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## Understanding **Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

## Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

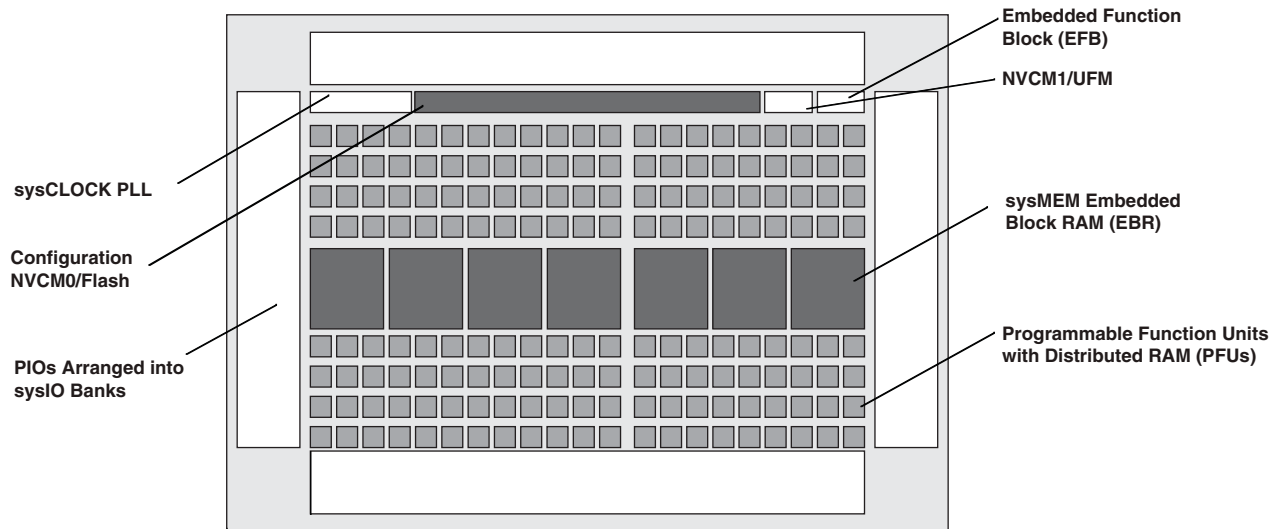
### Details

Product Status	Active
Number of LABs/CLBs	160
Number of Logic Elements/Cells	1280
Total RAM Bits	65536
Number of I/O	28
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C
Package / Case	36-UFBGA, WLCSP
Supplier Device Package	36-WLCSP (2.54x2.59)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-1300e-5uwg36ctr1k">https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-1300e-5uwg36ctr1k</a>

## Architecture Overview

The MachXO3L/LF family architecture contains an array of logic blocks surrounded by Programmable I/O (PIO). All logic density devices in this family have sysCLOCK™ PLLs and blocks of sysMEM Embedded Block RAM (EBRs). Figure 2-1 and Figure 2-2 show the block diagrams of the various family members.

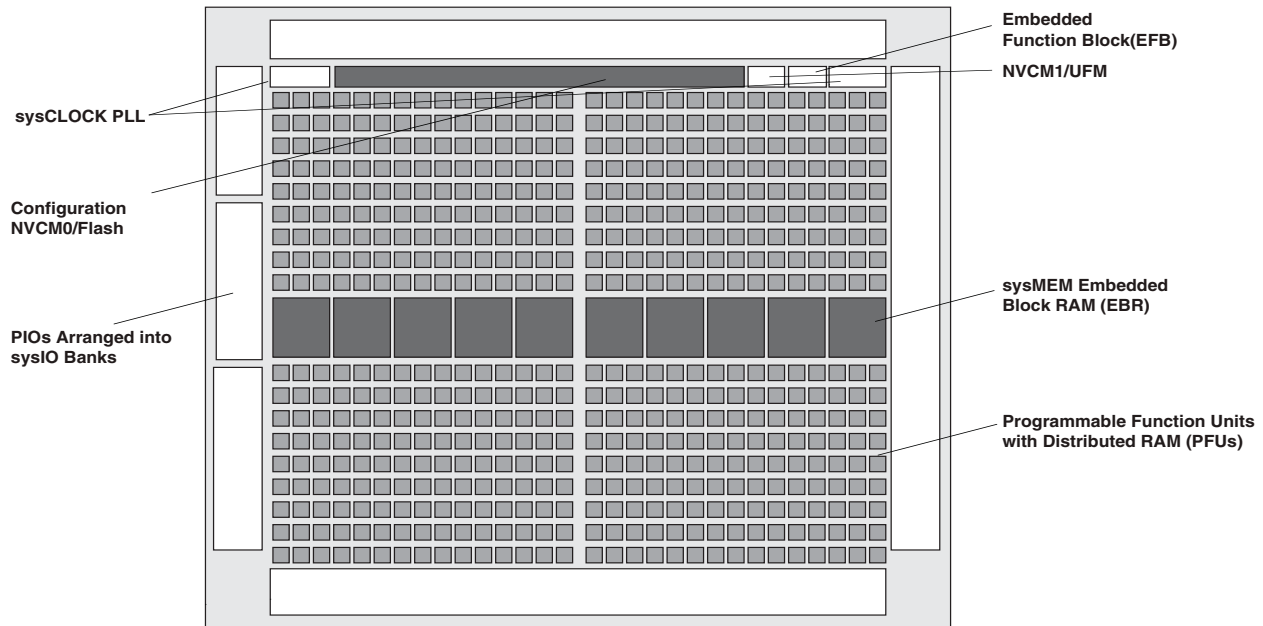
**Figure 2-1. Top View of the MachXO3L/LF-1300 Device**



**Notes:**

- MachXO3L/LF-640 is similar to MachXO3L/LF-1300. MachXO3L/LF-640 has a lower LUT count.
- MachXO3L devices have NVCM, MachXO3LF devices have Flash.

**Figure 2-2. Top View of the MachXO3L/LF-4300 Device**



- Notes:
- MachXO3L/LF-1300, MachXO3L/LF-2100, MachXO3L/LF-6900 and MachXO3L/LF-9400 are similar to MachXO3L/LF-4300. MachXO3L/LF-1300 has a lower LUT count, one PLL, and seven EBR blocks. MachXO3L/LF-2100 has a lower LUT count, one PLL, and eight EBR blocks. MachXO3L/LF-6900 has a higher LUT count, two PLLs, and 26 EBR blocks. MachXO3L/LF-9400 has a higher LUT count, two PLLs, and 48 EBR blocks.
  - MachXO3L devices have NVCM, MachXO3LF devices have Flash.

The logic blocks, Programmable Functional Unit (PFU) and sysMEM EBR blocks, are arranged in a two-dimensional grid with rows and columns. Each row has either the logic blocks or the EBR blocks. The PIO cells are located at the periphery of the device, arranged in banks. The PFU contains the building blocks for logic, arithmetic, RAM, ROM, and register functions. The PIOs utilize a flexible I/O buffer referred to as a sysIO buffer that supports operation with a variety of interface standards. The blocks are connected with many vertical and horizontal routing channel resources. The place and route software tool automatically allocates these routing resources.

