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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	LINbus, SIO, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	25
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 5.5V
Data Converters	A/D 9x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f212k4sdfp-x6

1. Overview

1.1 Features

The R8C/2K Group and R8C/2L Group of single-chip MCUs incorporates the R8C/Tiny Series CPU core, employing sophisticated instructions for a high level of efficiency. With 1 Mbyte of address space, and it is capable of executing instructions at high speed. In addition, the CPU core boasts a multiplier for high-speed operation processing.

Power consumption is low, and the supported operating modes allow additional power control. These MCUs also use an anti-noise configuration to reduce emissions of electromagnetic noise and are designed to withstand EMI.

Integration of many peripheral functions, including multifunction timer and serial interface, reduces the number of system components.

Furthermore, the R8C/2L Group has on-chip data flash (1 KB \times 2 blocks).

The difference between the R8C/2K Group and R8C/2L Group is only the presence or absence of data flash. Their peripheral functions are the same.

1.1.1 Applications

Electronic household appliances, office equipment, audio equipment, consumer equipment, etc.

Table 1.3 Specifications for R8C/2L Group (1)

Item	Function	Specification
CPU	Central processing unit	R8C/Tiny series core <ul style="list-style-type: none"> • Number of fundamental instructions: 89 • Minimum instruction execution time: <ul style="list-style-type: none"> 50 ns ($f(XIN) = 20$ MHz, $VCC = 3.0$ to 5.5 V) 100 ns ($f(XIN) = 10$ MHz, $VCC = 2.7$ to 5.5 V) 200 ns ($f(XIN) = 5$ MHz, $VCC = 2.2$ to 5.5 V) • Multiplier: 16 bits \times 16 bits \rightarrow 32 bits • Multiply-accumulate instruction: 16 bits \times 16 bits + 32 bits \rightarrow 32 bits • Operation mode: Single-chip mode (address space: 1 Mbyte)
Memory	ROM, RAM	Refer to Table 1.6 Product List for R8C/2L Group .
Power Supply Voltage Detection	Voltage detection circuit	<ul style="list-style-type: none"> • Power-on reset • Voltage detection 3
I/O Ports	Programmable I/O ports	<ul style="list-style-type: none"> • Input-only: 3 pins • CMOS I/O ports: 25, selectable pull-up resistor • High current drive ports: 8
Clock	Clock generation circuits	2 circuits: XIN clock oscillation circuit (with on-chip feedback resistor), On-chip oscillator (high-speed, low-speed) (high-speed on-chip oscillator has a frequency adjustment function) <ul style="list-style-type: none"> • Oscillation stop detection: XIN clock oscillation stop detection function • Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16 • Low power consumption modes: <ul style="list-style-type: none"> Standard operating mode (high-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode
Interrupts		<ul style="list-style-type: none"> • External: 4 sources, Internal: 15 sources, Software: 4 sources • Priority levels: 7 levels
Watchdog Timer		15 bits \times 1 (with prescaler), reset start selectable
Timer	Timer RA	8 bits \times 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode
	Timer RB	8 bits \times 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode
	Timer RC	16 bits \times 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)
	Timer RD	16 bits \times 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period)

1.2 Product List

Table 1.5 lists the Product List for R8C/2K Group, Figure 1.1 shows a Part Number, Memory Size, and Package of R8C/2K Group, Table 1.6 lists the Product List for R8C/2L Group, and Figure 1.2 shows a Part Number, Memory Size, and Package of R8C/2L Group.

Table 1.5 Product List for R8C/2K Group

Current of Dec. 2007

Part No.	ROM Capacity	RAM Capacity	Package Type	Remarks
R5F212K2SNFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version
R5F212K4SNFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SDFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version
R5F212K4SDFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SNXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version Factory programming product ⁽¹⁾
R5F212K4SNXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SDXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version Factory programming product ⁽¹⁾
R5F212K4SDXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	

(D): Under development

NOTE:

