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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
roduct Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
peed	24MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
eripherals	POR, PWM, WDT
lumber of I/O	16
rogram Memory Size	4KB (4K x 8)
rogram Memory Type	FLASH
EPROM Size	-
AM Size	256 x 8
oltage - Supply (Vcc/Vdd)	2.4V ~ 5.25V
ata Converters	A/D 8x14b; D/A 2x9b
scillator Type	Internal
perating Temperature	-40°C ~ 85°C (TA)
Nounting Type	Surface Mount
ackage / Case	20-SSOP (0.209", 5.30mm Width)
upplier Device Package	20-SSOP



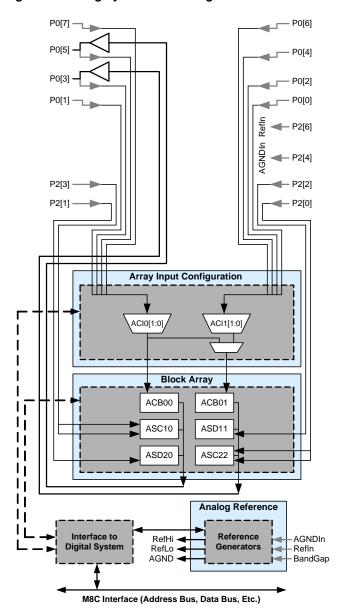
## **Analog System**

The analog system is composed of six configurable blocks, each comprised of an opamp circuit allowing the creation of complex analog signal flows. Analog peripherals are very flexible and can be customized to support specific application requirements. Some of the common PSoC analog functions for this device (most available as user modules) are:

- ADCs (up to two, with 6- to 14-bit resolution, selectable as incremental, delta-sigma, or successive approximation register (SAR))
- Filters (two- and four-pole band pass, low pass, and notch)
- Amplifiers (up to two, with selectable gain up to 48x)
- Instrumentation amplifiers (one with selectable gain up to 93x)
- Comparators (up to two, with 16 selectable thresholds)
- DACs (up to two, with 6- to 9-bit resolution)
- Multiplying DACs (up to two, with 6- to 9-bit resolution)
- High current output drivers (two with 30-mA drive)
- 1.3 V reference (as a system resource)
- DTMF dialer
- Modulators
- Correlators
- Peak detectors
- Many other topologies possible

Analog blocks are arranged in a column of three, which includes one continuous time (CT) and two switched capacitor (SC) blocks, as shown in Figure 2.

Figure 2. Analog System Block Diagram





subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an online support Forum to aid the designer.

#### In-Circuit Emulator

A low-cost, high-functionality in-circuit emulator (ICE) is available for development support. This hardware can program single devices.

The emulator consists of a base unit that connects to the PC using a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full-speed (24 MHz) operation.

# **Designing with PSoC Designer**

The development process for the PSoC device differs from that of a traditional fixed function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and by lowering inventory costs. These configurable resources, called PSoC Blocks, have the ability to implement a wide variety of user-selectable functions.

The PSoC development process can be summarized in the following four steps:

- 1. Select User Modules
- 2. Configure User Modules
- 3. Organize and Connect
- 4. Generate, Verify, and Debug

#### Select Components

PSoC Designer provides a library of pre-built, pre-tested hardware peripheral components called "user modules." User modules make selecting and implementing peripheral devices, both analog and digital, simple.

#### **Configure Components**

Each of the User Modules you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their

precise configuration to your particular application. For example, a PWM User Module configures one or more

digital PSoC blocks, one for each 8 bits of resolution. The user module parameters permit you to establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These user module datasheets explain the internal operation of the User Module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information you may need to successfully implement your design.

#### **Organize and Connect**

You build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. You perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

#### Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, you perform the "Generate Configuration Files" step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides application programming interfaces (APIs) with high-level functions to control and respond to hardware events at run time and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in C, assembly language, or both.

The last step in the development process takes place inside PSoC Designer's Debugger (access by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition

to traditional single-step, run-to-breakpoint and watch-variable features, the debug interface provides a large trace buffer and allows you to define complex breakpoint events that include monitoring address and data bus values, memory locations and external signals.



## **Pinouts**

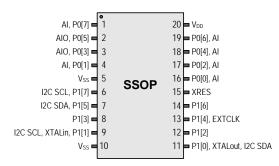
The automotive CY8C24x23A PSoC device is available in a variety of packages which are listed and illustrated in the following tables. Every port pin (labeled with a "P") is capable of digital I/O. However,  $V_{SS}$ ,  $V_{DD}$ , and XRES are not capable of digital I/O.

#### 20-Pin Part Pinout

Table 2. 20-Pin Part Pinout (Shrink Small-Outline Package (SSOP))

Pin	Ту	ре	Pin	<b>D</b>			
No.	Digital	Analog	Name	Description			
1	I/O	I	P0[7]	Analog column mux input			
2	I/O	I/O	P0[5]	Analog column mux input and column output			
3	I/O	I/O	P0[3]	Analog column mux input and column output			
4	I/O	I	P0[1]	Analog column mux input			
5	Po	wer	$V_{SS}$	Ground connection			
6	I/O		P1[7]	I <sup>2</sup> C serial clock (SCL)			
7	I/O		P1[5]	I <sup>2</sup> C serial data (SDA)			
8	I/O		P1[3]				
9	I/O		P1[1]	Crystal input (XTALin), I <sup>2</sup> C serial clock (SCL), ISSP-SCLK <sup>[5]</sup>			
10	Po	wer	$V_{SS}$	Ground connection			
11	I/O		P1[0]	Crystal output (XTALout), I <sup>2</sup> C serial data (SDA), ISSP-SDATA <sup>[5]</sup>			
12	I/O		P1[2]				
13	I/O		P1[4]	Optional external clock input (EXTCLK)			
14	I/O		P1[6]				
15	In	out	XRES	Active high external reset with internal pull down			
16	I/O	ı	P0[0]	Analog column mux input			
17	I/O	Į	P0[2]	Analog column mux input			
18	I/O	Ĭ	P0[4]	Analog column mux input			
19	I/O	I	P0[6]	Analog column mux input			
20	Po	wer	$V_{DD}$	Supply voltage			

