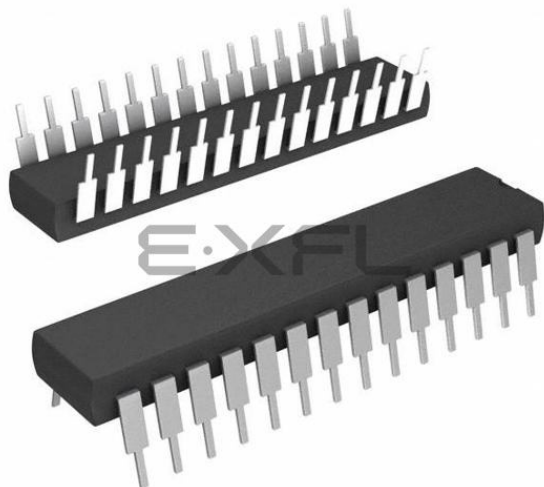




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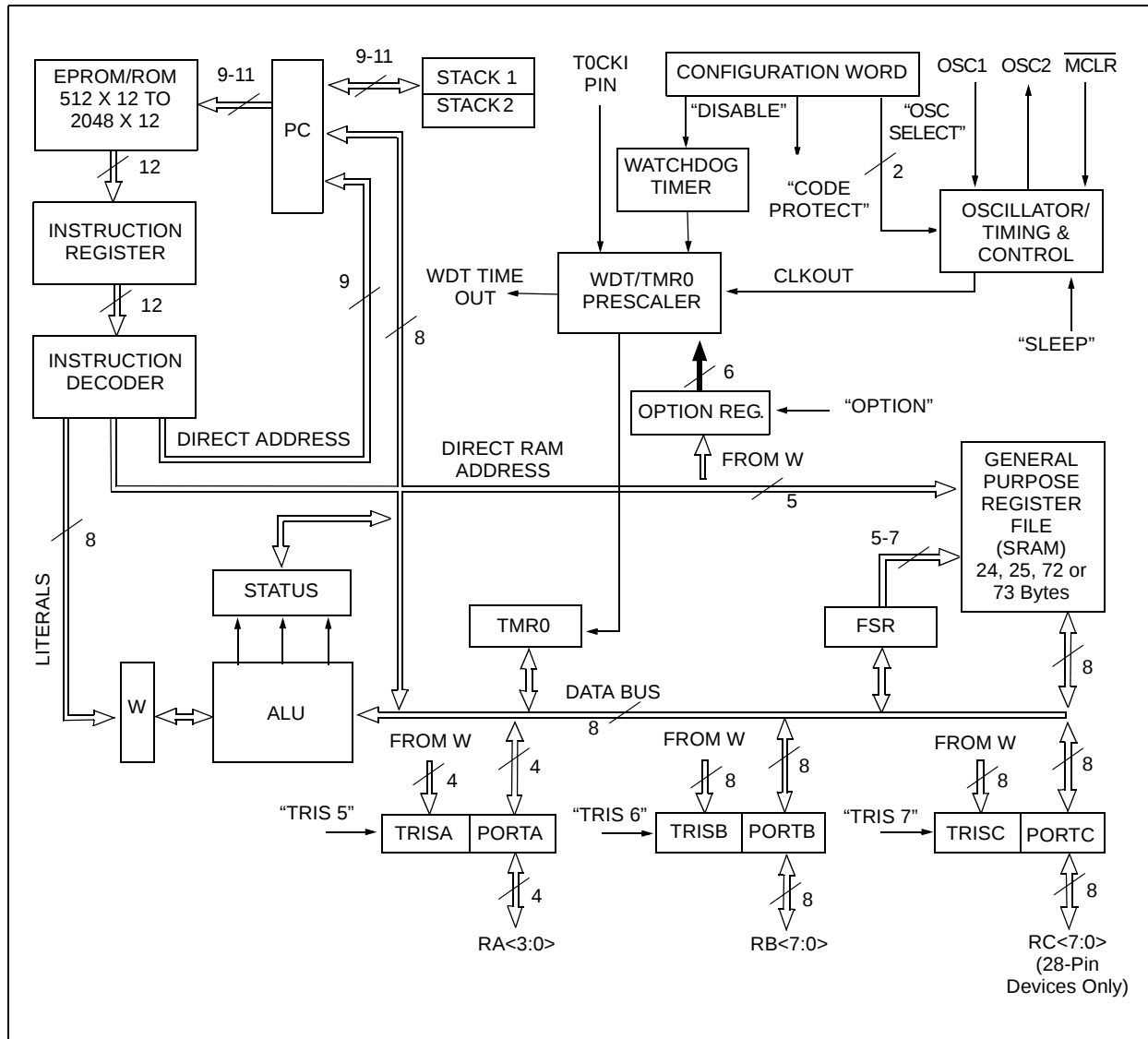
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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	20
Program Memory Size	768B (512 x 12)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	24 x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 6.25V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c55-lp-sp

PIC16C5X

FIGURE 3-1: PIC16C5X SERIES BLOCK DIAGRAM



8.1 Using Timer0 with an External Clock

When an external clock input is used for Timer0, it must meet certain requirements. The external clock requirement is due to internal phase clock (Tosc) synchronization. Also, there is a delay in the actual incrementing of Timer0 after synchronization.

8.1.1 EXTERNAL CLOCK SYNCHRONIZATION

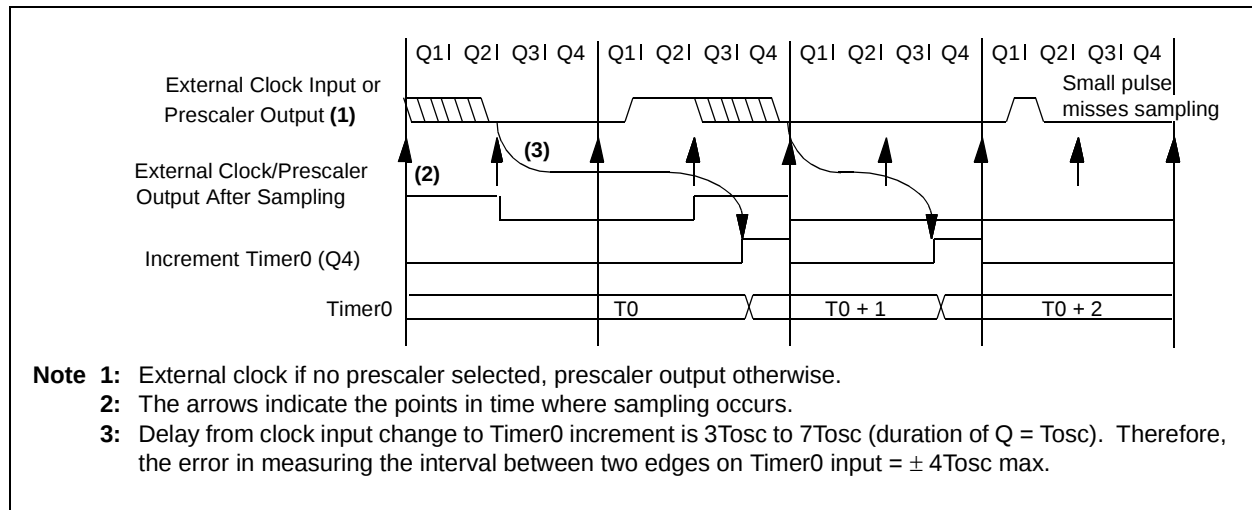
When no prescaler is used, the external clock input is the same as the prescaler output. The synchronization of T0CKI with the internal phase clocks is accomplished by sampling the prescaler output on the Q2 and Q4 cycles of the internal phase clocks (Figure 8-5). Therefore, it is necessary for T0CKI to be high for at least $2T_{osc}$ (and a small RC delay of 20 ns) and low for at least $2T_{osc}$ (and a small RC delay of 20 ns). Refer to the electrical specification of the desired device.