1. The user ROM is programmed before shipment.

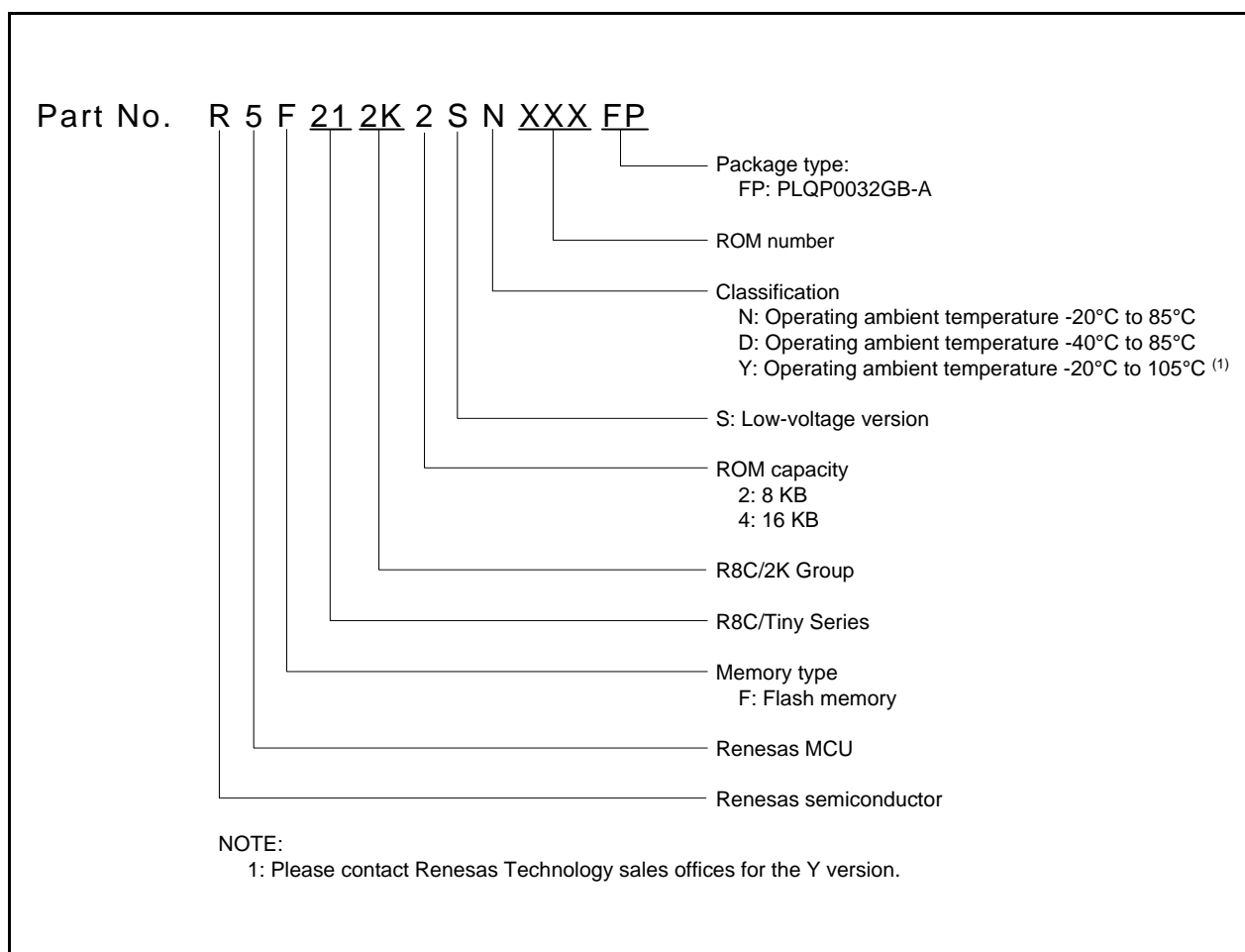


Figure 1.1 Part Number, Memory Size, and Package of R8C/2K Group

1.3 Block Diagram

Figure 1.3 shows a Block Diagram.

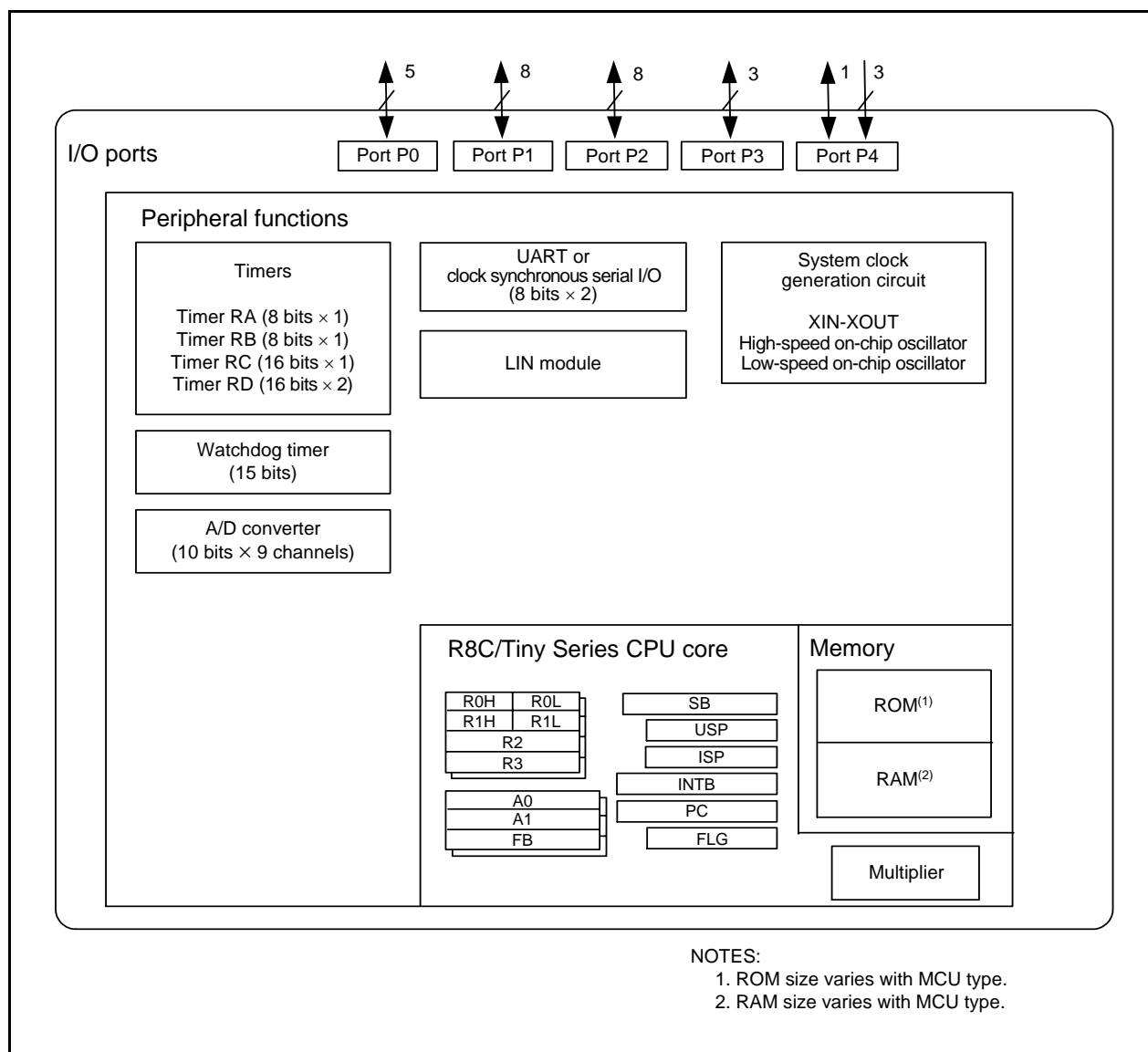


Figure 1.3 Block Diagram

Table 1.7 Pin Name Information by Pin Number

Pin Number	Control Pin	Port	I/O Pin Functions for of Peripheral Modules			
			Interrupt	Timer	Serial Interface	A/D Converter
1	VREF	P4_2				
2	MODE					
3	RESET					
4	XOUT	P4_7				
5	VSS/AVSS					
6	XIN	P4_6				
7	VCC/AVCC					
8		P3_3	INT3	TRCCLK		
9		P2_7		TRDIOD1		
10		P2_6		TRDIOC1		
11		P2_5		TRDIOB1		
12		P2_4		TRDIOA1		
13		P2_3		TRDIOD0		
14		P2_1		TRDIOB0		
15		P2_2		TRDIOC0		
16		P2_0		TRDIOA0/TRDCLK		
17		P4_5	INT0			
18		P1_7	INT1	TRAIO		
19		P1_6			CLK0	
20		P1_5	(INT1) ⁽¹⁾	(TRAIO) ⁽¹⁾	RXD0	
21		P1_4			TXD0	
22		P1_3	KI3	TRBO		AN11
23		P1_2	KI2	TRCIOB		AN10
24		P1_1	KI1	TRCIOA/TRCTRG		AN9
25		P1_0	KI0			AN8
26		P3_4		TRCIOC		
27		P3_5		TRCIOD		
28		P0_5				AN2
29		P0_3			CLK2	AN4
30		P0_2			RXD2	AN5
31		P0_1			TXD2	AN6
32		P0_0				AN7

NOTE:

1. Can be assigned to the pin in parentheses by a program.

1.5 Pin Functions

Table 1.8 lists Pin Functions.

