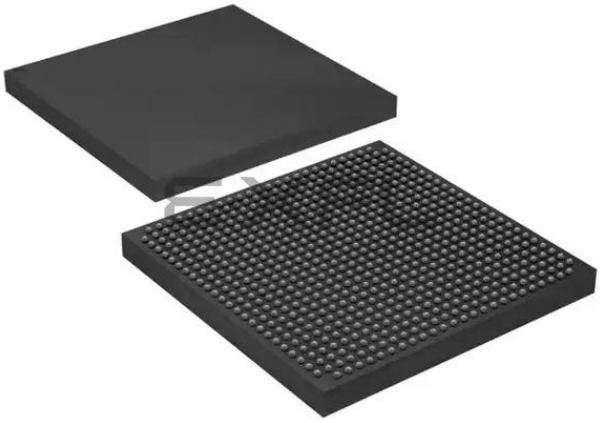

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	1057
Number of Logic Elements/Cells	10570
Total RAM Bits	920448
Number of I/O	362
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep1sgx10df672c7n

Power-down functions are static, in other words., they are implemented upon device configuration and programmed, through the Quartus II software, to static values. Resets can be static as well as dynamic inputs coming from the logic array or pins.

Table 2–11. Reset Signal Map to Stratix GX Blocks

Reset Signal	Transmitter Phase Compensation FIFO Module/ Byte Serializer	Transmitter 8B/10B Encoder	Transmitter Serializer	Transmitter Analog Circuits	Transmitter PLL	Transmitter XAUI State Machine	Transmitter Analog Circuits	BIST Generators	Receiver Deserializer	Receiver Word Aligner	Receiver Deskew FIFO Module	Receiver Rate Matcher	Receiver 8B/10B Decoder	Receiver Phase Comp FIFO Module/ Byte Deserializer	Receiver PLL / CRU	Receiver XAUI State Machine	BIST Verifiers	Receiver Analog Circuits
rxdigitalreset										✓	✓	✓	✓	✓		✓	✓	
rxanalogreset									✓						✓			✓
txdigitalreset	✓	✓				✓		✓										
pll_areset	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
pllenable	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

Voltage Reference Capabilities

Stratix GX transceivers provide voltage reference and bias circuitry. To set-up internal bias for controlling the transmitter output drivers' voltage swing—as well as to provide voltage/current biasing for other analog circuitry—use the internal bandgap voltage reference at 0.7 V. To provide bias for internal pull-up PMOS resistors for I/O termination at the serial interface of receiver and transmitter channels (independent of power supply drift, process changes, or temperature variation) an external resistor, which is connected to the external low voltage power supply, is

The logic array sends parallel data to the SERDES transmitter circuit when the TXLOADEN signal is asserted. This signal is generated by the high-speed counter circuitry of the logic array low-frequency clock's rising edge. The data is then transferred from the parallel register into the serial shift register by the TXLOADEN signal on the third rising edge of the high-frequency clock.

Figure 3–3 shows the block diagram of a single SERDES transmitter channel and Figure 3–4 shows the timing relationship between the data and clocks in Stratix GX devices in ×10 mode. *W* is the low-frequency multiplier and *J* is the data parallelization division factor.

Figure 3–3. Stratix GX High-Speed Interface Serialized in ×10 Mode

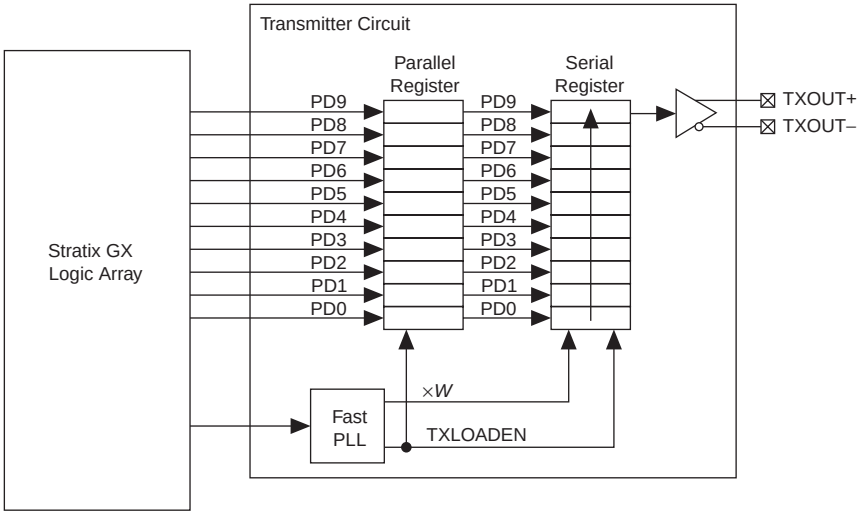
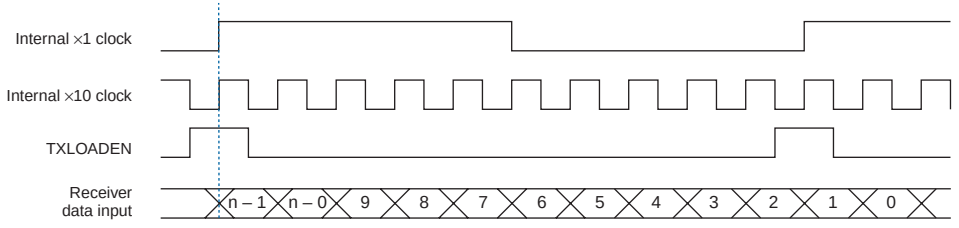


