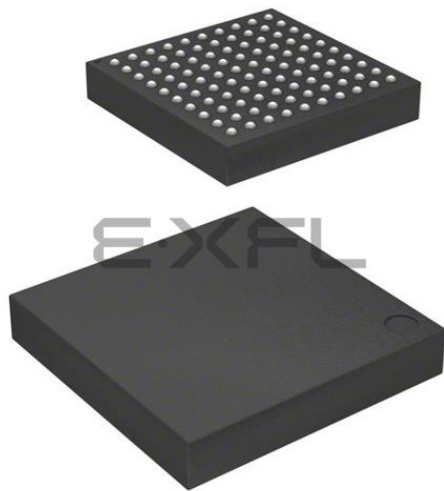




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, EBI/EMI, I ² C, MMC/SD, QSPI, SCI, SPI, SSI, UART/USART, USB
Peripherals	DMA, LCD, LVD, POR, PWM, WDT
Number of I/O	84
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	96K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 25x14b; D/A 3x8b, 3x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TFLGA
Supplier Device Package	100-TFLGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r7fs3a37a2a01clj-ac0

High efficiency 48-MHz Arm® Cortex®-M4 core, 512-KB code flash memory, 96-KB SRAM, Segment LCD Controller, Capacitive Touch Sensing Unit, USB 2.0 Full-Speed, 14-Bit A/D Converter, 12-Bit D/A Converter, security and safety features.

Features

■ Arm Cortex-M4 Core with Floating Point Unit (FPU)

- Armv7E-M architecture with DSP instruction set
- Maximum operating frequency: 48 MHz
- Support for 4-GB address space
- Arm Memory Protection Unit (Arm MPU) with 8 regions
- Debug and Trace: ITM, DWT, FPB, TPIU, and ETB
- CoreSight™ debug port: JTAG-DP and SW-DP

■ Memory

- 512-KB code flash memory
- 8-KB data flash memory (100,000 erase/write cycles)
- 96-KB SRAM
- Flash Cache (FCACHE)
- Memory Protection Units
- Memory Mirror Function (MMF)
- 128-bit unique ID

■ Connectivity

- USB 2.0 Full-Speed (USBFS) module
 - On-chip transceiver with voltage regulator
 - Compliant with USB Battery Charging Specification 1.2
- Serial Communications Interface (SCI) × 6
 - UART
 - Simple IIC
 - Simple SPI
- Serial Peripheral Interface (SPI) × 2
- I²C bus interface (IIC) × 3
- Controller Area Network (CAN) module
- Serial Sound Interface Enhanced (SSIE)
- SD/MMC Host Interface (SDHI)
- Quad Serial Peripheral Interface (QSPI)
- External address space
 - 8-bit or 16-bit bus space is selectable per area

■ Analog

- 14-bit A/D Converter (ADC14)
- 12-bit D/A Converter (DAC12)
- 8-bit D/A Converter (DAC8) × 2 (for ACMPPLP)
- Low Power Analog Comparator (ACMPPLP) × 2
- Operational Amplifier (OPAMP) × 4
- Temperature Sensor (TSN)

■ Timers

- General PWM Timer 32-bit (GPT32) × 4
- General PWM Timer 16-bit (GPT16) × 6
- Asynchronous General-Purpose Timer (AGT) × 2
- Watchdog Timer (WDT)

■ Safety

- Error Correction Code (ECC) in SRAM
- SRAM parity error check
- Flash area protection
- ADC self-diagnosis function
- Clock Frequency Accuracy Measurement Circuit (CAC)
- Cyclic Redundancy Check (CRC) calculator
- Data Operation Circuit (DOC)
- Port Output Enable for GPT (POEG)
- Independent Watchdog Timer (IWDT)
- GPIO readback level detection
- Register write protection
- Main oscillator stop detection
- Illegal memory access

■ System and Power Management

- Low power modes
- RealTime Clock (RTC) with calendar and Battery Backup support
- Event Link Controller (ELC)
- DMA Controller (DMAC) × 4
- Data Transfer Controller (DTC)
- Key Interrupt Function (KINT)
- Power-on reset
- Low Voltage Detection (LVD) with voltage settings

■ Security and Encryption

- AES128/256
- GHASH
- True Random Number Generator (TRNG)

■ Human Machine Interface (HMI)

- Segment LCD Controller (SLCDC)
 - Up to 54 segments × 4 commons
 - Up to 50 segments × 8 commons
- Capacitive Touch Sensing Unit (CTSU)

■ Multiple Clock Sources

- Main clock oscillator (MOSC)
 - (1 to 20 MHz when VCC = 2.4 to 5.5 V)
 - (1 to 8 MHz when VCC = 1.8 to 2.4 V)
 - (1 to 4 MHz when VCC = 1.6 to 1.8 V)
- Sub-clock oscillator (SOSC) (32.768 kHz)
- High-speed on-chip oscillator (HOCO)
 - (24, 32, 48, 64 MHz when VCC = 2.4 to 5.5 V)
 - (24, 32, 48 MHz when VCC = 1.8 to 5.5 V)
 - (24, 32 MHz when VCC = 1.6 to 5.5 V)
- Middle-speed on-chip oscillator (MOCO) (8 MHz)
- Low-speed on-chip oscillator (LOCO) (32.768 kHz)
- IWDT-dedicated on-chip oscillator (15 kHz)
- Clock trim function for HOCO/MOCO/LOCO
- Clock out support

■ General Purpose I/O Ports

- Up to 126 input/output pins
 - Up to 3 CMOS input
 - Up to 123 CMOS input/output
 - Up to 11 input/output 5 V tolerant
 - Up to 2 high current (20 mA)

■ Operating Voltage

- VCC: 1.6 to 5.5 V

■ Operating Temperature and Packages

- Ta = -40°C to +85°C
 - 145-pin LGA (7 mm × 7 mm, 0.5 mm pitch)
 - 121-pin BGA (8 mm × 8 mm, 0.65 mm pitch)
 - 100-pin LGA (7 mm × 7 mm, 0.65 mm pitch)
- Ta = -40°C to +105°C
 - 144-pin LQFP (20 mm × 20 mm, 0.5 mm pitch)
 - 100-pin LQFP (14 mm × 14 mm, 0.5 mm pitch)
 - 64-pin LQFP (10 mm × 10 mm, 0.5 mm pitch)
 - 64-pin QFN (8 mm × 8 mm, 0.4 mm pitch)

Pin number							Power, System, Clock, Debug, CAC, VBATT	Interrupt	I/O ports	External bus	Timers				Communication interfaces						Analog			HMI	
LGA145	LQFP144	BGA121	LQFP100	LGA100	LQFP64	QFN64					AGT	GPT_OPS, POEG	GPT	RTC	USBFS,CAN	SCI	IC	SP/QSPI	SSIE	SDHI	ADC14	DAC12, OPAMP	ACMPLP	SLCDC	CTSU
D11	32	C11	21	D8	12	12		IRQ4	P411		AGTO A1	GTOV UP	GTIOC 9A			TXD0/ MOSIO /SDA0 CTS3/ RTS3/ SS3		MOSIA		SD0D AT0				SEG7	TS7
C12	33	C10	22	E6	13	13		IRQ5	P410		AGTO B1	GTOV LO	GTIOC 9B			SCK3 RXD0/ MISO0 /SCL0		MISOA		SD0D AT1				SEG8	TS6
B13	34	C9	23	B10	14	14		IRQ6	P409			GTOV UP	GTIOC 5A		USB_E XICEN	TXD3/ MOSI3 /SDA3								SEG9	TS5
D10	35	B11	24	D7	15	15		IRQ7	P408			GTOV LO	GTIOC 5B		USB_I D	CTS1 RTS1/ SS1 RXD3/ MISO3 /SCL3	SCL0							SEG10	TS4
A13	36	A11	25	A10	16	16			P407		AGTIO 0			RTCO UT	USB_V BUS	CTS4 RTS4/ SS4	SDA0	SSLB3			ADTR G0			SEG11	TS3
B11	37	B9	26	B8	17	17	VSS_U SB																		
A12	38	A10	27	A9	18	18			P915						USB_ DM										
B12	39	B10	28	B9	19	19			P914						USB_ DP										
A11	40	A9	29	A8	20	20	VCC_ USB																		
C11	41	B8	30	C8	21	21	VCC_ USB_L DO																		
B10	42	C8	31	C7	22	22		IRQ0	P206	WAIT		GTIU			USB_V BUSE N	RXD4/ MISO4 /SCL4	SDA1	SSLB1		SD0D AT2				SEG12	TS1
A10	43	A8	32	A7	23	23	CLKO UT	IRQ1	P205	A16	AGTIO 1	GTIV	GTIOC 4A		USB_ OVRC URA	TXD4/ MOSI4 /SDA4 CTS9_ RTS9/ SS9	SCL1	SSLB0		SD0D AT3				SEG20	TSCA P
C10	44	D8	33	B7	24	24	CACR EF		P204	A18	AGTIO 1	GTIW	GTIOC 4B		USB_ OVRC URB	SCK4 SCK9	SCL0	RSPC KB		SD0D AT4				SEG23	TS0
A9	45	A7	34	D6				IRQ2	P203	A19			GTIOC 5A			CTS2_ RTS2/ SS2 TXD9/ MOSI9 /SDA9		MOSIB		SD0D AT5				SEG22	TSCA P
C9	46	B7	35	C6				IRQ3	P202	WR1/ BC1			GTIOC 5B			SCK2 RXD9/ MISO9 /SCL9		MISOB		SD0D AT6				SEG21	
B9	47	C7							P313	A20										SD0D AT7					
D9	48	D7							P314	A21											ADTR G0				
D8	49	E7							P315	A22						RXD4/ MISO4 /SCL4									
A8	50								P900	A23						TXD4/ MOSI4 /SDA4									
B8	51								P901		AGTIO 1					SCK4									
B7	52								P902		AGTO 1					CTS4_ RTS4/ SS4									
A7	53	A6	36	A6			VSS																		
A6	54	B6	37	B6			VCC																		
C7	55	C6	38	D5	25	25	RES																		
B6	56	D6	39	B5	26	26	MD		P201																

