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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 12x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UQFN Exposed Pad
Supplier Device Package	28-UQFN (4x4)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32gs202-e-m6">https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32gs202-e-m6</a>

**TABLE 4-3: INTERRUPT CONTROLLER REGISTER MAP**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IFS0	0800	NVMIF	—	ADCIF	U1TXIF	U1RXIF	SPI1IF	SPI1EIF	T3IF	T2IF	—	—	—	T1IF	OC1IF	IC1IF	INT0IF	0000
IFS1	0802	—	—	INT2IF	—	—	—	—	—	—	—	—	INT1IF	CNIF	AC1IF	MI2C1IF	SI2C1IF	0000
IFS3	0806	—	—	—	—	—	—	PSEMIF	—	—	—	—	—	—	—	—	—	0000
IFS4	0808	—	—	—	—	—	—	PSESIF	—	—	—	—	—	—	—	U1EIF	—	0000
IFS5	080A	PWM2IF	PWM1IF	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IFS6	080C	ADCAN1IF	ADCAN0IF	—	—	—	—	—	—	AC2IF	—	—	—	—	—	—	PWM3IF	0000
IFS7	080E	—	—	—	—	—	—	—	—	—	—	ADCAN7IF	ADCAN6IF	ADCAN5IF	ADCAN4IF	ADCAN3IF	ADCAN2IF	0000
IFS9	0812	—	—	ADCAN14IF	—	—	ADCAN11IF	ADCAN10IF	ADCAN9IF	ADCAN8IF	—	—	—	—	—	—	—	0000
IFS10	0814	—	—	I2C1BCIF	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IFS11	0816	—	—	—	—	—	—	—	—	—	—	—	—	ADFL0IF	ADCMP1IF	ADCMP0IF	—	0000
IEC0	0820	NVMIE	—	ADCIE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	T3IE	T2IE	—	—	—	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0822	—	—	INT2IE	—	—	—	—	—	—	—	—	INT1IE	CNIE	AC1IF	MI2C1IE	SI2C1IE	0000
IEC3	0826	—	—	—	—	—	—	PSEMIE	—	—	—	—	—	—	—	—	—	0000
IEC4	0828	—	—	—	—	—	—	PSESIE	—	—	—	—	—	—	—	U1EIE	—	0000
IEC5	082A	PWM2IE	PWM1IE	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IEC6	082C	ADCAN1IE	ADCAN0IE	—	—	—	—	—	AC3IE	AC2IE	—	—	—	—	—	—	PWM3IE	0000
IEC7	082E	—	—	—	—	—	—	—	—	—	—	ADCAN7IE	ADCAN6IE	ADCAN5IE	ADCAN4IE	ADCAN3IE	ADCAN2IE	0000
IEC9	0832	—	—	ADCAN14IE	—	—	ADCAN11IE	ADCAN10IE	ADCAN9IE	ADCAN8IE	—	—	—	—	—	—	—	0000
IEC10	0834	—	—	I2C1BCIE	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IEC11	0836	—	—	—	—	—	—	—	—	—	—	—	—	ADFL0IE	ADCMP1IE	ADCMP0IE	—	0000
IPC0	0840	—	T1IP2	T1IP1	T1IP0	—	OC1IP2	OC1IP1	OC1IP0	—	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0	4444
IPC1	0842	—	T2IP2	T2IP1	T2IP0	—	—	—	—	—	—	—	—	—	—	—	—	4000
IPC2	0844	—	U1RXIP2	U1RXIP1	U1RXIP0	—	SPI1IP2	SPI1IP1	SPI1IP0	—	SPI1EIP2	SPI1EIP1	SPI1EIP0	—	T3IP2	T3IP1	T3IP0	4444
IPC3	0846	—	NVMIP2	NVMIP1	NVMIP0	—	—	—	—	—	ADCIP2	ADCIP1	ADCIP0	—	U1TXIP2	U1TXIP1	U1TXIP0	4044
IPC4	0848	—	CNIP2	CNIP1	CNIP0	—	AC1IP2	AC1IP1	AC1IP0	—	MI2C1IP2	MI2C1IP1	MI2C1IP0	—	SI2C1IP2	SI2C1IP1	SI2C1IP0	4444
IPC5	084A	—	—	—	—	—	—	—	—	—	—	—	—	—	INT1IP2	INT1IP1	INT1IP0	0004
IPC7	084E	—	—	—	—	—	—	—	—	—	INT2IP2	INT2IP1	INT2IP0	—	—	—	—	0040
IPC14	085C	—	—	—	—	—	—	—	—	—	PSEMIP2	PSEMIP1	PSEMIP0	—	—	—	—	0040