Figure 3–4. Transmitter Timing Diagram



have four dedicated fast PLLs for clock multiplication. Table 3–3 shows the maximum number of channels in each Stratix GX device that support DPA.

Table 3–3. Stratix GX Source-Synchronous Differential I/O Resources

Device	Fast PLLs	Pin Count	Receiver Channels *(1)*	Transmitter Channels *(1)*	Receiver & Transmitter Channel Speed (Gbps) *(2)*	LEs
EP1SGX10C	2 *(3)*	672	22	22	1	10,570
EP1SGX10D	2 *(3)*	672	22	22	1	10,570
EP1SGX25C	2	672	39	39	1	25,660
EP1SGX25D	2	672	39	39	1	25,660
		1,020	39	39	1	25,660
EP1SGX25F	2	1,020	39	39	1	25,660
EP1SGX40D	4 *(4)*	1,020	45	45	1	41,250
EP1SGX40G	4 *(4)*	1,020	45	45	1	41,250

Notes to Table 3–3:

(1) This is the number of receiver or transmitter channels in the source-synchronous (I/O bank 1 and 2) interface of the device.

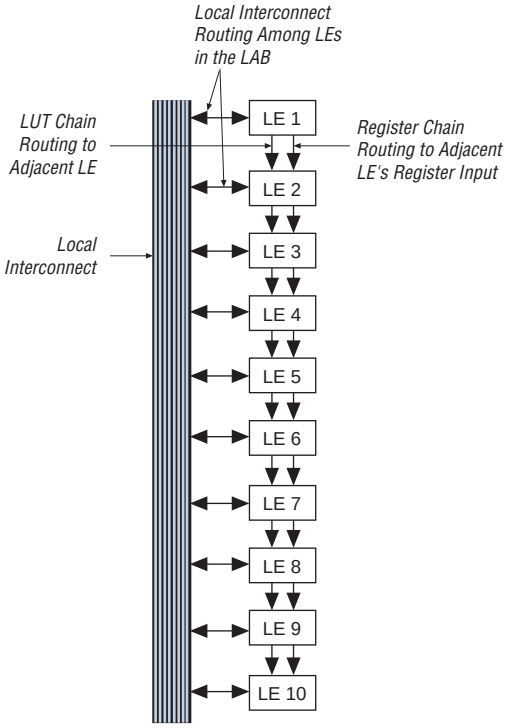
(2) Receiver channels operate at 1,000 Mbps with DPA. Without DPA, the receiver channels operate at 840 Mbps.

(3) One of the two fast PLLs in EP1SGX10C and EP1SGX10D devices supports DPA.

(4) Two of the four fast PLLs in EP1SGX40D and EP1SGX40G devices support DPA

The receiver and transmitter channels are interleaved so that each I/O row in I/O banks 1 and 2 of the device has one receiver channel and one transmitter channel per row. Figures 3–6 and 3–7 show the fast PLL and channels with DPA layout in EP1SGX10, EP1SGX25, and EP1SGX40 devices. In EP1SGX10 devices, only fast PLL 2 supports DPA operations.

Figure 4–9. LUT Chain & Register Chain Interconnects



The C4 interconnects span four LABs, M512, or M4K blocks up or down from a source LAB. Every LAB has its own set of C4 interconnects to drive either up or down. Figure 4–10 shows the C4 interconnect connections from an LAB in a column. The C4 interconnects can drive and be driven by all types of architecture blocks, including DSP blocks, TriMatrix memory blocks, and vertical IOEs. For LAB interconnection, a primary LAB or its LAB neighbor can drive a given C4 interconnect.
C4 interconnects can drive each other to extend their range as well as drive row interconnects for column-to-column connections.

