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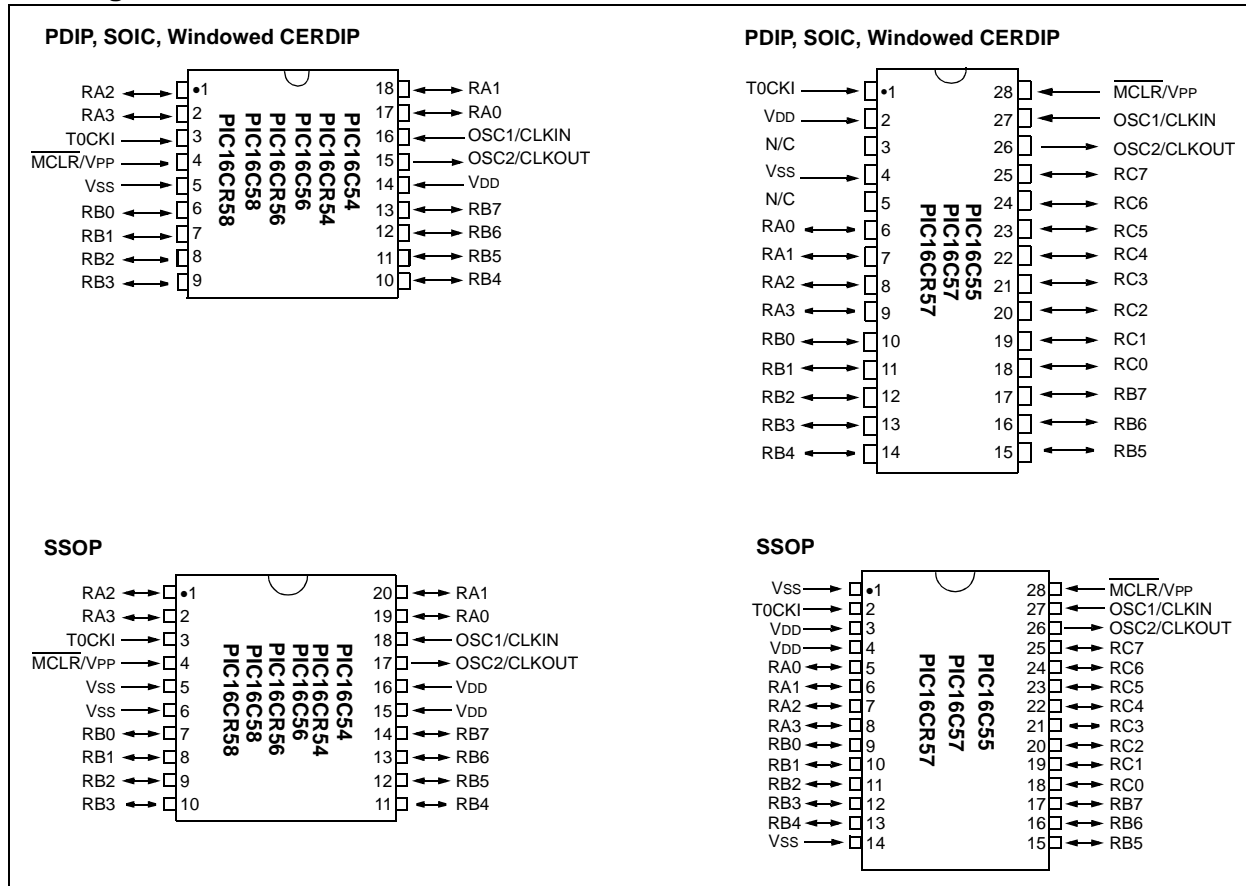
Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	20
Program Memory Size	768B (512 x 12)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	24 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 6.25V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c55-rci-sp

PIC16C5X

Pin Diagrams



Device Differences

Device	Voltage Range	Oscillator Selection (Program)	Oscillator	Process Technology (Microns)	ROM Equivalent	MCLR Filter
PIC16C54	2.5-6.25	Factory	See Note 1	1.2	PIC16CR54A	No
PIC16C54A	2.0-6.25	User	See Note 1	0.9	—	No
PIC16C54C	2.5-5.5	User	See Note 1	0.7	PIC16CR54C	Yes
PIC16C55	2.5-6.25	Factory	See Note 1	1.7	—	No
PIC16C55A	2.5-5.5	User	See Note 1	0.7	—	Yes
PIC16C56	2.5-6.25	Factory	See Note 1	1.7	—	No
PIC16C56A	2.5-5.5	User	See Note 1	0.7	PIC16CR56A	Yes
PIC16C57	2.5-6.25	Factory	See Note 1	1.2	—	No
PIC16C57C	2.5-5.5	User	See Note 1	0.7	PIC16CR57C	Yes
PIC16C58B	2.5-5.5	User	See Note 1	0.7	PIC16CR58B	Yes
PIC16CR54A	2.5-6.25	Factory	See Note 1	1.2	N/A	Yes
PIC16CR54C	2.5-5.5	Factory	See Note 1	0.7	N/A	Yes
PIC16CR56A	2.5-5.5	Factory	See Note 1	0.7	N/A	Yes
PIC16CR57C	2.5-5.5	Factory	See Note 1	0.7	N/A	Yes
PIC16CR58B	2.5-5.5	Factory	See Note 1	0.7	N/A	Yes

Note 1: If you change from this device to another device, please verify oscillator characteristics in your application.

Note: The table shown above shows the generic names of the PIC16C5X devices. For device varieties, please refer to Section 2.0.

PIC16C5X

NOTES:

PIC16C5X

6.2.2 SPECIAL FUNCTION REGISTERS

The Special Function Registers are registers used by the CPU and peripheral functions to control the operation of the device (Table 6-1).

The Special Registers can be classified into two sets. The Special Function Registers associated with the “core” functions are described in this section. Those related to the operation of the peripheral features are described in the section for each peripheral feature.

TABLE 6-1: SPECIAL FUNCTION REGISTER SUMMARY

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-on Reset	Details on Page
N/A	TRIS	I/O Control Registers (TRISA, TRISB, TRISC)								1111 1111	35
N/A	OPTION	Contains control bits to configure Timer0 and Timer0/WDT prescaler								--11 1111	30
00h	INDF	Uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	32
01h	TMR0	Timer0 Module Register								xxxx xxxx	38
02h ⁽¹⁾	PCL	Low order 8 bits of PC								1111 1111	31
03h	STATUS	PA2	PA1	PA0	\overline{TO}	\overline{PD}	Z	DC	C	0001 1xxx	29
04h	FSR	Indirect data memory address pointer								1xxx xxxx ⁽³⁾	32
05h	PORTA	—	—	—	—	RA3	RA2	RA1	RA0	---- xxxx	35
06h	PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	35
07h ⁽²⁾	PORTC	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	35

Legend: x = unknown, u = unchanged, — = unimplemented, read as '0' (if applicable). Shaded cells = unimplemented or unused

- Note 1:** The upper byte of the Program Counter is not directly accessible. See Section 6.5 for an explanation of how to access these bits.
- Note 2:** File address 07h is a General Purpose Register on the PIC16C54, PIC16CR54, PIC16C56, PIC16CR56, PIC16C58 and PIC16CR58.
- Note 3:** These values are valid for PIC16C57/CR57/C58/CR58. For the PIC16C54/CR54/C55/C56/CR56, the value on RESET is 111x xxxx and for \overline{MCLR} and WDT Reset, the value is 111u uuuu.

PIC16C5X

NOTES:

PIC16C5X

9.2 Watchdog Timer (WDT)

The Watchdog Timer (WDT) is a free running on-chip RC oscillator which does not require any external components. This RC oscillator is separate from the RC oscillator of the OSC1/CLKIN pin. That means that the WDT will run even if the clock on the OSC1/CLKIN and OSC2/CLKOUT pins have been stopped, for example, by execution of a `SLEEP` instruction. During normal operation or `SLEEP`, a WDT Reset or Wake-up Reset generates a device RESET.

The \overline{TO} bit (STATUS<4>) will be cleared upon a Watchdog Timer Reset (Section 6.3).

