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### Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	2566
Number of Logic Elements/Cells	25660
Total RAM Bits	1944576
Number of I/O	607
Number of Gates	-
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1020-BBGA
Supplier Device Package	1020-FBGA (33x33)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep1sgx25ff1020c5n">https://www.e-xfl.com/product-detail/intel/ep1sgx25ff1020c5n</a>

### Transceiver Blocks

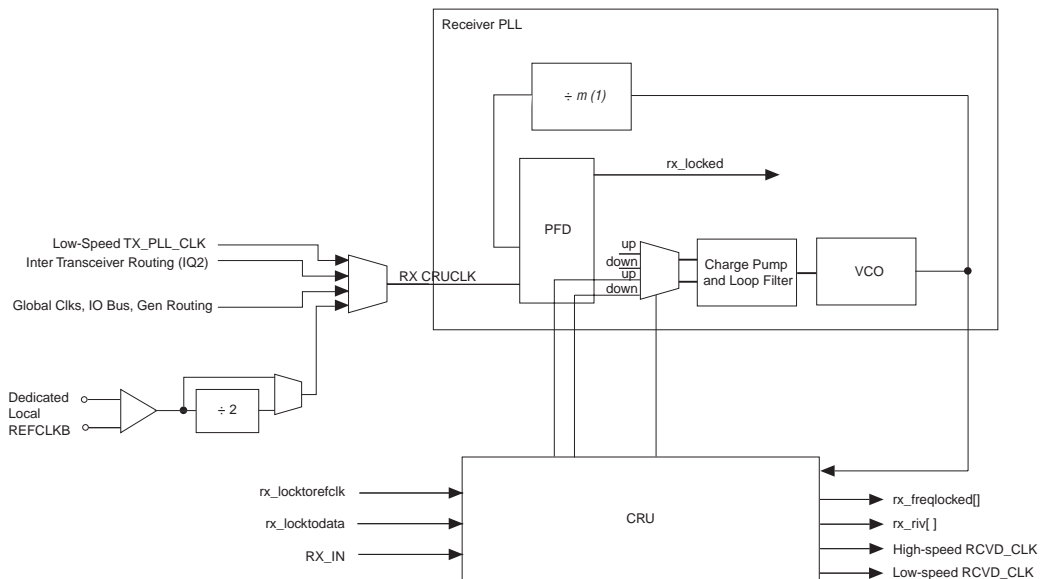
Stratix® GX devices incorporate dedicated embedded circuitry on the right side of the device, which contains up to 20 high-speed 3.1875-Gbps serial transceiver channels. Each Stratix GX transceiver block contains four full-duplex channels and supporting logic to transmit and receive high-speed serial data streams. The transceiver block uses the channels to deliver bidirectional point-to-point data transmissions with up to 3.1875 Gbps of data transition per channel.

There are up to 20 transceiver channels available on a single Stratix GX device. [Table 2–1](#) shows the number of transceiver channels available on each Stratix GX device.

<i>Table 2–1. Stratix GX Transceiver Channels</i>	
Device	Number of Transceiver Channels
EP1SGX10C	4
EP1SGX10D	8
EP1SGX25C	4
EP1SGX25D	8
EP1SGX25F	16
EP1SGX40D	8
EP1SGX40G	20

[Figure 2–1](#) shows the elements of the transceiver block, including the four channels, supporting logic, and I/O buffers. Each transceiver channel consists of a receiver and transmitter. The supporting logic contains a transmitter PLL to generate a high-speed clock used by the four transmitters. The receiver PLL within each transceiver channel generates the receiver reference clocks. The supporting logic also contains state machines to manage rate matching for XAUI and GIGE applications, in addition to channel bonding for XAUI applications.

