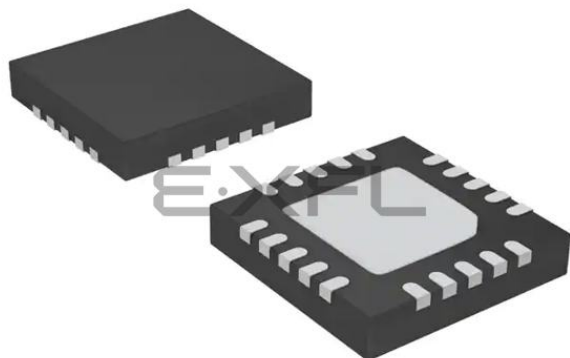




Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	8051
Core Size	8-Bit
Speed	25MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	15
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-VQFN Exposed Pad
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/c8051f854-c-gm

-
- Byte-level bit reversal.
 - Automatic CRC of flash contents on one or more 256-byte blocks.
 - Initial seed selection of 0x0000 or 0xFFFF.

7. SOIC-16 Package Specifications

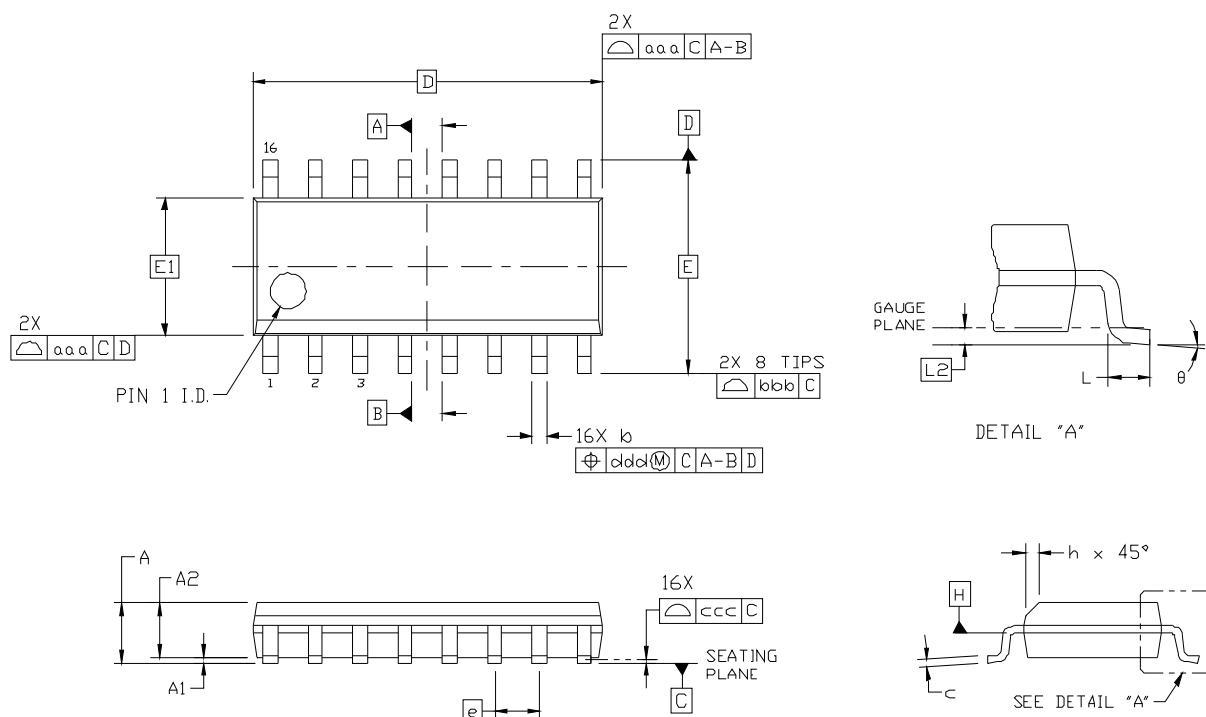


Figure 7.1. SOIC-16 Package Drawing

Table 7.1. SOIC-16 Package Dimensions

Dimension	Min	Nom	Max	Dimension	Min	Nom	Max
A	—		1.75	L	0.40		1.27
A1	0.10		0.25	L2	0.25 BSC		
A2	1.25		—	h	0.25		0.50
b	0.31		0.51	θ	0°		8°
c	0.17		0.25	aaa	0.10		
D	9.90 BSC			bbb	0.20		
E	6.00 BSC			ccc	0.10		
E1	3.90 BSC			ddd	0.25		
e	1.27 BSC						

Notes:

- All dimensions shown are in millimeters (mm) unless otherwise noted.
- Dimensioning and Tolerancing per ANSI Y14.5M-1994.
- This drawing conforms to the JEDEC Solid State Outline MS-012, Variation AC.
- Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

Table 9.2. Special Function Registers (Continued)

