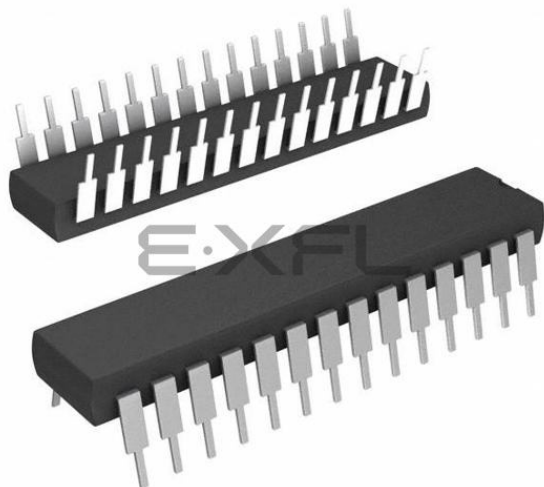




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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	20
Program Memory Size	3KB (2K x 12)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	72 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 6.25V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c57-rci-sp

PIC16C5X

NOTES:

6.3 STATUS Register

This register contains the arithmetic status of the ALU, the RESET status and the page preselect bits for program memories larger than 512 words.

The STATUS Register can be the destination for any instruction, as with any other register. If the STATUS Register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the $\overline{TO}$ and $\overline{PD}$ bits are not

writable. Therefore, the result of an instruction with the STATUS Register as destination may be different than intended.

For example, `CLRF STATUS` will clear the upper three bits and set the Z bit. This leaves the STATUS Register as `000u u1uu` (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF` and `MOVWF` instructions be used to alter the STATUS Register because these instructions do not affect the Z, DC or C bits from the STATUS Register. For other instructions which do affect STATUS Bits, see Section 10.0, Instruction Set Summary.

REGISTER 6-1: STATUS REGISTER (ADDRESS: 03h)

R/W-0	R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
PA2	PA1	PA0	$\overline{TO}$	$\overline{PD}$	Z	DC	C
bit 7							
							bit 0

bit 7: **PA2:** This bit unused at this time.

Use of the PA2 bit as a general purpose read/write bit is not recommended, since this may affect upward compatibility with future products.

bit 6-5: **PA<1:0>:** Program page preselect bits (PIC16C56/CR56)(PIC16C57/CR57)(PIC16C58/CR58)

00 = Page 0 (000h - 1FFh) - PIC16C56/CR56, PIC16C57/CR57, PIC16C58/CR58

01 = Page 1 (200h - 3FFh) - PIC16C56/CR56, PIC16C57/CR57, PIC16C58/CR58

10 = Page 2 (400h - 5FFh) - PIC16C57/CR57, PIC16C58/CR58

11 = Page 3 (600h - 7FFh) - PIC16C57/CR57, PIC16C58/CR58

Each page is 512 words.

Using the PA<1:0> bits as general purpose read/write bits in devices which do not use them for program page preselect is not recommended since this may affect upward compatibility with future products.

bit 4: **$\overline{TO}$:** Time-out bit

1 = After power-up, `CLRWDT` instruction, or `SLEEP` instruction

0 = A WDT time-out occurred

bit 3: **$\overline{PD}$:** Power-down bit

1 = After power-up or by the `CLRWDT` instruction

0 = By execution of the `SLEEP` instruction

bit 2: **Z:** Zero bit

1 = The result of an arithmetic or logic operation is zero

0 = The result of an arithmetic or logic operation is not zero

bit 1: **DC:** Digit carry/borrow bit (for `ADDWF` and `SUBWF` instructions)

ADDWF

1 = A carry from the 4th low order bit of the result occurred

0 = A carry from the 4th low order bit of the result did not occur

SUBWF

1 = A borrow from the 4th low order bit of the result did not occur

0 = A borrow from the 4th low order bit of the result occurred

bit 0: **C:** Carry/borrow bit (for `ADDWF`, `SUBWF` and `RRF`, `RLF` instructions)

ADDWF

1 = A carry occurred

0 = A carry did not occur

SUBWF

1 = A borrow did not occur

0 = A borrow occurred

RRF or RLF

Loaded with LSb or MSb, respectively

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

1 = bit is set

0 = bit is cleared

x = bit is unknown

PIC16C5X

6.4 OPTION Register

The OPTION Register is a 6-bit wide, write-only register which contains various control bits to configure the Timer0/WDT prescaler and Timer0.

By executing the OPTION instruction, the contents of the W Register will be transferred to the OPTION Register. A RESET sets the OPTION<5:0> bits.

REGISTER 6-2: OPTION REGISTER

U-0	U-0	W-1	W-1	W-1	W-1	W-1	W-1
—	—	T0CS	TOSE	PSA	PS2	PS1	PS0
bit 7							bit 0

bit 7-6: **Unimplemented:** Read as '0'

bit 5: **T0CS:** Timer0 clock source select bit
1 = Transition on T0CKI pin
0 = Internal instruction cycle clock (CLKOUT)

bit 4: **TOSE:** Timer0 source edge select bit
1 = Increment on high-to-low transition on T0CKI pin
0 = Increment on low-to-high transition on T0CKI pin

bit 3: **PSA:** Prescaler assignment bit
1 = Prescaler assigned to the WDT
0 = Prescaler assigned to Timer0

bit 2-0: **PS<2:0>:** Prescaler rate select bits

Bit Value	Timer0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

Legend:

R = Readable bit
-n = Value at POR

W = Writable bit
1 = bit is set

U = Unimplemented bit, read as '0'
0 = bit is cleared
x = bit is unknown

PIC16C5X

RLF Rotate Left f through Carry

Syntax: `[label] RLF f,d`

Operands: $0 \leq f \leq 31$
 $d \in [0,1]$

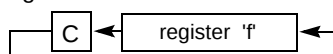
Operation: See description below

Status Affected: C

Encoding:

0011	01df	ffff
------	------	------

Description: The contents of register 'f' are rotated one bit to the left through the Carry Flag (STATUS<0>). If 'd' is 0 the result is placed in the W register. If 'd' is 1 the result is stored back in register 'f'.



Words: 1

Cycles: 1

Example: `RLF REG1, 0`

Before Instruction

REG1 = 1110 0110

C = 0

After Instruction

REG1 = 1110 0110

W = 1100 1100

C = 1

RRF Rotate Right f through Carry

Syntax: `[label] RRF f,d`

Operands: $0 \leq f \leq 31$
 $d \in [0,1]$

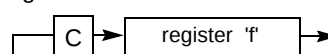
Operation: See description below

Status Affected: C

Encoding:

0011	00df	ffff
------	------	------

Description: The contents of register 'f' are rotated one bit to the right through the Carry Flag (STATUS<0>). If 'd' is 0 the result is placed in the W register. If 'd' is 1 the result is placed back in register 'f'.



Words: 1

Cycles: 1

Example: `RRF REG1, 0`

Before Instruction

REG1 = 1110 0110

C = 0

After Instruction

REG1 = 1110 0110

W = 0111 0011

C = 0

SLEEP Enter SLEEP Mode

Syntax: `[label] SLEEP`

Operands: None

Operation: 00h → WDT;
 0 → WDT prescaler; if assigned
 1 → $\overline{TO}$;
 0 → $\overline{PD}$

Status Affected: $\overline{TO}$, $\overline{PD}$

Encoding:

0000	0000	0011
------	------	------

Description: Time-out status bit ($\overline{TO}$) is set. The power-down status bit ($\overline{PD}$) is cleared. The WDT and its prescaler are cleared.
 The processor is put into SLEEP mode with the oscillator stopped. See section on SLEEP for more details.

