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## Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

## **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

### Details

Product Status	Active
Number of LABs/CLBs	858
Number of Logic Elements/Cells	6864
Total RAM Bits	245760
Number of I/O	206
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	256-VFBGA
Supplier Device Package	256-CSFBGA (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-6900e-6mg256c">https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-6900e-6mg256c</a>

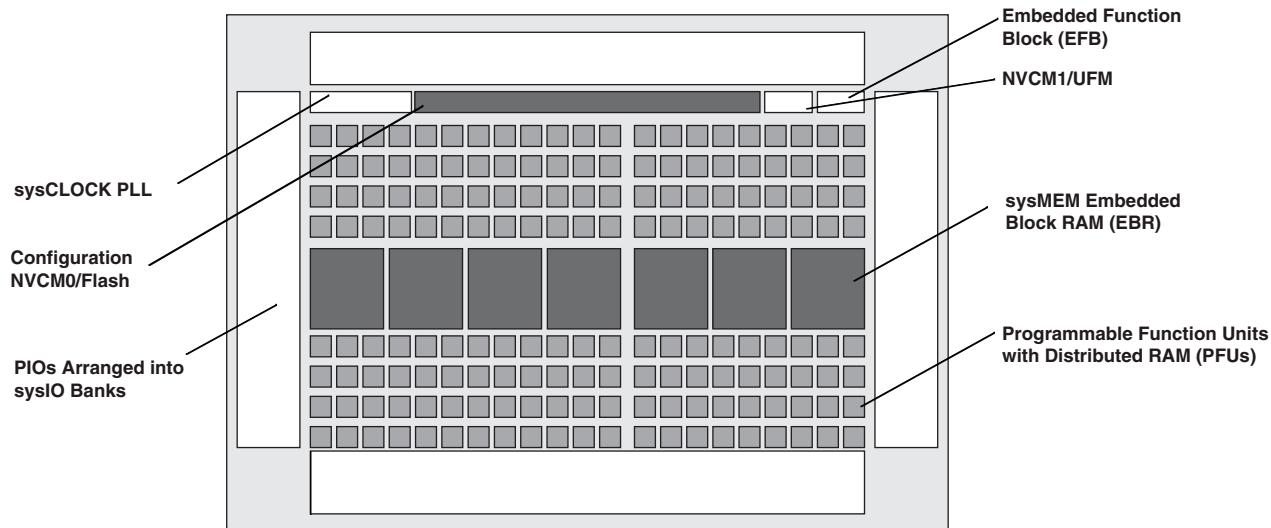
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Advance Data Sheet DS1047

### Architecture Overview

The MachXO3L/LF family architecture contains an array of logic blocks surrounded by Programmable I/O (PIO). All logic density devices in this family have sysCLOCK™ PLLs and blocks of sysMEM Embedded Block RAM (EBRs). Figure 2-1 and Figure 2-2 show the block diagrams of the various family members.

**Figure 2-1. Top View of the MachXO3L/LF-1300 Device**



Notes:

- MachXO3L/LF-640 is similar to MachXO3L/LF-1300. MachXO3L/LF-640 has a lower LUT count.
- MachXO3L devices have NVCM, MachXO3LF devices have Flash.

This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the  $t_{LOCK}$  parameter has been satisfied.

The MachXO3L/LF also has a feature that allows the user to select between two different reference clock sources dynamically. This feature is implemented using the PLLREFCS primitive. The timing parameters for the PLL are shown in the [sysCLOCK PLL Timing](#) table.

The MachXO3L/LF PLL contains a WISHBONE port feature that allows the PLL settings, including divider values, to be dynamically changed from the user logic. When using this feature the EFB block must also be instantiated in the design to allow access to the WISHBONE ports. Similar to the dynamic phase adjustment, when PLL settings are updated through the WISHBONE port the PLL may lose lock and not relock until the  $t_{LOCK}$  parameter has been satisfied. The timing parameters for the PLL are shown in the [sysCLOCK PLL Timing](#) table.

For more details on the PLL and the WISHBONE interface, see TN1282, [MachXO3 sysCLOCK PLL Design and Usage Guide](#).

