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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XFI

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	22
Program Memory Size	7KB (4K x 14)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	192 x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lc63at-04i-so

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



PIC16C63A/65B/73B/74B

PIC16C63A/65B/73B/74B Data Sheet Errata

The PIC16C63A/65B/73B/74B parts you have received conform functionally to the Device Data Sheet (DS30605**C**), except for the anomalies described below.

None.

Clarifications/Corrections to the Data Sheet:

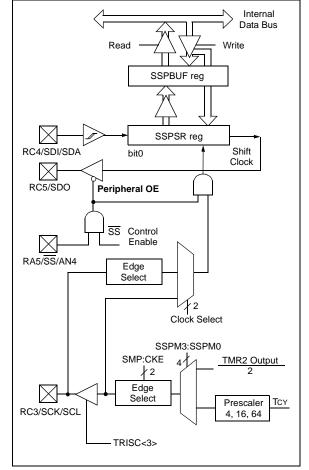
In the Device Data Sheet (DS30605**C**), the following clarifications and corrections should be noted.

1. Module: SSP (SPI[™] Mode)

In Section 10.2 ("SPI Mode"), Figure 10-1 and the note box immediately beneath it have been amended to better demonstrate the Peripheral OE line of the SSP module and describe its relationship to the TRISC<5> bit of PORTC.

Changes are indicated in **bold**.





- Note 1: When the SPI module is in Slave mode with SS pin control enabled (SSPCON<3:0> = 0100), the SPI module will reset if the SS pin is set to VDD.
 - **2:** If the SPI is used in Slave mode with CKE = '1', then \overline{SS} pin control must be enabled.
 - 3: When the SPI is in Slave mode with \overline{SS} pin control enabled (<u>SS</u>PCON<3:0> = 0100), the state of the SS pin can affect the state read back from the TRISC<5> bit. The Peripheral OE signal from the SSP module into PORTC, controls the state that is read back from the TRISC<5> bit (see Section 5.3 for information on PORTC). If Read-Modify-Write instructions, such as BSF, are performed on the TRISC register while the SS pin is high, this will cause the TRISC<5> bit to be set, thus disabling the SDO output.

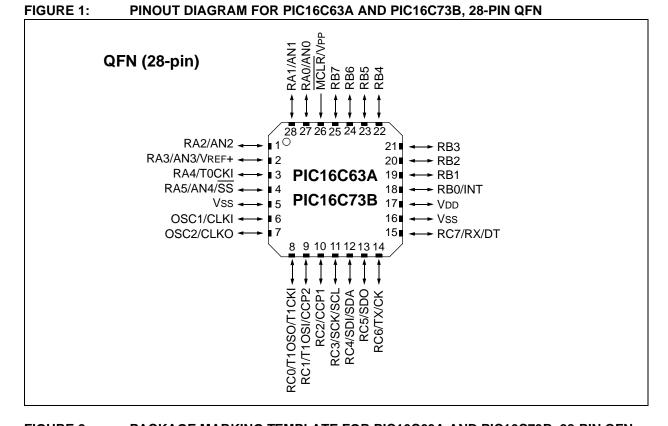
2. Module: Packaging (Pinout and Product Identification)

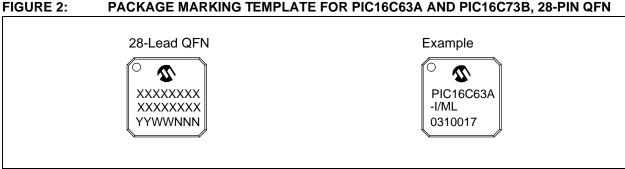
PIC16C63A and PIC16C73B devices are now offered in 28-pin near chip-scale micro lead frame packages (commonly known as "QFN"). This packaging type has been added to the product line since the latest revision of the Device Data Sheet.

The addition of this option requires the following additions to the Device Data Sheet. The referenced figures and tables follow this text.

1. The "Pin Diagram" on page 2 of the Data Sheet is amended with the addition of the 28-pin QFN pinout, shown in Figure 1.

- 2. Table 3-1 of Section 3.0 ("Architectural Overview") is replaced with an updated version that adds a column for QFN pin assignments. All new information is indicated in **bold**.
- 3. Section 18.1 ("Package Marking Information") is amended to include a marking template and example for 28-pin QFN devices. These are shown in Figure 2.
- 4. Section 18.0 ("Package Information") is amended to include the mechanical drawings of the 28-pin QFN package. These are shown in Figure 3 and Figure 4, respectively.
- 5. Table B-1 ("Device Differences") is amended to include the 28-pin QFN for the PIC16C63A and PIC16C73B devices.