Words: 1

Cycles: 1

Example: SLEEP

PIC16C5X

FIGURE 14-11: V_{TH} (INPUT THRESHOLD VOLTAGE) OF OSC1 INPUT (XT, HS, AND LP MODES) vs. V_{DD}

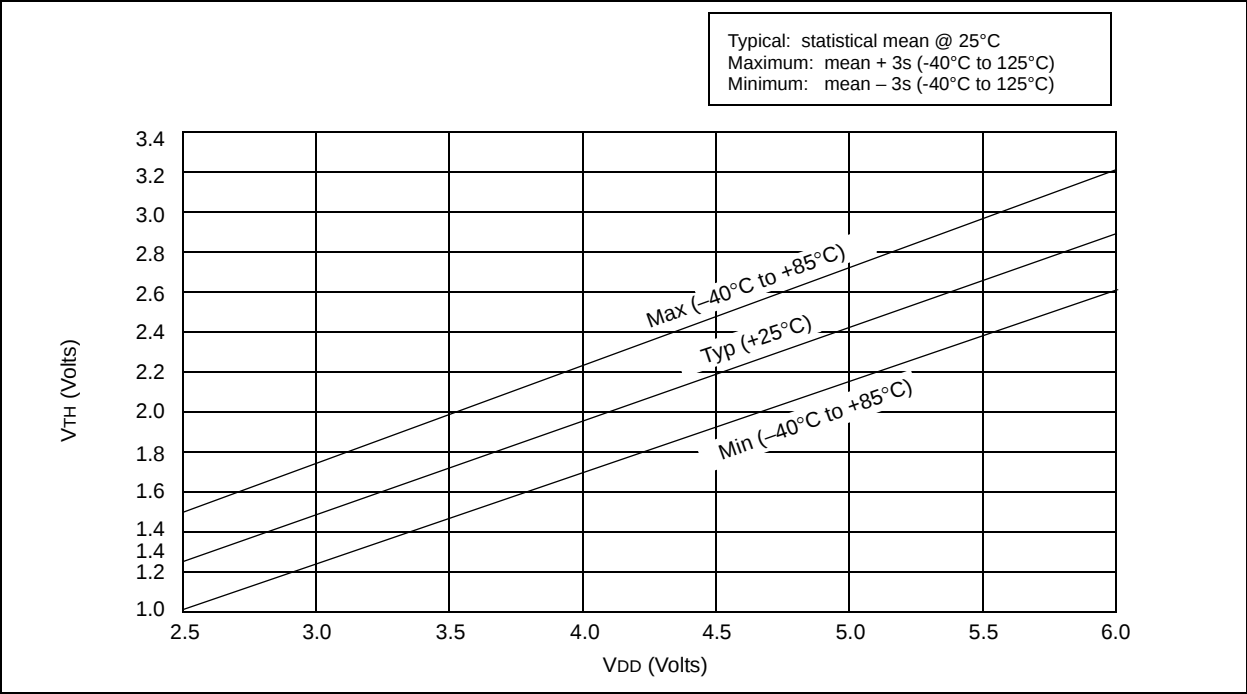


FIGURE 14-12: TYPICAL I_{DD} VS. FREQUENCY (EXTERNAL CLOCK, 25°C)

