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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, LINbus, SCI, SPI
Peripherals	LCD, PWM, WDT
Number of I/O	45
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x16b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08gw32clk">https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08gw32clk</a>

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## Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

<http://freescale.com/>

The following revision history table summarizes changes contained in this document.

Rev	Date	Description of Changes
1	5/26/2010	Initial public release
2	10/29/2010	Completed all the TBDs. Updated the voltage output data in the <a href="#">Table 20</a> . Changed the classification marking of $I_{INT}$ to C in the <a href="#">Table 8</a> .
3	1/28/2011	Updated <a href="#">Table 7</a> .

## Related Documentation

Find the most current versions of all documents at: <http://www.freescale.com>

### Reference Manual (MC9S08GW64RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

## Devices in the MC9S08GW64 Series

- <sup>1</sup> There are two 16-bit ADC modules, so two parallel conversions at two channels can be made simultaneously.
- <sup>2</sup> Each differential channel consists of two pins (DADPx and DADMx).
- <sup>3</sup> The I/O pins include one output-only pin.

The block diagram in [Figure 1](#) shows the structure of the MC9S08GW64 series MCUs.

high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pull-up resistor associated with the pin is enabled.

**Table 4. Absolute Maximum Ratings**

Rating	Symbol	Value	Unit
Supply voltage	$V_{DD}$	-0.3 to +3.8	V
Maximum current into $V_{DD}$	$I_{DD}$	120	mA
Digital input voltage	$V_{In}$	-0.3 to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins except PTA5 and PTB1) <sup>1, 2, 3</sup>	$I_D$	$\pm 25$	mA
Instantaneous maximum current Single pin limit (applies to PTA5 and PTB1) <sup>1, 2, 3</sup>	$I_D$	$\pm 50$	mA
Storage temperature range	$T_{stg}$	-55 to 150	°C

<sup>1</sup> Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive ( $V_{DD}$ ) and negative ( $V_{SS}$ ) clamp voltages, then use the larger of the two resistance values.

<sup>2</sup> All functional non-supply pins are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

<sup>3</sup> Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{In} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure external  $V_{DD}$  load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

### 3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

**Table 5. Thermal Characteristics**

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T <sub>A</sub>	T <sub>L</sub> to T <sub>H</sub> −40 to 85	°C
Maximum junction temperature	T <sub>J</sub>	95	°C
Thermal resistance Single-layer board			
80-pin LQFP	θ <sub>JA</sub>	61	°C/W
64-pin LQFP		70	
Thermal resistance Four-layer board			
80-pin LQFP	θ <sub>JA</sub>	48	°C/W
64-pin LQFP		52	

Table 7. ESD and Latch-Up Protection Characteristics

No.	Rating <sup>1</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	$V_{HBM}$	$\pm 2000$	—	V
2	Machine Model (MM)	$V_{MM}$	$\pm 200$	—	V
3	Charge device model (CDM)	$V_{CDM}$	$\pm 500$	—	V
4	Latch-up current at $T_A = 85^\circ\text{C}$ (applies to all pins except pin 31EXTAL1 and pin 30 XTAL1 in 80-pin package, applies to all pins except pin 23 EXTAL1 and pin 24 XTAL1 in 64-pin package)	$I_{LAT}$	$\pm 100^2$	—	mA
	Latch-up current at $T_A = 85^\circ\text{C}$ (applies to pin 31EXTAL1 and pin 30 XTAL1 in 80-pin package, applies to pin 23 EXTAL1 and pin 24 XTAL1 in 64-pin package)	$I_{LAT}$	$\pm 62^3$	—	mA

<sup>1</sup> Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

<sup>2</sup> These pins meet JESD78A Class II (section 1.2) Level A (section 1.3) requirement of  $\pm 100\text{mA}$ .

<sup>3</sup> This pin meets JESD78A Class II (section 1.2) Level B (section 1.3) characterization to  $\pm 62\text{mA}$ .

### 3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 8. DC Characteristics

Num	C	Characteristic	Symbol	Condition	Min	Typ <sup>1</sup>	Max	Unit
1		Operating Voltage			1.8		3.6	V
2	C	Output high voltage All non-LCD pins low-drive strength	$V_{OH}$	$V_{DD} > 1.8\text{ V}$ $I_{Load} = -0.6\text{ mA}$	$V_{DD} - 0.5$	—	—	V
	P	All non-LCD pins high-drive strength		$V_{DD} > 2.7\text{ V}$ $I_{Load} = -10\text{ mA}$	$V_{DD} - 0.5$	—	—	
	C			$V_{DD} > 1.8\text{ V}$ $I_{Load} = -3\text{ mA}$	$V_{DD} - 0.5$	—	—	
3	C	Output high voltage All LCD/GPIO pins low-drive strength	$V_{OH}$	$V_{DD} > 1.8\text{ V}$ $I_{Load} = -0.5\text{ mA}$	$V_{DD} - 0.5$	—	—	V
	P	All LCD/GPIO pins high-drive strength		$V_{DD} > 2.7\text{ V}$ $I_{Load} = -2.5\text{ mA}$	$V_{DD} - 0.5$	—	—	
	C			$V_{DD} > 1.8\text{ V}$ $I_{Load} = -1\text{ mA}$	$V_{DD} - 0.5$	—	—	
4	D	Output high current Max total $I_{OH}$ for all ports	$I_{OHT}$		—	—	100	mA