**Figure 2-7. PLL Diagram**

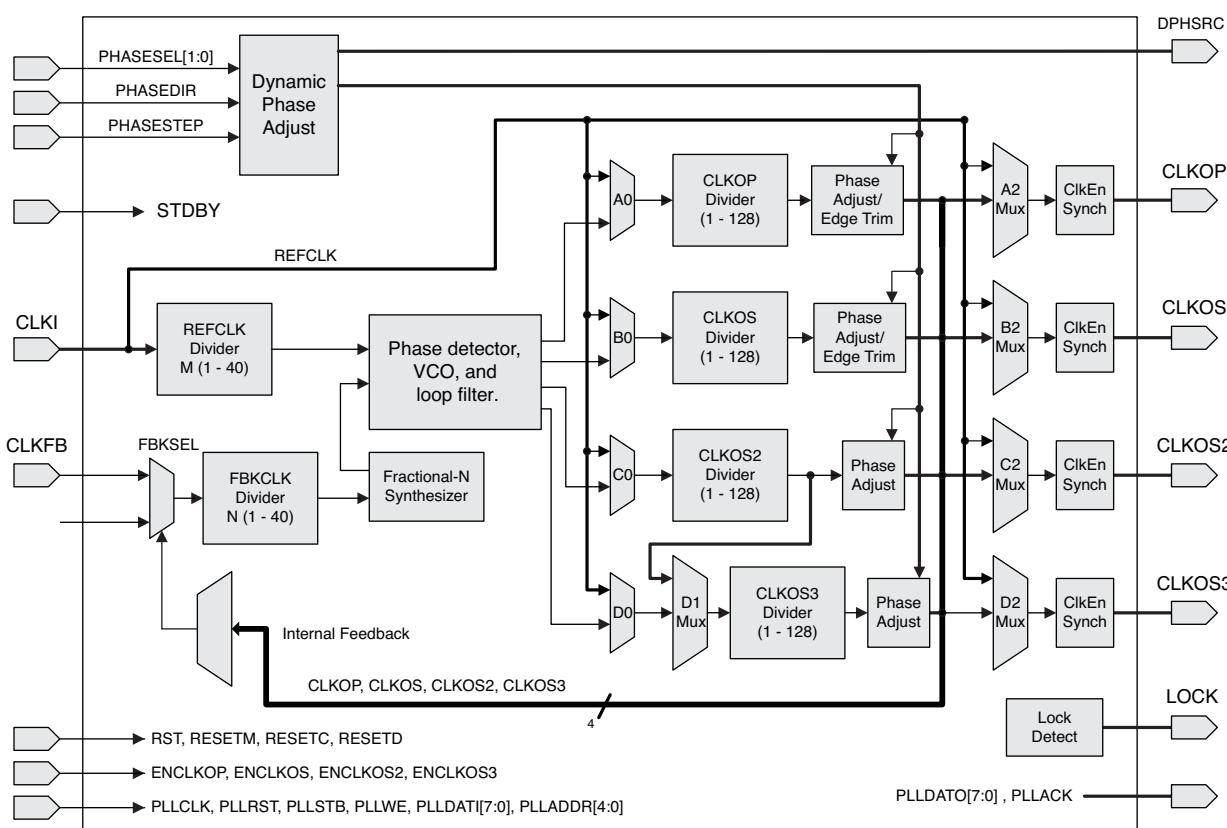


Table 2-4 provides signal descriptions of the PLL block.

**Table 2-4. PLL Signal Descriptions**

Port Name	I/O	Description
CLKI	I	Input clock to PLL
CLKFB	I	Feedback clock
PHASESEL[1:0]	I	Select which output is affected by Dynamic Phase adjustment ports
PHASEDIR	I	Dynamic Phase adjustment direction
PHASESTEP	I	Dynamic Phase step – toggle shifts VCO phase adjust by one step.

**Table 2-5. sysMEM Block Configurations**

Memory Mode	Configurations
Single Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9
True Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9
Pseudo Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18
FIFO	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18

### Bus Size Matching

All of the multi-port memory modes support different widths on each of the ports. The RAM bits are mapped LSB word 0 to MSB word 0, LSB word 1 to MSB word 1, and so on. Although the word size and number of words for each port varies, this mapping scheme applies to each port.

### RAM Initialization and ROM Operation

If desired, the contents of the RAM can be pre-loaded during device configuration. EBR initialization data can be loaded from the NVCM or Configuration Flash.

MachXO3LF EBR initialization data can also be loaded from the UFM. To maximize the number of UFM bits, initialize the EBRs used in your design to an all-zero pattern. Initializing to an all-zero pattern does not use up UFM bits. MachXO3LF devices have been designed such that multiple EBRs share the same initialization memory space if they are initialized to the same pattern.

By preloading the RAM block during the chip configuration cycle and disabling the write controls, the sysMEM block can also be utilized as a ROM.

### Memory Cascading

Larger and deeper blocks of RAM can be created using EBR sysMEM Blocks. Typically, the Lattice design tools cascade memory transparently, based on specific design inputs.

### Single, Dual, Pseudo-Dual Port and FIFO Modes

Figure 2-8 shows the five basic memory configurations and their input/output names. In all the sysMEM RAM modes, the input data and addresses for the ports are registered at the input of the memory array. The output data of the memory is optionally registered at the memory array output.

If an EBR is pre-loaded during configuration, the GSR input must be disabled or the release of the GSR during device wake up must occur before the release of the device I/Os becoming active.

These instructions apply to all EBR RAM, ROM and FIFO implementations. For the EBR FIFO mode, the GSR signal is always enabled and the WE and RE signals act like the clock enable signals in Figure 2-10. The reset timing rules apply to the RPReset input versus the RE input and the RST input versus the WE and RE inputs. Both RST and RPReset are always asynchronous EBR inputs. For more details refer to TN1290, [Memory Usage Guide for MachXO3 Devices](#).

Note that there are no reset restrictions if the EBR synchronous reset is used and the EBR GSR input is disabled.

## Programmable I/O Cells (PIC)

The programmable logic associated with an I/O is called a PIO. The individual PIO are connected to their respective sysIO buffers and pads. On the MachXO3L/LF devices, the PIO cells are assembled into groups of four PIO cells called a Programmable I/O Cell or PIC. The PICs are placed on all four sides of the device.

On all the MachXO3L/LF devices, two adjacent PIOs can be combined to provide a complementary output driver pair.

All PIO pairs can implement differential receivers. Half of the PIO pairs on the top edge of these devices can be configured as true LVDS transmit pairs. The PIO pairs on the bottom edge of these devices have on-chip differential termination and also provide PCI support.