Register	Address	Register Description	Page
ADC0L	0xBD	ADC0 Data Word Low Byte	106
ADC0LTH	0xC6	ADC0 Less-Than High Byte	109
ADC0LTL	0xC5	ADC0 Less-Than Low Byte	110
ADC0MX	0xBB	ADC0 Multiplexer Selection	111
ADC0PWR	0xDF	ADC0 Power Control	103
ADC0TK	0xB9	ADC0 Burst Mode Track Time	104
B	0xF0	B Register	123
CKCON	0x8E	Clock Control	269
CLKSEL	0xA9	Clock Selection	129
CPT0CN	0x9B	Comparator 0 Control	134
CPT0MD	0x9D	Comparator 0 Mode	135
CPT0MX	0x9F	Comparator 0 Multiplexer Selection	136
CPT1CN	0xBF	Comparator 1 Control	137
CPT1MD	0xAB	Comparator 1 Mode	138
CPT1MX	0xAA	Comparator 1 Multiplexer Selection	139
CRC0AUTO	0xD2	CRC0 Automatic Control	146
CRC0CN	0xCE	CRC0 Control	143
CRC0CNT	0xD3	CRC0 Automatic Flash Sector Count	147
CRC0DAT	0xDE	CRC0 Data Output	145
CRC0FLIP	0xCF	CRC0 Bit Flip	148
CRC0IN	0xDD	CRC0 Data Input	144
DERIVID	0xAD	Derivative Identification	70
DEVICEID	0xB5	Device Identification	69
DPH	0x83	Data Pointer High	120
DPL	0x82	Data Pointer Low	119
EIE1	0xE6	Extended Interrupt Enable 1	78
EIP1	0xF3	Extended Interrupt Priority 1	80
FLKEY	0xB7	Flash Lock and Key	67

12.2. Interrupt Control Registers

Register 12.1. IE: Interrupt Enable

Bit	7	6	5	4	3	2	1	0
Name	EA	ESPI0	ET2	ES0	ET1	EX1	ET0	EX0
Type	RW	RW	RW	RW	RW	RW	RW	RW
Reset	0	0	0	0	0	0	0	0
SFR Address: 0xA8 (bit-addressable)								

Table 12.2. IE Register Bit Descriptions

Bit	Name	Function
7	EA	Enable All Interrupts. Globally enables/disables all interrupts and overrides individual interrupt mask settings. 0: Disable all interrupt sources. 1: Enable each interrupt according to its individual mask setting.
6	ESPI0	Enable SPI0 Interrupt. This bit sets the masking of the SPI0 interrupts. 0: Disable all SPI0 interrupts. 1: Enable interrupt requests generated by SPI0.
5	ET2	Enable Timer 2 Interrupt. This bit sets the masking of the Timer 2 interrupt. 0: Disable Timer 2 interrupt. 1: Enable interrupt requests generated by the TF2L or TF2H flags.
4	ES0	Enable UART0 Interrupt. This bit sets the masking of the UART0 interrupt. 0: Disable UART0 interrupt. 1: Enable UART0 interrupt.
3	ET1	Enable Timer 1 Interrupt. This bit sets the masking of the Timer 1 interrupt. 0: Disable all Timer 1 interrupt. 1: Enable interrupt requests generated by the TF1 flag.
2	EX1	Enable External Interrupt 1. This bit sets the masking of External Interrupt 1. 0: Disable external interrupt 1. 1: Enable interrupt requests generated by the INT1 input.
1	ET0	Enable Timer 0 Interrupt. This bit sets the masking of the Timer 0 interrupt. 0: Disable all Timer 0 interrupt. 1: Enable interrupt requests generated by the TF0 flag.

14.8. Voltage and Ground Reference Options

The voltage reference multiplexer is configurable to use an externally connected voltage reference, the internal voltage reference, or one of two power supply voltages. The ground reference mux allows the ground reference for ADC0 to be selected between the ground pin (GND) or a port pin dedicated to analog ground (AGND).

The voltage and ground reference options are configured using the REF0CN register.

Important Note About the VREF and AGND Inputs: Port pins are used as the external VREF and AGND inputs. When using an external voltage reference, VREF should be configured as an analog input and skipped by the digital crossbar. When using AGND as the ground reference to ADC0, AGND should be configured as an analog input and skipped by the Digital Crossbar.

14.8.1. External Voltage Reference

To use an external voltage reference, REFSL should be set to 00. Bypass capacitors should be added as recommended by the manufacturer of the external voltage reference. If the manufacturer does not provide recommendations, a 4.7uF in parallel with a 0.1uF capacitor is recommended.

14.8.2. Internal Voltage Reference

For applications requiring the maximum number of port I/O pins, or very short VREF turn-on time, the high-speed reference will be the best internal reference option to choose. The internal reference is selected by setting REFSL to 11. When selected, the internal reference will be automatically enabled/disabled on an as-needed basis by the ADC. The reference can be set to one of two voltage values: 1.65 V or 2.4 V, depending on the value of the IREFLVL bit.

For applications with a non-varying power supply voltage, using the power supply as the voltage reference can provide the ADC with added dynamic range at the cost of reduced power supply noise rejection. To use the external supply pin (VDD) or the 1.8 V regulated digital supply voltage as the reference source, REFSL should be set to 01 or 10, respectively.

Internal reference sources are not routed to the VREF pin, and do not require external capacitors. The electrical specifications tables detail SAR clock and throughput limitations for each reference source.

14.8.3. Analog Ground Reference

To prevent ground noise generated by switching digital logic from affecting sensitive analog measurements, a separate analog ground reference option is available. When enabled, the ground reference for the ADC during both the tracking/sampling and the conversion periods is taken from the AGND pin. Any external sensors sampled by the ADC should be referenced to the AGND pin. If an external voltage reference is used, the AGND pin should be connected to the ground of the external reference and its associated decoupling capacitor. The separate analog ground reference option is enabled by setting GNDSL to 1. Note that when sampling the internal temperature sensor, the internal chip ground is always used for the sampling operation, regardless of the setting of the GNDSL bit. Similarly, whenever the internal 1.65 V high-speed reference is selected, the internal chip ground is always used during the conversion period, regardless of the setting of the GNDSL bit.