**Figure 2–13. Receiver PLL & CRU Circuit**

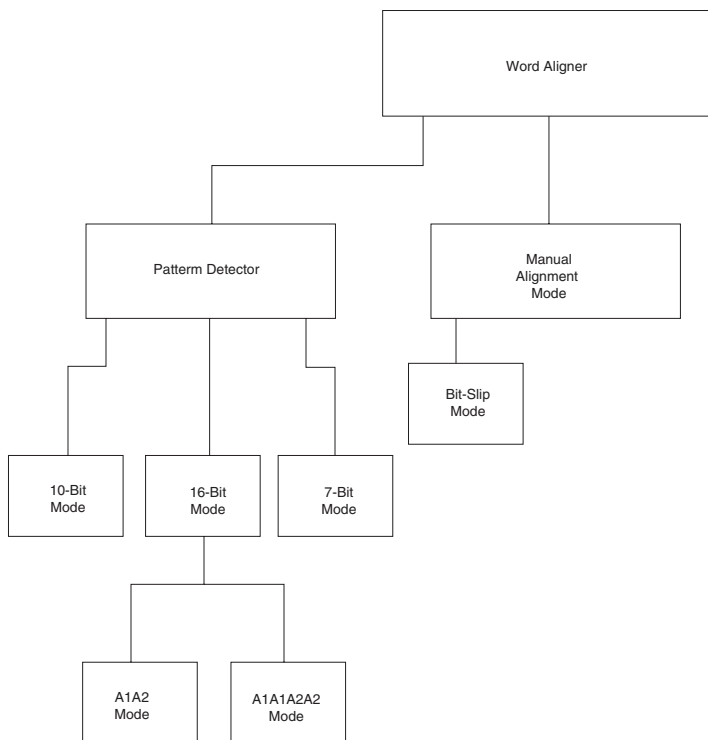


**Note to Figure 2–13:**  
(1)  $m = 8, 10, 16, \text{ or } 20$ .

The receiver PLLs and CRUs are capable of supporting up to 3.1875 Gbps. The input clock frequency for –5 and –6 speed grade devices is limited to 650 MHz if you use the REFCLKB pin or 325 MHz if you use the other clock routing resources. The maximum input clock frequency for –7 speed grade devices is 312.5 MHz if you use the REFCLKB pin or 156.25 MHz with the other clock routing resources. An optional RX\_LOCKED port (active low signal) is available to indicate whether the PLL is locked to the reference clock. The receiver PLL has a programmable loop bandwidth, which can be set to low, medium, or high. The loop bandwidth parameter can be statically set by the Quartus II software.

Table 2–5 lists the adjustable parameters of the receiver PLL and CRU. All the parameters listed are statically programmable in the Quartus II software.

<b>Table 2–5. Receiver PLL &amp; CRU Adjustable Parameters (Part 1 of 2)</b>	
<b>Parameter</b>	<b>Specifications</b>
Input reference frequency range	25 MHz to 650 MHz
Data rate support	500 Mbps to 3.1875 Gbps

**Figure 2–15. Word Aligner in Bit-Slip Mode**

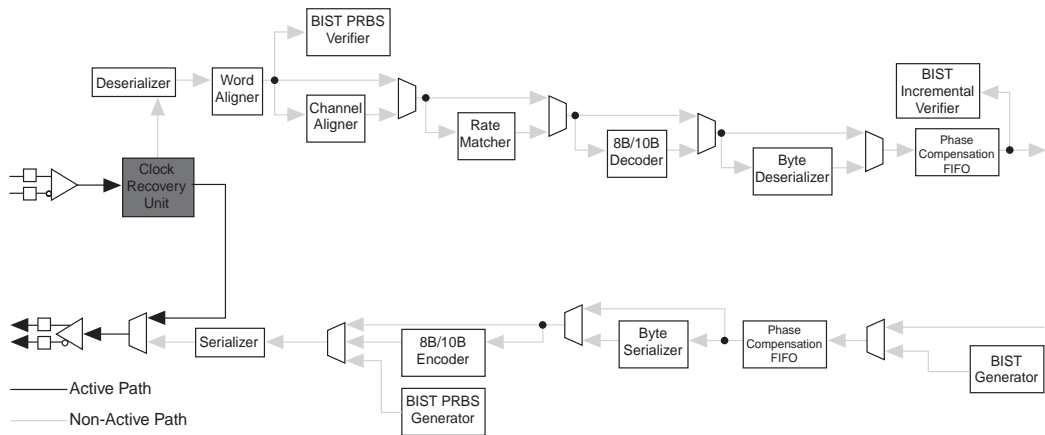
In the bit-slip mode, the byte boundary can be modified by a barrel shifter to slip the byte boundary one bit at a time via a user-controlled bit-slip port. The bit-slip mode supports both 8-bit and 10-bit data paths operating in a single or double-width mode.

The pattern detector is active in the bit-slip mode, and it detects the user-defined pattern that is specified in the MegaWizard® Plug-In Manager.

The bit-slip mode is available only in Custom mode and SONET mode.

Figure 2–16 shows the word aligner in 16-bit mode.

**Figure 2–23. Data Path in Reverse Serial Loopback Mode**



## BIST (Built-In Self Test)

The Stratix GX transceiver has built-in self test modes to aid in debug and testing. The BIST modes are set in the Stratix GX MegaWizard Plug-In Manager in the Quartus II software. Only one BIST mode can be set for any single instance of the transceiver block. The BIST mode applies to all channels used in a transceiver.

The following is a list of the available BIST modes:

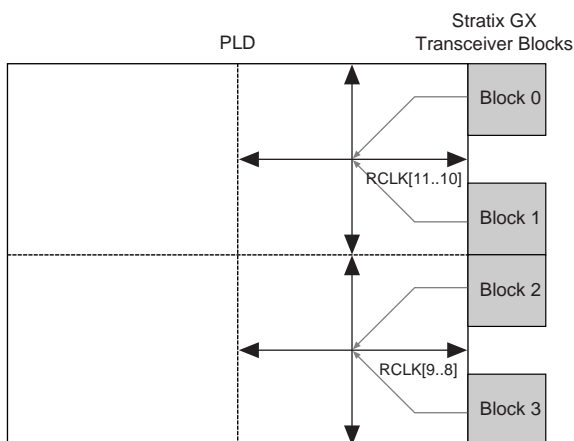
- PRBS generator and verifier
- Incremental mode generator and verifier
- High-frequency generator
- Low-frequency generator
- Mixed-frequency generator

Figures 2–24 and 2–25 are diagrams of the BIST PRBS data path and the BIST incremental data path, respectively.

The receiver PLL can also drive the fast regional, regional clocks, and local routing adjacent to the associated transceiver block. Figures 2–28 through 2–31 show which fast regional and regional clock resource can be used by the recovered clock.

