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Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|---|
| Product Status | Obsolete |
| Number of LABs/CLBs | 185000 |
| Number of Logic Elements/Cells | 490000 |
| Total RAM Bits | 46080000 |
| Number of I/O | 696 |
| Number of Gates | - |
| Voltage - Supply | 0.87V ~ 0.93V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 1517-BBGA, FCBGA |
| Supplier Device Package | 1517-FBGA (40x40) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/5sgxea5k1f40i2n |

Table 1. Stratix V GX and GS Commercial and Industrial Speed Grade Offering ^{(1), (2), (3)} (Part 2 of 2)

| Transceiver Speed Grade | Core Speed Grade | | | | | | | |
|--------------------------|------------------|---------|-----|-----|---------|---------|--------------------|-----|
| | C1 | C2, C2L | C3 | C4 | I2, I2L | I3, I3L | I3YY | I4 |
| 3 GX channel—8.5 Gbps | — | Yes | Yes | Yes | — | Yes | Yes ⁽⁴⁾ | Yes |

Notes to Table 1:

- (1) C = Commercial temperature grade; I = Industrial temperature grade.
 (2) Lower number refers to faster speed grade.
 (3) C2L, I2L, and I3L speed grades are for low-power devices.
 (4) I3YY speed grades can achieve up to 10.3125 Gbps.

Table 2 lists the industrial and commercial speed grades for the Stratix V GT devices.

Table 2. Stratix V GT Commercial and Industrial Speed Grade Offering ^{(1), (2)}

| Transceiver Speed Grade | Core Speed Grade | | | |
|--|------------------|-----|-----|-----|
| | C1 | C2 | I2 | I3 |
| 2 GX channel—12.5 Gbps GT channel—28.05 Gbps | Yes | Yes | — | — |
| 3 GX channel—12.5 Gbps GT channel—25.78 Gbps | Yes | Yes | Yes | Yes |

Notes to Table 2:

- (1) C = Commercial temperature grade; I = Industrial temperature grade.
 (2) Lower number refers to faster speed grade.

Absolute Maximum Ratings

Absolute maximum ratings define the maximum operating conditions for Stratix V devices. The values are based on experiments conducted with the devices and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied for these conditions.



Conditions other than those listed in Table 3 may cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time may have adverse effects on the device.

Table 3. Absolute Maximum Ratings for Stratix V Devices (Part 1 of 2)

| Symbol | Description | Minimum | Maximum | Unit |
|---------------------|--|---------|---------|------|
| V _{CC} | Power supply for core voltage and periphery circuitry | −0.5 | 1.35 | V |
| V _{CCPT} | Power supply for programmable power technology | −0.5 | 1.8 | V |
| V _{CCPGM} | Power supply for configuration pins | −0.5 | 3.9 | V |
| V _{CC_AUX} | Auxiliary supply for the programmable power technology | −0.5 | 3.4 | V |
| V _{CCBAT} | Battery back-up power supply for design security volatile key register | −0.5 | 3.9 | V |
| V _{CCPD} | I/O pre-driver power supply | −0.5 | 3.9 | V |
| V _{CCIO} | I/O power supply | −0.5 | 3.9 | V |

Table 12. OCT Without Calibration Resistance Tolerance Specifications for Stratix V Devices (Part 2 of 2)

| Symbol | Description | Conditions | Resistance Tolerance | | | | Unit |
|----------------------|--|-----------------------------------|----------------------|--------|--------------|--------|------|
| | | | C1 | C2, I2 | C3, I3, I3YY | C4, I4 | |
| 50-Ω R _S | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.8 and 1.5 V | ±30 | ±30 | ±40 | ±40 | % |
| 50-Ω R _S | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.2 V | ±35 | ±35 | ±50 | ±50 | % |
| 100-Ω R _D | Internal differential termination (100-Ω setting) | V _{CCPD} = 2.5 V | ±25 | ±25 | ±25 | ±25 | % |

Calibration accuracy for the calibrated series and parallel OCTs are applicable at the moment of calibration. When voltage and temperature conditions change after calibration, the tolerance may change.

OCT calibration is automatically performed at power-up for OCT-enabled I/Os. Table 13 lists the OCT variation with temperature and voltage after power-up calibration. Use Table 13 to determine the OCT variation after power-up calibration and Equation 1 to determine the OCT variation without recalibration.

Equation 1. OCT Variation Without Recalibration for Stratix V Devices ^{(1), (2), (3), (4), (5), (6)}

$$R_{OCT} = R_{SCAL} \left(1 + \left\langle \frac{dR}{dT} \times \Delta T \right\rangle \pm \left\langle \frac{dR}{dV} \times \Delta V \right\rangle \right)$$

Notes to Equation 1:

- (1) The R_{OCT} value shows the range of OCT resistance with the variation of temperature and V_{CCIO}.
- (2) R_{SCAL} is the OCT resistance value at power-up.
- (3) ΔT is the variation of temperature with respect to the temperature at power-up.
- (4) ΔV is the variation of voltage with respect to the V_{CCIO} at power-up.
- (5) dR/dT is the percentage change of R_{SCAL} with temperature.
- (6) dR/dV is the percentage change of R_{SCAL} with voltage.

Table 13 lists the on-chip termination variation after power-up calibration.

Table 13. OCT Variation after Power-Up Calibration for Stratix V Devices (Part 1 of 2) ⁽¹⁾

| Symbol | Description | V _{CCIO} (V) | Typical | Unit |
|--------|--|-----------------------|---------|--------|
| dR/dV | OCT variation with voltage without recalibration | 3.0 | 0.0297 | % / mV |
| | | 2.5 | 0.0344 | |
| | | 1.8 | 0.0499 | |
| | | 1.5 | 0.0744 | |
| | | 1.2 | 0.1241 | |

Switching Characteristics

This section provides performance characteristics of the Stratix V core and periphery blocks.

These characteristics can be designated as Preliminary or Final.

- Preliminary characteristics are created using simulation results, process data, and other known parameters. The title of these tables show the designation as “Preliminary.”
- Final numbers are based on actual silicon characterization and testing. The numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions. There are no designations on finalized tables.

Transceiver Performance Specifications

This section describes transceiver performance specifications.

Table 23 lists the Stratix V GX and GS transceiver specifications.

