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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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##### Details

Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	23
Program Memory Size	16KB (5.5K x 24)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5V
Data Converters	A/D 19x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fv16km102t-i-ss">https://www.e-xfl.com/product-detail/microchip-technology/pic24fv16km102t-i-ss</a>

# PIC24FV16KM204 FAMILY

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TABLE 1-2: DEVICE FEATURES FOR THE PIC24F16KM104 FAMILY

Features	PIC24F16KM104	PIC24F16KM102	PIC24F08KM102	PIC24F08KM101
Operating Frequency	DC-32 MHz			
Program Memory (bytes)	16K	16K	8K	8K
Program Memory (instructions)	5632	5632	2816	2816
Data Memory (bytes)		1024		
Data EEPROM Memory (bytes)		512		
Interrupt Sources (soft vectors/NMI traps)		25 (21/4)		
Voltage Range		1.8-3.6V		
I/O Ports	PORTA<11:0> PORTB<15:0> PORTC<9:0>	PORTA<7:0> PORTB<15:0>	PORTA<6:0> PORTB<15:12,9:7, 4,2:0>	
Total I/O Pins	38	24	18	
Timers	5 (One 16-bit timer, two MCCPs/SCCPs with up to two 16/32 timers each)			
Capture/Compare/PWM modules				
MCCP		1		
SCCP		1		
Serial Communications				
MSSP		1		
UART		1		
Input Change Notification Interrupt	37	23	17	
12-Bit Analog-to-Digital Module (input channels)	22	19	16	
Analog Comparators		1		
8-Bit Digital-to-Analog Converters		—		
Operational Amplifiers		—		
Charge Time Measurement Unit (CTMU)		Yes		
Real-Time Clock and Calendar (RTCC)		—		
Configurable Logic Cell (CLC)		1		
Resets (and delays)	POR, BOR, RESET Instruction, MCLR, WDT, Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (PWRT, OST, PLL Lock)			
Instruction Set	76 Base Instructions, Multiple Addressing Mode Variations			
Packages	44-Pin QFN/TQFP, 48-Pin UQFN	28-Pin SPDIP/SSOP/SOIC/QFN	20-Pin SOIC/SSOP/PDIP	

# PIC24FV16KM204 FAMILY

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TABLE 1-4: DEVICE FEATURES FOR THE PIC24FV16KM104 FAMILY

Features	PIC24FV16KM104	PIC24FV16KM102	PIC24FV08KM102	PIC24FV08KM101
Operating Frequency	DC-32 MHz			
Program Memory (bytes)	16K	16K	8K	8K
Program Memory (instructions)	5632	5632	2816	2816
Data Memory (bytes)		1024		
Data EEPROM Memory (bytes)		512		
Interrupt Sources (soft vectors/NMI traps)		25 (21/4)		
Voltage Range		2.0-5.5V		
I/O Ports	PORTA<11:7,5:0> PORTB<15:0> PORTC<9:0>	PORTA<7,5:0> PORTB<15:0>	PORTA<5:0> PORTB<15:12,9:7, 4,2:0>	
Total I/O Pins	37	23	17	
Timers	5 (One 16-bit timer, two MCCPs/SCCPs with up to two 16/32 timers each)			
Capture/Compare/PWM modules				
MCCP		1		
SCCP		1		
Serial Communications				
MSSP		1		
UART		1		
Input Change Notification Interrupt	36	22	16	
12-Bit Analog-to-Digital Module (input channels)	22	19	16	
Analog Comparators		1		
8-Bit Digital-to-Analog Converters		—		
Operational Amplifiers		—		
Charge Time Measurement Unit (CTMU)		Yes		
Real-Time Clock and Calendar (RTCC)		—		
Configurable Logic Cell (CLC)		1		
Resets (and delays)	POR, BOR, RESET Instruction, MCLR, WDT, Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (PWRT, OST, PLL Lock)			
Instruction Set	76 Base Instructions, Multiple Addressing Mode Variations			
Packages	44-Pin QFN/TQFP, 48-Pin UQFN	28-Pin SPDIP/SSOP/SOIC/QFN	20-Pin SOIC/SSOP/PDIP	



## 4.2 Data Address Space

The PIC24F core has a separate, 16-bit-wide data memory space, addressable as a single linear range. The Data Space is accessed using two Address Generation Units (AGUs), one each for read and write operations. The Data Space memory map is displayed in Figure 4-3.

