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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 12x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-VQFN (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d4-mhr">https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d4-mhr</a>

## 12. WDT – Watchdog Timer

### 12.1 Features

- Issues a device reset if the timer is not reset before its timeout period
- Asynchronous operation from dedicated oscillator
- 1kHz output of the 32kHz ultra low power oscillator
- 11 selectable timeout periods, from 8ms to 8s
- Two operation modes:
  - Normal mode
  - Window mode
- Configuration lock to prevent unwanted changes

### 12.2 Overview

The watchdog timer (WDT) is a system function for monitoring correct program operation. It makes it possible to recover from error situations such as runaway or deadlocked code. The WDT is a timer, configured to a predefined timeout period, and is constantly running when enabled. If the WDT is not reset within the timeout period, it will issue a microcontroller reset. The WDT is reset by executing the WDR (watchdog timer reset) instruction from the application code.

The window mode makes it possible to define a time slot or window inside the total timeout period during which WDT must be reset. If the WDT is reset outside this window, either too early or too late, a system reset will be issued. Compared to the normal mode, this can also catch situations where a code error causes constant WDR execution.

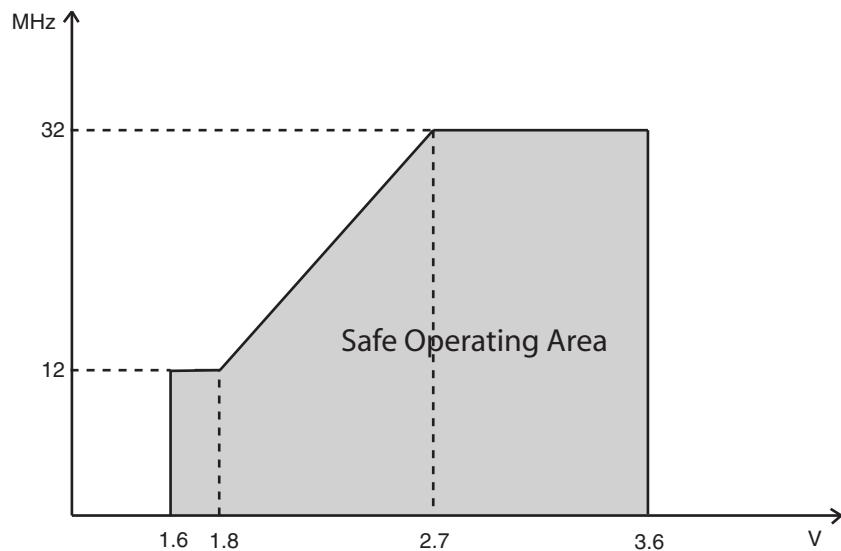
The WDT will run in active mode and all sleep modes, if enabled. It is asynchronous, runs from a CPU-independent clock source, and will continue to operate to issue a system reset even if the main clocks fail.

The configuration change protection mechanism ensures that the WDT settings cannot be changed by accident. For increased safety, a fuse for locking the WDT settings is also available.

## 30. Instruction Set Summary

Mnemonics	Operands	Description	Operation		Flags	#Clocks
Arithmetic and Logic Instructions						
ADD	Rd, Rr	Add without Carry	Rd	$\leftarrow$ Rd + Rr	Z,C,N,V,S,H	1
ADC	Rd, Rr	Add with Carry	Rd	$\leftarrow$ Rd + Rr + C	Z,C,N,V,S,H	1
ADIW	Rd, K	Add Immediate to Word	Rd	$\leftarrow$ Rd + 1:Rd + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract without Carry	Rd	$\leftarrow$ Rd - Rr	Z,C,N,V,S,H	1
SUBI	Rd, K	Subtract Immediate	Rd	$\leftarrow$ Rd - K	Z,C,N,V,S,H	1
SBC	Rd, Rr	Subtract with Carry	Rd	$\leftarrow$ Rd - Rr - C	Z,C,N,V,S,H	1
SBCI	Rd, K	Subtract Immediate with Carry	Rd	$\leftarrow$ Rd - K - C	Z,C,N,V,S,H	1
SBIW	Rd, K	Subtract Immediate from Word	Rd + 1:Rd	$\leftarrow$ Rd + 1:Rd - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND	Rd	$\leftarrow$ Rd • Rr	Z,N,V,S	1
ANDI	Rd, K	Logical AND with Immediate	Rd	$\leftarrow$ Rd • K	Z,N,V,S	1
OR	Rd, Rr	Logical OR	Rd	$\leftarrow$ Rd v Rr	Z,N,V,S	1
ORI	Rd, K	Logical OR with Immediate	Rd	$\leftarrow$ Rd v K	Z,N,V,S	1
EOR	Rd, Rr	Exclusive OR	Rd	$\leftarrow$ Rd $\oplus$ Rr	Z,N,V,S	1
COM	Rd	One's Complement	Rd	$\leftarrow$ \$FF - Rd	Z,C,N,V,S	1
NEG	Rd	Two's Complement	Rd	$\leftarrow$ \$00 - Rd	Z,C,N,V,S,H	1
SBR	Rd,K	Set Bit(s) in Register	Rd	$\leftarrow$ Rd v K	Z,N,V,S	1
CBR	Rd,K	Clear Bit(s) in Register	Rd	$\leftarrow$ Rd • (\$FFh - K)	Z,N,V,S	1
INC	Rd	Increment	Rd	$\leftarrow$ Rd + 1	Z,N,V,S	1
DEC	Rd	Decrement	Rd	$\leftarrow$ Rd - 1	Z,N,V,S	1
TST	Rd	Test for Zero or Minus	Rd	$\leftarrow$ Rd • Rd	Z,N,V,S	1
CLR	Rd	Clear Register	Rd	$\leftarrow$ Rd $\oplus$ Rd	Z,N,V,S	1
SER	Rd	Set Register	Rd	$\leftarrow$ \$FF	None	1
MUL	Rd,Rr	Multiply Unsigned	R1:R0	$\leftarrow$ Rd x Rr (UU)	Z,C	2
MULS	Rd,Rr	Multiply Signed	R1:R0	$\leftarrow$ Rd x Rr (SS)	Z,C	2
MULSU	Rd,Rr	Multiply Signed with Unsigned	R1:R0	$\leftarrow$ Rd x Rr (SU)	Z,C	2
FMUL	Rd,Rr	Fractional Multiply Unsigned	R1:R0	$\leftarrow$ Rd x Rr<<1 (UU)	Z,C	2
FMULS	Rd,Rr	Fractional Multiply Signed	R1:R0	$\leftarrow$ Rd x Rr<<1 (SS)	Z,C	2
FMULSU	Rd,Rr	Fractional Multiply Signed with Unsigned	R1:R0	$\leftarrow$ Rd x Rr<<1 (SU)	Z,C	2
Branch instructions						
RJMP	k	Relative Jump	PC	$\leftarrow$ PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC(15:0) PC(21:16)	$\leftarrow$ Z, $\leftarrow$ 0	None	2
EIJMP		Extended Indirect Jump to (Z)	PC(15:0) PC(21:16)	$\leftarrow$ Z, $\leftarrow$ EIND	None	2
JMP	k	Jump	PC	$\leftarrow$ k	None	3
RCALL	k	Relative Call Subroutine	PC	$\leftarrow$ PC + k + 1	None	2 / 3 <sup>(1)</sup>