In the EP1SGX25 device, the receiver PLL recovered clocks from transceiver blocks 0 and 1 drive RCLK[1..0] while transceiver blocks 2 and 3 drive RCLK[7..6]. The regional clocks feed logic in their associated regions.

**Figure 2–28. EP1SGX25 Receiver PLL Recovered Clock to Regional Clock Connection**

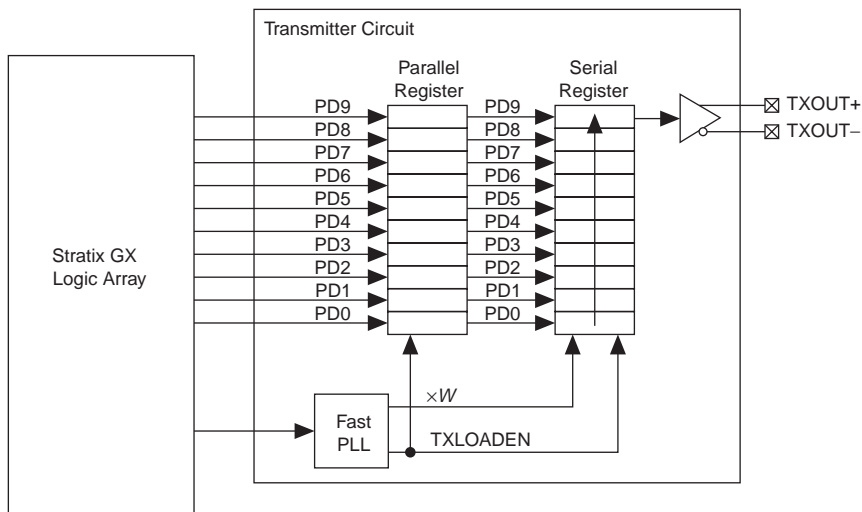


In addition, the receiver PLL's recovered clocks can drive fast regional lines (FCLK) as shown Figure 2–29. The fast regional clocks can feed logic in their associated regions.

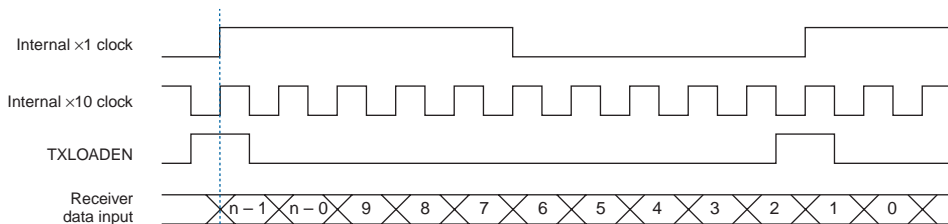
The logic array sends parallel data to the SERDES transmitter circuit when the TXLOADEN signal is asserted. This signal is generated by the high-speed counter circuitry of the logic array low-frequency clock's rising edge. The data is then transferred from the parallel register into the serial shift register by the TXLOADEN signal on the third rising edge of the high-frequency clock.

Figure 3–3 shows the block diagram of a single SERDES transmitter channel and Figure 3–4 shows the timing relationship between the data and clocks in Stratix GX devices in  $\times 10$  mode.  $W$  is the low-frequency multiplier and  $J$  is the data parallelization division factor.

**Figure 3–3. Stratix GX High-Speed Interface Serialized in  $\times 10$  Mode**

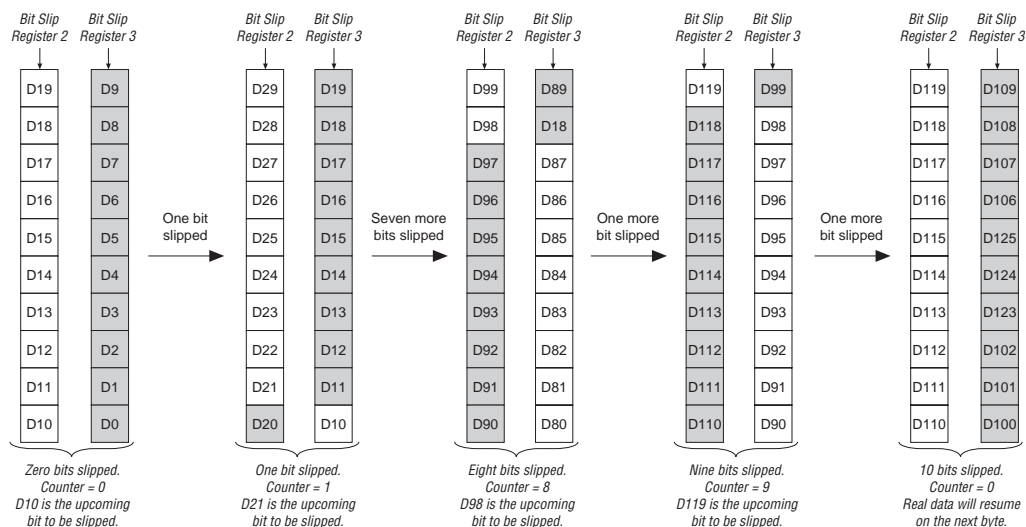


**Figure 3–4. Transmitter Timing Diagram**



The DPA data-realignment circuitry allows further realignment beyond what the  $J$  multiplication factor allows. You can set the  $J$  multiplication factor to be 8 or 10. However, because data must be continuously clocked in on each low-speed clock cycle, the upcoming bit to be realigned and previous  $n - 1$  bits of data are selected each time the data realignment logic's counter passes  $n - 1$ . At this point the data is selected entirely from bit-slip register 3 (see Figure 3–11) as the counter is reset to 0. The logic array receives a new valid byte of data on the next divided low speed clock cycle. Figure 3–11 shows the data realignment logic output selection from data in the data realignment register 2 and data realignment register 3 based on its current counter value upon continuous request of data slipping from the logic array.

