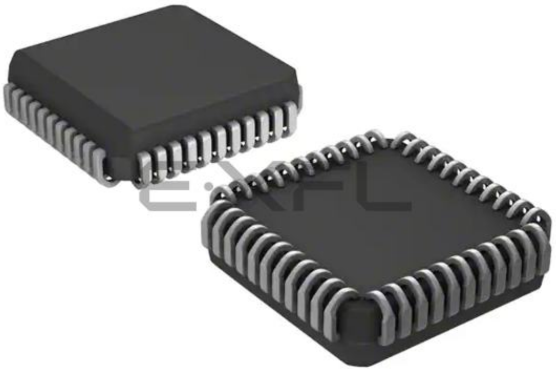

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	31
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f1601vn020sc00tr

Use of All Uppercase Letters

The use of all uppercase letters designates the names of states and commands.

- Example 1: The bus is considered BUSY after the Start condition.
- Example 2: A START command triggers the processing of the initialization sequence.

Bit Numbering

Bits are numbered from *0* to *n–1* where *n* indicates the total number of bits. For example, the 8 bits of a register are numbered from 0 to 7.

Safeguards

It is important that all users understand the following safety terms, which are defined here.

Caution: Indicates a procedure or file may become corrupted if the user does not follow directions.

Trademarks

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External Pin Reset

The RESET pin has a Schmitt-triggered input and an internal pull-up. Once the RESET pin is asserted, the device progresses through the Short Reset sequence. While the RESET input pin is asserted Low, the Z8F640x family device continues to be held in the Reset state. If the RESET pin is held Low beyond the Short Reset time-out, the device exits the Reset state immediately following RESET pin deassertion. Following a Short Reset initiated by the external RESET pin, the EXT status bit in the Watch-Dog Timer Control (WDTCTL) register is set to 1.

Stop Mode Recovery

Stop mode is entered by execution of a STOP instruction by the eZ8 CPU. Refer to the **Low-Power Modes** chapter for detailed Stop mode information. During Stop Mode Recovery, the Z8F640x family device is held in reset for 514 cycles of the Watch-Dog Timer oscillator followed by 16 cycles of the system clock (crystal oscillator). Stop Mode Recovery does not affect any values in the Register File, including the Stack Pointer, Register Pointer, Flags and general-purpose RAM.

The eZ8 CPU fetches the Reset vector at Program Memory addresses 0002H and 0003H and loads that value into the Program Counter. Program execution begins at the Reset vector address. Following Stop Mode Recovery, the STOP bit in the Watch-Dog Timer Control Register is set to 1. Table 9 lists the Stop Mode Recovery sources and resulting actions. The text following provides more detailed information on each of the Stop Mode Recovery sources.

Table 9. Stop Mode Recovery Sources and Resulting Action

Operating Mode	Stop Mode Recovery Source	Action
Stop mode	Watch-Dog Timer time-out when configured for Reset	Stop Mode Recovery
	Watch-Dog Timer time-out when configured for interrupt	Stop Mode Recovery followed by interrupt (if interrupts are enabled)
	Data transition on any GPIO Port pin enabled as a Stop Mode Recovery source	Stop Mode Recovery

Stop Mode Recovery Using Watch-Dog Timer Time-Out

If the Watch-Dog Timer times out during Stop mode, the Z8F640x family device undergoes a STOP Mode Recovery sequence. In the Watch-Dog Timer Control register, the WDT and STOP bits are set to 1. If the Watch-Dog Timer is configured to generate an interrupt upon time-out and the device is configured to respond to interrupts, the Z8F640x family device services the Watch-Dog Timer interrupt request following the normal Stop Mode Recovery sequence.

Interrupt Request 2 Register

The Interrupt Request 2 (IRQ2) register (Table 25) stores interrupt requests for both vectored and polled interrupts. When a request is presented to the interrupt controller, the corresponding bit in the IRQ2 register becomes 1. If interrupts are globally enabled (vectored interrupts), the interrupt controller passes an interrupt request to the eZ8 CPU. If interrupts are globally disabled (polled interrupts), the eZ8 CPU can read the Interrupt Request 1 register to determine if any interrupt requests are pending.

