E ·) Chattine Semiconductor Corporation - <u>LCMXO3LF-9400E-6BG400C Datasheet</u>



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Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	1175
Number of Logic Elements/Cells	9400
Total RAM Bits	442368
Number of I/O	335
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-CABGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/lcmxo3lf-9400e-6bg400c

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Table 1-1. MachXO3L/LF Family Selection Guide

Features		MachXO3L-640/ MachXO3LF-640	MachXO3L-1300/ MachXO3LF-1300	MachXO3L-2100/ MachXO3LF-2100	MachXO3L-4300/ MachXO3LF-4300	MachXO3L-6900/ MachXO3LF-6900	MachXO3L-9400/ MachXO3LF-9400
LUTs		640	1300	2100	4300	6900	9400
Distributed R/	AM (kbits)	5	10	16	34	54	73
EBR SRAM (kbits)		64	64	74	92	240	432
Number of PLLs		1	1	1	2	2	2
Hardened	l ² C	2	2	2	2	2	2
Functions:	SPI	1	1	1	1	1	1
	Timer/Counter	1	1	1	1	1	1
	Oscillator	1	1	1	1	1	1
MIPI D-PHY S	Support	Yes	Yes	Yes	Yes	Yes	Yes
Multi Time Pr NVCM	ogrammable	MachXO3L-640	MachXO3L-1300	MachXO3L-2100	MachXO3L-4300	MachXO3L-6900	MachXO3L-9400
Programmabl	Programmable Flash		MachXO3LF-1300	MachXO3LF-2100	MachXO3LF-4300	MachXO3LF-6900	MachXO3LF-9400
Packages				ΙΟ			
36-ball WLCSP ¹ (2.5 mm x 2.5 mm, 0.4 mm)			28				
49-ball WLCSP ¹ (3.2 mm x 3.2 mm, 0.4 mm)				38			
81-ball WLCSP ¹ (3.8 mm x 3.8 mm, 0.4 mm)					63		
121-ball csfBGA ¹ (6 mm x 6 mm, 0.5 mm)		100	100	100	100		
256-ball csfB (9 mm x 9 mn	GA ¹ n, 0.5 mm)		206	206	206	206	206
324-ball csfB (10 mm x 10	GA ¹ mm, 0.5 mm)		2	268	268	281	
256-ball caBGA ² (14 mm x 14 mm, 0.8 mm)			206	206	206	206	206
324-ball caBC (15 mm x 15 i	àA² mm, 0.8 mm)			279	279	279	
400-ball caB0 (17 mm x 17 i	àA² mm, 0.8 mm)				335	335	335
484-ball caBC (19 mm x 19	3A² mm, 0.8 mm)						384

1. Package is only available for E=1.2 V devices.

2. Package is only available for C=2.5 V/3.3 V devices.

Introduction

MachXO3[™] device family is an Ultra-Low Density family that supports the most advanced programmable bridging and IO expansion. It has the breakthrough IO density and the lowest cost per IO. The device IO features have the integrated support for latest industry standard IO.

The MachXO3L/LF family of low power, instant-on, non-volatile PLDs has five devices with densities ranging from 640 to 9400 Look-Up Tables (LUTs). In addition to LUT-based, low-cost programmable logic these devices feature Embedded Block RAM (EBR), Distributed RAM, Phase Locked Loops (PLLs), pre-engineered source synchronous I/O support, advanced configuration support including dual-boot capability and hardened versions of commonly used functions such as SPI controller, I²C controller and timer/counter. MachXO3LF devices also support User Flash Memory (UFM). These features allow these devices to be used in low cost, high volume consumer and system applications.

The MachXO3L/LF devices are designed on a 65nm non-volatile low power process. The device architecture has several features such as programmable low swing differential I/Os and the ability to turn off I/O banks, on-chip PLLs



and oscillators dynamically. These features help manage static and dynamic power consumption resulting in low static power for all members of the family.

The MachXO3L/LF devices are available in two versions C and E with two speed grades: -5 and -6, with -6 being the fastest. C devices have an internal linear voltage regulator which supports external VCC supply voltages of 3.3 V or 2.5 V. E devices only accept 1.2 V as the external VCC supply voltage. With the exception of power supply voltage both C and E are functionally compatible with each other.

The MachXO3L/LF PLDs are available in a broad range of advanced halogen-free packages ranging from the space saving 2.5 x 2.5 mm WLCSP to the 19 x 19 mm caBGA. MachXO3L/LF devices support density migration within the same package. Table 1-1 shows the LUT densities, package and I/O options, along with other key parameters.

The MachXO3L/LF devices offer enhanced I/O features such as drive strength control, slew rate control, PCI compatibility, bus-keeper latches, pull-up resistors, pull-down resistors, open drain outputs and hot socketing. Pull-up, pull-down and bus-keeper features are controllable on a "per-pin" basis.