When a prescaler is used, the external clock input is divided by the asynchronous ripple counter-type prescaler so that the prescaler output is symmetrical. For the external clock to meet the sampling requirement, the ripple counter must be taken into account. Therefore, it is necessary for T0CKI to have a period of at least $4T_{osc}$ (and a small RC delay of 40 ns) divided by the prescaler value. The only requirement on T0CKI high and low time is that they do not violate the minimum pulse width requirement of 10 ns. Refer to parameters 40, 41 and 42 in the electrical specification of the desired device.

8.1.2 TIMER0 INCREMENT DELAY

Since the prescaler output is synchronized with the internal clocks, there is a small delay from the time the external clock edge occurs to the time the Timer0 module is actually incremented. Figure 8-5 shows the delay from the external clock edge to the timer incrementing.

FIGURE 8-5: TIMER0 TIMING WITH EXTERNAL CLOCK



8.2 Prescaler

An 8-bit counter is available as a prescaler for the Timer0 module, or as a postscaler for the Watchdog Timer (WDT), respectively (Section 9.2.1). For simplicity, this counter is being referred to as “prescaler” throughout this data sheet. Note that the prescaler may be used by either the Timer0 module or the WDT, but not both. Thus, a prescaler assignment for the Timer0 module means that there is no prescaler for the WDT, and vice-versa.

The PSA and PS<2:0> bits (OPTION<3:0>) determine prescaler assignment and prescale ratio.

When assigned to the Timer0 module, all instructions writing to the TMR0 register (e.g., CLRF 1, MOVWF 1, BSF 1,x, etc.) will clear the prescaler. When assigned to WDT, a CLRWDT instruction will clear the prescaler along with the WDT. The prescaler is neither readable nor writable. On a RESET, the prescaler contains all '0's.

8.2.1 SWITCHING PRESCALER ASSIGNMENT

The prescaler assignment is fully under software control (i.e., it can be changed “on the fly” during program execution). To avoid an unintended device RESET, the following instruction sequence (Example 8-1) must be executed when changing the prescaler assignment from Timer0 to the WDT.

EXAMPLE 8-1: CHANGING PRESCALER (TIMER0→WDT)

```
CLRWDT          ;Clear WDT
CLRF    TMR0     ;Clear TMR0 & Prescaler
MOVLW  B'00xx1111' ;Last 3 instructions in
                    this example
OPTION          ;are required only if
                ;desired
CLRWDT          ;PS<2:0> are 000 or
                ;001
MOVLW  B'00xx1xxx' ;Set Prescaler to
OPTION          ;desired WDT rate
```

To change prescaler from the WDT to the Timer0 module, use the sequence shown in Example 8-2. This sequence must be used even if the WDT is disabled. A CLRWDT instruction should be executed before switching the prescaler.

EXAMPLE 8-2: CHANGING PRESCALER (WDT→TIMER0)

```
CLRWDT          ;Clear WDT and
                ;prescaler
MOVLW  B'xxxx0xxx' ;Select TMR0, new
                    ;prescale value and
                    ;clock source
OPTION
```

PIC16C5X

XORLW Exclusive OR literal with W

Syntax: `[label] XORLW k`

Operands: $0 \leq k \leq 255$

Operation: $(W) .XOR. k \rightarrow (W)$

Status Affected: Z

Encoding:

1111	kkkk	kkkk
------	------	------

Description: The contents of the W register are XOR'ed with the eight bit literal 'k'. The result is placed in the W register.

Words: 1

Cycles: 1

Example: `XORLW 0xAF`

Before Instruction

W = 0xB5

After Instruction

W = 0x1A

XORWF Exclusive OR W with f

Syntax: `[label] XORWF f,d`

Operands: $0 \leq f \leq 31$
 $d \in [0,1]$

Operation: $(W) .XOR. (f) \rightarrow (dest)$

Status Affected: Z

Encoding:

0001	10df	ffff
------	------	------

Description: Exclusive OR the contents of the W register with register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is 1 the result is stored back in register 'f'.

Words: 1

Cycles: 1

Example `XORWF REG, 1`

Before Instruction

REG = 0xAF

W = 0xB5

After Instruction

REG = 0x1A

W = 0xB5

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NOTES:

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12.5 DC Characteristics: PIC16C54/55/56/57-RCE, XTE, 10E, HSE, LPE (Extended)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for extended				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D030	V_{IL}	Input Low Voltage					
		I/O ports	V_{SS}	—	$0.15 V_{DD}$	V	Pin at hi-impedance PIC16C5X-RC only ⁽³⁾ PIC16C5X-XT, 10, HS, LP
		MCLR (Schmitt Trigger)	V_{SS}	—	$0.15 V_{DD}$	V	
		T0CKI (Schmitt Trigger)	V_{SS}	—	$0.15 V_{DD}$	V	
		OSC1 (Schmitt Trigger)	V_{SS}	—	$0.15 V_{DD}$	V	
		OSC1 (Schmitt Trigger)	V_{SS}	—	$0.3 V_{DD}$	V	
D040	V_{IH}	Input High Voltage					
		I/O ports	$0.45 V_{DD}$	—	V_{DD}	V	For all V_{DD} ⁽⁴⁾ $4.0\text{V} < V_{DD} \leq 5.5\text{V}$ ⁽⁴⁾ $V_{DD} > 5.5\text{V}$
		I/O ports	2.0	—	V_{DD}	V	
		I/O ports	$0.36 V_{DD}$	—	V_{DD}	V	
		MCLR (Schmitt Trigger)	$0.85 V_{DD}$	—	V_{DD}	V	
		T0CKI (Schmitt Trigger)	$0.85 V_{DD}$	—	V_{DD}	V	PIC16C5X-RC only ⁽³⁾ PIC16C5X-XT, 10, HS, LP
		OSC1 (Schmitt Trigger)	$0.85 V_{DD}$	—	V_{DD}	V	
D050	V_{HYS}	Hysteresis of Schmitt Trigger inputs	$0.15 V_{DD}^*$	—	—	V	
D060	I_{IL}	Input Leakage Current ^(1,2)					For $V_{DD} \leq 5.5\text{V}$: $V_{SS} \leq V_{PIN} \leq V_{DD}$, pin at hi-impedance $V_{PIN} = V_{SS} + 0.25\text{V}$ $V_{PIN} = V_{DD}$ $V_{SS} \leq V_{PIN} \leq V_{DD}$ $V_{SS} \leq V_{PIN} \leq V_{DD}$, PIC16C5X-XT, 10, HS, LP
		I/O ports	–1	0.5	+1	μA	
		MCLR	–5	—	—	μA	
		MCLR	—	0.5	+5	μA	
		T0CKI	–3	0.5	+3	μA	
D080	V_{OL}	Output Low Voltage					
		I/O ports	—	—	0.6	V	$I_{OL} = 8.7\text{ mA}$, $V_{DD} = 4.5\text{V}$ $I_{OL} = 1.6\text{ mA}$, $V_{DD} = 4.5\text{V}$, PIC16C5X-RC
D090	V_{OH}	Output High Voltage ⁽²⁾					
		I/O ports	$V_{DD} - 0.7$	—	—	V	$I_{OH} = -5.4\text{ mA}$, $V_{DD} = 4.5\text{V}$ $I_{OH} = -1.0\text{ mA}$, $V_{DD} = 4.5\text{V}$, PIC16C5X-RC
D090	V_{OH}	OSC2/CLKOUT	$V_{DD} - 0.7$	—	—	V	

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C . This data is for design guidance only and is not tested.