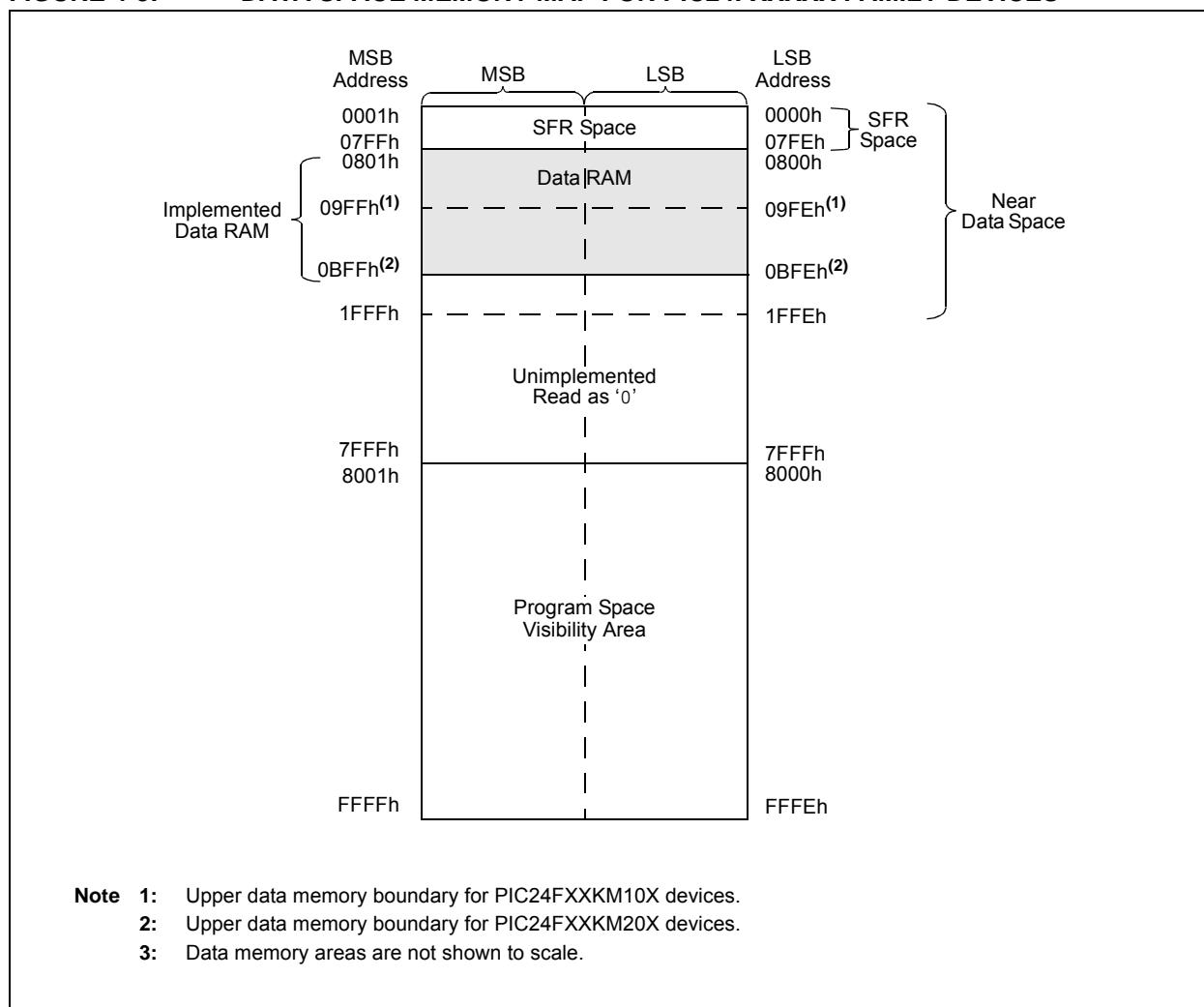
All Effective Addresses (EAs) in the data memory space are 16 bits wide and point to bytes within the Data Space. This gives a Data Space address range of 64 Kbytes or 32K words. The lower half of the data memory space (that is, when EA<15> = 0) is used for implemented memory addresses, while the upper half (EA<15> = 1) is reserved for the Program Space Visibility (PSV) area (see **Section 4.3.3 “Reading Data From Program Memory Using Program Space Visibility”**).

Depending on the particular device, PIC24FV16KM family devices implement either 512 or 1024 words of data memory. Should an EA point to a location outside of this area, an all zero word or byte will be returned.