**Figure 3–11. DPA Data Realigner**



Use the `rx_channel_data_align` signal within the device to activate the data realigner. You can use internal logic or an external pin to control the `rx_channel_data_align` signal. To ensure the rising edge of the `rx_channel_data_align` signal is latched into the control logic, the `rx_channel_data_align` signal should stay high for at least two low-frequency clock cycles.



its own fan-out LUT. This provides another mechanism for improved fitting. The LE can also drive out registered and unregistered versions of the LUT output.

## LUT Chain & Register Chain

In addition to the three general routing outputs, the LEs within an LAB have LUT chain and register chain outputs. LUT chain connections allow LUTs within the same LAB to cascade together for wide input functions. Register chain outputs allow registers within the same LAB to cascade together. The register chain output allows an LAB to use LUTs for a single combinatorial function and the registers to be used for an unrelated shift register implementation. These resources speed up connections between LABs while saving local interconnect resources. See [“MultiTrack Interconnect” on page 4–11](#) for more information on LUT chain and register chain connections.

## addnsub Signal

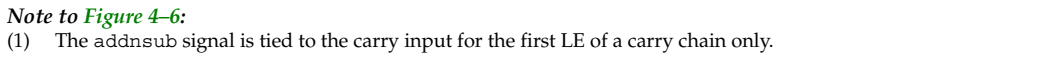
The LE’s dynamic adder/subtractor feature saves logic resources by using one set of LEs to implement both an adder and a subtractor. This feature is controlled by the LAB-wide control signal `addnsub`. The `addnsub` signal sets the LAB to perform either  $A + B$  or  $A - B$ . The LUT computes addition, and subtraction is computed by adding the two’s complement of the intended subtractor. The LAB-wide signal converts to two’s complement by inverting the B bits within the LAB and setting carry-in = 1 to add one to the least significant bit (LSB). The LSB of an adder/subtractor must be placed in the first LE of the LAB, where the LAB-wide `addnsub` signal automatically sets the carry-in to 1. The Quartus II Compiler automatically places and uses the adder/subtractor feature when using adder/subtractor parameterized functions.

## LE Operating Modes

The Stratix GX LE can operate in one of the following modes:

- Normal mode
- Dynamic arithmetic mode

Each mode uses LE resources differently. In each mode, eight available inputs to the LE—the four data inputs from the LAB local interconnect; `carry-in0` and `carry-in1` from the previous LE; the LAB carry-in from the previous carry-chain LAB; and the register chain connection—are directed to different destinations to implement the desired logic function. LAB-wide signals provide clock, asynchronous clear, asynchronous preset load, synchronous clear, synchronous load, and



M4K RAM blocks support byte writes when the write port has a data width of 16, 18, 32, or 36 bits. The byte enables allow the input data to be masked so the device can write to specific bytes. The unwritten bytes retain the previous written value. Table 4–6 summarizes the byte selection.

<b>Table 4–6. Byte Enable for M4K Blocks</b> <i>Notes (1), (2)</i>		
<b>byteena[3..0]</b>	<b>datain ×18</b>	<b>datain ×36</b>
[0] = 1	[8..0]	[8..0]
[1] = 1	[17..9]	[17..9]
[2] = 1	–	[26..18]
[3] = 1	–	[35..27]

**Notes to Table 4–6:**

- (1) Any combination of byte enables is possible.
- (2) Byte enables can be used in the same manner with 8-bit words, that is, in ×16 and ×32 modes.

The M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (renwe, address, byte enable, datain, and output registers). Only the output register can be bypassed. The eight labclk signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. LEs can also control the clock\_a, clock\_b, renwe\_a, renwe\_b, clr\_a, clr\_b, clocken\_a, and clocken\_b signals, as shown in Figure 4–16.

