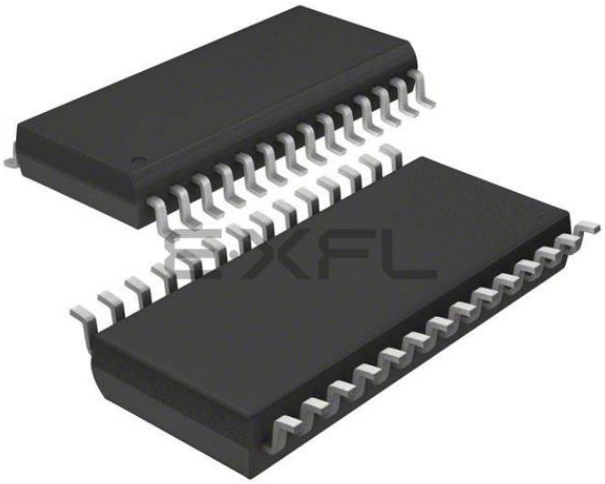


Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	24
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.25V
Data Converters	A/D 28x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c21534-24pvxit

More Information

Cypress provides a wealth of data at www.cypress.com to help you to select the right PSoC device for your design, and to help you to quickly and effectively integrate the device into your design. For a comprehensive list of resources, see the knowledge base article, How to Design with PSoC® 1, PowerPSoC®, and PLC – KBA88292. Following is an abbreviated list for PSoC 1:

- Overview: PSoC Portfolio, PSoC Roadmap
- Product Selectors: PSoC 1, PSoC 3, PSoC 4, PSoC 5LP
- In addition, PSoC Designer includes a device selection tool.
- Application notes: Cypress offers a large number of PSoC application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with PSoC 1 are:
  - Getting Started with PSoC® 1 – AN75320
  - PSoC® 1 - Getting Started with GPIO – AN2094
  - PSoC® 1 Analog Structure and Configuration – AN74170
  - PSoC® 1 Switched Capacitor Analog Blocks – AN2041
  - Selecting Analog Ground and Reference – AN2219

Note: For CY8C21x34B devices related Application note please click here.

- Development Kits:
  - CY3210-PSoCEval1 supports all PSoC 1 Mixed-Signal Array families, including automotive, except CY8C25/26xxx devices. The kit includes an LCD module, potentiometer, LEDs, and breadboarding space.
  - CY3214-PSoCEvalUSB features a development board for the CY8C24x94 PSoC device. Special features of the board include USB and CapSense development and debugging support.

Note: For CY8C21x34B devices related Development Kits please click here.

The MiniProg1 and MiniProg3 devices provide interfaces for flash programming and debug.

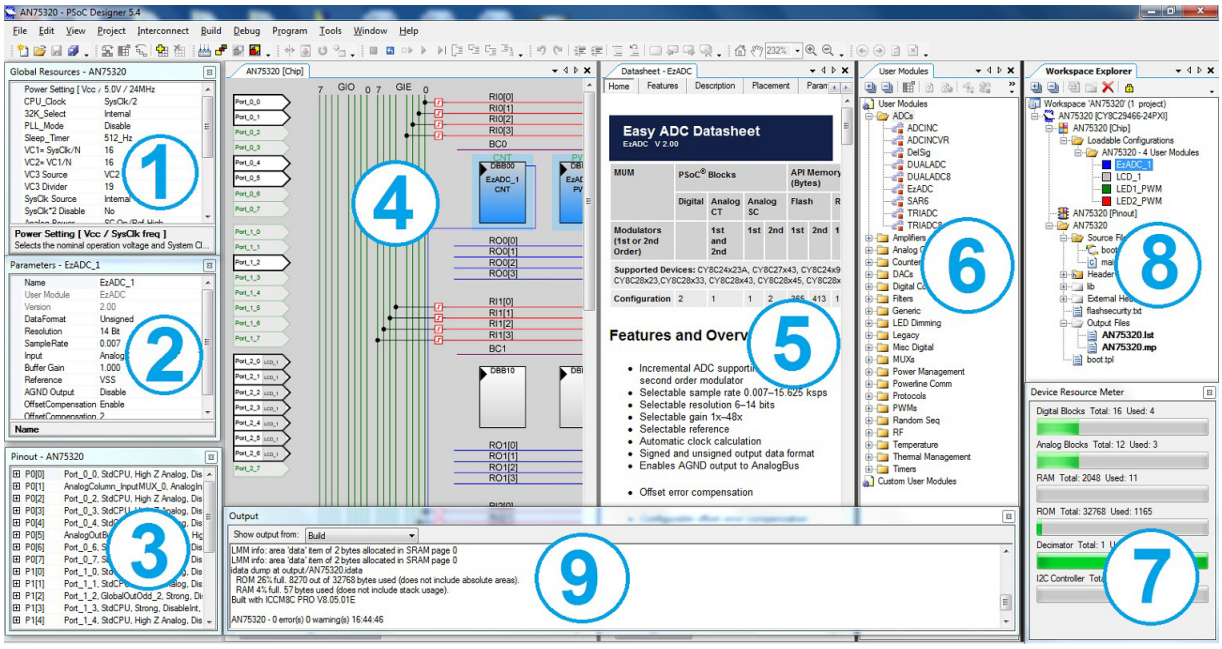
PSoC Designer

PSoC Designer is a free Windows-based Integrated Design Environment (IDE). Develop your applications using a library of pre-characterized analog and digital peripherals in a drag-and-drop design environment. Then, customize your design leveraging the dynamically generated API libraries of code. Figure 1 shows PSoC Designer windows. **Note:** This is not the default view.

1. **Global Resources –** all device hardware settings.
2. **Parameters –** the parameters of the currently selected User Modules.
3. **Pinout –** information related to device pins.
4. **Chip-Level Editor –** a diagram of the resources available on the selected chip.
5. **Datasheet –** the datasheet for the currently selected UM
6. **User Modules –** all available User Modules for the selected device.
7. **Device Resource Meter –** device resource usage for the current project configuration.
8. **Workspace –** a tree level diagram of files associated with the project.
9. **Output –** output from project build and debug operations.

Note: For detailed information on PSoC Designer, go to **PSoC® Designer** > **Help** > **Documentation** > **Designer Specific Documents** > **IDE User Guide**.