In the MachXO3L/LF family, the number of sysIO banks varies by device. There are different types of I/O buffers on the different banks. Refer to the details in later sections of this document. The sysMEM EBRs are large, dedicated fast memory blocks. These blocks can be configured as RAM, ROM or FIFO. FIFO support includes dedicated FIFO pointer and flag “hard” control logic to minimize LUT usage.

The MachXO3L/LF registers in PFU and sysIO can be configured to be SET or RESET. After power up and device is configured, the device enters into user mode with these registers SET/RESET according to the configuration setting, allowing device entering to a known state for predictable system function.

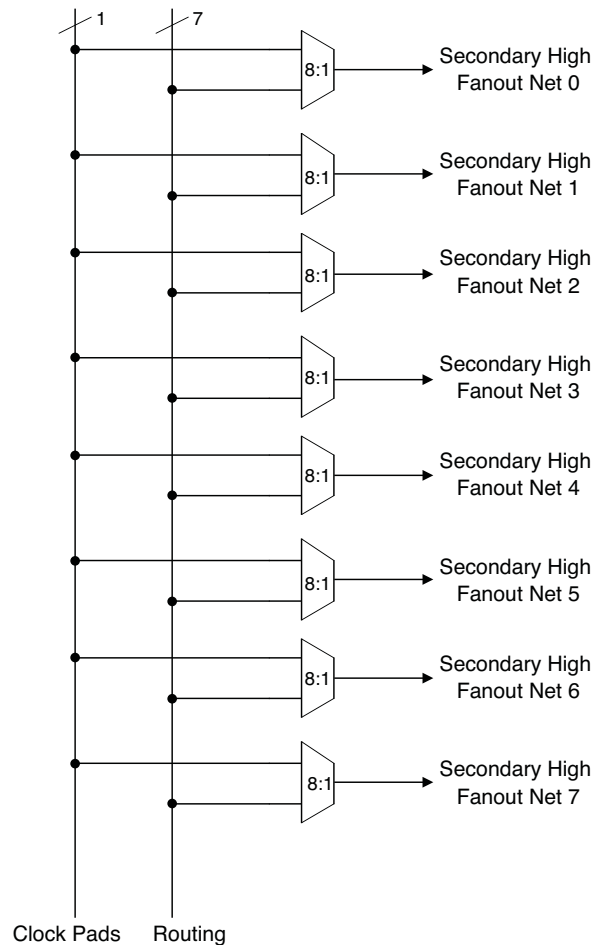
The MachXO3L/LF architecture also provides up to two sysCLOCK Phase Locked Loop (PLL) blocks. These blocks are located at the ends of the on-chip NVCM/Flash block. The PLLs have multiply, divide, and phase shifting capabilities that are used to manage the frequency and phase relationships of the clocks.

MachXO3L/LF devices provide commonly used hardened functions such as SPI controller, I<sup>2</sup>C controller and timer/counter.

MachXO3LF devices also provide User Flash Memory (UFM). These hardened functions and the UFM interface to the core logic and routing through a WISHBONE interface. The UFM can also be accessed through the SPI, I<sup>2</sup>C and JTAG ports.

Every device in the family has a JTAG port that supports programming and configuration of the device as well as access to the user logic. The MachXO3L/LF devices are available for operation from 3.3 V, 2.5 V and 1.2 V power supplies, providing easy integration into the overall system.

**Figure 2-6. Secondary High Fanout Nets for MachXO3L/LF Devices**



### sysCLOCK Phase Locked Loops (PLLs)

The sysCLOCK PLLs provide the ability to synthesize clock frequencies. All MachXO3L/LF devices have one or more sysCLOCK PLL. CLKI is the reference frequency input to the PLL and its source can come from an external I/O pin or from internal routing. CLKFB is the feedback signal to the PLL which can come from internal routing or an external I/O pin. The feedback divider is used to multiply the reference frequency and thus synthesize a higher frequency clock output.

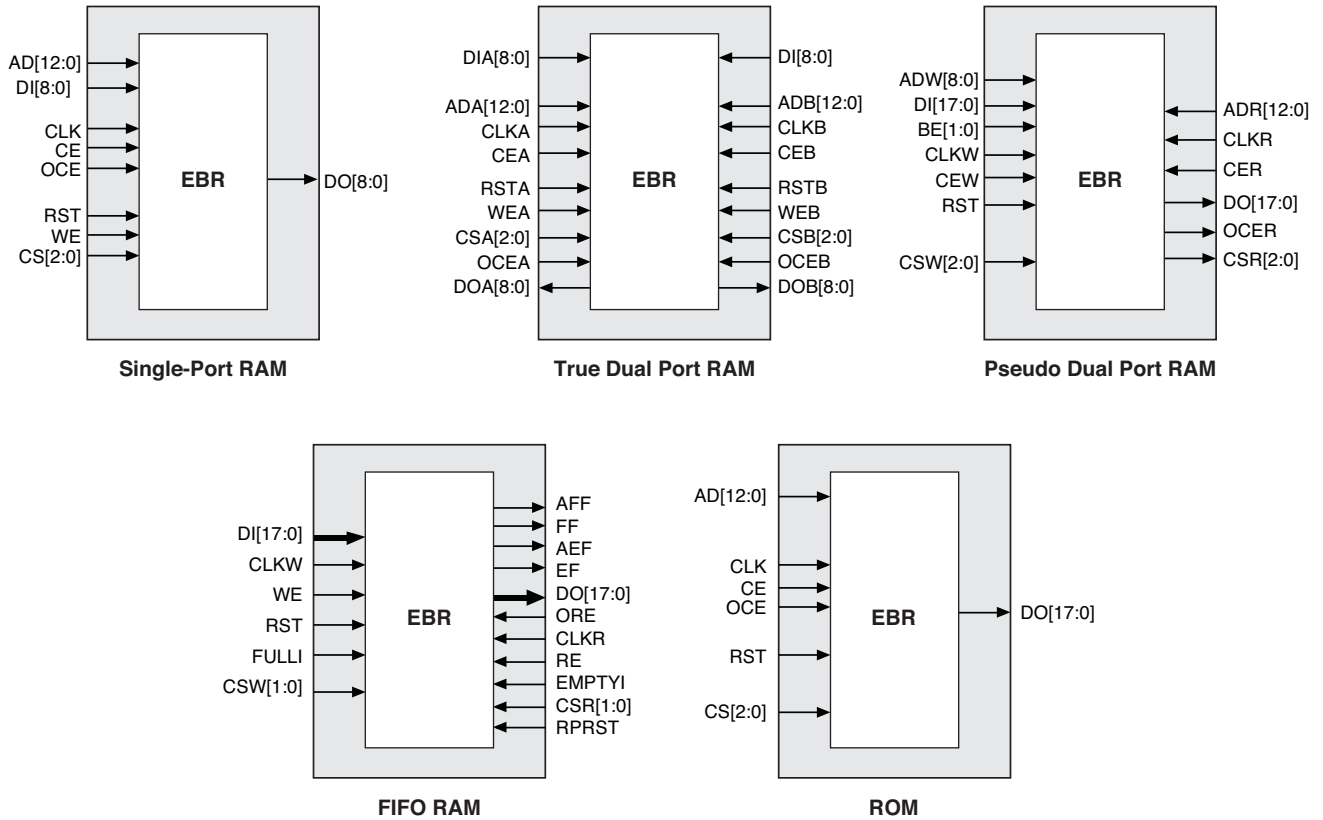
The MachXO3L/LF sysCLOCK PLLs support high resolution (16-bit) fractional-N synthesis. Fractional-N frequency synthesis allows the user to generate an output clock which is a non-integer multiple of the input frequency. For more information about using the PLL with Fractional-N synthesis, please see TN1282, [MachXO3 sysCLOCK PLL Design and Usage Guide](#).

