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**Understanding Embedded - CPLDs (Complex Programmable Logic Devices)** 

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

## **Applications of Embedded - CPLDs**

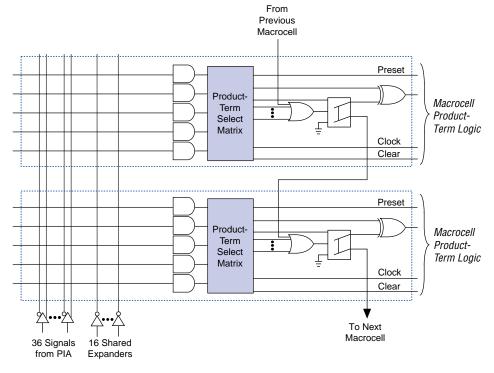
Details	
Product Status	Obsolete
Programmable Type	In System Programmable
Delay Time tpd(1) Max	5.5 ns
Voltage Supply - Internal	2.375V ~ 2.625V
Number of Logic Elements/Blocks	32
Number of Macrocells	512
Number of Gates	10000
Number of I/O	212
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	-
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/intel/epm7512bfc256-5gz

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Figure 4. MAX 7000B Parallel Expanders

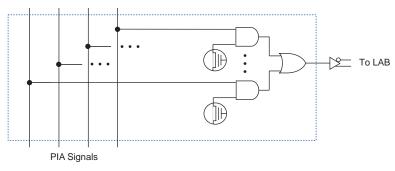
Unused product terms in a macrocell can be allocated to a neighboring macrocell.



# **Programmable Interconnect Array**

Logic is routed between LABs on the PIA. This global bus is a programmable path that connects any signal source to any destination on the device. All MAX 7000B dedicated inputs, I/O pins, and macrocell outputs feed the PIA, which makes the signals available throughout the entire device. Only the signals required by each LAB are actually routed from the PIA into the LAB. Figure 5 shows how the PIA signals are routed into the LAB. An EEPROM cell controls one input to a two-input AND gate, which selects a PIA signal to drive into the LAB.

Figure 5. MAX 7000B PIA Routing



While the routing delays of channel-based routing schemes in masked or field-programmable gate arrays (FPGAs) are cumulative, variable, and path-dependent, the MAX 7000B PIA has a predictable delay. The PIA makes a design's timing performance easy to predict.

#### I/O Control Blocks

The I/O control block allows each I/O pin to be individually configured for input, output, or bidirectional operation. All I/O pins have a tri-state buffer that is individually controlled by one of the global output enable signals or directly connected to ground or  $V_{CC}.$  Figure 6 shows the I/O control block for MAX 7000B devices. The I/O control block has six or ten global output enable signals that are driven by the true or complement of two output enable signals, a subset of the I/O pins, or a subset of the I/O macrocells.

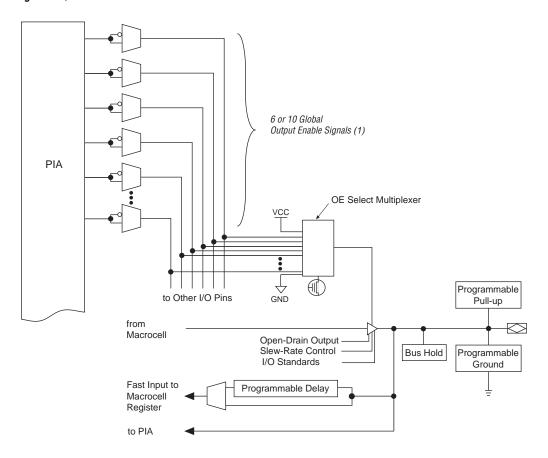


Figure 6. I/O Control Block of MAX 7000B Devices

#### Note:

(1) EPM7032B, EPM7064B, EPM7128B, and EPM7256B devices have six output enable signals. EPM7512B devices have ten output enable signals.