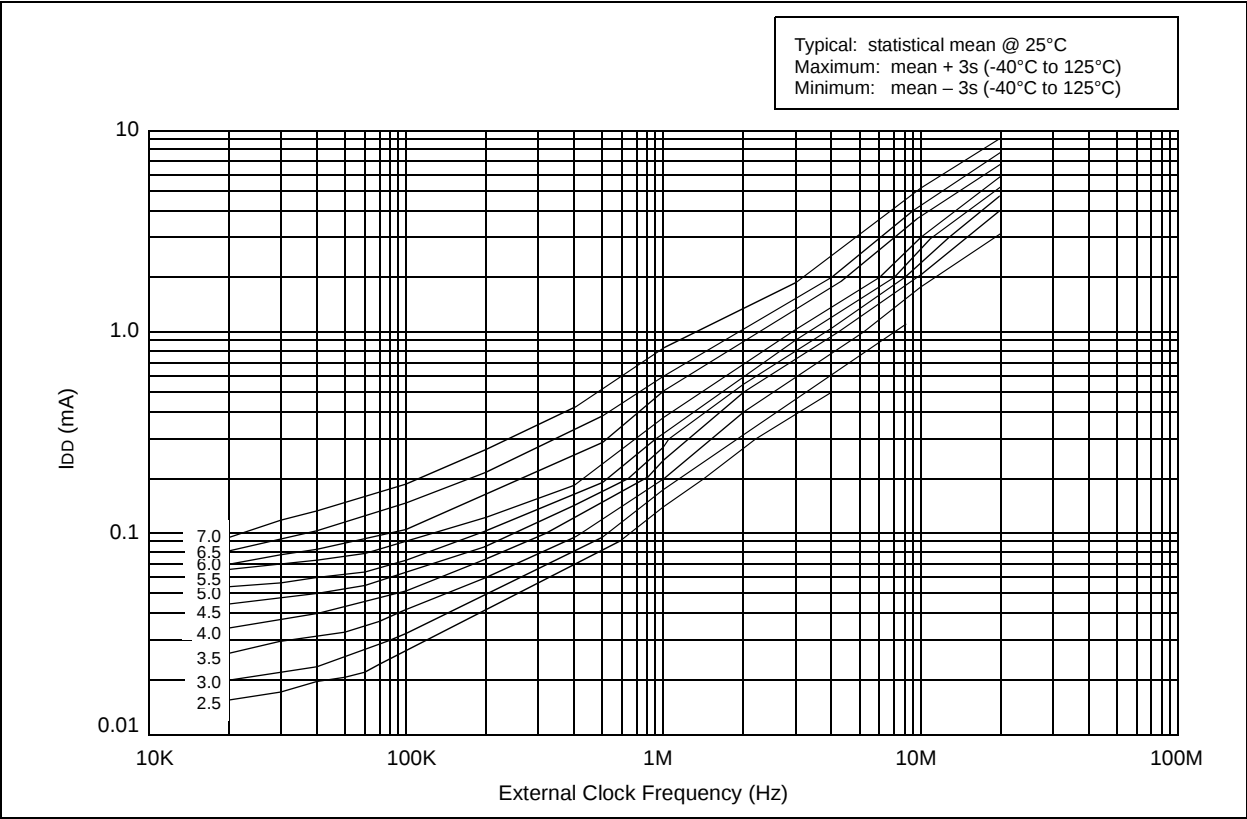


FIGURE 14-21: PORTA, B AND C IoL vs. VOL, VDD = 3 V

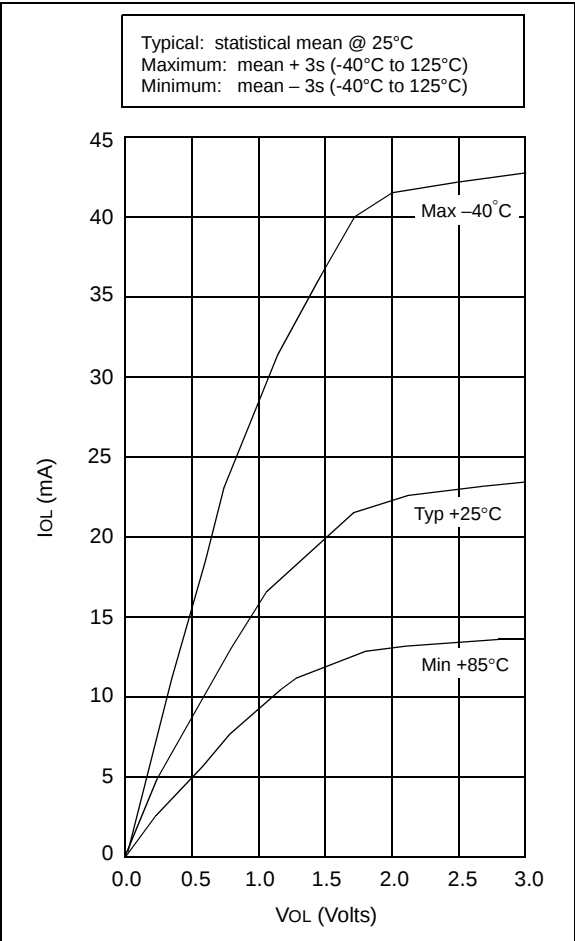
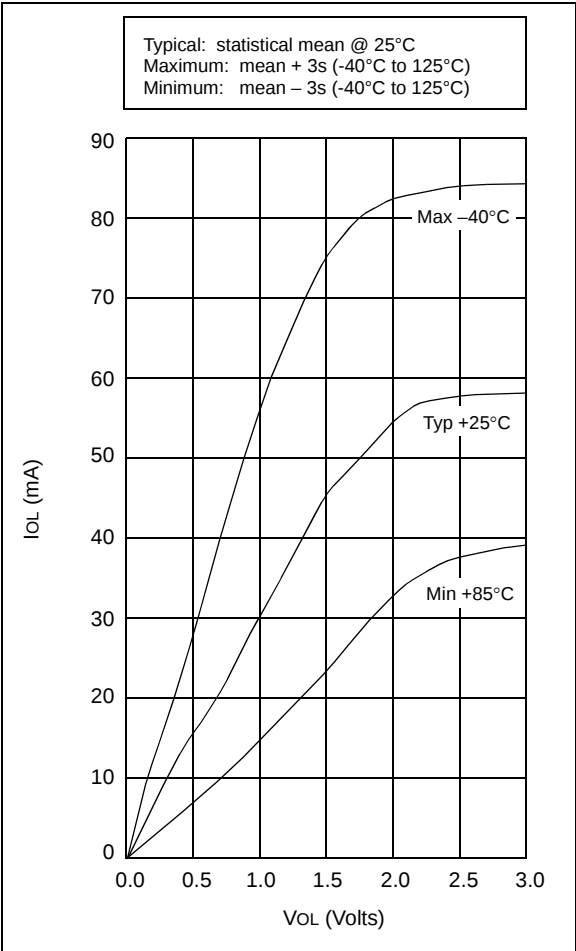


FIGURE 14-22: PORTA, B AND C IoL vs. VOL, VDD = 5 V



PIC16C5X

15.5 Timing Parameter Symbolology and Load Conditions

The timing parameter symbols have been created with one of the following formats:

- 1. TppS2ppS
- 2. TppS

T		T	Time
F	Frequency		

Lowercase letters (pp) and their meanings:

pp		mc	$\overline{\text{MCLR}}$
2	to	osc	oscillator
ck	CLKOUT	os	OSC1
cy	cycle time	t0	T0CKI
drt	device reset timer	wdt	watchdog timer
io	I/O port		

Uppercase letters and their meanings:

S		P	Period
F	Fall	R	Rise
H	High	V	Valid
I	Invalid (Hi-impedance)	Z	Hi-impedance
L	Low		

FIGURE 15-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS - PIC16C54A

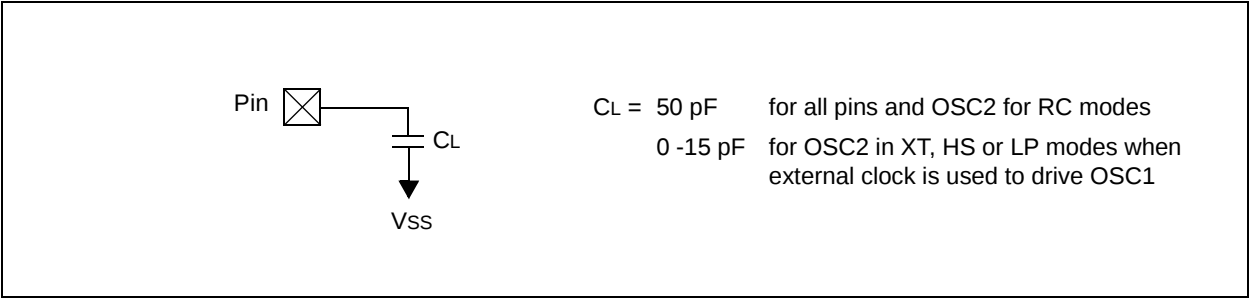


FIGURE 16-14: TYPICAL I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 300 pF, 25°C)

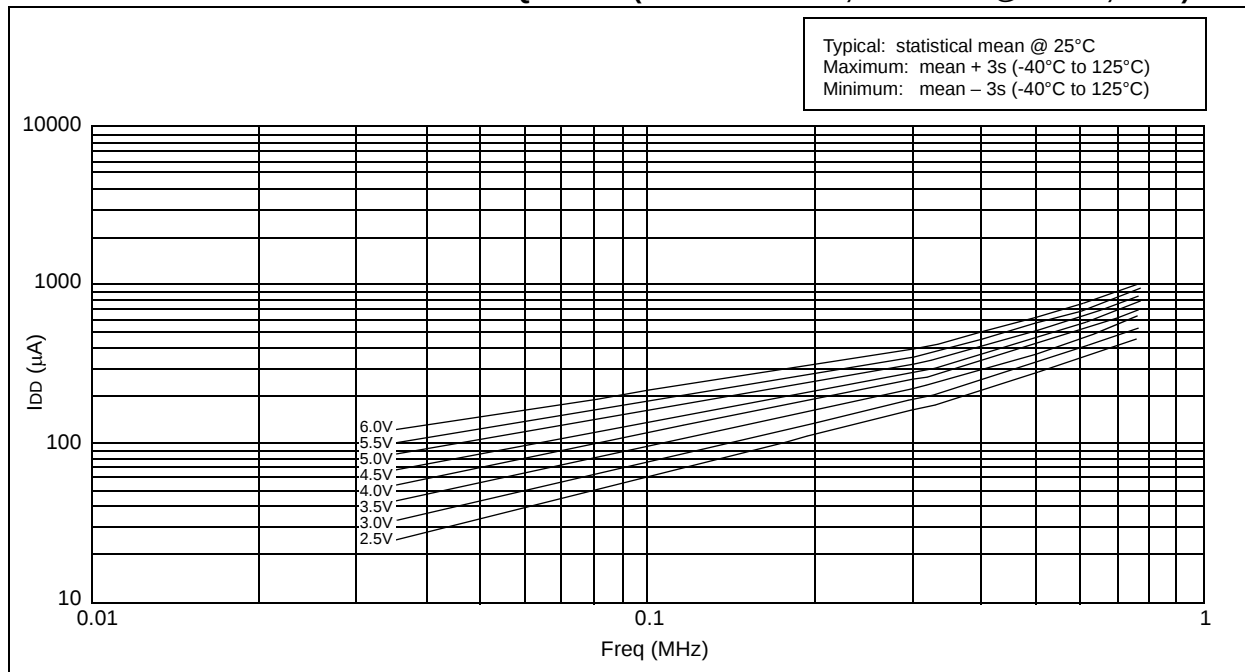
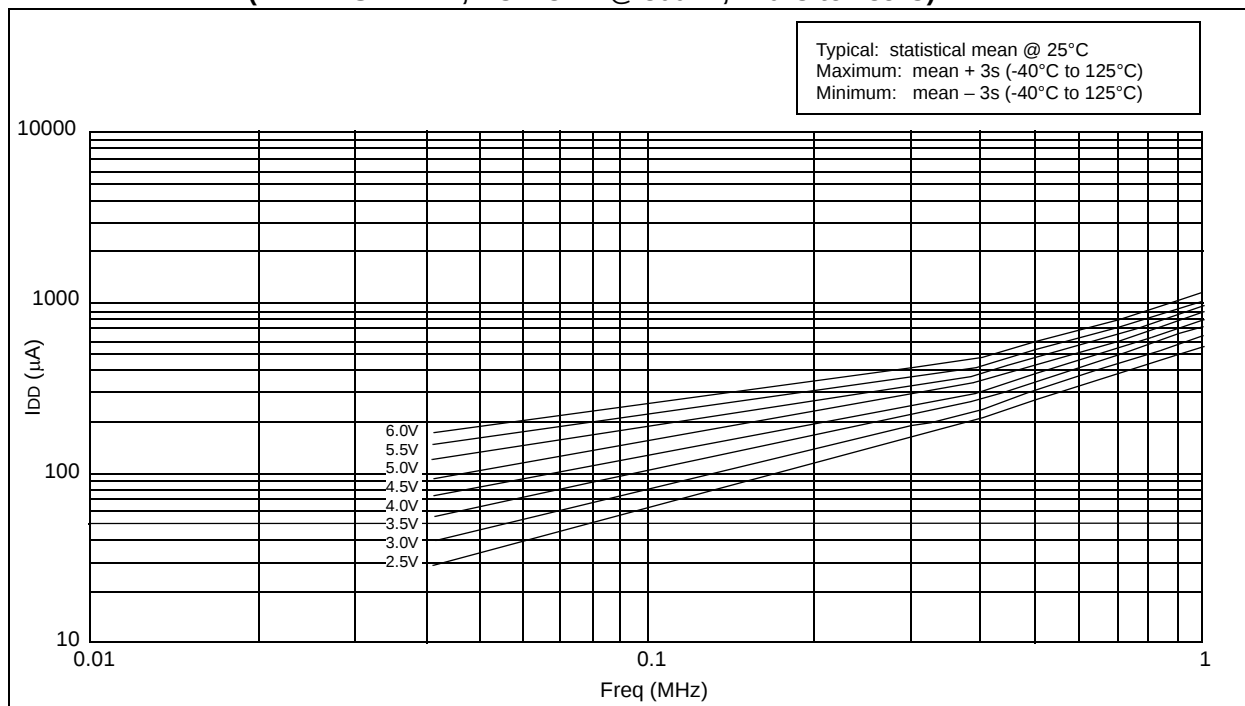