Table 25. Interrupt Request 2 Register (IRQ2)

BITS	7	6	5	4	3	2	1	0
FIELD	T3I	U1RXI	U1TXI	DMAI	PC3I	PC2I	PC1I	PC0I
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC6H							

T3I—Timer 3 Interrupt Request
0 = No interrupt request is pending for Timer 3.
1 = An interrupt request from Timer 3 is awaiting service.

U1RXI—UART 1 Receive Interrupt Request
0 = No interrupt request is pending for the UART1 receiver.
1 = An interrupt request from UART1 receiver is awaiting service.

U1TXI—UART 1 Transmit Interrupt Request
0 = No interrupt request is pending for the UART 1 transmitter.
1 = An interrupt request from the UART 1 transmitter is awaiting service.

DMAI—DMA Interrupt Request
0 = No interrupt request is pending for the DMA.
1 = An interrupt request from the DMA is awaiting service.

PC*x*I—Port C Pin *x* Interrupt Request
0 = No interrupt request is pending for GPIO Port C pin *x*.
1 = An interrupt request from GPIO Port C pin *x* is awaiting service.

where *x* indicates the specific GPIO Port C pin number (0 through 3).

- Disable the timer
- Configure the timer for PWM mode.
- Set the prescale value.
- Set the initial logic level (High or Low) and PWM High/Low transition for the Timer Output alternate function.

2. Write to the Timer High and Low Byte registers to set the starting count value (typically `0001H`). This only affects the first pass in PWM mode. After the first timer reset in PWM mode, counting always begins at the reset value of `0001H`.
3. Write to the PWM High and Low Byte registers to set the PWM value.
4. Write to the Timer Reload High and Low Byte registers to set the Reload value (PWM period). The Reload value must be greater than the PWM value.
5. If desired, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
6. Configure the associated GPIO port pin for the Timer Output alternate function.
7. Write to the Timer Control register to enable the timer and initiate counting.

The PWM period is given by the following equation:

$$\textbf{PWM Period (s)} = \frac{\textbf{Reload Value} \times \textbf{Prescale}}{\textbf{System Clock Frequency (Hz)}}$$

If an initial starting value other than `0001H` is loaded into the Timer High and Low Byte registers, the One-Shot mode equation must be used to determine the first PWM time-out period.

If `TPOL` is set to 0, the ratio of the PWM output High time to the total period is given by:

$$\textbf{PWM Output High Time Ratio (\%)} = \frac{\textbf{Reload Value} - \textbf{PWM Value}}{\textbf{Reload Value}} \times 100$$

If `TPOL` is set to 1, the ratio of the PWM output High time to the total period is given by:

$$\textbf{PWM Output High Time Ratio (\%)} = \frac{\textbf{PWM Value}}{\textbf{Reload Value}} \times 100$$

Capture Mode

In Capture mode, the current timer count value is recorded when the desired external Timer Input transition occurs. The Capture count value is written to the Timer PWM High and Low Byte Registers. The timer input is the system clock. The `TPOL` bit in the Timer Control register determines if the Capture occurs on a rising edge or a falling edge of the

Timer 0-3 Control Registers

The Timer 0-3 Control (TxCTL) registers enable/disable the timers, set the prescaler value, and determine the timer operating mode.

Table 44. Timer 0-3 Control Register (TxCTL)

BITS	7	6	5	4	3	2	1	0
FIELD	TEN	TPOL	PRES			TMODE		
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F07H, F0FH, F17H, F1FH							

TEN—Timer Enable
0 = Timer is disabled.
1 = Timer enabled to count.

TPOL—Timer Input/Output Polarity
Operation of this bit is a function of the current operating mode of the timer.

One-Shot mode
When the timer is disabled, the Timer Output signal is set to the value of this bit. When the timer is enabled, the Timer Output signal is complemented upon timer Reload.

Continuous mode
When the timer is disabled, the Timer Output signal is set to the value of this bit. When the timer is enabled, the Timer Output signal is complemented upon timer Reload.