### 4.2.1 DATA SPACE WIDTH

The data memory space is organized in byte-addressable, 16-bit-wide blocks. Data is aligned in data memory and registers as 16-bit words, but all the Data Space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

**FIGURE 4-3: DATA SPACE MEMORY MAP FOR PIC24FXXXX FAMILY DEVICES<sup>(3)</sup>**





# PIC24FV16KM204 FAMILY

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## REGISTER 8-2: CORCON: CPU CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/C-0, HSC	R/W-0	U-0	U-0
—	—	—	—	IPL3 <sup>(2)</sup>	PSV <sup>(1)</sup>	—	—
bit 7							bit 0

**Legend:**

C = Clearable bit

HSC = Hardware Settable/Clearable bit

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

 bit 15-4      **Unimplemented:** Read as '0'

 bit 3      **IPL3:** CPU Interrupt Priority Level Status bit<sup>(2)</sup>

1 = CPU Interrupt Priority Level is greater than 7

0 = CPU Interrupt Priority Level is 7 or less

 bit 1-0      **Unimplemented:** Read as '0'

**Note 1:** See Register 3-2 for the description of this bit, which is not dedicated to interrupt control functions.

**2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

**Note:** Bit 2 is described in **Section 3.0 “CPU”**.

# PIC24FV16KM204 FAMILY

## REGISTER 8-12: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0
NVMIE	—	AD1IE	U1TXIE	U1RXIE	—	—	CCT2IE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CCT1IE	CCP4IE	CCP3IE	—	T1IE	CCP2IE	CCP1IE	INT0IE
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **NVMIE:** NVM Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **AD1IE:** A/D Conversion Complete Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 12 **U1TXIE:** UART1 Transmitter Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 11 **U1RXIE:** UART1 Receiver Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 10-9 **Unimplemented:** Read as '0'
- bit 8 **CCT2IE:** Capture/Compare 2 Timer Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 7 **CCT1IE:** Capture/Compare 1 Timer Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 6 **CCP4IE:** Capture/Compare 4 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 5 **CCP3IE:** Capture/Compare 3 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **T1IE:** Timer1 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 2 **CCP2IE:** Capture/Compare 2 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 1 **CCP1IE:** Capture/Compare 1 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 0 **INT0IE:** External Interrupt 0 Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled

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## REGISTER 8-19: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T1IP2	T1IP1	T1IP0	—	CCP2IP2	CCP2IP1	CCP2IP0
bit 15						bit 8	

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CCP1IP2	CCP1IP1	CCP1IP0	—	INT0IP2	INT0IP1	INT0IP0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14-12    **T1IP<2:0>:** Timer1 Interrupt Priority bits  
111 = Interrupt is Priority 7 (highest priority interrupt)  
•  
•  
•  
001 = Interrupt is Priority 1  
000 = Interrupt source is disabled
- bit 11       **Unimplemented:** Read as '0'
- bit 10-8     **CCP2IP<2:0>:** Capture/Compare 2 Event Interrupt Priority bits  
111 = Interrupt is Priority 7 (highest priority interrupt)  
•  
•  
•  
001 = Interrupt is Priority 1  
000 = Interrupt source is disabled
- bit 7        **Unimplemented:** Read as '0'
- bit 6-4      **CCP1IP<2:0>:** Capture/Compare 1 Event Interrupt Priority bits  
111 = Interrupt is Priority 7 (highest priority interrupt)  
•  
•  
•  
001 = Interrupt is Priority 1  
000 = Interrupt source is disabled
- bit 3        **Unimplemented:** Read as '0'
- bit 2-0      **INT0IP<2:0>:** External Interrupt 0 Interrupt Priority bits  
111 = Interrupt is Priority 7 (highest priority interrupt)  
•  
•  
•  
001 = Interrupt is Priority 1  
000 = Interrupt source is disabled





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## REGISTER 22-1: CMxCON: COMPARATOR x CONTROL REGISTERS