## Input Gearbox

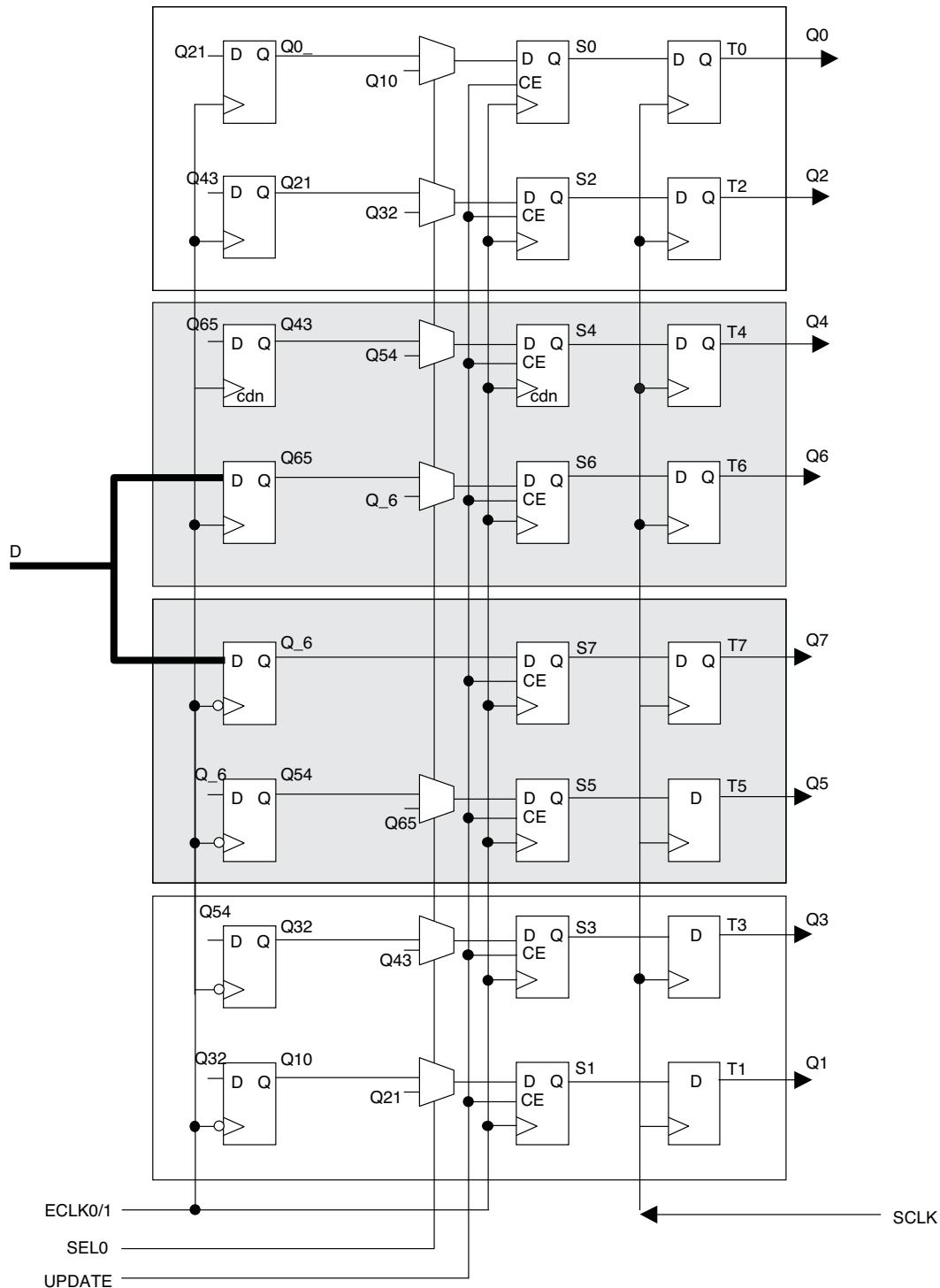
Each PIC on the bottom edge has a built-in 1:8 input gearbox. Each of these input gearboxes may be programmed as a 1:7 de-serializer or as one IDDRX4 (1:8) gearbox or as two IDDRX2 (1:4) gearboxes. Table 2-9 shows the gearbox signals.

**Table 2-9. Input Gearbox Signal List**

Name	I/O Type	Description
D	Input	High-speed data input after programmable delay in PIO A input register block
ALIGNWD	Input	Data alignment signal from device core
SCLK	Input	Slow-speed system clock
ECLK[1:0]	Input	High-speed edge clock
RST	Input	Reset
Q[7:0]	Output	Low-speed data to device core: Video RX(1:7): Q[6:0] GDDRX4(1:8): Q[7:0] GDDRX2(1:4)(IOL-A): Q4, Q5, Q6, Q7 GDDRX2(1:4)(IOL-C): Q0, Q1, Q2, Q3

These gearboxes have three stage pipeline registers. The first stage registers sample the high-speed input data by the high-speed edge clock on its rising and falling edges. The second stage registers perform data alignment based on the control signals UPDATE and SEL0 from the control block. The third stage pipeline registers pass the data to the device core synchronized to the low-speed system clock. Figure 2-13 shows a block diagram of the input gearbox.

**Figure 2-13. Input Gearbox**



More information on the input gearbox is available in TN1281, [Implementing High-Speed Interfaces with MachXO3 Devices](#).

## Output Gearbox

Each PIC on the top edge has a built-in 8:1 output gearbox. Each of these output gearboxes may be programmed as a 7:1 serializer or as one ODDRX4 (8:1) gearbox or as two ODDRX2 (4:1) gearboxes. Table 2-10 shows the gearbox signals.

**Table 2-10. Output Gearbox Signal List**

Name	I/O Type	Description
Q	Output	High-speed data output
D[7:0]	Input	Low-speed data from device core
Video TX(7:1): D[6:0]		
GDDRX4(8:1): D[7:0]		
GDDRX2(4:1)(IOL-A): D[3:0]		
GDDRX2(4:1)(IOL-C): D[7:4]		
SCLK	Input	Slow-speed system clock
ECLK [1:0]	Input	High-speed edge clock
RST	Input	Reset

The gearboxes have three stage pipeline registers. The first stage registers sample the low-speed input data on the low-speed system clock. The second stage registers transfer data from the low-speed clock registers to the high-speed clock registers. The third stage pipeline registers controlled by high-speed edge clock shift and mux the high-speed data out to the sysIO buffer. Figure 2-14 shows the output gearbox block diagram.

## Static Supply Current – C/E Devices<sup>1, 2, 3, 6</sup>

Symbol	Parameter	Device	Typ. <sup>4</sup>	Units
$I_{CC}$	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	4.8	mA
		LCMXO3L/LF-2100C	4.8	mA
		LCMXO3L/LF-2100C 324 Ball Package	8.45	mA
		LCMXO3L/LF-4300C	8.45	mA
		LCMXO3L/LF-4300C 400 Ball Package	12.87	mA
		LCMXO3L/LF-6900C <sup>7</sup>	12.87	mA
		LCMXO3L/LF-9400C <sup>7</sup>	17.86	mA
		LCMXO3L/LF-640E	1.00	mA
		LCMXO3L/LF-1300E	1.00	mA
		LCMXO3L/LF-1300E 256 Ball Package	1.39	mA
		LCMXO3L/LF-2100E	1.39	mA
		LCMXO3L/LF-2100E 324 Ball Package	2.55	mA
		LCMXO3L/LF-4300E	2.55	mA
		LCMXO3L/LF-6900E	4.06	mA
		LCMXO3L/LF-9400E	5.66	mA
$I_{CCIO}$	Bank Power Supply <sup>5</sup> VCCIO = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, [Power Estimation and Management for MachXO3 Devices](#).
2. Assumes blank pattern with the following characteristics: all outputs are tri-stated, all inputs are configured as LVC MOS and held at V<sub>CCIO</sub> or GND, on-chip oscillator is off, on-chip PLL is off.
3. Frequency = 0 MHz.
4. T<sub>J</sub> = 25 °C, power supplies at nominal voltage.
5. Does not include pull-up/pull-down.
6. To determine the MachXO3L/LF peak start-up current data, use the Power Calculator tool.
7. Determination of safe ambient operating conditions requires use of the Diamond Power Calculator tool.