The WDT can be permanently disabled by programming the configuration bit `WDTE` as a '0' (Section 9.1). Refer to the PIC16C5X Programming Specifications (Literature Number DS30190) to determine how to access the configuration word.

9.2.1 WDT PERIOD

An 8-bit counter is available as a prescaler for the Timer0 module (Section 8.2), or as a postscaler for the Watchdog Timer (WDT), respectively. For simplicity, this counter is being referred to as "prescaler" throughout this data sheet. Note that the prescaler may be used by either the Timer0 module or the WDT, but not

both. Thus, a prescaler assignment for the Timer0 module means that there is no prescaler for the WDT, and vice-versa.

The `PSA` and `PS<2:0>` bits (OPTION<3:0>) determine prescaler assignment and prescale ratio (Section 6.4).

The WDT has a nominal time-out period of 18 ms (with no prescaler). If a longer time-out period is desired, a prescaler with a division ratio of up to 1:128 can be assigned to the WDT (under software control) by writing to the `OPTION` register. Thus, time-out a period of a nominal 2.3 seconds can be realized. These periods vary with temperature, `VDD` and part-to-part process variations (see Device Characterization).

Under worst case conditions (`VDD` = Min., Temperature = Max., WDT prescaler = 1:128), it may take several seconds before a WDT time-out occurs.

9.2.2 WDT PROGRAMMING CONSIDERATIONS

The `CLRWDT` instruction clears the WDT and the prescaler, if assigned to the WDT, and prevents it from timing out and generating a device RESET.

The `SLEEP` instruction RESETS the WDT and the prescaler, if assigned to the WDT. This gives the maximum `SLEEP` time before a WDT Wake-up Reset.

FIGURE 9-1: WATCHDOG TIMER BLOCK DIAGRAM

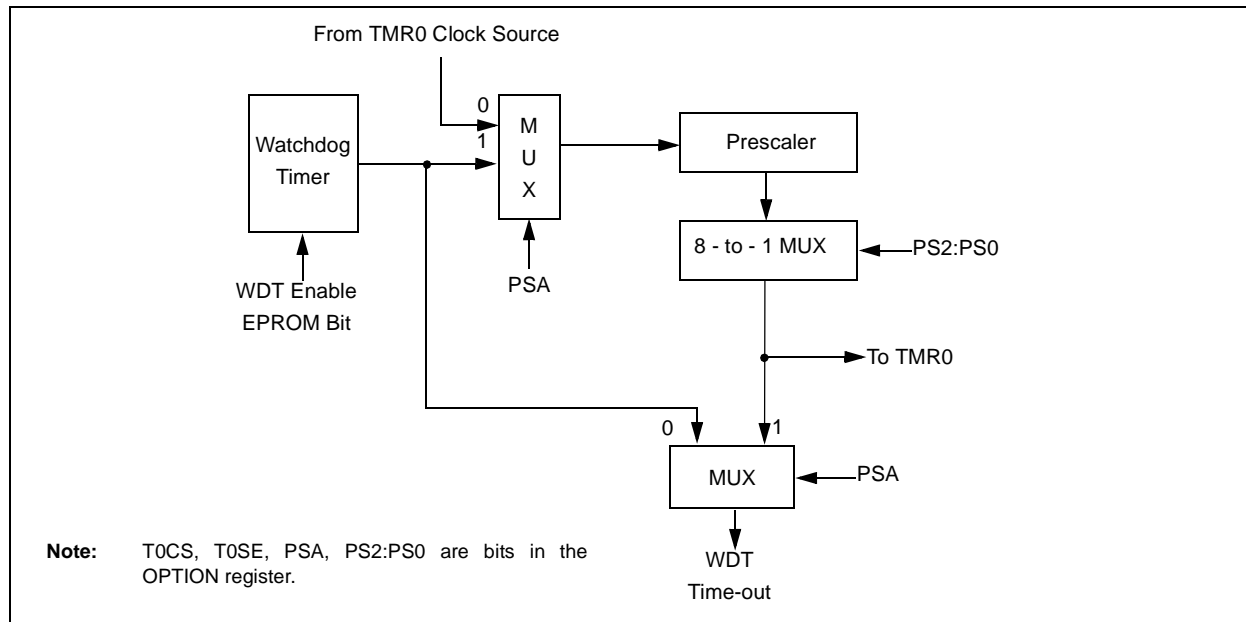


TABLE 9-1: SUMMARY OF REGISTERS ASSOCIATED WITH THE WATCHDOG TIMER

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-On Reset	Value on MCLR and WDT Reset
N/A	OPTION	—	—	Tosc	Tose	PSA	PS2	PS1	PS0	--11 1111	--11 1111

Legend: u = unchanged, - = unimplemented, read as '0'. Shaded cells not used by Watchdog Timer.

ADDWF Add W and f

Syntax: [*label*] ADDWF f,d

Operands: $0 \leq f \leq 31$
 $d \in [0,1]$

Operation: $(W) + (f) \rightarrow (\text{dest})$

Status Affected: C, DC, Z

Encoding:

0001	11df	ffff
------	------	------

Description: Add the contents of the W register and register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is '1' the result is stored back in register 'f'.

Words: 1

Cycles: 1

Example: ADDWF TEMP_REG, 0

Before Instruction

W = 0x17
TEMP_REG = 0xC2

After Instruction

W = 0xD9
TEMP_REG = 0xC2

ANDWF AND W with f

Syntax: [*label*] ANDWF f,d

Operands: $0 \leq f \leq 31$
 $d \in [0,1]$

Operation: $(W) .\text{AND}. (f) \rightarrow (\text{dest})$

Status Affected: Z

Encoding:

0001	01df	ffff
------	------	------

Description: The contents of the W register are AND'ed with register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is '1' the result is stored back in register 'f'.

Words: 1

Cycles: 1

Example: ANDWF TEMP_REG, 1

Before Instruction

W = 0x17
TEMP_REG = 0xC2

After Instruction

W = 0x17
TEMP_REG = 0x02

ANDLW AND literal with W

Syntax: [*label*] ANDLW k

Operands: $0 \leq k \leq 255$

Operation: $(W) .\text{AND}. (k) \rightarrow (W)$

Status Affected: Z

Encoding:

1110	kkkk	kkkk
------	------	------

Description: The contents of the W register are AND'ed with the eight-bit literal 'k'. The result is placed in the W register.

Words: 1

Cycles: 1

Example: ANDLW H'5F'

Before Instruction

W = 0xA3

After Instruction

W = 0x03

BCF Bit Clear f

Syntax: [*label*] BCF f,b

Operands: $0 \leq f \leq 31$
 $0 \leq b \leq 7$

Operation: $0 \rightarrow (f)$

Status Affected: None

Encoding:

0100	bbbf	ffff
------	------	------

Description: Bit 'b' in register 'f' is cleared.

Words: 1

Cycles: 1

Example: BCF FLAG_REG, 7

Before Instruction

FLAG_REG = 0xC7

After Instruction

FLAG_REG = 0x47

15.0 ELECTRICAL CHARACTERISTICS - PIC16C54A

Absolute Maximum Ratings^(†)

Ambient temperature under bias	–55°C to +125°C
Storage temperature	–65°C to +150°C
Voltage on VDD with respect to VSS	0 to +7.5V
Voltage on MCLR with respect to VSS.....	0 to +14V
Voltage on all other pins with respect to VSS	–0.6V to (VDD + 0.6V)
Total power dissipation ⁽¹⁾	800 mW
Max. current out of Vss pin	150 mA
Max. current into VDD pin	100 mA
Max. current into an input pin (T0CKI only)	±500 µA
Input clamp current, I _{IK} (V _I < 0 or V _I > VDD).....	±20 mA
Output clamp current, I _{OK} (V _O < 0 or V _O > VDD)	±20 mA
Max. output current sunk by any I/O pin	25 mA
Max. output current sourced by any I/O pin	20 mA
Max. output current sourced by a single I/O port (PORTA or B)	50 mA
Max. output current sunk by a single I/O port (PORTA or B)	50 mA

