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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	EC000
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	8MHz
Co-Processors/DSP	-
RAM Controllers	-
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	-
SATA	-
USB	-
Voltage - I/O	5.0V
Operating Temperature	0°C ~ 70°C (TA)
Security Features	-
Package / Case	68-LCC (J-Lead)
Supplier Device Package	68-PLCC (24.21x24.21)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc68hc000ei8r2

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LIST OF ILLUSTRATIONS (Continued)

Table 2-2. Instruction Set Summary (Sheet 3 of 4)

Opcode	Operation	Syntax
MOVE USP	If supervisor state then USP → An or An → USP else TRAP	MOVE USP,An MOVE An,USP
MOVEC	If supervisor state then Rc → Rn or Rn → Rc else TRAP	MOVEC Rc,Rn MOVEC Rn,Rc
MOVEM	Registers → Destination Source → Registers	MOVEM register list,<ea> MOVEM <ea>,register list
MOVEP	Source → Destination	MOVEP Dx,(d,Ay) MOVEP (d,Ay),Dx
MOVEQ	Immediate Data → Destination	MOVEQ # <data>,Dn
MOVES	If supervisor state then Rn → Destination [DFC] or Source [SFC] → Rn else TRAP	MOVES Rn,<ea> MOVES <ea>,Rn
MULS	Source × Destination → Destination	MULS.W <ea>,Dn 16 x 16 → 32
MULU	Source × Destination → Destination	MULU.W <ea>,Dn 16 x 16 → 32
NBCD	0 – (Destination$_{10}$) – X → Destination	NBCD <ea>
NEG	0 – (Destination) → Destination	NEG <ea>
NEGX	0 – (Destination) – X → Destination	NEGX <ea>
NOP	None	NOP
NOT	~Destination → Destination	NOT <ea>
OR	Source V Destination → Destination	OR <ea>,Dn OR Dn,<ea>
ORI	Immediate Data V Destination → Destination	ORI # <data>,<ea>
ORI to CCR	Source V CCR → CCR	ORI # <data>,CCR
ORI to SR	If supervisor state then Source V SR → SR else TRAP	ORI # <data>,SR
PEA	Sp – 4 → SP; <ea> → (SP)	PEA <ea>
RESET	If supervisor state then Assert $\overline{\text{RESET}}$ Line else TRAP	RESET
ROL, ROR	Destination Rotated by <count> → Destination	ROd[1] Rx,Dy ROd[1] # <data>,Dy ROd[1] <ea>
ROXL, ROXR	Destination Rotated with X by <count> → Destination	ROXd[1] Dx,Dy ROXd[1] # <data>,Dy ROXd[1] <ea>
RTD	(SP) → PC; SP + 4 + d → SP	RTD #<displacement>

