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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	8051
Core Size	8-Bit
Speed	25MHz
Connectivity	SMBus (2-Wire/I ² C), SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, Temp Sensor, WDT
Number of I/O	24
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4.25K x 8
Voltage - Supply (Vcc/Vdd)	0.9V ~ 3.6V
Data Converters	A/D 23x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/c8051f920-g-gqr

C8051F93x-C8051F92x

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1.2. Port Input/Output

Digital and analog resources are available through 24 I/O pins (C8051F930/20) or 16 I/O pins (C8051F931/21). Port pins are organized as three byte-wide ports. Port pins P0.0–P2.6 can be defined as digital or analog I/O. Digital I/O pins can be assigned to one of the internal digital resources or used as general purpose I/O (GPIO). Analog I/O pins are used by the internal analog resources. P2.7 can be used as GPIO and is shared with the C2 Interface Data signal (C2D). See Section “27. C2 Interface” on page 324 for more details.

The designer has complete control over which digital and analog functions are assigned to individual Port pins, limited only by the number of physical I/O pins. This resource assignment flexibility is achieved through the use of a Priority Crossbar Decoder. See Section “21.3. Priority Crossbar Decoder” on page 221 for more information on the Crossbar.

All Port I/Os are 5 V tolerant when used as digital inputs or open-drain outputs. For Port I/Os configured as push-pull outputs, current is sourced from the VDD/DC+ supply. Port I/Os used for analog functions can operate up to the VDD/DC+ supply voltage. See Section “21.1. Port I/O Modes of Operation” on page 217 for more information on Port I/O operating modes and the electrical specifications chapter for detailed electrical specifications.

