Infineon Technologies - MB90F357TESPMC1-GE1 Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	24MHz
Connectivity	CANbus, EBI/EMI, I²C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, WDT
Number of I/O	51
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	A/D 15x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f357tespmc1-ge1

■ MASK ROM products/Evaluation products

Parameter \ Part Number	MB90351E MB90352E	MB90351TE MB90352TE	MB90351ES MB90352ES	MB90351TES MB90352TES	MB90V340E-101	MB90V340E-102
Type	MASK ROM products				Evaluation products	
CPU	F^2MC-16LX CPU					
System clock	PLL clock multiplication circuit (×1, ×2, ×3, ×4, ×6, 1/2 when PLL stops) Minimum instruction execution time : 42 ns (oscillation clock 4 MHz, PLL × 6)					
ROM	MASK ROM 64 Kbytes : MB90351E(S), MB90351TE(S) 128 Kbytes : MB90352E(S), MB90352TE(S)				External	
RAM	4 Kbytes				30 Kbytes	
Emulator-specific power supply*	—				Yes	
Sub clock pin (X0A, X1A) (Max 100 kHz)	Yes		No		No	Yes
Clock supervisor	No					
Low voltage/CPU operation detection reset	No	Yes	No	Yes	No	
Operating voltage range	3.5 V to 5.5 V : at normal operating (not using A/D converter) 4.0 V to 5.5 V : at using A/D converter 4.5 V to 5.5 V : at using external bus				5 V ± 10%	
Operating temperature range	−40°C to +125°C				—	
Package	LQFP-64				PGA-299	
LIN-UART	2 channels				5 channels	
	Wide range of baud rate settings using a dedicated baud rate generator (reload timer) Special synchronous options for adapting to different synchronous serial protocols LIN functionality working either as master or slave LIN device					
I^2C (400 kbps)	1 channel				2 channels	
A/D converter	15 channels				24 channels	
	10-bit or 8-bit resolution Conversion time : Min 3 μs includes sample time (per one channel)					
16-bit reload timer	2 channels				4 channels	
	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = Machine clock frequency) Supports External Event Count function.					
16-bit free-run timer (2 channels)	Free-run Timer 0 (clock input FRCK0) corresponds to ICU0/1. Free-run Timer 1 (clock input FRCK1) corresponds to ICU4/5/6/7, OCU4/5/6/7.				Free-run Timer 0 corresponds to ICU0/1/2/3, OCU0/1/2/3. Free-run Timer 1 corresponds to ICU4/5/6/7, OCU4/5/6/7.	
	Signals an interrupt when overflowing. Supports Timer Clear when it matches Output Compare (ch.0, ch.4) . Operation clock frequency : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4, fsys/2^5, fsys/2^6, fsys/2^7 (fsys = Machine clock frequency)					

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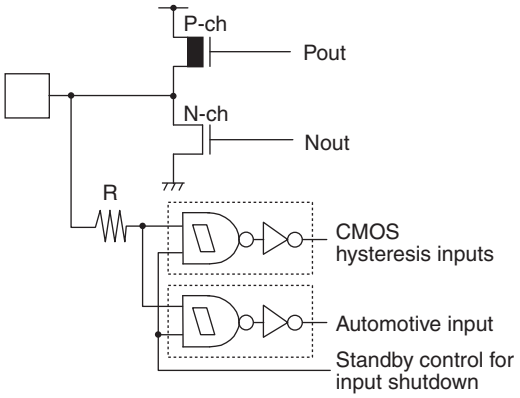
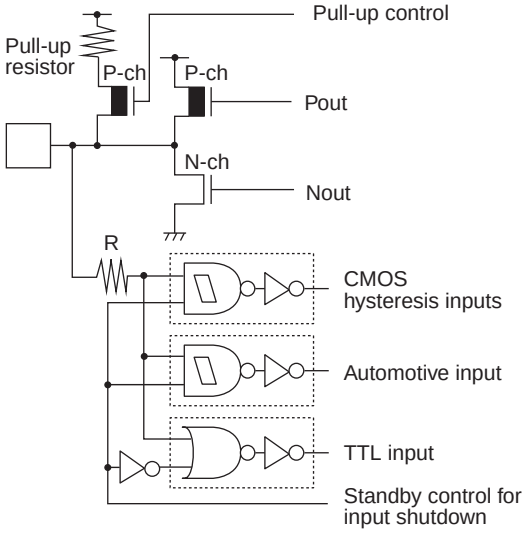
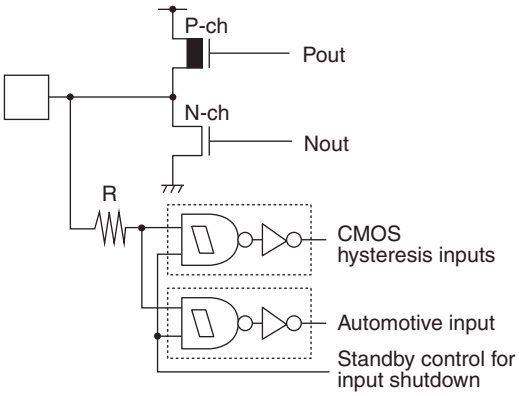
Parameter \ Part Number	MB90F356E MB90F357E	MB90F356TE MB90F357TE	MB90F356ES MB90F357ES	MB90F356TES MB90F357TES
16-bit input capture	6 channels			
	Retains 16-bit free-run timer value by (rising edge, falling edge or rising & falling edge), signals an interrupt.			
8/16-bit programmable pulse generator	6 channels (16-bit)/10 channels (8-bit) 8-bit reload counters × 12 8-bit reload registers for L pulse width×12 8-bit reload registers for H pulse width×12			
	Supports 8-bit and 16-bit operation modes. A pair of 8-bit reload counters can be configured as one 16-bit reload counter or as 8-bit prescaler + 8-bit reload counter. Operation clock frequency : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4 or 128 μs@fosc = 4 MHz (fsys = Machine clock frequency, fosc = Oscillation clock frequency)			
CAN interface	1 channel			
	Conforms to CAN Specification Version 2.0 Part A and B. Automatic re-transmission in case of error Automatic transmission responding to Remote Frame Prioritized 16 message buffers for data and ID Supports multiple messages. Flexible configuration of acceptance filtering : Full bit compare/Full bit mask/Two partial bit masks Supports up to 1 Mbps.			
External interrupt	8 channels			
	Can be used rising edge, falling edge, starting up by H/L level input, external interrupt, extended intelligent I/O services (EI^{2}OS) and DMA.			
D/A converter	—			
I/O ports	Virtually all external pins can be used as general purpose I/O port. All push-pull outputs Bit-wise settable as input/output or peripheral module signal Settable as CMOS schmitt trigger/ automotive inputs TTL input level settable for external bus (only for external bus pin)			
Flash memory	Supports automatic programming, Embedded Algorithm Write/Erase/Erase-Suspend/Resume commands A flag indicating completion of the algorithm Number of erase cycles : 10000 times Data retention time : 20 years Boot block configuration Erase can be performed on each block. Block protection with external programming voltage Flash Security Feature for protecting the content of the Flash (MB90F357x only)			
Corresponding EVA name	MB90V340E-104		MB90V340E-103	