Table 1.8 Pin Functions

Item	Pin Name	I/O Type	Description
Power supply input	VCC, VSS	–	Apply 2.2 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin.
Analog power supply input	AVCC, AVSS	–	Power supply for the A/D converter. Connect a capacitor between AVCC and AVSS.
Reset input	$\overline{\text{RESET}}$	I	Input “L” on this pin resets the MCU.
MODE	MODE	I	Connect this pin to VCC via a resistor.
XIN clock input	XIN	I	These pins are provided for XIN clock generation circuit I/O. Connect a ceramic resonator or a crystal oscillator between the XIN and XOUT pins ⁽¹⁾ . To use an external clock, input it to the XIN pin and leave the XOUT pin open.
XIN clock output	XOUT	O	
$\overline{\text{INT}}$ interrupt input	$\overline{\text{INT0}}$, $\overline{\text{INT1}}$, $\overline{\text{INT3}}$	I	$\overline{\text{INT}}$ interrupt input pins. $\overline{\text{INT0}}$ is timer RB, timer RC and timer RD input pins.
Key input interrupt	$\overline{\text{KI0}}$ to $\overline{\text{KI3}}$	I	Key input interrupt input pins
Timer RA	TRAIO	I/O	Timer RA I/O pin
Timer RB	TRBO	O	Timer RB output pin
Timer RC	TRCLK	I	External clock input pin
	TRCTR $\overline{\text{G}}$	I	External trigger input pin
	TRCIOA, TRCIOB, TRCIOC, TRCIOD	I/O	Timer RC I/O pins
Timer RD	TRDIOA0, TRDIOA1, TRDIOB0, TRDIOB1, TRDIOC0, TRDIOC1, TRDIOD0, TRDIOD1	I/O	Timer RD I/O pins
	TRDCLK	I	External clock input pin
Serial interface	CLK0, CLK2	I/O	Transfer clock I/O pins
	RXD0, RXD2	I	Serial data input pins
	TXD0, TXD2	O	Serial data output pins
Reference voltage input	VREF	I	Reference voltage input pin to A/D converter
A/D converter	AN2, AN4 to AN11	I	Analog input pins to A/D converter
I/O port	P0_0 to P0_3, P0_5, P1_0 to P1_7, P2_0 to P2_7, P3_3 to P3_5, P4_5,	I/O	CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually. Any port set to input can be set to use a pull-up resistor or not by a program. P2_0 to P2_7 also function as LED drive ports.
Input port	P4_2, P4_6, P4_7	I	Input-only ports

I: Input O: Output I/O: Input and output

NOTE:

1. Refer to the oscillator manufacturer for oscillation characteristics.

2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP, and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.

3. Memory

3.1 R8C/2K Group

Figure 3.1 is a Memory Map of R8C/2K Group. The R8C/2K Group has 1 Mbyte of address space from addresses 00000h to FFFFFh.

The internal ROM is allocated lower addresses, beginning with address 0FFFFh. For example, a 16-Kbyte internal ROM area is allocated addresses 0C000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. They store the starting address of each interrupt routine.

The internal RAM is allocated higher addresses beginning with address 00400h. For example, a 1.5-Kbyte internal RAM area is allocated addresses 00400h to 009FFh. The internal RAM is used not only for storing data but also for calling subroutines and as stacks when interrupt requests are acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh. The peripheral function control registers are allocated here. All addresses within the SFR, which have nothing allocated are reserved for future use and cannot be accessed by users.