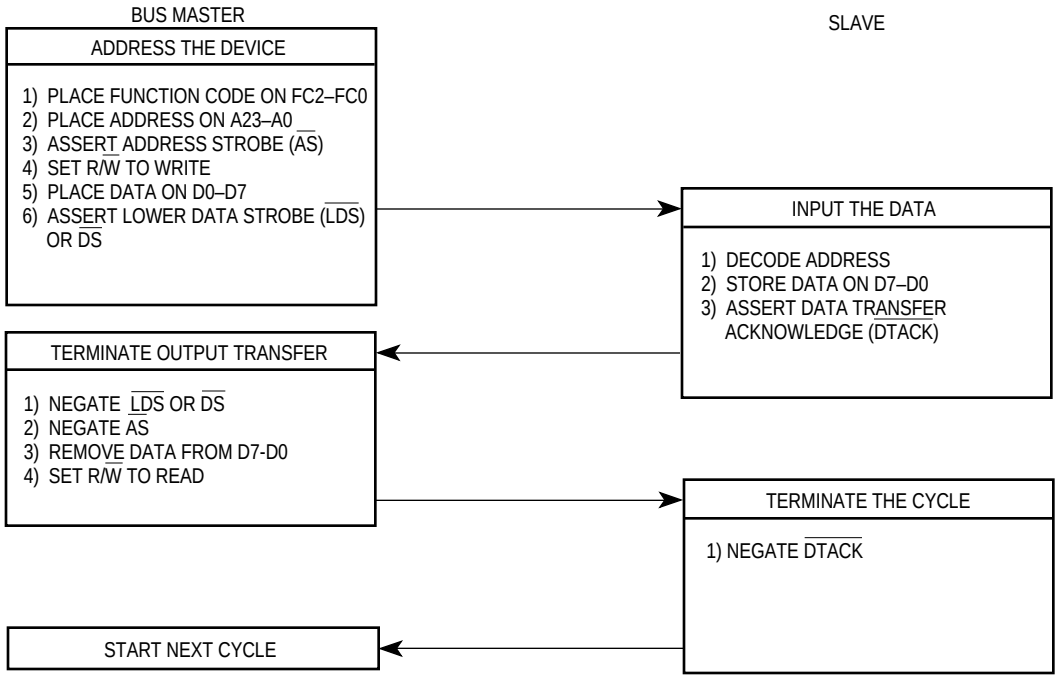


Figure 4-3. Byte Write-Cycle Flowchart

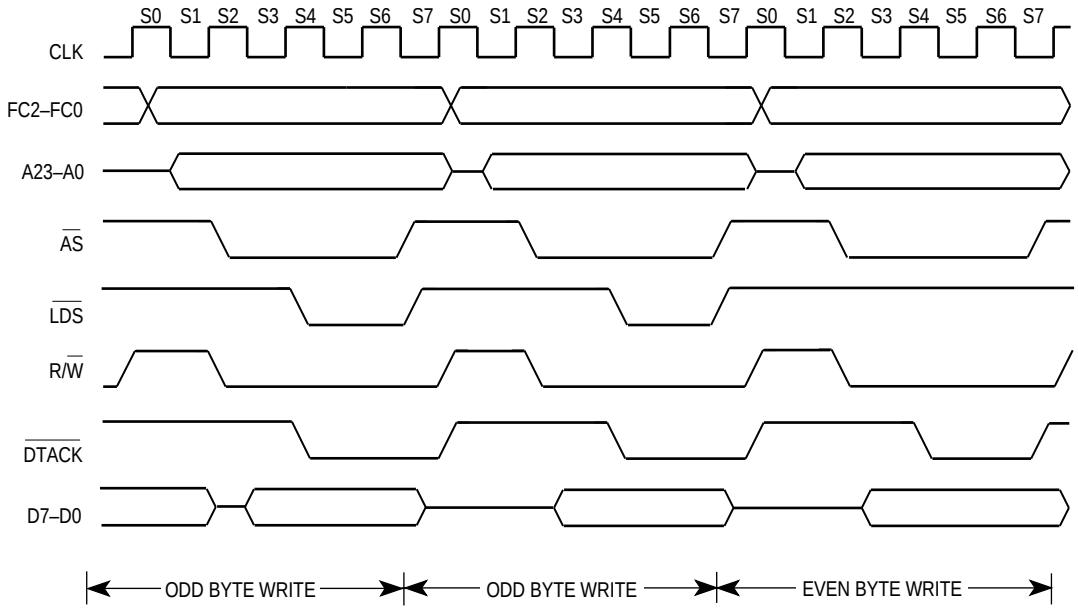


Figure 4-4. Write-Cycle Timing Diagram

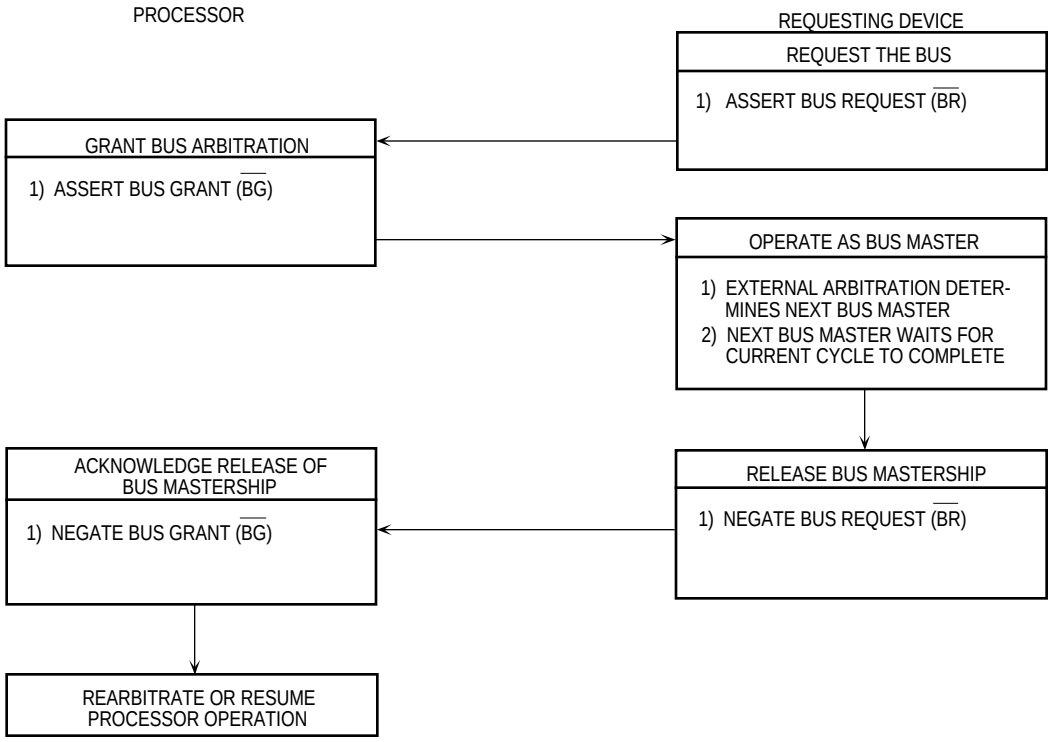


Figure 5-14. 2-Wire Bus Arbitration Cycle Flowchart

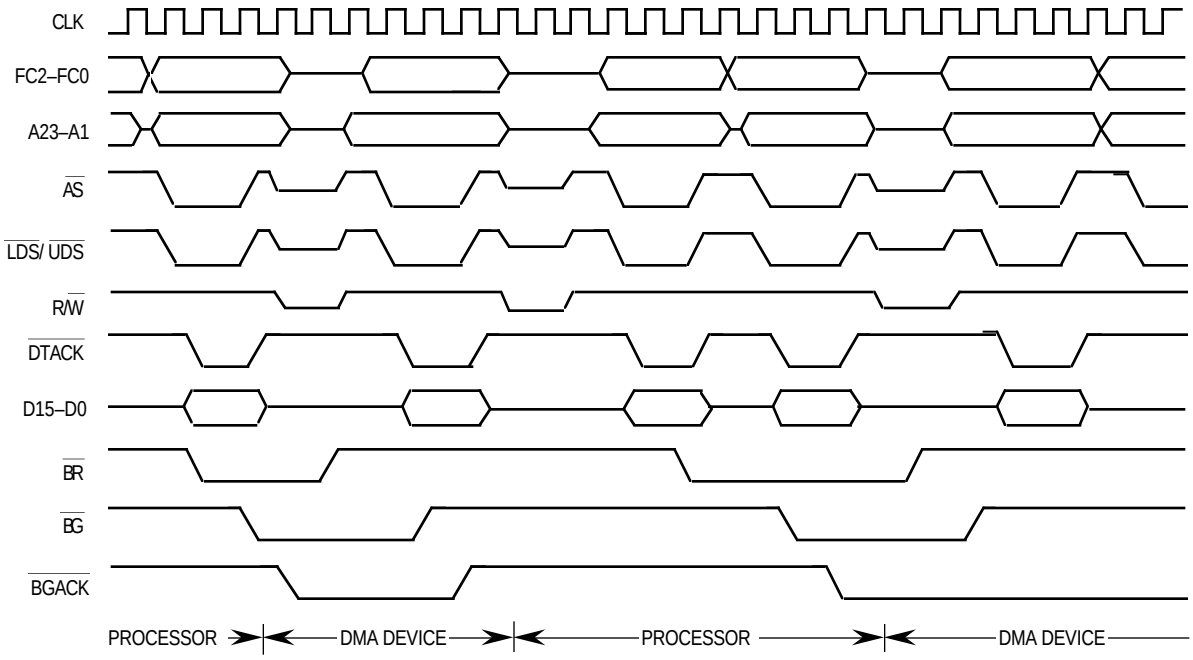


Figure 5-15. 3-Wire Bus Arbitration Timing Diagram (Not Applicable to 48-Pin MC68008 or MC68EC000)