When the tri-state buffer control is connected to ground, the output is tri-stated (high impedance) and the I/O pin can be used as a dedicated input. When the tri-state buffer control is connected to  $V_{CC}$ , the output is enabled.

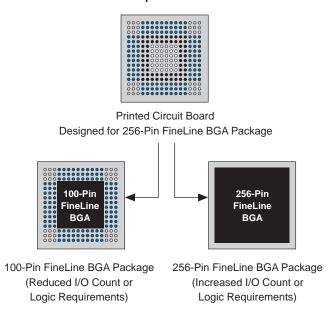
The MAX 7000B architecture provides dual I/O feedback, in which macrocell and pin feedbacks are independent. When an I/O pin is configured as an input, the associated macrocell can be used for buried logic.

# SameFrame Pin-Outs

MAX 7000B devices support the SameFrame pin-out feature for FineLine BGA and 0.8-mm Ultra FineLine BGA packages. The SameFrame pin-out feature is the arrangement of balls on FineLine BGA and 0.8-mm Ultra FineLine BGA packages such that the lower-ball-count packages form a subset of the higher-ball-count packages. SameFrame pin-outs provide the flexibility to migrate not only from device to device within the same package, but also from one package to another. FineLine BGA packages are compatible with other FineLine BGA packages, and 0.8-mm Ultra FineLine BGA packages are compatible with other 0.8-mm Ultra FineLine BGA packages. A given printed circuit board (PCB) layout can support multiple device density/package combinations. For example, a single board layout can support a range of devices from an EPM7064B device in a 100-pin FineLine BGA package to an EPM7512B device in a 256-pin FineLine BGA package.

The Altera software provides support to design PCBs with SameFrame pin-out devices. Devices can be defined for present and future use. The Altera software generates pin-outs describing how to layout a board to take advantage of this migration (see Figure 7).

Figure 7. SameFrame Pin-Out Example



# In-System Programmability (ISP)

MAX 7000B devices can be programmed in-system via an industry-standard 4-pin IEEE Std. 1149.1 (JTAG) interface. ISP offers quick, efficient iterations during design development and debugging cycles. The MAX 7000B architecture internally generates the high programming voltages required to program EEPROM cells, allowing in-system programming with only a single 2.5-V power supply. During in-system programming, the I/O pins are tri-stated and weakly pulled-up to eliminate board conflicts. The pull-up value is nominally 50 k³4.

MAX 7000B devices have an enhanced ISP algorithm for faster programming. These devices also offer an ISP\_Done bit that provides safe operation when in-system programming is interrupted. This ISP\_Done bit, which is the last bit programmed, prevents all I/O pins from driving until the bit is programmed.

ISP simplifies the manufacturing flow by allowing devices to be mounted on a PCB with standard pick-and-place equipment before they are programmed. MAX 7000B devices can be programmed by downloading the information via in-circuit testers, embedded processors, the Altera MasterBlaster communications cable, and the ByteBlasterMV parallel port download cable. Programming the devices after they are placed on the board eliminates lead damage on high-pin-count packages (e.g., QFP packages) due to device handling. MAX 7000B devices can be reprogrammed after a system has already shipped to the field. For example, product upgrades can be performed in the field via software or modem.

In-system programming can be accomplished with either an adaptive or constant algorithm. An adaptive algorithm reads information from the unit and adapts subsequent programming steps to achieve the fastest possible programming time for that unit. A constant algorithm uses a pre-defined (non-adaptive) programming sequence that does not take advantage of adaptive algorithm programming time improvements. Some in-circuit testers cannot program using an adaptive algorithm. Therefore, a constant algorithm must be used. MAX 7000B devices can be programmed with either an adaptive or constant (non-adaptive) algorithm.

The Jam Standard Test and Programming Language (STAPL), JEDEC standard JESD-71, can be used to program MAX 7000B devices with in-circuit testers, PCs, or embedded processors.



For more information on using the Jam language, see *Application Note 88* (*Using the Jam Language for ISP & ICR via an Embedded Processor*) and *Application Note 122* (*Using STAPL for ISP & ICR via an Embedded Processor*).