Figure 1. PSoC Designer Layout



Contents

Development Tools

PSoC Designer™ is the revolutionary integrated design environment (IDE) that you can use to customize PSoC to meet your specific application requirements. PSoC Designer software accelerates system design and time to market. Develop your applications using a library of precharacterized analog and digital peripherals (called user modules) in a drag-and-drop design environment. Then, customize your design by leveraging the dynamically generated application programming interface (API) libraries of code. Finally, debug and test your designs with the integrated debug environment, including in-circuit emulation and standard software debug features. PSoC Designer includes:

- Application editor graphical user interface (GUI) for device and user module configuration and dynamic reconfiguration
- Extensive user module catalog
- Integrated source-code editor (C and assembly)
- Free C compiler with no size restrictions or time limits
- Built-in debugger
- In-circuit emulation
- Built-in support for communication interfaces:
  - Hardware and software I^2C [8] slaves and masters
  - Full-speed USB 2.0
  - Up to four full-duplex universal asynchronous receiver/transmitters (UARTs), SPI master and slave, and wireless

PSoC Designer supports the entire library of PSoC 1 devices and runs on Windows XP, Windows Vista, and Windows 7.

PSoC Designer Software Subsystems

Design Entry

In the chip-level view, choose a base device to work with. Then select different onboard analog and digital components that use the PSoC blocks, which are called user modules. Examples of user modules are ADCs, DACs, amplifiers, and filters. Configure the user modules for your chosen application and connect them to each other and to the proper pins. Then generate your project. This prepopulates your project with APIs and libraries that you can use to program your application.

The tool also supports easy development of multiple configurations and dynamic reconfiguration. Dynamic reconfiguration makes it possible to change configurations at run time. In essence, this allows you to use more than 100 percent of PSoC's resources for an application.

Code Generation Tools

The code generation tools work seamlessly within the PSoC Designer interface and have been tested with a full range of debugging tools. You can develop your design in C, assembly, or a combination of the two.

Assemblers. The assemblers allow you to merge assembly code seamlessly with C code. Link libraries automatically use absolute addressing or are compiled in relative mode, and are linked with other software modules to get absolute addressing.

C Language Compilers. C language compilers are available that support the PSoC family of devices. The products allow you to create complete C programs for the PSoC family devices. The optimizing C compilers provide all of the features of C, tailored to the PSoC architecture. They come complete with embedded libraries providing port and bus operations, standard keypad and display support, and extended math functionality.

Debugger

PSoC Designer has a debug environment that provides hardware in-circuit emulation, allowing you to test the program in a physical system while providing an internal view of the PSoC device. Debugger commands allow you to read and program and read and write data memory, and read and write I/O registers. You can read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows you to create a trace buffer of registers and memory locations of interest.

Online Help System

The online help system displays online, context-sensitive help. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an online support Forum to aid the designer.

In-Circuit Emulator

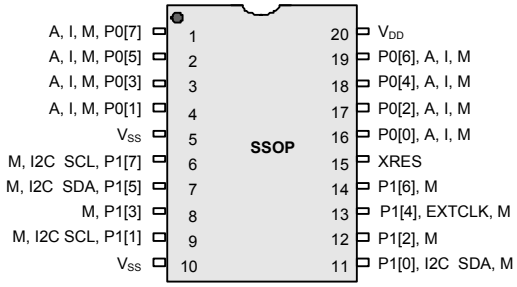
A low-cost, high-functionality in-circuit emulator (ICE) is available for development support. This hardware can program single devices.

The emulator consists of a base unit that connects to the PC using a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full-speed (24 MHz) operation.

Note
8. Errata:The I^2C block exhibits occasional data and bus corruption errors when the I^2C master initiates transactions while the device is transitioning in to or out of sleep mode.

20-pin Part Pinout

Figure 5. CY8C21334 20-pin PSoC Device



CY8C21334 20-pin SSOP Pin Definitions

Pin No.	Type		Name	Description
	Digital	Analog		
1	I/O	I, M	P0[7]	Analog column mux input
2	I/O	I, M	P0[5]	Analog column mux input
3	I/O	I, M	P0[3]	Analog column mux input, integrating input
4	I/O	I, M	P0[1]	Analog column mux input, integrating input
5	Power		V_{SS}	Ground connection [11]
6	I/O	M	P1[7]	I^2C SCL
7	I/O	M	P1[5]	I^2C SDA
8	I/O	M	P1[3]	
9	I/O	M	P1[1]	I^2C SCL, ISSP-SCLK[12]
10	Power		V_{SS}	Ground connection [11]
11	I/O	M	P1[0]	I^2C SDA, ISSP-SDATA[12]
12	I/O	M	P1[2]	
13	I/O	M	P1[4]	Optional external clock input (EXTCLK)
14	I/O	M	P1[6]	
15	Input		XRES	Active high external reset with internal pull-down
16	I/O	I, M	P0[0]	Analog column mux input
17	I/O	I, M	P0[2]	Analog column mux input
18	I/O	I, M	P0[4]	Analog column mux input
19	I/O	I, M	P0[6]	Analog column mux input
20	Power		V_{DD}	Supply voltage

LEGEND A = Analog, I = Input, O = Output, and M = Analog Mux Input.

Notes
11. All V_{SS} pins should be brought out to one common GND plane.
12. These are the ISSP pins, which are not High Z at POR. See the *PSoC Technical Reference Manual* for details.