* : It is setting of Jumper switch (TOOL VCC) when Emulator (MB2147-01) is used.
Please refer to the Emulator hardware manual about details.

Type	Circuit	Remarks
F		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = −4 mA) ■ CMOS hysteresis inputs (With input shutdown function when is standby) ■ Automotive input (With the standby-time input shutdown function)
G		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = −4 mA) ■ CMOS hysteresis inputs (With the standby-time input shutdown function) ■ Automotive input (With the standby-time input shutdown function) ■ TTL input (With the standby-time input shutdown function) ■ Programmable pull-up resistor: approx. 50 kΩ
H		■ CMOS level output (I_{OL} = 3 mA, I_{OH} = −3 mA) ■ CMOS hysteresis inputs (With the standby-time input shutdown function) ■ Automotive input (With the standby-time input shutdown function)

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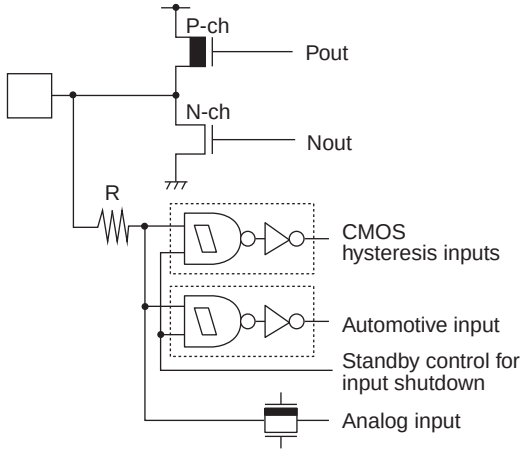
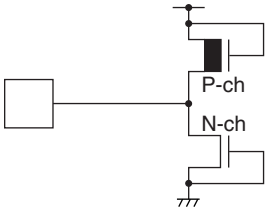
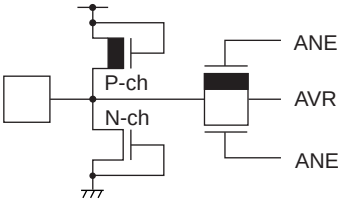
Type	Circuit	Remarks
I		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = −4 mA) ■ CMOS hysteresis inputs (With the standby-time input shutdown function) ■ Automotive input (With the standby-time input shutdown function) ■ Analog input for A/D converter
K		Protection circuit for power supply input
L		■ With the protection circuit of A/D converter reference voltage power input pin ■ Flash memory devices do not have a protection circuit against V_{CC} for pin AVRH.

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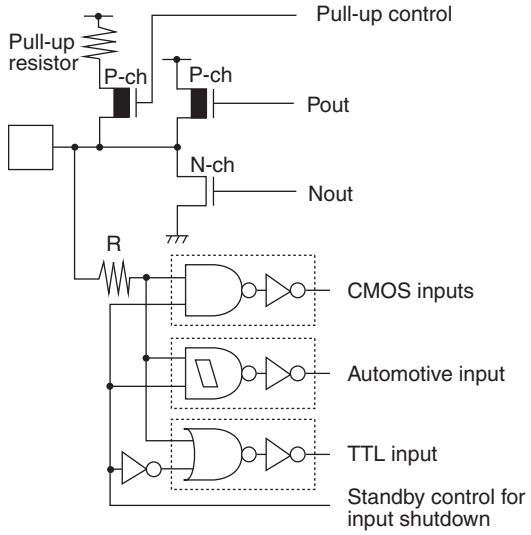
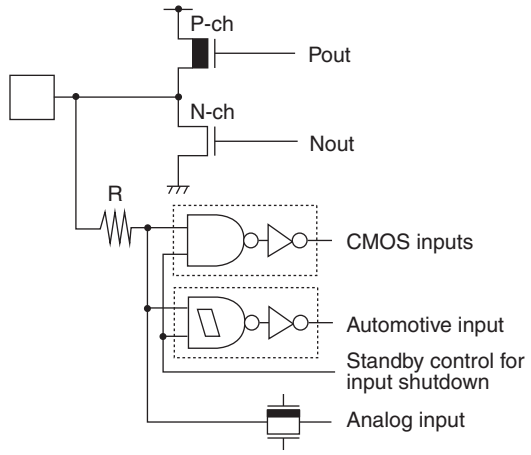
Type	Circuit	Remarks
N		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = −4 mA) ■ CMOS inputs (With the standby-time input shutdown function) ■ Automotive input (With the standby-time input shutdown function) ■ TTL input (With the standby-time input shutdown function) ■ Programmable pull-up resistor: approx. 50 kΩ
O		■ CMOS level output (I_{OL} = 4 mA, I_{OH} = −4 mA) ■ CMOS inputs (With the standby-time input shutdown function) ■ Automotive input (With the standby-time input shutdown function) ■ Analog input for A/D converter

7. Handling Devices

1. Preventing latch-up

CMOS IC may suffer latch-up under the following conditions :

■A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.

■A voltage higher than the rated voltage is applied between V_{CC} and V_{SS} pins.

■The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current drastically, causing thermal damage to the device.

For the same reason, also be careful not to let the analog power-supply voltage (AV_{CC}, AVRH) exceed the digital power-supply voltage (V_{CC}) .

