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## Understanding **Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

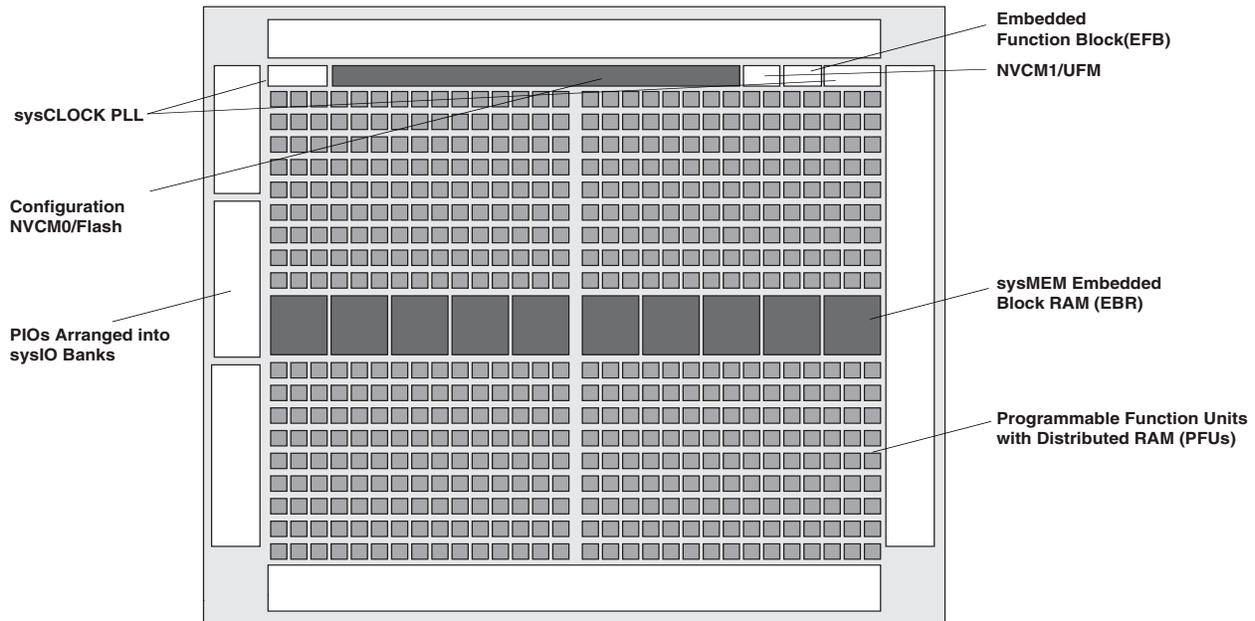
## Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

### Details

Product Status	Active
Number of LABs/CLBs	540
Number of Logic Elements/Cells	4320
Total RAM Bits	94208
Number of I/O	335
Number of Gates	-
Voltage - Supply	2.375V ~ 3.465V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-CABGA (17x17)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3lf-4300c-6bg400i">https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3lf-4300c-6bg400i</a>

**Figure 2-2. Top View of the MachXO3L/LF-4300 Device**



- Notes:
- MachXO3L/LF-1300, MachXO3L/LF-2100, MachXO3L/LF-6900 and MachXO3L/LF-9400 are similar to MachXO3L/LF-4300. MachXO3L/LF-1300 has a lower LUT count, one PLL, and seven EBR blocks. MachXO3L/LF-2100 has a lower LUT count, one PLL, and eight EBR blocks. MachXO3L/LF-6900 has a higher LUT count, two PLLs, and 26 EBR blocks. MachXO3L/LF-9400 has a higher LUT count, two PLLs, and 48 EBR blocks.
  - MachXO3L devices have NVCM, MachXO3LF devices have Flash.

The logic blocks, Programmable Functional Unit (PFU) and sysMEM EBR blocks, are arranged in a two-dimensional grid with rows and columns. Each row has either the logic blocks or the EBR blocks. The PIO cells are located at the periphery of the device, arranged in banks. The PFU contains the building blocks for logic, arithmetic, RAM, ROM, and register functions. The PIOs utilize a flexible I/O buffer referred to as a sysIO buffer that supports operation with a variety of interface standards. The blocks are connected with many vertical and horizontal routing channel resources. The place and route software tool automatically allocates these routing resources.

In the MachXO3L/LF family, the number of sysIO banks varies by device. There are different types of I/O buffers on the different banks. Refer to the details in later sections of this document. The sysMEM EBRs are large, dedicated fast memory blocks. These blocks can be configured as RAM, ROM or FIFO. FIFO support includes dedicated FIFO pointer and flag “hard” control logic to minimize LUT usage.

The MachXO3L/LF registers in PFU and sysI/O can be configured to be SET or RESET. After power up and device is configured, the device enters into user mode with these registers SET/RESET according to the configuration setting, allowing device entering to a known state for predictable system function.

The MachXO3L/LF architecture also provides up to two sysCLOCK Phase Locked Loop (PLL) blocks. These blocks are located at the ends of the on-chip NVCM/Flash block. The PLLs have multiply, divide, and phase shifting capabilities that are used to manage the frequency and phase relationships of the clocks.

MachXO3L/LF devices provide commonly used hardened functions such as SPI controller, I<sup>2</sup>C controller and timer/counter.

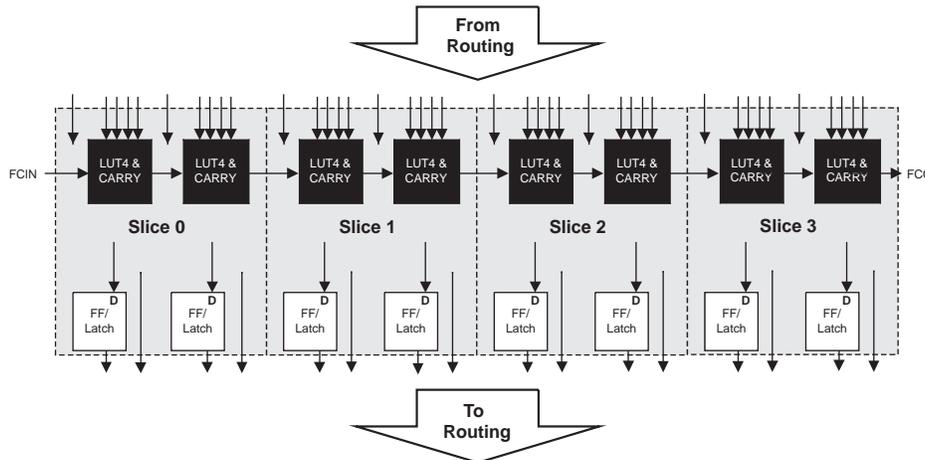
MachXO3LF devices also provide User Flash Memory (UFM). These hardened functions and the UFM interface to the core logic and routing through a WISHBONE interface. The UFM can also be accessed through the SPI, I<sup>2</sup>C and JTAG ports.

Every device in the family has a JTAG port that supports programming and configuration of the device as well as access to the user logic. The MachXO3L/LF devices are available for operation from 3.3 V, 2.5 V and 1.2 V power supplies, providing easy integration into the overall system.