32-pin Part Pinout

Figure 7. CY8C21434 32-pin PSoC Device

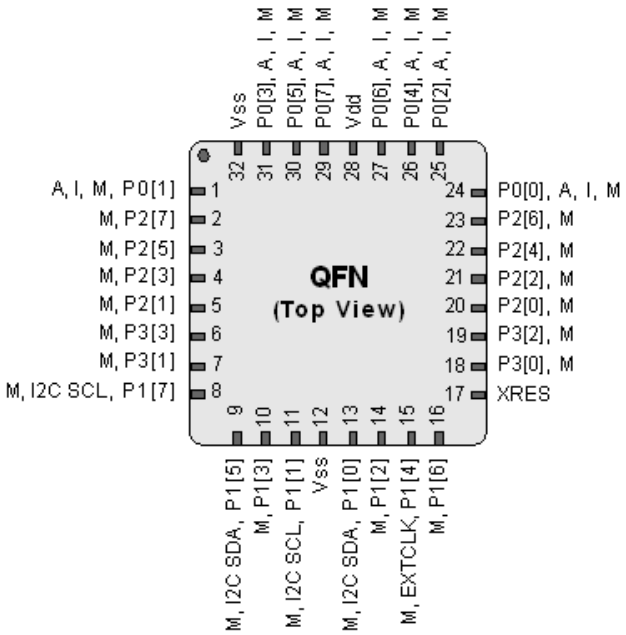


Figure 7. CY8C21634 32-pin PSoC Device

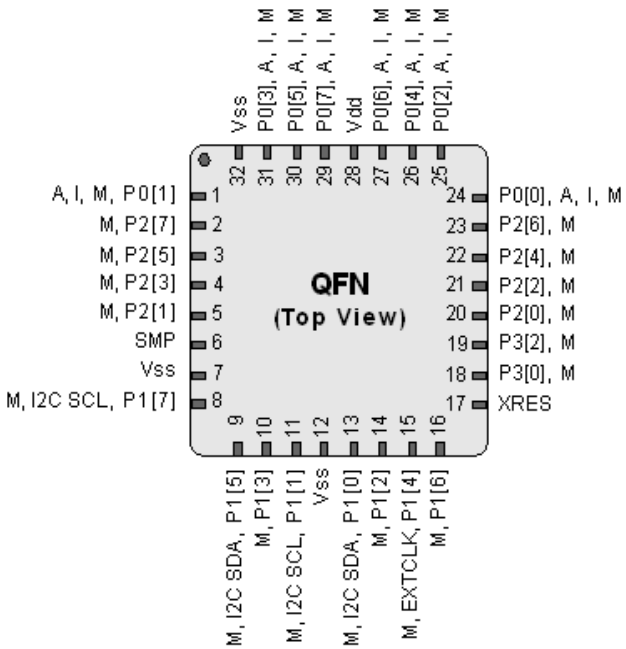


Figure 8. CY8C21434 32-pin Sawn PSoC Device Sawn

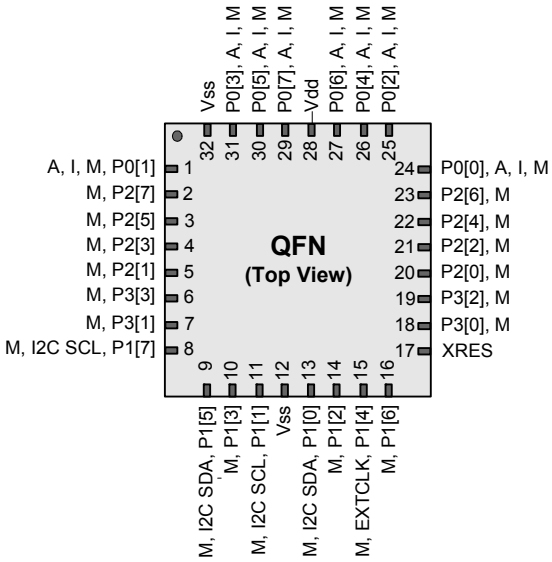
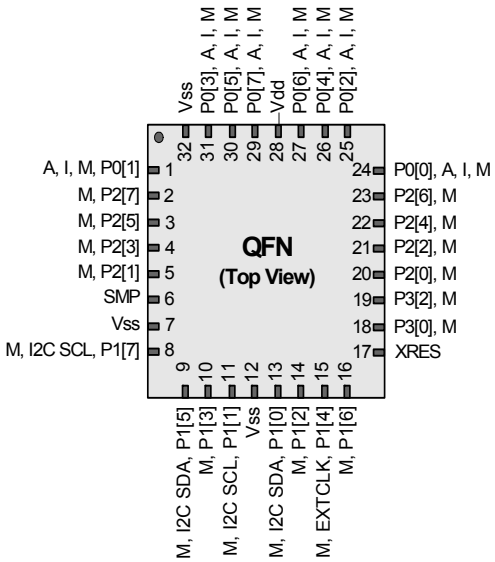


Figure 9. CY8C21634 32-pin Sawn PSoC Device Sawn



CY8C21001 56-pin SSOP Pin Definitions (continued)

Pin No.	Type		Pin Name	Description
	Digital	Analog		
20	I/O		P3[1]	
21			NC	No connection. Pin must be left floating
22			NC	No connection. Pin must be left floating
23	I/O		P1[7]	I^2C SCL
24	I/O		P1[5]	I^2C SDA
25			NC	No connection. Pin must be left floating
26	I/O		P1[3]	I_{FMTEST}
27	I/O		P1[1]	I^2C SCL, ISSP-SCLK[19]
28	Power		V_{SS}	Ground connection [18]
29			NC	No connection. Pin must be left floating
30			NC	No connection. Pin must be left floating
31	I/O		P1[0]	I^2C SDA, ISSP-SDATA[19]
32	I/O		P1[2]	V_{FMTEST}
33	I/O		P1[4]	Optional external clock input (EXTCLK)
34	I/O		P1[6]	
35			NC	No connection. Pin must be left floating
36			NC	No connection. Pin must be left floating
37			NC	No connection. Pin must be left floating
38			NC	No connection. Pin must be left floating
39			NC	No connection. Pin must be left floating
40			NC	No connection. Pin must be left floating
41	Input		XRES	Active high external reset with internal pull-down
42	OCD		HCLK	OCD high-speed clock output
43	OCD		CCLK	OCD CPU clock output
44	I/O		P3[0]	
45	I/O		P3[2]	
46			NC	No connection. Pin must be left floating
47			NC	No connection. Pin must be left floating
48	I/O	I	P2[0]	
49	I/O	I	P2[2]	
50	I/O		P2[4]	
51	I/O		P2[6]	
52	I/O	I	P0[0]	Analog column mux input
53	I/O	I	P0[2]	Analog column mux input and column output
54	I/O	I	P0[4]	Analog column mux input and column output
55	I/O	I	P0[6]	Analog column mux input
56	Power		V_{DD}	Supply voltage

LEGEND: A = Analog, I = Input, O = Output, and OCD = On-Chip Debug.

Notes
18. All V_{SS} pins should be brought out to one common GND plane.
19. These are the ISSP pins, which are not High Z at POR. See the *PSoC Technical Reference Manual* for details.