Table 23. Transceiver Specifications for Stratix V GX and GS Devices ⁽¹⁾ (Part 1 of 7)

| Symbol/ Description | Conditions | Transceiver Speed Grade 1 | | | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|--|---|---|-----|-----|------------------------------|-----|-----|------------------------------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| Reference Clock | | | | | | | | | | | |
| Supported I/O Standards | Dedicated reference clock pin | 1.2-V PCML, 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, Differential LVPECL, LVDS, and HCSL | | | | | | | | | |
| | RX reference clock pin | 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS | | | | | | | | | |
| Input Reference Clock Frequency (CMU PLL) ⁽⁸⁾ | — | 40 | — | 710 | 40 | — | 710 | 40 | — | 710 | MHz |
| Input Reference Clock Frequency (ATX PLL) ⁽⁸⁾ | — | 100 | — | 710 | 100 | — | 710 | 100 | — | 710 | MHz |
| Rise time | Measure at ±60 mV of differential signal ⁽²⁶⁾ | — | — | 400 | — | — | 400 | — | — | 400 | ps |
| Fall time | Measure at ±60 mV of differential signal ⁽²⁶⁾ | — | — | 400 | — | — | 400 | — | — | 400 | |
| Duty cycle | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| Spread-spectrum modulating clock frequency | PCI Express® (PCIe®) | 30 | — | 33 | 30 | — | 33 | 30 | — | 33 | kHz |

Table 23. Transceiver Specifications for Stratix V GX and GS Devices ⁽¹⁾ (Part 7 of 7)

| Symbol/ Description | Conditions | Transceiver Speed Grade 1 | | | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|------------------------|------------|------------------------------|-----|-----|------------------------------|-----|-----|------------------------------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| $t_{pll_lock}^{(16)}$ | — | — | — | 10 | — | — | 10 | — | — | 10 | μs |

Notes to Table 23:

- (1) Speed grades shown in Table 23 refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Stratix V Device Overview*.
- (2) The reference clock common mode voltage is equal to the V_{CCR_GXB} power supply level.
- (3) This supply must be connected to 1.0 V if the transceiver is configured at a data rate > 6.5 Gbps, and to 1.05 V if configured at a data rate > 10.3 Gbps when DFE is used. For data rates up to 6.5 Gbps, you can connect this supply to 0.85 V.
- (4) This supply follows $VCCR_GXB$.
- (5) The device cannot tolerate prolonged operation at this absolute maximum.
- (6) The differential eye opening specification at the receiver input pins assumes that **Receiver Equalization** is disabled. If you enable **Receiver Equalization**, the receiver circuitry can tolerate a lower minimum eye opening, depending on the equalization level.
- (7) The Quartus II software automatically selects the appropriate slew rate depending on the configured data rate or functional mode.
- (8) The input reference clock frequency options depend on the data rate and the device speed grade.
- (9) The line data rate may be limited by PCS-FPGA interface speed grade.
- (10) Refer to Figure 1 for the GX channel AC gain curves. The total effective AC gain is the AC gain minus the DC gain.
- (11) t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.
- (12) t_{LTD} is time required for the receiver CDR to start recovering valid data after the rx_is_lockedtodata signal goes high.
- (13) t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the rx_is_lockedtodata signal goes high when the CDR is functioning in the manual mode.
- (14) $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the rx_is_lockedtoref signal goes high when the CDR is functioning in the manual mode.
- (15) $t_{pll_powerdown}$ is the PLL powerdown minimum pulse width.
- (16) t_{pll_lock} is the time required for the transmitter CMU/ATX PLL to lock to the input reference clock frequency after coming out of reset.
- (17) To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula: REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.
- (18) The maximum peak to peak differential input voltage V_{ID} after device configuration is equal to $4 \times (\text{absolute } V_{MAX} \text{ for receiver pin} - V_{ICM})$.
- (19) For ES devices, R_{REF} is $2000 \Omega \pm 1\%$.
- (20) To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + $20 \times \log(f/622)$.
- (21) SFP/+ optical modules require the host interface to have RD+/- differentially terminated with 100Ω . The internal OCT feature is available after the Stratix V FPGA configuration is completed. Altera recommends that FPGA configuration is completed before inserting the optical module. Otherwise, minimize unnecessary removal and insertion with unconfigured devices.
- (22) Refer to Figure 2.
- (23) For oversampling designs to support data rates less than the minimum specification, the CDR needs to be in LTR mode only.
- (24) I3YY devices can achieve data rates up to 10.3125 Gbps.
- (25) When you use fPLL as a TXPLL of the transceiver.
- (26) REFCLK performance requires to meet transmitter REFCLK phase noise specification.
- (27) Minimum eye opening of 85 mV is only for the unstressed input eye condition.

Table 25 shows the approximate maximum data rate using the standard PCS.

Table 25. Stratix V Standard PCS Approximate Maximum Date Rate ⁽¹⁾, ⁽³⁾

| Mode ⁽²⁾ | Transceiver Speed Grade | PMA Width | 20 | 20 | 16 | 16 | 10 | 10 | 8 | 8 |
|---------------------|-------------------------|---------------------------------------|---------|---------|---------|---------|-----|-----|------|------|
| | | PCS/Core Width | 40 | 20 | 32 | 16 | 20 | 10 | 16 | 8 |
| FIFO | 1 | C1, C2, C2L, I2, I2L core speed grade | 12.2 | 11.4 | 9.76 | 9.12 | 6.5 | 5.8 | 5.2 | 4.72 |
| | 2 | C1, C2, C2L, I2, I2L core speed grade | 12.2 | 11.4 | 9.76 | 9.12 | 6.5 | 5.8 | 5.2 | 4.72 |
| | | C3, I3, I3L core speed grade | 9.8 | 9.0 | 7.84 | 7.2 | 5.3 | 4.7 | 4.24 | 3.76 |
| | 3 | C1, C2, C2L, I2, I2L core speed grade | 8.5 | 8.5 | 8.5 | 8.5 | 6.5 | 5.8 | 5.2 | 4.72 |
| | | I3YY core speed grade | 10.3125 | 10.3125 | 7.84 | 7.2 | 5.3 | 4.7 | 4.24 | 3.76 |
| | | C3, I3, I3L core speed grade | 8.5 | 8.5 | 7.84 | 7.2 | 5.3 | 4.7 | 4.24 | 3.76 |
| | | C4, I4 core speed grade | 8.5 | 8.2 | 7.04 | 6.56 | 4.8 | 4.2 | 3.84 | 3.44 |
| Register | 1 | C1, C2, C2L, I2, I2L core speed grade | 12.2 | 11.4 | 9.76 | 9.12 | 6.1 | 5.7 | 4.88 | 4.56 |
| | 2 | C1, C2, C2L, I2, I2L core speed grade | 12.2 | 11.4 | 9.76 | 9.12 | 6.1 | 5.7 | 4.88 | 4.56 |
| | | C3, I3, I3L core speed grade | 9.8 | 9.0 | 7.92 | 7.2 | 4.9 | 4.5 | 3.96 | 3.6 |
| | 3 | C1, C2, C2L, I2, I2L core speed grade | 10.3125 | 10.3125 | 10.3125 | 10.3125 | 6.1 | 5.7 | 4.88 | 4.56 |
| | | I3YY core speed grade | 10.3125 | 10.3125 | 7.92 | 7.2 | 4.9 | 4.5 | 3.96 | 3.6 |
| | | C3, I3, I3L core speed grade | 8.5 | 8.5 | 7.92 | 7.2 | 4.9 | 4.5 | 3.96 | 3.6 |
| | | C4, I4 core speed grade | 8.5 | 8.2 | 7.04 | 6.56 | 4.4 | 4.1 | 3.52 | 3.28 |