Note 1: The leakage current on the $\overline{\text{MCLR}}/\text{VPP}$ pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltage.

2: Negative current is defined as coming out of the pin.

3: For PIC16C5X-RC devices, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC16C5X be driven with external clock in RC mode.

4: The user may use the better of the two specifications.

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13.2 DC Characteristics: PIC16CR54A-04E, 10E, 20E (Extended)

PIC16CR54A-04E, 10E, 20E (Extended)			Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for extended				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D001	VDD	Supply Voltage RC, XT and LP modes HS mode	3.25 4.5	— —	6.0 5.5	V V	
D002	VDR	RAM Data Retention Voltage ⁽¹⁾	—	1.5*	—	V	Device in SLEEP mode
D003	VPOR	VDD Start Voltage to ensure Power-on Reset	—	VSS	—	V	See Section 5.1 for details on Power-on Reset
D004	SVDD	VDD Rise Rate to ensure Power-on Reset	0.05*	—	—	V/ms	See Section 5.1 for details on Power-on Reset
D010	IDD	Supply Current ⁽²⁾ RC ⁽³⁾ and XT modes HS mode HS mode	— — —	1.8 4.8 9.0	3.3 10 20	mA mA mA	FOSC = 4.0 MHz, VDD = 5.5V FOSC = 10 MHz, VDD = 5.5V FOSC = 16 MHz, VDD = 5.5V
D020	IPD	Power-down Current ⁽²⁾	— —	5.0 0.8	22 18	μA μA	VDD = 3.25V, WDT enabled VDD = 3.25V, WDT disabled

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

Note 1: This is the limit to which VDD can be lowered in SLEEP mode without losing RAM data.

2: The supply current is mainly a function of the operating voltage and frequency. Other factors such as bus loading, oscillator type, bus rate, internal code execution pattern and temperature also have an impact on the current consumption.

a) The test conditions for all IDD measurements in active Operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tristated, pulled to VSS, T0CKI = VDD, MCLR = VDD; WDT enabled/disabled as specified.

b) For standby current measurements, the conditions are the same, except that the device is in SLEEP mode. The power-down current in SLEEP mode does not depend on the oscillator type.

3: Does not include current through REXT. The current through the resistor can be estimated by the formula: $I_R = V_{DD}/2R_{EXT}$ (mA) with REXT in kΩ.

14.0 DEVICE CHARACTERIZATION - PIC16C54A

The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

“Typical” represents the mean of the distribution at 25°C. “Maximum” or “minimum” represents (mean + 3 σ) or (mean – 3 σ) respectively, where σ is a standard deviation, over the whole temperature range.

FIGURE 14-1: TYPICAL RC OSCILLATOR FREQUENCY vs. TEMPERATURE

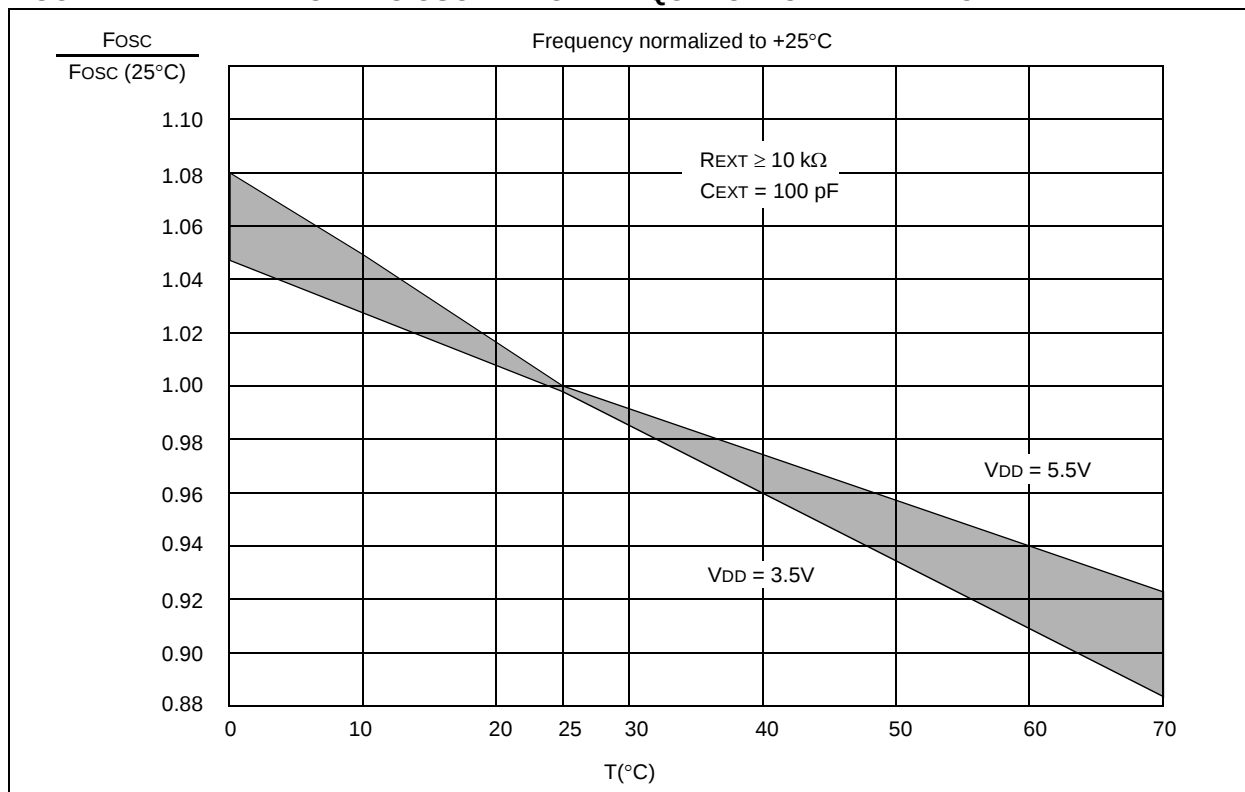


TABLE 14-1: RC OSCILLATOR FREQUENCIES

C_{EXT}	R_{EXT}	Average F_{osc} @ 5 V, 25°C	
20 pF	3.3K	5 MHz	± 27%
	5K	3.8 MHz	± 21%
	10K	2.2 MHz	± 21%
	100K	262 kHz	± 31%
100 pF	3.3K	1.6 MHz	± 13%
	5K	1.2 MHz	± 13%
	10K	684 kHz	± 18%
	100K	71 kHz	± 25%
300 pF	3.3K	660 kHz	± 10%
	5.0K	484 kHz	± 14%
	10K	267 kHz	± 15%
	100K	29 kHz	± 19%

The frequencies are measured on DIP packages.

