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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	21
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 12x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep16gs202-i-so

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REGISTER 3-2: CORCON: CORE CONTROL REGISTER (CONTINUED)

- bit 2 **SFA:** Stack Frame Active Status bit
 1 = Stack frame is active; W14 and W15 address of 0x0000 to 0xFFFF, regardless of DSRPAG
 0 = Stack frame is not active; W14 and W15 address of Base Data Space
- bit 1 **RND:** Rounding Mode Select bit
 1 = Biased (conventional) rounding is enabled
 0 = Unbiased (convergent) rounding is enabled
- bit 0 **IF:** Integer or Fractional Multiplier Mode Select bit
 1 = Integer mode is enabled for DSP multiply
 0 = Fractional mode is enabled for DSP multiply

- Note 1:** This bit is always read as '0'.
- 2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

REGISTER 3-3: CTXTSTAT: CPU W REGISTER CONTEXT STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
—	—	—	—	—	CCTXI2	CCTXI1	CCTXI0
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
—	—	—	—	—	MCTXI2	MCTXI1	MCTXI0
bit 7						bit 0	

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

- bit 15-11 **Unimplemented:** Read as '0'
- bit 10-8 **CCTXI<2:0>:** Current (W Register) Context Identifier bits
 111 = Reserved
 •
 •
 •
 011 = Reserved
 010 = Alternate Working Register Set 2 is currently in use
 001 = Alternate Working Register Set 1 is currently in use
 000 = Default register set is currently in use
- bit 7-3 **Unimplemented:** Read as '0'
- bit 2-0 **MCTXI<2:0>:** Manual (W Register) Context Identifier bits
 111 = Reserved
 •
 •
 •
 011 = Reserved
 010 = Alternate Working Register Set 2 was most recently manually selected
 001 = Alternate Working Register Set 1 was most recently manually selected
 000 = Default register set was most recently manually selected

TABLE 4-17: NVM REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0728	WR	WREN	WRERR	NVMSIDL	—	—	RPDF	URERR	—	—	—	—	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000
NVMADR	072A	NVMADR<15:0>																0000
NVMADRU	072C	—	—	—	—	—	—	—	—	—	—	—	—	NVMADR<23:16>				0000
NVMKEY	072E	—	—	—	—	—	—	—	—	—	—	—	NVMKEY<7:0>					0000
NVMSRCADR	0730	NVMSRCADR<15:0>																0000
NVMSRCADRH	0732	—	—	—	—	—	—	—	—	—	—	—	NVMSRCADR<23:16>					0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-18: SYSTEM CONTROL REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
RCON	0740	TRAPR	IOPUWR	—	—	VREGSF	—	CM	VREGS	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	Note 1	
OSCCON	0742	—	COSC2	COSC1	COSC0	—	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	—	CF	—	—	OSWEN	Note 2	
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	FRCDIV2	FRCDIV1	FRCDIV0	PLLPOST1	PLLPOST0	—	PLLPRE4	PLLPRE3	PLLPRE2	PLLPRE1	PLLPRE0	3040	
PLLFBD	0746	—	—	—	—	—	—	—	PLLDIV<8:0>								0030		
OSCTUN	0748	—	—	—	—	—	—	—	—	—	—	TUN<5:0>						0000	
LFSR	074C	—	LFSR<14:0>																0000
ACLKCON	0750	ENAPLL	APLLCK	SELACLK	—	—	APSTSCLR2	APSTSCLR1	APSTSCLR0	ASRCSEL	FRCSEL	—	—	—	—	—	—	2740	

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: RCON register Reset values are dependent on the type of Reset.

2: OSCCON register Reset values are dependent on the Configuration fuses.

TABLE 4-19: PMD REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0760	—	—	T3MD	T2MD	T1MD	—	PWMMD	—	I2C1MD	—	U1MD	—	SPI1MD	—	—	ADCMD	0000
PMD2	0762	—	—	—	—	—	—	—	IC1MD	—	—	—	—	—	—	—	OC1MD	0000
PMD3	0764	—	—	—	—	—	CMPMD	—	—	—	—	—	—	—	—	—	—	0000
PMD6	076A	—	—	—	—	—	PWM3MD	PWM2MD	PWM1MD	—	—	—	—	—	—	—	—	0000
PMD7	076C	—	—	—	—	—	—	CMP2MD	CMP1MD	—	—	—	—	—	—	PGA1MD	—	0000
PMD8	076E	—	—	—	—	—	PGA2MD	—	—	—	—	—	—	—	—	—	—	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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REGISTER 5-5: NVMSRCADRL: NVM SOURCE DATA ADDRESS LOW REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15-0 **NVMSRCADR<15:0>**: Source Data Address bits
 The RAM address of the data to be programmed into Flash when the NVMOP<3:0> bits are set to row programming.

