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Understanding Embedded - CPLDs (Complex Programmable Logic Devices)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

Applications of Embedded - CPLDs

Details	
Product Status	Obsolete
Programmable Type	In System Programmable
Delay Time tpd(1) Max	7.5 ns
Voltage Supply - Internal	2.375V ~ 2.625V
Number of Logic Elements/Blocks	16
Number of Macrocells	256
Number of Gates	5000
Number of I/O	164
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	256-BGA
Supplier Device Package	256-FBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/intel/epm7256bfi256-7

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

- Additional design entry and simulation support provided by EDIF 2 0 0 and 3 0 0 netlist files, library of parameterized modules (LPMs), Verilog HDL, VHDL, and other interfaces to popular EDA tools from manufacturers such as Cadence, Exemplar Logic, Mentor Graphics, OrCAD, Synopsys, Synplicity, and VeriBest
- Programming support with Altera's Master Programming Unit (MPU), MasterBlaster™ serial/universal serial bus (USB) communications cable, and ByteBlasterMV™ parallel port download cable, as well as programming hardware from third-party manufacturers and any Jam™ STAPL File (.jam), Jam Byte-Code File (.jbc), or Serial Vector Format File (.svf)-capable incircuit tester

General Description

MAX 7000B devices are high-density, high-performance devices based on Altera's second-generation MAX architecture. Fabricated with advanced CMOS technology, the EEPROM-based MAX 7000B devices operate with a 2.5-V supply voltage and provide 600 to 10,000 usable gates, ISP, pin-to-pin delays as fast as 3.5 ns, and counter speeds up to 303.0 MHz. See Table 2.

Table 2. MAX 7000B Speed GradesNote (1)								
Device		Speed Grade						
	-3	-3 -4 -5 -7 -10						
EPM7032B	✓		✓	✓				
EPM7064B	✓		✓	✓				
EPM7128B		✓		✓	✓			
EPM7256B			✓	✓	✓			
EPM7512B			✓	✓	✓			

Notes:

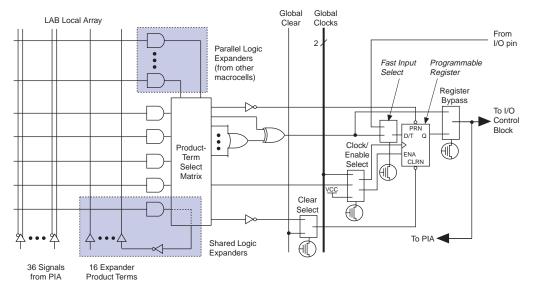
 Contact Altera Marketing for up-to-date information on available device speed grades.

The MAX 7000B architecture supports 100% TTL emulation and high-density integration of SSI, MSI, and LSI logic functions. It easily integrates multiple devices ranging from PALs, GALs, and 22V10s to MACH and pLSI devices. MAX 7000B devices are available in a wide range of packages, including PLCC, BGA, FineLine BGA, 0.8-mm Ultra FineLine BGA, PQFP, TQFP, and TQFP packages. See Table 3.

Macrocells

The MAX 7000B macrocell can be individually configured for either sequential or combinatorial logic operation. The macrocell consists of three functional blocks: the logic array, the product-term select matrix, and the programmable register. Figure 2 shows the MAX 7000B macrocell.

Figure 2. MAX 7000B Macrocell



Combinatorial logic is implemented in the logic array, which provides five product terms per macrocell. The product-term select matrix allocates these product terms for use as either primary logic inputs (to the OR and XOR gates) to implement combinatorial functions, or as secondary inputs to the macrocell's register preset, clock, and clock enable control functions.

