Evit ce Semiconductor Corporation - <u>LCMXO3L-9400C-5BG400C Datasheet</u>



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Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	1175
Number of Logic Elements/Cells	9400
Total RAM Bits	442368
Number of I/O	335
Number of Gates	-
Voltage - Supply	2.375V ~ 3.465V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-CABGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-9400c-5bg400c

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MachXO3 Family Data Sheet Introduction

January 2016

Features

Solutions

- Smallest footprint, lowest power, high data throughput bridging solutions for mobile applications
- Optimized footprint, logic density, IO count, IO performance devices for IO management and logic applications
- High IO/logic, lowest cost/IO, high IO devices for IO expansion applications

■ Flexible Architecture

- Logic Density ranging from 640 to 9.4K LUT4
- High IO to LUT ratio with up to 384 IO pins

Advanced Packaging

- 0.4 mm pitch: 1K to 4K densities in very small footprint WLCSP (2.5 mm x 2.5 mm to 3.8 mm x 3.8 mm) with 28 to 63 IOs
- 0.5 mm pitch: 640 to 6.9K LUT densities in 6 mm x 6 mm to 10 mm x 10 mm BGA packages with up to 281 IOs
- 0.8 mm pitch: 1K to 9.4K densities with up to 384 IOs in BGA packages

Pre-Engineered Source Synchronous I/O

- DDR registers in I/O cells
- Dedicated gearing logic
- 7:1 Gearing for Display I/Os
- Generic DDR, DDRx2, DDRx4

High Performance, Flexible I/O Buffer

- Programmable sysIO[™] buffer supports wide range of interfaces:
 - LVCMOS 3.3/2.5/1.8/1.5/1.2
 - LVTTL
 - LVDS, Bus-LVDS, MLVDS, LVPECL
 - MIPI D-PHY Emulated
 - Schmitt trigger inputs, up to 0.5 V hysteresis
- Ideal for IO bridging applications
- I/Os support hot socketing
- On-chip differential termination
- Programmable pull-up or pull-down mode

■ Flexible On-Chip Clocking

- · Eight primary clocks
- Up to two edge clocks for high-speed I/O interfaces (top and bottom sides only)
- Up to two analog PLLs per device with fractional-n frequency synthesis
 - Wide input frequency range (7 MHz to 400 MHz)
- Non-volatile, Multi-time Programmable
 - Instant-on
 - Powers up in microseconds
 - · Optional dual boot with external SPI memory
 - Single-chip, secure solution
 - Programmable through JTAG, SPI or I²C
 - MachXO3L includes multi-time programmable NVCM
 - MachXO3LF infinitely reconfigurable Flash

 Supports background programming of non-volatile memory

TransFR Reconfiguration

In-field logic update while IO holds the system state

Enhanced System Level Support

- On-chip hardened functions: SPI, I²C, timer/ counter
- On-chip oscillator with 5.5% accuracy
- Unique TraceID for system tracking
- Single power supply with extended operating range
- IEEE Standard 1149.1 boundary scan
- IEEE 1532 compliant in-system programming

Applications

- Consumer Electronics
- Compute and Storage
- Wireless Communications
- Industrial Control Systems
- Automotive System

Low Cost Migration Path

- Migration from the Flash based MachXO3LF to the NVCM based MachXO3L
- · Pin compatible and equivalent timing

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Advance Data Sheet DS1047



This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the $t_{I,OCK}$ parameter has been satisfied.

The MachXO3L/LF also has a feature that allows the user to select between two different reference clock sources dynamically. This feature is implemented using the PLLREFCS primitive. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

The MachXO3L/LF PLL contains a WISHBONE port feature that allows the PLL settings, including divider values, to be dynamically changed from the user logic. When using this feature the EFB block must also be instantiated in the design to allow access to the WISHBONE ports. Similar to the dynamic phase adjustment, when PLL settings are updated through the WISHBONE port the PLL may lose lock and not relock until the t_{LOCK} parameter has been satisfied. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

For more details on the PLL and the WISHBONE interface, see TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide.



Figure 2-7. PLL Diagram

Table 2-4 provides signal descriptions of the PLL block.

Table 2-4	. PLL	Signal	Descriptions
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Port Name	I/O	Description	
CLKI	Ι	Input clock to PLL	
CLKFB	I	edback clock	
PHASESEL[1:0]	Ι	Select which output is affected by Dynamic Phase adjustment ports	
PHASEDIR	I	Dynamic Phase adjustment direction	
PHASESTEP	Ι	Dynamic Phase step – toggle shifts VCO phase adjust by one step.	



Table 2-4. PLL Signal Descriptions (Continued)

