Infineon Technologies - MB90352ESPMC-GS-145E1 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, I²C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, WDT
Number of I/O	51
Program Memory Size	128KB (128K x 8)
Program Memory Type	Mask ROM
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 15x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90352espmc-gs-145e1

- 8/16-bit PPG timer : 8-bit ∞ 10 channels or 16-bit × 6 channels
- 16-bit reload timer : 2 channels (only Evaluation products has 4 channels)
- 16- bit input/output timer
  - 16-bit free-run timer : 2 channels (FRT0 : ICU0/1, FRT1 : ICU4/5/6/7, OCU4/5/6/7)
  - 16- bit input capture: (ICU) : 6 channels
  - 16-bit output compare : (OCU) : 4 channels

FULL-CAN interface: 1 channel

- Compliant with CAN standard Version2.0 Part A and Part B
- 16 message buffers are built-in
- CAN wake-up function

LIN-UART: 2 channels

- Equipped with full-duplex double buffer
- Clock-asynchronous or clock-synchronous serial transmission is available.

I^2C interface: 1 channel

Up to 400 kbps transfer rate

DTP/External interrupt: 8 channels, CAN wakeup: 1 channel

Module for activation of extended intelligent I/O service (EI^2OS), DMA, and generation of external interrupt by external input.

Delay interrupt generator module

Generates interrupt request for task switching.

8/10-bit A/D converter: 15 channels

- Resolution is selectable between 8-bit and 10-bit.
- Activation by external trigger input is allowed.
- Conversion time : 3 µs (at 24 MHz machine clock, including sampling time)

Address matching detection (Program patch) function

- Address matching detection for 6 address pointers.

Capable of changing input voltage level for port

- Automotive/CMOS-Schmitt (initial level is Automotive in single chip mode)
- TTL level (corresponds to external bus pins only, initial level of these pins is TTL in external bus mode)

Low voltage/CPU operation detection reset (devices with T-suffix)

- Detects low voltage (4.0 V ± 0.3 V) and resets automatically
- Resets automatically when program is runaway and counter is not cleared within interval time
  (approx. 262 ms : external 4 MHz)

Dual operation Flash memory (only devices 128 Kbytes Flash memory)

- Erase/write and read can be executed in the different bank (Upper Bank/Lower Bank) at the same time.

Supported T_A = + 125°C

The maximum operating frequency is 24 MHz* : (at T_A = +125°C) .

Flash security function

- Protects the content of Flash memory
  (MB90F352x, MB90F357x only)

External bus interface

- 4 Mbytes external memory space
  MB90F351E(S), MB90F351TE(S), MB90F352E(S), MB90F352TE(S) : External bus Interface can not be used in internal vector mode. It can be used only in external vector mode.

* : If used exceeding T_A = + 105 °C, be sure to contact Cypress for reliability limitations.

2. Product Lineup 2 (With Clock supervisor function)

■ Flash memory products

Parameter \ Part Number	MB90F356E MB90F357E	MB90F356TE MB90F357TE	MB90F356ES MB90F357ES	MB90F356TES MB90F357TES
Type	Flash memory products			
CPU	F^2MC-16LX CPU			
System clock	On-chip PLL clock multiplier (×1, ×2, ×3, ×4, ×6, 1/2 when PLL stops) Minimum instruction execution time : 42 ns (oscillation clock 4 MHz, PLL × 6)			
ROM	64 Kbytes Flash memory : MB90F356E(S), MB90F356TE(S) 128 Kbytes Dual operation Flash memory (Erase/write and read can be operated at the same time) : MB90F357E(S), MB90F357TE(S)			
RAM	4 Kbytes			
Emulator-specific power supply*	—			
Sub clock pin (X0A, X1A)	Yes		No	
Clock supervisor	Yes			
Low voltage/CPU operation detection reset	No	Yes	No	Yes
Operating voltage range	3.5 V to 5.5 V : at normal operating (not using A/D converter) 3.5 V to 5.5 V : at using A/D converter/Flash programming 3.5 V to 5.5 V : at using external bus			
Operating temperature range	−40°C to +125°C			
Package	LQFP-64			
LIN-UART	2 channels			
	Wide range of baud rate settings using a dedicated baud rate generator (reload timer) Special synchronous options for adapting to different synchronous serial protocols LIN functionality working either as master or slave LIN device			
I^2C (400 kbps)	1 channel			
A/D converter	15 channels			
	10-bit or 8-bit resolution Conversion time : Min 3 μs includes sample time (per one channel)			
16-bit reload timer (4 channels)	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = Machine clock frequency) Supports External Event Count function.			
16-bit free-run timer (2 channels)	Free-run Timer 0 (clock input FRCK0) corresponds to ICU 0/1. Free-run Timer 1 (clock input FRCK1) corresponds to ICU 4/5/6/7, OCU 4/5/6/7.			
	Signals an interrupt when overflowing. Supports Timer Clear when a match with Output Compare (Channel 0, 4) . Operation clock frequency : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4, fsys/2^5, fsys/2^6, fsys/2^7 (fsys = Machine clock frequency)			
16-bit output compare	4 channels			
	Signals an interrupt when 16-bit free-run Timer matches with output compare registers. A pair of compare registers can be used to generate an output signal.			

