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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|---|
| Product Status | Obsolete |
| Number of LABs/CLBs | 234720 |
| Number of Logic Elements/Cells | 622000 |
| Total RAM Bits | 51200000 |
| Number of I/O | 600 |
| Number of Gates | - |
| Voltage - Supply | 0.82V ~ 0.88V |
| Mounting Type | Surface Mount |
| Operating Temperature | 0°C ~ 85°C (TJ) |
| Package / Case | 1517-BBGA, FCBGA |
| Supplier Device Package | 1517-FBGA (40x40) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/5sgxea7n2f40c2ln |

Table 3. Absolute Maximum Ratings for Stratix V Devices (Part 2 of 2)

| Symbol | Description | Minimum | Maximum | Unit |
|-----------------------|--------------------------------|---------|---------|------|
| V _{CCD_FPLL} | PLL digital power supply | −0.5 | 1.8 | V |
| V _{CCA_FPLL} | PLL analog power supply | −0.5 | 3.4 | V |
| V _I | DC input voltage | −0.5 | 3.8 | V |
| T _J | Operating junction temperature | −55 | 125 | °C |
| T _{STG} | Storage temperature (No bias) | −65 | 150 | °C |
| I _{OUT} | DC output current per pin | −25 | 40 | mA |

Table 4 lists the absolute conditions for the transceiver power supply for Stratix V GX, GS, and GT devices.

Table 4. Transceiver Power Supply Absolute Conditions for Stratix V GX, GS, and GT Devices

| Symbol | Description | Devices | Minimum | Maximum | Unit |
|-----------------------|--|------------|---------|---------|------|
| V _{CCA_GXBL} | Transceiver channel PLL power supply (left side) | GX, GS, GT | −0.5 | 3.75 | V |
| V _{CCA_GXBR} | Transceiver channel PLL power supply (right side) | GX, GS | −0.5 | 3.75 | V |
| V _{CCA_GTBR} | Transceiver channel PLL power supply (right side) | GT | −0.5 | 3.75 | V |
| V _{CCHIP_L} | Transceiver hard IP power supply (left side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCHIP_R} | Transceiver hard IP power supply (right side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCHSSI_L} | Transceiver PCS power supply (left side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCHSSI_R} | Transceiver PCS power supply (right side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCR_GXBL} | Receiver analog power supply (left side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCR_GXBR} | Receiver analog power supply (right side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCR_GTBR} | Receiver analog power supply for GT channels (right side) | GT | −0.5 | 1.35 | V |
| V _{CCT_GXBL} | Transmitter analog power supply (left side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCT_GXBR} | Transmitter analog power supply (right side) | GX, GS, GT | −0.5 | 1.35 | V |
| V _{CCT_GTBR} | Transmitter analog power supply for GT channels (right side) | GT | −0.5 | 1.35 | V |
| V _{CCL_GTBR} | Transmitter clock network power supply (right side) | GT | −0.5 | 1.35 | V |
| V _{CCH_GXBL} | Transmitter output buffer power supply (left side) | GX, GS, GT | −0.5 | 1.8 | V |
| V _{CCH_GXBR} | Transmitter output buffer power supply (right side) | GX, GS, GT | −0.5 | 1.8 | V |

Maximum Allowed Overshoot and Undershoot Voltage

During transitions, input signals may overshoot to the voltage shown in Table 5 and undershoot to −2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

Table 6. Recommended Operating Conditions for Stratix V Devices (Part 2 of 2)

| Symbol | Description | Condition | Min ⁽⁴⁾ | Typ | Max ⁽⁴⁾ | Unit |
|-------------------|------------------------|--------------|--------------------|-----|--------------------|------|
| t _{RAMP} | Power supply ramp time | Standard POR | 200 μ s | — | 100 ms | — |
| | | Fast POR | 200 μ s | — | 4 ms | — |

Notes to Table 6:

- (1) V_{CCPD} must be 2.5 V when V_{CCIO} is 2.5, 1.8, 1.5, 1.35, 1.25 or 1.2 V. V_{CCPD} must be 3.0 V when V_{CCIO} is 3.0 V.
- (2) If you do not use the design security feature in Stratix V devices, connect V_{CCBAT} to a 1.2- to 3.0-V power supply. Stratix V power-on-reset (POR) circuitry monitors V_{CCBAT}. Stratix V devices will not exit POR if V_{CCBAT} stays at logic low.
- (3) C2L and I2L can also be run at 0.90 V for legacy boards that were designed for the C2 and I2 speed grades.
- (4) The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

Table 7 lists the transceiver power supply recommended operating conditions for Stratix V GX, GS, and GT devices.

Table 7. Recommended Transceiver Power Supply Operating Conditions for Stratix V GX, GS, and GT Devices (Part 1 of 2)