Table 2.2 Recommended operating conditions

Parameter	Symbol	Value	Min	Typ	Max	Unit
Power supply voltages	VCC*1, *2	When USBFS is not used	1.6	-	5.5	V
		When USBFS is used USB Regulator Disable	VCC_USB	-	3.6	V
		When USBFS is used USB Regulator Enable	VCC_USB_LDO	-	5.5	V
	VSS		-	0	-	V
USB power supply voltages	VCC_USB	When USBFS is not used	-	VCC	-	V
		When USBFS is used USB Regulator Disable (Input)	3.0	3.3	3.6	V
	VCC_USB_LDO	When USBFS is not used	-	VCC	-	V
		When USBFS is used USB Regulator Disable	-	VCC	-	V
		When USBFS is used USB Regulator Enable	3.8	-	5.5	V
	VSS_USB		-	0	-	V
VBATT power supply voltage	VBATT	When the battery backup function is not used	-	VCC	-	V
		When the battery backup function is used	1.6	-	3.6	V
Analog power supply voltages	AVCC0*1, *2		1.6	-	5.5	V
	AVSS0		-	0	-	V
	VREFH0	When used as ADC14 Reference	1.6	-	AVCC0	V
	VREFL0		-	0	-	V
	VREFH	When used as DAC12 Reference	1.6	-	AVCC0	V
	VREFL		-	0	-	V

Note 1. Use AVCC0 and VCC under the following conditions:

AVCC0 and VCC can be set individually within the operating range when $VCC \geq 2.2\text{ V}$ and $AVCC0 \geq 2.2\text{ V}$

$AVCC0 = VCC$ when $VCC < 2.2\text{ V}$ or $AVCC0 < 2.2\text{ V}$

Note 2. When powering on the VCC and AVCC0 pins, power them on at the same time or the VCC pin first and then the AVCC0 pin.

2.2 DC Characteristics

2.2.1 Tj/Ta Definition

Table 2.3 DC characteristics

 Conditions: Products with operating temperature (T_a) -40 to $+105^{\circ}\text{C}$

Parameter	Symbol	Typ	Max	Unit	Test conditions
Permissible junction temperature	Tj	-	125	$^{\circ}\text{C}$	High-speed mode Middle-speed mode Low-voltage mode Low-speed mode Subosc-speed mode
			105*1		

Note: Make sure that $T_j = T_a + \theta_{ja} \times \text{total power consumption (W)}$, where total power consumption = $(V_{CC} - V_{OH}) \times \Sigma I_{OH} + V_{OL} \times \Sigma I_{OL} + I_{CCmax} \times V_{CC}$.

Note 1. The upper limit of operating temperature is 85°C or 105°C , depending on the product. For details, see [section 1.3, Part Numbering](#). If the part number shows the operation temperature at 85°C , then the maximum value of Tj is 105°C , otherwise, it is 125°C .

2.2.2 I/O V_{IH} , V_{IL}

Table 2.4 I/O V_{IH} , V_{IL} (1)

 Conditions: $V_{CC} = AV_{CC0} = V_{CC_USB} = V_{CC_USB_LDO} = 2.7$ to 5.5V , $V_{BATT} = 1.6$ to 3.6V , $V_{SS} = AV_{SS0} = 0\text{V}$

Parameter		Symbol	Min	Typ	Max	Unit	Test conditions
Schmitt trigger input voltage	IIC*1 (except for SMBus)	V_{IH}	$V_{CC} \times 0.7$	-	5.8	V	-
		V_{IL}	-	-	$V_{CC} \times 0.3$		
		ΔV_T	$V_{CC} \times 0.05$	-	-		
	RES, NMI Other peripheral input pins excluding IIC	V_{IH}	$V_{CC} \times 0.8$	-	-		
		V_{IL}	-	-	$V_{CC} \times 0.2$		
		ΔV_T	$V_{CC} \times 0.1$	-	-		
Input voltage (except for Schmitt trigger input pin)	IIC (SMBus)*2	V_{IH}	2.2	-	-		$V_{CC} = 3.6$ to 5.5V
		V_{IH}	2.0	-	-		$V_{CC} = 2.7$ to 3.6V
		V_{IL}	-	-	0.8		-
	5V-tolerant ports*3	V_{IH}	$V_{CC} \times 0.8$	-	5.8		
		V_{IL}	-	-	$V_{CC} \times 0.2$		
	P914, P915	V_{IH}	$V_{CC_USB} \times 0.8$	-	$V_{CC_USB} + 0.3$		
		V_{IL}	-	-	$V_{CC_USB} \times 0.2$		
	P000 to P015	V_{IH}	$AV_{CC0} \times 0.8$	-	-		
		V_{IL}	-	-	$AV_{CC0} \times 0.2$		
	EXTAL D00 to D15 Input ports pins except for P000 to P015, P914, P915	V_{IH}	$V_{CC} \times 0.8$	-	-		
		V_{IL}	-	-	$V_{CC} \times 0.2$		
	When V_{BATT} power supply is selected	V_{IH}	$V_{BATT} \times 0.8$	-	$V_{BATT} + 0.3$		
		V_{IL}	-	-	$V_{BATT} \times 0.2$		
		ΔV_T	$V_{BATT} \times 0.05$	-	-		

Note 1. P205, P206, P400, P401, P407, P408, P511, P512 (total 8 pins).

Note 2. P100, P101, P204, P205, P206, P400, P401, P407, P408, P511, P512 (total 11 pins).

Note 3. P205, P206, P400 to P404, P407, P408, P511, P512 (total 11 pins).

2.2.3 I/O I_{OH} , I_{OL} **Table 2.6** I/O I_{OH} , I_{OL} (1 of 2)Conditions: $V_{CC} = AV_{CC0} = V_{CC_USB} = V_{CC_USB_LCO} = 1.6$ to 5.5 V

Parameter			Symbol	Min	Typ	Max	Unit
Permissible output current (average value per pin)	Ports P212, P213	-	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
	Port P408	Low drive*1	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
		Middle drive for IIC Fast-mode*4 $V_{CC} = 2.7$ to 5.5 V	I_{OH}	-	-	-8.0	mA
			I_{OL}	-	-	8.0	mA
		Middle drive*2 $V_{CC} = 3.0$ to 5.5 V	I_{OH}	-	-	-20.0	mA
			I_{OL}	-	-	20.0	mA
	Port P409	Low drive*1	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
		Middle drive*2 $V_{CC} = 2.7$ to 3.0 V	I_{OH}	-	-	-8.0	mA
			I_{OL}	-	-	8.0	mA
		Middle drive*2 $V_{CC} = 3.0$ to 5.5 V	I_{OH}	-	-	-20.0	mA
			I_{OL}	-	-	20.0	mA
	Ports P100 to P115, P201 to P204, P300 to P315, P500 to P503, P600 to P606, P608 to P614, P800 to P809, P900 to P902 (total 67 pins)	Low drive*1	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
		Middle drive*2	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	8.0	mA
	Ports P914, P915	-	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
	Other output pin*3	Low drive*1	I_{OH}	-	-	-4.0	mA
			I_{OL}	-	-	4.0	mA
		Middle drive*2	I_{OH}	-	-	-8.0	mA
			I_{OL}	-	-	8.0	mA