Port Name	I/O	Description	
CLKOP	0	Primary PLL output clock (with phase shift adjustment)	
CLKOS	0	Secondary PLL output clock (with phase shift adjust)	
CLKOS2	0	Secondary PLL output clock2 (with phase shift adjust)	
CLKOS3	0	Secondary PLL output clock3 (with phase shift adjust)	
LOCK	0	PLL LOCK, asynchronous signal. Active high indicates PLL is locked to input and feed- back signals.	
DPHSRC	0	Dynamic Phase source – ports or WISHBONE is active	
STDBY	I	Standby signal to power down the PLL	
RST	I	PLL reset without resetting the M-divider. Active high reset.	
RESETM	I	PLL reset - includes resetting the M-divider. Active high reset.	
RESETC	I	Reset for CLKOS2 output divider only. Active high reset.	
RESETD	I	Reset for CLKOS3 output divider only. Active high reset.	
ENCLKOP	I	Enable PLL output CLKOP	
ENCLKOS	I	Enable PLL output CLKOS when port is active	
ENCLKOS2	I	Enable PLL output CLKOS2 when port is active	
ENCLKOS3	I	Enable PLL output CLKOS3 when port is active	
PLLCLK	I	PLL data bus clock input signal	
PLLRST	I	PLL data bus reset. This resets only the data bus not any register values.	
PLLSTB	I	PLL data bus strobe signal	
PLLWE	I	PLL data bus write enable signal	
PLLADDR [4:0]	I	PLL data bus address	
PLLDATI [7:0]	I	PLL data bus data input	
PLLDATO [7:0]	0	PLL data bus data output	
PLLACK	0	PLL data bus acknowledge signal	

sysMEM Embedded Block RAM Memory

The MachXO3L/LF devices contain sysMEM Embedded Block RAMs (EBRs). The EBR consists of a 9-Kbit RAM, with dedicated input and output registers. This memory can be used for a wide variety of purposes including data buffering, PROM for the soft processor and FIFO.

sysMEM Memory Block

The sysMEM block can implement single port, dual port, pseudo dual port, or FIFO memories. Each block can be used in a variety of depths and widths as shown in Table 2-5.



Figure 2-8. sysMEM Memory Primitives





Port Name	Description	Active State
CLK	Clock	Rising Clock Edge
CE	Clock Enable	Active High
OCE ¹	Output Clock Enable	Active High
RST	Reset	Active High
BE ¹	Byte Enable	Active High
WE	Write Enable	Active High
AD	Address Bus	
DI	Data In	_
DO	Data Out	_
CS	Chip Select	Active High
AFF	FIFO RAM Almost Full Flag	
FF	FIFO RAM Full Flag	_
AEF	FIFO RAM Almost Empty Flag	_
EF	FIFO RAM Empty Flag	_
RPRST	FIFO RAM Read Pointer Reset	_

Table 2-6. EBR Signal Descriptions

1. Optional signals.

2. For dual port EBR primitives a trailing 'A' or 'B' in the signal name specifies the EBR port A or port B respectively.

3. For FIFO RAM mode primitive, a trailing 'R' or 'W' in the signal name specifies the FIFO read port or write port respectively.

4. For FIFO RAM mode primitive FULLI has the same function as CSW(2) and EMPTYI has the same function as CSR(2).

In FIFO mode, CLKW is the write port clock, CSW is the write port chip select, CLKR is the read port clock, CSR is the read port clock, CSR is the read port clock.

The EBR memory supports three forms of write behavior for single or dual port operation:

- 1. **Normal** Data on the output appears only during the read cycle. During a write cycle, the data (at the current address) does not appear on the output. This mode is supported for all data widths.
- 2. Write Through A copy of the input data appears at the output of the same port. This mode is supported for all data widths.
- 3. Read-Before-Write When new data is being written, the old contents of the address appears at the output.

FIFO Configuration

The FIFO has a write port with data-in, CEW, WE and CLKW signals. There is a separate read port with data-out, RCE, RE and CLKR signals. The FIFO internally generates Almost Full, Full, Almost Empty and Empty Flags. The Full and Almost Full flags are registered with CLKW. The Empty and Almost Empty flags are registered with CLKR. Table 2-7 shows the range of programming values for these flags.

Table 2-7. Programmable FIFO Flag Ranges

Flag Name	Programming Range	
Full (FF)	1 to max (up to 2 ^N -1)	
Almost Full (AF)	1 to Full-1	
Almost Empty (AE)	1 to Full-1	
Empty (EF)	0	

N = Address bit width.

The FIFO state machine supports two types of reset signals: RST and RPRST. The RST signal is a global reset that clears the contents of the FIFO by resetting the read/write pointer and puts the FIFO flags in their initial reset



state. The RPRST signal is used to reset the read pointer. The purpose of this reset is to retransmit the data that is in the FIFO. In these applications it is important to keep careful track of when a packet is written into or read from the FIFO.

Memory Core Reset

The memory core contains data output latches for ports A and B. These are simple latches that can be reset synchronously or asynchronously. RSTA and RSTB are local signals, which reset the output latches associated with port A and port B respectively. The Global Reset (GSRN) signal resets both ports. The output data latches and associated resets for both ports are as shown in Figure 2-9.

Figure 2-9. Memory Core Reset



For further information on the sysMEM EBR block, please refer to TN1290, Memory Usage Guide for MachXO3 Devices.

EBR Asynchronous Reset

EBR asynchronous reset or GSR (if used) can only be applied if all clock enables are low for a clock cycle before the reset is applied and released a clock cycle after the reset is released, as shown in Figure 2-10. The GSR input to the EBR is always asynchronous.

Figure 2-10. EBR Asynchronous Reset (Including GSR) Timing Diagram

Reset	
Clock	
Clock	

If all clock enables remain enabled, the EBR asynchronous reset or GSR may only be applied and released after the EBR read and write clock inputs are in a steady state condition for a minimum of 1/f_{MAX} (EBR clock). The reset release must adhere to the EBR synchronous reset setup time before the next active read or write clock edge.