Two kinds of expander product terms ("expanders") are available to supplement macrocell logic resources:

- Shareable expanders, which are inverted product terms that are fed back into the logic array
- Parallel expanders, which are product terms borrowed from adjacent macrocells

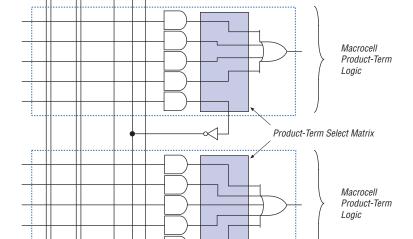
Expander Product Terms

Although most logic functions can be implemented with the five product terms available in each macrocell, more complex logic functions require additional product terms. Another macrocell can be used to supply the required logic resources. However, the MAX 7000B architecture also offers both shareable and parallel expander product terms ("expanders") that provide additional product terms directly to any macrocell in the same LAB. These expanders help ensure that logic is synthesized with the fewest possible logic resources to obtain the fastest possible speed.

Shareable Expanders

Each LAB has 16 shareable expanders that can be viewed as a pool of uncommitted single product terms (one from each macrocell) with inverted outputs that feed back into the logic array. Each shareable expander can be used and shared by any or all macrocells in the LAB to build complex logic functions. A small delay (t_{SEXP}) is incurred when shareable expanders are used. Figure 3 shows how shareable expanders can feed multiple macrocells.

Figure 3. MAX 7000B Shareable Expanders



Shareable expanders can be shared by any or all macrocells in an LAB.

Altera Corporation 9

16 Shared

Expanders

36 Signals

from PIA

Parallel Expanders

Parallel expanders are unused product terms that can be allocated to a neighboring macrocell to implement fast, complex logic functions. Parallel expanders allow up to 20 product terms to directly feed the macrocell OR logic, with five product terms provided by the macrocell and 15 parallel expanders provided by neighboring macrocells in the LAB.

The Altera Compiler can automatically allocate up to three sets of up to five parallel expanders to the macrocells that require additional product terms. Each set of five parallel expanders incurs a small, incremental timing delay (t_{PEXP}). For example, if a macrocell requires 14 product terms, the Compiler uses the five dedicated product terms within the macrocell and allocates two sets of parallel expanders; the first set includes five product terms and the second set includes four product terms, increasing the total delay by $2 \times t_{PEXP}$.

Two groups of eight macrocells within each LAB (e.g., macrocells 1 through 8, and 9 through 16) form two chains to lend or borrow parallel expanders. A macrocell borrows parallel expanders from lower-numbered macrocells. For example, macrocell 8 can borrow parallel expanders from macrocell 7, from macrocells 7 and 6, or from macrocells 7, 6, and 5. Within each group of eight, the lowest-numbered macrocell can only lend parallel expanders and the highest-numbered macrocell can only borrow them. Figure 4 shows how parallel expanders can be borrowed from a neighboring macrocell.

In-System Programmability (ISP)

MAX 7000B devices can be programmed in-system via an industry-standard 4-pin IEEE Std. 1149.1 (JTAG) interface. ISP offers quick, efficient iterations during design development and debugging cycles. The MAX 7000B architecture internally generates the high programming voltages required to program EEPROM cells, allowing in-system programming with only a single 2.5-V power supply. During in-system programming, the I/O pins are tri-stated and weakly pulled-up to eliminate board conflicts. The pull-up value is nominally 50 k³4.

MAX 7000B devices have an enhanced ISP algorithm for faster programming. These devices also offer an ISP_Done bit that provides safe operation when in-system programming is interrupted. This ISP_Done bit, which is the last bit programmed, prevents all I/O pins from driving until the bit is programmed.

ISP simplifies the manufacturing flow by allowing devices to be mounted on a PCB with standard pick-and-place equipment before they are programmed. MAX 7000B devices can be programmed by downloading the information via in-circuit testers, embedded processors, the Altera MasterBlaster communications cable, and the ByteBlasterMV parallel port download cable. Programming the devices after they are placed on the board eliminates lead damage on high-pin-count packages (e.g., QFP packages) due to device handling. MAX 7000B devices can be reprogrammed after a system has already shipped to the field. For example, product upgrades can be performed in the field via software or modem.

In-system programming can be accomplished with either an adaptive or constant algorithm. An adaptive algorithm reads information from the unit and adapts subsequent programming steps to achieve the fastest possible programming time for that unit. A constant algorithm uses a pre-defined (non-adaptive) programming sequence that does not take advantage of adaptive algorithm programming time improvements. Some in-circuit testers cannot program using an adaptive algorithm. Therefore, a constant algorithm must be used. MAX 7000B devices can be programmed with either an adaptive or constant (non-adaptive) algorithm.

