

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XFI

Product Status	Active
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	40
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 4x14b; D/A 4x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c27543-24axit

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



More Information

Cypress provides a wealth of data at www.cypress.com to help you to select the right PSoC device for your design, and to help you to quickly and effectively integrate the device into your design. For a comprehensive list of resources, see the knowledge base article "How to Design with PSoC[®] 1, PowerPSoC[®], and PLC – KBA88292". Following is an abbreviated list for PSoC 1:

- Overview: PSoC Portfolio, PSoC Roadmap
- Product Selectors: PSoC 1, PSoC 3, PSoC 4, PSoC 5LP
- In addition, PSoC Designer includes a device selection tool.
- Application notes: Cypress offers a large number of PSoC application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with PSoC 1 are:
 - □ Getting Started with PSoC[®] 1 AN75320
 - □ PSoC[®] 1 Getting Started with GPIO AN2094
 - □ PSoC[®] 1 Analog Structure and Configuration AN74170
 - □ PSoC[®] 1 Switched Capacitor Analog Blocks AN2041
 - Selecting Analog Ground and Reference AN2219

Note: For CY8C27X43 devices related Application note please click here.

- Development Kits:
 - CY3210-PSoCEval1 supports all PSoC 1 Mixed-Signal Array families, including automotive, except CY8C25/26xxx devices. The kit includes an LCD module, potentiometer, LEDs, and breadboarding space.
 - CY3214-PSoCEvalUSB features a development board for the CY8C24x94 PSoC device. Special features of the board include USB and CapSense development and debugging support.

Note: For CY8C27X43 devices related Development Kits please click here.

The MiniProg1 and MiniProg3 devices provide interfaces for flash programming and debug.

PSoC Designer

PSoC Designer is a free Windows-based Integrated Design Environment (IDE). Develop your applications using a library of pre-characterized analog and digital peripherals in a drag-and-drop design environment. Then, customize your design leveraging the dynamically generated API libraries of code. Figure 1 shows PSoC Designer windows. **Note:** This is not the default view.

- 1. Global Resources all device hardware settings.
- 2. **Parameters –** the parameters of the currently selected User Modules.
- 3. Pinout information related to device pins.
- 4. Chip-Level Editor a diagram of the resources available on the selected chip.
- 5. Datasheet the datasheet for the currently selected UM
- 6. User Modules all available User Modules for the selected device.
- 7. **Device Resource Meter –** device resource usage for the current project configuration.
- 8. Workspace a tree level diagram of files associated with the project.
- 9. Output output from project build and debug operations.

Note: For detailed information on PSoC Designer, go to PSoC[®] Designer > Help > Documentation > Designer Specific Documents > IDE User Guide.

Figure 1. PSoC Designer Layout





The digital blocks can be connected to any GPIO through a series of global buses that can route any signal to any pin. The buses also enable signal multiplexing and for performing logic operations. This configurability frees your designs from the constraints of a fixed peripheral controller.

Digital blocks are provided in rows of four, where the number of blocks varies by PSoC device family. This lets you the optimum choice of system resources for your application. Family resources are shown in the table titled PSoC Device Characteristics on page 6.

Analog System

The analog system is composed of 12 configurable blocks, each comprised of an opamp circuit allowing the creation of complex analog signal flows. Analog peripherals are very flexible and can be customized to support specific application requirements. Some of the more common PSoC analog functions (most available as user modules) are as follows:

- ADCs (up to 4, with 6- to 14-bit resolution, selectable as incremental, delta sigma, and SAR)
- Filters (2, 4, 6, and 8 pole band pass, low pass, and notch)
- Amplifiers (up to four, with selectable gain to 48x)
- Instrumentation amplifiers (up to two, with selectable gain to 93x)
- Comparators (up to four, with 16 selectable thresholds)
- DACs (up to four, with 6- to 9-bit resolution)
- Multiplying DACs (up to four, with 6- to 9-bit resolution)
- High current output drivers (four with 30 mA drive as a core resource)
- 1.3-V reference (as a system resource)
- DTMF dialer
- Modulators
- Correlators
- Peak detectors
- Many other topologies possible

Analog blocks are provided in columns of three, which includes one continuous time (CT) and two switched capacitor (SC) blocks, as shown in the following figure.

Figure 3. Analog System Block Diagram





Additional System Resources

System resources, some of which have been previously listed, provide additional capability useful to complete systems. Additional resources include a multiplier, decimator, switch mode pump, low voltage detection, and power on reset.

- Digital clock dividers provide three customizable clock frequencies for use in applications. The clocks can be routed to both the digital and analog systems. Additional clocks can be generated using digital PSoC blocks as clock dividers.
- Multiply accumulate (MAC) provides fast 8-bit multiplier with 32-bit accumulate, to assist in general math and digital filters.
- The decimator provides a custom hardware filter for digital signal processing applications including the creation of Delta Sigma ADCs.

- The I²C module provides 100 and 400 kHz communication over two wires. Slave, master, and multi-master modes are all supported.
- LVD interrupts can signal the application of falling voltage levels, while the advanced power-on reset (POR) circuit eliminates the need for a system supervisor.
- An internal 1.3-V reference provides an absolute reference for the analog system, including ADCs and DACs.
- An integrated switch mode pump (SMP) generates normal operating voltages from a single 1.2-V battery cell, providing a low cost boost converter.

PSoC Device Characteristics

Depending on your PSoC device characteristics, the digital and analog systems can have 16, 8, or 4 digital blocks and 12, 6, or 4 analog blocks. The following table lists the resources available for specific PSoC device groups. The PSoC device covered by this datasheet is highlighted in Table 1.