## PFU Blocks

The core of the MachXO3L/LF device consists of PFU blocks, which can be programmed to perform logic, arithmetic, distributed RAM and distributed ROM functions. Each PFU block consists of four interconnected slices numbered 0 to 3 as shown in Figure 2-3. Each slice contains two LUTs and two registers. There are 53 inputs and 25 outputs associated with each PFU block.

**Figure 2-3. PFU Block Diagram**



## Slices

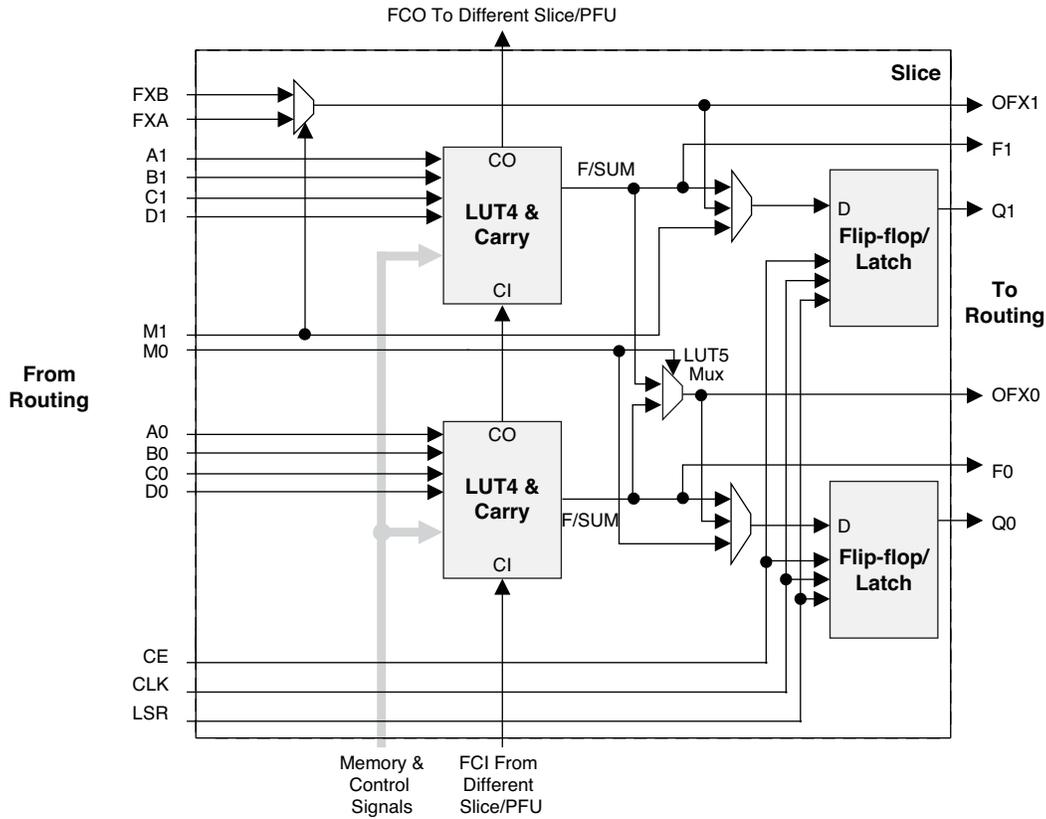
Slices 0-3 contain two LUT4s feeding two registers. Slices 0-2 can be configured as distributed memory. Table 2-1 shows the capability of the slices in PFU blocks along with the operation modes they enable. In addition, each PFU contains logic that allows the LUTs to be combined to perform functions such as LUT5, LUT6, LUT7 and LUT8. The control logic performs set/reset functions (programmable as synchronous/ asynchronous), clock select, chip-select and wider RAM/ROM functions.

**Table 2-1. Resources and Modes Available per Slice**

Slice	PFU Block	
	Resources	Modes
Slice 0	2 LUT4s and 2 Registers	Logic, Ripple, RAM, ROM
Slice 1	2 LUT4s and 2 Registers	Logic, Ripple, RAM, ROM
Slice 2	2 LUT4s and 2 Registers	Logic, Ripple, RAM, ROM
Slice 3	2 LUT4s and 2 Registers	Logic, Ripple, ROM

Figure 2-4 shows an overview of the internal logic of the slice. The registers in the slice can be configured for positive/negative and edge triggered or level sensitive clocks. All slices have 15 inputs from routing and one from the carry-chain (from the adjacent slice or PFU). There are seven outputs: six for routing and one to carry-chain (to the adjacent PFU). Table 2-2 lists the signals associated with Slices 0-3.

**Figure 2-4. Slice Diagram**



For Slices 0 and 1, memory control signals are generated from Slice 2 as follows:

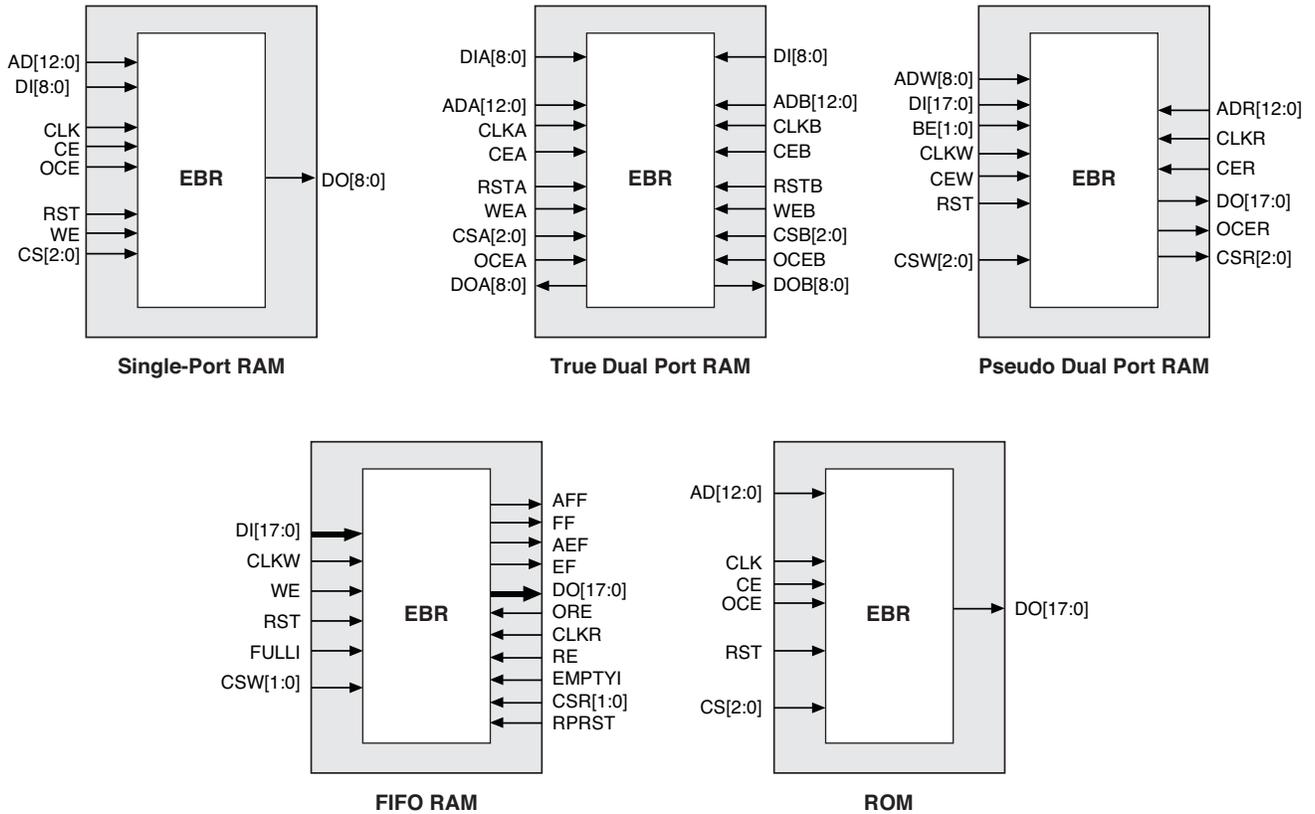
- WCK is CLK
- WRE is from LSR
- DI[3:2] for Slice 1 and DI[1:0] for Slice 0 data from Slice 2
- WAD [A:D] is a 4-bit address from slice 2 LUT input