Notes to Table 25:

- (1) The maximum data rate is in Gbps.
- (2) The Phase Compensation FIFO can be configured in FIFO mode or register mode. In the FIFO mode, the pointers are not fixed, and the latency can vary. In the register mode the pointers are fixed for low latency.
- (3) The maximum data rate is also constrained by the transceiver speed grade. Refer to Table 1 for the transceiver speed grade.

Table 27 shows the V_{OD} settings for the GX channel.

Table 27. Typical V_{OD} Setting for GX Channel, TX Termination = 100 Ω ⁽²⁾

| Symbol | V_{OD} Setting | V_{OD} Value (mV) | V_{OD} Setting | V_{OD} Value (mV) |
|---|------------------|---------------------|------------------|---------------------|
| V_{OD} differential peak to peak typical ⁽³⁾ | 0 ⁽¹⁾ | 0 | 32 | 640 |
| | 1 ⁽¹⁾ | 20 | 33 | 660 |
| | 2 ⁽¹⁾ | 40 | 34 | 680 |
| | 3 ⁽¹⁾ | 60 | 35 | 700 |
| | 4 ⁽¹⁾ | 80 | 36 | 720 |
| | 5 ⁽¹⁾ | 100 | 37 | 740 |
| | 6 | 120 | 38 | 760 |
| | 7 | 140 | 39 | 780 |
| | 8 | 160 | 40 | 800 |
| | 9 | 180 | 41 | 820 |
| | 10 | 200 | 42 | 840 |
| | 11 | 220 | 43 | 860 |
| | 12 | 240 | 44 | 880 |
| | 13 | 260 | 45 | 900 |
| | 14 | 280 | 46 | 920 |
| | 15 | 300 | 47 | 940 |
| | 16 | 320 | 48 | 960 |
| | 17 | 340 | 49 | 980 |
| | 18 | 360 | 50 | 1000 |
| | 19 | 380 | 51 | 1020 |
| | 20 | 400 | 52 | 1040 |
| | 21 | 420 | 53 | 1060 |
| | 22 | 440 | 54 | 1080 |
| | 23 | 460 | 55 | 1100 |
| | 24 | 480 | 56 | 1120 |
| | 25 | 500 | 57 | 1140 |
| | 26 | 520 | 58 | 1160 |
| | 27 | 540 | 59 | 1180 |
| | 28 | 560 | 60 | 1200 |
| | 29 | 580 | 61 | 1220 |
| | 30 | 600 | 62 | 1240 |
| | 31 | 620 | 63 | 1260 |

Note to Table 27:

- (1) If TX termination resistance = 100 Ω , this VOD setting is illegal.
- (2) The tolerance is +/-20% for all VOD settings except for settings 2 and below.
- (3) Refer to Figure 2.

Figure 2 shows the differential transmitter output waveform.

Figure 2. Differential Transmitter Output Waveform

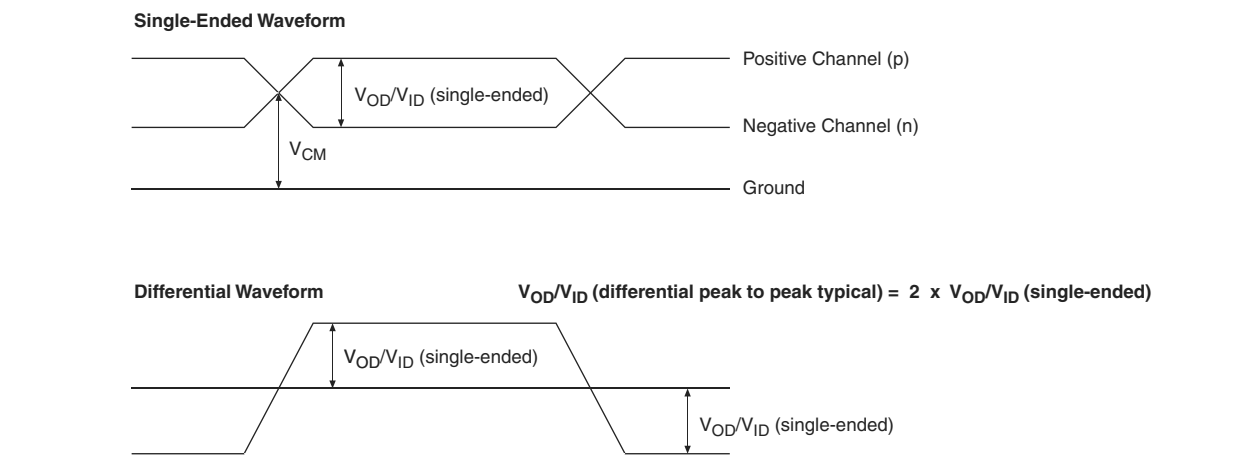


Figure 3 shows the Stratix V AC gain curves for GX channels.

Figure 3. AC Gain Curves for GX Channels (full bandwidth)



Stratix V GT devices contain both GX and GT channels. All transceiver specifications for the GX channels not listed in Table 28 are the same as those listed in Table 23.

