# E · / Hat lice Semiconductor Corporation - LCMXO3L-9400E-5MG256I Datasheet



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#### Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

#### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	1175
Number of Logic Elements/Cells	9400
Total RAM Bits	442368
Number of I/O	206
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	256-VFBGA
Supplier Device Package	256-CSFBGA (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3l-9400e-5mg256i

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### Table 1-1. MachXO3L/LF Family Selection Guide

Features		MachXO3L-640/ MachXO3LF-640	MachXO3L-1300/ MachXO3LF-1300	MachXO3L-2100/ MachXO3LF-2100	MachXO3L-4300/ MachXO3LF-4300	MachXO3L-6900/ MachXO3LF-6900	MachXO3L-9400/ MachXO3LF-9400
LUTs		640	1300	2100	4300	6900	9400
Distributed R	Distributed RAM (kbits)		10	16	34	54	73
EBR SRAM (	kbits)	64 64 74 92 240		432			
Number of PL	Ls	1	1	1	2	2	2
Hardened	I <sup>2</sup> C	2	2	2	2	2	2
Functions:	SPI	1	1	1	1	1	1
	Timer/Counter	1	1	1	1	1	1
	Oscillator	1	1	1	1	1	1
MIPI D-PHY	Support	Yes	Yes	Yes	Yes	Yes	Yes
Multi Time Pr NVCM	ogrammable	MachXO3L-640	MachXO3L-1300	MachXO3L-2100	MachXO3L-4300	MachXO3L-6900	MachXO3L-9400
Programmabl	le Flash	MachXO3LF-640	MachXO3LF-1300	MachXO3LF-2100	MachXO3LF-4300	MachXO3LF-6900	MachXO3LF-9400
Packages				ю			
36-ball WLCSP <sup>1</sup> (2.5 mm x 2.5 mm, 0.4 mm)			28				
49-ball WLCSP <sup>1</sup> (3.2 mm x 3.2 mm, 0.4 mm)				38			
81-ball WLCSP <sup>1</sup> (3.8 mm x 3.8 mm, 0.4 mm)					63		
121-ball csfBGA <sup>1</sup> (6 mm x 6 mm, 0.5 mm)		100	100	100	100		
256-ball csfBGA <sup>1</sup> (9 mm x 9 mm, 0.5 mm)		2	206	206	206	206	206
324-ball csfB (10 mm x 10				268	268	281	
256-ball caB0 (14 mm x 14			206	206	206	206	206
324-ball caB0 (15 mm x 15				279	279	279	
400-ball caB0 (17 mm x 17					335	335	335
484-ball caB0 (19 mm x 19							384

1. Package is only available for E=1.2 V devices.

2. Package is only available for C=2.5 V/3.3 V devices.

### Introduction

MachXO3<sup>™</sup> device family is an Ultra-Low Density family that supports the most advanced programmable bridging and IO expansion. It has the breakthrough IO density and the lowest cost per IO. The device IO features have the integrated support for latest industry standard IO.

The MachXO3L/LF family of low power, instant-on, non-volatile PLDs has five devices with densities ranging from 640 to 9400 Look-Up Tables (LUTs). In addition to LUT-based, low-cost programmable logic these devices feature Embedded Block RAM (EBR), Distributed RAM, Phase Locked Loops (PLLs), pre-engineered source synchronous I/O support, advanced configuration support including dual-boot capability and hardened versions of commonly used functions such as SPI controller, I<sup>2</sup>C controller and timer/counter. MachXO3LF devices also support User Flash Memory (UFM). These features allow these devices to be used in low cost, high volume consumer and system applications.

The MachXO3L/LF devices are designed on a 65nm non-volatile low power process. The device architecture has several features such as programmable low swing differential I/Os and the ability to turn off I/O banks, on-chip PLLs



### Figure 2-4. Slice Diagram



For Slices 0 and 1, memory control signals are generated from Slice 2 as follows:

- WCK is CLK
   WRE is from LSR
- DI[3:2] for Slice 1 and DI[1:0] for Slice 0 data from Slice 2
- WAD [A:D] is a 4-bit address from slice 2 LUT input

 Table 2-2. Slice Signal Descriptions

Function	Туре	Signal Names	Description
Input	Data signal	A0, B0, C0, D0	Inputs to LUT4
Input	Data signal	A1, B1, C1, D1	Inputs to LUT4
Input	Multi-purpose	M0/M1	Multi-purpose input
Input	Control signal	CE	Clock enable
Input	Control signal	LSR	Local set/reset
Input	Control signal	CLK	System clock
Input	Inter-PFU signal	FCIN	Fast carry in <sup>1</sup>
Output	Data signals	F0, F1	LUT4 output register bypass signals
Output	Data signals	Q0, Q1	Register outputs
Output	Data signals	OFX0	Output of a LUT5 MUX
Output	Data signals	OFX1	Output of a LUT6, LUT7, LUT8 <sup>2</sup> MUX depending on the slice
Output	Inter-PFU signal	FCO	Fast carry out <sup>1</sup>

1. See Figure 2-3 for connection details.

2. Requires two PFUs.



### Modes of Operation

Each slice has up to four potential modes of operation: Logic, Ripple, RAM and ROM.