A user-programmable internal oscillator is included in MachXO3L/LF devices. The clock output from this oscillator may be divided by the timer/counter for use as clock input in functions such as LED control, key-board scanner and similar state machines.

The MachXO3L/LF devices also provide flexible, reliable and secure configuration from on-chip NVCM/Flash. These devices can also configure themselves from external SPI Flash or be configured by an external master through the JTAG test access port or through the I²C port. Additionally, MachXO3L/LF devices support dual-boot capability (using external Flash memory) and remote field upgrade (TransFR) capability.

Lattice provides a variety of design tools that allow complex designs to be efficiently implemented using the MachXO3L/LF family of devices. Popular logic synthesis tools provide synthesis library support for MachXO3L/LF. Lattice design tools use the synthesis tool output along with the user-specified preferences and constraints to place and route the design in the MachXO3L/LF device. These tools extract the timing from the routing and back-annotate it into the design for timing verification.

Lattice provides many pre-engineered IP (Intellectual Property) LatticeCORE[™] modules, including a number of reference designs licensed free of charge, optimized for the MachXO3L/LF PLD family. By using these configurable soft core IP cores as standardized blocks, users are free to concentrate on the unique aspects of their design, increasing their productivity.



Modes of Operation

Each slice has up to four potential modes of operation: Logic, Ripple, RAM and ROM.

Logic Mode

In this mode, the LUTs in each slice are configured as 4-input combinatorial lookup tables. A LUT4 can have 16 possible input combinations. Any four input logic functions can be generated by programming this lookup table. Since there are two LUT4s per slice, a LUT5 can be constructed within one slice. Larger look-up tables such as LUT6, LUT7 and LUT8 can be constructed by concatenating other slices. Note LUT8 requires more than four slices.

Ripple Mode

Ripple mode supports the efficient implementation of small arithmetic functions. In Ripple mode, the following functions can be implemented by each slice:

- Addition 2-bit
- Subtraction 2-bit
- Add/subtract 2-bit using dynamic control
- Up counter 2-bit
- Down counter 2-bit
- Up/down counter with asynchronous clear
- Up/down counter with preload (sync)
- Ripple mode multiplier building block
- Multiplier support
- Comparator functions of A and B inputs
 - A greater-than-or-equal-to B
 - A not-equal-to B
 - A less-than-or-equal-to B

Ripple mode includes an optional configuration that performs arithmetic using fast carry chain methods. In this configuration (also referred to as CCU2 mode) two additional signals, Carry Generate and Carry Propagate, are generated on a per-slice basis to allow fast arithmetic functions to be constructed by concatenating slices.

RAM Mode

In this mode, a 16x4-bit distributed single port RAM (SPR) can be constructed by using each LUT block in Slice 0 and Slice 1 as a 16x1-bit memory. Slice 2 is used to provide memory address and control signals.

MachXO3L/LF devices support distributed memory initialization.

The Lattice design tools support the creation of a variety of different size memories. Where appropriate, the software will construct these using distributed memory primitives that represent the capabilities of the PFU. Table 2-3 shows the number of slices required to implement different distributed RAM primitives. For more information about using RAM in MachXO3L/LF devices, please see TN1290, Memory Usage Guide for MachXO3 Devices.

Table 2-3. Number of Slices Required For Implementing Distributed RAM

	SPR 16x4	PDPR 16x4		
Number of slices	3	3		
Note: SPB = Single Port BAM_PDPB = Pseudo Dual Port BAM				

ote: SPR = Single Port RAM, PDPR = Pseudo Dual



Figure 2-5. Primary Clocks for MachXO3L/LF Devices



Eight secondary high fanout nets are generated from eight 8:1 muxes as shown in Figure 2-6. One of the eight inputs to the secondary high fanout net input mux comes from dual function clock pins and the remaining seven come from internal routing. The maximum frequency for the secondary clock network is shown in MachXO3L/LF External Switching Characteristics table.



This phase shift can be either programmed during configuration or can be adjusted dynamically. In dynamic mode, the PLL may lose lock after a phase adjustment on the output used as the feedback source and not relock until the $t_{I,OCK}$ parameter has been satisfied.

The MachXO3L/LF also has a feature that allows the user to select between two different reference clock sources dynamically. This feature is implemented using the PLLREFCS primitive. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

The MachXO3L/LF PLL contains a WISHBONE port feature that allows the PLL settings, including divider values, to be dynamically changed from the user logic. When using this feature the EFB block must also be instantiated in the design to allow access to the WISHBONE ports. Similar to the dynamic phase adjustment, when PLL settings are updated through the WISHBONE port the PLL may lose lock and not relock until the t_{LOCK} parameter has been satisfied. The timing parameters for the PLL are shown in the sysCLOCK PLL Timing table.

For more details on the PLL and the WISHBONE interface, see TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide.



Figure 2-7. PLL Diagram

Table 2-4 provides signal descriptions of the PLL block.