R/W-0 CON	R/W-0 COE	R/W-0 CPOL	R/W-0 CLPWR	U-0	U-0	R/W-0 CEVT	R-0 COUT
bit 15						bit 8	
R/W-0 EVPOL1 <sup>(2)</sup>	R/W-0 EVPOLO <sup>(2)</sup>	U-0 —	R/W-0 CREF1	R/W-0 CREF0	U-0 —	R/W-0 CCH1	R/W-0 CCH0
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- |           |  |
|-----------|--|
| bit 15    | <b>CON:</b> Comparator x Enable bit<br>1 = Comparator is enabled<br>0 = Comparator is disabled   |
| bit 14    | <b>COE:</b> Comparator x Output Enable bit<br>1 = Comparator output is present on the CxOUT pin<br>0 = Comparator output is internal only  |
| bit 13    | <b>CPOL:</b> Comparator x Output Polarity Select bit<br>1 = Comparator output is inverted<br>0 = Comparator output is not inverted   |
| bit 12    | <b>CLPWR:</b> Comparator x Low-Power Mode Select bit<br>1 = Comparator operates in Low-Power mode<br>0 = Comparator does not operate in Low-Power mode   |
| bit 11-10 | <b>Unimplemented:</b> Read as '0'  |
| bit 9     | <b>CEVT:</b> Comparator x Event bit<br>1 = Comparator event, defined by EVPOL<1:0>, has occurred; subsequent Triggers and interrupts are disabled until the bit is cleared<br>0 = Comparator event has not occurred  |
| bit 8     | <b>COUT:</b> Comparator x Output bit<br><u>When CPOL = 0:</u><br>1 = VIN+ > VIN-<br>0 = VIN+ < VIN-<br><u>When CPOL = 1:</u><br>1 = VIN+ < VIN-<br>0 = VIN+ > VIN-   |
| bit 7-6   | <b>EVPOL&lt;1:0&gt;:</b> Trigger/Event/Interrupt Polarity Select bits <sup>(2)</sup><br>11 = Trigger/event/interrupt is generated on any change of the comparator output (while CEVT = 0)<br>10 = Trigger/event/interrupt is generated on the high-to-low transition of the comparator output<br>01 = Trigger/event/interrupt is generated on the low-to-high transition of the comparator output<br>00 = Trigger/event/interrupt generation is disabled |
| bit 5     | <b>Unimplemented:</b> Read as '0'  |
| bit 4-3   | <b>CREF&lt;1:0&gt;:</b> Comparator x Reference Select bits (non-inverting input)<br>11 = Non-inverting input connects to the DAC2 output<br>10 = Non-inverting input connects to the DAC1 output<br>01 = Non-inverting input connects to the internal CVREF voltage<br>00 = Non-inverting input connects to the CxINA pin  |

**Note 1:** BGBUF1 voltage is configured by BUFREF1<1:0> (BUFCON0<1:0>).

**2:** If the EVPOL<1:0> bits are set to a value other than '00', the first interrupt generated will occur on any transition of COUT. Subsequent interrupts will occur based on the EVPOLx bits setting.

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The WDT, prescaler and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSCx bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

If the WDT is enabled in hardware ( $\text{FWDTEN}_{<1:0>} = 11$ ), it will continue to run during Sleep or Idle modes. When the WDT time-out occurs, the device will wake and code execution will continue from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bit (RCON<3:2>) will need to be cleared in software after the device wakes up.

The WDT Flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

**Note:** The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

## 25.3.1 WINDOWED OPERATION

The Watchdog Timer has an optional Fixed Window mode of operation. In this Windowed mode, CLRWDT instructions can only reset the WDT during the last 1/4 of the programmed WDT period. A CLRWDT instruction executed before that window causes a WDT Reset, similar to a WDT time-out.