Figure 4–21. M-RAM Row Unit Interface to Interconnect

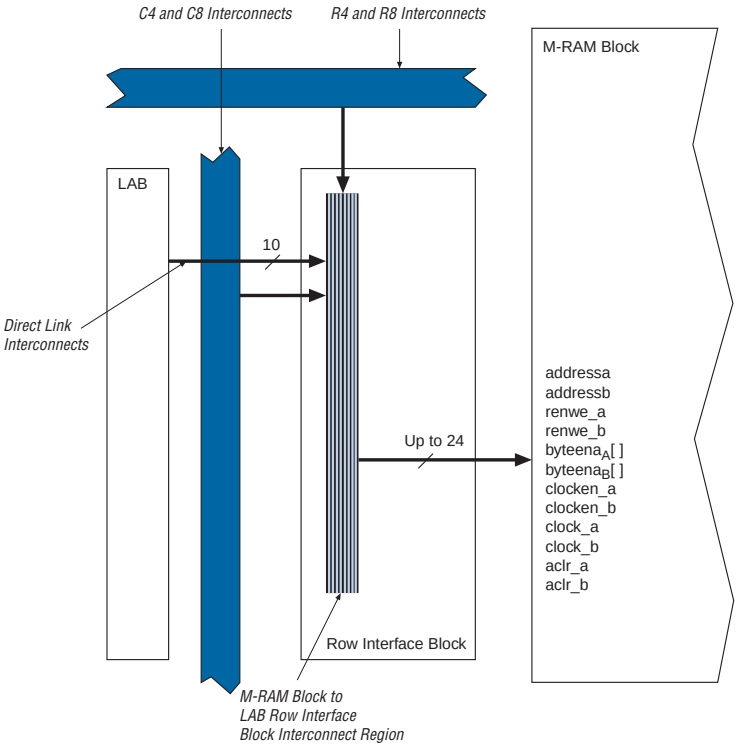
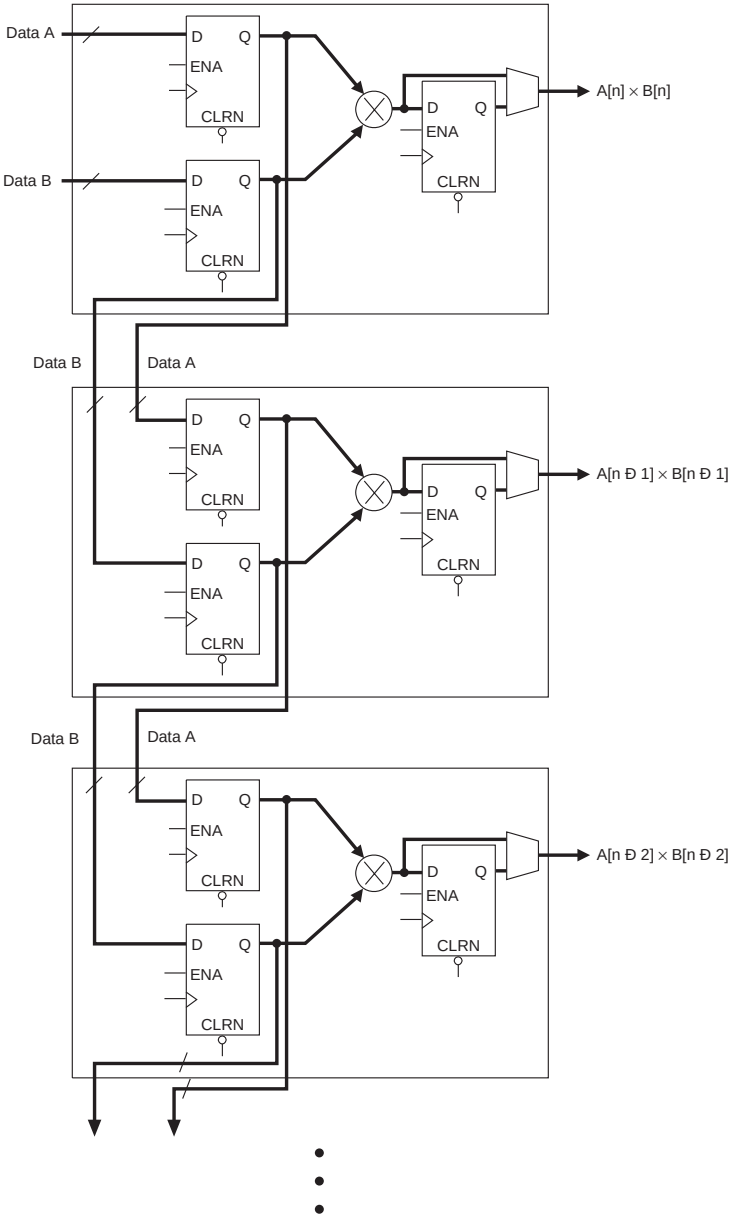


Figure 4–32. Multiplier Sub-Blocks Using Input Shift Register Connections *Note (1)*



Note to Figure 4–32:
(1) Either Data A or Data B input can be set to a parallel input for constant coefficient multiplication.