FIGURE 16-15: MAXIMUM I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 300 pF, -40°C to +85°C)



PIC16C5X

NOTES:

PIC16C5X

17.3 DC Characteristics: PIC16C54C/C55A/C56A/C57C/C58B-04, 20 (Commercial, Industrial, Extended) PIC16LC54C/LC55A/LC56A/LC57C/LC58B-04 (Commercial, Industrial) PIC16CR54C/CR56A/CR57C/CR58B-04, 20 (Commercial, Industrial, Extended) PIC16LCR54C/LCR56A/LCR57C/LCR58B-04 (Commercial, Industrial)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature				
			0°C ≤ TA ≤ +70°C for commercial				
			–40°C ≤ TA ≤ +85°C for industrial				
			–40°C ≤ TA ≤ +125°C for extended				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
D030	VIL	Input Low Voltage I/O Ports I/O Ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1 (Schmitt Trigger) OSC1	VSS VSS VSS VSS VSS VSS	— — — — — —	0.8 V 0.15 VDD 0.15 VDD 0.15 VDD 0.15 VDD 0.3 VDD	V V V V V V	4.5V < VDD ≤ 5.5V Otherwise RC mode only ⁽³⁾ XT, HS and LP modes
D040	VIH	Input High Voltage I/O ports I/O ports MCLR (Schmitt Trigger) T0CKI (Schmitt Trigger) OSC1 (Schmitt Trigger) OSC1	2.0 0.25 VDD+0.8 0.85 VDD 0.85 VDD 0.85 VDD 0.7 VDD	— — — — — —	VDD VDD VDD VDD VDD VDD	V V V V V V	4.5V < VDD ≤ 5.5V Otherwise RC mode only ⁽³⁾ XT, HS and LP modes
D050	VHYS	Hysteresis of Schmitt Trigger inputs	0.15 VDD*	—	—	V	
D060	IIL	Input Leakage Current^(1,2) I/O ports MCLR MCLR T0CKI OSC1	-1.0 -5.0 -3.0 -3.0	0.5 — 0.5 0.5 0.5	+1.0 +5.0 +3.0 +3.0 —	μA μA μA μA μA	For VDD ≤ 5.5V: VSS ≤ VPIN ≤ VDD, pin at hi-impedance VPIN = VSS +0.25V VPIN = VDD VSS ≤ VPIN ≤ VDD VSS ≤ VPIN ≤ VDD, XT, HS and LP modes
D080	VOL	Output Low Voltage I/O ports OSC2/CLKOUT	— —	— —	0.6 0.6	V V	IOL = 8.7 mA, VDD = 4.5V IOL = 1.6 mA, VDD = 4.5V, RC mode only
D090	VOH	Output High Voltage⁽²⁾ I/O ports OSC2/CLKOUT	VDD - 0.7 VDD - 0.7	— —	— —	V V	IOH = -5.4 mA, VDD = 4.5V IOH = -1.0 mA, VDD = 4.5V, RC mode only

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is based on characterization results at 25°C. This data is for design guidance only and is not tested.

Note 1: The leakage current on the MCLR/VPIN pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltage.

2: Negative current is defined as coming out of the pin.

3: For the RC mode, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC16C5X be driven with external clock in RC mode.

FIGURE 17-8: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER TIMING - PIC16C5X, PIC16CR5X