Table 15.1. CIP-51 Instruction Set Summary (Continued)

Mnemonic	Description	Bytes	Clock Cycles
XCH A, Rn	Exchange Register with A	1	1
XCH A, direct	Exchange direct byte with A	2	2
XCH A, @Ri	Exchange indirect RAM with A	1	2
XCHD A, @Ri	Exchange low nibble of indirect RAM with A	1	2
Boolean Manipulation			
CLR C	Clear Carry	1	1
CLR bit	Clear direct bit	2	2
SETB C	Set Carry	1	1
SETB bit	Set direct bit	2	2
CPL C	Complement Carry	1	1
CPL bit	Complement direct bit	2	2
ANL C, bit	AND direct bit to Carry	2	2
ANL C, /bit	AND complement of direct bit to Carry	2	2
ORL C, bit	OR direct bit to carry	2	2
ORL C, /bit	OR complement of direct bit to Carry	2	2
MOV C, bit	Move direct bit to Carry	2	2
MOV bit, C	Move Carry to direct bit	2	2
JC rel	Jump if Carry is set	2	2/3
JNC rel	Jump if Carry is not set	2	2/3
JB bit, rel	Jump if direct bit is set	3	3/4
JNB bit, rel	Jump if direct bit is not set	3	3/4
JBC bit, rel	Jump if direct bit is set and clear bit	3	3/4
Program Branching			
ACALL addr11	Absolute subroutine call	2	3
LCALL addr16	Long subroutine call	3	4
RET	Return from subroutine	1	5
RETI	Return from interrupt	1	5
AJMP addr11	Absolute jump	2	3
LJMP addr16	Long jump	3	4
SJMP rel	Short jump (relative address)	2	3
JMP @A+DPTR	Jump indirect relative to DPTR	1	3
JZ rel	Jump if A equals zero	2	2/3
JNZ rel	Jump if A does not equal zero	2	2/3
CJNE A, direct, rel	Compare direct byte to A and jump if not equal	3	3/4
CJNE A, #data, rel	Compare immediate to A and jump if not equal	3	3/4
CJNE Rn, #data, rel	Compare immediate to Register and jump if not equal	3	3/4
CJNE @Ri, #data, rel	Compare immediate to indirect and jump if not equal	3	4/5
DJNZ Rn, rel	Decrement Register and jump if not zero	2	2/3

Register 20.13. PCA0CPM2: PCA Capture/Compare Mode

Bit	7	6	5	4	3	2	1	0
Name	PWM16	ECOM	CAPP	CAPN	MAT	TOG	PWM	ECCF
Type	RW	RW	RW	RW	RW	RW	RW	RW
Reset	0	0	0	0	0	0	0	0
SFR Address: 0xDC								

Table 20.15. PCA0CPM2 Register Bit Descriptions

Bit	Name	Function
7	PWM16	16-bit Pulse Width Modulation Enable. This bit enables 16-bit mode when Pulse Width Modulation mode is enabled. 0: 8 to 11-bit PWM selected. 1: 16-bit PWM selected.
6	ECOM	Comparator Function Enable. This bit enables the comparator function.
5	CAPP	Capture Positive Function Enable. This bit enables the positive edge capture capability.
4	CAPN	Capture Negative Function Enable. This bit enables the negative edge capture capability.
3	MAT	Match Function Enable. This bit enables the match function. When enabled, matches of the PCA counter with a module's capture/compare register cause the CCF2 bit in the PCA0MD register to be set to logic 1.
2	TOG	Toggle Function Enable. This bit enables the toggle function. When enabled, matches of the PCA counter with the capture/compare register cause the logic level on the CEX2 pin to toggle. If the PWM bit is also set to logic 1, the module operates in Frequency Output Mode.
1	PWM	Pulse Width Modulation Mode Enable. This bit enables the PWM function. When enabled, a pulse width modulated signal is output on the CEX2 pin. 8 to 11-bit PWM is used if PWM16 is cleared; 16-bit mode is used if PWM16 is set to logic 1. If the TOG bit is also set, the module operates in Frequency Output Mode.
0	ECCF	Capture/Compare Flag Interrupt Enable. This bit sets the masking of the Capture/Compare Flag (CCF2) interrupt. 0: Disable CCF2 interrupts. 1: Enable a Capture/Compare Flag interrupt request when CCF2 is set.

21.2. Assigning Port I/O Pins to Analog and Digital Functions

Port I/O pins can be assigned to various analog, digital, and external interrupt functions. The port pins assigned to analog functions should be configured for analog I/O, and port pins assigned to digital or external interrupt functions should be configured for digital I/O.

21.2.1. Assigning Port I/O Pins to Analog Functions

Table 21.1 shows all available analog functions that require port I/O assignments. Table 21.1 shows the potential mapping of port I/O to each analog function.

Table 21.1. Port I/O Assignment for Analog Functions

Analog Function	Potentially Assignable Port Pins	SFR(s) used for Assignment
ADC Input	P0.0 - P1.7	ADC0MX, PnSKIP, PnMDIN
Comparator0 Input	P0.0 - P1.7	CPT0MX, PnSKIP, PnMDIN
Comparator1 Input	P0.0 - P1.7	CPT1MX, PnSKIP, PnMDIN
Voltage Reference (VREF)	P0.0	REF0CN, PnSKIP, PnMDIN
Reference Ground (AGND)	P0.1	REF0CN, PnSKIP, PnMDIN

21.2.2. Assigning Port I/O Pins to Digital Functions

Any port pins not assigned to analog functions may be assigned to digital functions or used as GPIO. Most digital functions rely on the crossbar for pin assignment; however, some digital functions bypass the crossbar in a manner similar to the analog functions listed above. Table 21.2 shows all digital functions available through the crossbar and the potential mapping of port I/O to each function.

