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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	-
Core Size	8-Bit
Speed	12MHz
Connectivity	SIO, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	18
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 7x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-LFSOP (0.173", 4.40mm Width)
Supplier Device Package	24-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/onsemi/lc87f0g08auja-zh

Function Details**■Flash ROM**

- Capable of on-board programming with a wide range of supply voltages : 2.2 to 5.5V
- Block-erasable in 128 byte units
- Writes data in 2-byte units
- 8192×8 bits

■RAM

- 256×9 bits

■Bus Cycle Time

- 83.3ns (12MHz, $V_{DD}=2.7V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)
- 125ns (8MHz, $V_{DD}=2.0V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)
- 250ns (4MHz, $V_{DD}=1.8V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)

Note : The bus cycle time here refers to the ROM read speed.

■Minimum Instruction Cycle Time (tCYC)

- 250ns (12MHz, $V_{DD}=2.7V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)
- 375ns (8MHz, $V_{DD}=2.0V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)
- 750ns (4MHz, $V_{DD}=1.8V$ to 5.5V, $T_a=-40^{\circ}C$ to $85^{\circ}C$)

■Potrs

- Normal withstand voltage I/O ports whose I/O direction can be designated in 1-bit units
18(P0n, P1n, P70, CF1, CF2)
- Reset pins
1(\overline{RES})
- Power supply pins
3(V_{SS1} , V_{SS2} , V_{DD1})
- Reference voltage outputs
1(V_{REF})
- Dedicated debugger port
1(OWP0)

■Timers

- Timer 0 : 16-bit timer/counter with 2 capture registers.
 - Mode 0 : 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) \times 2 channels
 - Mode 1 : 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers)
+ 8-bit counter (with two 8-bit capture registers)
 - Mode 2 : 16-bit timer with an 8-bit programmable prescaler (with two 16-bit capture registers)
 - Mode 3 : 16-bit counter (with two 16-bit capture registers)
- Timer 1 : 16-bit timer/counter that supports PWM/toggle outputs
 - Mode 0 : 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/
counter with an 8-bit prescaler (with toggle outputs)
 - Mode 1 : 8-bit PWM with an 8-bit prescaler \times 2 channels
 - Mode 2 : 16-bit timer/counter with an 8-bit prescaler (with toggle outputs)
(toggle outputs also possible from lower-order 8 bits)
 - Mode 3 : 16-bit timer with an 8-bit prescaler (with toggle outputs)
(lower-order 8 bits may be used as a PWM output)
- Base timer
 - (1) The clock is selectable from the subclock (32.768kHz crystal oscillation), the low speed RC, system clock, and timer 0 prescaler output.
 - (2) with an 8-bit programmable prescaler
 - (3) Interrupts programmable in 5 different time schemes

■SIO

- SIO1 : 8-bit asynchronous/synchronous serial interface
 - Mode 0 : Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
 - Mode 1 : Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
 - Mode 2 : Bus mode 1 (start detect, 8 data bits, 2 to 512 tCYC transfer clocks)
 - Mode 3 : Bus mode 2 (start detect, 8 data bits, stop detect)

■AD Converter:

- AD converter input port with $10 \times /20 \times$ amplifier (1channel)
- AD converter input port (7channel)
 - 12-/8-bit resolution selectable AD converter
- Selectable reference voltage source for an AD converter
(Selectable from V_{DD} , Internal Reference Voltage Generator Circuit(VREF) .)

■Internal Reference Voltage Generator Circuit(VREF)

- Generates 2.0V/4.0V for AD converter.

■Comparator

Comparator input pin (1 channel)
Comparator output pin (1 channel)
Comparator output set high when (comparator input level) < 1.22V
Comparator output set low when (comparator input level) > 1.22V

■Clock Output Function

- Generates clocks with a clock rate of 1/1, 1/2, 1/4, 1/8, 1/16, 1/32, or 1/64 of the source oscillation clock that is selected as the system clock.

■Watchdog Timer

- Generates an internal reset on an overflow occurring in the timer running on the low-speed RC oscillator clock (approx. 30kHz) or subclock.
- Operating mode at standby is selectable from 3 modes
(continue counting/suspend operation/suspend counting with the count value retained)

■Interrupts

- 15 sources, 10 vectors

- 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
- 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address is given priority.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4
4	0001BH	H or L	INT3/BT
5	00023H	H or L	T0H
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	HPWM2
8	0003BH	H or L	SIO1
9	00043H	H or L	ADC
10	0004BH	H or L	P0/VCPWM

- Priority levels $X > H > L$
- Of interrupts of the same level, the one with the smallest vector address takes precedence.

■Subroutine Stack Levels: Up to 128levels (the stack is allocated in RAM.)**■High-speed Multiplication/Division Instructions**

- 16 bits \times 8 bits (5 tCYC execution time)
- 24 bits \times 16 bits (12 tCYC execution time)
- 16 bits \div 8 bits (8 tCYC execution time)
- 24 bits \div 16 bits (12 tCYC execution time)

■Oscillation Circuits

- Internal oscillation circuits
 - 1) Low-speed RC oscillation circuit: For system clock (approx.30kHz)
 - 2) Medium-speed RC oscillation circuit: For system clock (1MHz)
 - 3) Hi-speed RC oscillation circuit1: For system clock (8MHz)
 - 4) Hi-speed RC oscillation circuit2: For High speed PWM (40MHz)

■System Clock Divider Function

- Can run on low consumption current.
- Minimum instruction cycle selectable from 375ns, 750ns, 1.5 μ s, 3.0 μ s, 6.0 μ s, 12.0 μ s, 24.0 μ s, 48.0 μ s, and 96.0 μ s (at 8MHz main clock)

■Internal Reset Circuit

- Power-on reset (POR) function
 - 1) POR reset is generated only at power-on time.
 - 2) The POR release level is 1.67V.
- Low-voltage detection reset (LVD) function
 - 1) LVD and POR functions are combined to generate resets when power is turned on and when power voltage falls below a certain level.
 - 2) The use/disuse of the LVD function and the low voltage threshold level can be selected from 7 levels (1.91V, 2.01V, 2.31V, 2.51V, 2.81V, 3.79V and 4.28V), through option configuration.

■ Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
 - 1) Oscillation is not halted automatically.
 - 2) There are three ways of resetting the HALT mode.
 - (1) Setting the reset pin to the low level
 - (2) Having the watchdog timer or LVD function generate a reset
 - (3) Having an interrupt generated
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
 - 1) The CF, RC and crystal oscillators automatically stop operation.