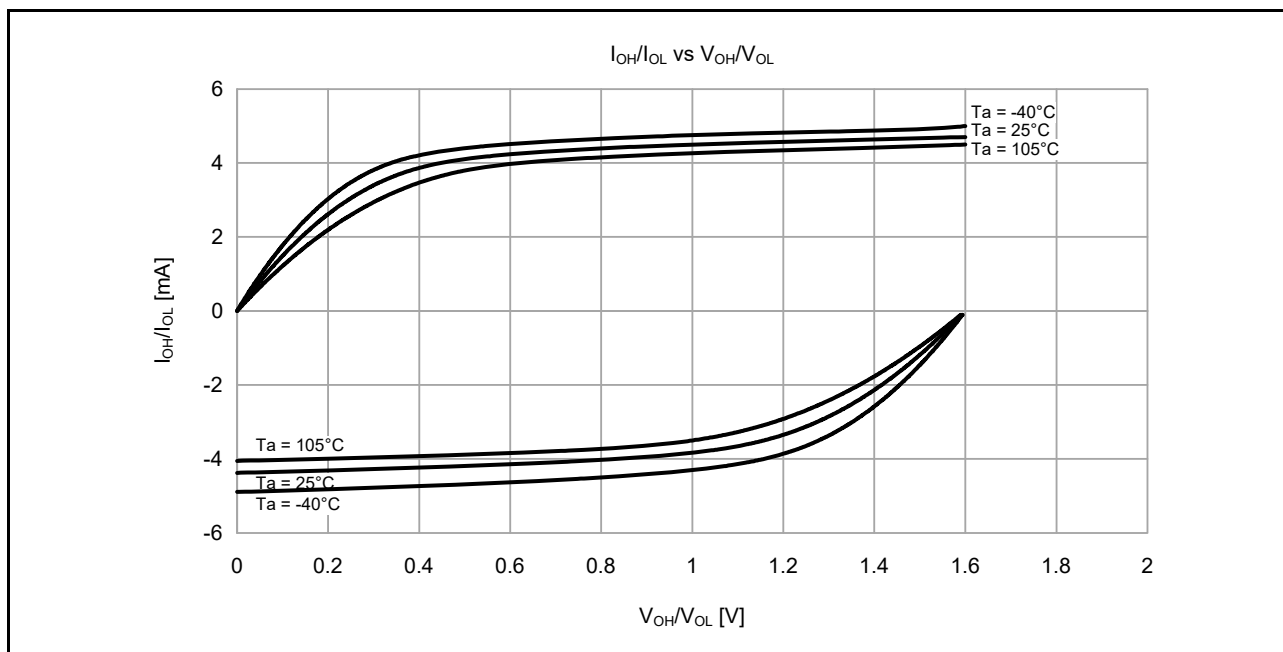


Figure 2.8 V_{OH}/V_{OL} and I_{OH}/I_{OL} temperature characteristics at $V_{CC} = 1.6$ V when middle drive output is selected (reference data)

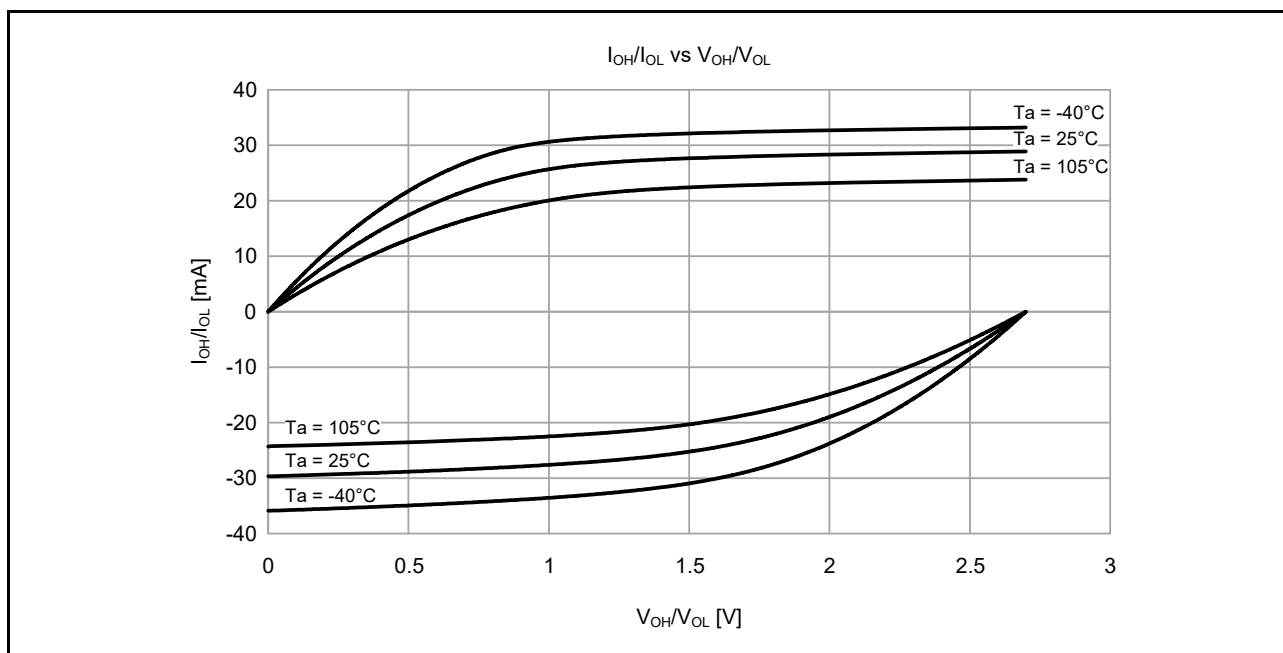


Figure 2.9 V_{OH}/V_{OL} and I_{OH}/I_{OL} temperature characteristics at $V_{CC} = 2.7$ V when middle drive output is selected (reference data)

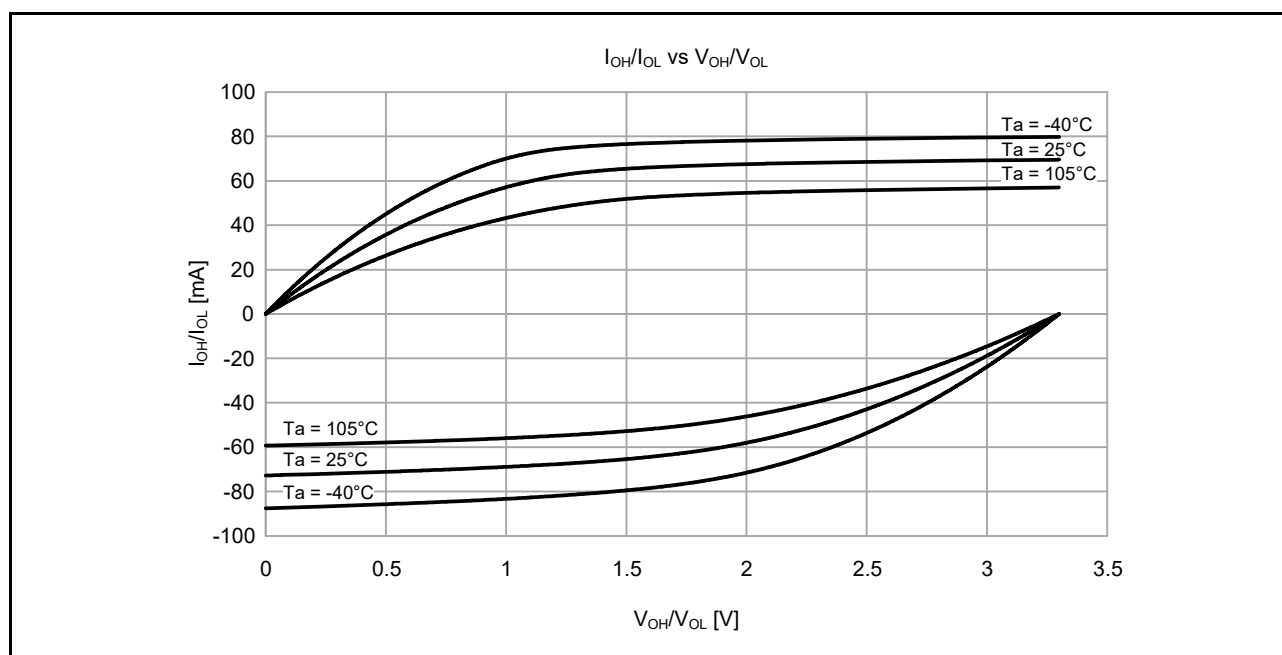


Figure 2.14 V_{OH}/V_{OL} and I_{OH}/I_{OL} temperature characteristics at $V_{CC} = 3.3$ V when middle drive output is selected (reference data)