■ MASK ROM products/Evaluation products

Parameter \ Part Number	MB90356E MB90357E	MB90356TE MB90357TE	MB90356ES MB90357ES	MB90356TES MB90357TES	MB90V340E-103	MB90V340E-104
CPU	F^2MC-16LX CPU					
System clock	On-chip PLL clock multiplier (×1, ×2, ×3, ×4, ×6, 1/2 when PLL stops) Minimum instruction execution time : 42 ns (oscillation clock 4 MHz, PLL × 6)					
ROM	MASK ROM 64 Kbytes :MB90356E(S), MB90356TE(S) 128 Kbytes :MB90357E(S), MB90357TE(S)				External	
RAM	4 Kbytes				30 Kbytes	
Emulator-specific power supply*	—				Yes	
Sub clock pin (X0A, X1A)	Yes		No		No	Yes
Clock supervisor	Yes					
Low voltage/CPU operation detection reset	No	Yes	No	Yes	No	
Operating voltage range	3.5 V to 5.5 V : at normal operating (not using A/D converter) 4.0 V to 5.5 V : at using A/D converter 4.5 V to 5.5 V : at using external bus				5 V ± 10%	
Operating temperature range	−40°C to +125°C				—	
Package	LQFP-64				PGA-299	
LIN-UART	2 channels				5 channels	
	Wide range of baud rate settings using a dedicated baud rate generator (reload timer) Special synchronous options for adapting to different synchronous serial protocols LIN functionality working either as master or slave LIN device					
I^2C (400 kbps)	1 channel				2 channels	
A/D converter	15 channels				24 channels	
	10-bit or 8-bit resolution Conversion time : Min 3 μs includes sample time (per one channel)					
16-bit reload timer (4 channels)	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = Machine clock frequency) Supports External Event Count function.					
16-bit free-run timer (2 channels)	Free-run Timer 0 (clock input FRCK0) corresponds to ICU 0/1. Free-run Timer 1 (clock input FRCK1) corresponds to ICU 4/5/6/7, OCU 4/5/6/7.				Free-run Timer 0 corresponds to ICU 0/1/2/3, OCU 0/1/2/3. Free-run Timer 1 corresponds to ICU 4/5/6/7, OCU 4/5/6/7.	
	Signals an interrupt when overflowing. Supports Timer Clear when a match with Output Compare (Channel 0, 4) . Operation clock frequency : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4, fsys/2^5, fsys/2^6, fsys/2^7 (fsys = Machine clock frequency)					

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3. Packages and Product Correspondence

Package	MB90V340E-101 MB90V340E-102 MB90V340E-103 MB90V340E-104	MB90351E (S) , MB90351TE (S) MB90F351E (S) , MB90F351TE (S) MB90352E (S) , MB90352TE (S) MB90F352E (S) , MB90F352TE (S) MB90356E (S) , MB90356TE (S) MB90F356E (S) , MB90F356TE (S) MB90357E (S) , MB90357TE (S) MB90F357E (S) , MB90F357TE (S)
PGA-299C-A01	◯	×
FPT-64P-M23 (12.0 mm □, 0.65 mm pitch)	×	◯
FPT-64P-M24 (10.0 mm □, 0.50 mm pitch)	×	◯

◯ : Yes, × : No

Note : Refer to “Package Dimensions” for detail of each package.

Pin No.	Pin name	I/O Circuit type*	Function
24 to 31	P00 to P07	G	General purpose I/O ports. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD00 to AD07		Input/output pins of external address data bus lower 8 bits. This function is enabled when the external bus is enabled.
	INT8 to INT15		External interrupt request input pins for INT8 to INT15
32	P10	G	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD08		Input/output pin for external bus address data bus bit 8. This function is enabled when external bus is enabled.
	TIN1		Event input pin for reload timer1
33	P11	G	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD09		Input/output pin for external bus address data bus bit 9. This function is enabled when external bus is enabled.
	TOT1		Output pin for reload timer1
34	P12	N	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD10		Input/output pin for external bus address data bus bit 10. This function is enabled when external bus is enabled.
	SIN3		Serial data input pin for UART3
	INT11R		External interrupt request input pin for INT11
35	P13	G	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD11		Input/output pin for external bus address data bus bit 11. This function is enabled when external bus is enabled.
	SOT3		Serial data output pin for UART3
36	P14	G	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD12		Input/output pin for external bus address data bus bit 12. This function is enabled when external bus is enabled.
	SCK3		Clock input/output pin for UART3
37	P15	N	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD13		Input/output pin for external bus address data bus bit 13. This function is enabled when external bus is enabled.
38	P16	G	General purpose I/O port. The register can be set to select whether to use a pull-up resistor. This function is enabled in single-chip mode.
	AD14		Input/output pin for external bus address data bus bit 14. This function is enabled when external bus is enabled.

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Please ask each crystal maker to evaluate the oscillational characteristics of the crystal and this device.

9. Turning-on sequence of power supply to A/D converter and analog inputs

Make sure to turn on the A/D converter power supply (AV_{CC}, AVRH) and analog inputs (AN0 to AN14) after turning-on the digital power supply (V_{CC}) .Turn-off the digital power after turning off the A/D converter power
supply and analog inputs. In this case, make sure that the power supply voltage does not exceed the rated voltage of the A/D converter (turning on/of the analog and digital power supplies simultaneously is acceptable).

10. Connection of unused pins of A/D converter if A/D converter is not used

Connect unused pins of A/D converter to $AV_{CC} = V_{CC}$, $AV_{SS} = AVRH = V_{SS}$.

11. Notes on energization

To prevent the internal regulator circuit from malfunctioning, set the voltage rise time during energization at
50 µs or more (0.2 V to 2.7 V) .