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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## REGISTER 5-5: NVMSRCADRL: NVM SOURCE DATA ADDRESS LOW REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **NVMSRCADR<15:0>**: Source Data Address bits

The RAM address of the data to be programmed into Flash when the NVMOP<3:0> bits are set to row programming.

## REGISTER 5-6: NVMSRCADRH: NVM SOURCE DATA ADDRESS HIGH REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<31:24>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMSRCADR<23:16>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **NVMSRCADR<31:16>**: Source Data Address bits

The RAM address of the data to be programmed into Flash when the NVMOP<3:0> bits are set to row programming. These bits must be always programmed to zero.

# dsPIC33EPXXGS202 FAMILY

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## 6.1 Reset Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page contains the latest updates and additional information.

### 6.1.1 KEY RESOURCES

- **“Reset”** (DS70602) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools

# dsPIC33EPXXGS202 FAMILY

**FIGURE 7-2: dsPIC33EPXXGS202 FAMILY ALTERNATE INTERRUPT VECTOR TABLE**

<div style="display: flex; align-items: center;"> <div style="writing-mode: vertical-rl; transform: rotate(180deg);">Decreasing Natural Order Priority</div> <div style="margin: 0 10px;"> <div style="width: 100%; height: 100%; border-left: 1px solid black; border-right: 1px solid black; position: relative;"> <div style="position: absolute; top: 0; left: -5px;">↑</div> <div style="position: absolute; bottom: 0; left: -5px;">↓</div> </div> </div> </div>	Reserved	$\text{BSLIM}<12:0>^{(1)} + 0x000000$	<div style="display: flex; align-items: center;"> <div style="writing-mode: vertical-rl; transform: rotate(180deg);">AINT</div> <div style="margin: 0 10px;"> <div style="width: 100%; height: 100%; border-left: 1px solid black; border-right: 1px solid black; position: relative;"> <div style="position: absolute; top: 0; left: -5px;">↑</div> <div style="position: absolute; bottom: 0; left: -5px;">↓</div> </div> </div> </div>
	Reserved	$\text{BSLIM}<12:0>^{(1)} + 0x000002$	
	Oscillator Fail Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x000004$	
	Address Error Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x000006$	
	Generic Hard Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x000008$	
	Stack Error Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x00000A$	
	Math Error Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x00000C$	
	Reserved	$\text{BSLIM}<12:0>^{(1)} + 0x00000E$	
	Generic Soft Trap Vector	$\text{BSLIM}<12:0>^{(1)} + 0x000010$	
	Reserved	$\text{BSLIM}<12:0>^{(1)} + 0x000012$	
	Interrupt Vector 0	$\text{BSLIM}<12:0>^{(1)} + 0x000014$	
	Interrupt Vector 1	$\text{BSLIM}<12:0>^{(1)} + 0x000016$	
	:	:	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 52	$\text{BSLIM}<12:0>^{(1)} + 0x00007C$	
	Interrupt Vector 53	$\text{BSLIM}<12:0>^{(1)} + 0x00007E$	
	Interrupt Vector 54	$\text{BSLIM}<12:0>^{(1)} + 0x000080$	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 116	$\text{BSLIM}<12:0>^{(1)} + 0x0000FC$	
	Interrupt Vector 117	$\text{BSLIM}<12:0>^{(1)} + 0x0000FE$	
	Interrupt Vector 118	$\text{BSLIM}<12:0>^{(1)} + 0x000100$	
	Interrupt Vector 119	$\text{BSLIM}<12:0>^{(1)} + 0x000102$	
	Interrupt Vector 120	$\text{BSLIM}<12:0>^{(1)} + 0x000104$	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 244	$\text{BSLIM}<12:0>^{(1)} + 0x0001FC$	
	Interrupt Vector 245	$\text{BSLIM}<12:0>^{(1)} + 0x0001FE$	