Table 28 lists the Stratix V GT transceiver specifications.

Table 28. Transceiver Specifications for Stratix V GT Devices (Part 3 of 5) ⁽¹⁾

| Symbol/ Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|--|---------------------------------|------------------------------|---------------|--------|------------------------------|---------------|--------|-----------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Differential on-chip termination resistors ⁽⁷⁾ | GT channels | — | 100 | — | — | 100 | — | Ω |
| Differential on-chip termination resistors for GX channels ⁽¹⁹⁾ | 85- Ω setting | — | 85 \pm 30% | — | — | 85 \pm 30% | — | Ω |
| | 100- Ω setting | — | 100 \pm 30% | — | — | 100 \pm 30% | — | Ω |
| | 120- Ω setting | — | 120 \pm 30% | — | — | 120 \pm 30% | — | Ω |
| | 150- Ω setting | — | 150 \pm 30% | — | — | 150 \pm 30% | — | Ω |
| V _{ICM} (AC coupled) | GT channels | — | 650 | — | — | 650 | — | mV |
| VICM (AC and DC coupled) for GX Channels | VCCR_GXB = 0.85 V or 0.9 V | — | 600 | — | — | 600 | — | mV |
| | VCCR_GXB = 1.0 V full bandwidth | — | 700 | — | — | 700 | — | mV |
| | VCCR_GXB = 1.0 V half bandwidth | — | 750 | — | — | 750 | — | mV |
| t _{LTR} ⁽⁹⁾ | — | — | — | 10 | — | — | 10 | μ s |
| t _{LTD} ⁽¹⁰⁾ | — | 4 | — | — | 4 | — | — | μ s |
| t _{LTD_manual} ⁽¹¹⁾ | — | 4 | — | — | 4 | — | — | μ s |
| t _{LTR_LTD_manual} ⁽¹²⁾ | — | 15 | — | — | 15 | — | — | μ s |
| Run Length | GT channels | — | — | 72 | — | — | 72 | CID |
| | GX channels | ⁽⁸⁾ | | | | | | |
| CDR PPM | GT channels | — | — | 1000 | — | — | 1000 | \pm PPM |
| | GX channels | ⁽⁸⁾ | | | | | | |
| Programmable equalization (AC Gain) ⁽⁵⁾ | GT channels | — | — | 14 | — | — | 14 | dB |
| | GX channels | ⁽⁸⁾ | | | | | | |
| Programmable DC gain ⁽⁶⁾ | GT channels | — | — | 7.5 | — | — | 7.5 | dB |
| | GX channels | ⁽⁸⁾ | | | | | | |
| Differential on-chip termination resistors ⁽⁷⁾ | GT channels | — | 100 | — | — | 100 | — | Ω |
| Transmitter | | | | | | | | |
| Supported I/O Standards | — | 1.4-V and 1.5-V PCML | | | | | | |
| Data rate (Standard PCS) | GX channels | 600 | — | 8500 | 600 | — | 8500 | Mbps |
| Data rate (10G PCS) | GX channels | 600 | — | 12,500 | 600 | — | 12,500 | Mbps |

Table 31. PLL Specifications for Stratix V Devices (Part 2 of 3)

| Symbol | Parameter | Min | Typ | Max | Unit |
|--|--|------|---------|--|-----------|
| t_{INCCJ} ^{(3), (4)} | Input clock cycle-to-cycle jitter ($f_{\text{REF}} \geq 100$ MHz) | — | — | 0.15 | UI (p-p) |
| | Input clock cycle-to-cycle jitter ($f_{\text{REF}} < 100$ MHz) | −750 | — | +750 | ps (p-p) |
| $t_{\text{OUTPJ_DC}}$ ⁽⁵⁾ | Period Jitter for dedicated clock output ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 175 ⁽¹⁾ | ps (p-p) |
| | Period Jitter for dedicated clock output ($f_{\text{OUT}} < 100$ MHz) | — | — | 17.5 ⁽¹⁾ | mUI (p-p) |
| $t_{\text{FOUTPJ_DC}}$ ⁽⁵⁾ | Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 250 ⁽¹¹⁾ , 175 ⁽¹²⁾ | ps (p-p) |
| | Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 25 ⁽¹¹⁾ , 17.5 ⁽¹²⁾ | mUI (p-p) |
| $t_{\text{OUTCCJ_DC}}$ ⁽⁵⁾ | Cycle-to-Cycle Jitter for a dedicated clock output ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 175 | ps (p-p) |
| | Cycle-to-Cycle Jitter for a dedicated clock output ($f_{\text{OUT}} < 100$ MHz) | — | — | 17.5 | mUI (p-p) |
| $t_{\text{FOUTCCJ_DC}}$ ⁽⁵⁾ | Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 250 ⁽¹¹⁾ , 175 ⁽¹²⁾ | ps (p-p) |
| | Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz)+ | — | — | 25 ⁽¹¹⁾ , 17.5 ⁽¹²⁾ | mUI (p-p) |
| $t_{\text{OUTPJ_IO}}$ ^{(5), (8)} | Period Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Period Jitter for a clock output on a regular I/O ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{FOUTPJ_IO}}$ ^{(5), (8), (11)} | Period Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 ⁽¹⁰⁾ | ps (p-p) |
| | Period Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 ⁽¹⁰⁾ | mUI (p-p) |
| $t_{\text{OUTCCJ_IO}}$ ^{(5), (8)} | Cycle-to-cycle Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Cycle-to-cycle Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 ⁽¹⁰⁾ | mUI (p-p) |
| $t_{\text{FOUTCCJ_IO}}$ ^{(5), (8), (11)} | Cycle-to-cycle Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 ⁽¹⁰⁾ | ps (p-p) |
| | Cycle-to-cycle Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{CASC_OUTPJ_DC}}$ ^{(5), (6)} | Period Jitter for a dedicated clock output in cascaded PLLs ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 175 | ps (p-p) |
| | Period Jitter for a dedicated clock output in cascaded PLLs ($f_{\text{OUT}} < 100$ MHz) | — | — | 17.5 | mUI (p-p) |
| f_{DRIFT} | Frequency drift after PFDENA is disabled for a duration of 100 μ s | — | — | ± 10 | % |
| dK_{BIT} | Bit number of Delta Sigma Modulator (DSM) | 8 | 24 | 32 | Bits |
| k_{VALUE} | Numerator of Fraction | 128 | 8388608 | 2147483648 | — |