12. Stabilization of power supply voltage

A sudden change in the supply voltage may cause the device to malfunction even within the V_{CC} supply voltage operating range. Therefore, the V_{CC} supply voltage should be stabilized. For reference, the supply voltage should be controlled so that V_{CC} ripple variations (peak- to-peak values) at commercial frequencies (50 MHz/
60 MHz) fall below 10% of the standard V_{CC} supply voltage and the coefficient of fluctuation does not exceed 0.1 V/ms at instantaneous power switching.

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Address	Register	Abbreviation	Access	Resource name	Initial value
$0079C3_H$ to $0079DF_H$	Reserved				
$0079E0_H$	Detect Address Setting Register 0	PADR0	R/W	Address Match Detection 0	$XXXXXXXX_B$
$0079E1_H$	Detect Address Setting Register 0	PADR0	R/W		$XXXXXXXX_B$
$0079E2_H$	Detect Address Setting Register 0	PADR0	R/W		$XXXXXXXX_B$
$0079E3_H$	Detect Address Setting Register 1	PADR1	R/W		$XXXXXXXX_B$
$0079E4_H$	Detect Address Setting Register 1	PADR1	R/W		$XXXXXXXX_B$
$0079E5_H$	Detect Address Setting Register 1	PADR1	R/W		$XXXXXXXX_B$
$0079E6_H$	Detect Address Setting Register 2	PADR2	R/W		$XXXXXXXX_B$
$0079E7_H$	Detect Address Setting Register 2	PADR2	R/W		$XXXXXXXX_B$
$0079E8_H$	Detect Address Setting Register 2	PADR2	R/W		$XXXXXXXX_B$
$0079E9_H$ to $0079EF_H$	Reserved				
$0079F0_H$	Detect Address Setting Register 3	PADR3	R/W	Address Match Detection 1	$XXXXXXXX_B$
$0079F1_H$	Detect Address Setting Register 3	PADR3	R/W		$XXXXXXXX_B$
$0079F2_H$	Detect Address Setting Register 3	PADR3	R/W		$XXXXXXXX_B$
$0079F3_H$	Detect Address Setting Register 4	PADR4	R/W		$XXXXXXXX_B$
$0079F4_H$	Detect Address Setting Register 4	PADR4	R/W		$XXXXXXXX_B$
$0079F5_H$	Detect Address Setting Register 4	PADR4	R/W		$XXXXXXXX_B$
$0079F6_H$	Detect Address Setting Register 5	PADR5	R/W		$XXXXXXXX_B$
$0079F7_H$	Detect Address Setting Register 5	PADR5	R/W		$XXXXXXXX_B$
$0079F8_H$	Detect Address Setting Register 5	PADR5	R/W		$XXXXXXXX_B$
$0079F9_H$ to $007BFF_H$	Reserved				
$007C00_H$ to $007DFF_H$	Reserved for CAN controller 1. Refer to “CAN Controllers”				
$007E00_H$ to $007FFF_H$	Reserved				

Notes : ″ Initial value of “X” represents unknown value.
″ Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results reading unknown value.

11. CAN Controllers

■ Compliant with CAN standard Version2.0 Part A and Part B
- Supports tr12ansmission/reception in standard frame and extended frame formats

■ Supports transmitting of data frames by receiving remote frames

■ 16 transmitting/receiving message buffers
- 29-bit ID and 8-byte data
- Multi-level message buffer configuration

■ Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
- Two acceptance mask registers in either standard frame format or extended frame formats

■ Bit rate programmable from 10 kbps to 2 Mbps (when input clock is at 16 MHz)

List of Control Registers

Address CAN1	Register	Abbreviation	Access	Initial Value
000080_H	Message buffer enable register	BVALR	R/W	00000000_B 00000000_B
000081_H				
000082_H	Transmit request register	TREQR	R/W	00000000_B 00000000_B
000083_H				
000084_H	Transmit cancel register	TCANR	W	00000000_B 00000000_B
000085_H				
000086_H	Transmission complete register	TCR	R/W	00000000_B 00000000_B
000087_H				
000088_H	Receive complete register	RCR	R/W	00000000_B 00000000_B
000089_H				
$00008A_H$	Remote request receiving register	RRTRR	R/W	00000000_B 00000000_B
$00008B_H$				
$00008C_H$	Receive overrun register	ROVRR	R/W	00000000_B 00000000_B
$00008D_H$				
$00008E_H$	Reception interrupt enable register	RIER	R/W	00000000_B 00000000_B
$00008F_H$				

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Address CAN1	Register	Abbreviation	Access	Initial Value
$007D00_H$	Control status register	CSR	R/W, W R/W, R	$0XXXX0X1_B$ $00XXX000_B$
$007D01_H$				
$007D02_H$	Last event indicator register	LEIR	R/W	$000X0000_B$ $XXXXXXXX_B$
$007D03_H$				
$007D04_H$	Receive/transmit error counter	RTEC	R	00000000_B 00000000_B
$007D05_H$				
$007D06_H$	Bit timing register	BTR	R/W	11111111_B $X1111111_B$
$007D07_H$				
$007D08_H$	IDE register	IDER	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007D09_H$				
$007D0A_H$	Transmit RTR register	TRTRR	R/W	00000000_B 00000000_B
$007D0B_H$				
$007D0C_H$	Remote frame receive waiting register	RFWTR	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007D0D_H$				
$007D0E_H$	Transmit interrupt enable register	TIER	R/W	00000000_B 00000000_B
$007D0F_H$				
$007D10_H$	Acceptance mask select register	AMSR	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007D11_H$				
$007D12_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007D13_H$				
$007D14_H$	Acceptance mask register 0	AMR0	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007D15_H$				
$007D16_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007D17_H$				
$007D18_H$	Acceptance mask register 1	AMR1	R/W	$XXXXXXXX_B$ $XXXXXXXX_B$
$007D19_H$				
$007D1A_H$				$XXXXXXXX_B$ $XXXXXXXX_B$
$007D1B_H$				