REGISTER 5-6: NVMSRCADRH: NVM SOURCE DATA ADDRESS HIGH REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<31:24>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<23:16>							
bit 7				bit 0			

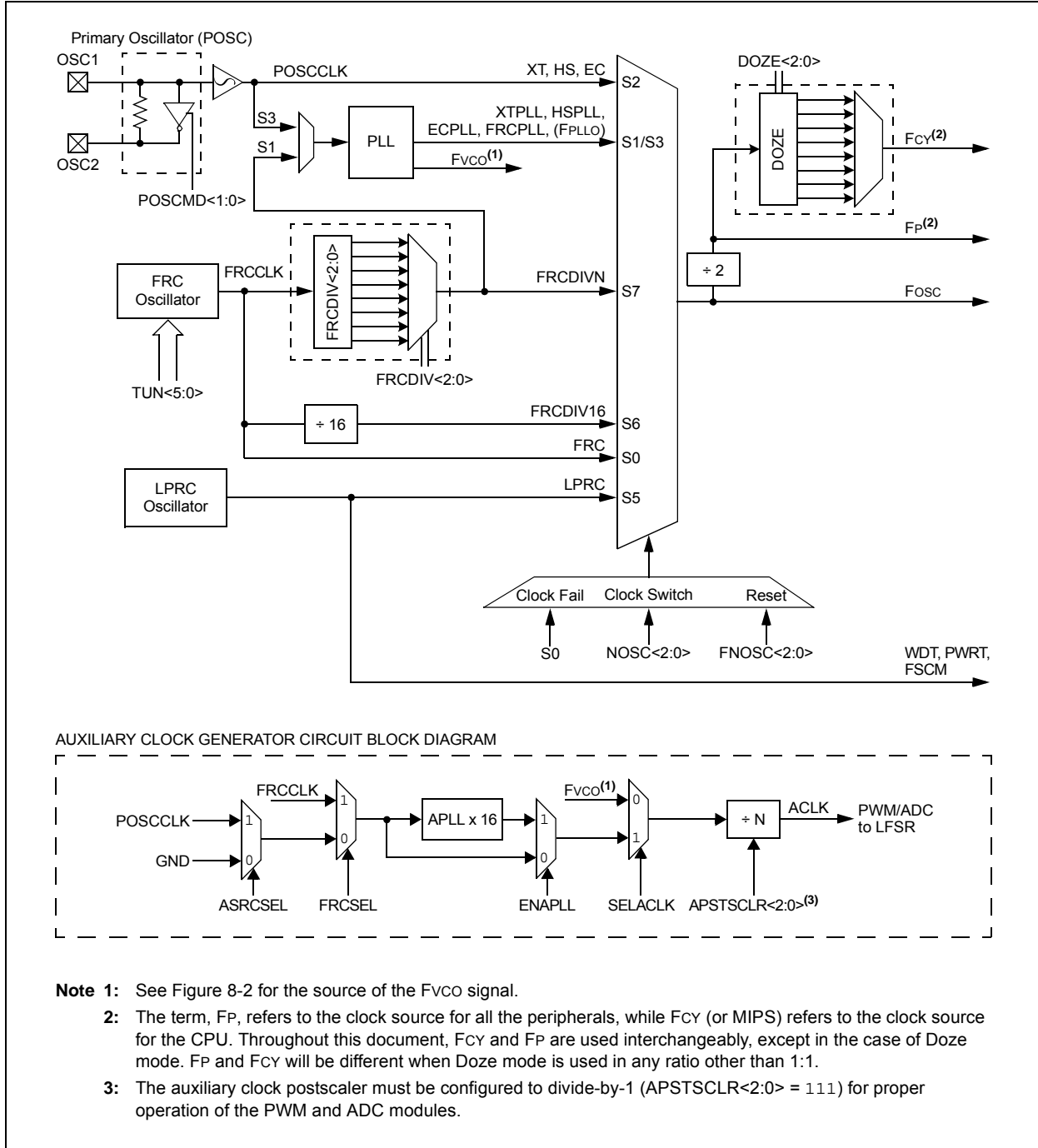
Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15-0 **NVMSRCADR<31:16>**: Source Data Address bits
 The RAM address of the data to be programmed into Flash when the NVMOP<3:0> bits are set to row programming. These bits must be always programmed to zero.