For FIR filters, the DSP block combines the four-multipliers adder mode with the shift register inputs. One set of shift inputs contains the filter data, while the other holds the coefficients loaded in serial or parallel. The input shift register eliminates the need for shift registers external to the DSP block (that is, implemented in LEs). This architecture simplifies filter design since the DSP block implements all of the filter circuitry.

One DSP block can implement an entire 18-bit FIR filter with up to four taps. For FIR filters larger than four taps, DSP blocks can be cascaded with additional adder stages implemented in LEs.

Table 4–15 shows the different number of multipliers possible in each DSP block mode according to size. These modes allow the DSP blocks to implement numerous applications for DSP including FFTs, complex FIR, FIR, and 2D FIR filters, equalizers, IIR, correlators, matrix multiplication and many other functions.

Table 4–15. Multiplier Size & Configurations per DSP block

DSP Block Mode	9 × 9	18 × 18	36 × 36 *(1)*
Multiplier	Eight multipliers with eight product outputs	Four multipliers with four product outputs	One multiplier with one product output
Multiply-accumulator	Two multiply and accumulate (52 bits)	Two multiply and accumulate (52 bits)	–
Two-multipliers adder	Four sums of two multiplier products each	Two sums of two multiplier products each	–
Four-multipliers adder	Two sums of four multiplier products each	One sum of four multiplier products each	–

Note to Table 4–15:
(1) The number of supported multiply functions shown is based on signed/signed or unsigned/unsigned implementations.

DSP Block Interface

Stratix GX device DSP block outputs can cascade down within the same DSP block column. Dedicated connections between DSP blocks provide fast connections between the shift register inputs to cascade the shift register chains. You can cascade DSP blocks for 9 × 9- or 18 × 18-bit FIR filters larger than four taps, with additional adder stages implemented in LEs. If the DSP block is configured as 36 × 36 bits, the adder, subtractor, or accumulator stages are implemented in LEs. Each DSP block can route the shift register chain out of the block to cascade two full columns of DSP blocks.

The DSP block is divided into eight block units that interface with eight LAB rows on the left and right. Each block unit can be considered half of an 18 × 18-bit multiplier sub-block with 18 inputs and 18 outputs. A local interconnect region is associated with each DSP block. Like an LAB, this interconnect region can be fed with 10 direct link interconnects from the LAB to the left or right of the DSP block in the same row. All row and column routing resources can access the DSP block's local interconnect region. The outputs also work similarly to LAB outputs as well. Nine outputs from the DSP block can drive to the left LAB through direct link interconnects and nine can drive to the right LAB though direct link interconnects. All 18 outputs can drive to all types of row and column routing. Outputs can drive right- or left-column routing. Figures 4–39 and 4–40 show the DSP block interfaces to LAB rows.