The ISP circuitry in MAX 7000B devices is compliant with the IEEE Std. 1532 specification. The IEEE Std. 1532 is a standard developed to allow concurrent ISP between multiple PLD vendors.

By combining the pulse and shift times for each of the programming stages, the program or verify time can be derived as a function of the TCK frequency, the number of devices, and specific target device(s). Because different ISP-capable devices have a different number of EEPROM cells, both the total fixed and total variable times are unique for a single device.

## Programming a Single MAX 7000B Device

The time required to program a single MAX 7000B device in-system can be calculated from the following formula:

$$t_{PROG} = t_{PPULSE} + \frac{Cycle_{PTCK}}{f_{TCK}}$$

where:  $t_{PROG} = \text{Programming time}$   $t_{PPULSE} = \text{Sum of the fixed times to erase, program, and}$ 

verify the EEPROM cells

 $Cycle_{PTCK}$  = Number of TCK cycles to program a device

= TCK frequency

The ISP times for a stand-alone verification of a single MAX 7000B device can be calculated from the following formula:

$$t_{VER} = t_{VPULSE} + \frac{Cycle_{VTCK}}{f_{TCK}}$$

where:  $t_{VER}$  = Verify time  $t_{VPULSE}$  = Sum of the fixed times to verify the EEPROM cells  $Cycle_{VTCK}$  = Number of TCK cycles to verify a device

The instruction register length of MAX 7000B devices is ten bits. The MAX 7000B USERCODE register length is 32 bits. Tables 7 and 8 show the boundary-scan register length and device IDCODE information for MAX 7000B devices.

Table 7. MAX 7000B Boundary-Scan Register Length						
Device	Boundary-Scan Register Length					
EPM7032B	96					
EPM7064B	192					
EPM7128B	288					
EPM7256B	480					
EPM7512B	624					

Table 8. 32-Bit MAX 7000B Device IDCODENote (1)								
Device	IDCODE (32 Bits)							
	Version (4 Bits)	Part Number (16 Bits)	Manufacturer's Identity (11 Bits)	1 (1 Bit) (2)				
EPM7032B	0010	0111 0000 0011 0010	00001101110	1				
EPM7064B	0010	0111 0000 0110 0100	00001101110	1				
EPM7128B	0010	0111 0001 0010 1000	00001101110	1				
EPM7256B	0010	0111 0010 0101 0110	00001101110	1				
EPM7512B	0010	0111 0101 0001 0010	00001101110	1				

#### Notes:

- (1) The most significant bit (MSB) is on the left.
- (2) The least significant bit (LSB) for all JTAG IDCODEs is 1.



See Application Note 39 (IEEE 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices) for more information on JTAG boundary-scan testing.

Figure 8 shows the timing information for the JTAG signals.

Table 10. MAX 7000B MultiVolt I/O Support								
V <sub>CCIO</sub> (V) Input Signal (V) Output Signal (V)								
	1.8	2.5	3.3	5.0	1.8	2.5	3.3	5.0
1.8	<b>✓</b>	<b>✓</b>	<b>✓</b>		<b>✓</b>			
2.5	<b>✓</b>	<b>✓</b>	<b>✓</b>			<b>✓</b>		
3.3	<b>✓</b>	<b>✓</b>	<b>✓</b>				<b>✓</b>	<b>✓</b>

# **Open-Drain Output Option**

MAX 7000B devices provide an optional open-drain (equivalent to open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write enable signals) that can be asserted by any of several devices. It can also provide an additional wired-OR plane.

# **Programmable Ground Pins**

Each unused I/O pin on MAX 7000B devices may be used as an additional ground pin. This programmable ground feature does not require the use of the associated macrocell; therefore, the buried macrocell is still available for user logic.