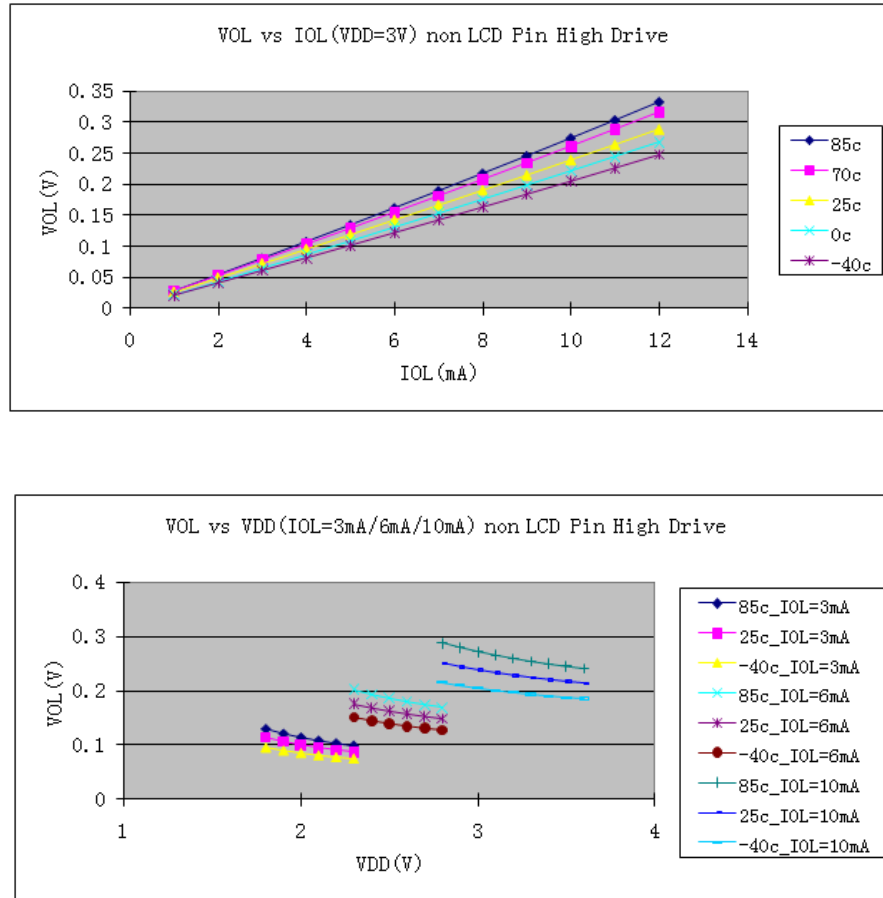


Figure 7. Typical Low-Side Driver (Sink) Characteristics(Non LCD pins) — High Drive (PTxDSn = 1)

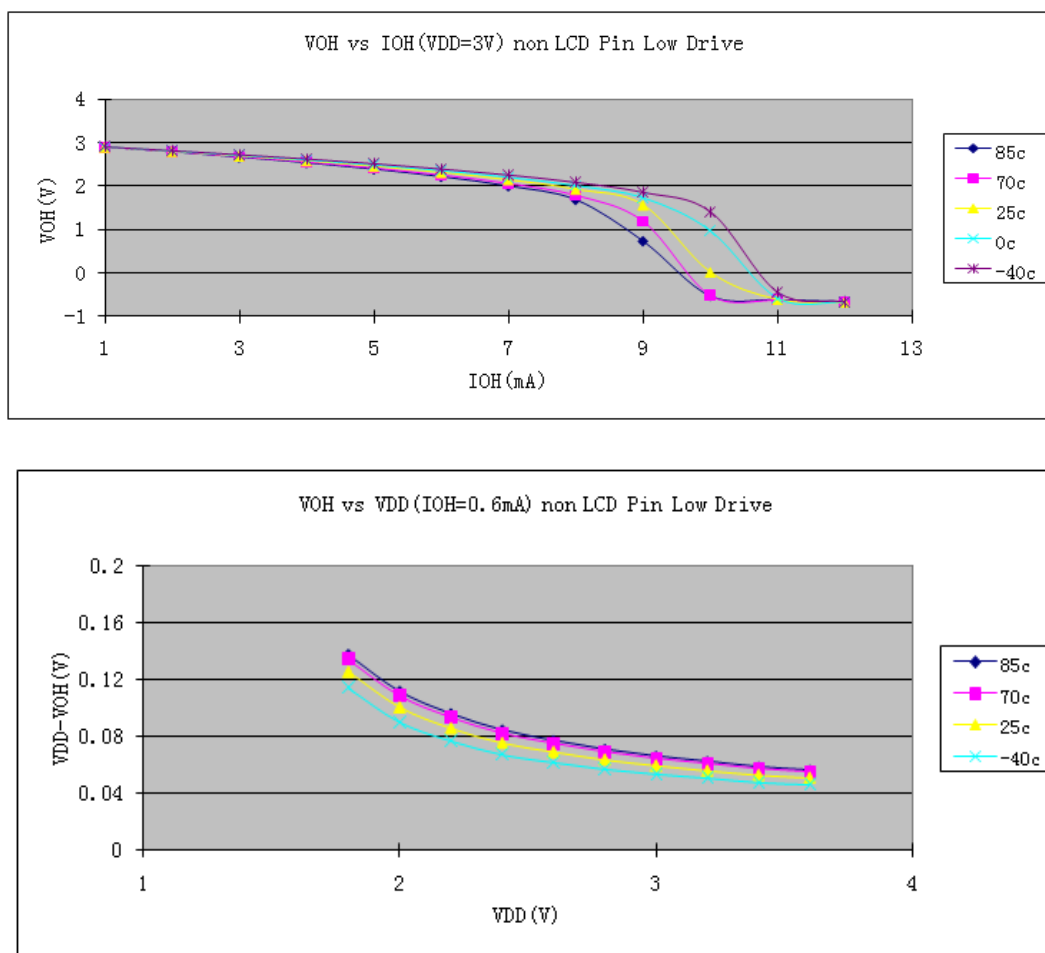


Figure 8. Typical High-Side (Source) Characteristics (Non LCD pins)— Low Drive (PTxDSn = 0)