Figure 3. CY8C24223A 20-Pin PSoC Device



 $\textbf{LEGEND}\text{: } A = Analog, \ I = Input, \ and \ O = Output.$ 

#### Note

<sup>5.</sup> These are the ISSP pins, which are not high Z when coming out of POR. See the PSoC Technical Reference Manual for details.



# Registers

## **Register Conventions**

This section lists the registers of the automotive CY8C24x23A PSoC device. For detailed register information, refer to the *PSoC Technical Reference Manual.* 

The register conventions specific to this section are listed in the following table.

Table 4. Abbreviations

Convention	Description
R	Read register or bit(s)
W	Write register or bit(s)
L	Logical register or bit(s)
С	Clearable register or bit(s)
#	Access is bit specific

#### **Register Mapping Tables**

The PSoC device has a total register address space of 512 bytes. The register space is referred to as I/O space and is divided into two banks, bank 0 and bank 1. The XIO bit in the Flag register (CPU\_F) determines which bank the user is currently in. When the XIO bit is set to '1', the user is in bank 1.

**Note** In the following register mapping tables, blank fields are Reserved and must not be accessed.



Table 6. Register Map Bank 1 Table: Configuration Space

Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access
PRT0DM0	00	RW		40		ASC10CR0	80	RW		C0	
PRT0DM1	01	RW		41		ASC10CR1	81	RW		C1	
PRT0IC0	02	RW		42		ASC10CR2	82	RW		C2	
PRT0IC1	03	RW		43		ASC10CR3	83	RW		C3	
PRT1DM0	04	RW		44		ASD11CR0	84	RW		C4	
PRT1DM1	05	RW		45		ASD11CR1	85	RW		C5	
PRT1IC0	06	RW		46		ASD11CR2	86	RW		C6	
PRT1IC1	07	RW		47		ASD11CR3	87	RW		C7	
PRT2DM0	08	RW		48			88			C8	
PRT2DM1	09	RW		49			89			C9	
PRT2IC0	0A	RW		4A			8A			CA	
PRT2IC1	0B	RW		4B			8B			СВ	
	0C			4C			8C			CC	
	0D			4D			8D			CD	
	0E			4E			8E			CE	
	0F			4F			8F			CF	
	10			50		ASD20CR0	90	RW	GDI_O_IN	D0	RW
	11			51		ASD20CR1	91	RW	GDI_E_IN	D1	RW
	12		1	52		ASD20CR2	92	RW	GDI_O_OU	D2	RW
	13		1	53		ASD20CR3	93	RW	GDI_E_OU	D3	RW
	14		1	54		ASC21CR0	94	RW	,	D4	<b></b>
	15		1	55		ASC21CR1	95	RW		D5	-
	16		<del> </del>	56		ASC21CR2	96	RW		D6	<del>                                     </del>
	17		1	57		ASC21CR2	97	RW		D7	1
	18		1	58		A0021010	98	1744		D8	
	19		1	59		1	99			D9	
	1A		1	5A		1	9A			DA DA	
	1B		1	5B		1	9B			DB	
	1C		-	5C			9C			DC	
	1D			5D			9D		OSC_GO_EN	DD	RW
	1E			5E			9E		OSC_GC_LN	DE	RW
	1F			5F			9F		OSC_CR4	DF	RW
DBB00FN	20	RW	CLK_CR0	60	RW		A0		OSC_CR3	E0	RW
DBB00FN DBB00IN		RW	CLK_CR1		RW				OSC_CR0		RW
DBB000IN	21	RW	ABF_CR0	61	RW		A1 A2		OSC_CR1	E1 E2	RW
DBB00C0	23	KW	AMD_CR0	62	RW					E3	RW
DBB01FN	23	DW	AIVID_CRU	63 64	KVV		A3 A4		VLT_CR VLT_CMP	E4	RW
DBB01FN DBB01IN	25	RW					A4 A5		VLI_CIVIP	E5	ĸ
			AMD OD4	65	DW						
DBB01OU	26	RW	AMD_CR1	66	RW		A6			E6	
DODOGENI	27	DW	ALT_CR0	67	RW		A7		INAC TO	E7	107
DCB02FN	28	RW		68			A8		IMO_TR	E8	W
DCB02IN	29	RW		69			A9		ILO_TR	E9	W
DCB02OU	2A	RW		6A			AA		BDG_TR	EA	RW
	2B			6B			AB		ECO_TR	EB	W
DCB03FN	2C	RW	Į	6C			AC			EC	
DCB03IN	2D	RW		6D			AD			ED	
DCB03OU	2E	RW	<b>!</b>	6E		<b>.</b>	AE			EE	
	2F			6F		I	AF			EF	
	30		ACB00CR3	70	RW	RDI0RI	B0	RW		F0	
	31		ACB00CR0	71	RW	RDI0SYN	B1	RW		F1	
	32		ACB00CR1	72	RW	RDI0IS	B2	RW		F2	
	33		ACB00CR2	73	RW	RDI0LT0	В3	RW		F3	
	34		ACB01CR3	74	RW	RDI0LT1	B4	RW		F4	
	35		ACB01CR0	75	RW	RDI0RO0	B5	RW		F5	
	36		ACB01CR1	76	RW	RDI0RO1	B6	RW		F6	
	37		ACB01CR2	77	RW		B7		CPU_F	F7	RL
	38			78			B8			F8	
	39			79			B9			F9	
	3A		Ī	7A		Ī	BA			FA	
	3B			7B			BB			FB	İ
	3C		1	7C			BC			FC	1
	3D		1	7D		1	BD			FD	
	30										
	3E		1	7E			BE		CPU_SCR1	FE	#

