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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 11x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1933-e-ss

TABLE 1-2: PIC16(L)F1933 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/AN0/C12IN0-/C2OUT(1)/ SRNQ(1)/$\overline{SS}$(1)/VCAP(2)/SEG12	RA0	TTL	CMOS	General purpose I/O.
	AN0	AN	—	A/D Channel input.
	C12IN0-	AN	—	Comparator negative input.
	C2OUT	—	CMOS	Comparator output.
	SRNQ	—	CMOS	SR latch inverting output.
	$\overline{SS}$	ST	—	Slave Select input.
	VCAP	Power	Power	Filter capacitor for Voltage Regulator (PIC16F1933 only).
	SEG12	—	AN	LCD Analog output.
RA1/AN1/C12IN1-/SEG7	RA1	TTL	CMOS	General purpose I/O.
	AN1	AN	—	A/D Channel input.
	C12IN1-	AN	—	Comparator negative input.
	SEG7	—	AN	LCD Analog output.
RA2/AN2/C2IN+/VREF-/ DACOUT/COM2	RA2	TTL	CMOS	General purpose I/O.
	AN2	AN	—	A/D Channel input.
	C2IN+	AN	—	Comparator positive input.
	VREF-	AN	—	A/D Negative Voltage Reference input.
	DACOUT	—	AN	Voltage Reference output.
	COM2	—	AN	LCD Analog output.
RA3/AN3/C1IN+/VREF+/ COM3/SEG15	RA3	TTL	CMOS	General purpose I/O.
	AN3	AN	—	A/D Channel input.
	C1IN+	AN	—	Comparator positive input.
	VREF+	AN	—	A/D Voltage Reference input.
	COM3	—	AN	LCD Analog output.
	SEG15	—	AN	LCD Analog output.
RA4/C1OUT/CPS6/T0CKI/SRQ/ CCP5/SEG4	RA4	TTL	CMOS	General purpose I/O.
	C1OUT	—	CMOS	Comparator output.
	CPS6	AN	—	Capacitive sensing input.
	T0CKI	ST	—	Timer0 clock input.
	SRQ	—	CMOS	SR latch non-inverting output.
	CCP5	ST	CMOS	Capture/Compare/PWM.
	SEG4	—	AN	LCD Analog output.
RA5/AN4/C2OUT(1)/CPS7/ SRNQ(1)/$\overline{SS}$(1)/VCAP(2)/SEG5	RA5	TTL	CMOS	General purpose I/O.
	AN4	AN	—	A/D Channel input.
	C2OUT	—	CMOS	Comparator output.
	CPS7	AN	—	Capacitive sensing input.
	SRNQ	—	CMOS	SR latch inverting output.
	$\overline{SS}$	ST	—	Slave Select input.
	VCAP	Power	Power	Filter capacitor for Voltage Regulator (PIC16F1933 only).
	SEG5	—	AN	LCD Analog output.

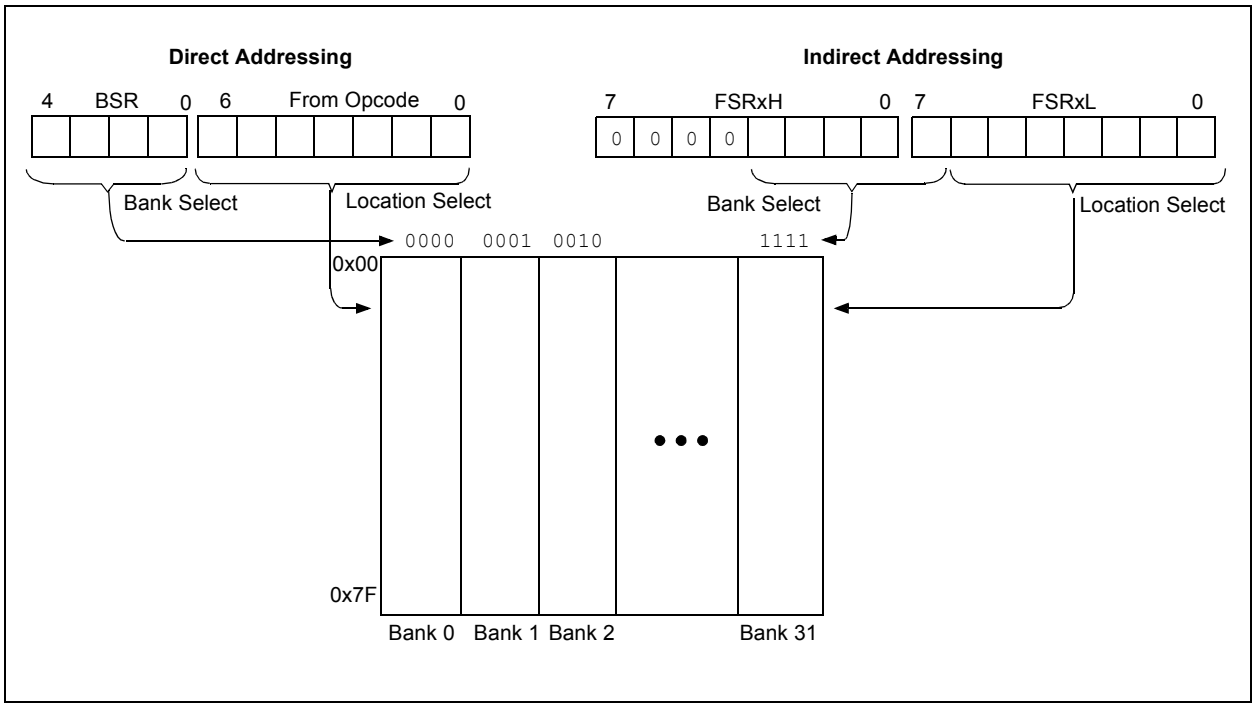
Legend: AN = Analog input or output; CMOS = CMOS compatible input or output; OD = Open Drain
TTL = TTL compatible input; ST = Schmitt Trigger input with CMOS levels; I^2C™ = Schmitt Trigger input with I^2C levels
HV = High Voltage; XTAL = Crystal

Note 1: Pin function is selectable via the APFCON register.
2: PIC16F1933 devices only.

3.6.1 TRADITIONAL DATA MEMORY

The traditional data memory is a region from FSR address 0x000 to FSR address 0xFFF. The addresses correspond to the absolute addresses of all SFR, GPR and common registers.

