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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	Coldfire V1
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	CANbus, EBI/EMI, I²C, SCI, SPI, USB OTG
Peripherals	LVD, PWM, WDT
Number of I/O	69
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x16b; D/A 1x12b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	104-LFBGA
Supplier Device Package	104-MAPBGA (10x10)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mcf51mm256cml

1 Features

The following table provides a cross-comparison of the features of the MCF51MM256/128 according to package.

Table 1. MCF51MM256/128 Features by MCU and Package

Feature	MCF51MM256				MCF51MM128	
FLASH Size (bytes)	262144				131072	
RAM Size (bytes)	32K				32K	
Pin Quantity	104	100	81	80	81	80
Programmable Analog Comparator (PRACMP)	yes	yes	yes	yes	yes	yes
Debug Module (DBG)	yes	yes	yes	yes	yes	yes
Multipurpose Clock Generator (MCG)	yes	yes	yes	yes	yes	yes
Inter-Integrated Communication (IIC)	yes	yes	yes	yes	yes	yes
Interrupt Request Pin (IRQ)	yes	yes	yes	yes	yes	yes
Keyboard Interrupt (KBI)	16	16	16	16	16	16
Digital General Purpose I/O[1]	69	65	48	47	48	47
Dedicated Analog Input Pins	14	14	14	14	14	14
Power and Ground Pins	8	8	8	8	8	8
Time Of Day (TOD)	yes	yes	yes	yes	yes	yes
Serial Communications (SCI1)	yes	yes	yes	yes	yes	yes
Serial Communications (SCI2)	yes	yes	yes	yes	yes	yes
Serial Peripheral Interface (SPI1(FIFO))	yes	yes	yes	yes	yes	yes
Serial Peripheral Interface(SPI2)	yes	yes	yes	yes	yes	yes
Carrier Modulator Timer Pin (IRO)	yes	yes	yes	yes	yes	yes
TPM Input Clock Pin (TPMCLK)	yes	yes	yes	yes	yes	yes
TPM1 Channels	4	4	4	4	4	4
TPM2 Channels	4	4	4	4	4	4
XOSC1	yes	yes	yes	yes	yes	yes
XOSC2	yes	yes	yes	yes	yes	yes
USB On-the-Go	yes	yes	yes	yes	yes	yes
Mini-FlexBus	yes	yes	DATA[2]	DATA[2]	DATA[2]	DATA[2]
Rapid GPIO	16	16	9	9	9	9
MEASUREMENT ENGINE						
Programmable Delay Block (PDB)	yes	yes	yes	yes	yes	yes
16-Bit SAR ADC Differential Channels[3]	4	4	4	4	4	4
16-Bit SAR ADC Single-Ended Channels	8	8	8	8	8	8
DAC Ouput Pin (DACO)	yes	yes	yes	yes	yes	yes
Voltage Reference Output Pin (VREFO)	yes	yes	yes	yes	yes	yes
General Purpose Operational Amplifier (OPAMP)	yes	yes	yes	yes	yes	yes
Trans-Impedance Amplifier (TRIAMP)	yes	yes	yes	yes	yes	yes

1 Port I/O count does not include $\overline{\text{BLMS}}$, BKGD and IRQ. $\overline{\text{BLMS}}$ and BKGD are Output only, IRQ is input only.

2 The 80/81 pin packages contain the Mini-FlexBus data pins to support an 8-bit data bus interface to external peripherals.

3 Each differential channel is comprised of 2 pin inputs.

2 Pinouts and Pin Assignments

2.1 104-Pin MAPBGA

The following figure shows the 104-pin MAPBGA pinout configuration.

	1	2	3	4	5	6	7	8	9	10	11	
A	PTF6	PTF7	USB_DP	USB_DM	VUSB33	PTF4	PTF3	FB_AD12	PTJ7	PTJ5	PTJ4	A
B	PTG0	PTA0	PTG3	VBUS	PTF5	PTJ6	PTH0	PTE5	PTF0	PTF1	PTF2	B
C	IRO	PTG4	PTA6	PTG2	PTG6	PTG5	PTG7	PTH1	PTE4	PTE6	PTE7	C
D	PTA5	PTA4	PTB1	VDD1		VDD2		VDD3	PTA1	PTE3	PTE2	D
E	VSSA	PTA7	PTB0						PTA2	PTJ3	PTE1	E
F	VREFL	INP1-	INP2-	PTG1				PTC7	PTJ2	PTJ0	PTJ1	F
G	TRIOUT1	OUT1	OUT2						PTD5	PTD7	PTE0	G
H	VINP1	VINN1	PTA3	VSS1		VSS2		VSS3	PTD4	PTD3	PTD2	H
J	DADP0	DADM0	PTH7	PTH6	PTH4	PTH3	PTH2	PTD6	PTC2	PTC0	PTC1	J
K	VINP2	VINN2	DADP1	PTH5	PTB6	PTB7	PTC3	PTD1	PTC4	PTC5	PTC6	K
L	TRIOUT2	DACO	DADM1	VREFO	VREFH	VDDA	PTB3	PTB2	PTD0	PTB5	PTB4	L
	1	2	3	4	5	6	7	8	9	10	11	

Figure 2. 104-Pin MAPBGA

2.2 100-Pin LQFP

The following figure shows the 100-pin LQFP pinout configuration.