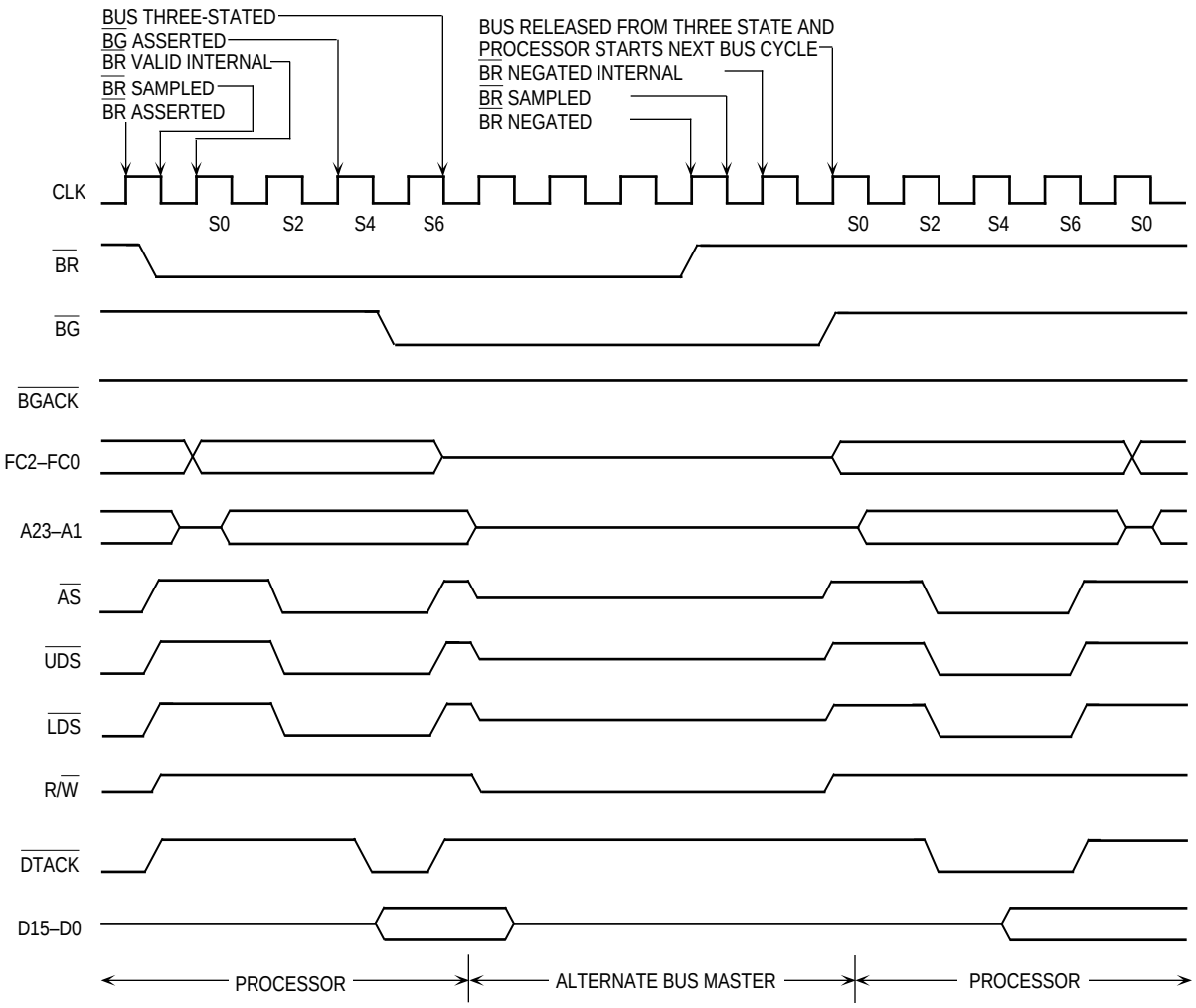


Figure 5-24. 2-Wire Bus Arbitration Timing Diagram—Special Case

5.4. BUS ERROR AND HALT OPERATION

In a bus architecture that requires a handshake from an external device, such as the asynchronous bus used in the M68000 Family, the handshake may not always occur. A bus error input is provided to terminate a bus cycle in error when the expected signal is not asserted. Different systems and different devices within the same system require different maximum-response times. External circuitry can be provided to assert the bus error signal after the appropriate delay following the assertion of address strobe.

In a virtual memory system, the bus error signal can be used to indicate either a page fault or a bus timeout. An external memory management unit asserts bus error when the page that contains the required data is not resident in memory. The processor suspends execution of the current instruction while the page is loaded into memory. The MC68010 pushes enough information on the stack to be able to resume execution of the instruction following return from the bus error exception handler.

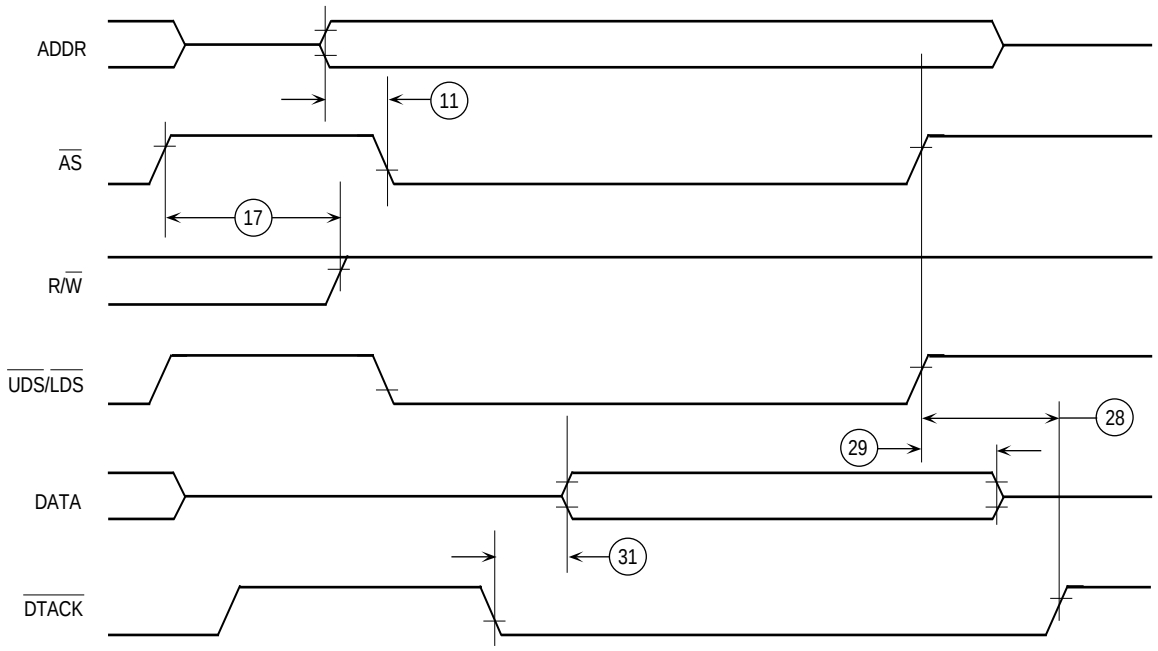


Figure 5-33. Pseudo-Asynchronous Read Cycle

During a write cycle, after the processor asserts $\overline{AS}$ but before driving the data bus, the processor drives R/$\overline{W}$ low. Parameter #55 specifies the minimum time between the transition of R/$\overline{W}$ and the driving of the data bus, which is effectively the maximum turnoff time for any device driving the data bus.