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FIGURE 8-1: OSCILLATOR SYSTEM DIAGRAM



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REGISTER 8-2: CLKDIV: CLOCK DIVISOR REGISTER (CONTINUED)

bit 4-0 **PLLPRE<4:0>**: PLL Phase Detector Input Divider Select bits (also denoted as 'N1', PLL prescaler)
 11111 = Input divided by 33
 •
 •
 •
 00001 = Input divided by 3
 00000 = Input divided by 2 (default)

- Note 1:** The DOZE<2:0> bits can only be written to when the DOZEN bit is clear. If DOZEN = 1, any writes to DOZE<2:0> are ignored.
2: This bit is cleared when the ROI bit is set and an interrupt occurs.
3: The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

REGISTER 8-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PLLDIV8
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
PLLDIV<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'
 bit 8-0 **PLLDIV<8:0>**: PLL Feedback Divisor bits (also denoted as 'M', PLL multiplier)
 111111111 = 513
 •
 •
 •
 000110000 = 50 (default)
 •
 •
 •
 000000010 = 4
 000000001 = 3
 000000000 = 2

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TABLE 10-1: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)

Input Name ⁽¹⁾	Function Name	Register	Configuration Bits
External Interrupt 1	INT1	RPINR0	INT1R<7:0>
External Interrupt 2	INT2	RPINR1	INT2R<7:0>
Timer1 External Clock	T1CK	RPINR2	T1CKR<7:0>
Timer2 External Clock	T2CK	RPINR3	T2CKR<7:0>
Timer3 External Clock	T3CK	RPINR3	T3CKR<7:0>
Input Capture 1	IC1	RPINR7	IC1R<7:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<7:0>
PWM Fault 1	FLT1	RPINR12	FLT1R<7:0>
PWM Fault 2	FLT2	RPINR12	FLT2R<7:0>
PWM Fault 3	FLT3	RPINR13	FLT3R<7:0>
PWM Fault 4	FLT4	RPINR13	FLT4R<7:0>
UART1 Receive	U1RX	RPINR18	U1RXR<7:0>
UART1 Clear-to-Send	$\overline{U1CTS}$	RPINR18	U1CTSR<7:0>
SPI1 Data Input	SDI1	RPINR20	SDI1R<7:0>
SPI1 Clock Input	SCK1	RPINR20	SCK1R<7:0>
SPI1 Slave Select	$\overline{SS1}$	RPINR21	SS1R<7:0>
PWM Synchronous Input 1	SYNCI1	RPINR37	SYNCI1R<7:0>
PWM Synchronous Input 2	SYNCI2	RPINR38	SYNCI2R<7:0>
PWM Fault 5	FLT5	RPINR42	FLT5R<7:0>
PWM Fault 6	FLT6	RPINR42	FLT6R<7:0>
PWM Fault 7	FLT7	RPINR43	FLT7R<7:0>
PWM Fault 8	FLT8	RPINR43	FLT8R<7:0>

Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger input buffers.

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REGISTER 10-16: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP33R5	RP33R4	RP33R3	RP33R2	RP33R1	RP33R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP32R5	RP32R4	RP32R3	RP32R2	RP32R1	RP32R0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP33R<5:0>:** Peripheral Output Function is Assigned to RP33 Output Pin bits
 (see Table 10-2 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP32R<5:0>:** Peripheral Output Function is Assigned to RP32 Output Pin bits
 (see Table 10-2 for peripheral function numbers)

REGISTER 10-17: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP35R5	RP35R4	RP35R3	RP35R2	RP35R1	RP35R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP34R5	RP34R4	RP34R3	RP34R2	RP34R1	RP34R0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP35R<5:0>:** Peripheral Output Function is Assigned to RP35 Output Pin bits
 (see Table 10-2 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP34R<5:0>:** Peripheral Output Function is Assigned to RP34 Output Pin bits
 (see Table 10-2 for peripheral function numbers)

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REGISTER 15-10: MDC: PWM MASTER DUTY CYCLE REGISTER^(1,2)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
MDC<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
MDC<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

bit 15-0 **MDC<15:0>**: Master PWM Duty Cycle Value bits

- Note 1:** The smallest pulse width that can be generated on the PWMx output corresponds to a value of 0x0008, while the maximum pulse width generated corresponds to a value of Period – 0x0008.
- 2:** As the duty cycle gets closer to 0% or 100% of the PWM period (0 to 40 ns, depending on the mode of operation), PWM duty cycle resolution will increase from 1 to 3 LSBs.