Figure 2-11. Group of Four Programmable I/O Cells





Input Gearbox

Each PIC on the bottom edge has a built-in 1:8 input gearbox. Each of these input gearboxes may be programmed as a 1:7 de-serializer or as one IDDRX4 (1:8) gearbox or as two IDDRX2 (1:4) gearboxes. Table 2-9 shows the gearbox signals.

Table 2-9. Input Gearbox Signal List

Name	I/O Type	Description
D	Input	High-speed data input after programmable delay in PIO A input register block
ALIGNWD	Input	Data alignment signal from device core
SCLK	Input	Slow-speed system clock
ECLK[1:0]	Input	High-speed edge clock
RST	Input	Reset
Q[7:0]	Output	Low-speed data to device core: Video RX(1:7): Q[6:0] GDDRX4(1:8): Q[7:0] GDDRX2(1:4)(IOL-A): Q4, Q5, Q6, Q7 GDDRX2(1:4)(IOL-C): Q0, Q1, Q2, Q3

These gearboxes have three stage pipeline registers. The first stage registers sample the high-speed input data by the high-speed edge clock on its rising and falling edges. The second stage registers perform data alignment based on the control signals UPDATE and SEL0 from the control block. The third stage pipeline registers pass the data to the device core synchronized to the low-speed system clock. Figure 2-13 shows a block diagram of the input gearbox.



Output Gearbox

Each PIC on the top edge has a built-in 8:1 output gearbox. Each of these output gearboxes may be programmed as a 7:1 serializer or as one ODDRX4 (8:1) gearbox or as two ODDRX2 (4:1) gearboxes. Table 2-10 shows the gearbox signals.

Table 2-10. Output Gearbox Signal List

Name	I/O Type	Description
Q	Output	High-speed data output
D[7:0]	Input	Low-speed data from device core
Video TX(7:1): D[6:0]		
GDDRX4(8:1): D[7:0]		
GDDRX2(4:1)(IOL-A): D[3:0]		
GDDRX2(4:1)(IOL-C): D[7:4]		
SCLK	Input	Slow-speed system clock
ECLK [1:0]	Input	High-speed edge clock
RST	Input	Reset

The gearboxes have three stage pipeline registers. The first stage registers sample the low-speed input data on the low-speed system clock. The second stage registers transfer data from the low-speed clock registers to the high-speed clock registers. The third stage pipeline registers controlled by high-speed edge clock shift and mux the high-speed data out to the sysIO buffer. Figure 2-14 shows the output gearbox block diagram.



Figure 2-18. PC Core Block Diagram



Table 2-14 describes the signals interfacing with the I²C cores.

 Table 2-14. PC Core Signal Description

Signal Name	I/O	Description
i2c_scl	Bi-directional	Bi-directional clock line of the I ² C core. The signal is an output if the I ² C core is in master mode. The signal is an input if the I ² C core is in slave mode. MUST be routed directly to the pre-assigned I/O of the chip. Refer to the Pinout Information section of this document for detailed pad and pin locations of I ² C ports in each MachXO3L/LF device.
i2c_sda	Bi-directional	Bi-directional data line of the l^2C core. The signal is an output when data is transmitted from the l^2C core. The signal is an input when data is received into the l^2C core. MUST be routed directly to the pre-assigned I/O of the chip. Refer to the Pinout Information section of this document for detailed pad and pin locations of l^2C ports in each MachXO3L/LF device.
i2c_irqo	Output	Interrupt request output signal of the I ² C core. The intended usage of this signal is for it to be connected to the WISHBONE master controller (i.e. a microcontroller or state machine) and request an interrupt when a specific condition is met. These conditions are described with the I ² C register definitions.
cfg_wake	Output	Wake-up signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" feature has been set within the EFB GUI, I^2C Tab.
cfg_stdby	Output	Stand-by signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" feature has been set within the EFB GUI, I^2C Tab.

Hardened SPI IP Core

Every MachXO3L/LF device has a hard SPI IP core that can be configured as a SPI master or slave. When the IP core is configured as a master it will be able to control other SPI enabled chips connected to the SPI bus. When the core is configured as the slave, the device will be able to interface to an external SPI master. The SPI IP core on MachXO3L/LF devices supports the following functions:

- Configurable Master and Slave modes
- Full-Duplex data transfer
- Mode fault error flag with CPU interrupt capability
- Double-buffered data register
- Serial clock with programmable polarity and phase
- LSB First or MSB First Data Transfer
- Interface to custom logic through 8-bit WISHBONE interface



There are some limitations on the use of the hardened user SPI. These are defined in the following technical notes:

- TN1087, Minimizing System Interruption During Configuration Using TransFR Technology (Appendix B)
- TN1293, Using Hardened Control Functions in MachXO3 Devices

Figure 2-19. SPI Core Block Diagram



Table 2-15 describes the signals interfacing with the SPI cores.

Table 2-15. SPI Core Signal Description

Signal Name	I/O	Master/Slave	Description	
spi_csn[0]	0	Master	SPI master chip-select output	
spi_csn[17]	0	Master	Additional SPI chip-select outputs (total up to eight slaves)	
spi_scsn	I	Slave	SPI slave chip-select input	
spi_irq	0	Master/Slave	Interrupt request	
spi_clk	I/O	Master/Slave	SPI clock. Output in master mode. Input in slave mode.	
spi_miso	I/O	Master/Slave	SPI data. Input in master mode. Output in slave mode.	
spi_mosi	I/O	Master/Slave	SPI data. Output in master mode. Input in slave mode.	
sn	I	Slave	Configuration Slave Chip Select (active low), dedicated for selecting the Configuration Logic.	
cfg_stdby	0	Master/Slave	Stand-by signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" fe ture has been set within the EFB GUI, SPI Tab.	
cfg_wake	0	Master/Slave	Wake-up signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" feature has been set within the EFB GUI, SPI Tab.	