### Logic Mode

In this mode, the LUTs in each slice are configured as 4-input combinatorial lookup tables. A LUT4 can have 16 possible input combinations. Any four input logic functions can be generated by programming this lookup table. Since there are two LUT4s per slice, a LUT5 can be constructed within one slice. Larger look-up tables such as LUT6, LUT7 and LUT8 can be constructed by concatenating other slices. Note LUT8 requires more than four slices.

### **Ripple Mode**

Ripple mode supports the efficient implementation of small arithmetic functions. In Ripple mode, the following functions can be implemented by each slice:

- Addition 2-bit
- Subtraction 2-bit
- Add/subtract 2-bit using dynamic control
- Up counter 2-bit
- Down counter 2-bit
- Up/down counter with asynchronous clear
- Up/down counter with preload (sync)
- Ripple mode multiplier building block
- Multiplier support
- Comparator functions of A and B inputs
  - A greater-than-or-equal-to B
  - A not-equal-to B
  - A less-than-or-equal-to B

Ripple mode includes an optional configuration that performs arithmetic using fast carry chain methods. In this configuration (also referred to as CCU2 mode) two additional signals, Carry Generate and Carry Propagate, are generated on a per-slice basis to allow fast arithmetic functions to be constructed by concatenating slices.

### **RAM Mode**

In this mode, a 16x4-bit distributed single port RAM (SPR) can be constructed by using each LUT block in Slice 0 and Slice 1 as a 16x1-bit memory. Slice 2 is used to provide memory address and control signals.

MachXO3L/LF devices support distributed memory initialization.

The Lattice design tools support the creation of a variety of different size memories. Where appropriate, the software will construct these using distributed memory primitives that represent the capabilities of the PFU. Table 2-3 shows the number of slices required to implement different distributed RAM primitives. For more information about using RAM in MachXO3L/LF devices, please see TN1290, Memory Usage Guide for MachXO3 Devices.

#### Table 2-3. Number of Slices Required For Implementing Distributed RAM

	SPR 16x4	PDPR 16x4
Number of slices	3	3
Note: SPB = Single Port BA	M. PDPR = Pseudo	Dual Port RAM

ote: SPR = Single Port RAM, PDPR = Pseudo Dual

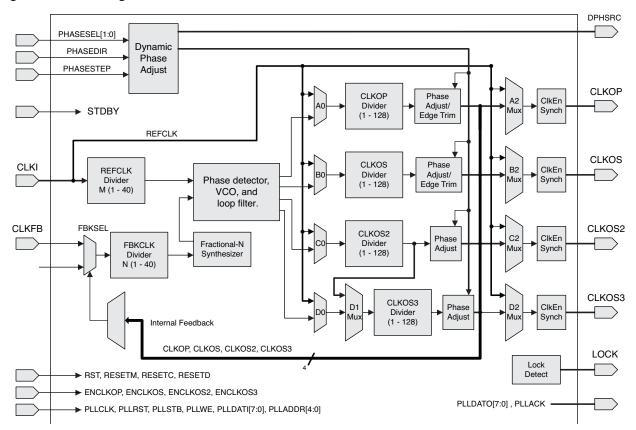


This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the  $t_{I,OCK}$  parameter has been satisfied.

The MachXO3L/LF also has a feature that allows the user to select between two different reference clock sources dynamically. This feature is implemented using the PLLREFCS primitive. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

The MachXO3L/LF PLL contains a WISHBONE port feature that allows the PLL settings, including divider values, to be dynamically changed from the user logic. When using this feature the EFB block must also be instantiated in the design to allow access to the WISHBONE ports. Similar to the dynamic phase adjustment, when PLL settings are updated through the WISHBONE port the PLL may lose lock and not relock until the t<sub>LOCK</sub> parameter has been satisfied. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

For more details on the PLL and the WISHBONE interface, see TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide.



#### Figure 2-7. PLL Diagram

Table 2-4 provides signal descriptions of the PLL block.