## sysIO Differential Electrical Characteristics

The LVDS differential output buffers are available on the top side of the MachXO3L/LF PLD family.

### LVDS

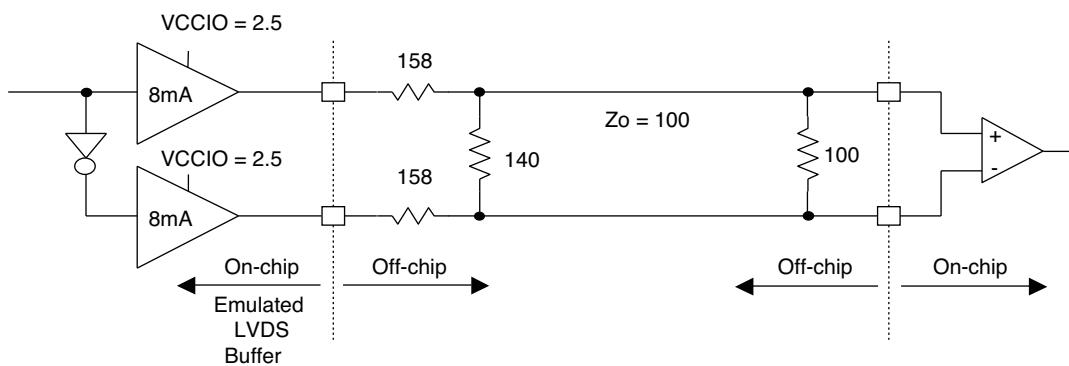
#### Over Recommended Operating Conditions

Parameter Symbol	Parameter Description	Test Conditions	Min.	Typ.	Max.	Units
$V_{INP}$ , $V_{INM}$	Input Voltage	$V_{CCIO} = 3.3$ V	0	—	2.605	V
		$V_{CCIO} = 2.5$ V	0	—	2.05	V
$V_{THD}$	Differential Input Threshold		±100	—		mV
$V_{CM}$	Input Common Mode Voltage	$V_{CCIO} = 3.3$ V	0.05	—	2.6	V
		$V_{CCIO} = 2.5$ V	0.05	—	2.0	V
$I_{IN}$	Input current	Power on	—	—	±10	µA
$V_{OH}$	Output high voltage for $V_{OP}$ or $V_{OM}$	$R_T = 100$ Ohm	—	1.375	—	V
$V_{OL}$	Output low voltage for $V_{OP}$ or $V_{OM}$	$R_T = 100$ Ohm	0.90	1.025	—	V
$V_{OD}$	Output voltage differential	$(V_{OP} - V_{OM})$ , $R_T = 100$ Ohm	250	350	450	mV
$\Delta V_{OD}$	Change in $V_{OD}$ between high and low		—	—	50	mV
$V_{OS}$	Output voltage offset	$(V_{OP} - V_{OM})/2$ , $R_T = 100$ Ohm	1.125	1.20	1.395	V
$\Delta V_{OS}$	Change in $V_{OS}$ between H and L		—	—	50	mV
$I_{OSD}$	Output short circuit current	$V_{OD} = 0$ V driver outputs shorted	—	—	24	mA

## LVDS Emulation

MachXO3L/LF devices can support LVDS outputs via emulation (LVDS25E). The output is emulated using complementary LVCMS outputs in conjunction with resistors across the driver outputs on all devices. The scheme shown in Figure 3-1 is one possible solution for LVDS standard implementation. Resistor values in Figure 3-1 are industry standard values for 1% resistors.

**Figure 3-1. LVDS Using External Resistors (LVDS25E)**



Note: All resistors are  $\pm 1\%$ .

**Table 3-1. LVDS25E DC Conditions**

Over Recommended Operating Conditions

Parameter	Description	Typ.	Units
$Z_{OUT}$	Output impedance	20	Ohms
$R_S$	Driver series resistor	158	Ohms
$R_P$	Driver parallel resistor	140	Ohms
$R_T$	Receiver termination	100	Ohms
$V_{OH}$	Output high voltage	1.43	V
$V_{OL}$	Output low voltage	1.07	V
$V_{OD}$	Output differential voltage	0.35	V
$V_{CM}$	Output common mode voltage	1.25	V
$Z_{BACK}$	Back impedance	100.5	Ohms
$I_{DC}$	DC output current	6.03	mA