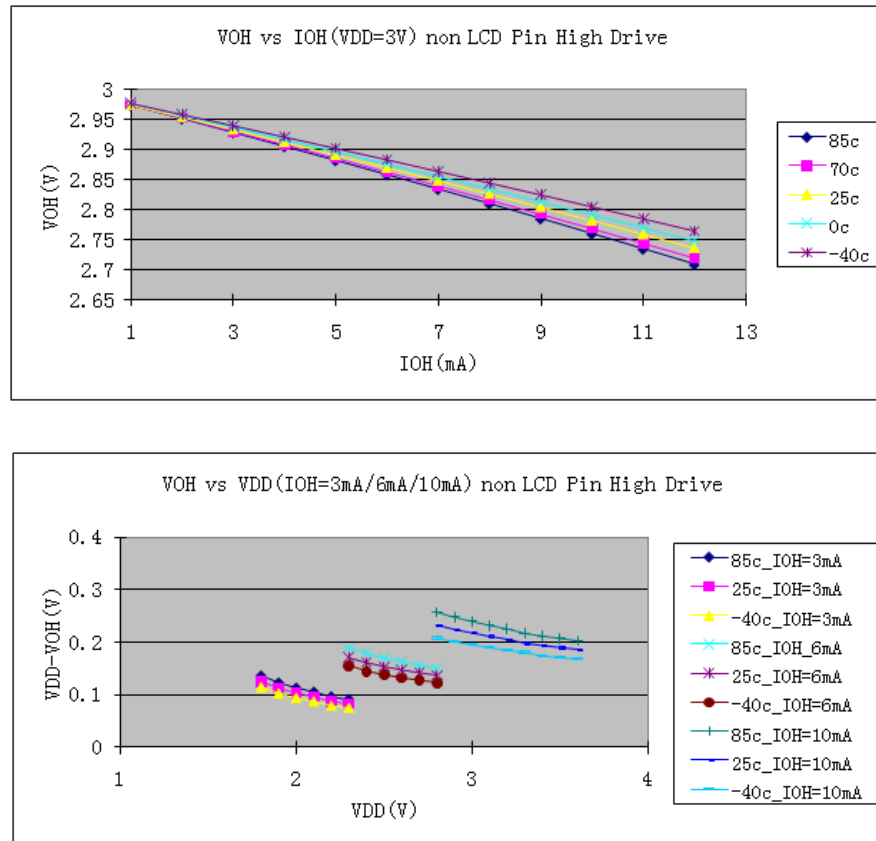


Figure 9. Typical High-Side (Source) Characteristics(Non LCD pins) — High Drive (PTxDSn = 1)



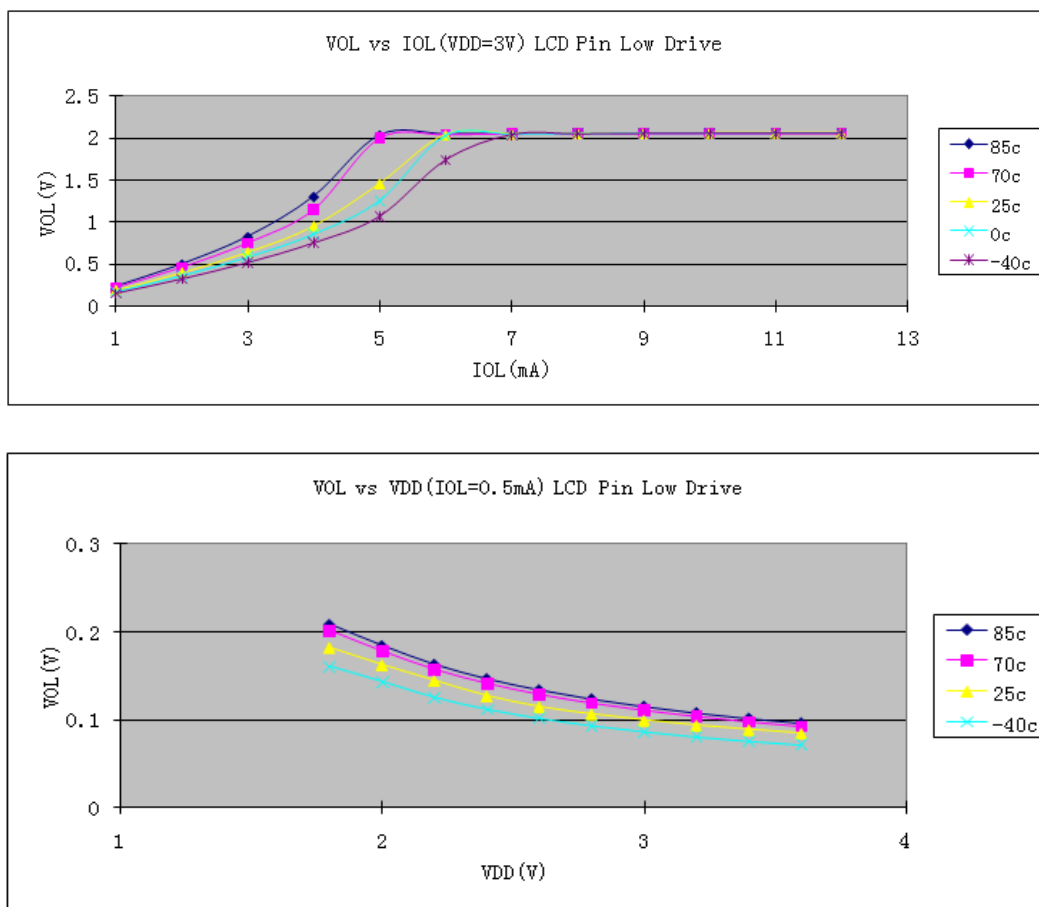


Figure 10. Typical Low-Side Driver (Sink) Characteristics(LCD/GPIO pins) — Low Drive (PTxDSn = 0)

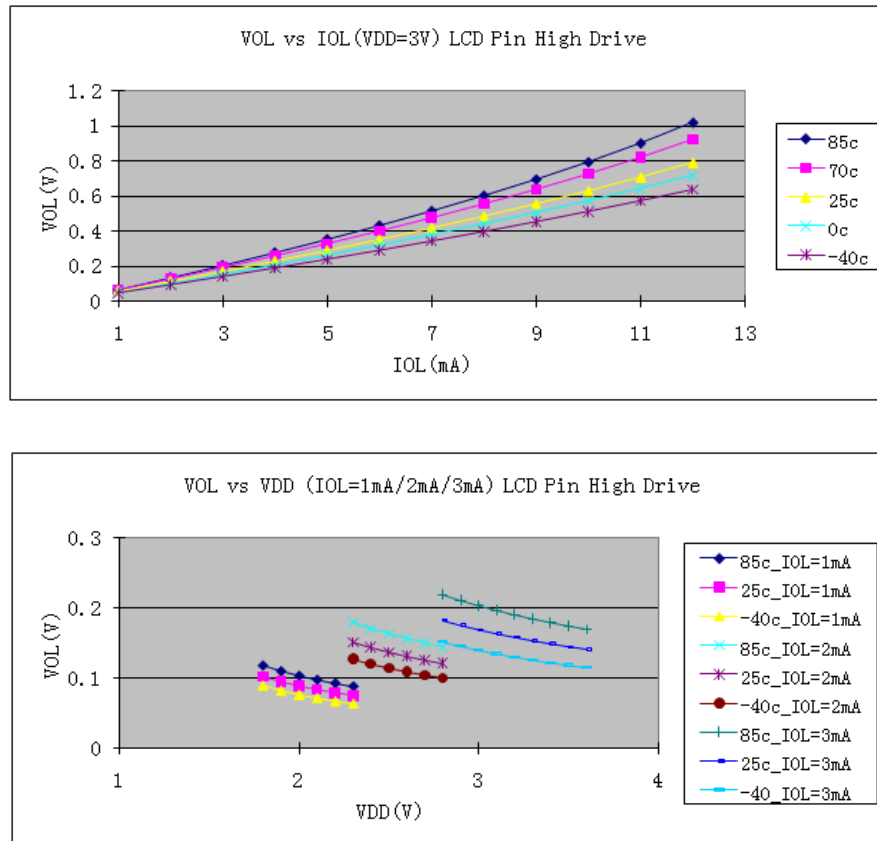


Figure 11. Typical Low-Side Driver (Sink) Characteristics(LCD/GPIO pins) — High Drive (PTxDSn = 1)