Note 1: Power dissipation is calculated as follows: $P_{dis} = V_{DD} \times \{I_{DD} - \sum I_{OH}\} + \sum \{(V_{DD} - V_{OH}) \times I_{OH}\} + \sum (V_{OL} \times I_{OL})$

† NOTICE: Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

15.5 Timing Parameter Symbolology and Load Conditions

The timing parameter symbols have been created with one of the following formats:

- 1. TppS2ppS
- 2. TppS

T			
F	Frequency	T	Time

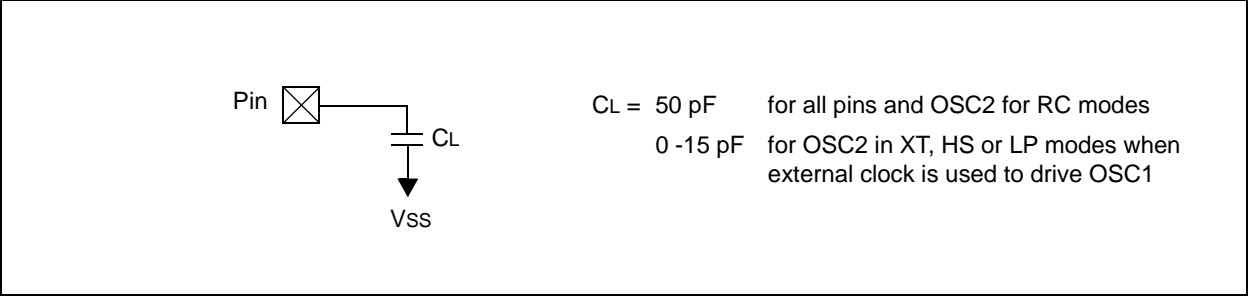
Lowercase letters (pp) and their meanings:

pp			
2	to	mc	MCLR
ck	CLKOUT	osc	oscillator
cy	cycle time	os	OSC1
drt	device reset timer	t0	T0CKI
io	I/O port	wdt	watchdog timer

Uppercase letters and their meanings:

S			
F	Fall	P	Period
H	High	R	Rise
I	Invalid (Hi-impedance)	V	Valid
L	Low	Z	Hi-impedance

FIGURE 15-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS - PIC16C54A



PIC16C5X

FIGURE 15-4: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER TIMING - PIC16C54A

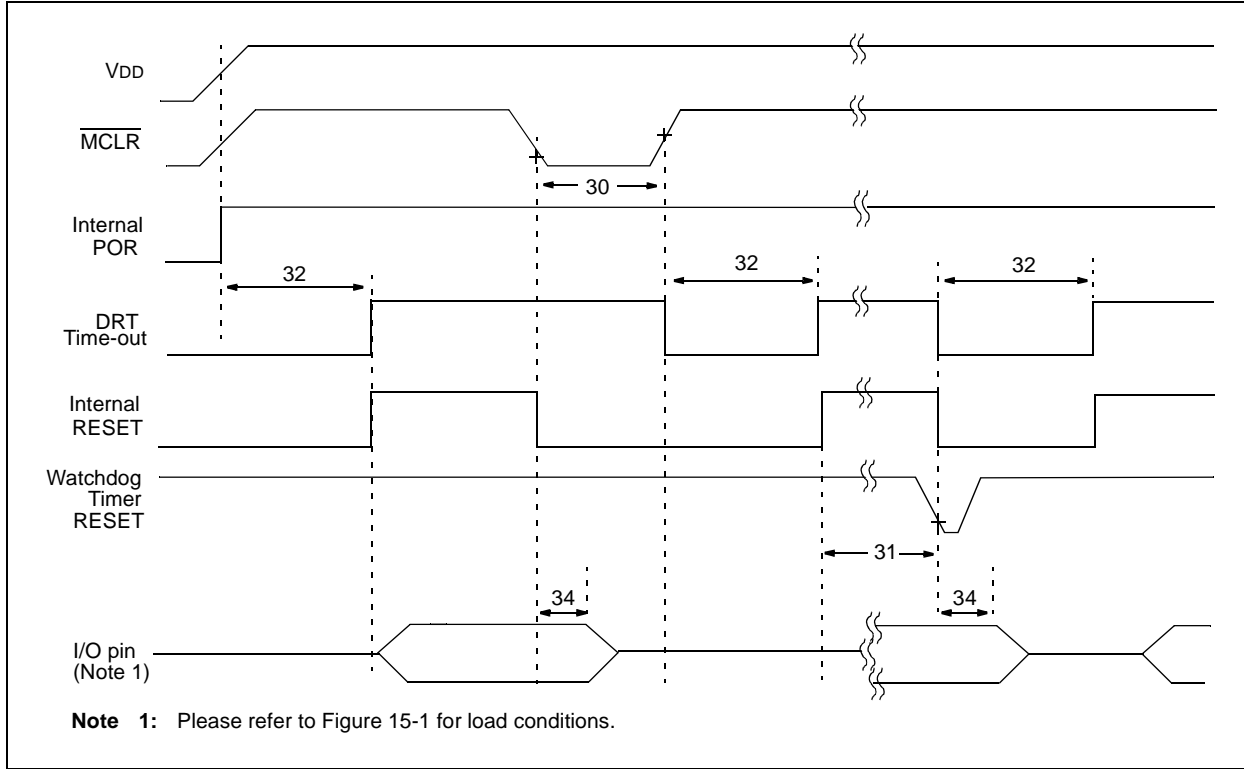


TABLE 15-3: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER - PIC16C54A

Standard Operating Conditions (unless otherwise specified)							
AC Characteristics							
		Operating Temperature					
		0°C ≤ TA ≤ +70°C for commercial					
		-40°C ≤ TA ≤ +85°C for industrial					
		-20°C ≤ TA ≤ +85°C for industrial - PIC16LV54A-02I					
		-40°C ≤ TA ≤ +125°C for extended					
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
30	TmCL	MCLR Pulse Width (low)	100* 1	— —	— —	ns μs	VDD = 5.0V VDD = 5.0V (PIC16LV54A only)
31	Twdt	Watchdog Timer Time-out Period (No Prescaler)	9.0*	18*	30*	ms	VDD = 5.0V (Comm)
32	TDRT	Device Reset Timer Period	9.0*	18*	30*	ms	VDD = 5.0V (Comm)
34	TioZ	I/O Hi-impedance from MCLR Low	— —	— —	100* 1μs	ns —	(PIC16LV54A only)

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 16-7: V_{TH} (INPUT THRESHOLD VOLTAGE) OF I/O PINS - V_{DD}