Blank fields are Reserved and must not be accessed.

# Access is bit specific.



# **Absolute Maximum Ratings**

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

**Table 7. Absolute Maximum Ratings** 

Symbol	Description	Min	Тур	Max	Units	Notes
T <sub>STG</sub>	Storage temperature	<del>-</del> 55	25	+100	°C	Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ±25 °C. Time spent in storage at a temperature greater than 65 °C counts toward the Flash <sub>DR</sub> electrical specification in Table 20 on page 26.
Т <sub>ВАКЕТЕМР</sub>	Bake temperature	_	125	See package label	°C	
t <sub>BAKETIME</sub>	Bake time	See package label	-	72	Hours	
T <sub>A</sub>	Ambient temperature with power applied	-40	-	+85	°C	
$V_{DD}$	Supply voltage on V <sub>DD</sub> relative to V <sub>SS</sub>	-0.5	_	+6.0	V	
V <sub>IO</sub>	DC input voltage	$V_{SS} - 0.5$	-	V <sub>DD</sub> + 0.5	V	
V <sub>IOZ</sub>	DC voltage applied to tristate	$V_{SS} - 0.5$	-	V <sub>DD</sub> + 0.5	V	
I <sub>MIO</sub>	Maximum current into any port pin	-25	-	+50	mΑ	
ESD	Electrostatic discharge voltage	2000	_	_	V	Human body model ESD.
LU	Latch up current	_	_	200	mA	

# **Operating Temperature**

**Table 8. Operating Temperature** 

Symbol	Description	Min	Тур	Max	Units	Notes
T <sub>A</sub>	Ambient temperature	-40	-	+85	°C	
TJ	Junction temperature	-40	1	+100	°C	The temperature rise from ambient to junction is package specific. See Table 33 on page 37. The user must limit the power consumption to comply with this requirement.



## DC GPIO Specifications

Table 10 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , 3.0 V to 3.6 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25  $^{\circ}\text{C}$  and are for design guidance only.

Table 10. DC GPIO Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
R <sub>PU</sub>	Pull-up resistor	4	5.6	8	kΩ	
R <sub>PD</sub>	Pull-down resistor	4	5.6	8	kΩ	Also applies to the internal pull-down resistor on the XRES pin.
V <sub>OH</sub>	High output level	V <sub>DD</sub> – 1.0	-	-	V	$I_{OH}$ = 10 mA, $V_{DD}$ = 4.75 to 5.25 V (maximum 40 mA on even port pins (for example, P0[2], P1[4]), maximum 40 mA on odd port pins (for example, P0[3], P1[5])). 80 mA maximum combined $I_{OH}$ budget.
V <sub>OL</sub>	Low output level	-	-	0.75	V	$I_{OL}$ = 25 mA, $V_{DD}$ = 4.75 to 5.25 V (maximum 100 mA on even port pins (for example, P0[2], P1[4]), maximum 100 mA on odd port pins (for example, P0[3], P1[5])). 150 mA maximum combined $I_{OL}$ budget.
I <sub>OH</sub>	High-level source current	10	_	-	mA	$V_{OH} \ge V_{DD} - 1.0$ V, see the limitations of the total current in the note for $V_{OH}$ .
I <sub>OL</sub>	Low-level sink current	25	_	-	mA	$V_{OL} \le 0.75 \text{ V}$ , see the limitations of the total current in the note for $V_{OL}$ .
$V_{IL}$	Input low level	_	-	0.8	V	
V <sub>IH</sub>	Input high level	2.1	_		V	
V <sub>H</sub>	Input hysteresis	_	60	_	mV	
I <sub>IL</sub>	Input leakage (absolute value)	_	1	_	nA	Gross tested to 1 μA.
C <sub>IN</sub>	Capacitive load on pins as input	_	3.5	10	pF	Package and pin dependent. T <sub>A</sub> = 25 °C
C <sub>OUT</sub>	Capacitive load on pins as output	_	3.5	10	pF	Package and pin dependent. T <sub>A</sub> = 25 °C



#### DC Operational Amplifier Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , 3.0 V to 3.6 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25  $^{\circ}\text{C}$  and are for design guidance only.

The operational amplifier is a component of both the analog CT PSoC blocks and the analog SC PSoC blocks. The guaranteed specifications are measured in the analog CT PSoC block.