| Symbol | Description | Devices | Minimum ⁽⁴⁾ | Typical | Maximum ⁽⁴⁾ | Unit |
|-----------------------------------|---|------------|------------------------|---------|------------------------|------|
| V _{CCA_GXBL} (1), (3) | Transceiver channel PLL power supply (left side) | GX, GS, GT | 2.85 | 3.0 | 3.15 | V |
| | | | 2.375 | 2.5 | 2.625 | |
| V _{CCA_GXBR} (1), (3) | Transceiver channel PLL power supply (right side) | GX, GS | 2.85 | 3.0 | 3.15 | V |
| | | | 2.375 | 2.5 | 2.625 | |
| V _{CCA_GTBR} | Transceiver channel PLL power supply (right side) | GT | 2.85 | 3.0 | 3.15 | V |
| V _{CCHIP_L} | Transceiver hard IP power supply (left side; C1, C2, I2, and I3YY speed grades) | GX, GS, GT | 0.87 | 0.9 | 0.93 | V |
| | Transceiver hard IP power supply (left side; C2L, C3, C4, I2L, I3, I3L, and I4 speed grades) | GX, GS, GT | 0.82 | 0.85 | 0.88 | V |
| V _{CCHIP_R} | Transceiver hard IP power supply (right side; C1, C2, I2, and I3YY speed grades) | GX, GS, GT | 0.87 | 0.9 | 0.93 | V |
| | Transceiver hard IP power supply (right side; C2L, C3, C4, I2L, I3, I3L, and I4 speed grades) | GX, GS, GT | 0.82 | 0.85 | 0.88 | V |
| V _{CCHSSI_L} | Transceiver PCS power supply (left side; C1, C2, I2, and I3YY speed grades) | GX, GS, GT | 0.87 | 0.9 | 0.93 | V |
| | Transceiver PCS power supply (left side; C2L, C3, C4, I2L, I3, I3L, and I4 speed grades) | GX, GS, GT | 0.82 | 0.85 | 0.88 | V |
| V _{CCHSSI_R} | Transceiver PCS power supply (right side; C1, C2, I2, and I3YY speed grades) | GX, GS, GT | 0.87 | 0.9 | 0.93 | V |
| | Transceiver PCS power supply (right side; C2L, C3, C4, I2L, I3, I3L, and I4 speed grades) | GX, GS, GT | 0.82 | 0.85 | 0.88 | V |
| V _{CCR_GXBL} (2) | Receiver analog power supply (left side) | GX, GS, GT | 0.82 | 0.85 | 0.88 | V |
| | | | 0.87 | 0.90 | 0.93 | |
| | | | 0.97 | 1.0 | 1.03 | |
| | | | 1.03 | 1.05 | 1.07 | |

Table 11. OCT Calibration Accuracy Specifications for Stratix V Devices ⁽¹⁾ (Part 2 of 2)

| Symbol | Description | Conditions | Calibration Accuracy | | | | Unit |
|--|--|---|----------------------|------------|----------------|------------|------|
| | | | C1 | C2,I2 | C3,I3, I3YY | C4,I4 | |
| 50-Ω R _S | Internal series termination with calibration (50-Ω setting) | V _{CCIO} = 3.0, 2.5, 1.8, 1.5, 1.2 V | ±15 | ±15 | ±15 | ±15 | % |
| 34-Ω and 40-Ω R _S | Internal series termination with calibration (34-Ω and 40-Ω setting) | V _{CCIO} = 1.5, 1.35, 1.25, 1.2 V | ±15 | ±15 | ±15 | ±15 | % |
| 48-Ω, 60-Ω, 80-Ω, and 240-Ω R _S | Internal series termination with calibration (48-Ω, 60-Ω, 80-Ω, and 240-Ω setting) | V _{CCIO} = 1.2 V | ±15 | ±15 | ±15 | ±15 | % |
| 50-Ω R _T | Internal parallel termination with calibration (50-Ω setting) | V _{CCIO} = 2.5, 1.8, 1.5, 1.2 V | -10 to +40 | -10 to +40 | -10 to +40 | -10 to +40 | % |
| 20-Ω, 30-Ω, 40-Ω, 60-Ω, and 120-Ω R _T | Internal parallel termination with calibration (20-Ω, 30-Ω, 40-Ω, 60-Ω, and 120-Ω setting) | V _{CCIO} = 1.5, 1.35, 1.25 V | -10 to +40 | -10 to +40 | -10 to +40 | -10 to +40 | % |
| 60-Ω and 120-Ω R _T | Internal parallel termination with calibration (60-Ω and 120-Ω setting) | V _{CCIO} = 1.2 | -10 to +40 | -10 to +40 | -10 to +40 | -10 to +40 | % |
| 25-Ω R _{S_left_shift} | Internal left shift series termination with calibration (25-Ω R _{S_left_shift} setting) | V _{CCIO} = 3.0, 2.5, 1.8, 1.5, 1.2 V | ±15 | ±15 | ±15 | ±15 | % |

Note to Table 11:

(1) OCT calibration accuracy is valid at the time of calibration only.

Table 12 lists the Stratix V OCT without calibration resistance tolerance to PVT changes.

Table 12. OCT Without Calibration Resistance Tolerance Specifications for Stratix V Devices (Part 1 of 2)

| Symbol | Description | Conditions | Resistance Tolerance | | | | Unit |
|-----------------------------|--|-----------------------------------|----------------------|-------|-----------------|--------|------|
| | | | C1 | C2,I2 | C3, I3, I3YY | C4, I4 | |
| 25-Ω R, 50-Ω R _S | Internal series termination without calibration (25-Ω setting) | V _{CCIO} = 3.0 and 2.5 V | ±30 | ±30 | ±40 | ±40 | % |
| 25-Ω R _S | Internal series termination without calibration (25-Ω setting) | V _{CCIO} = 1.8 and 1.5 V | ±30 | ±30 | ±40 | ±40 | % |
| 25-Ω R _S | Internal series termination without calibration (25-Ω setting) | V _{CCIO} = 1.2 V | ±35 | ±35 | ±50 | ±50 | % |

Table 12. OCT Without Calibration Resistance Tolerance Specifications for Stratix V Devices (Part 2 of 2)

| Symbol | Description | Conditions | Resistance Tolerance | | | | Unit |
|----------------------|--|-----------------------------------|----------------------|--------|--------------|--------|------|
| | | | C1 | C2, I2 | C3, I3, I3YY | C4, I4 | |
| 50-Ω R _S | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.8 and 1.5 V | ±30 | ±30 | ±40 | ±40 | % |
| 50-Ω R _S | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.2 V | ±35 | ±35 | ±50 | ±50 | % |
| 100-Ω R _D | Internal differential termination (100-Ω setting) | V _{CCPD} = 2.5 V | ±25 | ±25 | ±25 | ±25 | % |

Calibration accuracy for the calibrated series and parallel OCTs are applicable at the moment of calibration. When voltage and temperature conditions change after calibration, the tolerance may change.

OCT calibration is automatically performed at power-up for OCT-enabled I/Os. Table 13 lists the OCT variation with temperature and voltage after power-up calibration. Use Table 13 to determine the OCT variation after power-up calibration and Equation 1 to determine the OCT variation without recalibration.

