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Understanding <u>Embedded - CPLDs (Complex Programmable Logic Devices)</u>

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

Applications of Embedded - CPLDs

Details	
Product Status	Obsolete
Programmable Type	In System Programmable
Delay Time tpd(1) Max	5 ns
Voltage Supply - Internal	2.375V ~ 2.625V
Number of Logic Elements/Blocks	4
Number of Macrocells	64
Number of Gates	1250
Number of I/O	40
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	-
Supplier Device Package	48-TQFP
Purchase URL	https://www.e-xfl.com/product-detail/intel/epm7064btc48-5

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

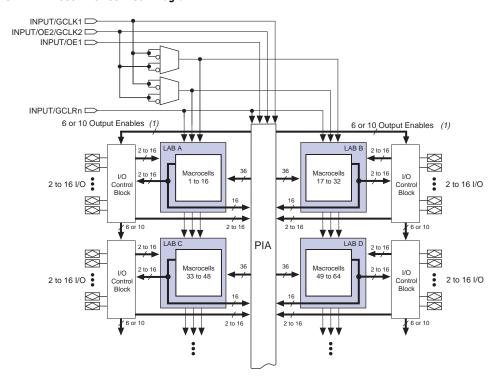


Figure 1. MAX 7000B Device Block Diagram

Note:

(1) EPM7032B, EPM7064B, EPM7128B, and EPM7256B devices have six output enables. EPM7512B devices have ten output enables.

Logic Array Blocks

The MAX 7000B device architecture is based on the linking of high-performance LABs. LABs consist of 16 macrocell arrays, as shown in Figure 1. Multiple LABs are linked together via the PIA, a global bus that is fed by all dedicated input pins, I/O pins, and macrocells.

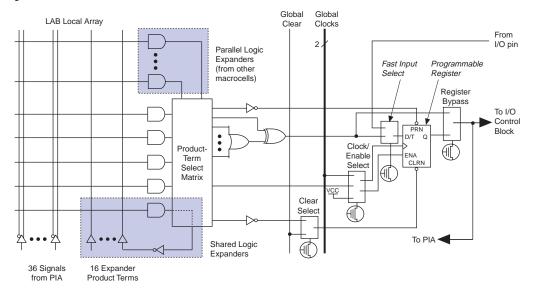
Each LAB is fed by the following signals:

- 36 signals from the PIA that are used for general logic inputs
- Global controls that are used for secondary register functions
- Direct input paths from I/O pins to the registers that are used for fast setup times

Macrocells

The MAX 7000B macrocell can be individually configured for either sequential or combinatorial logic operation. The macrocell consists of three functional blocks: the logic array, the product-term select matrix, and the programmable register. Figure 2 shows the MAX 7000B macrocell.

Figure 2. MAX 7000B Macrocell



Combinatorial logic is implemented in the logic array, which provides five product terms per macrocell. The product-term select matrix allocates these product terms for use as either primary logic inputs (to the OR and XOR gates) to implement combinatorial functions, or as secondary inputs to the macrocell's register preset, clock, and clock enable control functions.

Two kinds of expander product terms ("expanders") are available to supplement macrocell logic resources:

- Shareable expanders, which are inverted product terms that are fed back into the logic array
- Parallel expanders, which are product terms borrowed from adjacent macrocells

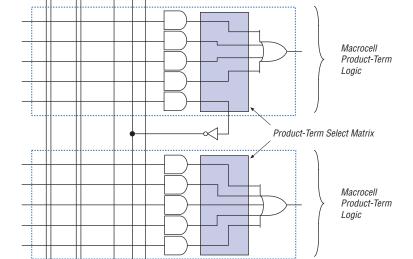
Expander Product Terms

Although most logic functions can be implemented with the five product terms available in each macrocell, more complex logic functions require additional product terms. Another macrocell can be used to supply the required logic resources. However, the MAX 7000B architecture also offers both shareable and parallel expander product terms ("expanders") that provide additional product terms directly to any macrocell in the same LAB. These expanders help ensure that logic is synthesized with the fewest possible logic resources to obtain the fastest possible speed.