See Table 7-1 for Interrupt Vector Details

**Note 1:** The address depends on the size of the Boot Segment defined by BSLIM<12:0>.  
 $[(\text{BSLIM}<12:0> - 1) \times 0x400] + \text{Offset}$ .

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NOTES:

## 10.5 I/O Helpful Tips

1. In some cases, certain pins, as defined in Table 25-11 under “Injection Current”, have internal protection diodes to VDD and VSS. The term, “Injection Current”, is also referred to as “Clamp Current”. On designated pins, with sufficient external current-limiting precautions by the user, I/O pin input voltages are allowed to be greater or less than the data sheet absolute maximum ratings, with respect to the VSS and VDD supplies. Note that when the user application forward biases either of the high or low side internal input clamp diodes, that the resulting current being injected into the device, that is clamped internally by the VDD and VSS power rails, may affect the ADC accuracy by four to six counts.
2. I/O pins that are shared with any analog input pin (i.e., ANx) are always analog pins by default after any Reset. Consequently, configuring a pin as an analog input pin automatically disables the digital input pin buffer and any attempt to read the digital input level by reading PORTx or LATx will always return a ‘0’, regardless of the digital logic level on the pin. To use a pin as a digital I/O pin on a shared ANx pin, the user application needs to configure the Analog Pin Configuration registers in the I/O ports module (i.e., ANSELx) by setting the appropriate bit that corresponds to that I/O port pin to a ‘0’.

**Note:** Although it is not possible to use a digital input pin when its analog function is enabled, it is possible to use the digital I/O output function, TRISx = 0x0, while the analog function is also enabled. However, this is not recommended, particularly if the analog input is connected to an external analog voltage source, which would create signal contention between the analog signal and the output pin driver.

3. Most I/O pins have multiple functions. Referring to the device pin diagrams in this data sheet, the priorities of the functions allocated to any pins are indicated by reading the pin name from left-to-right. The left most function name takes precedence over any function to its right in the naming convention. For example: AN16/T2CK/T7CK/RC1. This indicates that AN16 is the highest priority in this example and will supersede all other functions to its right in the list. Those other functions to its right, even if enabled, would not work as long as any other function to its left was enabled. This rule applies to all of the functions listed for a given pin.
4. Each pin has an internal weak pull-up resistor and pull-down resistor that can be configured using the CNPUx and CNPDx registers, respectively. These resistors eliminate the need for external resistors in certain applications. The internal pull-up is up to  $\sim(VDD - 0.8)$ , not VDD. This value is still above the minimum VIH of CMOS and TTL devices.
5. When driving LEDs directly, the I/O pin can source or sink more current than what is specified in the VOH/IOH and VOL/IOL DC characteristics specification. The respective IOH and IOL current rating only applies to maintaining the corresponding output at or above the VOH, and at or below the VOL levels. However, for LEDs, unlike digital inputs of an externally connected device, they are not governed by the same minimum VIH/VIL levels. An I/O pin output can safely sink or source any current less than that listed in the Absolute Maximum Ratings in **Section 25.0 “Electrical Characteristics”** of this data sheet. For example:

$$VOH = 2.4V @ IOH = -8 mA \text{ and } VDD = 3.3V$$

The maximum output current sourced by any 8 mA I/O pin = 12 mA.

LED source current < 12 mA is technically permitted.

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## 11.1 Timer1 Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page contains the latest updates and additional information.