Each output has its own output divider, thus allowing the PLL to generate different frequencies for each output. The output dividers can have a value from 1 to 128. The output dividers may also be cascaded together to generate low frequency clocks. The CLKOP, CLKOS, CLKOS2, and CLKOS3 outputs can all be used to drive the MachXO3L/LF clock distribution network directly or general purpose routing resources can be used.

The LOCK signal is asserted when the PLL determines it has achieved lock and de-asserted if a loss of lock is detected. A block diagram of the PLL is shown in Figure 2-7.

The setup and hold times of the device can be improved by programming a phase shift into the CLKOS, CLKOS2, and CLKOS3 output clocks which will advance or delay the output clock with reference to the CLKOP output clock.

**Figure 2-8. sysMEM Memory Primitives**



**Table 2-6. EBR Signal Descriptions**

Port Name	Description	Active State
CLK	Clock	Rising Clock Edge
CE	Clock Enable	Active High
OCE <sup>1</sup>	Output Clock Enable	Active High
RST	Reset	Active High
BE <sup>1</sup>	Byte Enable	Active High
WE	Write Enable	Active High
AD	Address Bus	—
DI	Data In	—
DO	Data Out	—
CS	Chip Select	Active High
AFF	FIFO RAM Almost Full Flag	—
FF	FIFO RAM Full Flag	—
AEF	FIFO RAM Almost Empty Flag	—
EF	FIFO RAM Empty Flag	—
RPRST	FIFO RAM Read Pointer Reset	—

1. Optional signals.
2. For dual port EBR primitives a trailing 'A' or 'B' in the signal name specifies the EBR port A or port B respectively.
3. For FIFO RAM mode primitive, a trailing 'R' or 'W' in the signal name specifies the FIFO read port or write port respectively.
4. For FIFO RAM mode primitive FULLI has the same function as CSW(2) and EMPTYI has the same function as CSR(2).
5. In FIFO mode, CLKW is the write port clock, CSW is the write port chip select, CLKR is the read port clock, CSR is the read port chip select, ORE is the output read enable.

The EBR memory supports three forms of write behavior for single or dual port operation:

1. **Normal** – Data on the output appears only during the read cycle. During a write cycle, the data (at the current address) does not appear on the output. This mode is supported for all data widths.
2. **Write Through** – A copy of the input data appears at the output of the same port. This mode is supported for all data widths.
3. **Read-Before-Write** – When new data is being written, the old contents of the address appears at the output.

**FIFO Configuration**

The FIFO has a write port with data-in, CEW, WE and CLKW signals. There is a separate read port with data-out, RCE, RE and CLKR signals. The FIFO internally generates Almost Full, Full, Almost Empty and Empty Flags. The Full and Almost Full flags are registered with CLKW. The Empty and Almost Empty flags are registered with CLKR. Table 2-7 shows the range of programming values for these flags.

**Table 2-7. Programmable FIFO Flag Ranges**

Flag Name	Programming Range
Full (FF)	1 to max (up to $2^N-1$ )
Almost Full (AF)	1 to Full-1
Almost Empty (AE)	1 to Full-1
Empty (EF)	0

N = Address bit width.

The FIFO state machine supports two types of reset signals: RST and RPRST. The RST signal is a global reset that clears the contents of the FIFO by resetting the read/write pointer and puts the FIFO flags in their initial reset

## sysIO Buffer

Each I/O is associated with a flexible buffer referred to as a sysIO buffer. These buffers are arranged around the periphery of the device in groups referred to as banks. The sysIO buffers allow users to implement a wide variety of standards that are found in today's systems including LVCMOS, TTL, PCI, LVDS, BLVDS, MLVDS and LVPECL.

Each bank is capable of supporting multiple I/O standards. In the MachXO3L/LF devices, single-ended output buffers, ratioed input buffers (LVTTL, LVCMOS and PCI), differential (LVDS) input buffers are powered using I/O supply voltage ( $V_{CCIO}$ ). Each sysIO bank has its own  $V_{CCIO}$ .

MachXO3L/LF devices contain three types of sysIO buffer pairs.

### 1. Left and Right sysIO Buffer Pairs

The sysIO buffer pairs in the left and right banks of the device consist of two single-ended output drivers and two single-ended input buffers (for ratioed inputs such as LVCMOS and LVTTL). The I/O pairs on the left and right of the devices also have differential input buffers.

### 2. Bottom sysIO Buffer Pairs

The sysIO buffer pairs in the bottom bank of the device consist of two single-ended output drivers and two single-ended input buffers (for ratioed inputs such as LVCMOS and LVTTL). The I/O pairs on the bottom also have differential input buffers. Only the I/Os on the bottom banks have programmable PCI clamps and differential input termination. The PCI clamp is enabled after  $V_{CC}$  and  $V_{CCIO}$  are at valid operating levels and the device has been configured.

### 3. Top sysIO Buffer Pairs

The sysIO buffer pairs in the top bank of the device consist of two single-ended output drivers and two single-ended input buffers (for ratioed inputs such as LVCMOS and LVTTL). The I/O pairs on the top also have differential I/O buffers. Half of the sysIO buffer pairs on the top edge have true differential outputs. The sysIO buffer pair comprising of the A and B PIOs in every PIC on the top edge have a differential output driver.

## Typical I/O Behavior During Power-up

The internal power-on-reset (POR) signal is deactivated when  $V_{CC}$  and  $V_{CCIO0}$  have reached  $V_{PORUP}$  level defined in the Power-On-Reset Voltage table in the DC and Switching Characteristics section of this data sheet. After the POR signal is deactivated, the FPGA core logic becomes active. It is the user's responsibility to ensure that all  $V_{CCIO}$  banks are active with valid input logic levels to properly control the output logic states of all the I/O banks that are critical to the application. The default configuration of the I/O pins in a blank device is tri-state with a weak pull-down to GND (some pins such as PROGRAMN and the JTAG pins have weak pull-up to  $V_{CCIO}$  as the default functionality). The I/O pins will maintain the blank configuration until  $V_{CC}$  and  $V_{CCIO}$  (for I/O banks containing configuration I/Os) have reached  $V_{PORUP}$  levels at which time the I/Os will take on the user-configured settings only after a proper download/configuration.

There are various ways a user can ensure that there are no spurious signals on critical outputs as the device powers up. These are discussed in more detail in TN1280, [MachXO3 sysIO Usage Guide](#).