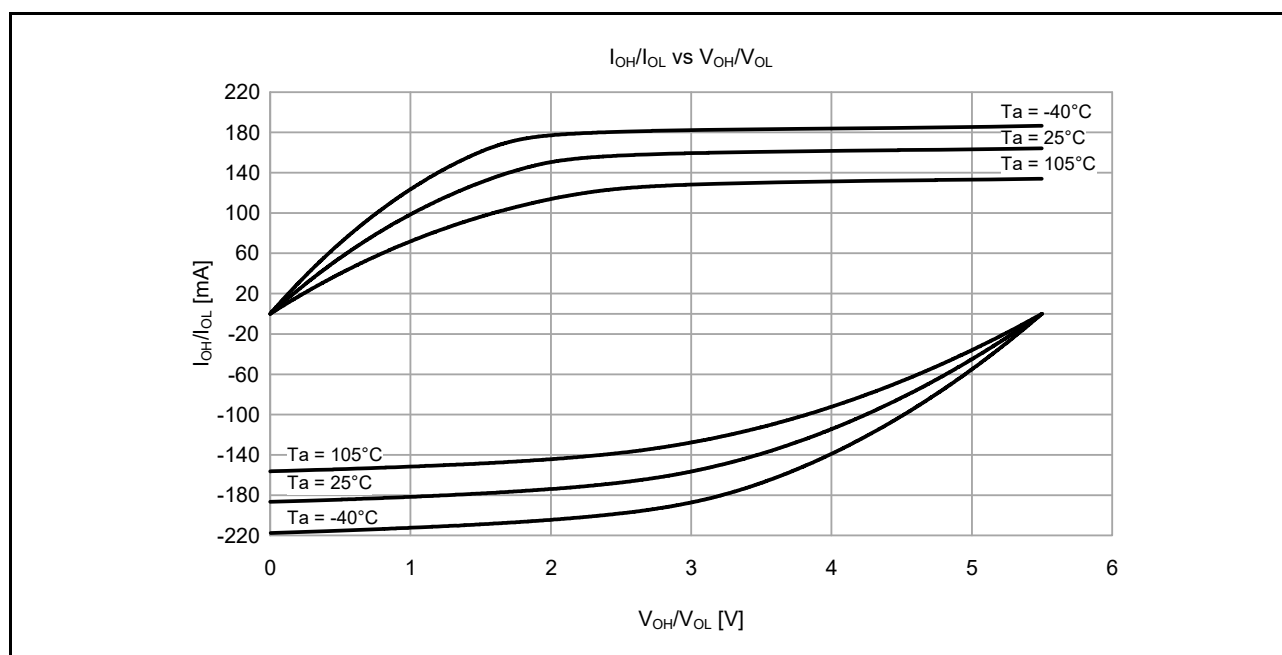


Figure 2.15 V_{OH}/V_{OL} and I_{OH}/I_{OL} temperature characteristics at $V_{CC} = 5.5$ V when middle drive output is selected (reference data)

2.2.9 Operating and Standby Current

Table 2.11 Operating and standby current (1) (1 of 2)

Conditions: VCC = AVCC0 = 1.6 to 5.5 V

Parameter					Symbol	Typ*10	Max	Unit	Test conditions	
Supply current*1	High-speed mode*2	Normal mode	All peripheral clock disabled, while (1) code executing from flash*5	ICLK = 48 MHz	I _{CC}	8.4	-	mA	*7	
				ICLK = 32 MHz		5.9	-			
				ICLK = 16 MHz		3.5	-			
				ICLK = 8 MHz		2.3	-			
			All peripheral clock disabled, CoreMark code executing from flash*5	ICLK = 48 MHz		17.9	-			
				ICLK = 32 MHz		12.4	-			
				ICLK = 16 MHz		7.0	-			
				ICLK = 8 MHz		4.3	-			
			All peripheral clock enabled, while (1) code executing from flash*5	ICLK = 48 MHz		21.2	-		*9	
				ICLK = 32 MHz		16.0	-		*8	
				ICLK = 16 MHz		8.8	-			
				ICLK = 8 MHz		5.1	-			
			All peripheral clock enabled, code executing from SRAM*5	ICLK = 48 MHz		-	56.0		*9	
			Sleep mode	All peripheral clock disabled*5		ICLK = 48 MHz	3.7		-	*7
						ICLK = 32 MHz	2.7		-	
						ICLK = 16 MHz	2.0		-	
		ICLK = 8 MHz				1.5	-			
		All peripheral clock enabled*5		ICLK = 48 MHz		16.4	-		*9	
				ICLK = 32 MHz		12.7	-		*8	
				ICLK = 16 MHz		7.2	-			
				ICLK = 8 MHz		4.3	-			
		Increase during BGO operation*6				2.5	-		-	
	Middle-speed mode*2	Normal mode	All peripheral clock disabled, while (1) code executing from flash*5	ICLK = 12 MHz	I _{CC}	2.5	-	mA	*7	
				ICLK = 8 MHz		2.1	-			
				ICLK = 1 MHz		1.0	-			
			All peripheral clock disabled, CoreMark code executing from flash*5	ICLK = 12 MHz		5.2	-			
				ICLK = 8 MHz		4.0	-			
				ICLK = 1 MHz		1.3	-			
			All peripheral clock enabled, while (1) code executing from flash*5	ICLK = 12 MHz		6.5	-		*8	
ICLK = 8 MHz				4.8		-				
ICLK = 1 MHz				1.6		-				
All peripheral clock enabled, code executing from SRAM*5			ICLK = 12 MHz	-		23.0				
Sleep mode		All peripheral clock disabled*5	ICLK = 12 MHz	1.4		-	*7			
			ICLK = 8 MHz	1.3		-				
			ICLK = 1 MHz	0.9		-				
		All peripheral clock enabled*5	ICLK = 12 MHz	5.3		-	*8			
			ICLK = 8 MHz	4.0		-				
			ICLK = 1 MHz	1.5		-				
Increase during BGO operation*6				2.5		-	-			

Table 2.14 Operating and standby current (4)

Conditions: VCC = AVCC0 = 1.6 to 5.5 V, VREFH0 = 2.7 V to AVCC0

Parameter			Symbol	Min	Typ	Max	Unit	Test conditions
Analog power supply current	During A/D conversion (at high-speed conversion)		I _{AVCC}	-	-	3.0	mA	-
	During A/D conversion (at low power conversion)			-	-	1.0	mA	-
	During D/A conversion (per channel)*1			-	0.4	0.8	mA	-
	Waiting for A/D and D/A conversion (all units)*6			-	-	1.0	μA	-
Reference power supply current	During A/D conversion		I _{REFH0}	-	-	150	μA	-
	Waiting for A/D conversion (all units)			-	-	60	nA	-
	During D/A conversion		I _{REFH}	-	50	100	μA	-
	Waiting for D/A conversion (all units)			-	-	100	μA	-
Temperature sensor			I _{TNS}	-	75	-	μA	-
Low-Power Analog Comparator operating current	Window mode		I _{CMLP}	-	15	-	μA	-
	Comparator High-speed mode			-	10	-	μA	-
	Comparator Low-speed mode			-	2	-	μA	-
	Comparator Low-speed mode using DAC8			-	820	-	μA	-
Operational Amplifier operating current	Low power mode	1 unit operating	I _{AMP}	-	2.5	4.0	μA	-
		2 units operating		-	4.5	8.0	μA	-
		3 units operating		-	6.5	11.0	μA	-
		4 units operating		-	8.5	14.0	μA	-
	High speed mode	1 unit operating		-	140	220	μA	-
		2 units operating		-	280	410	μA	-
		3 units operating		-	420	600	μA	-
		4 units operating		-	560	780	μA	-
LCD operating current	External resistance division method f _{LCD} = f _{SUB} = 128 Hz, 1/3 bias, and 4-time slice		I _{LCD1} *5	-	0.34	-	μA	-
	Internal voltage boosting method (VLCD.VLCD = 04) f _{LCD} = f _{SUB} = 128 Hz, 1/3 bias, and 4-time slice		I _{LCD2} *5	-	0.92	-	μA	-
	Capacitor split method f _{LCD} = f _{SUB} = 128 Hz, 1/3 bias, and 4-time slice		I _{LCD3} *5	-	0.19	-	μA	-
USB operating current	During USB communication operation under the following settings and conditions: • Host controller operation is set to full-speed mode Bulk OUT transfer (64 bytes) × 1, bulk IN transfer (64 bytes) × 1 • Connect peripheral devices via a 1-meter USB cable from the USB port.		I _{USBH} *2	-	4.3 (VCC) 0.9 (VCC_USB)*4	-	mA	-
	During USB communication operation under the following settings and conditions: • Device controller operation is set to full-speed mode Bulk OUT transfer (64 bytes) × 1, bulk IN transfer (64 bytes) × 1 • Connect the host device via a 1-meter USB cable from the USB port.		I _{USBF} *2	-	3.6 (VCC) 1.1 (VCC_USB)*4	-	mA	-
	During suspended state under the following setting and conditions: • Device controller operation is set to full-speed mode (pull up the USB_DP pin) • Software standby mode • Connect the host device via a 1-meter USB cable from the USB port.		I _{SUSP} *3	-	0.35 (VCC) 170 (VCC_USB)*4	-	μA	-

Note 1. The reference power supply current is included in the power supply current value for D/A conversion.

Note 2. Current consumed only by the USBFS.

Note 3. Includes the current supplied from the pull-up resistor of the USB_DP pin to the pull-down resistor of the host device, in addition to the current consumed by the MCU during the suspended state.

Note 4. When VCC = VCC_USB = 3.3 V.

Note 5. Current flowing only to the LCD controller. Not including the current that flows through the LCD panel.