PSoC Part Number	Digital I/O	Digital Rows	Digital Blocks	Analog Inputs	Analog Outputs	Analog Columns	Analog Blocks	SRAM Size	Flash Size
CY8C29x66	up to 64	4	16	up to 12	4	4	12	2 K	32 K
CY8C28xxx	up to 44	up to 3	up to 12	up to 44	up to 4	up to 6	up to 12 + 4 ^[4]	1 K	16 K
CY8C27x43	up to 44	2	8	up to 12	4	4	12	256	16 K
CY8C24x94	up to 56	1	4	up to 48	2	2	6	1 K	16 K
CY8C24x23A	up to 24	1	4	up to 12	2	2	6	256	4 K
CY8C23x33	up to 26	1	4	up to 12	2	2	4	256	8 K
CY8C22x45	up to 38	2	8	up to 38	0	4	6 ^[4]	1 K	16 K
CY8C21x45	up to 24	1	4	up to 24	0	4	6 ^[4]	512	8 K
CY8C21x34	up to 28	1	4	up to 28	0	2	4 ^[4]	512	8 K
CY8C21x23	up to 16	1	4	up to 8	0	2	4 ^[4]	256	4 K
CY8C20x34	up to 28	0	0	up to 28	0	0	3 ^[4, 5]	512	8 K
CY8C20xx6	up to 36	0	0	up to 36	0	0	3 ^[4, 5]	up to 2 K	up to 32 K

Table 1. PSoC Device Characteristics

4. Limited analog functionality.

5. Two analog blocks and one $CapSense^{\mathbb{R}}$.



Pinouts

The CY8C27x43 PSoC device is available in a variety of packages which are listed and illustrated in the following tables. Every port pin (labeled with a "P") is capable of Digital I/O. However, Vss, V_{DD} , SMP, and XRES are not capable of Digital I/O.

8-pin Part Pinout

Table 2. Pin Definitions – 8-pin PDIP

Pin	Ту	pe	Pin	Description				
No.	Digital	Analog	Name	Description				
1	I/O	I/O	P0[5]	Analog column mux input and column output				
2	I/O	I/O	P0[3]	Analog column mux input and column output				
3	I/O		P1[1]	Crystal Input (XTALin), I ² C serial clock (SCL), ISSP-SCLK ^[6]				
4	Po	wer	Vss	Ground connection.				
5	I/O		P1[0]	Crystal output (XTALout), I ² C serial data (SDA), ISSP-SDATA ^[6]				
6	I/O	I/O	P0[2]	Analog column mux input and column output				
7	I/O	I/O	P0[4]	Analog column mux input and column output				
8	Po	wer	V _{DD}	Supply voltage				
			nout and					

Figure 4. CY8C27143 8-pin PSoC Device



END: A = Analog, I = Input, and O = Output.

20-pin Part Pinout

Table 3. Pin Definitions – 20-pin SSOP, SOIC

Pin	Ту	Туре		Description				
No.	Digital	Analog	Name	Description				
1	I/O	I	P0[7]	Analog column mux input				
2	I/O	I/O	P0[5]	Analog column mux input and column output				
3	I/O	I/O	P0[3]	Analog column mux input and column output				
4	I/O	I	P0[1]	Analog column mux input				
5	Po	wer	SMP	Switch Mode Pump (SMP) connection to external components required				
6	I/O		P1[7]	I ² C Serial Clock (SCL)				
7	I/O		P1[5]	I ² C Serial Data (SDA)				
8	I/O		P1[3]					
9	I/O		P1[1]	Crystal input (XTALin), I ² C SCL, ISSP-SCLK ^[6]				
10	Power		Vss	Ground connection.				
11	I/O		P1[0]	Crystal output (XTALout), I ² C SDA, ISSP-SDATA ^[6]				
12	I/O		P1[2]					
13	I/O		P1[4]	Optional external clock input (EXTCLK)				
14	I/O		P1[6]					
15	In	put	XRES	Active high external reset with internal pull down				
16	I/O	I	P0[0]	Analog column mux input				
17	I/O	I/O	P0[2]	Analog column mux input and column output				
18	I/O	I/O	P0[4]	Analog column mux input and column output				
19	I/O	I	P0[6]	Analog column mux input				
20	Po	wer	V_{DD}	Supply voltage				

Figure 5. CY8C27243 20-pin PSoC Device

A, I, P0[7] A, IO, P0[5] A, IO, P0[3] A, I, P0[1] SMP I2CSCL, P1[7] I2CSDA, P1[5] P1[3] I2CSCL, XTALIn, P1[1] Vss	1 2 3 4 5 6 7 8 9	20 19 18 SSOP 16 SOIC 15 14 13 12	V _{DD} P0[6], A, I P0[4], A, IO P0[2], A, IO P0[0], A, I XRES P1[6] P1[4], EXTCLK P1[2] P1[0] XTAL out 125D2
SMP= SMP= I2CSCL, P1[7]= I2CSDA, P1[5]= P1[3]= I2CSCL, XTALin, P1[1] = Vss=	4 5 6 7 8 9 10	SSOP 16 SOIC 15 14 13 12 11	P0[0], A, I XRES P1[6] P1[4], EXTCLK P1[2] P1[0], XTALout, I

LEGEND: A = Analog, I = Input, and O = Output.

Note

6. These are the ISSP pins, which are not High Z at POR (Power On Reset). See the PSoC Programmable System-on-Chip Technical Reference Manual for details.



Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8C27x43 PSoC device. For the most up to date electrical specifications, confirm that you have the most recent datasheet by going to the web at http://www.cypress.com.

Specifications are valid for –40 °C \leq T_A \leq 85 °C and T_J \leq 100 °C, except where noted. Specifications for devices running at greater than 12 MHz are valid for –40 °C \leq T_A \leq 70 °C and T_J \leq 82 °C.