Note: The low-speed RC oscillator is controlled directly by the watchdog timer; its oscillation in the standby mode is also controlled by the watchdog timer.
 - 2) There are four ways of resetting the HOLD mode:
 - (1) Setting the reset pin to the lower level
 - (2) Having the watchdog timer or LVD function generate a reset
 - (3) Having an interrupt source established at one of the INT0, INT1, INT2 and INT4 pins
* INT0 and INT1 can be used in the level sense mode only.
 - (4) Having an interrupt source established at port 0.
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer. (when X'tal oscillation or low-speed RC oscillation is selected).
 - 1) The CF, low-speed, and medium-speed RC oscillators automatically stop operation.

Note: The low-speed RC oscillator is controlled directly by the watchdog timer; its oscillation in the standby mode is also controlled by the watchdog timer.

Note: If the base timer is run with low-speed RC oscillation selected as the base timer input clock source and the X'tal HOLD mode is entered, the low-speed RC oscillator retains the state that is established when the X'tal HOLD mode is entered.
 - 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - 3) There are five ways of resetting the X'tal HOLD mode.
 - (1) Setting the reset pin to the low level
 - (2) Having the watchdog timer or LVD function generate a reset
 - (3) Having an interrupt source established at one of the INT0, INT1, INT2, and INT4 pins
* INT0 and INT1 can be used in the level sense mode only.
 - (4) Having an interrupt source established at port 0
 - (5) Having an interrupt source established in the base timer circuit

■ VCPWM: Frequency tunable 12-bit PWM × 2ch

■ High speed PWM (HPWM2)

8-/10- bits PWM × 1ch

- 1) The PWM clock is selectable from system clock and Hi-speed RC2 (40MHz)
- 2) The PWM type is selectable from 8 bits(Normal mode) and 10 bits(additive puls mode).

■ Temperature sensor

- Sensor voltage can be compared by the AD converter.

■ On-chip Debugger Function

- Supports software debugging with the IC mounted on the target board.
- Provides 1 channel of on-chip debugger pin.
OWP0

■ Data Security Function

- Protects the program data stored in flash memory from unauthorized read or copy.

Note: This data security function does not necessarily provide absolute data security.

■ Package Form

- SSOP24 (225mil): Lead-free and halogen-free type

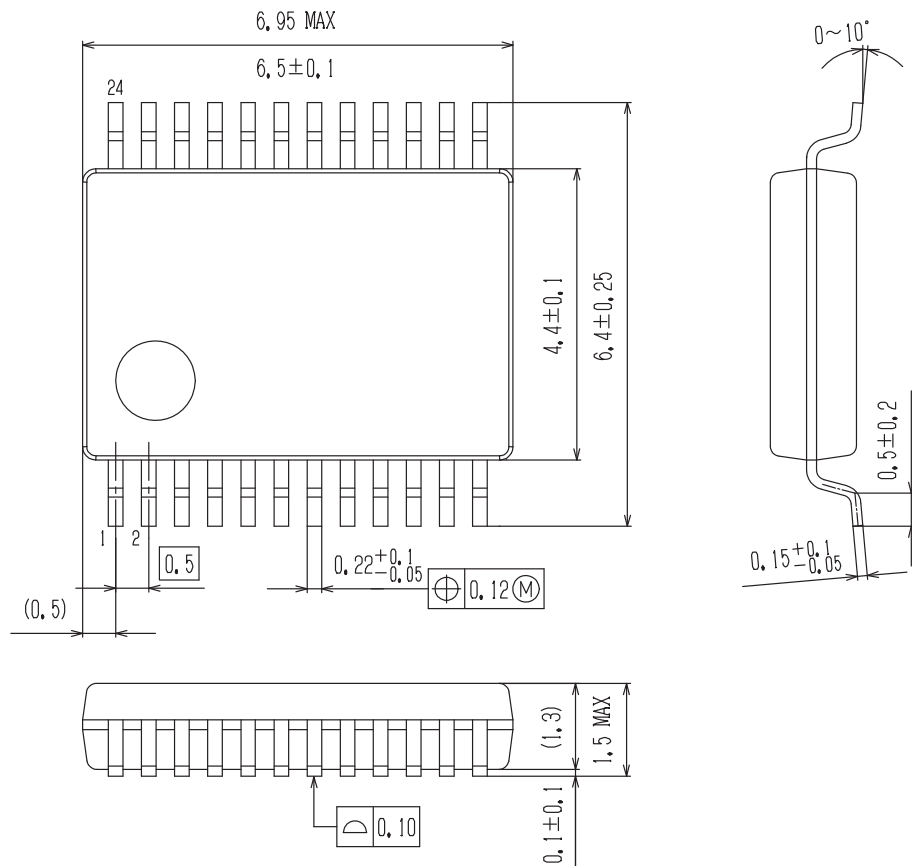
Package Dimensions

unit : mm

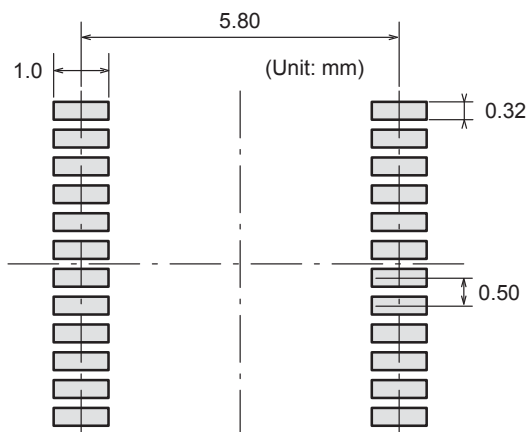
SSOP24 (225mil)

CASE 565AR

ISSUE A



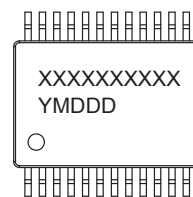
SOLDERING FOOTPRINT*



NOTE: The measurements are not to guarantee but for reference only.