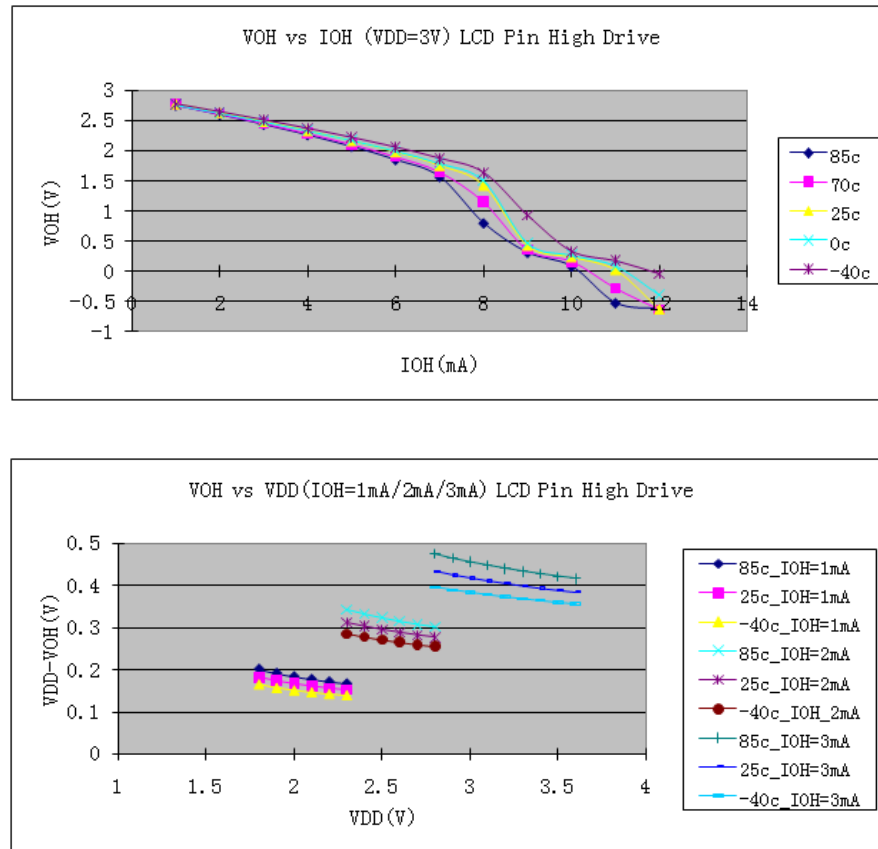


Figure 13. Typical High-Side (Source) Characteristics(LCD/GPIO pins) — High Drive (PTxDSn = 1)

### 3.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Table 9. Supply Current Characteristics

Num	C	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typ <sup>1</sup>	Max	Unit	Temp (°C)
1	C	Run supply current FEI mode, all modules on, running from Flash	R <sub>IDD</sub>	20 MHz	3	17.4	20.5	mA	-40 to 85°C
	T			2 MHz		2.6	—		
2	C	Run supply current FEI mode, all modules off, running from Flash	R <sub>IDD</sub>	20 MHz	3	10.5	—	mA	-40 to 85°C
	T			2 MHz		1.6	—		
3	T	Run supply current LPRS=0, all modules off, running from Flash	R <sub>IDD</sub>	16 kHz FBILP	3	158	—	μA	-40 to 85°C
	T			16 kHz FBELP		148	—		
4	T	Run supply current LPRS=1, all modules off; running from Flash	R <sub>IDD</sub>	16 kHz FBILP	3	160	—	μA	-40 to 85°C
	T			16 kHz FBELP		23	—		

### 3.8 External Oscillator (XOSCVLP) Characteristics

Reference [Figure 14](#) and [Figure 15](#) for crystal or resonator circuits.

**Table 11. XOSCVLP and ICS Specifications (Temperature Range = –40 to 85°C Ambient)**

Num	C	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1) High range (RANGE = 1), low power (HGO = 0)	$f_{lo}$ $f_{hi}$ $f_{hi}$	32 1 1	— — —	38.4 16 8	kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO=0) Other oscillator settings	$C_1, C_2$	See Note <sup>2</sup> See Note <sup>3</sup>			
3	D	Feedback resistor Low range, low power (RANGE=0, HGO=0) <sup>2</sup> Low range, high gain (RANGE=0, HGO=1) High range (RANGE=1, HGO=X)	$R_F$	— — —	— 10 1	— — —	MΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0) <sup>2</sup> Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	$R_S$	— — — — — — —	— 100 0 0 0 0 0	— — — 0 10 20	kΩ
5	C	Crystal start-up time <sup>4</sup> Low range, low power Low range, high gain High range, low power High range, high gain	$t_{CSTL}$ $t_{CSTH}$	— — — —	600 400 5 15	— — — —	ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	$f_{extal}$	0.03125 0	— —	20 20	MHz MHz

<sup>1</sup> Data in Typical column was characterized at 3.0 V, 25°C or is typical recommended value.

<sup>2</sup> Load capacitors ( $C_1, C_2$ ), feedback resistor ( $R_F$ ) and series resistor ( $R_S$ ) are incorporated internally when RANGE=HGO=0.

<sup>3</sup> See crystal or resonator manufacturer's recommendation.

<sup>4</sup> Proper PC board layout procedures must be followed to achieve specifications.