List of Message Buffers (ID Registers)

Address CAN1	Register	Abbreviation	Access	Initial Value
$007C00_H$ to $007C1F_H$	General-purpose RAM	—	R/W	$XXXXXXXX_B$ to $XXXXXXXX_B$
$007C20_H$	ID register 0	IDR0	R/W	$XXXXXXXX_B$
$007C21_H$				$XXXXXXXX_B$
$007C22_H$				$XXXXXXXX_B$
$007C23_H$				$XXXXXXXX_B$
$007C24_H$	ID register 1	IDR1	R/W	$XXXXXXXX_B$
$007C25_H$				$XXXXXXXX_B$
$007C26_H$				$XXXXXXXX_B$
$007C27_H$				$XXXXXXXX_B$
$007C28_H$	ID register 2	IDR2	R/W	$XXXXXXXX_B$
$007C29_H$				$XXXXXXXX_B$
$007C2A_H$				$XXXXXXXX_B$
$007C2B_H$				$XXXXXXXX_B$
$007C2C_H$	ID register 3	IDR3	R/W	$XXXXXXXX_B$
$007C2D_H$				$XXXXXXXX_B$
$007C2E_H$				$XXXXXXXX_B$
$007C2F_H$				$XXXXXXXX_B$
$007C30_H$	ID register 4	IDR4	R/W	$XXXXXXXX_B$
$007C31_H$				$XXXXXXXX_B$
$007C32_H$				$XXXXXXXX_B$
$007C33_H$				$XXXXXXXX_B$
$007C34_H$	ID register 5	IDR5	R/W	$XXXXXXXX_B$
$007C35_H$				$XXXXXXXX_B$
$007C36_H$				$XXXXXXXX_B$
$007C37_H$				$XXXXXXXX_B$
$007C38_H$	ID register 6	IDR6	R/W	$XXXXXXXX_B$
$007C39_H$				$XXXXXXXX_B$
$007C3A_H$				$XXXXXXXX_B$
$007C3B_H$				$XXXXXXXX_B$
$007C3C_H$	ID register 7	IDR7	R/W	$XXXXXXXX_B$
$007C3D_H$				$XXXXXXXX_B$
$007C3E_H$				$XXXXXXXX_B$
$007C3F_H$				$XXXXXXXX_B$

(Continued)

List of Message Buffers (DLC Registers and Data Registers)

Address CAN1	Register	Abbreviation	Access	Initial Value
$007C60_H$	DLC register 0	DLCR0	R/W	$XXXXXXXX_B$
$007C61_H$				
$007C62_H$	DLC register 1	DLCR1	R/W	$XXXXXXXX_B$
$007C63_H$				
$007C64_H$	DLC register 2	DLCR2	R/W	$XXXXXXXX_B$
$007C65_H$				
$007C66_H$	DLC register 3	DLCR3	R/W	$XXXXXXXX_B$
$007C67_H$				
$007C68_H$	DLC register 4	DLCR4	R/W	$XXXXXXXX_B$
$007C69_H$				
$007C6A_H$	DLC register 5	DLCR5	R/W	$XXXXXXXX_B$
$007C6B_H$				
$007C6C_H$	DLC register 6	DLCR6	R/W	$XXXXXXXX_B$
$007C6D_H$				
$007C6E_H$	DLC register 7	DLCR7	R/W	$XXXXXXXX_B$
$007C6F_H$				
$007C70_H$	DLC register 8	DLCR8	R/W	$XXXXXXXX_B$
$007C71_H$				
$007C72_H$	DLC register 9	DLCR9	R/W	$XXXXXXXX_B$
$007C73_H$				
$007C74_H$	DLC register 10	DLCR10	R/W	$XXXXXXXX_B$
$007C75_H$				
$007C76_H$	DLC register 11	DLCR11	R/W	$XXXXXXXX_B$
$007C77_H$				
$007C78_H$	DLC register 12	DLCR12	R/W	$XXXXXXXX_B$
$007C79_H$				
$007C7A_H$	DLC register 13	DLCR13	R/W	$XXXXXXXX_B$
$007C7B_H$				
$007C7C_H$	DLC register 14	DLCR14	R/W	$XXXXXXXX_B$
$007C7D_H$				
$007C7E_H$	DLC register 15	DLCR15	R/W	$XXXXXXXX_B$
$007C7F_H$				