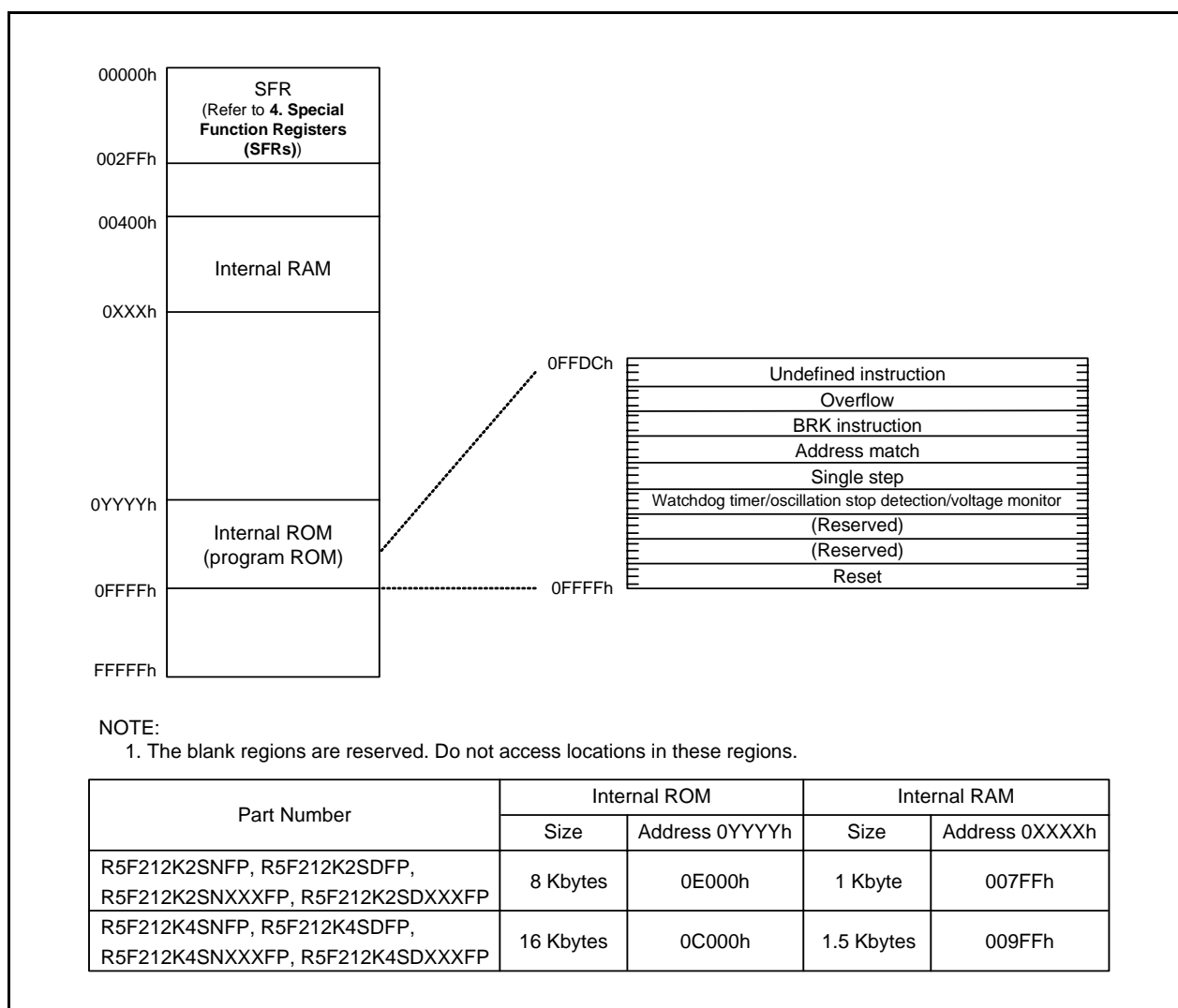


Figure 3.1 Memory Map of R8C/2K Group

Table 4.4 SFR Information (4)⁽¹⁾

Address	Register	Symbol	After reset
00C0h	A/D Register	AD	XXh
00C1h			XXh
00C2h			
00C3h			
00C4h			
00C5h			
00C6h			
00C7h			
00C8h			
00C9h			
00CAh			
00CBh			
00CCh			
00CDh			
00CEh			
00CFh			
00D0h			
00D1h			
00D2h			
00D3h			
00D4h	A/D Control Register 2	ADCON2	00h
00D5h	A/D Control Register 0	ADCON0	00h
00D6h			
00D7h	A/D Control Register 1	ADCON1	00h
00D8h			
00D9h			
00DAh			
00DBh			
00DCh			
00DDh			
00DEh			
00DFh			
00E0h	Port P0 Register	P0	XXh
00E1h	Port P1 Register	P1	XXh
00E2h	Port P0 Direction Register	PD0	00h
00E3h	Port P1 Direction Register	PD1	00h
00E4h	Port P2 Register	P2	XXh
00E5h	Port P3 Register	P3	XXh
00E6h	Port P2 Direction Register	PD2	00h
00E7h	Port P3 Direction Register	PD3	00h
00E8h	Port P4 Register	P4	XXh
00E9h			
00EAh	Port P4 Direction Register	PD4	00h
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h			
00F1h			
00F2h			
00F3h			
00F4h	Port P2 Drive Capacity Control Register	P2DRR	00h
00F5h	Pin Select Register 1	PINSR1	XXh
00F6h	Pin Select Register 2	PINSR2	XXh
00F7h	Pin Select Register 3	PINSR3	XXh
00F8h	Port Mode Register	PMR	00h
00F9h	External Input Enable Register	INTEN	00h
00FAh	INT Input Filter Select Register	INTF	00h
00FBh	Key Input Enable Register	KIEN	00h
00FCh	Pull-Up Control Register 0	PUR0	00h
00FDh	Pull-Up Control Register 1	PUR1	XX000000b
00FEh			
00FFh			

X: Undefined

NOTE:

1. The blank regions are reserved. Do not access locations in these regions.

5. Electrical Characteristics

The electrical characteristics of N version ($T_{opr} = -20^{\circ}\text{C}$ to 85°C) and D version ($T_{opr} = -40^{\circ}\text{C}$ to 85°C) are listed below.

Please contact Renesas Technology sales offices for the electrical characteristics in the Y version ($T_{opr} = -20^{\circ}\text{C}$ to 105°C).

Table 5.1 Absolute Maximum Ratings

Symbol	Parameter	Condition	Rated Value	Unit
V_{CC}/AV_{CC}	Supply voltage		-0.3 to 6.5	V
V_I	Input voltage		-0.3 to $V_{CC} + 0.3$	V
V_O	Output voltage		-0.3 to $V_{CC} + 0.3$	V
P_d	Power dissipation	$T_{opr} = 25^{\circ}\text{C}$	500	mW
T_{opr}	Operating ambient temperature		-20 to 85 (N version) / -40 to 85 (D version)	$^{\circ}\text{C}$
T_{stg}	Storage temperature		-65 to 150	$^{\circ}\text{C}$