The Jam Standard Test and Programming Language (STAPL), JEDEC standard JESD-71, can be used to program MAX 7000B devices with in-circuit testers, PCs, or embedded processors.



For more information on using the Jam language, see *Application Note 88* (*Using the Jam Language for ISP & ICR via an Embedded Processor*) and *Application Note 122* (*Using STAPL for ISP & ICR via an Embedded Processor*).

The ISP circuitry in MAX 7000B devices is compliant with the IEEE Std. 1532 specification. The IEEE Std. 1532 is a standard developed to allow concurrent ISP between multiple PLD vendors.

The programming times described in Tables 4 through 6 are associated with the worst-case method using the enhanced ISP algorithm.

Table 4. MAX 7000B t _{PULSE} & Cycle _{TCK} Values						
Device	Programming Stand-Alone Verification			Verification		
	t _{PPULSE} (s)	Cycle _{PTCK}	t _{VPULSE} (s)	Cycle _{VTCK}		
EMP7032B	2.12	70,000	0.002	18,000		
EMP7064B	2.12	120,000	0.002	35,000		
EMP7128B	2.12	222,000	0.002	69,000		
EMP7256B	2.12	466,000	0.002	151,000		
EMP7512B	2.12	914,000	0.002	300,000		

Tables 5 and 6 show the in-system programming and stand alone verification times for several common test clock frequencies.

Table 5. MAX 7000B In-System Programming Times for Different Test Clock Frequencies									
Device		f _{TCK}						Units	
	10 MHz	5 MHz	2 MHz	1 MHz	500 kHz	200 kHz	100 kHz	50 kHz	
EMP7032B	2.13	2.13	2.15	2.19	2.26	2.47	2.82	3.52	S
EMP7064B	2.13	2.14	2.18	2.24	2.36	2.72	3.32	4.52	S
EMP7128B	2.14	2.16	2.23	2.34	2.56	3.23	4.34	6.56	S
EMP7256B	2.17	2.21	2.35	2.58	3.05	4.45	6.78	11.44	S
EMP7512B	2.21	2.30	2.58	3.03	3.95	6.69	11.26	20.40	S

Table 1. MAX 7000B Stand-Alone Verification Times for Different Test Clock Frequencies									
Device		f _{TCK}						Units	
	10 MHz	5 MHz	2 MHz	1 MHz	500 kHz	200 kHz	100 kHz	50 kHz	
EMP7032B	0.00	0.01	0.01	0.02	0.04	0.09	0.18	0.36	S
EMP7064B	0.01	0.01	0.02	0.04	0.07	0.18	0.35	0.70	S
EMP7128B	0.01	0.02	0.04	0.07	0.14	0.35	0.69	1.38	S
EMP7256B	0.02	0.03	0.08	0.15	0.30	0.76	1.51	3.02	S
EMP7512B	0.03	0.06	0.15	0.30	0.60	1.50	3.00	6.00	S

The instruction register length of MAX 7000B devices is ten bits. The MAX 7000B USERCODE register length is 32 bits. Tables 7 and 8 show the boundary-scan register length and device IDCODE information for MAX 7000B devices.

Table 7. MAX 7000B Boundary-Scan Register Length					
Device	Boundary-Scan Register Length				
EPM7032B	96				
EPM7064B	192				
EPM7128B	288				
EPM7256B	480				
EPM7512B	624				

Table 8. 32-Bit MAX 7000B Device IDCODE Note (1)							
Device		IDCODE (32 Bits)					
	Version (4 Bits)	1 211 112 (112 2112)					
EPM7032B	0010	0111 0000 0011 0010	00001101110	1			
EPM7064B	0010	0111 0000 0110 0100	00001101110	1			
EPM7128B	0010	0111 0001 0010 1000	00001101110	1			
EPM7256B	0010	0111 0010 0101 0110	00001101110	1			
EPM7512B	0010	0111 0101 0001 0010	00001101110	1			

Notes:

- (1) The most significant bit (MSB) is on the left.
- (2) The least significant bit (LSB) for all JTAG IDCODEs is 1.