Table 11. 5-V DC Operational Amplifier Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V <sub>OSOA</sub>	Input offset voltage (absolute value) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	- - -	1.6 1.3 1.2	10 8 7.5	mV mV mV	
TCV <sub>OSOA</sub>	Average input offset voltage drift	_	7.0	35.0	μV/°C	
I <sub>EBOA</sub>	Input leakage current (Port 0 analog pins)	_	20	_	pА	Gross tested to 1 μA.
C <sub>INOA</sub>	Input capacitance (Port 0 analog pins)	_	4.5	9.5	pF	Package and pin dependent. T <sub>A</sub> = 25 °C.
V <sub>CMOA</sub>	Common mode voltage range Common mode voltage range (high power or high opamp bias)	0.0 0.5	-	V <sub>DD</sub> V <sub>DD</sub> – 0.5	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
G <sub>OLOA</sub>	Open loop gain Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	60 60 80	1 1 1	- - -	dB dB dB	Specification is applicable at high power. For all other bias modes (except high power, high opamp bias), minimum is 60 dB.
V <sub>OHIGHOA</sub>	High output voltage swing (internal signals) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	V <sub>DD</sub> - 0.2 V <sub>DD</sub> - 0.2 V <sub>DD</sub> - 0.5	- - -	- - -	V V V	
V <sub>OLOWOA</sub>	Low output voltage swing (internal signals) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	_ _ _	- - -	0.2 0.2 0.5	V V V	
Isoa	Supply current (including associated AGND buffer) Power = low, Opamp bias = high Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high Power = high, Opamp bias = high	- - - - -	150 300 600 1200 2400 4600	200 400 800 1600 3200 6400	μΑ μΑ μΑ μΑ μΑ	
PSRR <sub>OA</sub>	Supply voltage rejection ratio	64	80	-	dB	$V_{SS} \le V_{IN} \le (V_{DD} - 2.25 \text{ V}) \text{ or } (V_{DD} - 1.25 \text{ V}) \le V_{IN} \le V_{DD}.$



Table 12. 3.3-V DC Operational Amplifier Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V <sub>OSOA</sub>	Input offset voltage (absolute value) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	_ _ _	1.65 1.32 -	10 8 -	mV mV mV	Power = high, Opamp bias = high is not allowed.
TCV <sub>OSOA</sub>	Average input offset voltage drift	-	7.0	35.0	μV/°C	
I <sub>EBOA</sub>	Input leakage current (Port 0 analog pins)	_	20	-	pА	Gross tested to 1 μA.
C <sub>INOA</sub>	Input capacitance (Port 0 analog pins)	_	4.5	9.5	pF	Package and pin dependent. T <sub>A</sub> = 25 °C
V <sub>CMOA</sub>	Common mode voltage range	0.2	1	V <sub>DD</sub> – 0.2	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
G <sub>OLOA</sub>	Open loop gain Power = low, Opamp bias = low Power = medium, Opamp bias = low Power = high, Opamp bias = low	60 60 80	1 1 1	_ _ _	dB dB dB	Specification is applicable at high power. For all other bias modes (except high power, high opamp bias), minimum is 60 dB.
V <sub>OHIGHOA</sub>	High output voltage swing (internal signals) Power = low, Opamp bias = low Power = medium, Opamp bias = low Power = high, Opamp bias = low	V <sub>DD</sub> - 0.2 V <sub>DD</sub> - 0.2 V <sub>DD</sub> - 0.2		_ _ _	V V V	
V <sub>OLOWOA</sub>	Low output voltage swing (internal signals) Power = low, Opamp bias = low Power = medium, Opamp bias = low Power = high, Opamp bias = low	_ _ _	1 1 1	0.2 0.2 0.2	V V V	
I <sub>SOA</sub>	Supply current (including associated AGND buffer) Power = low, Opamp bias = low Power = low, Opamp bias = high Power = medium, Opamp bias = low Power = medium, Opamp bias = high Power = high, Opamp bias = low Power = high, Opamp bias = high	- - - -	150 300 600 1200 2400	200 400 800 1600 3200	μΑ μΑ μΑ μΑ μΑ	Power = high, Opamp bias = high is not allowed.
PSRR <sub>OA</sub>	Supply voltage rejection ratio	64	80	_	dB	$V_{SS} \le VIN \le (V_{DD} - 2.25)$ or $(V_{DD} - 1.25 \text{ V}) \le VIN \le V_{DD}$ .

#### DC Low Power Comparator Specifications

Table 13 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le \text{T}_{\text{A}} \le 85~^{\circ}\text{C}$ , 3.0~V to 3.6~V and  $-40~^{\circ}\text{C} \le \text{T}_{\text{A}} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5~V at  $25~^{\circ}\text{C}$  and are for design guidance only.

Table 13. DC Low Power Comparator Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V <sub>REFLPC</sub>	Low power comparator (LPC) reference voltage range	0.2	-	V <sub>DD</sub> – 1	V	
I <sub>SLPC</sub>	LPC supply current	1	10	40	μА	
V <sub>OSLPC</sub>	LPC voltage offset	ı	2.5	30	mV	



## DC Analog Output Buffer Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C  $\leq$  T<sub>A</sub>  $\leq$  85 °C, 3.0 V to 3.6 V and –40 °C  $\leq$  T<sub>A</sub>  $\leq$  85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