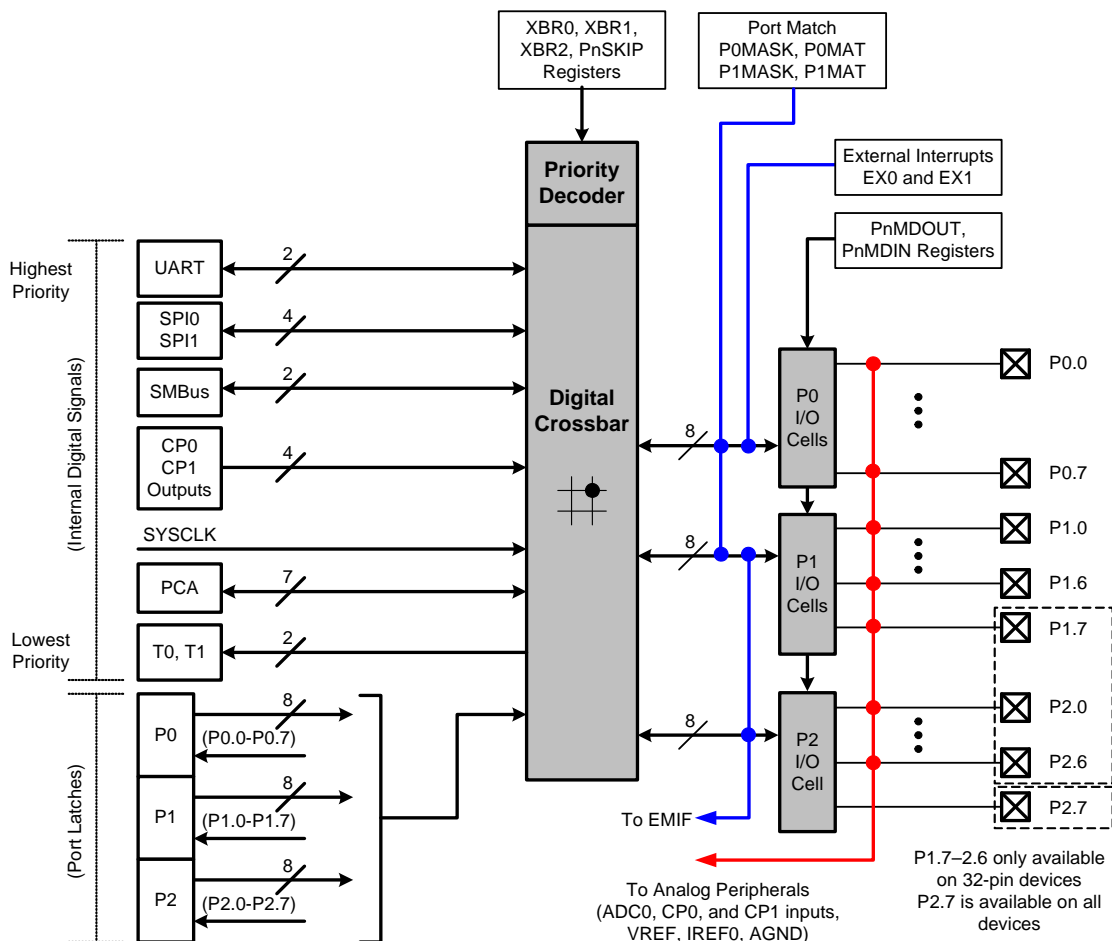


Figure 1.5. Port I/O Functional Block Diagram

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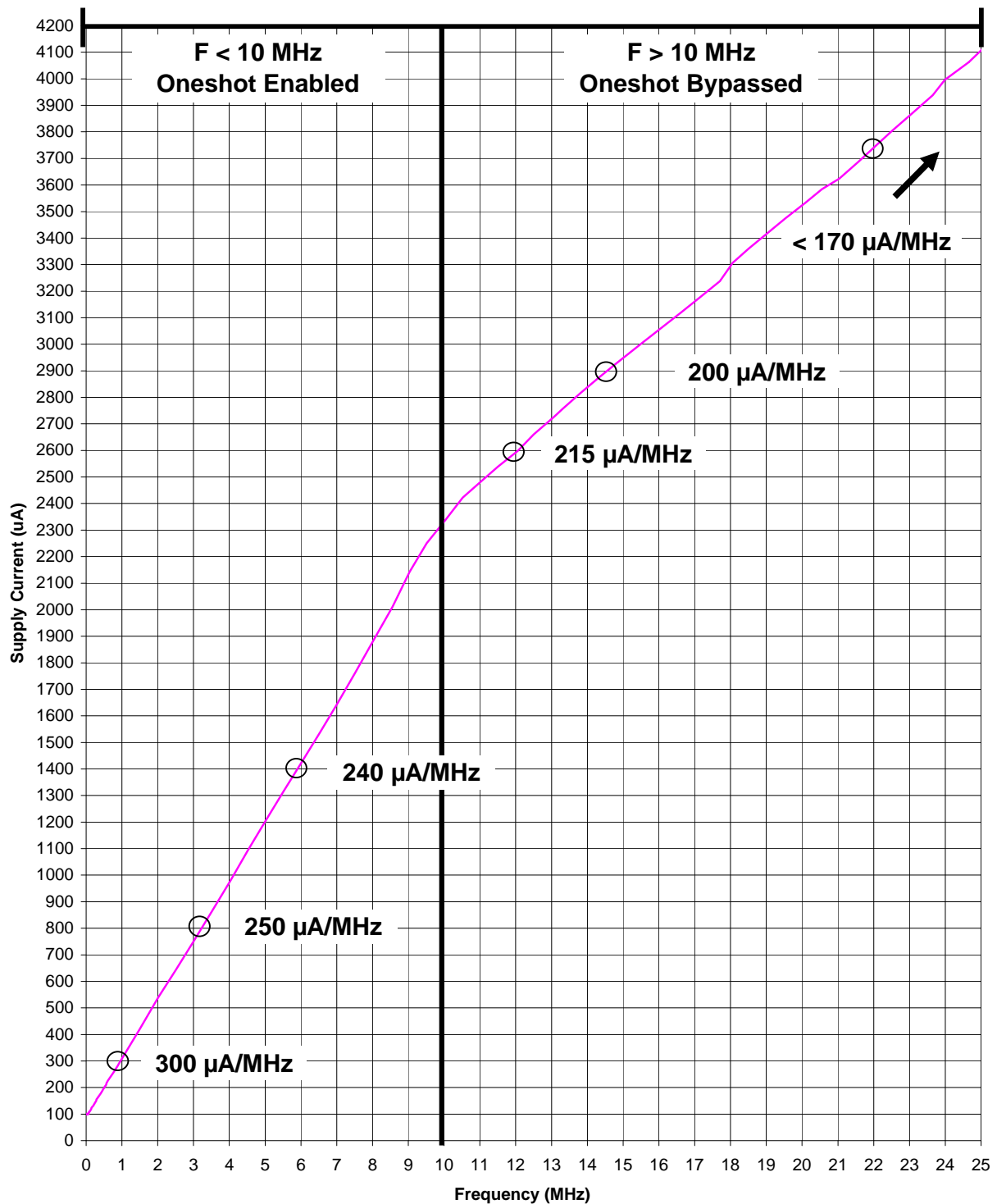


Figure 4.1. Active Mode Current (External CMOS Clock)

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SFR Definition 5.2. ADC0CF: ADC0 Configuration

Bit	7	6	5	4	3	2	1	0
Name	AD0SC[4:0]					AD08BE	AD0TM	AMP0GN
Type	R/W					R/W	R/W	R/W
Reset	1	1	1	1	1	0	0	0

SFR Page = 0x0; SFR Address = 0xBC

Bit	Name	Function
7:3	AD0SC[4:0]	<p>ADC0 SAR Conversion Clock Divider. SAR Conversion clock is derived from FCLK by the following equation, where AD0SC refers to the 5-bit value held in bits AD0SC[4:0]. SAR Conversion clock requirements are given in Table 4.9. BURSTEN = 0: FCLK is the current system clock. BURSTEN = 1: FCLK is the 20 MHz low power oscillator, independent of the system clock.</p> $AD0SC = \frac{FCLK}{CLK_{SAR}} - 1 *$ <p>*Round the result up.</p> <p>or</p> $CLK_{SAR} = \frac{FCLK}{AD0SC + 1}$
2	AD08BE	<p>ADC0 8-Bit Mode Enable. 0: ADC0 operates in 10-bit mode (normal operation). 1: ADC0 operates in 8-bit mode.</p>
1	AD0TM	<p>ADC0 Track Mode. Selects between Normal or Delayed Tracking Modes. 0: Normal Track Mode: When ADC0 is enabled, conversion begins immediately following the start-of-conversion signal. 1: Delayed Track Mode: When ADC0 is enabled, conversion begins 3 SAR clock cycles following the start-of-conversion signal. The ADC is allowed to track during this time.</p>
0	AMP0GN	<p>ADC0 Gain Control. 0: The on-chip PGA gain is 0.5. 1: The on-chip PGA gain is 1.</p>

7.2. Comparator Outputs

When a comparator is enabled, its output is a logic 1 if the voltage at the positive input is higher than the voltage at the negative input. When disabled, the comparator output is a logic 0. The comparator output is synchronized with the system clock as shown in Figure 7.2. The synchronous “latched” output (CP0, CP1) can be polled in software (CPnOUT bit), used as an interrupt source, or routed to a Port pin through the Crossbar.