Counter mode
When the timer is disabled, the Timer Output signal is set to the value of this bit. When the timer is enabled, the Timer Output signal is complemented upon timer Reload.

PWM mode
0 = Timer Output is forced Low (0) when the timer is disabled. When enabled, the Timer Output is forced High (1) upon PWM count match and forced Low (0) upon Reload.
1 = Timer Output is forced High (1) when the timer is disabled. When enabled, the Timer Output is forced Low (0) upon PWM count match and forced High (1) upon Reload.

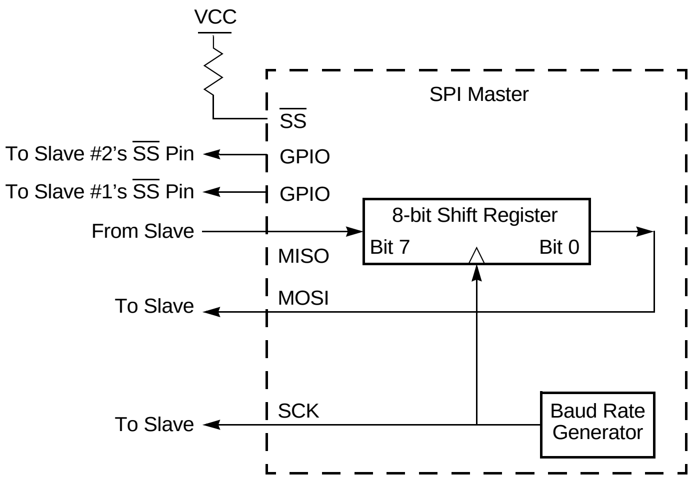


Figure 75. SPI Configured as a Master in a Single Master, Multiple Slave System

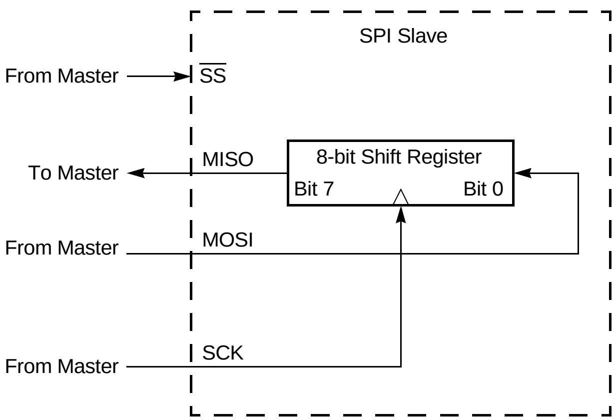


Figure 76. SPI Configured as a Slave

Operation

The SPI is a full-duplex, synchronous, character-oriented channel that supports a four-wire interface (serial clock, transmit, receive and Slave select). The SPI block consists of trans-

Flash Memory

Overview

The Z8F640x family features up to 64KB (65,536 bytes) of non-volatile Flash memory with read/write/erase capability. The Flash Memory can be programmed and erased in-circuit by either user code or through the On-Chip Debugger.

The Flash memory array is arranged in pages with 512 bytes per page. The 512-byte page is the minimum Flash block size that can be erased. Each page is divided into 8 rows of 64 bytes. The Flash memory also contains a High Sector that can be enabled for writes and erase separately from the rest of the Flash array. The first 2 bytes of the Flash Program memory are used as Option Bits. Refer to the **Option Bits** chapter for more information on their operation.

Table 83 describes the Flash memory configuration for each device in the Z8F640x family. Figure 84 illustrates the Flash memory arrangement.