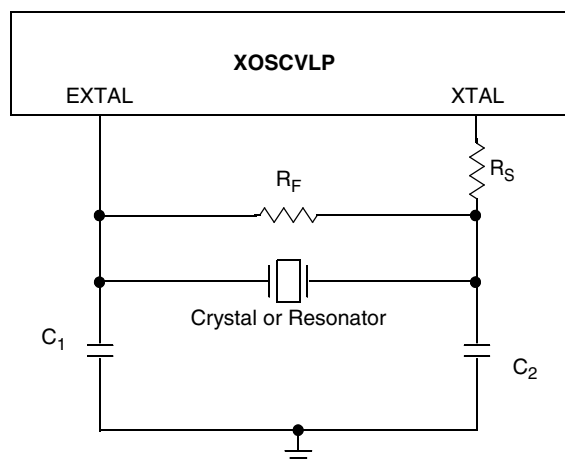


Figure 14. Typical Crystal or Resonator Circuit: High Range and Low Range/High Gain

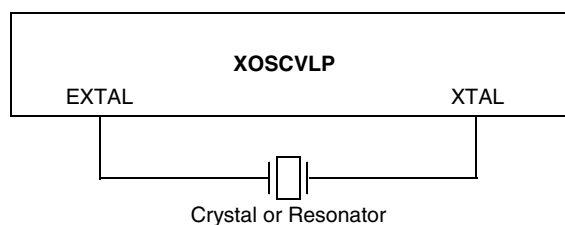


Figure 15. Typical Crystal or Resonator Circuit: Low Range/Low Power

### 3.9 Internal Clock Source (ICS) Characteristics

Table 12. ICS Frequency Specifications (Temperature Range = -40 to 85°C Ambient)

Num	C	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	P	Average internal reference frequency — factory trimmed at VDD = 3.6 V and temperature = 25 °C	$f_{int\_ft}$	—	32.768	—	kHz
2	P	Average internal reference frequency - trimmed	$f_{int\_t}$	31.25	—	39.063	kHz
3	T	Internal reference start-up time	$t_{IRST}$	—	—	6	μs
4	P	DCO output frequency range - untrimmed	$f_{dco\_ut}$	12.8	16.8	21.33	MHz
5	P	DCO output frequency range - trimmed	$f_{dco\_t}$	16	—	20	MHz
6	C	Resolution of trimmed DCO output frequency at fixed voltage and temperature (using FTRIM)	$\Delta f_{dco\_res\_t}$	—	± 0.1	± 0.2	% $f_{dco}$
7	C	Resolution of trimmed DCO output frequency at fixed voltage and temperature (not using FTRIM)	$\Delta f_{dco\_res\_t}$	—	± 0.2	± 0.4	% $f_{dco}$
8	C	Total deviation from trimmed DCO output frequency over voltage and temperature	$\Delta f_{dco\_t}$	—	+ 0.5 - 1.0	± 2	% $f_{dco}$

Table 12. ICS Frequency Specifications (Temperature Range = -40 to 85°C Ambient) (continued)

Num	C	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
9	C	Total deviation from trimmed DCO output frequency over fixed voltage and temperature range of 0°C to 70 °C	$\Delta f_{\text{dco\_t}}$	—	$\pm 0.5$	$\pm 1$	% $f_{\text{dco}}$
10	C	FLL acquisition time <sup>2</sup>	$t_{\text{Acquire}}$	—	—	1	ms
11	C	Long term jitter of DCO output clock (averaged over 2-ms interval) <sup>3</sup>	$C_{\text{Jitter}}$	—	0.02	0.2	% $f_{\text{dco}}$

<sup>1</sup> Data in Typical column was characterized at 3.0 V, 25°C or is typical recommended value.

<sup>2</sup> This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

<sup>3</sup> Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum  $f_{\text{Bus}}$ . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via  $V_{\text{DD}}$  and  $V_{\text{SS}}$  and variation in the crystal oscillator frequency increase the  $C_{\text{Jitter}}$  percentage for a given interval.

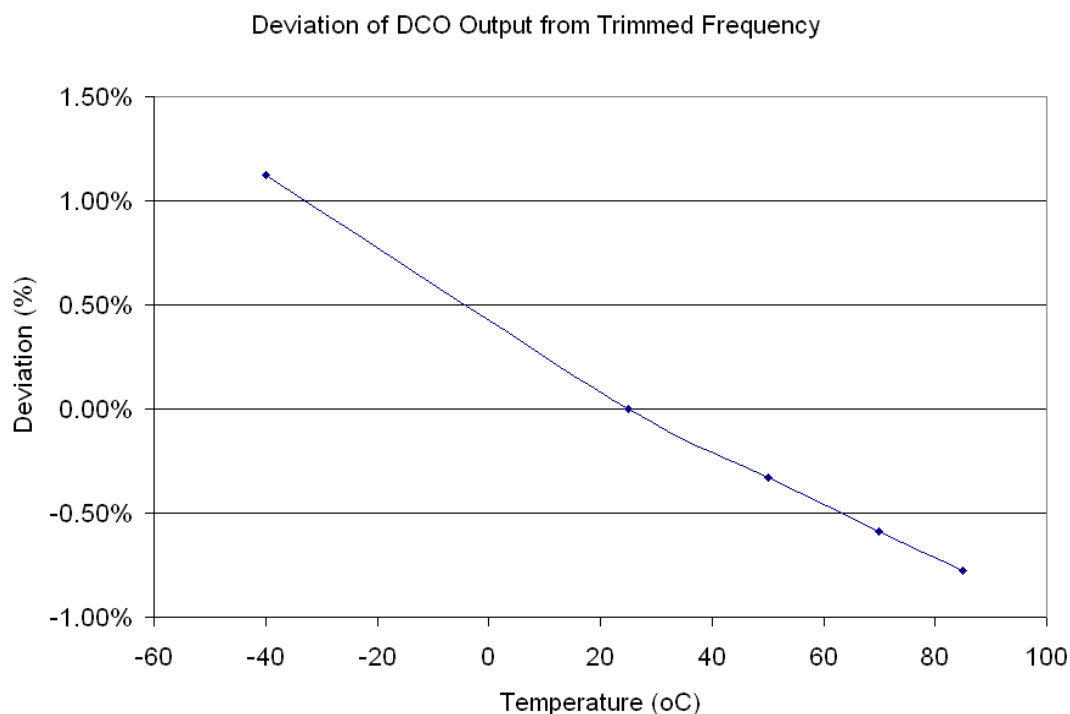


Figure 16. Deviation of DCO Output from Trimmed Frequency (20 MHz, 3.0 V)

### 3.10 AC Characteristics

This section describes timing characteristics for each peripheral system.