**Table 2-2. Slice Signal Descriptions**

Function	Type	Signal Names	Description
Input	Data signal	A0, B0, C0, D0	Inputs to LUT4
Input	Data signal	A1, B1, C1, D1	Inputs to LUT4
Input	Multi-purpose	M0/M1	Multi-purpose input
Input	Control signal	CE	Clock enable
Input	Control signal	LSR	Local set/reset
Input	Control signal	CLK	System clock
Input	Inter-PFU signal	FCIN	Fast carry in <sup>1</sup>
Output	Data signals	F0, F1	LUT4 output register bypass signals
Output	Data signals	Q0, Q1	Register outputs
Output	Data signals	OFX0	Output of a LUT5 MUX
Output	Data signals	OFX1	Output of a LUT6, LUT7, LUT8 <sup>2</sup> MUX depending on the slice
Output	Inter-PFU signal	FCO	Fast carry out <sup>1</sup>

1. See Figure 2-3 for connection details.  
2. Requires two PFUs.

**Figure 2-8. sysMEM Memory Primitives**

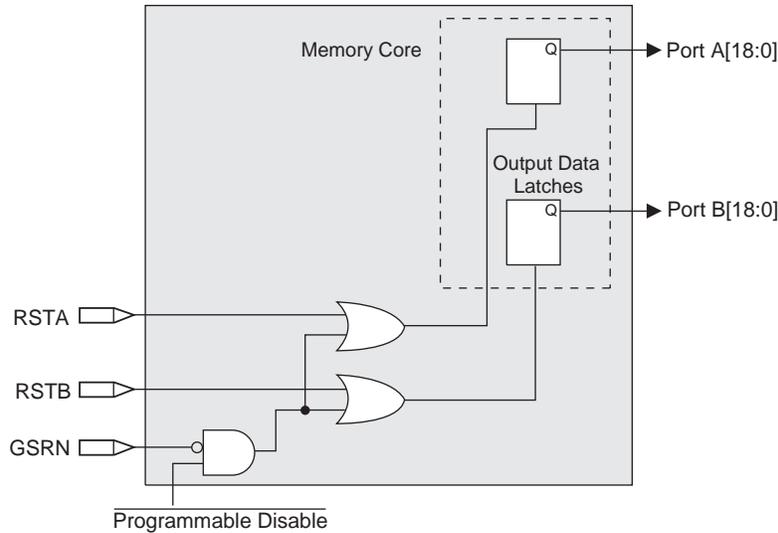


state. The RPRST signal is used to reset the read pointer. The purpose of this reset is to retransmit the data that is in the FIFO. In these applications it is important to keep careful track of when a packet is written into or read from the FIFO.

**Memory Core Reset**

The memory core contains data output latches for ports A and B. These are simple latches that can be reset synchronously or asynchronously. RSTA and RSTB are local signals, which reset the output latches associated with port A and port B respectively. The Global Reset (GSRN) signal resets both ports. The output data latches and associated resets for both ports are as shown in Figure 2-9.

**Figure 2-9. Memory Core Reset**

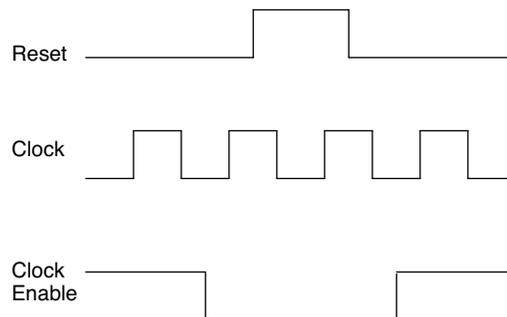


For further information on the sysMEM EBR block, please refer to TN1290, [Memory Usage Guide for MachXO3 Devices](#).

**EBR Asynchronous Reset**

EBR asynchronous reset or GSR (if used) can only be applied if all clock enables are low for a clock cycle before the reset is applied and released a clock cycle after the reset is released, as shown in Figure 2-10. The GSR input to the EBR is always asynchronous.

**Figure 2-10. EBR Asynchronous Reset (Including GSR) Timing Diagram**



If all clock enables remain enabled, the EBR asynchronous reset or GSR may only be applied and released after the EBR read and write clock inputs are in a steady state condition for a minimum of  $1/f_{MAX}$  (EBR clock). The reset release must adhere to the EBR synchronous reset setup time before the next active read or write clock edge.

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If an EBR is pre-loaded during configuration, the GSR input must be disabled or the release of the GSR during device wake up must occur before the release of the device I/Os becoming active.

These instructions apply to all EBR RAM, ROM and FIFO implementations. For the EBR FIFO mode, the GSR signal is always enabled and the WE and RE signals act like the clock enable signals in Figure 2-10. The reset timing rules apply to the RPRreset input versus the RE input and the RST input versus the WE and RE inputs. Both RST and RPRreset are always asynchronous EBR inputs. For more details refer to TN1290, [Memory Usage Guide for MachXO3 Devices](#).

Note that there are no reset restrictions if the EBR synchronous reset is used and the EBR GSR input is disabled.

## **Programmable I/O Cells (PIC)**

The programmable logic associated with an I/O is called a PIO. The individual PIO are connected to their respective sysIO buffers and pads. On the MachXO3L/LF devices, the PIO cells are assembled into groups of four PIO cells called a Programmable I/O Cell or PIC. The PICs are placed on all four sides of the device.

On all the MachXO3L/LF devices, two adjacent PIOs can be combined to provide a complementary output driver pair.

All PIO pairs can implement differential receivers. Half of the PIO pairs on the top edge of these devices can be configured as true LVDS transmit pairs. The PIO pairs on the bottom edge of these devices have on-chip differential termination and also provide PCI support.

## PIO

The PIO contains three blocks: an input register block, output register block and tri-state register block. These blocks contain registers for operating in a variety of modes along with the necessary clock and selection logic.