Figure 11. Voltage versus CPU Frequency

Absolute Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

Table 12. Absolute Maximum Ratings

Symbol	Description	Min	Тур	Max	Unit	Notes
T _{STG}	Storage temperature	-55	25	+100	°C	Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 65 °C degrade reliability.
T _{BAKETEMP}	Bake temperature	-	125	See package label	°C	
^t вакетіме	Bake time	See package label	_	72	Hours	
T _A	Ambient temperature with power applied	-40	-	+85	°C	
V _{DD}	Supply voltage on V _{DD} relative to Vss	-0.5	-	+6.0	V	
V _{IO}	DC input voltage	Vss – 0.5	-	V _{DD} + 0.5	V	
V _{IOZ}	DC voltage applied to tristate	Vss – 0.5	-	V _{DD} + 0.5	V	
I _{MIO}	Maximum current into any port pin	-25	-	+50	mA	
I _{MAIO}	Maximum current into any port pin configured as analog driver	-50	-	+50	mA	
ESD	Electrostatic discharge voltage	2000	-	-	V	Human body model ESD.
LU	Latch-up current	-	-	200	mA	



Table 16. 5-V DC Operational Amplifier Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
CMRR _{OA}	Common mode rejection ratio Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	60 60 60	_ _ _		dB dB dB	Specification is applicable at both High and Low opamp bias.
G _{OLOA}	Open loop gain Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	60 60 80	- - -		dB dB dB	Specification is applicable at High opamp bias. For Low opamp bias mode, minimum is 60 dB.
V _{OHIGHOA}	High output voltage swing (internal signals) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	$V_{DD} - 0.2$ $V_{DD} - 0.2$ $V_{DD} - 0.5$			V V V	
V _{OLOWOA}	Low output voltage swing (internal signals) Power = low, Opamp bias = high Power = medium, Opamp bias = high Power = high, Opamp bias = high	- - -	_ _ _	0.2 0.2 0.5	V V V	
Isoa	Supply current (including associated AGND buffer) Power = low, Opamp bias = low Power = low, Opamp bias = high Power = medium, Opamp bias = low Power = medium, Opamp bias = high Power = high, Opamp bias = low Power = high, Opamp bias = high	- - - - -	150 300 600 1200 2400 4600	200 400 800 1600 3200 6400	μΑ μΑ μΑ μΑ μΑ	
PSRR _{OA}	Supply voltage rejection ratio	60	-	_	dB	$Vss \leq V_{IN} \leq (V_{DD} - 2.25) \text{ or } (V_{DD} - 1.25 \text{ V}) \leq V_{IN} \leq V_{DD}.$

Table 17. 3.3-V DC Operational Amplifier Specifications

Symbol	Description	Min	Тур	Max	Unit	Notes
V _{OSOA}	Input offset voltage (absolute value) Power = low, Opamp bias = low Power = low, Opamp bias = high Power = medium, Opamp bias = low Power = medium, Opamp bias = high Power = high, Opamp bias = low Power = high, Opamp bias = high	- - - - -	1.4 1.4 1.4 1.4 1.4 -	10 10 10 10 10 	mV mV mV mV mV mV	Power = high, Opamp bias = high setting is not allowed for 3.3 V V _{DD} operation.
TCV _{OSOA}	Average input offset voltage drift	_	7	40	µV/°C	
I _{EBOA}	Input leakage current (port 0 analog pins)	_	20	_	pА	Gross tested to 1µA.
C _{INOA}	Input capacitance (port 0 analog pins)	-	4.5	9.5	pF	Package and pin dependent. Temp = 25 °C.
V _{CMOA}	Common mode voltage range	0.2	-	V _{DD} – 0.2	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
CMRR _{OA}	Common mode rejection ratio Power = low, Opamp bias = low Power = medium, Opamp bias = low Power = high, Opamp bias = low	50 50 50	_ _ _		dB dB dB	Specification is applicable at Low opamp bias. For High bias mode (except High Power, High opamp bias), minimum is 60 dB.
G _{OLOA}	Open loop gain Power = low, Opamp bias = low Power = medium, Opamp bias = low Power = high, Opamp bias = low	60 60 80	_ _ _		dB dB dB	Specification is applicable at Low opamp bias. For High opamp bias mode (except High Power, High opamp bias), minimum is 60 dB.



Table 22. 5-V DC Analog Reference Specifications (continued)

Reference ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Мах	Unit
	RefPower = high Opamp bias = high	V _{REFHI}	Ref High	P2[4] + P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] – 0.085	P2[4] + P2[6] – 0.016	P2[4] + P2[6] + 0.044	V
		V _{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4] – P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.022	P2[4] – P2[6] + 0.010	P2[4] – P2[6] + 0.055	V
	RefPower = high Opamp bias = low	V _{REFHI}	Ref High	P2[4] + P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] – 0.077	P2[4] + P2[6] – 0.010	P2[4] + P2[6] + 0.051	V
06001		V _{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4] – P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.022	P2[4] – P2[6] + 0.005	P2[4] – P2[6] + 0.039	V
	RefPower = medium Opamp bias = high	V _{REFHI}	Ref High	P2[4] + P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] – 0.070	P2[4] + P2[6] – 0.010	P2[4] + P2[6] + 0.050	V
		V _{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4] – P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.022	P2[4] – P2[6] + 0.005	P2[4] – P2[6] + 0.039	V
	RefPower = medium Opamp bias = low	V _{REFHI}	Ref High	P2[4] + P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] + P2[6] – 0.070	P2[4] + P2[6] – 0.007	P2[4] + P2[6] + 0.054	V
		V _{AGND}	AGND	P2[4]	P2[4]	P2[4]	P2[4]	-
		V _{REFLO}	Ref Low	P2[4] – P2[6] (P2[4] = V _{DD} /2, P2[6] = 1.3 V)	P2[4] – P2[6] – 0.022	P2[4] – P2[6] + 0.002	P2[4] – P2[6] + 0.032	V
	RefPower = high	V _{REFHI}	Ref High	V _{DD}	V _{DD} – 0.037	V _{DD} – 0.009	V _{DD}	V
	Opamp blas = high	V _{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.061	$V_{DD}/2 - 0.006$	$V_{DD}/2 + 0.047$	V
		V _{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.007	V _{SS} + 0.028	V
	RefPower = high	V _{REFHI}	Ref High	V _{DD}	V _{DD} – 0.039	V _{DD} – 0.006	V _{DD}	V
	Opamp bias = low	V _{AGND}	AGND	V _{DD} /2	$V_{DD}/2 - 0.049$	$V_{DD}/2 - 0.005$	$V_{DD}/2 + 0.036$	V
06010		V _{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.005	V _{SS} + 0.019	V
00010	RefPower = medium	V _{REFHI}	Ref High	V _{DD}	V _{DD} – 0.037	V _{DD} – 0.007	V _{DD}	V
	Opamp bias = nigh	V _{AGND}	AGND	V _{DD} /2	V _{DD} /2 - 0.054	V _{DD} /2 - 0.005	$V_{DD}/2 + 0.041$	V
		V _{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.006	V _{SS} + 0.024	V
	RefPower = medium	V _{REFHI}	Ref High	V _{DD}	V _{DD} – 0.042	V _{DD} – 0.005	V _{DD}	V
		V _{AGND}	AGND	V _{DD} /2	V _{DD} /2 – 0.046	V _{DD} /2 - 0.004	$V_{DD}/2 + 0.034$	V
		V _{REFLO}	Ref Low	V _{SS}	V _{SS}	V _{SS} + 0.004	V _{SS} + 0.017	V