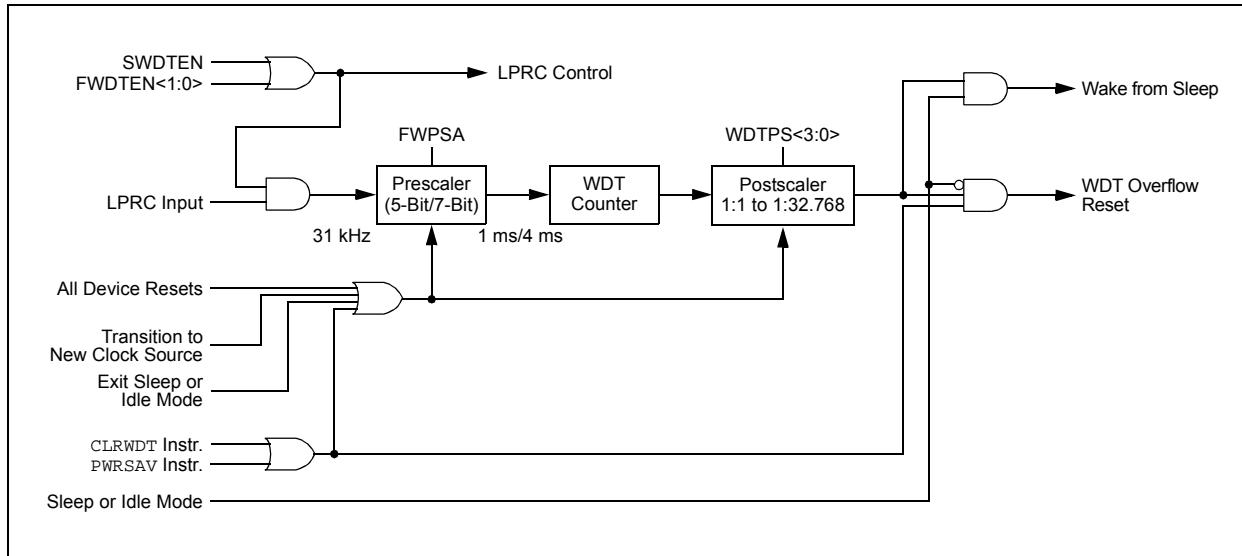
Windowed WDT mode is enabled by programming the Configuration bit, WINDIS (FWDT<6>), to '0'.

## 25.3.2 CONTROL REGISTER

The WDT is enabled or disabled by the FWDTEN<1:0> Configuration bits. When both of the FWDTEN<1:0> Configuration bits are set, the WDT is always enabled.

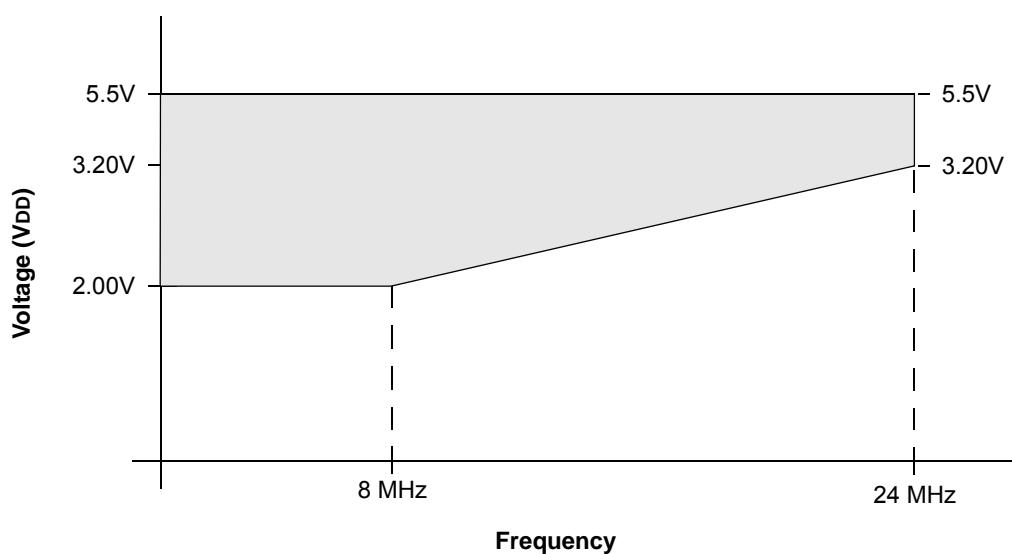
The WDT can be optionally controlled in software when the FWDTEN<1:0> Configuration bits have been programmed to '10'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user to enable the WDT for critical code segments, and disable the WDT during non-critical segments, for maximum power savings. When the FWDTEN<1:0> bits are set to '01', the WDT is only enabled in Run and Idle modes, and is disabled in Sleep. Software control of the SWDTEN bit (RCON<5>) is disabled with this setting.