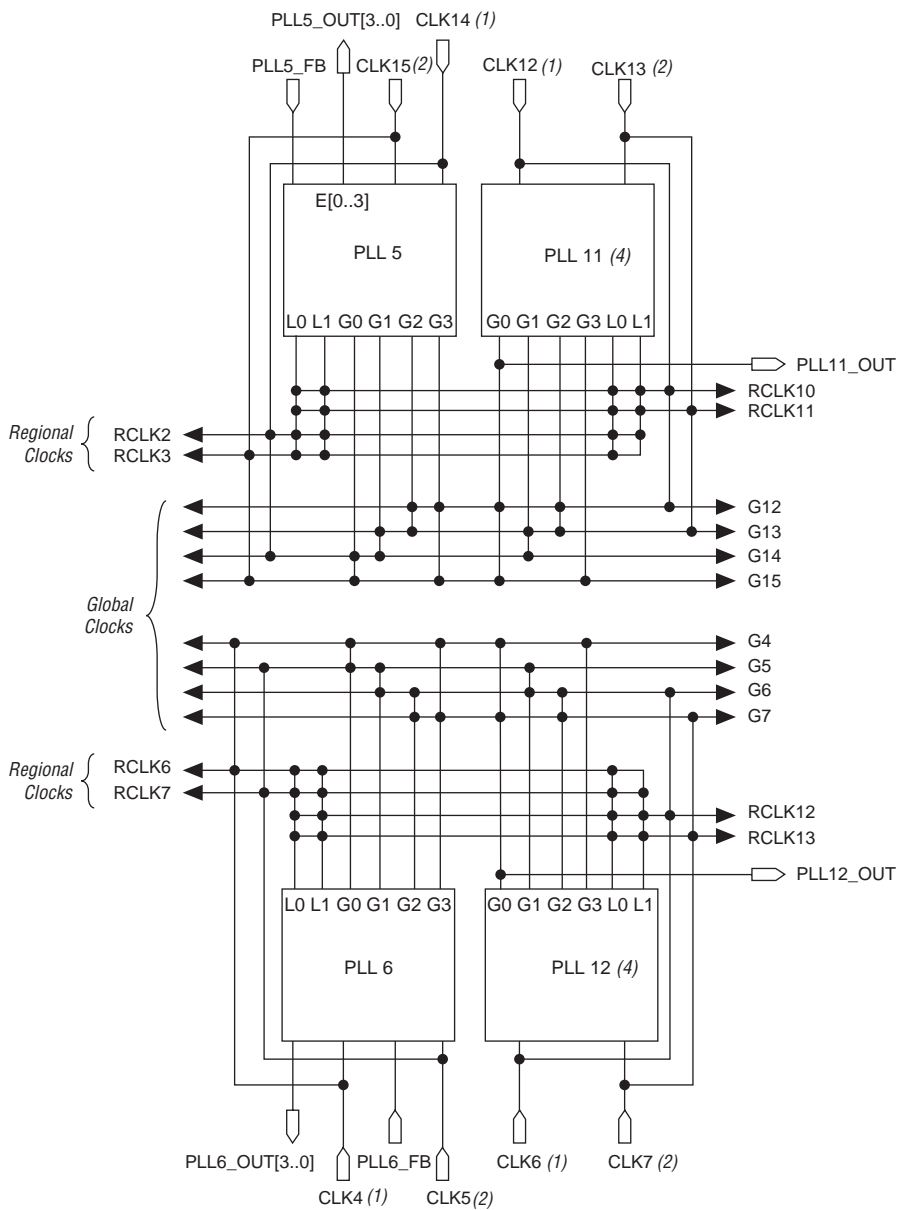
The R4, R8, C4, C8, and direct link interconnects from adjacent LABs drive the M4K RAM block local interconnect. The M4K RAM blocks can communicate with LABs on either the left or right side through these row resources or with LAB columns on either the right or left with the column resources. Up to 10 direct link input connections to the M4K RAM Block are possible from the left adjacent LABs and another 10 possible from the right adjacent LAB. M4K RAM block outputs can also connect to left and right LABs through 10 direct link interconnects each. Figure 4–17 shows the M4K RAM block to logic array interface.

### *Pipeline/Post Multiply Register*

The output of  $9 \times 9$ - or  $18 \times 18$ -bit multipliers can optionally feed a register to pipeline multiply-accumulate and multiply-add/subtract functions. For  $36 \times 36$ -bit multipliers, this register pipelines the multiplier function.

### **Adder/Output Blocks**

The result of the multiplier sub-blocks are sent to the adder/output block which consist of an adder/subtractor/accumulator unit, summation unit, output select multiplexer, and output registers. The results are used to configure the adder/output block as a pure output, accumulator, a simple two-multiplier adder, four-multiplier adder, or final stage of the 36-bit multiplier. You can configure the adder/output block to use output registers in any mode, and must use output registers for the accumulator. The system cannot use adder/output blocks independently of the multiplier. [Figure 4-33](#) shows the adder and output stages.

**Figure 4–50. Global & Regional Clock Connections From Top Clock Pins & Enhanced PLL Outputs** *Note (1)***Note to Figure 4–50:**

(1) PLLs 5, 6, 11, and 12 are enhanced PLLs.

pin. The I/O standards supported by any particular bank determines what standards are possible for an external clock output driven by the fast PLL in that bank.

Table 4–20 shows the I/O standards supported by fast PLL input pins.

<b>Table 4–20. Fast PLL Port Input Pin I/O Standards</b>		
<b>I/O Standard</b>	<b>Input</b>	
	<b>INCLK</b>	<b>PLEENABLE</b>
LVTTTL	✓	✓
LVCMOS	✓	✓
2.5 V	✓	
1.8 V	✓	
1.5 V	✓	
3.3-V PCI		
3.3-V PCI-X		
LVPECL	✓	
3.3-V PCML	✓	
LVDS	✓	
HyperTransport technology	✓	
Differential HSTL	✓	
Differential SSTL		
3.3-V GTL	✓	
3.3-V GTL+	✓	
1.5V HSTL class I	✓	
1.5V HSTL class II	✓	
SSTL-18 class I	✓	
SSTL-18 class II	✓	
SSTL-2 class I	✓	
SSTL-2 class II	✓	
SSTL-3 class I	✓	
SSTL-3 class II	✓	
AGP (1× and 2×)	✓	
CTT	✓	

### *Phase Shifting*

Stratix GX device fast PLLs have advanced clock shift capability that enables programmable phase shifts. You can enter a phase shift (in degrees or time units) for each PLL clock output port or for all outputs together in one shift. You can perform phase shifting in time units with a resolution range of 150 to 400 ps. This resolution is a function of the VCO period.