2. Treatment of unused pins

Leaving unused input pins open may result in misbehavior or latch up and possible permanent damage of the device. Therefore they must be pulled up or pulled down through resistors. In this case those resistors should be more than 2 kΩ.

Unused I/O pins should be set to the output state and can be left open, or the input state with the above described connection.

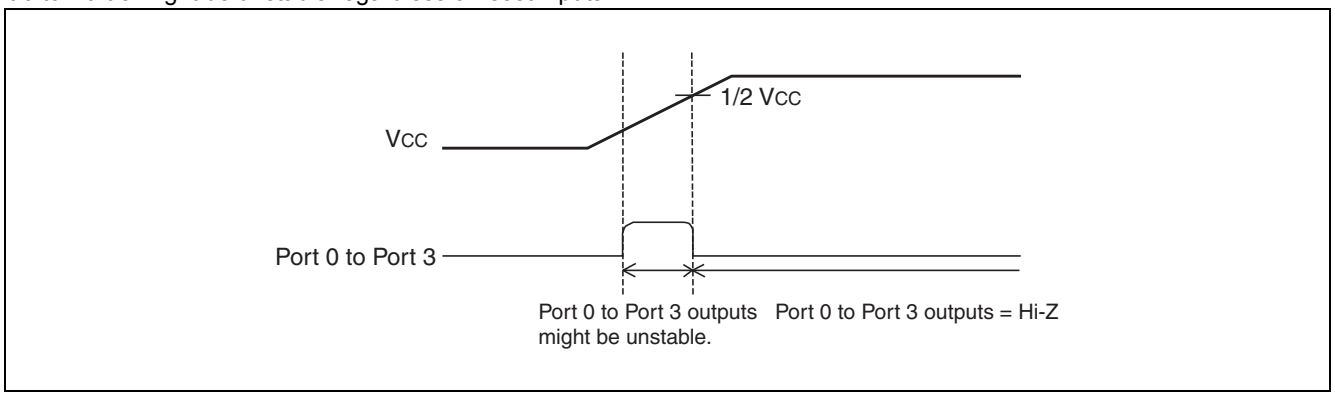
13. Serial Communication

There is a possibility to receive wrong data due to the noise or other causes on the serial communication. Therefore, design a printed circuit board so as to avoid noise.

Retransmit the data if an error occurs because of applying the checksum to the last data in consideration of receiving wrong data due to the noise.

14. Port 0 to port 3 output during power-on (External-bus mode)

As shown below, when power is turned on in external-bus mode, there is a possibility that output signal of Port 0 to Port 3 might be unstable regardless of reset inputs.



15. Setting using CAN function

To use CAN function, please set “1” to DIRECT bit of CAN direct mode register (CDMR).

16. Flash security function

The security byte is located in the area of the Flash memory. If protection code 01_H is written in the security byte, the Flash memory is in the protected state by security.
Therefore please do not write 01_H in this address if you do not use the security function.
Please refer to following table for the address of the security byte.

Product name	Flash memory size	Address for security bit
MB90F352E(S) MB90F352TE(S) MB90F357E(S) MB90F357TE(S)	Embedded 1 Mbit Flash memory	$FE0001_H$

17. Operation with T_A = +105°C or more

If used exceeding $T_A = +105°C$, please contact Cypress sales representatives for reliability limitations.

18. Low voltage/CPU operation reset circuit

The low voltage detection reset circuit is a function that monitors power supply voltage in order to detect when a voltage drops below a given voltage level. When a low voltage condition is detected, an internal reset signal is generated.
The CPU operation detection reset circuit is a 20-bit counter that uses oscillation as a count clock and generates an internal reset signal if not cleared within a given time after startup.

(1) Low voltage detection reset circuit

Detection voltage
4.0 V ± 0.3 V

When a low voltage condition is detected, the low voltage detection flag (LVRC : LVRF) is set to “1” and an internal reset signal is output.
Because the low voltage detection reset circuit continues to operate even in stop mode, detection of a low voltage condition generates an internal reset and releases stop mode.

10. I/O Map

Address	Register	Abbreviation	Access	Resource name	Initial value
000000_H	Port 0 Data Register	PDR0	R/W	Port 0	$XXXXXXXX_B$
000001_H	Port 1 Data Register	PDR1	R/W	Port 1	$XXXXXXXX_B$
000002_H	Port 2 Data Register	PDR2	R/W	Port 2	$XXXXXXXX_B$
000003_H	Port 3 Data Register	PDR3	R/W	Port 3	$XXXXXXXX_B$
000004_H	Port 4 Data Register	PDR4	R/W	Port 4	$XXXXXXXX_B$
000005_H	Port 5 Data Register	PDR5	R/W	Port 5	$XXXXXXXX_B$
000006_H	Port 6 Data Register	PDR6	R/W	Port 6	$XXXXXXXX_B$
000007_H to $00000A_H$	Reserved				
$00000B_H$	Port 5 Analog Input Enable Register	ADER5	R/W	Port 5, A/D	11111111_B
$00000C_H$	Port 6 Analog Input Enable Register	ADER6	R/W	Port 6, A/D	11111111_B
$00000D_H$	Reserved				
$00000E_H$	Input Level Select Register 0	ILSR0	R/W	Ports	00000000_B
$00000F_H$	Input Level Select Register 1	ILSR1	R/W	Ports	00000000_B
000010_H	Port 0 Direction Register	DDR0	R/W	Port 0	00000000_B
000011_H	Port 1 Direction Register	DDR1	R/W	Port 1	00000000_B
000012_H	Port 2 Direction Register	DDR2	R/W	Port 2	$XX000000_B$
000013_H	Port 3 Direction Register	DDR3	R/W	Port 3	00000000_B
000014_H	Port 4 Direction Register	DDR4	R/W	Port 4	$XX000000_B$
000015_H	Port 5 Direction Register	DDR5	R/W	Port 5	$X0000000_B$
000016_H	Port 6 Direction Register	DDR6	R/W	Port 6	00000000_B
000017_H to 000019_H	Reserved				
$00001A_H$	SIN input Level Setting Register	DDRA	W	UART2, UART3	$X00XXXXX_B$
$00001B_H$	Reserved				
$00001C_H$	Port 0 Pull-up Control Register	PUCR0	R/W	Port 0	00000000_B
$00001D_H$	Port 1 Pull-up Control Register	PUCR1	R/W	Port 1	00000000_B
$00001E_H$	Port 2 Pull-up Control Register	PUCR2	R/W	Port 2	00000000_B
$00001F_H$	Port 3 Pull-up Control Register	PUCR3	R/W	Port 3	00000000_B
000020_H to 000037_H	Reserved				