Pin Name	DIP Pin#	SOIC Pin#	QFN Pin#	I/O/P Type	Buffer Type	Description
OSC1/CLKIN	9	9	6		ST/CMOS ⁽³⁾	Oscillator crystal input/external clock source input.
OSC2/CLKOUT	10	10	7	0	_	Oscillator crystal output. Connects to crystal or resonator in crystal oscillator mode. In RC mode, the OSC2 pin outputs CLKOUT which has 1/4 the frequency of OSC1, and denotes the instruction cycle rate.
MCLR/Vpp	1	1	26	I/P	ST	Master clear (RESET) input or programming voltage input. This pin is an active low RESET to the device.
						PORTA is a bidirectional I/O port.
RA0/AN0 ⁽⁴⁾	2	2	27	I/O	TTL	RA0 can also be analog input 0 ⁽⁴⁾ .
RA1/AN1 ⁽⁴⁾	3	3	28	I/O	TTL	RA1 can also be analog input 1 ⁽⁴⁾ .
RA2/AN2 ⁽⁴⁾	4	4	1	I/O	TTL	RA2 can also be analog input 2 ⁽⁴⁾ .
RA3/AN3/VREF ⁽⁴⁾	5	5	2	I/O	TTL	RA3 can also be analog input 3 or analog reference voltage ⁽⁴⁾ .
RA4/T0CKI	6	6	3	I/O	ST	RA4 can also be the clock input to the Timer0 module. Output is open drain type.
RA5/SS/AN4 ⁽⁴⁾	7	7	4	I/O	TTL	RA5 can also be analog input 4 ⁽⁴⁾ or the slave select for the synchronous serial port.
						PORTB is a bidirectional I/O port. PORTB can be software
						programmed for internal weak pull-up on all inputs.
RB0/INT	21	21	18	I/O	TTL/ST ⁽¹⁾	RB0 can also be the external interrupt pin.
RB1	22	22	19	I/O	TTL	
RB2	23	23	20	I/O	TTL	
RB3	24	24	21	I/O	TTL	
RB4	25	25	22	I/O	TTL	Interrupt-on-change pin.
RB5	26	26	23	I/O	TTL	Interrupt-on-change pin.
RB6	27	27	24	I/O	TTL/ST ⁽²⁾	Interrupt-on-change pin. Serial programming clock.
RB7	28	28	25	I/O	TTL/ST ⁽²⁾	Interrupt-on-change pin. Serial programming data.
						PORTC is a bidirectional I/O port.
RC0/T1OSO/T1CKI	11	11	8	I/O	ST	RC0 can also be the Timer1 oscillator output or Timer1 clock input.
RC1/T1OSI/CCP2	12	12	9	I/O	ST	RC1 can also be the Timer1 oscillator input or Capture2 input/Compare2 output/PWM2 output.
RC2/CCP1	13	13	10	I/O	ST	RC2 can also be the Capture1 input/Compare1 output/PWM1 output.
RC3/SCK/SCL	14	14	11	I/O	ST	RC3 can also be the synchronous serial clock input/outpu for both SPI and I ² C modes.
RC4/SDI/SDA	15	15	12	I/O	ST	RC4 can also be the SPI Data In (SPI mode) or data I/O (I^2 C mode).
RC5/SDO	16	16	13	I/O	ST	RC5 can also be the SPI Data Out (SPI mode).
RC6/TX/CK	17	17	14	I/O	ST	RC6 can also be the USART Asynchronous Transmit or Synchronous Clock.
RC7/RX/DT	18	18	15	I/O	ST	RC7 can also be the USART Asynchronous Receive or Synchronous Data.
Vss	8, 19	8, 19	16	Р	-	Ground reference for logic and I/O pins.
Vdd	20	20	17	Р	_	Positive supply for logic and I/O pins.
Legend: I = input		O = out	out	1/0	= input/output	P = power