Table 2-4. PLL Signal	Descriptions
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Port Name	I/O	Description
CLKI	I	Input clock to PLL
CLKFB	I	Feedback clock
PHASESEL[1:0]	IASESEL[1:0] I Select which output is affected by Dynamic Phase adjustment ports	
PHASEDIR I Dynamic Phase adjustment direction		Dynamic Phase adjustment direction
PHASESTEP	I	Dynamic Phase step – toggle shifts VCO phase adjust by one step.



If an EBR is pre-loaded during configuration, the GSR input must be disabled or the release of the GSR during device wake up must occur before the release of the device I/Os becoming active.

These instructions apply to all EBR RAM, ROM and FIFO implementations. For the EBR FIFO mode, the GSR signal is always enabled and the WE and RE signals act like the clock enable signals in Figure 2-10. The reset timing rules apply to the RPReset input versus the RE input and the RST input versus the WE and RE inputs. Both RST and RPReset are always asynchronous EBR inputs. For more details refer to TN1290, Memory Usage Guide for MachXO3 Devices.

Note that there are no reset restrictions if the EBR synchronous reset is used and the EBR GSR input is disabled.

### Programmable I/O Cells (PIC)

The programmable logic associated with an I/O is called a PIO. The individual PIO are connected to their respective sysIO buffers and pads. On the MachXO3L/LF devices, the PIO cells are assembled into groups of four PIO cells called a Programmable I/O Cell or PIC. The PICs are placed on all four sides of the device.

On all the MachXO3L/LF devices, two adjacent PIOs can be combined to provide a complementary output driver pair.

All PIO pairs can implement differential receivers. Half of the PIO pairs on the top edge of these devices can be configured as true LVDS transmit pairs. The PIO pairs on the bottom edge of these devices have on-chip differential termination and also provide PCI support.



### Figure 2-14. Output Gearbox



More information on the output gearbox is available in TN1281, Implementing High-Speed Interfaces with MachXO3 Devices.



Table 2-11 shows the I/O standards (together with their supply and reference voltages) supported by the MachXO3L/LF devices. For further information on utilizing the sysIO buffer to support a variety of standards please see TN1280, MachXO3 sysIO Usage Guide.

### Table 2-11. Supported Input Standards

		VCCIO (Typ.)					
Input Standard	3.3 V	2.5 V	1.8 V	1.5 V	1.2 V		
Single-Ended Interfaces							
LVTTL	Yes						
LVCMOS33	Yes						
LVCMOS25		Yes					
LVCMOS18			Yes				
LVCMOS15				Yes			
LVCMOS12					Yes		
PCI	Yes						
Differential Interfaces		•					
LVDS	Yes	Yes					
BLVDS, MLVDS, LVPECL, RSDS	Yes	Yes					
MIPI <sup>1</sup>	Yes	Yes					
LVTTLD	Yes						
LVCMOS33D	Yes						
LVCMOS25D		Yes					
LVCMOS18D			Yes				

1. These interfaces can be emulated with external resistors in all devices.



There are some limitations on the use of the hardened user SPI. These are defined in the following technical notes:

- TN1087, Minimizing System Interruption During Configuration Using TransFR Technology (Appendix B)
- TN1293, Using Hardened Control Functions in MachXO3 Devices

### Figure 2-19. SPI Core Block Diagram



Table 2-15 describes the signals interfacing with the SPI cores.

Table 2-15. SPI Core Signal Description

Signal Name	I/O	Master/Slave	Description
spi_csn[0]	0	Master	SPI master chip-select output
spi_csn[17]	0	Master	Additional SPI chip-select outputs (total up to eight slaves)
spi_scsn	I	Slave	SPI slave chip-select input
spi_irq	0	Master/Slave	Interrupt request
spi_clk	I/O	Master/Slave	SPI clock. Output in master mode. Input in slave mode.
spi_miso	I/O	Master/Slave	SPI data. Input in master mode. Output in slave mode.
spi_mosi	I/O	Master/Slave	SPI data. Output in master mode. Input in slave mode.
sn	I	Slave	Configuration Slave Chip Select (active low), dedicated for selecting the Con- figuration Logic.
cfg_stdby	0	Master/Slave	Stand-by signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" feature has been set within the EFB GUI, SPI Tab.
cfg_wake	О	Master/Slave	Wake-up signal – To be connected only to the power module of the MachXO3L/LF device. The signal is enabled only if the "Wakeup Enable" feature has been set within the EFB GUI, SPI Tab.



For more details on these embedded functions, please refer to TN1293, Using Hardened Control Functions in MachXO3 Devices.