REGISTER 15-11: PWMKEY: PWM PROTECTION LOCK/UNLOCK KEY REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PWMKEY<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PWMKEY<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

bit 15-0 **PWMKEY<15:0>**: PWM Protection Lock/Unlock Key Value bits

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REGISTER 15-22: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER (CONTINUED)

- bit 7-3 **FLTSRC<4:0>**: Fault Control Signal Source Select for PWMx Generator # bits
- 11111 = Reserved
 - 10001 = Reserved
 - 10000 = Reserved
 - 01111 = Reserved
 - 01110 = Analog Comparator 2
 - 01101 = Analog Comparator 1
 - 01100 = Reserved
 - 01011 = Reserved
 - 01010 = Reserved
 - 01001 = Reserved
 - 01000 = Fault 8
 - 00111 = Fault 7
 - 00110 = Fault 6
 - 00101 = Fault 5
 - 00100 = Fault 4
 - 00011 = Fault 3
 - 00010 = Fault 2
 - 00001 = Fault 1
 - 00000 = Reserved
- bit 2 **FLTPOL**: Fault Polarity for PWMx Generator # bit⁽¹⁾
- 1 = The selected Fault source is active-low
 - 0 = The selected Fault source is active-high
- bit 1-0 **FLTMOD<1:0>**: Fault Mode for PWMx Generator # bits
- 11 = Fault input is disabled
 - 10 = Reserved
 - 01 = The selected Fault source forces the PWMxH, PWMxL pins to the FLTDATx values (cycle)
 - 00 = The selected Fault source forces the PWMxH, PWMxL pins to the FLTDATx values (latched condition)

Note 1: These bits should be changed only when PTEN (PTCON<15>) = 0.

REGISTER 15-23: STRIGx: PWMx SECONDARY TRIGGER COMPARE VALUE REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STRGCMP<12:5>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
STRGCMP<4:0>					—	—	—
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

- bit 15-3 **STRGCMP<12:0>**: Secondary Trigger Compare Value bits
- When the secondary PWMx functions in the local time base, this register contains the compare values that can trigger the ADC module.

bit 2-0 **Unimplemented:** Read as '0'

Note 1: STRIGx cannot generate the PWMx trigger interrupts.

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REGISTER 16-3: SPI1CON2: SPI CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
FRMEN	SPIFSD	FRMPOL	—	—	—	—	—
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	FRMDLY	SPIBEN
bit 7						bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15 **FRMEN:** Framed SPI1 Support bit
 1 = Framed SPI1 support is enabled ($\overline{SS1}$ pin is used as frame sync pulse input/output)
 0 = Framed SPI1 support is disabled
- bit 14 **SPIFSD:** Frame Sync Pulse Direction Control bit
 1 = Frame sync pulse input (slave)
 0 = Frame sync pulse output (master)
- bit 13 **FRMPOL:** Frame Sync Pulse Polarity bit
 1 = Frame sync pulse is active-high
 0 = Frame sync pulse is active-low
- bit 12-2 **Unimplemented:** Read as '0'
- bit 1 **FRMDLY:** Frame Sync Pulse Edge Select bit
 1 = Frame sync pulse coincides with first bit clock
 0 = Frame sync pulse precedes first bit clock
- bit 0 **SPIBEN:** Enhanced Buffer Enable bit
 1 = Enhanced buffer is enabled
 0 = Enhanced buffer is disabled (Standard mode)

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18.3 UART Control Registers

REGISTER 18-1: U1MODE: UART1 MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾	—	USIDL	IREN ⁽²⁾	RTSMD	—	UEN1	UEN0
bit 15							bit 8