Table 83. Z8F640x family Flash Memory Configurations

Part Number	Flash Size KB (Bytes)	Flash Pages	Program Memory Addresses	Flash High Sector Size KB (Bytes)	High Sector Addresses
Z8F160x	16 (16,384)	32	0000H - 3FFFH	1 (1024)	3C00H - 3FFFH
Z8F240x	24 (24,576)	48	0000H - 5FFFH	2 (2048)	5800H - 5FFFH
Z8F320x	32 (32,768)	64	0000H - 7FFFH	2 (2048)	7800H - 7FFFH
Z8F480x	48 (49,152)	96	0000H - BFFFH	4 (4096)	B000H - BFFFH
Z8F640x	64 (65,536)	128	0000H - FFFFH	8 (8192)	E000H - FFFFH

Flash Control Register Definitions

Flash Control Register

The Flash Controller must be unlocked via the Flash Control register before programming or erasing the Flash memory. Writing the sequence `73H 8CH`, sequentially, to the Flash Control register unlocks the Flash Controller. When the Flash Controller is unlocked, writing to the Flash Control register can initiate either Page Erase or Mass Erase of the Flash memory. Writing an invalid value or an invalid sequence returns the Flash Controller to its locked state. The Write-only Flash Control Register shares its Register File address with the Read-only Flash Status Register.

Table 85. Flash Control Register (FCTL)

BITS	7	6	5	4	3	2	1	0
FIELD	FCMD							
RESET	0	0	0	0	0	0	0	0
R/W	W	W	W	W	W	W	W	W
ADDR	FF8H							

FCMD—Flash Command
73H = First unlock command.
8CH = Second unlock command.
95H = Page erase command (must be third command in sequence to initiate Page Erase).
63H = Mass erase command (must be third command in sequence to initiate Mass Erase).

Flash Page Select Register

The Flash Page Select register is used to select one of the 128 available Flash memory pages to be erased in a Page Erase operation. Each Flash Page contains 512 bytes of Flash memory. During a Page Erase operation, all Flash memory having addresses with the most significant 7-bits given by `FPS[6:0]` are erased (all bytes written to `FFH`).

Table 87. Flash Page Select Register (FPS)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved	PAGE						
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FF9H							

Reserved
This bit is reserved and must be 0.

PAGE—Page Select
This 7-bit field identifies the Flash memory page for Page Erase operation.
Program Memory Address[15:9] = PAGE[6:0]

On-Chip Debugger

Overview

The Z8F640x family devices have an integrated On-Chip Debugger (OCD) that provides advanced debugging features including:

- Reading and writing of the Register File
- Reading and writing of Program and Data Memory
- Setting of Breakpoints and Watchpoints
- Execution of eZ8 CPU instructions.

Architecture

The On-Chip Debugger consists of four primary functional blocks: transmitter, receiver, auto-baud generator, and debug controller. Figure 86 illustrates the architecture of the On-Chip Debugger