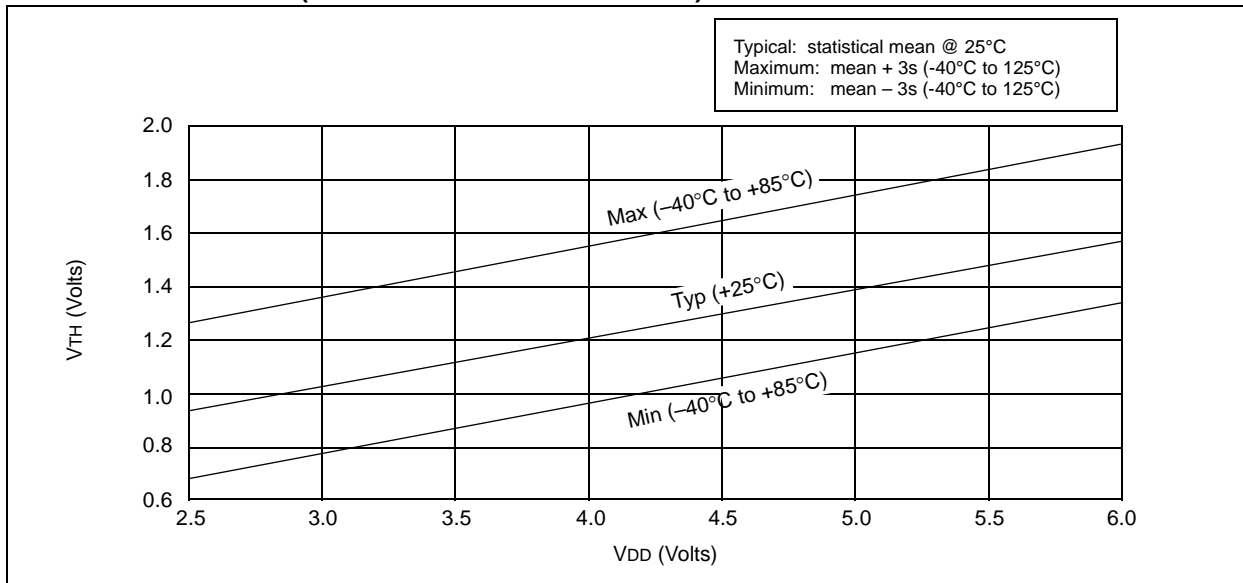


FIGURE 16-8: V_{TH} (INPUT THRESHOLD VOLTAGE) OF OSC1 INPUT (IN XT, HS, AND LP MODES) vs. V_{DD}

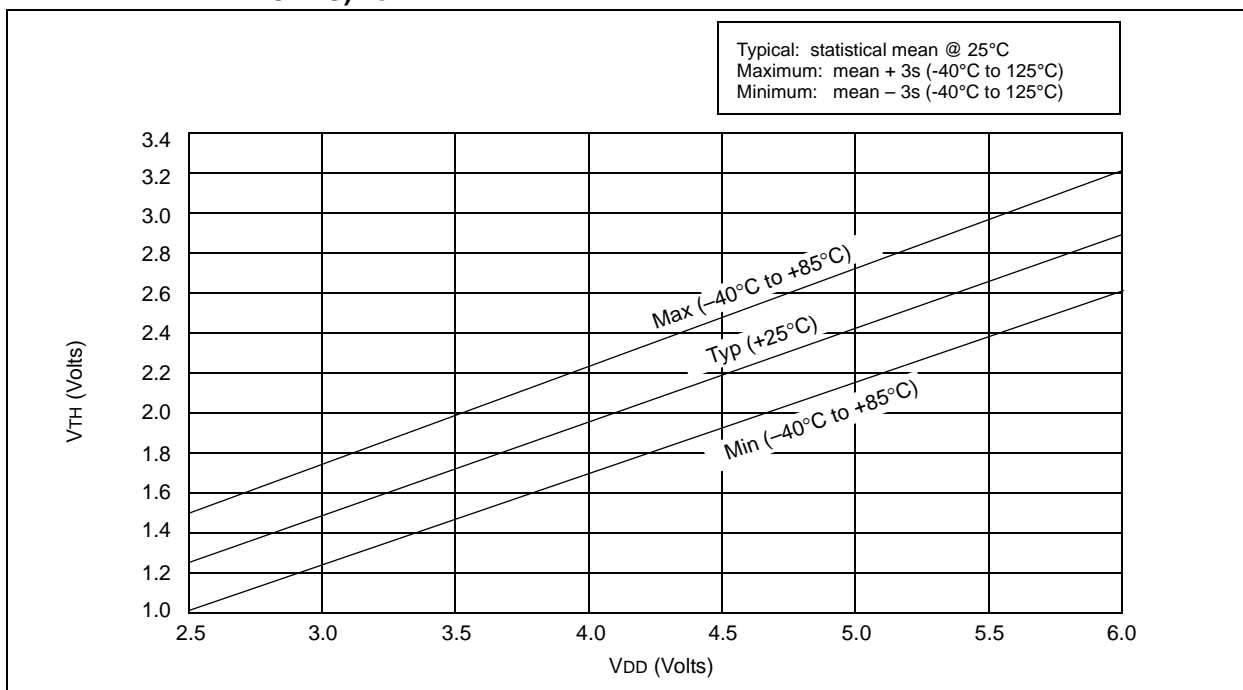


FIGURE 16-10: TYPICAL I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 20 pF, 25°C)

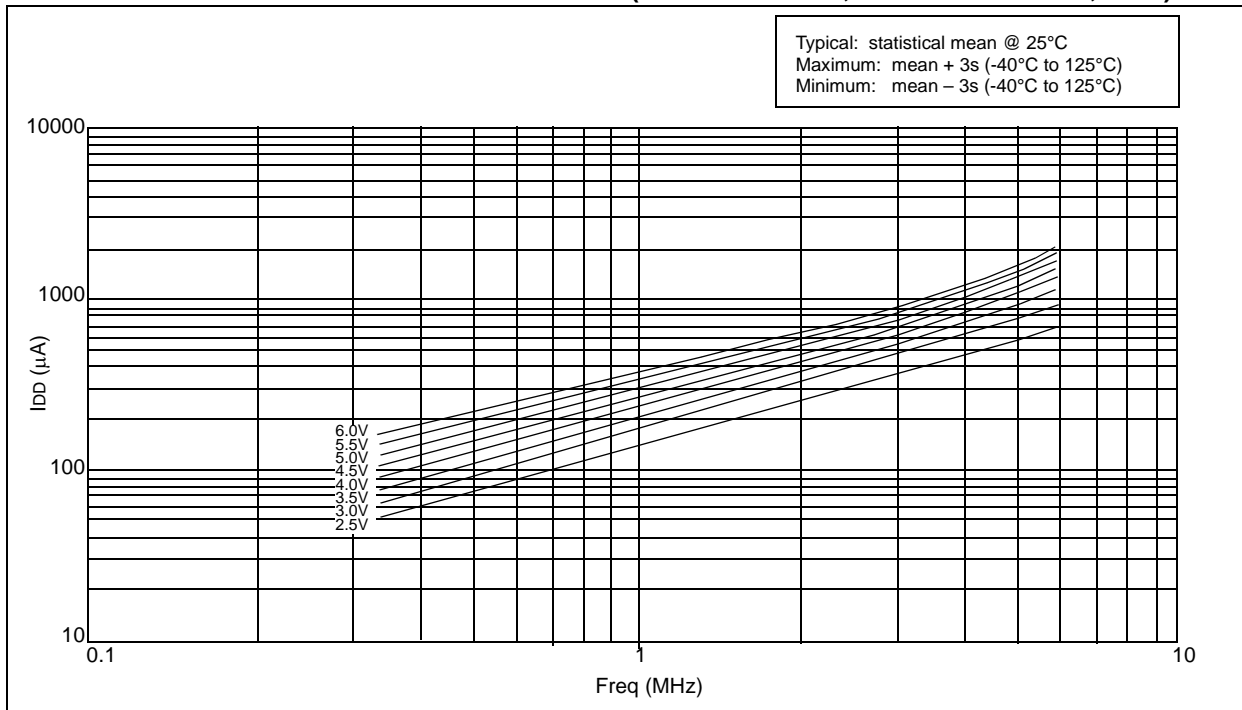


FIGURE 16-11: MAXIMUM I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 20 pF, -40°C to +85°C)