Table 22. 5-V DC Analog Reference Specifications (continued)

Reference ARF_CR [5:3]	Reference Power Settings	Symbol	Reference	Description	Min	Тур	Мах	Unit
	RefPower = high	V _{REFHI}	Ref High	3 × Bandgap	3.788	3.891	3.986	V
	Opamp bias = high	V _{AGND}	AGND	2 × Bandgap	2.500	2.604	3.699	V
		V _{REFLO}	Ref Low	Bandgap	1.257	1.306	1.359	V
	RefPower = high	V _{REFHI}	Ref High	3 × Bandgap	3.792	3.893	3.982	V
	Opamp blas = low	V _{AGND}	AGND	2 × Bandgap	2.518	2.602	2.692	V
06011		V _{REFLO}	Ref Low	Bandgap	1.256	1.302	1.354	V
00011	RefPower = medium	V _{REFHI}	Ref High	3 × Bandgap	3.795	3.894	3.993	V
	Opamp bias = high	V _{AGND}	AGND	2 × Bandgap	2.516	2.603	2.698	V
		V _{REFLO}	Ref Low	Bandgap	1.256	1.303	1.353	V
	RefPower = medium Opamp bias = low	V _{REFHI}	Ref High	3 × Bandgap	3.792	3.895	3.986	V
		V _{AGND}	AGND	2 × Bandgap	2.522	2.602	2.685	V
		V _{REFLO}	Ref Low	Bandgap	1.255	1.301	1.350	V
	RefPower = high Opamp bias = high	V _{REFHI}	Ref High	2 × Bandgap + P2[6] (P2[6] = 1.3 V)	2.495 – P2[6]	2.586 – P2[6]	2.657 – P2[6]	V
		V _{AGND}	AGND	2 × Bandgap	2.502	2.604	2.719	V
		V _{REFLO}	Ref Low	2 × Bandgap – P2[6] (P2[6] = 1.3 V)	2.531 – P2[6]	2.611 – P2[6]	2.681 – P2[6]	V
	RefPower = high Opamp bias = low	V _{REFHI}	Ref High	2 × Bandgap + P2[6] (P2[6] = 1.3 V)	2.500 – P2[6]	2.591 – P2[6]	2.662 – P2[6]	V
		V _{AGND}	AGND	2 × Bandgap	2.519	2.602	2.693	V
05100		V _{REFLO}	Ref Low	2 × Bandgap – P2[6] (P2[6] = 1.3 V)	2.530 – P2[6]	2.605 – P2[6]	2.666 – P2[6]	V
00100	RefPower = medium Opamp bias = high	V _{REFHI}	Ref High	2 × Bandgap + P2[6] (P2[6] = 1.3 V)	2.503 – P2[6]	2.592 – P2[6]	2.662 – P2[6]	V
		V _{AGND}	AGND	2 × Bandgap	2.517	2.603	2.698	V
		V _{REFLO}	Ref Low	2 × Bandgap – P2[6] (P2[6] = 1.3 V)	2.529 – P2[6]	2.606 – P2[6]	2.665 – P2[6]	V
	RefPower = medium Opamp bias = low	V _{REFHI}	Ref High	2 × Bandgap + P2[6] (P2[6] = 1.3 V)	2.505 – P2[6]	2.594 – P2[6]	2.665 – P2[6]	V
		V _{AGND}	AGND	2 × Bandgap	2.525	2.602	2.685	V
		V _{REFLO}	Ref Low	2 × Bandgap – P2[6] (P2[6] = 1.3 V)	2.528 – P2[6]	2.603 – P2[6]	2.661 – P2[6]	V



DC Programming Specifications

Table 26 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and -40 °C \leq T_A \leq 85 °C, or 3.0 V to 3.6 V and -40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