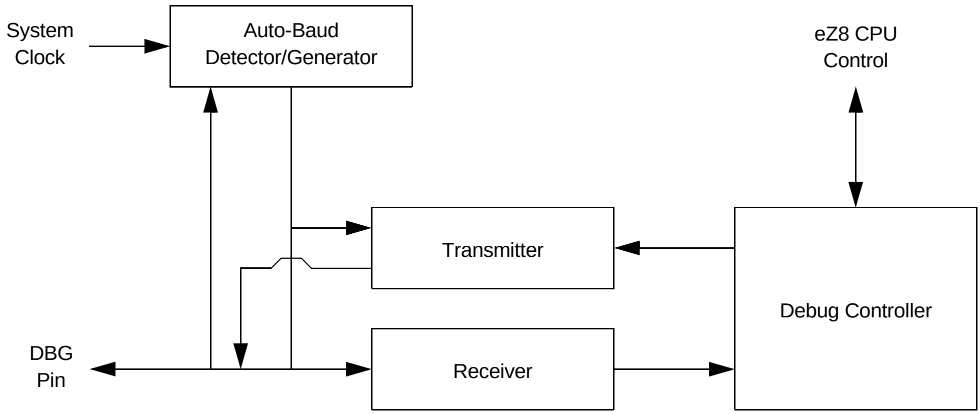


Figure 86. On-Chip Debugger Block Diagram

Table 100. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
68-Pin PLCC Maximum Ratings at 70^0C to 105^0C				
Total power dissipation		500	mW	
Maximum current into V_{DD} or out of V_{SS}		140	mA	
64-Pin LQFP Maximum Ratings at -40°C to 70°C				
Total power dissipation		1000	mW	
Maximum current into V_{DD} or out of V_{SS}		275	mA	
64-Pin LQFP Maximum Ratings at 70^0C to 105^0C				
Total power dissipation		540	mW	
Maximum current into V_{DD} or out of V_{SS}		150	mA	
44-Pin PLCC Maximum Ratings at -40°C to 70°C				
Total power dissipation		750	mW	
Maximum current into V_{DD} or out of V_{SS}		200	mA	
44-Pin PLCC Maximum Ratings at 70^0C to 105^0C				
Total power dissipation		295	mW	
Maximum current into V_{DD} or out of V_{SS}		83	mA	
44-pin LQFP Maximum Ratings at -40°C to 70°C				
Total power dissipation		750	mW	
Maximum current into V_{DD} or out of V_{SS}		200	mA	
44-pin LQFP Maximum Ratings at 70^0C to 105^0C				
Total power dissipation		410	mW	
Maximum current into V_{DD} or out of V_{SS}		114	mA	
40-Pin PDIP Maximum Ratings at -40°C to 70°C				
Total power dissipation		1000	mW	
Maximum current into V_{DD} or out of V_{SS}		275	mA	
40-Pin PDIP Maximum Ratings at 70°C to 105°C				
Total power dissipation		540	mW	
Maximum current into V_{DD} or out of V_{SS}		150	mA	

Notes:
1. This voltage applies to all pins except the following: V_{DD}, AV_{DD}, pins supporting analog input (Port B and Port H), $\overline{RESET}$, and where noted otherwise.

DC Characteristics

Table 101 lists the DC characteristics of the Z8F640x family devices. All voltages are referenced to V_{SS}, the primary system ground.

Table 101. DC Characteristics

Symbol	Parameter	$T_A = -40^0C$ to 105^0C			Units	Conditions
		Minimum	Typical	Maximum		
V_{DD}	Supply Voltage	3.0	–	3.6	V	
V_{IL1}	Low Level Input Voltage	-0.3	–	$0.3*V_{DD}$	V	For all input pins except $\overline{\text{RESET}}$, DBG, and XIN.
V_{IL2}	Low Level Input Voltage	-0.3	–	$0.2*V_{DD}$	V	For $\overline{\text{RESET}}$, DBG, and XIN.
V_{IH1}	High Level Input Voltage	$0.7*V_{DD}$	–	5.5	V	Port A, C, D, E, F, and G pins.
V_{IH2}	High Level Input Voltage	$0.7*V_{DD}$	–	$V_{DD}+0.3$	V	Port B and H pins.
V_{IH3}	High Level Input Voltage	$0.8*V_{DD}$	–	$V_{DD}+0.3$	V	$\overline{\text{RESET}}$, DBG, and XIN pins.
V_{OL1}	Low Level Output Voltage	–	–	0.4	V	V_{DD} = 3.0V; I_{OL} = 2mA High Output Drive disabled.
V_{OH1}	High Level Output Voltage	2.4	–	–	V	V_{DD} = 3.0V; I_{OH} = -2mA High Output Drive disabled.
V_{OL2}	Low Level Output Voltage	–	–	0.6	V	V_{DD} = 3.3V; I_{OL} = 20mA High Output Drive enabled. $T_A = -40^0C$ to $+70^0C$
V_{OL3}	Low Level Output Voltage	–	–	0.6	V	V_{DD} = 3.3V; I_{OL} = 15mA High Output Drive enabled. $T_A = 70^0C$ to $+105^0C$
V_{OH2}	High Level Output Voltage	2.4	–	–	V	V_{DD} = 3.3V; I_{OH} = -20mA High Output Drive enabled. $T_A = -40^0C$ to $+70^0C$
V_{OH3}	High Level Output Voltage	2.4	–	–	V	V_{DD} = 3.3V; I_{OH} = -15mA High Output Drive enabled. $T_A = 70^0C$ to $+105^0C$
I_{IL}	Input Leakage Current	-5	–	+5	µA	V_{DD} = 3.6V; V_{IN} = VDD or VSS[1]
I_{TL}	Tri-State Leakage Current	-5	–	+5	µA	V_{DD} = 3.6V
C_{PAD}	GPIO Port Pad Capacitance	–	8.0[2]	–	pF	
C_{XIN}	XIN Pad Capacitance	–	8.0[2]	–	pF	
C_{XOUT}	XOUT Pad Capacitance	–	9.5[2]	–	pF	