Table 4. Register Map 1 Table: Configuration Space

Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access
PRT0DM0	00	RW		40		ASE10CR0	80	RW		C0	
PRT0DM1	01	RW		41			81			C1	
PRT0IC0	02	RW		42			82			C2	
PRT0IC1	03	RW		43			83			C3	
PRT1DM0	04	RW		44		ASE11CR0	84	RW		C4	
PRT1DM1	05	RW		45			85			C5	
PRT1IC0	06	RW		46			86			C6	
PRT1IC1	07	RW		47			87			C7	
PRT2DM0	08	RW		48			88			C8	
PRT2DM1	09	RW		49			89			C9	
PRT2IC0	0A	RW		4A			8A			CA	
PRT2IC1	0B	RW		4B			8B			CB	
PRT3DM0	0C	RW		4C			8C			CC	
PRT3DM1	0D	RW		4D			8D			CD	
PRT3IC0	0E	RW		4E			8E			CE	
PRT3IC1	0F	RW		4F			8F			CF	
	10			50			90		GDI_O_IN	D0	RW
	11			51			91		GDI_E_IN	D1	RW
	12			52			92		GDI_O_OU	D2	RW
	13			53			93		GDI_E_OU	D3	RW
	14			54			94			D4	
	15			55			95			D5	
	16			56			96			D6	
	17			57			97			D7	
	18			58			98		MUX_CR0	D8	RW
	19			59			99		MUX_CR1	D9	RW
	1A			5A			9A		MUX_CR2	DA	RW
	1B			5B			9B		MUX_CR3	DB	RW
	1C			5C			9C			DC	
	1D			5D			9D		OSC_GO_EN	DD	RW
	1E			5E			9E		OSC_CR4	DE	RW
	1F			5F			9F		OSC_CR3	DF	RW
DBB00FN	20	RW	CLK_CR0	60	RW		A0		OSC_CR0	E0	RW
DBB00IN	21	RW	CLK_CR1	61	RW		A1		OSC_CR1	E1	RW
DBB00OU	22	RW	ABF_CR0	62	RW		A2		OSC_CR2	E2	RW
	23		AMD_CR0	63	RW		A3		VLT_CR	E3	RW
DBB01FN	24	RW	CMP_GO_EN	64	RW		A4		VLT_CMP	E4	R
DBB01IN	25	RW		65			A5		ADC0_TR	E5	RW
DBB01OU	26	RW	AMD_CR1	66	RW		A6		ADC1_TR	E6	RW
	27		ALT_CR0	67	RW		A7			E7	
DCB02FN	28	RW		68			A8		IMO_TR	E8	W
DCB02IN	29	RW		69			A9		ILO_TR	E9	W
DCB02OU	2A	RW		6A			AA		BDG_TR	EA	RW
	2B		CLK_CR3	6B	RW		AB		ECO_TR	EB	W
DCB03FN	2C	RW	TMP_DR0	6C	RW		AC			EC	
DCB03IN	2D	RW	TMP_DR1	6D	RW		AD			ED	
DCB03OU	2E	RW	TMP_DR2	6E	RW		AE			EE	
	2F		TMP_DR3	6F	RW		AF			EF	
	30			70		RDI0RI	B0	RW		F0	
	31			71		RDI0SYN	B1	RW		F1	
	32		ACE00CR1	72	RW	RDI0IS	B2	RW		F2	
	33		ACE00CR2	73	RW	RDI0LT0	B3	RW		F3	
	34			74		RDI0LT1	B4	RW		F4	
	35			75		RDI0RO0	B5	RW		F5	
	36		ACE01CR1	76	RW	RDI0RO1	B6	RW		F6	
	37		ACE01CR2	77	RW		B7		CPU_F	F7	RL
	38			78			B8			F8	
	39			79			B9			F9	
	3A			7A			BA		FLS_PR1	FA	RW
	3B			7B			BB			FB	
	3C			7C			BC			FC	
	3D			7D			BD		DAC_CR	FD	RW
	3E			7E			BE		CPU_SCR1	FE	#
	3F			7F			BF		CPU_SCR0	FF	#

Blank fields are reserved and must not be accessed.

Access is bit specific.

Absolute Maximum Ratings

Symbol	Description	Min	Typ	Max	Units	Notes
T_{STG}	Storage temperature	–55	25	+100	°C	Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 65 °C degrade reliability.
$T_{BAKETEMP}$	Bake temperature	–	125	See package label	°C	
$t_{BAKETIME}$	Bake time	See package label	–	72	Hours	
T_A	Ambient temperature with power applied	–40	–	+85	°C	
V_{DD}	Supply voltage on V_{DD} relative to V_{SS}	–0.5	–	+6.0	V	
V_{IO}	DC input voltage	V_{SS} – 0.5	–	V_{DD} + 0.5	V	
V_{IOZ}	DC voltage applied to tri-state	V_{SS} – 0.5	–	V_{DD} + 0.5	V	
I_{MIO}	Maximum current into any port pin	–25	–	+50	mA	
ESD	Electrostatic discharge voltage	2000	–	–	V	Human body model ESD.
LU	Latch-up current	–	–	200	mA	

Operating Temperature

Symbol	Description	Min	Typ	Max	Units	Notes
T_A	Ambient temperature	–40	–	+85	°C	
T_J	Junction temperature	–40	–	+100	°C	The temperature rise from ambient to junction is package specific. See Table 29 on page 38. You must limit the power consumption to comply with this requirement.

Table 11. DC Switch Mode Pump (SMP) Specifications (continued)

Symbol	Description	Min	Typ	Max	Units	Notes
E_2	Efficiency	35	80	–	%	For I load = 1mA, V_{PUMP} = 2.55 V, V_{BAT} = 1.3 V, 10 µH inductor, 1 µF capacitor, and Schottky diode
F_{PUMP}	Switching frequency	–	1.3	–	MHz	
DC_{PUMP}	Switching duty cycle	–	50	–	%	

DC Analog Mux Bus Specifications

Table 12 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 12. DC Analog Mux Bus Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
R_{SW}	Switch resistance to common analog bus	–	–	400 800	Ω	V_{DD} ≥ 2.7 V 2.4 V ≤ V_{DD} ≤ 2.7 V
R_{VDD}	Resistance of initialization switch to V_{DD}	–	–	800	Ω	

DC POR and LVD Specifications

Table 13 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 13. DC POR and LVD Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
	V_{DD} value for PPOR trip					V_{DD} must be greater than or equal to 2.5 V during startup, the reset from the XRES pin, or reset from watchdog
V_{PPOR0}	PORLEV[1:0] = 00b	–	2.36	2.40	V	
V_{PPOR1}	PORLEV[1:0] = 01b	–	2.82	2.95	V	
V_{PPOR2}	PORLEV[1:0] = 10b	–	4.55	4.70	V	
	V_{DD} value for LVD trip					
V_{LVD0}	VM[2:0] = 000b	2.40	2.45	2.51[21]	V	
V_{LVD1}	VM[2:0] = 001b	2.85	2.92	2.99[22]	V	
V_{LVD2}	VM[2:0] = 010b	2.95	3.02	3.09	V	
V_{LVD3}	VM[2:0] = 011b	3.06	3.13	3.20	V	
V_{LVD4}	VM[2:0] = 100b	4.37	4.48	4.55	V	
V_{LVD5}	VM[2:0] = 101b	4.50	4.64	4.75	V	
V_{LVD6}	VM[2:0] = 110b	4.62	4.73	4.83	V	
V_{LVD7}	VM[2:0] = 111b	4.71	4.81	4.95	V	
	V_{DD} value for pump trip					
V_{PUMP0}	VM[2:0] = 000b	2.45	2.55	2.62[23]	V	
V_{PUMP1}	VM[2:0] = 001b	2.96	3.02	3.09	V	
V_{PUMP2}	VM[2:0] = 010b	3.03	3.10	3.16	V	
V_{PUMP3}	VM[2:0] = 011b	3.18	3.25	3.32[24]	V	
V_{PUMP4}	VM[2:0] = 100b	4.54	4.64	4.74	V	
V_{PUMP5}	VM[2:0] = 101b	4.62	4.73	4.83	V	
V_{PUMP6}	VM[2:0] = 110b	4.71	4.82	4.92	V	
V_{PUMP7}	VM[2:0] = 111b	4.89	5.00	5.12	V	

Notes
21. Always greater than 50 mV above V_{PPOR} (PORLEV = 00) for falling supply.
22. Always greater than 50 mV above V_{PPOR} (PORLEV = 01) for falling supply.
23. Always greater than 50 mV above V_{LVD0}.
24. Always greater than 50 mV above V_{LVD3}.