Table 21.2. Port I/O Assignment for Digital Functions

Digital Function	Potentially Assignable Port Pins	SFR(s) Used for Assignment
UART0, SPI0, SMBus0, CP0, CP0A, CP1, CP1A, SYSCLK, PCA0 (CEX0-2 and ECI), T0, T1 or T2.	Any port pin available for assignment by the crossbar. This includes P0.0 - P1.7 pins which have their PnSKIP bit set to '0'. Note: The crossbar will always assign UART0 pins to P0.4 and P0.5.	XBR0, XBR1, XBR2
Any pin used for GPIO	P0.0 - P2.1	P0SKIP, P1SKIP, P2SKIP

21.4.3. Port Drive Strength

Port drive strength can be controlled on a port-by-port basis using the PRTDRV register. Each port has a bit in PRTDRV to select the high or low drive strength setting for all pins on that port. By default, all ports are configured for high drive strength.

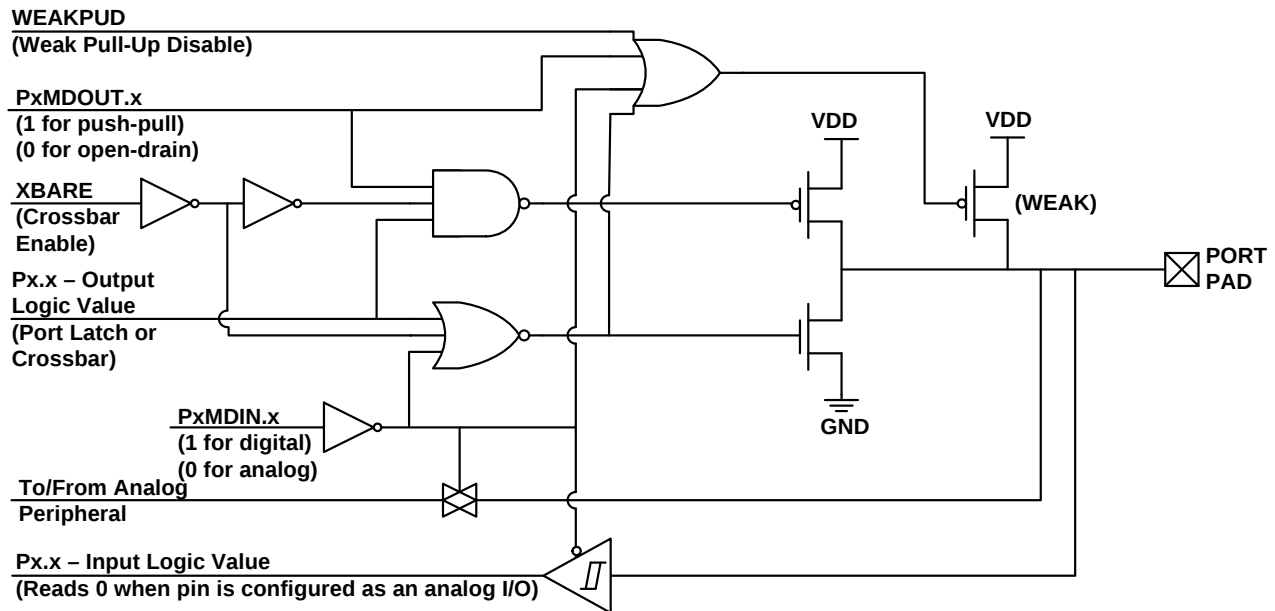


Figure 21.4. Port I/O Cell Block Diagram

21.5. Port Match

Port match functionality allows system events to be triggered by a logic value change on one or more port I/O pins. A software controlled value stored in the PnMATCH registers specifies the expected or normal logic values of the associated port pins (for example, P0MATCH.0 would correspond to P0.0). A port mismatch event occurs if the logic levels of the port's input pins no longer match the software controlled value. This allows software to be notified if a certain change or pattern occurs on the input pins regardless of the XBRn settings.

The PnMASK registers can be used to individually select which pins should be compared against the PnMATCH registers. A port mismatch event is generated if $(Pn \& PnMASK) \neq (PnMATCH \& PnMASK)$ for all ports with a PnMAT and PnMASK register.

A port mismatch event may be used to generate an interrupt or wake the device from idle mode. See the interrupts and power options chapters for more details on interrupt and wake-up sources.

21.6. Direct Read/Write Access to Port I/O Pins

All port I/O are accessed through corresponding special function registers (SFRs) that are both byte addressable and bit addressable. When writing to a port, the value written to the SFR is latched to maintain the output data value at each pin. When reading, the logic levels of the port's input pins are returned regardless of the XBRn settings (i.e., even when the pin is assigned to another signal by the crossbar, the port register can always read its corresponding port I/O pin). The exception to this is the execution of the read-modify-write instructions that target a Port Latch register as the destination. The read-modify-write instructions when operating on a port SFR are the following: ANL, ORL, XRL, JBC, CPL, INC, DEC, DJNZ and MOV, CLR or SETB, when the destination is an individual bit in a port SFR. For these instructions, the value of the latch register (not the pin) is read, modified, and written back to the SFR.