Shareable Expanders

Each LAB has 16 shareable expanders that can be viewed as a pool of uncommitted single product terms (one from each macrocell) with inverted outputs that feed back into the logic array. Each shareable expander can be used and shared by any or all macrocells in the LAB to build complex logic functions. A small delay (t_{SEXP}) is incurred when shareable expanders are used. Figure 3 shows how shareable expanders can feed multiple macrocells.

Figure 3. MAX 7000B Shareable Expanders



Shareable expanders can be shared by any or all macrocells in an LAB.

Altera Corporation 9

16 Shared

Expanders

36 Signals

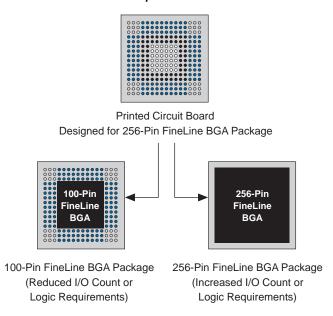
from PIA

SameFrame Pin-Outs

MAX 7000B devices support the SameFrame pin-out feature for FineLine BGA and 0.8-mm Ultra FineLine BGA packages. The SameFrame pin-out feature is the arrangement of balls on FineLine BGA and 0.8-mm Ultra FineLine BGA packages such that the lower-ball-count packages form a subset of the higher-ball-count packages. SameFrame pin-outs provide the flexibility to migrate not only from device to device within the same package, but also from one package to another. FineLine BGA packages are compatible with other FineLine BGA packages, and 0.8-mm Ultra FineLine BGA packages are compatible with other 0.8-mm Ultra FineLine BGA packages. A given printed circuit board (PCB) layout can support multiple device density/package combinations. For example, a single board layout can support a range of devices from an EPM7064B device in a 100-pin FineLine BGA package to an EPM7512B device in a 256-pin FineLine BGA package.

The Altera software provides support to design PCBs with SameFrame pin-out devices. Devices can be defined for present and future use. The Altera software generates pin-outs describing how to layout a board to take advantage of this migration (see Figure 7).

Figure 7. SameFrame Pin-Out Example



By combining the pulse and shift times for each of the programming stages, the program or verify time can be derived as a function of the TCK frequency, the number of devices, and specific target device(s). Because different ISP-capable devices have a different number of EEPROM cells, both the total fixed and total variable times are unique for a single device.

Programming a Single MAX 7000B Device

The time required to program a single MAX 7000B device in-system can be calculated from the following formula:

$$t_{PROG} = t_{PPULSE} + \frac{Cycle_{PTCK}}{f_{TCK}}$$

where: $t_{PROG} = \text{Programming time}$ $t_{PPULSE} = \text{Sum of the fixed times to erase, program, and}$

verify the EEPROM cells

 $Cycle_{PTCK}$ = Number of TCK cycles to program a device

= TCK frequency

The ISP times for a stand-alone verification of a single MAX 7000B device can be calculated from the following formula:

$$t_{VER} = t_{VPULSE} + \frac{Cycle_{VTCK}}{f_{TCK}}$$

where: t_{VER} = Verify time t_{VPULSE} = Sum of the fixed times to verify the EEPROM cells $Cycle_{VTCK}$ = Number of TCK cycles to verify a device

The instruction register length of MAX 7000B devices is ten bits. The MAX 7000B USERCODE register length is 32 bits. Tables 7 and 8 show the boundary-scan register length and device IDCODE information for MAX 7000B devices.

Table 7. MAX 7000B Boundary-Sca	n Register Length			
Device	Boundary-Scan Register Length 96 192 288 480			
EPM7032B	96			
EPM7064B	192			
EPM7128B	288			
EPM7256B	480			
EPM7512B	624			

Table 8. 32-1	Table 8. 32-Bit MAX 7000B Device IDCODENote (1)										
Device		IDCODE (32 I	Bits)								
	Version (4 Bits)	Part Number (16 Bits)	Manufacturer's Identity (11 Bits)	1 (1 Bit) (2)							
EPM7032B	0010	0111 0000 0011 0010	00001101110	1							
EPM7064B	0010	0111 0000 0110 0100	00001101110	1							
EPM7128B	0010	0111 0001 0010 1000	00001101110	1							
EPM7256B	0010	0111 0010 0101 0110	00001101110	1							
EPM7512B	0010	0111 0101 0001 0010	00001101110	1							

Notes:

- (1) The most significant bit (MSB) is on the left.
- (2) The least significant bit (LSB) for all JTAG IDCODEs is 1.