### 11.1.1 KEY RESOURCES

- **“Timers”** (DS70362) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools



# dsPIC33EPXXGS202 FAMILY

**REGISTER 13-2: IC1CON2: INPUT CAPTURE CONTROL REGISTER 2**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

R/W-0	R/W-0, HS	U-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-1
ICTRIG <sup>(1)</sup>	TRIGSTAT <sup>(2)</sup>	—	SYNCSEL4 <sup>(3)</sup>	SYNCSEL3 <sup>(3)</sup>	SYNCSEL2 <sup>(3)</sup>	SYNCSEL1 <sup>(3)</sup>	SYNCSEL0 <sup>(3)</sup>
bit 7						bit 0	

<b>Legend:</b>	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **ICTRIG:** Input Capture Trigger Operation Select bit<sup>(1)</sup>

1 = Input source used to trigger the input capture timer (Trigger mode)

0 = Input source used to synchronize the input capture timer to a timer of another module (Synchronization mode)

bit 6 **TRIGSTAT:** Timer Trigger Status bit<sup>(2)</sup>

1 = IC1TMR has been triggered and is running

0 = IC1TMR has not been triggered and is being held clear

bit 5 **Unimplemented:** Read as '0'

**Note 1:** The input source is selected by the SYNCSEL<4:0> bits of the IC1CON2 register.

**2:** This bit is set by the selected input source (selected by SYNCSEL<4:0> bits); it can be read, set and cleared in software.

**3:** Do not use the IC1 module as its own sync or trigger source.

**4:** This option should only be selected as a trigger source and not as a synchronization source.

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## REGISTER 15-1: PTCON: PWM TIME BASE CONTROL REGISTER

R/W-0	U-0	R/W-0	HS/HC-0	R/W-0	R/W-0	R/W-0	R/W-0
PTEN	—	PTSIDL	SESTAT	SEIEN	EIPU <sup>(1)</sup>	SYNCPOL <sup>(1)</sup>	SYNCOEN <sup>(1)</sup>
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SYNCEN <sup>(1)</sup>	SYNCSRC2 <sup>(1)</sup>	SYNCSRC1 <sup>(1)</sup>	SYNCSRC0 <sup>(1)</sup>	SEVTPS3 <sup>(1)</sup>	SEVTPS2 <sup>(1)</sup>	SEVTPS1 <sup>(1)</sup>	SEVTPS0 <sup>(1)</sup>
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit	HS = Hardware Settable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 15      **PTEN:** PWM Module Enable bit  
1 = PWM module is enabled  
0 = PWM module is disabled
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **PTSIDL:** PWM Time Base Stop in Idle Mode bit  
1 = PWM time base halts in CPU Idle mode  
0 = PWM time base runs in CPU Idle mode
- bit 12      **SESTAT:** Special Event Interrupt Status bit  
1 = Special event interrupt is pending  
0 = Special event interrupt is not pending
- bit 11      **SEIEN:** Special Event Interrupt Enable bit  
1 = Special event interrupt is enabled  
0 = Special event interrupt is disabled
- bit 10      **EIPU:** Enable Immediate Period Updates bit<sup>(1)</sup>  
1 = Active Period register is updated immediately  
0 = Active Period register updates occur on PWM cycle boundaries
- bit 9      **SYNCPOL:** Synchronize Input and Output Polarity bit<sup>(1)</sup>  
1 = SYNCIx/SYNCO1 polarity is inverted (active-low)  
0 = SYNCIx/SYNCO1 is active-high
- bit 8      **SYNCOEN:** Primary Time Base Synchronization Enable bit<sup>(1)</sup>  
1 = SYNCO1 output is enabled  
0 = SYNCO1 output is disabled
- bit 7      **SYNCEN:** External Time Base Synchronization Enable bit<sup>(1)</sup>  
1 = External synchronization of primary time base is enabled  
0 = External synchronization of primary time base is disabled
- bit 6-4      **SYNCSRC<2:0>:** Synchronous Source Selection bits<sup>(1)</sup>  
111 = Reserved  
101 = Reserved  
100 = Reserved  
011 = Reserved  
010 = Reserved  
001 = SYNCI2  
000 = SYNCI1

**Note 1:** These bits should be changed only when PTEN = 0. In addition, when using the SYNCIx feature, the user application must program the Period register with a value that is slightly larger than the expected period of the external synchronization input signal.