The asynchronous “raw” comparator output (CP0A, CP1A) is used by the low power mode wakeup logic and reset decision logic. See the Power Options chapter and the Reset Sources chapter for more details on how the asynchronous comparator outputs are used to make wake-up and reset decisions. The asynchronous comparator output can also be routed directly to a Port pin through the Crossbar, and is available for use outside the device even if the system clock is stopped.

When using a Comparator as an interrupt source, Comparator interrupts can be generated on rising-edge and/or falling-edge comparator output transitions. Two independent interrupt flags (CPnRIF and CPnFIF) allow software to determine which edge caused the Comparator interrupt. The comparator rising-edge and falling-edge interrupt flags are set by hardware when a corresponding edge is detected regardless of the interrupt enable state. Once set, these bits remain set until cleared by software.

The rising-edge and falling-edge interrupts can be individually enabled using the CPnRIE and CPnFIE interrupt enable bits in the CPTnMD register. In order for the CPnRIF and/or CPnFIF interrupt flags to generate an interrupt request to the CPU, the Comparator must be enabled as an interrupt source and global interrupts must be enabled. See the Interrupt Handler chapter for additional information.

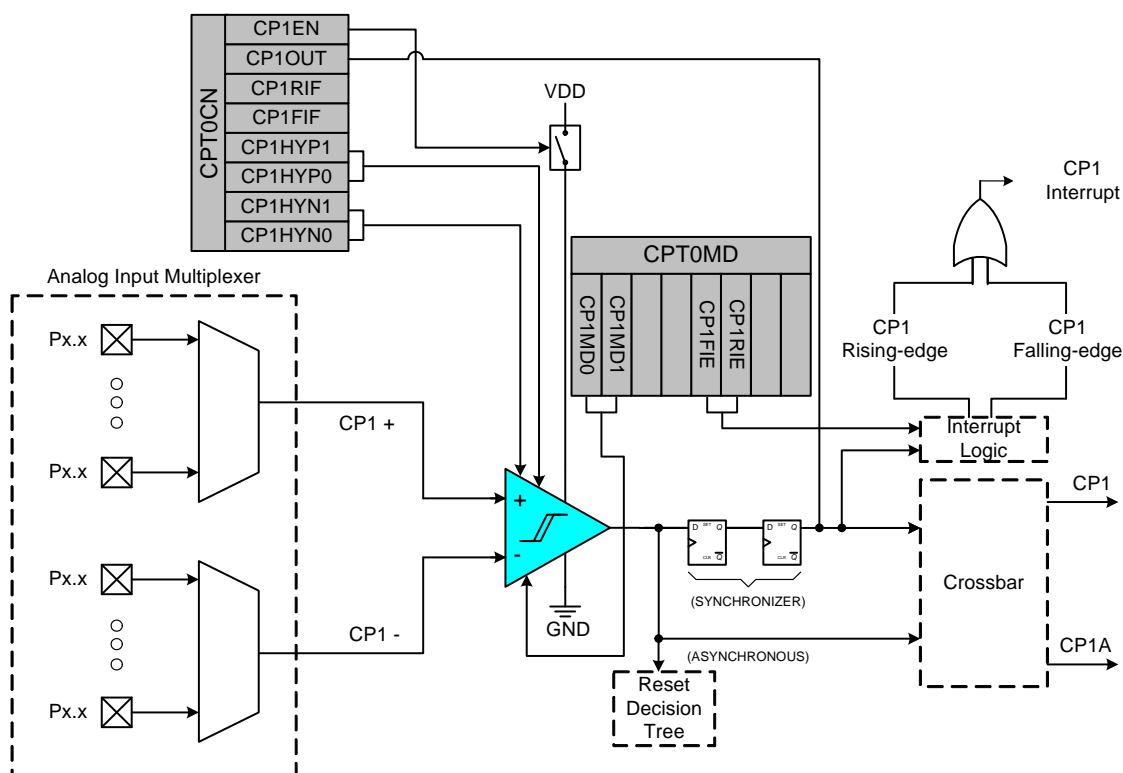


Figure 7.2. Comparator 1 Functional Block Diagram

Table 11.3. Special Function Registers (Continued)