Programming and Erase Supply Current – C/E Devices^{1, 2, 3, 4}

Symbol	Parameter	Device	Typ.⁴	Units
I _{CC}	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	22.1	mA
		LCMXO3L/LF-2100C	22.1	mA
		LCMXO3L/LF-2100C 324 Ball Package	26.8	mA
		LCMXO3L/LF-4300C	26.8	mA
		LCMXO3L/LF-4300C 400 Ball Package	33.2	mA
		LCMXO3L/LF-6900C	33.2	mA
		LCMXO3L/LF-9400C	39.6	mA
		LCMXO3L/LF-640E	17.7	mA
		LCMXO3L/LF-1300E	17.7	mA
		LCMXO3L/LF-1300E 256 Ball Package	18.3	mA
		LCMXO3L/LF-2100E	18.3	mA
		LCMXO3L/LF-2100E 324 Ball Package	20.4	mA
		LCMXO3L/LF-4300E	20.4	mA
		LCMXO3L/LF-6900E	23.9	mA
		LCMXO3L/LF-9400E	28.5	mA
I _{CCIO}	Bank Power Supply ⁵ VCCIO = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, Power Estimation and Management for MachXO3 Devices.

2. Assumes all inputs are held at $V_{\mbox{\scriptsize CCIO}}$ or GND and all outputs are tri-stated.

3. Typical user pattern.

4. JTAG programming is at 25 MHz.

5. $T_J = 25$ °C, power supplies at nominal voltage.

6. Per bank. $V_{CCIO} = 2.5$ V. Does not include pull-up/pull-down.



LVPECL

The MachXO3L/LF family supports the differential LVPECL standard through emulation. This output standard is emulated using complementary LVCMOS outputs in conjunction with resistors across the driver outputs on all the devices. The LVPECL input standard is supported by the LVDS differential input buffer. The scheme shown in Differential LVPECL is one possible solution for point-to-point signals.

Figure 3-3. Differential LVPECL



Table 3-3. LVPECL DC Conditions¹

Symbol	Description	Nominal	Units
Z _{OUT}	Output impedance	20	Ohms
R _S	Driver series resistor	93	Ohms
R _P	Driver parallel resistor	196	Ohms
R _T	Receiver termination	100	Ohms
V _{OH}	Output high voltage	2.05	V
V _{OL}	Output low voltage	1.25	V
V _{OD}	Output differential voltage	0.80	V
V _{CM}	Output common mode voltage	1.65	V
Z _{BACK}	Back impedance	100.5	Ohms
I _{DC}	DC output current	12.11	mA

Over Recommended Operating Conditions

1. For input buffer, see LVDS table.

For further information on LVPECL, BLVDS and other differential interfaces please see details of additional technical documentation at the end of the data sheet.



MachXO3L/LF External Switching Characteristics – C/E Devices^{1, 2, 3, 4, 5, 6, 10}

				6	_		
Parameter	Description	Device	Min.	Max.	Min.	Max.	Units
Clocks							
Primary Clo	cks						-
f _{MAX_PRI} ⁷	Frequency for Primary Clock Tree	All MachXO3L/LF devices	_	388	_	323	MHz
t _{W_PRI}	Clock Pulse Width for Primary Clock	All MachXO3L/LF devices	0.5		0.6		ns
		MachXO3L/LF-1300		867	_	897	ps
		MachXO3L/LF-2100		867		897	ps
t _{SKEW_PRI}	Primary Clock Skew Within a Device	MachXO3L/LF-4300	_	865	_	892	ps
		MachXO3L/LF-6900	_	902	_	942	ps
		MachXO3L/LF-9400	_	908	_	950	ps
Edge Clock							
f _{MAX_EDGE} ⁷	Frequency for Edge Clock	MachXO3L/LF		400	_	333	MHz
Pin-LUT-Pin	Propagation Delay						
t _{PD}	Best case propagation delay through one LUT-4	All MachXO3L/LF devices		6.72		6.96	ns
General I/O	Pin Parameters (Using Primary Clock with	out PLL)					
		MachXO3L/LF-1300	—	7.46	—	7.66	ns
		MachXO3L/LF-2100	_	7.46	_	7.66	ns
t _{CO}	Clock to Output - PIO Output Register	MachXO3L/LF-4300	_	7.51		7.71	ns
		MachXO3L/LF-6900	_	7.54		7.75	ns
		MachXO3L/LF-9400	_	7.53		7.83	ns
		MachXO3L/LF-1300	-0.20	_	-0.20		ns
		MachXO3L/LF-2100	-0.20	_	-0.20		ns
t _{SU}	Clock to Data Setup - PIO Input Register	MachXO3L/LF-4300	-0.23	_	-0.23		ns
		MachXO3L/LF-6900	-0.23		-0.23		ns
		MachXO3L/LF-9400	-0.24		-0.24		ns
		MachXO3L/LF-1300	1.89		2.13		ns
		MachXO3L/LF-2100	1.89	_	2.13		ns
t _H	Clock to Data Hold - PIO Input Register	MachXO3L/LF-4300	1.94	_	2.18		ns
		MachXO3L/LF-6900	1.98	_	2.23		ns
		MachXO3L/LF-9400	1.99	_	2.24		ns
		MachXO3L/LF-1300	1.61	_	1.76		ns
		MachXO3L/LF-2100	1.61	_	1.76		ns
t _{SU DEL}	Clock to Data Setup - PIO Input Register	MachXO3L/LF-4300	1.66	_	1.81		ns
	with Data input Delay	MachXO3L/LF-6900	1.53	_	1.67		ns
		MachXO3L/LF-9400	1.65	_	1.80		ns
		MachXO3L/LF-1300	-0.23	_	-0.23		ns
		MachXO3L/LF-2100	-0.23	_	-0.23		ns
^t H DEL	Clock to Data Hold - PIO Input Register with	MachXO3L/LF-4300	-0.25	_	-0.25	_	ns
	Input Data Delay	MachXO3L/LF-6900	-0.21	_	-0.21	_	ns
		MachXO3L/LF-9400	-0.24	_	-0.24	_	ns
f _{MAX_IO}	Clock Frequency of I/O and PFU Register	All MachXO3L/LF devices	—	388	—	323	MHz