### *Control Signals*

The fast PLL has the same `lock` output, `pllenable` input, and `areset` input control signals as the enhanced PLL.

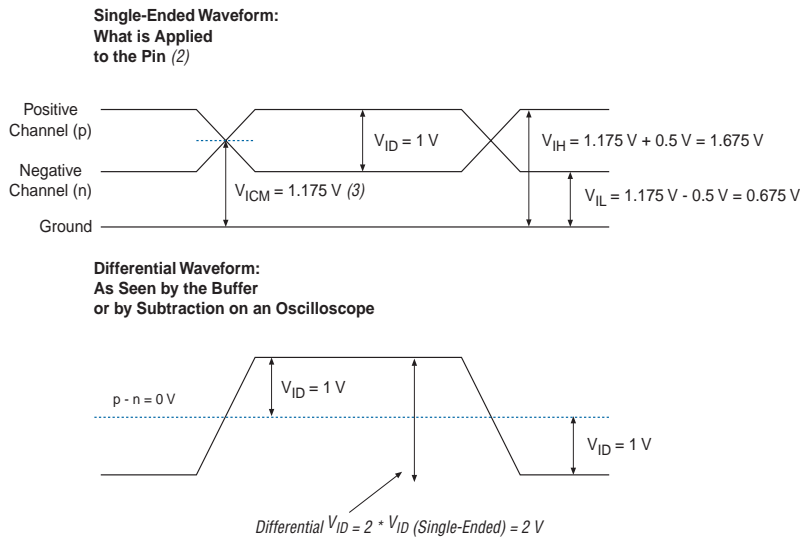
For more information on high-speed differential I/O support, see the *High-Speed Source-Synchronous Differential I/O Interfaces in Stratix GX Devices* chapter of the *Stratix GX Device Handbook, Volume 2*.

## I/O Structure

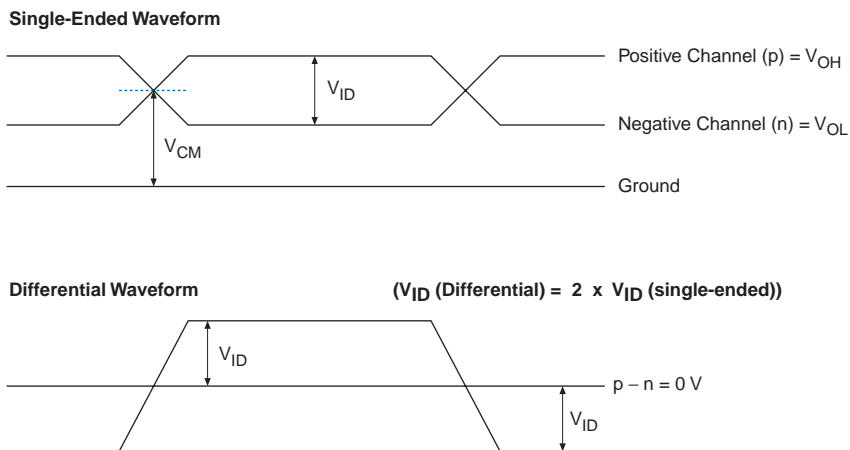
IOEs provide many features, including:

- Dedicated differential and single-ended I/O buffers
- 3.3-V, 64-bit, 66-MHz PCI compliance
- 3.3-V, 64-bit, 133-MHz PCI-X 1.0 compliance
- Joint Test Action Group (JTAG) boundary-scan test (BST) support
- Differential on-chip termination for LVDS I/O standard
- Programmable pull-up during configuration
- Output drive strength control
- Slew-rate control
- Tri-state buffers
- Bus-hold circuitry
- Programmable pull-up resistors
- Programmable input and output delays
- Open-drain outputs
- DQ and DQS I/O pins
- Double-data rate (DDR) Registers

The IOE in Stratix GX devices contains a bidirectional I/O buffer, six registers, and a latch for a complete embedded bidirectional single data rate or DDR transfer. [Figure 4–58](#) shows the Stratix GX IOE structure. The IOE contains two input registers (plus a latch), two output registers, and two output enable registers. The design can use both input registers and the latch to capture DDR input and both output registers to drive DDR outputs. Additionally, the design can use the output enable (OE) register for fast clock-to-output enable timing. The negative edge-clocked OE register is used for DDR SDRAM interfacing. The Quartus II software automatically duplicates a single OE register that controls multiple output or bidirectional pins.

**Figure 6–2. Receiver Input Waveform Example with Values****Notes to Figure 6–2:**

- (1) The values in this figure are for example only.
- (2) These values must meet the voltages specified in the section “Operating Conditions” on page 6–1.
- (3) If internal termination is used, the common mode is generated after the pins.