**Figure 32-8. Maximum Frequency vs.  $V_{CC}$**



**Table 32-56. Two-wire Interface Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$V_{IH}$	Input high voltage		0.7V <sub>CC</sub>		$V_{CC}+0.5$	V
$V_{IL}$	Input low voltage		-0.5		0.3V <sub>CC</sub>	
$V_{hys}$	Hysteresis of Schmitt trigger inputs		0.05V <sub>CC</sub> <sup>(1)</sup>			
$V_{OL}$	Output low voltage	3mA, sink current	0		0.4	
$t_r$	Rise time for both SDA and SCL		$20+0.1C_b$ <sup>(1)(2)</sup>		300	ns
$t_{of}$	Output fall time from $V_{IHmin}$ to $V_{ILmax}$		$10pF < C_b < 400pF$ <sup>(2)</sup>		250	
$t_{SP}$	Spikes suppressed by input filter		0		50	
$I_I$	Input current for each I/O Pin	$0.1V_{CC} < V_I < 0.9V_{CC}$	-10		10	$\mu A$
$C_I$	Capacitance for each I/O Pin				10	pF
$f_{SCL}$	SCL clock frequency	$f_{PER}$ <sup>(3)</sup> >max(10f <sub>SCL</sub> , 250kHz)	0		400	kHz
$R_P$	Value of pull-up resistor	$f_{SCL} \leq 100\text{kHz}$	$\frac{V_{CC}-0.4V}{3mA}$		$\frac{100ns}{C_b}$	$\Omega$
		$f_{SCL} > 100\text{kHz}$			$\frac{300ns}{C_b}$	
$t_{HD;STA}$	Hold time (repeated) START condition	$f_{SCL} \leq 100\text{kHz}$	4.0			$\mu s$
		$f_{SCL} > 100\text{kHz}$	0.6			
$t_{LOW}$	Low period of SCL clock	$f_{SCL} \leq 100\text{kHz}$	4.7			
		$f_{SCL} > 100\text{kHz}$	1.3			
$t_{HIGH}$	High period of SCL clock	$f_{SCL} \leq 100\text{kHz}$	4.0			
		$f_{SCL} > 100\text{kHz}$	0.6			
$t_{SU;STA}$	Set-up time for a repeated START condition	$f_{SCL} \leq 100\text{kHz}$	4.7			$\mu s$
		$f_{SCL} > 100\text{kHz}$	0.6			
$t_{HD;DAT}$	Data hold time	$f_{SCL} \leq 100\text{kHz}$	0		3.45	$\mu s$
		$f_{SCL} > 100\text{kHz}$	0		0.9	
$t_{SU;DAT}$	Data setup time	$f_{SCL} \leq 100\text{kHz}$	250			$ns$
		$f_{SCL} > 100\text{kHz}$	100			
$t_{SU;STO}$	Setup time for STOP condition	$f_{SCL} \leq 100\text{kHz}$	4.0			$\mu s$
		$f_{SCL} > 100\text{kHz}$	0.6			
$t_{BUF}$	Bus free time between a STOP and START condition	$f_{SCL} \leq 100\text{kHz}$	4.7			$\mu s$
		$f_{SCL} > 100\text{kHz}$	1.3			

- Notes:
- Required only for  $f_{SCL} > 100\text{kHz}$ .
  - $C_b$  = Capacitance of one bus line in pF.
  - $f_{PER}$  = Peripheral clock frequency.

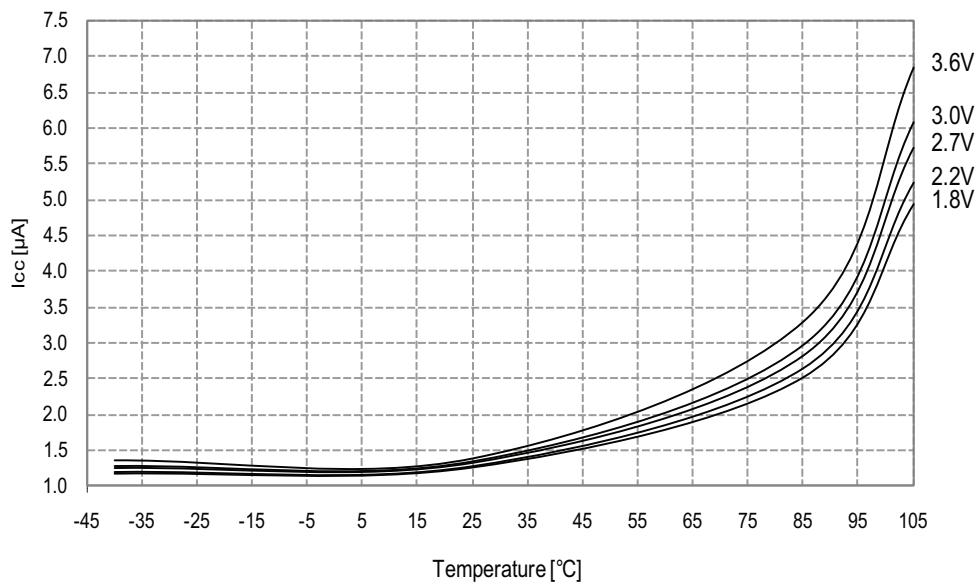
**Table 32-90. Current Consumption for Modules and Peripherals**

Symbol	Parameter	Condition <sup>(1)</sup>	Min.	Typ.	Max.	Units
$I_{CC}$	ULP oscillator			1.0		$\mu A$
	32.768kHz int. oscillator			29		
	2MHz int. oscillator			85		
		DFLL enabled with 32.768kHz int. osc. as reference		115		
	32MHz int. oscillator			270		
		DFLL enabled with 32.768kHz int. osc. as reference		440		
	PLL	20x multiplication factor, 32MHz int. osc. DIV4 as reference		320		
	Watchdog Timer			1.0		
	BOD	Continuous mode		138		
		Sampled mode, includes ULP oscillator		1.2		
	Internal 1.0V reference			260		
	Temperature sensor			250		
	ADC	150ksps $V_{REF} = \text{Ext ref}$		3.0		$mA$
			CURRLIMIT = LOW	2.6		
			CURRLIMIT = MEDIUM	2.1		
			CURRLIMIT = HIGH	1.6		
	AC	High Speed mode		330		$\mu A$
		Low power mode		130		
	Timer/Counter			16		
	USART	Rx and Tx enabled, 9600 BAUD		2.5		
	Flash memory and EEPROM programming			4.0	8.0	$mA$

Note: 1. All parameters measured as the difference in current consumption between module enabled and disabled. All data at  $V_{CC} = 3.0V$ ,  $\text{Clk}_{SYS} = 1\text{MHz}$  external clock without prescaling,  $T = 25^\circ C$  unless other conditions are given.

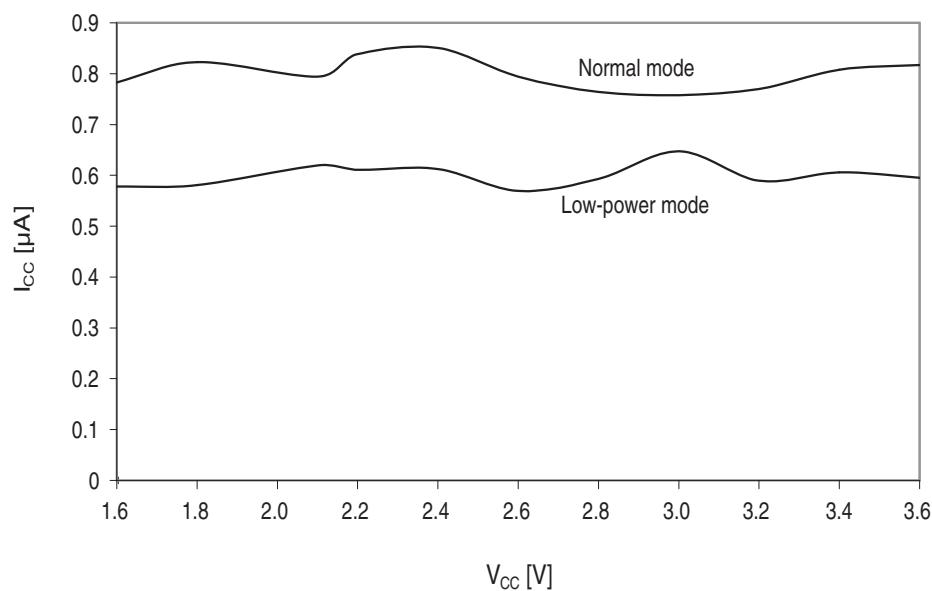
Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$R_Q$	Negative impedance <sup>(1)</sup>	XOSCPWR=0, FRQRANGE=0	0.4MHz resonator, CL=100pF	2.4k		
			1MHz crystal, CL=20pF	8.7k		
			2MHz crystal, CL=20pF	2.1k		
		XOSCPWR=0, FRQRANGE=1, CL=20pF	2MHz crystal	4.2k		
			8MHz crystal	250		
			9MHz crystal	195		
		XOSCPWR=0, FRQRANGE=2, CL=20pF	8MHz crystal	360		
			9MHz crystal	285		
			12MHz crystal	155		
		XOSCPWR=0, FRQRANGE=3, CL=20pF	9MHz crystal	365		
			12MHz crystal	200		
			16MHz crystal	105		
		XOSCPWR=1, FRQRANGE=0, CL=20pF	9MHz crystal	435		
			12MHz crystal	235		
			16MHz crystal	125		
		XOSCPWR=1, FRQRANGE=1, CL=20pF	9MHz crystal	495		
			12MHz crystal	270		
			16MHz crystal	145		
		XOSCPWR=1, FRQRANGE=2, CL=20pF	12MHz crystal	305		
			16MHz crystal	160		
		XOSCPWR=1, FRQRANGE=3, CL=20pF	12MHz crystal	380		
			16MHz crystal	205		
ESR		SF = safety factor				$\min(R_Q)/SF$ k $\Omega$
Start-up time		XOSCPWR=0, FRQRANGE=0	0.4MHz resonator, CL=100pF		1.0	
		XOSCPWR=0, FRQRANGE=1	2MHz crystal, CL=20pF		2.6	
		XOSCPWR=0, FRQRANGE=2	8MHz crystal, CL=20pF		0.8	ms
		XOSCPWR=0, FRQRANGE=3	12MHz crystal, CL=20pF		1.0	
		XOSCPWR=1, FRQRANGE=3	16MHz crystal, CL=20pF		1.4	