SFRs are listed in alphabetical order. All undefined SFR locations are reserved

Register	Address	SFR Page	Description	Page
P0SKIP	0xD4	0x0	Port 0 Skip	230
P1	0x90	All	Port 1 Latch	233
P1DRV	0xA5	0xF	Port 1 Drive Strength	235
P1MASK	0xBF	0x0	Port 1 Mask	228
P1MAT	0xCF	0x0	Port 1 Match	228
P1MDIN	0xF2	0x0	Port 1 Input Mode Configuration	234
P1MDOUT	0xA5	0x0	Port 1 Output Mode Configuration	234
P1SKIP	0xD5	0x0	Port 1 Skip	233
P2	0xA0	All	Port 2 Latch	235
P2DRV	0xA6	0xF	Port 2 Drive Strength	237
P2MDIN	0xF3	0x0	Port 2 Input Mode Configuration	236
P2MDOUT	0xA6	0x0	Port 2 Output Mode Configuration	237
P2SKIP	0xD6	0x0	Port 2 Skip	236
PCA0CN	0xD8	0x0	PCA0 Control	318
PCA0CPH0	0xFC	0x0	PCA0 Capture 0 High	323
PCA0CPH1	0xEA	0x0	PCA0 Capture 1 High	323
PCA0CPH2	0xEC	0x0	PCA0 Capture 2 High	323
PCA0CPH3	0xEE	0x0	PCA0 Capture 3 High	323
PCA0CPH4	0xFE	0x0	PCA0 Capture 4 High	323
PCA0CPH5	0xD3	0x0	PCA0 Capture 5 High	323
PCA0CPL0	0xFB	0x0	PCA0 Capture 0 Low	323
PCA0CPL1	0xE9	0x0	PCA0 Capture 1 Low	323
PCA0CPL2	0xEB	0x0	PCA0 Capture 2 Low	323
PCA0CPL3	0xED	0x0	PCA0 Capture 3 Low	323
PCA0CPL4	0xFD	0x0	PCA0 Capture 4 Low	323
PCA0CPL5	0xD2	0x0	PCA0 Capture 5 Low	323
PCA0CPM0	0xDA	0x0	PCA0 Module 0 Mode Register	321
PCA0CPM1	0xDB	0x0	PCA0 Module 1 Mode Register	321
PCA0CPM2	0xDC	0x0	PCA0 Module 2 Mode Register	321
PCA0CPM3	0xDD	0x0	PCA0 Module 3 Mode Register	321
PCA0CPM4	0xDE	0x0	PCA0 Module 4 Mode Register	321
PCA0CPM5	0xCE	0x0	PCA0 Module 5 Mode Register	321
PCA0H	0xFA	0x0	PCA0 Counter High	322
PCA0L	0xF9	0x0	PCA0 Counter Low	322

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Table 11.3. Special Function Registers (Continued)

SFRs are listed in alphabetical order. All undefined SFR locations are reserved

Register	Address	SFR Page	Description	Page
PCA0MD	0xD9	0x0	PCA0 Mode	319
PCA0PWM	0xDF	0x0	PCA0 PWM Configuration	320
PCON	0x87	0x0	Power Control	166
PMU0CF	0xB5	0x0	PMU0 Configuration	165
PSCTL	0x8F	0x0	Program Store R/W Control	156
PSW	0xD0	All	Program Status Word	111
REF0CN	0xD1	0x0	Voltage Reference Control	91
REG0CN	0xC9	0x0	Voltage Regulator (VREG0) Control	183
RSTSRC	0xEF	0x0	Reset Source Configuration/Status	190
RTC0ADR	0xAC	0x0	RTC0 Address	205
RTC0DAT	0xAD	0x0	RTC0 Data	205
RTC0KEY	0xAE	0x0	RTC0 Key	204
SBUF0	0x99	0x0	UART0 Data Buffer	266
SCON0	0x98	0x0	UART0 Control	265
SFRPAGE	0xA7	All	SFR Page	131
SMB0ADM	0xF5	0x0	SMBus Slave Address Mask	250
SMB0ADR	0xF4	0x0	SMBus Slave Address	250
SMB0CF	0xC1	0x0	SMBus0 Configuration	245
SMB0CN	0xC0	0x0	SMBus0 Control	247
SMB0DAT	0xC2	0x0	SMBus0 Data	251
SP	0x81	All	Stack Pointer	110
SPI0CFG	0xA1	0x0	SPI0 Configuration	276
SPI0CKR	0xA2	0x0	SPI0 Clock Rate Control	278
SPI0CN	0xF8	0x0	SPI0 Control	277
SPI0DAT	0xA3	0x0	SPI0 Data	279
SPI1CFG	0x84	0x0	SPI1 Configuration	276
SPI1CKR	0x85	0x0	SPI1 Clock Rate Control	278
SPI1CN	0xB0	0x0	SPI1 Control	277
SPI1DAT	0x86	0x0	SPI1 Data	279
TCON	0x88	0x0	Timer/Counter Control	289
TH0	0x8C	0x0	Timer/Counter 0 High	292
TH1	0x8D	0x0	Timer/Counter 1 High	292
TL0	0x8A	0x0	Timer/Counter 0 Low	291
TL1	0x8B	0x0	Timer/Counter 1 Low	291

18.2. Power-Fail (VDD/DC+ Supply Monitor) Reset

C8051F93x-C8051F92x devices have a VDD/DC+ Supply Monitor that is enabled and selected as a reset source after each power-on or power-fail reset. When enabled and selected as a reset source, any power down transition or power irregularity that causes VDD/DC+ to drop below V_{RST} will cause the RST pin to be driven low and the CIP-51 will be held in a reset state (see Figure 18.3). When VDD/DC+ returns to a level above V_{RST} , the CIP-51 will be released from the reset state.

After a power-fail reset, the PORSF flag reads 1, the contents of RAM invalid, and the VDD/DC+ supply monitor is enabled and selected as a reset source. The enable state of the VDD/DC+ supply monitor and its selection as a reset source is only altered by power-on and power-fail resets. For example, if the VDD/DC+ supply monitor is de-selected as a reset source and disabled by software, then a software reset is performed, the VDD/DC+ supply monitor will remain disabled and de-selected after the reset.