**Figure 6–3. Transmitter Output Waveforms for Differential I/O Standards**



**Table 6–35. Stratix GX Device Performance (Part 2 of 3)** *Notes (1), (2)*

Applications		Resources Used			Performance			
		LEs	TriMatrix Memory Blocks	DSP Blocks	-5 Speed Grade	-6 Speed Grade	-7 Speed Grade	Units
TriMatrix memory M512 block	Simple dual-port RAM 32 × 18 bit	0	1	0	317.76	277.62	241.48	MHz
	FIFO 32 × 18 bit	30	1	0	319.18	278.86	242.54	MHz
TriMatrix memory M4K block	Simple dual-port RAM 128 × 36 bit	0	1	0	290.86	255.55	222.27	MHz
	True dual-port RAM 128 × 18 bit	0	1	0	290.86	255.55	222.27	MHz
	FIFO 128 × 36 bit	34	1	0	290.86	255.55	222.27	MHz
TriMatrix memory M-RAM block	Single port RAM 4K × 144 bit	1	1	0	255.95	223.06	194.06	MHz
	Simple dual-port RAM 4K × 144 bit	0	1	0	255.95	233.06	194.06	MHz
	True dual-port RAM 4K × 144 bit	0	1	0	255.95	233.06	194.06	MHz
	Single port RAM 8K × 72 bit	0	1	0	278.94	243.19	211.59	MHz
	Simple dual-port RAM 8K × 72 bit	0	1	0	255.95	223.06	194.06	MHz
	True dual-port RAM 8K × 72 bit	0	1	0	255.95	223.06	194.06	MHz
	Single port RAM 16K × 36 bit	0	1	0	280.66	254.32	221.28	MHz
	Simple dual-port RAM 16K × 36 bit	0	1	0	269.83	237.69	206.82	MHz

**Table 6–87. High-Speed I/O Specifications (Part 3 of 4)** *Notes (1), (2)*

Symbol	Conditions			-5 Speed Grade			-6 Speed Grade			-7 Speed Grade			Unit
				Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
DPA Lock Time	Standard	Training Pattern	Transition Density										
	SPI-4, CSIX	0000 0000 0011 1111 1111	10%	256			256			256			(4)
	Rapid IO	0000 1111	25%	256			256			256			(4)
		1001 0000	50%	256			256			256			(4)
	Misc	1010 1010	100 %	256			256			256			(4)
		0101 0101		256			256			256			(4)
TCCS	All					200			200			300	ps
SW	PCML ( $J = 4, 7, 8, 10$ )			750			750			800			ps
	PCML ( $J = 2$ )			900			900			1,200			ps
	PCML ( $J = 1$ )			1,500			1,500			1,700			ps
	LVDS and LVPECL ( $J = 1$ )			500			500			550			ps
	LVDS, LVPECL, HyperTransport technology ( $J = 2$ through 10)			440			440			500			ps
Input jitter tolerance (peak-to-peak)	All					250			250			250	ps
Output jitter (peak-to-peak)	All					160			160			200	ps
Output $t_{RISE}$	LVDS			80	110	120	80	110	120	80	110	120	ps
	HyperTransport technology			110	170	200	110	170	200	120	170	200	ps
	LVPECL			90	130	150	90	130	150	100	135	150	ps
	PCML			80	110	135	80	110	135	80	110	135	ps

**Table 6–88. Enhanced PLL Specifications for -5 Speed Grades (Part 2 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{OUTDUTY}}$	Duty cycle for external clock output (when set to 50%)	45		55	%
$t_{\text{JITTER}}$	Period jitter for external clock output (5)			$\pm 100$ ps for >200 MHz $\text{outclk}$ $\pm 20$ mUI for <200 MHz $\text{outclk}$	ps or mUI
$t_{\text{CONFIG5,6}}$	Time required to reconfigure the scan chains for PLLs 5 and 6			$289/f_{\text{SCANCLK}}$	
$t_{\text{CONFIG11,12}}$	Time required to reconfigure the scan chains for PLLs 11 and 12			$193/f_{\text{SCANCLK}}$	
$t_{\text{SCANCLK}}$	$\text{scanclk}$ frequency (4)			22	MHz
$t_{\text{DLOCK}}$	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays) (6)			100	$\mu\text{s}$
$t_{\text{LOCK}}$	Time required to lock from end of device configuration	10		400	$\mu\text{s}$
$f_{\text{VCO}}$	PLL internal VCO operating range	300		800 (7)	MHz
$t_{\text{LSKEW}}$	Clock skew between two external clock outputs driven by the same counter		$\pm 50$		ps
$t_{\text{SKEW}}$	Clock skew between two external clock outputs driven by the different counters with the same settings		$\pm 75$		ps
$f_{\text{SS}}$	Spread spectrum modulation frequency	30		150	kHz
% spread	Percentage spread for spread spectrum frequency (9)	0.4	0.5	0.6	%
$t_{\text{ARESET}}$	Minimum pulse width on $\text{areset}$ signal	10			ns