AC Electrical Characteristics

AC Chip-Level Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 16. 5-V and 3.3-V AC Chip-Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{IMO24} [28]	IMO frequency for 24 MHz	23.4	24	24.6[29,30]	MHz	Trimmed for 5 V or 3.3 V operation using factory trim values. See Figure 14 on page 20. SLIMO mode = 0
F_{IMO6} [28]	IMO frequency for 6 MHz	5.52	6	6.48 [29,30]	MHz	Trimmed for 5 V or 3.3 V operation using factory trim values. See Figure 14 on page 20. SLIMO mode = 1
F_{CPU1}	CPU frequency (5 V nominal)	0.091	24	24.6[29]	MHz	24 MHz only for SLIMO mode = 0
F_{CPU2}	CPU frequency (3.3 V nominal)	0.091	12	12.3[30]	MHz	SLIMO mode = 0
F_{BLK5}	Digital PSoC block frequency (5 V nominal)	0	48	49.2[29,31]	MHz	Refer to AC Digital Block Specifications on page 29
F_{BLK33}	Digital PSoC block frequency (3.3 V nominal)	0	24	24.6[31]	MHz	
F_{32K1}	ILO frequency	15	32	64	kHz	
F_{32K_U}	ILO untrimmed frequency	5	–	100	kHz	After a reset and before the M8C starts to run, the ILO is not trimmed. See the system resets section of the *PSoC Technical Reference Manual* for details on this timing
t_{XRST}	External reset pulse width	10	–	–	µs	
DC24M	24 MHz duty cycle	40	50	60	%	
DC_{ILO}	ILO duty cycle	20	50	80	%	
Step24M	24 MHz trim step size	–	50	–	kHz	
Fout48M	48 MHz output frequency	46.8	48.0	49.2[29,30]	MHz	Trimmed. Using factory trim values
F_{MAX}	Maximum frequency of signal on row input or row output.	–	–	12.3	MHz	
SR_{POWER_UP}	Power supply slew rate	–	–	250	V/ms	V_{DD} slew rate during power-up
$t_{POWERUP}$	Time from end of POR to CPU executing code	–	16	100	ms	Power-up from 0 V. See the System Resets section of the *PSoC Technical Reference Manual*
t_{jit_IMO}	24-MHz IMO cycle-to-cycle jitter (RMS)[32]	–	200	700	ps	
	24-MHz IMO long term N cycle-to-cycle jitter (RMS)[32]	–	300	900	ps	N = 32
	24-MHz IMO period jitter (RMS)[32]	–	100	400	ps	

Notes
28. Errata: The worst case IMO frequency deviation when operated below 0 °C and above +70 °C and within the upper and lower datasheet temperature range is ±5%.
29. 4.75 V < V_{DD} < 5.25 V.
30. 3.0 V < V_{DD} < 3.6 V. See application note AN2012 “Adjusting PSoC Microcontroller Trims for Dual Voltage-Range Operation” for information on trimming for operation at 3.3 V.
31. See the individual user module datasheets for information on maximum frequencies for user modules.
32. Refer to Cypress Jitter Specifications Application Note AN5054 “Understanding Datasheet Jitter Specifications for Cypress Timing Products” at www.cypress.com under Application Notes for more information.

Table 17. 2.7-V AC Chip-Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{IMO12} [33]	IMO frequency for 12 MHz	11.04	12	12.96 [34, 35]	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 14 on page 20. SLIMO mode = 1
F_{IMO6} [33]	IMO frequency for 6 MHz	5.52	6	6.48 [34, 35]	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 14 on page 20. SLIMO mode = 1
F_{CPU1}	CPU frequency (2.7 V nominal)	0.093	3	3.15[34]	MHz	12 MHz only for SLIMO mode = 0
F_{BLK27}	Digital PSoC block frequency (2.7 V nominal)	0	12	12.5[34,35]	MHz	Refer to AC Digital Block Specifications on page 29
F_{32K1}	ILO frequency	8	32	96	kHz	
F_{32K_U}	ILO untrimmed frequency	5	–	100	kHz	After a reset and before the M8C starts to run, the ILO is not trimmed. See the System Resets section of the *PSoC Technical Reference Manual* for details on this timing
t_{XRST}	External reset pulse width	10	–	–	µs	
DC_{ILO}	IILO duty cycle	20	50	80	%	
F_{MAX}	Maximum frequency of signal on row input or row output.	–	–	12.3	MHz	
SR_{POWER_UP}	Power supply slew rate	–	–	250	V/ms	V_{DD} slew rate during power-up
$t_{POWERUP}$	Time from end of POR to CPU executing code	–	16	100	ms	Power-up from 0 V. See the System Resets section of the *PSoC Technical Reference Manual*.
t_{jit_IMO}	12 MHz IMO cycle-to-cycle jitter (RMS)[36]	–	400	1000	ps	
	12 MHz IMO long term N cycle-to-cycle jitter (RMS)[36]	–	600	1300	ps	N = 32
	12 MHz IMO period jitter (RMS)[36]	–	100	500	ps	

Notes
33. Errata: The worst case IMO frequency deviation when operated below 0 °C and above +70 °C and within the upper and lower datasheet temperature range is ±5%.
34. 2.4 V < V_{DD} < 3.0 V.
35. See Application Note AN2012 “Adjusting PSoC Microcontroller Trims for Dual Voltage-Range Operation” available at http://www.cypress.com for information on maximum frequency for user modules.
36. Refer to Cypress Jitter Specifications Application Note AN5054 “Understanding Datasheet Jitter Specifications for Cypress Timing Products” at www.cypress.com under Application Notes for more information.