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**REGISTER 15-6: STCON2: PWM SECONDARY CLOCK DIVIDER SELECT REGISTER 2**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	PCLKDIV<2:0> <sup>(1)</sup>		
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-3                      **Unimplemented:** Read as '0'  
bit 2-0                      **PCLKDIV<2:0>:** PWM Input Clock Prescaler (Divider) Select bits<sup>(1)</sup>  
                                    111 = Reserved  
                                    110 = Divide-by-64, maximum PWM timing resolution  
                                    101 = Divide-by-32, maximum PWM timing resolution  
                                    100 = Divide-by-16, maximum PWM timing resolution  
                                    011 = Divide-by-8, maximum PWM timing resolution  
                                    010 = Divide-by-4, maximum PWM timing resolution  
                                    001 = Divide-by-2, maximum PWM timing resolution  
                                    000 = Divide-by-1, maximum PWM timing resolution (power-on default)

**Note 1:** These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

**REGISTER 15-7: STPER: PWM SECONDARY MASTER TIME BASE PERIOD REGISTER<sup>(1,2)</sup>**

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
STPER<15:8>							
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
STPER<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **STPER<15:0>:** Secondary Master Time Base (SMTMR) Period Value bits

**Note 1:** The PWM time base has a minimum value of 0x0010 and a maximum value of 0xFFF8.  
**2:** Any period value that is less than 0x0028 must have the Least Significant 3 bits set to '0', thus yielding a period resolution at 8.32 ns (at fastest auxiliary clock rate).

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## REGISTER 19-4: ADCON2H: ADC CONTROL REGISTER 2 HIGH

R-0, HS, HC	R-0, HS, HC	U-0	U-0	U-0	U-0	R/W-0	R/W-0
REFRDY	REFERR	—	—	—	—	SHRSAMC9	SHRSAMC8
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SHRSAMC7	SHRSAMC6	SHRSAMC5	SHRSAMC4	SHRSAMC3	SHRSAMC2	SHRSAMC1	SHRSAMC0
bit 7						bit 0	

<b>Legend:</b>	HS = Hardware Settable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15 **REFRDY:** Band Gap and Reference Voltage Ready Flag bit

1 = Band gap is ready  
0 = Band gap is not ready

bit 14 **REFERR:** Band Gap or Reference Voltage Error Flag bit

1 = Band gap was removed after the ADC module was enabled (ADON = 1)  
0 = No band gap error was detected

bit 13-10 **Unimplemented:** Read as '0'

bit 9-0 **SHRSAMC<9:0>:** Shared ADC Core Sample Time Selection bits

These bits specify the number of shared ADC Core Clock (TADCORE) periods for the shared ADC core sample time.

1111111111 = 1025 TADCORE

•  
•  
•

0000000001 = 3 TADCORE

0000000000 = 2 TADCORE

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## REGISTER 19-20: ADTRIGxL: ADC CHANNEL TRIGGER x SELECTION REGISTER LOW (x = 0 to 3)

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	TRGSRC(4x+1)<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	TRGSRC(4x)<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **TRGSRC(4x+1)<4:0>:** Trigger Source Selection for Corresponding Analog Inputs bits

11111 = ADTRG31  
 11110 = Reserved  
 11101 = Reserved  
 11100 = Reserved  
 11011 = Reserved  
 11010 = PWM Generator 3 current-limit trigger  
 11001 = PWM Generator 2 current-limit trigger  
 11000 = PWM Generator 1 current-limit trigger  
 10111 = Reserved  
 10110 = Output Compare 1 trigger  
 10101 = Reserved  
 10100 = Reserved  
 10011 = Reserved  
 10010 = Reserved  
 10001 = PWM Generator 3 secondary trigger  
 10000 = PWM Generator 2 secondary trigger  
 01111 = PWM Generator 1 secondary trigger  
 01110 = PWM secondary Special Event Trigger  
 01101 = Timer2 period match  
 01100 = Timer1 period match  
 01011 = Reserved  
 01010 = Reserved  
 01001 = Reserved  
 01000 = Reserved  
 00111 = PWM Generator 3 primary trigger  
 00110 = PWM Generator 2 primary trigger  
 00101 = PWM Generator 1 primary trigger  
 00100 = PWM Special Event Trigger  
 00011 = Reserved  
 00010 = Level software trigger  
 00001 = Common software trigger  
 00000 = No trigger is enabled

bit 7-5 **Unimplemented:** Read as '0'