General Purpose I/O Port Output Timing

Figure 94 and Table 108 provide timing information for GPIO Port pins.

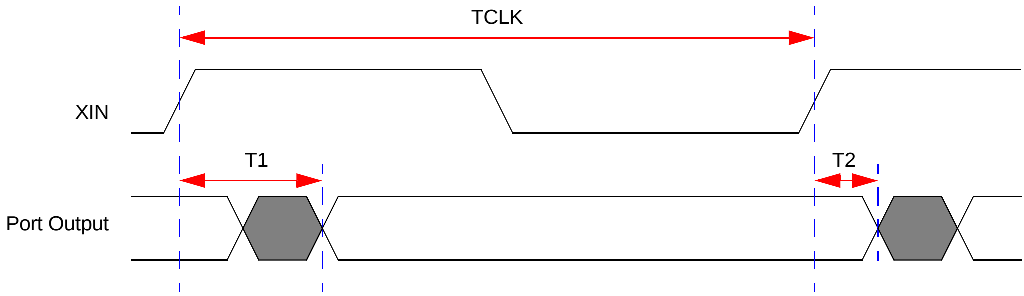


Figure 94. GPIO Port Output Timing

Table 108. GPIO Port Output Timing

		Delay (ns)	
Parameter	**Abbreviation**	**Minimum**	**Maximum**
T_1	XIN Rise to Port Output Valid Delay	–	15
T_2	XIN Rise to Port Output Hold Time	2	–

On-Chip Debugger Timing

Figure 95 and Table 109 provide timing information for DBG pins. The timing specifications presume a rise and fall time on DBG of less than 4µs.

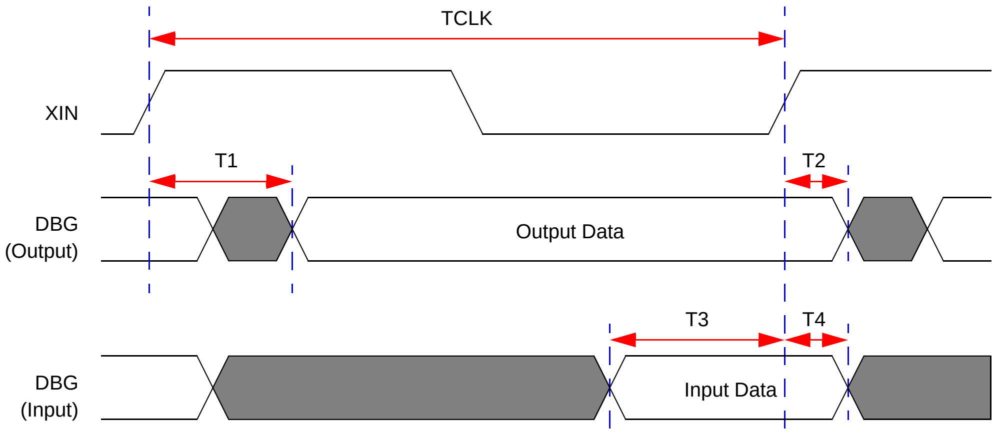


Figure 95. On-Chip Debugger Timing

Table 109. On-Chip Debugger Timing

		Delay (ns)	
Parameter	**Abbreviation**	**Minimum**	**Maximum**
DBG			
T_1	XIN Rise to DBG Valid Delay	–	15
T_2	XIN Rise to DBG Output Hold Time	2	–
T_3	DBG to XIN Rise Input Setup Time	10	–
T_4	DBG to XIN Rise Input Hold Time	5	–
	DBG frequency		System Clock / 4

I²C Timing

Figure 98 and Table 112 provide timing information for I2C pins.