### 3.10.1 Control Timing

Table 13. Control Timing

Num	C	Rating	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	D	Bus frequency ( $t_{cyc} = 1/f_{Bus}$ )	$f_{Bus}$	dc	—	20	MHz
2	D	Internal low power oscillator period	$t_{LPO}$	700	—	1300	$\mu s$
3	D	External reset pulse width <sup>2</sup>	$t_{extrst}$	100	—	—	ns
4	D	Reset low drive	$t_{rstdrv}$	$34 \times t_{cyc}$	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	$t_{MSSU}$	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup>	$t_{MSH}$	100	—	—	$\mu s$
7	D	IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	$t_{ILIH}, t_{IHIL}$	100 $1.5 \times t_{cyc}$	— —	— —	ns
8	D	Keyboard interrupt pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	$t_{ILIH}, t_{IHIL}$	100 $1.5 \times t_{cyc}$	— —	— —	ns
9	C	Port rise and fall time — Non-LCD Pins Low output drive (PTxDS = 0) (load = 50 pF) <sup>5, 6</sup> Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	$t_{Rise}, t_{Fall}$	— —	16 23	— —	ns
		Port rise and fall time — Non-LCD Pins High output drive (PTxDS = 1) (load = 50 pF) <sup>5, 6</sup> Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	$t_{Rise}, t_{Fall}$	— —	5 9	— —	ns
10	C	Voltage Regulator Recovery time	$t_{VRR}$	—	6	10	$\mu s$

<sup>1</sup> Typical values are based on characterization data at  $V_{DD} = 3.0$  V, 25°C unless otherwise stated.

<sup>2</sup> This is the shortest pulse that is guaranteed to be recognized as a reset pin request.

<sup>3</sup> To enter BDM mode following a POR, BKGD/MS should be held low during the power-up and for a hold time of  $t_{MSH}$  after  $V_{DD}$  rises above  $V_{LVD}$ .

<sup>4</sup> This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.

<sup>5</sup> Timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  levels. Temperature range –40°C to 85°C.

<sup>6</sup> Except for LCD pins in Open Drain mode.

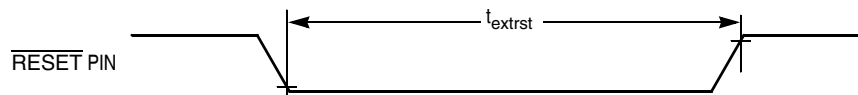
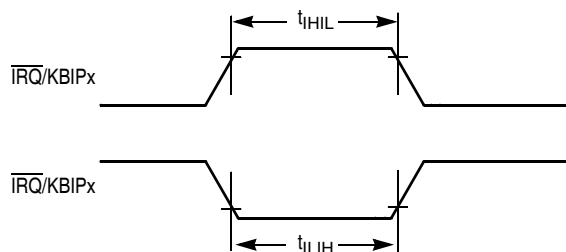


Figure 17. Reset Timing

Figure 18.  $\overline{\text{IRQ}}/\text{KBIPx}$  Timing

### 3.10.2 Timer (TPM/FTM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 14. TPM Input Timing

No.	C	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	$f_{\text{TCLK}}$	0	$f_{\text{Bus}}/4$	Hz
2	D	External clock period	$t_{\text{TCLK}}$	4	—	$t_{\text{cyc}}$
3	D	External clock high time	$t_{\text{clkh}}$	1.5	—	$t_{\text{cyc}}$
4	D	External clock low time	$t_{\text{clkl}}$	1.5	—	$t_{\text{cyc}}$
5	D	Input capture pulse width	$t_{\text{ICPW}}$	1.5	—	$t_{\text{cyc}}$

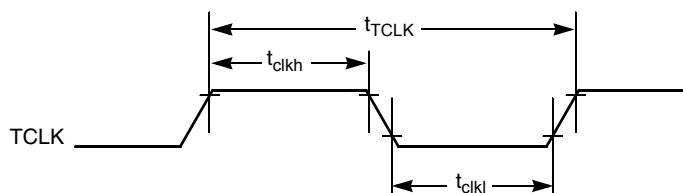
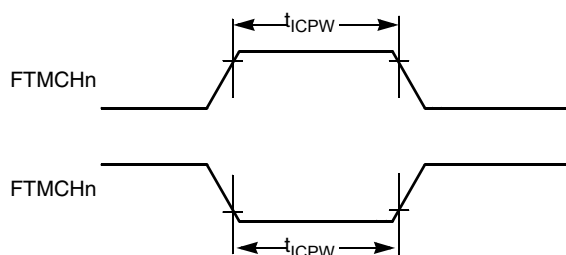
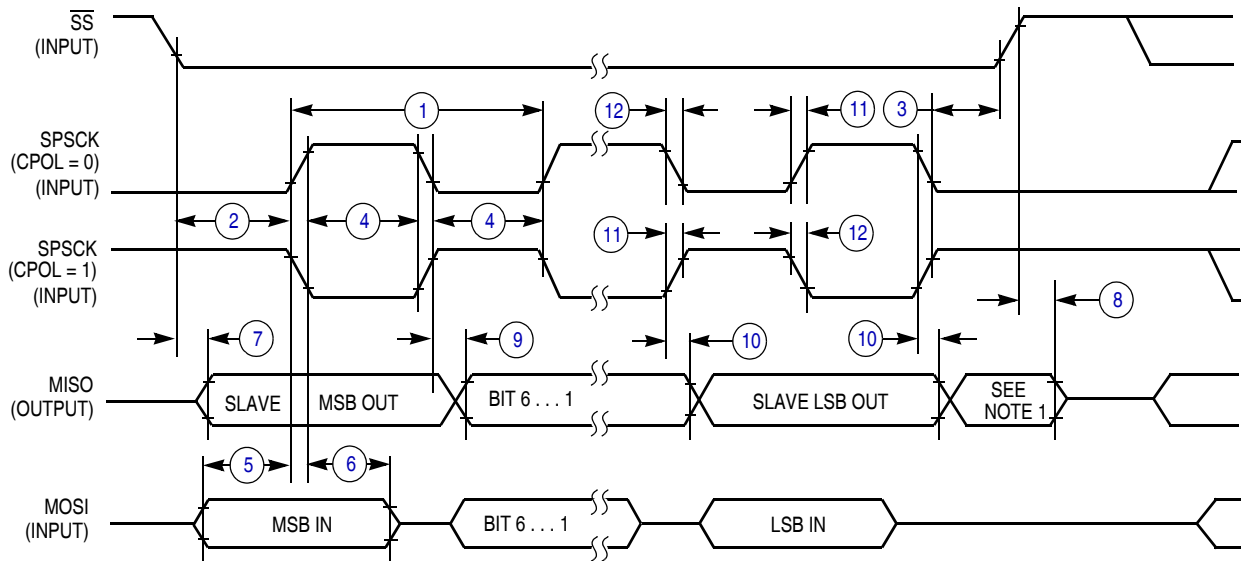