**FIGURE 25-2: WDT BLOCK DIAGRAM**



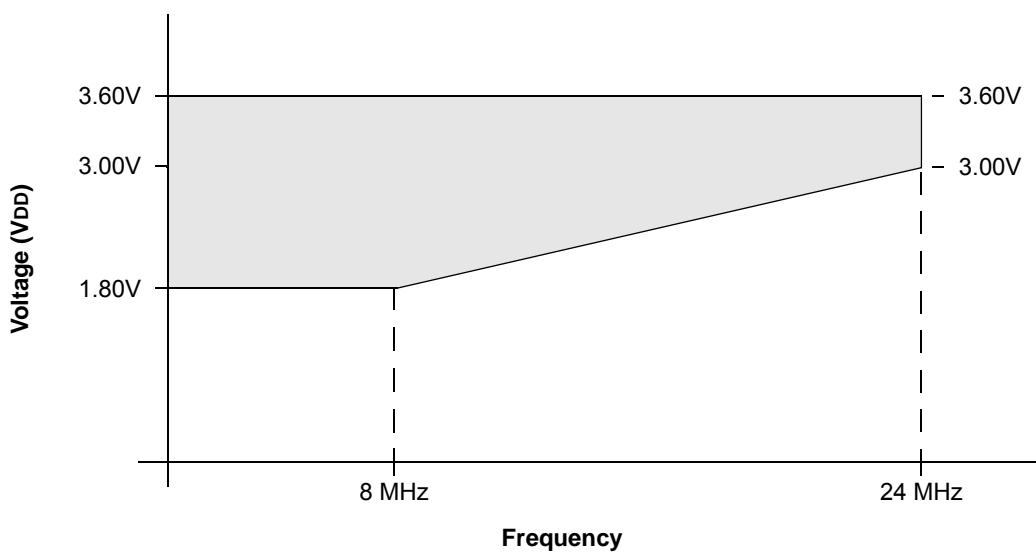
# PIC24FV16KM204 FAMILY

FIGURE 27-3: PIC24FV16KM204 FAMILY VOLTAGE-FREQUENCY GRAPH (EXTENDED)



Note: For frequencies between 8 MHz and 24 MHz,  $F_{MAX} = 13.33 \text{ MHz} * (V_{DD} - 2.0) + 8 \text{ MHz}$ .

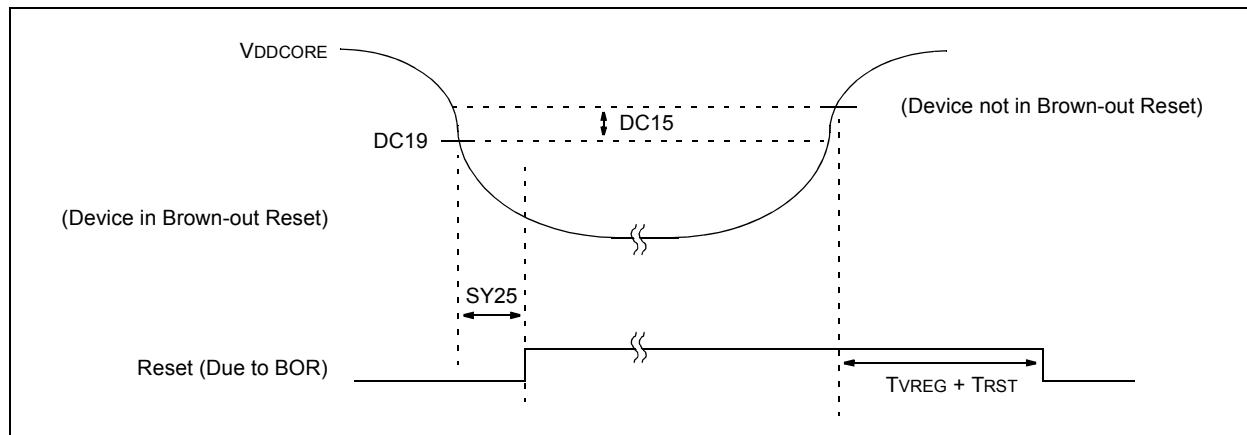
FIGURE 27-4: PIC24F16KM204 FAMILY VOLTAGE-FREQUENCY GRAPH (EXTENDED)



Note: For frequencies between 8 MHz and 24 MHz,  $F_{MAX} = 13.33 \text{ MHz} * (V_{DD} - 1.8) + 8 \text{ MHz}$ .