FIGURE 3-9: TRADITIONAL DATA MEMORY MAP



REGISTER 11-6: EECON2: EEPROM CONTROL 2 REGISTER

W-0/0	W-0/0	W-0/0	W-0/0	W-0/0	W-0/0	W-0/0	W-0/0
EEPROM Control Register 2							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
S = Bit can only be set	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **Data EEPROM Unlock Pattern bits**

To unlock writes, a 55h must be written first, followed by an AAh, before setting the WR bit of the EECON1 register. The value written to this register is used to unlock the writes. There are specific timing requirements on these writes. Refer to **Section 11.2.2 "Writing to the Data EEPROM Memory"** for more information.

TABLE 11-3: SUMMARY OF REGISTERS ASSOCIATED WITH DATA EEPROM

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
EECON1	EEPGD	CFGS	LWLO	FREE	WRERR	WREN	WR	RD	111
EECON2	EEPROM Control Register 2 (not a physical register)								99*
EEADRL	EEADRL<7:0>								110
EEADRH	—(1)	EEADRH<6:0							110
EEDATL	EEDATL<7:0>								110
EEDATH	—	—	EEDATH<5:0>						110
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	82
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	LCDIE	—	CCP2IE	84
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	LCDIF	—	CCP2IF	87

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Data EEPROM module.

* Page provides register information.

Note 1: Unimplemented, read as '1'.

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13.6 Register Definitions: Interrupt-on-Change Control

REGISTER 13-1: IOCBP: INTERRUPT-ON-CHANGE POSITIVE EDGE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCBP7	IOCBP6	IOCBP5	IOCBP4	IOCBP3	IOCBP2	IOCBP1	IOCBP0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **IOCBP<7:0>:** Interrupt-on-Change Positive Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a positive going edge. IOCBFx bit and IOCIF flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin.

REGISTER 13-2: IOCBN: INTERRUPT-ON-CHANGE NEGATIVE EDGE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCBN7	IOCBN6	IOCBN5	IOCBN4	IOCBN3	IOCBN2	IOCBN1	IOCBN0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **IOCBN<7:0>:** Interrupt-on-Change Negative Edge Enable bits

1 = Interrupt-on-Change enabled on the pin for a negative going edge. IOCBFx bit and IOCIF flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin.

REGISTER 13-3: IOCBF: INTERRUPT-ON-CHANGE FLAG REGISTER

R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
IOCBF7	IOCBF6	IOCBF5	IOCBF4	IOCBF3	IOCBF2	IOCBF1	IOCBF0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS - Bit is set in hardware

bit 7-0 **IOCBF<7:0>:** Interrupt-on-Change Flag bits

1 = An enabled change was detected on the associated pin.
Set when IOCBPx = 1 and a rising edge was detected on RBx, or when IOCBNx = 1 and a falling edge was detected on RBx.

0 = No change was detected, or the user cleared the detected change.

23.4.6 PWM STEERING MODE

In Single Output mode, PWM steering allows any of the PWM pins to be the modulated signal. Additionally, the same PWM signal can be simultaneously available on multiple pins.

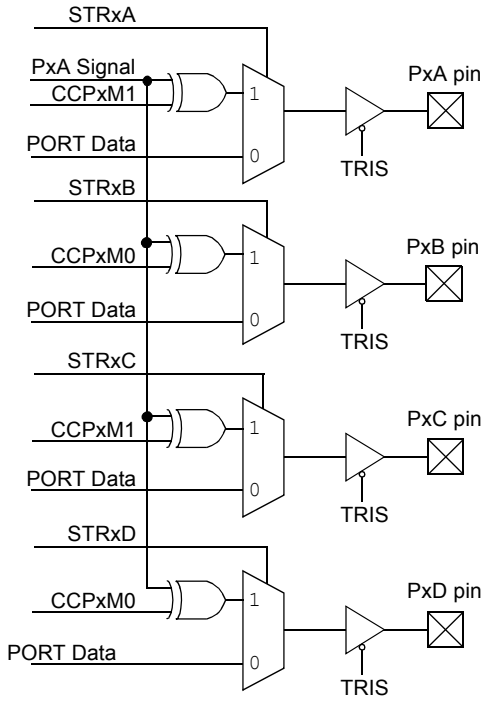
Once the Single Output mode is selected (CCPxM<3:2> = 11 and PxM<1:0> = 00 of the CCPxCON register), the user firmware can bring out the same PWM signal to one, two, three or four output pins by setting the appropriate STRx<D:A> bits of the PSTRxCON register, as shown in Table 23-9.

Note:	The associated TRIS bits must be set to output ('0') to enable the pin output driver in order to see the PWM signal on the pin.

While the PWM Steering mode is active, CCPxM<1:0> bits of the CCPxCON register select the PWM output polarity for the Px<D:A> pins.

The PWM auto-shutdown operation also applies to PWM Steering mode as described in **Section 23.4.3 "Enhanced PWM Auto-Shutdown mode"**. An auto-shutdown event will only affect pins that have PWM outputs enabled.

FIGURE 23-18: SIMPLIFIED STEERING BLOCK DIAGRAM



Note 1: Port outputs are configured as shown when the CCPxCON register bits PxM<1:0> = 00 and CCPxM<3:2> = 11.

2: Single PWM output requires setting at least one of the STRx bits.