Equation 1. OCT Variation Without Recalibration for Stratix V Devices ^{(1), (2), (3), (4), (5), (6)}

$$R_{OCT} = R_{SCAL} \left(1 + \left\langle \frac{dR}{dT} \times \Delta T \right\rangle \pm \left\langle \frac{dR}{dV} \times \Delta V \right\rangle \right)$$

Notes to Equation 1:

- (1) The R_{OCT} value shows the range of OCT resistance with the variation of temperature and V_{CCIO}.
- (2) R_{SCAL} is the OCT resistance value at power-up.
- (3) ΔT is the variation of temperature with respect to the temperature at power-up.
- (4) ΔV is the variation of voltage with respect to the V_{CCIO} at power-up.
- (5) dR/dT is the percentage change of R_{SCAL} with temperature.
- (6) dR/dV is the percentage change of R_{SCAL} with voltage.

Table 13 lists the on-chip termination variation after power-up calibration.

Table 13. OCT Variation after Power-Up Calibration for Stratix V Devices (Part 1 of 2) ⁽¹⁾

| Symbol | Description | V _{CCIO} (V) | Typical | Unit |
|--------|--|-----------------------|---------|--------|
| dR/dV | OCT variation with voltage without recalibration | 3.0 | 0.0297 | % / mV |
| | | 2.5 | 0.0344 | |
| | | 1.8 | 0.0499 | |
| | | 1.5 | 0.0744 | |
| | | 1.2 | 0.1241 | |

Table 23. Transceiver Specifications for Stratix V GX and GS Devices ⁽¹⁾ (Part 5 of 7)

| Symbol/ Description | Conditions | Transceiver Speed Grade 1 | | | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|---|--|------------------------------|---------------------|-------|------------------------------|---------------------|-------|------------------------------|---------------------|-------------------------------------|----------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| Programmable DC gain | DC Gain Setting = 0 | — | 0 | — | — | 0 | — | — | 0 | — | dB |
| | DC Gain Setting = 1 | — | 2 | — | — | 2 | — | — | 2 | — | dB |
| | DC Gain Setting = 2 | — | 4 | — | — | 4 | — | — | 4 | — | dB |
| | DC Gain Setting = 3 | — | 6 | — | — | 6 | — | — | 6 | — | dB |
| | DC Gain Setting = 4 | — | 8 | — | — | 8 | — | — | 8 | — | dB |
| Transmitter | | | | | | | | | | | |
| Supported I/O Standards | — | 1.4-V and 1.5-V PCML | | | | | | | | | |
| Data rate (Standard PCS) | — | 600 | — | 12200 | 600 | — | 12200 | 600 | — | 8500/ 10312.5 ⁽²⁴⁾ | Mbps |
| Data rate (10G PCS) | — | 600 | — | 14100 | 600 | — | 12500 | 600 | — | 8500/ 10312.5 ⁽²⁴⁾ | Mbps |
| Differential on- chip termination resistors | 85- Ω setting | — | 85 \pm 20% | — | — | 85 \pm 20% | — | — | 85 \pm 20% | — | Ω |
| | 100- Ω setting | — | 100 \pm 20% | — | — | 100 \pm 20% | — | — | 100 \pm 20% | — | Ω |
| | 120- Ω setting | — | 120 \pm 20% | — | — | 120 \pm 20% | — | — | 120 \pm 20% | — | Ω |
| | 150- Ω setting | — | 150 \pm 20% | — | — | 150 \pm 20% | — | — | 150 \pm 20% | — | Ω |
| V _{OCM} (AC coupled) | 0.65-V setting | — | 650 | — | — | 650 | — | — | 650 | — | mV |
| V _{OCM} (DC coupled) | — | — | 650 | — | — | 650 | — | — | 650 | — | mV |
| Rise time ⁽⁷⁾ | 20% to 80% | 30 | — | 160 | 30 | — | 160 | 30 | — | 160 | ps |
| Fall time ⁽⁷⁾ | 80% to 20% | 30 | — | 160 | 30 | — | 160 | 30 | — | 160 | ps |
| Intra-differential pair skew | Tx V _{CM} = 0.5 V and slew rate of 15 ps | — | — | 15 | — | — | 15 | — | — | 15 | ps |
| Intra-transceiver block transmitter channel-to- channel skew | x6 PMA bonded mode | — | — | 120 | — | — | 120 | — | — | 120 | ps |

Table 23. Transceiver Specifications for Stratix V GX and GS Devices ⁽¹⁾ (Part 7 of 7)

| Symbol/ Description | Conditions | Transceiver Speed Grade 1 | | | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|------------------------|------------|------------------------------|-----|-----|------------------------------|-----|-----|------------------------------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| $t_{pll_lock}^{(16)}$ | — | — | — | 10 | — | — | 10 | — | — | 10 | μs |

Notes to Table 23:

- (1) Speed grades shown in Table 23 refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Stratix V Device Overview*.
- (2) The reference clock common mode voltage is equal to the V_{CCR_GXB} power supply level.
- (3) This supply must be connected to 1.0 V if the transceiver is configured at a data rate > 6.5 Gbps, and to 1.05 V if configured at a data rate > 10.3 Gbps when DFE is used. For data rates up to 6.5 Gbps, you can connect this supply to 0.85 V.
- (4) This supply follows V_{CCR_GXB} .
- (5) The device cannot tolerate prolonged operation at this absolute maximum.
- (6) The differential eye opening specification at the receiver input pins assumes that **Receiver Equalization** is disabled. If you enable **Receiver Equalization**, the receiver circuitry can tolerate a lower minimum eye opening, depending on the equalization level.
- (7) The Quartus II software automatically selects the appropriate slew rate depending on the configured data rate or functional mode.
- (8) The input reference clock frequency options depend on the data rate and the device speed grade.
- (9) The line data rate may be limited by PCS-FPGA interface speed grade.
- (10) Refer to Figure 1 for the GX channel AC gain curves. The total effective AC gain is the AC gain minus the DC gain.
- (11) t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.
- (12) t_{LTD} is time required for the receiver CDR to start recovering valid data after the rx_is_lockedtodata signal goes high.
- (13) t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the rx_is_lockedtodata signal goes high when the CDR is functioning in the manual mode.
- (14) $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the rx_is_lockedtoref signal goes high when the CDR is functioning in the manual mode.
- (15) $t_{pll_powerdown}$ is the PLL powerdown minimum pulse width.
- (16) t_{pll_lock} is the time required for the transmitter CMU/ATX PLL to lock to the input reference clock frequency after coming out of reset.
- (17) To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula: REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.
- (18) The maximum peak to peak differential input voltage V_{ID} after device configuration is equal to $4 \times (\text{absolute } V_{MAX} \text{ for receiver pin} - V_{ICM})$.
- (19) For ES devices, R_{REF} is $2000 \Omega \pm 1\%$.
- (20) To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + $20 \times \log(f/622)$.
- (21) SFP/+ optical modules require the host interface to have RD+/- differentially terminated with 100Ω . The internal OCT feature is available after the Stratix V FPGA configuration is completed. Altera recommends that FPGA configuration is completed before inserting the optical module. Otherwise, minimize unnecessary removal and insertion with unconfigured devices.
- (22) Refer to Figure 2.
- (23) For oversampling designs to support data rates less than the minimum specification, the CDR needs to be in LTR mode only.
- (24) I3YY devices can achieve data rates up to 10.3125 Gbps.
- (25) When you use fPLL as a TXPLL of the transceiver.
- (26) REFCLK performance requires to meet transmitter REFCLK phase noise specification.
- (27) Minimum eye opening of 85 mV is only for the unstressed input eye condition.

Table 24 shows the maximum transmitter data rate for the clock network.

Table 24. Clock Network Maximum Data Rate Transmitter Specifications ⁽¹⁾

| Clock Network | ATX PLL | | | CMU PLL ⁽²⁾ | | | fPLL | | |
|--------------------------------|------------------------|--------------------|---------------------------------------|------------------------|--------------------|---------------------------------------|------------------------|--------------------|---------------------------------------|
| | Non-bonded Mode (Gbps) | Bonded Mode (Gbps) | Channel Span | Non-bonded Mode (Gbps) | Bonded Mode (Gbps) | Channel Span | Non-bonded Mode (Gbps) | Bonded Mode (Gbps) | Channel Span |
| x1 ⁽³⁾ | 14.1 | — | 6 | 12.5 | — | 6 | 3.125 | — | 3 |
| x6 ⁽³⁾ | — | 14.1 | 6 | — | 12.5 | 6 | — | 3.125 | 6 |
| x6 PLL Feedback ⁽⁴⁾ | — | 14.1 | Side-wide | — | 12.5 | Side-wide | — | — | — |
| xN (PCIe) | — | 8.0 | 8 | — | 5.0 | 8 | — | — | — |
| xN (Native PHY IP) | 8.0 | 8.0 | Up to 13 channels above and below PLL | 7.99 | 7.99 | Up to 13 channels above and below PLL | 3.125 | 3.125 | Up to 13 channels above and below PLL |
| | — | 8.01 to 9.8304 | Up to 7 channels above and below PLL | | | | | | |

Notes to Table 24:

- (1) Valid data rates below the maximum specified in this table depend on the reference clock frequency and the PLL counter settings. Check the MegaWizard message during the PHY IP instantiation.
- (2) ATX PLL is recommended at 8 Gbps and above data rates for improved jitter performance.
- (3) Channel span is within a transceiver bank.
- (4) Side-wide channel bonding is allowed up to the maximum supported by the PHY IP.

Table 28. Transceiver Specifications for Stratix V GT Devices (Part 1 of 5) ⁽¹⁾

| Symbol/ Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|--|--|--|-----------|------|------------------------------|-----------|------|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Reference Clock | | | | | | | | |
| Supported I/O Standards | Dedicated reference clock pin | 1.2-V PCML, 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, Differential LVPECL, LVDS, and HCSL | | | | | | |
| | RX reference clock pin | 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS | | | | | | |
| Input Reference Clock Frequency (CMU PLL) ⁽⁶⁾ | — | 40 | — | 710 | 40 | — | 710 | MHz |
| Input Reference Clock Frequency (ATX PLL) ⁽⁶⁾ | — | 100 | — | 710 | 100 | — | 710 | MHz |
| Rise time | 20% to 80% | — | — | 400 | — | — | 400 | ps |
| Fall time | 80% to 20% | — | — | 400 | — | — | 400 | |
| Duty cycle | — | 45 | — | 55 | 45 | — | 55 | % |
| Spread-spectrum modulating clock frequency | PCI Express (PCIe) | 30 | — | 33 | 30 | — | 33 | kHz |
| Spread-spectrum downspread | PCIe | — | 0 to −0.5 | — | — | 0 to −0.5 | — | % |
| On-chip termination resistors ⁽¹⁹⁾ | — | — | 100 | — | — | 100 | — | Ω |
| Absolute V _{MAX} ⁽³⁾ | Dedicated reference clock pin | — | — | 1.6 | — | — | 1.6 | V |
| | RX reference clock pin | — | — | 1.2 | — | — | 1.2 | |
| Absolute V _{MIN} | — | -0.4 | — | — | -0.4 | — | — | V |
| Peak-to-peak differential input voltage | — | 200 | — | 1600 | 200 | — | 1600 | mV |
| V _{ICM} (AC coupled) | Dedicated reference clock pin | 1050/1000 ⁽²⁾ | | | 1050/1000 ⁽²⁾ | | | mV |
| | RX reference clock pin | 1.0/0.9/0.85 ⁽²²⁾ | | | 1.0/0.9/0.85 ⁽²²⁾ | | | V |
| V _{ICM} (DC coupled) | HCSL I/O standard for PCIe reference clock | 250 | — | 550 | 250 | — | 550 | mV |