**Table 2-8. PIO Signal List**

Pin Name	I/O Type	Description
CE	Input	Clock Enable
D	Input	Pin input from sysIO buffer.
INDD	Output	Register bypassed input.
INCK	Output	Clock input
Q0	Output	DDR positive edge input
Q1	Output	Registered input/DDR negative edge input
D0	Input	Output signal from the core (SDR and DDR)
D1	Input	Output signal from the core (DDR)
TD	Input	Tri-state signal from the core
Q	Output	Data output signals to sysIO Buffer
TQ	Output	Tri-state output signals to sysIO Buffer
SCLK	Input	System clock for input and output/tri-state blocks.
RST	Input	Local set reset signal

### Input Register Block

The input register blocks for the PIOs on all edges contain delay elements and registers that can be used to condition high-speed interface signals before they are passed to the device core.

#### Left, Top, Bottom Edges

Input signals are fed from the sysIO buffer to the input register block (as signal D). If desired, the input signal can bypass the register and delay elements and be used directly as a combinatorial signal (INDD), and a clock (INCK). If an input delay is desired, users can select a fixed delay. I/Os on the bottom edge also have a dynamic delay, DEL[4:0]. The delay, if selected, reduces input register hold time requirements when using a global clock. The input block allows two modes of operation. In single data rate (SDR) the data is registered with the system clock (SCLK) by one of the registers in the single data rate sync register block. In Generic DDR mode, two registers are used to sample the data on the positive and negative edges of the system clock (SCLK) signal, creating two data streams.

## Output Gearbox

Each PIC on the top edge has a built-in 8:1 output gearbox. Each of these output gearboxes may be programmed as a 7:1 serializer or as one ODDR4 (8:1) gearbox or as two ODDR2 (4:1) gearboxes. Table 2-10 shows the gearbox signals.

**Table 2-10. Output Gearbox Signal List**

Name	I/O Type	Description
Q	Output	High-speed data output
D[7:0]	Input	Low-speed data from device core
Video TX(7:1): D[6:0]		
GDDR4(8:1): D[7:0]		
GDDR2(4:1)(IOL-A): D[3:0]		
GDDR2(4:1)(IOL-C): D[7:4]		
SCLK	Input	Slow-speed system clock
ECLK [1:0]	Input	High-speed edge clock
RST	Input	Reset

The gearboxes have three stage pipeline registers. The first stage registers sample the low-speed input data on the low-speed system clock. The second stage registers transfer data from the low-speed clock registers to the high-speed clock registers. The third stage pipeline registers controlled by high-speed edge clock shift and mux the high-speed data out to the sysIO buffer. Figure 2-14 shows the output gearbox block diagram.

**Table 2-12. Supported Output Standards**

Output Standard	V <sub>CCIO</sub> (Typ.)
<b>Single-Ended Interfaces</b>	
LVTTTL	3.3
LVC MOS33	3.3
LVC MOS25	2.5
LVC MOS18	1.8
LVC MOS15	1.5
LVC MOS12	1.2
LVC MOS33, Open Drain	—
LVC MOS25, Open Drain	—
LVC MOS18, Open Drain	—
LVC MOS15, Open Drain	—
LVC MOS12, Open Drain	—
PCI33	3.3
<b>Differential Interfaces</b>	
LVDS <sup>1</sup>	2.5, 3.3
BLVDS, MLVDS, RSDS <sup>1</sup>	2.5
LVPECL <sup>1</sup>	3.3
MIPI <sup>1</sup>	2.5
LVTTLD	3.3
LVC MOS33D	3.3
LVC MOS25D	2.5
LVC MOS18D	1.8

1. These interfaces can be emulated with external resistors in all devices.

### sysIO Buffer Banks

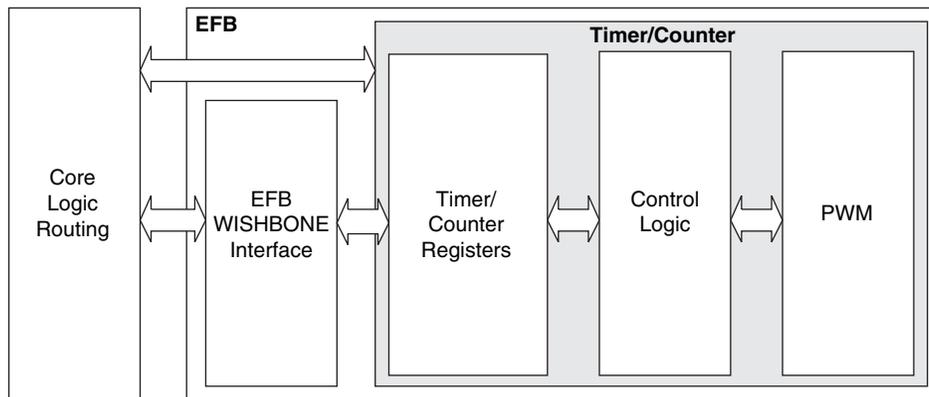
The numbers of banks vary between the devices of this family. MachXO3L/LF-1300 in the 256 Ball packages and the MachXO3L/LF-2100 and higher density devices have six I/O banks (one bank on the top, right and bottom side and three banks on the left side). The MachXO3L/LF-1300 and lower density devices have four banks (one bank per side). Figures 2-15 and 2-16 show the sysIO banks and their associated supplies for all devices.

## Hardened Timer/Counter

MachXO3L/LF devices provide a hard Timer/Counter IP core. This Timer/Counter is a general purpose, bi-directional, 16-bit timer/counter module with independent output compare units and PWM support. The Timer/Counter supports the following functions:

- Supports the following modes of operation:
  - Watchdog timer
  - Clear timer on compare match
  - Fast PWM
  - Phase and Frequency Correct PWM
- Programmable clock input source
- Programmable input clock prescaler
- One static interrupt output to routing
- One wake-up interrupt to on-chip standby mode controller.
- Three independent interrupt sources: overflow, output compare match, and input capture
- Auto reload
- Time-stamping support on the input capture unit
- Waveform generation on the output
- Glitch-free PWM waveform generation with variable PWM period
- Internal WISHBONE bus access to the control and status registers
- Stand-alone mode with preloaded control registers and direct reset input

**Figure 2-20. Timer/Counter Block Diagram**



**Table 2-16. Timer/Counter Signal Description**

Port	I/O	Description
tc_clk	I	Timer/Counter input clock signal
tc_rstn	I	Register tc_rstn_ena is preloaded by configuration to always keep this pin enabled
tc_ic	I	Input capture trigger event, applicable for non-pwm modes with WISHBONE interface. If enabled, a rising edge of this signal will be detected and synchronized to capture tc_cnt value into tc_icr for time-stamping.
tc_int	O	Without WISHBONE – Can be used as overflow flag With WISHBONE – Controlled by three IRQ registers
tc_oc	O	Timer counter output signal

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## Configuration and Testing

This section describes the configuration and testing features of the MachXO3L/LF family.

### IEEE 1149.1-Compliant Boundary Scan Testability

All MachXO3L/LF devices have boundary scan cells that are accessed through an IEEE 1149.1 compliant test access port (TAP). This allows functional testing of the circuit board, on which the device is mounted, through a serial scan path that can access all critical logic nodes. Internal registers are linked internally, allowing test data to be shifted in and loaded directly onto test nodes, or test data to be captured and shifted out for verification. The test access port consists of dedicated I/Os: TDI, TDO, TCK and TMS. The test access port shares its power supply with V<sub>CCIO</sub> Bank 0 and can operate with LVCMOS3.3, 2.5, 1.8, 1.5, and 1.2 standards.