After the processor places valid data on the bus, it asserts the data strobe signal(s). A data setup time, similar to the address setup time previously discussed, can be used to improve performance. Parameter #29 is the minimum time a slave device can accept valid data before recognizing a data strobe. The slave device asserts $\overline{DTACK}$ after it accepts the data. Parameter #25 is the minimum time after negation of the strobes during which the valid data remains on the address bus. Parameter #28 is the maximum time between the negation of the strobes by the processor and the negation of $\overline{DTACK}$ by the slave device. If $\overline{DTACK}$ remains asserted past the time specified by parameter #28, the processor may recognize it as being asserted early in the next bus cycle and may terminate that cycle prematurely. Figure 5-34 shows the important timing specifications for a pseudo-asynchronous write cycle.

is the maximum hold time for a low on R/$\overline{W}$ beyond the initiation of the read cycle.

STATE 1 Entering S1, a low period of the clock, the address of the accessed device is driven externally with an assertion delay defined by parameter #6.

STATE 2 On the rising edge of S2, a high period of the clock, $\overline{AS}$ is asserted. During a read cycle, $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ is also asserted at this time. Parameter #9 defines the assertion delay for these signals. For a write cycle, the R/$\overline{W}$ signal is driven low with a delay defined by parameter #20.

STATE 3 On the falling edge of the clock entering S3, the data bus is driven out of the high-impedance state with the data being written to the accessed device (in a write cycle). Parameter #23 specifies the data assertion delay. In a read cycle, no signal is altered in S3.

STATE 4 Entering the high clock period of S4, $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ is asserted (during a write cycle) on the rising edge of the clock. As in S2 for a read cycle, parameter #9 defines the assertion delay from the rising edge of S4 for $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$. In a read cycle, no signal is altered by the processor during S4.

Until the falling edge of the clock at the end of S4 (beginning of S5), no response from any external device except $\overline{RESET}$ is acknowledged by the processor. If either $\overline{DTACK}$ or $\overline{BERR}$ is asserted before the falling edge of S4 and satisfies the input setup time defined by parameter #47, the processor enters S5 and the bus cycle continues. If either $\overline{DTACK}$ or $\overline{BERR}$ is asserted but without meeting the setup time defined by parameter #47, the processor may recognize the signal and continue the bus cycle; the result is unpredictable. If neither $\overline{DTACK}$ nor $\overline{BERR}$ is asserted before the next rise of clock, the bus cycle remains in S4, and wait states (complete clock cycles) are inserted until one of the bus cycle termination is met.

STATE 5 S5 is a low period of the clock, during which the processor does not alter any signal.

STATE 6 S6 is a high period of the clock, during which data for a read operation is set up relative to the falling edge (entering S7). Parameter #27 defines the minimum period by which the data must precede the falling edge. For a write operation, the processor changes no signal during S6.

STATE 7 On the falling edge of the clock entering S7, the processor latches data and negates $\overline{AS}$ and $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ during a read cycle. The hold time for these strobes from this falling edge is specified by parameter #12. The hold time for data relative to the negation of $\overline{AS}$ and $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ is specified by parameter #29. For a write cycle, only $\overline{AS}$ and $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ are negated; timing parameter #12 also applies.

On the rising edge of the clock, at the end of S7 (which may be the start of S0 for the next bus cycle), the processor places the address bus in the high-impedance state. During a write cycle, the processor also places the data bus in the high-impedance state and drives R/$\overline{W}$ high. External logic circuitry should respond to the negation of the $\overline{AS}$ and $\overline{UDS}$, $\overline{LDS}$, and/or $\overline{DS}$ by negating $\overline{DTACK}$ and/or $\overline{BERR}$. Parameter #28 is the hold time for $\overline{DTACK}$, and parameter #30 is the hold time for $\overline{BERR}$.

Figure 5-35 shows a synchronous read cycle and the important timing parameters that apply. The timing for a synchronous read cycle, including relevant timing parameters, is shown in Figure 5-36.

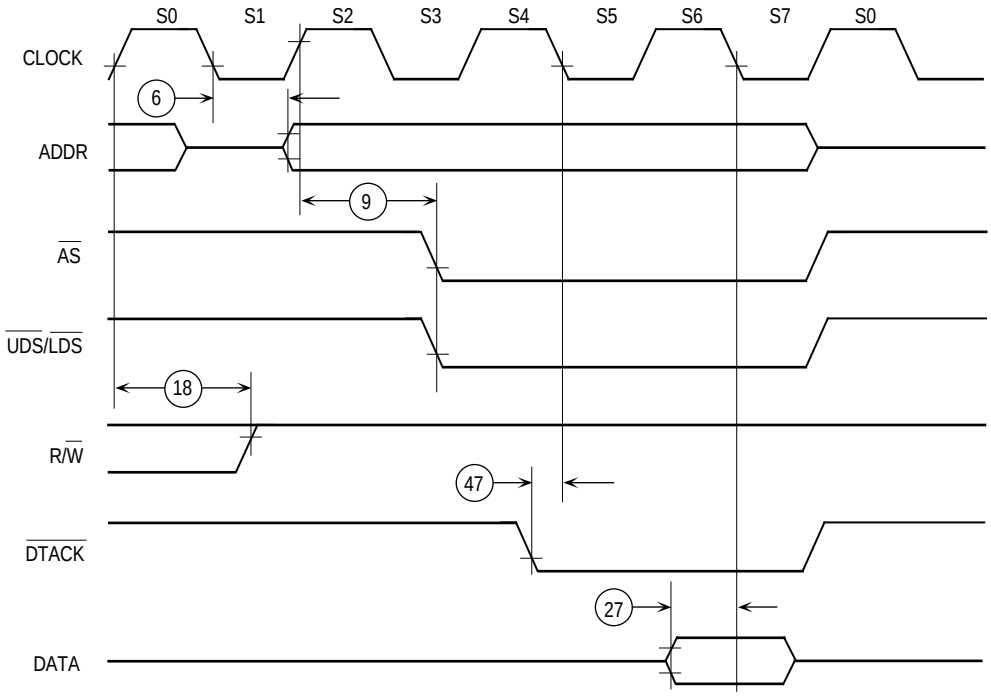


Figure 5-35. Synchronous Read Cycle

SECTION 6
EXCEPTION PROCESSING

This section describes operations of the processor outside the normal processing associated with the execution of instructions. The functions of the bits in the supervisor portion of the status register are described: the supervisor/user bit, the trace enable bit, and the interrupt priority mask. Finally, the sequence of memory references and actions taken by the processor for exception conditions are described in detail.

The processor is always in one of three processing states: normal, exception, or halted. The normal processing state is associated with instruction execution; the memory references are to fetch instructions and operands and to store results. A special case of the normal state is the stopped state, resulting from execution of a STOP instruction. In this state, no further memory references are made.

An additional, special case of the normal state is the loop mode of the MC68010, optionally entered when a test condition, decrement, and branch (DBcc) instruction is executed. In the loop mode, only operand fetches occur. See **Appendix A MC68010 Loop Mode Operation**.