#### Slew-Rate Control

The output buffer for each MAX 7000B I/O pin has an adjustable output slew rate that can be configured for low-noise or high-speed performance. A faster slew rate provides high-speed transitions for high-performance systems. However, these fast transitions may introduce noise transients into the system. A slow slew rate reduces system noise, but adds a nominal delay of 4 to 5 ns. When the configuration cell is turned off, the slew rate is set for low-noise performance. Each I/O pin has an individual EEPROM bit that controls the slew rate, allowing designers to specify the slew rate on a pin-by-pin basis. The slew rate control affects both the rising and falling edges of the output signal.

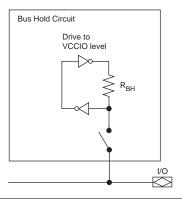
# Advanced I/O Standard Support

The MAX 7000B I/O pins support the following I/O standards: LVTTL, LVCMOS, 1.8-V I/O, 2.5-V I/O, GTL+, SSTL-3 Class I and II, and SSTL-2 Class I and II.

Two inverters implement the bus-hold circuitry in a loop that weakly drives back to the I/O pin in user mode.

Figure 10 shows a block diagram of the bus-hold circuit.

Figure 10. Bus-Hold Circuit



# PCI Compatibility

MAX 7000B devices are compatible with PCI applications as well as all 3.3-V electrical specifications in the *PCI Local Bus Specification Revision 2.2* except for the clamp diode. While having multiple clamp diodes on a signal trace may be redundant, designers can add an external clamp diode to meet the specification. Table 13 shows the MAX 7000B device speed grades that meet the PCI timing specifications.

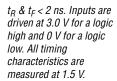
Table 13. MAX 70 Specifications	00B Device Speed Grades tha	t Meet PCI Timing
Device	Specif	ication
	33-MHz PCI	66-MHz PCI
EPM7032B	All speed grades	-3
EPM7064B	All speed grades	-3
EPM7128B	All speed grades	-4
EPM7256B	All speed grades	-5 (1)
EPM7512B	All speed grades	-5 (1)

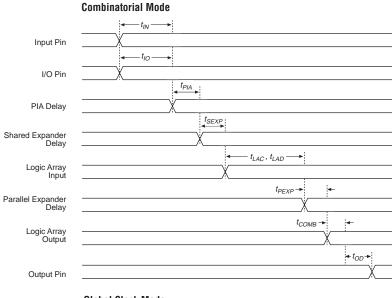
#### Note:

(1) The EPM7256B and EPM7512B devices in a -5 speed grade meet all PCI timing specifications for 66-MHz operation except the Input Setup Time to CLK—Bused Signal parameter. However, these devices are within 1 ns of that parameter. EPM7256B and EPM7512B devices meet all other 66-MHz PCI timing specifications.

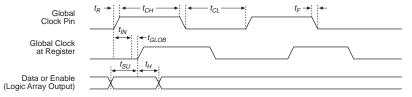
Table 1	5. MAX 7000B Device Recomm	ended Operating Conditions			
Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CCINT</sub>	Supply voltage for internal logic and input buffers	(10)	2.375	2.625	V
V <sub>CCIO</sub>	Supply voltage for output drivers, 3.3-V operation		3.0	3.6	V
	Supply voltage for output drivers, 2.5-V operation		2.375	2.625	V
	Supply voltage for output drivers, 1.8-V operation		1.71	1.89	V
V <sub>CCISP</sub>	Supply voltage during in-system programming		2.375	2.625	V
VI	Input voltage	(3)	-0.5	3.9	V
Vo	Output voltage		0	V <sub>CCIO</sub>	V
T <sub>A</sub>	Ambient temperature	For commercial use	0	70	° C
		For industrial use (11)	-40	85	° C
TJ	Junction temperature	For commercial use	0	90	° C
		For industrial use (11)	-40	105	° C
t <sub>R</sub>	Input rise time			40	ns
t <sub>F</sub>	Input fall time			40	ns