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

GENERIC MARKING DIAGRAM*



XXXXX = Specific Device Code

Y = Year

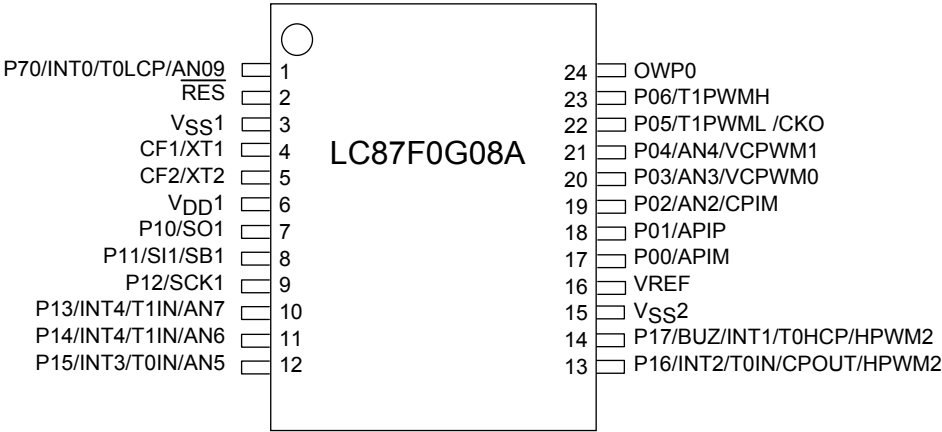
M = Month

DDD = Additional Traceability Data

*This information is generic. Please refer to device data sheet for actual part marking.
Pb-Free indicator, "G" or microdot "▪", may or may not be present.

LC87F0G08A

Pin Assignment

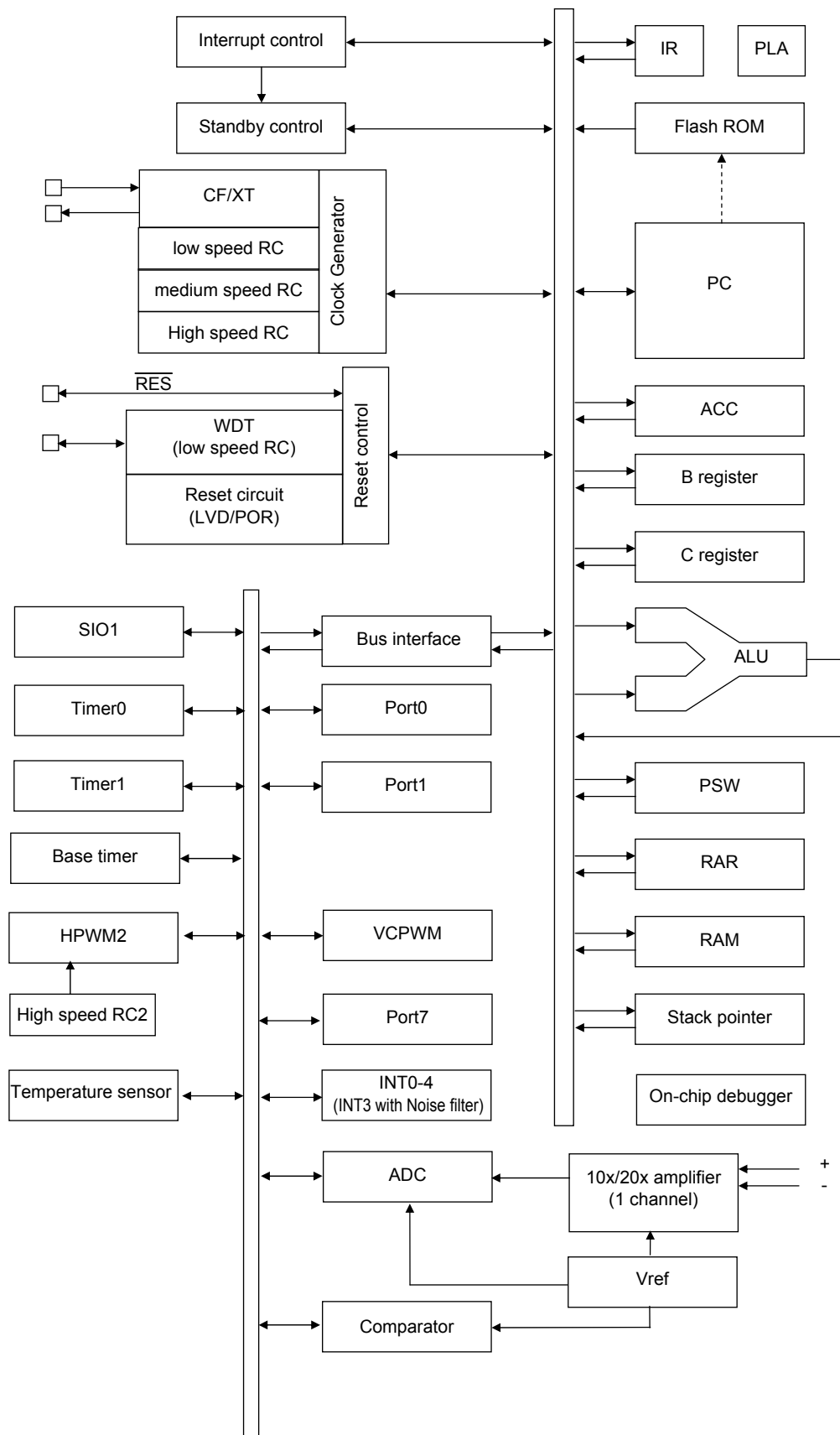


SSOP24(225mil) "Lead-/Halogen-free Type"

SSOP24	NAME
1	P70/INT0/T0LCP/AN09
2	RES
3	VSS1
4	CF1/XT1
5	CF2/XT2
6	VDD1
7	P10/SO1
8	P11/SI1/SB1
9	P12/SCK1
10	P13/INT4/T1IN/AN7
11	P14/INT4/T1IN/AN6
12	P15/INT3/T0IN/AN5

SSOP24	NAME
13	P16/INT2/T0IN/CPOUT/HPWM2
14	P17/BUZ/INT1/T0HCP/HPWM2
15	VSS2
16	VREF
17	P00/APIM
18	P01/APIP
19	P02/AN2/CPIM
20	P03/AN3/VCPWM0
21	P04/AN4/VCPWM1
22	P05/T1PWML/CKO
23	P06/T1PWMH
24	OWP0

System Block Diagram



LC87F0G08A

Continued from preceding page.