The percentage variation indicated here is part-to-part variation due to normal process distribution. The variation indicated is ± 3 standard deviations from the average value for $V_{DD} = 5\text{V}$.

PIC16C5X

FIGURE 14-11: V_{TH} (INPUT THRESHOLD VOLTAGE) OF OSC1 INPUT (XT, HS, AND LP MODES) vs. V_{DD}

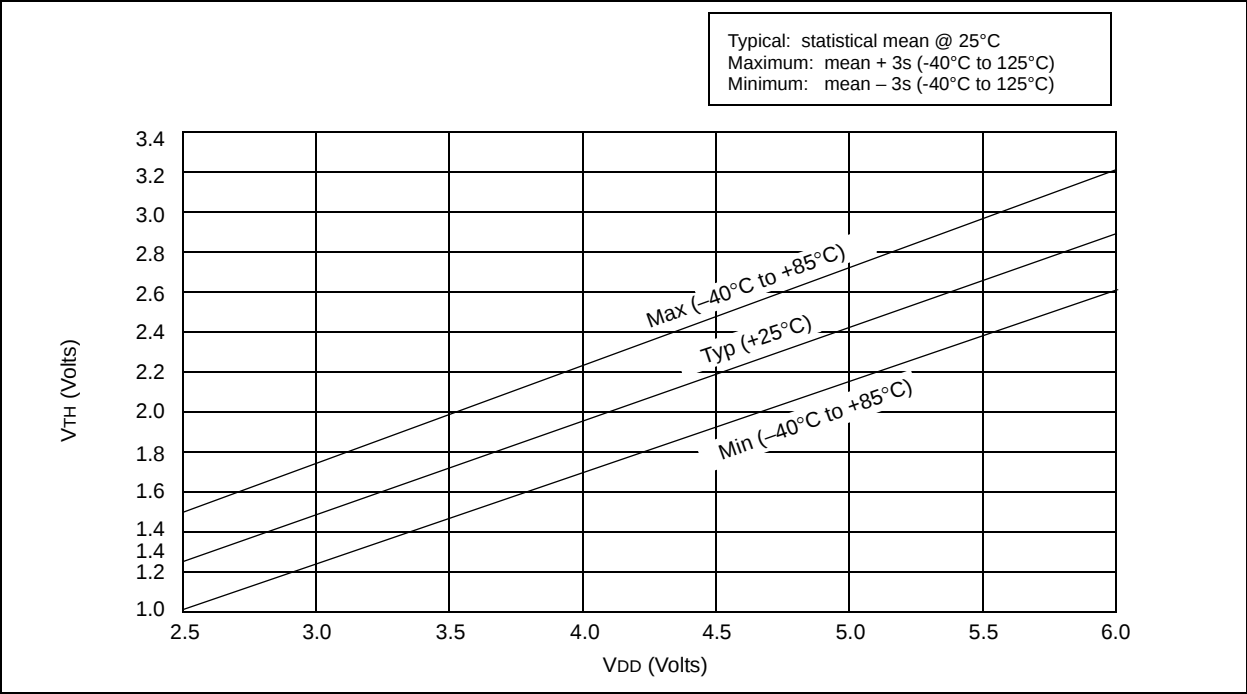


FIGURE 14-12: TYPICAL I_{DD} VS. FREQUENCY (EXTERNAL CLOCK, 25°C)