**Figure 33-17. Power-down Mode Supply Current vs. Temperature**  
*Watchdog and sampled BOD enabled and running from internal ULP oscillator*



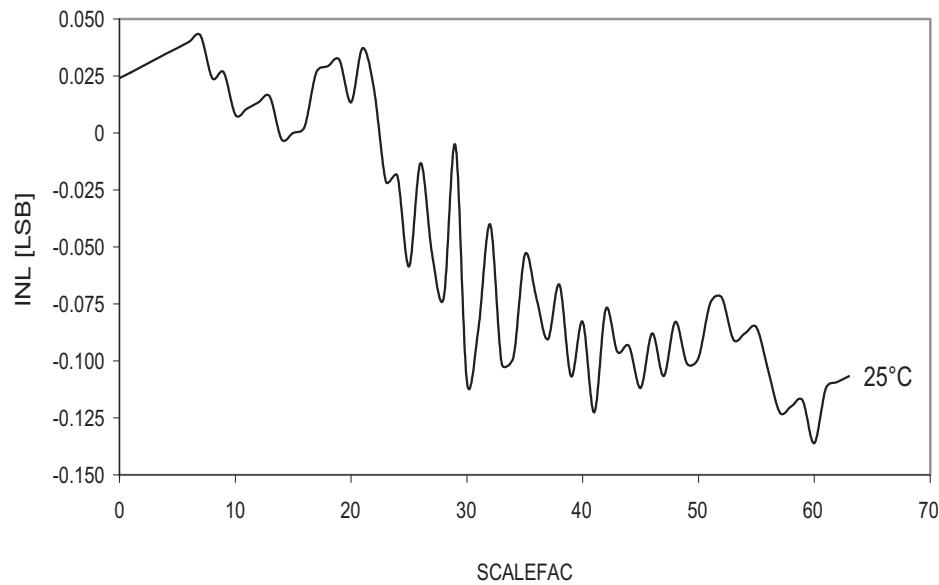
### 33.1.1.4 Power-save Mode Supply Current

**Figure 33-18. Power-save Mode Supply Current vs. $V_{CC}$**   
*Real Time Counter enabled and running from 1.024kHz output of 32.768kHz TOSC*



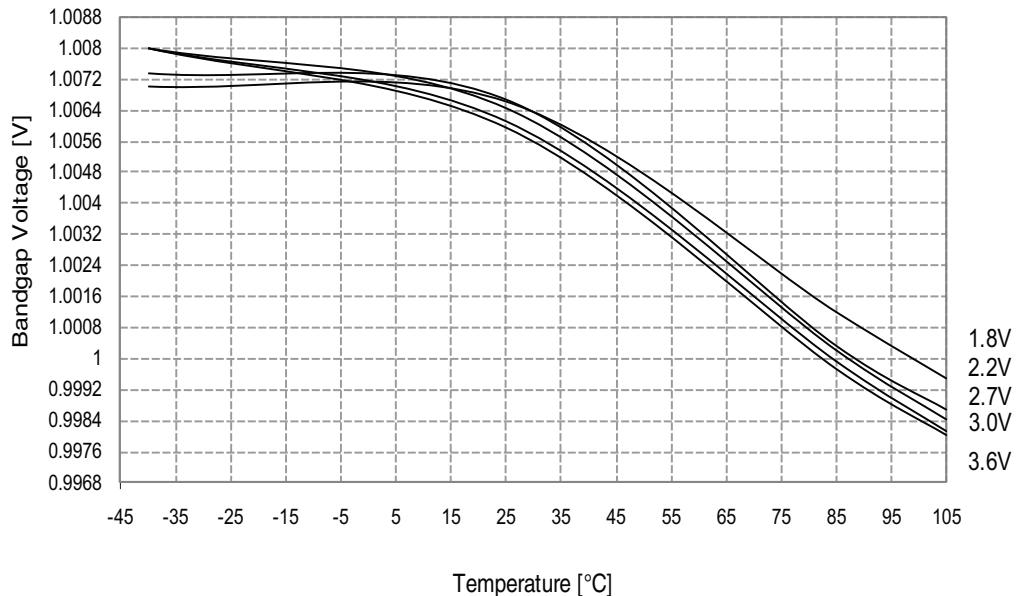
**Figure 33-53. Voltage Scaler INL vs. SCALEFAC**

$T = 25^\circ\text{C}$ ,  $V_{CC} = 3.0\text{V}$



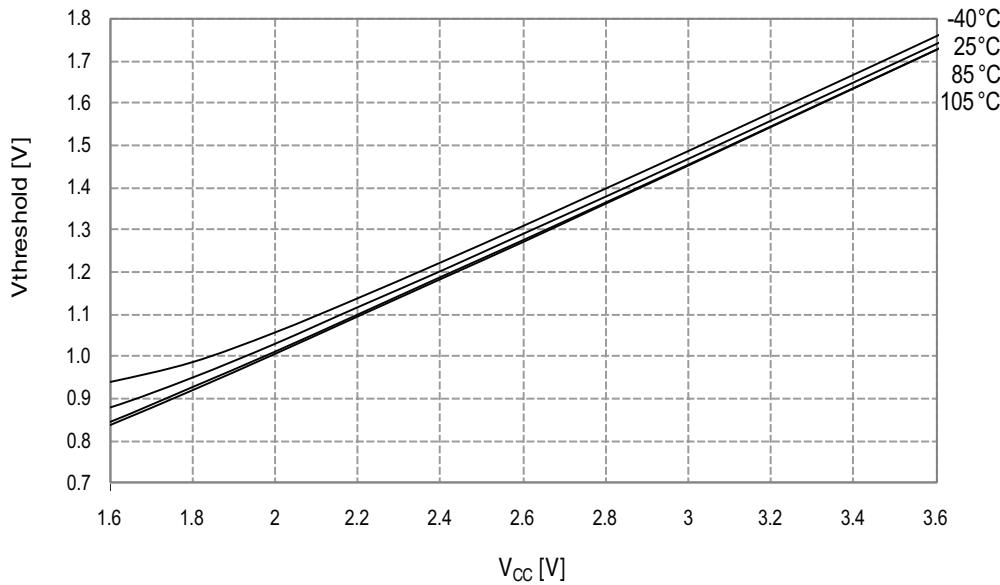
### 33.1.5 Internal 1.0V Reference Characteristics