Pin Name	I/O	Description	Option												
Port 7	I/O	<ul style="list-style-type: none">• 1-bit I/O port• I/O specifiable• Pull-up resistors can be turned on and off. <ul style="list-style-type: none">• Pin functions <p>P70 : INT0 input/HOLD release input/timer 0L capture input/AD converter input port (AN9)</p> <p>Interrupt acknowledge type</p> <table><tr><td></td><td>Rising</td><td>Falling</td><td>Rising & Falling</td><td>H level</td><td>L level</td></tr><tr><td>INT0</td><td>enable</td><td>enable</td><td>disable</td><td>enable</td><td>enable</td></tr></table>		Rising	Falling	Rising & Falling	H level	L level	INT0	enable	enable	disable	enable	enable	No
			Rising	Falling	Rising & Falling	H level	L level								
INT0			enable	enable	disable	enable	enable								
P70															
$\overline{\text{RES}}$	I	External reset input/internal reset output pin	Yes Internal pullup ON/OFF												
CF1/XT1	I/O	<ul style="list-style-type: none">• Ceramic oscillator/32.768kHz crystal oscillator input pin <ul style="list-style-type: none">• Pin functions• 1-bit I/O port• I/O specifiable (only Nch-open drain)	No												
CF2/XT2	I/O	<ul style="list-style-type: none">• Ceramic oscillator/32.768kHz crystal oscillator output pin <ul style="list-style-type: none">• Pin functions• 1-bit I/O port• I/O specifiable	No												
OWP0	I/O	On-chip debugger pin	No												

LC87F0G08A

Absolute Maximum Ratings at Ta = 25°C, VSS1 = VSS2 = 0V

Parameter		Symbol	Pin/Remarks	Conditions	VDD[V]	Specification			
						min	typ	max	unit
Maximum supply voltage		VDDMAX	VDD1			-0.3	to	+6.5	V
Input/output voltage		VIO	Port0,1 Port7 CF1,CF2, $\overline{\text{RES}}$			-0.3	to	VDD+0.3	
High level output current	Peak output current	IOPH(1)	Port0 Port1 CF2	<ul style="list-style-type: none"> When CMOS output type is selected Per 1 applicable pin 		-10			mA
	Average output current (Note 1-1)	IOMH(1)	Port0 Port1 CF2	<ul style="list-style-type: none"> When CMOS output type is selected Per 1 applicable pin 		-7.5			
	Total output current	ΣIOAH(1)	Port0,1, CF2	Total current of all applicable pins		-30			
Low level output current	Peak output current	IOPL(1)	Port0	• Per 1 applicable pin				20	mA
		IOPL(2)	Port1	• Per 1 applicable pin				20	
		IOPL(3)	Port7,CF1,CF2	• Per 1 applicable pin				10	
	Average output current (Note 1-1)	IOML(1)	Port0	• Per 1 applicable pin				15	
		IOML(2)	Port1	• Per 1 applicable pin				15	
		IOML(3)	Port7,CF1,CF2	• Per 1 applicable pin				7.5	
	Total output current	ΣIOAL(1)	Port0,1,7, CF1,CF2	Total current of all applicable pins				80	
Allowable power Dissipation		Pdmax(1)	SSOP24(225mil)	Ta=-40 to + 85°C Package with thermal resistance board (Note 1-2)				260	mW
Operating ambient Temperature		Topr				-40		+85	°C
Storage ambient temperature		Tstg				-55		+125	

Note 1-1: The average output current is an average of current values measured over 100ms intervals.

Note 1-2: SEMI standards thermal resistance board (size: 76.1×114.3×1.6mm, glass epoxy) is used.

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

LC87F0G08A

Allowable Operating Conditions at Ta = -40°C to +85°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	VDD[V]	Specification			unit
					min	typ	max	
Operating supply voltage (Note 2-1)	VDD(1)	VDD1	$0.245\mu\text{s} \leq \text{tCYC} \leq 200\mu\text{s}$		2.7		5.5	V
	VDD(2)		$0.367\mu\text{s} \leq \text{tCYC} \leq 200\mu\text{s}$		2.0		5.5	
	VDD(3)		$0.735\mu\text{s} \leq \text{tCYC} \leq 200\mu\text{s}$		1.8		5.5	
Memory sustaining supply voltage	VHD	VDD1	RAM and register contents sustained in HOLD mode.		1.6			
High level input voltage	VIH(1)	Port 0,1 P70		1.8 to 5.5	$0.3V_{DD} + 0.7$		VDD	
	VIH(4)	CF1,CF2, $\overline{\text{RES}}$		1.8 to 5.5	$0.75V_{DD}$		VDD	
Low level input voltage	VIL(1)	Port 0,1 P70		4.0 to 5.5	VSS		$0.1V_{DD} + 0.4$	
				1.8 to 4.0	VSS		$0.2V_{DD}$	
	VIL(4)	CF1,CF2, $\overline{\text{RES}}$		1.8 to 5.5	VSS		$0.25V_{DD}$	
Instruction cycle time (Note 2-2)	tCYC (Note 2-2)			2.7 to 5.5	0.245		200	μs
				2.0 to 5.5	0.367		200	
				1.8 to 5.5	0.735		200	
External system clock frequency	FEXCF	CF1	<ul style="list-style-type: none"> CF2 pin open System clock frequency division ratio=1/1 External system clock duty=50 ± 5% 	2.7 to 5.5	0.1		12	MHz
				2.2 to 5.5	0.1		8	
Oscillation frequency range (Note 2-3)	FmCF(1)	CF1,CF2	When 12MHz ceramic oscillation See Fig. 1.	2.7 to 5.5		12		MHz
	FmCF(2)	CF1,CF2	When 8MHz ceramic oscillation See Fig. 1.	2.2 to 5.5		8		
	FmCF(3)	CF1,CF2	When 4MHz ceramic oscillation See Fig. 1.	1.8 to 5.5		4		
	FmFRC(1)		Internal high-speed RC oscillation Ta=-10°C to +85°C (Note 2-4)	1.8 to 5.5	7.76	8.0	8.24	
	FmFRC(2)		Internal high-speed RC oscillation Ta=-40°C to +85°C (Note 2-4)	1.8 to 5.5	7.60	8.0	8.40	
	FmRC		Internal medium-speed RC oscillation	1.8 to 5.5	0.5	1.0	2.0	
	FmSRC		Internal low-speed RC oscillation (Note 2-5)	1.8 to 5.5	27	30	33	kHz
	FsX'tal	XT1,XT2	32.768kHz crystal oscillation See Fig. 2.	1.8 to 5.5		32.768		kHz
	FmPWMRC		Internal high-speed RC oscillation for HPWM2	2.7 to 5.5	38	40	42	MHz
Oscillation Stabilization Time	tmsCF	CF1,CF2	<ul style="list-style-type: none"> When oscillation circuit is switched from "oscillation stopped" to "oscillation enabled". See Fig. 3. 	See Table 1				μs
	tmsFRC (Note 2-4)			1.8 to 5.5			100	
	tmsPWMR C			1.8 to 5.5			100	
	tmsRC			1.8 to 5.5		0		
	tmsSRC (Note2-5)			1.8 to 5.5			1	ms
	tmsX'tal	XT1,XT2		See Table 2				

Note 2-1: VDD must be held greater than or equal to 2.7V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Note 2-3: See Tables 1 and 2 for the oscillation constants.