### Figure 14. MAX 7000B Switching Waveforms





#### **Global Clock Mode**



#### **Array Clock Mode**

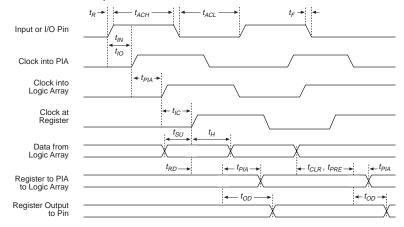


Table 19.	Table 19. EPM7032B Internal Timing Parameters Notes (1)								
Symbol	Parameter	Conditions	Speed Grade						Unit
			-3.5		-5.0		-7.5		
			Min	Max	Min	Max	Min	Max	
t <sub>IN</sub>	Input pad and buffer delay			0.3		0.5		0.7	ns
$t_{IO}$	I/O input pad and buffer delay			0.3		0.5		0.7	ns
t <sub>FIN</sub>	Fast input delay			0.9		1.3		2.0	ns
t <sub>FIND</sub>	Programmable delay adder for fast input			1.0		1.5		1.5	ns
t <sub>SEXP</sub>	Shared expander delay			1.5		2.1		3.2	ns
t <sub>PEXP</sub>	Parallel expander delay			0.4		0.6		0.9	ns
$t_{LAD}$	Logic array delay			1.4		2.0		3.1	ns
$t_{LAC}$	Logic control array delay			1.2		1.7		2.6	ns
t <sub>IOE</sub>	Internal output enable delay			0.1		0.2		0.3	ns
t <sub>OD1</sub>	Output buffer and pad delay slow slew rate = off V <sub>CCIO</sub> = 3.3 V	C1 = 35 pF		0.9		1.2		1.8	ns
t <sub>OD3</sub>	Output buffer and pad delay slow slew rate = on V <sub>CCIO</sub> = 2.5 V or 3.3 V	C1 = 35 pF		5.9		6.2		6.8	ns
t <sub>ZX1</sub>	Output buffer enable delay slow slew rate = off V <sub>CCIO</sub> = 3.3 V	C1 = 35 pF		1.6		2.2		3.4	ns
t <sub>ZX3</sub>	Output buffer enable delay slow slew rate = on V <sub>CCIO</sub> = 2.5 V or 3.3 V	C1 = 35 pF		6.6		7.2		8.4	ns
$t_{XZ}$	Output buffer disable delay	C1 = 5 pF		1.6		2.2		3.4	ns
$t_{SU}$	Register setup time		0.7		1.1		1.6		ns
t <sub>H</sub>	Register hold time		0.4		0.5		0.9		ns
t <sub>FSU</sub>	Register setup time of fast input		0.8		0.8		1.1		ns
$t_{FH}$	Register hold time of fast input		1.2		1.2		1.4		ns
$t_{RD}$	Register delay			0.5		0.6		0.9	ns
t <sub>COMB</sub>	Combinatorial delay			0.2		0.3		0.5	ns
t <sub>IC</sub>	Array clock delay			1.2		1.8		2.8	ns
t <sub>EN</sub>	Register enable time			1.2		1.7		2.6	ns
t <sub>GLOB</sub>	Global control delay			0.7		1.1		1.6	ns
t <sub>PRE</sub>	Register preset time			1.0		1.3		1.9	ns
t <sub>CLR</sub>	Register clear time			1.0		1.3		1.9	ns
t <sub>PIA</sub>	PIA delay	(2)		0.7		1.0		1.4	ns
$t_{LPA}$	Low-power adder	(4)		1.5		2.1		3.2	ns