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**FIGURE 27-9: BROWN-OUT RESET CHARACTERISTICS**



**TABLE 27-25: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER AND BROWN-OUT RESET TIMING REQUIREMENTS**

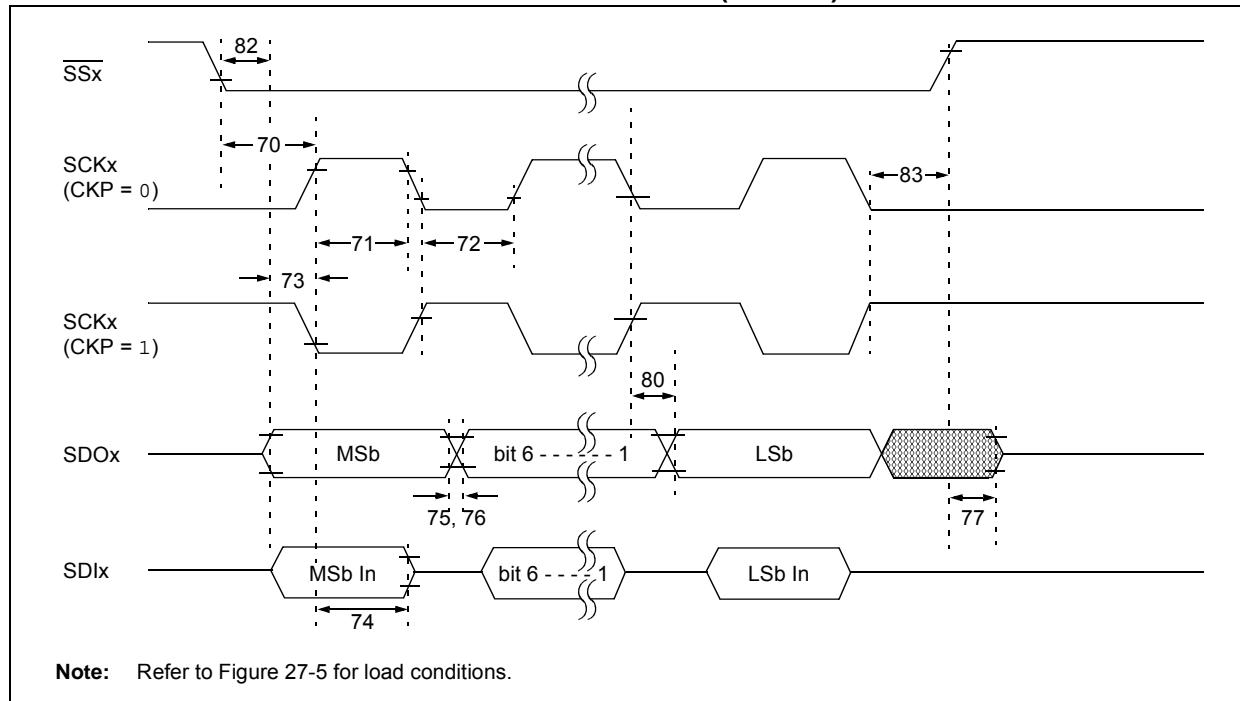
AC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204)				
Param No.	Symbol	Characteristic	Min.	Typ <sup>(1)</sup>	Max.	Units	Conditions
SY10	TmCL	MCLR Pulse Width (low)	2	—	—	μs	
SY11	TPWRT	Power-up Timer Period	50	64	90	ms	
SY12	TPOR	Power-on Reset Delay	1	5	10	μs	
SY13	TIOZ	I/O High-Impedance from MCLR Low or Watchdog Timer Reset	—	—	100	ns	
SY20	TWDT	Watchdog Timer Time-out Period	0.85	1.0	1.15	ms	1.32 prescaler
			3.4	4.0	4.6	ms	1:128 prescaler
SY25	TBOR	Brown-out Reset Pulse Width	1	—	—	μs	
SY35	TFSCM	Fail-Safe Clock Monitor Delay	—	2.0	2.3	μs	
SY45	TRST	Internal State Reset Time	—	5	—	μs	
SY50	TVREG	On-Chip Voltage Regulator Output Delay	—	10	—	μs	(Note 2)
SY55	TLOCK	PLL Start-up Time	—	100	—	μs	
SY65	TOST	Oscillator Start-up Time	—	1024	—	TOSC	
SY71	TPM	Program Memory Wake-up Time	—	1	—	μs	Sleep wake-up with PMSLP = 0
SY72	TLVR	Low-Voltage Regulator Wake-up Time	—	250	—	μs	

**Note 1:** Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.

**2:** This applies to PIC24FV16KMXXX devices only.

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**FIGURE 27-14: EXAMPLE SPI SLAVE MODE TIMING (CKE = 1)**