Note 6. When the MCU is in Software Standby mode or the MSTPCRD.MSTPD16 (ADC140 Module Stop bit) is in the module-stop state.

2.3.2 Clock Timing

Table 2.22 Clock timing (1 of 2)

Parameter		Symbol	Min	Typ	Max	Unit	Test conditions
EBCLK pin output cycle time	VCC = 2.7 V or above	t_{Bcyc}	83.3	-	-	ns	Figure 2.26
	VCC = 1.8 V or above		125	-	-		
	VCC = 1.6 V or above		500	-	-		
EBCLK pin output high pulse width	VCC = 2.7 V or above	t_{CH}	20	-	-	ns	
	VCC = 1.8 V or above		30	-	-		
	VCC = 1.6 V or above		150	-	-		
EBCLK pin output low pulse width	VCC = 2.7 V or above	t_{CL}	20	-	-	ns	
	VCC = 1.8 V or above		30	-	-		
	VCC = 1.6 V or above		150	-	-		
EBCLK pin output rise time	VCC = 2.7 V or above	t_{Cr}	-	-	15	ns	
	VCC = 2.4 V or above		-	-	25		
	VCC = 1.8 V or above		-	-	30		
	VCC = 1.6 V or above		-	-	50		
EBCLK pin output fall time	VCC = 2.7 V or above	t_{Cf}	-	-	15	ns	
	VCC = 2.4 V or above		-	-	25		
	VCC = 1.8 V or above		-	-	30		
	VCC = 1.6 V or above		-	-	50		
EXTAL external clock input cycle time		t_{Xcyc}	50	-	-	ns	Figure 2.27
EXTAL external clock input high pulse width		t_{XH}	20	-	-	ns	
EXTAL external clock input low pulse width		t_{XL}	20	-	-	ns	
EXTAL external clock rising time		t_{Xr}	-	-	5	ns	
EXTAL external clock falling time		t_{Xf}	-	-	5	ns	
EXTAL external clock input wait time*1		t_{EXWT}	0.3	-	-	μs	-
EXTAL external clock input frequency		f_{EXTAL}	-	-	20	MHz	$2.4 \leq VCC \leq 5.5$
			-	-	8		$1.8 \leq VCC < 2.4$
			-	-	1		$1.6 \leq VCC < 1.8$
Main clock oscillator oscillation frequency		f_{MAIN}	1	-	20	MHz	$2.4 \leq VCC \leq 5.5$
			1	-	8		$1.8 \leq VCC < 2.4$
			1	-	4		$1.6 \leq VCC < 1.8$
Main clock oscillation stabilization wait time (crystal)*9		$t_{MAINOSCWT}$	-	-	-*9	ms	
LOCO clock oscillation frequency		f_{LOCO}	27.8528	32.768	37.6832	kHz	-
LOCO clock oscillation stabilization time		t_{LOCO}	-	-	100	μs	Figure 2.28
IWDt-dedicated clock oscillation frequency		f_{ILOCO}	12.75	15	17.25	kHz	-
MOCO clock oscillation frequency		f_{MOCO}	6.8	8	9.2	MHz	-
MOCO clock oscillation stabilization time		t_{MOCO}	-	-	1	μs	-

Table 2.22 Clock timing (2 of 2)

Parameter	Symbol	Min	Typ	Max	Unit	Test conditions
HOCO clock oscillation frequency	f _{HOCO24}	23.64	24	24.36	MHz	Ta = -40 to -20°C 1.8 ≤ VCC ≤ 5.5
		22.68	24	25.32		Ta = -40 to 85°C 1.6 ≤ VCC < 1.8
		23.76	24	24.24		Ta = -20 to 85°C 1.8 ≤ VCC ≤ 5.5
		23.52	24	24.48		Ta = 85 to 105°C 2.4 ≤ VCC ≤ 5.5
	f _{HOCO32}	31.52	32	32.48		Ta = -40 to -20°C 1.8 ≤ VCC ≤ 5.5
		30.24	32	33.76		Ta = -40 to 85°C 1.6 ≤ VCC < 1.8
		31.68	32	32.32		Ta = -20 to 85°C 1.8 ≤ VCC ≤ 5.5
		31.36	32	32.64		Ta = 85 to 105°C 2.4 ≤ VCC ≤ 5.5
	f _{HOCO48} *4	47.28	48	48.72		Ta = -40 to -20°C 1.8 ≤ VCC ≤ 5.5
		47.52	48	48.48		Ta = -20 to 85°C 1.8 ≤ VCC ≤ 5.5
		47.04	48	48.96		Ta = 85 to 105°C 2.4 ≤ VCC ≤ 5.5
	f _{HOCO64} *5	63.04	64	64.96		Ta = -40 to -20°C 2.4 ≤ VCC ≤ 5.5
		63.36	64	64.64		Ta = -20 to 85°C 2.4 ≤ VCC ≤ 5.5
		62.72	64	65.28		Ta = 85 to 105°C 2.4 ≤ VCC ≤ 5.5
HOCO clock oscillation stabilization time*6, *7	Except low-voltage mode	t _{HOCO24}	-	-	μs	Figure 2.29
		t _{HOCO32}	-	-		
		t _{HOCO48}	-	-		
		t _{HOCO64}	-	-		
	Low-Voltage mode	t _{HOCO24}	-	-		
		t _{HOCO32}	-	-		
		t _{HOCO48}	-	-		
		t _{HOCO64}	-	-		
PLL input frequency*2	f _{PLLIN}	4	-	12.5	MHz	-
PLL circuit oscillation frequency*2	f _{PLL}	24	-	64	MHz	-
PLL clock oscillation stabilization time*8	t _{PLL}	-	-	55.5	μs	Figure 2.31
PLL free-running oscillation frequency	f _{PLLFR}	-	8	-	MHz	-
Sub-clock oscillator oscillation frequency	f _{SUB}	-	32.768	-	kHz	-
Sub-clock oscillator stabilization time*3	t _{SUBOSC}	-	-	-*3	s	Figure 2.32

Note 1. Time until the clock can be used after the Main Clock Oscillator Stop bit (MOSCCR.MOSTP) is set to 0 (operating) when the external clock is stable.

Note 2. The VCC range that the PLL can be used is 2.4 to 5.5 V.

Note 3. After changing the setting of the SOSCCR.SOSTP bit so that the sub-clock oscillator operates, only start using the sub-clock oscillator after the sub-clock oscillation stabilization wait time elapses, that is greater than or equal to the value recommended by the oscillator manufacturer.

Note 4. The 48-MHz HOCO can be used within a VCC range of 1.8 V to 5.5 V.

Note 5. The 64-MHz HOCO can be used within a VCC range of 2.4 V to 5.5 V.

Note 6. This is a characteristic when HOCOCR.HCSTP bit is set to 0 (oscillation) in MOCO stop state.

When HOCOCR.HCSTP bit is set to 0 (oscillation) during MOCO oscillation, this specification is shortened by 1 μs.

Note 7. Whether stabilization time has elapsed can be confirmed by OSCSF.HOCOSF.

Note 8. This is a characteristic when PLLCR.PLLSTP bit is set to 0 (operation) in MOCO stop state.

When PLLCR.PLLSTP bit is set to 0 (operation) during MOCO oscillation, this specification is shortened by 1 μs.

Note 9. When setting up the main clock, ask the oscillator manufacturer for an oscillation evaluation and use the results as the recommended oscillation stabilization time. Set the MOSCWTCR register to a value equal to or greater than the recommended stabilization time. After changing the setting of the MOSCCR.MOSTP bit so that the main clock oscillator operates, read the OSCSF.MOSCSF flag to confirm that it is 1, then start using the main clock.

Note 1. t_{PBcyc} : PCLKB cycle.

Note 2. t_{cac} : CAC count clock source cycle.

2.3.9 SCI Timing

Table 2.37 SCI timing (1)

Parameter				Symbol	Min	Max	Unit*1	Test conditions
SCI	Input clock cycle	Asynchronous		t_{Scyc}	4	-	t_{Pcyc}	Figure 2.53
		Clock synchronous			6	-		
	Input clock pulse width			t_{SCKW}	0.4	0.6	t_{Scyc}	
	Input clock rise time			t_{SCKr}	-	20	ns	
	Input clock fall time			t_{SCKf}	-	20	ns	
	Output clock cycle	Asynchronous		t_{Scyc}	6	-	t_{Pcyc}	
		Clock synchronous			4	-		
	Output clock pulse width			t_{SCKW}	0.4	0.6	t_{Scyc}	
	Output clock rise time		1.8 V or above	t_{SCKr}	-	20	ns	
			1.6 V or above		-	30		
	Output clock fall time		1.8 V or above	t_{SCKf}	-	20	ns	
			1.6 V or above		-	30		
	Transmit data delay (master)	Clock synchronous	1.8 V or above	t_{TXD}	-	40	ns	Figure 2.54
			1.6 V or above		-	45		
	Transmit data delay (slave)	Clock synchronous	2.7 V or above	t_{TXD}	-	55	ns	
			2.4 V or above		-	60		
			1.8 V or above		-	100		
			1.6 V or above		-	125		
	Receive data setup time (master)	Clock synchronous	2.7 V or above	t_{RXS}	45	-	ns	
			2.4 V or above		55	-		
			1.8 V or above		90	-		
			1.6 V or above		110	-		
	Receive data setup time (slave)	Clock synchronous	2.7 V or above	t_{RXS}	40	-	ns	
			1.6 V or above		45	-		
	Receive data hold time (master)	Clock synchronous		t_{RXH}	5	-	ns	
	Receive data hold time (slave)	Clock synchronous		t_{RXH}	40	-	ns	

Note 1. t_{Pcyc} : PCLKA cycle.