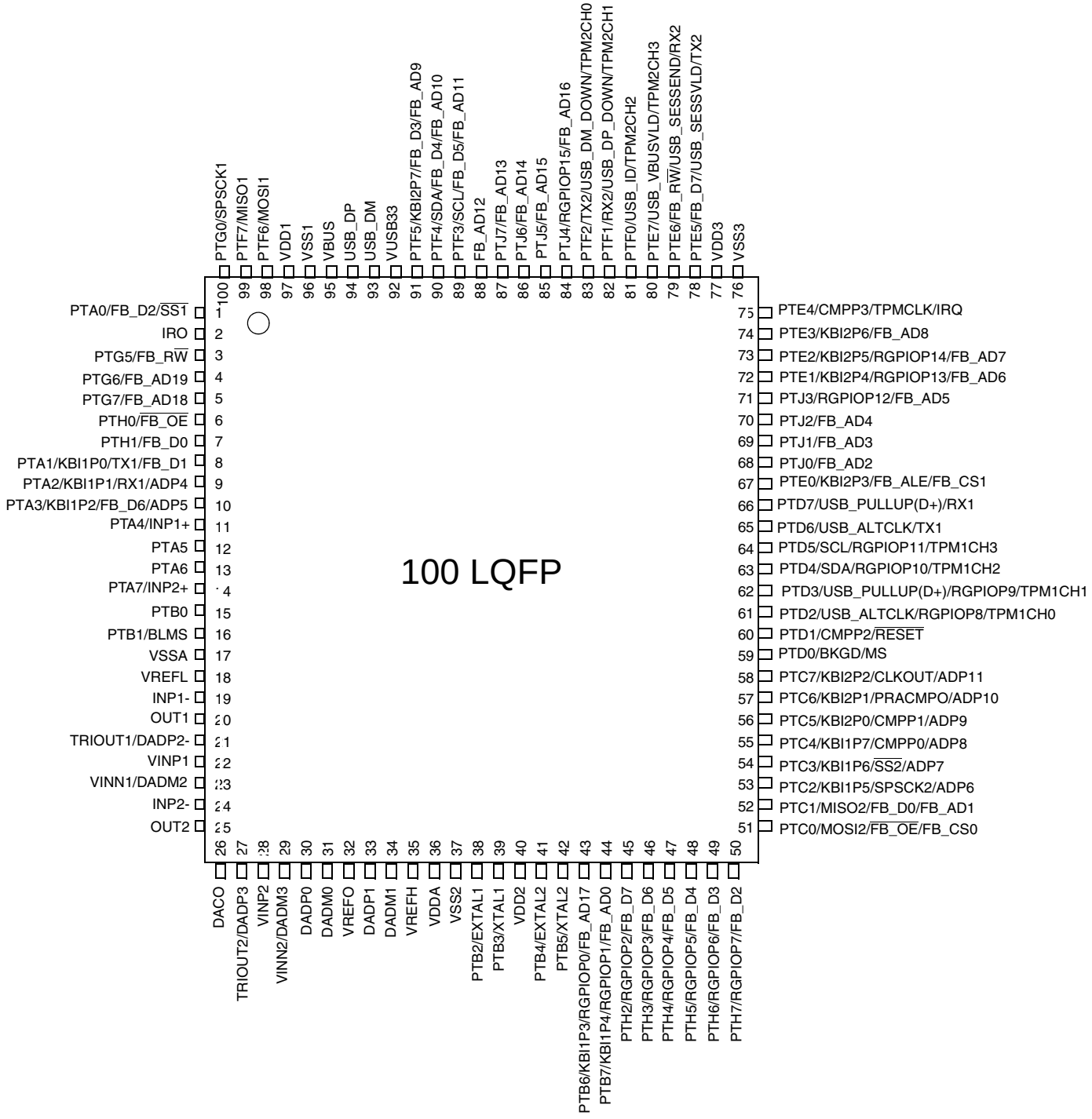

Figure 3. 100-Pin LQFP

Table 3. Package Pin Assignments (continued)