Note 2-4: An oscillation stabilization time of 100μs or longer must be provided before switching the system clock source after the state of the high-speed RC oscillation circuit is switched from "oscillation stopped" to "oscillation enabled".

Note 2-5: An oscillation stabilization time of 1ms or longer must be provided before switching the system clock source after the state of the low-speed RC oscillation circuit is switched from "oscillation stopped" to "oscillation enabled".

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

LC87F0G08A

Electrical Characteristics at Ta = -40°C to +85°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	VDD[V]	Specification			
					min	typ	max	unit
High level input current	I _{IH} (1)	Port 0,1, Port 7, $\overline{\text{RES}}$	Output disabled Pull-up resistor off V _{IN} =V _{DD} (Including output Tr's off leakage current)	1.8 to 5.5			1	μA
	I _{IH} (2)	CF1	V _{IN} =V _{DD}	1.8 to 5.5			15	
Low level input current	I _{IL} (1)	Port 0,1, Port 7, $\overline{\text{RES}}$	Output disabled Pull-up resistor off V _{IN} =V _{SS} (Including output Tr's off leakage current)	1.8 to 5.5	-1			μA
	I _{IL} (2)	CF1	V _{IN} =V _{SS}	1.8 to 5.5	-15			
High level output voltage	V _{OH} (1)	Port 0,1, CF2	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			V
	V _{OH} (2)		I _{OH} =-0.2mA	1.8 to 5.5	V _{DD} -0.4			
Low level output voltage	V _{OL} (1)	Port 0,1, P70,CF1,CF2	I _{OL} =10mA	4.5 to 5.5			1.5	
	V _{OL} (2)		I _{OL} =1.0mA	1.8 to 5.5			0.4	
Pull-up resistance	Rpu(1)	Port 0,1, P70	V _{OH} =0.9V _{DD}	4.5 to 5.5	15	35	80	k Ω
	Rpu(2)			1.8 to 4.5	18	50	230	
	Rpu(3)	$\overline{\text{RES}}$		1.8 to 5.5	300	400	500	
Hysteresis voltage	VHYS(1)	Port 0,1, P70		2.7 to 5.5		0.1V _{DD}		V
		$\overline{\text{RES}}$		1.8 to 5.5		0.07V _{DD}		
Pin capacitance	CP	All pins	For pins other than that under test: V _{IN} =V _{SS} f=1MHz Ta=25°C	1.8 to 5.5		10		pF

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

LC87F0G08A

<Recommended Operating Conditions>

External oscillation (FmCF)	Operating supply voltage range (V _{DD})	System division ratio (SYSDIV)	Cycle time (tCYC)	AD division ratio (ADDIV)	AD conversion time (TCAD)	
					12bit AD	8bit AD
CF-8MHz	2.7V to 5.5V	1/1	375ns	1/8	52.25μs	32.25μs
	2.2V to 5.5V	1/1	375ns	1/32	208.25μs	128.25μs
CF-4MHz	2.7V to 5.5V	1/1	750ns	1/8	104.5μs	64.5μs
	2.2V to 5.5V	1/1	750ns	1/16	208.5μs	128.5μs
	1.8V to 5.5V	1/1	750ns	1/32	416.5μs	256.5μs

Note 6-1: The quantization error ($\pm 1/2\text{LSB}$) is excluded from the absolute accuracy. The absolute accuracy is measured when no change occurs in the I/O state of the pins that are adjacent to the analog input channel during AD conversion processing.

Note 6-2: The conversion time refers to the interval from the time a conversion starting instruction is issued till the time the complete digital value against the analog input value is loaded in the result register.

The conversion time is twice the normal value when one of the following conditions occurs:

- The first AD conversion executed in the 12-bit AD conversion mode after a system reset
- The first AD conversion executed after the AD conversion mode is switched from 8-bit to 12-bit AD conversion mode

Note 6-3: See section 8, “10×/20× amplifier characteristics”, for analog channel 0 (10×/20× amplifier output).

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Reference Voltage Generator Circuit (VREF) Characteristics

at Ta = -40°C to +85°C, V_{SS1} = V_{SS2} = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
VREF=2V voltage accuracy	VREF2VO	VREF (Note 7-2)		1.8 to 2.0	V _{DD} -0.1		V _{DD}	V
				2.0 to 5.5	1.90		2.02	
				2.3 to 5.5	1.98		2.02	
VREF=4V voltage accuracy	VREF4VO			1.8 to 4.0	V _{DD} -0.1		V _{DD}	
				4.0 to 5.5	3.90		4.04	
				4.3 to 5.5	3.96		4.04	
VREFoutput current	VREFIO			1.8 to 5.5	V _{SS}		0.5	mA
Operation stabilization time (Note 7-1)	tVREFW			1.8 to 5.5			5	ms

Note 7-1: Refers to the interval between the time VR12ON and VR24ON are set to 1 and the time operation gets stabilized.

Note 7-2: An external 4.7μF capacitor must be connected to the VREF pin to stabilize the VREF voltage.

LC87F0G08A

Power-on Reset (POR) Characteristics at Ta = -40°C to +85°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin / Remarks	Conditions	Option Selected Voltage	Specification			
					min	typ	max	unit
POR release voltage	PORRL		Option selected (Note 11-1)	1.67V	1.10		1.79	V
Detection voltage unpredictable area	POUKS		See Fig. 8. (Note 11-2)			0.7	0.95	
Power supply rise time	PORIS		Power startup time from VDD=0V to 1.6V				100	ms

Note 11-1: The POR release voltage can be selected when the low-voltage detection feature is deselected.

Note 11-2: There is an unpredictable area before the transistor starts to turn on.