Over Recommended Operating Conditions



DC and Switching Characteristics MachXO3 Family Data Sheet

		-6		-	5	
Description	Device	Min.	Max.	Min.	Max.	Units
RX4 Outputs with Clock and Data Centere (.ECLK.Centered ^{8, 9}	d at Pin Using PCLK Pin fo	or Clock	Input –			
Output Data Valid Before CLK Output		0.455		0.570		ns
Output Data Valid After CLK Output		0.455	—	0.570	_	ns
DDRX4 Serial Output Data Speed	MachXO3L/LF devices,	—	800	_	630	Mbps
DDRX4 ECLK Frequency (minimum limited by PLL)	top side only	_	400	_	315	MHz
SCLK Frequency	-		100		79	MHz
Itputs – GDDR71_TX.ECLK.7:1 ^{8, 9}						
Output Data Invalid Before CLK Output			0.160	_	0.180	ns
Output Data Invalid After CLK Output			0.160		0.180	ns
DDR71 Serial Output Data Speed	MachXO3L/LF devices,		756		630	Mbps
DDR71 ECLK Frequency	top side only	_	378	—	315	MHz
7:1 Output Clock Frequency (SCLK) (mini- mum limited by PLL)		_	108	_	90	MHz
Outputs with Clock and Data Centered at P (.ECLK.Centered ^{10, 11, 12}	in Using PCLK Pin for Clo	ck Input	-			
Output Data Valid Before CLK Output		0.200	—	0.200	_	UI
Output Data Valid After CLK Output		0.200	—	0.200	_	UI
MIPI D-PHY Output Data Speed	All MachXO3L/LF devices, top side only	_	900	—	900	Mbps
MIPI D-PHY ECLK Frequency (minimum limited by PLL)		_	450	_	450	MHz
SCLK Frequency	<u> </u>	—	112.5	—	112.5	MHz
	Description RX4 Outputs with Clock and Data Centered CECLK.Centered ^{8, 9} Output Data Valid Before CLK Output Output Data Valid After CLK Output DDRX4 Serial Output Data Speed DDRX4 ECLK Frequency (minimum limited by PLL) SCLK Frequency ttputs – GDDR71_TX.ECLK.7:1 ^{8, 9} Output Data Invalid Before CLK Output Output Data Invalid After CLK Output DDR71 Serial Output Data Speed DDR71 ECLK Frequency 7:1 Output Clock Frequency (SCLK) (mini- mum limited by PLL) Outputs with Clock and Data Centered at P C.ECLK.Centered ^{10, 11, 12} Output Data Valid Before CLK Output Output Data Valid After CLK Output MIPI D-PHY Output Data Speed MIPI D-PHY ECLK Frequency (minimum limited by PLL) SCLK Frequency	DescriptionDeviceRX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for C.ECLK.Centered ^{8, 9} In Using PCLK Pin for C.ECLK.Centered ^{8, 9} Output Data Valid Before CLK OutputMachXO3L/LF devices, top side onlyDDRX4 Serial Output Data SpeedMachXO3L/LF devices, top side onlyDDRX4 ECLK Frequency (minimum limited by PLL)MachXO3L/LF devices, top side onlySCLK FrequencyOutput Data Invalid Before CLK OutputOutput Data Invalid After CLK OutputMachXO3L/LF devices, top side onlyOutput Data Invalid After CLK OutputMachXO3L/LF devices, top side onlyDDR71 Serial Output Data SpeedMachXO3L/LF devices, top side onlyDDR71 ECLK Frequency 7:1 Output Clock Frequency (SCLK) (mini- mum limited by PLL)MachXO3L/LF devices, top side onlyOutput Data Valid Before CLK OutputOutput Data Valid Before CLK OutputOutput Data Valid Before CLK OutputAll MachXO3L/LF devices, top side onlyOutput Data Valid After CLK OutputAll MachXO3L/LF devices, top side onlyMIPI D-PHY Output Data SpeedAll MachXO3L/LF devices, top side onlyMIPI D-PHY ECLK Frequency (minimum limited by PLL)All MachXO3L/LF devices, top side onlySCLK FrequencyAll MachXO3L/LF devices, top side only	Description Device Min. RX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock (LECLK.Centered ^{8,9}) 0.455 Output Data Valid Before CLK Output 0.455 DDRX4 Serial Output Data Speed MachXO3L/LF devices, top side only DDRX4 ECLK Frequency (minimum limited by PLL) MachXO3L/LF devices, top side only SCLK Frequency Output Data Invalid Before CLK Output Output Data Invalid Before CLK Output Output Data Invalid Before CLK Output Output Data Invalid After CLK Output DDR71 Serial Output Data Speed MachXO3L/LF devices, top side only DDR71 ECLK Frequency 7:1 Output Clock Frequency (SCLK) (minimum limited by PLL) Output Data Valid After CLK Output Output Data Valid After CLK Output Output Data Valid After CLK Output 0.200 0.200 0.200 Output Data Valid After CLK	-6Min.Max.RX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input - CLECLK.Centered ^{8, 9} Output Data Valid Before CLK Output0.455Output Data Valid After CLK OutputMachXO3L/LF devices, top side only0.455DDRX4 ECLK Frequency (minimum limited by PLL)MachXO3L/LF devices, top side only800SCLK Frequency (minimum limited by PLL)100400Output Data Invalid Before CLK Output0.160Output Data Invalid After CLK Output0.160DDR71 Serial Output Data Speed DDR71 Serial Output Data SpeedMachXO3L/LF devices, top side only108Output Swith Clock and Data Centered at Pin Using PCLK Pin for Clock Input - t.ECLK.Centered ^{10, 11, 12} 0.200Output Data Valid Before CLK Output DDR71 Serial Output Data SpeedAll MachXO3L/LF devices, top side only0.200Output Data Valid After CLK Output Mup PLL)All MachXO3L/LF devices, top side only0.200MIPI D-PHY Output Data Speed MIPI D-PHY CLK Frequency (minimum limited by PLL)All MachXO3L/LF devices, top side only450MIPI D-PHY ECLK Frequency (minimum limited by PLL)450450	Description Image: Description Image: Description Max. Min. Max. Min. RX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input - LECLK.Centered ^{8, 9} 0.455 - 0.570 Output Data Valid Before CLK Output MachXO3L/LF devices, top side only 0.455 - 0.570 DDRX4 Serial Output Data Speed MachXO3L/LF devices, top side only - 800 - DDRX4 ECLK Frequency (minimum limited by PLL) MachXO3L/LF devices, top side only - 400 - SCLK Frequency - 0.160 -	Description Device Min. Max. Min. Max. RX4 Outputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input - LECLK.Centered ^{9,9} 0.455 - 0.570 - Output Data Valid Before CLK Output MachXO3L/LF devices, top side only 0.455 - 0.570 - DDRX4 Serial Output Data Speed MachXO3L/LF devices, top side only 0.455 - 0.570 - DDRX4 ECLK Frequency (minimum limited by PLL) MachXO3L/LF devices, top side only - 800 - 630 SCLK Frequency - 0.160 - 916 - 916 Output Data Invalid Before CLK Output MachXO3L/LF devices, top side only - 0.160 - 0.180 DDR71 ECLK Frequency MachXO3L/LF devices, top side only - 756 - 630 DDR71 ECLK Frequency MachXO3L/LF devices, top side only - 756 - 630 DDR71 ECLK Frequency MachXO3L/LF devices, top side only - 108 - 90 Output Data Valid After CLK Output MachXO3L/LF