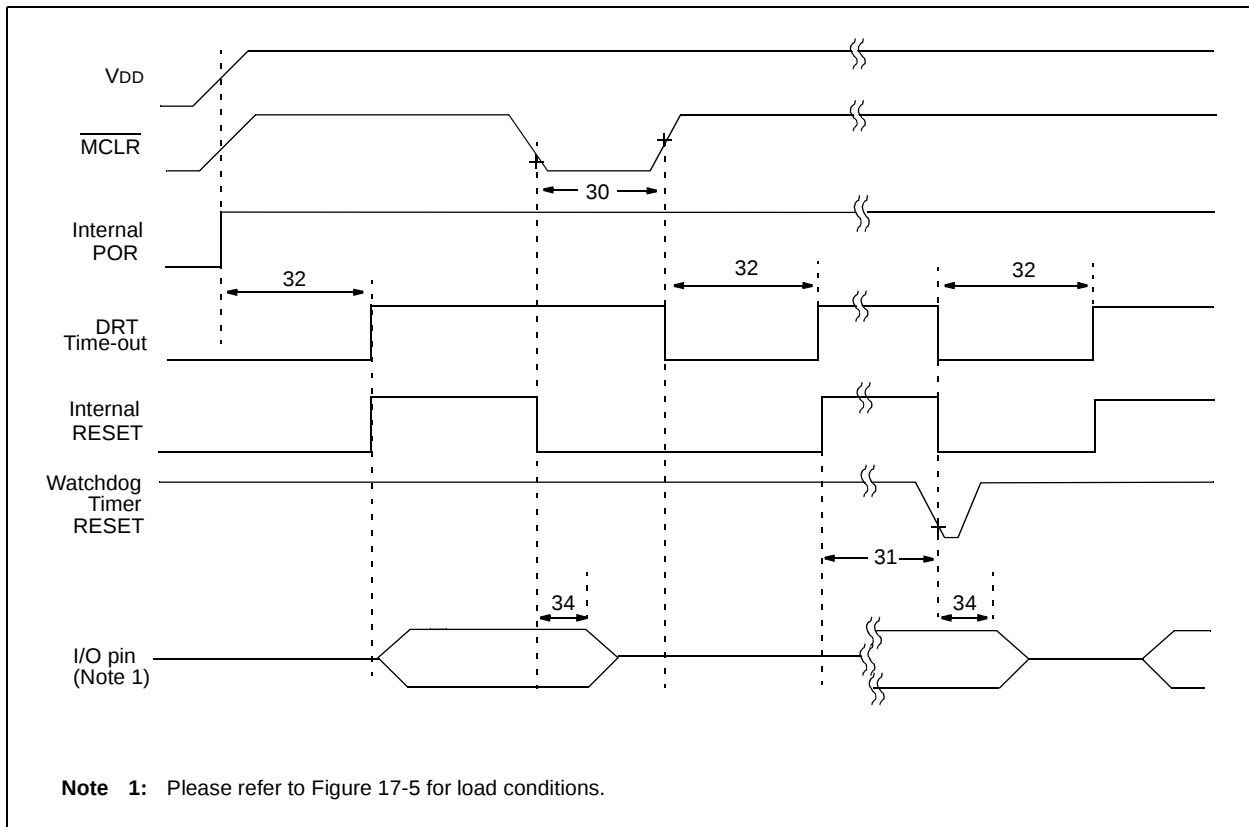


TABLE 17-3: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER - PIC16C5X, PIC16CR5X

Standard Operating Conditions (unless otherwise specified)							
AC Characteristics							
Operating Temperature 0°C ≤ TA ≤ +70°C for commercial -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended							
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
30	TmcL	MCLR Pulse Width (low)	1000*	—	—	ns	VDD = 5.0V
31	Twdt	Watchdog Timer Time-out Period (No Prescaler)	9.0*	18*	30*	ms	VDD = 5.0V (Comm)
32	TDRT	Device Reset Timer Period	9.0*	18*	30*	ms	VDD = 5.0V (Comm)
34	Tioz	I/O Hi-impedance from MCLR Low	100*	300*	1000*	ns	

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

PIC16C5X

FIGURE 18-10: V_{TH} (INPUT THRESHOLD TRIP POINT VOLTAGE) OF OSC1 INPUT (IN XT, HS AND LP MODES) vs. V_{DD}

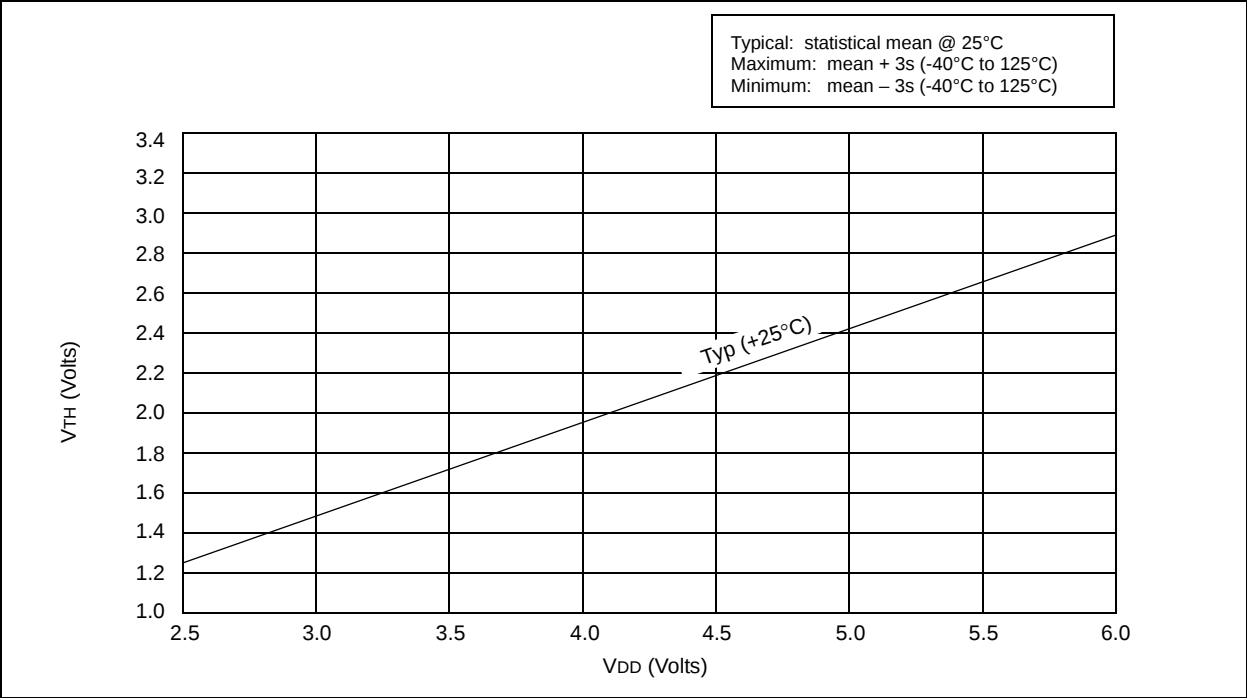
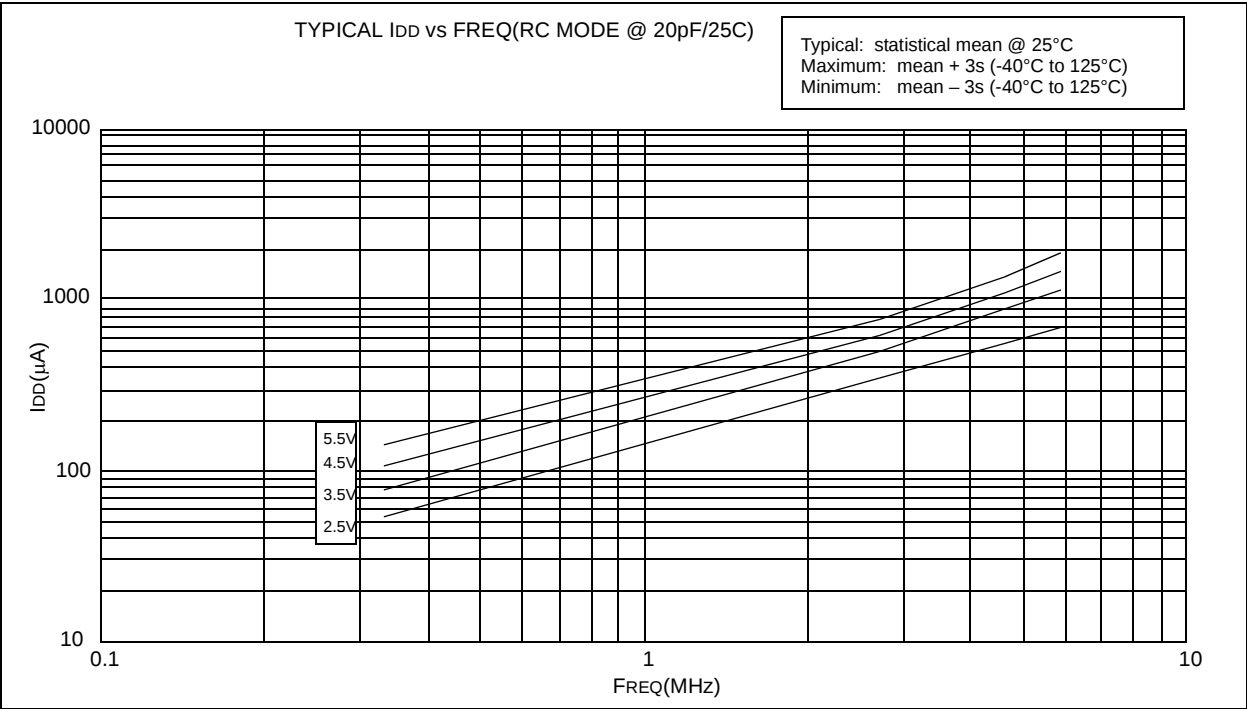