See Application Note 39 (IEEE 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices) for more information on JTAG boundary-scan testing.

Figure 8 shows the timing information for the JTAG signals.

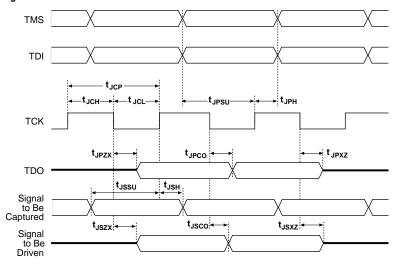


Figure 8. MAX 7000B JTAG Waveforms

Table 9 shows the JTAG timing parameters and values for MAX 7000B devices.

Table 9. Note (1)	JTAG Timing Parameters & Values for MAX 70	100B Dev	ices	
Symbol	Parameter	Min	Max	Unit
t _{JCP}	TCK clock period	100		ns
t _{JCH}	TCK clock high time	50		ns
t _{JCL}	TCK clock low time	50		ns
t _{JPSU}	JTAG port setup time	20		ns
t _{JPH}	JTAG port hold time	45		ns
t _{JPCO}	JTAG port clock to output		25	ns
t _{JPZX}	JTAG port high impedance to valid output		25	ns
t _{JPXZ}	JTAG port valid output to high impedance		25	ns
t _{JSSU}	Capture register setup time	20		ns
t _{JSH}	Capture register hold time	45		ns
t _{JSCO}	Update register clock to output		25	ns
t _{JSZX}	Update register high impedance to valid output		25	ns
t _{JSXZ}	Update register valid output to high impedance		25	ns

Note:

(1) Timing parameters in this table apply to all $V_{\mbox{CCIO}}$ levels.

MAX 7000B devices contain two I/O banks. Both banks support all standards. Each I/O bank has its own VCCIO pins. A single device can support 1.8-V, 2.5-V, and 3.3-V interfaces; each bank can support a different standard independently. Within a bank, any one of the terminated standards can be supported.

Figure 9 shows the arrangement of the MAX 7000B I/O banks.

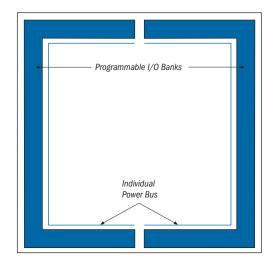


Figure 9. MAX 7000B I/O Banks for Various Advanced I/O Standards

Table 11 shows which macrocells have pins in each I/O bank.

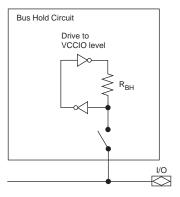
Table 11. Macrocell Pins Contained in Each I/O Bank					
Device	Bank 1	Bank 2			
EPM7032B	1-16	17-32			
EPM7064B	1-32	33-64			
EPM7128B	1-64	65-128			
EPM7256B	1-128, 177-181	129-176, 182-256			
EPM7512B	1-265	266-512			

Each MAX 7000B device has two VREF pins. Each can be set to a separate V_{REF} level. Any I/O pin that uses one of the voltage-referenced standards (GTL+, SSTL-2, or SSTL-3) may use either of the two VREF pins. If these pins are not required as VREF pins, they may be individually programmed to function as user I/O pins.

Two inverters implement the bus-hold circuitry in a loop that weakly drives back to the I/O pin in user mode.

Figure 10 shows a block diagram of the bus-hold circuit.

Figure 10. Bus-Hold Circuit



PCI Compatibility

MAX 7000B devices are compatible with PCI applications as well as all 3.3-V electrical specifications in the *PCI Local Bus Specification Revision 2.2* except for the clamp diode. While having multiple clamp diodes on a signal trace may be redundant, designers can add an external clamp diode to meet the specification. Table 13 shows the MAX 7000B device speed grades that meet the PCI timing specifications.