### **User Flash Memory (UFM)**

MachXO3LF devices provide a User Flash Memory block, which can be used for a variety of applications including storing a portion of the configuration image, initializing EBRs, to store PROM data or, as a general purpose user Flash memory. The UFM block connects to the device core through the embedded function block WISHBONE interface. Users can also access the UFM block through the JTAG, I2C and SPI interfaces of the device. The UFM block offers the following features:

- Non-volatile storage up to 256 kbits
- 100K write cycles
- Write access is performed page-wise; each page has 128 bits (16 bytes)
- Auto-increment addressing
- WISHBONE interface

For more information on the UFM, please refer to TN1293, Using Hardened Control Functions in MachXO3 Devices.

### **Standby Mode and Power Saving Options**

MachXO3L/LF devices are available in two options, the C and E devices. The C devices have a built-in voltage regulator to allow for 2.5 V V<sub>CC</sub> and 3.3 V V<sub>CC</sub> while the E devices operate at 1.2 V V<sub>CC</sub>.

MachXO3L/LF devices have been designed with features that allow users to meet the static and dynamic power requirements of their applications by controlling various device subsystems such as the bandgap, power-on-reset circuitry, I/O bank controllers, power guard, on-chip oscillator, PLLs, etc. In order to maximize power savings, MachXO3L/LF devices support a low power Stand-by mode.

In the stand-by mode the MachXO3L/LF devices are powered on and configured. Internal logic, I/Os and memories are switched on and remain operational, as the user logic waits for an external input. The device enters this mode when the standby input of the standby controller is toggled or when an appropriate I<sup>2</sup>C or JTAG instruction is issued by an external master. Various subsystems in the device such as the band gap, power-on-reset circuitry etc can be configured such that they are automatically turned "off" or go into a low power consumption state to save power when the device enters this state. Note that the MachXO3L/LF devices are powered on when in standby mode and all power supplies should remain in the Recommended Operating Conditions.



### **DC Electrical Characteristics**

Parameter	Condition	Min.	Тур.	Max.	Units
	Clamp OFF and $V_{CCIO} < V_{IN} < V_{IH}$ (MAX)		_	+175	μA
	Clamp OFF and $V_{IN} = V_{CCIO}$	-10	_	10	μA
Input or I/O Leakage	Clamp OFF and V <sub>CCIO</sub> - 0.97 V < V <sub>IN</sub> < V <sub>CCIO</sub>	-175		—	μΑ
	Clamp OFF and 0 V < $V_{IN}$ < $V_{CCIO}$ - 0.97 V		_	10	μA
	Clamp OFF and V <sub>IN</sub> = GND		_	10	μA
	Clamp ON and 0 V < V <sub>IN</sub> < V <sub>CCIO</sub>		_	10	μA
I/O Active Pull-up Current	0 < V <sub>IN</sub> < 0.7 V <sub>CCIO</sub>	-30		-309	μA
I/O Active Pull-down Current	V <sub>IL</sub> (MAX) < V <sub>IN</sub> < V <sub>CCIO</sub>	30		305	μA
Bus Hold Low sustaining current	$V_{IN} = V_{IL} (MAX)$	30		—	μA
Bus Hold High sustaining current	V <sub>IN</sub> = 0.7V <sub>CCIO</sub>	-30	_	_	μΑ
Bus Hold Low Overdrive current	$0 \leq V_{IN} \leq V_{CCIO}$	_	_	305	μΑ
Bus Hold High Overdrive current	$0 \le V_{IN} \le V_{CCIO}$	_	_	-309	μA
Bus Hold Trip Points		V <sub>IL</sub> (MAX)	_	V <sub>IH</sub> (MIN)	V
I/O Capacitance <sup>2</sup>	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V, 1.5 V, 1.2 V, V_{CC} = Typ., V_{IO} = 0 to V_{IH} (MAX)$	3	5	9	pf
Dedicated Input Capacitance <sup>2</sup>	$V_{CCIO} = 3.3 V, 2.5 V, 1.8 V, 1.5 V, 1.2 V, V_{CC} = Typ., V_{IO} = 0 to V_{IH} (MAX)$	3	5.5	7	pf
	V <sub>CCIO</sub> = 3.3 V, Hysteresis = Large		450		mV
	V <sub>CCIO</sub> = 2.5 V, Hysteresis = Large		250		mV
	V <sub>CCIO</sub> = 1.8 V, Hysteresis = Large		125		mV
Hysteresis for Schmitt	V <sub>CCIO</sub> = 1.5 V, Hysteresis = Large		100		mV
Trigger Inputs⁵	V <sub>CCIO</sub> = 3.3 V, Hysteresis = Small		250		mV
	V <sub>CCIO</sub> = 2.5 V, Hysteresis = Small		150		mV
	V <sub>CCIO</sub> = 1.8 V, Hysteresis = Small		60		mV
	V <sub>CCIO</sub> = 1.5 V, Hysteresis = Small		40		mV
	Input or I/O Leakage         I/O Active Pull-up Current         I/O Active Pull-down         Current         Bus Hold Low sustaining         current         Bus Hold Low sustaining         current         Bus Hold Low Overdrive         current         Bus Hold Low Overdrive         current         Bus Hold High Overdrive         current         Bus Hold Trip Points         I/O Capacitance <sup>2</sup> Dedicated Input         Capacitance <sup>2</sup>	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$