FIGURE 24-12: I²C START AND STOP CONDITIONS

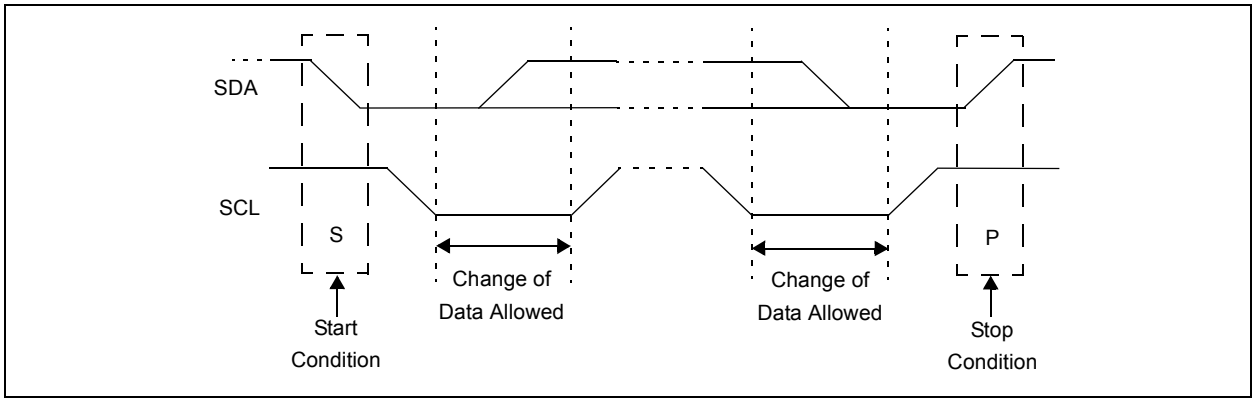
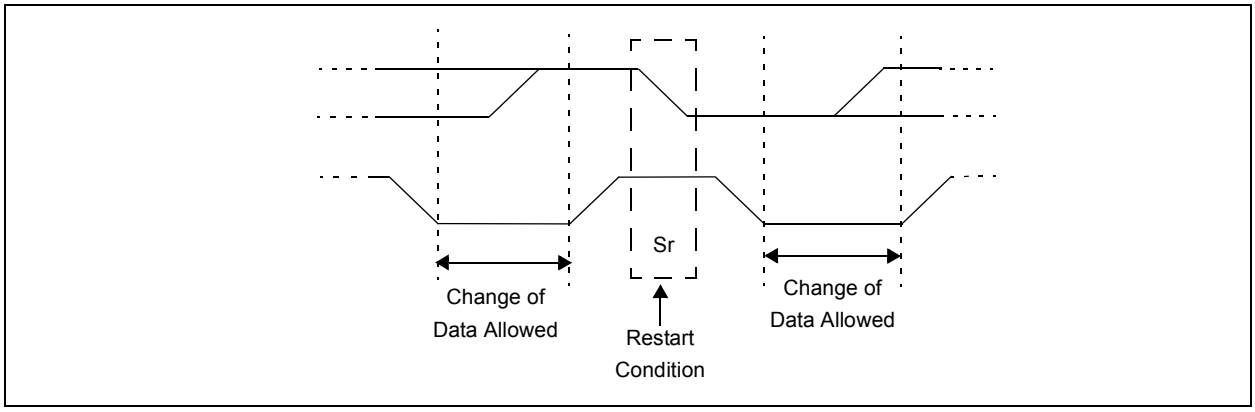


FIGURE 24-13: I²C RESTART CONDITION



24.6.13.2 Bus Collision During a Repeated Start Condition

During a Repeated Start condition, a bus collision occurs if:

a) A low level is sampled on SDA when SCL goes from a low level to a high level.

b) SCL goes low before SDA is asserted low, indicating that another master is attempting to transmit a data '1'.

When the user releases SDA and the pin is allowed to float high, the BRG is loaded with SSPADD and counts down to zero. The SCL pin is then deasserted and when sampled high, the SDA pin is sampled.

If SDA is low, a bus collision has occurred (i.e., another master is attempting to transmit a data '0', Figure 24-36). If SDA is sampled high, the BRG is reloaded and begins counting. If SDA goes from high-to-low before the BRG times out, no bus collision occurs because no two masters can assert SDA at exactly the same time.

If SCL goes from high-to-low before the BRG times out and SDA has not already been asserted, a bus collision occurs. In this case, another master is attempting to transmit a data '1' during the Repeated Start condition, see Figure 24-37.

If, at the end of the BRG time-out, both SCL and SDA are still high, the SDA pin is driven low and the BRG is reloaded and begins counting. At the end of the count, regardless of the status of the SCL pin, the SCL pin is driven low and the Repeated Start condition is complete.

FIGURE 24-36: BUS COLLISION DURING A REPEATED START CONDITION (CASE 1)

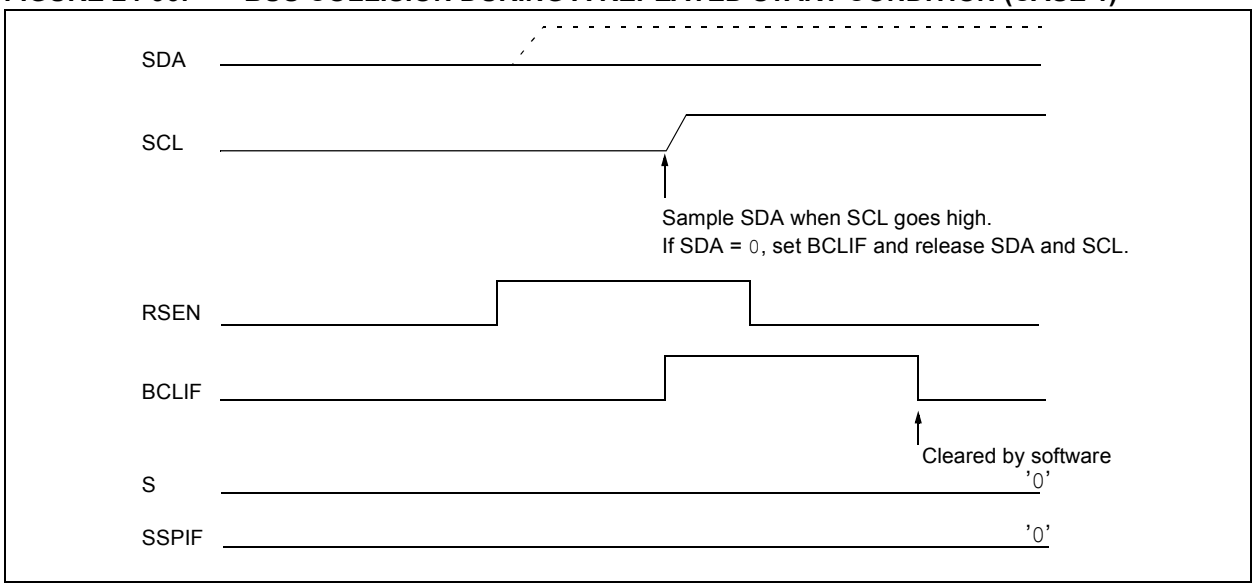
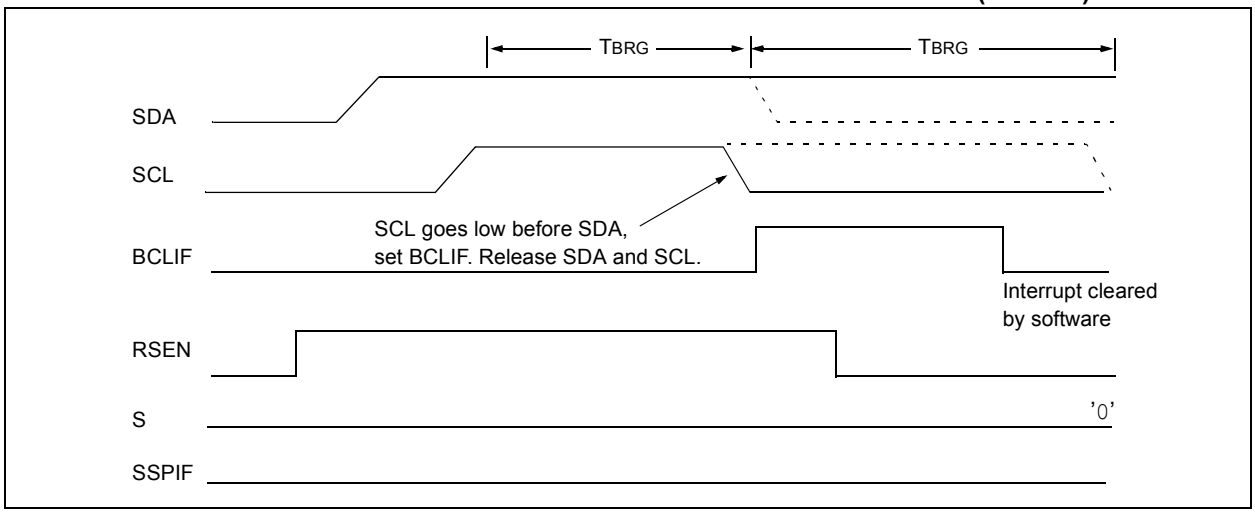