Figure 19. Timer External Clock



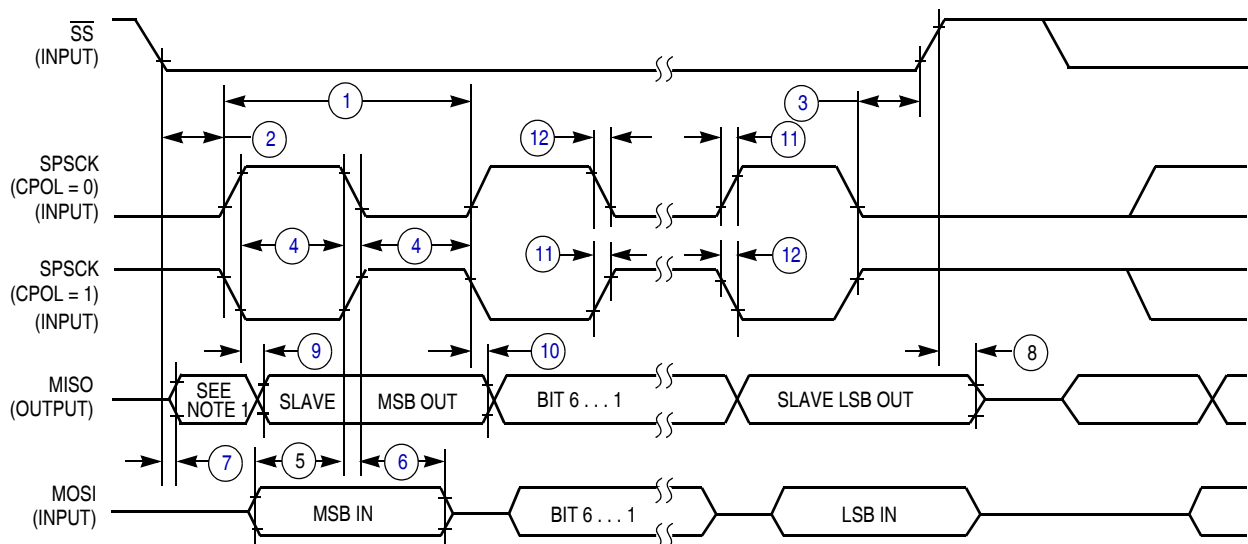




NOTE:

1. Not defined but normally MSB of character just received.

Figure 22. SPI Slave Timing (CPHA = 0)



NOTE:

1. Not defined but normally LSB of character just received.

Figure 23. SPI Slave Timing (CPHA = 1)

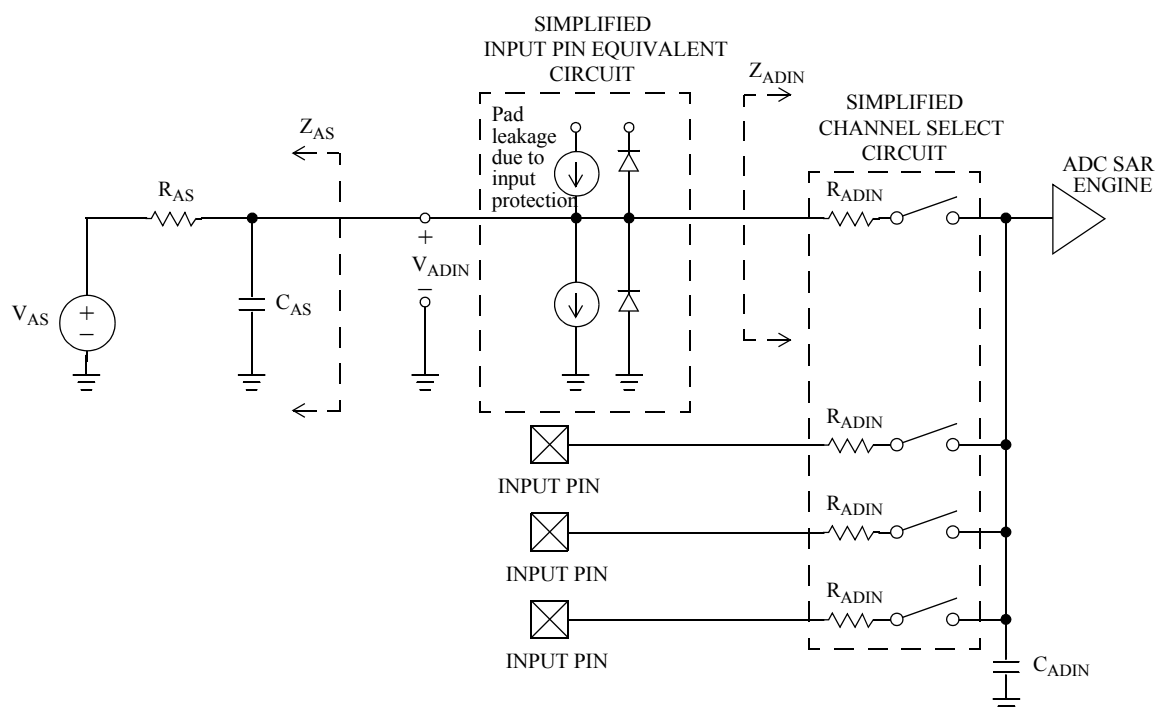


Figure 24. ADC Input Impedance Equivalency Diagram

Table 18. 16-bit ADC Characteristics full operating range( $V_{REFH} = V_{DDAD}$ ,  $V_{REFL} = V_{SSAD}$ ,  $F_{ADCK} \leq 10\text{MHz}$ )