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List of Message Buffers (DLC Registers and Data Registers)

Address CAN1	Register	Abbreviation	Access	Initial Value
$007C60_H$	DLC register 0	DLCR0	R/W	$XXXXXXXX_B$
$007C61_H$				
$007C62_H$	DLC register 1	DLCR1	R/W	$XXXXXXXX_B$
$007C63_H$				
$007C64_H$	DLC register 2	DLCR2	R/W	$XXXXXXXX_B$
$007C65_H$				
$007C66_H$	DLC register 3	DLCR3	R/W	$XXXXXXXX_B$
$007C67_H$				
$007C68_H$	DLC register 4	DLCR4	R/W	$XXXXXXXX_B$
$007C69_H$				
$007C6A_H$	DLC register 5	DLCR5	R/W	$XXXXXXXX_B$
$007C6B_H$				
$007C6C_H$	DLC register 6	DLCR6	R/W	$XXXXXXXX_B$
$007C6D_H$				
$007C6E_H$	DLC register 7	DLCR7	R/W	$XXXXXXXX_B$
$007C6F_H$				
$007C70_H$	DLC register 8	DLCR8	R/W	$XXXXXXXX_B$
$007C71_H$				
$007C72_H$	DLC register 9	DLCR9	R/W	$XXXXXXXX_B$
$007C73_H$				
$007C74_H$	DLC register 10	DLCR10	R/W	$XXXXXXXX_B$
$007C75_H$				
$007C76_H$	DLC register 11	DLCR11	R/W	$XXXXXXXX_B$
$007C77_H$				
$007C78_H$	DLC register 12	DLCR12	R/W	$XXXXXXXX_B$
$007C79_H$				
$007C7A_H$	DLC register 13	DLCR13	R/W	$XXXXXXXX_B$
$007C7B_H$				
$007C7C_H$	DLC register 14	DLCR14	R/W	$XXXXXXXX_B$
$007C7D_H$				
$007C7E_H$	DLC register 15	DLCR15	R/W	$XXXXXXXX_B$
$007C7F_H$				

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12. Interrupt Factors, Interrupt Vectors, Interrupt Control Register

Interrupt cause	EI^{2}OS corresponding	DMA ch number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
Reset	N	—	#08	FFFFDC$_H$	—	—
INT9 instruction	N	—	#09	FFFFD8$_H$	—	—
Exception	N	—	#10	FFFFD4$_H$	—	—
Reserved	N	—	#11	FFFFD0$_H$	ICR00	0000B0$_H$
Reserved	N	—	#12	FFFFCC$_H$		
CAN 1 RX / Input Capture 6	Y1	—	#13	FFFFC8$_H$	ICR01	0000B1$_H$
CAN 1 TX/NS / Input Capture 7	Y1	—	#14	FFFFC4$_H$		
I^{2}C	N	—	#15	FFFFC0$_H$	ICR02	0000B2$_H$
Reserved	N	—	#16	FFFFBC$_H$		
16-bit Reload Timer 0	Y1	0	#17	FFFFB8$_H$	ICR03	0000B3$_H$
16-bit Reload Timer 1	Y1	1	#18	FFFFB4$_H$		
16-bit Reload Timer 2	Y1	2	#19	FFFFB0$_H$	ICR04	0000B4$_H$
16-bit Reload Timer 3	Y1	—	#20	FFFFAC$_H$		
PPG 4/5	N	—	#21	FFFFA8$_H$	ICR05	0000B5$_H$
PPG 6/7	N	—	#22	FFFFA4$_H$		
PPG 8/9/C/D	N	—	#23	FFFFA0$_H$	ICR06	0000B6$_H$
PPG A/B/E/F	N	—	#24	FFFF9C$_H$		
Timebase Timer	N	—	#25	FFFF98$_H$	ICR07	0000B7$_H$
External Interrupt 8 to 11	Y1	3	#26	FFFF94$_H$		
Watch Timer	N	—	#27	FFFF90$_H$	ICR08	0000B8$_H$
External Interrupt 12 to 15	Y1	4	#28	FFFF8C$_H$		
A/D Converter	Y1	5	#29	FFFF88$_H$	ICR09	0000B9$_H$
Free-run Timer 0 / free-run Timer 1	N	—	#30	FFFF84$_H$		
Input Capture 4/5	Y1	6	#31	FFFF80$_H$	ICR10	0000BA$_H$
Output Compare 4/5	Y1	7	#32	FFFF7C$_H$		
Input Capture 0/1	Y1	8	#33	FFFF78$_H$	ICR11	0000BB$_H$
Output Compare 6/7	Y1	9	#34	FFFF74$_H$		
Reserved	N	10	#35	FFFF70$_H$	ICR12	0000BC$_H$
Reserved	N	11	#36	FFFF6C$_H$		
UART 3 RX	Y2	12	#37	FFFF68$_H$	ICR13	0000BD$_H$
UART 3 TX	Y1	13	#38	FFFF64$_H$		

(Continued)

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Interrupt cause	EI^{2}OS corresponding	DMA ch number	Interrupt vector		Interrupt control register	
			Number	Address	Number	Address
UART 2 RX	Y2	14	#39	$FFFF60_H$	ICR14	$0000BE_H$
UART 2 TX	Y1	15	#40	$FFFF5C_H$		
Flash Memory	N	—	#41	$FFFF58_H$	ICR15	$0000BF_H$
Delayed Interrupt	N	—	#42	$FFFF54_H$		

Y1 : Usable

Y2 : Usable, with EI^{2}OS stop function

N : Unusable

Notes :
- The peripheral resources sharing the ICR register have the same interrupt level.
- When the peripheral resources sharing the ICR register use extended intelligent I/O service, only one can use EI^{2}OS at a time.
- When either of the two peripheral resources sharing the ICR register specifies EI^{2}OS, the other one cannot use interrupts.