Table 36. High-Speed I/O Specifications for Stratix V Devices ^{(1), (2)} (Part 2 of 4)

| Symbol | Conditions | C1 | | | C2, C2L, I2, I2L | | | C3, I3, I3L, I3YY | | | C4,I4 | | | Unit |
|--|---|-----|-----|------|------------------|-----|------|-------------------|-----|------|-------|-----|------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| Transmitter | | | | | | | | | | | | | | |
| True Differential I/O Standards - f _{HSDR} (data rate) | SERDES factor J = 3 to 10 ^{(9), (11), (12), (13), (14), (15), (16)} | (6) | — | 1600 | (6) | — | 1434 | (6) | — | 1250 | (6) | — | 1050 | Mbps |
| | SERDES factor J ≥ 4 LVDS TX with DPA ^{(12), (14), (15), (16)} | (6) | — | 1600 | (6) | — | 1600 | (6) | — | 1600 | (6) | — | 1250 | Mbps |
| | SERDES factor J = 2, uses DDR Registers | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| | SERDES factor J = 1, uses SDR Register | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| Emulated Differential I/O Standards with Three External Output Resistor Networks - f _{HSDR} (data rate) ⁽¹⁰⁾ | SERDES factor J = 4 to 10 ⁽¹⁷⁾ | (6) | — | 1100 | (6) | — | 1100 | (6) | — | 840 | (6) | — | 840 | Mbps |
| t _{x Jitter} - True Differential I/O Standards | Total Jitter for Data Rate 600 Mbps - 1.25 Gbps | — | — | 160 | — | — | 160 | — | — | 160 | — | — | 160 | ps |
| | Total Jitter for Data Rate < 600 Mbps | — | — | 0.1 | — | — | 0.1 | — | — | 0.1 | — | — | 0.1 | UI |
| t _{x Jitter} - Emulated Differential I/O Standards with Three External Output Resistor Network | Total Jitter for Data Rate 600 Mbps - 1.25 Gbps | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 325 | ps |
| | Total Jitter for Data Rate < 600 Mbps | — | — | 0.2 | — | — | 0.2 | — | — | 0.2 | — | — | 0.25 | UI |

Table 36. High-Speed I/O Specifications for Stratix V Devices ⁽¹⁾, ⁽²⁾ (Part 3 of 4)

| Symbol | Conditions | C1 | | | C2, C2L, I2, I2L | | | C3, I3, I3L, I3YY | | | C4, I4 | | | Unit |
|--|---|----------------|-----|----------------|------------------|-----|----------------|-------------------|-----|----------------|----------------|-----|----------------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| t_{DUTY} | Transmitter output clock duty cycle for both True and Emulated Differential I/O Standards | 45 | 50 | 55 | 45 | 50 | 55 | 45 | 50 | 55 | 45 | 50 | 55 | % |
| t_{RISE} & t_{FALL} | True Differential I/O Standards | — | — | 160 | — | — | 160 | — | — | 200 | — | — | 200 | ps |
| | Emulated Differential I/O Standards with three external output resistor networks | — | — | 250 | — | — | 250 | — | — | 250 | — | — | 300 | ps |
| TCCS | True Differential I/O Standards | — | — | 150 | — | — | 150 | — | — | 150 | — | — | 150 | ps |
| | Emulated Differential I/O Standards | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 300 | ps |
| Receiver | | | | | | | | | | | | | | |
| True Differential I/O Standards - f_{HSDRDP} (data rate) | SERDES factor J = 3 to 10 ⁽¹¹⁾ , ⁽¹²⁾ , ⁽¹³⁾ , ⁽¹⁴⁾ , ⁽¹⁵⁾ , ⁽¹⁶⁾ | 150 | — | 1434 | 150 | — | 1434 | 150 | — | 1250 | 150 | — | 1050 | Mbps |
| | SERDES factor J ≥ 4 | 150 | — | 1600 | 150 | — | 1600 | 150 | — | 1600 | 150 | — | 1250 | Mbps |
| | LVDS RX with DPA ⁽¹²⁾ , ⁽¹⁴⁾ , ⁽¹⁵⁾ , ⁽¹⁶⁾ | 150 | — | 1600 | 150 | — | 1600 | 150 | — | 1600 | 150 | — | 1250 | Mbps |
| | SERDES factor J = 2, uses DDR Registers | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | Mbps |
| | SERDES factor J = 1, uses SDR Register | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | ⁽⁶⁾ | — | ⁽⁷⁾ | Mbps |

Table 36. High-Speed I/O Specifications for Stratix V Devices ^{(1), (2)} (Part 4 of 4)

| Symbol | Conditions | C1 | | | C2, C2L, I2, I2L | | | C3, I3, I3L, I3YY | | | C4, I4 | | | Unit |
|-------------------------------|---|-----|-----|-----------|------------------|-----|-----------|-------------------|-----|-----------|--------|-----|-----------|----------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f _{HSDR} (data rate) | SERDES factor J = 3 to 10 | (6) | — | (8) | (6) | — | (8) | (6) | — | (8) | (6) | — | (8) | Mbps |
| | SERDES factor J = 2, uses DDR Registers | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| | SERDES factor J = 1, uses SDR Register | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| DPA Mode | | | | | | | | | | | | | | |
| DPA run length | — | — | — | 1000 0 | — | — | 1000 0 | — | — | 1000 0 | — | — | 1000 0 | UI |
| Soft CDR mode | | | | | | | | | | | | | | |
| Soft-CDR PPM tolerance | — | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 300 | ± PPM |
| Non DPA Mode | | | | | | | | | | | | | | |
| Sampling Window | — | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 300 | ps |

Notes to Table 36:

- (1) When J = 3 to 10, use the serializer/deserializer (SERDES) block.
- (2) When J = 1 or 2, bypass the SERDES block.
- (3) This only applies to DPA and soft-CDR modes.
- (4) Clock Boost Factor (W) is the ratio between the input data rate to the input clock rate.
- (5) This is achieved by using the **LVDS** clock network.
- (6) The minimum specification depends on the clock source (for example, the PLL and clock pin) and the clock routing resource (global, regional, or local) that you use. The I/O differential buffer and input register do not have a minimum toggle rate.
- (7) The maximum ideal frequency is the SERDES factor (J) x the PLL maximum output frequency (f_{OUT}) provided you can close the design timing and the signal integrity simulation is clean.
- (8) You can estimate the achievable maximum data rate for non-DPA mode by performing link timing closure analysis. You must consider the board skew margin, transmitter delay margin, and receiver sampling margin to determine the maximum data rate supported.
- (9) If the receiver with DPA enabled and transmitter are using shared PLLs, the minimum data rate is 150 Mbps.
- (10) You must calculate the leftover timing margin in the receiver by performing link timing closure analysis. You must consider the board skew margin, transmitter channel-to-channel skew, and receiver sampling margin to determine leftover timing margin.
- (11) The F_{MAX} specification is based on the fast clock used for serial data. The interface F_{MAX} is also dependent on the parallel clock domain which is design-dependent and requires timing analysis.
- (12) Stratix V RX LVDS will need DPA. For Stratix V TX LVDS, the receiver side component must have DPA.
- (13) Stratix V LVDS serialization and de-serialization factor needs to be x4 and above.
- (14) Requires package skew compensation with PCB trace length.
- (15) Do not mix single-ended I/O buffer within LVDS I/O bank.
- (16) Chip-to-chip communication only with a maximum load of 5 pF.
- (17) When using True LVDS RX channels for emulated LVDS TX channel, only serialization factors 1 and 2 are supported.

Table 38. LVDS Soft-CDR/DPA Sinusoidal Jitter Mask Values for a Data Rate ≥ 1.25 Gbps

| Jitter Frequency (Hz) | | Sinusoidal Jitter (UI) |
|-----------------------|------------|------------------------|
| F1 | 10,000 | 25.000 |
| F2 | 17,565 | 25.000 |
| F3 | 1,493,000 | 0.350 |
| F4 | 50,000,000 | 0.350 |

Figure 9 shows the LVDS soft-CDR/DPA sinusoidal jitter tolerance specification for a data rate < 1.25 Gbps.

Figure 9. LVDS Soft-CDR/DPA Sinusoidal Jitter Tolerance Specification for a Data Rate < 1.25 Gbps

DLL Range, DQS Logic Block, and Memory Output Clock Jitter Specifications

Table 39 lists the DLL range specification for Stratix V devices. The DLL is always in 8-tap mode in Stratix V devices.

Table 39. DLL Range Specifications for Stratix V Devices ⁽¹⁾

| C1 | C2, C2L, I2, I2L | C3, I3, I3L, I3YY | C4,I4 | Unit |
|---------|------------------|-------------------|---------|------|
| 300-933 | 300-933 | 300-890 | 300-890 | MHz |

Note to Table 39:

- (1) Stratix V devices support memory interface frequencies lower than 300 MHz, although the reference clock that feeds the DLL must be at least 300 MHz. To support interfaces below 300 MHz, multiply the reference clock feeding the DLL to ensure the frequency is within the supported range of the DLL.

Table 40 lists the DQS phase offset delay per stage for Stratix V devices.

Table 40. DQS Phase Offset Delay Per Setting for Stratix V Devices ^{(1), (2)} (Part 1 of 2)

| Speed Grade | Min | Max | Unit |
|------------------|-----|-----|------|
| C1 | 8 | 14 | ps |
| C2, C2L, I2, I2L | 8 | 14 | ps |
| C3,I3, I3L, I3YY | 8 | 15 | ps |

Duty Cycle Distortion (DCD) Specifications

Table 44 lists the worst-case DCD for Stratix V devices.

Table 44. Worst-Case DCD on Stratix V I/O Pins ⁽¹⁾

| Symbol | C1 | | C2, C2L, I2, I2L | | C3, I3, I3L, I3YY | | C4, I4 | | Unit |
|-------------------|-----|-----|------------------|-----|-------------------|-----|--------|-----|------|
| | Min | Max | Min | Max | Min | Max | Min | Max | |
| Output Duty Cycle | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | % |

Note to Table 44:

(1) The DCD numbers do not cover the core clock network.

Configuration Specification

POR Delay Specification

Power-on reset (POR) delay is defined as the delay between the time when all the power supplies monitored by the POR circuitry reach the minimum recommended operating voltage to the time when the nSTATUS is released high and your device is ready to begin configuration.



For more information about the POR delay, refer to the *Hot Socketing and Power-On Reset in Stratix V Devices* chapter.

Table 45 lists the fast and standard POR delay specification.

Table 45. Fast and Standard POR Delay Specification ⁽¹⁾

| POR Delay | Minimum | Maximum |
|-----------|---------|---------|
| Fast | 4 ms | 12 ms |
| Standard | 100 ms | 300 ms |

Note to Table 45:

(1) You can select the POR delay based on the MSEL settings as described in the MSEL Pin Settings section of the “Configuration, Design Security, and Remote System Upgrades in Stratix V Devices” chapter.

JTAG Configuration Specifications

Table 46 lists the JTAG timing parameters and values for Stratix V devices.

Table 46. JTAG Timing Parameters and Values for Stratix V Devices

| Symbol | Description | Min | Max | Unit |
|-------------------------|------------------------------------|-----|-----|------|
| t _{JCP} | TCK clock period ⁽²⁾ | 30 | — | ns |
| t _{JCP} | TCK clock period ⁽²⁾ | 167 | — | ns |
| t _{JCH} | TCK clock high time ⁽²⁾ | 14 | — | ns |
| t _{JCL} | TCK clock low time ⁽²⁾ | 14 | — | ns |
| t _{JPSU (TDI)} | TDI JTAG port setup time | 2 | — | ns |
| t _{JPSU (TMS)} | TMS JTAG port setup time | 3 | — | ns |

Table 49. DCLK-to-DATA[] Ratio ⁽¹⁾ (Part 2 of 2)

| Configuration Scheme | Decompression | Design Security | DCLK-to-DATA[] Ratio |
|----------------------|---------------|-----------------|----------------------|
| FPP ×32 | Disabled | Disabled | 1 |
| | Disabled | Enabled | 4 |
| | Enabled | Disabled | 8 |
| | Enabled | Enabled | 8 |

Note to Table 49:

- (1) Depending on the DCLK-to-DATA[] ratio, the host must send a DCLK frequency that is r times the data rate in bytes per second (Bps), or words per second (Wps). For example, in FPP ×16 when the DCLK-to-DATA[] ratio is 2, the DCLK frequency must be 2 times the data rate in Wps. Stratix V devices use the additional clock cycles to decrypt and decompress the configuration data.