Table 2-4	. PLL	Signal	Descriptions
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Port Name	I/O	Description
CLKI	Ι	Input clock to PLL
CLKFB	I	Feedback clock
PHASESEL[1:0]	Ι	Select which output is affected by Dynamic Phase adjustment ports
PHASEDIR	I	Dynamic Phase adjustment direction
PHASESTEP	Ι	Dynamic Phase step – toggle shifts VCO phase adjust by one step.



 Table 2-5. sysMEM Block Configurations

Memory Mode	Configurations
Single Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9
True Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9
Pseudo Dual Port	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18
FIFO	8,192 x 1 4,096 x 2 2,048 x 4 1,024 x 9 512 x 18

Bus Size Matching

All of the multi-port memory modes support different widths on each of the ports. The RAM bits are mapped LSB word 0 to MSB word 0, LSB word 1 to MSB word 1, and so on. Although the word size and number of words for each port varies, this mapping scheme applies to each port.

RAM Initialization and ROM Operation

If desired, the contents of the RAM can be pre-loaded during device configuration. EBR initialization data can be loaded from the NVCM or Configuration Flash.

MachXO3LF EBR initialization data can also be loaded from the UFM. To maximize the number of UFM bits, initialize the EBRs used in your design to an all-zero pattern. Initializing to an all-zero pattern does not use up UFM bits. MachXO3LF devices have been designed such that multiple EBRs share the same initialization memory space if they are initialized to the same pattern.

By preloading the RAM block during the chip configuration cycle and disabling the write controls, the sysMEM block can also be utilized as a ROM.

Memory Cascading

Larger and deeper blocks of RAM can be created using EBR sysMEM Blocks. Typically, the Lattice design tools cascade memory transparently, based on specific design inputs.

Single, Dual, Pseudo-Dual Port and FIFO Modes

Figure 2-8 shows the five basic memory configurations and their input/output names. In all the sysMEM RAM modes, the input data and addresses for the ports are registered at the input of the memory array. The output data of the memory is optionally registered at the memory array output.



If an EBR is pre-loaded during configuration, the GSR input must be disabled or the release of the GSR during device wake up must occur before the release of the device I/Os becoming active.

These instructions apply to all EBR RAM, ROM and FIFO implementations. For the EBR FIFO mode, the GSR signal is always enabled and the WE and RE signals act like the clock enable signals in Figure 2-10. The reset timing rules apply to the RPReset input versus the RE input and the RST input versus the WE and RE inputs. Both RST and RPReset are always asynchronous EBR inputs. For more details refer to TN1290, Memory Usage Guide for MachXO3 Devices.

Note that there are no reset restrictions if the EBR synchronous reset is used and the EBR GSR input is disabled.

Programmable I/O Cells (PIC)

The programmable logic associated with an I/O is called a PIO. The individual PIO are connected to their respective sysIO buffers and pads. On the MachXO3L/LF devices, the PIO cells are assembled into groups of four PIO cells called a Programmable I/O Cell or PIC. The PICs are placed on all four sides of the device.

On all the MachXO3L/LF devices, two adjacent PIOs can be combined to provide a complementary output driver pair.

All PIO pairs can implement differential receivers. Half of the PIO pairs on the top edge of these devices can be configured as true LVDS transmit pairs. The PIO pairs on the bottom edge of these devices have on-chip differential termination and also provide PCI support.



Output Register Block

The output register block registers signals from the core of the device before they are passed to the sysIO buffers.

Left, Top, Bottom Edges

In SDR mode, D0 feeds one of the flip-flops that then feeds the output. The flip-flop can be configured as a D-type register or latch.

In DDR generic mode, D0 and D1 inputs are fed into registers on the positive edge of the clock. At the next falling edge the registered D1 input is registered into the register Q1. A multiplexer running off the same clock is used to switch the mux between the outputs of registers Q0 and Q1 that will then feed the output.

Figure 2-12 shows the output register block on the left, top and bottom edges.

Figure 2-12. MachXO3L/LF Output Register Block Diagram (PIO on the Left, Top and Bottom Edges)



Tri-state Register Block

The tri-state register block registers tri-state control signals from the core of the device before they are passed to the sysIO buffers. The block contains a register for SDR operation. In SDR, TD input feeds one of the flip-flops that then feeds the output.



Output Gearbox

Each PIC on the top edge has a built-in 8:1 output gearbox. Each of these output gearboxes may be programmed as a 7:1 serializer or as one ODDRX4 (8:1) gearbox or as two ODDRX2 (4:1) gearboxes. Table 2-10 shows the gearbox signals.

Table 2-10. Output Gearbox Signal List

Name	I/O Type	Description
Q	Output	High-speed data output
D[7:0]	Input	Low-speed data from device core
Video TX(7:1): D[6:0]		
GDDRX4(8:1): D[7:0]		
GDDRX2(4:1)(IOL-A): D[3:0]		
GDDRX2(4:1)(IOL-C): D[7:4]		
SCLK	Input	Slow-speed system clock
ECLK [1:0]	Input	High-speed edge clock
RST	Input	Reset

The gearboxes have three stage pipeline registers. The first stage registers sample the low-speed input data on the low-speed system clock. The second stage registers transfer data from the low-speed clock registers to the high-speed clock registers. The third stage pipeline registers controlled by high-speed edge clock shift and mux the high-speed data out to the sysIO buffer. Figure 2-14 shows the output gearbox block diagram.