Table 14. 5-V DC Analog Output Buffer Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V <sub>OSOB</sub>	Input offset voltage (absolute value)	_	3	12	mV	
TCV <sub>OSOB</sub>	Average input offset voltage drift	_	+6	_	μV/°C	
$V_{CMOB}$	Common mode input voltage range	0.5	_	V <sub>DD</sub> – 1.0	V	
R <sub>OUTOB</sub>	Output resistance Power = low Power = high		1	-	Ω	
V <sub>OHIGHOB</sub>	High output voltage swing (Load = $32 \Omega$ to $V_{DD}/2$ ) Power = low Power = high	0.5 × V <sub>DD</sub> + 1.1 0.5 × V <sub>DD</sub> + 1.1	_ _	- -	V V	
V <sub>OLOWOB</sub>	Low output voltage swing (Load = $32\Omega$ to $V_{DD}/2$ ) Power = low Power = high	_ _	_ _	0.5 × V <sub>DD</sub> – 1.3 0.5 × V <sub>DD</sub> – 1.3	V V	
I <sub>SOB</sub>	Supply current including bias cell (no load) Power = low Power = high	- -	1.1 2.6	5.1 8.8	mA mA	
PSRR <sub>OB</sub>	Supply voltage rejection ratio	52	64	_	dB	$V_{OUT} > (V_{DD} - 1.25).$
C <sub>L</sub>	Load Capacitance	-	1	200	pF	This specification applies to the external circuit that is being driven by the analog output buffer.

Table 15. 3.3-V DC Analog Output Buffer Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V <sub>OSOB</sub>	Input offset voltage (absolute value)	_	3	12	mV	
TCV <sub>OSOB</sub>	Average input offset voltage drift	_	+6	_	μV/°C	
$V_{CMOB}$	Common mode input voltage range	0.5	-	V <sub>DD</sub> – 1.0	V	
R <sub>OUTOB</sub>	Output resistance Power = low Power = high		1 1		Ω	
V <sub>OHIGHOB</sub>	High output voltage swing (Load = 1 k $\Omega$ to V <sub>DD</sub> /2) Power = low Power = high	0.5 × V <sub>DD</sub> + 1.0 0.5 × V <sub>DD</sub> + 1.0	_	_ _	V V	
V <sub>OLOWOB</sub>	Low output voltage swing (Load = 1 k $\Omega$ to V <sub>DD</sub> /2) Power = low Power = high		_ _	0.5 × V <sub>DD</sub> – 1.0 0.5 × V <sub>DD</sub> – 1.0	V V	
I <sub>SOB</sub>	Supply current including bias cell (no load) Power = low Power = high		0.8 2.0	2.0 4.3	mA mA	
PSRR <sub>OB</sub>	Supply voltage rejection ratio	52	64	_	dB	$V_{OUT} > (V_{DD} - 1.25).$
C <sub>L</sub>	Load Capacitance	_	_	200	pF	This specification applies to the external circuit that is being driven by the analog output buffer.



#### DC Analog Reference Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le T_{\text{A}} \le 85~^{\circ}\text{C}$ , 3.0 V to 3.6 V and  $-40~^{\circ}\text{C} \le T_{\text{A}} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25  $^{\circ}\text{C}$  and are for design guidance only.

The guaranteed specifications for RefHI and RefLO are measured through the analog continuous time PSoC blocks. The power levels for RefHI and RefLO refer to the analog reference control register. AGND is measured at P2[4] in AGND bypass mode. Each analog continuous time PSoC block adds a maximum of 10 mV additional offset error to guaranteed AGND specifications from the local AGND buffer. Reference control power can be set to medium or high unless otherwise noted.

**Note** Avoid using P2[4] for digital signaling when using an analog resource that depends on the analog reference. Some coupling of the digital signal may appear on the AGND.