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## REGISTER 20-1: CMPxCON: COMPARATOR x CONTROL REGISTER (x = 1,2) (CONTINUED)

bit 2	<b>ALTINP:</b> Alternate Input Select bit 1 = INSEL<1:0> bits select alternate inputs 0 = INSEL<1:0> bits select comparator inputs
bit 1	<b>CMPPOL:</b> Comparator Output Polarity Control bit 1 = Output is inverted 0 = Output is non-inverted
bit 0	<b>Unimplemented:</b> Read as '0'

## REGISTER 20-2: CMPxDAC: COMPARATOR DACx CONTROL REGISTER (x = 1,2)

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	CMREF<11:8>			
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CMREF<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15-12	<b>Unimplemented:</b> Read as '0'
bit 11-0	<b>CMREF&lt;11:0&gt;:</b> Comparator Reference Voltage Select bits 111111111111 = (CMREF<11:0> * (AVDD)/4096) • • • 000000000000 = 0.0 volts

# dsPIC33EPXXGS202 FAMILY

## 21.2 PGA Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

### 21.2.1 KEY RESOURCES

- **“Programmable Gain Amplifier (PGA)”** (DS70005146) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools

### REGISTER 21-1: PGAxCON: PGAx CONTROL REGISTER (x = 1,2)

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PGAEN	—	SELPI2	SELPI1	SELPI0	SELNI2	SELNI1	SELNI0
bit 15				bit 8			
U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	GAIN2	GAIN1	GAIN0
bit 7				bit 0			

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **PGAEN:** PGAx Enable bit  
1 = PGAx module is enabled  
0 = PGAx module is disabled (reduces power consumption)
- bit 14 **Unimplemented:** Read as '0'
- bit 13-11 **SELPI<2:0>:** PGAx Positive Input Selection bits  
111 = Reserved  
110 = Reserved  
101 = Reserved  
100 = Reserved  
011 = Reserved  
010 = PGAxP3  
001 = PGAxP2  
000 = PGAxP1
- bit 10-8 **SELNI<2:0>:** PGAx Negative Input Selection bits  
111 = Reserved  
110 = Reserved  
101 = Reserved  
100 = Reserved  
011 = Ground (Single-Ended mode)  
010 = Reserved  
001 = PGAxN2  
000 = Ground (Single-Ended mode)
- bit 7-3 **Unimplemented:** Read as '0'

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## 22.2 Device Calibration and Identification

The PGAX modules on the dsPIC33EPXXGS202 family devices require Calibration Data registers to improve performance of the module over a wide operating range. These Calibration registers are read-only and are stored in configuration memory space. Prior to enabling the module, the calibration data must be read (TBLPAG and Table Read instruction) and loaded into their respective SFR registers. The device calibration addresses are shown in Table 22-3.

The dsPIC33EPXXGS202 devices have two Identification registers near the end of configuration memory space that store the Device ID (DEVID) and Device Revision (DEVREV). These registers are used to determine the mask, variant and manufacturing information about the device. These registers are read-only and are shown in Register 22-1 and Register 22-2.