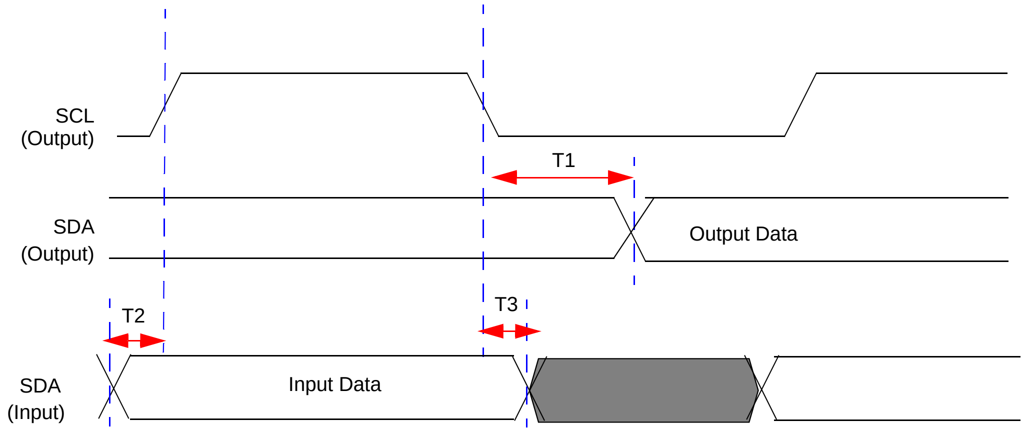


Figure 98. I²C Timing

Table 112. I²C Timing

		Delay (ns)	
Parameter	**Abbreviation**	**Minimum**	**Maximum**
T_1	SCL Fall to SDA output delay	SCL period/4	
T_2	SDA Input to SCL rising edge Setup Time	0	
T_3	SDA Input to SCL falling edge Hold Time	0	

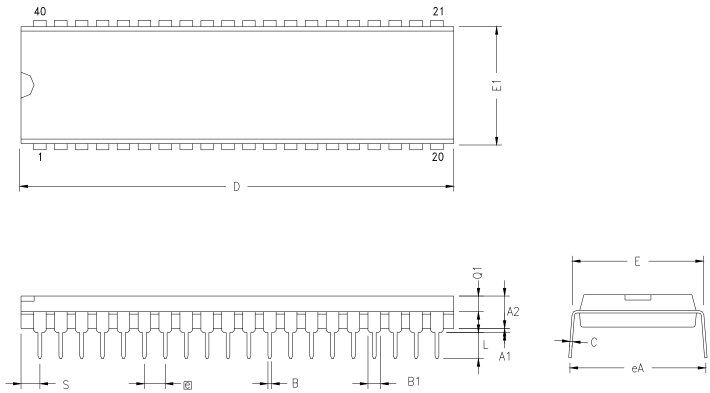
Table 126. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode dst	Address Mode src	Opcode(s) (Hex)	C	Z	S	V	D	H	Fetch Cycles	Instr. Cycles
BTJZ bit, src, dst	if src[bit] = 0 PC ← PC + X		r	F6	-	-	-	-	-	-	3	3
			Ir	F7							3	4
CALL dst	SP ← SP -2 @SP ← PC PC ← dst	IRR		D4	-	-	-	-	-	-	2	6
		DA		D6							3	3
CCF	C ← ~C			EF	*	-	-	-	-	-	1	2
CLR dst	dst ← 00H	R		B0	-	-	-	-	-	-	2	2
		IR		B1							2	3
COM dst	dst ← ~dst	R		60	-	*	*	0	-	-	2	2
		IR		61							2	3
CP dst, src	dst - src	r	r	A2	*	*	*	*	-	-	2	3
		r	Ir	A3							2	4
		R	R	A4							3	3
		R	IR	A5							3	4
		R	IM	A6							3	3
		IR	IM	A7							3	4
CPC dst, src	dst - src - C	r	r	1F A2	*	*	*	*	-	-	3	3
		r	Ir	1F A3							3	4
		R	R	1F A4							4	3
		R	IR	1F A5							4	4
		R	IM	1F A6							4	3
		IR	IM	1F A7							4	4
CPCX dst, src	dst - src - C	ER	ER	1F A8	*	*	*	*	-	-	5	3
		ER	IM	1F A9							5	3
CPX dst, src	dst - src	ER	ER	A8	*	*	*	*	-	-	4	3
		ER	IM	A9							4	3