R/W-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7							bit 0

Legend:	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	U = Unimplemented bit, read as '0'
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15 **UARTEN:** UART1 Enable bit⁽¹⁾
 1 = UART1 is enabled; all UART1 pins are controlled by UART1, as defined by UEN<1:0>
 0 = UART1 is disabled; all UART1 pins are controlled by PORT latches; UART1 power consumption is minimal
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **USIDL:** UART1 Stop in Idle Mode bit
 1 = Discontinues module operation when device enters Idle mode
 0 = Continues module operation in Idle mode
- bit 12 **IREN:** IrDA[®] Encoder and Decoder Enable bit⁽²⁾
 1 = IrDA encoder and decoder are enabled
 0 = IrDA encoder and decoder are disabled
- bit 11 **RTSMD:** Mode Selection for $\overline{U1RTS}$ Pin bit
 1 = $\overline{U1RTS}$ pin is in Simplex mode
 0 = $\overline{U1RTS}$ pin is in Flow Control mode
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **UEN<1:0>:** UART1 Pin Enable bits
 11 = U1TX, U1RX and BCLK1 pins are enabled and used; $\overline{U1CTS}$ pin is controlled by PORT latches
 10 = U1TX, U1RX, $\overline{U1CTS}$ and $\overline{U1RTS}$ pins are enabled and used
 01 = U1TX, U1RX and $\overline{U1RTS}$ pins are enabled and used; $\overline{U1CTS}$ pin is controlled by PORT latches
 00 = U1TX and U1RX pins are enabled and used; $\overline{U1CTS}$ and $\overline{U1RTS}$ /BCLK1 pins are controlled by PORT latches
- bit 7 **WAKE:** Wake-up on Start bit Detect During Sleep Mode Enable bit
 1 = UART1 continues to sample the U1RX pin, interrupt is generated on the falling edge; bit is cleared in hardware on the following rising edge
 0 = No wake-up is enabled
- bit 6 **LPBACK:** UART1 Loopback Mode Select bit
 1 = Enables Loopback mode
 0 = Loopback mode is disabled
- bit 5 **ABAUD:** Auto-Baud Enable bit
 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h) before other data; cleared in hardware upon completion
 0 = Baud rate measurement is disabled or completed

- Note 1:** Refer to “**Universal Asynchronous Receiver Transmitter (UART)**” (DS70000582) in the “*dsPIC33/PIC24 Family Reference Manual*” for information on enabling the UART1 module for receive or transmit operation.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).

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REGISTER 19-9: ADCON5L: ADC CONTROL REGISTER 5 LOW

R-0, HC, HS	U-0	U-0	U-0	U-0	U-0	R-0, HC, HS	R-0, HC, HS
SHRRDY	—	—	—	—	—	C1RDY	C0RDY
bit 15						bit 8	

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
SHRPWR	—	—	—	—	—	C1PWR	C0PWR
bit 7						bit 0	

Legend:	HS = Hardware Settable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

- bit 15 **SHRRDY:** Shared ADC Core Ready Flag bit
1 = ADC core is powered and ready for operation
0 = ADC core is not ready for operation
- bit 14-10 **Unimplemented:** Read as '0'
- bit 9-8 **C1RDY:C0RDY:** Dedicated ADC Core x Ready Flag bits
1 = ADC Core x is powered and ready for operation
0 = ADC Core x is not ready for operation
- bit 7 **SHRPWR:** Shared ADC Core x Power Enable bit
1 = ADC Core x is powered
0 = ADC Core x is off
- bit 6-2 **Unimplemented:** Read as '0'
- bit 1-0 **C1PWR:C0PWR:** Dedicated ADC Core x Power Enable bits
1 = ADC Core x is powered
0 = ADC Core x is off

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REGISTER 19-22: ADCAL0L: ADC CALIBRATION REGISTER 0 LOW

R-0, HC, HS	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CAL1RDY	—	—	—	CAL1SKIP	CAL1DIFF	CAL1EN	CAL1RUN
bit 15							bit 8