AC General Purpose I/O Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

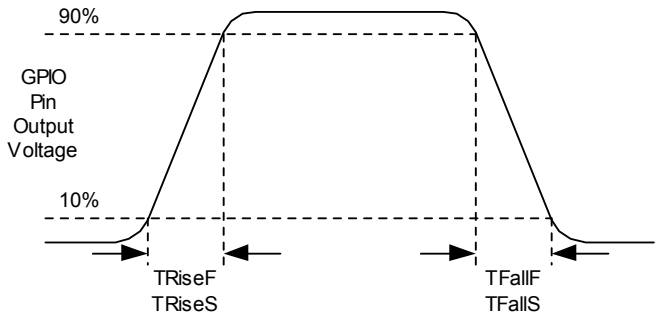
Table 18. 5-V and 3.3-V AC GPIO Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{GPIO}	GPIO operating frequency	0	–	12	MHz	Normal strong mode
TRiseF	Rise time, normal strong mode, Cload = 50 pF	3	–	18	ns	V_{DD} = 4.5 to 5.25 V, 10% to 90%
TFallF	Fall time, normal strong mode, Cload = 50 pF	2	–	18	ns	V_{DD} = 4.5 to 5.25 V, 10% to 90%
TRiseS	Rise time, slow strong mode, Cload = 50 pF	7	27	–	ns	V_{DD} = 3 to 5.25 V, 10% to 90%
TFallS	Fall time, slow strong mode, Cload = 50 pF	7	22	–	ns	V_{DD} = 3 to 5.25 V, 10% to 90%

Table 19. 2.7 V AC GPIO Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{GPIO}	GPIO operating frequency	0	–	3	MHz	Normal strong mode
TRiseF	Rise time, normal strong mode, Cload = 50 pF	6	–	50	ns	V_{DD} = 2.4 to 3.0 V, 10% to 90%
TFallF	Fall time, normal strong mode, Cload = 50 pF	6	–	50	ns	V_{DD} = 2.4 to 3.0 V, 10% to 90%
TRiseS	Rise time, slow strong mode, Cload = 50 pF	18	40	120	ns	V_{DD} = 2.4 to 3.0 V, 10% to 90%
TFallS	Fall time, slow strong mode, Cload = 50 pF	18	40	120	ns	V_{DD} = 2.4 to 3.0 V, 10% to 90%

Figure 13. GPIO Timing Diagram



AC Operational Amplifier Specifications

Table 20 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 20. AC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{COMP}	Comparator mode response time, 50 mV overdrive	–	–	100 200	ns ns	V_{DD} ≥ 3.0 V 2.4 V < V_{DD} < 3.0 V

Table 22. 2.7-V AC Digital Block Specifications

Function	Description	Min	Typ	Max	Units	Notes
All functions	Block input clock frequency	–	–	12.7	MHz	2.4 V < V_{DD} < 3.0 V
Timer	Capture pulse width	100[38]	–	–	ns	
	Input clock frequency, with or without capture	–	–	12.7	MHz	
Counter	Enable input pulse width	100	–	–	ns	
	Input clock frequency, no enable input	–	–	12.7	MHz	
	Input clock frequency, enable input	–	–	12.7	MHz	
Dead Band	Kill pulse width:					
	Asynchronous restart mode	20	–	–	ns	
	Synchronous restart mode	100	–	–	ns	
	Disable mode	100	–	–	ns	
	Input clock frequency	–	–	12.7	MHz	
CRCPRS (PRS Mode)	Input clock frequency	–	–	12.7	MHz	
CRCPRS (CRC Mode)	Input clock frequency	–	–	12.7	MHz	
SPIM	Input clock frequency	–	–	6.35	MHz	The SPI serial clock (SCLK) frequency is equal to the input clock frequency divided by 2.
SPIS	Input clock (SCLK) frequency	–	–	4.1	MHz	
	Width of SS_ Negated between transmissions	100	–	–	ns	
Transmitter	Input clock frequency	–	–	12.7	MHz	The baud rate is equal to the input clock frequency divided by 8.
Receiver	Input clock frequency	–	–	12.7	MHz	The baud rate is equal to the input clock frequency divided by 8.

AC External Clock Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, or 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 23. 5-V AC External Clock Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{OSCEXT}	Frequency	0.093	–	24.6	MHz	
–	High period	20.6	–	5300	ns	
–	Low period	20.6	–	–	ns	
–	Power-up IMO to switch	150	–	–	µs	

Note
38. 100 ns minimum input pulse width is based on the input synchronizers running at 12 MHz (84 ns nominal period).

AC Programming Specifications

Table 26 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, or 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 26. AC Programming Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{RSCLK}	Rise time of SCLK	1	–	20	ns	
T_{FSCLK}	Fall time of SCLK	1	–	20	ns	
T_{SSCLK}	Data setup time to falling edge of SCLK	40	–	–	ns	
T_{HSCLK}	Data hold time from falling edge of SCLK	40	–	–	ns	
F_{SCLK}	Frequency of SCLK	0	–	8	MHz	
T_{ERASEB}	Flash erase time (block)	–	10	–	ms	
T_{WRITE}	Flash block write time	–	40	–	ms	
T_{DSCLK}	Data out delay from falling edge of SCLK	–	–	45	ns	3.6 < V_{DD}
T_{DSCLK3}	Data out delay from falling edge of SCLK	–	–	50	ns	3.0 ≤ V_{DD} ≤ 3.6
T_{DSCLK2}	Data out delay from falling edge of SCLK	–	–	70	ns	2.4 ≤ V_{DD} ≤ 3.0
$T_{ERASEALL}$	Flash erase time (Bulk)	–	20	–	ms	Erase all blocks and protection fields at once
$T_{PROGRAM\_HOT}$	Flash block erase + flash block write time	–	–	100[39]	ms	0 °C ≤ Tj ≤ 100 °C
$T_{PROGRAM\_COLD}$	Flash block erase + flash block write time	–	–	200[39]	ms	–40 °C ≤ Tj ≤ 0 °C

AC I^2C [40] Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C ≤ T_A ≤ 85 °C, 3.0 V to 3.6 V and –40 °C ≤ T_A ≤ 85 °C, or 2.4 V to 3.0 V and –40 °C ≤ T_A ≤ 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, or 2.7 V at 25 °C and are for design guidance only.

Table 27. AC Characteristics of the I^2C SDA and SCL Pins for V_{DD} ≥ 3.0 V

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
F_{SCLI2C}	SCL clock frequency	0	100	0	400	kHz
$T_{HDSTAI2C}$	Hold time (repeated) start condition. After this period, the first clock pulse is generated	4.0	–	0.6	–	µs
T_{LOWI2C}	Low period of the SCL clock	4.7	–	1.3	–	µs
$T_{HIGHI2C}$	High period of the SCL clock	4.0	–	0.6	–	µs
$T_{SUSTAI2C}$	Setup time for a repeated start condition	4.7	–	0.6	–	µs
$T_{HDDATI2C}$	Data hold time	0	–	0	–	µs
$T_{SUDATI2C}$	Data setup time	250	–	100[41]	–	ns
$T_{SUSTOI2C}$	Setup time for stop condition	4.0	–	0.6	–	µs
T_{BUFI2C}	Bus free time between a stop and start condition	4.7	–	1.3	–	µs
T_{SPI2C}	Pulse width of spikes suppressed by the input filter.	–	–	0	50	ns

Notes

39. For the full industrial range, the user must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs application note AN2015 (Design Aids - Reading and Writing PSoC® Flash) for more information.
40. Errata: The I^2C block exhibits occasional data and bus corruption errors when the I^2C master initiates transactions while the device is transitioning in to or out of sleep mode.
41. A Fast-Mode I^2C-bus device may be used in a Standard-Mode I^2C-bus system, but it must meet the requirement $T_{SU;DAT}$ ≥ 250 ns. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If the device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line T_{rmax} + $T_{SU;DAT}$ = 1000 + 250 = 1250 ns (according to the Standard-Mode I^2C-bus specification) before the SCL line is released.