Low Voltage Detection Reset (LVD) Characteristics at Ta = -40°C to +85°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin / Remarks	Conditions	Option Selected Voltage	Specification			
					min	typ	max	unit
LVD reset voltage (Note 12-2)	LVDET		Option selected See Fig. 9. (Note 12-1) (Note 12-3)	1.91V	1.81	1.91	2.01	V
				2.01V	1.91	2.01	2.11	
				2.31V	2.21	2.31	2.41	
				2.51V	2.41	2.51	2.61	
				2.81V	2.71	2.81	2.93	
				3.79V	3.69	3.79	3.92	
				4.28V	4.18	4.28	4.41	
LVD voltage hysteresis	LVHYS			1.91V		55		mV
				2.01V		55		
				2.31V		55		
				2.51V		55		
				2.81V		60		
				3.79V		65		
				4.28V		65		
Detection voltage unpredictable area	LVUKS		See Fig. 9. (Note 12-4)			0.7	0.95	V
Minimum low voltage detection width (response sensitivity)	TLVDW		LVDET-0.5V See Fig. 10.		0.2			ms

Note 12-1: The LVD reset voltage can be selected from 7 levels when the low-voltage detection feature is selected.

Note 12-2: The hysteresis voltage is not included in the LVD reset voltage specification value.

Note 12-3: There are cases when the LVD reset voltage specification value is exceeded when a greater change in the output level or large current is applied to the port.

Note 12-4: There is an unpredictable area before the transistor starts to turn on.

LC87F0G08A

Consumption Current Characteristics at Ta = -40°C to +85°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin / Remarks	Conditions	V _{DD} [V]	Specification			
					min	typ	max	unit
Normal mode consumption current (Note 13-1) (Note 13-2)	IDDOP(1)	V _{DD} 1	<ul style="list-style-type: none">• FmCF=8MHz ceramic oscillation mode• System clock set to 8MHz mode• Internal low-/medium-speed RC oscillation stopped• Internal high-speed RC oscillation stopped• Frequency division ratio set to 1/1	2.2 to 5.5		3.8	5.2	mA
				2.2 to 3.6		2.2	2.9	
	IDDOP(2)		<ul style="list-style-type: none">• FmCF=4MHz ceramic oscillation mode• System clock set to 4MHz mode• Internal low-/medium-speed RC oscillation stopped• Internal high-speed RC oscillation stopped• Frequency division ratio set to 1/1	1.8 to 5.5		2.1	3.5	
				1.8 to 3.6		1.1	1.7	
	IDDOP(3)		<ul style="list-style-type: none">• FsX'tal=32.768kHz crystal oscillation mode• Internal low-speed RC oscillation stopped• System clock set to internal medium-speed RC oscillation mode• Internal high-speed RC oscillation stopped• Frequency division ratio set to 1/2	1.8 to 5.5		0.23	0.39	
				1.8 to 3.6		0.13	0.19	
	IDDOP(4)		<ul style="list-style-type: none">• FsX'tal=32.768kHz crystal oscillation mode• Internal low-/medium-speed RC oscillation stopped• System clock set to internal high-speed RC oscillation mode• Frequency division ratio set to 1/1	1.8 to 5.5		2.7	3.6	
				1.8 to 3.6		1.7	2.3	
	IDDOP(5)		<ul style="list-style-type: none">• External oscillation FsX'tal/FmCF stopped• System clock set to internal low-speed RC oscillation mode• Internal medium-speed RC oscillation stopped• Internal high-speed RC oscillation stopped• Frequency division ratio set to 1/1	1.8 to 5.5		10	42	μA
				1.8 to 3.6		6	21	
	IDDOP(6)		<ul style="list-style-type: none">• FsX'tal=32.768kHz crystal oscillation mode• System clock set to 32.768kHz mode• Internal low-/medium-speed RC oscillation stopped• Internal high-speed RC oscillation stopped• Frequency division ratio set to 1/2	1.8 to 5.5		46	101	
				1.8 to 3.6		16	40	

Continued on next page.

LC87F0G08A

F-ROM Programming Characteristics at Ta = +10°C to +55°C, VSS1 = VSS2 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	VDD[V]	Specification			
					min	typ	max	unit
Onboard programming current	IDDFW(1)	VDD1	• Excluding power dissipation in the microcontroller block	2.2 to 5.5		5	10	mA
Programming time	tFW(1)		• Erasing time	2.2 to 5.5		20	30	ms
	tFW(2)		• Programming time			40	60	μs

LC87F0G08A

Characteristics of a Sample Main System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Oscillator

■MURATA Manufacturing Co., Ltd.

Nominal Frequency	Type	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]		typ [ms]	max [ms]	
12MHz	SMD	CSTCE12M0G52-R0	(10)	(10)	Open	680	2.6 to 5.5	0.02	0.3	C1 and C2 integrated type
8MHz	SMD	CSTCE8M00G52-R0	(10)	(10)	Open	1k	2.1 to 5.5	0.02	0.3	
4MHz	SMD	CSTCR4M00G53-R0	(15)	(15)	Open	1.5k	1.8 to 5.5	0.03	0.45	

Characteristics of a Sample Subsystem Clock Oscillation Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit that Uses a Crystal Oscillator

■EPSON TOYOCOM

Nominal Frequency	Type	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]		typ [ms]	max [ms]	
32.768kHz	SMD	MC-306	9	9	Open	330k	1.8 to 5.5	1.4	4.0	Applicable CL value = 7.0pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized in the following cases (see Figure 3):

- Till the oscillation gets stabilized after the instruction for starting the subclock oscillation circuit is executed
- Till the oscillation gets stabilized after the HOLD mode is released.

Note: The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.