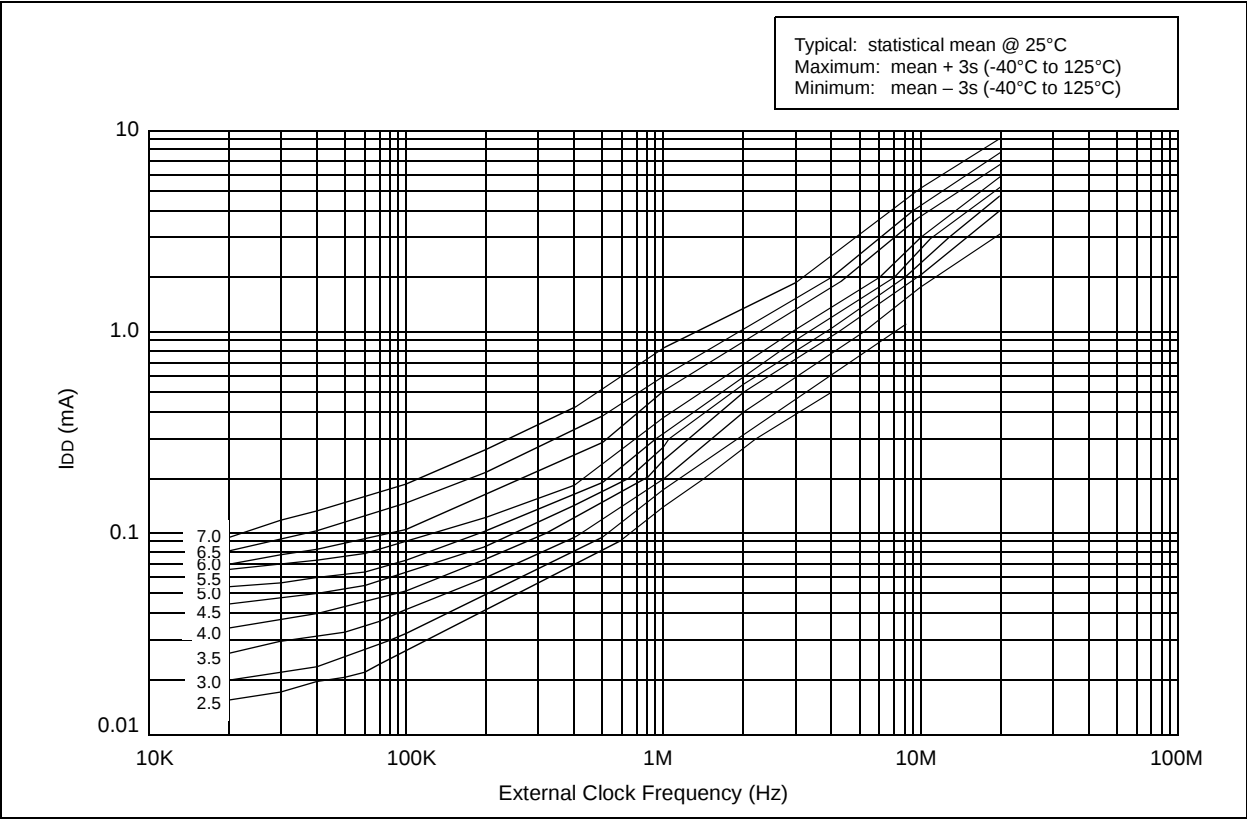


FIGURE 14-15: WDT TIMER TIME-OUT PERIOD vs. VDD⁽¹⁾

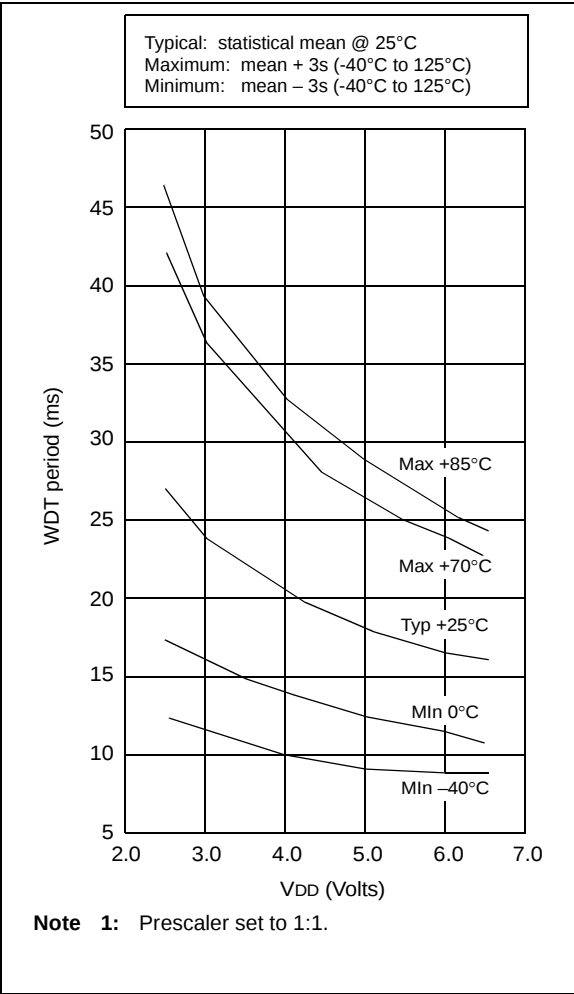
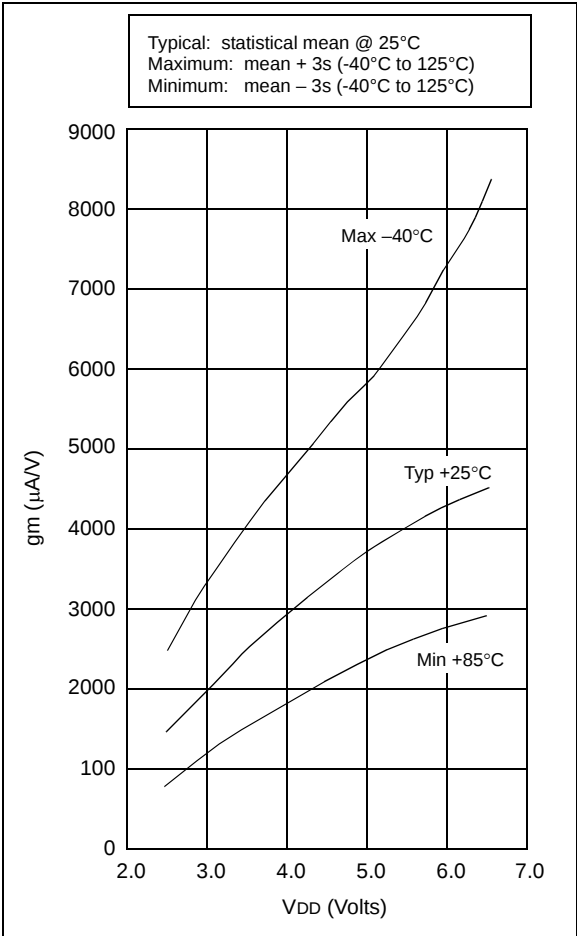


FIGURE 14-16: TRANSCONDUCTANCE (gm) OF HS OSCILLATOR vs. VDD



PIC16C5X

15.2 DC Characteristics: PIC16C54A-04E, 10E, 20E (Extended) PIC16LC54A-04E (Extended)

PIC16LC54A-04E (Extended)		Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for extended					
PIC16C54A-04E, 10E, 20E (Extended)		Standard Operating Conditions (unless otherwise specified) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for extended					
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D001	VDD	Supply Voltage					
		PIC16LC54A	3.0 2.5	— —	6.25 6.25	V V	XT and RC modes LP mode
D001A		PIC16C54A	3.5 4.5	— —	5.5 5.5	V V	RC and XT modes HS mode
D002	VDR	RAM Data Retention Voltage ⁽¹⁾	—	1.5*	—	V	Device in SLEEP mode
D003	VPOR	VDD Start Voltage to ensure Power-on Reset	—	VSS	—	V	See Section 5.1 for details on Power-on Reset
D004	SVDD	VDD Rise Rate to ensure Power-on Reset	0.05*	—	—	V/ms	See Section 5.1 for details on Power-on Reset
D010	IDD	Supply Current ⁽²⁾					
		PIC16LC54A	—	0.5	25	mA	FOSC = 4.0 MHz, VDD = 5.5V, RC ⁽³⁾ and XT modes
			—	11	27	μA	FOSC = 32 kHz, VDD = 2.5V, LP mode, Commercial
			—	11	35	μA	FOSC = 32 kHz, VDD = 2.5V, LP mode, Industrial
			—	11	37	μA	FOSC = 32 kHz, VDD = 2.5V, LP mode, Extended
D010A		PIC16C54A	—	1.8	3.3	mA	FOSC = 4.0 MHz, VDD = 5.5V, RC ⁽³⁾ and XT modes
			—	4.8	10	mA	FOSC = 10 MHz, VDD = 5.5V, HS mode
			—	9.0	20	mA	FOSC = 20 MHz, VDD = 5.5V, HS mode

Legend: Rows with standard voltage device data only are shaded for improved readability.

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

Note 1: This is the limit to which VDD can be lowered in SLEEP mode without losing RAM data.

Note 2: The supply current is mainly a function of the operating voltage and frequency. Other factors such as bus loading, oscillator type, bus rate, internal code execution pattern and temperature also have an impact on the current consumption.

a) The test conditions for all IDD measurements in active Operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tristated, pulled to VSS, T0CKI = VDD, MCLR = VDD; WDT enabled/disabled as specified.

b) For standby current measurements, the conditions are the same, except that the device is in SLEEP mode. The power-down current in SLEEP mode does not depend on the oscillator type.

Note 3: Does not include current through REXT. The current through the resistor can be estimated by the formula: $I_R = V_{DD}/2R_{EXT}$ (mA) with REXT in kΩ.

PIC16C5X

NOTES:

FIGURE 18-12: TYPICAL I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 100 pF, 25°C)