See Application Note 39 (IEEE 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices) for more information on JTAG boundary-scan testing.

Figure 8 shows the timing information for the JTAG signals.

Table 10. MAX 700	Table 10. MAX 7000B MultiVolt I/O Support										
V _{CCIO} (V)	V _{CCIO} (V) Input Signal (V) Output Signal (V)										
	1.8	2.5	3.3	5.0	1.8	2.5	3.3	5.0			
1.8	✓	✓	✓		✓						
2.5	✓	✓	✓			✓					
3.3	✓	✓	✓				✓	✓			

Open-Drain Output Option

MAX 7000B devices provide an optional open-drain (equivalent to open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write enable signals) that can be asserted by any of several devices. It can also provide an additional wired-OR plane.

Programmable Ground Pins

Each unused I/O pin on MAX 7000B devices may be used as an additional ground pin. This programmable ground feature does not require the use of the associated macrocell; therefore, the buried macrocell is still available for user logic.

Slew-Rate Control

The output buffer for each MAX 7000B I/O pin has an adjustable output slew rate that can be configured for low-noise or high-speed performance. A faster slew rate provides high-speed transitions for high-performance systems. However, these fast transitions may introduce noise transients into the system. A slow slew rate reduces system noise, but adds a nominal delay of 4 to 5 ns. When the configuration cell is turned off, the slew rate is set for low-noise performance. Each I/O pin has an individual EEPROM bit that controls the slew rate, allowing designers to specify the slew rate on a pin-by-pin basis. The slew rate control affects both the rising and falling edges of the output signal.

Advanced I/O Standard Support

The MAX 7000B I/O pins support the following I/O standards: LVTTL, LVCMOS, 1.8-V I/O, 2.5-V I/O, GTL+, SSTL-3 Class I and II, and SSTL-2 Class I and II.

MAX 7000B devices contain two I/O banks. Both banks support all standards. Each I/O bank has its own VCCIO pins. A single device can support 1.8-V, 2.5-V, and 3.3-V interfaces; each bank can support a different standard independently. Within a bank, any one of the terminated standards can be supported.

Figure 9 shows the arrangement of the MAX 7000B I/O banks.

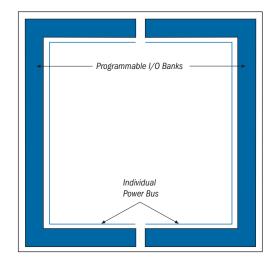


Figure 9. MAX 7000B I/O Banks for Various Advanced I/O Standards

Table 11 shows which macrocells have pins in each I/O bank.

Table 11. Macrocell Pins Co	ntained in Each I/O Bank	
Device	Bank 1	Bank 2
EPM7032B	1-16	17-32
EPM7064B	1-32	33-64
EPM7128B	1-64	65-128
EPM7256B	1-128, 177-181	129-176, 182-256
EPM7512B	1-265	266-512

Each MAX 7000B device has two VREF pins. Each can be set to a separate V_{REF} level. Any I/O pin that uses one of the voltage-referenced standards (GTL+, SSTL-2, or SSTL-3) may use either of the two VREF pins. If these pins are not required as VREF pins, they may be individually programmed to function as user I/O pins.

Power Sequencing & Hot-Socketing

Because MAX 7000B devices can be used in a mixed-voltage environment, they have been designed specifically to tolerate any possible power-up sequence. The $V_{\rm CCIO}$ and $V_{\rm CCINT}$ power planes can be powered in any order.

Signals can be driven into MAX 7000B devices before and during power-up (and power-down) without damaging the device. Additionally, MAX 7000B devices do not drive out during power-up. Once operating conditions are reached, MAX 7000B devices operate as specified by the user.

MAX 7000B device I/O pins will not source or sink more than 300 μ A of DC current during power-up. All pins can be driven up to 4.1 V during hot-socketing.