1. Exact performance may vary with device and design implementation. Commercial timing numbers are shown at 85 °C and 1.14 V. Other operating conditions, including industrial, can be extracted from the Diamond software.

2. General I/O timing numbers based on LVCMOS 2.5, 8 mA, 0pf load, fast slew rate.

3. Generic DDR timing numbers based on LVDS I/O (for input, output, and clock ports).

4. 7:1 LVDS (GDDR71) uses the LVDS I/O standard (for input, output, and clock ports).

5. For Generic DDRX1 mode $t_{SU} = t_{HO} = (t_{DVE} - t_{DVA} - 0.03 \text{ ns})/2$.

6. The t_{SU DEL} and t_{H DEL} values use the SCLK_ZERHOLD default step size. Each step is 105 ps (-6), 113 ps (-5), 120 ps (-4).

7. This number for general purpose usage. Duty cycle tolerance is +/-10%.

8. Duty cycle is $\pm -5\%$ for system usage.

9. Performance is calculated with 0.225 UI.

10. Performance is calculated with 0.20 UI.

11. Performance for Industrial devices are only supported with VCC between 1.16 V to 1.24 V.

12. Performance for Industrial devices and -5 devices are not modeled in the Diamond design tool.

13. The above timing numbers are generated using the Diamond design tool. Exact performance may vary with the device selected.