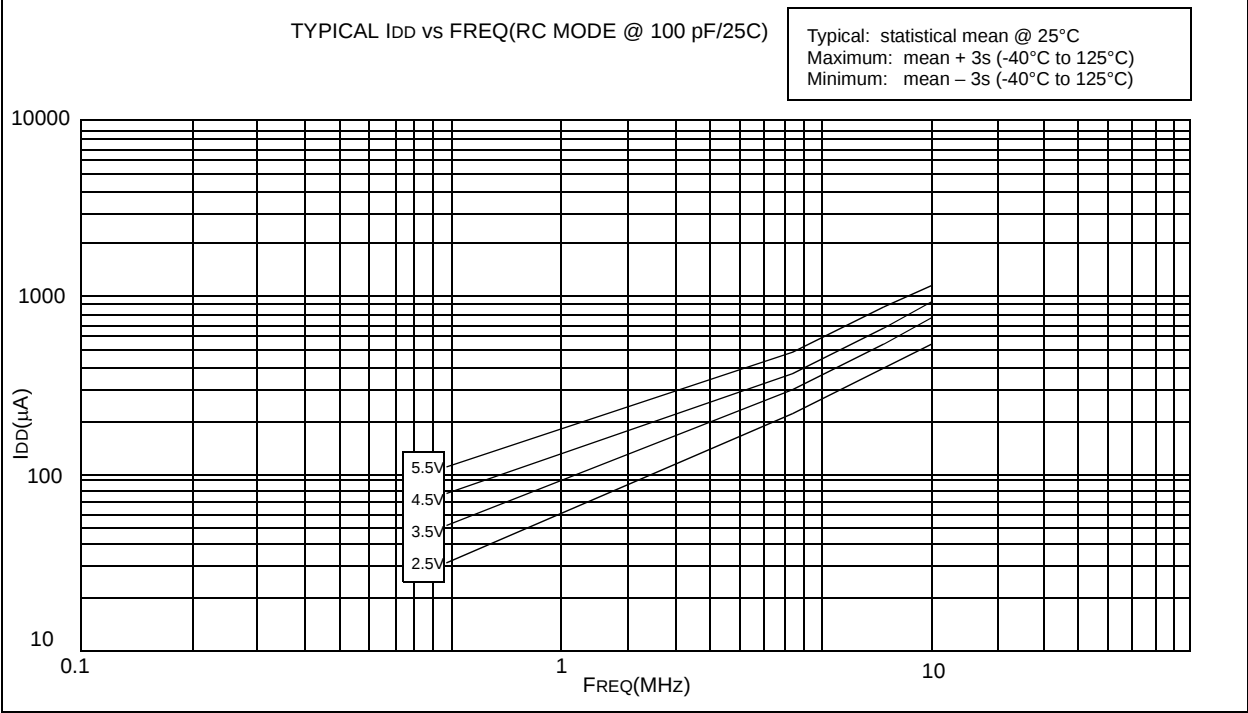


FIGURE 18-13: TYPICAL I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 300 pF, 25°C)

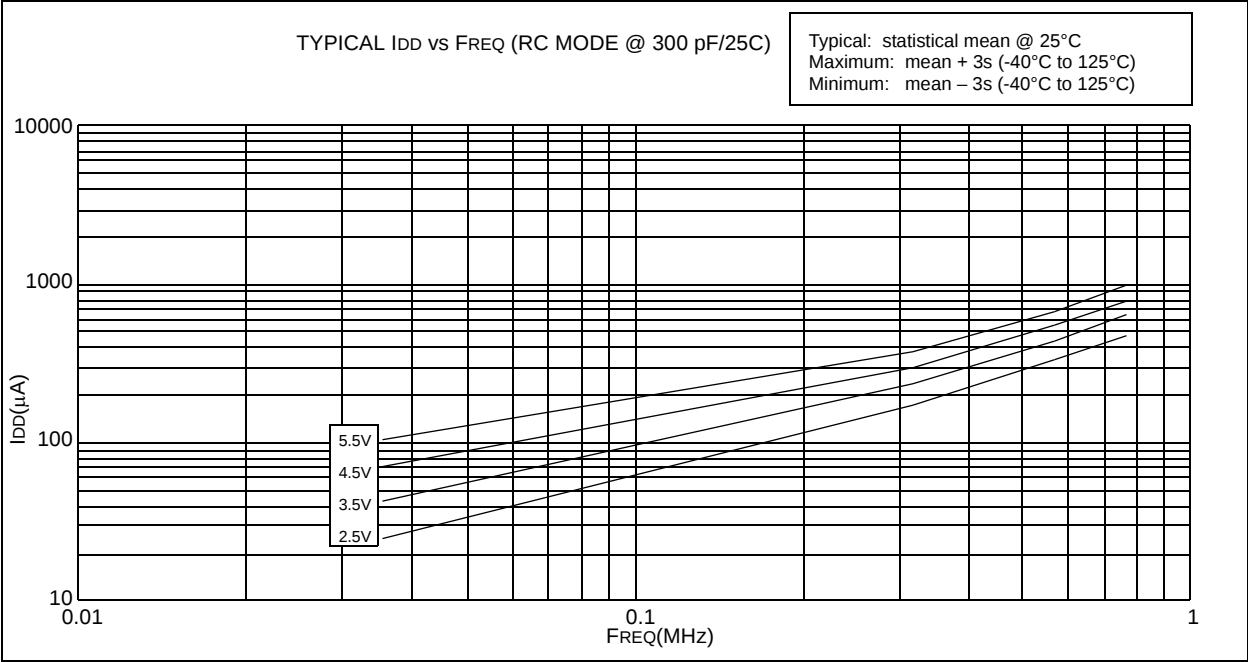


FIGURE 18-14: WDT TIMER TIME-OUT PERIOD vs. VDD⁽¹⁾

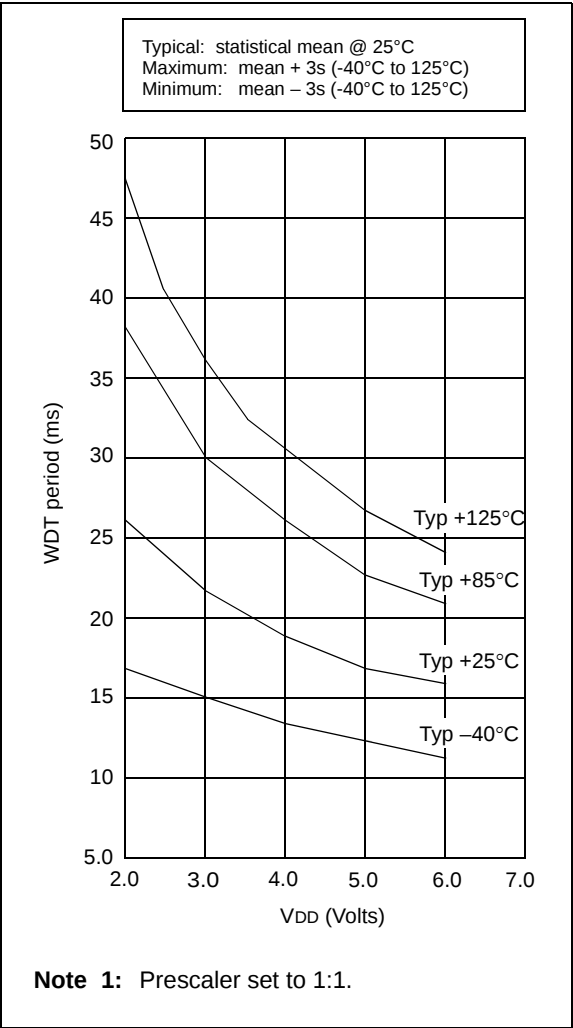
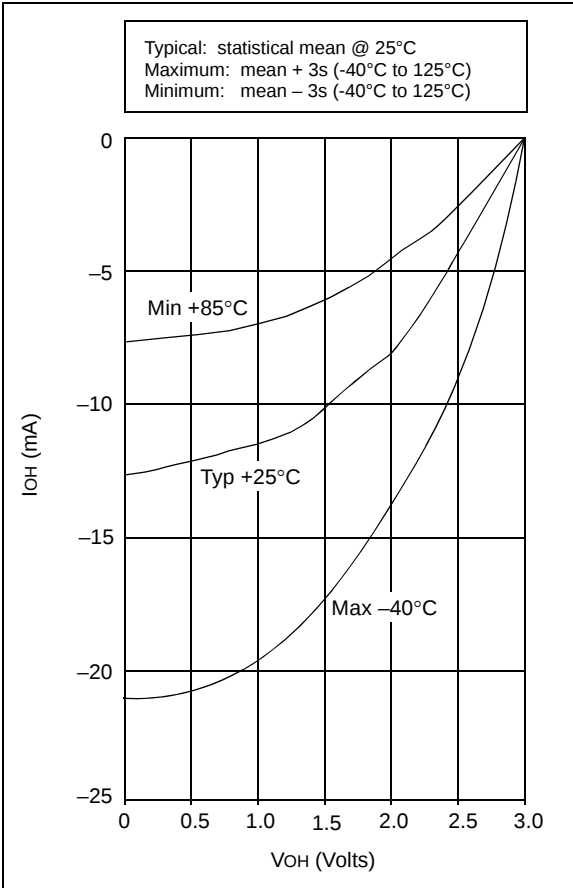