**Figure 33-54. ADC Internal 1.0V Reference vs. Temperature**



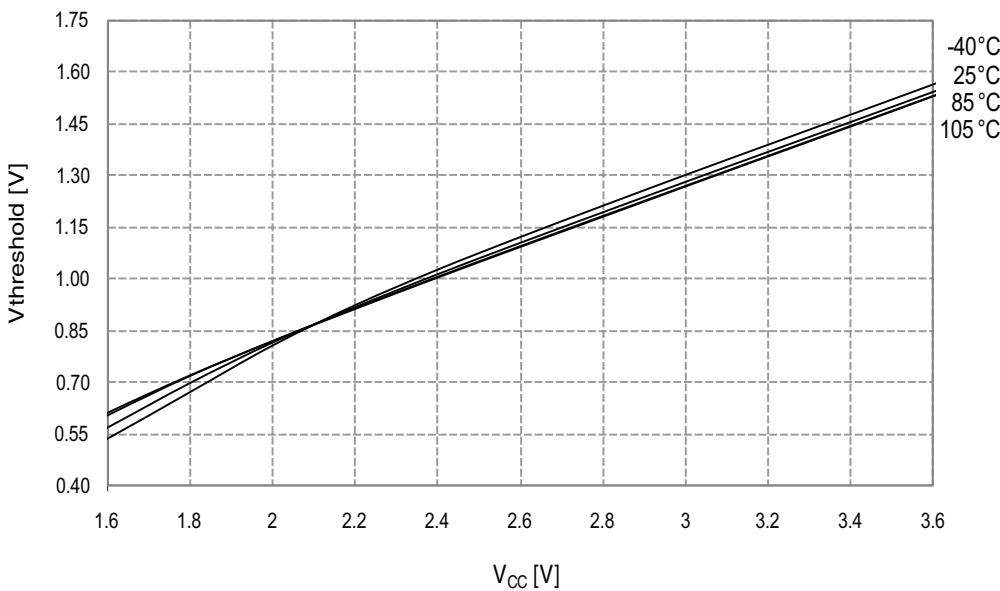
**Figure 33-112. I/O Pin Input Threshold Voltage vs.  $V_{CC}$**

$V_{IH}$  I/O pin read as “1”

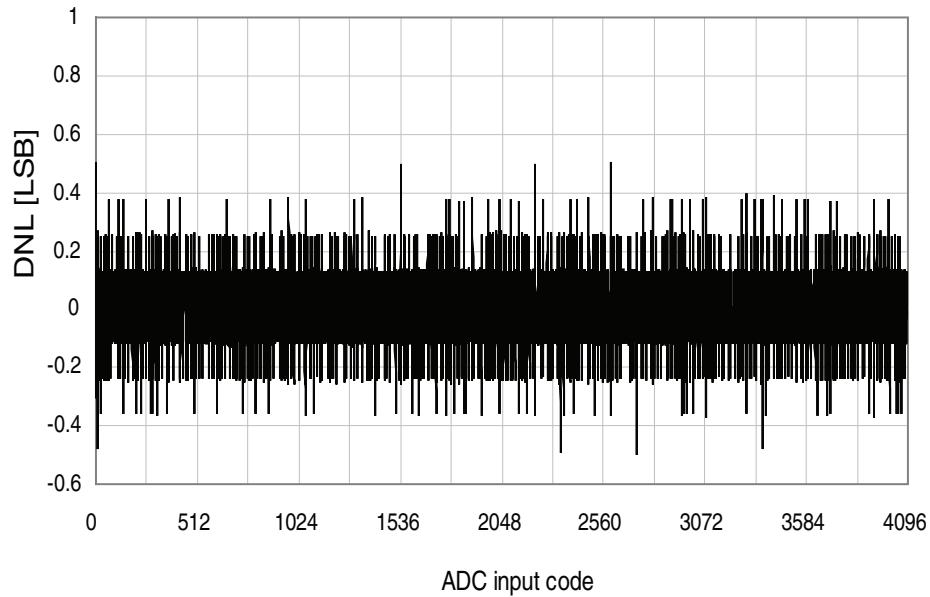


**Figure 33-113. I/O Pin Input Threshold Voltage vs.  $V_{CC}$**

$V_{IL}$  I/O pin read as “0”

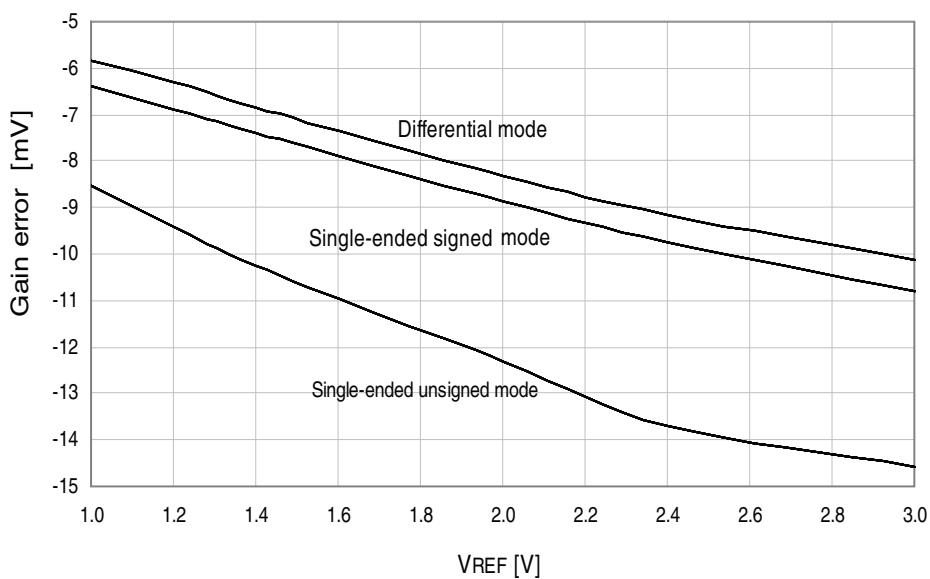


**Figure 33-120. DNL Error vs. Input code**



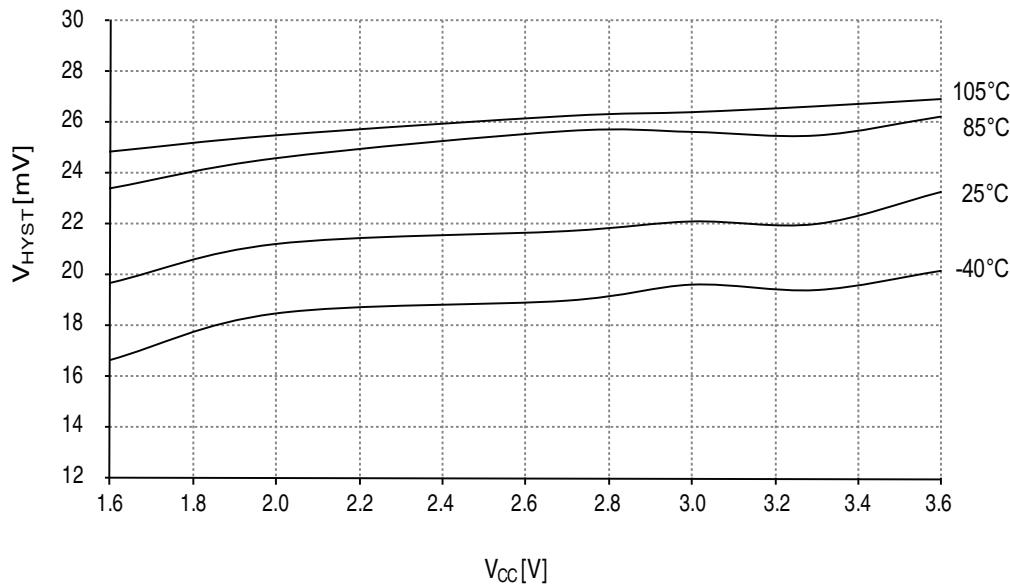
**Figure 33-121. Gain Error vs.  $V_{REF}$**