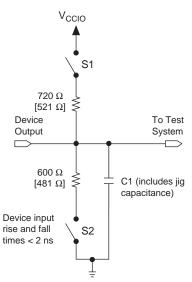
Table 13. MAX 70 Specifications	100B Device Speed Grades tha	nt Meet PCI Timing			
Device	Specification				
	33-MHz PCI	66-MHz PCI			
EPM7032B	All speed grades	-3			
EPM7064B	All speed grades	-3			
EPM7128B	All speed grades	-4			
EPM7256B	All speed grades	-5 (1)			
EPM7512B	All speed grades	-5 (1)			

Note:

(1) The EPM7256B and EPM7512B devices in a -5 speed grade meet all PCI timing specifications for 66-MHz operation except the Input Setup Time to CLK—Bused Signal parameter. However, these devices are within 1 ns of that parameter. EPM7256B and EPM7512B devices meet all other 66-MHz PCI timing specifications.

Figure 11. MAX 7000B AC Test Conditions

Power supply transients can affect AC measurements. Simultaneous transitions of multiple outputs should be avoided for accurate measurement. Threshold tests must not be performed under AC conditions. Large-amplitude, fast-groundcurrent transients normally occur as the device outputs discharge the load capacitances. When these transients flow through the parasitic inductance between the device ground pin and the test system ground, significant reductions in observable noise immunity can result. Numbers in brackets are for 2.5-V outputs. Numbers without brackets are for 3.3-V outputs. Switches S1 and S2 are open for all tests except output disable timing parameters.



Operating Conditions

Tables 14 through 17 provide information on absolute maximum ratings, recommended operating conditions, operating conditions, and capacitance for MAX 7000B devices.

Table 1	Table 14. MAX 7000B Device Absolute Maximum Ratings Note (1)								
Symbol	Parameter	Conditions	Min	Max	Unit				
V _{CCINT}	Supply voltage		-0.5	3.6	V				
V _{CCIO}	Supply voltage		-0.5	3.6	V				
VI	DC input voltage	(2)	-2.0	4.6	V				
I _{OUT}	DC output current, per pin		-33	50	mA				
T _{STG}	Storage temperature	No bias	-65	150	°C				
T _A	Ambient temperature	Under bias	-65	135	°C				
T _J	Junction temperature	Under bias	-65	135	°C				

Table 1	5. MAX 7000B Device Recomm	ended Operating Conditions			
Symbol	Parameter	Conditions	Min	Max	Unit
V _{CCINT}	Supply voltage for internal logic and input buffers	(10)	2.375	2.625	V
V _{CCIO}	Supply voltage for output drivers, 3.3-V operation		3.0	3.6	V
	Supply voltage for output drivers, 2.5-V operation		2.375	2.625	V
	Supply voltage for output drivers, 1.8-V operation		1.71		V
V _{CCISP}	Supply voltage during in-system programming		2.375	2.625	V
VI	Input voltage	(3)	-0.5	3.9	V
Vo	Output voltage		0	V _{CCIO}	V
T _A	Ambient temperature	For commercial use	0		° C
		For industrial use (11)	-40	85	° C
TJ	Junction temperature	For commercial use	0	90	° C
		For industrial use (11)	-40	105	° C
t _R	Input rise time			40	ns
t _F	Input fall time			40	ns

Table 17. MAX 7000B Device Capacitance Note (9)							
Symbol	Parameter	Conditions	Min	Max	Unit		
C _{IN}	Input pin capacitance	V _{IN} = 0 V, f = 1.0 MHz		8	pF		
C _{I/O}	I/O pin capacitance	V _{OUT} = 0 V, f = 1.0 MHz		8	pF		

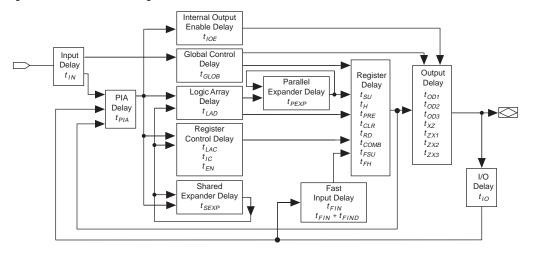
Notes to tables:

- (1) See the Operating Requirements for Altera Devices Data Sheet.
- (2) Minimum DC input voltage is -0.5 V. During transitions, the inputs may undershoot to -2.0 V or overshoot to 4.6 V for input currents less than 100 mA and periods shorter than 20 ns.
- (3) All pins, including dedicated inputs, I/O pins, and JTAG pins, may be driven before V_{CCINT} and V_{CCIO} are powered.
- (4) These values are specified under the Recommended Operating Conditions in Table 15 on page 29.
- (5) The parameter is measured with 50% of the outputs each sourcing the specified current. The I_{OH} parameter refers to high-level TTL or CMOS output current.
- (6) The parameter is measured with 50% of the outputs each sinking the specified current. The I_{OL} parameter refers to low-level TTL or CMOS output current.
- (7) This value is specified for normal device operation. During power-up, the maximum leakage current is ±300 μA.
- (8) This pull-up exists while devices are being programmed in-system and in unprogrammed devices during power-up. The pull-up resistor is from the pins to V_{CCIO}.
- (9) Capacitance is measured at 25° C and is sample-tested only. Two of the dedicated input pins (OE1 and GCLRN) have a maximum capacitance of 15 pF.
- (10) The POR time for all 7000B devices does not exceed 100 µs. The sufficient V_{CCINT} voltage level for POR is 2.375 V. The device is fully initialized within the POR time after V_{CCINT} reaches the sufficient POR voltage level.
- (11) These devices support in-system programming for -40° to 100° C. For in-system programming support between -40° and 0° C, contact Altera Applications.

Timing Model

MAX 7000B device timing can be analyzed with the Altera software, with a variety of popular industry-standard EDA simulators and timing analyzers, or with the timing model shown in Figure 13. MAX 7000B devices have predictable internal delays that enable the designer to determine the worst-case timing of any design. The Altera software provides timing simulation, point-to-point delay prediction, and detailed timing analysis for device-wide performance evaluation.

Figure 13. MAX 7000B Timing Model



The timing characteristics of any signal path can be derived from the timing model and parameters of a particular device. External timing parameters, which represent pin-to-pin timing delays, can be calculated as the sum of internal parameters. Figure 14 shows the timing relationship between internal and external delay parameters.



See *Application Note* 94 (*Understanding MAX* 7000 *Timing*) for more information.

Symbol	Parameter	Conditions	Speed Grade						Unit
			-4		-7		-10		-
			Min	Max	Min	Max	Min	Max	
t _{IN}	Input pad and buffer delay			0.3		0.6		0.8	ns
t_{IO}	I/O input pad and buffer delay			0.3		0.6		0.8	ns
t _{FIN}	Fast input delay			1.3		2.9		3.7	ns
t _{FIND}	Programmable delay adder for fast input			1.0		1.5		1.5	ns
t _{SEXP}	Shared expander delay			1.5		2.8		3.8	ns
t _{PEXP}	Parallel expander delay			0.4		0.8		1.0	ns
t_{LAD}	Logic array delay			1.6		2.9		3.8	ns
t _{LAC}	Logic control array delay			1.4		2.6		3.4	ns
t _{IOE}	Internal output enable delay			0.1		0.3		0.4	ns
t _{OD1}	Output buffer and pad delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		0.9		1.7		2.2	ns
t _{OD3}	Output buffer and pad delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		5.9		6.7		7.2	ns
t _{ZX1}	Output buffer enable delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		1.8		3.3		4.4	ns
t _{ZX3}	Output buffer enable delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		6.8		8.3		9.4	ns
t_{XZ}	Output buffer disable delay	C1 = 5 pF		1.8		3.3		4.4	ns
t_{SU}	Register setup time		1.0		1.9		2.6		ns
t _H	Register hold time		0.4		0.8		1.1		ns
t _{FSU}	Register setup time of fast input		0.8		0.9		0.9		ns
t_{FH}	Register hold time of fast input		1.2		1.6		1.6		ns
t_{RD}	Register delay			0.5		1.1		1.4	ns
t_{COMB}	Combinatorial delay			0.2		0.3		0.4	ns
t _{IC}	Array clock delay			1.4		2.8		3.6	ns
t_{EN}	Register enable time			1.4		2.6		3.4	ns
t_{GLOB}	Global control delay			1.1		2.3		3.1	ns
t _{PRE}	Register preset time			1.0		1.9		2.6	ns
t _{CLR}	Register clear time			1.0		1.9		2.6	ns
t _{PIA}	PIA delay	(2)		1.0		2.0		2.8	ns
t _{LPA}	Low-power adder	(4)		1.5		2.8		3.8	ns