Table 28. Transceiver Specifications for Stratix V GT Devices (Part 2 of 5) ⁽¹⁾

| Symbol/ Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|---|---|--|---------------|--------|------------------------------|---------------|--------|----------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Transmitter REFCLK Phase Noise (622 MHz) ⁽¹⁸⁾ | 100 Hz | — | — | -70 | — | — | -70 | dBc/Hz |
| | 1 kHz | — | — | -90 | — | — | -90 | |
| | 10 kHz | — | — | -100 | — | — | -100 | |
| | 100 kHz | — | — | -110 | — | — | -110 | |
| | ≥ 1 MHz | — | — | -120 | — | — | -120 | |
| Transmitter REFCLK Phase Jitter (100 MHz) ⁽¹⁵⁾ | 10 kHz to 1.5 MHz (PCIe) | — | — | 3 | — | — | 3 | ps (rms) |
| RREF ⁽¹⁷⁾ | — | — | 1800 ± 1% | — | — | 1800 ± 1% | — | Ω |
| Transceiver Clocks | | | | | | | | |
| fixedclk clock frequency | PCIe Receiver Detect | — | 100 or 125 | — | — | 100 or 125 | — | MHz |
| Reconfiguration clock (mgmt_clk_clk) frequency | — | 100 | — | 125 | 100 | — | 125 | MHz |
| Receiver | | | | | | | | |
| Supported I/O Standards | — | 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS | | | | | | |
| Data rate (Standard PCS) ⁽²¹⁾ | GX channels | 600 | — | 8500 | 600 | — | 8500 | Mbps |
| Data rate (10G PCS) ⁽²¹⁾ | GX channels | 600 | — | 12,500 | 600 | — | 12,500 | Mbps |
| Data rate | GT channels | 19,600 | — | 28,050 | 19,600 | — | 25,780 | Mbps |
| Absolute V _{MAX} for a receiver pin ⁽³⁾ | GT channels | — | — | 1.2 | — | — | 1.2 | V |
| Absolute V _{MIN} for a receiver pin | GT channels | -0.4 | — | — | -0.4 | — | — | V |
| Maximum peak-to-peak differential input voltage V _{ID} (diff p-p) before device configuration ⁽²⁰⁾ | GT channels | — | — | 1.6 | — | — | 1.6 | V |
| | GX channels | ⁽⁸⁾ | | | | | | |
| Maximum peak-to-peak differential input voltage V _{ID} (diff p-p) after device configuration ⁽¹⁶⁾ , ⁽²⁰⁾ | GT channels V _{CCR_GTB} = 1.05 V (V _{ICM} = 0.65 V) | — | — | 2.2 | — | — | 2.2 | V |
| | GX channels | ⁽⁸⁾ | | | | | | |
| Minimum differential eye opening at receiver serial input pins ⁽⁴⁾ , ⁽²⁰⁾ | GT channels | 200 | — | — | 200 | — | — | mV |
| | GX channels | ⁽⁸⁾ | | | | | | |

Table 28. Transceiver Specifications for Stratix V GT Devices (Part 4 of 5) ⁽¹⁾

| Symbol/ Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|--|--|------------------------------|-----|--------------------------------|------------------------------|-----|--------------------------------|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Data rate | GT channels | 19,600 | — | 28,050 | 19,600 | — | 25,780 | Mbps |
| Differential on-chip termination resistors | GT channels | — | 100 | — | — | 100 | — | Ω |
| | GX channels | (8) | | | | | | |
| V _{OCM} (AC coupled) | GT channels | — | 500 | — | — | 500 | — | mV |
| | GX channels | (8) | | | | | | |
| Rise/Fall time | GT channels | — | 15 | — | — | 15 | — | ps |
| | GX channels | (8) | | | | | | |
| Intra-differential pair skew | GX channels | (8) | | | | | | |
| Intra-transceiver block transmitter channel-to- channel skew | GX channels | (8) | | | | | | |
| Inter-transceiver block transmitter channel-to- channel skew | GX channels | (8) | | | | | | |
| CMU PLL | | | | | | | | |
| Supported Data Range | — | 600 | — | 12500 | 600 | — | 8500 | Mbps |
| t _{pll_powerdown} ⁽¹³⁾ | — | 1 | — | — | 1 | — | — | μs |
| t _{pll_lock} ⁽¹⁴⁾ | — | — | — | 10 | — | — | 10 | μs |
| ATX PLL | | | | | | | | |
| Supported Data Rate Range for GX Channels | VCO post- divider L=2 | 8000 | — | 12500 | 8000 | — | 8500 | Mbps |
| | L=4 | 4000 | — | 6600 | 4000 | — | 6600 | Mbps |
| | L=8 | 2000 | — | 3300 | 2000 | — | 3300 | Mbps |
| | L=8, Local/Central Clock Divider =2 | 1000 | — | 1762.5 | 1000 | — | 1762.5 | Mbps |
| Supported Data Rate Range for GT Channels | VCO post- divider L=2 | 9800 | — | 14025 | 9800 | — | 12890 | Mbps |
| t _{pll_powerdown} ⁽¹³⁾ | — | 1 | — | — | 1 | — | — | μs |
| t _{pll_lock} ⁽¹⁴⁾ | — | — | — | 10 | — | — | 10 | μs |
| fPLL | | | | | | | | |
| Supported Data Range | — | 600 | — | 3250/ 3.125 ⁽²³⁾ | 600 | — | 3250/ 3.125 ⁽²³⁾ | Mbps |
| t _{pll_powerdown} ⁽¹³⁾ | — | 1 | — | — | 1 | — | — | μs |

Table 28. Transceiver Specifications for Stratix V GT Devices (Part 5 of 5) ⁽¹⁾

| Symbol/ Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|---------------------------------|------------|------------------------------|-----|-----|------------------------------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| t_{pll_lock} ⁽¹⁴⁾ | — | — | — | 10 | — | — | 10 | μs |