Embedded Hardened IP Functions

All MachXO3L/LF devices provide embedded hardened functions such as SPI, I²C and Timer/Counter. MachXO3LF devices also provide User Flash Memory (UFM). These embedded blocks interface through the WISHBONE interface with routing as shown in Figure 2-17.

Figure 2-17. Embedded Function Block Interface



Hardened I²C IP Core

Every MachXO3L/LF device contains two I^2C IP cores. These are the primary and secondary I^2C IP cores. Either of the two cores can be configured either as an I^2C master or as an I^2C slave. The only difference between the two IP cores is that the primary core has pre-assigned I/O pins whereas users can assign I/O pins for the secondary core.

When the IP core is configured as a master it will be able to control other devices on the I^2C bus through the interface. When the core is configured as the slave, the device will be able to provide I/O expansion to an I^2C Master. The I^2C cores support the following functionality:

- Master and Slave operation
- 7-bit and 10-bit addressing
- Multi-master arbitration support
- Up to 400 kHz data transfer speed
- General call support
- Interface to custom logic through 8-bit WISHBONE interface



Hardened Timer/Counter

MachXO3L/LF devices provide a hard Timer/Counter IP core. This Timer/Counter is a general purpose, bi-directional, 16-bit timer/counter module with independent output compare units and PWM support. The Timer/Counter supports the following functions:

- Supports the following modes of operation:
 - Watchdog timer
 - Clear timer on compare match
 - Fast PWM
 - Phase and Frequency Correct PWM
- Programmable clock input source
- Programmable input clock prescaler
- One static interrupt output to routing
- One wake-up interrupt to on-chip standby mode controller.
- Three independent interrupt sources: overflow, output compare match, and input capture
- Auto reload
- Time-stamping support on the input capture unit
- Waveform generation on the output
- Glitch-free PWM waveform generation with variable PWM period
- Internal WISHBONE bus access to the control and status registers
- · Stand-alone mode with preloaded control registers and direct reset input

Figure 2-20. Timer/Counter Block Diagram



Table 2-16. Timer/Counter Signal Description

Port	I/O	Description
tc_clki	I	Timer/Counter input clock signal
tc_rstn	I	Register tc_rstn_ena is preloaded by configuration to always keep this pin enabled
tc_ic	I	Input capture trigger event, applicable for non-pwm modes with WISHBONE interface. If enabled, a rising edge of this signal will be detected and synchronized to capture tc_cnt value into tc_icr for time-stamping.
tc_int	0	Without WISHBONE – Can be used as overflow flag With WISHBONE – Controlled by three IRQ registers
tc_oc	0	Timer counter output signal



MachXO3 Family Data Sheet DC and Switching Characteristics

February 2017

Advance Data Sheet DS1047

Absolute Maximum Ratings^{1, 2, 3}

	MachXO3L/LF E (1.2 V)	MachXO3L/LF C (2.5 V/3.3 V)
Supply Voltage V _{CC}	\ldots .–0.5 V to 1.32 V \ldots .	–0.5 V to 3.75 V
Output Supply Voltage V _{CCIO}	–0.5 V to 3.75 V	–0.5 V to 3.75 V
I/O Tri-state Voltage Applied ^{4, 5}	–0.5 V to 3.75 V	–0.5 V to 3.75 V
Dedicated Input Voltage Applied ⁴	–0.5 V to 3.75 V	–0.5 V to 3.75 V
Storage Temperature (Ambient)	–55 °C to 125 °C	–55 °C to 125 °C
Junction Temperature (T ₁)	–40 °C to 125 °C	–40 °C to 125 °C

1. Stress above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. Functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

2. Compliance with the Lattice Thermal Management document is required.

3. All voltages referenced to GND.

4. Overshoot and undershoot of -2 V to (V_{IHMAX} + 2) volts is permitted for a duration of <20 ns.

5. The dual function I^2C pins SCL and SDA are limited to -0.25 V to 3.75 V or to -0.3 V with a duration of <20 ns.

Recommended Operating Conditions¹

Symbol	Parameter	Min.	Max.	Units
V _{CC} ¹	Core Supply Voltage for 1.2 V Devices	1.14	1.26	V
	Core Supply Voltage for 2.5 V/3.3 V Devices	2.375	3.465	V
V _{CCIO} ^{1, 2, 3}	I/O Driver Supply Voltage	1.14	3.465	V
t _{JCOM}	Junction Temperature Commercial Operation	0	85	°C
t _{JIND}	Junction Temperature Industrial Operation	-40	100	°C

1. Like power supplies must be tied together. For example, if V_{CCIO} and V_{CC} are both the same voltage, they must also be the same supply.