14. Above 800 Mbps is only supported with WLCSP and csfBGA packages

15. Between 800 Mbps to 900 Mbps:

a. VIDTH exceeds the MIPI D-PHY Input DC Conditions Table 3-4 and can be calculated with the equation tSU or tH = -0.0005*VIDTH + 0.3284

b. Example calculations

i. tSU and tHO = 0.28 with VIDTH = 100 mV

ii. tSU and tHO = 0.25 with VIDTH = 170 mV

iii. tSU and tHO = 0.20 with VIDTH = 270 mV



JTAG Port Timing Specifications

Symbol	Parameter	Min.	Max.	Units
f _{MAX}	TCK clock frequency	—	25	MHz
t _{BTCPH}	TCK [BSCAN] clock pulse width high	20	—	ns
t _{BTCPL}	TCK [BSCAN] clock pulse width low	20	—	ns
t _{BTS}	TCK [BSCAN] setup time	10	—	ns
t _{BTH}	TCK [BSCAN] hold time	8	—	ns
t _{BTCO}	TAP controller falling edge of clock to valid output	—	10	ns
t _{BTCODIS}	TAP controller falling edge of clock to valid disable	—	10	ns
t _{BTCOEN}	TAP controller falling edge of clock to valid enable	—	10	ns
t _{BTCRS}	BSCAN test capture register setup time	8	—	ns
t _{BTCRH}	BSCAN test capture register hold time	20	—	ns
t _{BUTCO}	BSCAN test update register, falling edge of clock to valid output	—	25	ns
t _{BTUODIS}	BSCAN test update register, falling edge of clock to valid disable	—	25	ns
t _{BTUPOEN}	BSCAN test update register, falling edge of clock to valid enable	—	25	ns

Figure 3-8. JTAG Port Timing Waveforms





MachXO3 Family Data Sheet Pinout Information

February 2017

Advance Data Sheet DS1047

Signal Descriptions

Signal Name	I/O	Descriptions						
General Purpose								
		[Edge] indicates the edge of the device on which the pad is located. Valid edge designations are L (Left), B (Bottom), R (Right), T (Top).						
		[Row/Column Number] indicates the PFU row or the column of the device on which the PIO Group exists. When Edge is T (Top) or (Bottom), only need to specify Row Number. When Edge is L (Left) or R (Right), only need to specify Column Number.						
		[A/B/C/D] indicates the PIO within the group to which the pad is connected.						
P[Edge] [Row/Column Number]_[A/B/C/D]	I/O	Some of these user-programmable pins are shared with special function pins. When not used as special function pins, these pins can be programmed as I/Os for user logic.						
		During configuration of the user-programmable I/Os, the user has an option to tri-state the I/Os and enable an internal pull-up, pull-down or buskeeper resistor. This option also applies to unused pins (or those not bonded to a package pin). The default during configuration is for user-programmable I/Os to be tri-stated with an internal pull-down resistor enabled. When the device is erased, I/Os will be tri-stated with an internal pull-down resistor enabled. Some pins, such as PROGRAMN and JTAG pins, default to tri-stated I/Os with pull-up resistors enabled when the device is erased.						
NC	—	No connect.						
GND	—	GND – Ground. Dedicated pins. It is recommended that all GNDs are tied together.						
VCC	_	V_{CC} – The power supply pins for core logic. Dedicated pins. It is recommended that all VCCs are tied to the same supply.						
VCCIOx	_	VCCIO – The power supply pins for I/O Bank x. Dedicated pins. It is recommended that all VCCIOs located in the same bank are tied to the same supply.						
PLL and Clock Functi	ons (Us	ed as user-programmable I/O pins when not used for PLL or clock pins)						
[LOC]_GPLL[T, C]_IN	_	Reference Clock (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.						
[LOC]_GPLL[T, C]_FB	_	Optional Feedback (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.						
PCLK [n]_[2:0]	—	Primary Clock pads. One to three clock pads per side.						
Test and Programmin	g (Dual f	function pins used for test access port and during sysCONFIG™)						
TMS	Ι	Test Mode Select input pin, used to control the 1149.1 state machine.						
ТСК	I	Test Clock input pin, used to clock the 1149.1 state machine.						
TDI	I	Test Data input pin, used to load data into the device using an 1149.1 state machine.						
TDO	0	Output pin – Test Data output pin used to shift data out of the device using 1149.1.						
		Optionally controls behavior of TDI, TDO, TMS, TCK. If the device is configured to use the JTAG pins (TDI, TDO, TMS, TCK) as general purpose I/O, then:						
JTAGENB	I	If JTAGENB is low: TDI, TDO, TMS and TCK can function a general purpose I/O.						
		If JTAGENB is high: TDI, TDO, TMS and TCK function as JTAG pins.						
		For more details, refer to TN1279, MachXO3 Programming and Configuration Usage Guide.						

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	MachXO3L/LF-4300								
	WLCSP81	CSFBGA121	CSFBGA256	CSFBGA324	CABGA256	CABGA324	CABGA400		
General Purpose IO per Bank									
Bank 0	29	24	50	71	50	71	83		
Bank 1	0	26	52	62	52	68	84		
Bank 2	20	26	52	72	52	72	84		
Bank 3	7	7	16	22	16	24	28		
Bank 4	0	7	16	14	16	16	24		
Bank 5	7	10	20	27	20	28	32		
Total General Purpose Single Ended IO	63	100	206	268	206	279	335		
Differential IO per Bank									
Bank 0	15	12	25	36	25	36	42		
Bank 1	0	13	26	30	26	34	42		
Bank 2	10	13	26	36	26	36	42		
Bank 3	3	3	8	10	8	12	14		
Bank 4	0	3	8	6	8	8	12		
Bank 5	3	5	10	13	10	14	16		
Total General Purpose Differential IO	31	49	103	131	103	140	168		
Dual Function IO	25	37	37	37	37	37	37		
Number 7:1 or 8:1 Gearboxes									
Number of 7:1 or 8:1 Output Gearbox Available (Bank 0)	10	7	18	18	18	18	21		
Number of 7:1 or 8:1 Input Gearbox Available (Bank 2)	10	13	18	18	18	18	21		
High-speed Differential Outputs									
Bank 0	10	7	18	18	18	18	21		
VCCIO Pins									
Bank 0	3	1	4	4	4	4	5		
Bank 1	0	1	3	4	4	4	5		
Bank 2	2	1	4	4	4	4	5		
Bank 3	1	1	2	2	1	2	2		
Bank 4	0	1	2	2	2	2	2		
Bank 5	1	1	2	2	1	2	2		
VCC	4	4	8	8	8	10	10		
GND	6	10	24	16	24	16	33		
NC	0	0	0	13	1	0	0		
Reserved for Configuration	1	1	1	1	1	1	1		
Total Count of Bonded Pins	81	121	256	324	256	324	400		