Table 5.2 Recommended Operating Conditions

Symbol	Parameter		Conditions	Standard			Unit
				Min.	Typ.	Max.	
V _{CC}	Supply voltage			2.2	–	5.5	V
AV _{CC}	Supply voltage			2.7	–	5.5	
V _{SS} /AV _{SS}	Supply voltage			–	0	–	V
V _{IH}	Input “H” voltage			0.8 V _{CC}	–	V _{CC}	V
V _{IL}	Input “L” voltage			0	–	0.2 V _{CC}	V
I _{OH} (sum)	Peak sum output “H” current	Sum of all pins I _{OH} (peak)		–	–	–160	mA
I _{OH} (sum)	Average sum output “H” current	Sum of all pins I _{OH} (avg)		–	–	–80	mA
I _{OH} (peak)	Peak output “H” current	Except P2_0 to P2_7		–	–	–10	mA
		P2_0 to P2_7		–	–	–40	mA
I _{OH} (avg)	Average output “H” current	Except P2_0 to P2_7		–	–	–5	mA
		P2_0 to P2_7		–	–	–20	mA
I _{OL} (sum)	Peak sum output “L” currents	Sum of all pins I _{OL} (peak)		–	–	160	mA
I _{OL} (sum)	Average sum output “L” currents	Sum of all pins I _{OL} (avg)		–	–	80	mA
I _{OL} (peak)	Peak output “L” currents	Except P2_0 to P2_7		–	–	10	mA
		P2_0 to P2_7		–	–	40	mA
I _{OL} (avg)	Average output “L” current	Except P2_0 to P2_7		–	–	5	mA
		P2_0 to P2_7		–	–	20	mA
f _(XIN)	XIN clock input oscillation frequency		3.0 V ≤ V _{CC} ≤ 5.5 V	0	–	20	MHz
			2.7 V ≤ V _{CC} < 3.0 V	0	–	10	MHz
			2.2 V ≤ V _{CC} < 2.7 V	0	–	5	MHz
–	System clock	OCD2 = 0 XIN clock selected	3.0 V ≤ V _{CC} ≤ 5.5 V	0	–	20	MHz
			2.7 V ≤ V _{CC} < 3.0 V	0	–	10	MHz
			2.2 V ≤ V _{CC} < 2.7 V	0	–	5	MHz
		OCD2 = 1 On-chip oscillator clock selected	FRA01 = 0 Low-speed on-chip oscillator clock selected	–	125	–	kHz
			FRA01 = 1 High-speed on-chip oscillator clock selected 3.0 V ≤ V _{CC} ≤ 5.5 V	–	–	20	MHz
			FRA01 = 1 High-speed on-chip oscillator clock selected 2.7 V ≤ V _{CC} ≤ 5.5 V	–	–	10	MHz
			FRA01 = 1 High-speed on-chip oscillator clock selected 2.2 V ≤ V _{CC} ≤ 5.5 V	–	–	5	MHz

NOTES:

1. V_{CC} = 2.2 to 5.5 V at T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.
2. The average output current indicates the average value of current measured during 100 ms.

Table 5.3 A/D Converter Characteristics

Symbol	Parameter		Conditions	Standard			Unit
				Min.	Typ.	Max.	
—	Resolution		$V_{ref} = AV_{CC}$	—	—	10	Bits
—	Absolute accuracy	10-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 5.0 \text{ V}$	—	—	± 3	LSB
		8-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 5.0 \text{ V}$	—	—	± 2	LSB
		10-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 3.3 \text{ V}$	—	—	± 5	LSB
		8-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 3.3 \text{ V}$	—	—	± 2	LSB
R_{ladder}	Resistor ladder		$V_{ref} = AV_{CC}$	10	—	40	$k\Omega$
t_{conv}	Conversion time	10-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 5.0 \text{ V}$	3.3	—	—	μs
		8-bit mode	$\phi_{AD} = 10 \text{ MHz}$, $V_{ref} = AV_{CC} = 5.0 \text{ V}$	2.8	—	—	μs
V_{ref}	Reference voltage			2.2	—	AV_{CC}	V
V_{IA}	Analog input voltage ⁽²⁾			0	—	AV_{CC}	V
—	A/D operating clock frequency	Without sample and hold	$V_{ref} = AV_{CC} = 2.7 \text{ to } 5.5 \text{ V}$	0.25	—	10	MHz
		With sample and hold	$V_{ref} = AV_{CC} = 2.7 \text{ to } 5.5 \text{ V}$	1	—	10	MHz

NOTES:

1. $AV_{CC} = 2.7 \text{ to } 5.5 \text{ V}$ at $T_{opr} = -20 \text{ to } 85^\circ\text{C}$ (N version) / $-40 \text{ to } 85^\circ\text{C}$ (D version), unless otherwise specified.
2. When the analog input voltage is over the reference voltage, the A/D conversion result will be 3FFh in 10-bit mode and FFh in 8-bit mode.

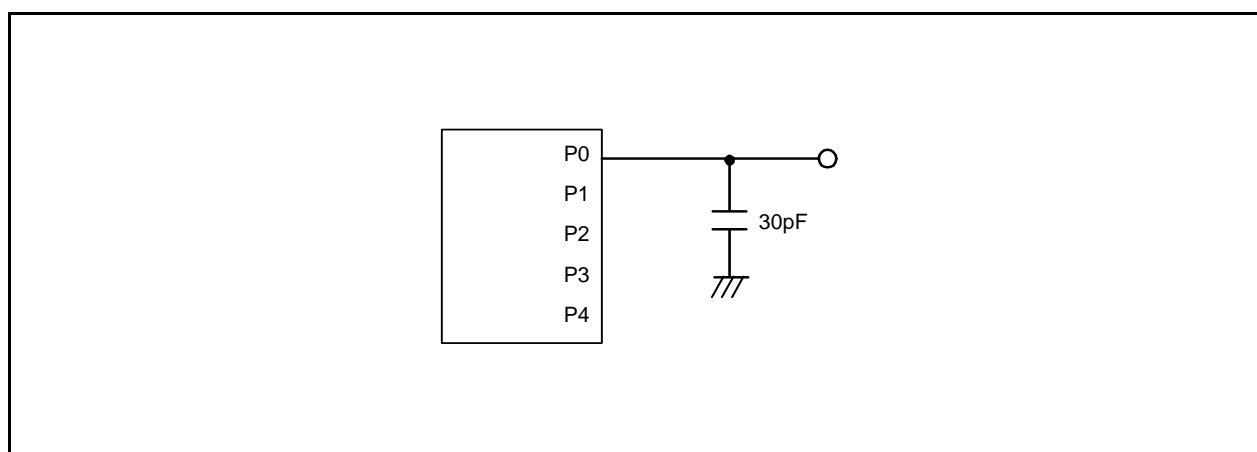
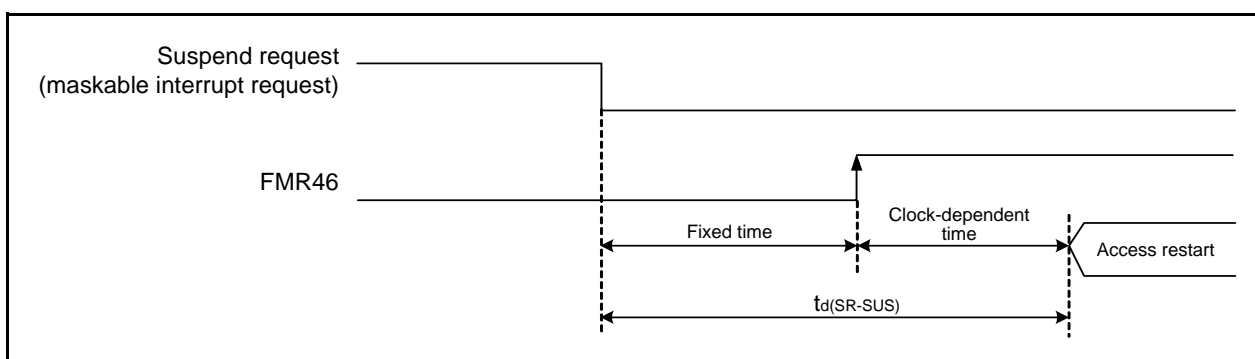
**Figure 5.1 Ports P0 to P4 Timing Measurement Circuit**