Table 16. 5-V DC Analog Reference Specifications

Reference ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Max	Units
0b000	RefPower = high	V <sub>REFHI</sub>	Ref High	V <sub>DD</sub> /2 + Bandgap	V <sub>DD</sub> /2 + 1.136	V <sub>DD</sub> /2 + 1.288	V <sub>DD</sub> /2 + 1.409	V
	Opamp bias = high	V <sub>AGND</sub>	AGND	V <sub>DD</sub> /2	$V_{DD}/2 - 0.138$	$V_{DD}/2 + 0.003$	$V_{DD}/2 + 0.132$	V
		V <sub>REFLO</sub>	Ref Low	V <sub>DD</sub> /2 – Bandgap	V <sub>DD</sub> /2 – 1.417	V <sub>DD</sub> /2 – 1.289	V <sub>DD</sub> /2 – 1.154	V
	RefPower = high	V <sub>REFHI</sub>	Ref High	V <sub>DD</sub> /2 + Bandgap	V <sub>DD</sub> /2 + 1.202	V <sub>DD</sub> /2 + 1.290	$V_{DD}/2 + 1.358$	V
	Opamp bias = low	V <sub>AGND</sub>	AGND	V <sub>DD</sub> /2	$V_{DD}/2 - 0.055$	$V_{DD}/2 + 0.001$	$V_{DD}/2 + 0.055$	V
		V <sub>REFLO</sub>	Ref Low	V <sub>DD</sub> /2 – Bandgap	V <sub>DD</sub> /2 – 1.369	V <sub>DD</sub> /2 – 1.295	V <sub>DD</sub> /2 – 1.218	V
	RefPower = medium	V <sub>REFHI</sub>	Ref High	V <sub>DD</sub> /2 + Bandgap	V <sub>DD</sub> /2 + 1.211	V <sub>DD</sub> /2 + 1.292	V <sub>DD</sub> /2 + 1.357	V
	Opamp bias = high	V <sub>AGND</sub>	AGND	V <sub>DD</sub> /2	$V_{DD}/2 - 0.055$	V <sub>DD</sub> /2	$V_{DD}/2 + 0.052$	V
		V <sub>REFLO</sub>	Ref Low	V <sub>DD</sub> /2 – Bandgap	V <sub>DD</sub> /2 – 1.368	V <sub>DD</sub> /2 – 1.298	V <sub>DD</sub> /2 – 1.224	V
	RefPower = medium Opamp bias = low	V <sub>REFHI</sub>	Ref High	V <sub>DD</sub> /2 + Bandgap	V <sub>DD</sub> /2 + 1.215	V <sub>DD</sub> /2 + 1.292	$V_{DD}/2 + 1.353$	V
		$V_{AGND}$	AGND	V <sub>DD</sub> /2	$V_{DD}/2 - 0.040$	V <sub>DD</sub> /2 – 0.001	$V_{DD}/2 + 0.033$	V
		V <sub>REFLO</sub>	Ref Low	V <sub>DD</sub> /2 – Bandgap	V <sub>DD</sub> /2 – 1.368	V <sub>DD</sub> /2 – 1.299	V <sub>DD</sub> /2 – 1.225	V
0b001	RefPower = high Opamp bias = high	$V_{REFHI}$	Ref High	P2[4]+P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.076	P2[4]+P2[6]- 0.021	P2[4]+P2[6]+ 0.041	V
		$V_{AGND}$	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V <sub>REFLO</sub>	Ref Low	P2[4]-P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.025	P2[4]-P2[6]+ 0.011	P2[4]-P2[6]+ 0.085	V
	RefPower = high Opamp bias = low	V <sub>REFHI</sub>	Ref High	P2[4]+P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.069	P2[4]+P2[6]- 0.014	P2[4]+P2[6]+ 0.043	V
		V <sub>AGND</sub>	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		$V_{REFLO}$	Ref Low	P2[4]–P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.029	P2[4]-P2[6]+ 0.005	P2[4]-P2[6]+ 0.052	V
	RefPower = medium Opamp bias = high	V <sub>REFHI</sub>	Ref High	P2[4]+P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.072	P2[4] + P2[6] - 0.011	P2[4]+P2[6]+ 0.048	V
		$V_{AGND}$	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		$V_{REFLO}$	Ref Low	P2[4]–P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] - P2[6] - 0.031	P2[4]-P2[6]+ 0.002	P2[4]-P2[6]+ 0.057	V
	RefPower = medium Opamp bias = low	$V_{REFHI}$	Ref High	P2[4]+P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] + P2[6] - 0.070	P2[4] + P2[6] - 0.009	P2[4]+P2[6]+ 0.047	V
		V <sub>AGND</sub>	AGND	P2[4]	P2[4]	P2[4]	P2[4]	_
		$V_{REFLO}$	Ref Low	P2[4]–P2[6] (P2[4] = V <sub>DD</sub> /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.033	P2[4]-P2[6]+ 0.001	P2[4]-P2[6]+ 0.039	V



Figure 7. PLL Lock Timing Diagram

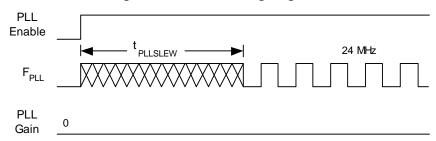


Figure 8. PLL Lock for Low Gain Setting Timing Diagram

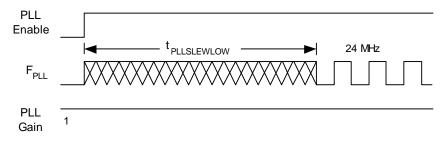
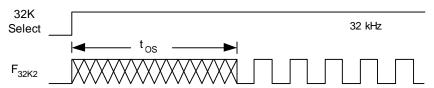


Figure 9. External Crystal Oscillator Startup Timing Diagram





## AC GPIO Specifications

Table 22 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , 3.0 V to 3.6 V and  $-40~^{\circ}\text{C} \le T_{A} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25  $^{\circ}\text{C}$  and are for design guidance only.

Table 22. AC GPIO Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
F <sub>GPIO</sub>	GPIO operating frequency	0	_	12.6 <sup>[16]</sup>	MHz	Normal strong mode
t <sub>RISEF</sub>	Rise time, normal strong mode, Cload = 50 pF	3	_	18	ns	V <sub>DD</sub> = 4.5 to 5.25 V, 10% to 90%
t <sub>FALLF</sub>	Fall time, normal strong mode, Cload = 50 pF	2	_	18	ns	V <sub>DD</sub> = 4.5 to 5.25 V, 10% to 90%
t <sub>RISES</sub>	Rise time, slow strong mode, Cload = 50 pF	10	27	_	ns	V <sub>DD</sub> = 3 to 5.25 V, 10% to 90%
t <sub>FALLS</sub>	Fall time, slow strong mode, Cload = 50 pF	10	22	_	ns	V <sub>DD</sub> = 3 to 5.25 V, 10% to 90%

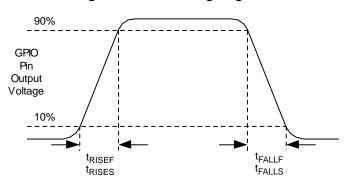


Figure 10. GPIO Timing Diagram

#### Note

16. Accuracy derived from IMO with appropriate trim for  $V_{\mbox{\scriptsize DD}}$  range.



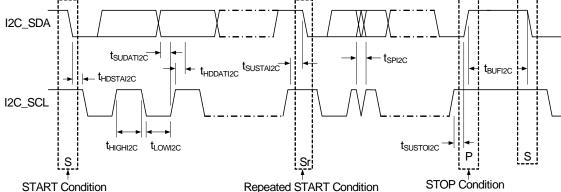
#### AC I<sup>2</sup>C Specifications

Table 32 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and  $-40~^{\circ}\text{C} \le \text{T}_{\text{A}} \le 85~^{\circ}\text{C}$ , 3.0 V to 3.6 V and  $-40~^{\circ}\text{C} \le \text{T}_{\text{A}} \le 85~^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25  $^{\circ}\text{C}$  and are for design guidance only.