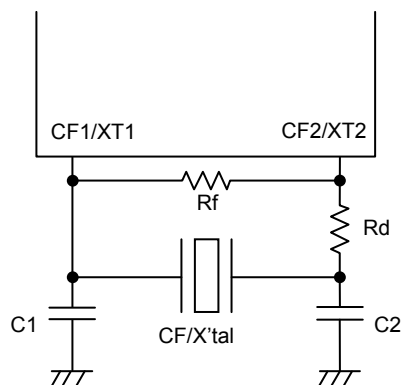


Figure 1 CF/XT Oscillator Circuit

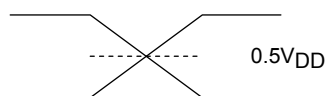
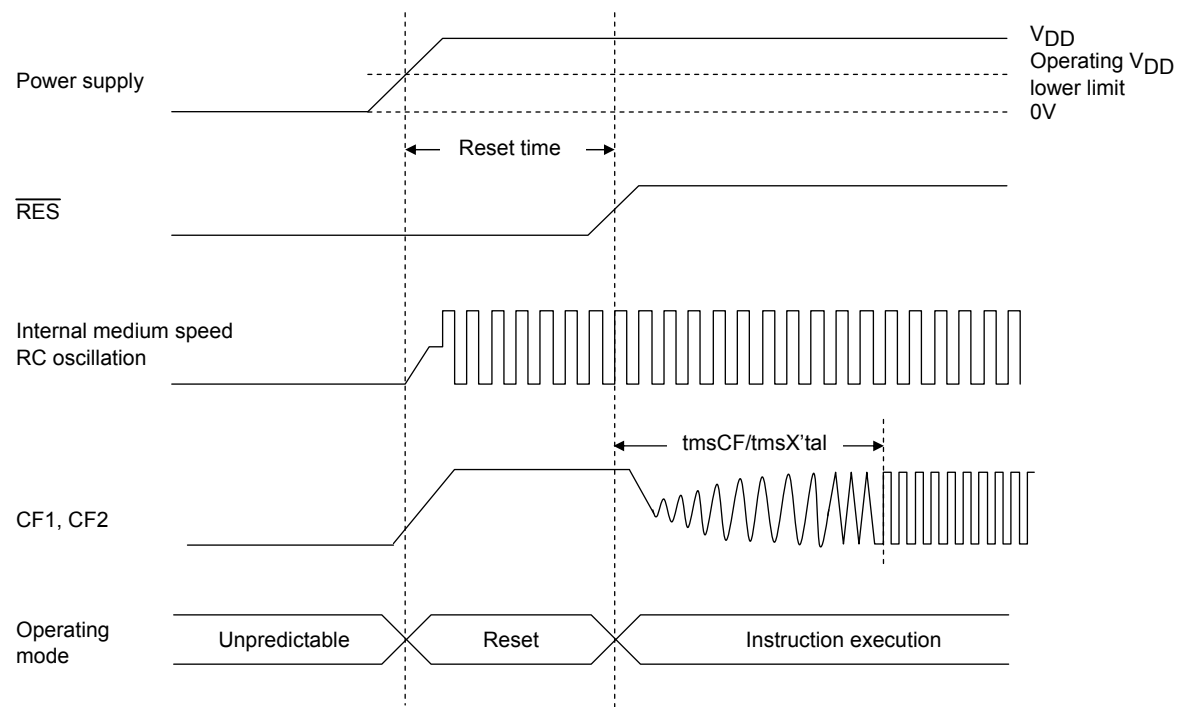
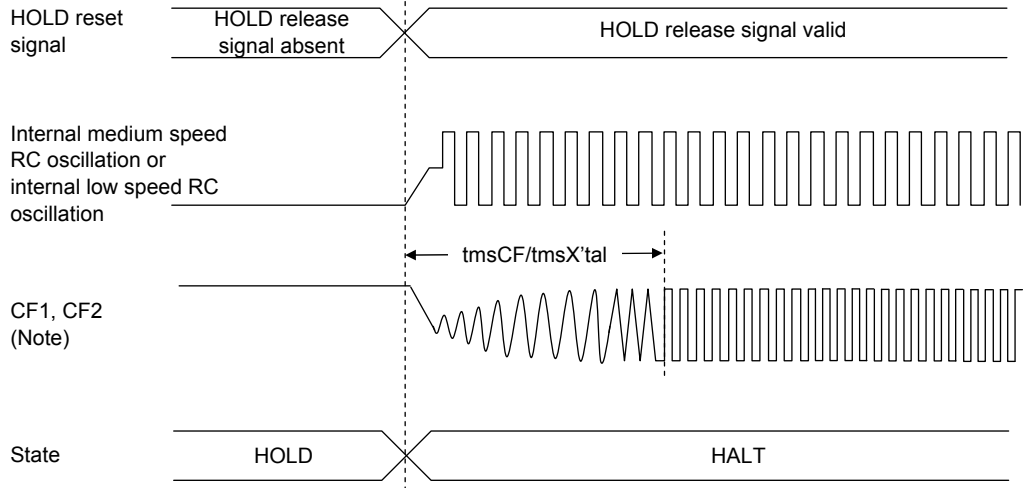


Figure 2 AC Timing Measurement Point



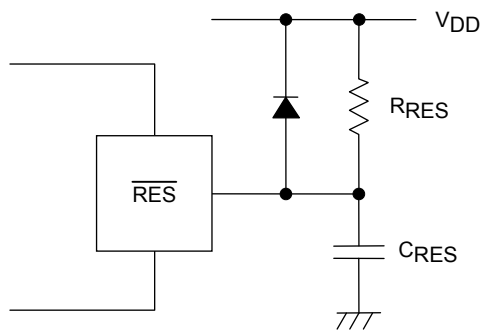
Reset Time and Oscillation Stabilization Time



HOLD Release Signal and Oscillation Stabilization Time

Note: When an external oscillation circuit is selected.

Figure 3 Oscillation Stabilization Time



Note:

The external circuit for reset may vary depending on the usage of POR and LVD. See "Reset Function" in the user's manual.