2. See recommended voltages by I/O standard in subsequent table.

3. V_{CCIO} pins of unused I/O banks should be connected to the V_{CC} power supply on boards.

Power Supply Ramp Rates¹

	iyp.	wax.	Units
t _{RAMP} Power supply ramp rates for all power supplies. 0.01	—	100	V/ms

1. Assumes monotonic ramp rates.

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Static Supply Current – C/E Devices^{1, 2, 3, 6}

Symbol	Parameter	Device	Typ.⁴	Units
I _{CC}	Core Power Supply	LCMXO3L/LF-1300C 256 Ball Package	4.8	mA
		LCMXO3L/LF-2100C	4.8	mA
		LCMXO3L/LF-2100C 324 Ball Package	8.45	mA
		LCMXO3L/LF-4300C	8.45	mA
		LCMXO3L/LF-4300C 400 Ball Package	12.87	mA
		LCMXO3L/LF-6900C ⁷	12.87	mA
		LCMXO3L/LF-9400C ⁷	17.86	mA
		LCMXO3L/LF-640E	1.00	mA
		LCMXO3L/LF-1300E	1.00	mA
		LCMXO3L/LF-1300E 256 Ball Package	1.39	mA
		LCMXO3L/LF-2100E	1.39	mA
		LCMXO3L/LF-2100E 324 Ball Package	2.55	mA
		LCMXO3L/LF-4300E	2.55	mA
		LCMXO3L/LF-6900E	4.06	mA
		LCMXO3L/LF-9400E	5.66	mA
I _{CCIO}	Bank Power Supply ⁵ VCCIO = 2.5 V	All devices	0	mA

1. For further information on supply current, please refer to TN1289, Power Estimation and Management for MachXO3 Devices.

2. Assumes blank pattern with the following characteristics: all outputs are tri-stated, all inputs are configured as LVCMOS and held at V_{CCIO} or GND, on-chip oscillator is off, on-chip PLL is off.

3. Frequency = 0 MHz.

4. $T_J = 25$ °C, power supplies at nominal voltage.

5. Does not include pull-up/pull-down.

6. To determine the MachXO3L/LF peak start-up current data, use the Power Calculator tool.

7. Determination of safe ambient operating conditions requires use of the Diamond Power Calculator tool.



sysIO Single-Ended DC Electrical Characteristics^{1, 2}

Input/Output	V	/IL	v	н	Voi Max.	Vou Min.	V _{OH} Min. I _{OL} Max.⁴	
Standard	Min. (V) ³	Max. (V)	Min. (V)	Max. (V)	(V)	(V)	(mA)	(mA)
							4	-4
					0.4	V 04	8	-8
	-0.3	0.8	2.0	3.6	0.4	VCCIO - 0.4	12	-12
							16	-16
					0.2	V _{CCIO} - 0.2	0.1	-0.1
							4	-4
					0.4	V 04	8	-8
LVCMOS 2.5	-0.3	0.7	1.7	3.6	0.4	V _{CCIO} - 0.4	12	-12
							16	-16
					0.2	V _{CCIO} - 0.2	0.1	-0.1
							4	-4
			0.051/	0.0	0.4	V _{CCIO} - 0.4	8	-8
LVCMOS 1.8	-0.3	0.35V _{CCIO}	0.65V _{CCIO}	3.6			12	-12
					0.2	V _{CCIO} - 0.2	0.1	-0.1
	-0.3		0.65V _{CCIO}		0.4	V 04	4	-4
LVCMOS 1.5		0.35V _{CCIO}		3.6	0.4	V _{CCIO} - 0.4	8	-8
					0.2	V _{CCIO} - 0.2	0.1	-0.1
			0.65V _{CCIO}		0.4	N 0.4	4	-2
LVCMOS 1.2	-0.3	.3 0.35V _{CCIO}		3.6	V _{CCIO} - 0.4	8	-6	
					0.2	V _{CCIO} - 0.2	0.1	-0.1
LVCMOS25R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS18R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS18R25	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS15R33	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS15R25	-0.3	VREF-0.1	VREF+0.1	3.6	NA	NA	NA	NA
LVCMOS12R33	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	24, 16, 12, 8, 4	NA Open Drain
LVCMOS12R25	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	16, 12, 8, 4	NA Open Drain
LVCMOS10R33	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	24, 16, 12, 8, 4	NA Open Drain
LVCMOS10R25	-0.3	VREF-0.1	VREF+0.1	3.6	0.40	NA Open Drain	16, 12, 8, 4	NA Open Drain

 MachXO3L/LF devices allow LVCMOS inputs to be placed in I/O banks where V_{CCIO} is different from what is specified in the applicable JEDEC specification. This is referred to as a ratioed input buffer. In a majority of cases this operation follows or exceeds the applicable JEDEC specification. The cases where MachXO3L/LF devices do not meet the relevant JEDEC specification are documented in the table below.