Package				Default Function	Alternate 1	Alternate 2	Alternate 3	Composite Pin Name
104 MAPBGA	100 LQFP	81 MAPBGA	80 LQFP					
H11	61	E7	50	PTD2	USB_ALTCLK	RGPIOP8	TPM1CH0	PTD2/USB_ALTCLK/RGPIOP8/TPM1CH0
H10	62	E8	51	PTD3	USB_PULLUP (D+)	RGPIOP9	TPM1CH1	PTD3/USB_PULLUP(D+)/RGPIOP9/TPM1CH1
H9	63	F9	52	PTD4	SDA	RGPIOP10	TPM1CH2	PTD4/SDA/RGPIOP10/TPM1CH2
G9	64	D7	53	PTD5	SCL	RGPIOP11	TPM1CH3	PTD5/SCL/RGPIOP11/TPM1CH3
J8	65	E9	54	PTD6	USB_ALTCLK	TX1	—	PTD6/USB_ALTCLK/TX1
G10	66	D8	55	PTD7	USB_PULLUP (D+)	RX1	—	PTD7/USB_PULLUP(D+) /RX1
G11	67	D9	56	PTE0	KBI2P3	FB_ALE	FB_CS1	PTE0/KBI2P3/FB_ALE/FB_CS1
F10	68	—	—	PTJ0	FB_AD2	—	—	PTJ0/FB_AD2
F11	69	—	—	PTJ1	FB_AD3	—	—	PTJ1/FB_AD3
F9	70	—	—	PTJ2	FB_AD4	—	—	PTJ2/FB_AD4
E10	71	—	—	PTJ3	RGPIOP12	FB_AD5	—	PTJ3/RGPIOP12/FB_AD5
E11	72	C9	57	PTE1	KBI2P4	RGPIOP13	FB_AD6	PTE1/KBI2P4/RGPIOP13/FB_AD6
D11	73	C8	58	PTE2	KBI2P5	RGPIOP14	FB_AD7	PTE2/KBI2P5/RGPIOP14/FB_AD7
D10	74	B9	59	PTE3	KBI2P6	FB_AD8	—	PTE3/KBI2P6/FB_AD8
C9	75	A9	60	PTE4	CMPP3	TPMCLK	IRQ	PTE4/CMPP3/TPMCLK/IRQ
H8	76	F5	61	VSS3	—	—	—	VSS3
D8	77	E5	62	VDD3	—	—	—	VDD3
B8	78	C7	63	PTE5	FB_D7	USB_ SESSVLD	TX2	PTE5/FB_D7/USB_SESSVLD/TX2
C10	79	C6	64	PTE6	FB_R$\overline{W}$	USB_ SESSEND	RX2	PTE6/FB_R$\overline{W}$/USB_SESSEND/RX2
C11	80	B6	65	PTE7	USB_ VBUSVLD	TPM2CH3	—	PTE7/USB_VBUSVLD/TPM2CH3
B9	81	B8	66	PTF0	USB_ID	TPM2CH2	—	PTF0/USB_ID/TPM2CH2
B10	82	B7	67	PTF1	RX2	USB_DP_D OWN	TPM2CH1	PTF1/RX2/USB_DP_DOWN/TPM2CH1
B11	83	C5	68	PTF2	TX2	USB_DM_ DOWN	TPM2CH0	PTF2/TX2/USB_DM_DOWN/TPM2CH0
A11	84	—	—	PTJ4	RGPIOP15	FB_AD16	—	PTJ4/RGPIOP15/FB_AD16
A10	85	—	—	PTJ5	FB_AD15	—	—	PTJ5/FB_AD15
B6	86	—	—	PTJ6	FB_AD14	—	—	PTJ6/FB_AD14
A9	87	—	—	PTJ7	FB_AD13	—	—	PTJ7/FB_AD13

For most applications, $P_{I/O} << P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_J + 273°C) \quad \textit{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273°C) + \theta_{JA} \times (P_D)^2 \quad \textit{Eqn. 3}$$

where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A.

3.4 ESD Protection Characteristics

Although damage from static discharge is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with CDF-AEC-Q00 Stress Test Qualification for Automotive Grade Integrated Circuits. (http://www.aecouncil.com/) This device was qualified to AEC-Q100 Rev E.

A device is considered to have failed if, after exposure to ESD pulses, the device no longer meets the device specification requirements. Complete dc parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 7. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human Body	Series Resistance	R1	1500	Ω
	Storage Capacitance	C	100	pF
	Number of Pulse per pin	—	3	—
Machine	Series Resistance	R1	0	Ω
	Storage Capacitance	C	200	pF
	Number of Pulse per pin	—	3	—
Latch-up	Minimum input voltage limit	—	–2.5	V
	Maximum input voltage limit	—	7.5	V

Table 8. ESD and Latch-Up Protection Characteristics

#	Rating	Symbol	Min	Max	Unit	C
1	Human Body Model (HBM)	V_{HBM}	±2000	—	V	T
2	Machine Model (MM)	V_{MM}	±200	—	V	T

Table 10. Supply Current Characteristics (continued)

#	Symbol	Parameter	Bus Freq	V_{DD} (V)	Typ[1]	Max	Unit	Temp (°C)	C
5	WI_{DD}	Wait mode supply current FEI mode, all modules OFF[3]							
			25.165 MHz	3	16.5	—	mA	–40 to 105	C
			20 MHz	3	10.3	—	mA	–40 to 105	T
			8 MHz	3	6.6	—	mA	–40 to 105	T
			1 MHz	3	1.7	—	mA	–40 to 105	T
6	$LPWI_{DD}$	Low-Power Wait mode supply current							
			16 KHz	3	28	62	µA	–40 to 105	T
7	$S2I_{DD}$	Stop2 mode supply current[4]							
			N/A	3	0.410	1.00	µA	–40 to 25	P
			N/A	3	3.7	10	µA	70	C
			N/A	3	10	20	µA	85	C
			N/A	3	21	31.5	µA	105	P
			N/A	2	0.410	0.640	µA	–40 to 25	C
			N/A	2	3.4	9	µA	70	C
			N/A	2	9.5	18	µA	85	C
			N/A	2	20	30	µA	105	C

Table 10. Supply Current Characteristics (continued)

#	Symbol	Parameter	Bus Freq	V_{DD} (V)	Typ[1]	Max	Unit	Temp (°C)	C
8	$S3I_{DD}$	Stop3 mode supply current[4] No clocks active	n/a	3	0.750	1.3	μA	–40 to 25	P
					8.5	18		70	C
					20	28		85	C
					53	63		105	P
				2	0.400	0.900		–40 to 25	C
					8.2	16		70	C
					18	26		85	C
					47	59		105	C

1 Data in Typical column was characterized at 3.0 V, 25°C or is typical recommended value.

2 ON = System Clock Gating Control registers turn on system clock to the corresponding modules.

3 OFF = System Clock Gating Control registers turn off system Clock to the corresponding modules.

4 All digital pins must be configured to a known state to prevent floating pins from adding current. Smaller packages may have some pins that are not bonded out; however, software must still be configured to the largest pin package available so that all pins are in a known state. Otherwise, floating pins that are not bonded in the smaller packages may result in a higher current draw. NOTE: I/O pins are configured to output low; input-only pins are configured to pullup-enabled. IRO pin connects to ground. FB_AD12 pin is pullup-enabled. TRIAMPx, OPAMPx, DACO, and VREFO pins are at reset state and unconnected.