FIGURE 24-37: BUS COLLISION DURING REPEATED START CONDITION (CASE 2)



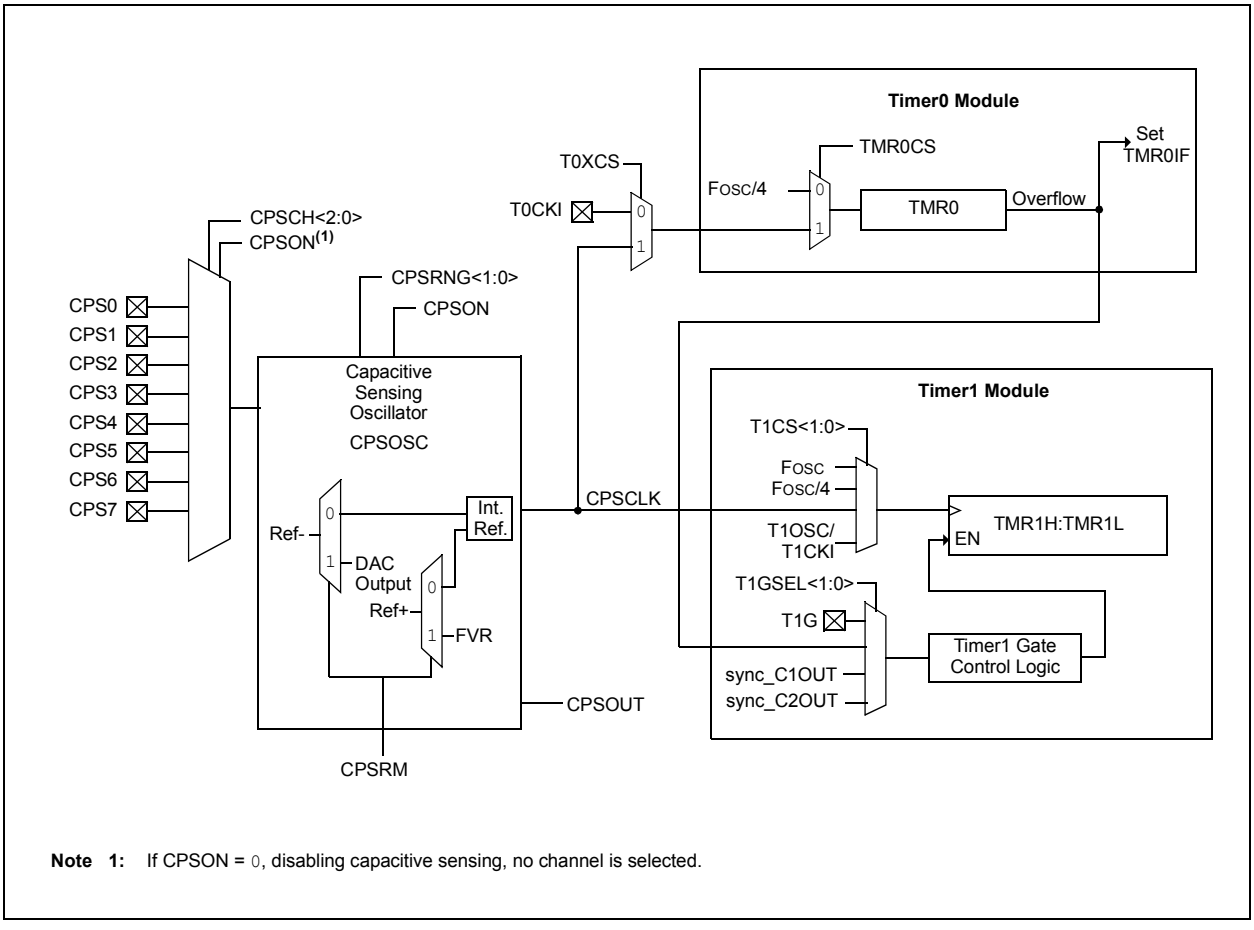
NOTES:

26.0 CAPACITIVE SENSING (CPS) MODULE

The Capacitive Sensing (CPS) module allows for an interaction with an end user without a mechanical interface. In a typical application, the CPS module is attached to a pad on a Printed Circuit Board (PCB), which is electrically isolated from the end user. When the end user places their finger over the PCB pad, a capacitive load is added, causing a frequency shift in the CPS module. The CPS module requires software and at least one timer resource to determine the change in frequency. Key features of this module include:

- Analog MUX for monitoring multiple inputs
- Capacitive sensing oscillator
- Multiple current ranges
- Multiple voltage reference modes
- Multiple timer resources
- Software control
- Operation during Sleep

FIGURE 26-1: CAPACITIVE SENSING BLOCK DIAGRAM



Note 1: If CPSON = 0, disabling capacitive sensing, no channel is selected.