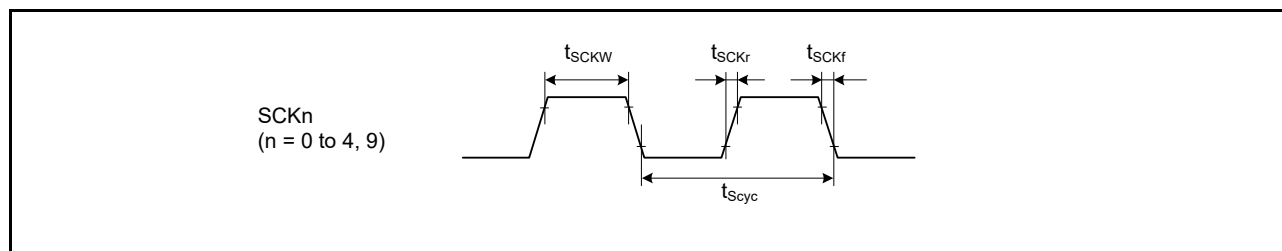


Figure 2.53 SCK clock input timing

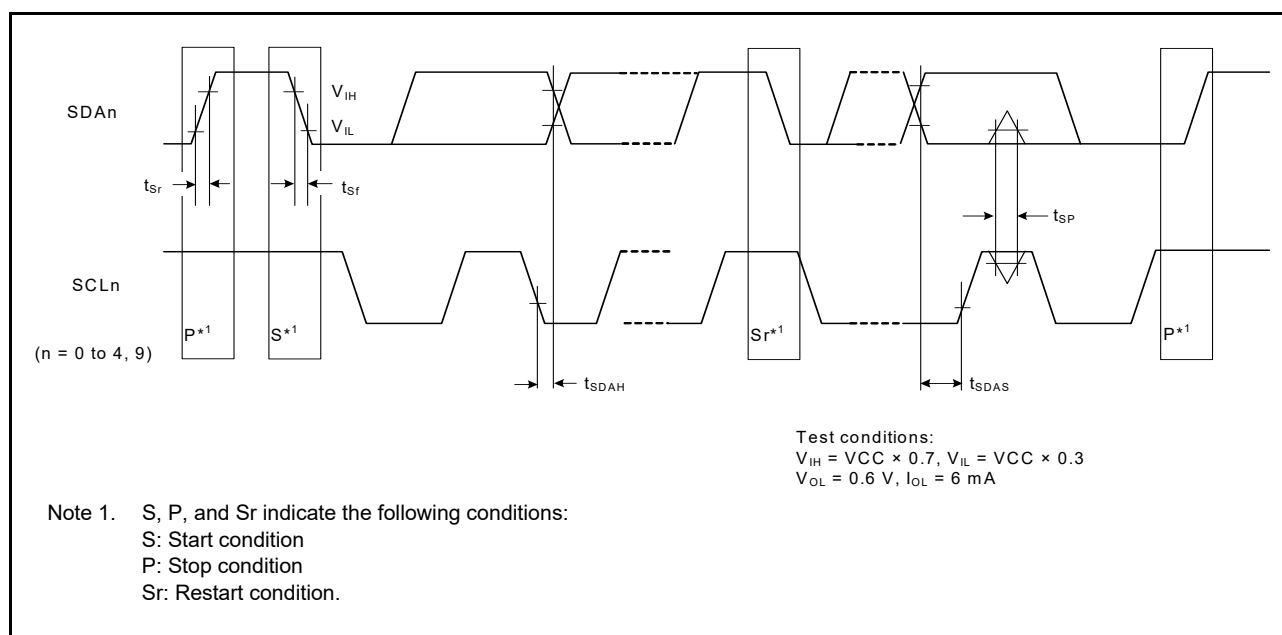


Figure 2.60 SCI simple IIC mode timing

Table 2.40 SPI timing (2 of 2)

Conditions: Middle drive output is selected in the Port Drive Capability in PmnPFS register

Parameter				Symbol	Min	Max	Unit*1	Test conditions	
SPI	Data output delay	Master	2.7 V or above	t _{OD}	-	14	ns	Figure 2.62 to Figure 2.67	
			2.4 V or above		-	20			
			1.8 V or above		-	25			
			1.6 V or above		-	30			
		Slave	2.7 V or above		-	50			
			2.4 V or above		-	60			
			1.8 V or above		-	85			
			1.6 V or above		-	110			
	Data output hold time	Master		t _{OH}	0	-	ns		
		Slave			0	-			
	Successive transmission delay	Master		t _{TD}	t _{SPcyc} + 2 × t _{Pcyc}	8 × t _{SPcyc} + 2 × t _{Pcyc}	ns		
		Slave			6 × t _{Pcyc}	-			
	MOSI and MISO rise and fall time	Output	2.7 V or above	t _{Dr} , t _{Df}	-	10	ns		
			2.4 V or above		-	15			
			1.8 V or above		-	20			
			1.6 V or above		-	30			
		Input			-	1	μs		
		SSL rise and fall time	Output		2.7 V or above	t _{SSLr} , t _{SSLf}	-		10
	2.4 V or above			-	15				
	1.8 V or above			-	20				
	1.6 V or above			-	30				
	Input		-	1	μs				
	Slave access time		2.4 V or above	t _{SA}	-		2 × t _{Pcyc} + 100		ns
			1.8 V or above		-	2 × t _{Pcyc} + 140			
			1.6 V or above		-	2 × t _{Pcyc} + 180			
	Slave output release time		2.4 V or above	t _{REL}	-	2 × t _{Pcyc} + 100	ns		
			1.8 V or above		-	2 × t _{Pcyc} + 140			
			1.6 V or above		-	2 × t _{Pcyc} + 180			

Note 1. t_{Pcyc} : PCLKA cycle.

Note 2. N is set as an integer from 1 to 8 by the SPCKD register.

Note 3. N is set as an integer from 1 to 8 by the SSLND register.

Note 4. The upper limit of RSPCK is 16 MHz.

Table 2.49 A/D conversion characteristics (2) in high-speed A/D conversion mode (2 of 2)

Conditions: VCC = AVCC0 = 2.7 to 5.5 V, VREFH0 = 2.7 to 5.5 V

Reference voltage range applied to the VREFH0 and VREFL0.

Parameter		Min	Typ	Max	Unit	Test conditions
Resolution		-	-	14	Bit	-
Conversion time*1 (Operation at PCLKC = 48 MHz)	Permissible signal source impedance Max. = 0.3 kΩ	1.06	-	-	μs	High-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 0Dh
		1.63	-	-	μs	Normal-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 28h
Offset error		-	±2.0	±18	LSB	High-precision channel
				±24.0	LSB	Other than above
Full-scale error		-	±3.0	±18	LSB	High-precision channel
				±24.0	LSB	Other than above
Quantization error		-	±0.5	-	LSB	-
Absolute accuracy		-	±5.0	±20	LSB	High-precision channel
				±32.0	LSB	Other than above
DNL differential nonlinearity error		-	±4.0	-	LSB	-
INL integral nonlinearity error		-	±4.0	±12.0	LSB	-

Note: The characteristics apply when no pin functions other than 14-bit A/D converter input are used. Absolute accuracy does not include quantization errors. Offset error, full-scale error, DNL differential nonlinearity error, and INL integral nonlinearity error do not include quantization errors.

Note 1. The conversion time is the sum of the sampling time and the comparison time. The number of sampling states is indicated for the test conditions.

Note 2. Except for I/O input capacitance (Cin), see [section 2.2.4, I/O V_{OH}, V_{OL}, and Other Characteristics](#).

Table 2.50 A/D conversion characteristics (3) in high-speed A/D conversion mode (1 of 2)

Conditions: VCC = AVCC0 = 2.4 to 5.5 V, VREFH0 = 2.4 to 5.5 V

Reference voltage range applied to the VREFH0 and VREFL0.