$T = 25^\circ\text{C}$ ,  $V_{CC} = 3.6\text{V}$ , ADC sample rate = 200ksps



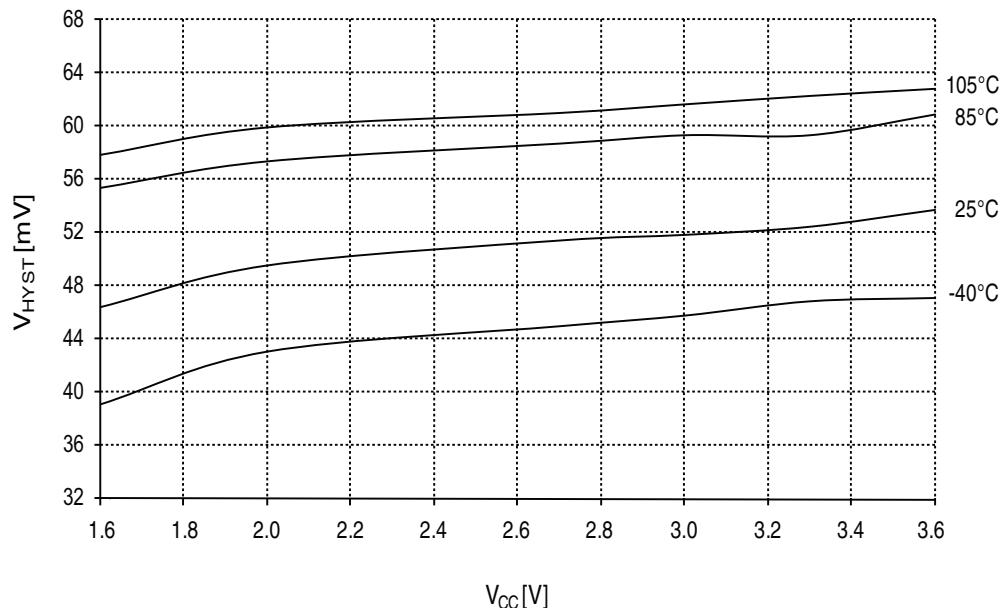
**Figure 33-128. Analog Comparator Hysteresis vs.  $V_{CC}$**

*Low power, small hysteresis*



**Figure 33-129. Analog Comparator Hysteresis vs.  $V_{CC}$**

*Low power, large hysteresis*



### 33.2.10 Two-Wire Interface Characteristics

Figure 33-156. SDA Hold Time vs. Temperature

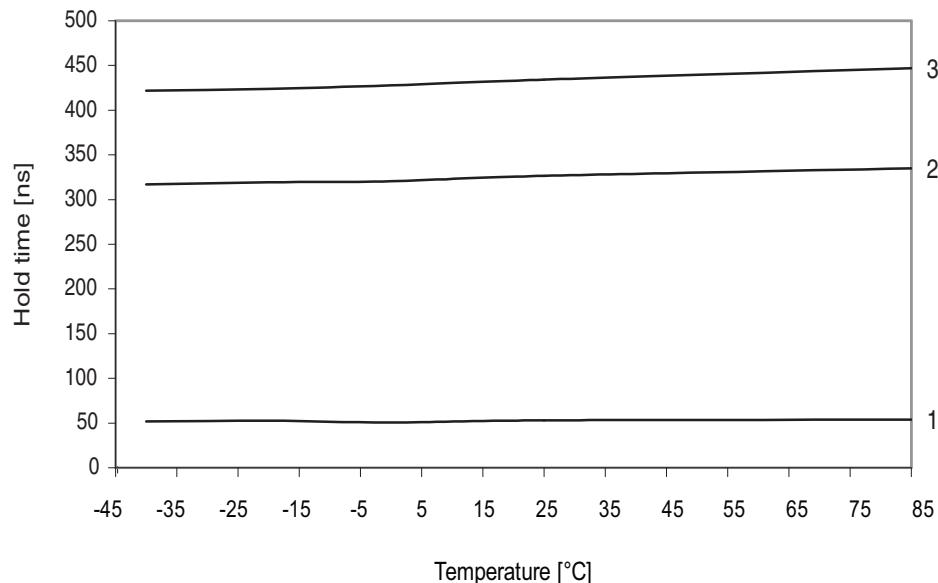
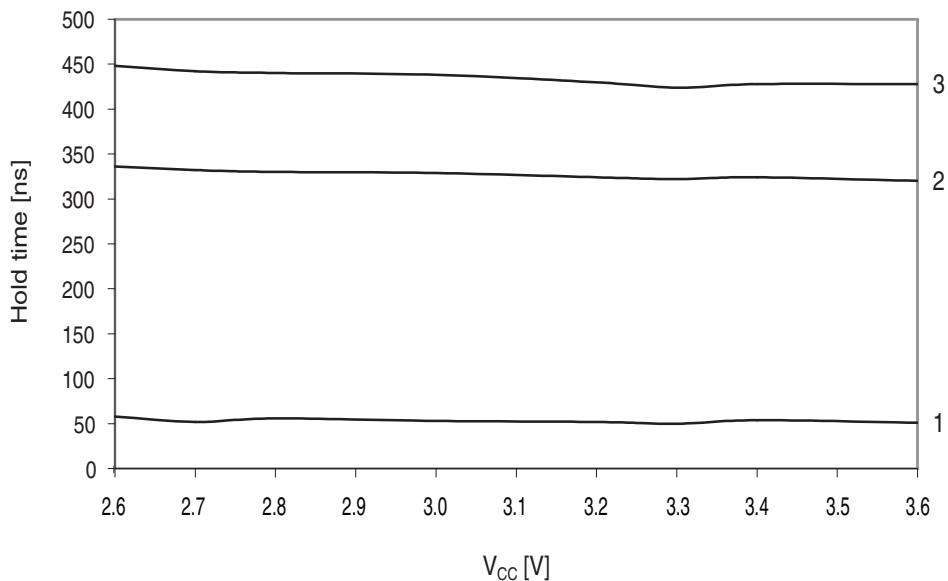
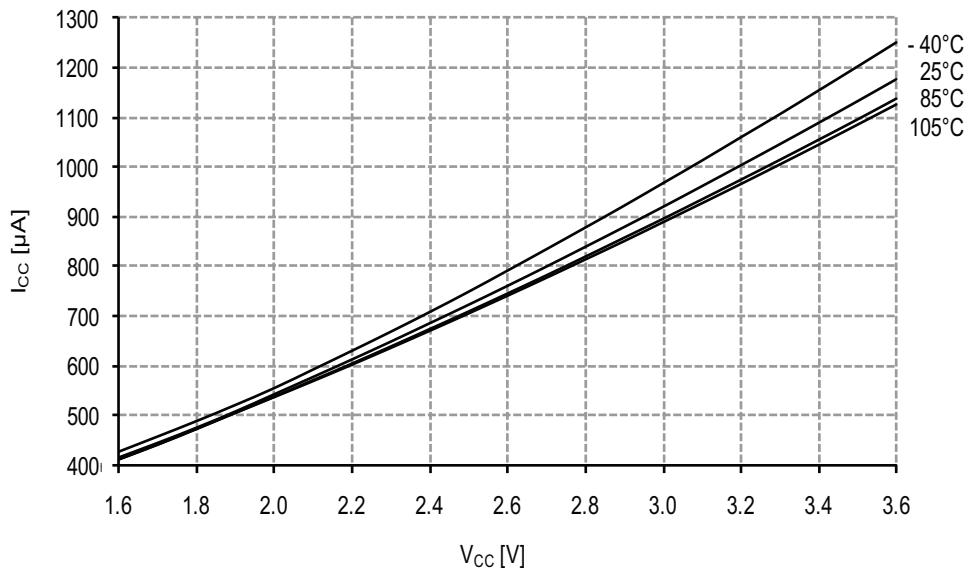