22.11. Supply Monitor Control Registers

Register 22.2. VDM0CN: Supply Monitor Control

Bit	7	6	5	4	3	2	1	0
Name	VDMEN	VDDSTAT	Reserved					
Type	RW	R	R					
Reset	X	X	X	X	X	X	X	X
SFR Address: 0xFF								

Table 22.2. VDM0CN Register Bit Descriptions

Bit	Name	Function
7	VDMEN	Supply Monitor Enable. This bit turns the supply monitor circuit on/off. The supply monitor cannot generate system resets until it is also selected as a reset source in register RSTSRC. Selecting the supply monitor as a reset source before it has stabilized may generate a system reset. In systems where this reset would be undesirable, a delay should be introduced between enabling the supply monitor and selecting it as a reset source. 0: Supply Monitor Disabled. 1: Supply Monitor Enabled.
6	VDDSTAT	Supply Status. This bit indicates the current power supply status (supply monitor output). 0: V_{DD} is at or below the supply monitor threshold. 1: V_{DD} is above the supply monitor threshold.
5:0	Reserved	Must write reset value.

should be disabled (by clearing the SPIEN bit, SPI0CN.0) when changing the clock phase or polarity. The clock and data line relationships for master mode are shown in Figure 23.5. For slave mode, the clock and data relationships are shown in Figure 23.6 and Figure 23.7. Note that CKPHA should be set to 0 on both the master and slave SPI when communicating between two Silicon Labs C8051 devices.

The SPI0 Clock Rate Register (SPI0CKR) controls the master mode serial clock frequency. This register is ignored when operating in slave mode. When the SPI is configured as a master, the maximum data transfer rate (bits/sec) is one-half the system clock frequency or 12.5 MHz, whichever is slower. When the SPI is configured as a slave, the maximum data transfer rate (bits/sec) for full-duplex operation is 1/10 the system clock frequency, provided that the master issues SCK, NSS (in 4-wire slave mode), and the serial input data synchronously with the slave's system clock. If the master issues SCK, NSS, and the serial input data asynchronously, the maximum data transfer rate (bits/sec) must be less than 1/10 the system clock frequency. In the special case where the master only wants to transmit data to the slave and does not need to receive data from the slave (i.e. half-duplex operation), the SPI slave can receive data at a maximum data transfer rate (bits/sec) of 1/4 the system clock frequency. This is provided that the master issues SCK, NSS, and the serial input data synchronously with the slave's system clock.