In battery-operated systems, the contents of RAM can be preserved near the end of the battery's usable life if the device is placed in sleep mode prior to a power-fail reset occurring. When the device is in sleep mode, the power-fail reset is automatically disabled and the contents of RAM are preserved as long as the VBAT supply does not fall below V_{POR} . A large capacitor can be used to hold the power supply voltage above V_{POR} while the user is replacing the battery. Upon waking from sleep mode, the enable and reset source select state of the VDD/DC+ supply monitor are restored to the value last set by the user.

To allow software early notification that a power failure is about to occur, the VDDOK bit is cleared when the VDD/DC+ supply falls below the V_{WARN} threshold. The VDDOK bit can be configured to generate an interrupt. See Section "12. Interrupt Handler" on page 136 for more details.

Important Note: To protect the integrity of Flash contents, the VDD/DC+ supply monitor must be enabled and selected as a reset source if software contains routines which erase or write Flash memory. If the VDD/DC+ supply monitor is not enabled, any erase or write performed on Flash memory will cause a Flash Error device reset.

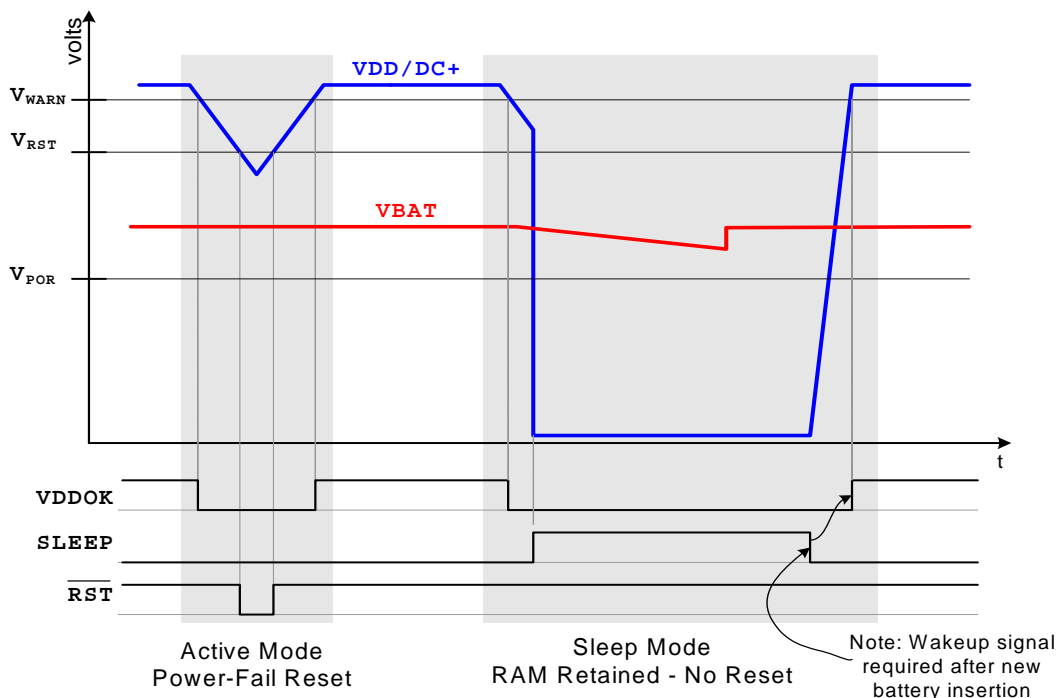


Figure 18.3. Power-Fail Reset Timing Diagram

19.4. Special Function Registers for Selecting and Configuring the System Clock

The clocking sources on C8051F93x-C8051F92x devices are enabled and configured using the OSCICN, OSCICL, OSCXCN and the SmaRTClock internal registers. See Section “20. SmaRTClock (Real Time Clock)” on page 200 for SmaRTClock register descriptions. The system clock source for the MCU can be selected using the CLKSEL register. To minimize active mode current, the oneshot timer which sets Flash read time should be bypassed when the system clock is greater than 10 MHz. See the FLSCL register description for details.

The clock selected as the system clock can be divided by 1, 2, 4, 8, 16, 32, 64, or 128. When switching between two clock divide values, the transition may take up to 128 cycles of the undivided clock source. The CLKRDY flag can be polled to determine when the new clock divide value has been applied. The clock divider must be set to "divide by 1" when entering suspend or sleep mode.

The system clock source may also be switched on-the-fly. The switchover takes effect after one clock period of the slower oscillator.

SFR Definition 19.1. CLKSEL: Clock Select

Bit	7	6	5	4	3	2	1	0
Name	CLKRDY	CLKDIV[2:0]				CLKSEL[2:0]		
Type	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	1	1	0	1	0	0

SFR Page = All Pages; SFR Address = 0xA9

Bit	Name	Function
7	CLKRDY	System Clock Divider Clock Ready Flag. 0: The selected clock divide setting has not been applied to the system clock. 1: The selected clock divide setting has been applied to the system clock.
6:4	CLKDIV[2:0]	System Clock Divider Bits. Selects the clock division to be applied to the undivided system clock source. 000: System clock is divided by 1. 001: System clock is divided by 2. 010: System clock is divided by 4. 011: System clock is divided by 8. 100: System clock is divided by 16. 101: System clock is divided by 32. 110: System clock is divided by 64. 111: System clock is divided by 128.
3		Unused. Read = 0b. Must Write 0b.
2:0	CLKSEL[2:0]	System Clock Select. Selects the oscillator to be used as the undivided system clock source. 000: Precision Internal Oscillator. 001: External Oscillator. 011: SmaRTClock Oscillator. 100: Low Power Oscillator. All other values reserved.