Table 26. DC Programming Specifications

Symbol	Description	Min	Тур	Max	Unit	Notes
V _{DDP}	V _{DD} for programming and erase	4.5	5	5.5	V	This specification applies to the functional requirements of external programmer tools.
V _{DDLV}	Low V _{DD} for verify	3	3.1	3.2	V	This specification applies to the functional requirements of external programmer tools.
V _{DDHV}	High V _{DD} for verify	5.1	5.2	5.3	V	This specification applies to the functional requirements of external programmer tools.
V _{DDIWRITE}	Supply voltage for flash write operation	3		5.25	V	This specification applies to this device when it is executing internal flash writes.
I _{DDP}	Supply current during programming or verify	-	5	25	mA	
V _{ILP}	Input low voltage during programming or verify	-	-	0.8	V	
V _{IHP}	Input high voltage during programming or verify	2.2	-	-	V	
I _{ILP}	Input current when applying V_{ILP} to P1[0] or P1[1] during programming or verify	-	-	0.2	mA	Driving internal pull-down resistor.
I _{IHP}	Input current when applying V_{IHP} to P1[0] or P1[1] during programming or verify	-	-	1.5	mA	Driving internal pull-down resistor.
V _{OLV}	Output low voltage during programming or verify	-	-	Vss + 0.75	V	
V _{OHV}	Output high voltage during programming or verify	V _{DD} – 1.0	-	V _{DD}	V	
Flash _{ENPB}	Flash endurance (per block)	50,000 ^[19]	-	-	Cycles	Erase/write cycles per block.
Flash _{ENT}	Flash endurance (total) ^[20]	1,800,000	-	-	Cycles	Erase/write cycles.
Flash _{DR}	Flash data retention	10	_	-	Years	

DC I²C Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and -40 °C \leq T_A \leq 85 °C, or 3.0 V to 3.6 V and -40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

Table 27. DC I²C Specifications

Parameter	Description	Min	Тур	Max	Units	Notes
V _{ILI2C} ^[21]	Input low level	-	-	0.3 × V _{DD}	V	$3.0~V \leq V_{DD} \leq 3.6~V$
		-	-	0.25 × V _{DD}	V	$4.75~V \leq V_{DD} \leq 5.25~V$
V _{IHI2C} ^[21]	Input high level	$0.7 \times V_{DD}$	-	-	V	$3.0~V \leq V_{DD} \leq 5.25~V$

Notes

^{19.} The 50,000 cycle flash endurance per block is only guaranteed if the flash is operating within one voltage range. Voltage ranges are 3.0 V to 3.6 V and 4.75 V to 5.25 V. 19: The 50,000 cycle hash endurance per block is only guaranteed in the hash is operating within one voltage range. Voltage ranges are 3.0 v to 3.6 v and 4.7 v to 5.25 v.
 20: A maximum of 36 x 50,000 block endurance cycles is allowed. This may be balanced between operations on 36x1 blocks of 50,000 maximum cycles each, 36 x 2 blocks of 25,000 maximum cycles each, or 36 x 4 blocks of 12,500 maximum cycles each (to limit the total number of cycles to 36 x 50,000 and that no single block ever sees more than 50,000 cycles).
 For the full industrial range, you must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs application note Design Aids – Reading and Writing PSoC[®] Flash – AN2015 for more information.
 21. All GPIOs meet the DC GPIO V_{IL} and V_{IH} specifications found in the DC GPIO specifications sections. The I²C GPIO pins also meet the above specs.



At low frequencies, the opamp noise is proportional to 1/f, power independent, and determined by device geometry. At high frequencies, increased power level reduces the noise spectrum level.



Figure 18. Typical Opamp Noise

AC Low-Power Comparator Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C \leq T_A \leq 85 °C, 3.0 V to 3.6 V and –40 °C \leq T_A \leq 85 °C, or 2.4 V to 3.0 V and –40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V at 25 °C and are for design guidance only.

Table 32. AC Low-Power Comparator Specifications

Symbol	Description	Min	Тур	Max	Unit	Notes
t _{RLPC}	LPC response time	Ι	-	50	μs	\geq 50 mV overdrive comparator reference set within V _{REFLPC} .



AC Digital Block Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C \leq T_A \leq 85 °C, or 3.0 V to 3.6 V and –40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

 Table 33. AC Digital Block Specifications

Function	Description	Min	Тур	Max	Unit	Notes
All functions	Block input clock frequency					
	$V_{DD} \ge 4.75 \text{ V}$	-	_	49.2	MHz	
	V _{DD} < 4.75 V	-	—	24.6	MHz	
Timer ^[26, 27]	Input clock frequency	•				
	No capture, $V_{DD} \ge 4.75 V$	-	_	49.2	MHz	
	No capture, V _{DD} < 4.75 V	-	_	24.6	MHz	
	With capture	-	_	24.6	MHz	
	Capture pulse width	50 ^[28]	-	-	ns	
Counter	Input clock frequency					
	No enable input, $V_{DD} \ge 4.75 \text{ V}$	-	_	49.2	MHz	
	No enable input, V _{DD} < 4.75 V	-	_	24.6	MHz	
	With enable input	-	-	24.6	MHz	
	Enable input pulse width	50 ^[28]	-	-	ns	
Dead Band	Kill pulse width				•	
	Asynchronous restart mode	20	—	-	ns	
	Synchronous restart mode	50 ^[28]	-	_	ns	
	Disable mode	50 ^[28]	-	-	ns	
	Input clock frequency					
	$V_{DD} \ge 4.75 \text{ V}$	-	-	49.2	MHz	
	V _{DD} < 4.75 V	-	_	24.6	MHz	
CRCPRS	Input clock frequency	•		•	•	
(PRS Mode)	$V_{DD} \ge 4.75 \text{ V}$	-	-	49.2	MHz	
	V _{DD} < 4.75 V	-	_	24.6	MHz	
CRCPRS (CRC Mode)	Input clock frequency	-	-	24.6	MHz	
SPIM	Input clock frequency	-	-	8.2	MHz	The SPI serial clock (SCLK) frequency is equal to the input clock frequency divided by 2.
SPIS ^[29]	Input clock (SCLK) frequency	-	-	4.1	MHz	The input clock is the SPI SCLK in SPIS mode.
	Width of SS_negated between transmissions	50 ^[28]	-	-	ns	
Transmitter	Input clock frequency					The baud rate is equal to the input clock frequency
	$V_{DD} \ge 4.75$ V, 2 stop bits	-	_	49.2	MHz	divided by 8.
	$V_{DD} \ge 4.75 \text{ V}, 1 \text{ stop bit}$	-	—	24.6	MHz	
	V _{DD} < 4.75 V	-	_	24.6	MHz	
Receiver	Input clock frequency					The baud rate is equal to the input clock frequency divided by 8.
	$V_{DD} \ge 4.75$ V, 2 stop bits	_	-	49.2	MHz	1
	$V_{DD} \ge 4.75 \text{ V}, 1 \text{ stop bit}$	-	-	24.6	MHz	1
	V _{DD} < 4.75 V	_	_	24.6	MHz	1

Notes

26. Errata: When operated between 4.75V to 5.25V, the input capture signal cannot be sourced from Row Output signals or the Broadcast clock signals. This problem has been fixed in silicon Rev B. For more information, see "Errata" on page 61.