If the DCLK-to-DATA[] ratio is greater than 1, at the end of configuration, you can only stop the DCLK (DCLK-to-DATA[] ratio – 1) clock cycles after the last data is latched into the Stratix V device.

Figure 11 shows the configuration interface connections between the Stratix V device and a MAX II or MAX V device for single device configuration.

Figure 11. Single Device FPP Configuration Using an External Host**Notes to Figure 11:**

- (1) Connect the resistor to a supply that provides an acceptable input signal for the Stratix V device. V_{CCPGM} must be high enough to meet the V_{IH} specification of the I/O on the device and the external host. Altera recommends powering up all configuration system I/Os with V_{CCPGM} .
- (2) You can leave the nCEO pin unconnected or use it as a user I/O pin when it does not feed another device's nCE pin.
- (3) The MSEL pin settings vary for different data width, configuration voltage standards, and POR delay. To connect MSEL, refer to the MSEL Pin Settings section of the "Configuration, Design Security, and Remote System Upgrades in Stratix V Devices" chapter.
- (4) If you use FPP ×8, use DATA[7..0]. If you use FPP ×16, use DATA[15..0].

FPP Configuration Timing when DCLK-to-DATA [] = 1

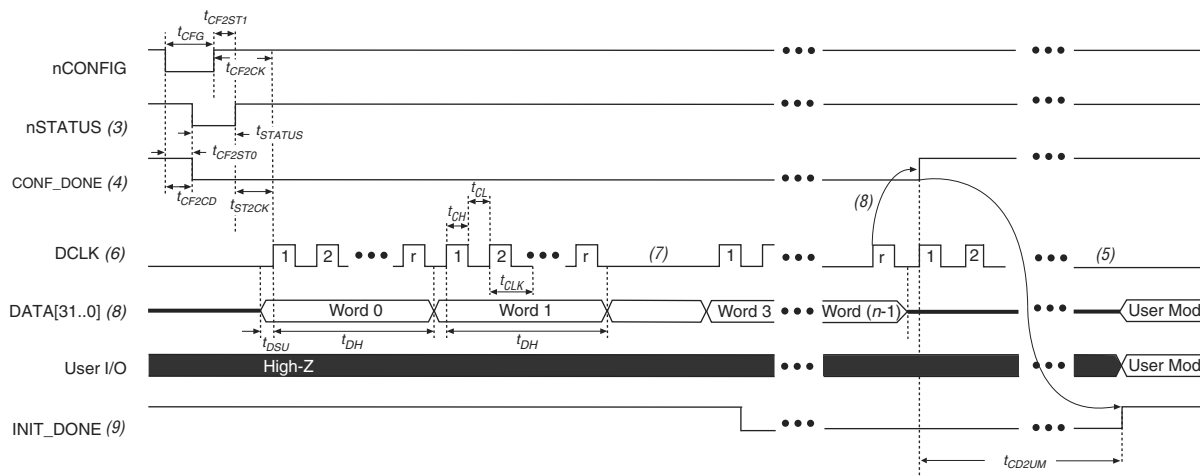
Figure 12 shows the timing waveform for FPP configuration when using a MAX II or MAX V device as an external host. This waveform shows timing when the DCLK-to-DATA [] ratio is 1.

Figure 12. FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is 1 ^{(1), (2)}



Notes to Figure 12:

- (1) Use this timing waveform when the DCLK-to-DATA [] ratio is 1.
- (2) The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF_DONE are at logic-high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
- (3) After power-up, the Stratix V device holds nSTATUS low for the time of the POR delay.
- (4) After power-up, before and during configuration, CONF_DONE is low.
- (5) Do not leave DCLK floating after configuration. DCLK is ignored after configuration is complete. It can toggle high or low if required.
- (6) For FPP x16, use DATA [15..0]. For FPP x8, use DATA [7..0]. DATA [31..0] are available as a user I/O pin after configuration. The state of this pin depends on the dual-purpose pin settings.
- (7) To ensure a successful configuration, send the entire configuration data to the Stratix V device. CONF_DONE is released high when the Stratix V device receives all the configuration data successfully. After CONF_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
- (8) After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Figure 13. FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is >1 (1), (2)**Notes to Figure 13:**

- (1) Use this timing waveform and parameters when the DCLK-to-DATA [] ratio is >1. To find out the DCLK-to-DATA [] ratio for your system, refer to Table 49 on page 55.
- (2) The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF_DONE are at logic high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
- (3) After power-up, the Stratix V device holds nSTATUS low for the time as specified by the POR delay.
- (4) After power-up, before and during configuration, CONF_DONE is low.
- (5) Do not leave DCLK floating after configuration. You can drive it high or low, whichever is more convenient.
- (6) "r" denotes the DCLK-to-DATA [] ratio. For the DCLK-to-DATA [] ratio based on the decompression and the design security feature enable settings, refer to Table 49 on page 55.
- (7) If needed, pause DCLK by holding it low. When DCLK restarts, the external host must provide data on the DATA [31 . . 0] pins prior to sending the first DCLK rising edge.
- (8) To ensure a successful configuration, send the entire configuration data to the Stratix V device. CONF_DONE is released high after the Stratix V device receives all the configuration data successfully. After CONF_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
- (9) After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Active Serial Configuration Timing

Table 52 lists the DCLK frequency specification in the AS configuration scheme.

Table 52. DCLK Frequency Specification in the AS Configuration Scheme ^{(1), (2)}

| Minimum | Typical | Maximum | Unit |
|---------|---------|---------|------|
| 5.3 | 7.9 | 12.5 | MHz |
| 10.6 | 15.7 | 25.0 | MHz |
| 21.3 | 31.4 | 50.0 | MHz |
| 42.6 | 62.9 | 100.0 | MHz |

Notes to Table 52:

- (1) This applies to the DCLK frequency specification when using the internal oscillator as the configuration clock source.
- (2) The AS multi-device configuration scheme does not support DCLK frequency of 100 MHz.

Figure 14 shows the single-device configuration setup for an AS ×1 mode.

Figure 14. AS Configuration Timing



Notes to Figure 14:

- (1) If you are using AS ×4 mode, this signal represents the AS_DATA [3 : 0] and EPCQ sends in 4-bits of data for each DCLK cycle.
- (2) The initialization clock can be from internal oscillator or CLKUSR pin.
- (3) After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Table 53 lists the timing parameters for AS ×1 and AS ×4 configurations in Stratix V devices.