Table 11. Typical Stop Mode Adders

#	Parameter	Condition	Temperature (°C)					Units	C
			-40	25	70	85	105		
1	LPO	—	50	75	100	150	250	nA	D
2	EREFSTEN	RANGE = HGO = 0	600	650	750	850	1000	nA	D
3	IREFSTEN[1]	—	—	73	80	93	125	μA	T
4	TOD	Does not include clock source current	50	75	100	150	250	nA	D
5	LVD[1]	LVDSE = 1	116	117	126	132	172	μA	T
6	PRACMP[1]	Not using the bandgap (BGBE = 0)	17	18	24	35	74	μA	T
7	ADC[1]	ADLPC = ADLSMP = 1 Not using the bandgap (BGBE = 0)	190	195	210	220	260	μA	T
8	DAC[1]	High-Power mode; no load on DACO	339	345	346	346	360	μA	T
		Low-Power mode	41	43	43	44	50	μA	T
9	OPAMP[1]	High-Power mode	276	350	370	376	390	μA	T
		Low-Power mode	42	49	57	58	68	μA	T
10	TRIAMP[1]	High-Power mode	420	432	433	438	478	μA	T
		Low-Power mode	52	52	52	55	60	μA	T

1 Not available in stop2 mode.

Table 15. 16-Bit ADC Operating Conditions (continued)

#	Symb	Characteristic	Conditions	Min	Typ[1]	Max	Unit	C	Comment
5	V_{REFL}	Ref Voltage Low		V_{SSA}	V_{SSA}	V_{SSA}	V	D	
6	V_{ADIN}	Input Voltage		V_{REFL}	—	V_{REFH}	V	D	
7	C_{ADIN}	Input Capacitance	16-bit modes 8/10/12-bit modes	—	8 4	10 5	pF	T	
8	R_{ADIN}	Input Resistance		—	2	5	kΩ	T	
9	R_{AS}	Analog Source Resistance							External to MCU Assumes ADLSMP=0
		16-bit mode	f_{ADCK} > 8 MHz	—	—	0.5	kΩ	T	
			4 MHz < f_{ADCK} < 8 MHz	—	—	1	kΩ	T	
			f_{ADCK} < 4 MHz	—	—	2	kΩ	T	
		13/12-bit mode	f_{ADCK} > 8 MHz	—	—	1	kΩ	T	
			4 MHz < f_{ADCK} < 8 MHz	—	—	2	kΩ	T	
			f_{ADCK} < 4 MHz	—	—	5	kΩ	T	
		11/10-bit mode	f_{ADCK} > 8 MHz	—	—	2	kΩ	T	
			4 MHz < f_{ADCK} < 8 MHz	—	—	5	kΩ	T	
			f_{ADCK} < 4 MHz	—	—	10	kΩ	T	
		9/8-bit mode	f_{ADCK} > 8 MHz	—	—	5	kΩ	T	
			f_{ADCK} < 8 MHz	—	—	10	kΩ	T	
10	f_{ADCK}	ADC Conversion Clock Frequency							
		ADLPC=0, ADHSC=1		1.0	—	8.0	MHz	D	
		ADLPC=0, ADHSC=0		1.0	—	5.0	MHz	D	
		ADLPC=1, ADHSC=0		1.0	—	2.5	MHz	D	

1 Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK}=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 DC potential difference.

Table 16. 16-Bit SAR ADC Characteristics full operating range ($V_{REFH} = V_{DDA}$, > 1.8, $V_{REFL} = V_{SSA} \leq$ 8 MHz, –40 to 85 °C)

#	Characteristic	Conditions[1]	Symb	Min	Typ[2]	Max	Unit	C	Comment
1	Supply Current	ADLPC=1, ADHSC=0	I_{DDAD}	—	215	—	μA	T	ADLSMP =0 ADCO=1
		ADLPC=0, ADHSC=0		—	470	—			
		ADLPC=0, ADHSC=1		—	610	—			
2	Supply Current	Stop, Reset, Module Off	I_{DDAD}	—	0.01	—	μA	T	
3	ADC Asynchronous Clock Source	ADLPC=1, ADHSC=0	f_{ADACK}	—	2.4	—	MHz	C	$t_{ADACK} = 1/f_{ADACK}$
		ADLPC=0, ADHSC=0		—	5.2	—			
		ADLPC=0, ADHSC=1		—	6.2	—			
4	Sample Time	See Reference Manual for sample times							
5	Conversion Time	See Reference Manual for conversion times							
6	Total Unadjusted Error	16-bit differential mode 16-bit single-ended mode	TUE	— —	±16 ±20	+48/ –40 +56/ –28	LSB[3]	T	32x Hardware Averaging (AVGE = %1 AVGS = %11)
		13-bit differential mode 12-bit single-ended mode		— —	±1.5 ±1.75	±3.0 ±3.5		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.7 ±0.8	±1.5 ±1.5		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.5 ±0.5	±1.0 ±1.0		T	
7	Differential Non-Linearity	16-bit differential mode 16-bit single-ended mode	DNL	— —	±2.5 ±2.5	+5/–3 +5/–3	LSB[2]	T	
		13-bit differential mode 12-bit single-ended mode		— —	±0.7 ±0.7	±1 ±1		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.5 ±0.5	±0.75 ±0.75		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.2 ±0.2	±0.5 ±0.5		T	