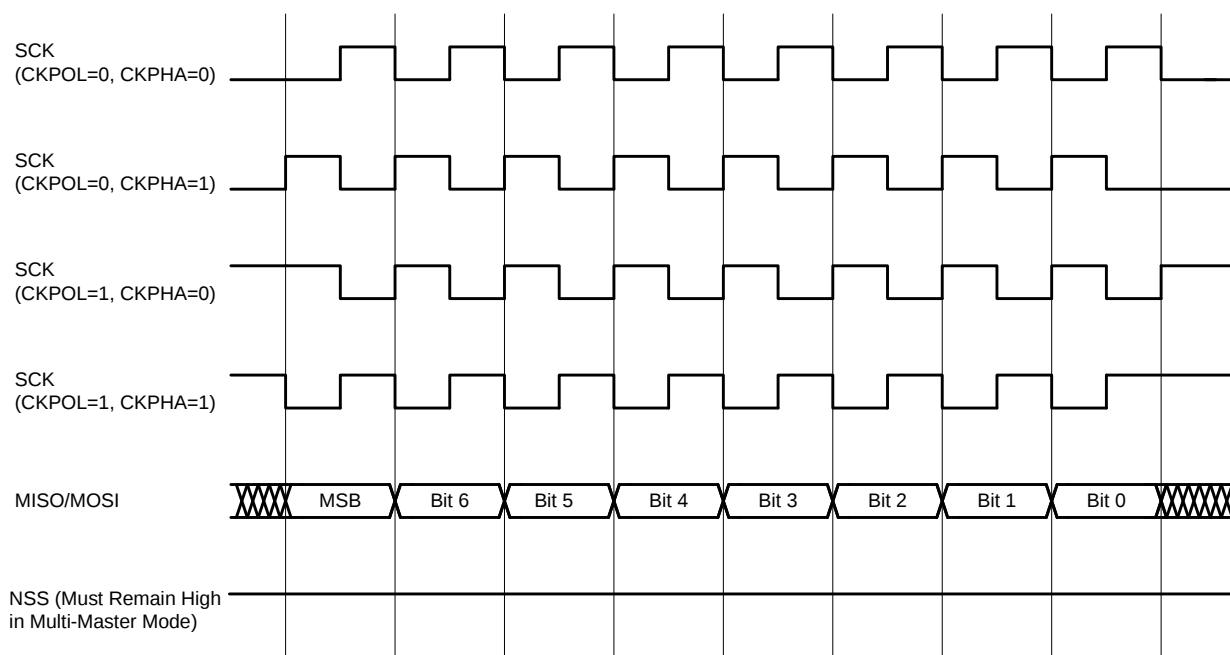


Figure 23.5. Master Mode Data/Clock Timing

Table 23.1. SPI Slave Timing Parameters

Parameter	Description	Min	Max	Units
Master Mode Timing (See Figure 23.8 and Figure 23.9)				
T_{MCKH}	SCK High Time	$1 \times T_{SYSCLK}$	—	ns
T_{MCKL}	SCK Low Time	$1 \times T_{SYSCLK}$	—	ns
T_{MIS}	MISO Valid to SCK Shift Edge	$1 \times T_{SYSCLK} + 20$	—	ns
T_{MIH}	SCK Shift Edge to MISO Change	0	—	ns
Slave Mode Timing (See Figure 23.10 and Figure 23.11)				
T_{SE}	NSS Falling to First SCK Edge	$2 \times T_{SYSCLK}$	—	ns
T_{SD}	Last SCK Edge to NSS Rising	$2 \times T_{SYSCLK}$	—	ns
T_{SEZ}	NSS Falling to MISO Valid	—	$4 \times T_{SYSCLK}$	ns
T_{SDZ}	NSS Rising to MISO High-Z	—	$4 \times T_{SYSCLK}$	ns
T_{CKH}	SCK High Time	$5 \times T_{SYSCLK}$	—	ns
T_{CKL}	SCK Low Time	$5 \times T_{SYSCLK}$	—	ns
T_{SIS}	MOSI Valid to SCK Sample Edge	$2 \times T_{SYSCLK}$	—	ns
T_{SIH}	SCK Sample Edge to MOSI Change	$2 \times T_{SYSCLK}$	—	ns
T_{SOH}	SCK Shift Edge to MISO Change	—	$4 \times T_{SYSCLK}$	ns
T_{SLH}	Last SCK Edge to MISO Change (CKPHA = 1 ONLY)	$6 \times T_{SYSCLK}$	$8 \times T_{SYSCLK}$	ns
Note: T_{SYSCLK} is equal to one period of the device system clock (SYSCLK).				

Register 23.2. SPI0CN: SPI0 Control

Bit	7	6	5	4	3	2	1	0
Name	SPIF	WCOL	MODF	RXOVRN	NSSMD		TXBMT	SPIEN
Type	RW	RW	RW	RW	RW		R	RW
Reset	0	0	0	0	0	1	1	0
SFR Address: 0xF8 (bit-addressable)								

Table 23.3. SPI0CN Register Bit Descriptions

Bit	Name	Function
7	SPIF	SPI0 Interrupt Flag. This bit is set to logic 1 by hardware at the end of a data transfer. If SPI interrupts are enabled, an interrupt will be generated. This bit is not automatically cleared by hardware, and must be cleared by software.
6	WCOL	Write Collision Flag. This bit is set to logic 1 if a write to SPI0DAT is attempted when TXBMT is 0. When this occurs, the write to SPI0DAT will be ignored, and the transmit buffer will not be written. If SPI interrupts are enabled, an interrupt will be generated. This bit is not automatically cleared by hardware, and must be cleared by software.
5	MODF	Mode Fault Flag. This bit is set to logic 1 by hardware when a master mode collision is detected (NSS is low, MSTEN = 1, and NSSMD = 01). If SPI interrupts are enabled, an interrupt will be generated. This bit is not automatically cleared by hardware, and must be cleared by software.
4	RXOVRN	Receive Overrun Flag (valid in slave mode only). This bit is set to logic 1 by hardware when the receive buffer still holds unread data from a previous transfer and the last bit of the current transfer is shifted into the SPI0 shift register. If SPI interrupts are enabled, an interrupt will be generated. This bit is not automatically cleared by hardware, and must be cleared by software.
3:2	NSSMD	Slave Select Mode. Selects between the following NSS operation modes: 00: 3-Wire Slave or 3-Wire Master Mode. NSS signal is not routed to a port pin. 01: 4-Wire Slave or Multi-Master Mode (Default). NSS is an input to the device. 10: 4-Wire Single-Master Mode. NSS is an output and logic low. 11: 4-Wire Single-Master Mode. NSS is an output and logic high.
1	TXBMT	Transmit Buffer Empty. This bit will be set to logic 0 when new data has been written to the transmit buffer. When data in the transmit buffer is transferred to the SPI shift register, this bit will be set to logic 1, indicating that it is safe to write a new byte to the transmit buffer.

STA and STO indicate that a START and/or STOP has been detected or generated since the last SMBus interrupt. STA and STO are also used to generate START and STOP conditions when operating as a master. Writing a 1 to STA will cause the SMBus interface to enter Master Mode and generate a START when the bus becomes free (STA is not cleared by hardware after the START is generated). Writing a 1 to STO while in Master Mode will cause the interface to generate a STOP and end the current transfer after the next ACK cycle. If STO and STA are both set (while in Master Mode), a STOP followed by a START will be generated.

The ARBLOST bit indicates that the interface has lost an arbitration. This may occur anytime the interface is transmitting (master or slave). A lost arbitration while operating as a slave indicates a bus error condition. ARBLOST is cleared by hardware each time SI is cleared.

The SI bit (SMBus Interrupt Flag) is set at the beginning and end of each transfer, after each byte frame, or when an arbitration is lost; see Table 24.3 for more details.

Important Note About the SI Bit: The SMBus interface is stalled while SI is set; thus SCL is held low, and the bus is stalled until software clears SI.

24.4.4.1. Software ACK Generation

When the EHACK bit in register SMB0ADM is cleared to 0, the firmware on the device must detect incoming slave addresses and ACK or NACK the slave address and incoming data bytes. As a receiver, writing the ACK bit defines the outgoing ACK value; as a transmitter, reading the ACK bit indicates the value received during the last ACK cycle. ACKRQ is set each time a byte is received, indicating that an outgoing ACK value is needed. When ACKRQ is set, software should write the desired outgoing value to the ACK bit before clearing SI. A NACK will be generated if software does not write the ACK bit before clearing SI. SDA will reflect the defined ACK value immediately following a write to the ACK bit; however SCL will remain low until SI is cleared. If a received slave address is not acknowledged, further slave events will be ignored until the next START is detected.

24.4.4.2. Hardware ACK Generation

When the EHACK bit in register SMB0ADM is set to 1, automatic slave address recognition and ACK generation is enabled. More detail about automatic slave address recognition can be found in Section 24.4.5. As a receiver, the value currently specified by the ACK bit will be automatically sent on the bus during the ACK cycle of an incoming data byte. As a transmitter, reading the ACK bit indicates the value received on the last ACK cycle. The ACKRQ bit is not used when hardware ACK generation is enabled. If a received slave address is NACKed by hardware, further slave events will be ignored until the next START is detected, and no interrupt will be generated.