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13.3 DC Characteristics

(T_A = −40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage (At V_{CC} = 5 V ± 10%)	V_{IHS}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Pin inputs if CMOS hysteresis input levels are selected (except P12, P15, P44, P45, P50)
	V_{IHA}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Pin inputs if Automotive input levels are selected
	V_{IHT}	—	—	2.0	—	V_{CC} + 0.3	V	Pin inputs if TTL input levels are selected
	V_{IHS}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P12, P15, P50 inputs if CMOS input levels are selected
	V_{IHI}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P44, P45 inputs if CMOS hysteresis input levels are selected
	V_{IHR}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{IHM}	—	—	V_{CC} − 0.3	—	V_{CC} + 0.3	V	MD input pin
"L" level input voltage (At V_{CC} = 5 V ± 10%)	V_{ILS}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	Pin inputs if CMOS hysteresis input levels are selected (except P12, P15, P44, P45, P50)
	V_{ILA}	—	—	V_{SS} − 0.3	—	0.5 V_{CC}	V	Pin inputs if Automotive input levels are selected
	V_{ILT}	—	—	V_{SS} − 0.3	—	0.8	V	Pin inputs if TTL input levels are selected
	V_{ILS}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P12, P15, P50 inputs if CMOS input levels are selected
	V_{ILI}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P44, P45 inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{ILM}	—	—	V_{SS} − 0.3	—	V_{SS} + 0.3	V	MD input pin
Output "H" voltage	V_{OH}	Normal outputs	V_{CC} = 4.5 V, I_{OH} = −4.0 mA	V_{CC} − 0.5	—	—	V	
Output "H" voltage	V_{OHI}	I^2C current outputs	V_{CC} = 4.5 V, I_{OH} = −3.0 mA	V_{CC} − 0.5	—	—	V	

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(T_A = −40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Sym-bol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Output “L” voltage	V_{OL}	Normal outputs	V_{CC} = 4.5 V, I_{OL} = 4.0 mA	—	—	0.4	V	
Output “L” voltage	V_{OLI}	I^2C current outputs	V_{CC} = 4.5 V, I_{OL} = 3.0 mA	—	—	0.4	V	
Input leak current	I_{IL}	—	V_{CC} = 5.5 V, V_{SS} < V_I < V_{CC}	− 1	—	+ 1	µA	
Pull-up resistance	R_{UP}	P00 to P07, P10 to P17, P20 to P25, P30 to P37, $\overline{RST}$	—	25	50	100	kΩ	
Pull-down resistance	R_{DOWN}	MD2	—	25	50	100	kΩ	Except Flash memory devices
Power supply current	I_{CC}	V_{CC}	V_{CC} = 5.0 V, Internal frequency : 24 MHz, At normal operation.	—	48	60	mA	
			V_{CC} = 5.0 V, Internal frequency : 24 MHz, At writing Flash memory.	—	53	65	mA	Flash memory devices
			V_{CC} = 5.0 V, Internal frequency : 24 MHz, At erasing Flash memory.	—	58	70	mA	Flash memory devices
	I_{CCS}		V_{CC} = 5.0 V, Internal frequency : 24 MHz, At Sleep mode.	—	25	35	mA	
	I_{CTS}		V_{CC} = 5.0 V, Internal frequency : 2 MHz, At Main Timer mode	—	0.3	0.8	mA	Devices without “T”-suffix
				—	0.4	1.0	mA	Devices with “T”-suffix
	I_{CTSPLL} [6]		V_{CC} = 5.0 V, Internal frequency : 24 MHz, At PLL Timer mode, external frequency = 4 MHz	—	4	7	mA	

(Continued)

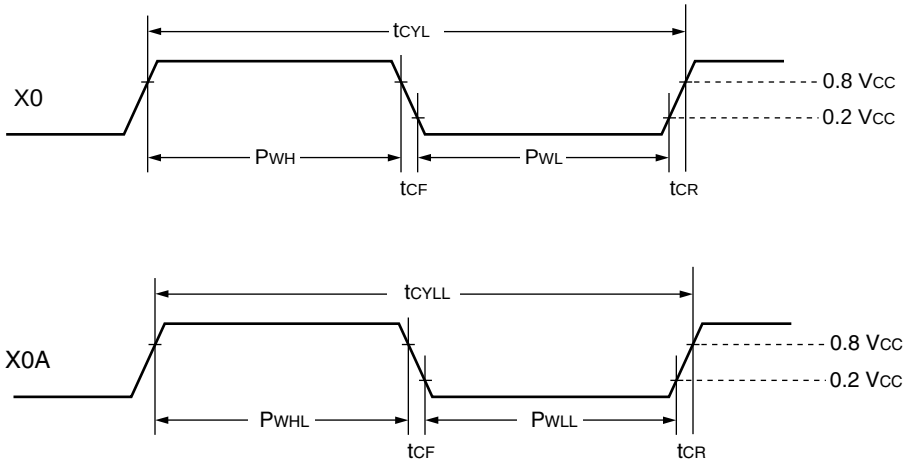
(Continued)

(T_A = –40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Internal operating clock frequency (machine clock)	f_{CP}	—	1.5	—	24	MHz	When using main clock
	f_{CPL}	—	—	8.192	50	kHz	When using sub clock
Internal operating clock cycle time (machine clock)	t_{CP}	—	41.67	—	666	ns	When using main clock
	t_{CPL}	—	20	122.1	—	µs	When using sub clock

*: The limitation is in the range of the clock frequency when PLL is used. Use within the range in graph of "· PLL guaranteed operation range External clock frequency and internal operation clock frequency".