R-0, HC, HS	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CAL0RDY	—	—	—	CAL0SKIP	CAL0DIFF	CAL0EN	CAL0RUN
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **CAL1RDY:** Dedicated ADC Core 1 Calibration Status Flag bit
 1 = Dedicated ADC Core 1 calibration is finished
 0 = Dedicated ADC Core 1 calibration is in progress
- bit 14-12 **Unimplemented:** Read as '0'
- bit 11 **CAL1SKIP:** Dedicated ADC Core 1 Calibration Bypass bit
 1 = After power-up, the dedicated ADC Core 1 will not be calibrated
 0 = After power-up, the dedicated ADC Core 1 will be calibrated
- bit 10 **CAL1DIFF:** Dedicated ADC Core 1 Pseudo-Differential Input Mode Calibration bit
 1 = Dedicated ADC Core 1 will be calibrated in Pseudo-Differential Input mode
 0 = Dedicated ADC Core 1 will be calibrated in Single-Ended Input mode
- bit 9 **CAL1EN:** Dedicated ADC Core 1 Calibration Enable bit
 1 = Dedicated ADC Core 1 calibration bits (CALxRDY, CALxSKIP, CALxDIFF and CALxRUN) can be accessed by software
 0 = Dedicated ADC Core 1 calibration bits are disabled
- bit 8 **CAL1RUN:** Dedicated ADC Core 1 Calibration Start bit
 1 = If this bit is set by software, the dedicated ADC Core 1 calibration cycle is started; this bit is automatically cleared by hardware
 0 = Software can start the next calibration cycle
- bit 7 **CAL0RDY:** Dedicated ADC Core 0 Calibration Status Flag bit
 1 = Dedicated ADC Core 0 calibration is finished
 0 = Dedicated ADC Core 0 calibration is in progress
- bit 6-4 **Unimplemented:** Read as '0'
- bit 3 **CAL0SKIP:** Dedicated ADC Core 0 Calibration Bypass bit
 1 = After power-up, the dedicated ADC Core 0 will not be calibrated
 0 = After power-up, the dedicated ADC Core 0 will be calibrated
- bit 2 **CAL0DIFF:** Dedicated ADC Core 0 Pseudo-Differential Input Mode Calibration bit
 1 = Dedicated ADC Core 0 will be calibrated in Pseudo-Differential Input mode
 0 = Dedicated ADC Core 0 will be calibrated in Single-Ended Input mode
- bit 1 **CAL0EN:** Dedicated ADC Core 0 Calibration Enable bit
 1 = Dedicated ADC Core 0 calibration bits (CALxRDY, CALxSKIP, CALxDIFF and CALxRUN) can be accessed by software
 0 = Dedicated ADC Core 0 calibration bits are disabled
- bit 0 **CAL0RUN:** Dedicated ADC Core 0 Calibration Start bit
 1 = If this bit is set by software, the dedicated ADC Core 0 calibration cycle is started; this bit is automatically cleared by hardware
 0 = Software can start the next calibration cycle

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24.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers (MCU) and dsPIC[®] digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
 - MPLAB[®] X IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB XC Compiler
 - MPASM[™] Assembler
 - MPLINK[™] Object Linker/
MPLIB[™] Object Librarian
 - MPLAB Assembler/Linker/Librarian for
Various Device Families
- Simulators
 - MPLAB X SIM Software Simulator
- Emulators
 - MPLAB REAL ICE[™] In-Circuit Emulator
- In-Circuit Debuggers/Programmers
 - MPLAB ICD 3
 - PICKit[™] 3
- Device Programmers
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,
Evaluation Kits and Starter Kits
- Third-party development tools

24.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows[®], Linux and Mac OS[®] X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

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TABLE 25-18: PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions
OS50	FPLLI	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range	0.8	—	8.0	MHz	ECPLL, XTPLL modes
OS51	FVCO	On-Chip VCO System Frequency	120	—	340	MHz	
OS52	TLOCK	PLL Start-up Time (Lock Time)	0.9	1.5	3.1	ms	
OS53	DCLK	CLKO Stability (Jitter) ⁽²⁾	-3	0.5	3	%	

Note 1: Data in “Typ.” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested in manufacturing.

2: This jitter specification is based on clock cycle-by-clock cycle measurements. To get the effective jitter for individual time bases, or communication clocks used by the application, use the following formula:

$$Effective\ Jitter = \frac{DCLK}{\sqrt{\frac{FOSC}{Time\ Base\ or\ Communication\ Clock}}}$$

For example, if Fosc = 120 MHz and the SPI1 Bit Rate = 10 MHz, the effective jitter is as follows:

$$Effective\ Jitter = \frac{DCLK}{\sqrt{\frac{120}{10}}} = \frac{DCLK}{\sqrt{12}} = \frac{DCLK}{3.464}$$

TABLE 25-19: AUXILIARY PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ. ⁽¹⁾	Max	Units	Conditions
OS56	FHPOUT	On-Chip 16x PLL CCO Frequency	112	118	120	MHz	
OS57	FHPIN	On-Chip 16x PLL Phase Detector Input Frequency	7.0	7.37	7.5	MHz	
OS58	Tsu	Frequency Generator Lock Time	—	—	10	µs	

Note 1: Data in “Typ.” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested in manufacturing.