For more details on boundary scan test, see AN8066, [Boundary Scan Testability with Lattice sysIO Capability](#) and TN1087, [Minimizing System Interruption During Configuration Using TransFR Technology](#).

### Device Configuration

All MachXO3L/LF devices contain two ports that can be used for device configuration. The Test Access Port (TAP), which supports bit-wide configuration and the sysCONFIG port which supports serial configuration through I<sup>2</sup>C or SPI. The TAP supports both the IEEE Standard 1149.1 Boundary Scan specification and the IEEE Standard 1532 In-System Configuration specification. There are various ways to configure a MachXO3L/LF device:

1. Internal NVCM/Flash Download
2. JTAG
3. Standard Serial Peripheral Interface (Master SPI mode) – interface to boot PROM memory
4. System microprocessor to drive a serial slave SPI port (SSPI mode)
5. Standard I<sup>2</sup>C Interface to system microprocessor

Upon power-up, the configuration SRAM is ready to be configured using the selected sysCONFIG port. Once a configuration port is selected, it will remain active throughout that configuration cycle. The IEEE 1149.1 port can be activated any time after power-up by sending the appropriate command through the TAP port. Optionally the device can run a CRC check upon entering the user mode. This will ensure that the device was configured correctly.

The sysCONFIG port has 10 dual-function pins which can be used as general purpose I/Os if they are not required for configuration. See TN1279, [MachXO3 Programming and Configuration Usage Guide](#) for more information about using the dual-use pins as general purpose I/Os.

Lattice design software uses proprietary compression technology to compress bit-streams for use in MachXO3L/LF devices. Use of this technology allows Lattice to provide a lower cost solution. In the unlikely event that this technology is unable to compress bitstreams to fit into the amount of on-chip NVCM/Flash, there are a variety of techniques that can be utilized to allow the bitstream to fit in the on-chip NVCM/Flash. For more details, refer to TN1279, [MachXO3 Programming and Configuration Usage Guide](#).

The Test Access Port (TAP) has five dual purpose pins (TDI, TDO, TMS, TCK and JTAGENB). These pins are dual function pins - TDI, TDO, TMS and TCK can be used as general purpose I/O if desired. For more details, refer to TN1279, [MachXO3 Programming and Configuration Usage Guide](#).

### TransFR (Transparent Field Reconfiguration)

TransFR is a unique Lattice technology that allows users to update their logic in the field without interrupting system operation using a simple push-button solution. For more details refer to TN1087, [Minimizing System Interruption During Configuration Using TransFR Technology](#) for details.

**Programming and Erase Supply Current – C/E Devices<sup>1, 2, 3, 4</sup>**

Symbol	Parameter	Device	Typ. <sup>4</sup>	Units
I <sub>CC</sub>	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	22.1	mA
		LCMXO3L/LF-2100C	22.1	mA
		LCMXO3L/LF-2100C 324 Ball Package	26.8	mA
		LCMXO3L/LF-4300C	26.8	mA
		LCMXO3L/LF-4300C 400 Ball Package	33.2	mA
		LCMXO3L/LF-6900C	33.2	mA
		LCMXO3L/LF-9400C	39.6	mA
		LCMXO3L/LF-640E	17.7	mA
		LCMXO3L/LF-1300E	17.7	mA
		LCMXO3L/LF-1300E 256 Ball Package	18.3	mA
		LCMXO3L/LF-2100E	18.3	mA
		LCMXO3L/LF-2100E 324 Ball Package	20.4	mA
		LCMXO3L/LF-4300E	20.4	mA
		LCMXO3L/LF-6900E	23.9	mA
		LCMXO3L/LF-9400E	28.5	mA
I <sub>CCIO</sub>	Bank Power Supply <sup>5</sup> V <sub>CCIO</sub> = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, [Power Estimation and Management for MachXO3 Devices](#).
2. Assumes all inputs are held at V<sub>CCIO</sub> or GND and all outputs are tri-stated.
3. Typical user pattern.
4. JTAG programming is at 25 MHz.
5. T<sub>J</sub> = 25 °C, power supplies at nominal voltage.
6. Per bank. V<sub>CCIO</sub> = 2.5 V. Does not include pull-up/pull-down.

**sysIO Single-Ended DC Electrical Characteristics<sup>1, 2</sup>**

Input/Output Standard	V <sub>IL</sub>		V <sub>IH</sub>		V <sub>OL</sub> Max. (V)	V <sub>OH</sub> Min. (V)	I <sub>OL</sub> Max. <sup>4</sup> (mA)	I <sub>OH</sub> Max. <sup>4</sup> (mA)
	Min. (V) <sup>3</sup>	Max. (V)	Min. (V)	Max. (V)				
LVCMOS 3.3 LVTTL	-0.3	0.8	2.0	3.6	0.4	V <sub>CCIO</sub> - 0.4	4	-4
							8	-8
							12	-12
							16	-16
					0.2	V <sub>CCIO</sub> - 0.2	0.1	-0.1
LVCMOS 2.5	-0.3	0.7	1.7	3.6	0.4	V <sub>CCIO</sub> - 0.4	4	-4
							8	-8
							12	-12
							16	-16
					0.2	V <sub>CCIO</sub> - 0.2	0.1	-0.1
LVCMOS 1.8	-0.3	0.35V <sub>CCIO</sub>	0.65V <sub>CCIO</sub>	3.6	0.4	V <sub>CCIO</sub> - 0.4	4	-4
							8	-8
							12	-12
							16	-16
					0.2	V <sub>CCIO</sub> - 0.2	0.1	-0.1
LVCMOS 1.5	-0.3	0.35V <sub>CCIO</sub>	0.65V <sub>CCIO</sub>	3.6	0.4	V <sub>CCIO</sub> - 0.4	4	-4
							8	-8
					0.2	V <sub>CCIO</sub> - 0.2	0.1	-0.1
LVCMOS 1.2	-0.3	0.35V <sub>CCIO</sub>	0.65V <sub>CCIO</sub>	3.6	0.4	V <sub>CCIO</sub> - 0.4	4	-2
							8	-6
					0.2	V <sub>CCIO</sub> - 0.2	0.1	-0.1
LVCMOS25R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS18R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS18R25	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS15R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS15R25	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS12R33	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	24, 16, 12, 8, 4	NA Open Drain
LVCMOS12R25	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	16, 12, 8, 4	NA Open Drain
LVCMOS10R33	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	24, 16, 12, 8, 4	NA Open Drain
LVCMOS10R25	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	16, 12, 8, 4	NA Open Drain

1. MachXO3L/LF devices allow LVCMOS inputs to be placed in I/O banks where V<sub>CCIO</sub> is different from what is specified in the applicable JEDEC specification. This is referred to as a ratioed input buffer. In a majority of cases this operation follows or exceeds the applicable JEDEC specification. The cases where MachXO3L/LF devices do not meet the relevant JEDEC specification are documented in the table below.
2. MachXO3L/LF devices allow for LVCMOS referenced I/Os which follow applicable JEDEC specifications. For more details about mixed mode operation please refer to please refer to TN1280, [MachXO3 sysIO Usage Guide](#).
3. The dual function I<sup>2</sup>C pins SCL and SDA are limited to a V<sub>IL</sub> min of -0.25 V or to -0.3 V with a duration of <10 ns.
4. For electromigration, the average DC current sourced or sinked by I/O pads between two consecutive V<sub>CCIO</sub> or GND pad connections, or between the last V<sub>CCIO</sub> or GND in an I/O bank and the end of an I/O bank, as shown in the Logic Signal Connections table (also shown as I/O grouping) shall not exceed a maximum of n \* 8 mA. "n" is the number of I/O pads between the two consecutive bank V<sub>CCIO</sub> or GND connections or between the last V<sub>CCIO</sub> and GND in a bank and the end of a bank. IO Grouping can be found in the Data Sheet Pin Tables, which can also be generated from the Lattice Diamond software.