The exception processing state is associated with interrupts, trap instructions, tracing, and other exceptional conditions. The exception may be internally generated by an instruction or by an unusual condition arising during the execution of an instruction. Externally, exception processing can be forced by an interrupt, by a bus error, or by a reset. Exception processing provides an efficient context switch so that the processor can handle unusual conditions.

The halted processing state is an indication of catastrophic hardware failure. For example, if during the exception processing of a bus error another bus error occurs, the processor assumes the system is unusable and halts. Only an external reset can restart a halted processor. Note that a processor in the stopped state is not in the halted state, nor vice versa.

6.1 PRIVILEGE MODES

The processor operates in one of two levels of privilege: the supervisor mode or the user mode. The privilege mode determines which operations are legal. The mode is optionally used by an external memory management device to control and translate accesses. The mode is also used to choose between the supervisor stack pointer (SSP) and the user stack pointer (USP) in instruction references.

Table 6-4. MC68010 Format Codes

Format Code	Stacked Information
0000	Short Format (4 Words)
1000	Long Format (29 Words)
All Others	Unassigned, Reserved

6.2.5 Exception Processing Sequence

In the first step of exception processing, an internal copy is made of the status register. After the copy is made, the S bit of the status register is set, putting the processor into the supervisor mode. Also, the T bit is cleared, which allows the exception handler to execute unhindered by tracing. For the reset and interrupt exceptions, the interrupt priority mask is also updated appropriately.

In the second step, the vector number of the exception is determined. For interrupts, the vector number is obtained by a processor bus cycle classified as an interrupt acknowledge cycle. For all other exceptions, internal logic provides the vector number. This vector number is then used to calculate the address of the exception vector.

The third step, except for the reset exception, is to save the current processor status. (The reset exception does not save the context and skips this step.) The current program counter value and the saved copy of the status register are stacked using the SSP. The stacked program counter value usually points to the next unexecuted instruction. However, for bus error and address error, the value stacked for the program counter is unpredictable and may be incremented from the address of the instruction that caused the error. Group 1 and 2 exceptions use a short format exception stack frame (format = 0000 on the MC68010). Additional information defining the current context is stacked for the bus error and address error exceptions.

The last step is the same for all exceptions. The new program counter value is fetched from the exception vector. The processor then resumes instruction execution. The instruction at the address in the exception vector is fetched, and normal instruction decoding and execution is started.

6.3 PROCESSING OF SPECIFIC EXCEPTIONS

The exceptions are classified according to their sources, and each type is processed differently. The following paragraphs describe in detail the types of exceptions and the processing of each type.

6.3.1 Reset

The reset exception corresponds to the highest exception level. The processing of the reset exception is performed for system initiation and recovery from catastrophic failure. Any processing in progress at the time of the reset is aborted and cannot be recovered. The processor is forced into the supervisor state, and the trace state is forced off. The

6.4 RETURN FROM EXCEPTION (MC68010)

In addition to returning from any exception handler routine on the MC68010, the RTE instruction resumes the execution of a suspended instruction by returning to the normal processing state after restoring all of the temporary register and control information stored during a bus error. For the RTE instruction to execute properly, the stack must contain valid and accessible data. The RTE instruction checks for data validity in two ways. First, the format/offset word is checked for a valid stack format code. Second, if the format code indicates the long stack format, the validity of the long stack data is checked as it is loaded into the processor. In addition, the data is checked for accessibility when the processor starts reading the long data. Because of these checks, the RTE instruction executes as follows:

1. Determine the stack format. This step is the same for any stack format and consists of reading the status register, program counter, and format/offset word. If the format code indicates a short stack format, execution continues at the new program counter address. If the format code is not an MC68010-defined stack format code, exception processing starts for a format error.
2. Determine data validity. For a long-stack format, the MC68010 begins to read the remaining stack data, checking for validity of the data. The only word checked for validity is the first of the 16 internal information words (SP + 26) shown in Figure 5-8. This word contains a processor version number (in bits 10–13) and proprietary internal information that must match the version number of the MC68010 attempting to read the data. This validity check is used to ensure that the data is properly interpreted by the RTE instruction. If the version number is incorrect for this processor, the RTE instruction is aborted and exception processing begins for a format error exception. Since the stack pointer is not updated until the RTE instruction has successfully read all the stack data, a format error occurring at this point does not stack new data over the previous bus error stack information.
3. Determine data accessibility. If the long-stack data is valid, the MC68010 performs a read from the last word (SP + 56) of the long stack to determine data accessibility. If this read is terminated normally, the processor assumes that the remaining words on the stack frame are also accessible. If a bus error is signaled before or during this read, a bus error exception is taken. After this read, the processor must be able to load the remaining data without receiving a bus error; therefore, if a bus error occurs on any of the remaining stack reads, the error becomes a double bus fault, and the MC68010 enters the halted state.

Table 8-5. Immediate Instruction Execution Times

Instruction	Size	op #, Dn	op #, An	op #, M
ADDI	Byte, Word	**8**(2/0)	—	**12**(2/1)+
	Long	**16**(3/0)	—	**20**(3/2)+
ADDQ	Byte, Word	**4**(1/0)	**4**(1/0)*	**8**(1/1)+
	Long	**8**(1/0)	**8**(1/0)	**12**(1/2)+
ANDI	Byte, Word	**8**(2/0)	—	**12**(2/1)+
	Long	**14**(3/0)	—	**20**(3/2)+
CMPI	Byte, Word	**8**(2/0)	—	**8**(2/0)+
	Long	**14**(3/0)	—	**12**(3/0)+
EORI	Byte, Word	**8**(2/0)	—	**12**(2/1)+
	Long	**16**(3/0)	—	**20**(3/2)+
MOVEQ	Long	**4**(1/0)	—	—
ORI	Byte, Word	**8**(2/0)	—	**12**(2/1)+
	Long	**16**(3/0)	—	**20**(3/2)+
SUBI	Byte, Word	**8**(2/0)	—	**12**(2/1)+
	Long	**16**(3/0)	—	**20**(3/2)+
SUBQ	Byte, Word	**4**(1/0)	**8**(1/0)*	**8**(1/1)+
	Long	**8**(1/0)	**8**(1/0)	**12**(1/2)+

8.5 SINGLE OPERAND INSTRUCTION EXECUTION TIMES

Table 8-6 lists the timing data for the single operand instructions. The total number of clock periods, the number of read cycles, and the number of write cycles are shown in the previously described format. The number of clock periods, the number of read cycles, and the number of write cycles, respectively, must be added to those of the effective address calculation where indicated by a plus sign (+).