Table 32. AC Characteristics of the I<sup>2</sup>C SDA and SCL Pins

Comple of	December	Standa	rd Mode	Fast	11	
Symbol	Description	Min	Max	Min	Max	Units
F <sub>SCLI2C</sub>	SCL clock frequency	0	100 <sup>[22]</sup>	0	400 <sup>[22]</sup>	kHz
t <sub>HDSTAI2C</sub>	Hold time (repeated) START condition. After this period, the first clock pulse is generated.	4.0	_	0.6	_	μS
t <sub>LOWI2C</sub>	LOW period of the SCL clock	4.7	-	1.3	-	μS
t <sub>HIGHI2C</sub>	HIGH period of the SCL clock	4.0	_	0.6	_	μS
t <sub>SUSTAI2C</sub>	Setup time for a repeated START condition	4.7	_	0.6	_	μS
t <sub>HDDATI2C</sub>	Data hold time		_	0	-	μS
t <sub>SUDATI2C</sub>	Data setup time	250	_	100 <sup>[23]</sup>	_	ns
t <sub>SUSTOI2C</sub>	Setup time for STOP condition	4.0	_	0.6	_	μS
t <sub>BUFI2C</sub>	Bus free time between a STOP and START condition	4.7	_	1.3	_	μS
t <sub>SPI2C</sub>	Pulse width of spikes are suppressed by the input filter.	_	-	0	50	ns

Figure 13. Definition for Timing for Fast/Standard Mode on the I<sup>2</sup>C Bus



<sup>22.</sup> F<sub>SCLI2C</sub> is derived from SysClk of the PSoC. This specification assumes that SysClk is operating at 24 MHz, nominal. If SysClk is at a lower frequency, then the F<sub>SCLI2C</sub> specification adjusts accordingly.

23. A Fast-Mode I2C-bus device can be used in a Standard-Mode I2C-bus system, but the requirement t<sub>SUDATI2C</sub> ≥ 250 ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line t<sub>rmax</sub> + t<sub>SUDATI2C</sub> = 1000 + 250 = 1250 ns (according to the Standard-Mode I2C-bus specification) before the SCL line is released.



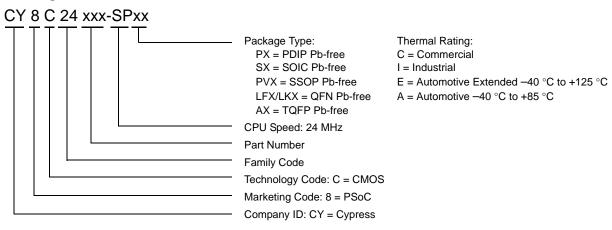
# **Ordering Information**

The following table lists the automotive CY8C24x23A PSoC device group's key package features and ordering codes.

Table 38. CY8C24x23A Automotive PSoC Device Key Features and Ordering Information

Package	Ordering Code	Flash (Bytes)	SRAM (Bytes)	Temperature Range	Digital Blocks	Analog Blocks	Digital I/O Pins	Analog Inputs	Analog Outputs	XRES Pin
20-Pin (210-Mil) SSOP	CY8C24223A-24PVXA	4 K	256	–40 °C to +85 °C	4	6	16	8	2	Yes
20-Pin (210-Mil) SSOP (Tape and Reel)	CY8C24223A-24PVXAT	4 K	256	–40 °C to +85 °C	4	6	16	8	2	Yes
28-Pin (210-Mil) SSOP	CY8C24423A-24PVXA	4 K	256	–40 °C to +85 °C	4	6	24	12 <sup>[1]</sup>	2	Yes
28-Pin (210-Mil) SSOP (Tape and Reel)	CY8C24423A-24PVXAT	4 K	256	–40 °C to +85 °C	4	6	24	12 <sup>[1]</sup>	2	Yes

# **Ordering Code Definitions**





#### Glossary (continued)

bias

- 1. A systematic deviation of a value from a reference value.
- 2. The amount by which the average of a set of values departs from a reference value.
- 3. The electrical, mechanical, magnetic, or other force (field) applied to a device to establish a reference level to operate the device.

block

- 1. A functional unit that performs a single function, such as an oscillator.
- A functional unit that may be configured to perform one of several functions, such as a digital PSoC block or an analog PSoC block.

buffer

- 1. A storage area for data that is used to compensate for a speed difference, when transferring data from one device to another. Usually refers to an area reserved for I/O operations, into which data is read, or from which data is written.
- A portion of memory set aside to store data, often before it is sent to an external device or as it is received from an external device.
- 3. An amplifier used to lower the output impedance of a system.

bus

- 1. A named connection of nets. Bundling nets together in a bus makes it easier to route nets with similar routing patterns.
- 2. A set of signals performing a common function and carrying similar data. Typically represented using vector notation; for example, address[7:0].
- 3. One or more conductors that serve as a common connection for a group of related devices.

clock

The device that generates a periodic signal with a fixed frequency and duty cycle. A clock is sometimes used to synchronize different logic blocks.

comparator

An electronic circuit that produces an output voltage or current whenever two input levels simultaneously satisfy predetermined amplitude requirements.

compiler

A program that translates a high level language, such as C, into machine language.