FIGURE 18-11: TYPICAL I_{DD} vs. FREQUENCY (WDT DISABLED, RC MODE @ 20 pF, 25°C)



PIC16C5X

FIGURE 19-5: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER TIMING - PIC16C5X-40

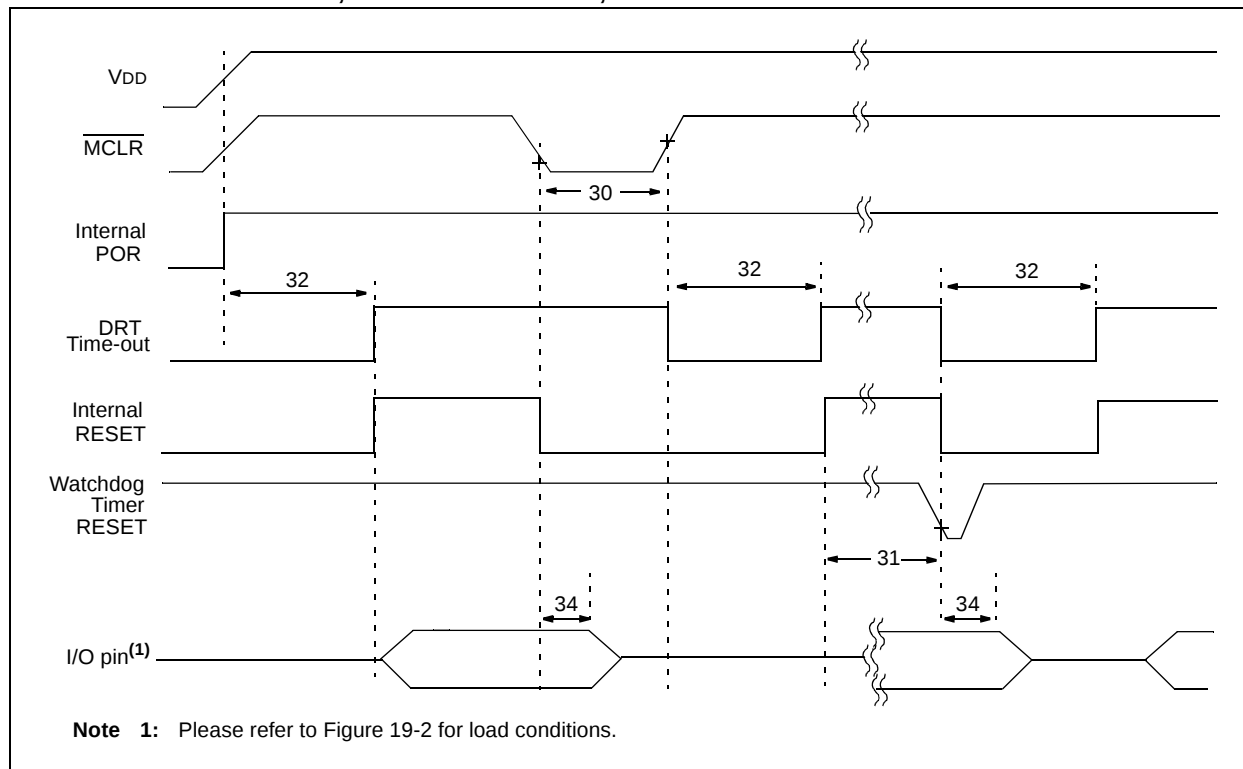


TABLE 19-3: RESET, WATCHDOG TIMER, AND DEVICE RESET TIMER - PIC16C5X-40

Standard Operating Conditions (unless otherwise specified)							
AC Characteristics							
Operating Temperature $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ (commercial)							
Operating Voltage V_{DD} range is described in Section 19.1.							
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
30	Tmcl	MCLR Pulse Width (low)	1000*	—	—	ns	$V_{DD} = 5.0\text{V}$
31	Twdt	Watchdog Timer Time-out Period (No Prescaler)	9.0*	18*	30*	ms	$V_{DD} = 5.0\text{V}$ (Comm)
32	TDRT	Device Reset Timer Period	9.0*	18*	30*	ms	$V_{DD} = 5.0\text{V}$ (Comm)
34	Tioz	I/O Hi-impedance from MCLR Low	100*	300*	1000*	ns	

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 19-6: TIMER0 CLOCK TIMINGS - PIC16C5X-40