Design Security

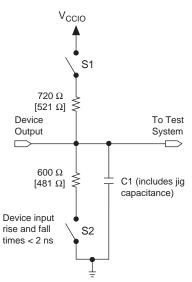
All MAX 7000B devices contain a programmable security bit that controls access to the data programmed into the device. When this bit is programmed, a design implemented in the device cannot be copied or retrieved. This feature provides a high level of design security, because programmed data within EEPROM cells is invisible. The security bit that controls this function, as well as all other programmed data, is reset only when the device is reprogrammed.

Generic Testing

MAX 7000B devices are fully functionally tested. Complete testing of each programmable EEPROM bit and all internal logic elements ensures 100% programming yield. AC test measurements are taken under conditions equivalent to those shown in Figure 11. Test patterns can be used and then erased during early stages of the production flow.

Figure 11. MAX 7000B AC Test Conditions

Power supply transients can affect AC measurements. Simultaneous transitions of multiple outputs should be avoided for accurate measurement. Threshold tests must not be performed under AC conditions. Large-amplitude, fast-groundcurrent transients normally occur as the device outputs discharge the load capacitances. When these transients flow through the parasitic inductance between the device ground pin and the test system ground, significant reductions in observable noise immunity can result. Numbers in brackets are for 2.5-V outputs. Numbers without brackets are for 3.3-V outputs. Switches S1 and S2 are open for all tests except output disable timing parameters.



Operating Conditions

Tables 14 through 17 provide information on absolute maximum ratings, recommended operating conditions, operating conditions, and capacitance for MAX 7000B devices.

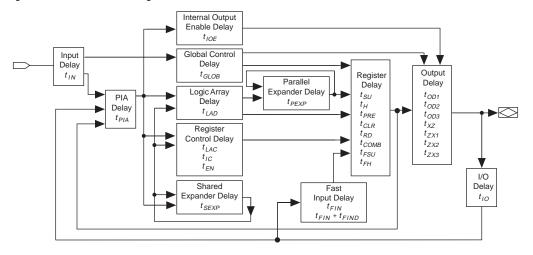
Table 1	Table 14. MAX 7000B Device Absolute Maximum Ratings Note (1)									
Symbol	Parameter	Conditions	Min	Max	Unit					
V _{CCINT}	Supply voltage		-0.5	3.6	V					
V _{CCIO}	Supply voltage		-0.5	3.6	V					
VI	DC input voltage	(2)	-2.0	4.6	V					
I _{OUT}	DC output current, per pin		-33	50	mA					
T _{STG}	Storage temperature	No bias	-65	150	°C					
T _A	Ambient temperature	Under bias	-65	135	°C					
T_{J}	Junction temperature	Under bias	-65	135	° C					

Table 15. MAX 7000B Device Recommended Operating Conditions Symbol Parameter Conditions Min Max U VCCINT Supply voltage for internal logic and input buffers (10) 2.375 2.625 VCCIO Supply voltage for output drivers, 3.3-V operation 3.0 3.6 Supply voltage for output drivers, 2.5-V operation 2.375 2.625 Supply voltage for output drivers, 1.8-V operation 1.71 1.89 VCCISP Supply voltage during in-system programming 2.375 2.625 VI Input voltage (3) -0.5 3.9					
Symbol	Parameter	Conditions	Min	Max	Unit
V _{CCINT}		(10)	2.375	2.625	V
V _{CCIO}			3.0	3.6	V
			2.375	2.625	V
			1.71	1.89	V
V _{CCISP}			2.375	2.625	V
VI	Input voltage	(3)	-0.5	3.9	V
Vo	Output voltage		0	V _{CCIO}	V
T _A	Ambient temperature	For commercial use	0	70	° C
		For industrial use (11)	-40	85	° C
TJ	Junction temperature	For commercial use	0	90	° C
		For industrial use (11)	-40	105	° C
t _R	Input rise time			40	ns
t _F	Input fall time			40	ns

Timing Model

MAX 7000B device timing can be analyzed with the Altera software, with a variety of popular industry-standard EDA simulators and timing analyzers, or with the timing model shown in Figure 13. MAX 7000B devices have predictable internal delays that enable the designer to determine the worst-case timing of any design. The Altera software provides timing simulation, point-to-point delay prediction, and detailed timing analysis for device-wide performance evaluation.