## Supported Standards

The MachXO3L/LF sysIO buffer supports both single-ended and differential standards. Single-ended standards can be further subdivided into LVCMOS, LVTTL, and PCI. The buffer supports the LVTTL, PCI, LVCMOS 1.2 V, 1.5 V, 1.8 V, 2.5 V, and 3.3 V standards. In the LVCMOS and LVTTL modes, the buffer has individually configurable options for drive strength, bus maintenance (weak pull-up, weak pull-down, bus-keeper latch or none) and open drain. BLVDS, MLVDS and LVPECL output emulation is supported on all devices. The MachXO3L/LF devices support on-chip LVDS output buffers on approximately 50% of the I/Os on the top bank. Differential receivers for LVDS, BLVDS, MLVDS and LVPECL are supported on all banks of MachXO3L/LF devices. PCI support is provided in the bottom bank of the MachXO3L/LF devices. Table 2-11 summarizes the I/O characteristics of the MachXO3L/LF PLDs.

**Table 2-12. Supported Output Standards**

Output Standard	V <sub>CCIO</sub> (Typ.)
<b>Single-Ended Interfaces</b>	
LVTTTL	3.3
LVC MOS33	3.3
LVC MOS25	2.5
LVC MOS18	1.8
LVC MOS15	1.5
LVC MOS12	1.2
LVC MOS33, Open Drain	—
LVC MOS25, Open Drain	—
LVC MOS18, Open Drain	—
LVC MOS15, Open Drain	—
LVC MOS12, Open Drain	—
PCI33	3.3
<b>Differential Interfaces</b>	
LVDS <sup>1</sup>	2.5, 3.3
BLVDS, MLVDS, RSDS <sup>1</sup>	2.5
LVPECL <sup>1</sup>	3.3
MIPI <sup>1</sup>	2.5
LVTTLD	3.3
LVC MOS33D	3.3
LVC MOS25D	2.5
LVC MOS18D	1.8

1. These interfaces can be emulated with external resistors in all devices.

### sysIO Buffer Banks

The numbers of banks vary between the devices of this family. MachXO3L/LF-1300 in the 256 Ball packages and the MachXO3L/LF-2100 and higher density devices have six I/O banks (one bank on the top, right and bottom side and three banks on the left side). The MachXO3L/LF-1300 and lower density devices have four banks (one bank per side). Figures 2-15 and 2-16 show the sysIO banks and their associated supplies for all devices.

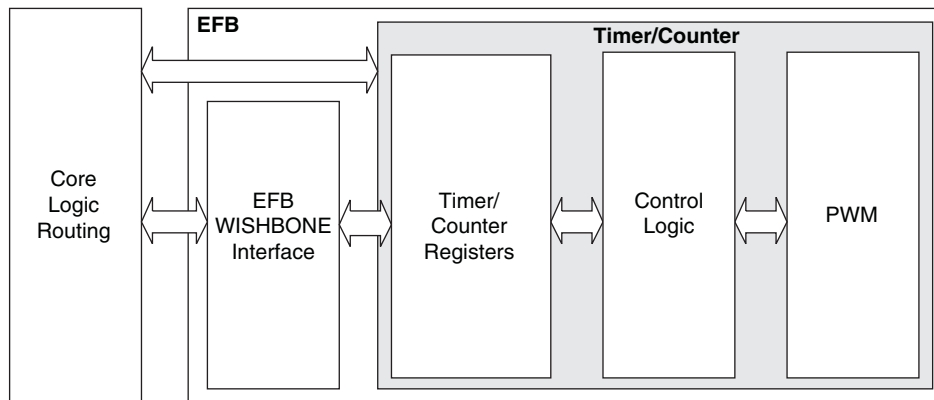


## Hardened Timer/Counter

MachXO3L/LF devices provide a hard Timer/Counter IP core. This Timer/Counter is a general purpose, bi-directional, 16-bit timer/counter module with independent output compare units and PWM support. The Timer/Counter supports the following functions:

- Supports the following modes of operation:
  - Watchdog timer
  - Clear timer on compare match
  - Fast PWM
  - Phase and Frequency Correct PWM
- Programmable clock input source
- Programmable input clock prescaler
- One static interrupt output to routing
- One wake-up interrupt to on-chip standby mode controller.
- Three independent interrupt sources: overflow, output compare match, and input capture
- Auto reload
- Time-stamping support on the input capture unit
- Waveform generation on the output
- Glitch-free PWM waveform generation with variable PWM period
- Internal WISHBONE bus access to the control and status registers
- Stand-alone mode with preloaded control registers and direct reset input

**Figure 2-20. Timer/Counter Block Diagram**



**Table 2-16. Timer/Counter Signal Description**

Port	I/O	Description
tc_clk	I	Timer/Counter input clock signal
tc_rstn	I	Register tc_rstn_ena is preloaded by configuration to always keep this pin enabled
tc_ic	I	Input capture trigger event, applicable for non-pwm modes with WISHBONE interface. If enabled, a rising edge of this signal will be detected and synchronized to capture tc_cnt value into tc_icr for time-stamping.
tc_int	O	Without WISHBONE – Can be used as overflow flag With WISHBONE – Controlled by three IRQ registers
tc_oc	O	Timer counter output signal

**Table 2-17. MachXO3L/LF Power Saving Features Description**

Device Subsystem	Feature Description
Bandgap	The bandgap can be turned off in standby mode. When the Bandgap is turned off, analog circuitry such as the POR, PLLs, on-chip oscillator, and differential I/O buffers are also turned off. Bandgap can only be turned off for 1.2 V devices.
Power-On-Reset (POR)	The POR can be turned off in standby mode. This monitors V <sub>CC</sub> levels. In the event of unsafe V <sub>CC</sub> drops, this circuit reconfigures the device. When the POR circuitry is turned off, limited power detector circuitry is still active. This option is only recommended for applications in which the power supply rails are reliable.
On-Chip Oscillator	The on-chip oscillator has two power saving features. It may be switched off if it is not needed in your design. It can also be turned off in Standby mode.
PLL	Similar to the on-chip oscillator, the PLL also has two power saving features. It can be statically switched off if it is not needed in a design. It can also be turned off in Standby mode. The PLL will wait until all output clocks from the PLL are driven low before powering off.
I/O Bank Controller	Differential I/O buffers (used to implement standards such as LVDS) consume more than ratioed single-ended I/Os such as LVCMOS and LVTTL. The I/O bank controller allows the user to turn these I/Os off dynamically on a per bank selection.
Dynamic Clock Enable for Primary Clock Nets	Each primary clock net can be dynamically disabled to save power.
Power Guard	Power Guard is a feature implemented in input buffers. This feature allows users to switch off the input buffer when it is not needed. This feature can be used in both clock and data paths. Its biggest impact is that in the standby mode it can be used to switch off clock inputs that are distributed using general routing resources.

For more details on the standby mode refer to TN1289, [Power Estimation and Management for MachXO3 Devices](#).