### BLVDS

The MachXO3L/LF family supports the BLVDS standard through emulation. The output is emulated using complementary LVCMOS outputs in conjunction with resistors across the driver outputs. The input standard is supported by the LVDS differential input buffer. BLVDS is intended for use when multi-drop and bi-directional multi-point differential signaling is required. The scheme shown in Figure 3-2 is one possible solution for bi-directional multi-point differential signals.

Figure 3-2. BLVDS Multi-point Output Example

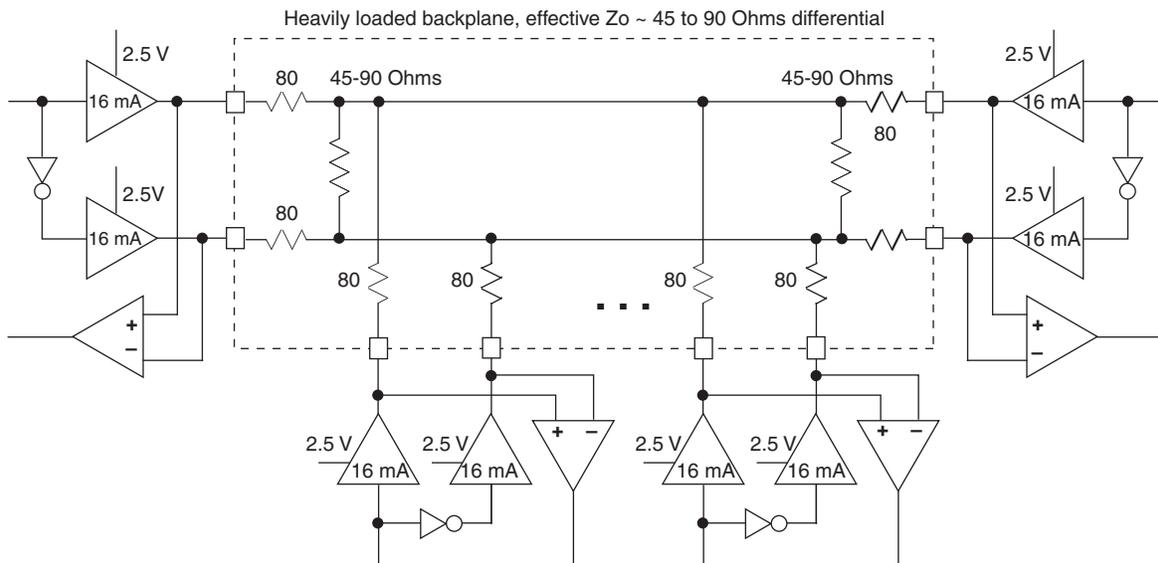


Table 3-2. BLVDS DC Conditions<sup>1</sup>

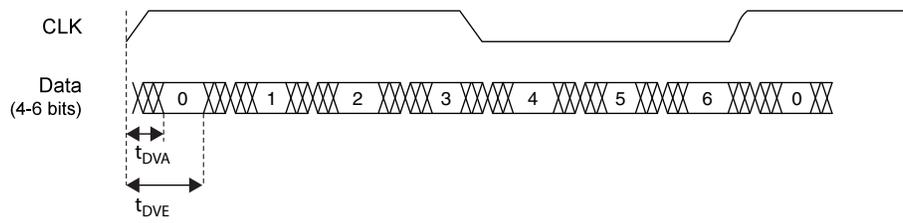
Over Recommended Operating Conditions

Symbol	Description	Nominal		Units
		Zo = 45	Zo = 90	
Z <sub>OUT</sub>	Output impedance	20	20	Ohms
R <sub>S</sub>	Driver series resistance	80	80	Ohms
R <sub>TLEFT</sub>	Left end termination	45	90	Ohms
R <sub>TRIGHT</sub>	Right end termination	45	90	Ohms
V <sub>OH</sub>	Output high voltage	1.376	1.480	V
V <sub>OL</sub>	Output low voltage	1.124	1.020	V
V <sub>OD</sub>	Output differential voltage	0.253	0.459	V
V <sub>CM</sub>	Output common mode voltage	1.250	1.250	V
I <sub>DC</sub>	DC output current	11.236	10.204	mA

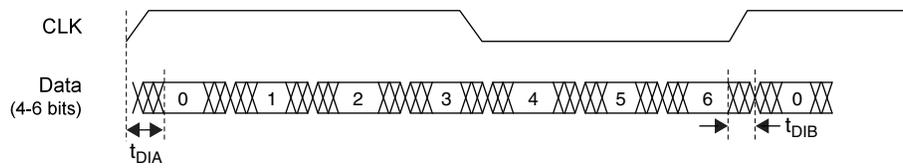
1. For input buffer, see LVDS table.