configuration space

In PSoC devices, the register space accessed when the XIO bit, in the CPU\_F register, is set to '1'

crystal oscillator

An oscillator in which the frequency is controlled by a piezoelectric crystal. Typically a piezoelectric crystal is less sensitive to ambient temperature than other circuit components.

cyclic redundancy check (CRC)

A calculation used to detect errors in data communications, typically performed using a linear feedback shift register. Similar calculations may be used for a variety of other purposes such as data compression.

data bus

A bi-directional set of signals used by a computer to convey information from a memory location to the central processing unit and vice versa. More generally, a set of signals used to convey data between digital functions.

debugger

A hardware and software system that allows you to analyze the operation of the system under development. A debugger usually allows the developer to step through the firmware one step at a time, set break points, and

analyze memory.

dead band

A period of time when neither of two or more signals are in their active state or in transition.

digital blocks

The 8-bit logic blocks that can act as a counter, timer, serial receiver, serial transmitter, CRC generator, pseudo-random number generator, or SPI.

digital-to-analog converter (DAC)

A device that changes a digital signal to an analog signal of corresponding magnitude. The analog-to-digital converter (ADC) performs the reverse operation.

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#### Glossary (continued)

duty cycle The relationship of a clock period high time to its low time, expressed as a percent.

emulator Duplicates (provides an emulation of) the functions of one system with a different system, so that the second

system appears to behave like the first system.

external reset

(XRES)

An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.

An electrically programmable and erasable, non-volatile technology that provides you the programmability and flash

data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power is

off.

flash block The smallest amount of flash ROM space that may be programmed at one time and the smallest amount of flash

space that may be protected.

frequency The number of cycles or events per unit of time, for a periodic function.

The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually gain

expressed in dB.

I<sup>2</sup>C A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). It is used to connect

> low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I2C uses only two bi-directional pins, clock and data, both running at the  $V_{DD}$  supply voltage and pulled high with resistors.

The bus operates up to 100 kbits/second in standard mode and 400 kbits/second in fast mode.

**ICE** The in-circuit emulator that allows you to test the project in a hardware environment, while viewing the debugging

device activity in a software environment (PSoC Designer).

input/output (I/O) A device that introduces data into or extracts data from a system.

A suspension of a process, such as the execution of a computer program, caused by an event external to that interrupt

process, and performed in such a way that the process can be resumed.

interrupt service routine (ISR)

A block of code that normal code execution is diverted to when the CPU receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.

iitter 1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams.

> 2. The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.

low voltage detect A circuit that senses VDD and provides an interrupt to the system when VDD falls below a selected threshold. (LVD)

M8C An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by

interfacing to the flash, SRAM, and register space.

A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in master device

width, the master device is the one that controls the timing for data exchanges between the cascaded devices

and an external interface. The controlled device is called the slave device.



#### Glossary (continued)

shift register A memory storage device that sequentially shifts a word either left or right to output a stream of serial data.

slave device A device that allows another device to control the timing for data exchanges between two devices. Or when

devices are cascaded in width, the slave device is the one that allows another device to control the timing of data exchanges between the cascaded devices and an external interface. The controlling device is called the master

device.

SRAM An acronym for static random access memory. A memory device where you can store and retrieve data at a high

rate of speed. The term static is used because, after a value is loaded into an SRAM cell, it remains unchanged

until it is explicitly altered or until power is removed from the device.

SROM An acronym for supervisory read only memory. The SROM holds code that is used to boot the device, calibrate

circuitry, and perform flash operations. The functions of the SROM may be accessed in normal user code,

operating from flash.

stop bit A signal following a character or block that prepares the receiving device to receive the next character or block.

synchronous 1. A signal whose data is not acknowledged or acted upon until the next active edge of a clock signal.

2. A system whose operation is synchronized by a clock signal.

tri-state A function whose output can adopt three states: 0, 1, and Z (high-impedance). The function does not drive any

value in the Z state and, in many respects, may be considered to be disconnected from the rest of the circuit,

allowing another output to drive the same net.

UART A UART or universal asynchronous receiver-transmitter translates between parallel bits of data and serial bits.

user modules Pre-built, pre-tested hardware/firmware peripheral functions that take care of managing and configuring the lower

level analog and digital PSoC blocks. User modules also provide high level API (Application Programming

Interface) for the peripheral function.

user space The bank 0 space of the register map. The registers in this bank are more likely to be modified during normal

program execution and not just during initialization. Registers in bank 1 are most likely to be modified only during

the initialization phase of the program.

 $V_{DD}$  A name for a power net meaning "voltage drain". The most positive power supply signal. Usually 5 V or 3.3 V.

V<sub>SS</sub> A name for a power net meaning "voltage source." The most negative power supply signal.

watchdog timer A timer that must be serviced periodically. If it is not serviced, the CPU resets after a specified period of time.



Documen Documen	Document Title: CY8C24223A, CY8C24423A Automotive PSoC® Programmable System-on-Chip Document Number: 001-52469								
Revision	ECN	Orig. of Change	Submission Date	Description of Change					
*	4691432	KUK	03/18/2015	Updated Electrical Specifications: Updated DC Electrical Characteristics: Updated DC Analog Reference Specifications: Updated description. Updated Packaging Information: Updated Packaging Dimensions: spec 51-85077 – Changed revision from *E to *F. spec 51-85079 – Changed revision from *E to *F. Updated Tape and Reel Information: spec 51-51100 – Changed revision from *C to *D. Updated to new template. Completing Sunset Review.					



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