## Power On Reset

MachXO3L/LF devices have power-on reset circuitry to monitor V<sub>CCINT</sub> and V<sub>CCIO</sub> voltage levels during power-up and operation. At power-up, the POR circuitry monitors V<sub>CCINT</sub> and V<sub>CCIO0</sub> (controls configuration) voltage levels. It then triggers download from the on-chip configuration NVCM/Flash memory after reaching the V<sub>PORUP</sub> level specified in the Power-On-Reset Voltage table in the DC and Switching Characteristics section of this data sheet. For “E” devices without voltage regulators, V<sub>CCINT</sub> is the same as the V<sub>CC</sub> supply voltage. For “C” devices with voltage regulators, V<sub>CCINT</sub> is regulated from the V<sub>CC</sub> supply voltage. From this voltage reference, the time taken for configuration and entry into user mode is specified as NVCM/Flash Download Time (t<sub>REFRESH</sub>) in the DC and Switching Characteristics section of this data sheet. Before and during configuration, the I/Os are held in tri-state. I/Os are released to user functionality once the device has finished configuration. Note that for “C” devices, a separate POR circuit monitors external V<sub>CC</sub> voltage in addition to the POR circuit that monitors the internal post-regulated power supply voltage level.

Once the device enters into user mode, the POR circuitry can optionally continue to monitor V<sub>CCINT</sub> levels. If V<sub>CCINT</sub> drops below V<sub>PORDNBG</sub> level (with the bandgap circuitry switched on) or below V<sub>PORDNSRAM</sub> level (with the bandgap circuitry switched off to conserve power) device functionality cannot be guaranteed. In such a situation the POR issues a reset and begins monitoring the V<sub>CCINT</sub> and V<sub>CCIO</sub> voltage levels. V<sub>PORDNBG</sub> and V<sub>PORDNSRAM</sub> are both specified in the Power-On-Reset Voltage table in the DC and Switching Characteristics section of this data sheet.

Note that once an “E” device enters user mode, users can switch off the bandgap to conserve power. When the bandgap circuitry is switched off, the POR circuitry also shuts down. The device is designed such that a mini-mal, low power POR circuit is still operational (this corresponds to the V<sub>PORDNSRAM</sub> reset point described in the paragraph above). However this circuit is not as accurate as the one that operates when the bandgap is switched on. The low power POR circuit emulates an SRAM cell and is biased to trip before the vast majority of SRAM cells flip. If users are concerned about the V<sub>CC</sub> supply dropping below V<sub>CC</sub> (min) they should not shut down the bandgap or POR circuit.

## TraceID

Each MachXO3L/LF device contains a unique (per device), TraceID that can be used for tracking purposes or for IP security applications. The TraceID is 64 bits long. Eight out of 64 bits are user-programmable, the remaining 56 bits are factory-programmed. The TraceID is accessible through the EFB WISHBONE interface and can also be accessed through the SPI, I<sup>2</sup>C, or JTAG interfaces.

## Density Shifting

The MachXO3L/LF family has been designed to enable density migration within the same package. Furthermore, the architecture ensures a high success rate when performing design migration from lower density devices to higher density devices. In many cases, it is also possible to shift a lower utilization design targeted for a high-density device to a lower density device. However, the exact details of the final resource utilization will impact the likely success in each case. When migrating from lower to higher density or higher to lower density, ensure to review all the power supplies and NC pins of the chosen devices. For more details refer to the [MachXO3 migration files](#).

## DC Electrical Characteristics

### Over Recommended Operating Conditions

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$I_{IL}, I_{IH}^{1,4}$	Input or I/O Leakage	Clamp OFF and $V_{CCIO} < V_{IN} < V_{IH} (MAX)$	—	—	+175	$\mu A$
		Clamp OFF and $V_{IN} = V_{CCIO}$	-10	—	10	$\mu A$
		Clamp OFF and $V_{CCIO} - 0.97 V < V_{IN} < V_{CCIO}$	-175	—	—	$\mu A$
		Clamp OFF and $0 V < V_{IN} < V_{CCIO} - 0.97 V$	—	—	10	$\mu A$
		Clamp OFF and $V_{IN} = GND$	—	—	10	$\mu A$
		Clamp ON and $0 V < V_{IN} < V_{CCIO}$	—	—	10	$\mu A$
$I_{PU}$	I/O Active Pull-up Current	$0 < V_{IN} < 0.7 V_{CCIO}$	-30	—	-309	$\mu A$
$I_{PD}$	I/O Active Pull-down Current	$V_{IL} (MAX) < V_{IN} < V_{CCIO}$	30	—	305	$\mu A$
$I_{BHLS}$	Bus Hold Low sustaining current	$V_{IN} = V_{IL} (MAX)$	30	—	—	$\mu A$
$I_{BHHS}$	Bus Hold High sustaining current	$V_{IN} = 0.7V_{CCIO}$	-30	—	—	$\mu A$
$I_{BHLO}$	Bus Hold Low Overdrive current	$0 \leq V_{IN} \leq V_{CCIO}$	—	—	305	$\mu A$
$I_{BHHO}$	Bus Hold High Overdrive current	$0 \leq V_{IN} \leq V_{CCIO}$	—	—	-309	$\mu A$
$V_{BHT}^3$	Bus Hold Trip Points		$V_{IL} (MAX)$	—	$V_{IH} (MIN)$	V
C1	I/O Capacitance <sup>2</sup>	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V, 1.5 V, 1.2 V, V_{CC} = Typ., V_{IO} = 0$ to $V_{IH} (MAX)$	3	5	9	pf
C2	Dedicated Input Capacitance <sup>2</sup>	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V, 1.5 V, 1.2 V, V_{CC} = Typ., V_{IO} = 0$ to $V_{IH} (MAX)$	3	5.5	7	pf
$V_{HYST}$	Hysteresis for Schmitt Trigger Inputs <sup>5</sup>	$V_{CCIO} = 3.3 V, Hysteresis = Large$	—	450	—	mV
		$V_{CCIO} = 2.5 V, Hysteresis = Large$	—	250	—	mV
		$V_{CCIO} = 1.8 V, Hysteresis = Large$	—	125	—	mV
		$V_{CCIO} = 1.5 V, Hysteresis = Large$	—	100	—	mV
		$V_{CCIO} = 3.3 V, Hysteresis = Small$	—	250	—	mV
		$V_{CCIO} = 2.5 V, Hysteresis = Small$	—	150	—	mV
		$V_{CCIO} = 1.8 V, Hysteresis = Small$	—	60	—	mV
		$V_{CCIO} = 1.5 V, Hysteresis = Small$	—	40	—	mV

1. Input or I/O leakage current is measured with the pin configured as an input or as an I/O with the output driver tri-stated. It is not measured with the output driver active. Bus maintenance circuits are disabled.
2.  $T_A$  25 °C,  $f = 1.0$  MHz.
3. Please refer to  $V_{IL}$  and  $V_{IH}$  in the sysIO Single-Ended DC Electrical Characteristics table of this document.
4. When  $V_{IH}$  is higher than  $V_{CCIO}$ , a transient current typically of 30 ns in duration or less with a peak current of 6mA can occur on the high-to-low transition. For true LVDS output pins in MachXO3L/LF devices,  $V_{IH}$  must be less than or equal to  $V_{CCIO}$ .
5. With bus keeper circuit turned on. For more details, refer to TN1280, [MachXO3 sysIO Usage Guide](#).