Table 5.4 Flash Memory (Program ROM) Electrical Characteristics

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
–	Program/erase endurance ⁽²⁾	R8C/2K Group	100 ⁽³⁾	–	–	times
		R8C/2L Group	1,000 ⁽³⁾	–	–	times
–	Byte program time		–	50	400	μs
–	Block erase time		–	0.4	9	s
t _d (SR-SUS)	Time delay from suspend request until suspend		–	–	97+CPU clock × 6 cycles	μs
–	Interval from erase start/restart until following suspend request		650	–	–	μs
–	Interval from program start/restart until following suspend request		0	–	–	ns
–	Time from suspend until program/erase restart		–	–	3+CPU clock × 4 cycles	μs
–	Program, erase voltage		2.7	–	5.5	V
–	Read voltage		2.2	–	5.5	V
–	Program, erase temperature		0	–	60	°C
–	Data hold time ⁽⁷⁾	Ambient temperature = 55°C	20	–	–	year

NOTES:

1. V_{CC} = 2.7 to 5.5 V at T_{opr} = 0 to 60°C, unless otherwise specified.
2. Definition of programming/erasure endurance
The programming and erasure endurance is defined on a per-block basis.
If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.
However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.
5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
7. The data hold time includes time that the power supply is off or the clock is not supplied.

**Figure 5.2 Time delay until Suspend****Table 5.6 Voltage Detection 0 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V _{det0}	Voltage detection level		2.2	2.3	2.4	V
—	Voltage detection circuit self power consumption	VCA25 = 1, V _{CC} = 5.0 V	—	0.9	—	μA
t _{d(E-A)}	Waiting time until voltage detection circuit operation starts ⁽²⁾		—	—	300	μs
V _{ccmin}	MCU operating voltage minimum value		2.2	—	—	V

NOTES:

1. The measurement condition is V_{CC} = 2.2 to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.

Table 5.7 Voltage Detection 1 Circuit Electrical Characteristics

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V _{det1}	Voltage detection level ⁽⁴⁾		2.70	2.85	3.00	V
—	Voltage monitor 1 interrupt request generation time ⁽²⁾		—	40	—	μs
—	Voltage detection circuit self power consumption	VCA26 = 1, V _{CC} = 5.0 V	—	0.6	—	μA
t _{d(E-A)}	Waiting time until voltage detection circuit operation starts ⁽³⁾		—	—	100	μs

NOTES:

1. The measurement condition is V_{CC} = 2.2 to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Time until the voltage monitor 1 interrupt request is generated after the voltage passes V_{det1}.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.
4. This parameter shows the voltage detection level when the power supply drops.
The voltage detection level when the power supply rises is higher than the voltage detection level when the power supply drops by approximately 0.1 V.

Table 5.8 Voltage Detection 2 Circuit Electrical Characteristics

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V _{det2}	Voltage detection level		3.3	3.6	3.9	V
—	Voltage monitor 2 interrupt request generation time ⁽²⁾		—	40	—	μs
—	Voltage detection circuit self power consumption	VCA27 = 1, V _{CC} = 5.0 V	—	0.6	—	μA
t _{d(E-A)}	Waiting time until voltage detection circuit operation starts ⁽³⁾		—	—	100	μs

NOTES:

1. The measurement condition is V_{CC} = 2.2 to 5.5 V and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version).
2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes V_{det2}.
3. Necessary time until the voltage detection circuit operates after setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.

Table 5.13 Electrical Characteristics (1) [V_{CC} = 5 V]

Symbol	Parameter		Condition	Standard			Unit
				Min.	Typ.	Max.	
V _{OH}	Output "H" voltage	Except P2_0 to P2_7, XOUT	I _{OH} = -5 mA	V _{CC} - 2.0	—	V _{CC}	V
			I _{OH} = -200 μ A	V _{CC} - 0.5	—	V _{CC}	V
		P2_0 to P2_7	Drive capacity HIGH I _{OH} = -20 mA	V _{CC} - 2.0	—	V _{CC}	V
			Drive capacity LOW I _{OH} = -5 mA	V _{CC} - 2.0	—	V _{CC}	V
		XOUT	Drive capacity HIGH I _{OH} = -1 mA	V _{CC} - 2.0	—	V _{CC}	V
			Drive capacity LOW I _{OH} = -500 μ A	V _{CC} - 2.0	—	V _{CC}	V
V _{OL}	Output "L" voltage	Except P2_0 to P2_7, XOUT	I _{OL} = 5 mA	—	—	2.0	V
			I _{OL} = 200 μ A	—	—	0.45	V
		P2_0 to P2_7	Drive capacity HIGH I _{OL} = 20 mA	—	—	2.0	V
			Drive capacity LOW I _{OL} = 5 mA	—	—	2.0	V
		XOUT	Drive capacity HIGH I _{OL} = 1 mA	—	—	2.0	V
			Drive capacity LOW I _{OL} = 500 μ A	—	—	2.0	V
V _{T+} -V _{T-}	Hysteresis	INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, RXD0, RXD2, CLK0, CLK2		0.1	0.5	—	V
		RESET		0.1	1.0	—	V
I _{IH}	Input "H" current		V _I = 5 V, V _{CC} = 5 V	—	—	5.0	μ A
I _{IL}	Input "L" current		V _I = 0 V, V _{CC} = 5 V	—	—	-5.0	μ A
R _{PULLUP}	Pull-up resistance		V _I = 0 V, V _{CC} = 5 V	30	50	167	k Ω
R _{FXIN}	Feedback resistance	XIN		—	1.0	—	M Ω
V _{RAM}	RAM hold voltage		During stop mode	1.8	—	—	V