Figure 13. MAX 7000B Timing Model



The timing characteristics of any signal path can be derived from the timing model and parameters of a particular device. External timing parameters, which represent pin-to-pin timing delays, can be calculated as the sum of internal parameters. Figure 14 shows the timing relationship between internal and external delay parameters.



See *Application Note* 94 (*Understanding MAX* 7000 *Timing*) for more information.

Symbol	Parameter	Conditions			Speed	Grade			Unit
			-	3	-5		-7		
			Min	Max	Min	Max	Min	Max	
t _{IN}	Input pad and buffer delay			0.3		0.5		0.7	ns
t_{IO}	I/O input pad and buffer delay			0.3		0.5		0.7	ns
t _{FIN}	Fast input delay			0.9		1.3		2.0	ns
t _{FIND}	Programmable delay adder for fast input			1.0		1.5		1.5	ns
t _{SEXP}	Shared expander delay			1.5		2.1		3.2	ns
t _{PEXP}	Parallel expander delay			0.4		0.6		0.9	ns
t_{LAD}	Logic array delay			1.4		2.0		3.1	ns
t_{LAC}	Logic control array delay			1.2		1.7		2.6	ns
t _{IOE}	Internal output enable delay			0.1		0.2		0.3	ns
t _{OD1}	Output buffer and pad delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		0.9		1.2		1.8	ns
t _{OD3}	Output buffer and pad delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		5.9		6.2		6.8	ns
t _{ZX1}	Output buffer enable delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		1.6		2.2		3.4	ns
t _{ZX3}	Output buffer enable delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		6.6		7.2		8.4	ns
t_{XZ}	Output buffer disable delay	C1 = 5 pF		1.6		2.2		3.4	ns
t _{SU}	Register setup time		0.7		1.1		1.6		ns
t_H	Register hold time		0.4		0.5		0.9		ns
t _{FSU}	Register setup time of fast input		0.8		0.8		1.1		ns
t_{FH}	Register hold time of fast input		1.2		1.2		1.4		ns
t_{RD}	Register delay			0.5		0.6		0.9	ns
t_{COMB}	Combinatorial delay			0.2		0.3		0.5	ns
t _{IC}	Array clock delay		İ	1.2		1.8		2.8	ns
t_{EN}	Register enable time		İ	1.2		1.7		2.6	ns
t_{GLOB}	Global control delay		İ	0.7		1.1		1.6	ns
t_{PRE}	Register preset time			1.0		1.3		1.9	ns
t _{CLR}	Register clear time			1.0		1.3		1.9	ns
t_{PIA}	PIA delay	(2)		0.7		1.0		1.4	ns
t_{LPA}	Low-power adder	(4)		1.5		2.1		3.2	ns

Symbol	Parameter	Conditions			Speed	Grade			Unit
				-4 -7			-10		Ē
			Min	Max	Min	Max	Min	Max	
t _{PD1}	Input to non-registered output	C1 = 35 pF (2)		4.0		7.5		10.0	ns
t _{PD2}	I/O input to non-registered output	C1 = 35 pF (2)		4.0		7.5		10.0	ns
t _{SU}	Global clock setup time	(2)	2.5		4.5		6.1		ns
t _H	Global clock hold time	(2)	0.0		0.0		0.0		ns
t _{FSU}	Global clock setup time of fast input		1.0		1.5		1.5		ns
t _{FH}	Global clock hold time of fast input		1.0		1.0		1.0		ns
^t FZHSU	Global clock setup time of fast input with zero hold time		2.0		3.0		3.0		ns
t _{FZHH}	Global clock hold time of fast input with zero hold time		0.0		0.0		0.0		ns
t _{CO1}	Global clock to output delay	C1 = 35 pF	1.0	2.8	1.0	5.7	1.0	7.5	ns
t _{CH}	Global clock high time		1.5		3.0		4.0		ns
t _{CL}	Global clock low time		1.5		3.0		4.0		ns
t _{ASU}	Array clock setup time	(2)	1.2		2.0		2.8		ns
t _{AH}	Array clock hold time	(2)	0.2		0.7		0.9		ns
t _{ACO1}	Array clock to output delay	C1 = 35 pF (2)	1.0	4.1	1.0	8.2	1.0	10.8	ns
t _{ACH}	Array clock high time		1.5		3.0		4.0		ns
t _{ACL}	Array clock low time		1.5		3.0		4.0		ns
t _{CPPW}	Minimum pulse width for clear and preset		1.5		3.0		4.0		ns
t _{CNT}	Minimum global clock period	(2)		4.1		7.9		10.6	ns
f _{CNT}	Maximum internal global clock frequency	(2), (3)	243.9		126.6		94.3		MHz
t _{ACNT}	Minimum array clock period	(2)		4.1		7.9		10.6	ns
f _{ACNT}	Maximum internal array clock frequency	(2), (3)	243.9		126.6		94.3		MHz