Parameter	Description	Device	-6		-5		Units
			Min.	Max.	Min.	Max.	
<b>Generic DDRX1 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR1_RX.SCLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	All MachXO3L/LF devices, all sides	—	0.317	—	0.344	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.742	—	0.702	—	UI
f <sub>DATA</sub>	DDRX1 Input Data Speed		—	300	—	250	Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX1 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR1_RX.SCLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	All MachXO3L/LF devices, all sides	0.566	—	0.560	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.778	—	0.879	—	ns
f <sub>DATA</sub>	DDRX1 Input Data Speed		—	300	—	—	Mbps
f <sub>DDRX1</sub>	DDRX1 SCLK Frequency		—	150	—	125	MHz
<b>Generic DDRX2 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR2_RX.ECLK.Aligned<sup>8,9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After CLK	MachXO3L/LF devices, bottom side only	—	0.316	—	0.342	UI
t <sub>DVE</sub>	Input Data Hold After CLK		0.710	—	0.675	—	UI
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDRX2 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR2_RX.ECLK.Centered<sup>8,9</sup></b>							
t <sub>SU</sub>	Input Data Setup Before CLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After CLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDRX2 Serial Input Data Speed		—	664	—	554	Mbps
f <sub>DDRX2</sub>	DDRX2 ECLK Frequency		—	332	—	277	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	166	—	139	MHz
<b>Generic DDR4 Inputs with Clock and Data Aligned at Pin Using PCLK Pin for Clock Input – GDDR4_RX.ECLK.Aligned<sup>8</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.307	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.782	—	0.699	—	UI
f <sub>DATA</sub>	DDRX4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDRX4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>Generic DDR4 Inputs with Clock and Data Centered at Pin Using PCLK Pin for Clock Input – GDDR4_RX.ECLK.Centered<sup>8</sup></b>							
t <sub>SU</sub>	Input Data Setup Before ECLK	MachXO3L/LF devices, bottom side only	0.233	—	0.219	—	ns
t <sub>HO</sub>	Input Data Hold After ECLK		0.287	—	0.287	—	ns
f <sub>DATA</sub>	DDRX4 Serial Input Data Speed		—	800	—	630	Mbps
f <sub>DDRX4</sub>	DDRX4 ECLK Frequency		—	400	—	315	MHz
f <sub>SCLK</sub>	SCLK Frequency		—	100	—	79	MHz
<b>7:1 LVDS Inputs (GDDR71_RX.ECLK.7:1)<sup>9</sup></b>							
t <sub>DVA</sub>	Input Data Valid After ECLK	MachXO3L/LF devices, bottom side only	—	0.290	—	0.320	UI
t <sub>DVE</sub>	Input Data Hold After ECLK		0.739	—	0.699	—	UI
f <sub>DATA</sub>	DDR71 Serial Input Data Speed		—	756	—	630	Mbps
f <sub>DDR71</sub>	DDR71 ECLK Frequency		—	378	—	315	MHz
f <sub>CLKIN</sub>	7:1 Input Clock Frequency (SCLK) (minimum limited by PLL)		—	108	—	90	MHz

**Figure 3-6. Receiver GDDR71\_RX. Waveforms**



**Figure 3-7. Transmitter GDDR71\_TX. Waveforms**



## sysCLOCK PLL Timing

### Over Recommended Operating Conditions

Parameter	Descriptions	Conditions	Min.	Max.	Units
$f_{IN}$	Input Clock Frequency (CLKI, CLKFB)		7	400	MHz
$f_{OUT}$	Output Clock Frequency (CLKOP, CLKOS, CLKOS2)		1.5625	400	MHz
$f_{OUT2}$	Output Frequency (CLKOS3 cascaded from CLKOS2)		0.0122	400	MHz
$f_{VCO}$	PLL VCO Frequency		200	800	MHz
$f_{PFD}$	Phase Detector Input Frequency		7	400	MHz
<b>AC Characteristics</b>					
$t_{DT}$	Output Clock Duty Cycle	Without duty trim selected <sup>3</sup>	45	55	%
$t_{DT\_TRIM}$ <sup>7</sup>	Edge Duty Trim Accuracy		-75	75	%
$t_{PH}$ <sup>4</sup>	Output Phase Accuracy		-6	6	%
$t_{OPJIT}$ <sup>1,8</sup>	Output Clock Period Jitter	$f_{OUT} > 100$ MHz	—	150	ps p-p
		$f_{OUT} < 100$ MHz	—	0.007	UIPP
	Output Clock Cycle-to-cycle Jitter	$f_{OUT} > 100$ MHz	—	180	ps p-p
		$f_{OUT} < 100$ MHz	—	0.009	UIPP
	Output Clock Phase Jitter	$f_{PFD} > 100$ MHz	—	160	ps p-p
		$f_{PFD} < 100$ MHz	—	0.011	UIPP
	Output Clock Period Jitter (Fractional-N)	$f_{OUT} > 100$ MHz	—	230	ps p-p
		$f_{OUT} < 100$ MHz	—	0.12	UIPP
Output Clock Cycle-to-cycle Jitter (Fractional-N)	$f_{OUT} > 100$ MHz	—	230	ps p-p	
	$f_{OUT} < 100$ MHz	—	0.12	UIPP	
$t_{SPO}$	Static Phase Offset	Divider ratio = integer	-120	120	ps
$t_W$	Output Clock Pulse Width	At 90% or 10% <sup>3</sup>	0.9	—	ns
$t_{LOCK}$ <sup>2,5</sup>	PLL Lock-in Time		—	15	ms
$t_{UNLOCK}$	PLL Unlock Time		—	50	ns
$t_{IPJIT}$ <sup>6</sup>	Input Clock Period Jitter	$f_{PFD} \geq 20$ MHz	—	1,000	ps p-p
		$f_{PFD} < 20$ MHz	—	0.02	UIPP
$t_{HI}$	Input Clock High Time	90% to 90%	0.5	—	ns
$t_{LO}$	Input Clock Low Time	10% to 10%	0.5	—	ns
$t_{STABLE}$ <sup>5</sup>	STANDBY High to PLL Stable		—	15	ms
$t_{RST}$	RST/RESETM Pulse Width		1	—	ns
$t_{RSTREC}$	RST Recovery Time		1	—	ns
$t_{RST\_DIV}$	RESETC/D Pulse Width		10	—	ns
$t_{RSTREC\_DIV}$	RESETC/D Recovery Time		1	—	ns
$t_{ROTATE\_SETUP}$	PHASESTEP Setup Time		10	—	ns
$t_{ROTATE\_WD}$	PHASESTEP Pulse Width		4	—	VCO Cycles

1. Period jitter sample is taken over 10,000 samples of the primary PLL output with a clean reference clock. Cycle-to-cycle jitter is taken over 1000 cycles. Phase jitter is taken over 2000 cycles. All values per JESD65B.
2. Output clock is valid after  $t_{LOCK}$  for PLL reset and dynamic delay adjustment.
3. Using LVDS output buffers.
4. CLKOS as compared to CLKOP output for one phase step at the maximum VCO frequency. See TN1282, [MachXO3 sysCLOCK PLL Design and Usage Guide](#) for more details.
5. At minimum  $f_{PFD}$ . As the  $f_{PFD}$  increases the time will decrease to approximately 60% the value listed.
6. Maximum allowed jitter on an input clock. PLL unlock may occur if the input jitter exceeds this specification. Jitter on the input clock may be transferred to the output clocks, resulting in jitter measurements outside the output specifications listed in this table.
7. Edge Duty Trim Accuracy is a percentage of the setting value. Settings available are 70 ps, 140 ps, and 280 ps in addition to the default value of none.
8. Jitter values measured with the internal oscillator operating. The jitter values will increase with loading of the PLD fabric and in the presence of SSO noise.