NOTE:

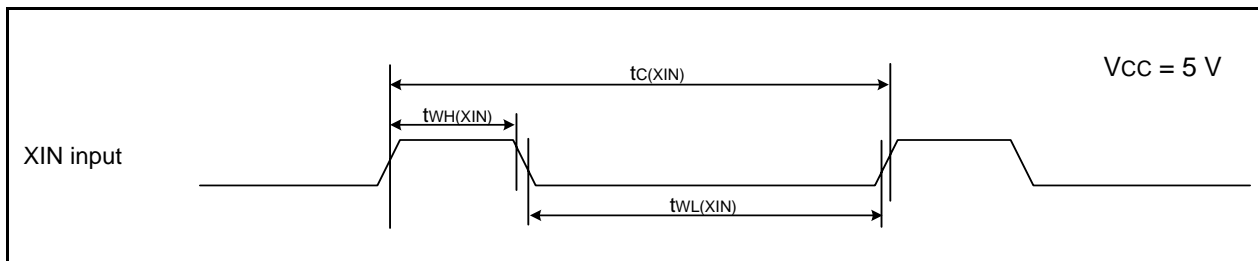
- V_{CC} = 4.2 to 5.5 V at T_{opr} = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 20 MHz, unless otherwise specified.

Table 5.15 Electrical Characteristics (3) [V_{CC} = 5 V]
(T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
I _{CC}	Power supply current (V _{CC} = 3.3 to 5.5 V) Single-chip mode, output pins are open, other pins are V _{SS}	Wait mode	–	25	75	μA
		Stop mode	–	0.8	3.0	μA

Timing Requirements**(Unless Otherwise Specified: $V_{CC} = 5\text{ V}$, $V_{SS} = 0\text{ V}$ at $T_{opr} = 25^{\circ}\text{C}$) [$V_{CC} = 5\text{ V}$]****Table 5.16 XIN Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(XIN)}$	XIN input cycle time	50	–	ns
$t_{WH(XIN)}$	XIN input "H" width	25	–	ns
$t_{WL(XIN)}$	XIN input "L" width	25	–	ns

**Figure 5.4 XIN Input Timing Diagram when $V_{CC} = 5\text{ V}$** **Table 5.17 TRAIO Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TRAIO)}$	TRAIO input cycle time	100	–	ns
$t_{WH(TRAIO)}$	TRAIO input "H" width	40	–	ns
$t_{WL(TRAIO)}$	TRAIO input "L" width	40	–	ns

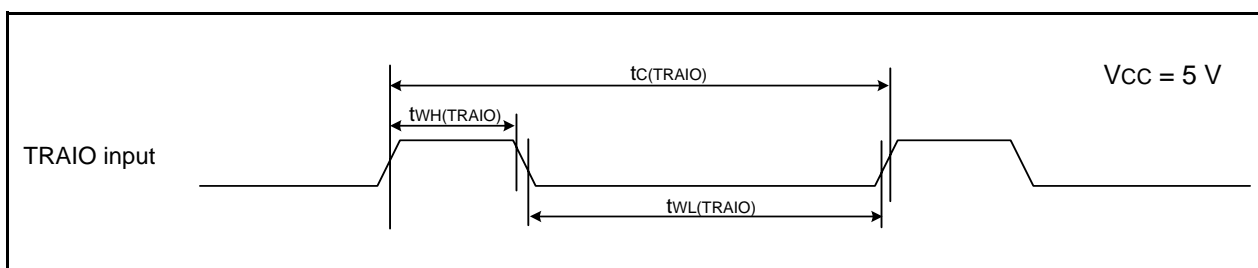
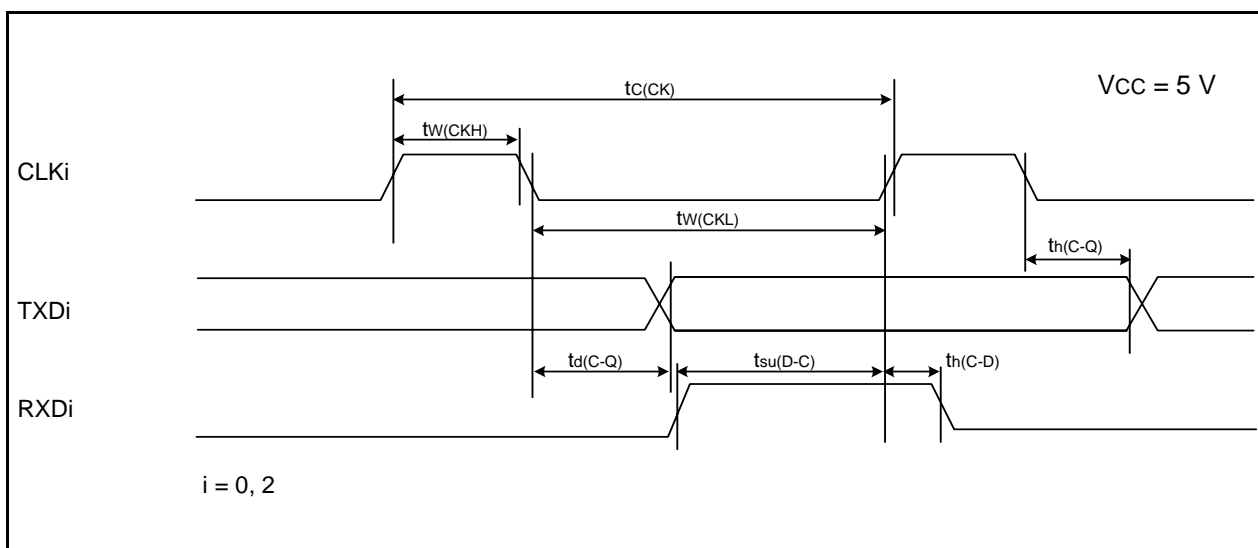
**Figure 5.5 TRAIO Input Timing Diagram when $V_{CC} = 5\text{ V}$**

Table 5.18 Serial Interface

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	200	—	ns
$t_{w(CKH)}$	CLKi input "H" width	100	—	ns
$t_{w(CKL)}$	CLKi input "L" width	100	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	50	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	50	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	ns