**Table 6–89. Enhanced PLL Specifications for -6 Speed Grades (Part 1 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{\text{IN}}$	Input clock frequency	3 (1)		650	MHz
$f_{\text{INDUTY}}$	Input clock duty cycle	40		60	%
$f_{\text{EINDUTY}}$	External feedback clock input duty cycle	40		60	%
$t_{\text{INJITTER}}$	Input clock period jitter			$\pm 200$ (2)	ps
$t_{\text{EINJITTER}}$	External feedback clock period jitter			$\pm 200$ (2)	ps
$t_{\text{FCOMP}}$	External feedback clock compensation time (3)			6	ns

**Table 6–89. Enhanced PLL Specifications for -6 Speed Grades (Part 2 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{OUT}$	Output frequency for internal global or regional clock	0.3		450	MHz
$f_{OUT\_EXT}$	Output frequency for external clock (2)	0.3		500	MHz
$t_{OUTDUTY}$	Duty cycle for external clock output (when set to 50%)	45		55	%
$t_{JITTER}$	Period jitter for external clock output (5)			$\pm 100$ ps for >200 MHz outclk $\pm 20$ mUI for <200 MHz outclk	ps or mUI
$t_{CONFIG5,6}$	Time required to reconfigure the scan chains for PLLs 5 and 6			$289/f_{SCANCLK}$	
$t_{CONFIG11,12}$	Time required to reconfigure the scan chains for PLLs 11 and 12			$193/f_{SCANCLK}$	
$t_{SCANCLK}$	scanclk frequency (4)			22	MHz
$t_{DLOCK}$	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays) (6) (10)	(8)		100	$\mu$ s
$t_{LOCK}$	Time required to lock from end of device configuration (10)	10		400	$\mu$ s
$f_{VCO}$	PLL internal VCO operating range	300		800 (7)	MHz
$t_{LSKEW}$	Clock skew between two external clock outputs driven by the same counter		$\pm 50$		ps
$t_{SKEW}$	Clock skew between two external clock outputs driven by the different counters with the same settings		$\pm 75$		ps
$f_{SS}$	Spread spectrum modulation frequency	30		150	kHz
% spread	Percentage spread for spread spectrum frequency (9)	0.4	0.5	0.6	%
$t_{ARESET}$	Minimum pulse width on areset signal	10			ns

**Table 6–90. Enhanced PLL Specifications for -7 Speed Grade (Part 1 of 3)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{IN}$	Input clock frequency	3 (1)		565	MHz
$f_{INDUTY}$	Input clock duty cycle	40		60	%
$f_{EINDUTY}$	External feedback clock input duty cycle	40		60	%
$t_{INJITTER}$	Input clock period jitter			$\pm 200$ (2)	ps
$t_{EINJITTER}$	External feedback clock period jitter			$\pm 200$ (2)	ps

Table 6–91 describes the Stratix GX device fast PLL specifications.

<b>Table 6–91. Fast PLL Specifications for -5 &amp; -6 Speed Grade Devices</b>				
<b>Symbol</b>	<b>Parameter</b>	<b>Min</b>	<b>Max</b>	<b>Unit</b>
$f_{IN}$	CLKIN frequency (for $m = 1$ ) (1)	300	717	MHz
	CLKIN frequency (for $m = 2$ to 19)	300/ $m$	1,000/ $m$	MHz
	CLKIN frequency (for $m = 20$ to 32)	10	1,000/ $m$	MHz
$f_{OUT}$	Output frequency for internal global or regional clock (2)	9.4	420	MHz
$f_{OUT\_EXT}$	Output frequency for external clock	9.375	717	MHz
$f_{VCO}$	VCO operating frequency	300	1,000	MHz
$t_{INDUTY}$	CLKIN duty cycle	40	60	%
$t_{INJITTER}$	Period jitter for CLKIN pin		±200	ps
$t_{DUTY}$	Duty cycle for DIFFIO 1 × CLKOUT pin (3)	45	55	%
$t_{JITTER}$	Period jitter for DIFFIO clock out (3)		±80	ps
	Period jitter for internal global or regional clock		±100 ps for >200-MHz outclk ±20 mUI for <200-MHz outclk	ps or mUI
$t_{LOCK}$	Time required for PLL to acquire lock	10	100	μs
$m$	Multiplication factors for $m$ counter (3)	1	32	Integer
$l_0, l_1, g_0$	Multiplication factors for $l_0, l_1$ , and $g_0$ counter (4), (5)	1	32	Integer
$t_{ARESET}$	Minimum pulse width on areset signal	10		ns

<b>Table 6–92. Fast PLL Specifications for -7 &amp; -8 Speed Grades (Part 1 of 2)</b>				
<b>Symbol</b>	<b>Parameter</b>	<b>Min</b>	<b>Max</b>	<b>Unit</b>
$f_{IN}$	CLKIN frequency (for $m = 1$ ) (1),	300	640	MHz
	CLKIN frequency (for $m = 2$ to 19)	300/ $m$	700/ $m$	MHz
	CLKIN frequency (for $m = 20$ to 32)	10	700/ $m$	MHz
$f_{OUT}$	Output frequency for internal global or regional clock (2)	9.375	420	MHz
$f_{OUT\_EXT}$	Output frequency for external clock	9.4	500	MHz
$f_{VCO}$	VCO operating frequency	300	700	MHz
$t_{INDUTY}$	CLKIN duty cycle	40	60	%
$t_{INJITTER}$	Period jitter for CLKIN pin		±200	ps