13. Electrical Characteristics

13.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	V_{SS} − 0.3	V_{SS} + 6.0	V	
	AV_{CC}	V_{SS} − 0.3	V_{SS} + 6.0	V	$V_{CC} = AV_{CC}$*2
	AVRH	V_{SS} − 0.3	V_{SS} + 6.0	V	$AV_{CC} \geq AVRH$*2
Input voltage*1	V_I	V_{SS} − 0.3	V_{SS} + 6.0	V	*3
Output voltage*1	V_O	V_{SS} − 0.3	V_{SS} + 6.0	V	*3
Maximum Clamp Current	I_{CLAMP}	−4.0	+4.0	mA	*5
Total Maximum Clamp Current	$\Sigma\lvert I_{CLAMP}\rvert$	—	40	mA	*5
“L” level maximum output current	I_{OL}	—	15	mA	*4
“L” level average output current	I_{OLAV}	—	4	mA	*4
“L” level maximum overall output current	ΣI_{OL}	—	100	mA	*4
“L” level average overall output current	ΣI_{OLAV}	—	50	mA	*4
“H” level maximum output current	I_{OH}	—	−15	mA	*4
“H” level average output current	I_{OHAV}	—	−4	mA	*4
“H” level maximum overall output current	ΣI_{OH}	—	−100	mA	*4
“H” level average overall output current	ΣI_{OHAV}	—	−50	mA	*4
Power consumption	P_D	—	454	mW	
Operating temperature	T_A	−40	+105	°C	
		−40	+125	°C	*6
Storage temperature	T_{STG}	−55	+150	°C	

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13.3 DC Characteristics

(T_A = −40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage (At V_{CC} = 5 V ± 10%)	V_{IHS}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Pin inputs if CMOS hysteresis input levels are selected (except P12, P15, P44, P45, P50)
	V_{IHA}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	Pin inputs if Automotive input levels are selected
	V_{IHT}	—	—	2.0	—	V_{CC} + 0.3	V	Pin inputs if TTL input levels are selected
	V_{IHS}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P12, P15, P50 inputs if CMOS input levels are selected
	V_{IHI}	—	—	0.7 V_{CC}	—	V_{CC} + 0.3	V	P44, P45 inputs if CMOS hysteresis input levels are selected
	V_{IHR}	—	—	0.8 V_{CC}	—	V_{CC} + 0.3	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{IHM}	—	—	V_{CC} − 0.3	—	V_{CC} + 0.3	V	MD input pin
"L" level input voltage (At V_{CC} = 5 V ± 10%)	V_{ILS}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	Pin inputs if CMOS hysteresis input levels are selected (except P12, P15, P44, P45, P50)
	V_{ILA}	—	—	V_{SS} − 0.3	—	0.5 V_{CC}	V	Pin inputs if Automotive input levels are selected
	V_{ILT}	—	—	V_{SS} − 0.3	—	0.8	V	Pin inputs if TTL input levels are selected
	V_{ILS}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P12, P15, P50 inputs if CMOS input levels are selected
	V_{ILI}	—	—	V_{SS} − 0.3	—	0.3 V_{CC}	V	P44, P45 inputs if CMOS hysteresis input levels are selected
	V_{ILR}	—	—	V_{SS} − 0.3	—	0.2 V_{CC}	V	$\overline{RST}$ input pin (CMOS hysteresis)
	V_{ILM}	—	—	V_{SS} − 0.3	—	V_{SS} + 0.3	V	MD input pin
Output "H" voltage	V_{OH}	Normal outputs	V_{CC} = 4.5 V, I_{OH} = −4.0 mA	V_{CC} − 0.5	—	—	V	
Output "H" voltage	V_{OHI}	I^2C current outputs	V_{CC} = 4.5 V, I_{OH} = −3.0 mA	V_{CC} − 0.5	—	—	V	

(Continued)

(Continued)

(T_A = −40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current	I_{CCT}	V_{CC}	V_{CC} = 5.0 V, Internal frequency: 8 kHz, During stopping clock supervisor, At watch mode T_A = +25°C	—	10	35	µA	MB90351E MB90F351E MB90352E MB90F352E MB90356E MB90F356E MB90357E MB90F357E
			V_{CC} = 5.0 V, Internal frequency: 8 kHz, During operating clock supervisor, At watch mode T_A = +25°C	—	25	150	µA	MB90356E MB90F356E MB90357E MB90F357E
			V_{CC} = 5.0 V, Internal CR oscillation/ 4 division, At watch mode T_A = +25°C	—	25	150	µA	MB90356ES MB90F356ES MB90357ES MB90F357ES
			V_{CC} = 5.0 V, Internal frequency: 8 kHz, During stopping clock supervisor, At watch mode T_A = +25°C	—	60	140	µA	MB90351TE MB90F351TE MB90352TE MB90F352TE MB90356TE MB90F356TE MB90357TE MB90F357TE
			V_{CC} = 5.0 V, Internal frequency: 8 kHz, During operating clock supervisor, At watch mode T_A = +25°C	—	80	250	µA	MB90356TE MB90F356TE MB90357TE MB90F357TE
			V_{CC} = 5.0 V, Internal CR oscillation/ 4 division, At watch mode T_A = +25°C	—	80	250	µA	MB90356TES MB90F356TES MB90357TES MB90F357TES
	I_{CCH}		V_{CC} = 5.0 V, At stop mode, T_A = +25°C	—	7	25	µA	Devices without “T”-suffix
				—	60	130	µA	Devices with “T”-suffix
Input capacity	C_{IN}	Other than C, AV_{CC}, AV_{SS}, AVRH, V_{CC}, V_{SS}	—	—	5	15	pF	