Flags Notation: * = Value is a function of the result of the operation.
- = Unaffected
X = Undefined
0 = Reset to 0
1 = Set to 1

Packaging

Figure 103 illustrates the 40-pin PDIP (plastic dual-inline package) available for the Z8F1601, Z8F2401, Z8F3201, Z8F4801, and Z8F6401 devices.



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.51	1.02	.020	.040
A2	3.18	3.94	.125	.155
B	0.38	0.53	.015	.021
B1	1.02	1.52	.040	.060
C	0.23	0.38	.009	.015
D	52.07	52.58	2.050	2.070
E	15.24	15.75	.600	.620
E1	13.59	14.22	.535	.560
e	2.54 TYP		.100 TYP	
eA	15.49	16.76	.610	.660
L	3.05	3.81	.120	.150
Q1	1.40	1.91	.055	.075
S	1.52	2.29	.060	.090

CONTROLLING DIMENSIONS : INCH

Figure 103. 40-Lead Plastic Dual-Inline Package (PDIP)

Ordering Information

Table 128. Ordering Information

Part	Flash KB (Bytes)	RAM KB (Bytes)	Max. Speed (MHz)	Temp (^{0}C)	Voltage (V)	Package	Part Number
Z8 Encore!® with 16KB Flash, Standard Temperature							
Z8 Encore!®	16 (16,384)	2 (2048)	20	0 to +70	3.0 - 3.6	PDIP-40	Z8F1601PM020SC
Z8 Encore!®	16 (16,384)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-44	Z8F1601AN020SC
Z8 Encore!®	16 (16,384)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-44	Z8F1601VN020SC
Z8 Encore!®	16 (16,384)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-64	Z8F1602AR020SC
Z8 Encore!®	16 (16,384)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-68	Z8F1602VS020SC
Z8 Encore!® with 24KB Flash, Standard Temperature							
Z8 Encore!®	24 (24,576)	2 (2048)	20	0 to +70	3.0 - 3.6	PDIP-40	Z8F2401PM020SC
Z8 Encore!®	24 (24,576)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-44	Z8F2401AN020SC
Z8 Encore!®	24 (24,576)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-44	Z8F2401VN020SC
Z8 Encore!®	24 (24,576)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-64	Z8F2402AR020SC
Z8 Encore!®	24 (24,576)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-68	Z8F2402VS020SC
Z8 Encore!® with 32KB Flash, Standard Temperature							
Z8 Encore!®	32 (32,768)	2 (2048)	20	0 to +70	3.0 - 3.6	PDIP-40	Z8F3201PM020SC
Z8 Encore!®	32 (32,768)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-44	Z8F3201AN020SC
Z8 Encore!®	32 (32,768)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-44	Z8F3201VN020SC
Z8 Encore!®	32 (32,768)	2 (2048)	20	0 to +70	3.0 - 3.6	LQFP-64	Z8F3202AR020SC
Z8 Encore!®	32 (32,768)	2 (2048)	20	0 to +70	3.0 - 3.6	PLCC-68	Z8F3202VS020SC
Z8 Encore!®with 48KB Flash, Standard Temperature							
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	PDIP-40	Z8F4801PM020SC
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	LQFP-44	Z8F4801AN020SC
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	PLCC-44	Z8F4801VN020SC
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	LQFP-64	Z8F4802AR020SC
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	PLCC-68	Z8F4802VS020SC
Z8 Encore!®	48 (49,152)	4 (4096)	20	0 to +70	3.0 - 3.6	QFP-80	Z8F4803FT020SC