Figure 4–39. DSP Block Interconnect Interface

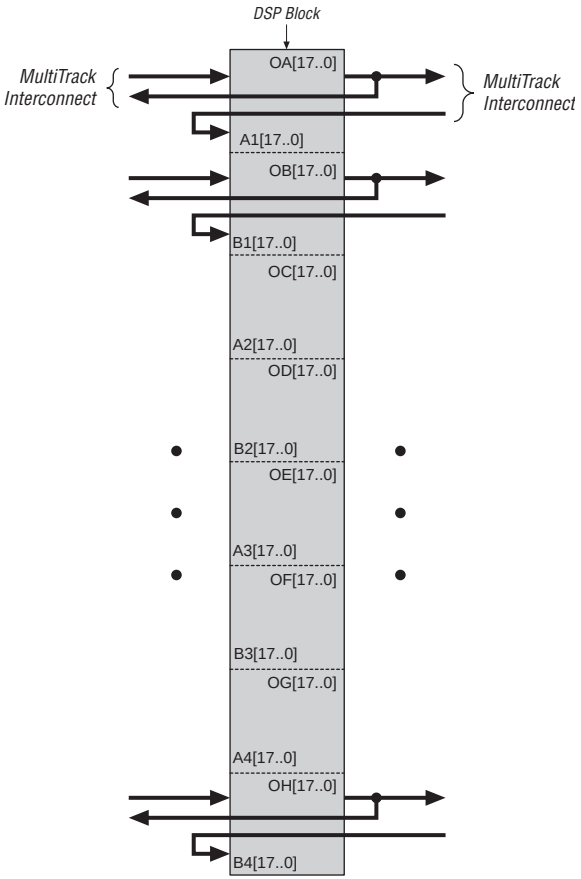
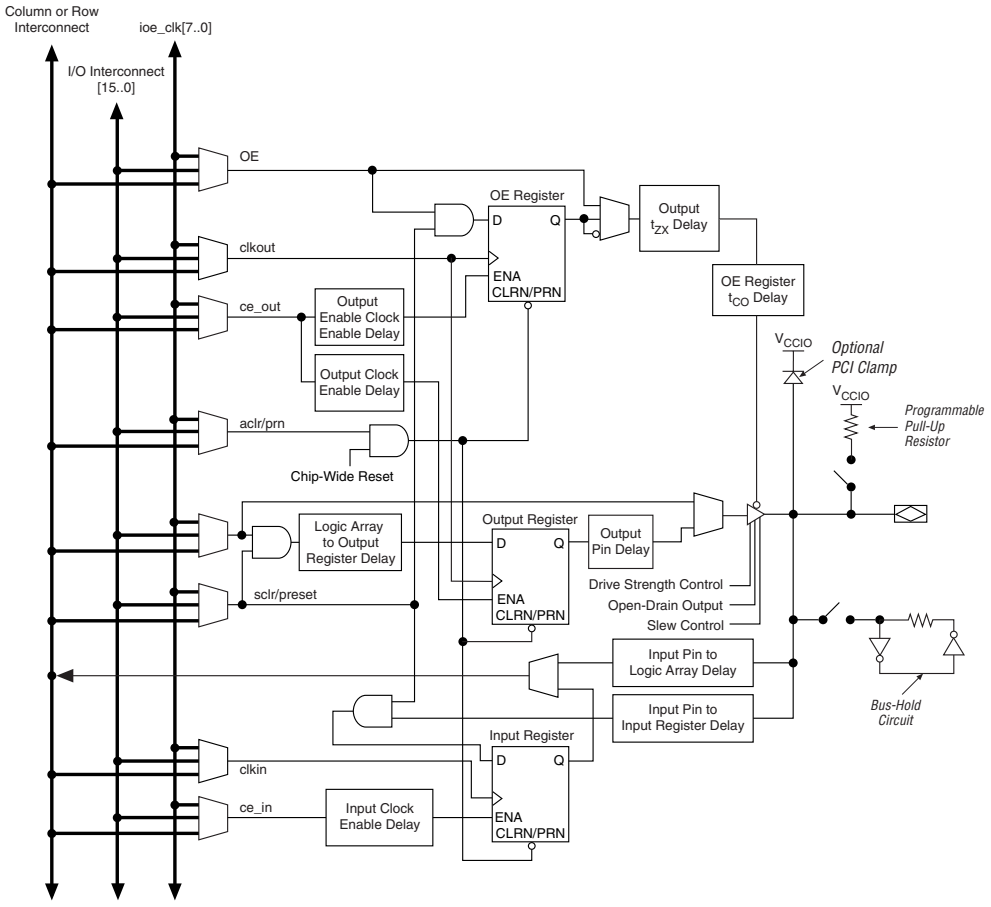


Figure 4–63. Stratix GX IOE in Bidirectional I/O Configuration *Note (1)*

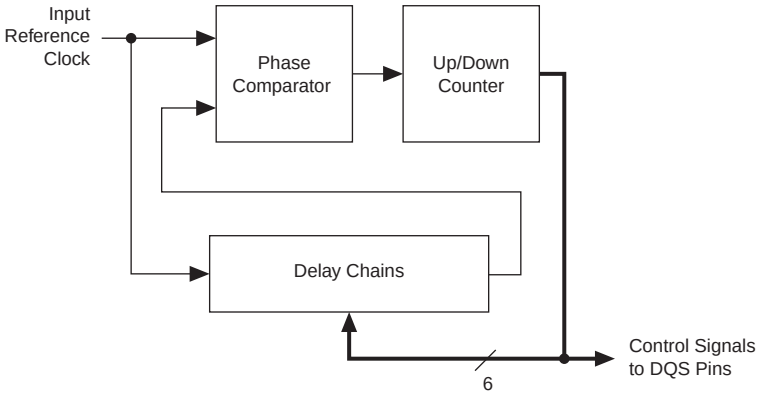


Note to Figure 4–63:
(1) All input signals to the IOE can be inverted at the IOE.

The Stratix GX device IOE includes programmable delays that can be activated to ensure zero hold times, input IOE register-to-logic array register transfers, or logic array-to-output IOE register transfers.

A path in which a pin directly drives a register may require the delay to ensure zero hold time, whereas a path in which a pin drives a register through combinatorial logic may not require the delay. Programmable delays exist for decreasing input-pin-to-logic-array and IOE input register delays. The Quartus II Compiler can program these delays to automatically minimize setup time while providing a zero hold time.

Figure 4–68. Simplified Diagram of the DQS Phase-Shift Circuitry



See the *External Memory Interfaces* chapter of the *Stratix GX Device Handbook, Volume 2* for more information on external memory interfaces.

Programmable Drive Strength

The output buffer for each Stratix GX device I/O pin has a programmable drive strength control for certain I/O standards. The LVTTL and LVCMOS standard has several levels of drive strength that the user can control. SSTL-3 class I and II, SSTL-2 class I and II, HSTL class I and II, and 3.3-V GTL+ support a minimum setting, the lowest drive strength that guarantees the I_{OH}/I_{OL} of the standard. Using minimum settings provides signal slew rate control to reduce system noise and signal overshoot.