Parameter		Min	Typ	Max	Unit	Test conditions
Frequency		1	-	32	MHz	-
Analog input capacitance*2	Cs	-	-	8 (reference data)	pF	High-precision channel
		-	-	9 (reference data)	pF	Normal-precision channel
Analog input resistance	Rs	-	-	2.5 (reference data)	kΩ	High-precision channel
		-	-	6.7 (reference data)	kΩ	Normal-precision channel
Analog input voltage range	Ain	0	-	VREFH0	V	-
12-bit mode						
Resolution		-	-	12	Bit	-
Conversion time*1 (Operation at PCLKC = 32 MHz)	Permissible signal source impedance Max. = 1.3 kΩ	1.41	-	-	μs	High-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 0Dh
		2.25	-	-	μs	Normal-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 28h
Offset error		-	±0.5	±4.5	LSB	High-precision channel
				±6.0	LSB	Other than above
Full-scale error		-	±0.75	±4.5	LSB	High-precision channel
				±6.0	LSB	Other than above
Quantization error		-	±0.5	-	LSB	-
Absolute accuracy		-	±1.25	±5.0	LSB	High-precision channel
				±8.0	LSB	Other than above
DNL differential nonlinearity error		-	±1.0	-	LSB	-
INL integral nonlinearity error		-	±1.0	±3.0	LSB	-

Table 2.50 A/D conversion characteristics (3) in high-speed A/D conversion mode (2 of 2)

Conditions: VCC = AVCC0 = 2.4 to 5.5 V, VREFH0 = 2.4 to 5.5 V

Reference voltage range applied to the VREFH0 and VREFL0.

Parameter		Min	Typ	Max	Unit	Test conditions
14-bit mode						
Resolution		-	-	14	Bit	-
Conversion time*1 (Operation at PCLKC = 32 MHz)	Permissible signal source impedance Max. = 1.3 kΩ	1.59	-	-	μs	High-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 0Dh
		2.44	-	-	μs	Normal-precision channel ADCSR.ADHSC = 0 ADSSTRn.SST[7:0] = 28h
Offset error		-	±2.0	±18	LSB	High-precision channel
				±24.0	LSB	Other than above
Full-scale error		-	±3.0	±18	LSB	High-precision channel
				±24.0	LSB	Other than above
Quantization error		-	±0.5	-	LSB	-
Absolute accuracy		-	±5.0	±20	LSB	High-precision channel
				±32.0	LSB	Other than above
DNL differential nonlinearity error		-	±4.0	-	LSB	-
INL integral nonlinearity error		-	±4.0	±12.0	LSB	-

Note: The characteristics apply when no pin functions other than 14-bit A/D converter input are used. Absolute accuracy does not include quantization errors. Offset error, full-scale error, DNL differential nonlinearity error, and INL integral nonlinearity error do not include quantization errors.

Note 1. The conversion time is the sum of the sampling time and the comparison time. The number of sampling states is indicated for the test conditions.

Note 2. Except for I/O input capacitance (Cin), see [section 2.2.4, I/O V_{OH}, V_{OL}, and Other Characteristics](#).

Table 2.51 A/D conversion characteristics (4) in low power A/D conversion mode (1 of 2)

Conditions: VCC = AVCC0 = 2.7 to 5.5 V, VREFH0 = 2.7 to 5.5 V

Reference voltage range applied to the VREFH0 and VREFL0.

Parameter		Min	Typ	Max	Unit	Test conditions
Frequency		1	-	24	MHz	-
Analog input capacitance*2	Cs	-	-	8 (reference data)	pF	High-precision channel
		-	-	9 (reference data)	pF	Normal-precision channel
Analog input resistance	Rs	-	-	2.5 (reference data)	kΩ	High-precision channel
		-	-	6.7 (reference data)	kΩ	Normal-precision channel
Analog input voltage range	Ain	0	-	VREFH0	V	-
12-bit mode						
Resolution		-	-	12	Bit	-
Conversion time*1 (Operation at PCLKC = 24 MHz)	Permissible signal source impedance Max. = 1.1 kΩ	2.25	-	-	μs	High-precision channel ADCSR.ADHSC = 1 ADSSTRn.SST[7:0] = 0Dh
		3.38	-	-	μs	Normal-precision channel ADCSR.ADHSC = 1 ADSSTRn.SST[7:0] = 28h
Offset error		-	±0.5	±4.5	LSB	High-precision channel
				±6.0	LSB	Other than above
Full-scale error		-	±0.75	±4.5	LSB	High-precision channel
				±6.0	LSB	Other than above
Quantization error		-	±0.5	-	LSB	-
Absolute accuracy		-	±1.25	±5.0	LSB	High-precision channel
				±8.0	LSB	Other than above
DNL differential nonlinearity error		-	±1.0	-	LSB	-

Table 2.55 14-bit A/D converter channel classification

Classification	Channel	Conditions	Remarks
High-precision channel	AN000 to AN015	AVCC0 = 1.6 to 5.5 V	Pins AN000 to AN015 cannot be used as general I/O, IRQ2, IRQ3 inputs, and TS transmission, when the A/D converter is in use
Normal-precision channel	AN016 to AN027		
Internal reference voltage input channel	Internal reference voltage	AVCC0 = 2.0 to 5.5 V	-
Temperature sensor input channel	Temperature sensor output	AVCC0 = 2.0 to 5.5 V	-

Table 2.56 A/D internal reference voltage characteristics

Conditions: VCC = AVCC0 = VREFH0 = 2.0 to 5.5 V*1

Parameter	Min	Typ	Max	Unit	Test conditions
Internal reference voltage input channel*2	1.36	1.43	1.50	V	-
Frequency*3	1	-	2	MHz	-
Sampling time*4	5.0	-	-	μs	-

Note 1. The internal reference voltage cannot be selected for input channels when AVCC0 < 2.0 V.

Note 2. The 14-bit A/D internal reference voltage indicates the voltage when the internal reference voltage is input to the 14-bit A/D converter.

Note 3. This is a parameter for ADC14 when the internal reference voltage is used as a high-potential reference voltage.

Note 4. This is a parameter for ADC14 when the internal reference voltage is selected for an analog input channel in ADC14.

2.7 TSN Characteristics

Table 2.60 TSN characteristics

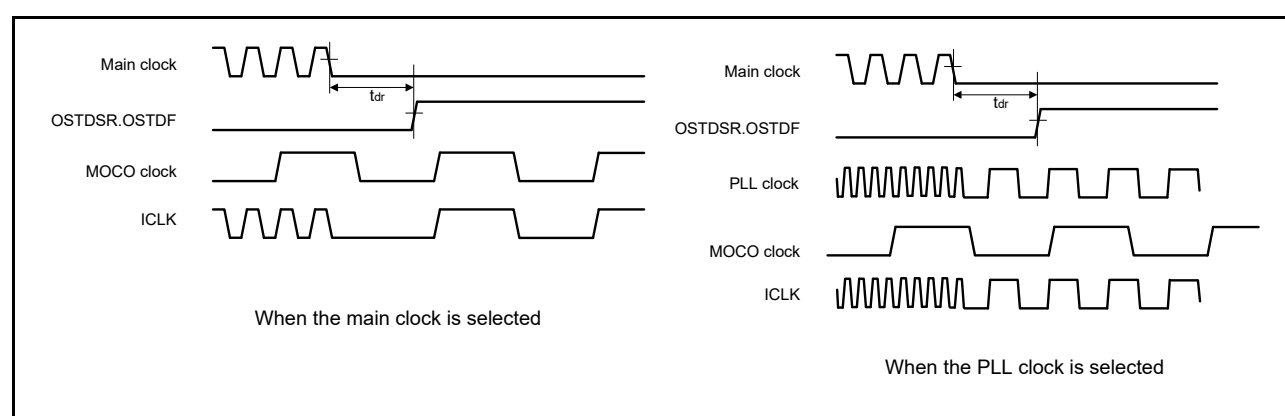
Conditions: VCC = AVCC0 = 2.0 to 5.5 V

Parameter	Symbol	Min	Typ	Max	Unit	Test conditions
Relative accuracy	-	-	±1.5	-	°C	2.4 V or above
	-	-	±2.0	-	°C	Below 2.4 V
Temperature slope	-	-	-3.65	-	mV/°C	-
Output voltage (at 25°C)	-	-	1.05	-	V	VCC = 3.3 V
Temperature sensor start time	t _{START}	-	-	5	μs	-
Sampling time	-	5	-	-	μs	-

2.8 OSC Stop Detect Characteristics

Table 2.61 Oscillation stop detection circuit characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Test conditions
Detection time	t _{dr}	-	-	1	ms	Figure 2.84