**sysCONFIG Port Timing Specifications**

Symbol	Parameter		Min.	Max.	Units
<b>All Configuration Modes</b>					
t <sub>PRGM</sub>	PROGRAMN low pulse accept		55	—	ns
t <sub>PRGMJ</sub>	PROGRAMN low pulse rejection		—	25	ns
t <sub>INITL</sub>	INITN low time	LCMXO3L/LF-640/ LCMXO3L/LF-1300	—	55	us
		LCMXO3L/LF-1300 256-Ball Package/ LCMXO3L/LF-2100	—	70	us
		LCMXO3L/LF-2100 324-Ball Package/ LCMXO3-4300	—	105	us
		LCMXO3L/LF-4300 400-Ball Package/ LCMXO3-6900	—	130	us
		LCMXO3L/LF-9400C	—	175	us
t <sub>DPPINIT</sub>	PROGRAMN low to INITN low		—	150	ns
t <sub>DPPDONE</sub>	PROGRAMN low to DONE low		—	150	ns
t <sub>IODISS</sub>	PROGRAMN low to I/O disable		—	120	ns
<b>Slave SPI</b>					
f <sub>MAX</sub>	CCLK clock frequency		—	66	MHz
t <sub>CCLKH</sub>	CCLK clock pulse width high		7.5	—	ns
t <sub>CCLKL</sub>	CCLK clock pulse width low		7.5	—	ns
t <sub>STSU</sub>	CCLK setup time		2	—	ns
t <sub>STH</sub>	CCLK hold time		0	—	ns
t <sub>STCO</sub>	CCLK falling edge to valid output		—	10	ns
t <sub>STOZ</sub>	CCLK falling edge to valid disable		—	10	ns
t <sub>STOV</sub>	CCLK falling edge to valid enable		—	10	ns
t <sub>SCS</sub>	Chip select high time		25	—	ns
t <sub>SCSS</sub>	Chip select setup time		3	—	ns
t <sub>SCSH</sub>	Chip select hold time		3	—	ns
<b>Master SPI</b>					
f <sub>MAX</sub>	MCLK clock frequency		—	133	MHz
t <sub>MCLKH</sub>	MCLK clock pulse width high		3.75	—	ns
t <sub>MCLKL</sub>	MCLK clock pulse width low		3.75	—	ns
t <sub>STSU</sub>	MCLK setup time		5	—	ns
t <sub>STH</sub>	MCLK hold time		1	—	ns
t <sub>CSSPI</sub>	INITN high to chip select low		100	200	ns
t <sub>MCLK</sub>	INITN high to first MCLK edge		0.75	1	us

	MachXO3L/LF-6900				
	CSFBGA256	CSFBGA324	CABGA256	CABGA324	CABGA400
<b>General Purpose IO per Bank</b>					
Bank 0	50	73	50	71	83
Bank 1	52	68	52	68	84
Bank 2	52	72	52	72	84
Bank 3	16	24	16	24	28
Bank 4	16	16	16	16	24
Bank 5	20	28	20	28	32
<b>Total General Purpose Single Ended IO</b>	<b>206</b>	<b>281</b>	<b>206</b>	<b>279</b>	<b>335</b>
<b>Differential IO per Bank</b>					
Bank 0	25	36	25	36	42
Bank 1	26	34	26	34	42
Bank 2	26	36	26	36	42
Bank 3	8	12	8	12	14
Bank 4	8	8	8	8	12
Bank 5	10	14	10	14	16
<b>Total General Purpose Differential IO</b>	<b>103</b>	<b>140</b>	<b>103</b>	<b>140</b>	<b>168</b>
<b>Dual Function IO</b>	<b>37</b>	<b>37</b>	<b>37</b>	<b>37</b>	<b>37</b>
<b>Number 7:1 or 8:1 Gearboxes</b>					
Number of 7:1 or 8:1 Output Gearbox Available (Bank 0)	20	21	20	21	21
Number of 7:1 or 8:1 Input Gearbox Available (Bank 2)	20	21	20	21	21
<b>High-speed Differential Outputs</b>					
Bank 0	20	21	20	21	21
<b>VCCIO Pins</b>					
Bank 0	4	4	4	4	5
Bank 1	3	4	4	4	5
Bank 2	4	4	4	4	5
Bank 3	2	2	1	2	2
Bank 4	2	2	2	2	2
Bank 5	2	2	1	2	2
<b>VCC</b>	<b>8</b>	<b>8</b>	<b>8</b>	<b>10</b>	<b>10</b>
<b>GND</b>	<b>24</b>	<b>16</b>	<b>24</b>	<b>16</b>	<b>33</b>
<b>NC</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>0</b>	<b>0</b>
<b>Reserved for Configuration</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>
<b>Total Count of Bonded Pins</b>	<b>256</b>	<b>324</b>	<b>256</b>	<b>324</b>	<b>400</b>

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3L-2100E-6MG324I	2100	1.2 V	6	Halogen-Free csfBGA	324	IND
LCMXO3L-2100C-5BG256C	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3L-2100C-6BG256C	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3L-2100C-5BG256I	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3L-2100C-6BG256I	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3L-2100C-5BG324C	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	COM
LCMXO3L-2100C-6BG324C	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	COM
LCMXO3L-2100C-5BG324I	2100	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	IND
LCMXO3L-2100C-6BG324I	2100	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	IND

Part Number	LUTs	Supply Voltage	Speed	Package	Leads	Temp.
LCMXO3L-4300E-5UWG81CTR	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3L-4300E-5UWG81CTR50	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3L-4300E-5UWG81CTR1K	4300	1.2 V	5	Halogen-Free WLCSP	81	COM
LCMXO3L-4300E-5UWG81ITR	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3L-4300E-5UWG81ITR50	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3L-4300E-5UWG81ITR1K	4300	1.2 V	5	Halogen-Free WLCSP	81	IND
LCMXO3L-4300E-5MG121C	4300	1.2 V	5	Halogen-Free csfBGA	121	COM
LCMXO3L-4300E-6MG121C	4300	1.2 V	6	Halogen-Free csfBGA	121	COM
LCMXO3L-4300E-5MG121I	4300	1.2 V	5	Halogen-Free csfBGA	121	IND
LCMXO3L-4300E-6MG121I	4300	1.2 V	6	Halogen-Free csfBGA	121	IND
LCMXO3L-4300E-5MG256C	4300	1.2 V	5	Halogen-Free csfBGA	256	COM
LCMXO3L-4300E-6MG256C	4300	1.2 V	6	Halogen-Free csfBGA	256	COM
LCMXO3L-4300E-5MG256I	4300	1.2 V	5	Halogen-Free csfBGA	256	IND
LCMXO3L-4300E-6MG256I	4300	1.2 V	6	Halogen-Free csfBGA	256	IND
LCMXO3L-4300E-5MG324C	4300	1.2 V	5	Halogen-Free csfBGA	324	COM
LCMXO3L-4300E-6MG324C	4300	1.2 V	6	Halogen-Free csfBGA	324	COM
LCMXO3L-4300E-5MG324I	4300	1.2 V	5	Halogen-Free csfBGA	324	IND
LCMXO3L-4300E-6MG324I	4300	1.2 V	6	Halogen-Free csfBGA	324	IND
LCMXO3L-4300C-5BG256C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	COM
LCMXO3L-4300C-6BG256C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	COM
LCMXO3L-4300C-5BG256I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	256	IND
LCMXO3L-4300C-6BG256I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	256	IND
LCMXO3L-4300C-5BG324C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	COM
LCMXO3L-4300C-6BG324C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	COM
LCMXO3L-4300C-5BG324I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	324	IND
LCMXO3L-4300C-6BG324I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	324	IND
LCMXO3L-4300C-5BG400C	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	COM
LCMXO3L-4300C-6BG400C	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	COM
LCMXO3L-4300C-5BG400I	4300	2.5 V / 3.3 V	5	Halogen-Free caBGA	400	IND
LCMXO3L-4300C-6BG400I	4300	2.5 V / 3.3 V	6	Halogen-Free caBGA	400	IND