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Internal Register Definition 20.8. CAPTUREn: SmaRTClock Timer Capture

Bit	7	6	5	4	3	2	1	0
Name	CAPTURE[31:0]							
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SmaRTClock Addresses: CAPTURE0 = 0x00; CAPTURE1 = 0x01; CAPTURE2 = 0x02; CAPTURE3: 0x03.

Bit	Name	Function
7:0	CAPTURE[31:0]	SmaRTClock Timer Capture. These 4 registers (CAPTURE3–CAPTURE0) are used to read or set the 32-bit SmaRTClock timer. Data is transferred to or from the SmaRTClock timer when the RTC0SET or RTC0CAP bits are set.

Note: The least significant bit of the timer capture value is in CAPTURE0.0.

Internal Register Definition 20.9. ALARMn: SmaRTClock Alarm Programmed Value

Bit	7	6	5	4	3	2	1	0
Name	ALARM[31:0]							
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SmaRTClock Addresses: ALARM0 = 0x08; ALARM1 = 0x09; ALARM2 = 0x0A; ALARM3 = 0x0B

Bit	Name	Function
7:0	ALARM[31:0]	SmaRTClock Alarm Programmed Value. These 4 registers (ALARM3–ALARM0) are used to set an alarm event for the SmaRTClock timer. The SmaRTClock alarm should be disabled (RTC0AEN=0) when updating these registers.

Note: The least significant bit of the alarm programmed value is in ALARM0.0.

21.1. Port I/O Modes of Operation

Port pins P0.0–P2.6 use the Port I/O cell shown in Figure 21.2. Each Port I/O cell can be configured by software for analog I/O or digital I/O using the PnMDIN registers. On reset, all Port I/O cells default to a digital high impedance state with weak pull-ups enabled.

21.1.1. Port Pins Configured for Analog I/O

Any pins to be used as Comparator or ADC input, external oscillator input/output, or AGND, VREF, or Current Reference output should be configured for analog I/O (PnMDIN.n = 0). When a pin is configured for analog I/O, its weak pullup and digital receiver are disabled. In most cases, software should also disable the digital output drivers. Port pins configured for analog I/O will always read back a value of 0 regardless of the actual voltage on the pin.

Configuring pins as analog I/O saves power and isolates the Port pin from digital interference. Port pins configured as digital inputs may still be used by analog peripherals; however, this practice is not recommended and may result in measurement errors.

21.1.2. Port Pins Configured For Digital I/O

Any pins to be used by digital peripherals (UART, SPI, SMBus, etc.), external digital event capture functions, or as GPIO should be configured as digital I/O (PnMDIN.n = 1). For digital I/O pins, one of two output modes (push-pull or open-drain) must be selected using the PnMDOUT registers.

Push-pull outputs (PnMDOUT.n = 1) drive the Port pad to the VDD/DC+ or GND supply rails based on the output logic value of the Port pin. Open-drain outputs have the high side driver disabled; therefore, they only drive the Port pad to GND when the output logic value is 0 and become high impedance inputs (both high and low drivers turned off) when the output logic value is 1.

When a digital I/O cell is placed in the high impedance state, a weak pull-up transistor pulls the Port pad to the VDD/DC+ supply voltage to ensure the digital input is at a defined logic state. Weak pull-ups are disabled when the I/O cell is driven to GND to minimize power consumption and may be globally disabled by setting WEAKPUD to 1. The user must ensure that digital I/O are always internally or externally pulled or driven to a valid logic state. Port pins configured for digital I/O always read back the logic state of the Port pad, regardless of the output logic value of the Port pin.