Figure 33-157. SDA Hold Time vs. Supply Voltage



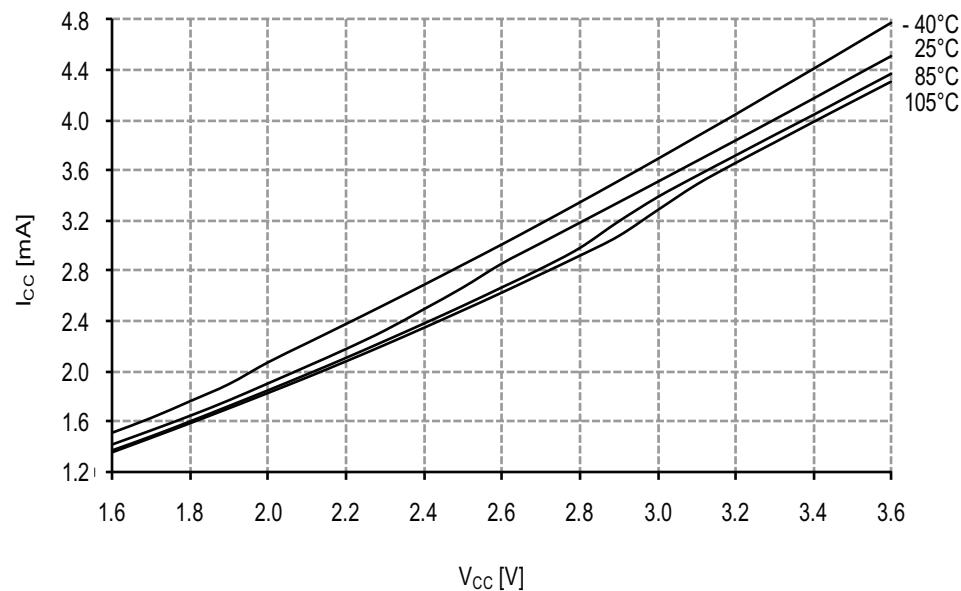
**Figure 33-163. Active Mode Supply Current vs.  $V_{CC}$**

$f_{SYS} = 2\text{MHz}$  internal oscillator

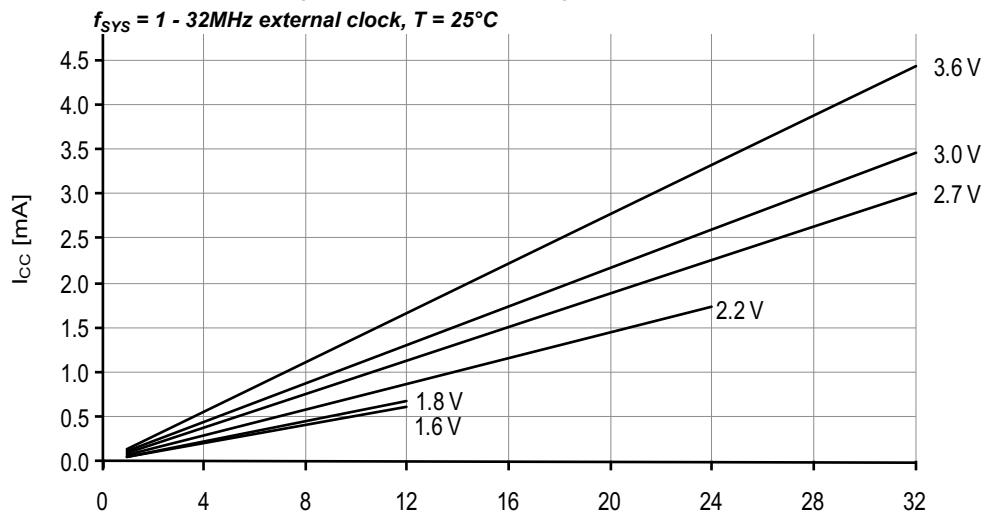


**Figure 33-164. Active Mode Supply Current vs.  $V_{CC}$**

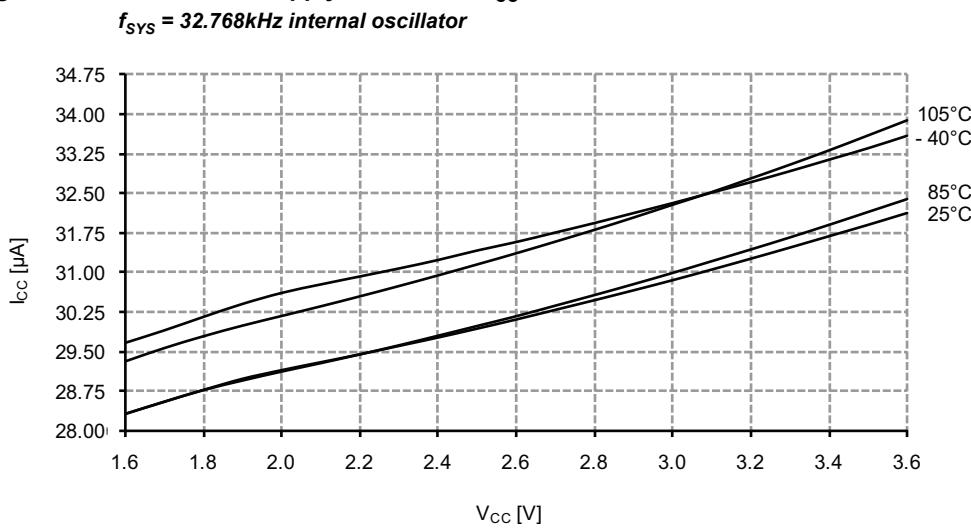
$f_{SYS} = 32\text{MHz}$  internal oscillator prescaled to 8MHz



**Figure 33-167. Idle Mode Supply Current vs. Frequency**

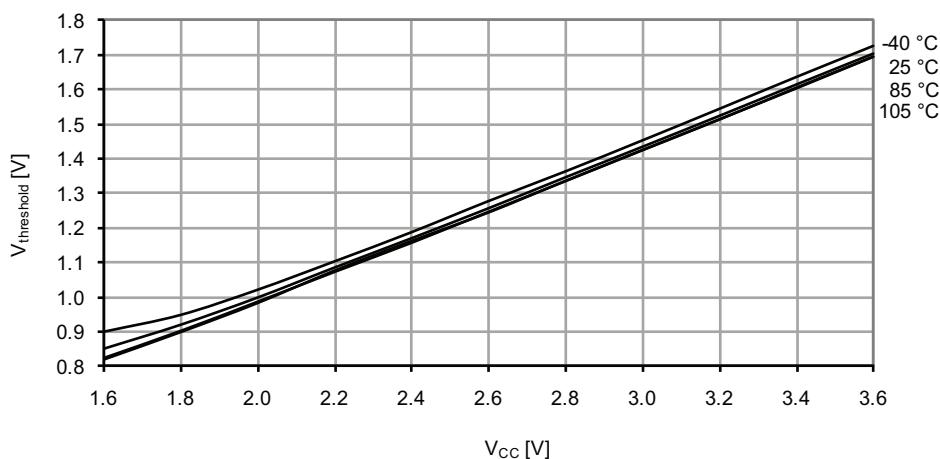


**Figure 33-168. Idle Mode Supply Current vs.  $V_{CC}$**



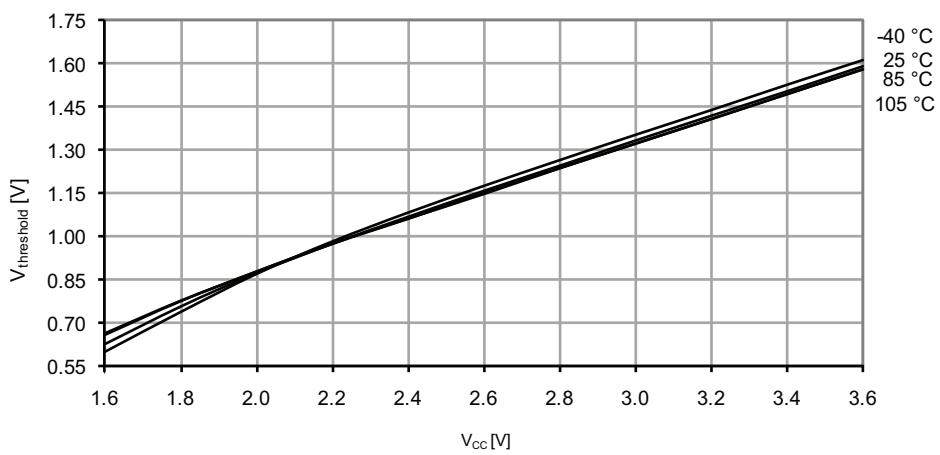
**Figure 33-191. I/O Pin Input Threshold Voltage vs.  $V_{CC}$**