Table 26. EPM7128	Table 26. EPM7128B Selectable I/O Standard Timing Adder Delays (Part 2 of 2) Note (1)									
I/O Standard	Parameter			Speed	Grade			Unit		
		-	4	-	7		10			
		Min	Max	Min	Max	Min	Max			
PCI	Input to PIA		0.0		0.0		0.0	ns		
	Input to global clock and clear		0.0		0.0		0.0	ns		
	Input to fast input register		0.0		0.0		0.0	ns		
	All outputs		0.0		0.0		0.0	ns		

Notes to tables:

- (1) These values are specified under the Recommended Operating Conditions in Table 15 on page 29. See Figure 14 for more information on switching waveforms.
- (2) These values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (3) Measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (4) The t_{LPA} parameter must be added to the t_{LAD} , t_{LAC} , t_{IC} , t_{ACL} , t_{CPPW} , t_{EN} , and t_{SEXP} parameters for macrocells running in low-power mode.

Symbol	Parameter	Conditions			Speed	Grade			Unit
			-	5	-7			10	
			Min	Max	Min	Max	Min	Max	
t _{PD1}	Input to non-registered output	C1 = 35 pF (2)		5.0		7.5		10.0	ns
t _{PD2}	I/O input to non-registered output	C1 = 35 pF (2)		5.0		7.5		10.0	ns
t _{SU}	Global clock setup time	(2)	3.3		4.8		6.6		ns
t _H	Global clock hold time	(2)	0.0		0.0		0.0		ns
t _{FSU}	Global clock setup time of fast input		1.0		1.5		1.5		ns
t _{FH}	Global clock hold time for fast input		1.0		1.0		1.0		ns
t _{FZHSU}	Global clock setup time of fast input with zero hold time		2.5		3.0		3.0		ns
t _{FZHH}	Global clock hold time of fast input with zero hold time		0.0		0.0		0.0		ns
t _{CO1}	Global clock to output delay	C1 = 35 pF	1.0	3.3	1.0	5.1	1.0	6.7	ns
t _{CH}	Global clock high time		2.0		3.0		4.0		ns
t _{CL}	Global clock low time		2.0		3.0		4.0		ns
t _{ASU}	Array clock setup time	(2)	1.4		2.0		2.8		ns
t _{AH}	Array clock hold time	(2)	0.4		0.8		1.0		ns
t _{ACO1}	Array clock to output delay	C1 = 35 pF (2)	1.0	5.2	1.0	7.9	1.0	10.5	ns
t _{ACH}	Array clock high time		2.0		3.0		4.0		ns
t _{ACL}	Array clock low time		2.0		3.0		4.0		ns
t _{CPPW}	Minimum pulse width for clear and preset		2.0		3.0		4.0		ns
t _{CNT}	Minimum global clock period	(2)		5.3		7.9		10.6	ns
f _{CNT}	Maximum internal global clock frequency	(2), (3)	188.7		126.6		94.3		MHz
t _{ACNT}	Minimum array clock period	(2)		5.3		7.9		10.6	ns
f _{ACNT}	Maximum internal array clock frequency	(2), (3)	188.7		126.6		94.3		MHz