1. Input or I/O leakage current is measured with the pin configured as an input or as an I/O with the output driver tri-stated. It is not measured with the output driver active. Bus maintenance circuits are disabled.

2. T<sub>A</sub> 25 °C, f = 1.0 MHz.

3. Please refer to V<sub>IL</sub> and V<sub>IH</sub> in the sysIO Single-Ended DC Electrical Characteristics table of this document.

 When V<sub>IH</sub> is higher than V<sub>CCIO</sub>, a transient current typically of 30 ns in duration or less with a peak current of 6mA can occur on the high-tolow transition. For true LVDS output pins in MachXO3L/LF devices, V<sub>IH</sub> must be less than or equal to V<sub>CCIO</sub>.

5. With bus keeper circuit turned on. For more details, refer to TN1280, MachXO3 sysIO Usage Guide.



# Programming and Erase Supply Current – C/E Devices<sup>1, 2, 3, 4</sup>

Symbol	Parameter	Device	Typ.⁴	Units
I <sub>CC</sub>	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	22.1	mA
		LCMXO3L/LF-2100C	22.1	mA
		LCMXO3L/LF-2100C 324 Ball Package	26.8	mA
		LCMXO3L/LF-4300C	26.8	mA
		LCMXO3L/LF-4300C 400 Ball Package	33.2	mA
		LCMXO3L/LF-6900C	33.2	mA
		LCMXO3L/LF-9400C	39.6	mA
		LCMXO3L/LF-640E	17.7	mA
		LCMXO3L/LF-1300E	17.7	mA
		LCMXO3L/LF-1300E 256 Ball Package	18.3	mA
		LCMXO3L/LF-2100E	18.3	mA
		LCMXO3L/LF-2100E 324 Ball Package	20.4	mA
		LCMXO3L/LF-4300E	20.4	mA
		LCMXO3L/LF-6900E	23.9	mA
		LCMXO3L/LF-9400E	28.5	mA
I <sub>CCIO</sub>	Bank Power Supply⁵ VCCIO = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, Power Estimation and Management for MachXO3 Devices.

2. Assumes all inputs are held at  $V_{\mbox{\scriptsize CCIO}}$  or GND and all outputs are tri-stated.

3. Typical user pattern.

4. JTAG programming is at 25 MHz.

5.  $T_J = 25$  °C, power supplies at nominal voltage.

6. Per bank.  $V_{CCIO} = 2.5$  V. Does not include pull-up/pull-down.



# sysIO Differential Electrical Characteristics

The LVDS differential output buffers are available on the top side of the MachXO3L/LF PLD family.

### LVDS

Parameter Symbol	Parameter Description	Test Conditions	Min.	Тур.	Max.	Units
V V	Input Voltage	V <sub>CCIO</sub> = 3.3 V	0	_	2.605	V
V <sub>INP</sub> V <sub>INM</sub>		$V_{CCIO} = 2.5 V$	0		2.05	V
V <sub>THD</sub>	Differential Input Threshold		±100			mV
M	Innut Common Made Voltage	$V_{CCIO} = 3.3 V$	0.05	_	2.6	V
V <sub>CM</sub>	Input Common Mode Voltage	$V_{CCIO} = 2.5 V$	0.05		2.0	V
I <sub>IN</sub>	Input current	Power on	_	_	±10	μA
V <sub>OH</sub>	Output high voltage for V <sub>OP</sub> or V <sub>OM</sub>	R <sub>T</sub> = 100 Ohm	_	1.375	—	V
V <sub>OL</sub>	Output low voltage for $V_{OP}$ or $V_{OM}$	R <sub>T</sub> = 100 Ohm	0.90	1.025	—	V
V <sub>OD</sub>	Output voltage differential	(V <sub>OP</sub> - V <sub>OM</sub> ), R <sub>T</sub> = 100 Ohm	250	350	450	mV
ΔV <sub>OD</sub>	Change in V <sub>OD</sub> between high and low		_	_	50	mV
V <sub>OS</sub>	Output voltage offset	$(V_{OP} - V_{OM})/2, R_{T} = 100 \text{ Ohm}$	1.125	1.20	1.395	V
ΔV <sub>OS</sub>	Change in V <sub>OS</sub> between H and L		_	_	50	mV
I <sub>OSD</sub>	Output short circuit current	V <sub>OD</sub> = 0 V driver outputs shorted	_	_	24	mA