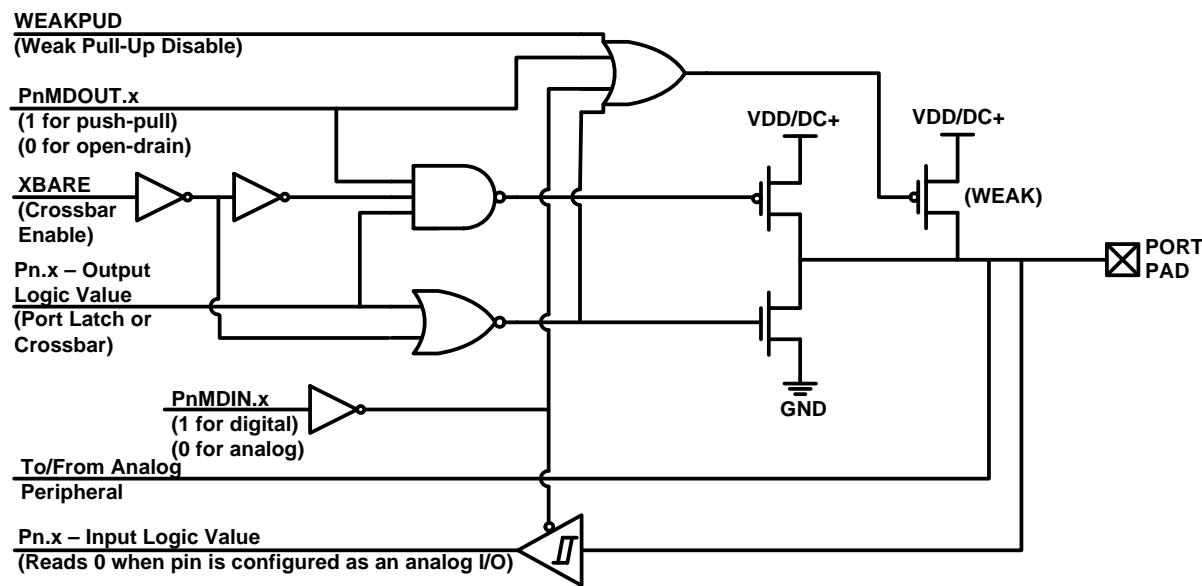


Figure 21.2. Port I/O Cell Block Diagram

C8051F93x-C8051F92x

	P0								P1								P2								
SF Signals	VREF	AGND	XTAL1	XTAL2			CNVSTR	IREF0	AD0	AD1	AD2	AD3	AD4	AD5	AD6	AD7	A8	A9	A10	A11	ALE	/RD	/WR		C2D
PIN I/O	0	1	2	3	4	5	6	7	0	1	2	3	4	5	6	7	0	1	2	3	4	5	6	7	
TX0																									
RX0																									
SCK (SPI1)																									
MISO (SPI1)																									
MOSI (SPI1)																									
NSS* (SPI1)																									
SCK (SPI0)																									
MISO (SPI0)																									
MOSI (SPI0)																									
NSS* (SPI0)																									
SDA																									
SCL																									
CP0																									
CP0A																									
CP1																									
CP1A																									
/SYSCLK																									
CEX0																									
CEX1																									
CEX2																									
CEX3																									
CEX4																									
CEX5																									
ECI																									
T0																									
T1																									
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	X
	P0SKIP[0:7]								P1SKIP[0:7]								P2SKIP[0:7]								

Figure 21.4. Crossbar Priority Decoder with Crystal Pins Skipped

22.4. Using the SMBus

The SMBus can operate in both Master and Slave modes. The interface provides timing and shifting control for serial transfers; higher level protocol is determined by user software. The SMBus interface provides the following application-independent features:

- Byte-wise serial data transfers
- Clock signal generation on SCL (Master Mode only) and SDA data synchronization
- Timeout/bus error recognition, as defined by the SMB0CF configuration register
- START/STOP timing, detection, and generation
- Bus arbitration
- Interrupt generation
- Status information
- Optional hardware recognition of slave address and automatic acknowledgement of address/data

SMBus interrupts are generated for each data byte or slave address that is transferred. When hardware acknowledgement is disabled, the point at which the interrupt is generated depends on whether the hardware is acting as a data transmitter or receiver. When a transmitter (i.e., sending address/data, receiving an ACK), this interrupt is generated after the ACK cycle so that software may read the received ACK value; when receiving data (i.e., receiving address/data, sending an ACK), this interrupt is generated before the ACK cycle so that software may define the outgoing ACK value. If hardware acknowledgement is enabled, these interrupts are always generated after the ACK cycle. See Section 22.5 for more details on transmission sequences.

Interrupts are also generated to indicate the beginning of a transfer when a master (START generated), or the end of a transfer when a slave (STOP detected). Software should read the SMB0CN (SMBus Control register) to find the cause of the SMBus interrupt. The SMB0CN register is described in Section 22.4.2; Table 22.5 provides a quick SMB0CN decoding reference.

SFR Definition 22.3. SMB0ADR: SMBus Slave Address

Bit	7	6	5	4	3	2	1	0
Name	SLV[6:0]							GC
Type	R/W							R/W
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xF4

Bit	Name	Function
7:1	SLV[6:0]	SMBus Hardware Slave Address. Defines the SMBus Slave Address(es) for automatic hardware acknowledgement. Only address bits which have a 1 in the corresponding bit position in SLVM[6:0] are checked against the incoming address. This allows multiple addresses to be recognized.
0	GC	General Call Address Enable. When hardware address recognition is enabled (EHACK = 1), this bit will determine whether the General Call Address (0x00) is also recognized by hardware. 0: General Call Address is ignored. 1: General Call Address is recognized.

SFR Definition 22.4. SMB0ADM: SMBus Slave Address Mask

Bit	7	6	5	4	3	2	1	0
Name	SLVM[6:0]							EHACK
Type	R/W							R/W
Reset	1	1	1	1	1	1	1	0

SFR Page = 0x0; SFR Address = 0xF5

Bit	Name	Function
7:1	SLVM[6:0]	SMBus Slave Address Mask. Defines which bits of register SMB0ADR are compared with an incoming address byte, and which bits are ignored. Any bit set to 1 in SLVM[6:0] enables comparisons with the corresponding bit in SLV[6:0]. Bits set to 0 are ignored (can be either 0 or 1 in the incoming address).
0	EHACK	Hardware Acknowledge Enable. Enables hardware acknowledgement of slave address and received data bytes. 0: Firmware must manually acknowledge all incoming address and data bytes. 1: Automatic Slave Address Recognition and Hardware Acknowledge is Enabled.