**TABLE 22-3: DEVICE CALIBRATION ADDRESSES<sup>(1)</sup>**

Calibration Name	Address	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PGA1CAL	800E48	—	—	—	—	—	—	—	—	—	—	—	PGA1 Calibration Data bits					
PGA2CAL	800E4C	—	—	—	—	—	—	—	—	—	—	—	PGA2 Calibration Data bits					

**Note 1:** The calibration data must be copied into its respective registers prior to enabling the module.



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## 25.1 DC Characteristics

**TABLE 25-1: OPERATING MIPS vs. VOLTAGE**

Characteristic	VDD Range (in Volts)	Temperature Range (in °C)	Maximum MIPS
			dsPIC33EPXXGS202 Family
—	3.0V to 3.6V <sup>(1)</sup>	-40°C to +85°C	70
—	3.0V to 3.6V <sup>(1)</sup>	-40°C to +125°C	60

**Note 1:** Device is functional at  $V_{BORMIN} < V_{DD} < V_{DDMIN}$ . Analog modules (ADC, PGAs and comparators) may have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 25-13 for the minimum and maximum BOR values.

**TABLE 25-2: THERMAL OPERATING CONDITIONS**

Rating	Symbol	Min.	Typ.	Max.	Unit
Industrial Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+125	°C
Operating Ambient Temperature Range	TA	-40	—	+85	°C
Extended Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+140	°C
Operating Ambient Temperature Range	TA	-40	—	+125	°C
Power Dissipation: Internal Chip Power Dissipation: $P_{INT} = V_{DD} \times (I_{DD} - \sum I_{OH})$ I/O Pin Power Dissipation: $I/O = \sum (\{V_{DD} - V_{OH}\} \times I_{OH}) + \sum (V_{OL} \times I_{OL})$	PD	PINT + PI/O			W
Maximum Allowed Power Dissipation	PDMAX	$(T_J - T_A)/\theta_{JA}$			W

**TABLE 25-3: THERMAL PACKAGING CHARACTERISTICS**

Characteristic	Symbol	Typ.	Max.	Unit	Notes
Package Thermal Resistance, 28-Pin QFN-S	$\theta_{JA}$	30.0	—	°C/W	1
Package Thermal Resistance, 28-Pin UQFN	$\theta_{JA}$	26.0	—	°C/W	1
Package Thermal Resistance, 28-Pin SOIC	$\theta_{JA}$	69.7	—	°C/W	1
Package Thermal Resistance, 28-Pin SSOP	$\theta_{JA}$	71.0	—	°C/W	1

**Note 1:** Junction to ambient thermal resistance, Theta-JA ( $\theta_{JA}$ ) numbers are achieved by package simulations.

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**TABLE 25-12: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic	Min. <sup>(1)</sup>	Typ.	Max.	Units	Conditions
DO10	VOL	<b>Output Low Voltage</b> 4x Sink Driver Pins <sup>(2)</sup>	—	—	0.4	V	VDD = 3.3V, IOL ≤ 6 mA, -40°C ≤ TA ≤ +85°C, IOL ≤ 5 mA, +85°C < TA ≤ +125°C
		<b>Output Low Voltage</b> 8x Sink Driver Pins <sup>(3)</sup>	—	—	0.4	V	VDD = 3.3V, IOL ≤ 12 mA, -40°C ≤ TA ≤ +85°C, IOL ≤ 8 mA, +85°C < TA ≤ +125°C
DO20	VOH	<b>Output High Voltage</b> 4x Source Driver Pins <sup>(2)</sup>	2.4	—	—	V	IOH ≥ -10 mA, VDD = 3.3V
		<b>Output High Voltage</b> 8x Source Driver Pins <sup>(3)</sup>	2.4	—	—	V	IOH ≥ -15 mA, VDD = 3.3V
DO20A	VOH1	<b>Output High Voltage</b> 4x Source Driver Pins <sup>(2)</sup>	1.5	—	—	V	IOH ≥ -14 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -12 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -7 mA, VDD = 3.3V
		<b>Output High Voltage</b> 8x Source Driver Pins <sup>(3)</sup>	1.5	—	—	V	IOH ≥ -22 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -18 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -10 mA, VDD = 3.3V

**Note 1:** Parameters are for design guidance only and are not tested in manufacturing.

**2:** Includes RB<14:11> pins.

**3:** Includes all I/O pins that are not 4x driver pins (see **Note 2**).

**TABLE 25-13: ELECTRICAL CHARACTERISTICS: BOR**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) <sup>(1)</sup> Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min. <sup>(2)</sup>	Typ.	Max.	Units	Conditions
BO10	VBOR	BOR Event on VDD Transition High-to-Low	2.65	—	2.95	V	VDD ( <b>Notes 2, 3</b> )

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, PGAs and comparators) may have degraded performance.