**TABLE 27-32: EXAMPLE SPI SLAVE MODE REQUIREMENTS (CKE = 1)**

Param No.	Symbol	Characteristic	Min	Max	Units	Conditions
70	TssL2scH, TssL2scl	SSx $\downarrow$ to SCKx $\downarrow$ or SCKx $\uparrow$ Input	3 TCY	—	ns	
70A	TssL2WB	SSx to Write to SSPxBUF	3 TCY	—	ns	
71	TsCH	SCKx Input High Time (Slave mode)	Continuous	1.25 TCY + 30	—	ns
71A			Single Byte	40	—	ns (Note 1)
72	TsCL	SCKx Input Low Time (Slave mode)	Continuous	1.25 TCY + 30	—	ns
72A			Single Byte	40	—	ns (Note 1)
73A	Tb2B	Last Clock Edge of Byte 1 to the First Clock Edge of Byte 2	1.5 TCY + 40	—	ns	(Note 2)
74	Tsch2dil, Tscl2dil	Hold Time of SDIx Data Input to SCKx Edge	40	—	ns	
75	TdoR	SDOx Data Output Rise Time	—	25	ns	
76	TdoF	SDOx Data Output Fall Time	—	25	ns	
77	Tssh2doz	SSx $\uparrow$ to SDOx Output High-Impedance	10	50	ns	
80	Tsch2dov, Tscl2dov	SDOx Data Output Valid After SCKx Edge	—	50	ns	
82	Tssl2dov	SDOx Data Output Valid After SSx $\downarrow$ Edge	—	50	ns	
83	Tsch2ssh, Tscl2ssh	SSx $\uparrow$ After SCKx Edge	1.5 TCY + 40	—	ns	
	Fck	SCKx Frequency	—	10	MHz	

**Note 1:** Requires the use of Parameter 73A.

**2:** Only if Parameters 71A and 72A are used.

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TABLE 27-39: 8-BIT DIGITAL-TO-ANALOG CONVERTER SPECIFICATIONS

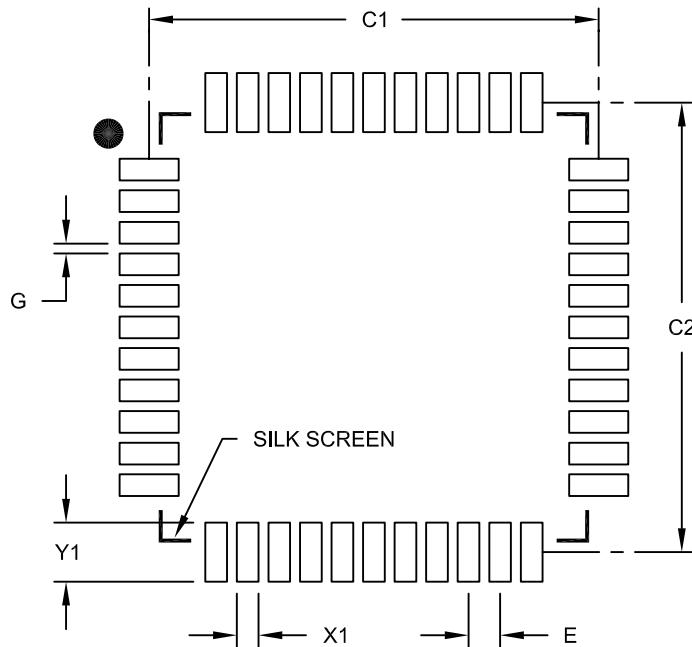
AC CHARACTERISTICS			Standard Operating Conditions: 1.8V to 3.6V (PIC24F16KM204) 2.0V to 5.5V (PIC24FV16KM204)				
Operating temperature			-40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min.	Typ	Max.	Units	Comments
		Resolution	8	—	—	bits	
		DACREF<1:0> Input Voltage Range	AVss + 1.8	—	AVDD	V	
		Differential Linearity Error (DNL)	—	—	±0.5	LSb	
		Integral Linearity Error (INL)	—	—	±1.5	LSb	
		Offset Error	—	—	±0.5	LSb	
		Gain Error	—	—	±3.0	LSb	
		Monotonicity	—	—	—	—	(Note 1)
		Output Voltage Range	AVss + 50	AVss + 5 to AVDD – 5	AVDD – 50	mV	0.5V input overdrive, no output loading
		Slew Rate	—	5	—	V/μs	
		Settling Time	—	10	—	μs	

Note 1: DAC output voltage never decreases with an increase in the data code.

# PIC24FV16KM204 FAMILY

44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch		0.80 BSC		
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B



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