Figure 2.84 Oscillation stop detection timing

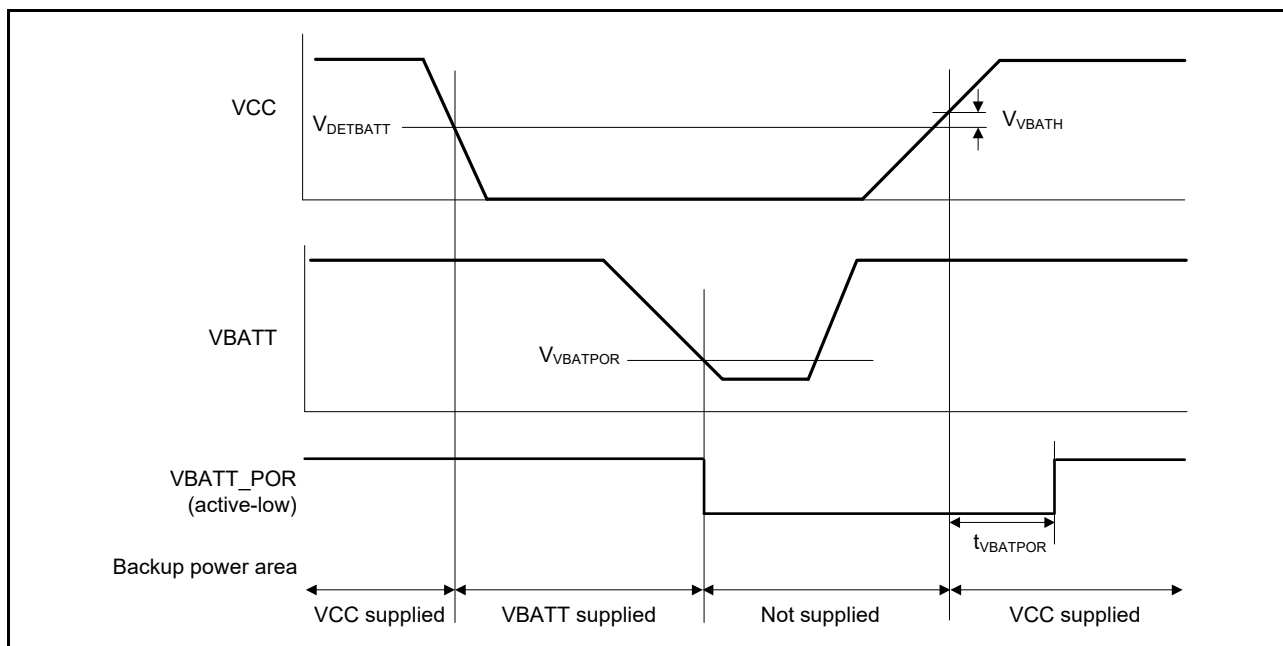


Figure 2.91 VBATT_POR reset timing

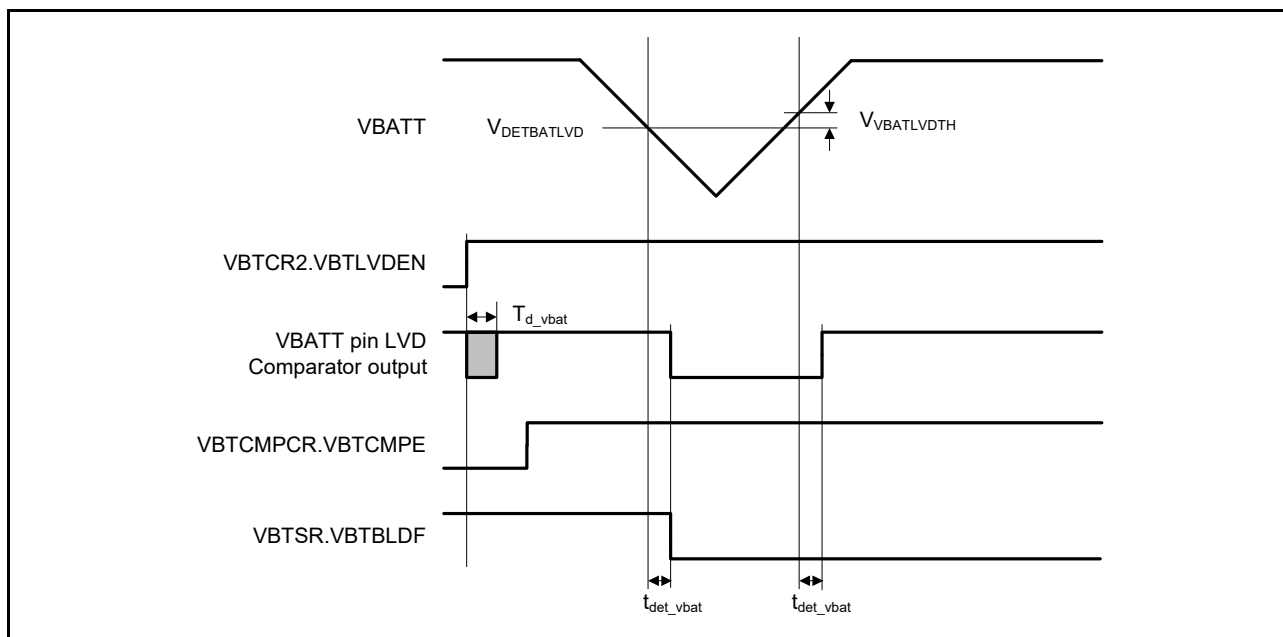
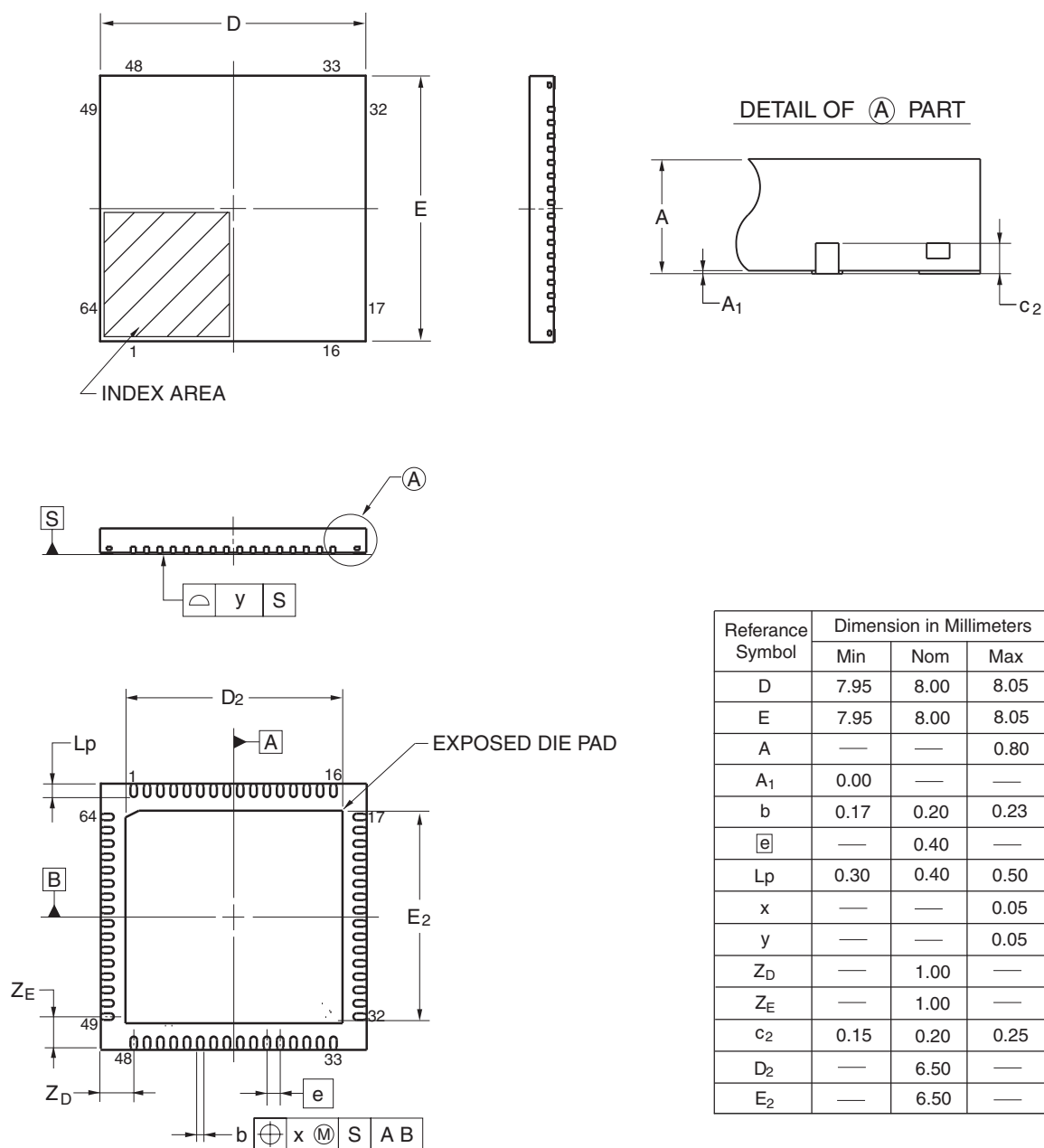


Figure 2.92 VBATT pin voltage detection circuit timing

JEITA Package code	RENESAS code	Previous code	MASS(TYP.)[g]
P-HWQFN64-8x8-0.40	PWQN0064LA-A	P64K8-40-9B5-3	0.16



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Figure 1.7 QFN 64-pin