- Receive new configuration data and write it into the configuration device

The factory configuration is the default and takes control if an error occurs while loading the application configuration.

While in the factory configuration, the factory-configuration logic performs the following operations:

- Loads a remote update-control register to determine the page address of the new application configuration
- Determines whether to enable a user watchdog timer for the application configuration
- Determines what the watchdog timer setting should be if it is enabled

The user watchdog timer is a counter that must be continually reset within a specific amount of time in the user mode of an application configuration to ensure that valid configuration occurred during a remote update. Only valid application configurations designed for remote update can reset the user watchdog timer in user mode. If a valid application configuration does not reset the user watchdog timer in a specific amount of time, the timer updates a status register and loads the factory configuration. The user watchdog timer is automatically disabled for factory configurations.

If an error occurs in loading the application configuration, the configuration logic writes a status register to specify the cause of the reconfiguration. Once this occurs, the Stratix GX device automatically loads the factory configuration, which reads the status register and determines the reason for reconfiguration. Based on the reason, the factory configuration takes appropriate steps and writes the remote update control register to specify the next application configuration page to be loaded.

When the Stratix GX device successfully loads the application configuration, it enters into user mode. The Stratix GX device then executes the main application of the user. Intellectual property (IP), such as a Nios® embedded processor, can help the Stratix GX device determine when remote update is coming. The Nios embedded processor or user logic receives incoming data, writes it to the configuration device, and loads the factory configuration. The factory configuration reads the remote update status register and determine the valid application configuration to load. Figure 5–1 shows the Stratix GX remote update. Figure 5–2 shows the transition diagram for remote update mode.

Internal Timing Parameters

Internal timing parameters are specified on a speed grade basis independent of device density. Tables 6–36 through 6–42 describe the Stratix GX device internal timing microparameters for LEs, IOEs, TriMatrix™ memory structures, DSP blocks, and MultiTrack interconnects.

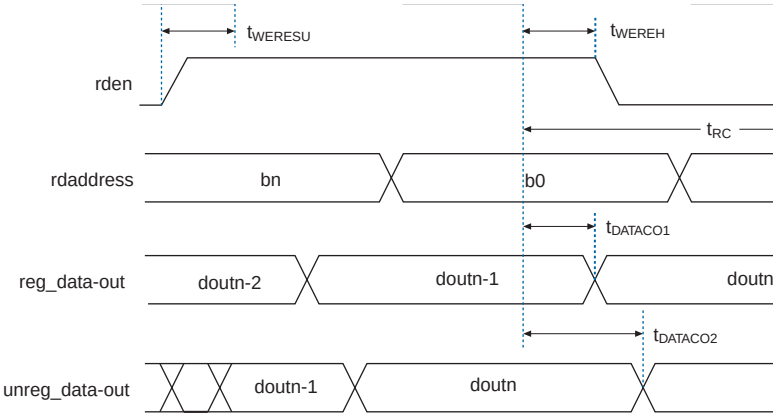
Table 6–36. LE Internal Timing Microparameter Descriptions

Symbol	Parameter
t_{SU}	LE register setup time before clock
t_{H}	LE register hold time after clock
t_{CO}	LE register clock-to-output delay
t_{LUT}	LE combinational LUT delay for data-in to data-out
t_{CLR}	Minimum clear pulse width
t_{PRE}	Minimum preset pulse width
t_{CLKHL}	Minimum clock high or low time

Table 6–37. IOE Internal Timing Microparameter Descriptions

Symbol	Parameter
t_{SU}	IOE input and output register setup time before clock
t_{H}	IOE input and output register hold time after clock
t_{CO}	IOE input and output register clock-to-output delay
$t_{PIN2COMBOUT\_R}$	Row input pin to IOE combinational output
$t_{PIN2COMBOUT\_C}$	Column input pin to IOE combinational output
$t_{COMBIN2PIN\_R}$	Row IOE data input to combinational output pin
$t_{COMBIN2PIN\_C}$	Column IOE data input to combinational output pin
t_{CLR}	Minimum clear pulse width
t_{PRE}	Minimum preset pulse width
t_{CLKHL}	Minimum clock high or low time

Figure 6–5. Stratix GX Transceiver Reset & PLL Lock Time Waveform *Note (1)*



Note to Figure 6–5:

(1) Waveforms are for minimum pulse width timing and output timing only. Please refer to the *Stratix GX Transceiver User Guide* for the complete reset sequence.

Tables 6–44 through 6–50 show the internal timing microparameters for all Stratix GX devices.