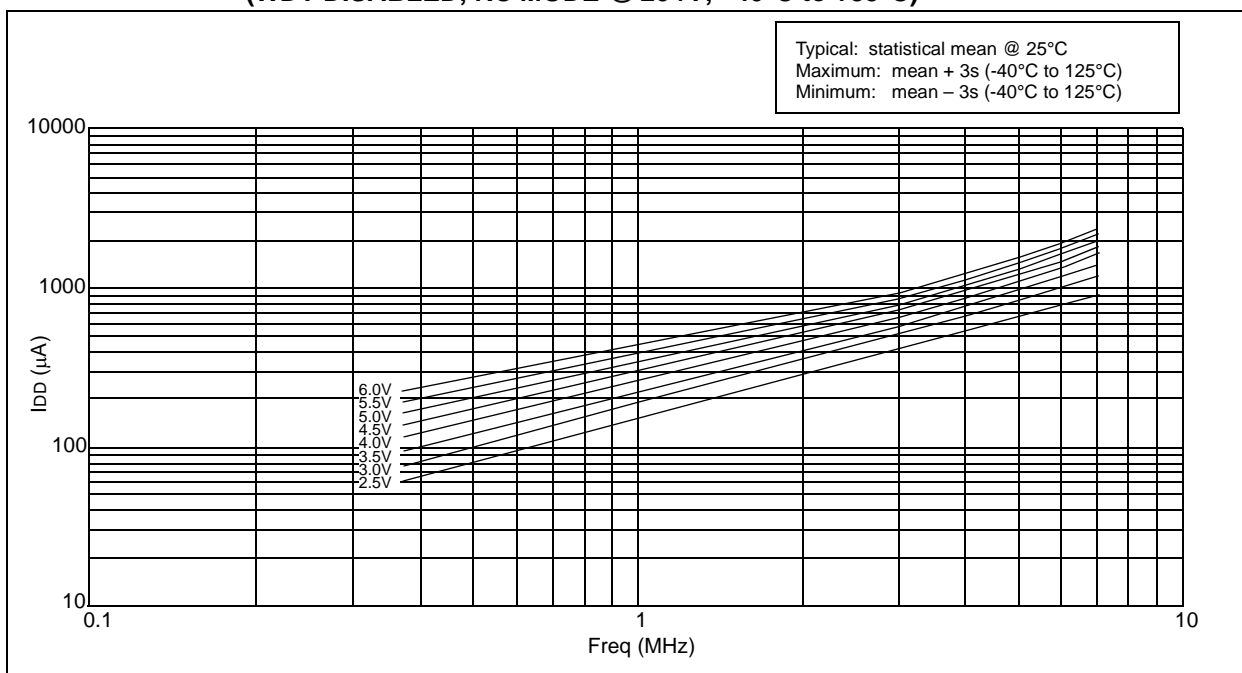


FIGURE 16-22: PORTA, B AND C IoL vs. VOL, VDD = 3V

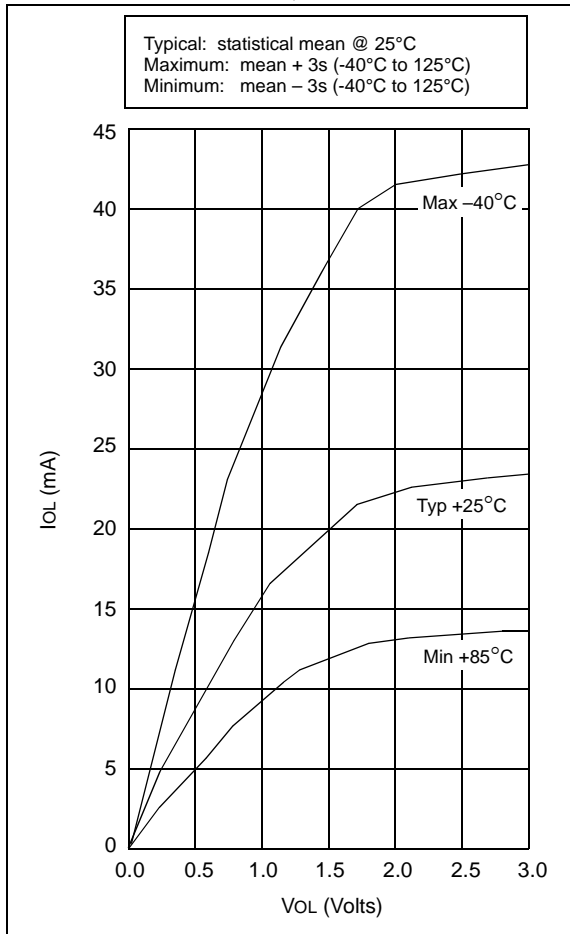


FIGURE 16-23: PORTA, B AND C IoL vs. VOL, VDD = 5V

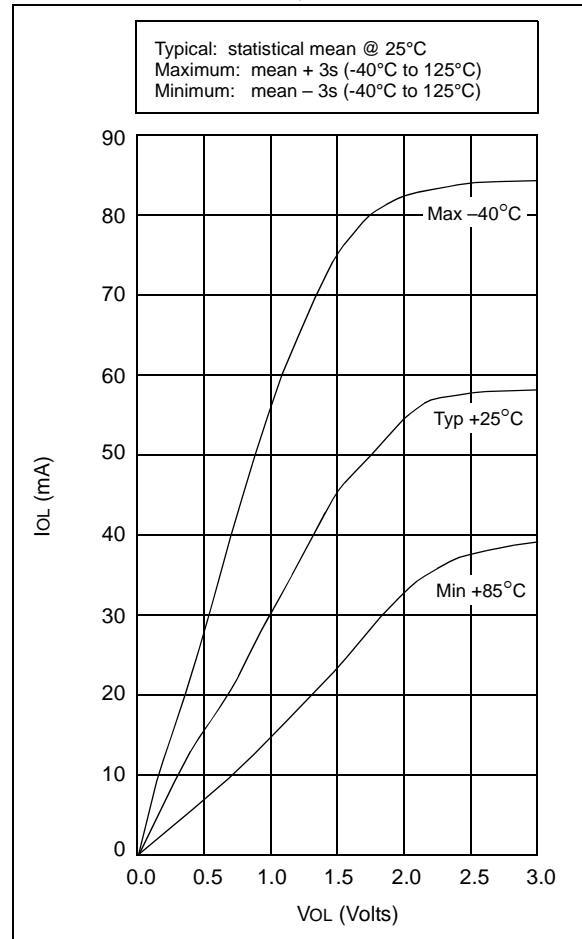


TABLE 16-2: INPUT CAPACITANCE FOR PIC16C54A/C58A

Pin	Typical Capacitance (pF)	
	18L PDIP	18L SOIC
RA port	5.0	4.3
RB port	5.0	4.3
MCLR	17.0	17.0
OSC1	4.0	3.5
OSC2/CLKOUT	4.3	3.5
T0CKI	3.2	2.8

All capacitance values are typical at 25°C. A part-to-part variation of $\pm 25\%$ (three standard deviations) should be taken into account.

PIC16C5X

17.3 DC Characteristics: PIC16C54C/C55A/C56A/C57C/C58B-04, 20 (Commercial, Industrial, Extended) PIC16LC54C/LC55A/LC56A/LC57C/LC58B-04 (Commercial, Industrial) PIC16CR54C/CR56A/CR57C/CR58B-04, 20 (Commercial, Industrial, Extended) PIC16LCR54C/LCR56A/LCR57C/LCR58B-04 (Commercial, Industrial)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature				
			0°C ≤ TA ≤ +70°C for commercial				
			-40°C ≤ TA ≤ +85°C for industrial				
			-40°C ≤ TA ≤ +125°C for extended				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D030	VIL	Input Low Voltage I/O Ports I/O Ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1 (Schmitt Trigger) OSC1	VSS VSS VSS VSS VSS VSS	— — — — — —	0.8 V 0.15 VDD 0.15 VDD 0.15 VDD 0.15 VDD 0.3 VDD	V V V V V V	4.5V < VDD ≤ 5.5V Otherwise RC mode only ⁽³⁾ XT, HS and LP modes
D040	VIH	Input High Voltage I/O ports I/O ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1 (Schmitt Trigger) OSC1	2.0 0.25 VDD+0.8 0.85 VDD 0.85 VDD 0.85 VDD 0.7 VDD	— — — — — —	VDD VDD VDD VDD VDD VDD	V V V V V V	4.5V < VDD ≤ 5.5V Otherwise RC mode only ⁽³⁾ XT, HS and LP modes
D050	VHYS	Hysteresis of Schmitt Trigger inputs	0.15 VDD*	—	—	V	
D060	IIL	Input Leakage Current^(1,2) I/O ports MCLR MCLR T0CKI OSC1	-1.0 -5.0 -3.0 -3.0	0.5 — 0.5 0.5 0.5	+1.0 +5.0 +3.0 +3.0 —	μA μA μA μA μA	For VDD ≤ 5.5V: VSS ≤ VPIN ≤ VDD, pin at hi-impedance VPIN = VSS +0.25V VPIN = VDD VSS ≤ VPIN ≤ VDD VSS ≤ VPIN ≤ VDD, XT, HS and LP modes
D080	VOL	Output Low Voltage I/O ports OSC2/CLKOUT	— —	— —	0.6 0.6	V V	IOL = 8.7 mA, VDD = 4.5V IOL = 1.6 mA, VDD = 4.5V, RC mode only
D090	VOH	Output High Voltage⁽²⁾ I/O ports OSC2/CLKOUT	VDD - 0.7 VDD - 0.7	— —	— —	V V	IOH = -5.4 mA, VDD = 4.5V IOH = -1.0 mA, VDD = 4.5V, RC mode only

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

Note 1: The leakage current on the MCLR/VPIN pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltage.