- Clock Timing

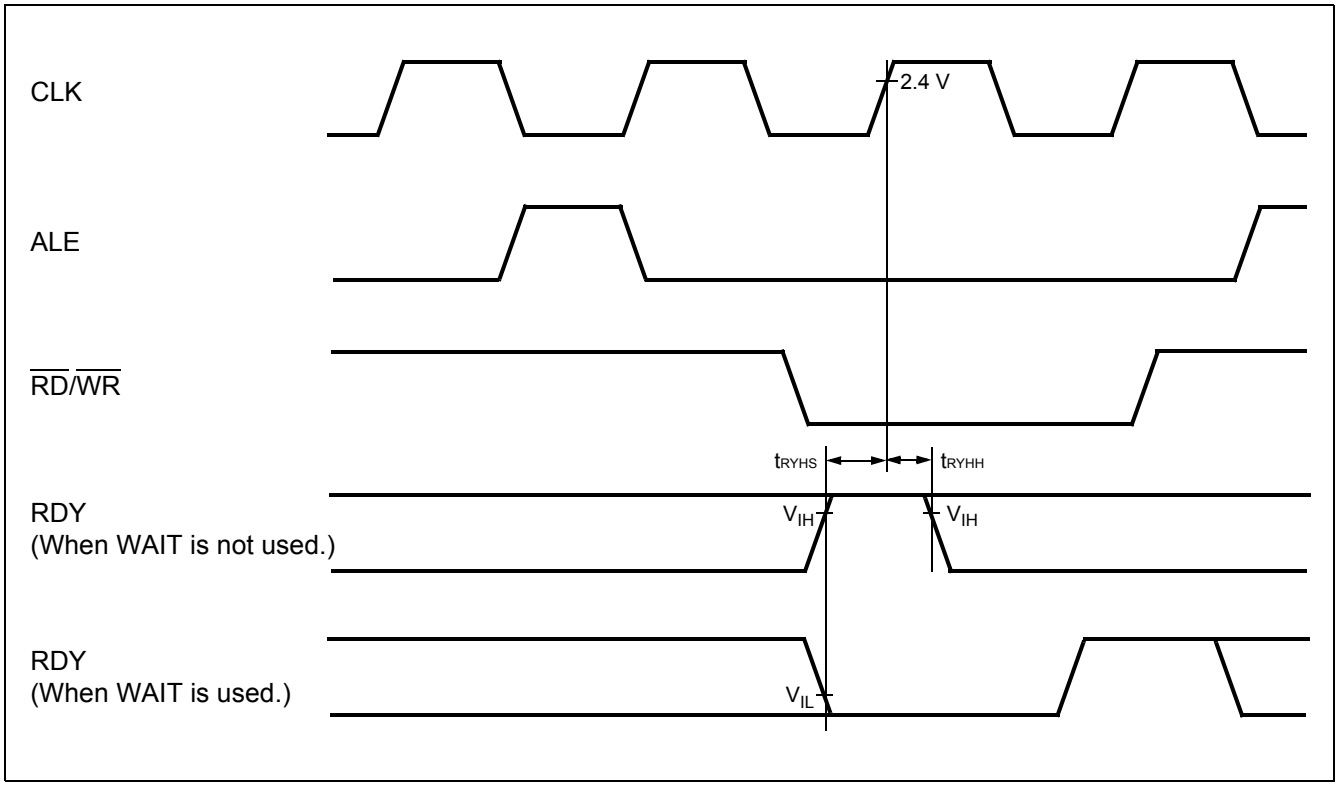


13.4.7 Ready Input Timing

(T_A = –40°C to +105°C, V_{CC} = 5.0 V ± 10 %, V_{SS} = 0.0 V, f_{CP} ≤ 24 MHz)

Parameter	Symbol	Pin	Condition	Value		Units	Remarks
				Min	Max		
RDY set-up time	t_{RYHS}	RDY	—	45	—	ns	f_{CP} = 16 MHz
				32	—	ns	f_{CP} = 24 MHz
RDY hold time	t_{RYHH}	RDY		0	—	ns	

Note : If the RDY set-up time is insufficient, use the auto-ready function.



13.4.9 LIN-UART2/3

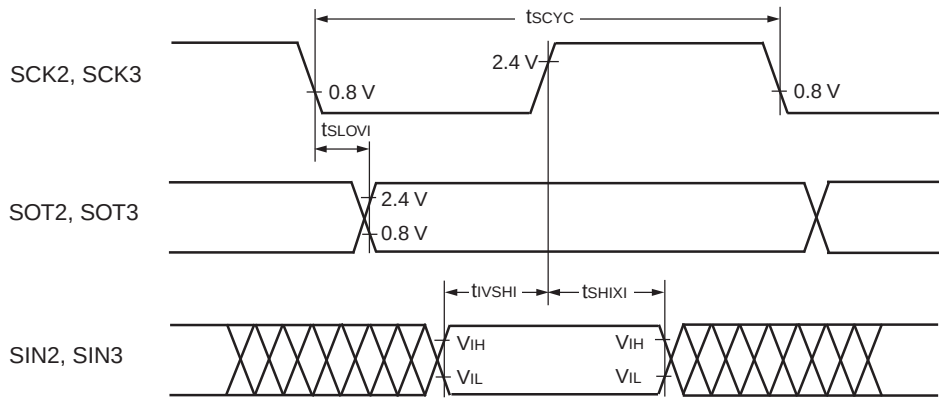
■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 0