Table 16. 16-Bit SAR ADC Characteristics full operating range ($V_{REFH} = V_{DDA}$, > 1.8, $V_{REFL} = V_{SSA} \leq 8$ MHz, –40 to 85 °C) (continued)

#	Characteristic	Conditions[1]	Symb	Min	Typ[2]	Max	Unit	C	Comment
8	Integral Non-Linearity	16-bit differential mode 16-bit single-ended mode	INL	— —	±6.0 ±10.0	±16.0 ±20.0	LSB[2]	T	
		13-bit differential mode 12-bit single-ended mode		— —	±1.0 ±1.0	±2.5 ±2.5		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.5 ±0.5	±1.0 ±1.0		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.3 ±0.3	±0.5 ±0.5		T	
9	Zero-Scale Error	16-bit differential mode 16-bit single-ended mode	E_{ZS}	— —	±4.0 ±4.0	+32/ –24 +24/ –16	LSB[2]	T	$V_{ADIN} = V_{SSA}$
		13-bit differential mode 12-bit single-ended mode		— —	±0.7 ±0.7	±2.5 ±2.0		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.4 ±0.4	±1.0 ±1.0		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.2 ±0.2	±0.5 ±0.5		T	
10	Full-Scale Error	16-bit differential mode 16-bit single-ended mode	E_{FS}	— —	+10/0 +14/0	+42/–2 +46/–2	LSB[2]	T	$V_{ADIN} = V_{DDA}$
		13-bit differential mode 12-bit single-ended mode		— —	±1.0 ±1.0	±3.5 ±3.5		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.4 ±0.4	±1.5 ±1.5		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.2 ±0.2	±0.5 ±0.5		T	
11	Quantization Error	16-bit modes	E_Q	—	–1 to 0	—	LSB[2]	D	
		≤13-bit modes		—	—	±0.5			
12	Effective Number of Bits	16-bit differential mode Avg=32 Avg=16 Avg=8 Avg=4 Avg=1	ENOB	 12.8 12.7 12.6 12.5 11.9	 14.2 13.8 13.6 13.3 12.5	 — — — — —	Bits	C	$F_{in} = F_{sample}/100$
13	Signal to Noise plus Distortion	See ENOB	SINAD	$SINAD = 6.02 \cdot ENOB + 1.76$			dB		

Table 17. 16-bit SAR ADC Characteristics full operating range ($V_{REFH} = V_{DDA}$, ≥ 2.7 V, $V_{REFL} = V_{SSA}$, $f_{ADACK} \leq 4$ MHz, ADHSC = 1)

#	Characteristic	Conditions[1]	Symb	Min	Typ[2]	Max	Unit	C	Comment
1	Total Unadjusted Error	16-bit differential mode 16-bit single-ended mode	TUE	— —	±16 ±20	+24/ –24 +32/–20	LSB[3]	T	32x Hardware Averaging (AVGE = %1 AVGS = %11)
		13-bit differential mode 12-bit single-ended mode		— —	±1.5 ±1.75	±2.0 ±2.5		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.7 ±0.8	±1.0 ±1.25		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.5 ±0.5	±1.0 ±1.0		T	
2	Differential Non-Linearity	16-bit differential mode 16-bit single-ended mode	DNL	— —	±2.5 ±2.5	±3 ±3	LSB[2]	T	
		13-bit differential mode 12-bit single-ended mode		— —	±0.7 ±0.7	±1 ±1		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.5 ±0.5	±0.75 ±0.75		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.2 ±0.2	±0.5 ±0.5		T	
3	Integral Non-Linearity	16-bit differential mode 16-bit single-ended mode	INL	— —	±6.0 ±10.0	±12.0 ±16.0	LSB[2]	T	
		13-bit differential mode 12-bit single-ended mode		— —	±1.0 ±1.0	±2.0 ±2.0		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.5 ±0.5	±1.0 ±1.0		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.3 ±0.3	±0.5 ±0.5		T	
4	Zero-Scale Error	16-bit differential mode 16-bit single-ended mode	E_{ZS}	— —	±4.0 ±4.0	+16/0 +16/-8	LSB[2]	T	$V_{ADIN} = V_{SSA}$
		13-bit differential mode 12-bit single-ended mode		— —	±0.7 ±0.7	±2.0 ±2.0		T	
		11-bit differential mode 10-bit single-ended mode		— —	±0.4 ±0.4	±1.0 ±1.0		T	
		9-bit differential mode 8-bit single-ended mode		— —	±0.2 ±0.2	±0.5 ±0.5		T	

2 This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bit is changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

3 This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

4 Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{BUS}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

5 625 ns represents 5 time quanta for CAN applications, under worst-case conditions of 8 MHz CAN bus clock, 1 Mbps CAN Bus speed, and 8 time quanta per bit for bit time settings. 5 time quanta is the minimum time between a synchronization edge and the sample point of a bit using 8 time quanta per bit.

6 Below D_{lock} minimum, the MCG is guaranteed to enter lock. Above D_{lock} maximum, the MCG will not enter lock. But if the MCG is already in lock, then the MCG may stay in lock.

7 Below D_{unl} minimum, the MCG will not exit lock if already in lock. Above D_{unl} maximum, the MCG is guaranteed to exit lock.