$V_{IH}$  I/O pin read as “1”



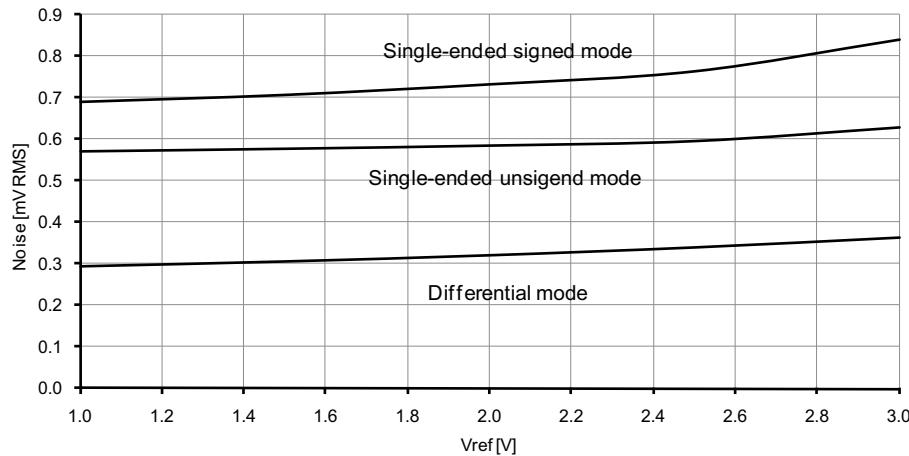
**Figure 33-192. I/O Pin Input Threshold Voltage vs.  $V_{CC}$**

$V_{IL}$  I/O pin read as “0”



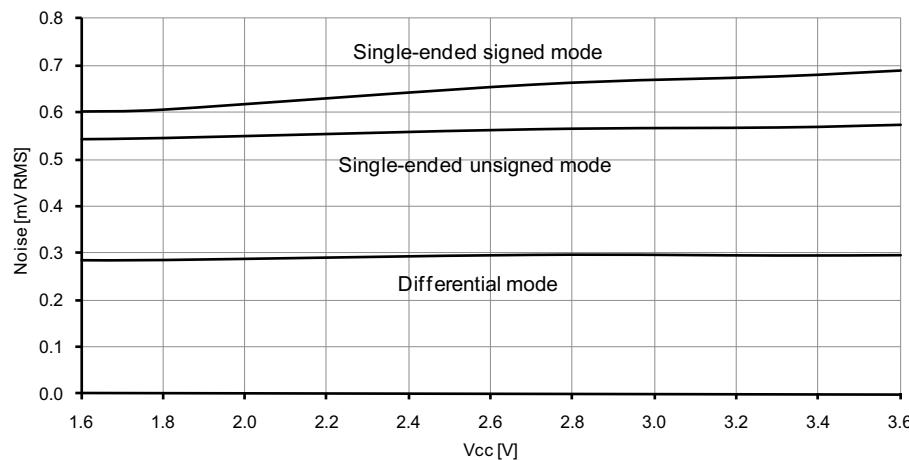
**Figure 33-205. Noise vs.  $V_{REF}$**

$T = 25^\circ\text{C}$ ,  $V_{CC} = 3.6\text{V}$ , ADC sampling speed = 500ksps



**Figure 33-206. Noise vs.  $V_{CC}$**

$T = 25^\circ\text{C}$ ,  $V_{REF}$  = external 1.0V, ADC sampling speed = 500ksps



### 33.3.10.3 2MHz Internal Oscillator

Figure 33-231. 2MHz Internal Oscillator Frequency vs. Temperature

*DFLL disabled*

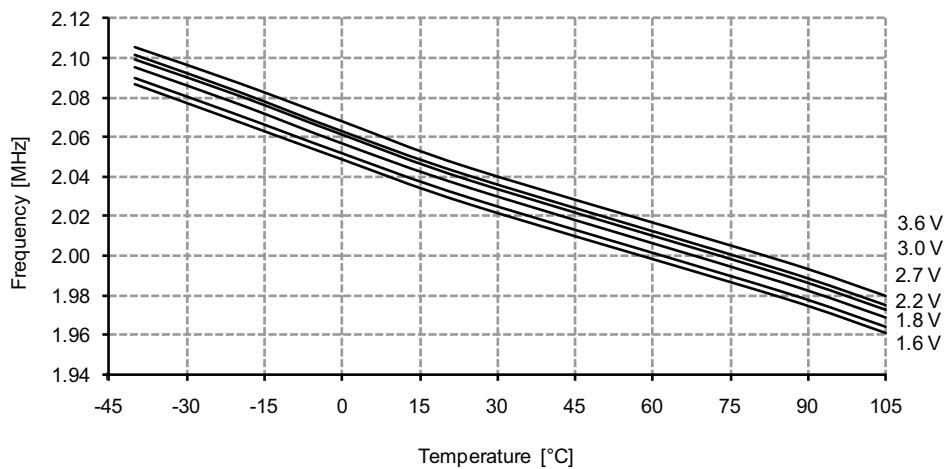
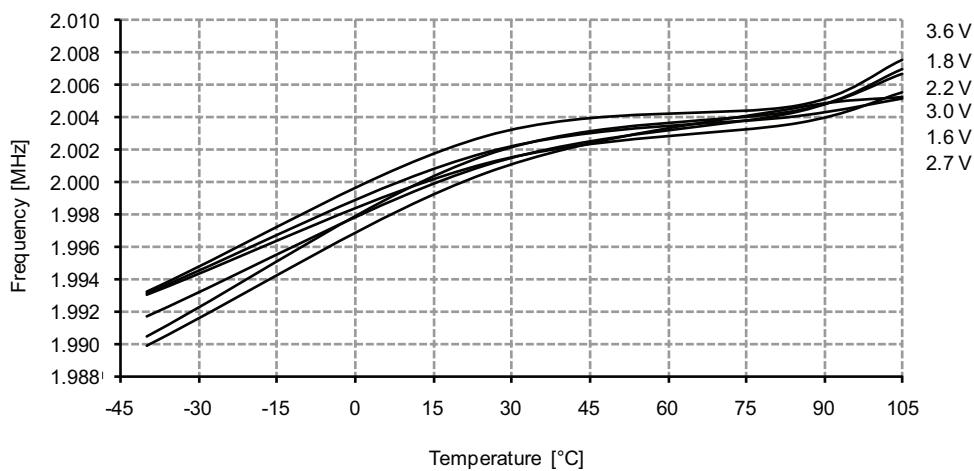