## MachXO3L/LF External Switching Characteristics – C/E Devices<sup>1, 2, 3, 4, 5, 6, 10</sup>

Over Recommended Operating Conditions

Parameter	Description	Device	-6		-5		Units			
			Min.	Max.	Min.	Max.				
<b>Clocks</b>										
<b>Primary Clocks</b>										
$f_{MAX\_PRI}^7$	Frequency for Primary Clock Tree	All MachXO3L/LF devices	—	388	—	323	MHz			
$t_{W\_PRI}$	Clock Pulse Width for Primary Clock	All MachXO3L/LF devices	0.5	—	0.6	—	ns			
$t_{SKEW\_PRI}$	Primary Clock Skew Within a Device	MachXO3L/LF-1300	—	867	—	897	ps			
		MachXO3L/LF-2100	—	867	—	897	ps			
		MachXO3L/LF-4300	—	865	—	892	ps			
		MachXO3L/LF-6900	—	902	—	942	ps			
		MachXO3L/LF-9400	—	908	—	950	ps			
<b>Edge Clock</b>										
$f_{MAX\_EDGE}^7$	Frequency for Edge Clock	MachXO3L/LF	—	400	—	333	MHz			
<b>Pin-LUT-Pin Propagation Delay</b>										
$t_{PD}$	Best case propagation delay through one LUT-4	All MachXO3L/LF devices	—	6.72	—	6.96	ns			
<b>General I/O Pin Parameters (Using Primary Clock without PLL)</b>										
$t_{CO}$	Clock to Output - PIO Output Register	MachXO3L/LF-1300	—	7.46	—	7.66	ns			
		MachXO3L/LF-2100	—	7.46	—	7.66	ns			
		MachXO3L/LF-4300	—	7.51	—	7.71	ns			
		MachXO3L/LF-6900	—	7.54	—	7.75	ns			
		MachXO3L/LF-9400	—	7.53	—	7.83	ns			
$t_{SU}$	Clock to Data Setup - PIO Input Register	MachXO3L/LF-1300	-0.20	—	-0.20	—	ns			
		MachXO3L/LF-2100	-0.20	—	-0.20	—	ns			
		MachXO3L/LF-4300	-0.23	—	-0.23	—	ns			
		MachXO3L/LF-6900	-0.23	—	-0.23	—	ns			
		MachXO3L/LF-9400	-0.24	—	-0.24	—	ns			
$t_H$	Clock to Data Hold - PIO Input Register	MachXO3L/LF-1300	1.89	—	2.13	—	ns			
		MachXO3L/LF-2100	1.89	—	2.13	—	ns			
		MachXO3L/LF-4300	1.94	—	2.18	—	ns			
		MachXO3L/LF-6900	1.98	—	2.23	—	ns			
		MachXO3L/LF-9400	1.99	—	2.24	—	ns			
$t_{SU\_DEL}$	Clock to Data Setup - PIO Input Register with Data Input Delay	MachXO3L/LF-1300	1.61	—	1.76	—	ns			
		MachXO3L/LF-2100	1.61	—	1.76	—	ns			
		MachXO3L/LF-4300	1.66	—	1.81	—	ns			
		MachXO3L/LF-6900	1.53	—	1.67	—	ns			
		MachXO3L/LF-9400	1.65	—	1.80	—	ns			
$t_{H\_DEL}$	Clock to Data Hold - PIO Input Register with Input Data Delay	MachXO3L/LF-1300	-0.23	—	-0.23	—	ns			
		MachXO3L/LF-2100	-0.23	—	-0.23	—	ns			
		MachXO3L/LF-4300	-0.25	—	-0.25	—	ns			
		MachXO3L/LF-6900	-0.21	—	-0.21	—	ns			
		MachXO3L/LF-9400	-0.24	—	-0.24	—	ns			
$f_{MAX\_IO}$	Clock Frequency of I/O and PFU Register	All MachXO3L/LF devices	—	388	—	323	MHz			

Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>Generic DDRX1 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX1_RX.SCLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	All MachXO3L/LF devices, all sides	—	0.317	—	0.344	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.742	—	0.702	—	UI
f <sub>DATA</sub>	DDRX1 Input Data Speed		—	300	—	250	Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX1 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX1_RX.SCLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	All MachXO3L/LF devices, all sides	0.566	—	0.560	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.778	—	0.879	—	ns
f <sub>DATA</sub>	DDRX1 Input Data Speed		—	300	—		Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX2 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX2_RX.ECLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	MachXO3L/LF devices, bottom side only	—	0.316	—	0.342	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.710	—	0.675	—	UI
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDRX2 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX2_RX.ECLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDR4 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX4_RX.ECLK.Aligned<sup>8</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.307	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.782	—	0.699	—	UI
f <sub>DATA</sub>	DDR4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDR4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>Generic DDR4 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX4_RX.ECLK.Centered<sup>8</sup></b>							
t <sub>SU</sub>	Input Data Setup Before ECLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After ECLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDR4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDR4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>7:1 LVDS Inputs (GDDR71_RX.ECLK.7:1)<sup>9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.290	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.739	—	0.699	—	UI
f <sub>DATA</sub>	DDR71 Serial Input Data Speed		—	756	—	630	Mbps
f <sub>DDR71</sub>	DDR71 ECLK Frequency		—	378	—	315	MHz
f <sub>CLKIN</sub>	7:1 Input Clock Frequency (SCLK) (minimum limited by PLL)		—	108	—	90	MHz

Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>MIPI D-PHY Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input - GDDRX4_RX.ECLK.Centered<sup>10, 11, 12</sup></b>							
$t_{SU}^{15}$	Input Data Setup Before ECLK	All MachXO3L/LF devices, bottom side only	0.200	—	0.200	—	UI
$t_{HO}^{15}$	Input Data Hold After ECLK		0.200	—	0.200	—	UI
$f_{DATA}^{14}$	MIPI D-PHY Input Data Speed		—	900	—	900	Mbps
$f_{DDRX4}^{14}$	MIPI D-PHY ECLK Frequency		—	450	—	450	MHz
$f_{SCLK}^{14}$	SCLK Frequency		—	112.5	—	112.5	MHz
<b>Generic DDR Outputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX1_TX.SCLK.Aligned<sup>8</sup></b>							
$t_{DIA}$	Output Data Invalid After CLK Output	All MachXO3L/LF devices, all sides	—	0.520	—	0.550	ns
$t_{DIB}$	Output Data Invalid Before CLK Output		—	0.520	—	0.550	ns
$f_{DATA}$	DDRX1 Output Data Speed		—	300	—	250	Mbps
$f_{DDRX1}$	DDRX1 SCLK frequency		—	150	—	125	MHz
<b>Generic DDR Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX1_TX.SCLK.Centered<sup>8</sup></b>							
$t_{DVB}$	Output Data Valid Before CLK Output	All MachXO3L/LF devices, all sides	1.210	—	1.510	—	ns
$t_{DVA}$	Output Data Valid After CLK Output		1.210	—	1.510	—	ns
$f_{DATA}$	DDRX1 Output Data Speed		—	300	—	250	Mbps
$f_{DDRX1}$	DDRX1 SCLK Frequency (minimum limited by PLL)		—	150	—	125	MHz
<b>Generic DDRX2 Outputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX2_TX.ECLK.Aligned<sup>8</sup></b>							
$t_{DIA}$	Output Data Invalid After CLK Output	MachXO3L/LF devices, top side only	—	0.200	—	0.215	ns
$t_{DIB}$	Output Data Invalid Before CLK Output		—	0.200	—	0.215	ns
$f_{DATA}$	DDRX2 Serial Output Data Speed		—	664	—	554	Mbps
$f_{DDRX2}$	DDRX2 ECLK frequency		—	332	—	277	MHz
$f_{SCLK}$	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDRX2 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX2_TX.ECLK.Centered<sup>8, 9</sup></b>							
$t_{DVB}$	Output Data Valid Before CLK Output	MachXO3L/LF devices, top side only	0.535	—	0.670	—	ns
$t_{DVA}$	Output Data Valid After CLK Output		0.535	—	0.670	—	ns
$f_{DATA}$	DDRX2 Serial Output Data Speed		—	664	—	554	Mbps
$f_{DDRX2}$	DDRX2 ECLK Frequency (minimum limited by PLL)		—	332	—	277	MHz
$f_{SCLK}$	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDRX4 Outputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDRX4_TX.ECLK.Aligned<sup>8, 9</sup></b>							
$t_{DIA}$	Output Data Invalid After CLK Output	MachXO3L/LF devices, top side only	—	0.200	—	0.215	ns
$t_{DIB}$	Output Data Invalid Before CLK Output		—	0.200	—	0.215	ns
$f_{DATA}$	DDRX4 Serial Output Data Speed		—	800	—	630	Mbps
$f_{DDRX4}$	DDRX4 ECLK Frequency		—	400	—	315	MHz
$f_{SCLK}$	SCLK Frequency		—	100	—	79	MHz

Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>Generic DDRX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX4_TX.ECLK.Centered<sup>8, 9</sup></b>							
t <sub>DVB</sub>	Output Data Valid Before CLK Output	MachXO3L/LF devices, top side only	0.455	—	0.570	—	ns
t <sub>DVA</sub>	Output Data Valid After CLK Output		0.455	—	0.570	—	ns
f <sub>DATA</sub>	DDRX4 Serial Output Data Speed		—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDRX4 ECLK Frequency (minimum limited by PLL)		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>7:1 LVDS Outputs – GDDR71_TX.ECLK.7:1<sup>8, 9</sup></b>							
t <sub>DIB</sub>	Output Data Invalid Before CLK Output	MachXO3L/LF devices, top side only	—	0.160	—	0.180	ns
t <sub>DIA</sub>	Output Data Invalid After CLK Output		—	0.160	—	0.180	ns
f <sub>DATA</sub>	DDR71 Serial Output Data Speed		—	756	—	630	Mbps
f <sub>DDR71</sub>	DDR71 ECLK Frequency		—	378	—	315	MHz
f <sub>CLKOUT</sub>	7:1 Output Clock Frequency (SCLK) (minimum limited by PLL)		—	108	—	90	MHz
<b>MIPI D-PHY Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDRX4_TX.ECLK.Centered<sup>10, 11, 12</sup></b>							
t <sub>DVB</sub>	Output Data Valid Before CLK Output	All MachXO3L/LF devices, top side only	0.200	—	0.200	—	UI
t <sub>DVA</sub>	Output Data Valid After CLK Output		0.200	—	0.200	—	UI
f <sub>DATA</sub> <sup>14</sup>	MIPI D-PHY Output Data Speed		—	900	—	900	Mbps
f <sub>DDRX4</sub> <sup>14</sup>	MIPI D-PHY ECLK Frequency (minimum limited by PLL)		—	450	—	450	MHz
f <sub>SCLK</sub> <sup>14</sup>	SCLK Frequency		—	112.5	—	112.5	MHz

1. Exact performance may vary with device and design implementation. Commercial timing numbers are shown at 85 °C and 1.14 V. Other operating conditions, including industrial, can be extracted from the Diamond software.
2. General I/O timing numbers based on LVCMS 2.5, 8 mA, 0pf load, fast slew rate.
3. Generic DDR timing numbers based on LVDS I/O (for input, output, and clock ports).
4. 7:1 LVDS (GDDR71) uses the LVDS I/O standard (for input, output, and clock ports).
5. For Generic DDRX1 mode  $t_{SU} = t_{HO} = (t_{DVE} - t_{DVA} - 0.03 \text{ ns})/2$ .
6. The  $t_{SU\_DEL}$  and  $t_{H\_DEL}$  values use the SCLK\_ZERHOLD default step size. Each step is 105 ps (-6), 113 ps (-5), 120 ps (-4).
7. This number for general purpose usage. Duty cycle tolerance is +/-10%.
8. Duty cycle is +/- 5% for system usage.
9. Performance is calculated with 0.225 UI.
10. Performance is calculated with 0.20 UI.
11. Performance for Industrial devices are only supported with VCC between 1.16 V to 1.24 V.
12. Performance for Industrial devices and -5 devices are not modeled in the Diamond design tool.
13. The above timing numbers are generated using the Diamond design tool. Exact performance may vary with the device selected.
14. Above 800 Mbps is only supported with WLCSP and csFBGA packages
15. Between 800 Mbps to 900 Mbps:
  - a. VIDTH exceeds the MIPI D-PHY Input DC Conditions Table 3-4 and can be calculated with the equation  $t_{SU} \text{ or } t_H = -0.0005 * VIDTH + 0.3284$
  - b. Example calculations
    - i.  $t_{SU}$  and  $t_{HO} = 0.28$  with VIDTH = 100 mV
    - ii.  $t_{SU}$  and  $t_{HO} = 0.25$  with VIDTH = 170 mV
    - iii.  $t_{SU}$  and  $t_{HO} = 0.20$  with VIDTH = 270 mV