26.4 Current Ranges

The capacitive sensing oscillator can operate within different current ranges, depending on the voltage reference mode and current range selections.

Within each of the two voltage reference modes, there are four current ranges. Selection between the voltage reference modes is controlled by the CPSRM bit of the CPSCON0 register. Clearing this bit selects the fixed voltage references provided by the capacitive sensing oscillator module. Setting this bit selects the variable voltage references supplied by the Fixed Voltage Reference (FVR) module and the Digital-to-Analog Converter (DAC) module. See Section **Section 26.3 "Voltage Reference Modes"** for more information on configuring the voltage references.

Selecting the current range within the voltage reference mode is controlled by configuring the CPSRNG<1:0> bits in the CPSCON0 register. See Table 26-1 for proper current mode selection.

The Noise Detection mode is unique in that it disables the constant current source associated with the selected input pin, but leaves the rest of the oscillator circuitry and pin structure active. This eliminates the oscillation frequency on the analog pin and greatly reduces the current consumed by the oscillator module. When noise is introduced onto the pin, the oscillator is driven at the frequency determined by the noise. This produces a detectable signal at the comparator stage, indicating the presence of activity on the pin.

Figure 26-2 shows a more detailed drawing of the constant current sources and comparators associated with the oscillator and input pin.

TABLE 26-1: CURRENT RANGE MODE SELECTION

CPSRM	Voltage Reference Mode	CPSRNG<1:0>	Current Range(1)
1	Variable	00	Noise Detection
		01	Low
		10	Medium
		11	High
0	Fixed	00	Off
		01	Low
		10	Medium
		11	High

Note 1: See Power-Down Currents (IPD) in **Section 30.0 "Electrical Specifications"** for more information.

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27.0 LIQUID CRYSTAL DISPLAY (LCD) DRIVER MODULE

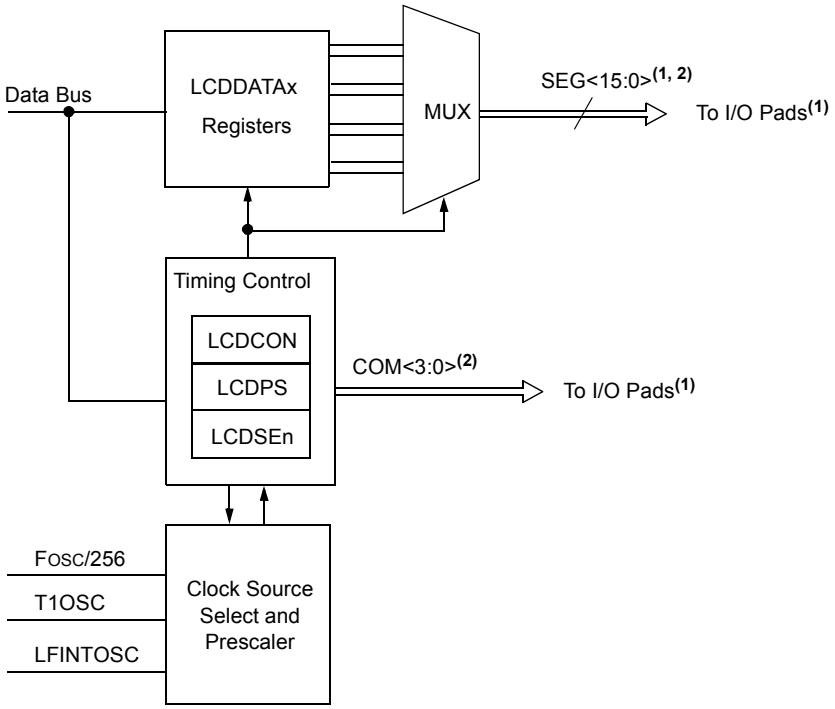
The Liquid Crystal Display (LCD) driver module generates the timing control to drive a static or multiplexed LCD panel. In the PIC16(L)F1933 device, the module drives the panels of up to four commons and up to 24 segments. The LCD module also provides control of the LCD pixel data.

The LCD driver module supports:

- Direct driving of LCD panel
- Three LCD clock sources with selectable prescaler
- Up to four common pins:
  - Static (1 common)
  - 1/2 multiplex (2 commons)
  - 1/3 multiplex (3 commons)
  - 1/4 multiplex (4 commons)
- Segment pins up to:
  - 16 (PIC16(L)F1933)
- Static, 1/2 or 1/3 LCD Bias

Note: COM3 and SEG15 share the same physical pin on the PIC16(L)F1933, therefore SEG15 is not available when using 1/4 multiplex displays.

FIGURE 27-1: LCD DRIVER MODULE BLOCK DIAGRAM



Note 1: These are not directly connected to the I/O pads, but may be tri-stated, depending on the configuration of the LCD module.

2: COM3 and SEG15 share the same physical pin on the PIC16(L)F1933, therefore SEG15 is not available when using 1/4 multiplex displays.

REGISTER 27-7: LCDRL: LCD REFERENCE LADDER CONTROL REGISTERS

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
LRLAP<1:0>		LRLBP<1:0>		—	LRLAT<2:0>		
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **LRLAP<1:0>:** LCD Reference Ladder A Time Power Control bits
During Time interval A (Refer to Figure 27-4):
00 = Internal LCD Reference Ladder is powered down and unconnected
01 = Internal LCD Reference Ladder is powered in Low-Power mode
10 = Internal LCD Reference Ladder is powered in Medium-Power mode
11 = Internal LCD Reference Ladder is powered in High-Power mode

bit 5-4 **LRLBP<1:0>:** LCD Reference Ladder B Time Power Control bits
During Time interval B (Refer to Figure 27-4):
00 = Internal LCD Reference Ladder is powered down and unconnected
01 = Internal LCD Reference Ladder is powered in Low-Power mode
10 = Internal LCD Reference Ladder is powered in Medium-Power mode
11 = Internal LCD Reference Ladder is powered in High-Power mode