**Static Supply Current – C/E Devices<sup>1, 2, 3, 6</sup>**

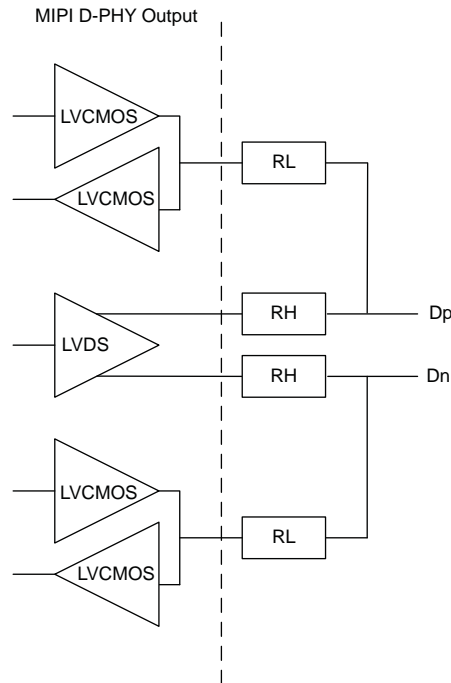
Symbol	Parameter	Device	Typ. <sup>4</sup>	Units
I <sub>CC</sub>	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	4.8	mA
		LCMXO3L/LF-2100C	4.8	mA
		LCMXO3L/LF-2100C 324 Ball Package	8.45	mA
		LCMXO3L/LF-4300C	8.45	mA
		LCMXO3L/LF-4300C 400 Ball Package	12.87	mA
		LCMXO3L/LF-6900C <sup>7</sup>	12.87	mA
		LCMXO3L/LF-9400C <sup>7</sup>	17.86	mA
		LCMXO3L/LF-640E	1.00	mA
		LCMXO3L/LF-1300E	1.00	mA
		LCMXO3L/LF-1300E 256 Ball Package	1.39	mA
		LCMXO3L/LF-2100E	1.39	mA
		LCMXO3L/LF-2100E 324 Ball Package	2.55	mA
		LCMXO3L/LF-4300E	2.55	mA
		LCMXO3L/LF-6900E	4.06	mA
LCMXO3L/LF-9400E	5.66	mA		
I <sub>CCIO</sub>	Bank Power Supply <sup>5</sup> V <sub>CCIO</sub> = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, [Power Estimation and Management for MachXO3 Devices](#).
2. Assumes blank pattern with the following characteristics: all outputs are tri-stated, all inputs are configured as LVCMOS and held at V<sub>CCIO</sub> or GND, on-chip oscillator is off, on-chip PLL is off.
3. Frequency = 0 MHz.
4. T<sub>J</sub> = 25 °C, power supplies at nominal voltage.
5. Does not include pull-up/pull-down.
6. To determine the MachXO3L/LF peak start-up current data, use the Power Calculator tool.
7. Determination of safe ambient operating conditions requires use of the Diamond Power Calculator tool.

	Description	Min.	Typ.	Max.	Units
<b>Low Power</b>					
VCCIO	VCCIO of the Bank with LVCMOS12D 6 mA drive bidirectional IO buffer		1.2		V
VIH	Logic 1 input voltage	—	—	0.88	V
VIL	Logic 0 input voltage, not in ULP State	0.55	—	—	V
VHYST	Input hysteresis	25	—	—	mV

1. Over Recommended Operating Conditions

**Figure 3-5. MIPI D-PHY Output Using External Resistors**

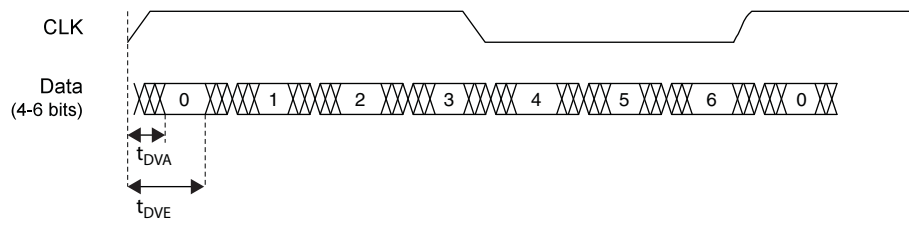


Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>General I/O Pin Parameters (Using Edge Clock without PLL)</b>							
t <sub>COE</sub>	Clock to Output - PIO Output Register	MachXO3L/LF-1300	—	7.53	—	7.76	ns
		MachXO3L/LF-2100	—	7.53	—	7.76	ns
		MachXO3L/LF-4300	—	7.45	—	7.68	ns
		MachXO3L/LF-6900	—	7.53	—	7.76	ns
		MachXO3L/LF-9400	—	8.93	—	9.35	ns
t <sub>SUE</sub>	Clock to Data Setup - PIO Input Register	MachXO3L/LF-1300	-0.19	—	-0.19	—	ns
		MachXO3L/LF-2100	-0.19	—	-0.19	—	ns
		MachXO3L/LF-4300	-0.16	—	-0.16	—	ns
		MachXO3L/LF-6900	-0.19	—	-0.19	—	ns
		MachXO3L/LF-9400	-0.20	—	-0.20	—	ns
t <sub>HE</sub>	Clock to Data Hold - PIO Input Register	MachXO3L/LF-1300	1.97	—	2.24	—	ns
		MachXO3L/LF-2100	1.97	—	2.24	—	ns
		MachXO3L/LF-4300	1.89	—	2.16	—	ns
		MachXO3L/LF-6900	1.97	—	2.24	—	ns
		MachXO3L/LF-9400	1.98	—	2.25	—	ns
t <sub>SU_DELE</sub>	Clock to Data Setup - PIO Input Register with Data Input Delay	MachXO3L/LF-1300	1.56	—	1.69	—	ns
		MachXO3L/LF-2100	1.56	—	1.69	—	ns
		MachXO3L/LF-4300	1.74	—	1.88	—	ns
		MachXO3L/LF-6900	1.66	—	1.81	—	ns
		MachXO3L/LF-9400	1.71	—	1.85	—	ns
t <sub>H_DELE</sub>	Clock to Data Hold - PIO Input Register with Input Data Delay	MachXO3L/LF-1300	-0.23	—	-0.23	—	ns
		MachXO3L/LF-2100	-0.23	—	-0.23	—	ns
		MachXO3L/LF-4300	-0.34	—	-0.34	—	ns
		MachXO3L/LF-6900	-0.29	—	-0.29	—	ns
		MachXO3L/LF-9400	-0.30	—	-0.30	—	ns
<b>General I/O Pin Parameters (Using Primary Clock with PLL)</b>							
t <sub>COPLL</sub>	Clock to Output - PIO Output Register	MachXO3L/LF-1300	—	5.98	—	6.01	ns
		MachXO3L/LF-2100	—	5.98	—	6.01	ns
		MachXO3L/LF-4300	—	5.99	—	6.02	ns
		MachXO3L/LF-6900	—	6.02	—	6.06	ns
		MachXO3L/LF-9400	—	5.55	—	6.13	ns
t <sub>SUPLL</sub>	Clock to Data Setup - PIO Input Register	MachXO3L/LF-1300	0.36	—	0.36	—	ns
		MachXO3L/LF-2100	0.36	—	0.36	—	ns
		MachXO3L/LF-4300	0.35	—	0.35	—	ns
		MachXO3L/LF-6900	0.34	—	0.34	—	ns
		MachXO3L/LF-9400	0.33	—	0.33	—	ns
t <sub>HPLL</sub>	Clock to Data Hold - PIO Input Register	MachXO3L/LF-1300	0.42	—	0.49	—	ns
		MachXO3L/LF-2100	0.42	—	0.49	—	ns
		MachXO3L/LF-4300	0.43	—	0.50	—	ns
		MachXO3L/LF-6900	0.46	—	0.54	—	ns
		MachXO3L/LF-9400	0.47	—	0.55	—	ns