**2:** Parameters are for design guidance only and are not tested in manufacturing.

**3:** The VBOR specification is relative to VDD.

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**TABLE 25-37: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)  
TIMING REQUIREMENTS**

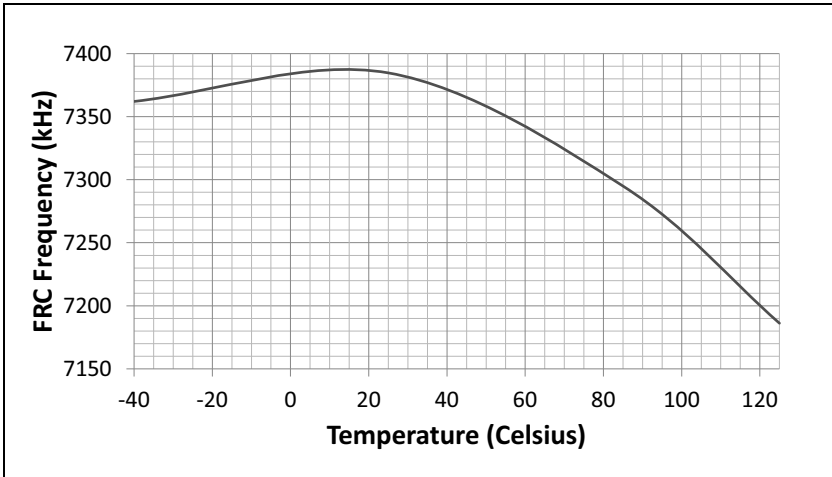
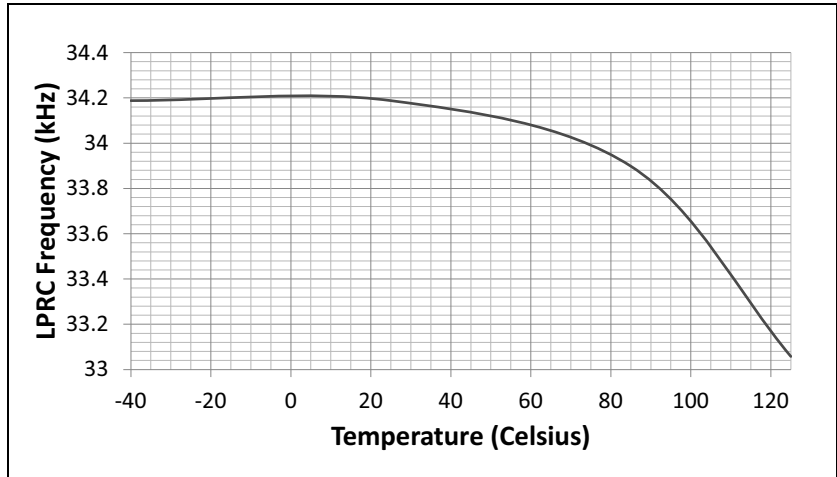
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP70	FscP	Maximum SCK1 Input Frequency	—	—	15	MHz	(Note 3)
SP72	TscF	SCK1 Input Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK1 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO1 Data Output Valid After SCK1 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{SS1}$ ↓ to SCK1 ↑ or SCK1 ↓ Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{SS1}$ ↑ to SDO1 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	Tsch2ssH, TscL2ssH	$\overline{SS1}$ ↑ After SCK1 Edge	1.5 TCY + 40	—	—	ns	(Note 4)

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in “Typ.” column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK1 is 66.7 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.

**4:** Assumes 50 pF load on all SPI1 pins.

**FIGURE 26-9: TYPICAL FRC FREQUENCY @  $V_{DD} = 3.3V$** **FIGURE 26-10: TYPICAL LPRC FREQUENCY @  $V_{DD} = 3.3V$** 

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