Table 19. XOSC (Temperature Range = –40 to 105°C Ambient)

#	Characteristic		Symbol	Min	Typ[1]	Max	Unit	C
1	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1)	• Low range (RANGE = 0)	f_{lo}	32	—	38.4	kHz	D
		• High range (RANGE = 1), • FEE or FBE mode [2]	f_{hi-fll}	1	—	5	MHz	D
		• High range (RANGE = 1), • PEE or PBE mode [3]	f_{hi-pll}	1	—	16	MHz	D
		• High range (RANGE = 1), • High gain (HGO = 1), • BLPE mode	f_{hi-hgo}	1	—	16	MHz	D
		• High range (RANGE = 1), • Low power (HGO = 0), • BLPE mode	f_{hi-lp}	1	—	8	MHz	D
2	Load capacitors		C_1 C_2	See crystal or resonator manufacturer's recommendation.				D
3	Feedback resistor	• Low range (32 kHz to 38.4 kHz)	R_F	—	10	—	MΩ	D
		• High range (1 MHz to 16 MHz)	—	—	1	—		D
4	Series resistor — Low range	• Low Gain (HGO = 0)	R_S	—	0	—	kΩ	D
		• High Gain (HGO = 1)		—	100	—		D
5	Series resistor — High range	• Low Gain (HGO = 0)	R_S	—	0	—	kΩ	D
		• High Gain (HGO = 1)						D
		≥ 8 MHz		—	0	0		D
		4 MHz		—	0	10		D
		1 MHz		—	0	20		D

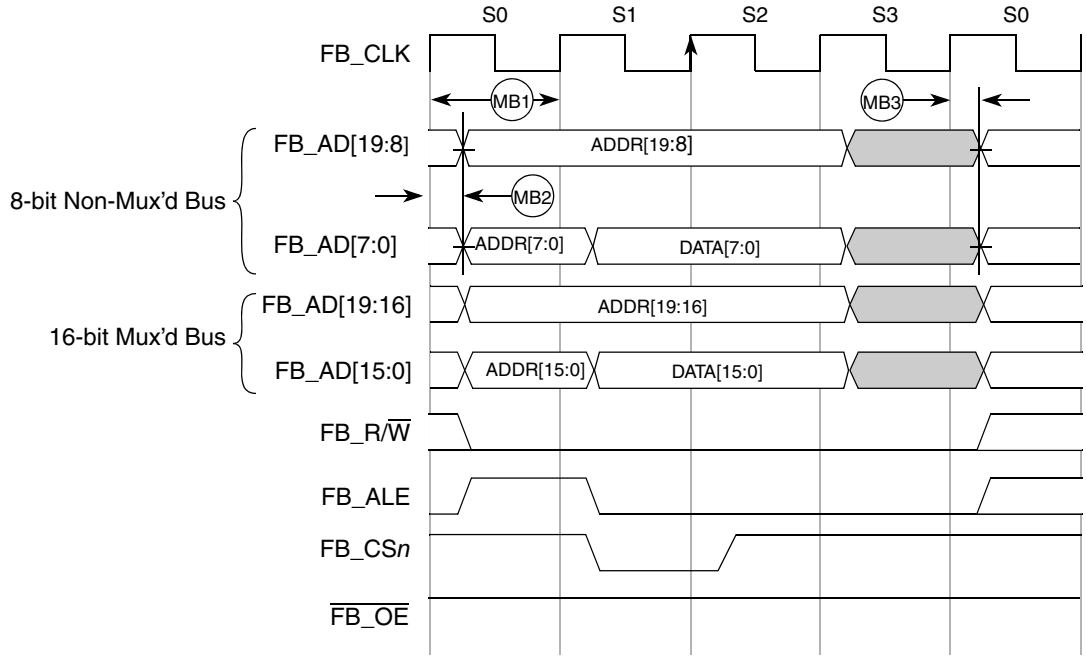

Figure 10. Mini-FlexBus Write Timing

3.12 AC Characteristics

This section describes ac timing characteristics for each peripheral system.

3.12.1 Control Timing

Table 21. Control Timing

#	Symbol	Parameter		Min	Typical[1]	Max	C	Unit
1	f_{Bus}	Bus frequency ($t_{cyc} = 1/f_{Bus}$)						MHz
			$V_{DD} \geq 1.8$ V	dc	—	10	D	
			$V_{DD} > 2.1$ V	dc	—	20	D	
			$V_{DD} > 2.4$ V	dc	—	25.165	D	
2	t_{LPO}	Internal low-power oscillator period		700	1000	1300	P	µs
3	t_{extrst}	External reset pulse width[2] ($t_{cyc} = 1/f_{Self\_reset}$)		100	—	—	D	ns
4	t_{rstdrv}	Reset low drive		66 x t_{cyc}	—	—	D	ns
5	t_{MSSU}	Active background debug mode latch setup time		500	—	—	D	ns
6	t_{MSH}	Active background debug mode latch hold time		100	—	—	D	ns
7	t_{ILIH}, t_{IHIL}	IRQ pulse width • Asynchronous path[2] • Synchronous path[3]		100 1.5 x t_{cyc}	—	—	D	ns
8	t_{ILIH}, t_{IHIL}	KBIPx pulse width • Asynchronous path[2] • Synchronous path[3]		100 1.5 x t_{cyc}	—	—	D	ns

Table 21. Control Timing (continued)

#	Symbol	Parameter	Min	Typical[1]	Max	C	Unit
9	t_{Rise}, t_{Fall}	Port rise and fall time (load = 50 pF)[4], Low Drive					ns
		Slew rate control disabled (PTxSE = 0)	—	11	—	D	
		Slew rate control enabled (PTxSE = 1)	—	35	—	D	
		Slew rate control disabled (PTxSE = 0)	—	40	—	D	
		Slew rate control enabled (PTxSE = 1)	—	75	—	D	

1 Typical values are based on characterization data at V_{DD} = 5.0 V, 25 °C unless otherwise stated.

2 This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

3 This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

4 Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40 °C to 105 °C.