2. MachXO3L/LF devices allow for LVCMOS referenced I/Os which follow applicable JEDEC specifications. For more details about mixed mode operation please refer to please refer to TN1280, MachXO3 sysIO Usage Guide.

3. The dual function I²C pins SCL and SDA are limited to a V_{IL} min of -0.25 V or to -0.3 V with a duration of <10 ns.

4. For electromigration, the average DC current sourced or sinked by I/O pads between two consecutive VCCIO or GND pad connections, or between the last VCCIO or GND in an I/O bank and the end of an I/O bank, as shown in the Logic Signal Connections table (also shown as I/O grouping) shall not exceed a maximum of n * 8 mA. "n" is the number of I/O pads between the two consecutive bank VCCIO or GND connections or between the last VCCIO and GND in a bank and the end of a bank. IO Grouping can be found in the Data Sheet Pin Tables, which can also be generated from the Lattice Diamond software.



BLVDS

The MachXO3L/LF family supports the BLVDS standard through emulation. The output is emulated using complementary LVCMOS outputs in conjunction with resistors across the driver outputs. The input standard is supported by the LVDS differential input buffer. BLVDS is intended for use when multi-drop and bi-directional multi-point differential signaling is required. The scheme shown in Figure 3-2 is one possible solution for bi-directional multi-point differential signals.

Figure 3-2. BLVDS Multi-point Output Example



Table 3-2. BLVDS DC Conditions¹

Over Recommended	Operating	Conditions
	operating	Contaitions

		Noi		
Symbol	Description	Zo = 45	Zo = 90	Units
Z _{OUT}	Output impedance	20	20	Ohms
R _S	Driver series resistance	80	80	Ohms
R _{TLEFT}	Left end termination	45	90	Ohms
R _{TRIGHT}	Right end termination	45	90	Ohms
V _{OH}	Output high voltage	1.376	1.480	V
V _{OL}	Output low voltage	1.124	1.020	V
V _{OD}	Output differential voltage	0.253	0.459	V
V _{CM}	Output common mode voltage	1.250	1.250	V
I _{DC}	DC output current	11.236	10.204	mA

1. For input buffer, see LVDS table.



MachXO3L/LF External Switching Characteristics – C/E Devices^{1, 2, 3, 4, 5, 6, 10}

			-6 -		5		
Parameter	Description	Device	Min.	Max.	Min.	Max.	Units
Clocks							
Primary Clo	cks						-
f _{MAX_PRI} ⁷	Frequency for Primary Clock Tree	All MachXO3L/LF devices	_	388	_	323	MHz
t _{W_PRI}	Clock Pulse Width for Primary Clock	All MachXO3L/LF devices	0.5		0.6		ns
		MachXO3L/LF-1300		867	_	897	ps
t _{SKEW_PRI}	Primary Clock Skew Within a Device	MachXO3L/LF-2100		867		897	ps
		MachXO3L/LF-4300	_	865	-	892	ps
		MachXO3L/LF-6900	_	902	-	942	ps
		MachXO3L/LF-9400	_	908	-	950	ps
Edge Clock							
f _{MAX_EDGE} ⁷	Frequency for Edge Clock	MachXO3L/LF		400	_	333	MHz
Pin-LUT-Pin	Propagation Delay						
t _{PD}	Best case propagation delay through one LUT-4	All MachXO3L/LF devices		6.72		6.96	ns
General I/O	Pin Parameters (Using Primary Clock with	out PLL)					
		MachXO3L/LF-1300	—	7.46	—	7.66	ns
		MachXO3L/LF-2100	_	7.46	_	7.66	ns
t _{CO}	Clock to Output - PIO Output Register	MachXO3L/LF-4300	_	7.51		7.71	ns
		MachXO3L/LF-6900	_	7.54		7.75	ns
		MachXO3L/LF-9400	_	7.53		7.83	ns
		MachXO3L/LF-1300	-0.20	_	-0.20		ns
		MachXO3L/LF-2100	-0.20	_	-0.20		ns
t _{SU}	Clock to Data Setup - PIO Input Register	MachXO3L/LF-4300	-0.23	_	-0.23		ns
		MachXO3L/LF-6900	-0.23		-0.23		ns
		MachXO3L/LF-9400	-0.24		-0.24		ns
		MachXO3L/LF-1300	1.89		2.13		ns
		MachXO3L/LF-2100	1.89	_	2.13		ns
t _H	Clock to Data Hold - PIO Input Register	MachXO3L/LF-4300	1.94	_	2.18		ns
		MachXO3L/LF-6900	1.98	_	2.23		ns
		MachXO3L/LF-9400	1.99	_	2.24		ns
		MachXO3L/LF-1300	1.61	_	1.76		ns
		MachXO3L/LF-2100	1.61	_	1.76		ns
t _{SU DEL}	Clock to Data Setup - PIO Input Register	MachXO3L/LF-4300	1.66	_	1.81		ns
	with Data input Delay	MachXO3L/LF-6900	1.53	_	1.67		ns
		MachXO3L/LF-9400	1.65	_	1.80		ns
		MachXO3L/LF-1300	-0.23	_	-0.23		ns
		MachXO3L/LF-2100	-0.23	_	-0.23		ns
^t H DEL	Clock to Data Hold - PIO Input Register with	MachXO3L/LF-4300	-0.25	_	-0.25	_	ns
	Input Data Delay	MachXO3L/LF-6900	-0.21	_	-0.21	_	ns
		MachXO3L/LF-9400	-0.24	_	-0.24	_	ns
f _{MAX_IO}	Clock Frequency of I/O and PFU Register	All MachXO3L/LF devices	—	388	—	323	MHz