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FIGURE 25-13: SPI1 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS

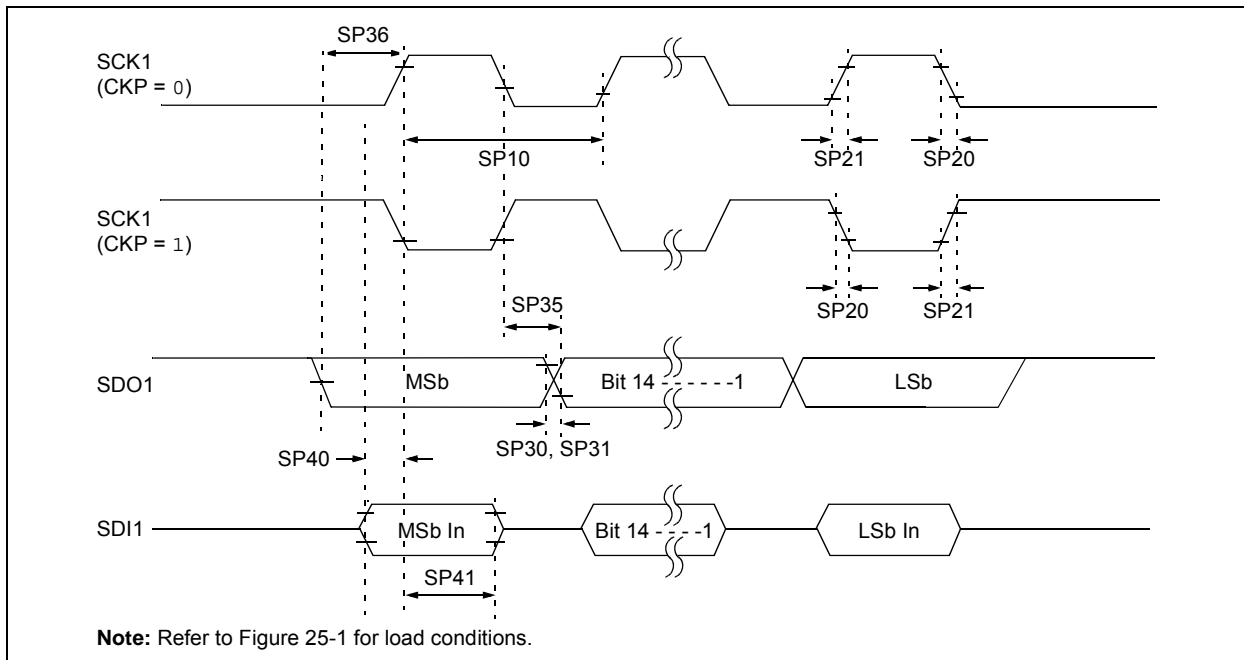


TABLE 25-33: SPI1 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP10	FscP	Maximum SCK1 Frequency	—	—	9	MHz	(Note 3)
SP20	TscF	SCK1 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK1 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO1 Data Output Valid After SCK1 Edge	—	6	20	ns	
SP36	TdoV2sc, TdoV2scl	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scl	Setup Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	

Note 1: These parameters are characterized but not tested in manufacturing.

Note 2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

Note 3: The minimum clock period for SCK1 is 111 ns. The clock generated in Master mode must not violate this specification.

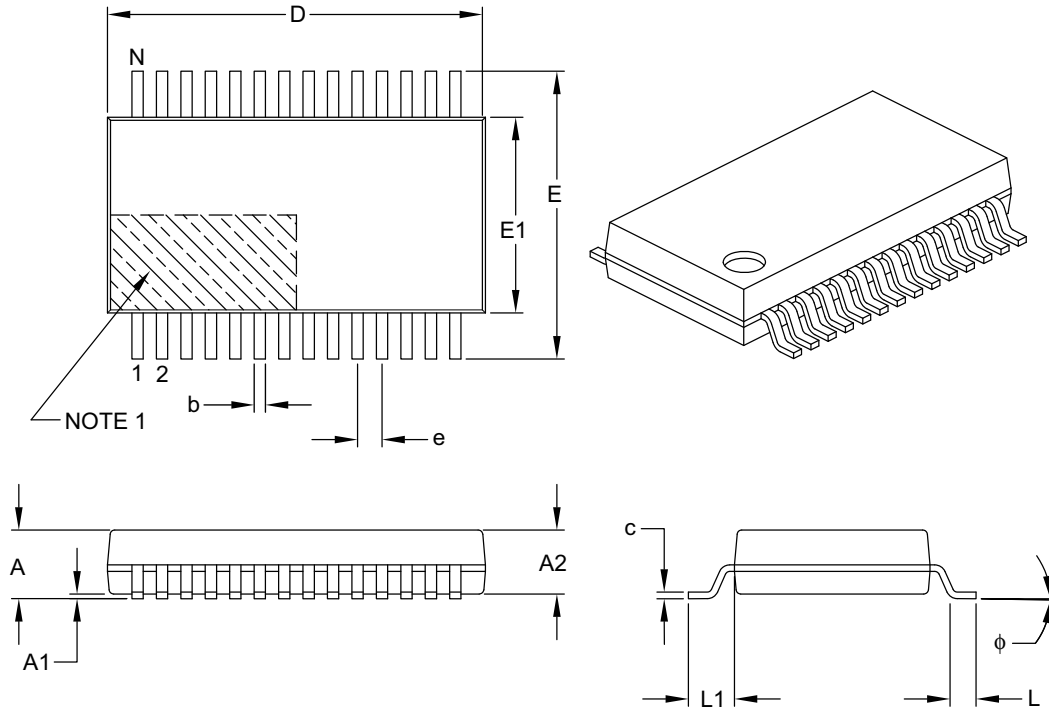
Note 4: Assumes 50 pF load on all SPI1 pins.