2: Negative current is defined as coming out of the pin.

3: For the RC mode, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC16C5X be driven with external clock in RC mode.

19.3 Timing Parameter Symbolology and Load Conditions

The timing parameter symbols have been created with one of the following formats:

- 1. TppS2ppS
- 2. TppS

T		T	Time
F	Frequency		
Lowercase letters (pp) and their meanings:			
pp		mc	MCLR
2	to	osc	oscillator
ck	CLKOUT	os	OSC1
cy	cycle time	t0	T0CKI
drt	device reset timer	wdt	watchdog timer
io	I/O port		
Uppercase letters and their meanings:			
S		P	Period
F	Fall	R	Rise
H	High	V	Valid
I	Invalid (Hi-impedance)	Z	Hi-impedance
L	Low		

FIGURE 19-2: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS - PIC16C54C/C55A/C56A/C57C/C58B-40

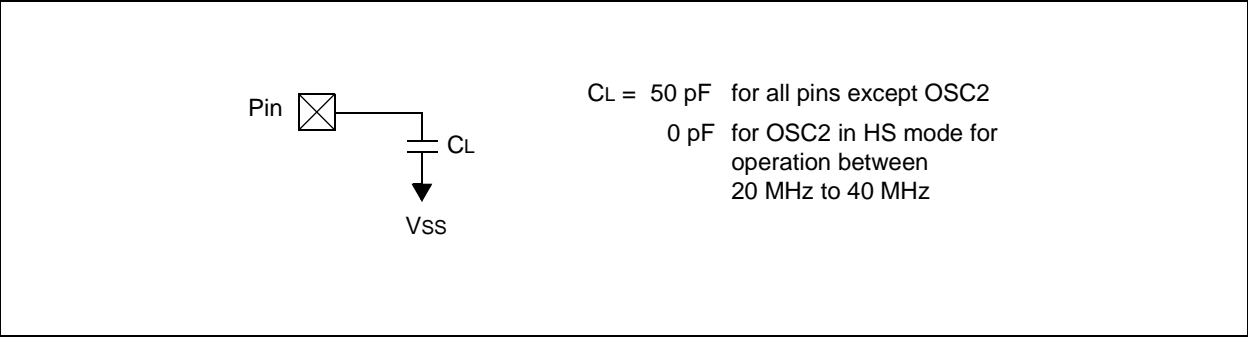


FIGURE 20-4: V_{TH} (INPUT THRESHOLD TRIP POINT VOLTAGE) OF I/O PINS vs. V_{DD}

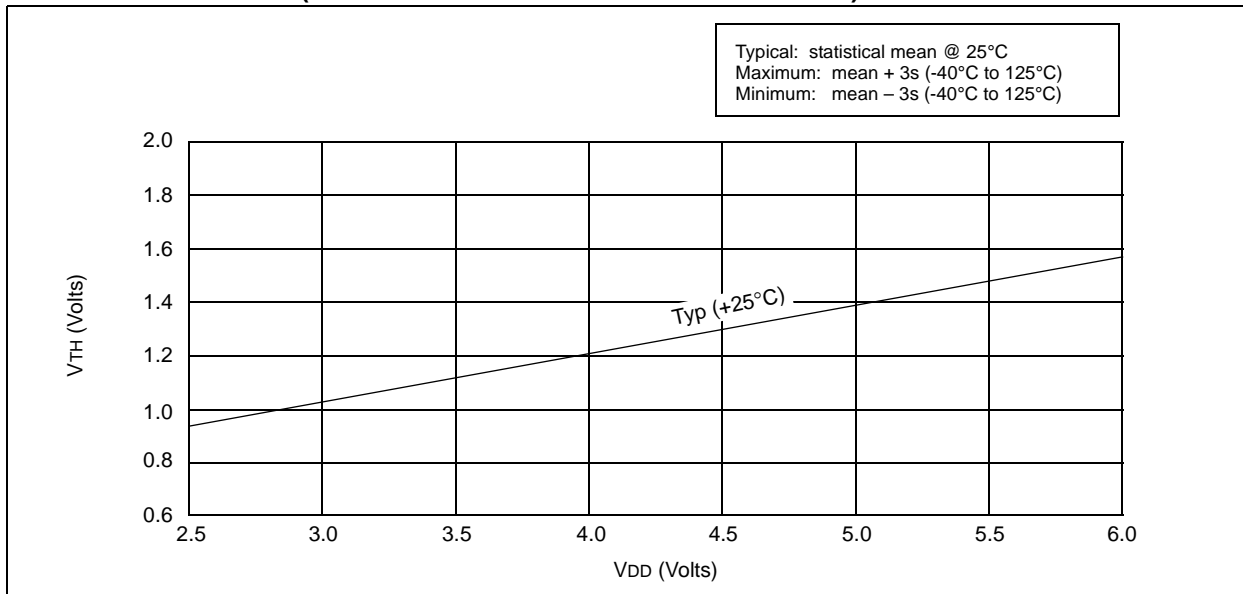


FIGURE 20-5: V_{TH} (INPUT THRESHOLD TRIP POINT VOLTAGE) OF OSC1 INPUT (HS MODE) vs. V_{DD}