27. Errata: When operated between 3.0V to 4.75V, the input capture signal can only be sourced from Row input signal that has been re-synchronized. This problem has been fixed in silicon Rev B. For more information, see "Errata" on page 61.

28.50 ns minimum input pulse width is based on the input synchronizers running at 24 MHz (42 ns nominal period).

29. Errata: In PSoC, when one output of one SPI Slave block is connected to the input of other SPI slave block, data is shifted correctly but last bit is read incorrectly. For the workaround and more information related to this problem, see "Errata" on page 61.



AC External Clock Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C \leq T_A \leq 85 °C, or 3.0 V to 3.6 V and –40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

Table 36. 5-V AC External Clock Specifications

Symbol	Description	Min	Тур	Max	Unit
FOSCEXT	Frequency	0.093	I	24.6	MHz
-	High period	20.6	-	5300	ns
-	Low period	20.6	-	-	ns
-	Power-up IMO to switch	150	-	-	μS

Table 37. 3.3-V AC External Clock Specifications

Symbol	Description	Min	Тур	Мах	Unit
F _{OSCEXT}	Frequency with CPU clock divide by 1 ^[30]	0.093	-	12.3	MHz
F _{OSCEXT}	Frequency with CPU clock divide by 2 or greater ^[31]	0.186	-	24.6	MHz
-	High period with CPU clock divide by 1	41.7	-	5300	ns
-	Low period with CPU clock divide by 1	41.7	-	-	ns
_	Power-up IMO to switch	150	1	-	μS

AC Programming Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C \leq T_A \leq 85 °C, or 3.0 V to 3.6 V and –40 °C \leq T_A \leq 85 °C, respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

Table 38. AC Programming Specifications

Symbol	Description	Min	Тур	Max	Unit	Notes
t _{RSCLK}	Rise time of SCLK	1	-	20	ns	
t _{FSCLK}	Fall time of SCLK	1	-	20	ns	
t _{SSCLK}	Data setup time to falling edge of SCLK	40	-	-	ns	
t _{HSCLK}	Data hold time from falling edge of SCLK	40	-	-	ns	
F _{SCLK}	Frequency of SCLK	0	-	8	MHz	
t _{ERASEB}	Flash erase time (Block)	-	30	-	ms	
t _{WRITE}	Flash block write time	-	10	-	ms	
t _{DSCLK}	Data out delay from falling edge of SCLK	-	-	45	ns	$V_{DD} > 3.6$
t _{DSCLK3}	Data out delay from falling edge of SCLK	-	-	50	ns	$3.0 \leq V_{DD} \leq 3.6$
t _{eraseall}	Flash erase time (Bulk)	-	95	-	ms	Erase all Blocks and protection fields at once
t _{PROGRAM_HOT}	Flash block erase + flash block write time	-	-	80 ^[32]	ms	$0~^{\circ}C \leq Tj \leq 100~^{\circ}C$
t _{PROGRAM_COLD}	Flash block erase + flash block write time	-	-	160 ^[32]	ms	-40 °C \leq Tj \leq 0 °C

Notes

- 30. Maximum CPU frequency is 12 MHz at 3.3 V. With the CPU clock divider set to 1, the external clock must adhere to the maximum frequency and duty cycle requirements.
- 31. If the frequency of the external clock is greater than 12 MHz, the CPU clock divider must be set to 2 or greater. In this case, the CPU clock divider ensures that the fifty percent duty cycle requirement is met.
- 32. For the full industrial range, you must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs application note Design Aids – Reading and Writing PSoC[®] Flash – AN2015 for more information.



CY8C27143/CY8C27243 CY8C27443/CY8C27543 CY8C27643





Important Note For information on the preferred dimensions for mounting QFN packages, see the following application note, *Design Guidelines for Cypress Quad Flat No Extended Lead (QFN) Packaged Devices – AN72845* available at http://www.cypress.com.



Glossary (continued)

bias	 A systematic deviation of a value from a reference value. The amount by which the average of a set of values departs from a reference value. The electrical, mechanical, magnetic, or other force (field) applied to a device to establish a reference level to operate the device.
block	 A functional unit that performs a single function, such as an oscillator. A functional unit that may be configured to perform one of several functions, such as a digital PSoC block or an analog PSoC block.
buffer	 A storage area for data that is used to compensate for a speed difference, when transferring data from one device to another. Usually refers to an area reserved for IO operations, into which data is read, or from which data is written.
	2. A portion of memory set aside to store data, often before it is sent to an external device or as it is received from an external device.
	3. An amplifier used to lower the output impedance of a system.
bus	1. A named connection of nets. Bundling nets together in a bus makes it easier to route nets with similar routing patterns.
	2. A set of signals performing a common function and carrying similar data. Typically represented using vector notation; for example, address[7:0].
	3. One or more conductors that serve as a common connection for a group of related devices.
clock	The device that generates a periodic signal with a fixed frequency and duty cycle. A clock is sometimes used to synchronize different logic blocks.
comparator	An electronic circuit that produces an output voltage or current whenever two input levels simultaneously satisfy predetermined amplitude requirements.
compiler	A program that translates a high level language, such as C, into machine language.
configuration space	In PSoC devices, the register space accessed when the XIO bit, in the CPU_F register, is set to '1'.
crystal oscillator	An oscillator in which the frequency is controlled by a piezoelectric crystal. Typically a piezoelectric crystal is less sensitive to ambient temperature than other circuit components.
cyclic redundancy check (CRC)	A calculation used to detect errors in data communications, typically performed using a linear feedback shift register. Similar calculations may be used for a variety of other purposes such as data compression.
data bus	A bi-directional set of signals used by a computer to convey information from a memory location to the central processing unit and vice versa. More generally, a set of signals used to convey data between digital functions.
debugger	A hardware and software system that allows you to analyze the operation of the system under development. A debugger usually allows the developer to step through the firmware one step at a time, set break points, and analyze memory.
dead band	A period of time when neither of two or more signals are in their active state or in transition.
digital blocks	The 8-bit logic blocks that can act as a counter, timer, serial receiver, serial transmitter, CRC generator, pseudo-random number generator, or SPI.
digital-to-analog (DAC)	A device that changes a digital signal to an analog signal of corresponding magnitude. The analog-to-digital (ADC) converter performs the reverse operation.