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **LRLAT<2:0>:** LCD Reference Ladder A Time Interval Control bits
Sets the number of 32 kHz clocks that the A Time Interval power mode is active

For type A waveforms (WFT = 0):

000 = Internal LCD Reference Ladder is always in 'B' Power mode
001 = Internal LCD Reference Ladder is in 'A' power mode for 1 clock and 'B' power mode for 15 clocks
010 = Internal LCD Reference Ladder is in 'A' power mode for 2 clocks and 'B' power mode for 14 clocks
011 = Internal LCD Reference Ladder is in 'A' power mode for 3 clocks and 'B' power mode for 13 clocks
100 = Internal LCD Reference Ladder is in 'A' power mode for 4 clocks and 'B' power mode for 12 clocks
101 = Internal LCD Reference Ladder is in 'A' power mode for 5 clocks and 'B' power mode for 11 clocks
110 = Internal LCD Reference Ladder is in 'A' power mode for 6 clocks and 'B' power mode for 10 clocks
111 = Internal LCD Reference Ladder is in 'A' power mode for 7 clocks and 'B' power mode for 9 clocks

For type B waveforms (WFT = 1):

000 = Internal LCD Reference Ladder is always in 'B' power mode.
001 = Internal LCD Reference Ladder is in 'A' power mode for 1 clock and 'B' power mode for 31 clocks
010 = Internal LCD Reference Ladder is in 'A' power mode for 2 clocks and 'B' power mode for 30 clocks
011 = Internal LCD Reference Ladder is in 'A' power mode for 3 clocks and 'B' power mode for 29 clocks
100 = Internal LCD Reference Ladder is in 'A' power mode for 4 clocks and 'B' power mode for 28 clocks
101 = Internal LCD Reference Ladder is in 'A' power mode for 5 clocks and 'B' power mode for 27 clocks
110 = Internal LCD Reference Ladder is in 'A' power mode for 6 clocks and 'B' power mode for 26 clocks
111 = Internal LCD Reference Ladder is in 'A' power mode for 7 clocks and 'B' power mode for 25 clocks

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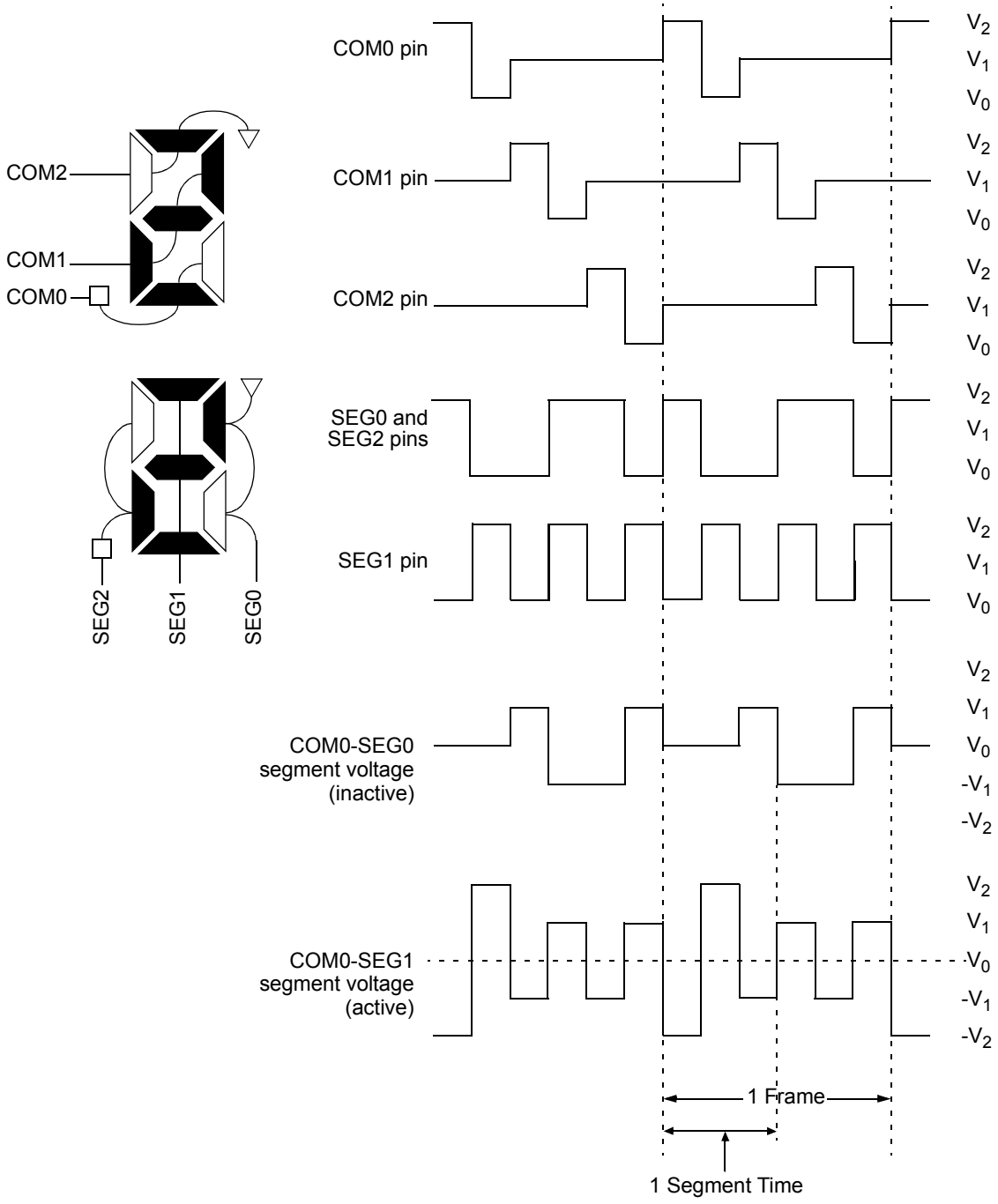
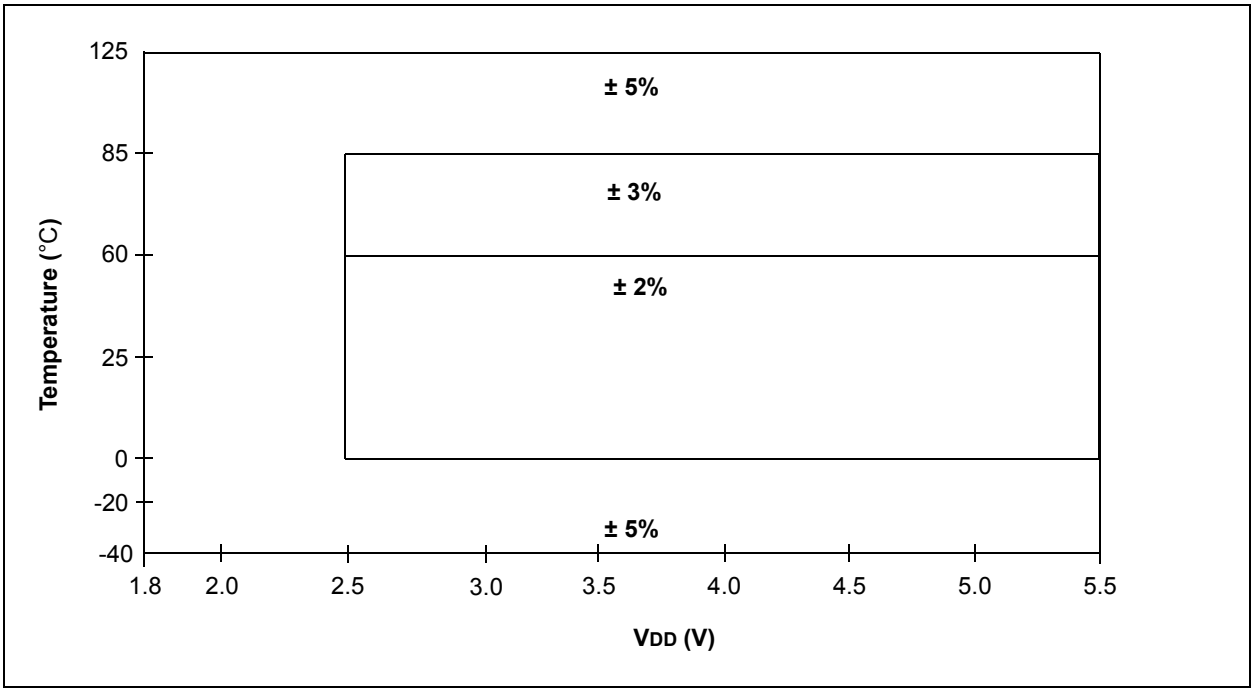
FIGURE 27-13: TYPE-A WAVEFORMS IN 1/3 MUX, 1/2 BIAS DRIVE