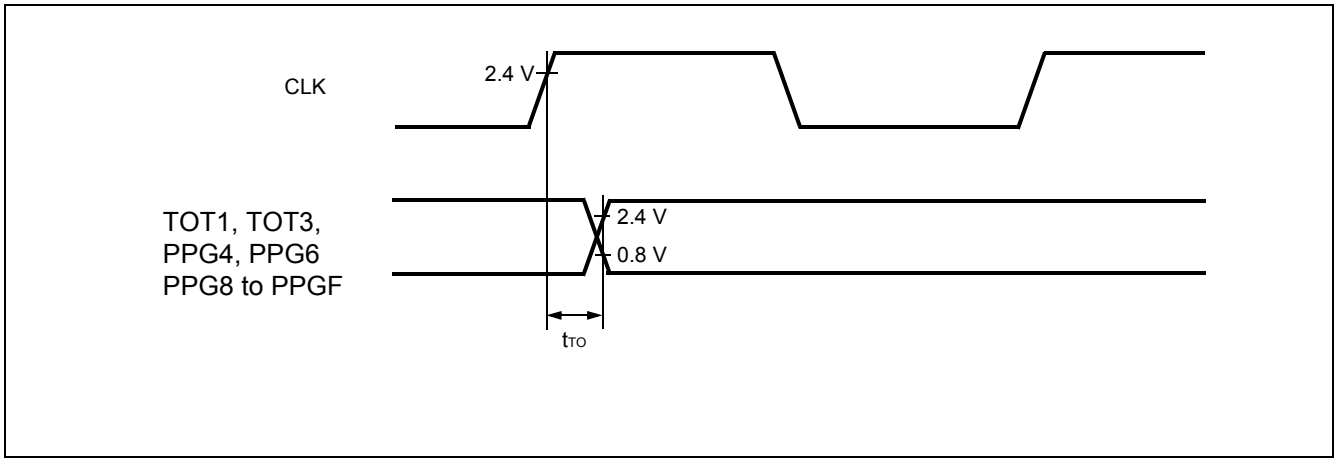
(T_A = –40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK2, SCK3	Internal shift clock mode output pins are CL = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCK2, SCK3 SOT2, SOT3		–50	+50	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK2, SCK3 SIN2, SIN3		t_{CP} + 80	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXI}	SCK2, SCK3 SIN2, SIN3		0	—	ns
Serial clock “L” pulse width	t_{SHSL}	SCK2, SCK3	External shift clock mode output pins are CL = 80 pF + 1 TTL.	3 t_{CP} - t_R	—	ns
Serial clock “H” pulse width	t_{SLSH}	SCK2, SCK3		t_{CP} + 10	—	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCK2, SCK3 SOT2, SOT3		—	2 t_{CP} + 60	ns
Valid SIN → SCK ↑	t_{IVSHE}	SCK2, SCK3 SIN2, SIN3		30	—	ns
SCK ↑ → Valid SIN hold time	t_{SHIXE}	SCK2, SCK3 SIN2, SIN3		t_{CP} + 30	—	ns
SCK fall time	t_F	SCK2, SCK3		—	10	ns
SCK rise time	t_R	SCK2, SCK3		—	10	ns

Notes :
- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.

″ Internal Shift Clock Mode





13.4.13 I^2C Timing

(T_A = −40°C to +125°C, V_{CC} = AV_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Condition	Standard-mode		Fast-mode*4		Unit
			Min	Max	Min	Max	
SCL clock frequency	f_{SCL}	R = 1.7 kΩ, C = 50 pF*1	0	100	0	400	kHz
Hold time for (repeated) START condition SDA ↓ → SCL ↓	t_{HDSTA}		4.0	—	0.6	—	µs
"L" width of the SCL clock	t_{LOW}		4.7	—	1.3	—	µs
"H" width of the SCL clock	t_{HIGH}		4.0	—	0.6	—	µs
Set-up time for a repeated START condition SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	0.6	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*2	0	0.9*3	µs
Data set-up time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250*5	—	100*5	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t_{SUSTO}		4.0	—	0.6	—	µs
Bus free time between STOP condition and START condition	t_{BUS}		4.7	—	1.3	—	µs

*1 : R,C : Pull-up resistor and load capacitor of the SCL and SDA lines.

*2 : The maximum t_{HDDAT} has to meet at least that the device does not exceed the "L" width (t_{LOW}) of the SCL signal.

*3 : A Fast-mode I^2C -bus device can be used in a Standard-mode I^2C-bus system, but the requirement $t_{SUDAT} \geq 250$ ns must be met.

*4 : For use at over 100 kHz, set the machine clock to at least 6 MHz.

*5 : Refer to "• Note of SDA, SCL set-up time".

13.5 A/D Converter

(T_A = −40°C to +125°C, 3.0 V ≤ AVRH, V_{CC} = AV_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	—	—	—	—	10	bit	
Total error	—	—	—	—	±3.0	LSB	
Nonlinearity error	—	—	—	—	±2.5	LSB	
Differential nonlinearity error	—	—	—	—	±1.9	LSB	
Zero reading voltage	V_{OT}	AN0 to AN14	AV_{SS} − 1.5×LSB	AV_{SS} + 0.5×LSB	AV_{SS} + 2.5×LSB	V	
Full scale reading voltage	V_{FST}	AN0 to AN14	AVRH − 3.5×LSB	AVRH − 1.5×LSB	AVRH + 0.5×LSB	V	
Compare time	—	—	1.0	—	16500	µs	4.5 V ≤ AV_{CC} ≤ 5.5 V
			2.0				4.0 V ≤ AV_{CC} < 4.5 V
Sampling time	—	—	0.5	—	×	µs	4.5 V ≤ AV_{CC} ≤ 5.5 V
			1.2				4.0 V ≤ AV_{CC} < 4.5 V
Analog port input current	I_{AIN}	AN0 to AN14	− 0.3	—	+ 0.3	µA	
Analog input voltage range	V_{AIN}	AN0 to AN14	AV_{SS}	—	AVRH	V	
Reference voltage range	—	AVRH	AV_{SS} + 2.7	—	AV_{CC}	V	
Power supply current	I_A	AV_{CC}	—	3.5	7.5	mA	
	I_{AH}	AV_{CC}	—	—	5	µA	*
Reference voltage supply current	I_R	AVRH	—	600	900	µA	
	I_{RH}	AVRH	—	—	5	µA	*
Offset between channels	—	AN0 to AN14	—	—	4	LSB	