Glossary (continued)

duty cycle	The relationship of a clock period high time to its low time, expressed as a percent.
emulator	Duplicates (provides an emulation of) the functions of one system with a different system, so that the second system appears to behave like the first system.
External Reset (XRES)	An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.
Flash	An electrically programmable and erasable, non-volatile technology that provides you the programmability and data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power is OFF.
Flash block	The smallest amount of Flash ROM space that may be programmed at one time and the smallest amount of Flash space that may be protected. A Flash block holds 64 bytes.
frequency	The number of cycles or events per unit of time, for a periodic function.
gain	The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually expressed in dB.
I ² C	A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). I2C is an Inter-Integrated Circuit. It is used to connect low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I2C uses only two bi-directional pins, clock and data, both running at +5V and pulled high with resistors. The bus operates at 100 kbits/second in standard mode and 400 kbits/second in fast mode.
ICE	The in-circuit emulator that allows you to test the project in a hardware environment, while viewing the debugging device activity in a software environment (PSoC Designer).
input/output (I/O)	A device that introduces data into or extracts data from a system.
interrupt	A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed.
interrupt service routine (ISR)	A block of code that normal code execution is diverted to when the M8C receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.
jitter	1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams.
	The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.
low-voltage detect (LVD)	A circuit that senses V_{DD} and provides an interrupt to the system when V_{DD} falls lower than a selected threshold.
M8C	An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by interfacing to the Flash, SRAM, and register space.
master device	A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in width, the master device is the one that controls the timing for data exchanges between the cascaded devices and an external interface. The controlled device is called the <i>slave device</i> .



Glossary (continued)

shift register	A memory storage device that sequentially shifts a word either left or right to output a stream of serial data.
slave device	A device that allows another device to control the timing for data exchanges between two devices. Or when devices are cascaded in width, the slave device is the one that allows another device to control the timing of data exchanges between the cascaded devices and an external interface. The controlling device is called the master device.
SRAM	An acronym for static random access memory. A memory device where you can store and retrieve data at a high rate of speed. The term static is used because, after a value is loaded into an SRAM cell, it remains unchanged until it is explicitly altered or until power is removed from the device.
SROM	An acronym for supervisory read only memory. The SROM holds code that is used to boot the device, calibrate circuitry, and perform Flash operations. The functions of the SROM may be accessed in normal user code, operating from Flash.
stop bit	A signal following a character or block that prepares the receiving device to receive the next character or block.
synchronous	 A signal whose data is not acknowledged or acted upon until the next active edge of a clock signal. A system whose operation is synchronized by a clock signal.
tri-state	A function whose output can adopt three states: 0, 1, and Z (high-impedance). The function does not drive any value in the Z state and, in many respects, may be considered to be disconnected from the rest of the circuit, allowing another output to drive the same net.
UART	A UART or universal asynchronous receiver-transmitter translates between parallel bits of data and serial bits.
user modules	Pre-build, pre-tested hardware/firmware peripheral functions that take care of managing and configuring the lower level Analog and Digital PSoC Blocks. User Modules also provide high level API (Application Programming Interface) for the peripheral function.
user space	The bank 0 space of the register map. The registers in this bank are more likely to be modified during normal program execution and not just during initialization. Registers in bank 1 are most likely to be modified only during the initialization phase of the program.
V _{DD}	A name for a power net meaning "voltage drain." The most positive power supply signal. Usually 5 V or 3.3 V.
V _{SS}	A name for a power net meaning "voltage source." The most negative power supply signal.
watchdog timer	A timer that must be serviced periodically. If it is not serviced, the CPU resets after a specified period of time.



2. Internal Main Oscillator (IMO) Tolerance Deviation at Temperature Extremes.

Problem Definition

Asynchronous Digital Communications Interfaces may fail framing beyond 0 to 70 °C. This problem does not affect end-product usage between 0 and 70 °C.

Parameters Affected

The IMO frequency tolerance. The worst case deviation when operated below 0° C and above +70°C and within the upper and lower datasheet temperature range is ±5%.

Trigger Condition(s)

The asynchronous Rx/Tx clock source IMO frequency tolerance may deviate beyond the data sheet limit of \pm 2.5% when operated beyond the temperature range of 0 to +70 °C.

Scope of Impact

This problem may affect UART, IrDA, and FSK implementations.

Workaround

Implement a quartz crystal stabilized clock source on at least one end of the asynchronous digital communications interface.

Fix Status

There are no fixes planned. The workaround listed above should be used.



Not in Production

Part Numbers Affected

Part Number	
CY8C27143	
CY8C27243	
CY8C27443	
CY8C27543	
CY8C27643	

Qualification Status

CY8C27X43 Rev. A - Not in production

Errata Summary

The following table defines the errata applicability to available devices.