Table 9-9. Single Operand Instruction Execution Times

Instruction	Size	Register	Memory
NBCD	Byte	**6**(1/0)	**8**(1/1)+
NEG	Byte, Word	**4**(1/0)	**8**(1/1)+
	Long	**6**(1/0)	**12**(1/2)+
NEGX	Byte, Word	**4**(1/0)	**8**(1/1)+
	Long	**6**(1/0)	**12**(1/2)+
NOT	Byte, Word	**4**(1/0)	**8**(1/1)+
	Long	**6**(1/0)	**12**(1/2)+
Scc	Byte, False	**4**(1/0)	**8**(1/1)+*
	Byte, True	**4**(1/0)	**8**(1/1)+*
TAS	Byte	**4**(1/0)	**14**(2/1)+*
TST	Byte, Word	**4**(1/0)	**4**(1/0)+
	Long	**4**(1/0)	**4**(1/0)+

+Add effective address calculation time.
*Use nonfetching effective address calculation time.

Table 9-10. Clear Instruction Execution Times

	Size	Dn	An	(An)	(An)+	–(An)	(d_{16}, An)	(d_8, An, Xn)*	(xxx).W	(xxx).L
CLR	Byte, Word	**4**(1/0)	—	**8**(1/1)	**8**(1/1)	**10**(1/1)	**12**(2/1)	**16**(2/1)	**12**(2/1)	**16**(3/1)
	Long	**6**(1/0)	—	**12**(1/2)	**12**(1/2)	**14**(1/2)	**16**(2/2)	**20**(2/2)	**16**(2/2)	**20**(3/2)

*The size of the index register (Xn) does not affect execution time.

is lost through the active P-channel transistor. Also, since only one transistor is turned on during the steady state, power consumption is determined by leakage currents.

Because the basic CMOS cell is composed of two complementary transistors, a virtual semiconductor controlled rectifier (SCR) may be formed when an input exceeds the supply voltage. The SCR that is formed by this high input causes the device to become latched in a mode that may result in excessive current drain and eventual destruction of the device. Although the MC68HC000 and MC68EC000 is implemented with input protection diodes, care should be exercised to ensure that the maximum input voltage specification is not exceeded. Some systems may require that the CMOS circuitry be isolated from voltage transients; other may require additional circuitry.

The MC68HC000 and MC68EC000, implemented in CMOS, is applicable to designs to which the following considerations are relevant:

1. The MC68HC000 and MC68EC000 completely satisfies the input/output drive requirements of CMOS logic devices.
2. The HCMOS MC68HC000 and MC68EC000 provides an order of magnitude reduction in power dissipation when compared to the HMOS MC68000. However, the MC68HC000 does not offer a "power-down" mode.

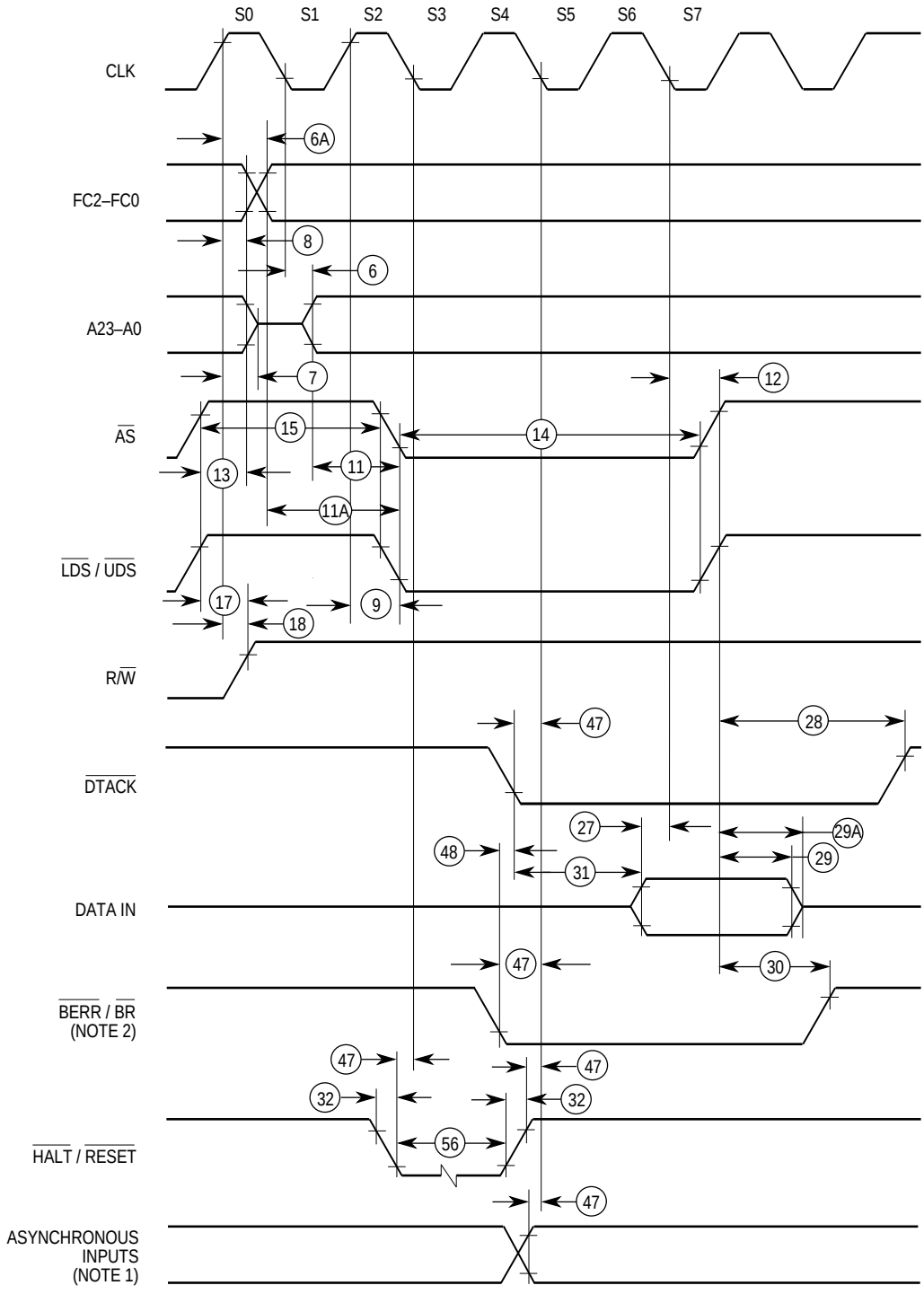
10.5 AC ELECTRICAL SPECIFICATION DEFINITIONS

The AC specifications presented consist of output delays, input setup and hold times, and signal skew times. All signals are specified relative to an appropriate edge of the clock and possibly to one or more other signals.