### **Over Recommended Operating Conditions**



### Maximum sysIO Buffer Performance

I/O Standard	Max. Speed	Units
MIPI	450	MHz
LVDS25	400	MHz
LVDS25E	150	MHz
BLVDS25	150	MHz
BLVDS25E	150	MHz
MLVDS25	150	MHz
MLVDS25E	150	MHz
LVPECL33	150	MHz
LVPECL33E	150	MHz
LVTTL33	150	MHz
LVTTL33D	150	MHz
LVCMOS33	150	MHz
LVCMOS33D	150	MHz
LVCMOS25	150	MHz
LVCMOS25D	150	MHz
LVCMOS18	150	MHz
LVCMOS18D	150	MHz
LVCMOS15	150	MHz
LVCMOS15D	150	MHz
LVCMOS12	91	MHz
LVCMOS12D	91	MHz



			-6		-5		
Parameter	Description	Device	Min.	Max.	Min.	Max.	Units
Generic DDF	RX1 Inputs with Clock and Data Aligned at	Pin Using PCLK Pin for Cl	ock Inpu	it —			
GDDRX1_RX	K.SCLK.Aligned <sup>8, 9</sup>	-	-				
t <sub>DVA</sub>	Input Data Valid After CLK			0.317	—	0.344	UI
t <sub>DVE</sub>	Input Data Hold After CLK	All MachXO3L/LF devices,	0.742	—	0.702		UI
f <sub>DATA</sub>	DDRX1 Input Data Speed	all sides	—	300	—	250	Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency		—	150	—	125	MHz
Generic DD GDDRX1_R	RX1 Inputs with Clock and Data Centered X.SCLK.Centered <sup>8, 9</sup>	d at Pin Using PCLK Pin fo	or Clock	Input –			
t <sub>SU</sub>	Input Data Setup Before CLK		0.566	—	0.560		ns
t <sub>HO</sub>	Input Data Hold After CLK	All MachXO3L/LF	0.778	—	0.879	—	ns
f <sub>DATA</sub>	DDRX1 Input Data Speed	devices, all sides		300	—		Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency			150	—	125	MHz
	RX2 Inputs with Clock and Data Aligned a K.ECLK.Aligned <sup>8,9</sup>	t Pin Using PCLK Pin for 0	Clock Inp	out –	1	ı	
t <sub>DVA</sub>	Input Data Valid After CLK		—	0.316	—	0.342	UI
t <sub>DVE</sub>	Input Data Hold After CLK	_	0.710		0.675		UI
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed	MachXO3L/LF devices,		664		554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency	_bottom side only		332	_	277	MHz
f <sub>SCLK</sub>	SCLK Frequency	_		166		139	MHz
	RX2 Inputs with Clock and Data Centered	at Pin Using PCLK Pin for	Clock II	nput –			
	K.ECLK.Centered <sup>8,9</sup>	Ū		•			
t <sub>SU</sub>	Input Data Setup Before CLK		0.233	—	0.219		ns
t <sub>HO</sub>	Input Data Hold After CLK		0.287	—	0.287		ns
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed	MachXO3L/LF devices, bottom side only		664	—	554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency	,		332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency			166	—	139	MHz
Generic DDF	R4 Inputs with Clock and Data Aligned at F	in Using PCLK Pin for Cloo	k Input	– GDDR	X4_RX.	ECLK.A	ligned <sup>8</sup>
t <sub>DVA</sub>	Input Data Valid After ECLK			0.307	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.782		0.699		UI
f <sub>DATA</sub>	DDRX4 Serial Input Data Speed	MachXO3L/LF devices, bottom side only	—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDRX4 ECLK Frequency			400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency			100	—	79	MHz
Generic DDF	4 Inputs with Clock and Data Centered at I	Pin Using PCLK Pin for Cloo	k Input	- GDDR	X4_RX.E	CLK.Ce	entered <sup>8</sup>
t <sub>SU</sub>	Input Data Setup Before ECLK		0.233		0.219		ns
t <sub>HO</sub>	Input Data Hold After ECLK		0.287		0.287		ns
f <sub>DATA</sub>	DDRX4 Serial Input Data Speed	MachXO3L/LF devices, bottom side only		800	—	630	Mbps
f <sub>DDRX4</sub>	DDRX4 ECLK Frequency			400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		_	100	—	79	MHz
	outs (GDDR71_RX.ECLK.7:1) <sup>9</sup>	•					
t <sub>DVA</sub>	Input Data Valid After ECLK		_	0.290		0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.739		0.699		UI
f <sub>DATA</sub>	DDR71 Serial Input Data Speed	MachXO3L/LF devices,	—	756	—	630	Mbps
f <sub>DDR71</sub>	DDR71 ECLK Frequency	bottom side only	<u> </u>	378	<b> </b>	315	MHz
f <sub>CLKIN</sub>	7:1 Input Clock Frequency (SCLK) (mini- mum limited by PLL)		_	108	_	90	MHz