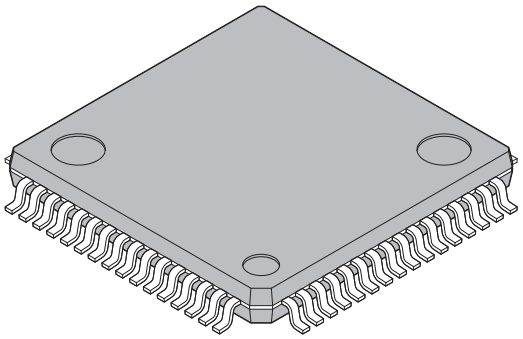
* : If A/D converter is not operating, a current when CPU is stopped is applicable (V_{CC} = AV_{CC} = AVRH = 5.0 V) .

Notes on A/D Converter Section

■ About the external impedance of the analog input and its sampling time

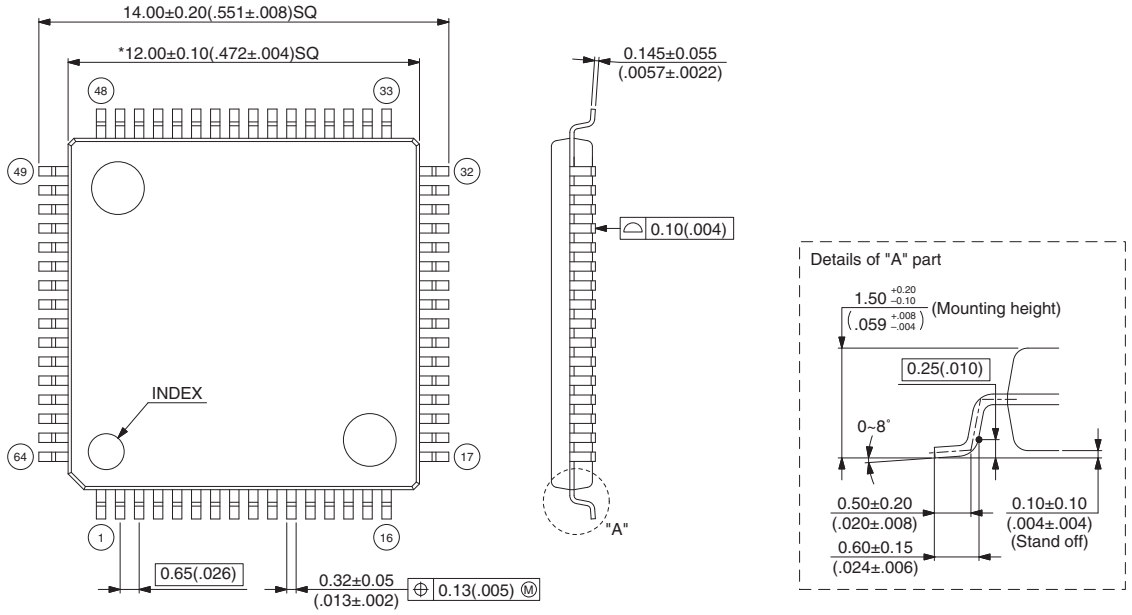
A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting
A/D conversion precision. Therefore to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. Also if the sampling time cannot be sufficient, connect a capacitor of about 0.1 µF to the analog input pin.

14.1 Package Dimensions

64-pin plastic LQFP		
	Lead pitch	0.65 mm
	Package width × package length	12.0 × 12.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Code (Reference)	P-LFQFP64-12×12-0.65
(FPT-64P-M23)		

64-pin plastic LQFP
(FPT-64P-M23)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values

(Continued)

15. Major Changes

Page	Section	Change Results
—	—	The following names are changed. UART → LIN-UART 16-bit I/O timer → 16-bit free-run timer
26	Handling Devices	Added the section ”13. Serial Communication”.
51	Electrical Characteristics Absolute Maximum Ratings	Changed the maximum value of power consumption.
63	Electrical Characteristics AC Characteristics	Changed the "(4) Clock Output Timing". Changed the Minimum value of cycle time. (41.76 → 41.67)
69 to 73		Changed the notation of “(9) LIN-UART”.
78	A/D Converter	Changed the notation of “Zero reading voltage” and “full scale reading voltage”.
85	Ordering Information	Changed the part number; MB90V340E-101 → MB90V340E-101CR MB90V340E-102 → MB90V340E-102CR MB90V340E-103 → MB90V340E-103CR MB90V340E-104 → MB90V340E-104CR

NOTE: Please see “Document History” about later revised information.

Document History

Document Title: MB90350E Series F^{2}MC-16LX 16-bit Microcontrollers Document Number: 002-04493				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	—	AKIH	10/12/2006	Migrated to Cypress and assigned document number 002-04993. No change to document contents or format.
*A	5193077	AKIH	04/07/2016	Updated to Cypress template