FIGURE 18-15: PORTA, B AND C I_{OH} vs. V_{OH}, VDD = 3 V



19.1 DC Characteristics: PIC16C54C/C55A/C56A/C57C/C58B-40 (Commercial)⁽¹⁾

PIC16C54C/C55A/C56A/C57C/C58B-40 (Commercial)			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature 0°C ≤ TA ≤ +70°C for commercial				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D001	VDD	Supply Voltage	4.5	—	5.5	V	HS mode from 20 - 40 MHz
D002	VDR	RAM Data Retention Voltage ⁽²⁾	—	1.5*	—	V	Device in SLEEP mode
D003	VPOR	VDD Start Voltage to ensure Power-on Reset	—	VSS	—	V	See Section 5.1 for details on Power-on Reset
D004	SVDD	VDD Rise Rate to ensure Power-on Reset	0.05*	—	—	V/ms	See Section 5.1 for details on Power-on Reset
D010	IDD	Supply Current ⁽³⁾	—	5.2 6.8	12.3 16	mA mA	FOSC = 40 MHz, VDD = 4.5V, HS mode FOSC = 40 MHz, VDD = 5.5V, HS mode
D020	IPD	Power-down Current ⁽³⁾	—	1.8 9.8	7.0 27*	μA μA	VDD = 5.5V, WDT disabled, Commercial VDD = 5.5V, WDT enabled, Commercial

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

- Note 1:** Device operation between 20 MHz to 40 MHz requires the following: VDD between 4.5V to 5.5V, OSC1 pin externally driven, OSC2 pin not connected, HS oscillator mode and commercial temperatures. For operation between DC and 20 MHz, See Section 19.1.
- 2:** This is the limit to which VDD can be lowered in SLEEP mode without losing RAM data.
- 3:** The supply current is mainly a function of the operating voltage and frequency. Other factors such as bus loading, oscillator type, bus rate, internal code execution pattern and temperature also have an impact on the current consumption.
- a) The test conditions for all IDD measurements in active Operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tristated, pulled to VSS, T0CKI = VDD, MCLR = VDD; WDT enabled/disabled as specified.
 - b) For standby current measurements, the conditions are the same, except that the device is in SLEEP mode. The power-down current in SLEEP mode does not depend on the oscillator type.

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19.2 DC Characteristics: PIC16C54C/C55A/C56A/C57C/C58B-40 (Commercial)⁽¹⁾

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature 0°C ≤ TA ≤ +70°C for commercial				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D030	VIL	Input Low Voltage I/O Ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1	VSS VSS VSS VSS	— — — —	0.8 0.15 VDD 0.15 VDD 0.2 VDD	V V V V	4.5V < VDD ≤ 5.5V HS, 20 MHz ≤ FOSC ≤ 40 MHz
D040	VIH	Input High Voltage I/O ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1	2.0 0.85 VDD 0.85 VDD 0.8 VDD	— — — —	VDD VDD VDD VDD	V V V V	4.5V < VDD ≤ 5.5V HS, 20 MHz ≤ FOSC ≤ 40 MHz
D050	VHYS	Hysteresis of Schmitt Trigger inputs	0.15 VDD*	—	—	V	
D060	IIL	Input Leakage Current^(2,3) I/O ports MCLR MCLR T0CKI OSC1	-1.0 -5.0 — -3.0 -3.0	0.5 — 0.5 0.5 0.5	+1.0 +5.0 +3.0 +3.0 —	μA μA μA μA μA	For VDD ≤ 5.5V: VSS ≤ VPIN ≤ VDD, pin at hi-impedance VPIN = VSS + 0.25V VPIN = VDD VSS ≤ VPIN ≤ VDD VSS ≤ VPIN ≤ VDD, HS
D080	VOL	Output Low Voltage I/O ports	—	—	0.6	V	IOL = 8.7 mA, VDD = 4.5V
D090	VOH	Output High Voltage⁽³⁾ I/O ports	VDD - 0.7	—	—	V	IOH = -5.4 mA, VDD = 4.5V

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

- Note 1:** Device operation between 20 MHz to 40 MHz requires the following: VDD between 4.5V to 5.5V, OSC1 pin externally driven, OSC2 pin not connected and HS oscillator mode and commercial temperatures. For operation between DC and 20 MHz, See Section 17.3.
- 2:** The leakage current on the MCLR/VPP pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltage.
- 3:** Negative current is defined as coming out of the pin.