Note: 1 Frame = 2 single segment times.

FIGURE 30-3: HFINTOSC FREQUENCY ACCURACY OVER DEVICE VDD AND TEMPERATURE



30.1 DC Characteristics: Supply Voltage

PIC16LF1933			Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended				
PIC16F1933			**Standard Operating Conditions (unless otherwise stated)** Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended				
Param. No.	**Sym.**	**Characteristic**	**Min.**	**Typ†**	**Max.**	**Units**	**Conditions**
D001	VDD	**Supply Voltage (VDDMIN, VDDMAX)**					
		PIC16LF1933	1.8 2.5	— —	3.6 3.6	V V	FOSC ≤ 16 MHz: FOSC ≤ 32 MHz (**Note 2**)
D001		PIC16F1933	1.8 2.5	— —	5.5 5.5	V V	FOSC ≤ 16 MHz: FOSC ≤ 32 MHz (**Note 2**)
D002*	VDR	**RAM Data Retention Voltage(1)**					
		PIC16LF1933	1.5	—	—	V	Device in Sleep mode
D002*		PIC16F1933	1.7	—	—	V	Device in Sleep mode
D002A*	VPOR*	**Power-on Reset Release Voltage**	—	1.6	—	V	
D002B*	VPORR*	**Power-on Reset Rearm Voltage**					
		PIC16LF1933	—	0.8	—	V	
D002B*		PIC16F1933	—	1.42	—	V	
D003	VADFVR	**Fixed Voltage Reference Voltage for ADC**	-8	—	6	%	1.024V, VDD ≥ 2.5V 2.048V, VDD ≥ 2.5V 4.096V, VDD ≥ 4.75V
D003A	VCDAFVR	**Fixed Voltage Reference Voltage for Comparator and DAC**	-11	—	7	%	1.024V, VDD ≥ 2.5V 2.048V, VDD ≥ 2.5V 4.096V, VDD ≥ 4.75V
D003B	VLCDFVR	**Fixed Voltage Reference Voltage for LCD Bias**	-11	—	10	%	3.072V, VDD ≥ 3.6V
D004*	SVDD	**VDD Rise Rate** to ensure internal Power-on Reset signal	0.05	—	—	V/ms	See **Section 6.1 "Power-On Reset (POR)"** for details.

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: This is the limit to which VDD can be lowered in Sleep mode without losing RAM data.

2: PLL required for 32 MHz operation.

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TABLE 30-16: I²C™ BUS DATA REQUIREMENTS

Param. No.	Symbol	Characteristic		Min.	Max.	Units	Conditions
SP100*	THIGH	Clock high time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	—	μs	Device must operate at a minimum of 10 MHz
			SSP module	1.5TCY	—		
SP101*	TLOW	Clock low time	100 kHz mode	4.7	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	1.3	—	μs	Device must operate at a minimum of 10 MHz
			SSP module	1.5TCY	—		
SP102*	TR	SDA and SCL rise time	100 kHz mode	—	1000	ns	
			400 kHz mode	20 + 0.1CB	300	ns	CB is specified to be from 10-400 pF
SP103*	TF	SDA and SCL fall time	100 kHz mode	—	250	ns	
			400 kHz mode	20 + 0.1CB	250	ns	CB is specified to be from 10-400 pF
SP106*	THD:DAT	Data input hold time	100 kHz mode	0	—	ns	
			400 kHz mode	0	0.9	μs	
SP107*	TSU:DAT	Data input setup time	100 kHz mode	250	—	ns	**(Note 2)**
			400 kHz mode	100	—	ns	
SP109*	TAA	Output valid from clock	100 kHz mode	—	3500	ns	**(Note 1)**
			400 kHz mode	—	—	ns	
SP110*	TBUF	Bus free time	100 kHz mode	4.7	—	μs	Time the bus must be free before a new transmission can start
			400 kHz mode	1.3	—	μs	
SP111	CB	Bus capacitive loading		—	400	pF	

* These parameters are characterized but not tested.