Characteristic	Conditions <sup>1</sup>	C	Symb	Min	Typ <sup>2</sup>	Max	Unit	Comment
Supply Current	ADLPC = 1, ADHSC = 0	T	I <sub>DDA</sub>	—	215	—	μA	ADLSMP = 0 ADCO = 1
	ADLPC = 0, ADHSC = 0			—	540	—		
	ADLPC=0, ADHSC=1			—	610	—		
Supply Current	Stop, Reset, Module Off	C	I <sub>DDA</sub>	—	0.072	—	μA	
ADC Asynchronous Clock Source	ADLPC = 1, ADHSC = 0	P	f <sub>ADACK</sub>	—	2.4	—	MHz	t <sub>ADACK</sub> = 1/f <sub>ADACK</sub>
	ADLPC = 0, ADHSC = 0			—	5.2	—		
	ADLPC = 0, ADHSC = 1			—	6.2	—		
Sample Time	See reference manual for sample times							
Conversion Time	See reference manual for conversion times							

<sup>1</sup> All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDAD}$

<sup>2</sup> Typical values assume  $V_{DDAD} = 3.0\text{V}$ , Temp =  $25^\circ\text{C}$ ,  $f_{ADCK} = 2.0\text{ MHz}$  unless otherwise stated. Typical values are for reference only and are not tested in production.

### 3.14 LCD Specifications

Table 21. LCD Electricals, 3-V Glass

C	Characteristic	Symbol	Min	Typ	Max	Unit
D	LCD Frame Frequency	$f_{\text{Frame}}$	28	30	58	Hz
D	LCD Charge Pump Capacitance	$C_{\text{LCD}}$		100	100	nF
D	LCD Bypass Capacitance	$C_{\text{BYLCD}}$		100	100	nF
D	LCD Glass Capacitance	$C_{\text{glass}}$		2000	8000	pF
D	$V_{\text{IREG}}$ HRefSel = 0 HRefSel = 1	$V_{\text{IREG}}$	.89 1.49	1.00 1.67	1.15 1.85 <sup>1</sup>	V
D	$V_{\text{IREG}}$ TRIM Resolution	$\Delta_{\text{RTRIM}}$	1.5			% $V_{\text{IREG}}$
D	$V_{\text{IREG}}$ Ripple HRefSel = 0 HRefSel = 1				.1 .15	V

<sup>1</sup>  $V_{\text{IREG}}$  Max can not exceed  $V_{\text{DD}} - 0.15$  V

### 3.15 FLASH Specifications

This section provides details about program/erase times and program-erase endurance for the FLASH memory.

Program and erase operations do not require any special power sources other than the normal  $V_{\text{DD}}$  supply. For more detailed information about program/erase operations, see the Memory section.

Table 22. FLASH Characteristics

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage for program/erase -40°C to 85°C	$V_{\text{prog/erase}}$	1.8		3.6	V
D	Supply voltage for read operation	$V_{\text{Read}}$	1.8		3.6	V
D	Internal FCLK frequency <sup>1</sup>	$f_{\text{FCLK}}$	150		200	kHz
D	Internal FCLK period (1/FCLK)	$t_{\text{Fcyc}}$	5		6.67	μs
P	Byte program time (random location) <sup>2</sup>	$t_{\text{prog}}$	9			$t_{\text{Fcyc}}$
P	Byte program time (burst mode) <sup>2</sup>	$t_{\text{Burst}}$	4			$t_{\text{Fcyc}}$
P	Page erase time <sup>2</sup>	$t_{\text{Page}}$	4000			$t_{\text{Fcyc}}$
P	Mass erase time <sup>2</sup>	$t_{\text{Mass}}$	20,000			$t_{\text{Fcyc}}$
D	Byte program current <sup>3</sup>	$R_{\text{IDDBP}}$	—	4	—	mA
D	Page erase current <sup>3</sup>	$R_{\text{IDDPE}}$	—	6	—	mA
C	Program/erase endurance <sup>4</sup> $T_{\text{L}}$ to $T_{\text{H}}$ = -40°C to + 85°C $T = 25^\circ\text{C}$		10,000	— 100,000	— —	cycles
C	Data retention <sup>5</sup>	$t_{\text{D-ret}}$	15	100	—	years

<sup>1</sup> The frequency of this clock is controlled by a software setting.

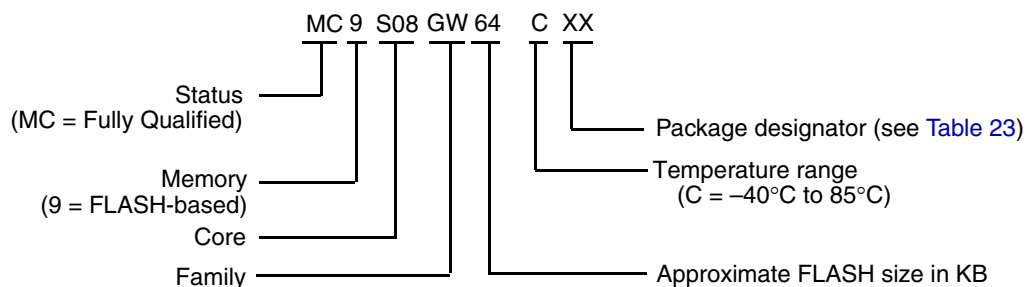
- <sup>2</sup> These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.
- <sup>3</sup> The program and erase currents are additional to the standard run  $I_{DD}$ . These values are measured at room temperatures with  $V_{DD} = 3.0$  V, bus frequency = 4.0 MHz.
- <sup>4</sup> Typical endurance for FLASH was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory*.
- <sup>5</sup> Typical data retention values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory*.

## 4 Ordering Information

This section contains the ordering information and the device numbering system for the MC9S08GW64 Series.

### 4.1 Device Numbering System

Example of the device numbering system:



## 5 Package Information and Mechanical Drawings

Table 23 provides the available package types and their document numbers. The latest package outline/mechanical drawings are available on the MC9S08GW64 Series Product Summary pages at <http://www.freescale.com>.

To view the latest drawing, either:

- Click on the appropriate link in Table 23, or
- Open a browser to the Freescale® website (<http://www.freescale.com>), and enter the appropriate document number (from Table 23) in the “Enter Keyword” search box at the top of the page.

**Table 23. Package Descriptions**

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
80	Low Quad Flat Package	LQFP	LK	917A	<a href="#">98ASS23237W</a>
64	Low Quad Flat Package	LQFP	LH	840F	<a href="#">98ASS23234W</a>

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