The measurement of the AC specifications is defined by the waveforms shown in Figure 10-2. To test the parameters guaranteed by Motorola, inputs must be driven to the voltage levels specified in the figure. Outputs are specified with minimum and/or maximum limits, as appropriate, and are measured as shown. Inputs are specified with minimum setup and hold times, and are measured as shown. Finally, the measurement for signal-to-signal specifications are shown.

NOTE

The testing levels used to verify conformance to the AC specifications does not affect the guaranteed DC operation of the device as specified in the DC electrical characteristics.



NOTES:
1. Setup time for the asynchronous inputs IPL2–IPL0 and AVEC (#47) guarantees their recognition at the next falling edge of the clock.
2. BR need fall at this time only to insure being recognized at the end of the bus cycle.
3. Timing measurements are referenced to and from a low voltage of 0.8 V and a high voltage of 2.0 V, unless otherwise noted. The voltage swing through this range should start outside and pass through the range such that the rise or fall is linear between 0.8 V and 2.0 V.

Figure 10-4. Read Cycle Timing Diagram
(Applies To All Processors Except The MC68EC000)

10.11 AC ELECTRICAL SPECIFICATIONS—MC68000 TO M6800 PERIPHERAL (V_{CC} = 5.0 Vdc ±5%; GND=0 Vdc; $T_A = T_L$ TO T_H; refer to figures 10-6)

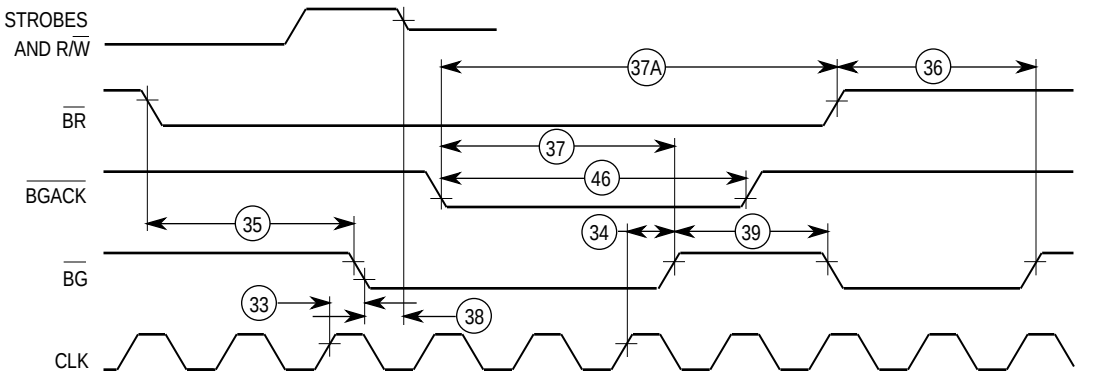
(Applies To All Processors Except The MC68EC000)

Num	Characteristic	8 MHz*		10 MHz*		12.5 MHz*		16.67 MHz `12F'		16 MHz		20 MHz**		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
12[1]	Clock Low to $\overline{AS}$, $\overline{DS}$ Negated	—	62	—	50	—	40	—	40	3	30	3	25	ns
18[1]	Clock High to R/$\overline{W}$ High (Read)	0	55	0	45	0	40	0	40	0	30	0	25	ns
20[1]	Clock High to R/$\overline{W}$ Low (Write)	0	55	0	45	0	40	0	40	0	30	0	25	ns
23	Clock Low to Data-Out Valid (Write)	—	62	—	50	—	50	—	50	—	30	—	25	ns
27	Data-In Valid to Clock Low (Setup Time on Read)	10	—	10	—	10	—	7	—	5	—	5	—	ns
29	$\overline{AS}$, $\overline{DS}$ Negated to Data-In Invalid (Hold Time on Read)	0	—	0	—	0	—	0	—	0	—	0	—	ns
40	Clock Low to $\overline{VMA}$ Asserted	—	70	—	70	—	70	—	50	—	50	—	40	ns
41	Clock Low to E Transition	—	55	—	45	—	35	—	35	—	35	—	30	ns
42	E Output Rise and Fall Time	—	15	—	15	—	15	—	15	—	15	—	12	ns
43	$\overline{VMA}$ Asserted to E High	200	—	150	—	90	—	80	—	80	—	60	—	ns
44	$\overline{AS}$, $\overline{DS}$ Negated to $\overline{VPA}$ Negated	0	120	0	90	0	70	0	50	0	50	0	42	ns
45	E Low to Control, Address Bus Invalid (Address Hold Time)	30	—	10	—	10	—	10	—	10	—	10	—	ns
47	Asynchronous Input Setup Time	10	—	10	—	10	—	10	—	10	—	5	—	ns
49[2]	$\overline{AS}$, $\overline{DS}$, Negated to E Low	-70	70	-55	55	-45	45	-35	35	-35	35	–30	30	ns
50	E Width High	450	—	350	—	280	—	220	—	220	—	190	—	ns
51	E Width Low	700	—	550	—	440	—	340	—	340	—	290	—	ns
54	E Low to Data-Out Invalid	30	—	20	—	15	—	10	—	10	—	5	—	ns

*These specifications represent improvement over previously published specifications for the 8-, 10-, and 12.5-MHz MC68000 and are valid only for product bearing date codes of 8827 and later.