Symbol	Parameter	Conditions			Speed	Grade			Unit
			-5 -7		7	-	10		
			Min	Max	Min	Max	Min	Max	
t _{PD1}	Input to non-registered output	C1 = 35 pF (2)		5.5		7.5		10.0	ns
t _{PD2}	I/O input to non-registered output	C1 = 35 pF (2)		5.5		7.5		10.0	ns
t _{SU}	Global clock setup time	(2)	3.6		4.9		6.5		ns
t _H	Global clock hold time	(2)	0.0		0.0		0.0		ns
t _{FSU}	Global clock setup time of fast input		1.0		1.5		1.5		ns
t _{FH}	Global clock hold time of fast input		1.0		1.0		1.0		ns
^t FZHSU	Global clock setup time of fast input with zero hold time		2.5		3.0		3.0		ns
t _{FZHH}	Global clock hold time of fast input with zero hold time		0.0		0.0		0.0		ns
t _{CO1}	Global clock to output delay	C1 = 35 pF	1.0	3.7	1.0	5.0	1.0	6.7	ns
t _{CH}	Global clock high time		3.0		3.0		4.0		ns
t _{CL}	Global clock low time		3.0		3.0		4.0		ns
t _{ASU}	Array clock setup time	(2)	1.4		1.9		2.5		ns
t _{AH}	Array clock hold time	(2)	0.5		0.6		0.8		ns
t _{ACO1}	Array clock to output delay	C1 = 35 pF (2)	1.0	5.9	1.0	8.0	1.0	10.7	ns
t _{ACH}	Array clock high time		3.0		3.0		4.0		ns
t _{ACL}	Array clock low time		3.0		3.0		4.0		ns
t _{CPPW}	Minimum pulse width for clear and preset		3.0		3.0		4.0		ns
t _{CNT}	Minimum global clock period	(2)		6.1		8.4		11.1	ns
f _{CNT}	Maximum internal global clock frequency	(2), (3)	163.9		119.0		90.1		MHz
t _{ACNT}	Minimum array clock period	(2)		6.1		8.4		11.1	ns
f _{ACNT}	Maximum internal array clock frequency	(2), (3)	163.9		119.0		90.1		MHz

Table 32. EPM7512B Selectable I/O Standard Timing Adder Delays (Part 2 of 2) Note (1)								
I/O Standard	Parameter	Speed Grade						Unit
		-5		-7		-10		
		Min	Max	Min	Max	Min	Max	
PCI	Input to PIA		0.0		0.0		0.0	ns
	Input to global clock and clear		0.0		0.0		0.0	ns
	Input to fast input register		0.0		0.0		0.0	ns
	All outputs		0.0		0.0		0.0	ns

Notes to tables:

- These values are specified under the Recommended Operating Conditions in Table 15 on page 29. See Figure 14 for more information on switching waveforms.
- (2) These values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.12 ns to the PIA timing value.
- (3) Measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (4) The t_{LPA} parameter must be added to the t_{LAD} , t_{LAC} , t_{IC} , t_{ACL} , t_{CPPW} , t_{EN} , and t_{SEXP} parameters for macrocells running in low-power mode.

Power Consumption

Supply power (P) versus frequency (f_{MAX} , in MHz) for MAX 7000B devices is calculated with the following equation:

$$P = P_{INT} + P_{IO} = I_{CCINT} \times V_{CC} + P_{IO}$$

The $P_{\rm IO}$ value, which depends on the device output load characteristics and switching frequency, can be calculated using the guidelines given in *Application Note 74 (Evaluating Power for Altera Devices)*.

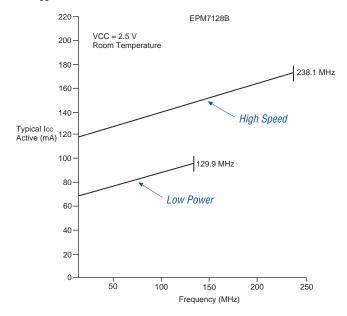
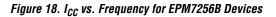


Figure 17. I_{CC} vs. Frequency for EPM7128B Devices



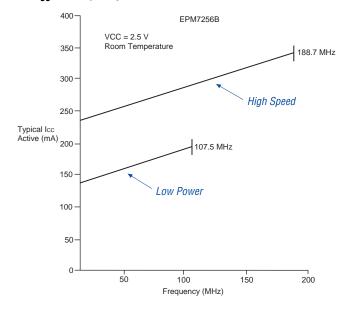


Figure 27. 208-Pin PQFP Package Pin-Out Diagram

Package outline not drawn to scale.