Figure 4 Sample Reset Circuit

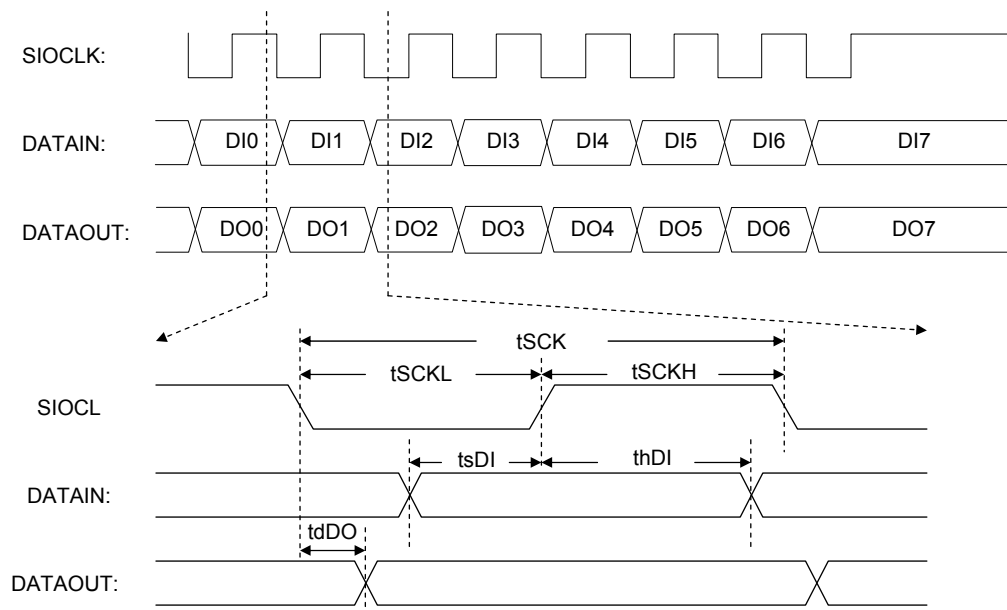


Figure 5 Serial I/O Waveform

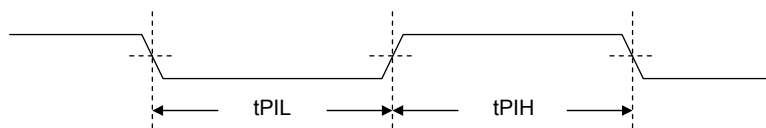


Figure 6 Pulse Input Timing Signal Waveform

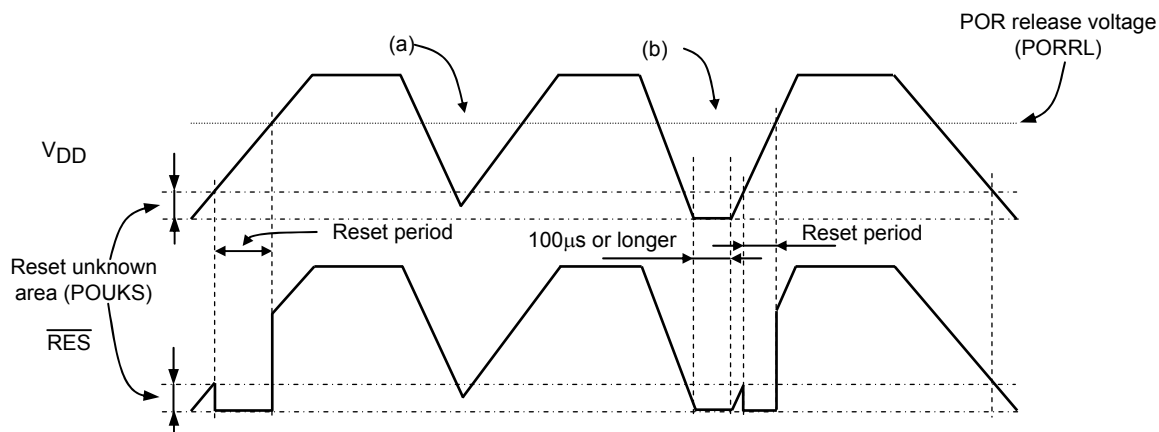


Figure 8 Example of POR Only (LVD Deselected) Mode Waveforms (at Reset Pin with R_{RES} Pull-up Resistor Only)

- The POR function generates a reset only when the power voltage goes up from the V_{SS} level.
- No stable reset will be generated if power is turned on again when the power level does not go down to the V_{SS} level as shown in (a). If such a case is anticipated, use the LVD function together with the POR function or implement an external reset circuit as shown below.
- A reset is generated only when the power level goes down to the V_{SS} level as shown in (b) and power is turned on again after this condition continues for 100µs or longer.

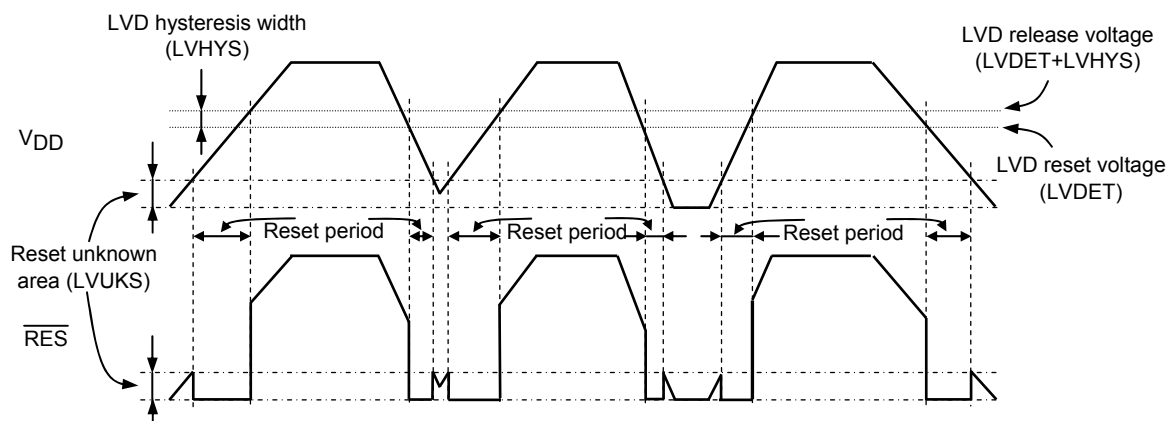


Figure 9 Example of POR + LVD Mode Waveforms (at Reset Pin with R_{RES} Pull-up Resistor Only)

- Resets are generated both when power is turned on and when the power level lowers.
- A hysteresis width (LVHYS) is provided to prevent the repetitions of reset release and entry cycles near the detection level.

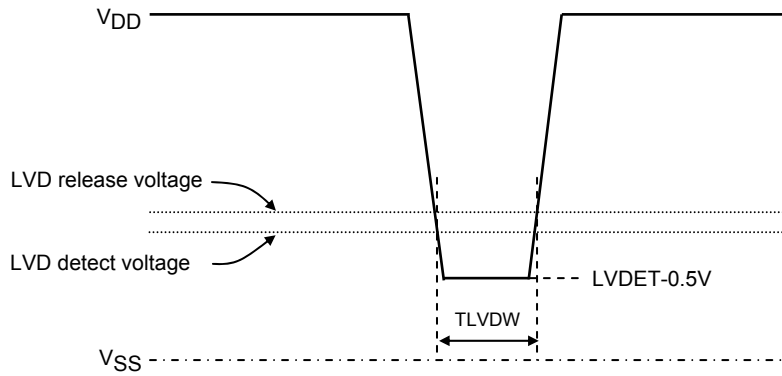


Figure 10 Minimum Low Voltage Detection Width (Example of Voltage Sag/Fluctuation Waveform)

ORDERING INFORMATION

Device	Package	Shipping (Qty / Packing)
LC87F0G08AUJA-AH	SSOP24(225mil) (Pb-Free / Halogen Free)	2000 / Tape & Reel
LC87F0G08AUJA-FH	SSOP24(225mil) (Pb-Free / Halogen Free)	2000 / Tape & Reel
LC87F0G08AUJA-ZH	SSOP24(225mil) (Pb-Free / Halogen Free)	1400 / Fan-Fold

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