Table 6–44. LE Internal Timing Microparameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{SU}	10		10		11		ps
t_{H}	100		100		114		ps
t_{CO}		156		176		202	ps
t_{LUT}		366		459		527	ps
t_{CLR}	100		100		114		ps
t_{PRE}	100		100		114		ps
t_{CLKHL}	100		100		114		ps

Table 6–45. IOE Internal Timing Microparameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{SU}	64		68		68		ps
t_{H}	76		80		80		ps
t_{CO}		162		171		171	ps
$t_{PIN2COMBOUT\_R}$		1,038		1,093		1,256	ps
$t_{PIN2COMBOUT\_C}$		927		976		1,122	ps
$t_{COMBIN2PIN\_R}$		2,944		3,099		3,563	ps
$t_{COMBIN2PIN\_C}$		3,189		3,357		3,860	ps
t_{CLR}	262		276		317		ps
t_{PRE}	262		276		317		ps
t_{CLKHL}	90		95		109		ps

Table 6–46. DSP Block Internal Timing Microparameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{SU}	0		0		0		ps
t_{H}	67		75		86		ps
t_{CO}		142		158		181	ps
$t_{INREG2PIPE18}$		2,613		2,982		3,429	ps
$t_{INREG2PIPE9}$		3,390		3,993		4,591	ps
$t_{PIPE2OUTREG2ADD}$		2,002		2,203		2,533	ps
$t_{PIPE2OUTREG4ADD}$		2,899		3,189		3,667	ps
t_{PD9}		3,709		4,081		4,692	ps
t_{PD18}		4,795		5,275		6,065	ps
t_{PD36}		7,495		8,245		9,481	ps
t_{CLR}	450		500		575		ps
t_{CLKHL}	1,350		1,500		1,724		ps

Table 6–48. M4K Block Internal Timing Microparameters (Part 2 of 2)

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{M4KDATACO1}$		571		635		729	ps
$t_{M4KDATACO2}$		3,984		4,507		5,182	ps
$t_{M4KCLKHL}$	150		167		192		ps
t_{M4KCLR}	170		189		255		ps

Table 6–49. M-RAM Block Internal Timing Microparameters

Symbol	-5		-6		-7		Unit
	Min	Max	Min	Max	Min	Max	
t_{MRAMRC}		4,364		4,838		5,562	ps
t_{MRAMWC}		3,654		4,127		4,746	ps
$t_{MRAMWERESU}$	25		25		28		ps
$t_{MRAMWERH}$	18		20		23		ps
$t_{MRAMDATASU}$	25		25		28		ps
$t_{MRAMDATAH}$	18		20		23		ps
$t_{MRAMWADDRASU}$	25		25		28		ps
$t_{MRAMWADDRH}$	18		20		23		ps
$t_{MRAMRADDRASU}$	25		25		28		ps
$t_{MRAMRADDRH}$	18		20		23		ps
$t_{MRAMDATABSU}$	25		25		28		ps
$t_{MRAMDATABH}$	18		20		23		ps
$t_{MRAMADDRBSU}$	25		25		28		ps
$t_{MRAMADDRBH}$	18		20		23		ps
$t_{MRAMDATACO1}$		1,038		1,053		1,210	ps
$t_{MRAMDATACO2}$		4,362		4,939		5,678	ps
$t_{MRAMCLKHL}$	270		300		345		ps
$t_{MRAMCLR}$	135		150		172		ps

Table 6–68. EP1SGX40 Column Pin Global Clock External I/O Timing Parameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.033		2.184		2.451		ns
t_{INH}	0.000		0.000		0.000		ns
t_{OUTCO}	2.000	5.689	2.000	6.116	2.000	7.010	ns
$t_{INSUPLL}$	1.228		1.278		1.415		ns
t_{INHPLL}	0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	0.500	2.594	0.500	2.732	0.500	3.113	ns

Table 6–69. EP1SGX40 Row Pin Fast Regional Clock External I/O Timing Parameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.450		2.662		3.046		ns
t_{INH}	0.000		0.000		0.000		ns
t_{OUTCO}	2.000	4.880	2.000	5.241	2.000	6.004	ns

Table 6–70. EP1SGX40 Row Pin Regional Clock External I/O Timing Parameters

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{INSU}	2.398		2.567		2.938		ns
t_{INH}	0.000		0.000		0.000		ns
t_{OUTCO}	2.000	4.932	2.000	5.336	2.000	6.112	ns
$t_{INSUPLL}$	1.126		1.186		1.352		ns
t_{INHPLL}	0.000		0.000		0.000		ns
$t_{OUTCOPLL}$	0.500	2.304	0.500	2.427	0.500	2.765	ns

Table 6–71. EP1SGX40 Row Pin Global Clock External I/O Timing Parameters (Part 1 of 2)

Symbol	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{INSU}	1.965		2.128		2.429		ns
t_{INH}	0.000		0.000		0.000		ns