## NVCM/Flash Download Time<sup>1, 2</sup>

Symbol	Parameter	Device	Typ.	Units
$t_{\text{REFRESH}}$	POR to Device I/O Active	LCMXO3L/LF-640	1.9	ms
		LCMXO3L/LF-1300	1.9	ms
		LCMXO3L/LF-1300 256-Ball Package	1.4	ms
		LCMXO3L/LF-2100	1.4	ms
		LCMXO3L/LF-2100 324-Ball Package	2.4	ms
		LCMXO3L/LF-4300	2.4	ms
		LCMXO3L/LF-4300 400-Ball Package	3.8	ms
		LCMXO3L/LF-6900	3.8	ms
		LCMXO3L/LF-9400C	5.2	ms

1. Assumes sysMEM EBR initialized to an all zero pattern if they are used.

2. The NVCM/Flash download time is measured starting from the maximum voltage of POR trip point.

## Signal Descriptions (Cont.)

Signal Name	I/O	Descriptions
<b>Configuration</b> (Dual function pins used during sysCONFIG)		
PROGRAMN	I	Initiates configuration sequence when asserted low. This pin always has an active pull-up.
INITN	I/O	Open Drain pin. Indicates the FPGA is ready to be configured. During configuration, a pull-up is enabled.
DONE	I/O	Open Drain pin. Indicates that the configuration sequence is complete, and the start-up sequence is in progress.
MCLK/CCLK	I/O	Input Configuration Clock for configuring an FPGA in Slave SPI mode. Output Configuration Clock for configuring an FPGA in SPI and SPI <sub>m</sub> configuration modes.
SN	I	Slave SPI active low chip select input.
CSSPIN	I/O	Master SPI active low chip select output.
SI/SPISI	I/O	Slave SPI serial data input and master SPI serial data output.
SO/SPISO	I/O	Slave SPI serial data output and master SPI serial data input.
SCL	I/O	Slave I <sup>2</sup> C clock input and master I <sup>2</sup> C clock output.
SDA	I/O	Slave I <sup>2</sup> C data input and master I <sup>2</sup> C data output.

	MachXO3L/LF-9400C			
	CSFBGA256	CABGA256	CABGA400	CABGA484
<b>General Purpose IO per Bank</b>				
Bank 0	50	50	83	95
Bank 1	52	52	84	96
Bank 2	52	52	84	96
Bank 3	16	16	28	36
Bank 4	16	16	24	24
Bank 5	20	20	32	36
<b>Total General Purpose Single Ended IO</b>	<b>206</b>	<b>206</b>	<b>335</b>	<b>383</b>
<b>Differential IO per Bank</b>				
Bank 0	25	25	42	48
Bank 1	26	26	42	48
Bank 2	26	26	42	48
Bank 3	8	8	14	18
Bank 4	8	8	12	12
Bank 5	10	10	16	18
<b>Total General Purpose Differential IO</b>	<b>103</b>	<b>103</b>	<b>168</b>	<b>192</b>
<b>Dual Function IO</b>	<b>37</b>	<b>37</b>	<b>37</b>	<b>45</b>
<b>Number 7:1 or 8:1 Gearboxes</b>				
Number of 7:1 or 8:1 Output Gearbox Available (Bank 0)	20	20	22	24
Number of 7:1 or 8:1 Input Gearbox Available (Bank 2)	20	20	22	24
<b>High-speed Differential Outputs</b>				
Bank 0	20	20	21	24
<b>VCCIO Pins</b>				
Bank 0	4	4	5	9
Bank 1	3	4	5	9
Bank 2	4	4	5	9
Bank 3	2	1	2	3
Bank 4	2	2	2	3
Bank 5	2	1	2	3
VCC	8	8	10	12
GND	24	24	33	52
NC	0	1	0	0
Reserved for Configuration	1	1	1	1
<b>Total Count of Bonded Pins</b>	<b>256</b>	<b>256</b>	<b>400</b>	<b>484</b>