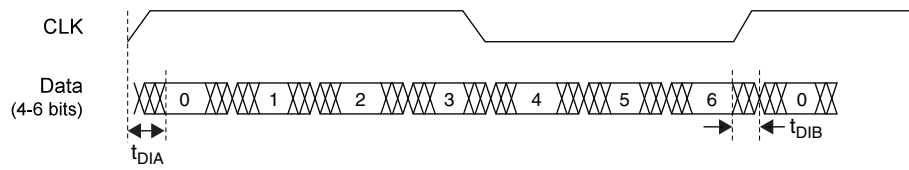
Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>Generic DDRX1 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR1_RX.SCLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	All MachXO3L/LF devices, all sides	—	0.317	—	0.344	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.742	—	0.702	—	UI
f <sub>DATA</sub>	DDR1 Input Data Speed		—	300	—	250	Mbps
f <sub>DDR1</sub>	DDR1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX1 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR1_RX.SCLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	All MachXO3L/LF devices, all sides	0.566	—	0.560	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.778	—	0.879	—	ns
f <sub>DATA</sub>	DDR1 Input Data Speed		—	300	—	—	Mbps
f <sub>DDR1</sub>	DDR1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX2 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR2_RX.ECLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	MachXO3L/LF devices, bottom side only	—	0.316	—	0.342	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.710	—	0.675	—	UI
f <sub>DATA</sub>	DDR2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDR2</sub>	DDR2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDRX2 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR2_RX.ECLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDR2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDR2</sub>	DDR2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDR4 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR4_RX.ECLK.Aligned<sup>8</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.307	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.782	—	0.699	—	UI
f <sub>DATA</sub>	DDR4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDR4</sub>	DDR4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>Generic DDR4 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR4_RX.ECLK.Centered<sup>8</sup></b>							
t <sub>SU</sub>	Input Data Setup Before ECLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After ECLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDR4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDR4</sub>	DDR4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>7:1 LVDS Inputs (GDDR71_RX.ECLK.7:1)<sup>9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.290	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.739	—	0.699	—	UI
f <sub>DATA</sub>	DDR71 Serial Input Data Speed		—	756	—	630	Mbps
f <sub>DDR71</sub>	DDR71 ECLK Frequency		—	378	—	315	MHz
f <sub>CLKIN</sub>	7:1 Input Clock Frequency (SCLK) (minimum limited by PLL)		—	108	—	90	MHz



**Figure 3-6. Receiver GDDR71\_RX. Waveforms**



**Figure 3-7. Transmitter GDDR71\_TX. Waveforms**



## I<sup>2</sup>C Port Timing Specifications<sup>1, 2</sup>

Symbol	Parameter	Min.	Max.	Units
f <sub>MAX</sub>	Maximum SCL clock frequency	—	400	kHz

- MachXO3L/LF supports the following modes:
  - Standard-mode (Sm), with a bit rate up to 100 kbit/s (user and configuration mode)
  - Fast-mode (Fm), with a bit rate up to 400 kbit/s (user and configuration mode)
- Refer to the I<sup>2</sup>C specification for timing requirements.

## SPI Port Timing Specifications<sup>1</sup>

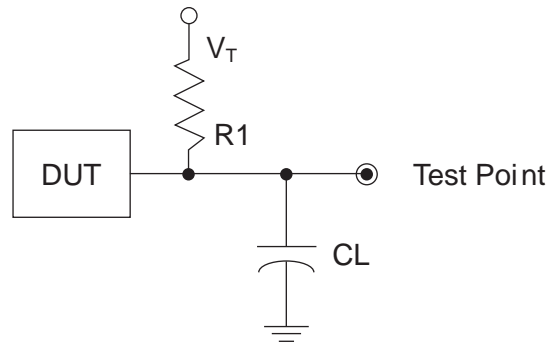
Symbol	Parameter	Min.	Max.	Units
f <sub>MAX</sub>	Maximum SCK clock frequency	—	45	MHz

- Applies to user mode only. For configuration mode timing specifications, refer to sysCONFIG Port Timing Specifications table in this data sheet.

## Switching Test Conditions

Figure 3-9 shows the output test load used for AC testing. The specific values for resistance, capacitance, voltage, and other test conditions are shown in Table 3-6.

**Figure 3-9. Output Test Load, LVTTTL and LVCMOS Standards**



**Table 3-6. Test Fixture Required Components, Non-Terminated Interfaces**

Test Condition	R1	CL	Timing Ref.	VT
LVTTTL and LVCMOS settings (L -> H, H -> L)	$\infty$	0pF	LVTTTL, LVCMOS 3.3 = 1.5 V	—
			LVCMOS 2.5 = V <sub>CCIO</sub> /2	—
			LVCMOS 1.8 = V <sub>CCIO</sub> /2	—
			LVCMOS 1.5 = V <sub>CCIO</sub> /2	—
			LVCMOS 1.2 = V <sub>CCIO</sub> /2	—
LVTTTL and LVCMOS 3.3 (Z -> H)	188	0pF	1.5	V <sub>OL</sub>
LVTTTL and LVCMOS 3.3 (Z -> L)			1.5	V <sub>OH</sub>
Other LVCMOS (Z -> H)			V <sub>CCIO</sub> /2	V <sub>OL</sub>
Other LVCMOS (Z -> L)			V <sub>CCIO</sub> /2	V <sub>OH</sub>
LVTTTL + LVCMOS (H -> Z)			V <sub>OH</sub> - 0.15	V <sub>OL</sub>
LVTTTL + LVCMOS (L -> Z)			V <sub>OL</sub> - 0.15	V <sub>OH</sub>

Note: Output test conditions for all other interfaces are determined by the respective standards.