FIGURE 20-4: V_{TH} (INPUT THRESHOLD TRIP POINT VOLTAGE) OF I/O PINS vs. V_{DD}

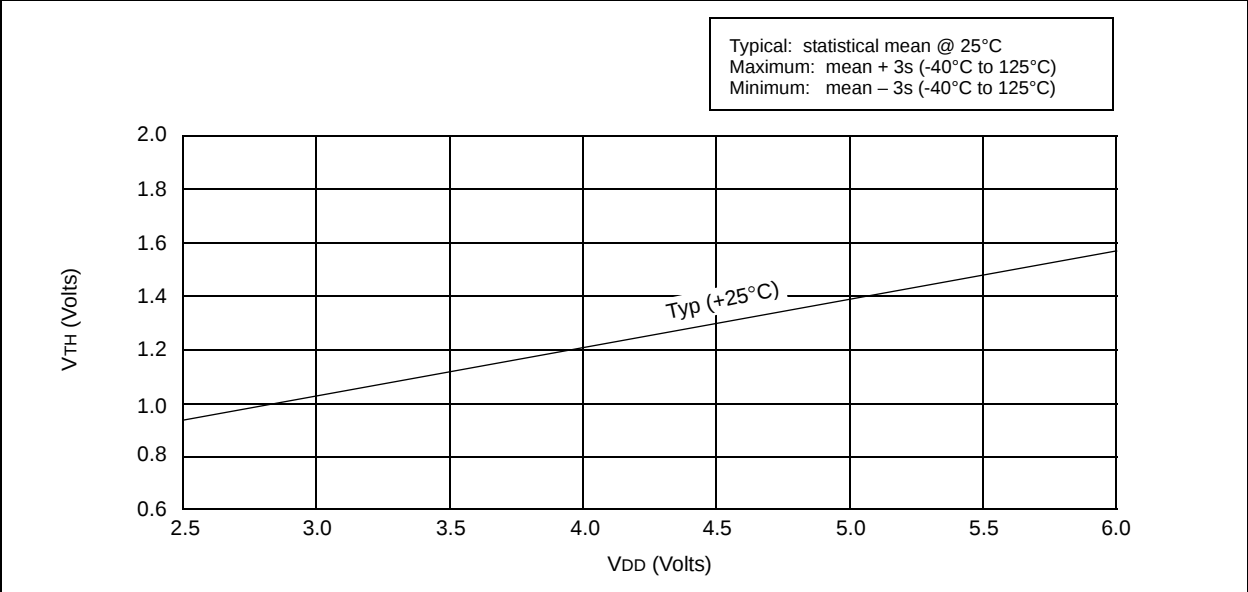
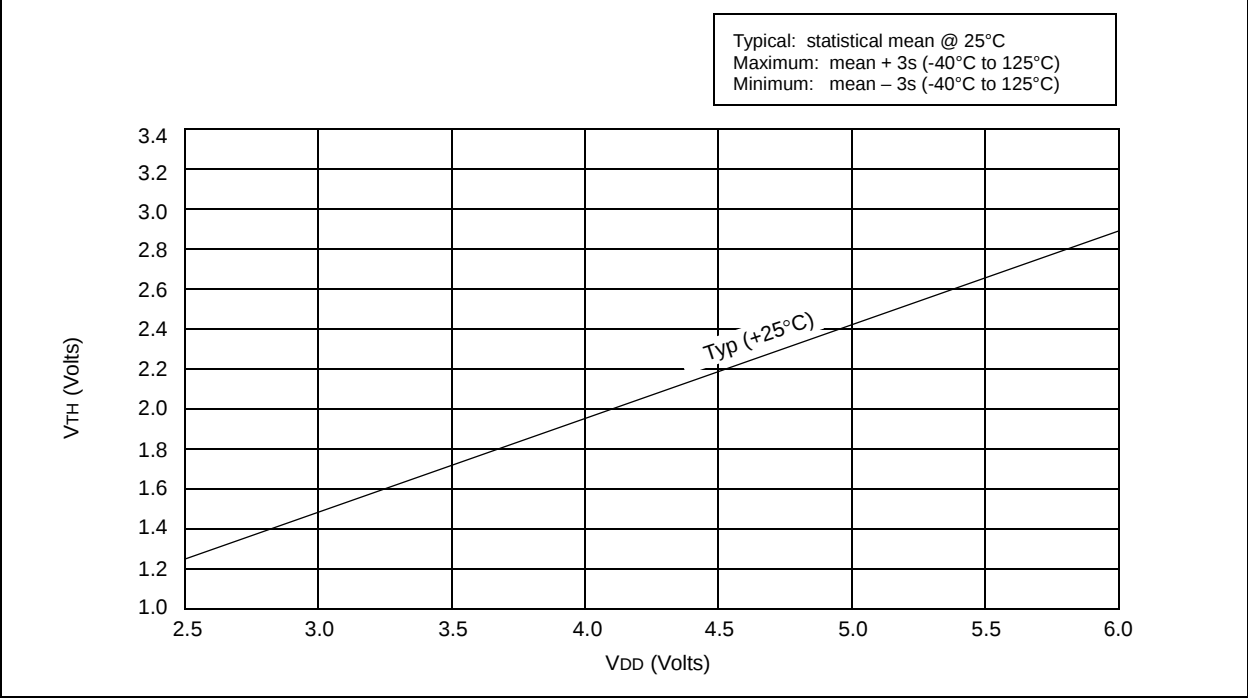


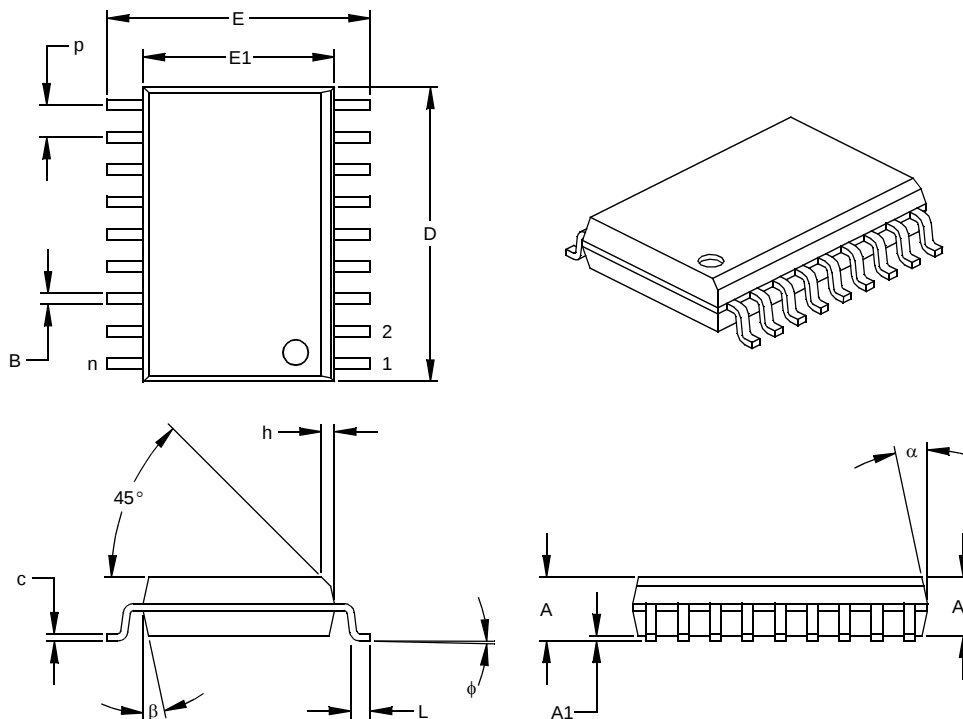
FIGURE 20-5: V_{TH} (INPUT THRESHOLD TRIP POINT VOLTAGE) OF OSC1 INPUT (HS MODE) vs. V_{DD}



PIC16C5X

18-Lead Plastic Small Outline (SO) – Wide, 300 mil (SOIC)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		18			18	
Pitch	p		.050			1.27	
Overall Height	A	.093	.099	.104	2.36	2.50	2.64
Molded Package Thickness	A2	.088	.091	.094	2.24	2.31	2.39
Standoff §	A1	.004	.008	.012	0.10	0.20	0.30
Overall Width	E	.394	.407	.420	10.01	10.34	10.67
Molded Package Width	E1	.291	.295	.299	7.39	7.49	7.59
Overall Length	D	.446	.454	.462	11.33	11.53	11.73
Chamfer Distance	h	.010	.020	.029	0.25	0.50	0.74
Foot Length	L	.016	.033	.050	0.41	0.84	1.27
Foot Angle	φ	0	4	8	0	4	8
Lead Thickness	c	.009	.011	.012	0.23	0.27	0.30
Lead Width	B	.014	.017	.020	0.36	0.42	0.51
Mold Draft Angle Top	α	0	12	15	0	12	15
Mold Draft Angle Bottom	β	0	12	15	0	12	15

* Controlling Parameter

§ Significant Characteristic

Notes:

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

JEDEC Equivalent: MS-013

Drawing No. C04-051

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