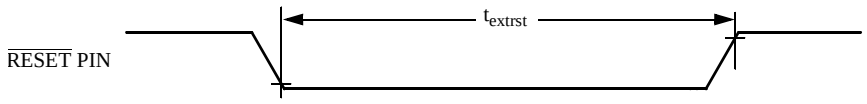

Figure 11. Reset Timing

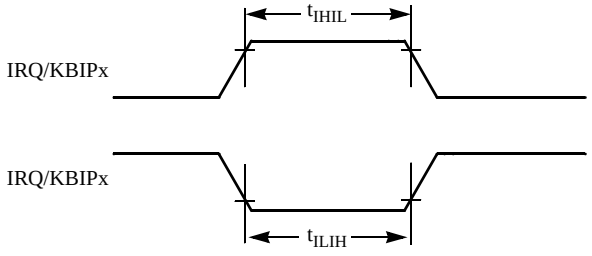

Figure 12. IRQ/KBIPx Timing

3.12.2 TPM Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 22. TPM Input Timing

#	C	Function	Symbol	Min	Max	Unit
1	—	External clock frequency	f_{TPMext}	dc	$f_{Bus}/4$	MHz
2	—	External clock period	t_{TPMext}	4	—	t_{cyc}
3	D	External clock high time	t_{clkh}	1.5	—	t_{cyc}
4	D	External clock low time	t_{clkl}	1.5	—	t_{cyc}
5	D	Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

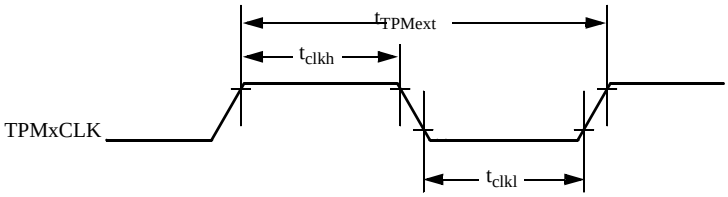

Figure 13. Timer External Clock

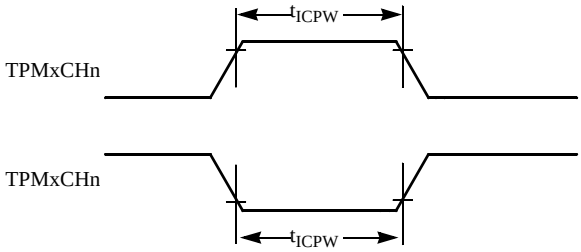

Figure 14. Timer Input Capture Pulse

3.13 SPI Characteristics

Table 23 and Figure 15 through Figure 18 describe the timing requirements for the SPI system.

Table 23. SPI Timing

No.[1]	Characteristic[2]	Symbol	Min	Max	Unit	C
1	Operating frequency Master Slave	f_{op}	$f_{Bus}/2048$ 0	$f_{Bus}/2$ $f_{Bus}/4$	Hz Hz	D
2	SPSCK period Master Slave	t_{SPSCK}	2 4	2048 —	t_{cyc} t_{cyc}	D
3	Enable lead time Master Slave	t_{Lead}	1/2 1	— —	t_{SPSCK} t_{cyc}	D
4	Enable lag time Master Slave	t_{Lag}	1/2 1	— —	t_{SPSCK} t_{cyc}	D
5	Clock (SPSCK) high or low time Master Slave	t_{WSPSCK}	$t_{cyc} - 30$ $t_{cyc} - 30$	1024 t_{cyc} —	ns ns	D
6	Data setup time (inputs) Master Slave	t_{SU} t_{SU}	15 15	— —	ns ns	D
7	Data hold time (inputs) Master Slave	t_{HI} t_{HI}	0 25	— —	ns ns	D
8	Slave access time[3]	t_a	—	1	t_{cyc}	D
9	Slave MISO disable time[4]	t_{dis}	—	1	t_{cyc}	D
10	Data valid (after SPSCK edge) Master Slave	t_v	— —	25 25	ns ns	D
11	Data hold time (outputs) Master Slave	t_{HO}	0 0	— —	ns ns	D
12	Rise time Input Output	t_{RI} t_{RO}	— —	$t_{cyc} - 25$ 25	ns ns	D
13	Fall time Input Output	t_{FI} t_{FO}	— —	$t_{cyc} - 25$ 25	ns ns	D

1 Numbers in this column identify elements in Figure 15 through Figure 18.

2 All timing is shown with respect to 20% V_{DD} and 70% V_{DD}, unless noted; 100 pF load on all SPI pins. All timing assumes slew rate control disabled and high drive strength enabled for SPI output pins.

3 Time to data active from high-impedance state.

4 Hold time to high-impedance state.

3.15 USB Electricals

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit http://www.usb.org.

If the Freescale USB On-the-Go implementation has electrical characteristics that deviate from the standard or require additional information, this space would be used to communicate that information.