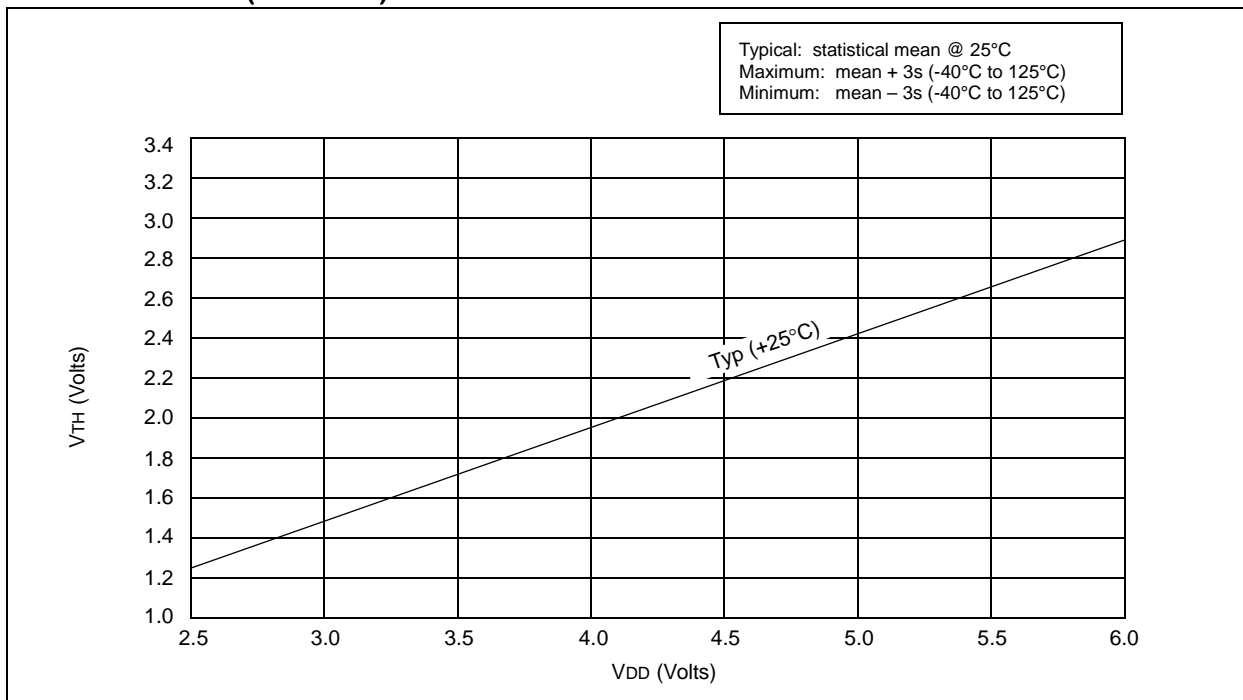
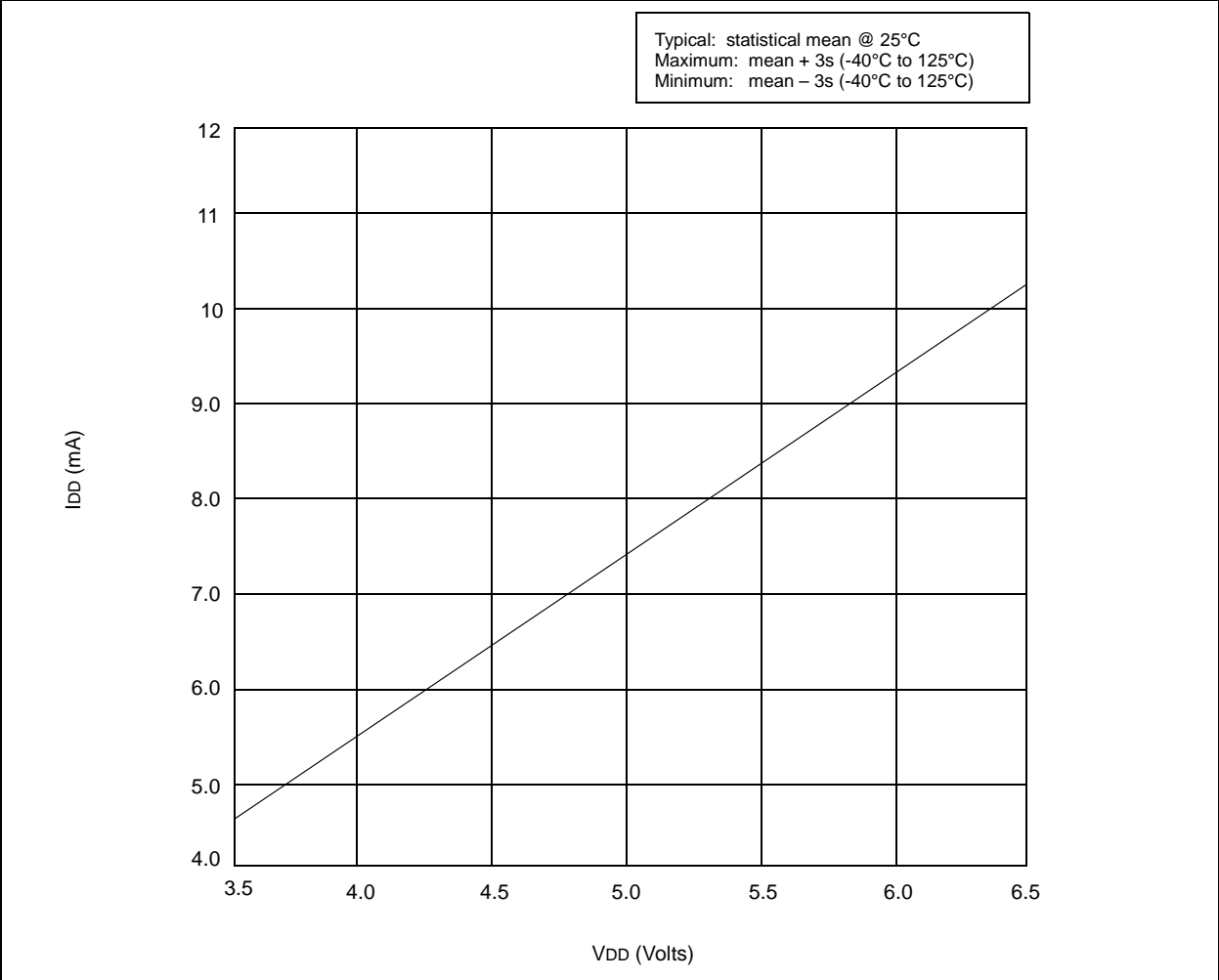


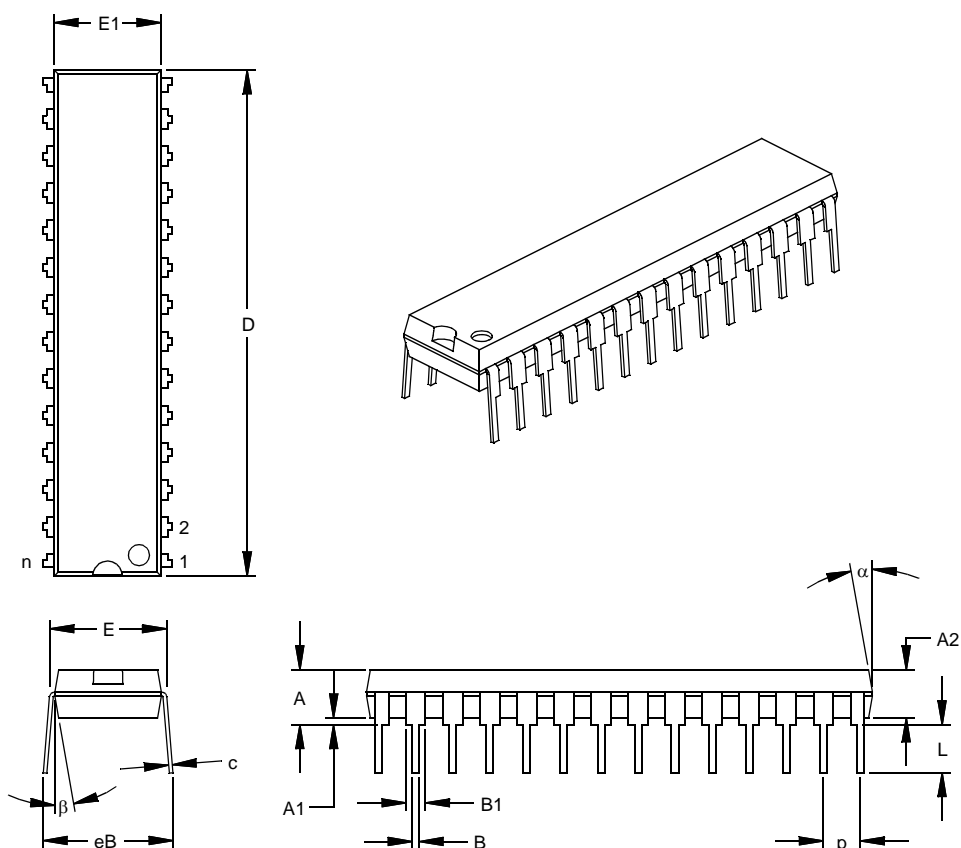
FIGURE 20-6: TYPICAL I_{DD} vs. V_{DD} (40 MHZ, WDT DISABLED, HS MODE, 70°C)



PIC16C5X

28-Lead Skinny Plastic Dual In-line (SP) – 300 mil (PDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.140	.150	.160	3.56	3.81	4.06
Molded Package Thickness	A2	.125	.130	.135	3.18	3.30	3.43
Base to Seating Plane	A1	.015			0.38		
Shoulder to Shoulder Width	E	.300	.310	.325	7.62	7.87	8.26
Molded Package Width	E1	.275	.285	.295	6.99	7.24	7.49
Overall Length	D	1.345	1.365	1.385	34.16	34.67	35.18
Tip to Seating Plane	L	.125	.130	.135	3.18	3.30	3.43
Lead Thickness	c	.008	.012	.015	0.20	0.29	0.38
Upper Lead Width	B1	.040	.053	.065	1.02	1.33	1.65
Lower Lead Width	B	.016	.019	.022	0.41	0.48	0.56
Overall Row Spacing	§ eB	.320	.350	.430	8.13	8.89	10.92
Mold Draft Angle Top	α	5	10	15	5	10	15
Mold Draft Angle Bottom	β	5	10	15	5	10	15