Symbol	Parameter	Conditions	Speed Grade						Unit
			-5		-7		-10		1
			Min	Max	Min	Max	Min	Max	
t _{IN}	Input pad and buffer delay			0.3		0.3		0.5	ns
t_{IO}	I/O input pad and buffer delay			0.3		0.3		0.5	ns
t _{FIN}	Fast input delay			2.2		3.2		4.0	ns
t _{FIND}	Programmable delay adder for fast input			1.5		1.5		1.5	ns
t _{SEXP}	Shared expander delay			1.5		2.1		2.7	ns
t _{PEXP}	Parallel expander delay			0.4		0.5		0.7	ns
t_{LAD}	Logic array delay			1.7		2.3		3.0	ns
t_{LAC}	Logic control array delay			1.5		2.0		2.6	ns
t _{IOE}	Internal output enable delay			0.1		0.2		0.2	ns
t _{OD1}	Output buffer and pad delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		0.9		1.2		1.6	ns
t _{OD3}	Output buffer and pad delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		5.9		6.2		6.6	ns
t _{ZX1}	Output buffer enable delay slow slew rate = off V _{CCIO} = 3.3 V	C1 = 35 pF		2.8		3.8		5.0	ns
t _{ZX3}	Output buffer enable delay slow slew rate = on V _{CCIO} = 2.5 V or 3.3 V	C1 = 35 pF		7.8		8.8		10.0	ns
t_{XZ}	Output buffer disable delay	C1 = 5 pF		2.8		3.8		5.0	ns
t_{SU}	Register setup time		1.5		2.0		2.6		ns
t _H	Register hold time		0.4		0.5		0.7		ns
t _{FSU}	Register setup time of fast input		0.8		1.1		1.1		ns
t_{FH}	Register hold time of fast input		1.2		1.4		1.4		ns
t_{RD}	Register delay			0.5		0.7		1.0	ns
t _{COMB}	Combinatorial delay			0.2		0.3		0.4	ns
t _{IC}	Array clock delay			1.8		2.4		3.1	ns
t_{EN}	Register enable time			1.5		2.0		2.6	ns
t _{GLOB}	Global control delay			2.0		2.8		3.6	ns
t _{PRE}	Register preset time			1.0		1.4		1.9	ns
t _{CLR}	Register clear time			1.0		1.4		1.9	ns
t_{PIA}	PIA delay	(2)		2.4		3.4		4.5	ns
t_{LPA}	Low-power adder	(4)		2.0		2.7		3.6	ns

I/O Standard	Parameter	Speed Grade					Unit	
		-5		-	-7		-10	
		Min	Max	Min	Max	Min	Max	
3.3 V TTL/CMOS	Input to PIA		0.0		0.0		0.0	ns
	Input to global clock and clear		0.0		0.0		0.0	ns
	Input to fast input register		0.0		0.0		0.0	ns
	All outputs		0.0		0.0		0.0	ns
2.5 V TTL/CMOS	Input to PIA		0.4		0.5		0.7	ns
	Input to global clock and clear		0.3		0.4		0.5	ns
	Input to fast input register		0.2		0.3		0.3	ns
	All outputs		0.2		0.3		0.3	ns
1.8 V TTL/CMOS	Input to PIA		0.7		1.0		1.3	ns
	Input to global clock and clear		0.6		0.8		1.0	ns
	Input to fast input register		0.5		0.6		0.8	ns
	All outputs		1.3		1.8		2.3	ns
SSTL-2 Class I	Input to PIA		1.5		2.0		2.7	ns
	Input to global clock and clear		1.4		1.9		2.5	ns
	Input to fast input register		1.1		1.5		2.0	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-2 Class II	Input to PIA		1.5		2.0		2.7	ns
	Input to global clock and clear		1.4		1.9		2.5	ns
	Input to fast input register		1.1		1.5		2.0	ns
	All outputs		-0.1		-0.1		-0.2	ns
SSTL-3 Class I	Input to PIA		1.4		1.9		2.5	ns
	Input to global clock and clear		1.2		1.6		2.2	ns
	Input to fast input register		1.0		1.4		1.8	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-3 Class II	Input to PIA		1.4		1.9		2.5	ns
	Input to global clock and clear		1.2		1.6		2.2	ns
	Input to fast input register		1.0		1.4		1.8	ns
	All outputs		0.0		0.0		0.0	ns
GTL+	Input to PIA		1.8		2.5		3.3	ns
	Input to global clock and clear		1.9		2.6		3.5	ns
	Input to fast input register		1.8		2.5		3.3	ns
	All outputs		0.0		0.0		0.0	ns