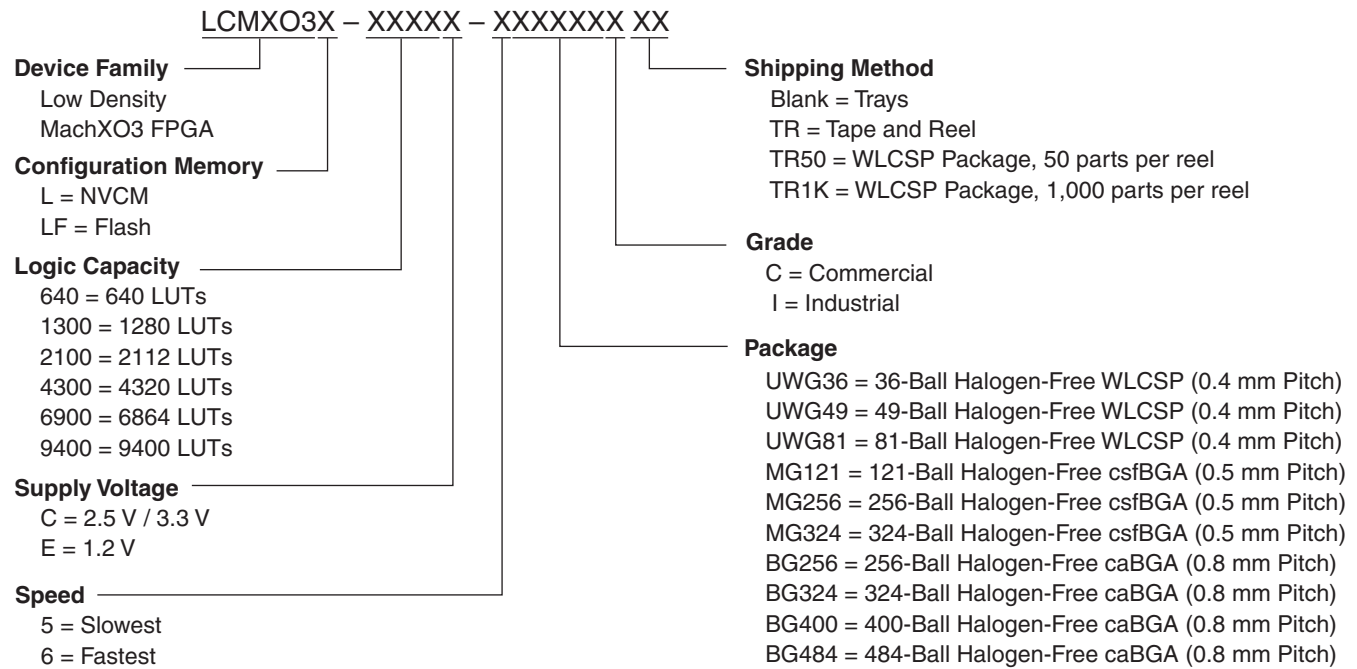
### Signal Descriptions

Signal Name	I/O	Descriptions
<b>General Purpose</b>		
P[Edge] [Row/Column Number]_[A/B/C/D]	I/O	<p>[Edge] indicates the edge of the device on which the pad is located. Valid edge designations are L (Left), B (Bottom), R (Right), T (Top).</p> <p>[Row/Column Number] indicates the PFU row or the column of the device on which the PIO Group exists. When Edge is T (Top) or (Bottom), only need to specify Row Number. When Edge is L (Left) or R (Right), only need to specify Column Number.</p> <p>[A/B/C/D] indicates the PIO within the group to which the pad is connected.</p> <p>Some of these user-programmable pins are shared with special function pins. When not used as special function pins, these pins can be programmed as I/Os for user logic.</p> <p>During configuration of the user-programmable I/Os, the user has an option to tri-state the I/Os and enable an internal pull-up, pull-down or buskeeper resistor. This option also applies to unused pins (or those not bonded to a package pin). The default during configuration is for user-programmable I/Os to be tri-stated with an internal pull-down resistor enabled. When the device is erased, I/Os will be tri-stated with an internal pull-down resistor enabled. Some pins, such as PROGRAMN and JTAG pins, default to tri-stated I/Os with pull-up resistors enabled when the device is erased.</p>
NC	—	No connect.
GND	—	GND – Ground. Dedicated pins. It is recommended that all GNDs are tied together.
VCC	—	V <sub>CC</sub> – The power supply pins for core logic. Dedicated pins. It is recommended that all VCCs are tied to the same supply.
VCCIO <sub>x</sub>	—	VCCIO – The power supply pins for I/O Bank x. Dedicated pins. It is recommended that all VCCIOs located in the same bank are tied to the same supply.
<b>PLL and Clock Functions</b> (Used as user-programmable I/O pins when not used for PLL or clock pins)		
[LOC]_GPLL[T, C]_IN	—	Reference Clock (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.
[LOC]_GPLL[T, C]_FB	—	Optional Feedback (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.
PCLK [n]_[2:0]	—	Primary Clock pads. One to three clock pads per side.
<b>Test and Programming</b> (Dual function pins used for test access port and during sysCONFIG™)		
TMS	I	Test Mode Select input pin, used to control the 1149.1 state machine.
TCK	I	Test Clock input pin, used to clock the 1149.1 state machine.
TDI	I	Test Data input pin, used to load data into the device using an 1149.1 state machine.
TDO	O	Output pin – Test Data output pin used to shift data out of the device using 1149.1.
JTAGENB	I	<p>Optionally controls behavior of TDI, TDO, TMS, TCK. If the device is configured to use the JTAG pins (TDI, TDO, TMS, TCK) as general purpose I/O, then:</p> <p>If JTAGENB is low: TDI, TDO, TMS and TCK can function a general purpose I/O.</p> <p>If JTAGENB is high: TDI, TDO, TMS and TCK function as JTAG pins.</p> <p>For more details, refer to TN1279, <a href="#">MachXO3 Programming and Configuration Usage Guide</a>.</p>

## Signal Descriptions (Cont.)

Signal Name	I/O	Descriptions
<b>Configuration</b> (Dual function pins used during sysCONFIG)		
PROGRAMN	I	Initiates configuration sequence when asserted low. This pin always has an active pull-up.
INITN	I/O	Open Drain pin. Indicates the FPGA is ready to be configured. During configuration, a pull-up is enabled.
DONE	I/O	Open Drain pin. Indicates that the configuration sequence is complete, and the start-up sequence is in progress.
MCLK/CCLK	I/O	Input Configuration Clock for configuring an FPGA in Slave SPI mode. Output Configuration Clock for configuring an FPGA in SPI and SPIm configuration modes.
SN	I	Slave SPI active low chip select input.
CSSPIN	I/O	Master SPI active low chip select output.
SI/SPISI	I/O	Slave SPI serial data input and master SPI serial data output.
SO/SPISO	I/O	Slave SPI serial data output and master SPI serial data input.
SCL	I/O	Slave I <sup>2</sup> C clock input and master I <sup>2</sup> C clock output.
SDA	I/O	Slave I <sup>2</sup> C data input and master I <sup>2</sup> C data output.

### MachXO3 Part Number Description



### Ordering Information

MachXO3L/LF devices have top-side markings as shown in the examples below, on the 256-Ball caBGA package with MachXO3-6900 device in Commercial Temperature in Speed Grade 5. Notice that for the MachXO3LF device, *LMXO3LF* is used instead of *LCMXO3LF* as in the Part Number.



Note: *LCMXO3LF* is marked with *LMXO3LF*

Note: Markings are abbreviated for small packages.