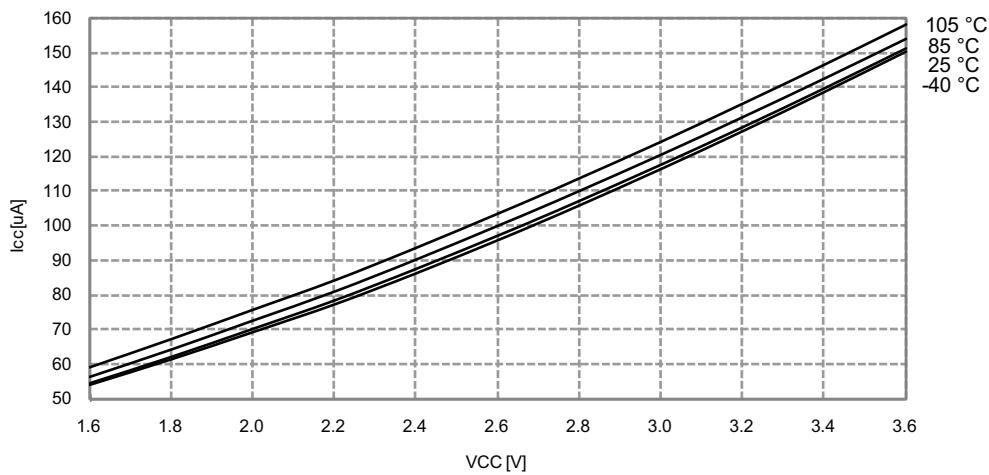
Figure 33-232. 2MHz Internal Oscillator Frequency vs. Temperature

*DFLL enabled, from the 32.768kHz internal oscillator*



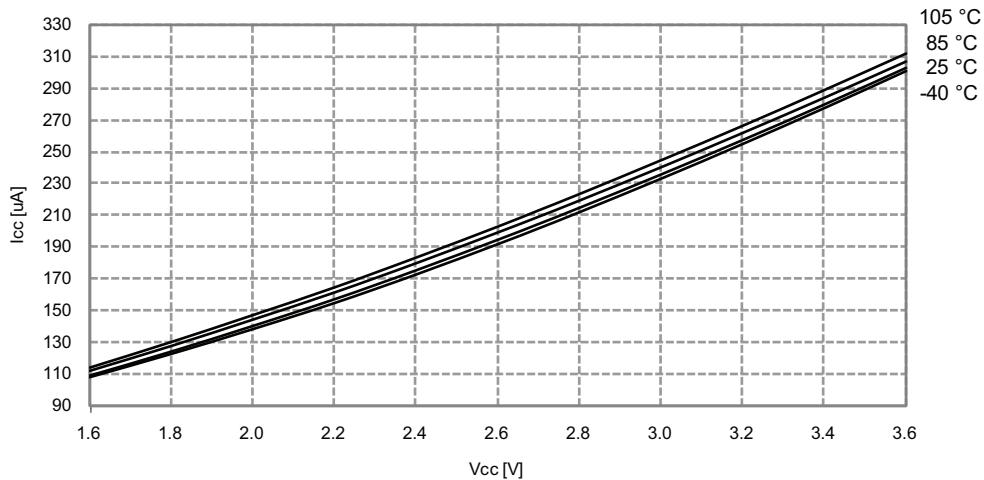
**Figure 33-253. Idle Mode Supply Current vs. V<sub>CC</sub>**

*f<sub>SYS</sub> = 1MHz external clock*



**Figure 33-254. Idle Mode Supply Current vs. V<sub>CC</sub>**

*f<sub>SYS</sub> = 2MHz internal oscillator*



### 33.4.2 I/O Pin Characteristics

#### 33.4.2.1 Pull-up

Figure 33-263. I/O Pin Pull-up Resistor Current vs. Input Voltage

$V_{CC} = 1.8V$

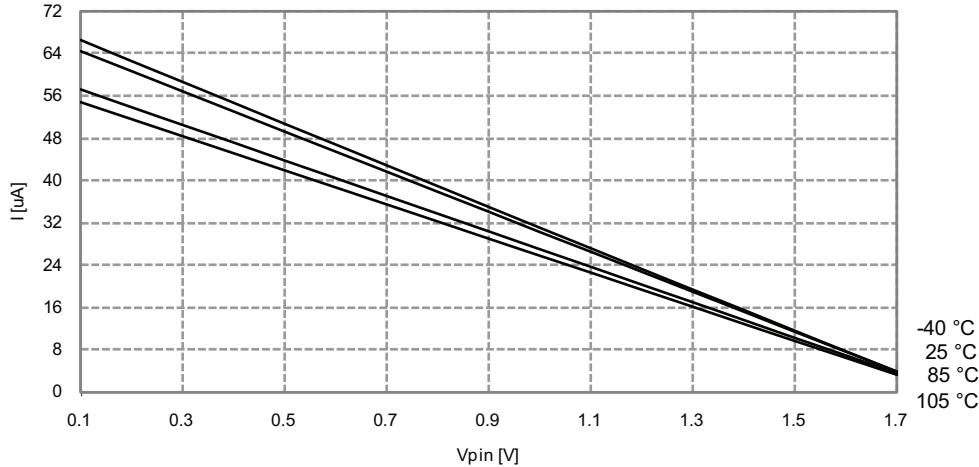
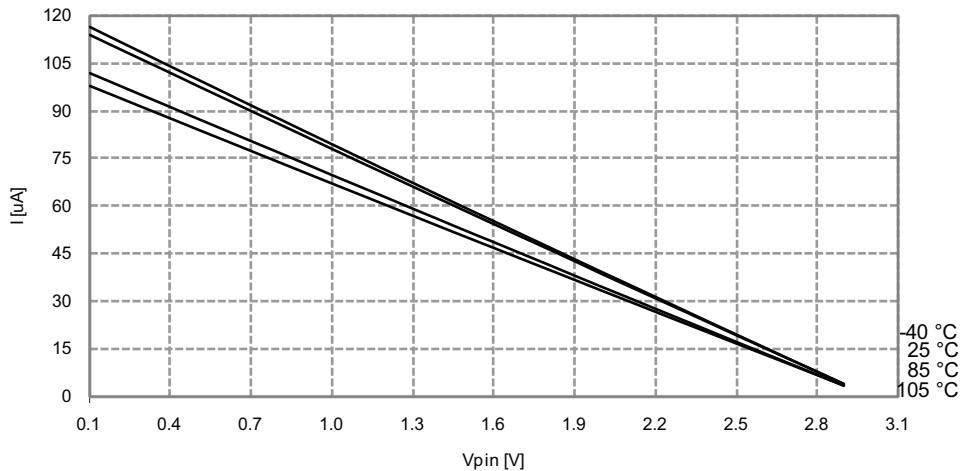


Figure 33-264. I/O Pin Pull-up Resistor Current vs. Input Voltage

$V_{CC} = 3.0V$



### 33.4.10.3 2MHz Internal Oscillator

Figure 33-315. 2MHz Internal Oscillator Frequency vs. Temperature

*DFLL disabled*

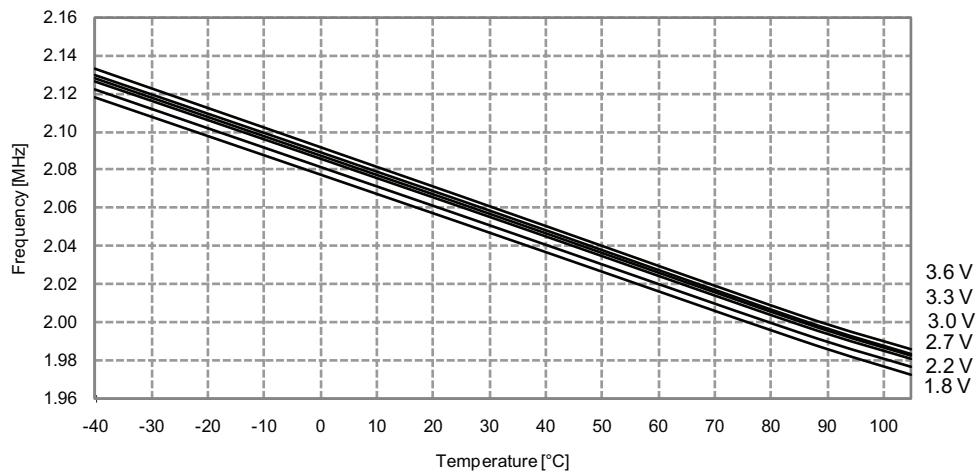


Figure 33-316. 2MHz Internal Oscillator Frequency vs. Temperature

*DFLL enabled, from the 32.768kHz internal oscillator*