The I_{CCINT} value depends on the switching frequency and the application logic. The I_{CCINT} value is calculated with the following equation:

 $I_{CCINT} =$

$$(A \times MC_{TON}) + [B \times (MC_{DEV} - MC_{TON})] + (C \times MC_{USED} \times f_{MAX} \times tog_{LC})$$

The parameters in this equation are:

MC_{TON} = Number of macrocells with the Turbo BitTM option turned on, as reported in the MAX+PLUS II Report File (.rpt)

 MC_{DEV} = Number of macrocells in the device

 MC_{USED} = Total number of macrocells in the design, as reported in

the Report File

 f_{MAX} = Highest clock frequency to the device

 tog_{LC} = Average percentage of logic cells toggling at each clock

(typically 12.5%)

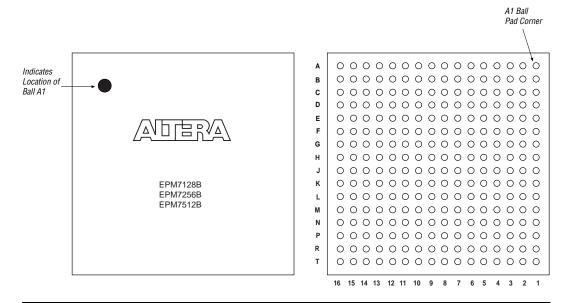
A, B, C = Constants, shown in Table 33

Table 33. MAX 7000B I _{CC} Equation Constants							
Device	A	В	C				
EPM7032B	0.91	0.54	0.010				
EPM7064B	0.91	0.54	0.012				
EPM7128B	0.91	0.54	0.016				
EPM7256B	0.91	0.54	0.017				
EPM7512B	0.91	0.54	0.019				

This calculation provides an I_{CC} estimate based on typical conditions using a pattern of a 16-bit, loadable, enabled, up/down counter in each LAB with no output load. Actual I_{CC} should be verified during operation because this measurement is sensitive to the actual pattern in the device and the environmental operating conditions.

Figure 29. 256-Pin FineLine BGA Package Pin-Out Diagram

Package outline not drawn to scale.



Revision History

The information contained in the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.5 supersedes information published in previous versions.

Version 3.5

The following changes were made to the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.5:

Updated Figure 28.

Version 3.4

The following changes were made to the MAX 7000B Programmable Logic Device Family Data Sheet version 3.4:

■ Updated text in the "Power Sequencing & Hot-Socketing" section.

Version 3.3

The following changes were made to the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.3:

- Updated Table 3.
- Added Tables 4 through 6.

Version 3.2

The following changes were made to the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.2:

 Updated Note (10) and added ambient temperature (T_A) information to Table 15.

Version 3.1

The following changes were made to the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.1:

- Updated V_{IH} and V_{IL} specifications in Table 16.
- Updated leakage current conditions in Table 16.

Version 3.0

The following changes were made to the *MAX 7000B Programmable Logic Device Family Data Sheet* version 3.0:

- Updated timing numbers in Table 1.
- Updated Table 16.
- Updated timing in Tables 18, 19, 21, 22, 24, 25, 27, 28, 30, and 31.



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