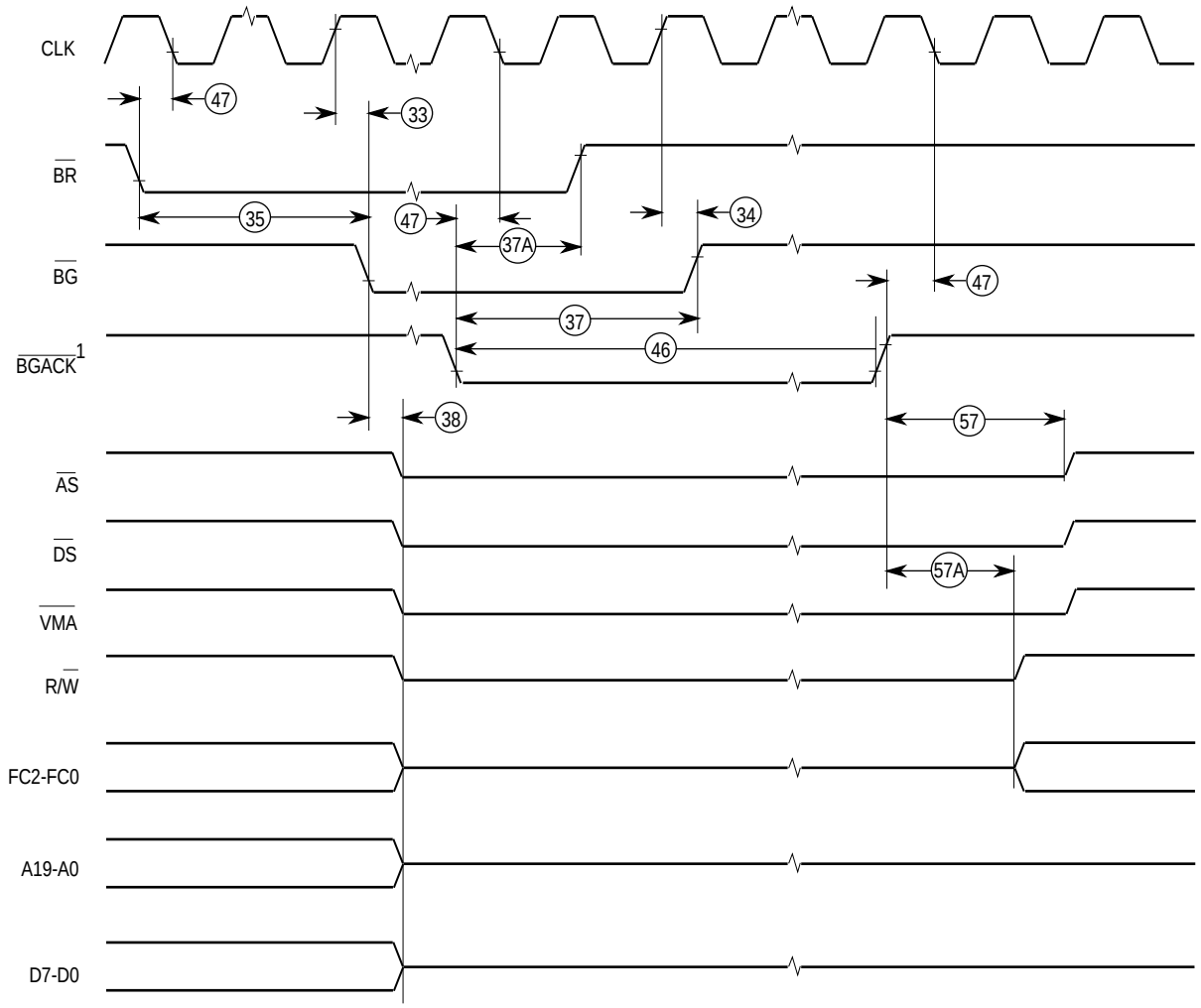
** This frequency applies only to MC68HC000 and MC68HC001.

NOTES:
1. For a loading capacitance of less than or equal to 50 pF, subtract 5 ns from the value given in the maximum columns.
2. The falling edge of S6 triggers both the negation of the strobes ($\overline{AS}$ and $\overline{DS}$) and the falling edge of E. Either of these events can occur first, depending upon the loading on each signal. Specificaton #49 indicates the absolute maximum skew that will occur between the rising edge of the strobes and the falling edge of the E clock.



NOTE: Setup time to the clock (#47) for the asynchronous inputs BERR, BGACK, BR, DTACK, IPL2-IPL0, and VPA guarantees their recognition at the next falling edge of the clock.

Figure 10-7. Bus Arbitration Timing
(Applies To All Processors Except The MC68EC000)



NOTES: Waveform measurements for all inputs and outputs are specified at: logic high 2.0 V, logic low = 0.8 V.
1. MC68008 52-Pin Version only.

Figure 10-9. Bus Arbitration Timing — Idle Bus Case
(Applies To All Processors Except The MC68EC000)

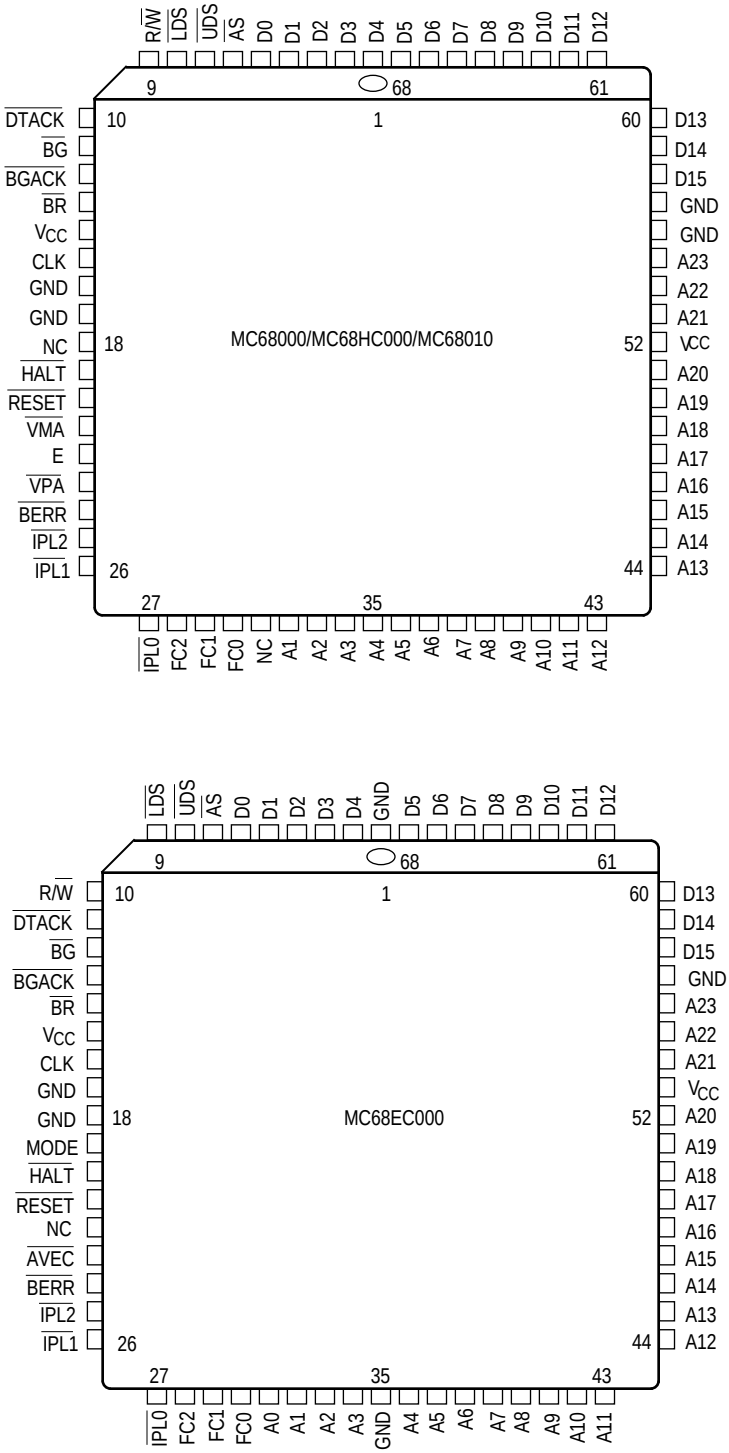


Figure 11-3. 68-Lead Quad Pack (1 of 2)