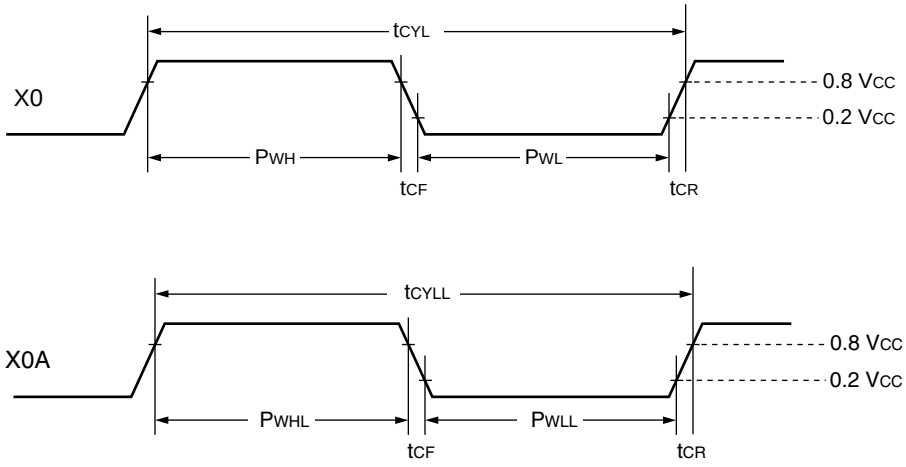
(Continued)

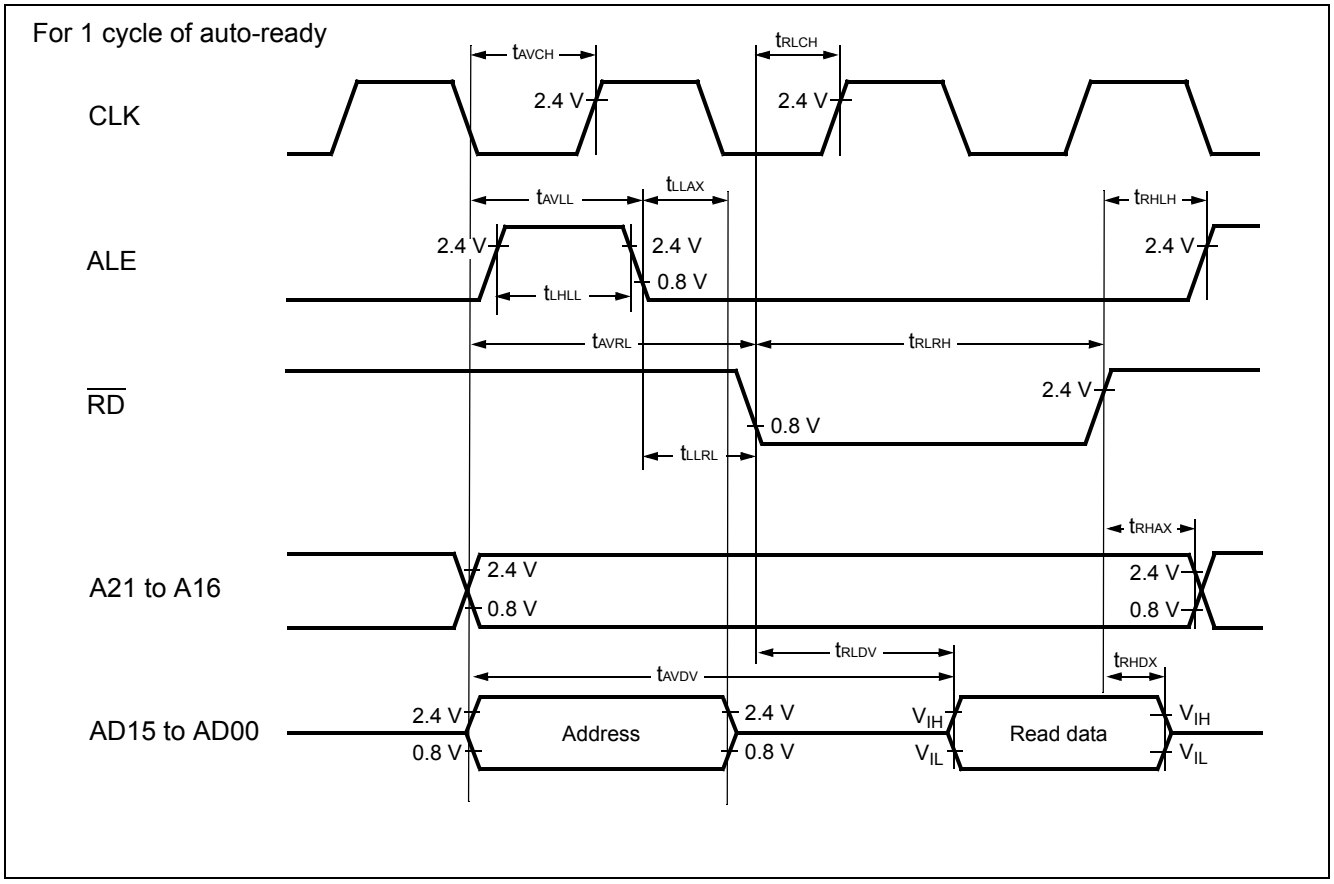
(T_A = –40°C to +125°C, V_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Pin	Value			Unit	Remarks
			Min	Typ	Max		
Internal operating clock frequency (machine clock)	f_{CP}	—	1.5	—	24	MHz	When using main clock
	f_{CPL}	—	—	8.192	50	kHz	When using sub clock
Internal operating clock cycle time (machine clock)	t_{CP}	—	41.67	—	666	ns	When using main clock
	t_{CPL}	—	20	122.1	—	µs	When using sub clock

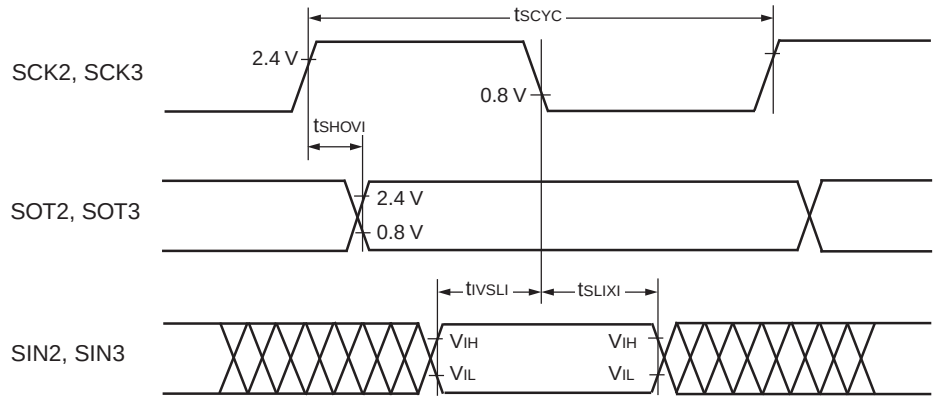
*: The limitation is in the range of the clock frequency when PLL is used. Use within the range in graph of "· PLL guaranteed operation range External clock frequency and internal operation clock frequency".

