	CB	SCLx, SDAx	—	—	400	pF	In I <sup>2</sup> C™ mode

**Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

# PIC24FV16KM204 FAMILY

**TABLE 27-21: PLL CLOCK TIMING SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
OS50	FPLLI	PLL Input Frequency Range	4	—	8	MHz	ECPLL, HSPLL modes, -40°C ≤ TA ≤ +85°C
OS51	FSYS	PLL Output Frequency Range	16	—	32	MHz	-40°C ≤ TA ≤ +85°C
OS52	TLOCK	PLL Start-up Time (Lock Time)	—	1	2	ms	
OS53	DCLK	CLKO Stability (Jitter)	-2	1	2	%	Measured over 100 ms period

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**TABLE 27-22: INTERNAL RC OSCILLATOR ACCURACY**

AC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
F20	FRC @ 8 MHz <sup>(1)</sup>	-2	—	+2	%	+25°C	3.0V ≤ VDD ≤ 3.6V, F device 3.2V ≤ VDD ≤ 5.5V, FV device
		-5	—	+5	%	-40°C ≤ TA ≤ +125°C	1.8V ≤ VDD ≤ 3.6V, F device 2.0V ≤ VDD ≤ 5.5V, FV device
F21	LPRC @ 31 kHz <sup>(2)</sup>	-15	—	+15	%	-40°C ≤ TA ≤ +125°C	1.8V ≤ VDD ≤ 3.6V, F device 2.0V ≤ VDD ≤ 5.5V, FV device

**Note 1:** The frequency is calibrated at +25°C and 3.3V. The OSCTUN bits can be used to compensate for temperature drift.

**2:** The change of LPRC frequency as VDD changes.

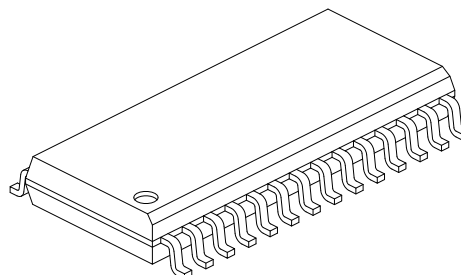
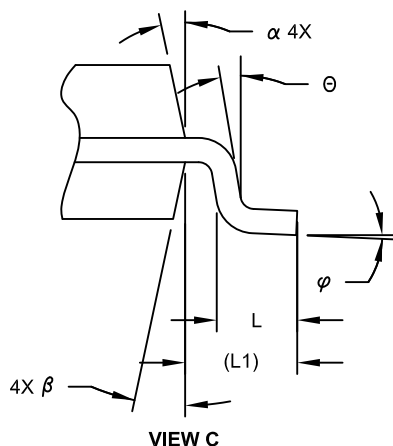
**TABLE 27-23: INTERNAL RC OSCILLATOR SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions
	TFRC	FRC Start-up Time	—	5	—	μs	
	TLPRC	LPRC Start-up Time	—	70	—	μs	

# PIC24FV16KM204 FAMILY

## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	1.27 BSC		
Overall Height	A	-	-	2.65
Molded Package Thickness	A2	2.05	-	-
Standoff §	A1	0.10	-	0.30
Overall Width	E	10.30 BSC		
Molded Package Width	E1	7.50 BSC		
Overall Length	D	17.90 BSC		
Chamfer (Optional)	h	0.25	-	0.75
Foot Length	L	0.40	-	1.27
Footprint	L1	1.40 REF		
Lead Angle	θ	0°	-	-
Foot Angle	φ	0°	-	8°
Lead Thickness	c	0.18	-	0.33
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

### Notes:

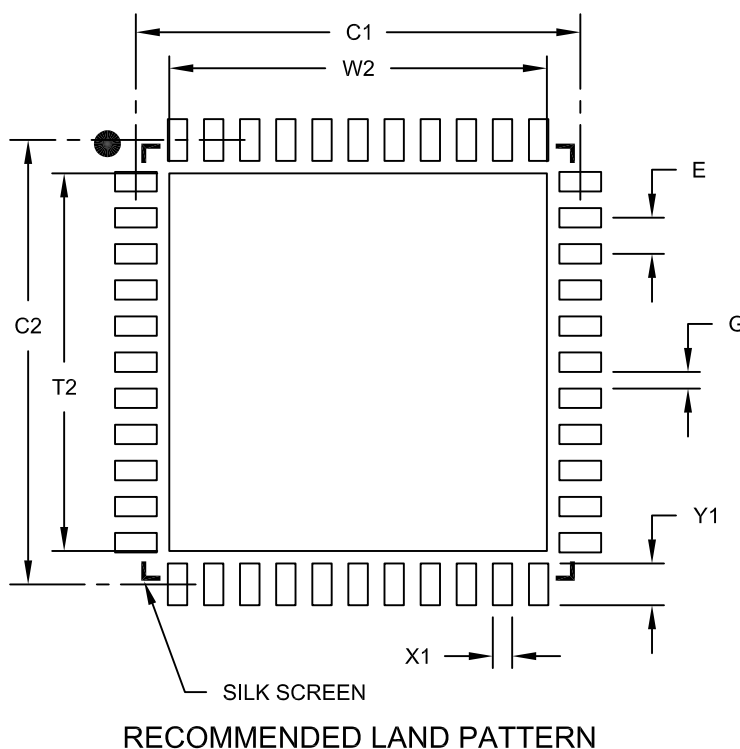
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.
- Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

# PIC24FV16KM204 FAMILY

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension	Limits	MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			6.60
Optional Center Pad Length	T2			6.60
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103B