Note 1: As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (min. 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.

2: A Fast mode (400 kHz) I²C™ bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement TSU:DAT ≥ 250 ns must then be met. This will automatically be the case if the device does not stretch the low period of the SCL signal. If such a device does stretch the low period of the SCL signal, it must output the next data bit to the SDA line TR max. + TSU:DAT = 1000 + 250 = 1250 ns (according to the Standard mode I²C bus specification), before the SCL line is released.

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FIGURE 31-3: IDD TYPICAL, XT AND EXTRC OSCILLATOR MODE, PIC16LF1933 ONLY

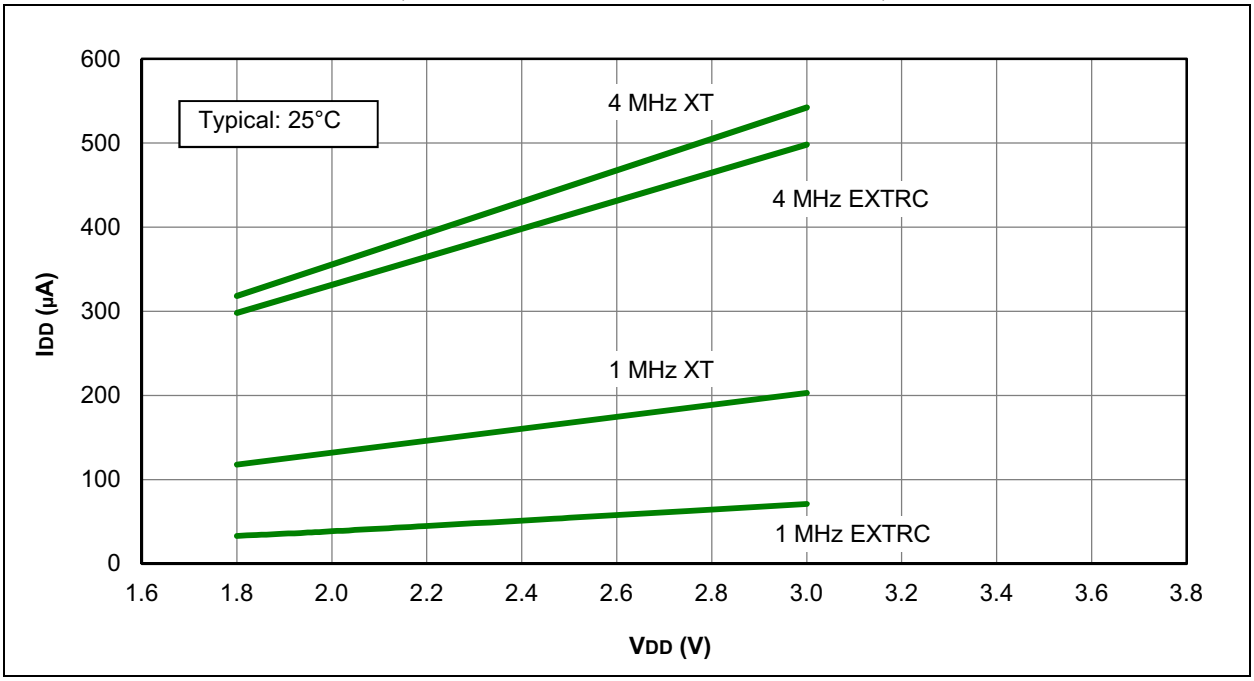
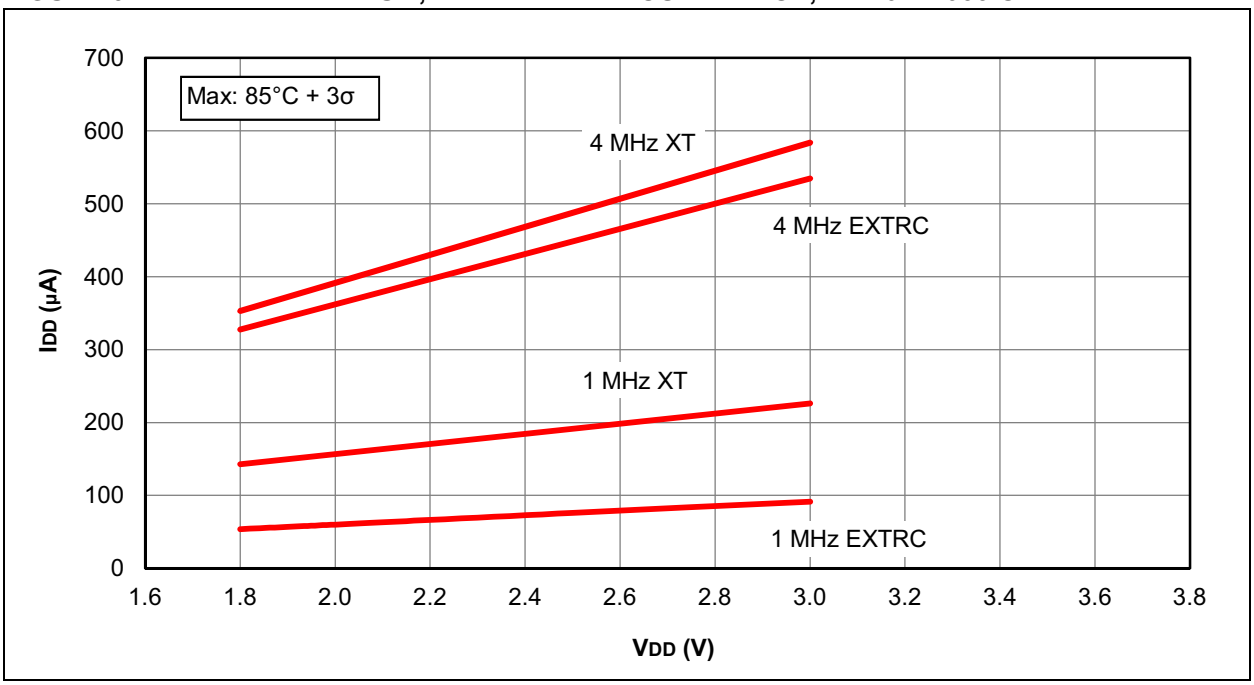


FIGURE 31-4: IDD MAXIMUM, XT AND EXTRC OSCILLATOR, PIC16LF1933 ONLY



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