- Clock Timing

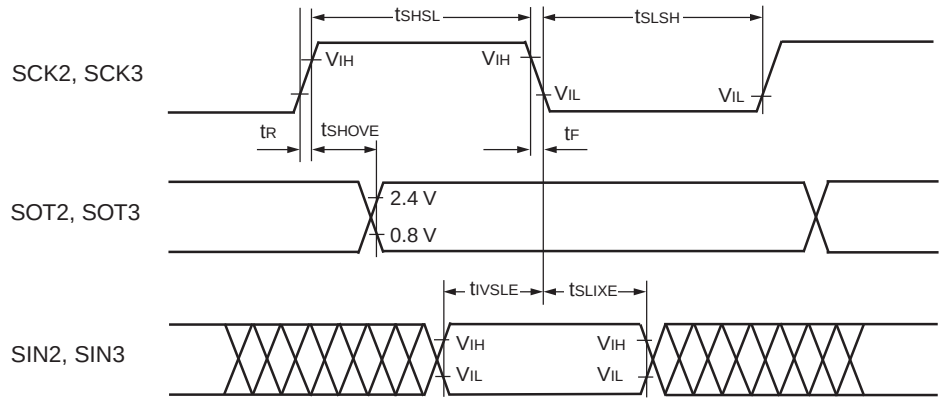



For 1 cycle of auto-ready
CLK
ALE
RD
A21 to A16
AD15 to AD00
tAVCH
tRLCH
2.4 V
tAVLL
tLLAX
tRHLH
0.8 V
tLHLL
tAVRL
tRLRH
tLLRL
tRHAX
tRLDV
tAVDV
tRHDX
Address
Read data
VIH
VIL

• Internal Shift Clock Mode



• External Shift Clock Mode

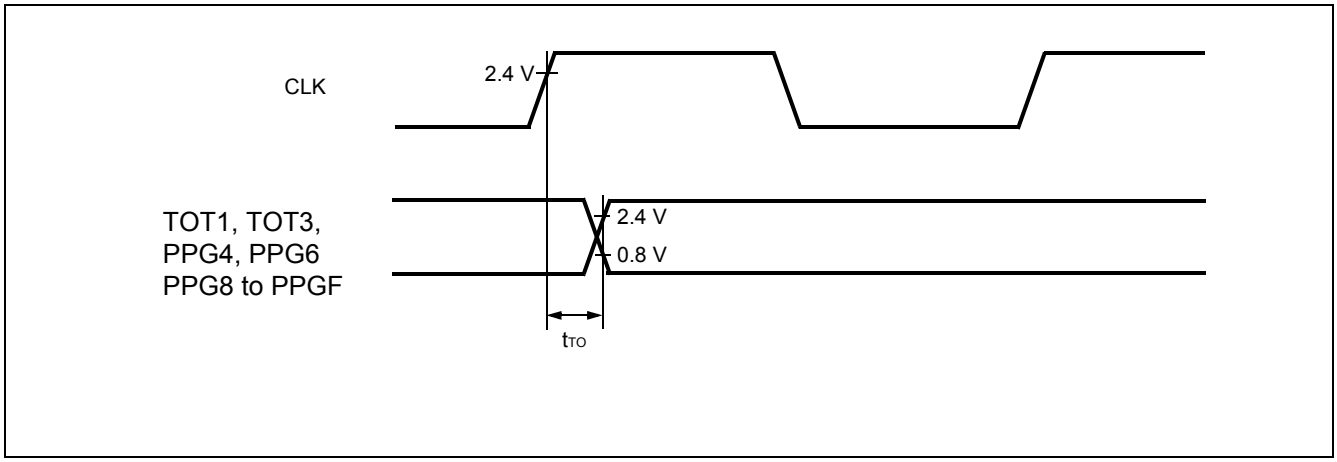


■ Bit setting: ESCR:SCES = 0, ECCR:SCDE = 1

(T_A = –40°C to +125°C, V_{CC} = 5.0 V ± 10%, $f_{CP} \leq$ 24 MHz, V_{SS} = 0 V)

Parameter	Symbol	Pin	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK2, SCK3	Internal clock operation output pins are CL = 80 pF + 1 TTL.	5 t_{CP}	—	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCK2, SCK3 SOT2, SOT3		–50	+50	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK2, SCK3 SIN2, SIN3		t_{CP} + 80	—	ns
SCK ↓ → Valid SIN hold time	t_{SLIXI}	SCK2, SCK3 SIN2, SIN3		0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK2, SCK3 SOT2, SOT3		3 t_{CP} – 70	—	ns

Notes : • C_L is load capacity value of pins when testing.
• t_{CP} is internal operating clock cycle time (machine clock) . Refer to “Clock Timing”.



13.4.13 I^2C Timing

(T_A = −40°C to +125°C, V_{CC} = AV_{CC} = 5.0 V ± 10%, f_{CP} ≤ 24 MHz, V_{SS} = AV_{SS} = 0 V)

Parameter	Symbol	Condition	Standard-mode		Fast-mode*4		Unit
			Min	Max	Min	Max	
SCL clock frequency	f_{SCL}	R = 1.7 kΩ, C = 50 pF*1	0	100	0	400	kHz
Hold time for (repeated) START condition SDA ↓ → SCL ↓	t_{HDSTA}		4.0	—	0.6	—	µs
"L" width of the SCL clock	t_{LOW}		4.7	—	1.3	—	µs
"H" width of the SCL clock	t_{HIGH}		4.0	—	0.6	—	µs
Set-up time for a repeated START condition SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	0.6	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*2	0	0.9*3	µs
Data set-up time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250*5	—	100*5	—	ns
Set-up time for STOP condition SCL ↑ → SDA ↑	t_{SUSTO}		4.0	—	0.6	—	µs
Bus free time between STOP condition and START condition	t_{BUS}		4.7	—	1.3	—	µs

*1 : R,C : Pull-up resistor and load capacitor of the SCL and SDA lines.