Notes to Table 28:

- (1) Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Stratix V Device Overview*.
- (2) The reference clock common mode voltage is equal to the VCCR_GXB power supply level.
- (3) The device cannot tolerate prolonged operation at this absolute maximum.
- (4) The differential eye opening specification at the receiver input pins assumes that receiver equalization is disabled. If you enable receiver equalization, the receiver circuitry can tolerate a lower minimum eye opening, depending on the equalization level.
- (5) Refer to Figure 5 for the GT channel AC gain curves. The total effective AC gain is the AC gain minus the DC gain.
- (6) Refer to Figure 6 for the GT channel DC gain curves.
- (7) CFP2 optical modules require the host interface to have the receiver data pins differentially terminated with 100 Ω. The internal OCT feature is available after the Stratix V FPGA configuration is completed. Altera recommends that FPGA configuration is completed before inserting the optical module. Otherwise, minimize unnecessary removal and insertion with unconfigured devices.
- (8) Specifications for this parameter are the same as for Stratix V GX and GS devices. See Table 23 for specifications.
- (9) t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.
- (10) t_{LTD} is time required for the receiver CDR to start recovering valid data after the $rx_is_lockedto\ data$ signal goes high.
- (11) t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the $rx_is_lockedto\ data$ signal goes high when the CDR is functioning in the manual mode.
- (12) $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the $rx_is_lockedto\ ref$ signal goes high when the CDR is functioning in the manual mode.
- (13) $tp11_powerdown$ is the PLL powerdown minimum pulse width.
- (14) $tp11_lock$ is the time required for the transmitter CMU/ATX PLL to lock to the input reference clock frequency after coming out of reset.
- (15) To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula:
REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.
- (16) The maximum peak to peak differential input voltage V_{ID} after device configuration is equal to $4 \times (\text{absolute } V_{MAX} \text{ for receiver pin} - V_{ICM})$.
- (17) For ES devices, RREF is 2000 Ω ±1%.
- (18) To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + 20*log(f/622).
- (19) SFP/+ optical modules require the host interface to have RD+/- differentially terminated with 100 Ω. The internal OCT feature is available after the Stratix V FPGA configuration is completed. Altera recommends that FPGA configuration is completed before inserting the optical module. Otherwise, minimize unnecessary removal and insertion with unconfigured devices.
- (20) Refer to Figure 4.
- (21) For oversampling design to support data rates less than the minimum specification, the CDR needs to be in LTR mode only.
- (22) This supply follows VCCR_GXB for both GX and GT channels.
- (23) When you use fPLL as a TXPLL of the transceiver.

Table 29 shows the V_{OD} settings for the GT channel.

Table 29. Typical V_{OD} Setting for GT Channel, TX Termination = 100 Ω

| Symbol | V_{OD} Setting | V_{OD} Value (mV) |
|---|------------------|---------------------|
| V_{OD} differential peak to peak typical ⁽¹⁾ | 0 | 0 |
| | 1 | 200 |
| | 2 | 400 |
| | 3 | 600 |
| | 4 | 800 |
| | 5 | 1000 |

Note:

(1) Refer to Figure 4.

Table 32. Block Performance Specifications for Stratix V DSP Devices (Part 2 of 2)

| Mode | Peformance | | | | | | | Unit |
|------------------------|------------|---------|---------|-----|---------------|-----|-----|------|
| | C1 | C2, C2L | I2, I2L | C3 | I3, I3L, I3YY | C4 | I4 | |
| Modes using Three DSPs | | | | | | | | |
| One complex 18 x 25 | 425 | 425 | 415 | 340 | 340 | 275 | 265 | MHz |
| Modes using Four DSPs | | | | | | | | |
| One complex 27 x 27 | 465 | 465 | 465 | 380 | 380 | 300 | 290 | MHz |

Memory Block Specifications

Table 33 lists the Stratix V memory block specifications.

Table 33. Memory Block Performance Specifications for Stratix V Devices ⁽¹⁾, ⁽²⁾ (Part 1 of 2)

| Memory | Mode | Resources Used | | Performance | | | | | | | Unit |
|--------|--|----------------|--------|-------------|---------|-----|-----|---------|---------------|-----|------|
| | | ALUTs | Memory | C1 | C2, C2L | C3 | C4 | I2, I2L | I3, I3L, I3YY | I4 | |
| MLAB | Single port, all supported widths | 0 | 1 | 450 | 450 | 400 | 315 | 450 | 400 | 315 | MHz |
| | Simple dual-port, x32/x64 depth | 0 | 1 | 450 | 450 | 400 | 315 | 450 | 400 | 315 | MHz |
| | Simple dual-port, x16 depth ⁽³⁾ | 0 | 1 | 675 | 675 | 533 | 400 | 675 | 533 | 400 | MHz |
| | ROM, all supported widths | 0 | 1 | 600 | 600 | 500 | 450 | 600 | 500 | 450 | MHz |

Table 36. High-Speed I/O Specifications for Stratix V Devices ^{(1), (2)} (Part 4 of 4)

| Symbol | Conditions | C1 | | | C2, C2L, I2, I2L | | | C3, I3, I3L, I3YY | | | C4, I4 | | | Unit |
|-------------------------------|---|-----|-----|-----------|------------------|-----|-----------|-------------------|-----|-----------|--------|-----|-----------|----------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f _{HSDR} (data rate) | SERDES factor J = 3 to 10 | (6) | — | (8) | (6) | — | (8) | (6) | — | (8) | (6) | — | (8) | Mbps |
| | SERDES factor J = 2, uses DDR Registers | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| | SERDES factor J = 1, uses SDR Register | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | (6) | — | (7) | Mbps |
| DPA Mode | | | | | | | | | | | | | | |
| DPA run length | — | — | — | 1000 0 | — | — | 1000 0 | — | — | 1000 0 | — | — | 1000 0 | UI |
| Soft CDR mode | | | | | | | | | | | | | | |
| Soft-CDR PPM tolerance | — | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 300 | ± PPM |
| Non DPA Mode | | | | | | | | | | | | | | |
| Sampling Window | — | — | — | 300 | — | — | 300 | — | — | 300 | — | — | 300 | ps |