Table 6–73. Stratix GX I/O Standard Row Pin Input Delay Adders (Part 2 of 2)

I/O Standard	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
1.5-V HSTL class II		0		0		0	ps
1.8-V HSTL class I		70		73		83	ps
1.8-V HSTL class II		70		73		83	ps
LVDS *(1)*		40		42		48	ps
LVPECL *(1)*		–50		–53		–61	ps
3.3-V PCML *(1)*		330		346		397	ps
HyperTransport *(1)*		80		84		96	ps

Table 6–74. Stratix GX I/O Standard Output Delay Adders for Fast Slew Rate on Column Pins (Part 1 of 2)

Standard		-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
		Min	Max	Min	Max	Min	Max	
LVCMOS	2 mA		570		599		689	ps
	4 mA		570		599		689	ps
	8 mA		350		368		423	ps
	12 mA		130		137		157	ps
	24 mA		0		0		0	ps
3.3-V LVTTL	4 mA		570		599		689	ps
	8 mA		350		368		423	ps
	12 mA		130		137		157	ps
	16 mA		70		74		85	ps
	24 mA		0		0		0	ps
2.5-V LVTTL	2 mA		830		872		1,002	ps
	8 mA		250		263		302	ps
	12 mA		140		147		169	ps
	16 mA		100		105		120	ps
1.8-V LVTTL	2 mA		420		441		507	ps
	8 mA		350		368		423	ps
	12 mA		350		368		423	ps
1.5-V LVTTL	2 mA		1,740		1,827		2,101	ps
	4 mA		1,160		1,218		1,400	ps
	8 mA		690		725		833	ps
GTL			–150		–157		–181	ps

Tables 6–78 and 6–79 show the adder delays for the column and row IOE programmable delays, respectively. These delays are controlled with the Quartus II software logic options listed in the Parameter column.

Table 6–78. Stratix GX IOE Programmable Delays on Column Pins

Parameter	Setting	-5 Speed Grade		-6 Speed Grade		-7 Speed Grade		Unit
		Min	Max	Min	Max	Min	Max	
Decrease input delay to internal cells	Off		3,970		4,367		5,022	ps
	On		3,390		3,729		4,288	ps
	Small		2,810		3,091		3,554	ps
	Medium		212		224		257	ps
	Large		212		224		257	ps
Decrease input delay to input register	Off		3900		4,290		4,933	ps
	On		0		0		0	ps
Decrease input delay to output register	Off		1,240		1,364		1,568	ps
	On		0		0		0	ps
Increase delay to output pin	Off		0		0		0	ps
	On		377		397		456	ps
Increase delay to output enable pin	Off		0		0		0	ps
	On		338		372		427	ps
Increase output clock enable delay	Off		0		0		0	ps
	On		540		594		683	ps
	Small		1,016		1,118		1,285	ps
	Large		1,016		1,118		1,285	ps
Increase input clock enable delay	Off		0		0		0	ps
	On		540		594		683	ps
	Small		1,016		1,118		1,285	ps
	Large		1,016		1,118		1,285	ps
Increase output enable clock enable delay	Off		0		0		0	ps
	On		540		594		683	ps
	Small		1,016		1,118		1,285	ps
	Large		1,016		1,118		1,285	ps

The scaling factors for output pin timing in Table 6–80 are shown in units of time per pF unit of capacitance (ps/pF). Add this delay to the combinational timing path for output or bidirectional pins in addition to the "I/O Adder" delays shown in Tables 6–72 through 6–77 and the "IOE Programmable Delays" in Tables 6–78 and 6–79.

Table 6–80. Output Delay Adder for Loading on LVTTL/LVCMOS Output Buffers

LVTTL/LVCMOS Standards						
Conditions		**Output Pin Adder Delay (ps/pF)**				
Parameter	**Value**	3.3-V LVTTL	2.5-V LVTTL	1.8-V LVTTL	1.5-V LVTTL	LVCMOS
Drive Strength	24 mA	15	–	–	-	8
	16 mA	25	18	–	–	–
	12 mA	30	25	25	–	15
	8 mA	50	35	40	35	20
	4 mA	60	–	–	80	30
	2 mA	–	75	120	160	60
SSTL/HSTL Standards						
Conditions		**Output Pin Adder Delay (ps/pF)**				
		SSTL-3	SSTL-2	SSTL-1.8	1.5-V HSTL	1.8-V HSTL
Class I		25	25	25	25	25
Class II		25	20	25	20	20
GTL+/GTL/CTT/PCI Standards						
Conditions		**Output Pin Adder Delay (ps/pF)**				
Parameter	**Value**	GTL+	GTL	CTT	PCI	AGP
V_{CCIO} voltage level	3.3 V	18	18	25	20	20
	2.5 V	15	18	-	-	-