I/O Standard	Parameter	Speed Grade						Unit
		-3.5		-5.0		-7.5		
		Min	Max	Min	Max	Min	Max	
3.3 V TTL/CMOS	Input to (PIA)		0.0		0.0		0.0	ns
	Input to global clock and clear		0.0		0.0		0.0	ns
	Input to fast input register		0.0		0.0		0.0	ns
	All outputs		0.0		0.0		0.0	ns
2.5 V TTL/CMOS	Input to PIA		0.3		0.4		0.6	ns
	Input to global clock and clear		0.3		0.4		0.6	ns
	Input to fast input register		0.2		0.3		0.4	ns
	All outputs		0.2		0.3		0.4	ns
1.8 V TTL/CMOS	Input to PIA		0.5		0.8		1.1	ns
	Input to global clock and clear		0.5		0.8		1.1	ns
	Input to fast input register		0.4		0.5		0.8	ns
	All outputs		1.2		1.8		2.6	ns
SSTL-2 Class I	Input to PIA		1.3		1.9		2.8	ns
	Input to global clock and clear		1.2		1.8		2.6	ns
	Input to fast input register		0.9		1.3		1.9	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-2 Class II	Input to PIA		1.3		1.9		2.8	ns
	Input to global clock and clear		1.2		1.8		2.6	ns
	Input to fast input register		0.9		1.3		1.9	ns
	All outputs		-0.1		-0.1		-0.2	ns
SSTL-3 Class I	Input to PIA		1.2		1.8		2.6	ns
	Input to global clock and clear		0.9		1.3		1.9	ns
	Input to fast input register		0.8		1.1		1.7	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-3 Class II	Input to PIA		1.2		1.8		2.6	ns
	Input to global clock and clear		0.9		1.3		1.9	ns
	Input to fast input register		0.8		1.1		1.7	ns
	All outputs		0.0		0.0		0.0	ns
GTL+	Input to PIA		1.6		2.3		3.4	ns
	Input to global clock and clear		1.6		2.3		3.4	ns
	Input to fast input register		1.5		2.1		3.2	ns
	All outputs		0.0		0.0		0.0	ns

I/O Standard	Parameter	Speed Grade						Unit
		-	5	-	7		10	
		Min	Max	Min	Max	Min	Max	
3.3 V TTL/CMOS	Input to PIA		0.0		0.0		0.0	ns
	Input to global clock and clear		0.0		0.0		0.0	ns
	Input to fast input register		0.0		0.0		0.0	ns
	All outputs		0.0		0.0		0.0	ns
2.5 V TTL/CMOS	Input to PIA		0.4		0.6		0.8	ns
	Input to global clock and clear		0.3		0.5		0.6	ns
	Input to fast input register		0.2		0.3		0.4	ns
	All outputs		0.2		0.3		0.4	ns
1.8 V TTL/CMOS	Input to PIA		0.6		0.9		1.2	ns
	Input to global clock and clear		0.6		0.9		1.2	ns
	Input to fast input register		0.5		0.8		1.0	ns
	All outputs		1.3		2.0		2.6	ns
SSTL-2 Class I	Input to PIA		1.5		2.3		3.0	ns
	Input to global clock and clear		1.3		2.0		2.6	ns
	Input to fast input register		1.1		1.7		2.2	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-2 Class II	Input to PIA		1.5		2.3		3.0	ns
	Input to global clock and clear		1.3		2.0		2.6	ns
	Input to fast input register		1.1		1.7		2.2	ns
	All outputs		-0.1		-0.2		-0.2	ns
SSTL-3 Class I	Input to PIA		1.4		2.1		2.8	ns
	Input to global clock and clear		1.1		1.7		2.2	ns
	Input to fast input register		1.0		1.5		2.0	ns
	All outputs		0.0		0.0		0.0	ns
SSTL-3 Class II	Input to PIA		1.4		2.1		2.8	ns
	Input to global clock and clear		1.1		1.7		2.2	ns
	Input to fast input register		1.0		1.5		2.0	ns
	All outputs		0.0		0.0		0.0	ns
GTL+	Input to PIA		1.8		2.7		3.6	ns
	Input to global clock and clear		1.8		2.7		3.6	ns
	Input to fast input register		1.7		2.6		3.4	ns
	All outputs		0.0		0.0		0.0	ns