Table 53. AS Timing Parameters for AS ×1 and AS ×4 Configurations in Stratix V Devices ^{(1), (2)} (Part 1 of 2)

| Symbol | Parameter | Minimum | Maximum | Units |
|----------|---|---------|---------|-------|
| t_{CO} | DCLK falling edge to AS_DATA0/ASDO output | — | 2 | ns |
| t_{SU} | Data setup time before falling edge on DCLK | 1.5 | — | ns |
| t_H | Data hold time after falling edge on DCLK | 0 | — | ns |

Remote System Upgrades

Table 56 lists the timing parameter specifications for the remote system upgrade circuitry.

Table 56. Remote System Upgrade Circuitry Timing Specifications

| Parameter | Minimum | Maximum | Unit |
|--------------------------|---------|---------|------|
| $t_{RU_nCONFIG}^{(1)}$ | 250 | — | ns |
| $t_{RU_nRSTIMER}^{(2)}$ | 250 | — | ns |

Notes to Table 56:

- (1) This is equivalent to strobing the reconfiguration input of the ALTREMOTE_UPDATE megafunction high for the minimum timing specification. For more information, refer to the Remote System Upgrade State Machine section of the “Configuration, Design Security, and Remote System Upgrades in Stratix V Devices” chapter.
- (2) This is equivalent to strobing the reset_timer input of the ALTREMOTE_UPDATE megafunction high for the minimum timing specification. For more information, refer to the User Watchdog Timer section of the “Configuration, Design Security, and Remote System Upgrades in Stratix V Devices” chapter.

User Watchdog Internal Circuitry Timing Specification

Table 57 lists the operating range of the 12.5-MHz internal oscillator.

Table 57. 12.5-MHz Internal Oscillator Specifications

| Minimum | Typical | Maximum | Units |
|---------|---------|---------|-------|
| 5.3 | 7.9 | 12.5 | MHz |

I/O Timing

Altera offers two ways to determine I/O timing—the Excel-based I/O Timing and the Quartus II Timing Analyzer.

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get an estimate of the timing budget as part of the link timing analysis. The Quartus II Timing Analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after you complete place-and-route.



You can download the Excel-based I/O Timing spreadsheet from the Stratix V Devices Documentation web page.

Programmable IOE Delay

Table 58 lists the Stratix V IOE programmable delay settings.

Table 58. IOE Programmable Delay for Stratix V Devices (Part 1 of 2)

| Parameter (1) | Available Settings | Min Offset (2) | Fast Model | | Slow Model | | | | | | | |
|------------------|-----------------------|----------------------|------------|------------|------------|-------|-------|-------|-------|-------------|-------|------|
| | | | Industrial | Commercial | C1 | C2 | C3 | C4 | I2 | I3, I3YY | I4 | Unit |
| D1 | 64 | 0 | 0.464 | 0.493 | 0.838 | 0.838 | 0.924 | 1.011 | 0.844 | 0.921 | 1.006 | ns |
| D2 | 32 | 0 | 0.230 | 0.244 | 0.415 | 0.415 | 0.459 | 0.503 | 0.417 | 0.456 | 0.500 | ns |

Document Revision History

Table 61 lists the revision history for this chapter.

Table 61. Document Revision History (Part 1 of 3)

| Date | Version | Changes |
|---------------|---------|---|
| June 2018 | 3.9 | <ul style="list-style-type: none"> ■ Added the “Stratix V Device Overshoot Duration” figure. |
| April 2017 | 3.8 | <ul style="list-style-type: none"> ■ Added a footnote to the “High-Speed I/O Specifications for Stratix V Devices” table. ■ Changed the minimum value for t_{CD2UMC} in the “PS Timing Parameters for Stratix V Devices” table. ■ Changed the condition for $100\text{-}\Omega$ R_D in the “OCT Without Calibration Resistance Tolerance Specifications for Stratix V Devices” table. ■ Changed the minimum value for t_{CD2UMC} in the “AS Timing Parameters for AS ‘1 and AS ‘4 Configurations in Stratix V Devices” table ■ Changed the minimum value for t_{CD2UMC} in the “FPP Timing Parameters for Stratix V Devices When the DCLK-to-DATA[] Ratio is >1” table. ■ Changed the minimum value for t_{CD2UMC} in the “FPP Timing Parameters for Stratix V Devices When the DCLK-to-DATA[] Ratio is >1” table. ■ Changed the minimum number of clock cycles value in the “Initialization Clock Source Option and the Maximum Frequency” table. |
| June 2016 | 3.7 | <ul style="list-style-type: none"> ■ Added the V_{ID} minimum specification for LVPECL in the “Differential I/O Standard Specifications for Stratix V Devices” table ■ Added the I_{OUT} specification to the “Absolute Maximum Ratings for Stratix V Devices” table. |
| December 2015 | 3.6 | <ul style="list-style-type: none"> ■ Added a footnote to the “High-Speed I/O Specifications for Stratix V Devices” table. |
| December 2015 | 3.5 | <ul style="list-style-type: none"> ■ Changed the transmitter, receiver, and ATX PLL data rate specifications in the “Transceiver Specifications for Stratix V GX and GS Devices” table. ■ Changed the configuration .rbf sizes in the “Uncompressed .rbf Sizes for Stratix V Devices” table. |
| July 2015 | 3.4 | <ul style="list-style-type: none"> ■ Changed the data rate specification for transceiver speed grade 3 in the following tables: <ul style="list-style-type: none"> ■ “Transceiver Specifications for Stratix V GX and GS Devices” ■ “Stratix V Standard PCS Approximate Maximum Date Rate” ■ “Stratix V 10G PCS Approximate Maximum Data Rate” ■ Changed the conditions for reference clock rise and fall time, and added a note to the “Transceiver Specifications for Stratix V GX and GS Devices” table. ■ Added a note to the “Minimum differential eye opening at receiver serial input pins” specification in the “Transceiver Specifications for Stratix V GX and GS Devices” table. ■ Changed the t_{CO} maximum value in the “AS Timing Parameters for AS ‘1 and AS ‘4 Configurations in Stratix V Devices” table. ■ Removed the CDR ppm tolerance specification from the “Transceiver Specifications for Stratix V GX and GS Devices” table. |