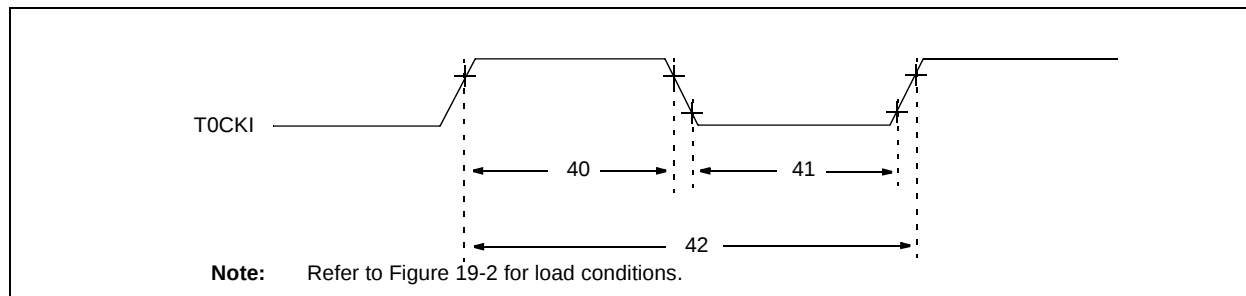


TABLE 19-4: TIMER0 CLOCK REQUIREMENTS PIC16C5X-40

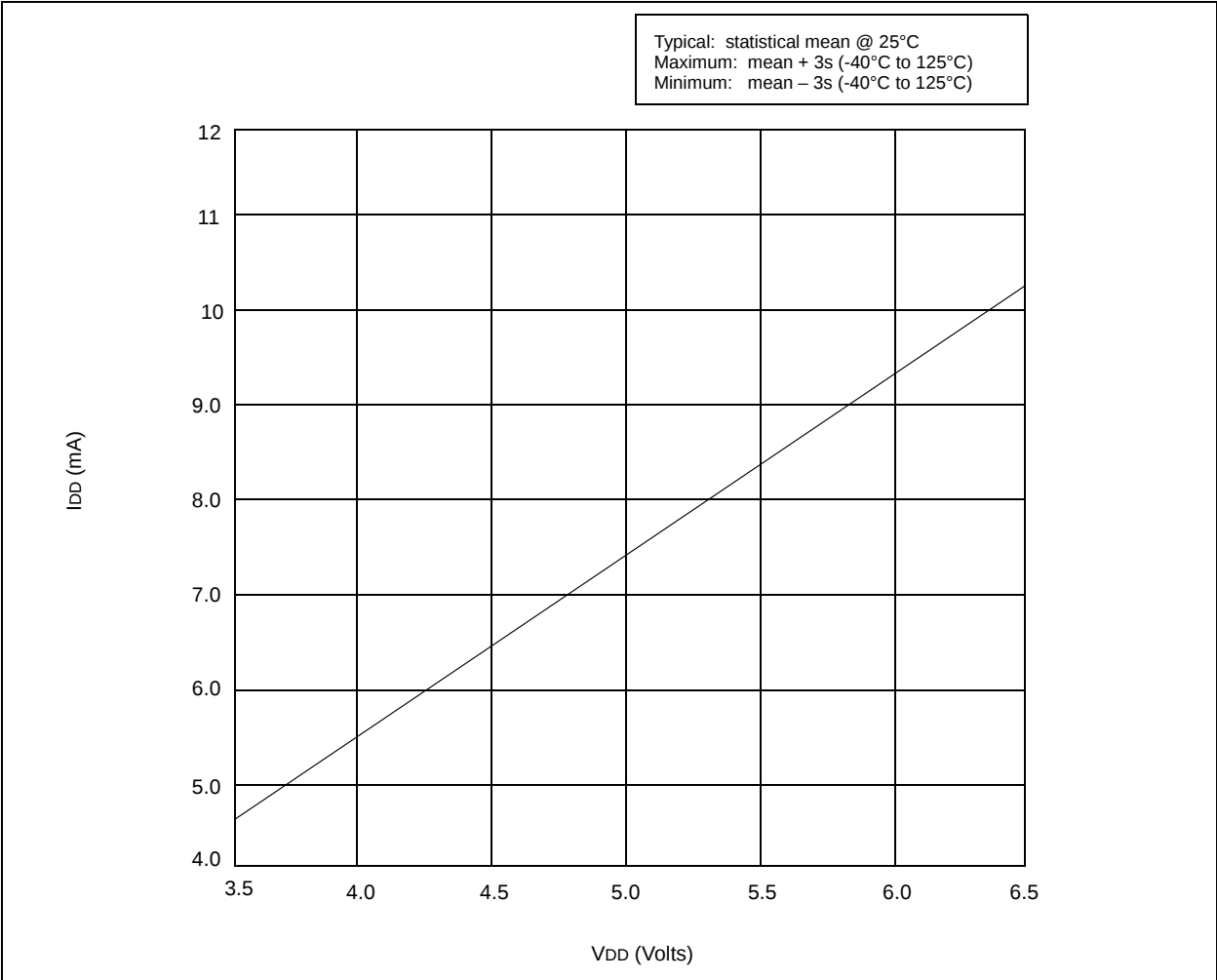
AC Characteristics			Standard Operating Conditions (unless otherwise specified)				
			Operating Temperature $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ for commercial				
Param No.	Symbol	Characteristic	Min	Typ†	Max	Units	Conditions
40	Tt0H	T0CKI High Pulse Width - No Prescaler	$0.5 T_{CY} + 20^*$	—	—	ns	
		- With Prescaler	10^*	—	—	ns	
41	Tt0L	T0CKI Low Pulse Width - No Prescaler	$0.5 T_{CY} + 20^*$	—	—	ns	
		- With Prescaler	10^*	—	—	ns	
42	Tt0P	T0CKI Period	$20 \text{ or } \frac{T_{CY} + 40^*}{N}$	—	—	ns	Whichever is greater. N = Prescale Value (1, 2, 4,..., 256)

* These parameters are characterized but not tested.

† Data in the Typical ("Typ") column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

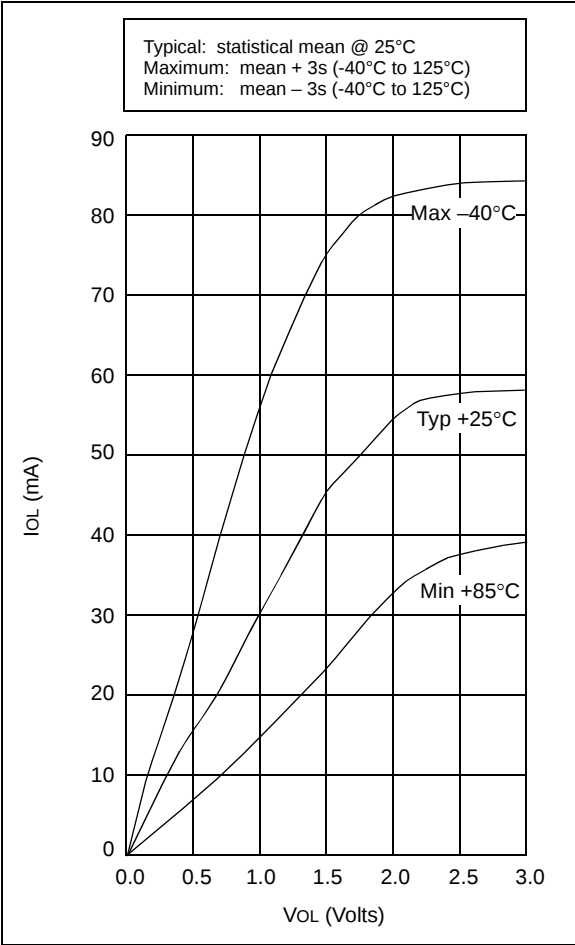
PIC16C5X

FIGURE 20-6: TYPICAL I_{DD} vs. V_{DD} (40 MHZ, WDT DISABLED, HS MODE, 70°C)



PIC16C5X

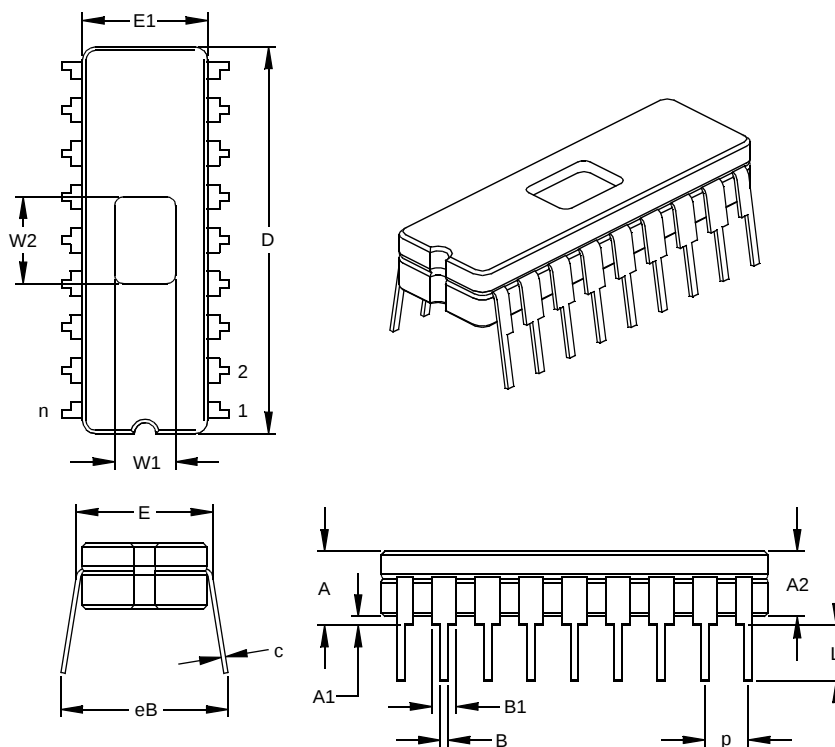
FIGURE 20-9: I_{OL} vs. V_{OL} , $V_{DD} = 5\text{ V}$



PIC16C5X

18-Lead Ceramic Dual In-line with Window (JW) – 300 mil (CERDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		18			18	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.170	.183	.195	4.32	4.64	4.95
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19
Standoff	A1	.015	.023	.030	0.38	0.57	0.76
Shoulder to Shoulder Width	E	.300	.313	.325	7.62	7.94	8.26
Ceramic Pkg. Width	E1	.285	.290	.295	7.24	7.37	7.49
Overall Length	D	.880	.900	.920	22.35	22.86	23.37
Tip to Seating Plane	L	.125	.138	.150	3.18	3.49	3.81
Lead Thickness	c	.008	.010	.012	0.20	0.25	0.30
Upper Lead Width	B1	.050	.055	.060	1.27	1.40	1.52
Lower Lead Width	B	.016	.019	.021	0.41	0.47	0.53
Overall Row Spacing	§ eB	.345	.385	.425	8.76	9.78	10.80
Window Width	W1	.130	.140	.150	3.30	3.56	3.81
Window Length	W2	.190	.200	.210	4.83	5.08	5.33