Over Recommended Operating Conditions



sysCLOCK PLL Timing

Parameter	Descriptions	Conditions	Min.	Max.	Units
f _{IN}	Input Clock Frequency (CLKI, CLKFB)		7	400	MHz
f _{OUT}	Output Clock Frequency (CLKOP, CLKOS, CLKOS)		1.5625	400	MHz
f _{OUT2}	Output Frequency (CLKOS3 cascaded from CLKOS2)		0.0122	400	MHz
f _{VCO}	PLL VCO Frequency		200	800	MHz
f _{PFD}	Phase Detector Input Frequency		7	400	MHz
AC Characteri	stics	·			
t _{DT}	Output Clock Duty Cycle	Without duty trim selected ³	45	55	%
t _{DT_TRIM} ⁷	Edge Duty Trim Accuracy		-75	75	%
t _{PH} ⁴	Output Phase Accuracy		-6	6	%
	Output Cleak Pariad littar	f _{OUT} > 100 MHz	—	150	ps p-p
		f _{OUT} < 100 MHz	—	0.007	UIPP
	Output Clock Cycle-to-cycle, litter	f _{OUT} > 100 MHz	—	180	ps p-p
		f _{OUT} < 100 MHz	—	0.009	UIPP
+ 1.8	Output Clock Phase litter	f _{PFD} > 100 MHz	—	160	ps p-p
^l opjit ^{1,2}	Output Clock Phase Jitter	f _{PFD} < 100 MHz	—	0.011	UIPP
	Output Clock Pariod Litter (Fractional N)	f _{OUT} > 100 MHz	—	230	ps p-p
	Output Clock Period Jitter (Fractional-N)	f _{OUT} < 100 MHz	—	0.12	UIPP
	Output Clock Cycle-to-cycle Jitter	f _{OUT} > 100 MHz	—	230	ps p-p
	(Fractional-N)	f _{OUT} < 100 MHz	—	0.12	UIPP
t _{SPO}	Static Phase Offset	Divider ratio = integer	-120	120	ps
t _W	Output Clock Pulse Width	At 90% or 10% ³	0.9	—	ns
tLOCK ^{2, 5}	PLL Lock-in Time		—	15	ms
t _{UNLOCK}	PLL Unlock Time		—	50	ns
• 6	Innut Cleak Davied Litter	f _{PFD} ≥ 20 MHz	—	1,000	ps p-p
'IPJIT		f _{PFD} < 20 MHz	—	0.02	UIPP
t _{HI}	Input Clock High Time	90% to 90%	0.5	—	ns
t _{LO}	Input Clock Low Time	10% to 10%	0.5	—	ns
t _{STABLE} ⁵	STANDBY High to PLL Stable		—	15	ms
t _{RST}	RST/RESETM Pulse Width		1	_	ns
t _{RSTREC}	RST Recovery Time		1		ns
t _{RST DIV}	RESETC/D Pulse Width		10		ns
t _{RSTREC} DIV	RESETC/D Recovery Time		1		ns
t _{ROTATE-SETUP}	PHASESTEP Setup Time		10		ns
t _{ROTATE_WD}	PHASESTEP Pulse Width		4	—	VCO Cycles

Over Recommended Operating Conditions

1. Period jitter sample is taken over 10,000 samples of the primary PLL output with a clean reference clock. Cycle-to-cycle jitter is taken over 1000 cycles. Phase jitter is taken over 2000 cycles. All values per JESD65B.

2. Output clock is valid after t_{LOCK} for PLL reset and dynamic delay adjustment.

3. Using LVDS output buffers.

4. CLKOS as compared to CLKOP output for one phase step at the maximum VCO frequency. See TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide for more details.

5. At minimum $\rm f_{PFD}$ As the $\rm f_{PFD}$ increases the time will decrease to approximately 60% the value listed.

6. Maximum allowed jitter on an input clock. PLL unlock may occur if the input jitter exceeds this specification. Jitter on the input clock may be transferred to the output clocks, resulting in jitter measurements outside the output specifications listed in this table.