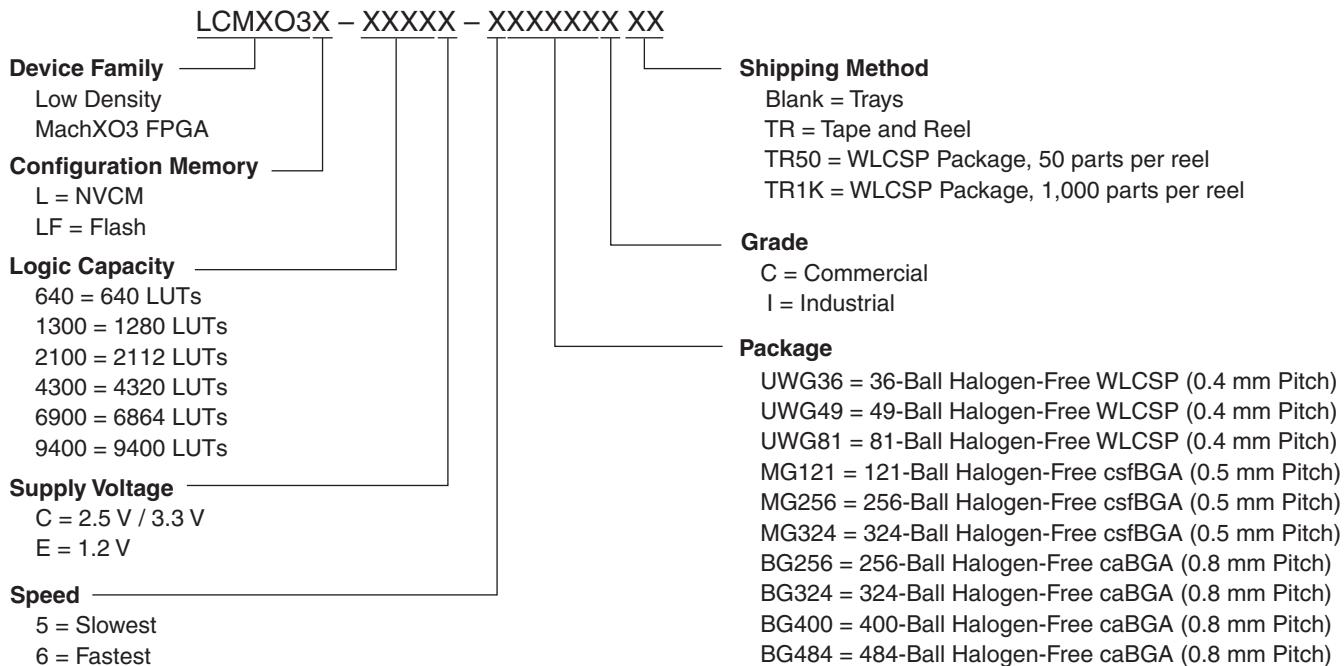
# MachXO3 Family Data Sheet

## Ordering Information

May 2016

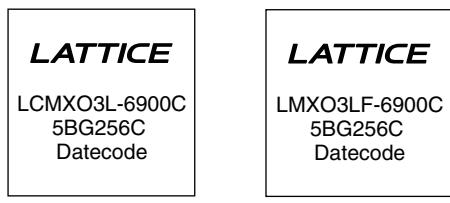
Advance Data Sheet DS1047

### MachXO3 Part Number Description



### Ordering Information

MachXO3L/LF devices have top-side markings as shown in the examples below, on the 256-Ball caBGA package with MachXO3-6900 device in Commercial Temperature in Speed Grade 5. Notice that for the MachXO3LF device, *LMXO3LF* is used instead of *LCMXO3LF* as in the Part Number.



Note: *LCMXO3LF* is marked with *LMXO3LF*

*Note: Markings are abbreviated for small packages.*

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3LF-2100E-6MG324I	2100	1.2 V	6	Halogen-Free csfBGA	324	IND
LCMXO3LF-2100C-5BG256C	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3LF-2100C-6BG256C	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3LF-2100C-5BG256I	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3LF-2100C-6BG256I	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3LF-2100C-5BG324C	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	COM
LCMXO3LF-2100C-6BG324C	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	COM
LCMXO3LF-2100C-5BG324I	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	IND
LCMXO3LF-2100C-6BG324I	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	IND

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3LF-4300E-5UWG81CTR	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3LF-4300E-5UWG81CTR50	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3LF-4300E-5UWG81CTR1K	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3LF-4300E-5UWG81ITR	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3LF-4300E-5UWG81ITR50	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3LF-4300E-5UWG81ITR1K	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3LF-4300E-5MG121C	4300	1.2 V	5	Halogen-Free csfBGA	121	COM
LCMXO3LF-4300E-6MG121C	4300	1.2 V	6	Halogen-Free csfBGA	121	COM
LCMXO3LF-4300E-5MG121I	4300	1.2 V	5	Halogen-Free csfBGA	121	IND
LCMXO3LF-4300E-6MG121I	4300	1.2 V	6	Halogen-Free csfBGA	121	IND
LCMXO3LF-4300E-5MG256C	4300	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3LF-4300E-6MG256C	4300	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3LF-4300E-5MG256I	4300	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3LF-4300E-6MG256I	4300	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3LF-4300E-5MG324C	4300	1.2 V	5	Halogen-Free csfBGA	324	COM
LCMXO3LF-4300E-6MG324C	4300	1.2 V	6	Halogen-Free csfBGA	324	COM
LCMXO3LF-4300E-5MG324I	4300	1.2 V	5	Halogen-Free csfBGA	324	IND
LCMXO3LF-4300E-6MG324I	4300	1.2 V	6	Halogen-Free csfBGA	324	IND
LCMXO3LF-4300C-5BG256C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3LF-4300C-6BG256C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3LF-4300C-5BG256I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3LF-4300C-6BG256I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3LF-4300C-5BG324C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	COM
LCMXO3LF-4300C-6BG324C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	COM
LCMXO3LF-4300C-5BG324I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	IND
LCMXO3LF-4300C-6BG324I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	IND
LCMXO3LF-4300C-5BG400C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	COM
LCMXO3LF-4300C-6BG400C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	COM
LCMXO3LF-4300C-5BG400I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	IND
LCMXO3LF-4300C-6BG400I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	IND

Date	Version	Section	Change Summary
June 2014	1.0	—	Product name/trademark adjustment.
		Introduction	Updated Features section.
			Updated Table 1-1, MachXO3L Family Selection Guide. Changed fcCSP packages to csfBGA. Adjusted 121-ball csfBGA arrow.
			Introduction section general update.
		Architecture	General update.
		DC and Switching Characteristics	Updated sysIO Recommended Operating Conditions section. Removed V <sub>REF</sub> (V) column. Added standards.
			Updated Maximum sysIO Buffer Performance section. Added MIPI I/O standard.
			Updated MIPI D-PHY Emulation section. Changed Low Speed to Low Power. Updated Table 3-4, MIPI DC Conditions.
			Updated Table 3-5, MIPI D-PHY Output DC Conditions.
			Updated Maximum sysIO Buffer Performance section.
			Updated MachXO3L External Switching Characteristics – C/E Device section.
May 2014	00.3	Introduction	Updated Features section.
			Updated Table 1-1, MachXO3L Family Selection Guide. Moved 121-ball fcCSP arrow.
			General update of Introduction section.
		Architecture	General update.
		Pinout Information	Updated Pin Information Summary section. Updated or added data on WLCSP49, WLCSP81, CABGA324, and CABGA400 for specific devices.
		Ordering Information	Updated MachXO3L Part Number Description section. Updated or added data on WLCSP49, WLCSP81, CABGA324, and CABGA400 for specific devices.
			Updated Ultra Low Power Commercial and Industrial Grade Devices, Halogen Free (RoHS) Packaging section. Added part numbers.
February 2014	00.2	DC and Switching Characteristics	Updated MachXO3L External Switching Characteristics – C/E Devices table. Removed LPDDR and DDR2 parameters.
	00.1	—	Initial release.