### Figure 3-6. Receiver GDDR71\_RX. Waveforms



Figure 3-7. Transmitter GDDR71\_TX. Waveforms





# NVCM/Flash Download Time<sup>1, 2</sup>

Symbol Parameter		Device	Тур.	Units	
t <sub>REFRESH</sub> POR to Device I/C	POR to Device I/O Active	LCMXO3L/LF-640	1.9	ms	
		LCMXO3L/LF-1300	1.9	ms	
		LCMXO3L/LF-1300 256-Ball Package	1.4	ms	
		LCMXO3L/LF-2100	1.4	ms	
		LCMXO3L/LF-2100 324-Ball Package	2.4	ms	
		LCMXO3L/LF-4300	2.4	ms	
		LCMXO3L/LF-4300 400-Ball Package	3.8	ms	
		LCMXO3L/LF-6900	3.8	ms	
		LCMXO3L/LF-9400C	5.2	ms	

1. Assumes sysMEM EBR initialized to an all zero pattern if they are used.

2. The NVCM/Flash download time is measured starting from the maximum voltage of POR trip point.



# MachXO3 Family Data Sheet Pinout Information

February 2017

Advance Data Sheet DS1047

# **Signal Descriptions**

Signal Name	I/O	Descriptions			
General Purpose					
		[Edge] indicates the edge of the device on which the pad is located. Valid edge designations are L (Left), B (Bottom), R (Right), T (Top).			
		[Row/Column Number] indicates the PFU row or the column of the device on which the PIO Group exists. When Edge is T (Top) or (Bottom), only need to specify Row Number. When Edge is L (Left) or R (Right), only need to specify Column Number.			
		[A/B/C/D] indicates the PIO within the group to which the pad is connected.			
P[Edge] [Row/Column Number]_[A/B/C/D]	I/O	Some of these user-programmable pins are shared with special function pins. When not used as special function pins, these pins can be programmed as I/Os for user logic.			
		During configuration of the user-programmable I/Os, the user has an option to tri-state the I/Os and enable an internal pull-up, pull-down or buskeeper resistor. This option also applies to unused pins (or those not bonded to a package pin). The default during configuration is for user-programmable I/Os to be tri-stated with an internal pull-down resistor enabled. When the device is erased, I/Os will be tri-stated with an internal pull-down resistor enabled. Some pins, such as PROGRAMN and JTAG pins, default to tri-stated I/Os with pull-up resistors enabled when the device is erased.			
NC	_	No connect.			
GND	_	GND – Ground. Dedicated pins. It is recommended that all GNDs are tied together.			
VCC	_	$V_{CC}$ – The power supply pins for core logic. Dedicated pins. It is recommended that all VCCs are tied to the same supply.			
VCCIOx		VCCIO – The power supply pins for I/O Bank x. Dedicated pins. It is recommended that all VCCIOs located in the same bank are tied to the same supply.			
PLL and Clock Function	ons (Us	ed as user-programmable I/O pins when not used for PLL or clock pins)			
[LOC]_GPLL[T, C]_IN	_	Reference Clock (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.			
[LOC]_GPLL[T, C]_FB	_	Optional Feedback (PLL) input pads: [LOC] indicates location. Valid designations are L (Left PLL) and R (Right PLL). T = true and C = complement.			
PCLK [n]_[2:0]		Primary Clock pads. One to three clock pads per side.			
Test and Programming	g (Dual i	function pins used for test access port and during sysCONFIG™)			
TMS	Ι	Test Mode Select input pin, used to control the 1149.1 state machine.			
ТСК	Ι	Test Clock input pin, used to clock the 1149.1 state machine.			
TDI	Ι	Test Data input pin, used to load data into the device using an 1149.1 state machine.			
TDO	0	Output pin – Test Data output pin used to shift data out of the device using 1149.1.			
		Optionally controls behavior of TDI, TDO, TMS, TCK. If the device is configured to use the JTAG pins (TDI, TDO, TMS, TCK) as general purpose I/O, then:			
JTAGENB	Ι	If JTAGENB is low: TDI, TDO, TMS and TCK can function a general purpose I/O.			
		If JTAGENB is high: TDI, TDO, TMS and TCK function as JTAG pins.			
		For more details, refer to TN1279, MachXO3 Programming and Configuration Usage Guide.			