SFR Definition 24.1. SPIInCFG: SPI Configuration

Bit	7	6	5	4	3	2	1	0
Name	SPIBSY	MSTEN	CKPHA	CKPOL	SLVSEL	NSSIN	SRMT	RXBMT
Type	R	R/W	R/W	R/W	R	R	R	R
Reset	0	0	0	0	0	1	1	1

SFR Addresses: SPI0CFG = 0xA1, SPI1CFG = 0x84

SFR Pages: SPI0CFG = 0x0, SPI1CFG = 0x0

Bit	Name	Function
7	SPIBSY	SPI Busy. This bit is set to logic 1 when a SPI transfer is in progress (master or slave mode).
6	MSTEN	Master Mode Enable. 0: Disable master mode. Operate in slave mode. 1: Enable master mode. Operate as a master.
5	CKPHA	SPI Clock Phase. 0: Data centered on first edge of SCK period.* 1: Data centered on second edge of SCK period.*
4	CKPOL	SPI Clock Polarity. 0: SCK line low in idle state. 1: SCK line high in idle state.
3	SLVSEL	Slave Selected Flag. Set to logic 1 whenever the NSS pin is low indicating SPI0 is the selected slave. It is cleared to logic 0 when NSS is high (slave not selected). This bit does not indicate the instantaneous value at the NSS pin, but rather a de-glitched version of the pin input.
2	NSSIN	NSS Instantaneous Pin Input. This bit mimics the instantaneous value that is present on the NSS port pin at the time that the register is read. This input is not de-glitched.
1	SRMT	Shift Register Empty (valid in slave mode only). Set to logic 1 when data has been transferred in/out of the shift register, and there is no data is available to read from the transmit buffer or write to the receive buffer. Set to logic 0 when a data byte is transferred to the shift register from the transmit buffer or by a transition on SCK. Note: SRMT = 1 in Master Mode.
0	RXBMT	Receive Buffer Empty (valid in slave mode only). Set to logic 1 when the receive buffer has been read and contains no new information. If there is new information available in the receive buffer that has not been read, this bit will return to logic 0. Note: RXBMT = 1 in Master Mode.
<p>*Note: In slave mode, data on MOSI is sampled in the center of each data bit. In master mode, data on MISO is sampled one SYSCLK before the end of each data bit, to provide maximum settling time for the slave device. See Table 24.1 for timing parameters.</p>		

SFR Definition 25.4. TL0: Timer 0 Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TL0[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0x8A

Bit	Name	Function
7:0	TL0[7:0]	Timer 0 Low Byte. The TL0 register is the low byte of the 16-bit Timer 0.

SFR Definition 25.5. TL1: Timer 1 Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TL1[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0x8B

Bit	Name	Function
7:0	TL1[7:0]	Timer 1 Low Byte. The TL1 register is the low byte of the 16-bit Timer 1.

SFR Definition 25.9. TMR2RLL: Timer 2 Reload Register Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR2RLL[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xCA

Bit	Name	Function
7:0	TMR2RLL[7:0]	Timer 2 Reload Register Low Byte. TMR2RLL holds the low byte of the reload value for Timer 2.

SFR Definition 25.10. TMR2RLH: Timer 2 Reload Register High Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR2RLH[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xCB

Bit	Name	Function
7:0	TMR2RLH[7:0]	Timer 2 Reload Register High Byte. TMR2RLH holds the high byte of the reload value for Timer 2.

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SFR Definition 25.13. TMR3CN: Timer 3 Control

Bit	7	6	5	4	3	2	1	0
Name	TF3H	TF3L	TF3LEN	TF3CEN	T3SPLIT	TR3	T3XCLK[1:0]	
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Reset	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0x91

Bit	Name	Function
7	TF3H	Timer 3 High Byte Overflow Flag. Set by hardware when the Timer 3 high byte overflows from 0xFF to 0x00. In 16 bit mode, this will occur when Timer 3 overflows from 0xFFFF to 0x0000. When the Timer 3 interrupt is enabled, setting this bit causes the CPU to vector to the Timer 3 interrupt service routine. This bit is not automatically cleared by hardware.
6	TF3L	Timer 3 Low Byte Overflow Flag. Set by hardware when the Timer 3 low byte overflows from 0xFF to 0x00. TF3L will be set when the low byte overflows regardless of the Timer 3 mode. This bit is not automatically cleared by hardware.
5	TF3LEN	Timer 3 Low Byte Interrupt Enable. When set to 1, this bit enables Timer 3 Low Byte interrupts. If Timer 3 interrupts are also enabled, an interrupt will be generated when the low byte of Timer 3 overflows.
4	TF3CEN	Timer 3 Comparator 1/External Oscillator Capture Enable. When set to 1, this bit enables Timer 3 Capture Mode.
3	T3SPLIT	Timer 3 Split Mode Enable. When this bit is set, Timer 3 operates as two 8-bit timers with auto-reload. 0: Timer 3 operates in 16-bit auto-reload mode. 1: Timer 3 operates as two 8-bit auto-reload timers.
2	TR3	Timer 3 Run Control. Timer 3 is enabled by setting this bit to 1. In 8-bit mode, this bit enables/disables TMR3H only; TMR3L is always enabled in split mode.
1:0	T3XCLK[1:0]	Timer 3 External Clock Select. This bit selects the “external” and “capture trigger” clock sources for Timer 3. If Timer 3 is in 8-bit mode, this bit selects the “external” clock source for both timer bytes. Timer 3 Clock Select bits (T3MH and T3ML in register CKCON) may still be used to select between the “external” clock and the system clock for either timer. Note: External clock sources are synchronized with the system clock. 00: External Clock is SYSCLK /12. Capture trigger is Comparator 1. 01: External Clock is External Oscillator/8. Capture trigger is Comparator 1. 10: External Clock is SYSCLK/12. Capture trigger is External Oscillator/8. 11: External Clock is Comparator 1. Capture trigger is External Oscillator/8.