Thermal Impedances

Table 29. Thermal Impedances per Package

Package	Typical θ_{JA} [42]	Typical θ_{JC}
16-pin SOIC	123 °C/W	55 °C/W
20-pin SSOP	117 °C/W	41 °C/W
28-pin SSOP	96 °C/W	39 °C/W
32-pin QFN[43] 5 × 5 mm 0.60 Max	27 °C/W	15 °C/W
32-pin QFN[43] 5 × 5 mm 1.00 Max	22 °C/W	12 °C/W
56-pin SSOP	48 °C/W	24 °C/W

Solder Reflow Specifications

Table 30 shows the solder reflow temperature limits that must not be exceeded.

Table 30. Solder Reflow Specifications

Package	Maximum Peak Temperature (T_C)	Maximum Time above T_C – 5 °C
16-pin SOIC	260 °C	30 seconds
20-pin SSOP	260 °C	30 seconds
28-pin SSOP	260 °C	30 seconds
32-pin QFN	260 °C	30 seconds
56-pin SSOP	260 °C	30 seconds

Notes
42. $T_J = T_A + \text{Power} \times \theta_{JA}$
43. To achieve the thermal impedance specified for the QFN package, refer to *Application Note EROS - Design Guidelines for Cypress Quad Flat No Extended Lead (QFN) Packaged Devices* available at http://www.cypress.com.
44. Higher temperatures may be required based on the solder melting point. Typical temperatures for solder are 220 ± 5 °C with Sn-Pb or 245 ± 5 °C with Sn-Ag-Cu paste. Refer to the solder manufacturer specifications.

Ordering Information

Package	Ordering Code	Flash (Bytes)	SRAM (Bytes)	Switch Mode Pump	Temperature Range	Digital Blocks	Analog Blocks	Digital I/O Pins	Analog Inputs	Analog Outputs	XRES Pin
16-Pin (150-Mil) SOIC	CY8C21234-24SXI	8 K	512	Yes	–40 °C to +85 °C	4	4	12	12[47]	0	No
16-Pin (150-Mil) SOIC (Tape and Reel)	CY8C21234-24SXIT	8 K	512	Yes	–40 °C to +85 °C	4	4	12	12[47]	0	No
20-Pin (210-Mil) SSOP	CY8C21334-24PVXI	8 K	512	No	–40 °C to +85 °C	4	4	16	16[47]	0	Yes
20-Pin (210-Mil) SSOP (Tape and Reel)	CY8C21334-24PVXIT	8 K	512	No	–40 °C to +85 °C	4	4	16	16[47]	0	Yes
28-Pin (210-Mil) SSOP	CY8C21534-24PVXI	8 K	512	No	–40 °C to +85 °C	4	4	24	24[47]	0	Yes
28-Pin (210-Mil) SSOP (Tape and Reel)	CY8C21534-24PVXIT	8 K	512	No	–40 °C to +85 °C	4	4	24	24[47]	0	Yes
32-Pin (5 × 5 mm 1.00 max) Sawn QFN	CY8C21434-24LTXI	8 K	512	No	–40 °C to +85 °C	4	4	28	28[47]	0	Yes
32-Pin (5 × 5 mm 1.00 max) Sawn QFN [48] (Tape and Reel)	CY8C21434-24LTXIT	8 K	512	No	–40 °C to +85 °C	4	4	28	28[47]	0	Yes
32-Pin (5 × 5 mm 0.60 max) Thin Sawn QFN	CY8C21434-24LQXI	8 K	512	No	–40 °C to +85 °C	4	4	28	28[47]	0	Yes
32-Pin (5 × 5 mm 0.60 max) Thin Sawn QFN (Tape and Reel)	CY8C21434-24LQXIT	8 K	512	No	–40 °C to +85 °C	4	4	28	28[47]	0	Yes
32-Pin (5 × 5 mm 1.00 max) Sawn QFN [48]	CY8C21634-24LTXI	8 K	512	Yes	–40 °C to +85 °C	4	4	26	26[47]	0	Yes
32-Pin (5 × 5 mm 1.00 max) Sawn QFN [48] (Tape and Reel)	CY8C21634-24LTXIT	8 K	512	Yes	–40 °C to +85 °C	4	4	26	26[47]	0	Yes
56-Pin OCD SSOP	CY8C21001-24PVXI	8 K	512	Yes	–40 °C to +85 °C	4	4	26	26[47]	0	Yes
	CY8C21434-12X14I	Please contact sales office or Field Applications Engineer (FAE) for more information.									

Note For Die sales information, contact a local Cypress sales office or Field Applications Engineer (FAE).

Notes
47. All Digital I/O Pins also connect to the common analog mux.
48. Refer to the section 32-pin Part Pinout on page 12 for pin differences.

Acronyms

Table 32 lists the acronyms that are used in this document.

Table 32. Acronyms Used in this Datasheet

Acronym	Description	Acronym	Description
AC	alternating current	MIPS	million instructions per second
ADC	analog-to-digital converter	OCD	on-chip debug
API	application programming interface	PCB	printed circuit board
CMOS	complementary metal oxide semiconductor	PDIP	plastic dual-in-line package
CPU	central processing unit	PGA	programmable gain amplifier
CRC	cyclic redundancy check	PLL	phase-locked loop
CT	continuous time	POR	power on reset
DAC	digital-to-analog converter	PPOR	precision power on reset
DC	direct current	PRS	pseudo-random sequence
DTMF	dual-tone multi-frequency	PSoC®	Programmable System-on-Chip
ECO	external crystal oscillator	PWM	pulse width modulator
EEPROM	electrically erasable programmable read-only memory	QFN	quad flat no leads
GPIO	general purpose I/O	RTC	real time clock
ICE	in-circuit emulator	SAR	successive approximation
IDE	integrated development environment	SC	switched capacitor
ILO	internal low speed oscillator	SLIMO	slow IMO
IMO	internal main oscillator	SMP	switch-mode pump
I/O	input/output	SOIC	small-outline integrated circuit
IrDA	infrared data association	SPI™	serial peripheral interface
ISSP	in-system serial programming	SRAM	static random access memory
LCD	liquid crystal display	SROM	supervisory read only memory
LED	light-emitting diode	SSOP	shrink small-outline package
LPC	low power comparator	UART	universal asynchronous receiver / transmitter
LVD	low voltage detect	USB	universal serial bus
MAC	multiply-accumulate	WDT	watchdog timer
MCU	microcontroller unit	XRES	external reset

Reference Documents

CY8CPLC20, CY8CLED16P01, CY8C29x66, CY8C27x43, CY8C24x94, CY8C24x23, CY8C24x23A, CY8C22x13, CY8C21x34, CY8C21x23, CY7C64215, CY7C603xx, CY8CNP1xx, and CYWUSB6953 PSoC® Programmable System-on-Chip Technical Reference Manual (TRM) (001-14463)

Design Aids – Reading and Writing PSoC® Flash - AN2015 (001-40459)

Application Notes for Surface Mount Assembly of Amkor's MicroLeadFrame (MLF) Packages – available at http://www.amkor.com.