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27.2 Package Details

28-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	0.65 BSC		
Overall Height	A	–	–	2.00
Molded Package Thickness	A2	1.65	1.75	1.85
Standoff	A1	0.05	–	–
Overall Width	E	7.40	7.80	8.20
Molded Package Width	E1	5.00	5.30	5.60
Overall Length	D	9.90	10.20	10.50
Foot Length	L	0.55	0.75	0.95
Footprint	L1	1.25 REF		
Lead Thickness	c	0.09	–	0.25
Foot Angle	ϕ	0°	4°	8°
Lead Width	b	0.22	–	0.38

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

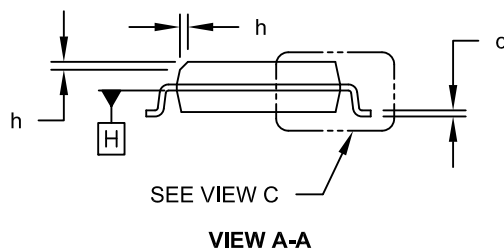
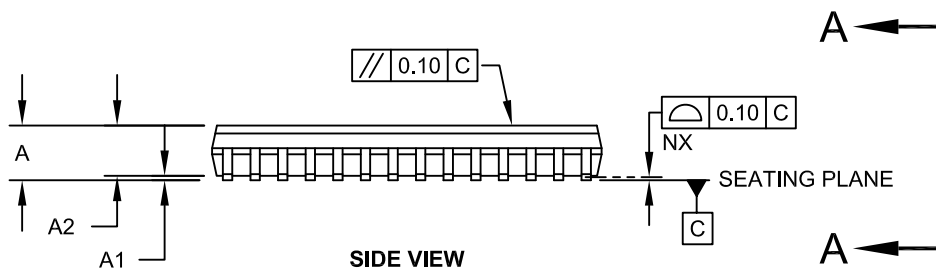
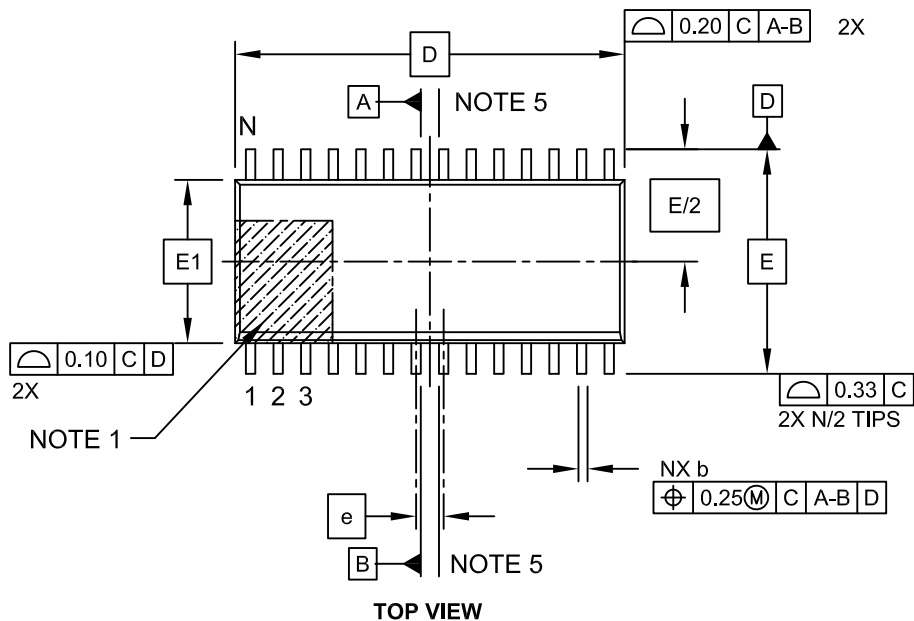
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-073B

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28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-052C Sheet 1 of 2

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NOTES:

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