Table 24.3 lists all sources for hardware changes to the SMB0CN bits. Refer to Table 24.5 for SMBus status decoding using the SMB0CN register.

Table 24.3. Sources for Hardware Changes to SMB0CN

Bit	Set by Hardware When:	Cleared by Hardware When:
MASTER	■ A START is generated.	■ A STOP is generated. ■ Arbitration is lost.
TXMODE	■ START is generated. ■ SMB0DAT is written before the start of an SMBus frame.	■ A START is detected. ■ Arbitration is lost. ■ SMB0DAT is not written before the start of an SMBus frame.
STA	■ A START followed by an address byte is received.	■ Must be cleared by software.
STO	■ A STOP is detected while addressed as a slave. ■ Arbitration is lost due to a detected STOP.	■ A pending STOP is generated.

25.1.4. Mode 3: Two 8-bit Counter/Timers (Timer 0 Only)

In Mode 3, Timer 0 is configured as two separate 8-bit counter/timers held in TL0 and TH0. The counter/timer in TL0 is controlled using the Timer 0 control/status bits in TCON and TMOD: TR0, CT0, GATE0 and TF0. TL0 can use either the system clock or an external input signal as its timebase. The TH0 register is restricted to a timer function sourced by the system clock or prescaled clock. TH0 is enabled using the Timer 1 run control bit TR1. TH0 sets the Timer 1 overflow flag TF1 on overflow and thus controls the Timer 1 interrupt.

Timer 1 is inactive in Mode 3. When Timer 0 is operating in Mode 3, Timer 1 can be operated in Modes 0, 1 or 2, but cannot be clocked by external signals nor set the TF1 flag and generate an interrupt. However, the Timer 1 overflow can be used to generate baud rates for the SMBus and/or UART, and/or initiate ADC conversions. While Timer 0 is operating in Mode 3, Timer 1 run control is handled through its mode control settings. To run Timer 1 while Timer 0 is in Mode 3, set the Timer 1 Mode as 0, 1, or 2. To disable Timer 1, configure it for Mode 3.

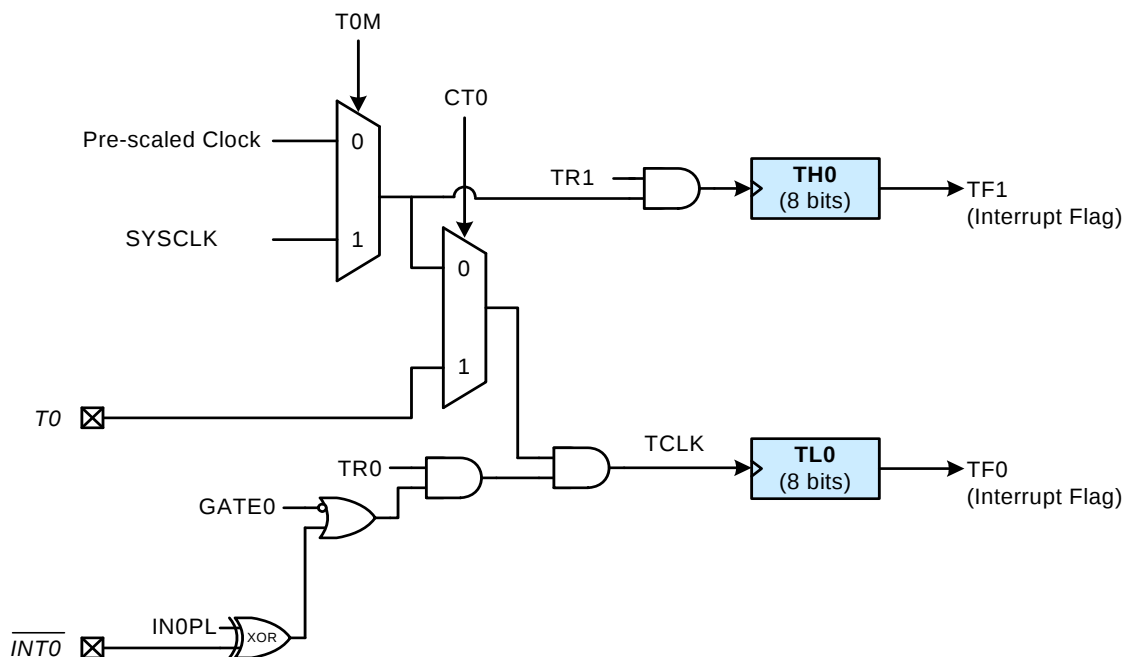


Figure 25.3. T0 Mode 3 Block Diagram

Register 25.3. TMOD: Timer 0/1 Mode

Bit	7	6	5	4	3	2	1	0
Name	GATE1	CT1	T1M		GATE0	CT0	T0M	
Type	RW	RW	RW		RW	RW	RW	
Reset	0	0	0	0	0	0	0	0
SFR Address: 0x89								