Table 25. Internal USB 3.3 V Voltage Regulator Characteristics

#	Characteristic	Symbol	Min	Typ	Max	Unit	C
1	Regulator operating voltage	V_{regin}	3.9	—	5.5	V	C
2	VREG output	V_{regout}	3	3.3	3.75	V	P
3	V_{USB33} input with internal VREG disabled	$V_{usb33in}$	3	3.3	3.6	V	C
4	VREG Quiescent Current	I_{VRQ}	—	0.5	—	mA	C

Table 28. TRIAMP Characteristics 1.8–3.6 V, –40°C~105°C (continued)

#	Characteristic[1]	Symbol	Min	Typ[2]	Max	Unit	C
28	Input Voltage Noise Density	f= 1 kHz	—	160	—	nV/√Hz	T

1 All parameters are measured at 3.0 V, CL= 47 pF across temperature –40 to + 105 °C unless specified.
2 Data in Typical column was characterized at 3.0 V, 25°C or is typical recommended value.

3.18 OPAMP Electrical Parameters

Table 29. OPAMP Characteristics 1.8–3.6 V

#	Characteristics[1]	Symbol	Min	Typ[2]	Max	Unit	C
1	Operating Voltage	V_{DD}	1.8	—	3.6	V	C
2	Supply Current (I_{OUT}=0mA, CL=0 Low-Power mode)	I_{SUPPLY}	—	48	80	μA	T
3	Supply Current (I_{OUT}=0mA, CL=0 High-Speed mode)	I_{SUPPLY}	—	350	500	μA	T
4	Input Offset Voltage	V_{OS}	—	±2	±6	mV	T
5	Input Offset Voltage Temperature Coefficient	α_{VOS}	—	10	—	μV/C	T
6	Input Offset Current (–40°C to 105°C)	I_{OS}	—	±2.5	±250	nA	T
7	Input Offset Current (–40°C to 50°C)	I_{OS}	—	—	45	nA	T
8	Positive Input Bias Current (–40°C to 105°C)	I_{BIAS}	—	0.8	3.5	nA	T
9	Positive Input Bias Current (–40°C to 50°C)	I_{BIAS}	—	—	±2	nA	T
10	Negative Input Bias Current (–40°C to 105°C)	I_{BIAS}	—	2.5	250	nA	T
11	Negative Input Bias Current (–40°C to 50°C)	I_{BIAS}	—	—	45	nA	T
12	Input Common Mode Voltage Low	V_{CML}	0.1	—	—	V	T
13	Input Common Mode Voltage High	V_{CMH}	—	—	V_{DD}	V	T
14	Input Resistance	R_{IN}	—	500	—	MΩ	T
15	Input Capacitances	C_{IN}	—	—	10	pF	D
16	AC Input Impedance (f_{IN}=100kHz Negative Channel)	$\|X_{IN}\|$	—	52	—	kΩ	D
17	AC Input Impedance (f_{IN}=100kHz Positive Channel)	$\|X_{IN}\|$	—	132	—	kΩ	D
18	Input Common Mode Rejection Ratio	CMRR	55	65	—	dB	T
19	Power Supply Rejection Ratio	PSRR	60	65	—	dB	T
20	Slew Rate (ΔV_{IN}=100mV Low-Power mode)	SR	0.1	—	—	V/μs	T
21	Slew Rate (ΔV_{IN}=100mV High-Speed mode)	SR	1	—	—	V/μs	T
22	Unity Gain Bandwidth (Low-Power mode)	GBW	0.2	—	—	MHz	T
23	Unity Gain Bandwidth (High-Speed mode)	GBW	1	—	—	MHz	T
24	DC Open Loop Voltage Gain	A_V	80	90	—	dB	T
25	Load Capacitance Driving Capability	CL(max)	—	—	100	pF	T
26	Output Impedance AC Open Loop (@100 kHz Low-Power mode)	R_{OUT}	—	4k	—	Ω	D

4 Ordering Information

This section contains ordering information for the device numbering system. See Table 1 for feature summary by package information.

4.1 Part Numbers

Table 30. Orderable Part Number Summary

Freescale Part Number	Description	Flash / SRAM (Kbytes)	Package	Temperature
MCF51MM256VML	MCF51MM256 ColdFire Microcontroller	256K/32K	104 MAPBGA	–40 to 105 °C
MCF51MM256VLL	MCF51MM256 ColdFire Microcontroller	256K/32K	100 LQFP	–40 to 105 °C
MCF51MM256VMB	MCF51MM256 ColdFire Microcontroller	256K/32K	81 MAPBGA	–40 to 105 °C
MCF51MM256VLK	MCF51MM256 ColdFire Microcontroller	256K/32K	80 LQFP	–40 to 105 °C
MCF51MM128VMB	MCF51MM128 ColdFire Microcontroller	128K/32K	81 MAPBGA	–40 to 105 °C
MCF51MM128VLK	MCF51MM128 ColdFire Microcontroller	128K/32K	80 LQFP	–40 to 105 °C

4.2 Package Information

Table 31. Package Descriptions

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
100	Low Quad Flat Package	LQFP	LL	983-03	98ASS23308W
80	Low Quad Flat Package	LQFP	LK	1418	98ASS23174W
104	MAP BGA Package	MAPBGA	ML	1285-02	98ARH98267A
81	MAP BGA Package	MAPBGA	MB	1662-01	98ASA10670D

4.3 Mechanical Drawings

Table 31 provides the available package types and their document numbers. The latest package outline/mechanical drawings are available on the MCF51MM256/128 Product Summary pages at http://www.freescale.com.

To view the latest drawing, either:

- Click on the appropriate link in Table 31, or
- Open a browser to the Freescale website (http://www.freescale.com), and enter the appropriate document number (from Table 31) in the “Enter Keyword” search box at the top of the page.

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