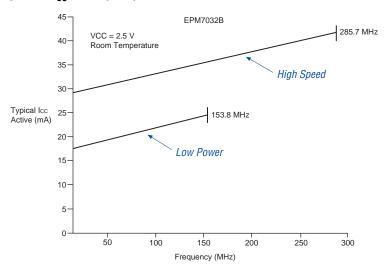
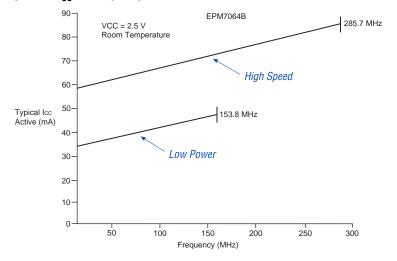


Figure 15. I<sub>CC</sub> vs. Frequency for EPM7032B Devices





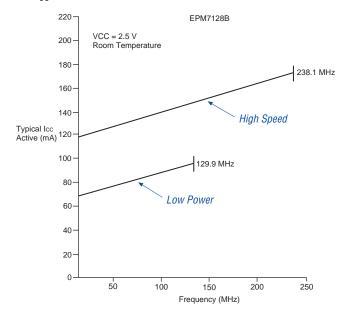
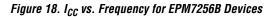
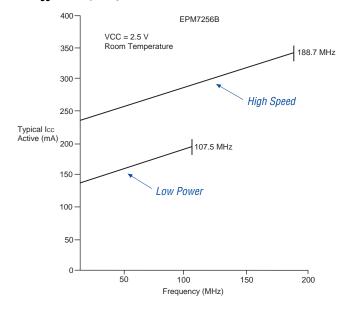


Figure 17.  $I_{CC}$  vs. Frequency for EPM7128B Devices





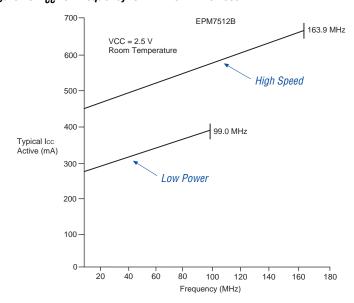


Figure 19.  $I_{CC}$  vs. Frequency for EPM7512B Devices

Figure 23. 100-Pin TQFP Package Pin-Out Diagram

Package outline not drawn to scale.

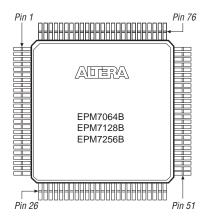


Figure 24. 100-Pin FineLine BGA Package Pin-Out Diagram

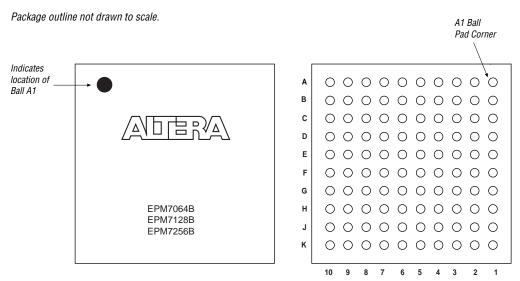


Figure 25. 144-Pin TQFP Package Pin-Out Diagram

Package outline not drawn to scale.

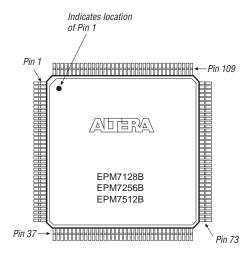
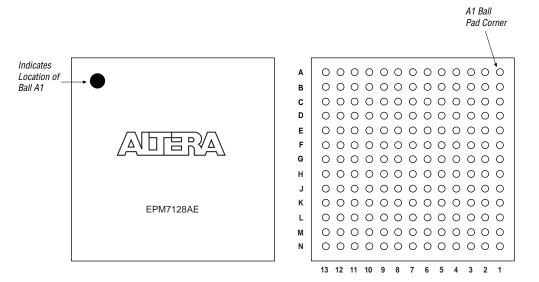


Figure 26. 169-Pin Ultra FineLine BGA Pin-Out Diagram

Package outline not drawn to scale.



### Figure 28. 256-Pin BGA Package Pin-Out Diagram

Package outline not drawn to scale.