 $i = 0, 2$ **Figure 5.6 Serial Interface Timing Diagram when Vcc = 5 V****Table 5.19 External Interrupt \overline{INTi} ($i = 0, 1, 3$) Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	\overline{INTi} input "H" width	250 ⁽¹⁾	—	ns
$t_{w(INL)}$	\overline{INTi} input "L" width	250 ⁽²⁾	—	ns

NOTES:

- When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.
- When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

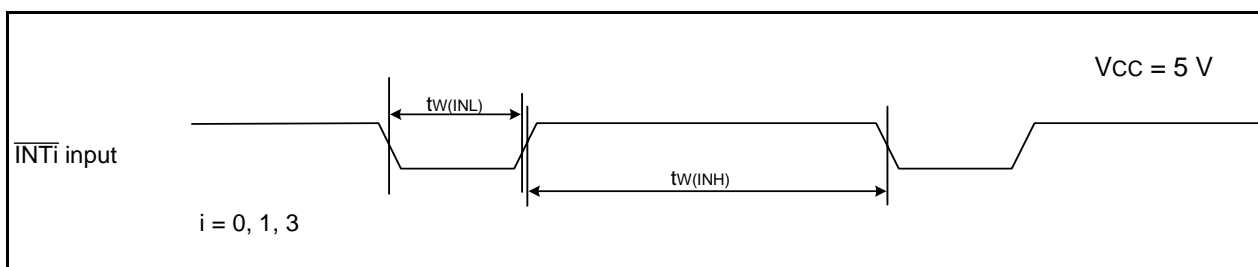
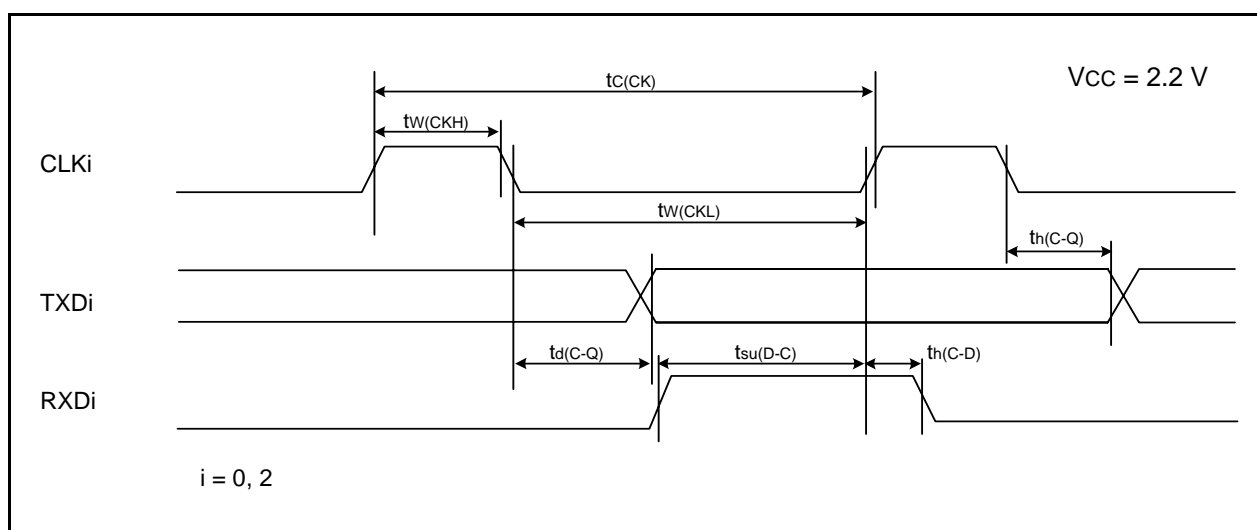
**Figure 5.7 External Interrupt \overline{INTi} Input Timing Diagram when Vcc = 5 V**

Table 5.30 Serial Interface

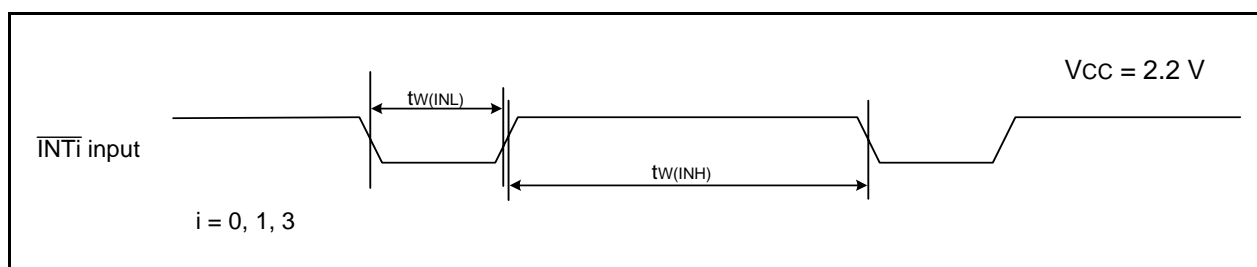
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	800	—	ns
$t_{w(CKH)}$	CLKi input "H" width	400	—	ns
$t_{w(CKL)}$	CLKi input "L" width	400	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	200	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	150	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	ns

 $i = 0, 2$ **Figure 5.14 Serial Interface Timing Diagram when Vcc = 2.2 V****Table 5.31 External Interrupt \overline{INTi} ($i = 0, 1, 3$) Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	\overline{INTi} input "H" width	1000 ⁽¹⁾	—	ns
$t_{w(INL)}$	\overline{INTi} input "L" width	1000 ⁽²⁾	—	ns

NOTES:

1. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input HIGH width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the \overline{INTi} input filter select bit, use an \overline{INTi} input LOW width of either (1/digital filter clock frequency \times 3) or the minimum value of standard, whichever is greater.

**Figure 5.15 External Interrupt \overline{INTi} Input Timing Diagram when Vcc = 2.2 V**

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1 Harbour Front Avenue, #06-10, Keppel Bay Tower, Singapore 098632
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Renesas Technology Malaysia Sdn. Bhd
Unit 906, Block B, Menara Amcorp, Amcorp Trade Centre, No.18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia
Tel: <603> 7955-9390, Fax: <603> 7955-9510