Items	Part Number	Silicon Revision	Fix Status
1. The Timer Capture Input signal is limited to re-synchronized Row Inputs or Analog Comparator bus inputs when operating over 4.75 V.	All parts affected	A	Fix confirmed in Silicon Rev B
2. The Timer Capture Inputs are limited to re-synchronized Row Inputs when operating at less than 4.75 V.	All parts affected	A	Fix confirmed in Silicon Rev B
3. The I2C_CFG, I2C_SCR, and I2C_MSCR registers have some restrictions as to the CPU frequency that must be in effect when these registers are written.	All parts affected	A	Fix confirmed in Silicon Rev B

1. The Timer Capture Input signal is limited to re-synchronized Row Inputs or Analog Comparator bus inputs when operating over 4.75 V.

Problem Definition

When the device is operating at 4.75 V to 5.25 V, the Input Capture signal source for a digital block operating in Timer mode is limited to either a Row Input signal that has been re-synchronized, or an Analog Comparator bus input. The Row Output signals, or the Broadcast clock signals, cannot be used as a source for the Timer Capture signal.

Parameters Affected

NA

Trigger Condition(S)

Device operating with VCC between 4.75 V to 5.25 V.

Scope of Impact

Digital blocks operating in timer mode and user modules relying on the timer's output are affected by this errata element.

Workaround

To connect the Input Capture signal to the output of another block in the same row, run the output of that block to a Row Output, then to a Global Output, then back to a Global Input, then a Row Input, where the signal can be resynchronized. When connecting the Input Capture signal to an output of a block in a different row, the connection will naturally follow the path of Global Output, to Global Input, then to Row Input.

Fix Status

Fix in silicon rev B



Document History Page (continued)

Document Document	Document Title: CY8C27143/CY8C27243/CY8C27443/CY8C27543/CY8C27643, PSoC [®] Programmable System-on-Chip™ Document Number: 38-12012					
Revision	ECN	Origin of Change	Submission Date	Description of Change		
*P	2899847	NJF / HMI	03/26/10	Added CY8C27643-24LKXI and CY8C27643-24LTXI to Emulation and Programming Accessories on page 52. Updated Cypress website links. Added T _{BAKETEMP} and T _{BAKETIME} parameters in Absolute Maximum Ratings on page 19. Updated AC electrical specs. Updated Note in Packaging Information on page 44. Updated package diagrams. Updated Thermal Impedances, Solder Reflow Specifications, and Capaci- tance on Crystal Pins. Removed Third Party Tools and Build a PSoC Emulator into your Board. Updated Ordering Code Definitions on page 54. Updated Ordering Information table. Updated links in Sales, Solutions, and Legal Information.		
*Q	2949177	ECU	06/10/2010	Updated content to match current style guide and data sheet template. No technical updates		
*R	3032514	NJF	09/17/10	Added PSoC Device Characteristics table. Added DC I ² C Specifications table. Added T _{32K U} max limit. Added Tjit_IMO specification, removed existing jitter specifications. Updated Analog reference tables. Updated Units of Measure, Acronyms, Glossary, and References sections. Updated solder reflow specifications. No specific changes were made to AC Digital Block Specifications table and I ² C Timing Diagram. They were updated for clearer understanding. Updated Figure 13 since the labelling for y-axis was incorrect. Template and styles update.		
*S	3092470	GDK	11/22/10	Removed the following pruned parts from the data sheet. CY8C27643-24LFXIT CY8C27643-24LFXI		
*T	3180303	HMI	02/23/2011	Updated Packaging Information.		
*U	3378917	GIR	09/28/2011	The text "Pin must be left floating" is included under Description of NC pin in Table 8 on page 14. Updated Table 42 on page 50 for improved clarity. Removed Footnote # 31 and its reference under Table 42 on page 50. Removed inactive part CY8C27643-24LKXI from Table 43 on page 52.		
*V	3525102	UVS	02/14/2012	Updated 48-pin sawn QFN package revision. No technical update.		
*W	3598316	LURE / XZNG	04/24/2012	Changed the PWM description string from "8- to 32-bit" to "8- and 16-bit".		
*X	3959251	GVH	04/09/2013	Updated Packaging Information: spec 51-85014 – Changed revision from *F to *G. spec 51-85061 – Changed revision from *E to *F. spec 001-13191 – Changed revision from *F to *G. spec 51-85062 – Changed revision from *E to *F. Added Errata.		
*Y	3997627	GVH	05/11/2013	Updated Packaging Information: spec 51-85026 – Changed revision from *F to *G. Updated Errata.		



Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

Products	
Automotive	cypress.com/go/automotive
Clocks & Buffers	cypress.com/go/clocks
Interface	cypress.com/go/interface
Lighting & Power Control	cypress.com/go/powerpsoc
	cypress.com/go/plc
Memory	cypress.com/go/memory
PSoC	cypress.com/go/psoc
Touch Sensing	cypress.com/go/touch
USB Controllers	cypress.com/go/USB
Wireless/RF	cypress.com/go/wireless

PSoC[®] Solutions

psoc.cypress.com/solutions PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP

Cypress Developer Community Community | Forums | Blogs | Video | Training

Technical Support cypress.com/go/support

© Cypress Semiconductor Corporation, 2003-2014. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for medical, life support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress' product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.

Document Number: 38-12012 Rev. AB

Revised September 19, 2014

Page 69 of 69

PSoC Designer[™] and Programmable System-on-Chip[™] are trademarks and PSoC® and CapSense® are registered trademarks of Cypress Semiconductor Corporation. Purchase of I²C components from Cypress or one of its sublicensed Associated Companies conveys a license under the Philips I²C Patent Rights to use these components in an I²C system, provided that the system conforms to the I²C Standard Specification as defined by Philips. As from October 1st, 2006 Philips Semiconductors has a new trade name - NXP Semiconductors. All products and company names mentioned in this document may be the trademarks of their respective holders.