Notes to Table 36:

- (1) When J = 3 to 10, use the serializer/deserializer (SERDES) block.
- (2) When J = 1 or 2, bypass the SERDES block.
- (3) This only applies to DPA and soft-CDR modes.
- (4) Clock Boost Factor (W) is the ratio between the input data rate to the input clock rate.
- (5) This is achieved by using the **LVDS** clock network.
- (6) The minimum specification depends on the clock source (for example, the PLL and clock pin) and the clock routing resource (global, regional, or local) that you use. The I/O differential buffer and input register do not have a minimum toggle rate.
- (7) The maximum ideal frequency is the SERDES factor (J) x the PLL maximum output frequency (f_{OUT}) provided you can close the design timing and the signal integrity simulation is clean.
- (8) You can estimate the achievable maximum data rate for non-DPA mode by performing link timing closure analysis. You must consider the board skew margin, transmitter delay margin, and receiver sampling margin to determine the maximum data rate supported.
- (9) If the receiver with DPA enabled and transmitter are using shared PLLs, the minimum data rate is 150 Mbps.
- (10) You must calculate the leftover timing margin in the receiver by performing link timing closure analysis. You must consider the board skew margin, transmitter channel-to-channel skew, and receiver sampling margin to determine leftover timing margin.
- (11) The F_{MAX} specification is based on the fast clock used for serial data. The interface F_{MAX} is also dependent on the parallel clock domain which is design-dependent and requires timing analysis.
- (12) Stratix V RX LVDS will need DPA. For Stratix V TX LVDS, the receiver side component must have DPA.
- (13) Stratix V LVDS serialization and de-serialization factor needs to be x4 and above.
- (14) Requires package skew compensation with PCB trace length.
- (15) Do not mix single-ended I/O buffer within LVDS I/O bank.
- (16) Chip-to-chip communication only with a maximum load of 5 pF.
- (17) When using True LVDS RX channels for emulated LVDS TX channel, only serialization factors 1 and 2 are supported.

Table 42. Memory Output Clock Jitter Specification for Stratix V Devices ⁽¹⁾, (Part 2 of 2) ⁽²⁾, ⁽³⁾

| Clock Network | Parameter | Symbol | C1 | | C2, C2L, I2, I2L | | C3, I3, I3L, I3YY | | C4,I4 | | Unit |
|---------------|------------------------------|-----------------|-------|------|------------------|------|-------------------|-----|-------|-----|------|
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| PHY Clock | Clock period jitter | $t_{JIT(per)}$ | -25 | 25 | -25 | 25 | -30 | 30 | -35 | 35 | ps |
| | Cycle-to-cycle period jitter | $t_{JIT(cc)}$ | -50 | 50 | -50 | 50 | -60 | 60 | -70 | 70 | ps |
| | Duty cycle jitter | $t_{JIT(duty)}$ | -37.5 | 37.5 | -37.5 | 37.5 | -45 | 45 | -56 | 56 | ps |

Notes to Table 42:

- (1) The clock jitter specification applies to the memory output clock pins generated using differential signal-splitter and DDIO circuits clocked by a PLL output routed on a PHY, regional, or global clock network as specified. Altera recommends using PHY clock networks whenever possible.
- (2) The clock jitter specification applies to the memory output clock pins clocked by an integer PLL.
- (3) The memory output clock jitter is applicable when an input jitter of 30 ps peak-to-peak is applied with bit error rate (BER) -12, equivalent to 14 sigma.

OCT Calibration Block Specifications

Table 43 lists the OCT calibration block specifications for Stratix V devices.

Table 43. OCT Calibration Block Specifications for Stratix V Devices

| Symbol | Description | Min | Typ | Max | Unit |
|----------------|---|-----|------|-----|--------|
| OCTUSRCLK | Clock required by the OCT calibration blocks | — | — | 20 | MHz |
| T_{OCTCAL} | Number of OCTUSRCLK clock cycles required for OCT R_S/R_T calibration | — | 1000 | — | Cycles |
| $T_{OCTSHIFT}$ | Number of OCTUSRCLK clock cycles required for the OCT code to shift out | — | 32 | — | Cycles |
| T_{RS_RT} | Time required between the <code>dyn_term_ctrl</code> and <code>oe</code> signal transitions in a bidirectional I/O buffer to dynamically switch between OCT R_S and R_T (Figure 10) | — | 2.5 | — | ns |

Figure 10 shows the timing diagram for the `oe` and `dyn_term_ctrl` signals.

Figure 10. Timing Diagram for `oe` and `dyn_term_ctrl` Signals

Table 48. Minimum Configuration Time Estimation for Stratix V Devices

| Variant | Member Code | Active Serial ⁽¹⁾ | | | Fast Passive Parallel ⁽²⁾ | | |
|---------|-------------|------------------------------|------------|---------------------|--------------------------------------|------------|---------------------|
| | | Width | DCLK (MHz) | Min Config Time (s) | Width | DCLK (MHz) | Min Config Time (s) |
| GS | D3 | 4 | 100 | 0.344 | 32 | 100 | 0.043 |
| | D4 | 4 | 100 | 0.534 | 32 | 100 | 0.067 |
| | | 4 | 100 | 0.344 | 32 | 100 | 0.043 |
| | D5 | 4 | 100 | 0.534 | 32 | 100 | 0.067 |
| | D6 | 4 | 100 | 0.741 | 32 | 100 | 0.093 |
| | D8 | 4 | 100 | 0.741 | 32 | 100 | 0.093 |
| E | E9 | 4 | 100 | 0.857 | 32 | 100 | 0.107 |
| | EB | 4 | 100 | 0.857 | 32 | 100 | 0.107 |

Notes to Table 48:

(1) DCLK frequency of 100 MHz using external CLKUSR.