MachXO3L Ultra Low Power Commercial and Industrial Grade Devices, Halogen Free (RoHS) Packaging

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3L-640E-5MG121C	640	1.2 V	5	Halogen-Free csfBGA	121	COM
LCMXO3L-640E-6MG121C	640	1.2 V	6	Halogen-Free csfBGA	121	COM
LCMXO3L-640E-5MG121I	640	1.2 V	5	Halogen-Free csfBGA	121	IND
LCMXO3L-640E-6MG121I	640	1.2 V	6	Halogen-Free csfBGA	121	IND

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3L-1300E-5UWG36CTR	1300	1.2 V	5	Halogen-Free WLCSP	36	COM
LCMXO3L-1300E-5UWG36CTR50	1300	1.2 V	5	Halogen-Free WLCSP	36	COM
LCMXO3L-1300E-5UWG36CTR1K	1300	1.2 V	5	Halogen-Free WLCSP	36	COM
LCMXO3L-1300E-5UWG36ITR	1300	1.2 V	5	Halogen-Free WLCSP	36	IND
LCMXO3L-1300E-5UWG36ITR50	1300	1.2 V	5	Halogen-Free WLCSP	36	IND
LCMXO3L-1300E-5UWG36ITR1K	1300	1.2 V	5	Halogen-Free WLCSP	36	IND
LCMXO3L-1300E-5MG121C	1300	1.2 V	5	Halogen-Free csfBGA	121	COM
LCMXO3L-1300E-6MG121C	1300	1.2 V	6	Halogen-Free csfBGA	121	COM
LCMXO3L-1300E-5MG1211	1300	1.2 V	5	Halogen-Free csfBGA	121	IND
LCMXO3L-1300E-6MG1211	1300	1.2 V	6	Halogen-Free csfBGA	121	IND
LCMXO3L-1300E-5MG256C	1300	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3L-1300E-6MG256C	1300	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3L-1300E-5MG256I	1300	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3L-1300E-6MG256I	1300	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3L-1300C-5BG256C	1300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3L-1300C-6BG256C	1300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3L-1300C-5BG256I	1300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3L-1300C-6BG256I	1300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3L-2100E-5UWG49CTR	2100	1.2 V	5	Halogen-Free WLCSP	49	COM
LCMXO3L-2100E-5UWG49CTR50	2100	1.2 V	5	Halogen-Free WLCSP	49	COM
LCMXO3L-2100E-5UWG49CTR1K	2100	1.2 V	5	Halogen-Free WLCSP	49	COM
LCMXO3L-2100E-5UWG49ITR	2100	1.2 V	5	Halogen-Free WLCSP	49	IND
LCMXO3L-2100E-5UWG49ITR50	2100	1.2 V	5	Halogen-Free WLCSP	49	IND
LCMXO3L-2100E-5UWG49ITR1K	2100	1.2 V	5	Halogen-Free WLCSP	49	IND
LCMXO3L-2100E-5MG121C	2100	1.2 V	5	Halogen-Free csfBGA	121	COM
LCMXO3L-2100E-6MG121C	2100	1.2 V	6	Halogen-Free csfBGA	121	COM
LCMXO3L-2100E-5MG121I	2100	1.2 V	5	Halogen-Free csfBGA	121	IND
LCMXO3L-2100E-6MG1211	2100	1.2 V	6	Halogen-Free csfBGA	121	IND
LCMXO3L-2100E-5MG256C	2100	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3L-2100E-6MG256C	2100	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3L-2100E-5MG256I	2100	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3L-2100E-6MG256I	2100	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3L-2100E-5MG324C	2100	1.2 V	5	Halogen-Free csfBGA	324	COM
LCMXO3L-2100E-6MG324C	2100	1.2 V	6	Halogen-Free csfBGA	324	COM
LCMXO3L-2100E-5MG324I	2100	1.2 V	5	Halogen-Free csfBGA	324	IND



MachXO3 Family Data Sheet Supplemental Information

January 2016

Advance Data Sheet DS1047

For Further Information

A variety of technical notes for the MachXO3 family are available on the Lattice web site.

- TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide
- TN1281, Implementing High-Speed Interfaces with MachXO3 Devices
- TN1280, MachXO3 sysIO Usage Guide
- TN1279, MachXO3 Programming and Configuration Usage Guide
- TN1074, PCB Layout Recommendations for BGA Packages
- TN1087, Minimizing System Interruption During Configuration Using TransFR Technology
- AN8066, Boundary Scan Testability with Lattice sysIO Capability
- MachXO3 Device Pinout Files
- Thermal Management document
- Lattice design tools

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