* Controlling Parameter

§ Significant Characteristic

Notes:

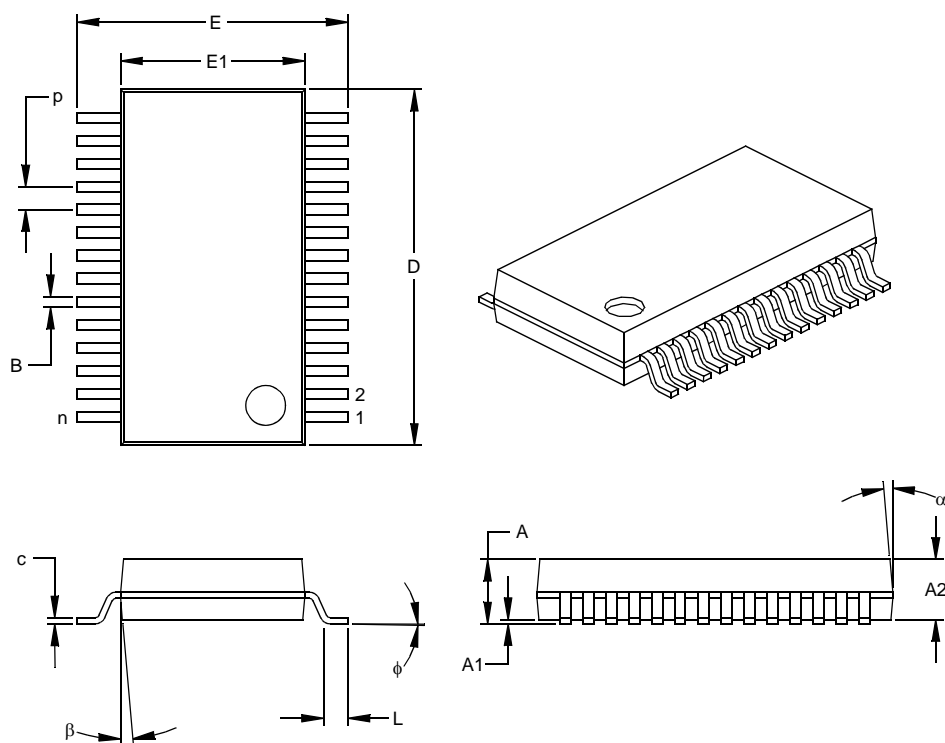
Dimension D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

JEDEC Equivalent: MO-095

Drawing No. C04-070

28-Lead Plastic Shrink Small Outline (SS) – 209 mil, 5.30 mm (SSOP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES			MILLIMETERS*		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	P		.026			0.65	
Overall Height	A	.068	.073	.078	1.73	1.85	1.98
Molded Package Thickness	A2	.064	.068	.072	1.63	1.73	1.83
Standoff §	A1	.002	.006	.010	0.05	0.15	0.25
Overall Width	E	.299	.309	.319	7.59	7.85	8.10
Molded Package Width	E1	.201	.207	.212	5.11	5.25	5.38
Overall Length	D	.396	.402	.407	10.06	10.20	10.34
Foot Length	L	.022	.030	.037	0.56	0.75	0.94
Lead Thickness	c	.004	.007	.010	0.10	0.18	0.25
Foot Angle	φ	0	4	8	0.00	101.60	203.20
Lead Width	B	.010	.013	.015	0.25	0.32	0.38
Mold Draft Angle Top	α	0	5	10	0	5	10
Mold Draft Angle Bottom	β	0	5	10	0	5	10

* Controlling Parameter
§ Significant Characteristic

Notes:

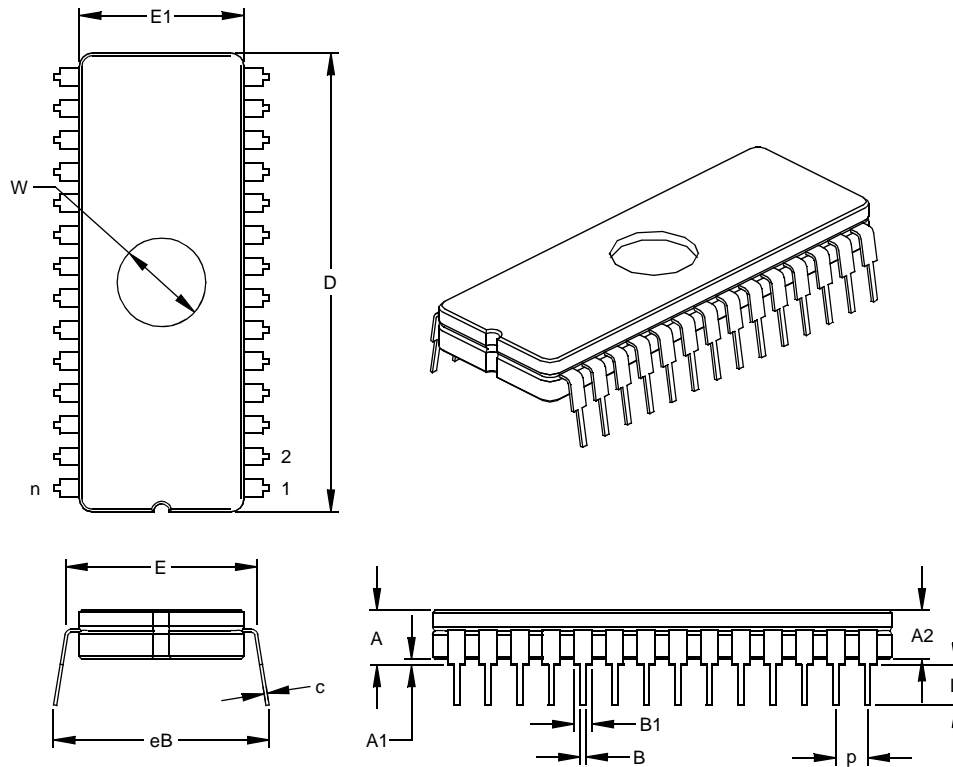
Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

JEDEC Equivalent: MS-150

Drawing No. C04-073

28-Lead Ceramic Dual In-line with Window (JW) – 600 mil (CERDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.195	.210	.225	4.95	5.33	5.72
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19
Standoff	A1	.015	.038	.060	0.38	0.95	1.52
Shoulder to Shoulder Width	E	.595	.600	.625	15.11	15.24	15.88
Ceramic Pkg. Width	E1	.514	.520	.526	13.06	13.21	13.36
Overall Length	D	1.430	1.460	1.490	36.32	37.08	37.85
Tip to Seating Plane	L	.125	.138	.150	3.18	3.49	3.81
Lead Thickness	c	.008	.010	.012	0.20	0.25	0.30
Upper Lead Width	B1	.050	.058	.065	1.27	1.46	1.65
Lower Lead Width	B	.016	.020	.023	0.41	0.51	0.58
Overall Row Spacing	§	eB	.610	.660	15.49	16.76	18.03
Window Diameter	W	.270	.280	.290	6.86	7.11	7.37

* Controlling Parameter
 § Significant Characteristic
 JEDEC Equivalent: MO-103
 Drawing No. C04-013

APPENDIX A: COMPATIBILITY

To convert code written for PIC16CXX to PIC16C5X, the user should take the following steps:

1. Check any `CALL`, `GOTO` or instructions that modify the PC to determine if any program memory page select operations (PA2, PA1, PA0 bits) need to be made.
2. Revisit any computed jump operations (write to PC or add to PC, etc.) to make sure page bits are set properly under the new scheme.
3. Eliminate any special function register page switching. Redefine data variables to reallocate them.
4. Verify all writes to STATUS, OPTION, and FSR registers since these have changed.
5. Change RESET vector to proper value for processor used.
6. Remove any use of the `ADDLW`, `RETURN` and `SUBLW` instructions.
7. Rewrite any code segments that use interrupts.

APPENDIX B: REVISION HISTORY

Revision KE (January 2013)

Added a note to each package outline drawing.