(2) Max FPGA FPP bandwidth may exceed bandwidth available from some external storage or control logic.

Fast Passive Parallel Configuration Timing

This section describes the fast passive parallel (FPP) configuration timing parameters for Stratix V devices.

DCLK-to-DATA[] Ratio for FPP Configuration

FPP configuration requires a different DCLK-to-DATA[] ratio when you enable the design security, decompression, or both features. Table 49 lists the DCLK-to-DATA[] ratio for each combination.

Table 49. DCLK-to-DATA[] Ratio ⁽¹⁾ (Part 1 of 2)

| Configuration Scheme | Decompression | Design Security | DCLK-to-DATA[] Ratio |
|----------------------|---------------|-----------------|----------------------|
| FPP ×8 | Disabled | Disabled | 1 |
| | Disabled | Enabled | 1 |
| | Enabled | Disabled | 2 |
| | Enabled | Enabled | 2 |
| FPP ×16 | Disabled | Disabled | 1 |
| | Disabled | Enabled | 2 |
| | Enabled | Disabled | 4 |
| | Enabled | Enabled | 4 |

Table 49. DCLK-to-DATA[] Ratio ⁽¹⁾ (Part 2 of 2)

| Configuration Scheme | Decompression | Design Security | DCLK-to-DATA[] Ratio |
|----------------------|---------------|-----------------|----------------------|
| FPP ×32 | Disabled | Disabled | 1 |
| | Disabled | Enabled | 4 |
| | Enabled | Disabled | 8 |
| | Enabled | Enabled | 8 |

Note to Table 49:

- (1) Depending on the DCLK-to-DATA[] ratio, the host must send a DCLK frequency that is r times the data rate in bytes per second (Bps), or words per second (Wps). For example, in FPP ×16 when the DCLK-to-DATA[] ratio is 2, the DCLK frequency must be 2 times the data rate in Wps. Stratix V devices use the additional clock cycles to decrypt and decompress the configuration data.



If the DCLK-to-DATA[] ratio is greater than 1, at the end of configuration, you can only stop the DCLK (DCLK-to-DATA[] ratio – 1) clock cycles after the last data is latched into the Stratix V device.

Figure 11 shows the configuration interface connections between the Stratix V device and a MAX II or MAX V device for single device configuration.

Figure 11. Single Device FPP Configuration Using an External Host**Notes to Figure 11:**

- (1) Connect the resistor to a supply that provides an acceptable input signal for the Stratix V device. V_{CCPGM} must be high enough to meet the V_{IH} specification of the I/O on the device and the external host. Altera recommends powering up all configuration system I/Os with V_{CCPGM} .
- (2) You can leave the nCEO pin unconnected or use it as a user I/O pin when it does not feed another device's nCE pin.
- (3) The MSEL pin settings vary for different data width, configuration voltage standards, and POR delay. To connect MSEL, refer to the MSEL Pin Settings section of the "Configuration, Design Security, and Remote System Upgrades in Stratix V Devices" chapter.
- (4) If you use FPP ×8, use DATA[7..0]. If you use FPP ×16, use DATA[15..0].

Table 58. IOE Programmable Delay for Stratix V Devices (Part 2 of 2)

| Parameter (1) | Available Settings | Min Offset (2) | Fast Model | | Slow Model | | | | | | | |
|------------------|-----------------------|----------------------|------------|------------|------------|-------|-------|-------|-------|-------------|-------|------|
| | | | Industrial | Commercial | C1 | C2 | C3 | C4 | I2 | I3, I3YY | I4 | Unit |
| D3 | 8 | 0 | 1.587 | 1.699 | 2.793 | 2.793 | 2.992 | 3.192 | 2.811 | 3.047 | 3.257 | ns |
| D4 | 64 | 0 | 0.464 | 0.492 | 0.838 | 0.838 | 0.924 | 1.011 | 0.843 | 0.920 | 1.006 | ns |
| D5 | 64 | 0 | 0.464 | 0.493 | 0.838 | 0.838 | 0.924 | 1.011 | 0.844 | 0.921 | 1.006 | ns |
| D6 | 32 | 0 | 0.229 | 0.244 | 0.415 | 0.415 | 0.458 | 0.503 | 0.418 | 0.456 | 0.499 | ns |

Notes to Table 58:

- (1) You can set this value in the Quartus II software by selecting **D1**, **D2**, **D3**, **D5**, and **D6** in the **Assignment Name** column of **Assignment Editor**.
- (2) Minimum offset does not include the intrinsic delay.

Programmable Output Buffer Delay

Table 59 lists the delay chain settings that control the rising and falling edge delays of the output buffer. The default delay is 0 ps.

Table 59. Programmable Output Buffer Delay for Stratix V Devices (1)

| Symbol | Parameter | Typical | Unit |
|---------------------|----------------------------------|-------------|------|
| D _{OUTBUF} | Rising and/or falling edge delay | 0 (default) | ps |
| | | 25 | ps |
| | | 50 | ps |
| | | 75 | ps |

Note to Table 59:

- (1) You can set the programmable output buffer delay in the Quartus II software by setting the **Output Buffer Delay Control** assignment to either positive, negative, or both edges, with the specific values stated here (in ps) for the **Output Buffer Delay** assignment.

Glossary

Table 60 lists the glossary for this chapter.

Table 60. Glossary (Part 1 of 4)

| Letter | Subject | Definitions |
|--------|----------------------|---|
| A | — | — |
| B | | |
| C | | |
| D | — | — |
| E | — | — |
| F | f _{HCLK} | Left and right PLL input clock frequency. |
| | f _{HSDR} | High-speed I/O block—Maximum and minimum LVDS data transfer rate (f _{HSDR} = 1/TUI), non-DPA. |
| | f _{HSDRDPA} | High-speed I/O block—Maximum and minimum LVDS data transfer rate (f _{HSDRDPA} = 1/TUI), DPA. |