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# Signal Descriptions (Cont.)

Signal Name	I/O	Descriptions			
Configuration (Dual function pins used during sysCONFIG)					
PROGRAMN	I	Initiates configuration sequence when asserted low. This pin always has an active pull-up.			
INITN	I/O	Open Drain pin. Indicates the FPGA is ready to be configured. During configuration, a pull-up is enabled.			
DONE	I/O	Open Drain pin. Indicates that the configuration sequence is complete, and the start-up sequence is in progress.			
MCLK/CCLK	I/O	Input Configuration Clock for configuring an FPGA in Slave SPI mode. Output Configuration Clock for configuring an FPGA in SPI and SPIm configuration modes.			
SN	I	Slave SPI active low chip select input.			
CSSPIN	I/O	Master SPI active low chip select output.			
SI/SPISI	I/O	Slave SPI serial data input and master SPI serial data output.			
SO/SPISO	I/O	Slave SPI serial data output and master SPI serial data input.			
SCL	I/O	Slave I <sup>2</sup> C clock input and master I <sup>2</sup> C clock output.			
SDA	I/O	Slave I <sup>2</sup> C data input and master I <sup>2</sup> C data output.			



# MachXO3 Family Data Sheet Ordering Information

May 2016

Advance Data Sheet DS1047

### MachXO3 Part Number Description



### **Ordering Information**

MachXO3L/LF devices have top-side markings as shown in the examples below, on the 256-Ball caBGA package with MachXO3-6900 device in Commercial Temperature in Speed Grade 5. Notice that for the MachXO3LF device, *LMXO3LF* is used instead of *LCMXO3LF* as in the Part Number.



with LMXO3LF

Note: Markings are abbreviated for small packages.

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Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3LF-6900E-5MG256C	6900	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3LF-6900E-6MG256C	6900	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3LF-6900E-5MG256I	6900	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3LF-6900E-6MG256I	6900	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3LF-6900E-5MG324C	6900	1.2 V	5	Halogen-Free csfBGA	324	COM
LCMXO3LF-6900E-6MG324C	6900	1.2 V	6	Halogen-Free csfBGA	324	COM
LCMXO3LF-6900E-5MG324I	6900	1.2 V	5	Halogen-Free csfBGA	324	IND
LCMXO3LF-6900E-6MG324I	6900	1.2 V	6	Halogen-Free csfBGA	324	IND
LCMXO3LF-6900C-5BG256C	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3LF-6900C-6BG256C	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3LF-6900C-5BG256I	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3LF-6900C-6BG256I	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3LF-6900C-5BG324C	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	COM
LCMXO3LF-6900C-6BG324C	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	COM
LCMXO3LF-6900C-5BG324I	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	IND
LCMXO3LF-6900C-6BG324I	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	IND
LCMXO3LF-6900C-5BG400C	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	COM
LCMXO3LF-6900C-6BG400C	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	COM
LCMXO3LF-6900C-5BG400I	6900	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	IND
LCMXO3LF-6900C-6BG400I	6900	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	IND
Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3LF-9400E-5MG256C	9400	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3LF-9400E-6MG256C	9400	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3LF-9400E-5MG256I	9400	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3LF-9400E-6MG256I	9400	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3LF-9400C-5BG256C	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3LF-9400C-6BG256C	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3LF-9400C-5BG256I	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3LF-9400C-6BG256I	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3LF-9400C-5BG400C	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	400	COM
LCMXO3LF-9400C-6BG400C	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	400	COM
LCMXO3LF-9400C-5BG400I	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	400	IND
LCMXO3LF-9400C-6BG400I	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	400	IND
LCMXO3LF-9400C-5BG484C	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	484	COM
LCMXO3LF-9400C-6BG484C	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	484	COM
LCMXO3LF-9400C-5BG484I	9400	2.5 V/3.3 V	5	Halogen-Free caBGA	484	IND
LCMXO3LF-9400C-6BG484I	9400	2.5 V/3.3 V	6	Halogen-Free caBGA	484	IND