*2 : The maximum t_{HDDAT} has to meet at least that the device does not exceed the "L" width (t_{LOW}) of the SCL signal.

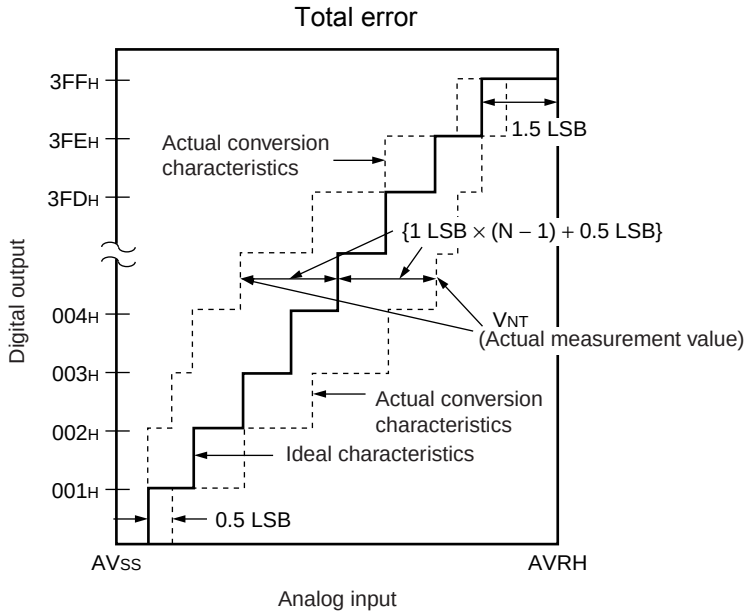
*3 : A Fast-mode I^2C -bus device can be used in a Standard-mode I^2C-bus system, but the requirement $t_{SUDAT} \geq 250$ ns must be met.

*4 : For use at over 100 kHz, set the machine clock to at least 6 MHz.

*5 : Refer to "• Note of SDA, SCL set-up time".

13.6 Definition of A/D Converter Terms

Resolution	:	Analog variation that is recognized by an A/D converter.
Non linearity error	:	Deviation between a line across zero-transition line (“00 0000 0000” ← → “00 0000 0001”) and full-scale transition line (“11 1111 1110” ← → “11 1111 1111”) and actual conversion characteristics.
Differential linearity error	:	Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.
Total error	:	Difference between an actual value and a theoretical value. A total error includes zero transition error, full-scale transition error, and linear error.



$$\text{Total error of digital output “N”} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + 0.5\ \text{LSB}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$1\ \text{LSB (Ideal value)} = \frac{AVRH - AV_{SS}}{1024}\ [\text{V}]$$

N : A/D converter digital output value

V_{OT} (Ideal value) $= AV_{SS} + 0.5$ LSB [V]

V_{FST} (Ideal value) $= AVRH - 1.5$ LSB [V]

V_{NT} : A voltage at which digital output transits from $(N - 1)_H$ to N_H.

(Continued)

(Continued)

Part number	Package	Remarks
MB90F351EPMC1	64-pin plastic LQFP FPT-64P-M24 10.0 mm □, 0.50 mm pitch	Flash memory products (64 Kbytes)
MB90F351ESPMC1		
MB90F351TEPMC1		
MB90F351TESPMC1		
MB90F356EPMC1		
MB90F356ESPMC1		
MB90F356TEPMC1		
MB90F356TESPMC1		
MB90F352EPMC1	64-pin plastic LQFP FPT-64P-M24 10.0 mm □, 0.50 mm pitch	Dual operation Flash memory products (128 Kbytes)
MB90F352ESPMC1		
MB90F352TEPMC1		
MB90F352TESPMC1		
MB90F357EPMC1		
MB90F357ESPMC1		
MB90F357TEPMC1		
MB90F357TESPMC1		
MB90351EPMC1	64-pin plastic LQFP FPT-64P-M24 10.0 mm □, 0.50 mm pitch	MASK ROM products (64 Kbytes)
MB90351ESPMC1		
MB90351TEPMC1		
MB90351TESPMC1		
MB90356EPMC1		
MB90356ESPMC1		
MB90356TEPMC1		
MB90356TESPMC1		
MB90352EPMC1	64-pin plastic LQFP FPT-64P-M24 10.0 mm □, 0.50 mm pitch	MASK ROM products (128 Kbytes)
MB90352ESPMC1		
MB90352TEPMC1		
MB90352TESPMC1		
MB90357EPMC1		
MB90357ESPMC1		
MB90357TEPMC1		
MB90357TESPMC1		
MB90V340E-101CR	299-pin ceramic PGA PGA-299C-A01	Device for evaluation
MB90V340E-102CR		
MB90V340E-103CR		
MB90V340E-104CR		

15. Major Changes

Page	Section	Change Results
—	—	The following names are changed. UART → LIN-UART 16-bit I/O timer → 16-bit free-run timer
26	Handling Devices	Added the section ”13. Serial Communication”.
51	Electrical Characteristics Absolute Maximum Ratings	Changed the maximum value of power consumption.
63	Electrical Characteristics AC Characteristics	Changed the "(4) Clock Output Timing". Changed the Minimum value of cycle time. (41.76 → 41.67)
69 to 73		Changed the notation of “(9) LIN-UART”.
78	A/D Converter	Changed the notation of “Zero reading voltage” and “full scale reading voltage”.
85	Ordering Information	Changed the part number; MB90V340E-101 → MB90V340E-101CR MB90V340E-102 → MB90V340E-102CR MB90V340E-103 → MB90V340E-103CR MB90V340E-104 → MB90V340E-104CR

NOTE: Please see “Document History” about later revised information.

Document History

Document Title: MB90350E Series F^{2}MC-16LX 16-bit Microcontrollers Document Number: 002-04493				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	—	AKIH	10/12/2006	Migrated to Cypress and assigned document number 002-04993. No change to document contents or format.
*A	5193077	AKIH	04/07/2016	Updated to Cypress template

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