* Controlling Parameter

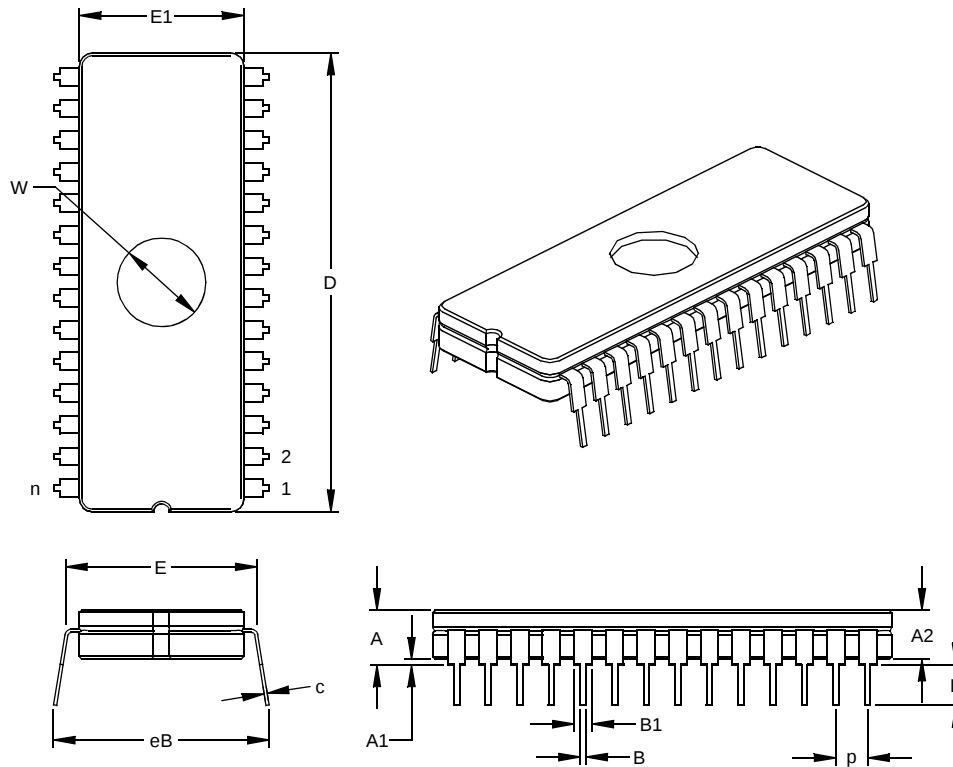
§ Significant Characteristic

JEDEC Equivalent: MO-036

Drawing No. C04-010

28-Lead Ceramic Dual In-line with Window (JW) – 600 mil (CERDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.195	.210	.225	4.95	5.33	5.72
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19
Standoff	A1	.015	.038	.060	0.38	0.95	1.52
Shoulder to Shoulder Width	E	.595	.600	.625	15.11	15.24	15.88
Ceramic Pkg. Width	E1	.514	.520	.526	13.06	13.21	13.36
Overall Length	D	1.430	1.460	1.490	36.32	37.08	37.85
Tip to Seating Plane	L	.125	.138	.150	3.18	3.49	3.81
Lead Thickness	c	.008	.010	.012	0.20	0.25	0.30
Upper Lead Width	B1	.050	.058	.065	1.27	1.46	1.65
Lower Lead Width	B	.016	.020	.023	0.41	0.51	0.58
Overall Row Spacing	§	eB	.610	.660	15.49	16.76	18.03
Window Diameter	W	.270	.280	.290	6.86	7.11	7.37

* Controlling Parameter
 § Significant Characteristic
 JEDEC Equivalent: MO-103
 Drawing No. C04-013

PIC16C5X

M

MCLR Reset	
Register values on	20
Memory Map	
PIC16C54/CR54/C55	25
PIC16C56/CR56	25
PIC16C57/CR57/C58/CR58	25
Memory Organization	25
MOVF	56
MOVLW	56
MOVWF	57
MPLAB C17 and MPLAB C18 C Compilers	61
MPLAB ICD In-Circuit Debugger	63
MPLAB ICE High Performance Universal In-Circuit Emulator with MPLAB IDE	62
MPLAB Integrated Development Environment Software	61
MPLINK Object Linker/MPLIB Object Librarian	62

N

NOP	57
-----------	----

O

One-Time-Programmable (OTP) Devices	7
OPTION	57
OPTION Register	30
Value on reset	20
Oscillator Configurations	15
Oscillator Types	
HS	15
LP	15
RC	15
XT	15

P

PA0 bit	29
PA1 bit	29
Paging	31
PC	31
Value on reset	20
PD bit	19, 29
Peripheral Features	1
PICDEM 1 Low Cost PIC MCU Demonstration Board	63
PICDEM 17 Demonstration Board	64
PICDEM 2 Low Cost PIC16CXX Demonstration Board	63
PICDEM 3 Low Cost PIC16CXXX Demonstration Board	64
PICSTART Plus Entry Level Development Programmer	63
Pin Configurations	2
Pinout Description - PIC16C54, PIC16CR54, PIC16C56, PIC16CR56, PIC16C58, PIC16CR58	11
Pinout Description - PIC16C55, PIC16C57, PIC16CR57 ...	12
PORTA	35
Value on reset	20
PORTB	35
Value on reset	20
PORTC	35
Value on reset	20
Power-Down Mode	47
Power-On Reset (POR)	21
Register values on	20
Prescaler	40
PRO MATE II Universal Device Programmer	63
Program Counter	31
Program Memory Organization	25
Program Verification/Code Protection	47

Q

Q cycles	13
Quick-Turnaround-Production (QTP) Devices	7

R

RC Oscillator	17
Read Only Memory (ROM) Devices	7
Read-Modify-Write	36
Register File Map	
PIC16C54, PIC16CR54, PIC16C55, PIC16C56, PIC16CR56	26
PIC16C57/CR57	27
PIC16C58/CR58	27
Registers	
Special Function	28
Value on reset	20
Reset	19
Reset on Brown-Out	23
RETLW	57
RLF	58
RRF	58

S

Serialized Quick-Turnaround-Production (SQTP) Devices...	7
SLEEP	43, 47, 58
Software Simulator (MPLAB SIM)	62
Special Features of the CPU	43
Special Function Registers	28
Stack	32
STATUS Register	9, 29
Value on reset	20
SUBWF	59
SWAPF	59

T

Timer0	
Switching Prescaler Assignment	40
Timer0 (TMR0) Module	37
TMR0 register - Value on reset	20
TMR0 with External Clock	39
Timing Diagrams and Specifications	
PIC16C54/55/56/57	74
PIC16C54A	111
PIC16C54C/CR54C/C55A/C56A/CR56A/C57C/CR57C/ C58B/CR58B	140
PIC16C54C/CR54C/C55A/C56A/CR56A/C57C/CR57C/ C58B/CR58B-40	160
PIC16CR54A	86
Timing Parameter Symbolology and Load Conditions	
PIC16C54/55/56/57	73
PIC16C54A	110
PIC16C54C/CR54C/C55A/C56A/CR56A/C57C/CR57C/ C58B/CR58B	139
PIC16C54C/CR54C/C55A/C56A/CR56A/C57C/CR57C/ C58B/CR58B-40	159
PIC16CR54A	85
TO bit	19, 29
TRIS	59
TRIS Registers	35
Value on reset	20

U

UV Erasable Devices	7
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