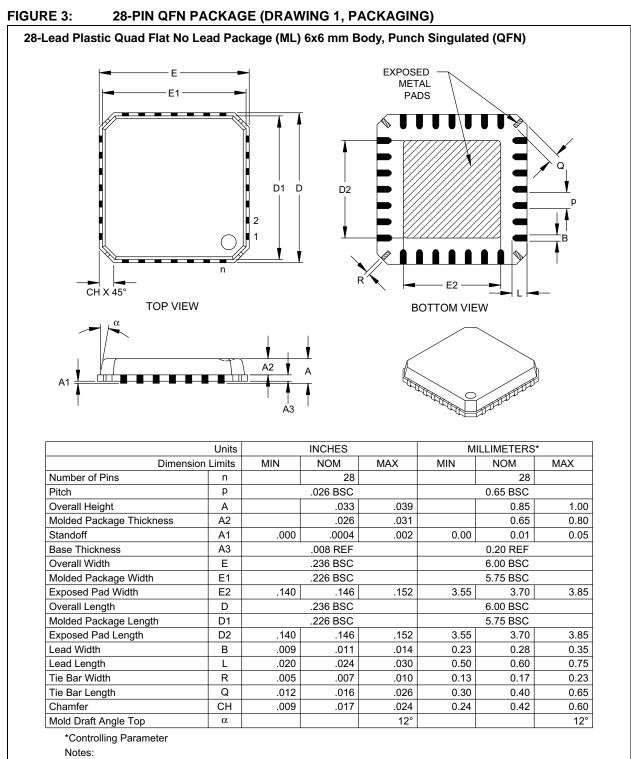
TABLE 3-1:PIC16C63A/73B PINOUT DESCRIPTION

Note 1: This buffer is a Schmitt Trigger input when configured as the external interrupt.

2: This buffer is a Schmitt Trigger input when used in Serial Programming mode.

3: This buffer is a Schmitt Trigger input when configured in RC Oscillator mode and a CMOS input otherwise.

4: A/D module is not available in the PIC16C63A.

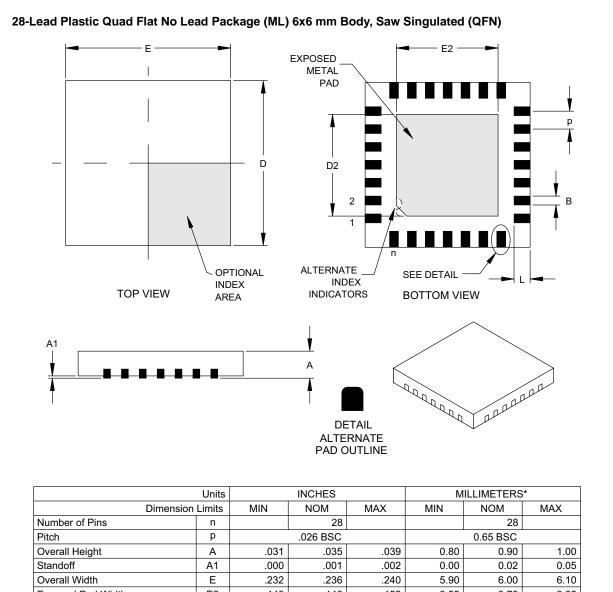


Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side. JEDEC equivalent: mMO-220

Drawing No. C04-114

PIC16C63A/65B/73B/74B

FIGURE 4: 28-PIN QFN PACKAGE (DRAWING 2, PACKAGING)



Exposed Pad Width E2 .140 .146 .152 3.55 3.70 3.85 **Overall Length** D .232 .236 .240 5.90 6.00 6.10 Exposed Pad Length D2 .140 .146 .152 3.55 3.70 3.85 Lead Width В .009 .011 .013 0.23 0.28 0.33 Lead Length L .020 .022 .024 0.50 0.55 0.60

*Controlling Parameter Notes: JEDEC equivalent: mMO-220 Drawing No. C04-105

3. Module: RESET

Section 13.4.1 ("POWER-ON RESET (POR)") has been amended to clarify the minimum specifications required for MCLR in order to RESET the PIC16CXXX. The following paragraphs and figure have been added:

If a $\overline{\text{MCLR}}$ pulse occurs that is less that the minimum specification (parameter #30), improper device operation can occur.

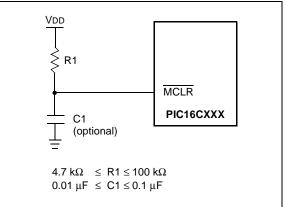
If the minimum specification cannot be met, then an external circuit must be used to ensure that any pulse width less than the <u>specification</u> will be filtered before it reaches the MCLR pin.

A possible circuit to remedy this is shown in Figure 5. This circuit works by delaying the MCLR release following a power-up. If no delay is required, the capacitor may be omitted.

An alternative would be to use a supervisory circuit to control MCLR.

Design validation should be performed to verify that the application works as expected.

FIGURE 5: MCLR EXTERNAL CIRCUIT



REVISION HISTORY

Rev A Document (7/2003) First revision of this document. Device Data Sheet Clarification issues 1 (SSP), 2 (Packaging) and 3 (RESET).

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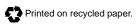
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