Table 25.5. TMOD Register Bit Descriptions

Bit	Name	Function
7	GATE1	Timer 1 Gate Control. 0: Timer 1 enabled when TR1 = 1 irrespective of INT1 logic level. 1: Timer 1 enabled only when TR1 = 1 and INT1 is active as defined by bit IN1PL in register IT01CF.
6	CT1	Counter/Timer 1 Select. 0: Timer Mode. Timer 1 increments on the clock defined by T1M in the CKCON register. 1: Counter Mode. Timer 1 increments on high-to-low transitions of an external pin (T1).
5:4	T1M	Timer 1 Mode Select. These bits select the Timer 1 operation mode. 00: Mode 0, 13-bit Counter/Timer 01: Mode 1, 16-bit Counter/Timer 10: Mode 2, 8-bit Counter/Timer with Auto-Reload 11: Mode 3, Timer 1 Inactive
3	GATE0	Timer 0 Gate Control. 0: Timer 0 enabled when TR0 = 1 irrespective of INT0 logic level. 1: Timer 0 enabled only when TR0 = 1 and INT0 is active as defined by bit IN0PL in register IT01CF.
2	CT0	Counter/Timer 0 Select. 0: Timer Mode. Timer 0 increments on the clock defined by T0M in the CKCON register. 1: Counter Mode. Timer 0 increments on high-to-low transitions of an external pin (T0).
1:0	T0M	Timer 0 Mode Select. These bits select the Timer 0 operation mode. 00: Mode 0, 13-bit Counter/Timer 01: Mode 1, 16-bit Counter/Timer 10: Mode 2, 8-bit Counter/Timer with Auto-Reload 11: Mode 3, Two 8-bit Counter/Timers

Register 25.4. TL0: Timer 0 Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TL0							
Type	RW							
Reset	0	0	0	0	0	0	0	0
SFR Address: 0x8A								

Table 25.6. TL0 Register Bit Descriptions

Bit	Name	Function
7:0	TL0	Timer 0 Low Byte. The TL0 register is the low byte of the 16-bit Timer 0.

Register 25.15. TMR3RLH: Timer 3 Reload High Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3RLH							
Type	RW							
Reset	0	0	0	0	0	0	0	0
SFR Address: 0x93								

Table 25.17. TMR3RLH Register Bit Descriptions

Bit	Name	Function
7:0	TMR3RLH	Timer 3 Reload High Byte. When operating in one of the auto-reload modes, TMR3RLH holds the reload value for the high byte of Timer 3 (TMR3H). When operating in capture mode, TMR3RLH is the captured value of TMR3H.

Register 25.16. TMR3L: Timer 3 Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3L							
Type	RW							
Reset	0	0	0	0	0	0	0	0
SFR Address: 0x94								

Table 25.18. TMR3L Register Bit Descriptions

Bit	Name	Function
7:0	TMR3L	Timer 3 Low Byte. In 16-bit mode, the TMR3L register contains the low byte of the 16-bit Timer 3. In 8-bit mode, TMR3L contains the 8-bit low byte timer value.

29. C2 Interface

C8051F85x/86x devices include an on-chip Silicon Labs 2-Wire (C2) debug interface to allow flash programming and in-system debugging with the production part installed in the end application. The C2 interface uses a clock signal (C2CK) and a bi-directional C2 data signal (C2D) to transfer information between the device and a host system. Details on the C2 protocol can be found in the C2 Interface Specification.

29.1. C2 Pin Sharing

The C2 protocol allows the C2 pins to be shared with user functions so that in-system debugging and flash programming may be performed. C2CK is shared with the $\overline{\text{RST}}$ pin, while the C2D signal is shared with a port I/O pin. This is possible because C2 communication is typically performed when the device is in the halt state, where all on-chip peripherals and user software are stalled. In this halted state, the C2 interface can safely 'borrow' the C2CK and C2D pins. In most applications, external resistors are required to isolate C2 interface traffic from the user application. A typical isolation configuration is shown in Figure 29.1.

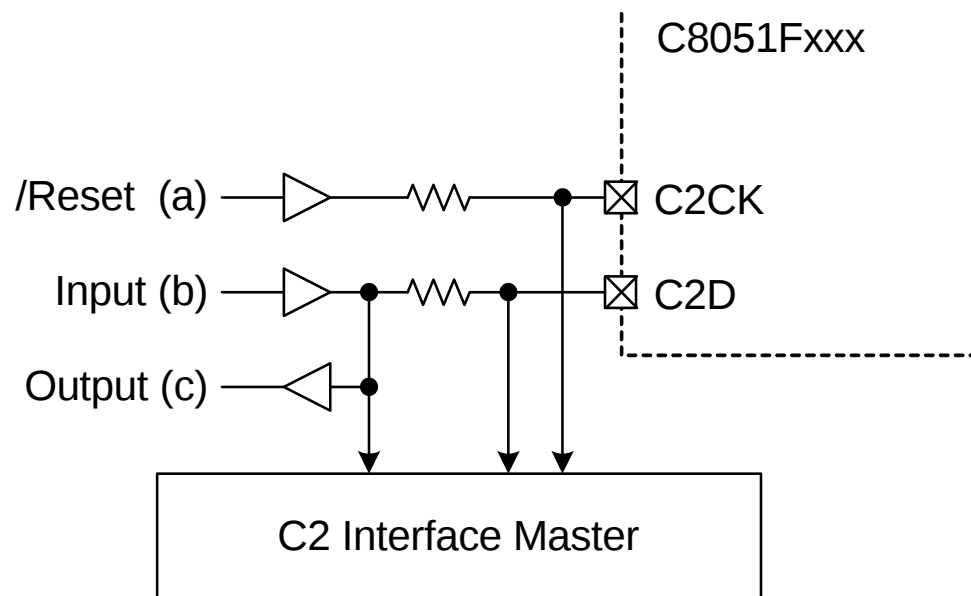


Figure 29.1. Typical C2 Pin Sharing

The configuration in Figure 29.1 assumes the following:

1. The user input (b) cannot change state while the target device is halted.
2. The $\overline{\text{RST}}$ pin on the target device is used as an input only.

Additional resistors may be necessary depending on the specific application.