Document Conventions

Units of Measure

Table 33 lists the units of measures.

Table 33. Units of Measure

Symbol	Unit of Measure	Symbol	Unit of Measure
kB	1024 bytes	µH	micro henry
dB	decibels	µs	microsecond
°C	degree Celsius	ms	millisecond
µF	microfarad	ns	nanosecond
fF	femto farad	ps	picosecond
pF	picofarad	µV	microvolt
kHz	kilohertz	mV	millivolts
MHz	megahertz	mVpp	millivolts peak-to-peak
rt-Hz	root hertz	nV	nano volt
kΩ	kilo ohm	V	volt
Ω	ohm	µW	microwatt
µA	microampere	W	watt
mA	milliampere	mm	millimeter
nA	nano ampere	ppm	parts per million
pA	pico ampere	%	percent
mH	millihenry		

Numeric Conventions

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase ‘h’ (for example, ‘14h’ or ‘3Ah’). Hexadecimal numbers may also be represented by a ‘0x’ prefix, the C coding convention. Binary numbers have an appended lowercase ‘b’ (for example, 01010100b’ or ‘01000011b’). Numbers not indicated by an ‘h’ or ‘b’ are decimals.

Glossary

active high	1. A logic signal having its asserted state as the logic 1 state. 2. A logic signal having the logic 1 state as the higher voltage of the two states.
analog blocks	The basic programmable opamp circuits. These are SC (switched capacitor) and CT (continuous time) blocks. These blocks can be interconnected to provide ADCs, DACs, multi-pole filters, gain stages, and much more.
analog-to-digital (ADC)	A device that changes an analog signal to a digital signal of corresponding magnitude. Typically, an ADC converts a voltage to a digital number. The digital-to-analog (DAC) converter performs the reverse operation.
Application programming interface (API)	A series of software routines that comprise an interface between a computer application and lower level services and functions (for example, user modules and libraries). APIs serve as building blocks for programmers that create software applications.
asynchronous	A signal whose data is acknowledged or acted upon immediately, irrespective of any clock signal.
bandgap reference	A stable voltage reference design that matches the positive temperature coefficient of VT with the negative temperature coefficient of VBE, to produce a zero temperature coefficient (ideally) reference.
bandwidth	1. The frequency range of a message or information processing system measured in hertz. 2. The width of the spectral region over which an amplifier (or absorber) has substantial gain (or loss); it is sometimes represented more specifically as, for example, full width at half maximum.

Glossary (continued)

duty cycle	The relationship of a clock period high time to its low time, expressed as a percent.
emulator	Duplicates (provides an emulation of) the functions of one system with a different system, so that the second system appears to behave like the first system.
External Reset (XRES)	An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.
Flash	An electrically programmable and erasable, non-volatile technology that provides you the programmability and data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power is OFF.
Flash block	The smallest amount of Flash ROM space that may be programmed at one time and the smallest amount of Flash space that may be protected. A Flash block holds 64 bytes.
frequency	The number of cycles or events per unit of time, for a periodic function.
gain	The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually expressed in dB.
I^2C	A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). I2C is an Inter-Integrated Circuit. It is used to connect low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I2C uses only two bi-directional pins, clock and data, both running at +5 V and pulled high with resistors. The bus operates at 100 kbits/second in standard mode and 400 kbits/second in fast mode.
ICE	The in-circuit emulator that allows you to test the project in a hardware environment, while viewing the debugging device activity in a software environment (PSoC Designer).
input/output (I/O)	A device that introduces data into or extracts data from a system.
interrupt	A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed.
interrupt service routine (ISR)	A block of code that normal code execution is diverted to when the M8C receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.
jitter	1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams. 2. The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.
low-voltage detect (LVD)	A circuit that senses Vdd and provides an interrupt to the system when Vdd falls below a selected threshold.
M8C	An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by interfacing to the Flash, SRAM, and register space.
master device	A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in width, the master device is the one that controls the timing for data exchanges between the cascaded devices and an external interface. The controlled device is called the ***slave device.***

CY8C21X34 Errata Summary

The following table defines the errata applicability to available CY8C21X34 family devices. An "X" indicates that the errata pertains to the selected device.

Note Errata items, in the table below, are hyperlinked. Click on any item entry to jump to its description.

Items	Part Number	Silicon Revision	Fix Status
[1.]. Internal Main Oscillator (IMO) Tolerance Deviation at Temperature Extremes	CY8C21X34	A	No fix is currently planned.
[2]. I2C Errors	CY8C21X34	A	No fix is currently planned.

1. Internal Main Oscillator (IMO) Tolerance Deviation at Temperature Extremes

- **Problem Definition**
  Asynchronous Digital Communications Interfaces may fail framing beyond 0 °C to 70 °C. This problem does not affect end-product usage between 0 °C and 70 °C.
- **Parameters Affected**
  The IMO frequency tolerance. The worst case deviation when operated below 0 °C and above +70 °C and within the upper and lower datasheet temperature range is ±5%.
- **Trigger Condition(S)**
  The asynchronous Rx/Tx clock source IMO frequency tolerance may deviate beyond the datasheet limit of ±2.5% when operated beyond the temperature range of 0 °C to +70 °C.
- **Scope of Impact**
  This problem may affect UART, IrDA, and FSK implementations.
- **Workaround**
  Implement a quartz crystal stabilized clock source on at least one end of the asynchronous digital communications interface.
- **Fix Status**
  No fix is currently planned.

2. I^2C Errors

- **Problem Definition**
  The I^2C block exhibits occasional data and bus corruption errors when the I^2C master initiates transactions while the device is transitioning in to or out of sleep mode.
- **Parameters Affected**
  Affects reliability of I^2C communication to device, between I^2C master, and third party I^2C slaves.
- **Trigger Condition(S)**
  Triggered by transitions into and out of the device's sleep mode.
- **Scope of Impact**
  This problem may affect UART, IrDA, and FSK implementations.
- **Workaround**
  Firmware workarounds are available in firmware. Generally the workaround consists of disconnecting the I^2C block from the bus prior to going to sleep modes. I^2C transactions during sleep are supported by a protocol in which the master wakes the device prior to the I^2C transaction
- **Fix Status**
  Will not be fixed.