7. Edge Duty Trim Accuracy is a percentage of the setting value. Settings available are 70 ps, 140 ps, and 280 ps in addition to the default value of none.

8. Jitter values measured with the internal oscillator operating. The jitter values will increase with loading of the PLD fabric and in the presence of SSO noise.



I²C Port Timing Specifications^{1, 2}

Symbol	Parameter	Min.	Max.	Units
f _{MAX}	Maximum SCL clock frequency		400	kHz

1. MachXO3L/LF supports the following modes:

• Standard-mode (Sm), with a bit rate up to 100 kbit/s (user and configuration mode)

• Fast-mode (Fm), with a bit rate up to 400 kbit/s (user and configuration mode)

2. Refer to the I^2C specification for timing requirements.

SPI Port Timing Specifications¹

Symbol	Parameter	Min.	Max.	Units
f _{MAX}	Maximum SCK clock frequency		45	MHz

1. Applies to user mode only. For configuration mode timing specifications, refer to sysCONFIG Port Timing Specifications table in this data sheet.

Switching Test Conditions

Figure 3-9 shows the output test load used for AC testing. The specific values for resistance, capacitance, voltage, and other test conditions are shown in Table 3-6.

Figure 3-9. Output Test Load, LVTTL and LVCMOS Standards



Table 3-6. Test Fixture Required Components	, Non-Terminated Interfaces
---	-----------------------------

Test Condition	R1	CL	Timing Ref.	VT
		0pF	LVTTL, LVCMOS 3.3 = 1.5 V	_
	x		LVCMOS 2.5 = $V_{CCIO}/2$	_
LVTTL and LVCMOS settings (L -> H, H -> L)			LVCMOS 1.8 = $V_{CCIO}/2$	
			LVCMOS 1.5 = $V_{CCIO}/2$	_
			LVCMOS 1.2 = $V_{CCIO}/2$	_
LVTTL and LVCMOS 3.3 (Z -> H)		0.5	1.5	V _{OL}
LVTTL and LVCMOS 3.3 (Z -> L)	100		1.5	V _{OH}
Other LVCMOS (Z -> H)			V _{CCIO} /2	V _{OL}
Other LVCMOS (Z -> L)	100	орі	V _{CCIO} /2	V _{OH}
LVTTL + LVCMOS (H -> Z)			V _{OH} - 0.15	V _{OL}
LVTTL + LVCMOS (L -> Z)			V _{OL} - 0.15	V _{OH}

Note: Output test conditions for all other interfaces are determined by the respective standards.



		М	achXO3L/LF-69	00	
	CSFBGA256	CSFBGA324	CABGA256	CABGA324	CABGA400
General Purpose IO per Bank		•	•	•	•
Bank 0	50	73	50	71	83
Bank 1	52	68	52	68	84
Bank 2	52	72	52	72	84
Bank 3	16	24	16	24	28
Bank 4	16	16	16	16	24
Bank 5	20	28	20	28	32
Total General Purpose Single Ended IO	206	281	206	279	335
Differential IO per Bank		•	•	•	•
Bank 0	25	36	25	36	42
Bank 1	26	34	26	34	42
Bank 2	26	36	26	36	42
Bank 3	8	12	8	12	14
Bank 4	8	8	8	8	12
Bank 5	10	14	10	14	16
Total General Purpose Differential IO	103	140	103	140	168
Dual Function IO	37	37	37	37	37
Number 7:1 or 8:1 Gearboxes		•	•		
Number of 7:1 or 8:1 Output Gearbox Available (Bank 0)	20	21	20	21	21
Number of 7:1 or 8:1 Input Gearbox Available (Bank 2)	20	21	20	21	21
High-speed Differential Outputs		•	•		
Bank 0	20	21	20	21	21
VCCIO Pins		•	•	•	•
Bank 0	4	4	4	4	5
Bank 1	3	4	4	4	5
Bank 2	4	4	4	4	5
Bank 3	2	2	1	2	2
Bank 4	2	2	2	2	2
Bank 5	2	2	1	2	2
VCC	8	8	8	10	10
GND	24	16	24	16	33
NC	0	0	1	0	0
Reserved for Configuration	1	1	1	1	1
Total Count of Bonded Pins	256	324	256	324	400



MachXO3 Family Data Sheet Supplemental Information

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Advance Data Sheet DS1047

For Further Information

A variety of technical notes for the MachXO3 family are available on the Lattice web site.

- TN1282, MachXO3 sysCLOCK PLL Design and Usage Guide
- TN1281, Implementing High-Speed Interfaces with MachXO3 Devices
- TN1280, MachXO3 sysIO Usage Guide
- TN1279, MachXO3 Programming and Configuration Usage Guide
- TN1074, PCB Layout Recommendations for BGA Packages
- TN1087, Minimizing System Interruption During Configuration Using TransFR Technology
- AN8066, Boundary Scan Testability with Lattice sysIO Capability
- MachXO3 Device Pinout Files
- Thermal Management document
- Lattice design tools

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